

# Embedded Linux Conference 2017: **Beagle BoF**



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# Beagle BoF outline



- ELC tomorrow: talks and showcase
- BeagleBone OSHW ecosystem
- New: BB Wireless, BB Blue, BB X15
- Debian images
- Debian 9 (“Stretch”) planning
- U-Boot Overlays
- Development resources



# ELC 2017: tomorrow!



- **ELC Technical Showcase**
  - BeagleBoard X15 & BeagleBone Blue
  - Wednesday, February 22, 5:10 pm - 7:00 pm
- **Educational Robotics Critical for the Future of Linux**
  - Jason Kridner, Texas Instruments
  - Wednesday, February 22 • 10:30am - 11:20am
- **Google Summer of Code and BeagleBoard.org**
  - Drew Fustini, BeagleBoard.org Foundation
  - Wednesday, February 22 • 11:30am - 12:20pm

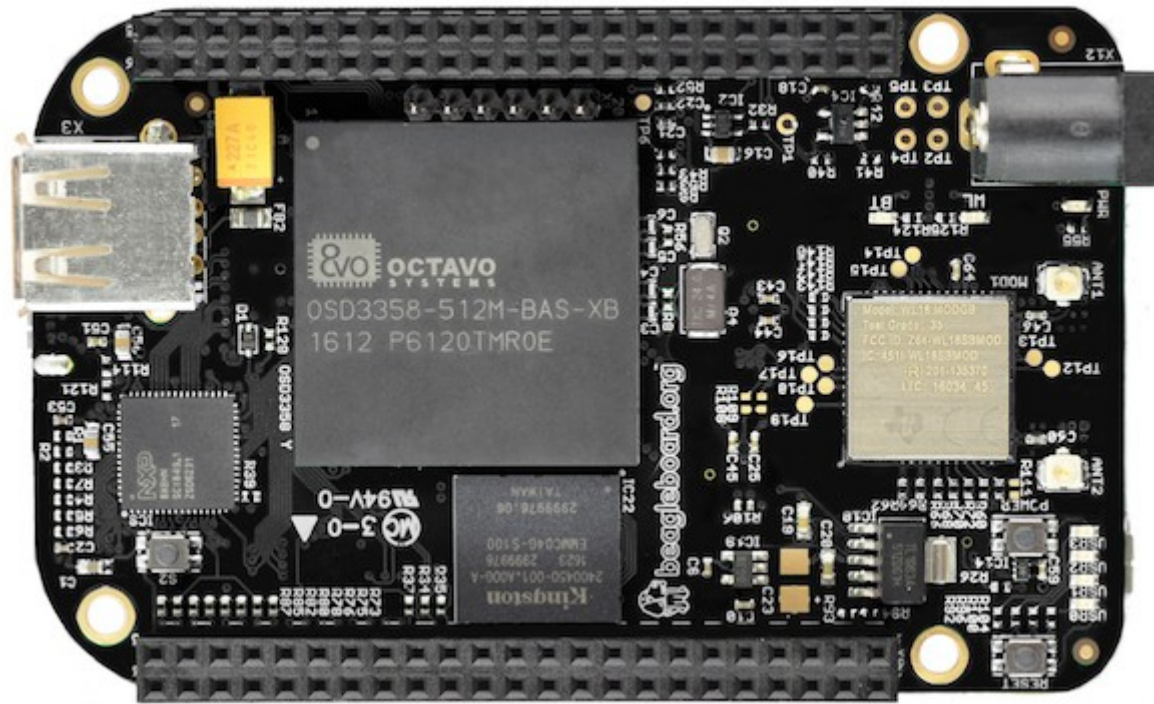


## Open Source Hardware BeagleBone derivatives

	Capes	HDMI	Flash	Special
BeagleBoard.org BeagleBone	Y	N	N	JTAG
BeagleBoard.org BeagleBone Black	Y	Y	Y	-
Arrow BeagleBone Black Industrial	Y	Y	Y	Industrial
Element14 BeagleBone Black Industrial	Y	Y	Y	Industrial
SeeedStudio BeagleBone Green	Y	N	Y	Grove
SanCloud BeagleBone Enhanced	Y	Y	Y	1GB, 1Gbit, wireless
BeagleBoard.org BeagleBone Blue	N	N	Y	Robotics
BeagleBoard.org BeagleBoard-X15	N	Y	N	Big jump in CPUs and I/O



## BeagleBone Black Wireless



- WiFi 802.11b/g/n and Bluetooth 4.1 with BLE
- 1<sup>st</sup> Beagle with **Octavo System-in-Package (SiP)**
- **Designed in EAGLE** (*BBB was OrCad/Allegro*)





# BeagleBoard.org BeagleBone Blue preview

## What is demonstrated

➔ Self-hosted web IDE

## Self-balancing robot run as a userspace task written in C

## Connected USB camera

## Bluetooth speaker for audio

A custom-built robot chassis with a blue PCB. The board features a USB port, various electronic components, and two large black wheels. The robot is shown from a top-down perspective, highlighting its compact design and the integration of the PCB into the chassis.

## Pre-integrated H/W elements for robotics

## 4-layer PCB design

Bottom side  
μUSB client  
μSD slot  
4GB eMMC flash

9 axis IMU and  
barometer

Power LED

4 battery level LEDs

Charger LED

2 cell LiPo battery  
connector

8 servo motor  
outputs

Boot select

4 quadrature  
encoder inputs

4 DC motor  
drivers

4 ADCs

Power out

6 user LEDs

2 user buttons

Reset button

Power button

USB host

2 antennas

TI WiLink™ 8  
802.11b/g/n  
Bluetooth 4.1/BLE

9-18V DC input

GPIO and serial JST connectors

CAN				
I2C	4 GPIOs (GP0)	SPI (S1:2)	UART (UT1)	UART (UT5)
4 GPIOs (GP1)	UART (GPS)	SPI (S1:1)	UART (UT0)	UART (DSM)

Octavo Systems OSD3358 System-in-Package  
1-GHz TI ARM® Cortex®-A8, 512-MB DDR3, power management

Source code or detail technical information availability

<https://github.com/jadonk/beaglebone-blue>

<https://github.com/beagleboard/linux>

<https://github.com/beagleboard/image-builder>

Hardware Information <https://bbb.io/blue>

1-GHz ARM Cortex-A8, programmable real-time units,  
4×DC motor drive, 8×servo motor, WiFi/BT, USB, IMU,  
2 cell LiPo battery mgmt, 4xquad enc barometer



## BeagleBoard.org BeagleBoard-X15

Jason Kridner

### What is demonstrated

- Open hardware computer
  - ➔ Debian Linux system
  - ➔ Open source 2D graphics acceleration
  - ➔ Video acceleration
  - ➔ OpenCL C66 DSP support
  - ➔ Mainline kernel support
  - ➔ GCC compiler support
    - ✓ ARM Cortex-A15
    - ✓ ARM Cortex-M4
    - ✓ TI C66x
    - ✓ TI PRU



### What was improved

- Fastest BeagleBoard available
- More cores and more types of cores
- Lots more I/O capability and bandwidth
- More RAM (2GB)
- Great open hardware ARM build platform

Hardware Information <https://bbb.io/x15>

Dual-core ARM Cortex-A15, dual C66x DSPs, quad programmable real-time units, 3×USB 3.0, PCIe, 2×GigE, 2GB RAM, 4GB eMMC flash.

Source code or detail technical information availability

<https://github.com/beagleboard/beagleboard-x15>  
<https://github.com/beagleboard/linux>  
<https://github.com/beagleboard/image-builder>



# Debian images



- [BeagleBoard.org Latest Firmware Images](#)
  - 2016-11-06: Debian 8.6 (“Jessie”)
- [Debian Image Testing Snapshots](#)
  - 2017-02-12
    - Machinekit
    - Jessie Snapshot LXQT (*full desktop*)
    - Jessie Snapshot IoT (*smaller size*)
    - Jessie Snapshot console (*minimum size*)
    - Stretch testing (*the future!*)





# Debian 9 (“Stretch”)



- root: password <blank> -> password "root"
- root: ssh access -> ssh access disabled
- debian: sudo doesn't ask for password -> sudo asks
- Device-tree-compiler: our v1.4.2-fork -> dtc git mainline
- Kernel: v4.4.x-ti/v4.9.x-ti
- U-boot: v2017.03+ with device tree overlays.
- U-Boot overlays by default with cape-universal overlay applied



# U-Boot Overlays



- U-Boot now has Device Tree Overlay support
  - debian testing: 2017-01-03 (U-Boot Cape Manager edition)
- U-Boot Overlays is currently under development, while the items below may work on "last weeks" version
- Please report bugs to:  
[beagleboard/bb.org-overlays/issues](http://beagleboard/bb.org-overlays/issues)
  - Always double check the version you are using for comparison.



# U-Boot Overlays



- **Migration Guide: U-Boot Overlays**
- **U-Boot /boot/uEnv.txt configuration**
  - enable\_uboot\_overlays=1
- **U-Boot Disable onboard devices**
  - Disable eMMC: disable\_uboot\_overlay\_emmc=1
  - Disable HDMI VIDEO & AUDIO:  
disable\_uboot\_overlay\_video=1
  - Disable HDMI AUDIO: disable\_uboot\_overlay\_audio=1
  - Disable WL1835: disable\_uboot\_overlay\_wireless=1



# U-Boot Overlays



- **U-Boot Override external capes**
  - Cape device tree overlays: [beagleboard/bb.org-overlays](http://beagleboard.org/overlays)
  - `uboot_overlay_addr0=/lib/firmware/<file0>.dtbo`
  - `uboot_overlay_addr1=/lib/firmware/<file1>.dtbo`
  - `uboot_overlay_addr2=/lib/firmware/<file2>.dtbo`
  - `uboot_overlay_addr3=/lib/firmware/<file3>.dtbo`
  - Plus one custom cape: `dtb_overlay=/lib/firmware/<file4>.dtbo`
- **U-Boot Cape Universal**
  - Utilize [beaglebone-universal-io](http://beaglebone-universal-io) config-pin
  - Enable in `/boot/uEnv.txt`: `enable_uboot_cape_universal=1`



# U-Boot Overlays



- U-Boot overlay white list will continue to grow
  - [0002-U-Boot-BeagleBone-Cape-Manager.patch](#)
- If you have a cape, please test, and let's make sure everyone has a good out of box experience!





# Development resources



- Mailing lists: [bbb.io/discuss](http://bbb.io/discuss)
- IRC: [bbb.io/chat](http://bbb.io/chat)
- Kernel build:
  - [RobertCNelson/ti-linux-kernel-dev](https://github.com/RobertCNelson/ti-linux-kernel-dev)
- Kernel repo:
  - [beagleboard/linux](https://github.com/beagleboard/linux)
- DTB Rebuilder
  - [RobertCNelson/dtb-rebuilder](https://github.com/RobertCNelson/dtb-rebuilder)
- Device Tree Overlays for bb.org boards
  - [beagleboard/bb.org-overlays](https://github.com/beagleboard/bb.org-overlays)