

## CURSOR BASED IMPLEMENTATION

- ↳ Combines the best of array & linked list
- ↳ logic is the same as linked list but the data structure is an array.
- ↳ Although it's like an array, no shifting is involved
- ↳ The point of cursor based is to avoid shifting of elements
- ↳ Cursor based also limits the space in where the linked list manipulation takes place.

CURSOR BASED → ARRAY DATASTRUCTURE WITH LINKED LIST MANIPULATION

LINKED LIST

pointer to node

pointer to pointer to node

NULL

vs.

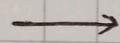
CURSOR BASED

int (index of the array)

int \* (integer pointer)

-1

Linked list



dynamic memory

Cursor Based

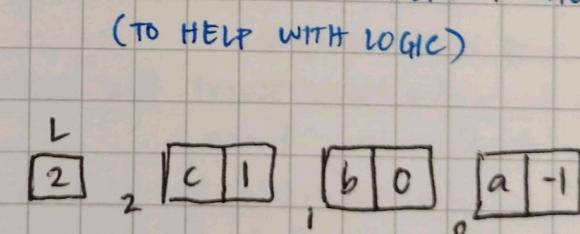


Array cells.

Virtual Heap VH	
arrHeap	
0	[a   1]
1	[b   0]
2	[e   1]
3	[ ]   4]
4	[ ]   1]

List L	
	[2]

L

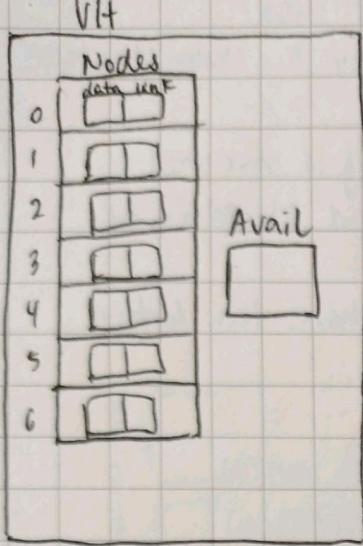


The list looks like a linked list.

Remember: Cursor Based logic

Follows linked list logic.

## ON ACCESSING :



```
# define MAX 7
typedef struct {
    char data;
    int link;
} nodetype;
```

```
typedef struct {
    nodetype Nodes[MAX];
    int Avail;
} VirtualHeap;
```

NAME	DATATYPE	ACCESSING	EXAMPLES
VH	STRUCTURE	.	VH.Nodes
VH.Nodes	Array	[ ]	VH.Nodes [x-1]
VH.Nodes [x-1]	STRUCTURE	.	VH.Nodes [x-1].link
VH.Nodes [x-1].link	INTEGER	.	

## ON CODE EFFICIENCY :

What makes code efficient?

\* conciseness

↳ how short the code looks

\* Running time

↳ affected by how many variables need to be initialized

\* Space

↳ how many allocations does the code need?

The different datastructures manipulate space in different ways.

## CURSOR-BASED MANAGEMENT FUNCTIONS

### ① INITIALIZING THE VIRTUAL HEAP

↳ to link all the nodes (array cells) together

### ② ALLOC SPACE $\approx$ malloc() $\approx$ deleteFirstNode

↳ TAKING THE FIRST AVAILABLE NODE &  
RETURNING IT TO THE CALLING FUNCTION  
(the node that was taken from the virtual heap  
acts as new space allocated to be used by the  
calling function.)

### ③ DEALLOC SPACE $\approx$ free() $\approx$ insertFirstNode()

↳ THE INDEX OF THE NODE IN THE FUNCTION CALL  
WILL BE RETURNED TO THE LIST OF AVAILABLE  
NODES IN THE VIRTUAL HEAP.

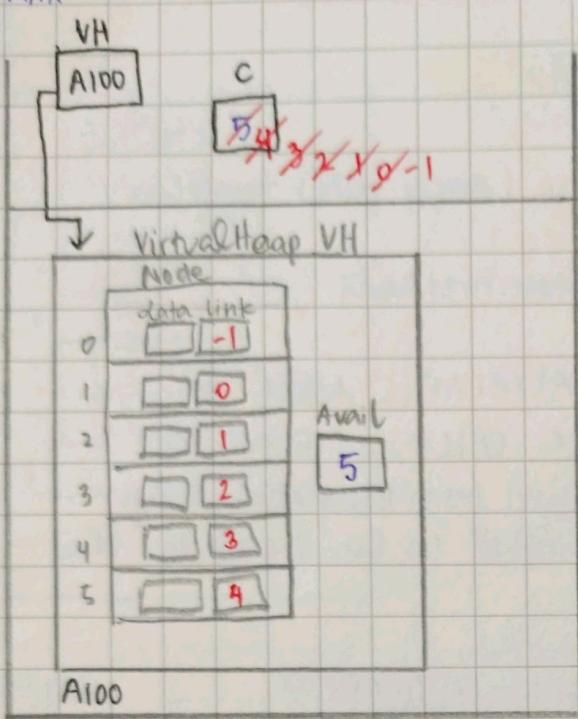
### ① INITIALIZING THE VIRTUAL HEAP

```
void initializeVirtualHeap (VirtualHeap * VH) { // pass by address
    int c; // initializing a counter
    to represent the indexes
    of the array
    because we're changing values
    inside the virtual heap
    VH->Avail = MAX - 1; // assigning the index of the
    first available node in the virtual heap
    for (c = VH->Avail; c >= 0; c--) {
        VH->Nodes[c].link = c - 1;
    }
}
```

loop to assign values of  
the link portion in each  
array cell to link to the  
next available cell

## initializeVirtualHeap() SIMULATION

MAX = 6



AR of initializeVirtualHeap()

AR of main()

initializeVirtualHeap(&VH);

A100

## ② ALLOCSPACE (DELETING FIRST AVAILABLE NODE)

↳ returns the index of the first available node, which will no longer be part of the available nodes in the virtual heap.  
Returns -1 (or the sentinel value if list is empty).

index or sentinel value

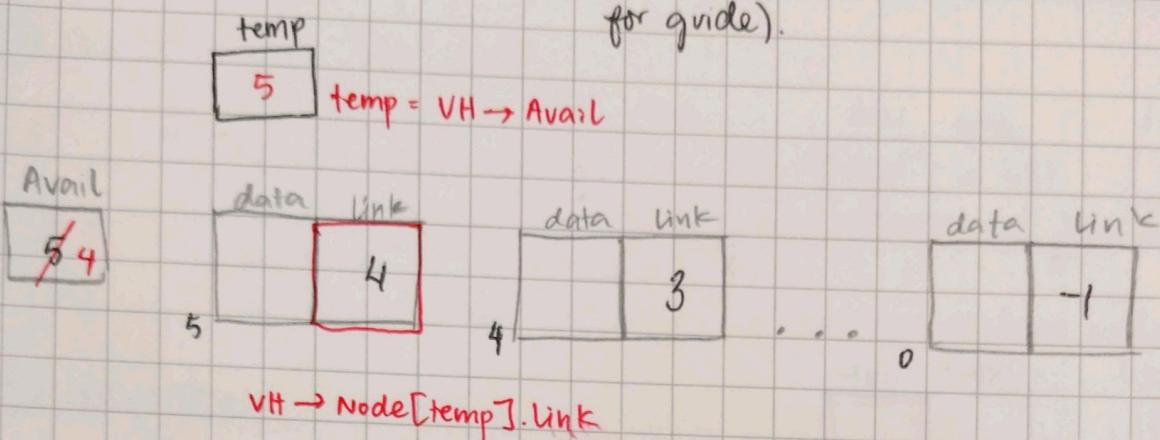
```
int allocSpace (VirtualHeap * VH) { // pass by address, obviously
    int temp = VH->Avail; // temp holds index of node to be deleted
    if (temp != -1) {
        // checks if list of Avail is empty
    }
}
```

VH → Avail = VH → Node [temp].link;

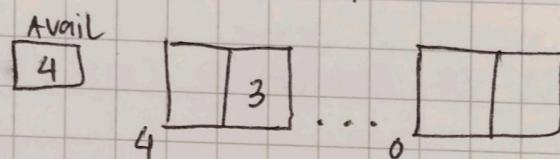
↳ let Avail point to the next available node,  
the index stored in the link of the temp  
index

```
} // returns the index of the deleted node,
// ready to be used by the calling function.
```

allocSpace() ILLUSTRATION (not actual representation, strictly for guide).



RESULTING LIST OF AVAILABLE CELLS/ NODES



### ③ DEALLOCSPACE (INSERTING A NODE/ CELL BACK INTO THE VIRTUAL HEAP)

↳ given an index, it will insert a cell with the same index back into the virtual heap, so that it belongs to the list of available nodes

void deallocateSpace (VirtualHeap \* VH, int index) {

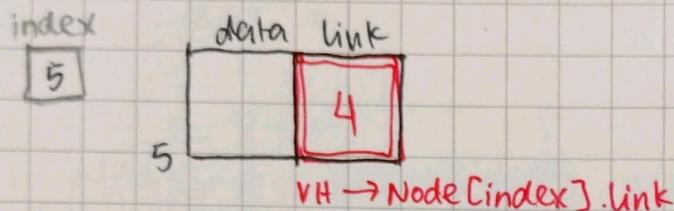
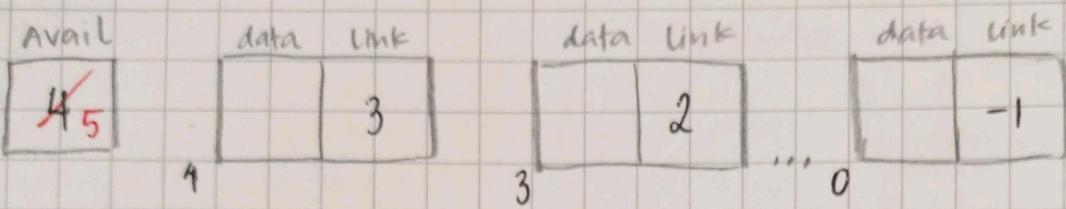
VH → Node [index].link = VH → Avail;

↳ connects new node (cell) to the next available node (which is the index stored in Avail)

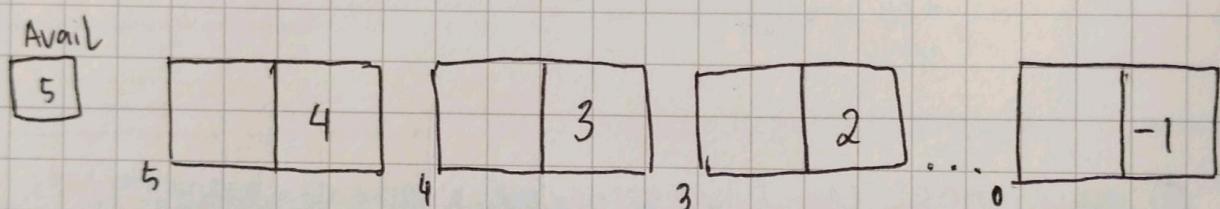
VH → Avail = index;

↳ Assigns the index to avail where it can be accessed as part of the list of available nodes.

## deallocSpace () ILLUSTRATION



RESULTING LIST OF AVAILABLE CELLS / NODES



## ADT LIST OPERATIONS - CURSOR BASED EDITION

### ① INITIALIZING THE LIST

- ↳ in cursor implementation, the list "head" is just an integer. In linked list, we initialize a list by pointing it to NULL.  
In cursor based, NULL is -1 (or any sentinel value)

### ② INSERTION

- ↳ literally a translation from linked list insertion functions. PPN vs. pointer to integer

### ③ DELETION

- ↳ also LL translation. PPN vs. pointer to integer

### ④ DISPLAY

- ↳ LL translation. PN vs. integer.

## ADT LIST OPERATIONS - LL. VS. CURSOR BASED

### INSERT

#### LINKED LIST

- `temp = (LIST) malloc (size of (struct node))`
- `temp → data = elem`
- `temp → link = * trav`  
pointer-pointer-node
- `* trav = temp;`  
dynamically allocated  
node address

#### CURSOR BASED

- `temp = allocSpace (VH)`
- `VH → Node [temp]. data = elem`
- `VH → Node [temp]. link = * trav`  
pointer to integer
- `* trav = temp;`  
index of array

## DELETE

### LINKED LIST

- $\text{temp} = * \text{trav}$   
 $\text{trav} = \text{PPN}$
- $* \text{trav} = \text{temp} \rightarrow \text{link}$

- $\text{free}(\text{temp})$

dynamically allocated  
location in memory i.e node

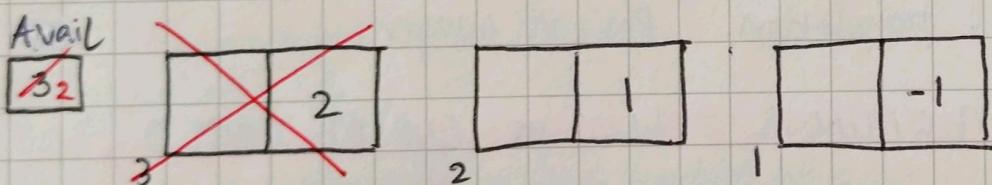
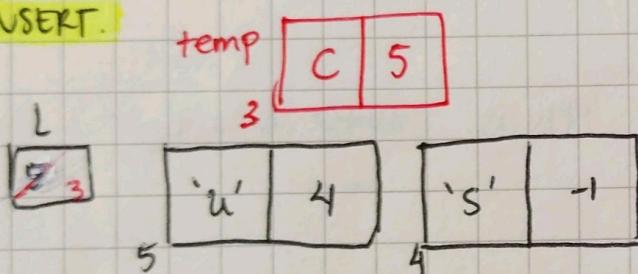
## CURSOR-BASED

- $\text{temp} = * \text{trav}$   
 $\text{trav} = \text{pointer to integer}$
- $* \text{trav} = \text{VH} \rightarrow \text{head}[\text{temp}], \text{link}$

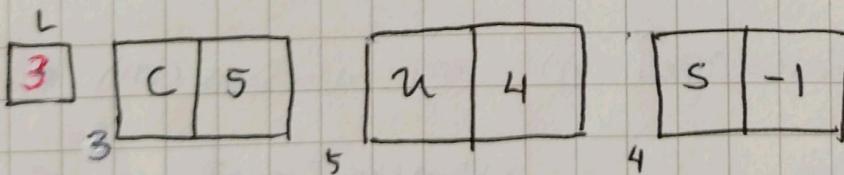
- $\text{deallocSpace}(\text{VH}, \text{temp});$   
integer, index  
of array

## ILLUSTRATIONS

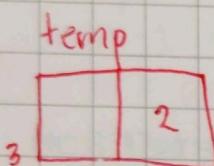
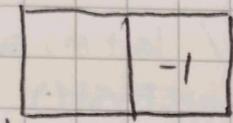
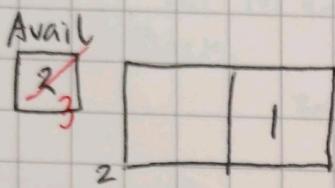
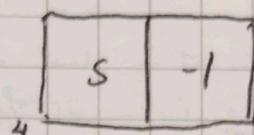
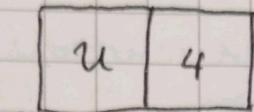
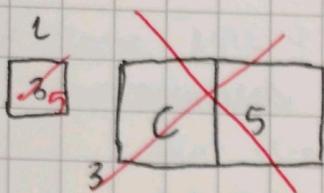
### INSERT.



### RESULTING LIST.



**DELETE.**



**RESULTING LIST:**

