# **Matthew Strong**

(720)-626-4057 mast4878@colorado.edu github.com/peasant98 linkedin.com/in/matthewhstrong

#### **ENGINEERING EXPERIENCE**

### **Co-Founder and CTO**, Boulder CO — *Udana Systems*

February 2018 - Present

Udana Systems is developing fully autonomous drone delivery targeting small to medium retail and food businesses. I lead development on the most intensive engineering tasks and additionally architect our machine learning and embedded systems integration. Our product is still in development.

# **Undergraduate Research Assistant,** Boulder CO — HIRO Robotics Group

Sep 2019 - Present

Research assistant at HIRO (Human Interaction and RObotics). Currently developing Franka Robot integration for our own low level controller with control down to inverse kinematics.

# **Software Engineer Intern,** Redmond WA — *Microsoft*

May 2019 - August 2019

Developed and Deployed Global Search for Dynamics 365 For Talent. Implemented an end-to-end feature with Angular and Typescript (frontend), C# (backend), and XML (entity schema).

#### **EDUCATION**

# **University of Colorado Boulder** — Computer Science, BS

August 2017 - Present

**4.0 Overall GPA**, BOLD Scholar and Sewall Scholar

**Relevant Coursework:** Advanced Data Science, Intro to Robotics, Algorithms, Data Structures, Operating Systems, Computer Systems, Data Science Team

#### **Skills**

**Languages:** Python, C++, C#, C, Go, Javascript, Typescript, HTML, CSS, Dart, Bash, SQL

**Frameworks:** ROS, Tensorflow, Keras, MAVROS, Django, Vue.js, Angular, Flutter, ASP.Net MVC

**Miscellaneous:** Linux, Git, Docker, ArduPilot, ArduCopter, OpenCV, Machine Learning, Computer Vision, Airsim

#### **PROJECTS**

## Udana AI Engine Udana Systems

Python, Tensorflow, Keras, Docker

A comprehensive machine learning suite built with Tensorflow and Keras for our computer vision needs.

# **ArduCopter Teleoperations,** *Personal Project*

C++, ROS, ArduCopter, MAVROS

Developed a user-controlled system from scratch with MAVROS and ROS for ArduCopter non-RC control.

Tested both in simulation (Gazebo/Microsoft Airsim) and a real drone.

# Neural Network, Personal Project

Python, Numpy

Developed a neural network from scratch in Python. 98% success rate on handwritten digits data.

### **Bike Buddy**, Group Project

Django, Flutter, Raspberry Pi/Arduino, Jekyll

An app allowing users to virtually lock their bikes, causing an alarm to sound and a notification if the bike is moved. Included a custom API, Flutter frontend, and embedded system portion where bikes can be equipped with a GPS, Raspberry Pi, and Arduino.

# NBA SVR and SVC, Personal Project

Python, Numpy

Predicts NBA records based on conference and division, and predicts position based on height and weight.