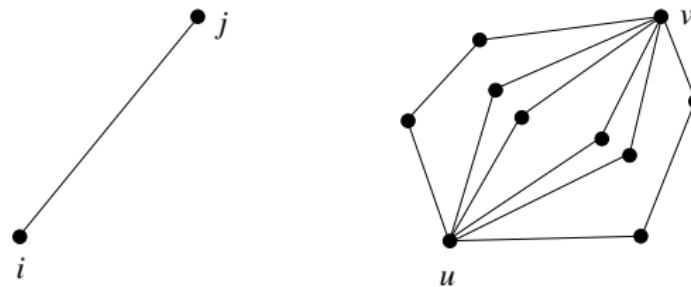


# Algebraic Distance on Graphs

based on paper in SISC 2011

Introduction to Network Science, Spring 14

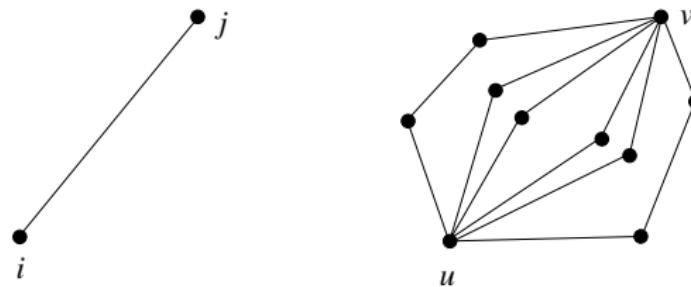
# How to model a connectivity between graph vertices?



Possible problems in (hyper)graph models:

- unweighted edges;
- edges with almost identical weights:  $0.999 \approx? 1.001$ ;
- incomplete set of edges.

# How to model a connectivity between graph vertices?



Possible problems in (hyper)graph models open questions like

- how to break ties?
- should we choose a heaviest edge?
- should we match a disconnected pair?

# How can one measure a connectivity?

Some existing approaches

- Shortest path
- All/some (weighted) indirect paths
- Spectral approaches
- Flow network capacity based approaches
- Random-walk approaches: commute time, first-passage time, etc. (Fouss, Pirotte, Renders, Saerens, ...)
- Speed of convergence of the compatible relaxation from AMG (Brandt, Ron, Livne, ...)
- Probabilistic interpretation of a diffusion (Nadler, Lafon, Coifman, Kevrekidis, ...)
- Minimization of effective resistance of a graph (Ghosh, Boyd, Saberi, ...)

# Stationary iterative relaxation

Simulation process that shows which pair of vertices tends to be ‘more connected’ than other.

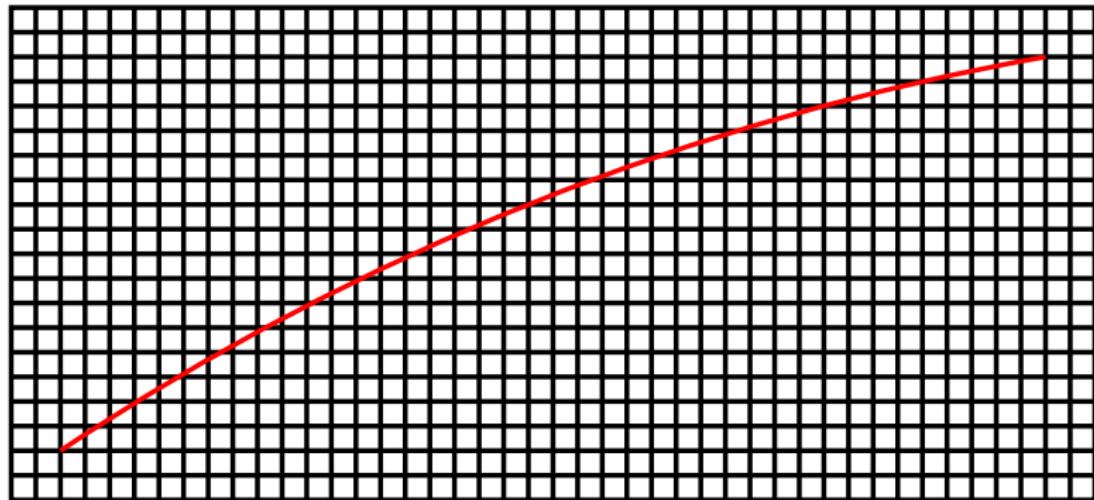
- ①  $\forall i \in V$  define  $x_i = \text{rand}()$
- ② Do  $k$  times step 3
- ③  $\forall i \in V$   $x_i^k = (1 - \omega)x_i^{k-1} + \omega \sum_j w_{ij}x_j^{k-1} / \sum_j w_{ij}$

## Conjecture

If  $|x_i - x_j| > |x_u - x_v|$  then the local connectivity between  $u$  and  $v$  is **stronger** than that between  $i$  and  $j$ .

We will call  $s_{ij}^{(k)} = |x_i - x_j|$  the *algebraic distance* between  $i$  and  $j$  after  $k$  iterations.

# Toy example: graph mesh 20x40+diagonal

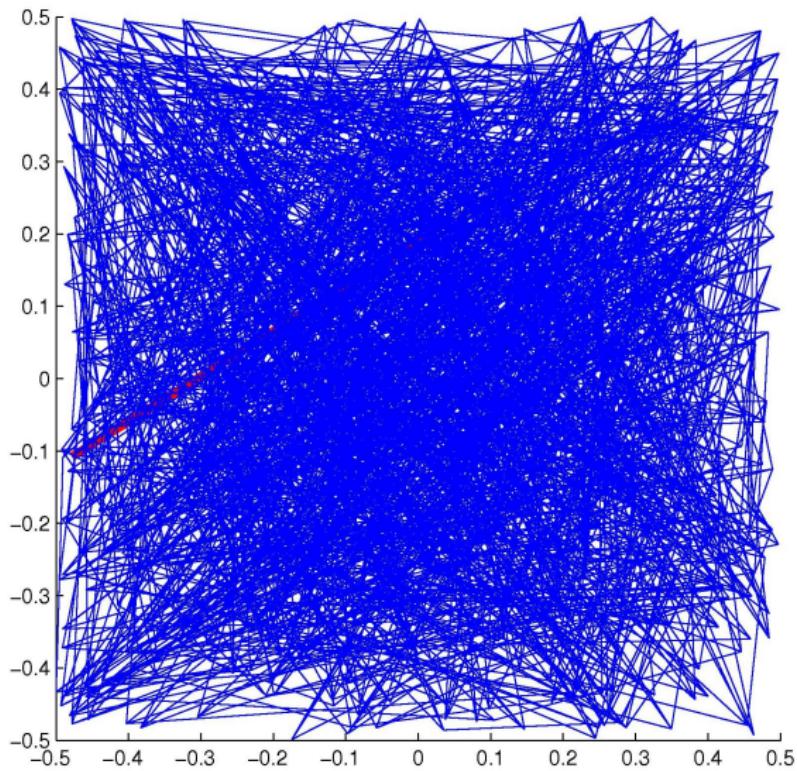


20

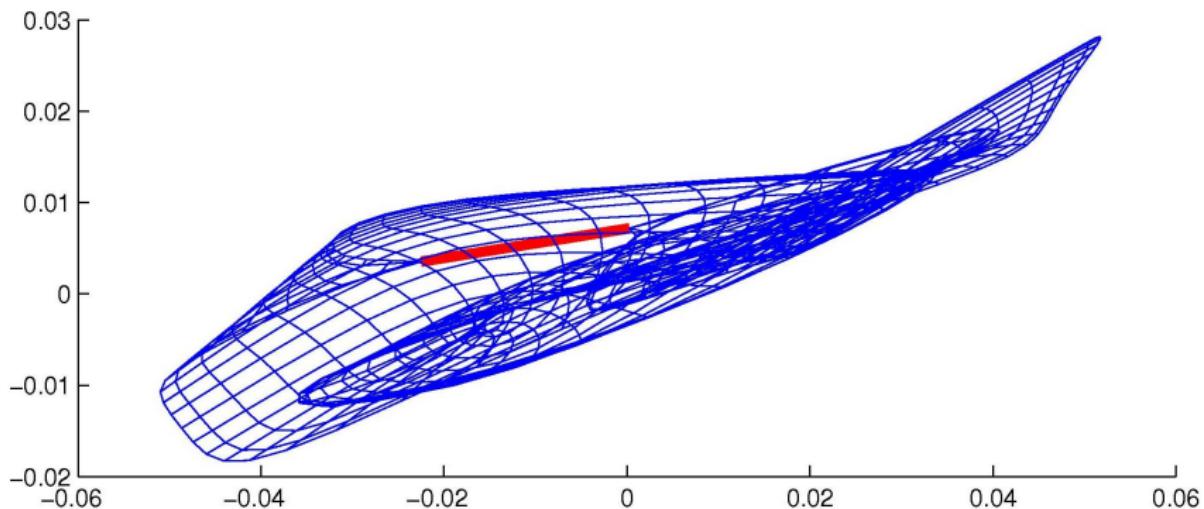
40

edge weights: red=2, black=1

# Mesh 20x40+diagonal, random 2D initialization



# Mesh 20x40+diagonal, after 15 iterations of JOR



# Stationary iterative relaxation

Rewrite the iterative process as  $x^{(k+1)} = Hx^{(k)}$ , where  $H$ :

$$H_{GS} = (D - L)^{-1}U, \quad H_{SOR} = (D/\omega - L)^{-1}((1/\omega - 1)D + U), \\ H_{JAC} = D^{-1}(L + U), \quad H_{JOR} = (D/\omega)^{-1}((1/\omega - 1)D + L + U).$$

## Definition

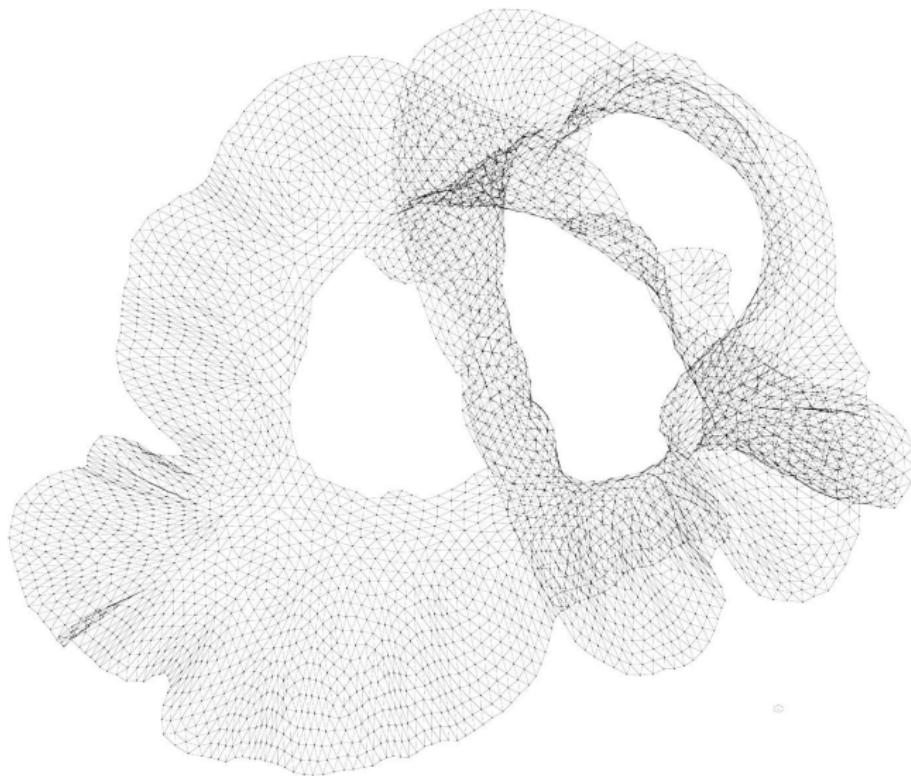
**Extended  $p$ -normed algebraic distance** between  $i$  and  $j$  after  $k$  iterations  $x^{(k+1)} = Hx^{(k)}$  on  $R$  random initializations

$$\rho_{ij}^{(k)} := \left( \sum_{r=1}^R |x_i^{(k,r)} - x_j^{(k,r)}|^p \right)^{1/p}$$

Algebraic distance is inspired by **Bootstrap Algebraic Multigrid**

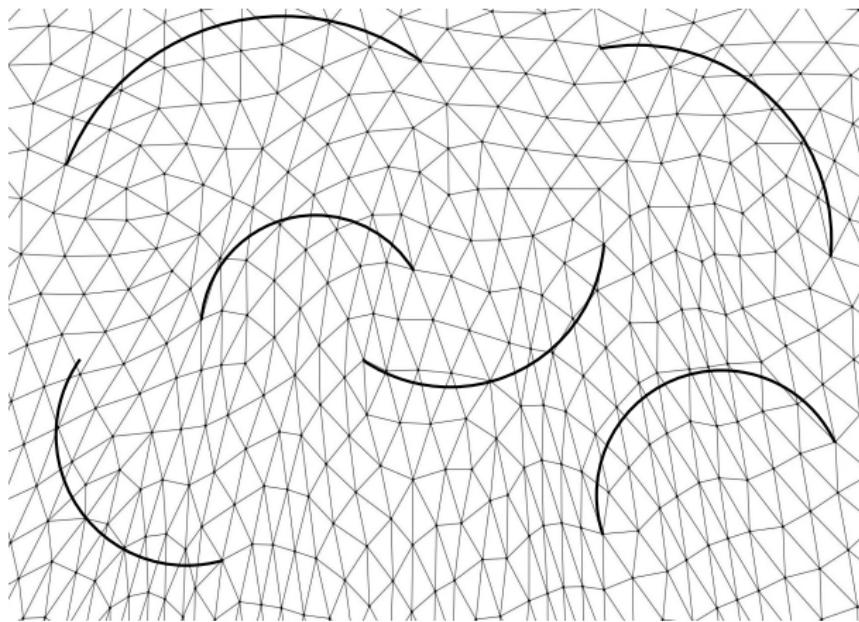
# Example: airfoil - finite element graph, $|E| \approx 13000$

For every edge  $ij$  there exist a path  $i - k - j$

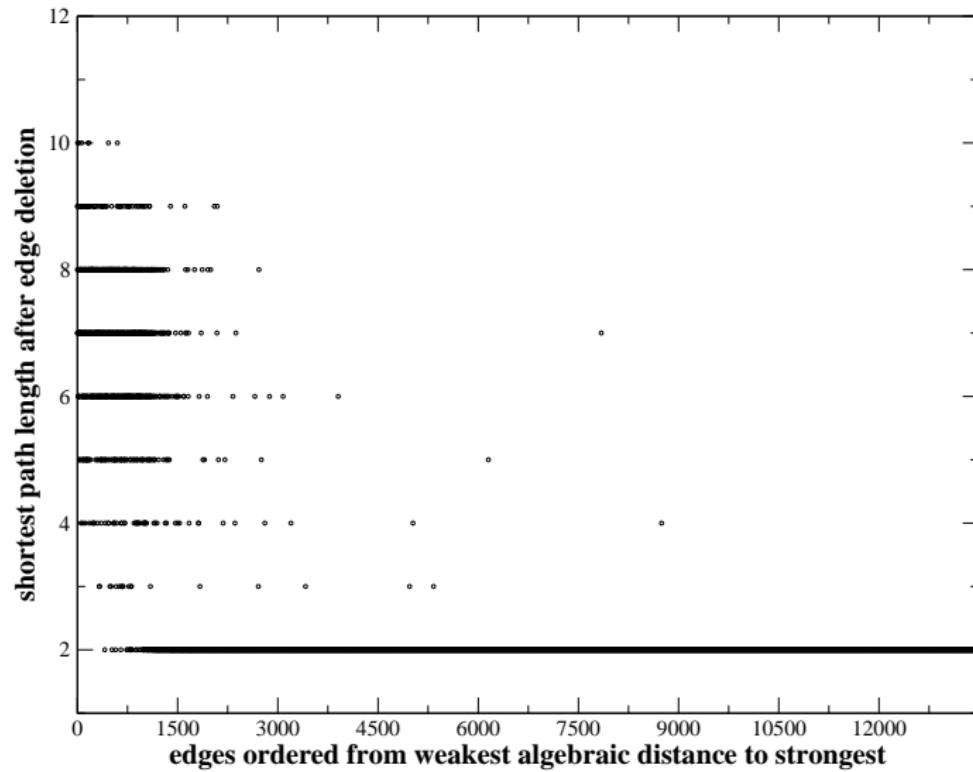


# Input: airfoil + 1500 random edges

- Add 1500 edges such that for every new edge  $ij$ , the second shortest path between  $i$  and  $j$ ,  $p_2$ , has length  $2 < |p_2| < 11$
- Calculate  $\rho_{ij}^{(k)}$ ,  $R = 5$ ,  $k = 15$ ,  $p = 2$



# Shortest paths after edge deletion



# Analysis and Model

- convergence properties of  $H$
- how to choose  $x^{(0)}$
- properties of early iterations
- special focus on JOR
- define "**Mutually Reinforcing Model**" of graph vertices and their neighborhoods
- describe this model using JOR

## Theorem

Given a connected graph, let  $(\mu_i, \hat{v}_i)$  be the eigen-pairs of  $(L, D)$ , labeled in nondecreasing order of the eigenvalues, and assume that  $\mu_2 \neq \mu_3 \neq \mu_{n-1} \neq \mu_n$ . Unless  $\omega = 2/(\mu_2 + \mu_n)$ ,  $\hat{s}_{ij}^{(k)}$  will always converge to a limit  $|(\mathbf{e}_i - \mathbf{e}_j)^T \xi|$  in the order  $O(\theta^k)$ , for some  $\xi$  and  $0 < \theta < 1$ .

- (i) If  $0 < \omega < \frac{2}{(\mu_3 + \mu_n)}$ , then  $\xi \in \text{span}\{\hat{v}_2\}$  and  $\theta = \frac{1 - \omega \mu_3}{1 - \omega \mu_2}$ ;
- (ii) If  $\frac{2}{(\mu_3 + \mu_n)} \leq \omega < \frac{2}{(\mu_2 + \mu_n)}$ , then  $\xi \in \text{span}\{\hat{v}_2\}$  and  $\theta = -\frac{1 - \omega \mu_n}{1 - \omega \mu_2}$ ;
- (iii) If  $\frac{2}{(\mu_2 + \mu_n)} < \omega < \min\{\frac{2}{(\mu_2 + \mu_{n-1})}, \frac{2}{\mu_n}\}$ , then  $\xi \in \text{span}\{\hat{v}_n\}$  and  $\theta = -\frac{1 - \omega \mu_2}{1 - \omega \mu_n}$ ;
- (iv) If  $\frac{2}{(\mu_2 + \mu_{n-1})} \leq \omega < \frac{2}{\mu_n}$ , then  $\xi \in \text{span}\{\hat{v}_n\}$  and  $\theta = \frac{1 - \omega \mu_{n-1}}{1 - \omega \mu_n}$ .

## Theorem

Given a graph, let  $(\mu_i, \hat{v}_i)$  be the eigen-pairs of  $(L, D)$ , labeled in nondecreasing order of the eigenvalues. Denote  $\hat{V} = [\hat{v}_1, \dots, \hat{v}_n]$ . Let  $x^{(0)}$  be the initial vector of the JOR process, and let  $a = \hat{V}^{-1}x^{(0)}$  with  $a_1 \neq 0$ . If the following two conditions are satisfied:

$$1 - \omega\mu_n \geq 0 \quad \text{and} \quad f_k := \frac{\alpha r_k^{2k}(1 - r_k)^2}{1 + \alpha r_k^{2k}(1 + r_k)^2} \leq \frac{1}{\kappa},$$

where  $\alpha = (\sum_{i \neq 1} a_i^2) / (4a_1^2)$ ,  $r_k$  is the unique root at  $[0, 1]$  of

$$2\alpha r^{2k+2} + 2\alpha r^{2k+1} + (k+1)r - k = 0,$$

**then**  $1 - \left\langle \frac{x^{(k)}}{\|x^{(k)}\|}, \frac{x^{(k+1)}}{\|x^{(k+1)}\|} \right\rangle^2 \leq \frac{4\text{cond}(D)f_k}{(1 + \text{cond}(D)f_k)^2}$ .

## Sketch of Theorems

- We cannot use  $H_{JAC}$  for bipartite components. Other iteration matrices are convergent with particular  $\omega$ .
- JOR: Given a connected graph, let  $(\mu_i, \hat{v}_i)$  be the eigen-pairs of the matrix pencil  $(L, D)$ . The normalized algebraic distance will converge either to  $\text{span}\{\hat{v}_2\}$  or  $\text{span}\{\hat{v}_n\}$ .
- JOR: Usually, the convergence will be slow. For example, in many cases it will be  $O\left(\left|\frac{\sigma_3}{\sigma_2}\right|^k\right)$ , where  $\sigma_i$  is an eigenvalue of  $H_{JOR}$ .
- JOR: **However**, after small number of iterations ( $k$ ),  $x^{(k)}$  will be very close to  $x^{(k+1)}$ .

# Interpretation

A mutually reinforcing environment:

- Everybody is influenced by its neighbors:

$$x_i = \mu x_i + \sum_j \left( \frac{w_{ij}}{\sum_k w_{ik}} \right) x_j.$$

- $0 \leq \mu \leq 1$ :
  - When  $\mu$  is close to zero, the environment plays a major role.
  - When  $\mu$  is close to one, the entities are stubborn.
- $\mu$  is a property of the entire environment.
- Two entities  $x_i$  and  $x_j$  are close/similar if

$|x_i - x_j|$  is small.

# Interpretation

Matrix form of the model

$$x = \mu x + D^{-1} W x,$$

or

$$Lx = \mu Dx \quad (0 \leq \mu \leq 1).$$

Possibilities:

- $\mu = 0, x = \mathbf{1}$ . A strong reinforcing environment, but no discriminating power.
- $\mu = \mu_2, x = \hat{v}_2$ . Good. ( $\mu_2$  usually close to zero.)

The limit of the scaled algebraic distance  $\hat{s}_{ij}^{(k)}$  exactly meets the second possibility.

$$\hat{s}_{ij}^{(k)} \rightarrow \left| (\mathbf{e}_i - \mathbf{e}_j)^T \hat{v}_2 \right|.$$

# Interpretation

At an early stage of the iterations (assuming that the iterates are normalized):

$$x^{(k)} \approx x^{(k+1)} = \frac{H_{JOR} x^{(k)}}{\text{normalization}} \approx \frac{(I - \omega D^{-1} L)x^{(k)}}{1 - \omega\mu_2}.$$

Simplified to

$$x^{(k)} \approx \mu_2 x^{(k)} + D^{-1} W x^{(k)}.$$

This means that  $x^{(k)}$  approximately satisfies the model.

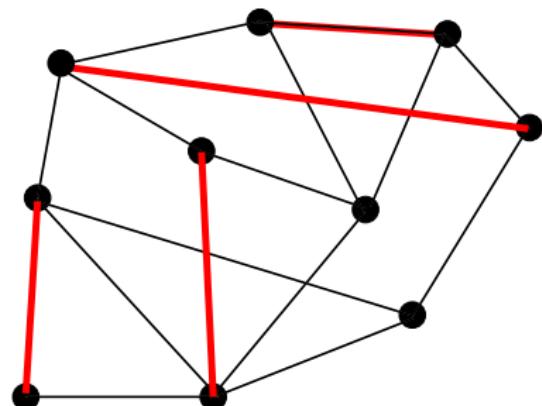
**Conclusion:**  $\hat{v}_2$  is good.  $x^{(k)}$  is also good. They both fit the mutually reinforcing model.

# Applications

# Maximum weighted matching problem

- Graph  $G = (V, E)$
- Weighting function on edges  
 $w : E \rightarrow \mathbb{R}^+$
- Matching:  $M \subseteq E$  with no incident edges.
- $w(M) = \sum_{ij \in M} w_{ij}$
- Maximum weighted matching:  
 $M', \forall M \quad w(M') \geq w(M)$

Methods: textbook greedy algorithm; path growing algorithm  
[DrakeHougardy03]



# Heuristic for weighted matching problem: GREEDY+

## Preprocessing:

**Input:** Graph  $G$

**Output:** edge weights  $s'_{ij}$

For all edges  $ij \in E$  calculate  $\rho_{ij}^{(k)}$  for some  $k$ ,  $R$  and  $p$

For all nodes  $i \in V$  define  $a_i = \sum_{ij \in E} 1/\rho_{ij}^{(k)}$

For all edges  $ij \in E$  define  $s'_{ij} = a_i/\delta_i + a_j/\delta_j$

## GREEDY algorithm:

**Input:** Graph  $G$  with new edge weights  $s'_{ij}$

**Output:** weight of matching  $M$  with original edge weights

$M \leftarrow \emptyset$

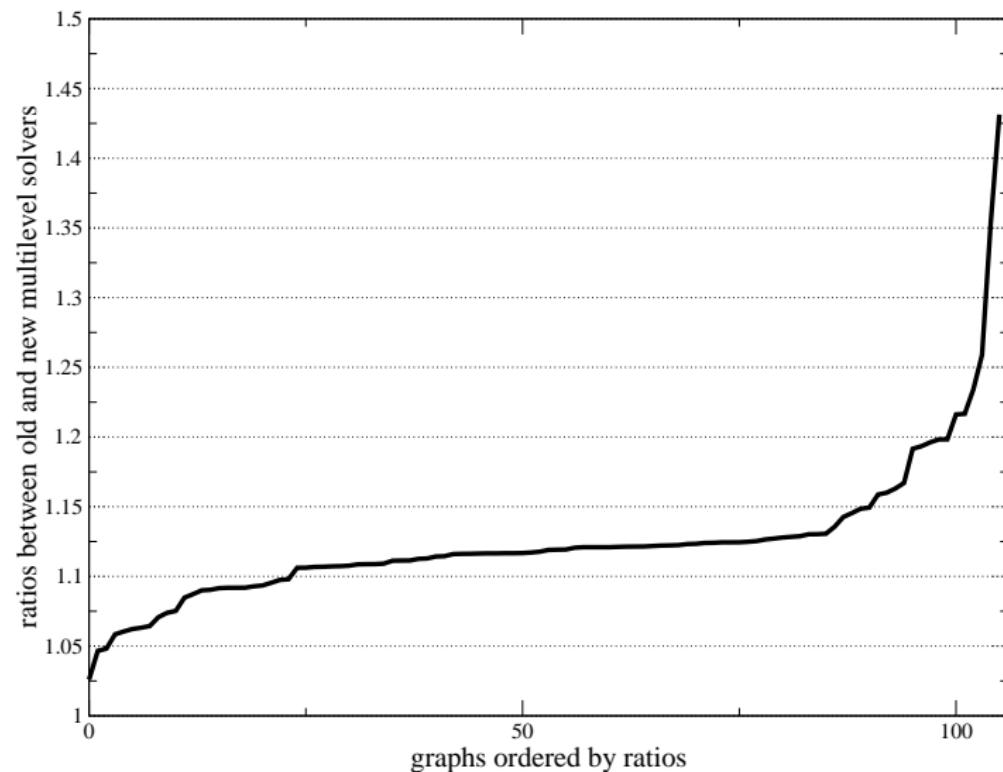
**while**  $E \neq \emptyset$  **do**

| add the lightest edge  $e \in E$  to  $M$

| remove  $e$  and all its incident edges from  $E$

**end**

# Experimental results: weighted matching problem



## Preprocessing:

**Input:** Graph  $G$

**Output:** node weights  $a_i$

For all edges  $ij \in E$  calculate  $\rho_{ij}^{(k)}$  for some  $k$ ,  $R$  and  $p$

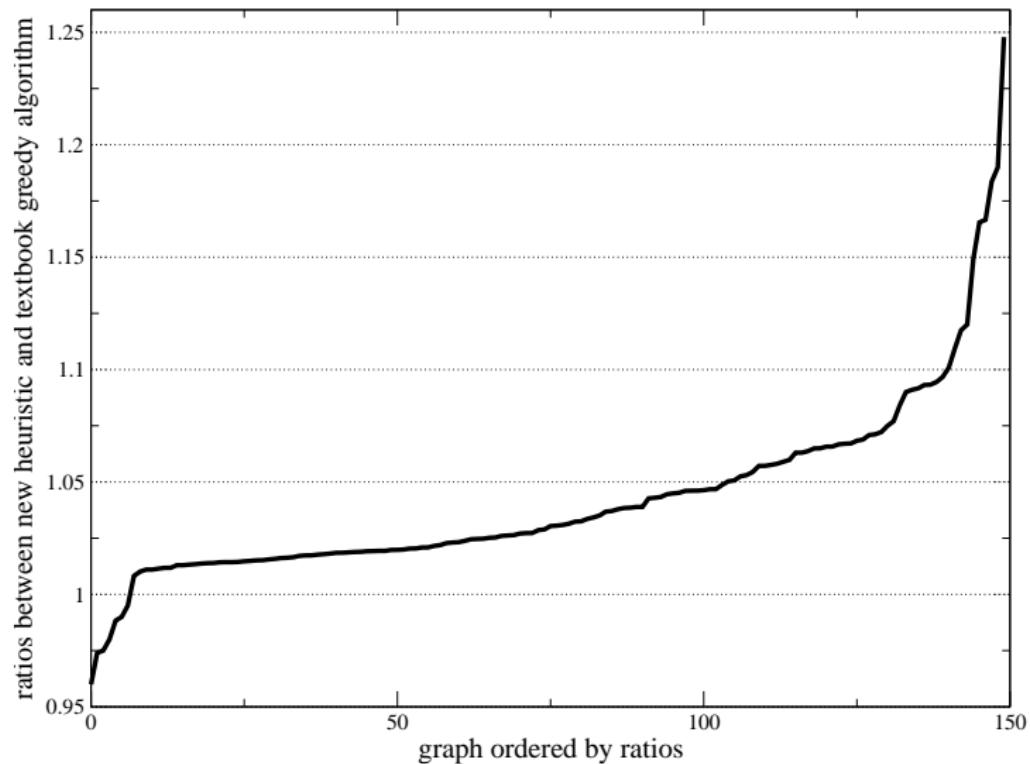
For all nodes  $i \in V$  define  $a_i = \sum_{ij \in E} 1/\rho_{ij}^{(k)}$

For all edges  $ij \in E$  define  $\rho'_{ij} = \rho_{ij}^{(k)} / (a_i + a_j)$

For all nodes  $i \in V$  redefine  $a_i = \sum_{ij \in E} \rho'_{ij}$

Sort  $V$  by  $a_i$  and output its increasing order

# Experimental results: maximum independent set

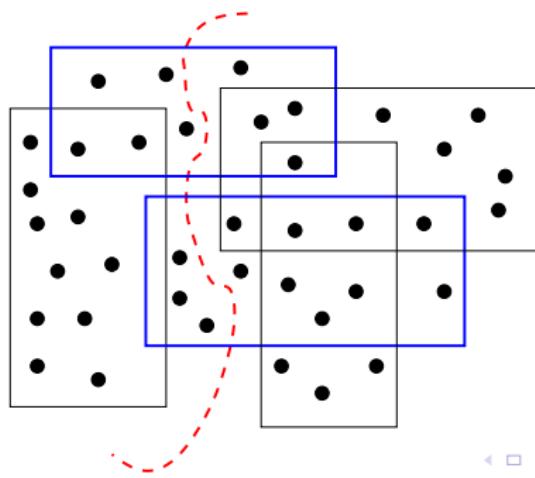


# (Hyper)graph $k$ -partitioning

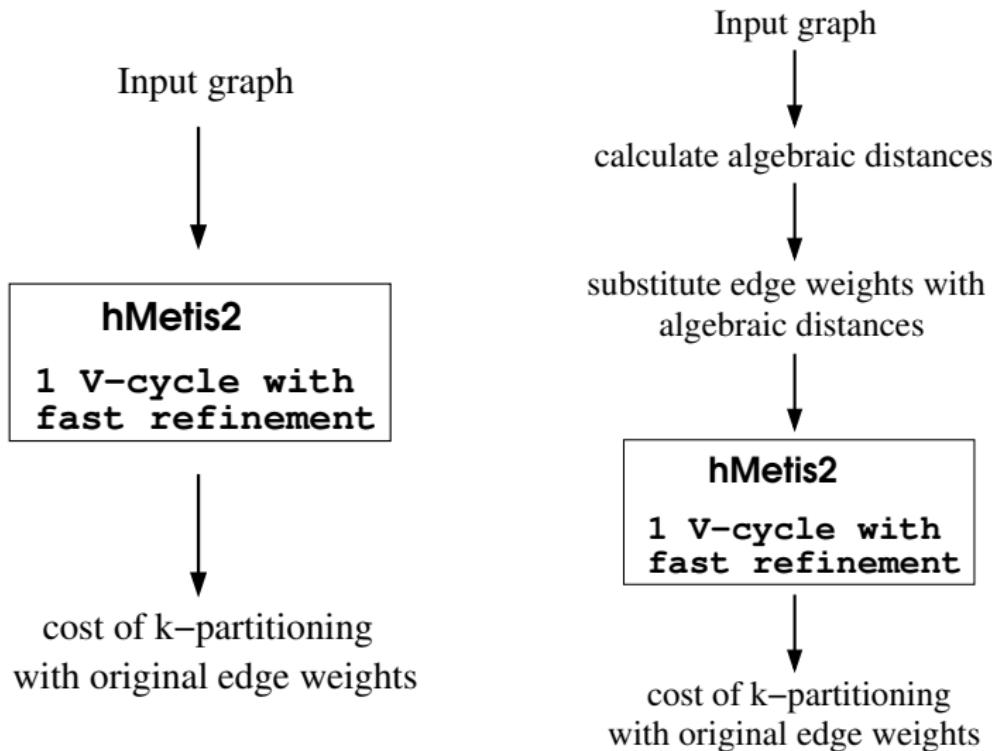
Given a hypergraph  $\mathcal{H} = (\mathcal{V}, \mathcal{E})$

$$\text{minimize} \sum_{\substack{h \in \mathcal{E} \text{ s.t. } \exists i, j \in h \text{ and} \\ i \in \pi_p \Rightarrow j \notin \pi_p}} w_h$$

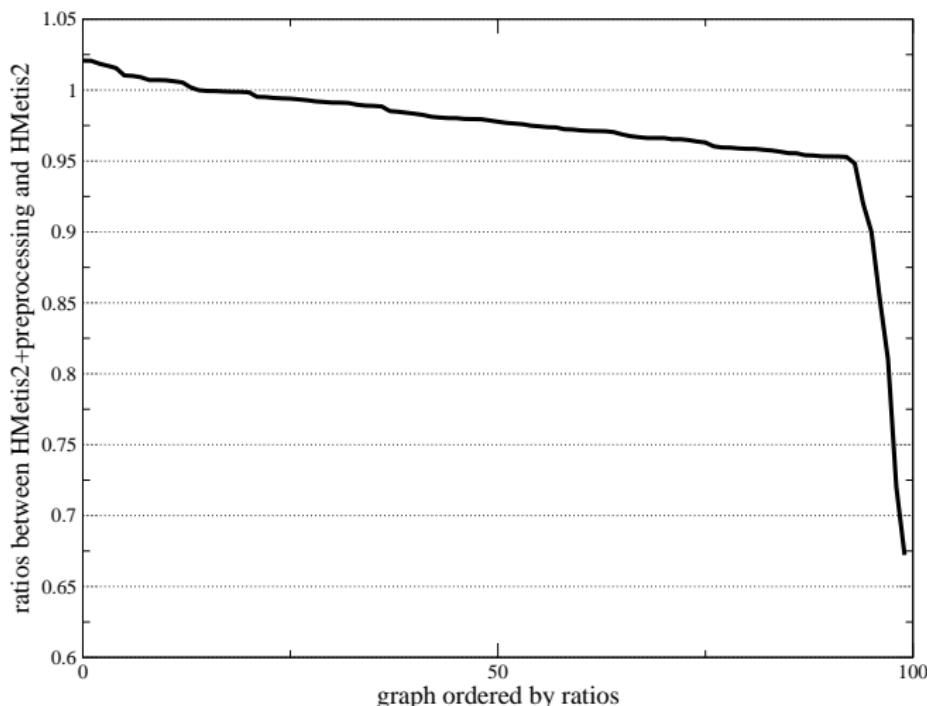
such that  $\forall p \in \{1, \dots, k\}, |\pi_p| \leq (1 + \alpha) \cdot \frac{|V|}{k}$



# (Hyper)graph partitioning



# Experimental results: 2-partitioning



# Algebraic distance for hypergraphs

## Preprocessing:

**Input:** Hypergraph  $\mathcal{H}$ ,  $k = 20$ ,  $R = 10$

**Output:** weights  $s_h^{(k)}$

$G = (V, E) \leftarrow$  bipartite graph model of  $\mathcal{H}$

Create  $R$  initial vectors  $x^{(0,r)}$

**for**  $r = 1, \dots, R$  **do**

**for**  $m=1, \dots, k$  **do**

$x_i^{(m,r)} \leftarrow \sum_j w_{ij} x_j^{(m-1,r)} / \sum_j w_{ij}, \forall i$

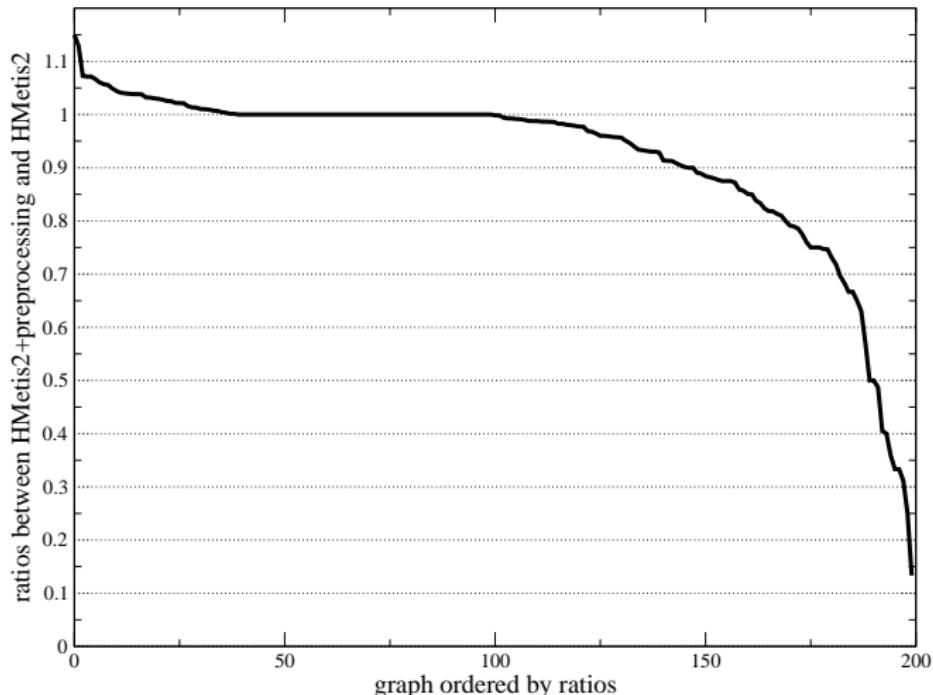
**end**

**end**

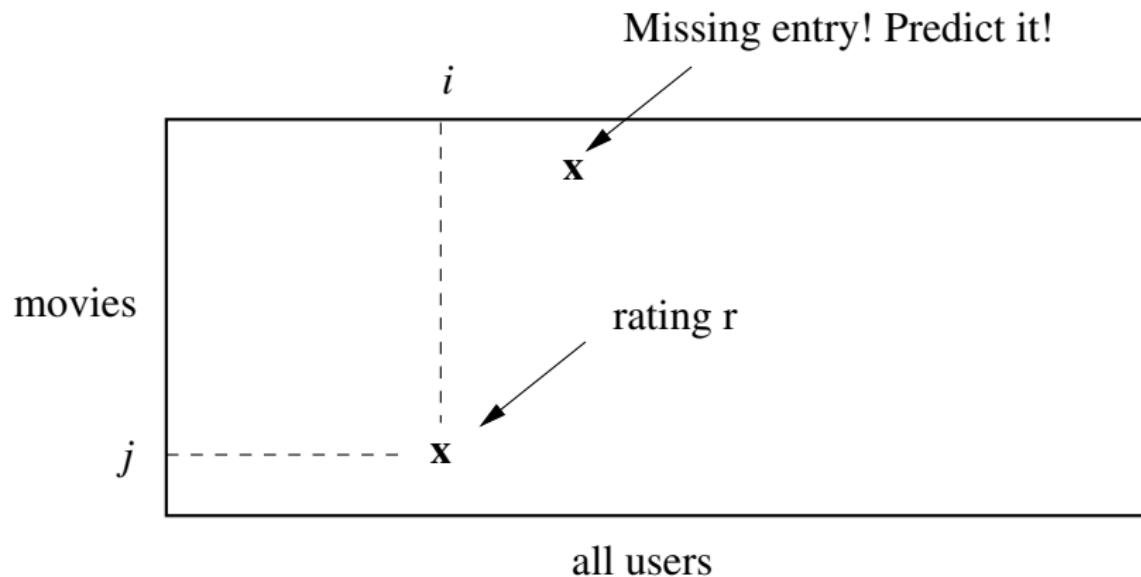
$s_h^{(k)} \leftarrow \sum_r \max_{i,j \in h} |x_i^{(k,r)} - x_j^{(k,r)}|, \forall h \in \mathcal{E}$

**Algebraic distance on hypergraph** :=  $s_h^{(k)}$

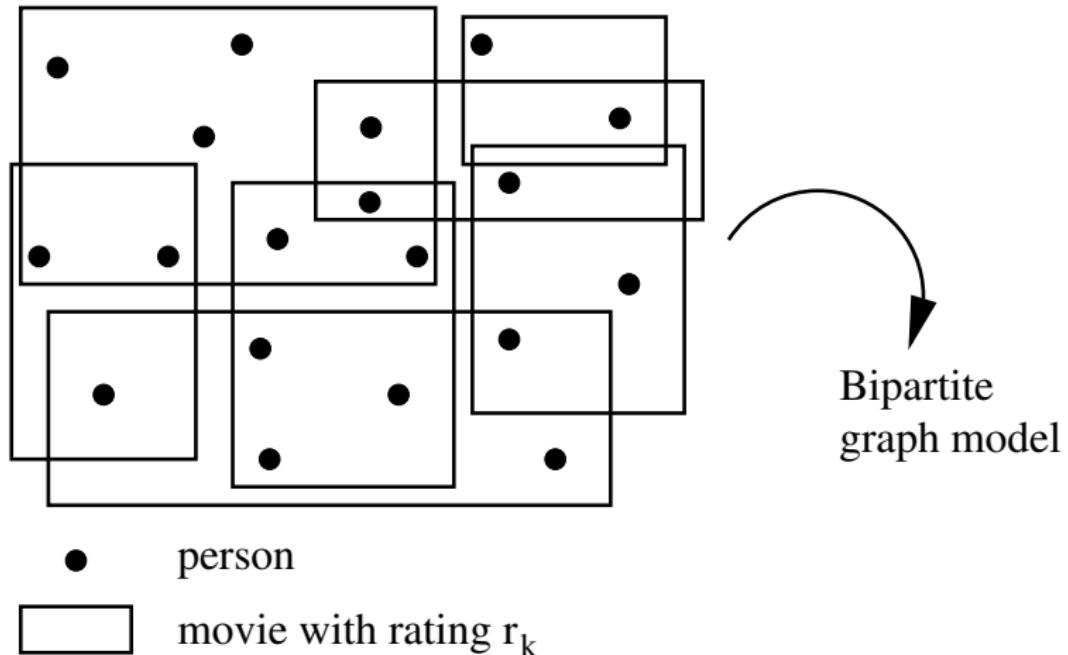
# Experimental results: 2-partitioning of hypergraphs



# Recommendation systems: Netflix problem



# Recommendation systems: hypergraph model



## Preprocessing:

**Input:** Hypergraph  $\mathcal{H}$

**Output:** weights  $s_h^{(k)}$

$G = (V, E) \leftarrow$  bipartite graph model of  $\mathcal{H}$

Calculate algebraic distances for movies

Introduce them as new weights for hyperedges (for example, scale the matrix columns)

# Algebraic distance for recommendation systems

Measure of success is the root mean square error  
(More or less) all SVD-based methods perform similarly on the Netflix database, RMSE $\approx$ 0.90-0.92

# Algebraic distance for recommendation systems

Measure of success is the root mean square error  
(More or less) all SVD-based methods perform similarly on the Netflix database,  $\text{RMSE} \approx 0.90\text{-}0.92$

- Remove 85% of the data

# Algebraic distance for recommendation systems

Measure of success is the root mean square error  
(More or less) all SVD-based methods perform similarly on the Netflix database,  $\text{RMSE} \approx 0.90\text{-}0.92$

- Remove 85% of the data
- SVD-based methods with **linear** combination of latent factors,  $\text{RMSE} > 1.00$

# Algebraic distance for recommendation systems

Measure of success is the root mean square error  
(More or less) all SVD-based methods perform similarly on the Netflix database,  $\text{RMSE} \approx 0.90\text{-}0.92$

- Remove 85% of the data
- SVD-based methods with **linear** combination of latent factors,  $\text{RMSE} > 1.00$
- SVD-based methods with **high-order polynomial** combination of latent factors,  $\text{RMSE} \approx 0.92\text{-}0.94$   
*Roderick, S, "High-order Polynomial Interpolation for Predicting Decisions", 2009*

# Algebraic distance for recommendation systems

Measure of success is the root mean square error  
(More or less) all SVD-based methods perform similarly on the Netflix database,  $\text{RMSE} \approx 0.90\text{-}0.92$

- Remove 85% of the data
- SVD-based methods with **linear** combination of latent factors,  $\text{RMSE} > 1.00$
- SVD-based methods with **high-order polynomial** combination of latent factors,  $\text{RMSE} \approx 0.92\text{-}0.94$   
*Roderick, S, "High-order Polynomial Interpolation for Predicting Decisions", 2009*
- **Algebraic distance + SVD-based methods** with **high-order polynomial** combination of latent factors,  $\text{RMSE} \approx 0.90\text{-}0.92$