



Probabilistic Logic Programming with Fusemate: Main Ideas and Recent Developments

Peter Baumgartner

CSIRO/Data61 (StatML)
ANU CECC

About

- PhD in 1996 in Germany, on Automated Reasoning
- NICTA 2005, CSIRO since 2014

Research Interest

Knowledge representation and reasoning

Designing inference systems

Applications

D61 Applications



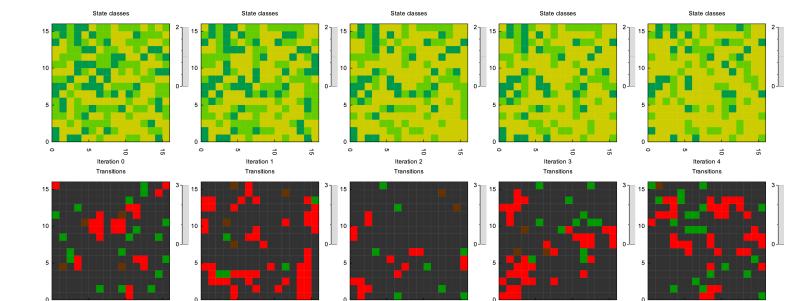
Computer Factory



Factory floor



Taxi rides in NYC

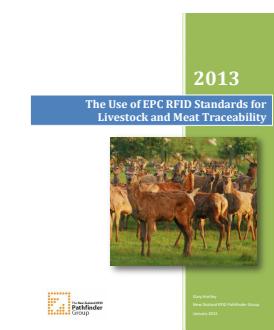


Valuing Sustainability - Future states

Recently

Probabilistic Logic Programming (PLP)

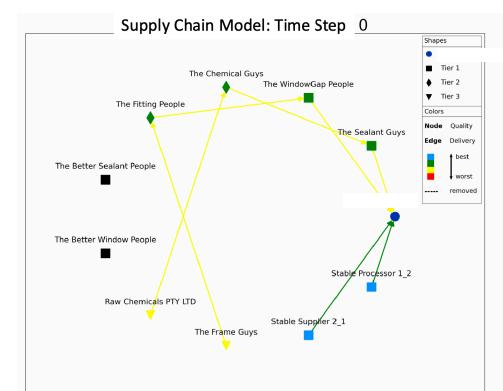
Combination with LLM (with Lachlan McGinness)



Food supply chain



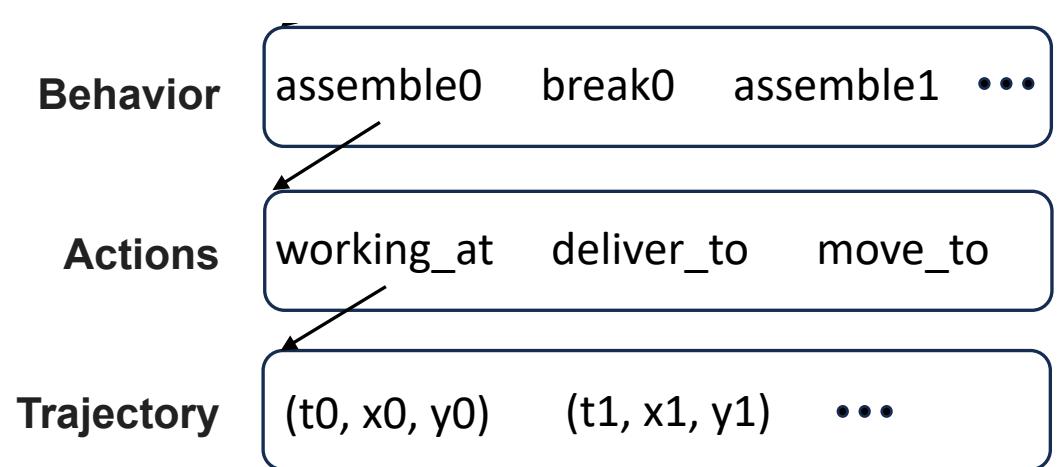
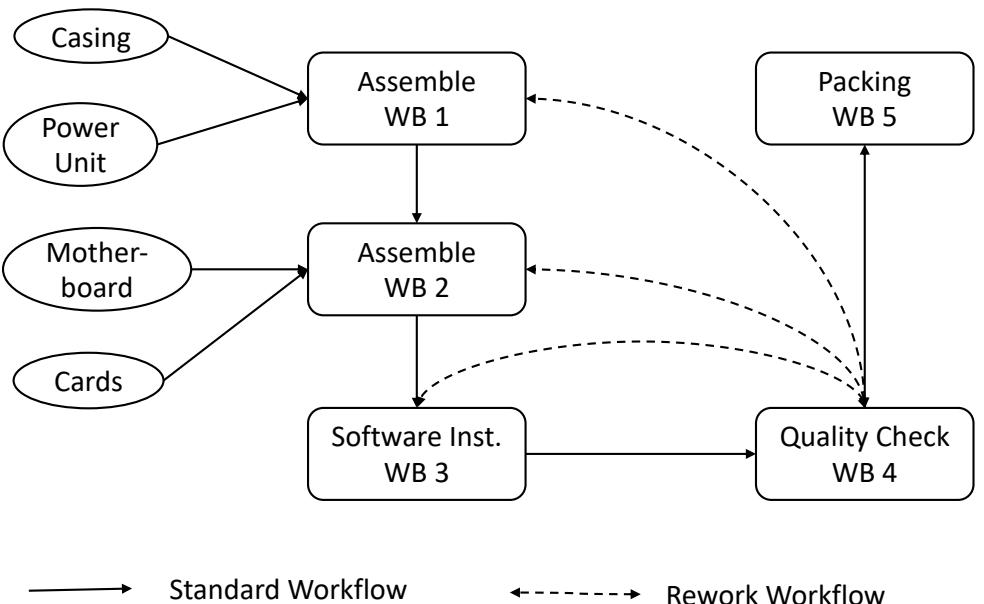
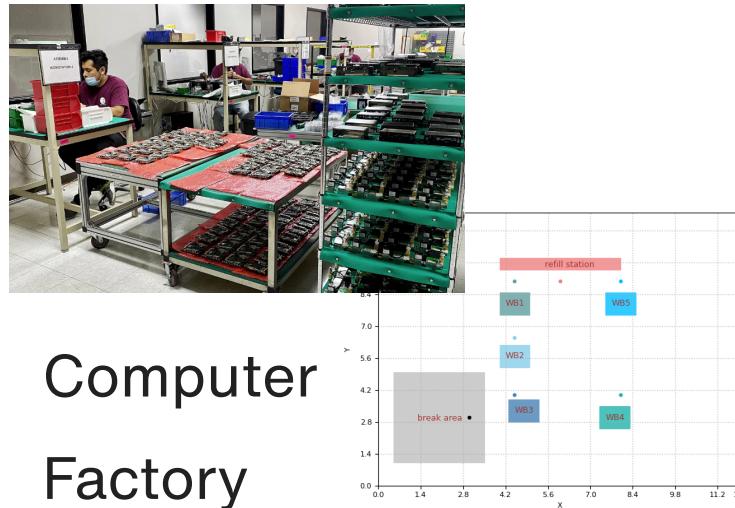
Beef supply chain



Factory supply chain

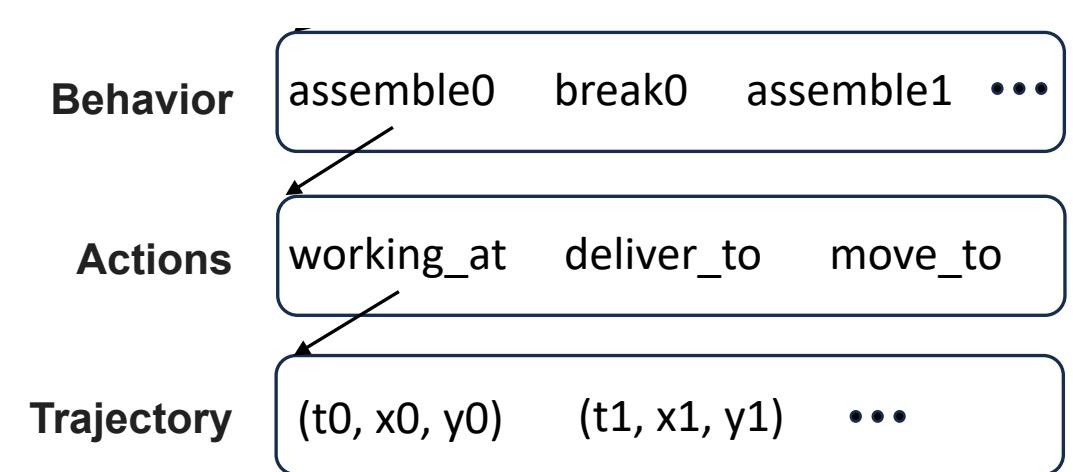
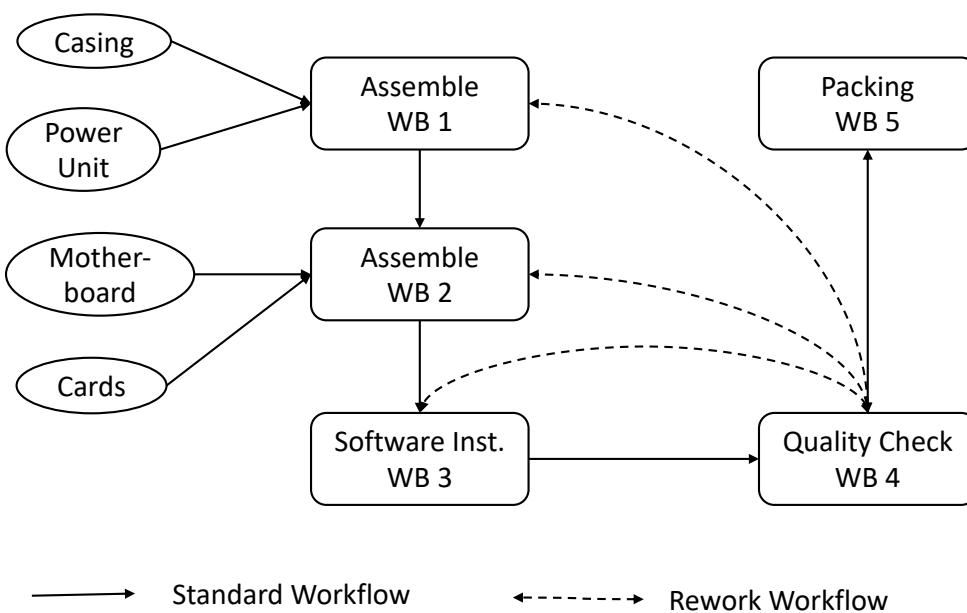
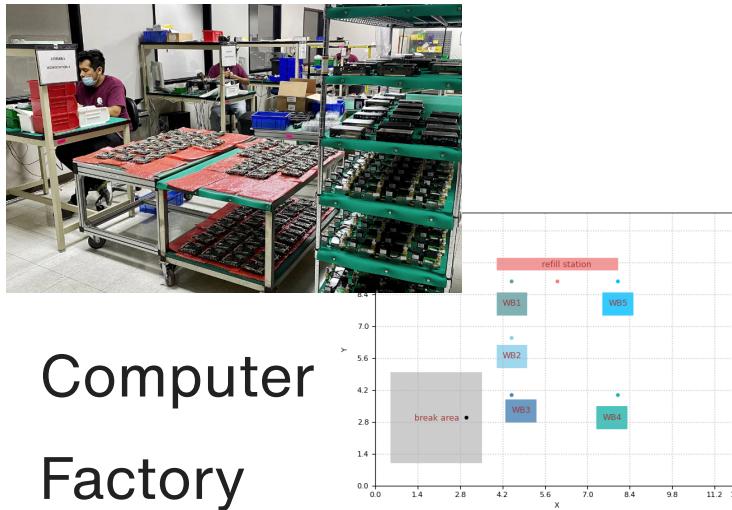
States - Transitions - Uncertainty

TLDR; Computer Factory Example (FDMF)



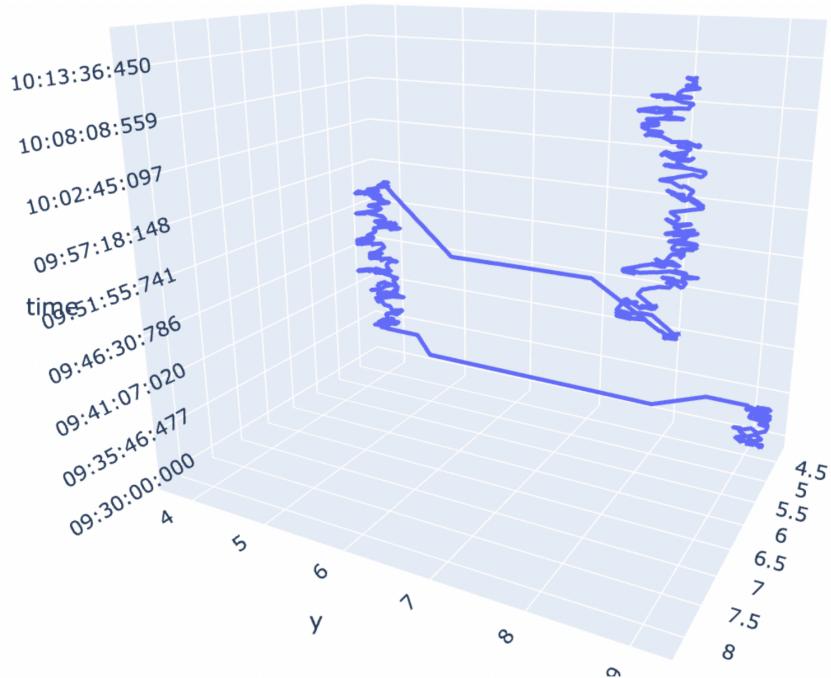
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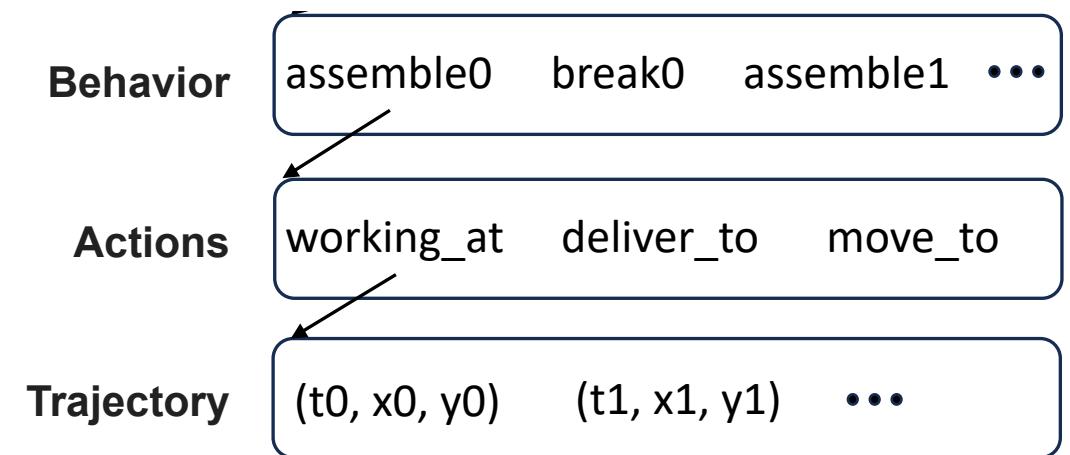
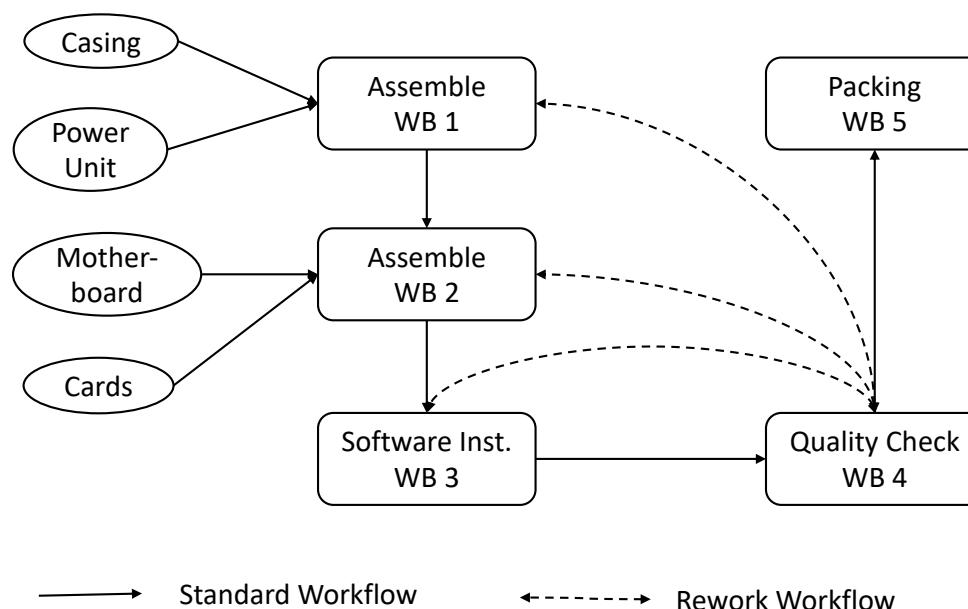
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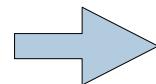


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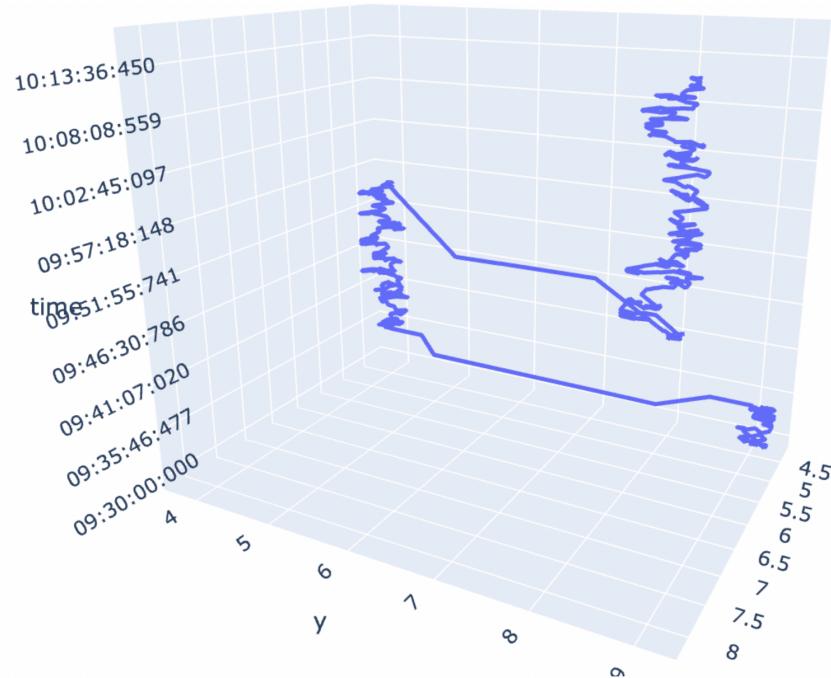


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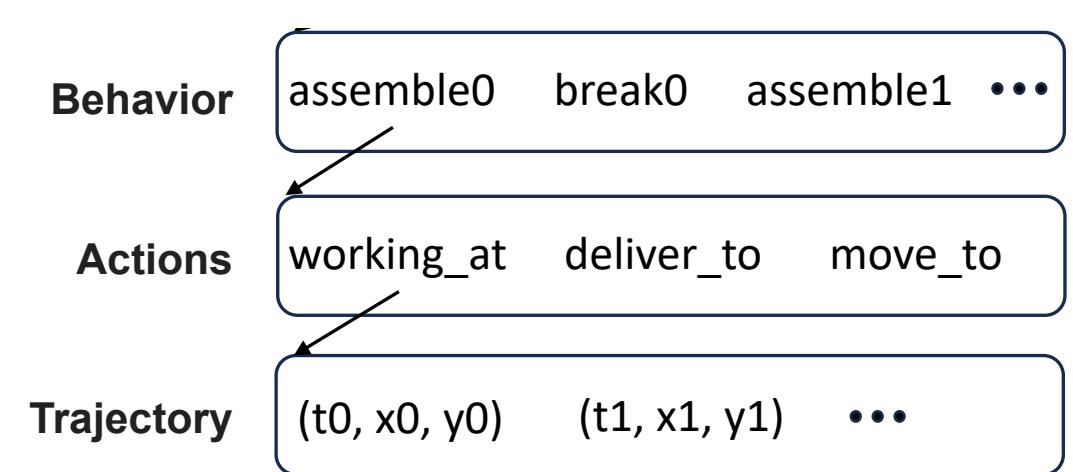
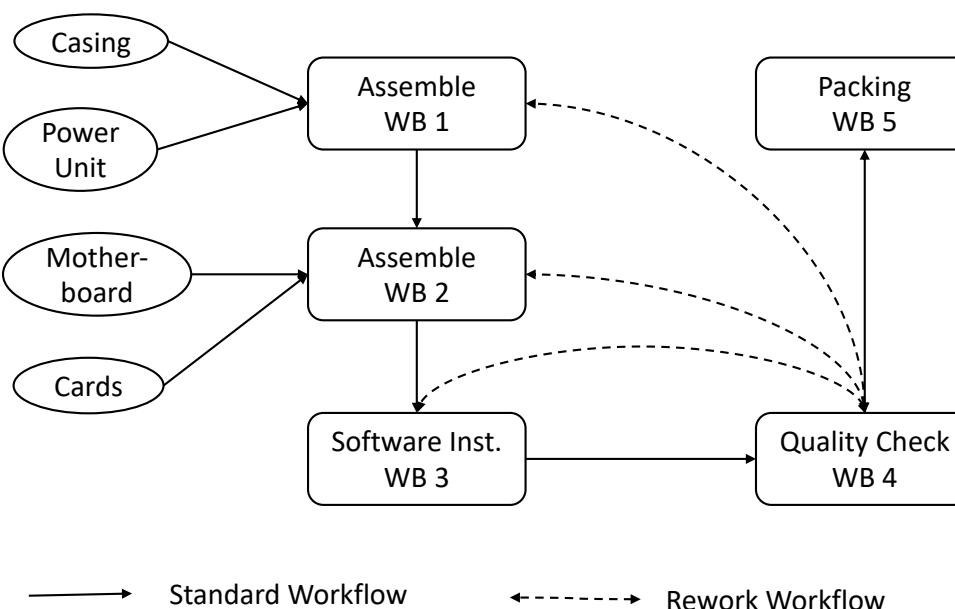
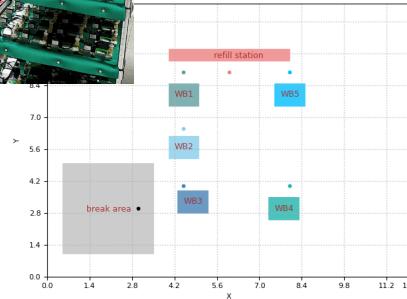
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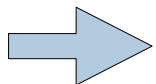


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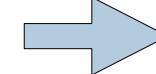


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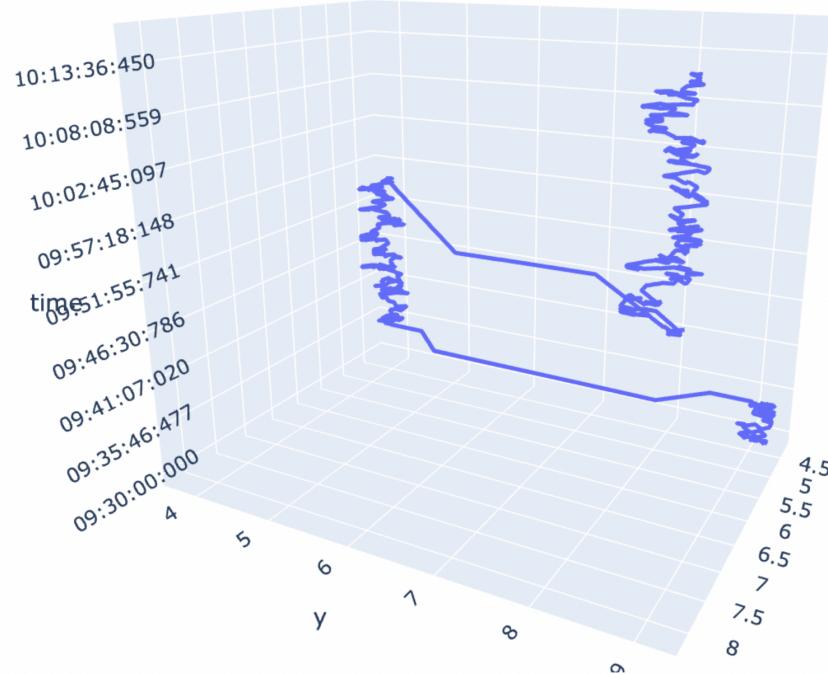


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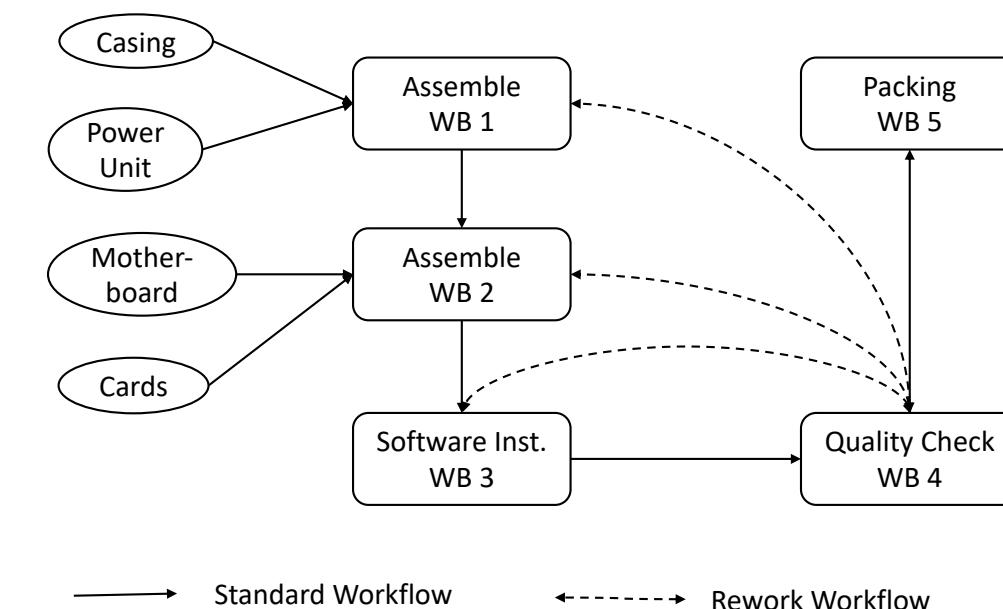
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Behavior

assemble0 break0 assemble1 ...

Actions

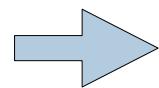
working_at deliver_to move_to

Trajectory

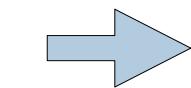
(t0, x0, y0) (t1, x1, y1) ...

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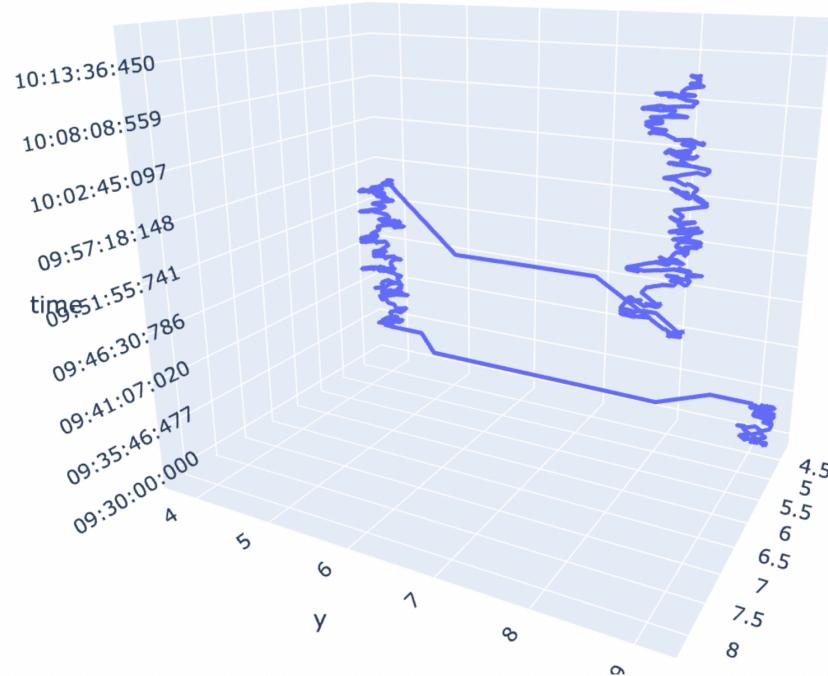


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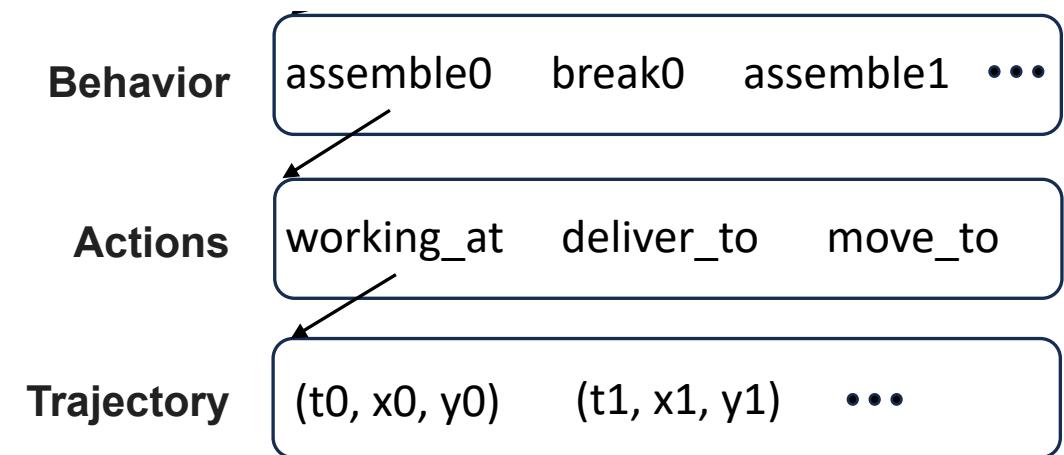
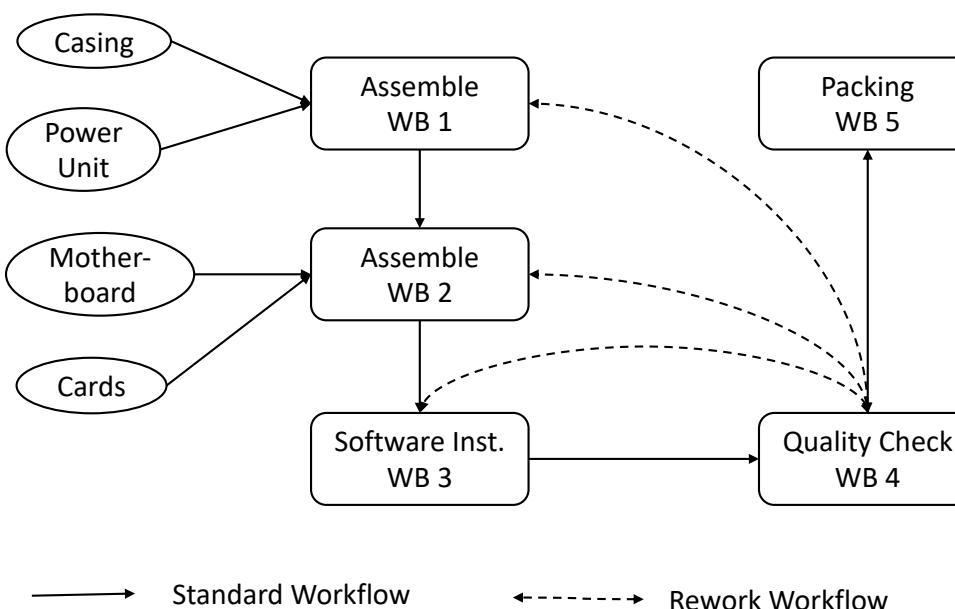
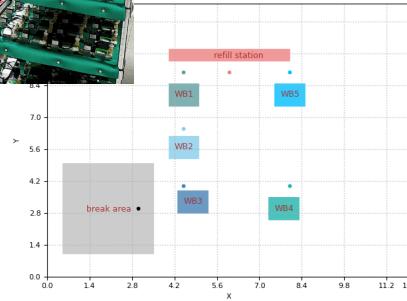
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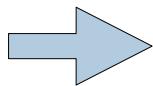


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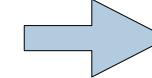


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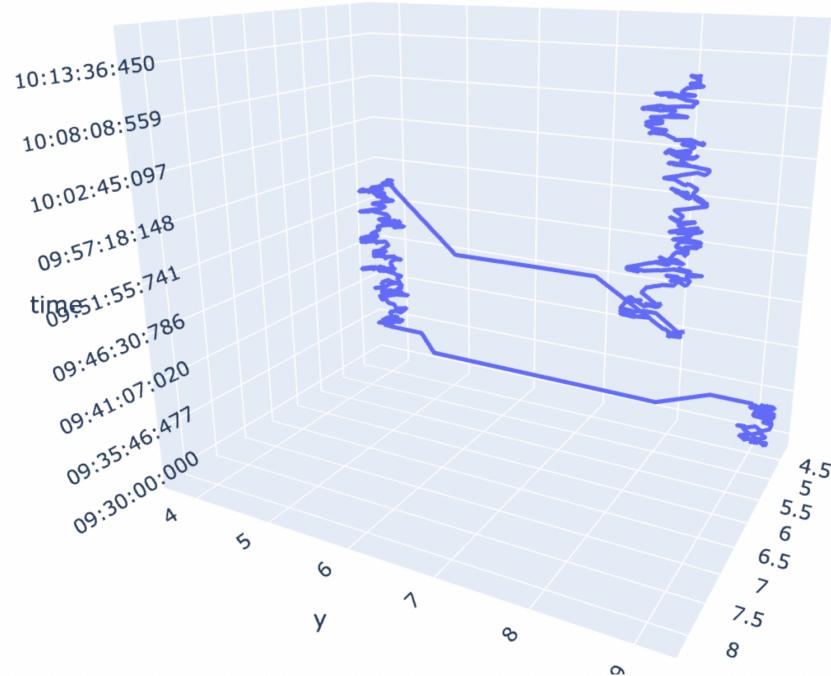


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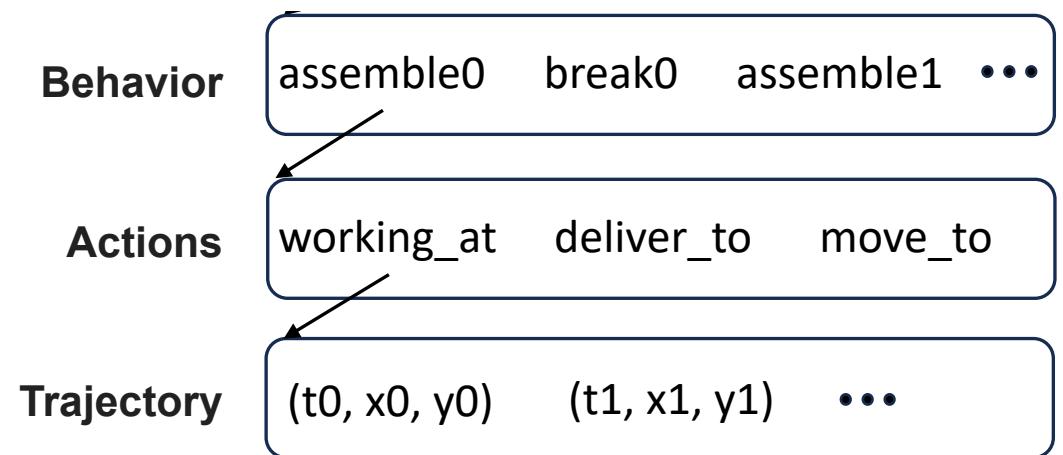
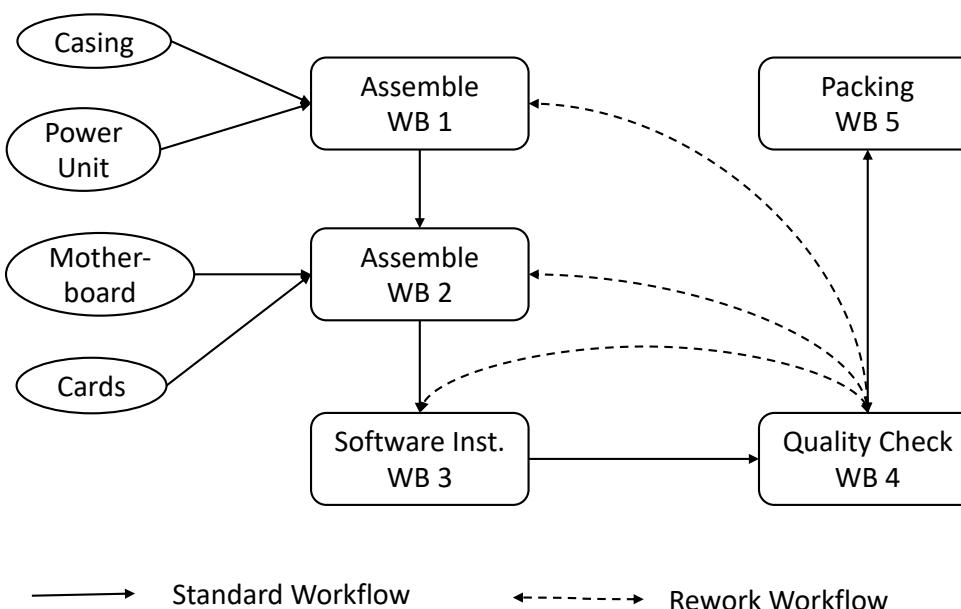
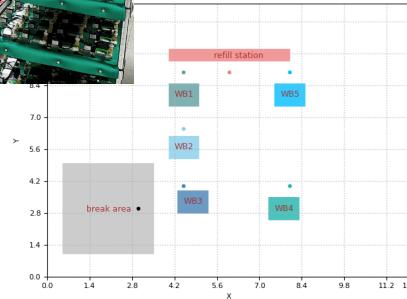
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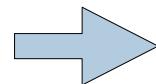


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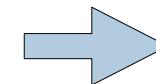


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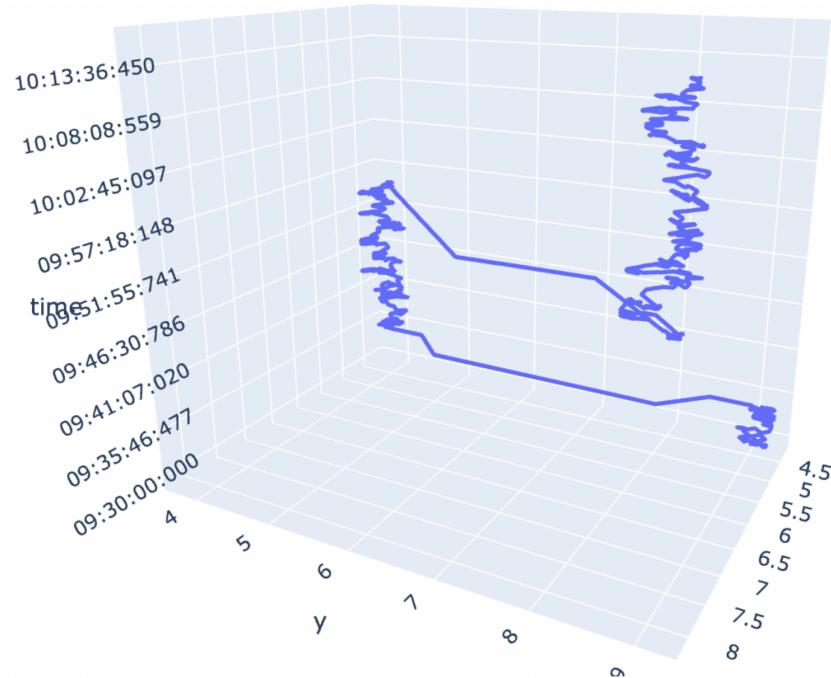


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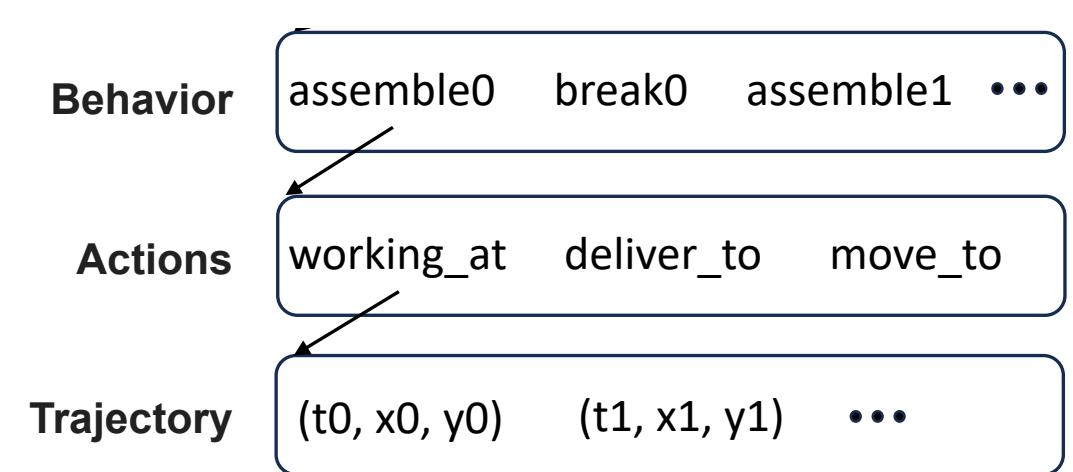
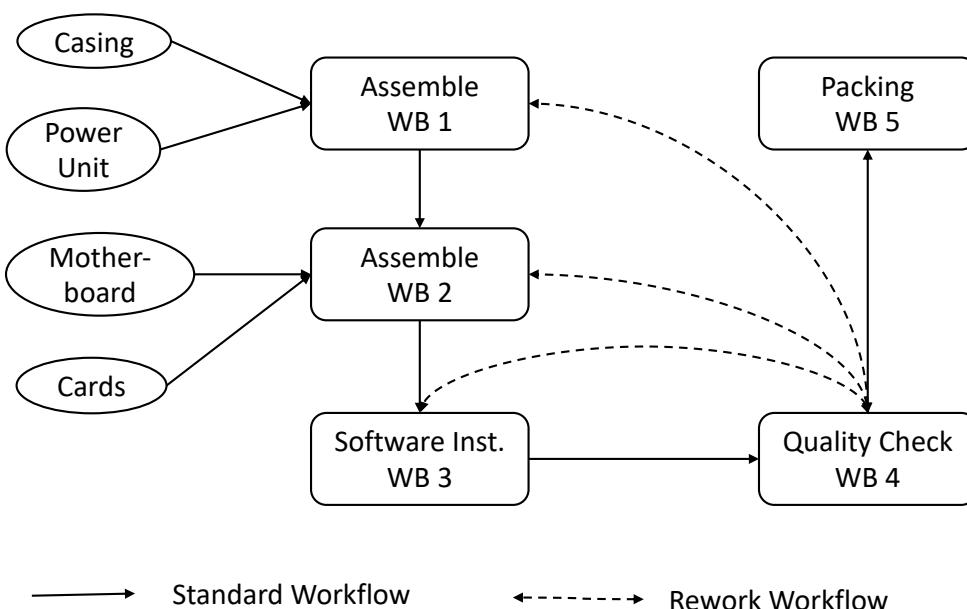
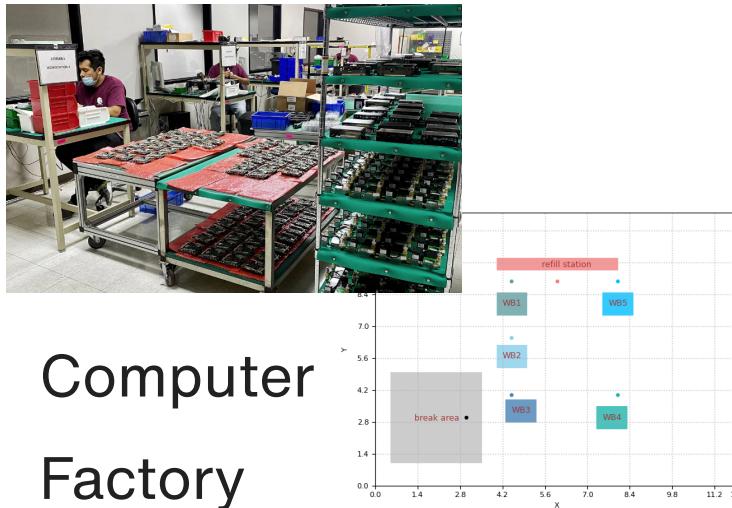
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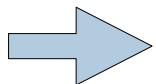
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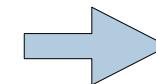


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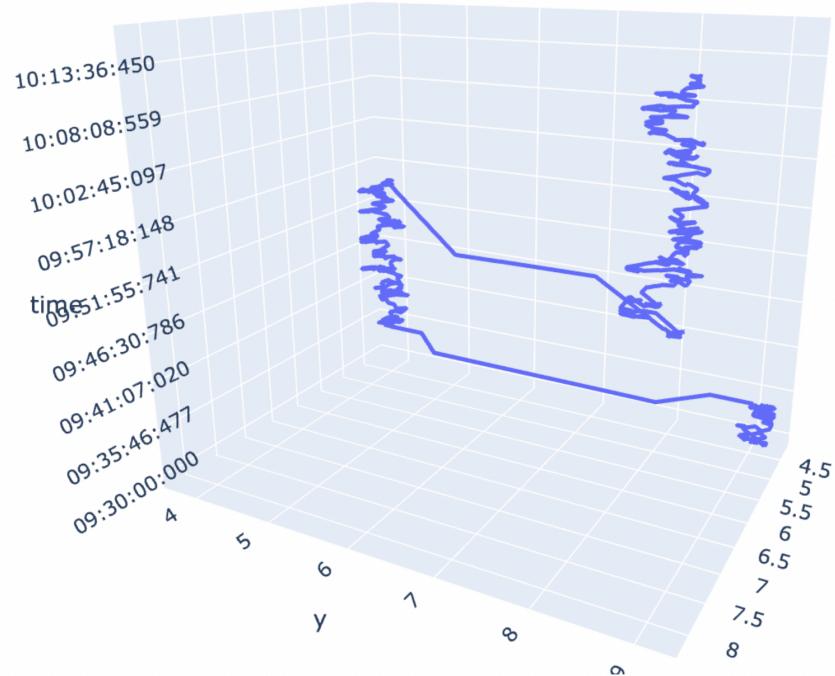


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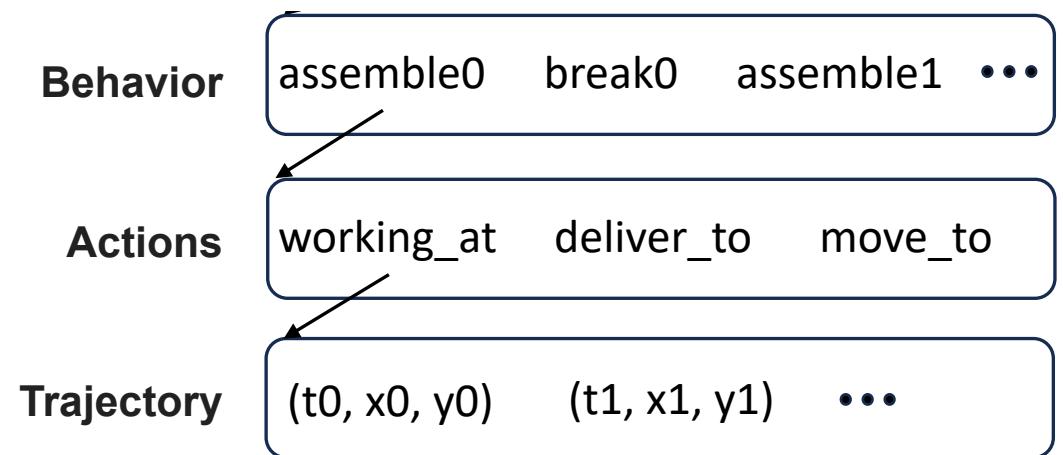
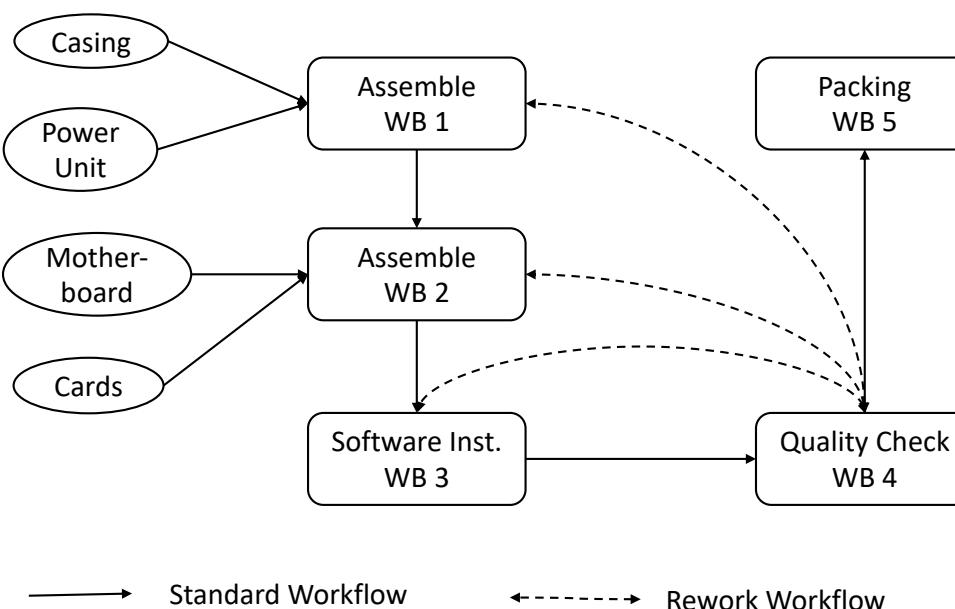
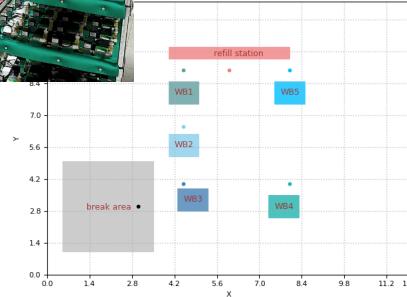
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Hidden Markov Model

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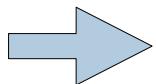


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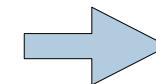


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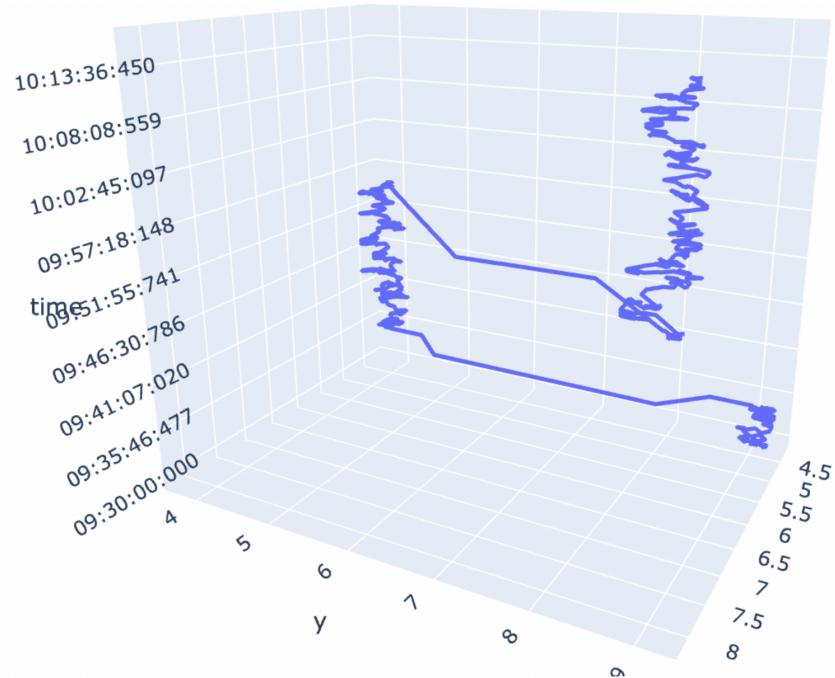


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Hidden Markov Model

PLP can do much more!

Part 1

- Probabilistic
- Logic
- Programming
- **Fusemate Implementation**

Part 2

- LLMs + Logic (Programming)
- Neural Networks + Logic (Programming)

Logic

“Algorithm = Logic + Control”

- Model the problem at hand with “logic”
- Feed into automated reasoning system
- Push button and get solution

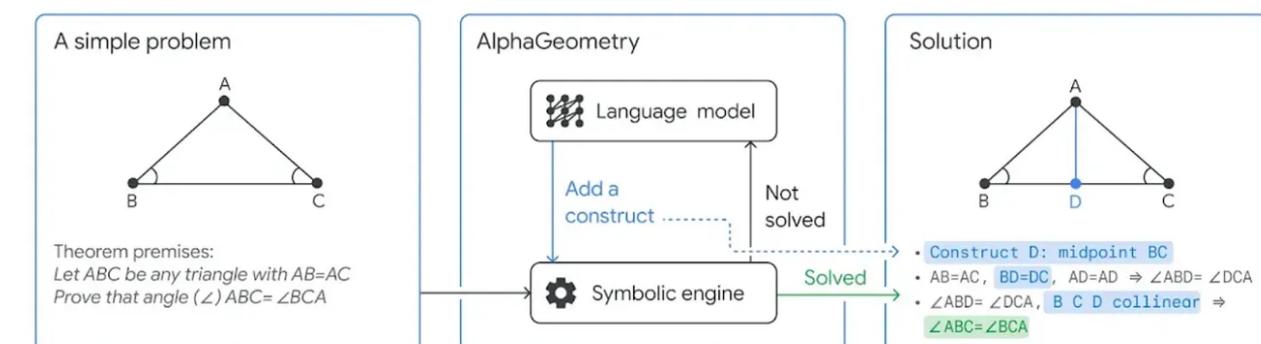
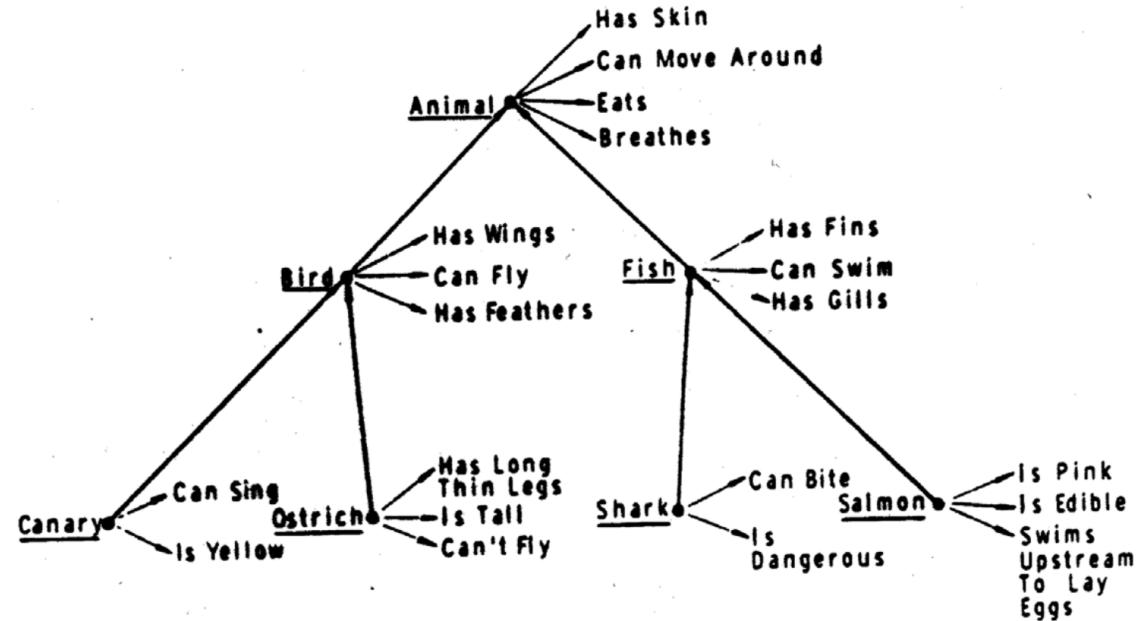
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Classical
Non-monotonic
Modal
Probabilistic
Temporal
Graphs (Ontologies)
Relational (Tables)
Built-in Theories

Reasoning Tasks

Proving
Disproving
Query answering
Model computation
Knowledge Completion
Diagnosis

flight(toronto, london).
flight(london, rome).
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flight(X, Y) :- flight(X, Z), flight(Z, Y).



AlphaGeometry, AlphaProof, LLM-modulo, ...

Relational

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Neuro-Symbolic

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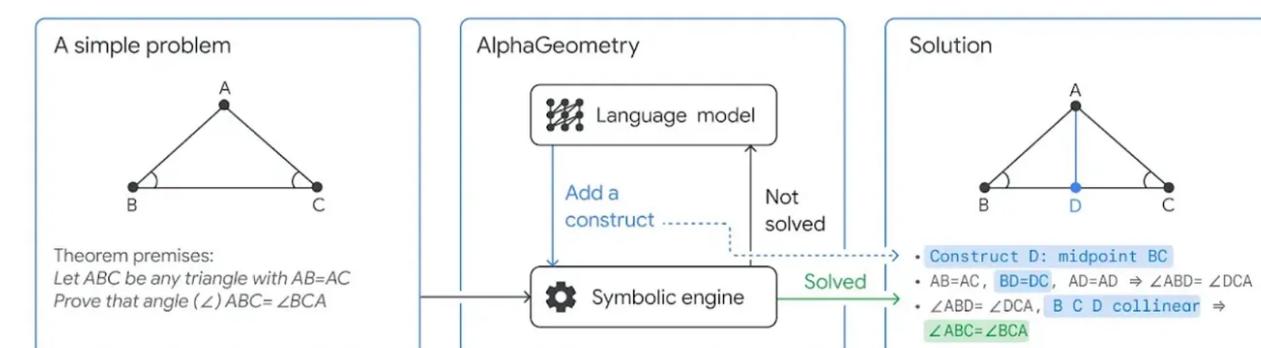
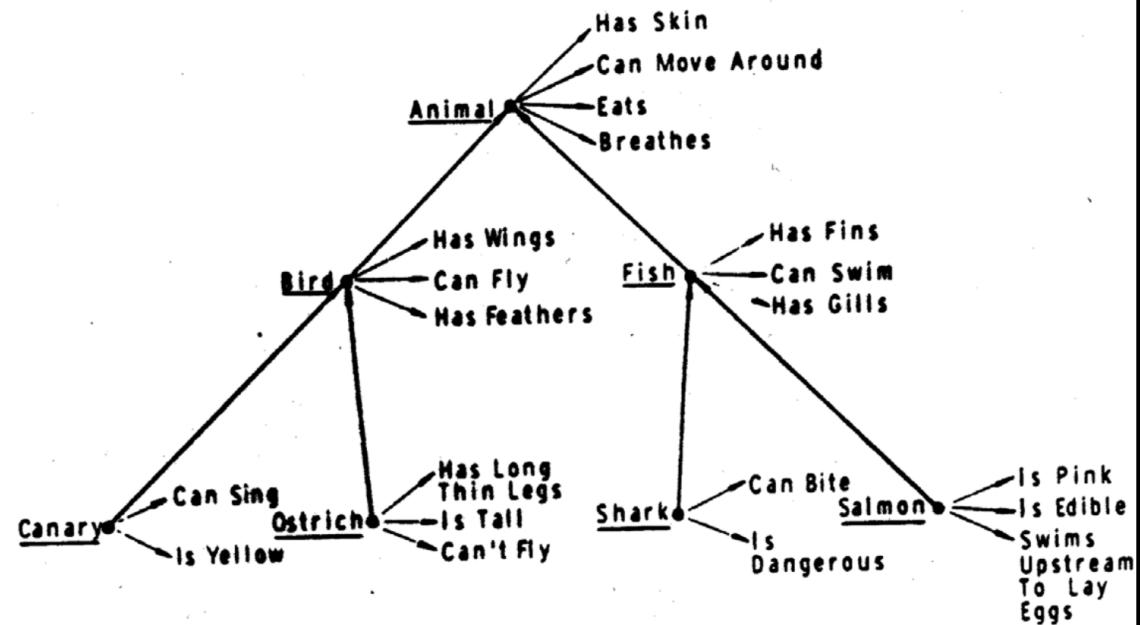
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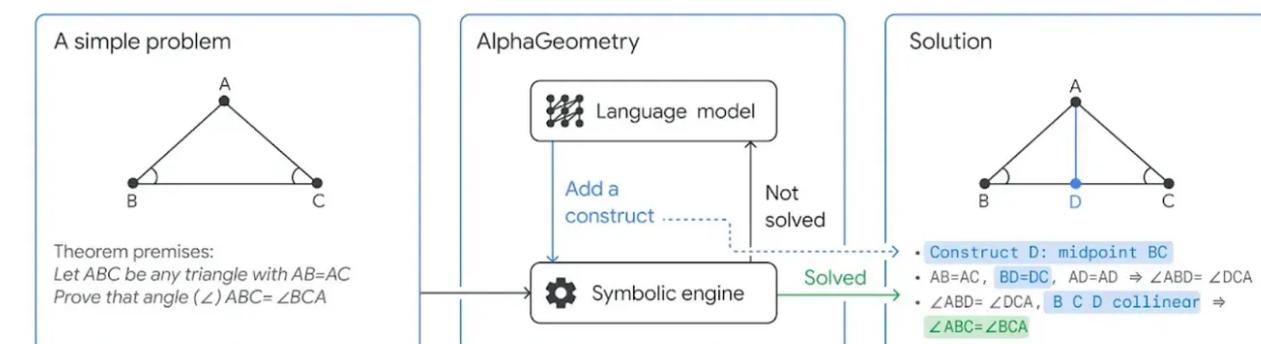
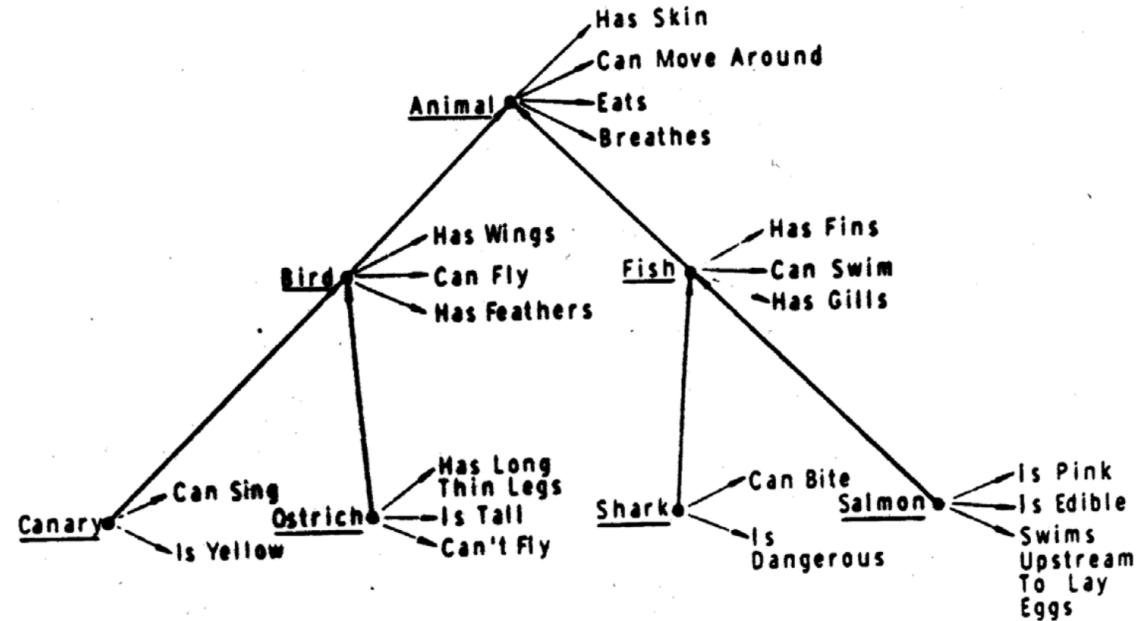
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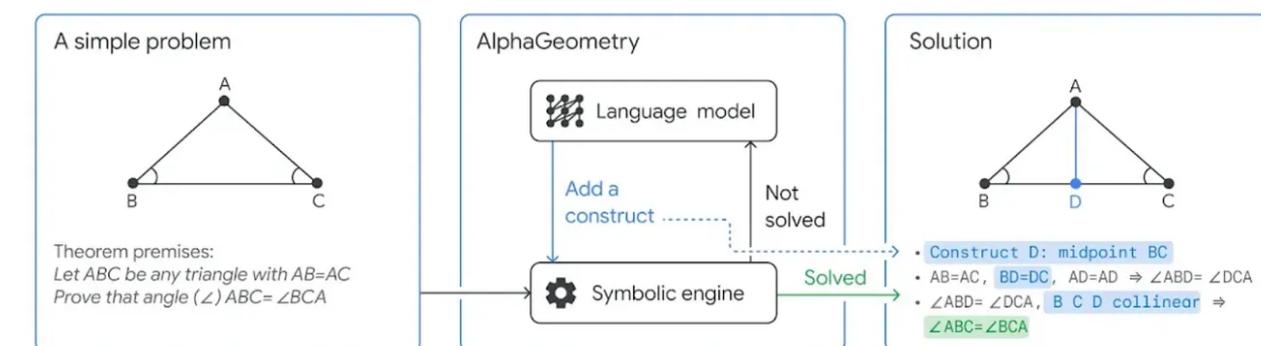
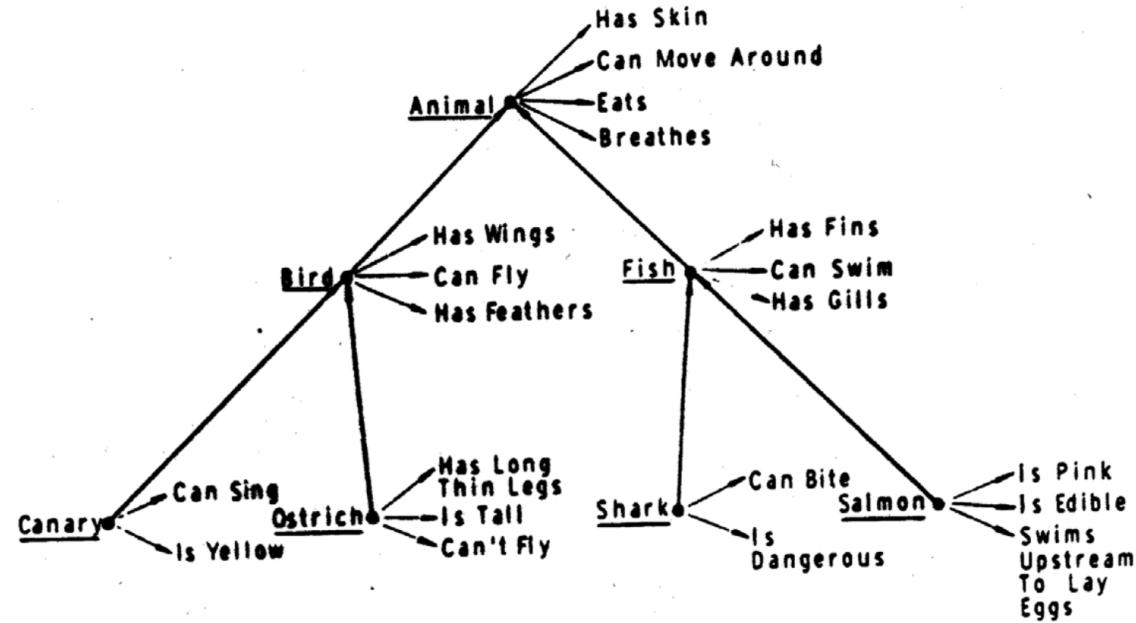
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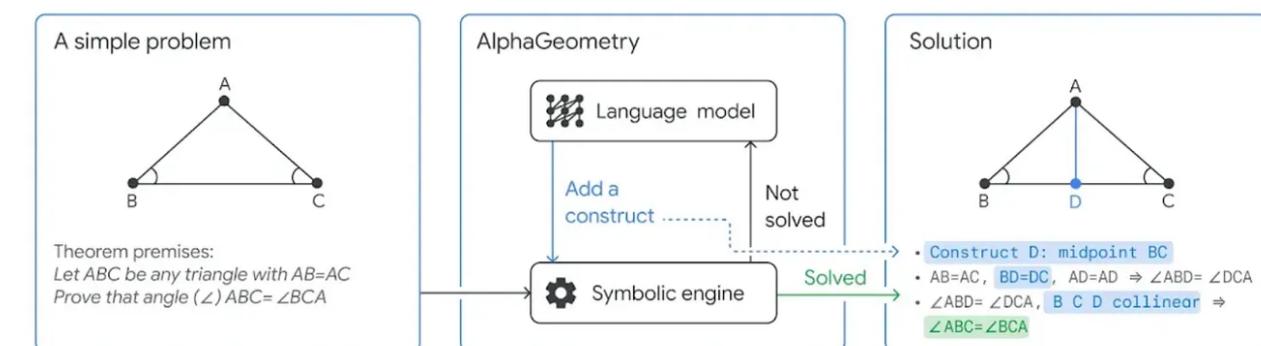
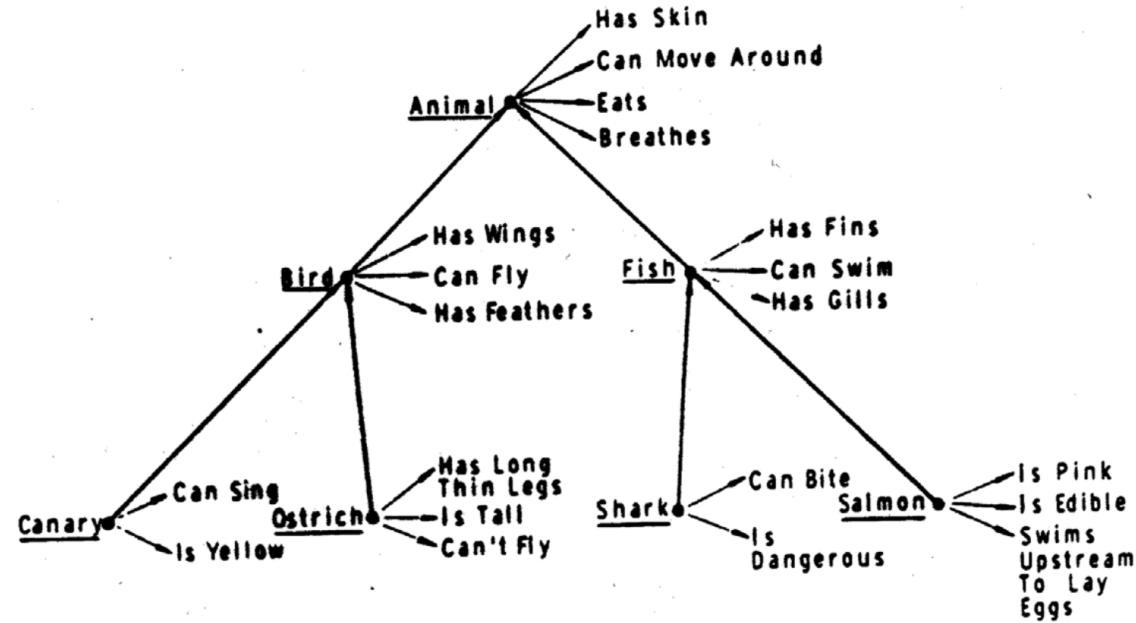
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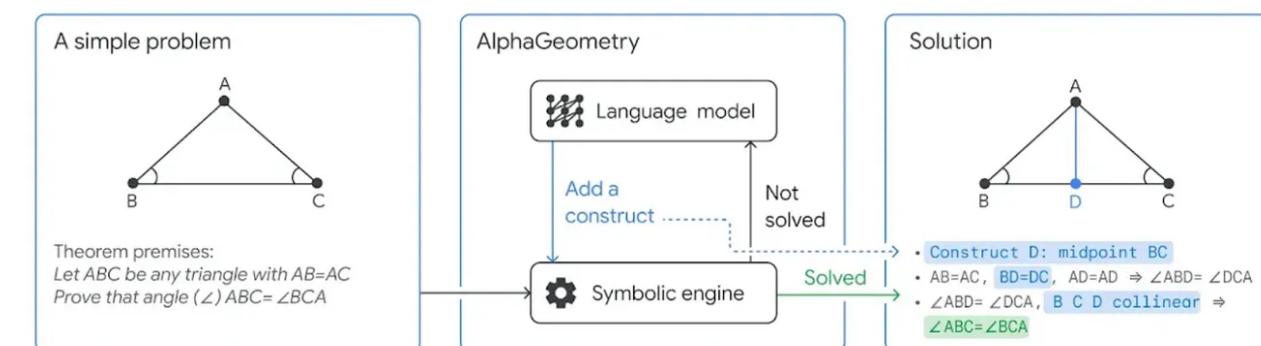
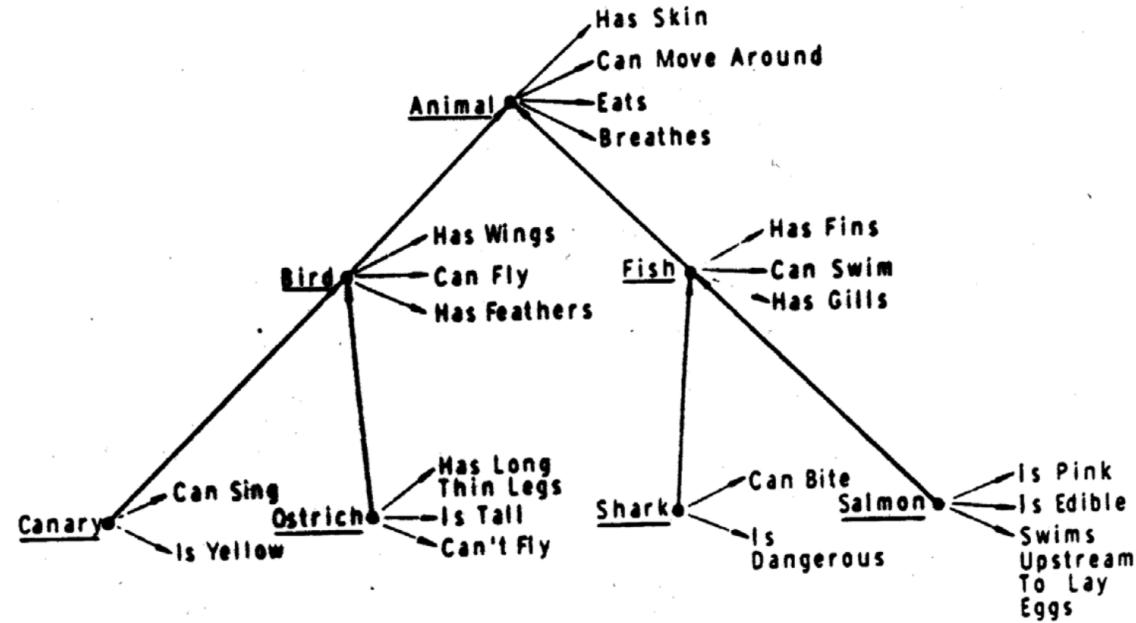
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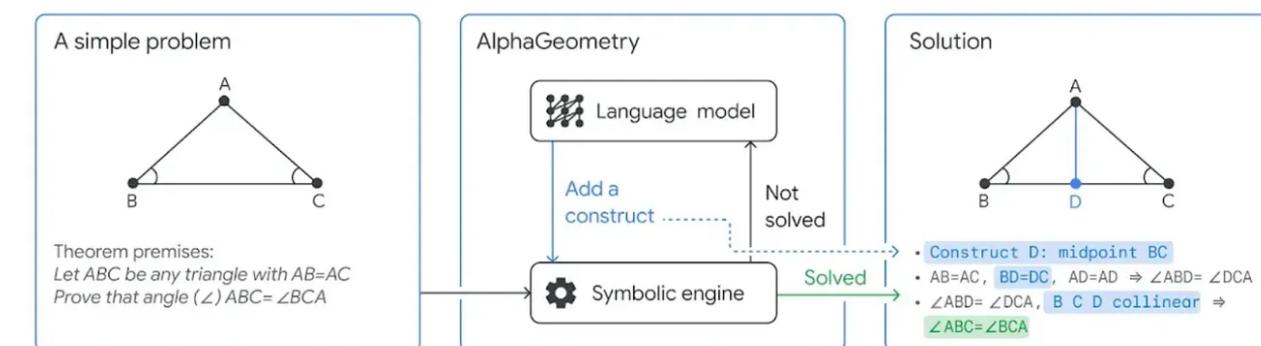
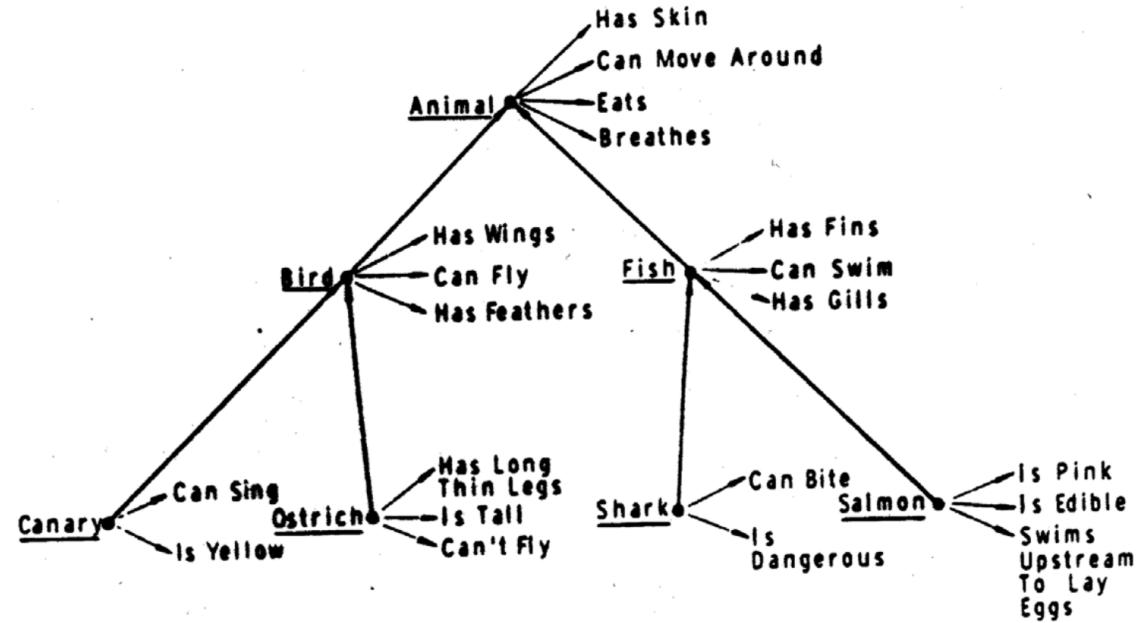
Logic

Classical
Non-monotonic
Modal
Probabilistic
Temporal
Graphs (Ontologies)
Relational (Tables)
Built-in Theories

Reasoning Tasks

Proving
Disproving
Query answering
Model computation
Knowledge Completion
Diagnosis

flight(toronto, london).
flight(london, rome).
flight(chicago, london).
flight(X, Y) :- flight(X, Z), flight(Z, Y).



AlphaGeometry, AlphaProof, LLM-modulo, ...

Relational

Ontology

Neuro-Symbolic

Logic

“Algorithm = Logic + Control”

- Model the problem at hand with “logic”
- Feed into automated reasoning system
- Push button and get solution



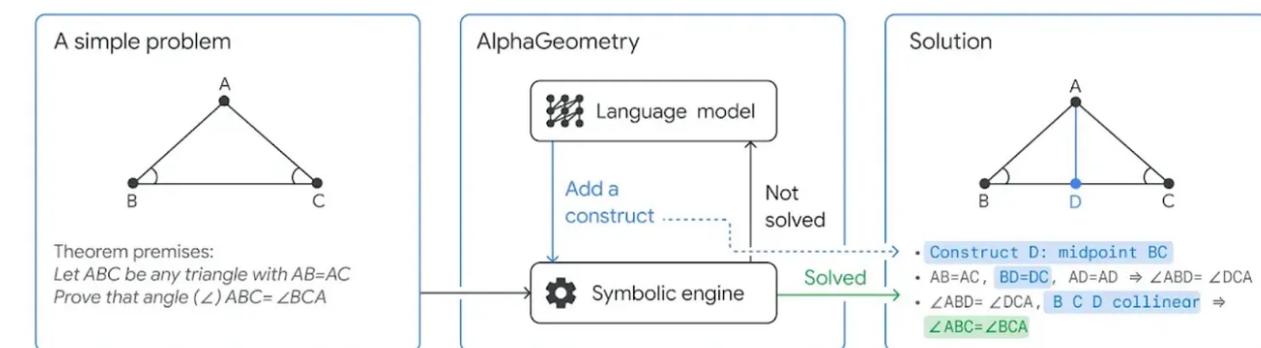
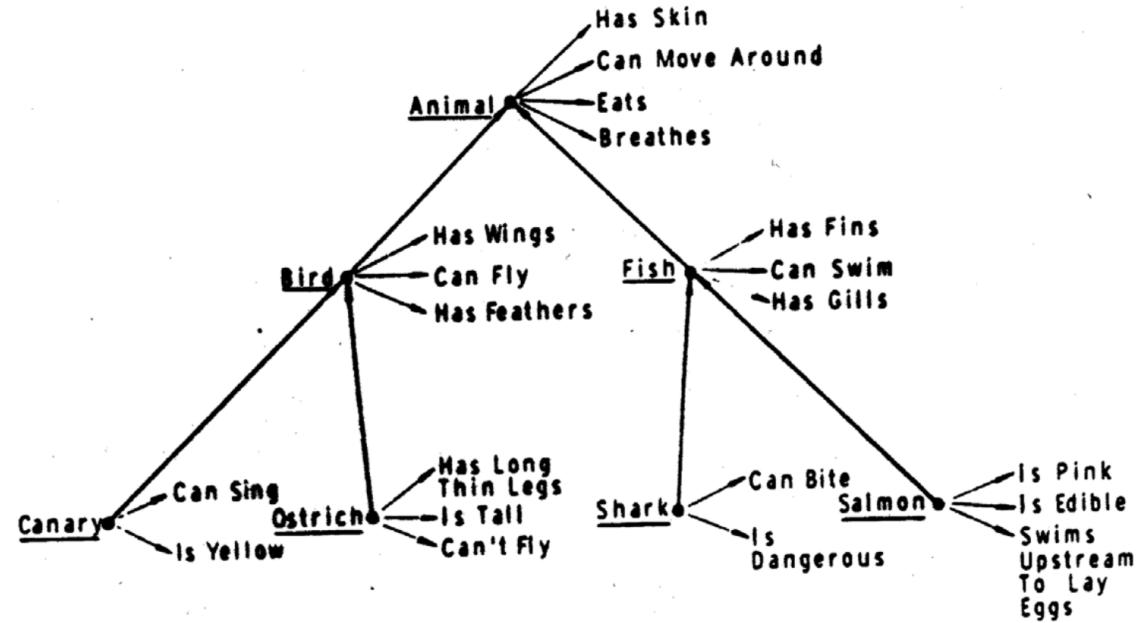
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“Logic” vs “Logic Programming”?

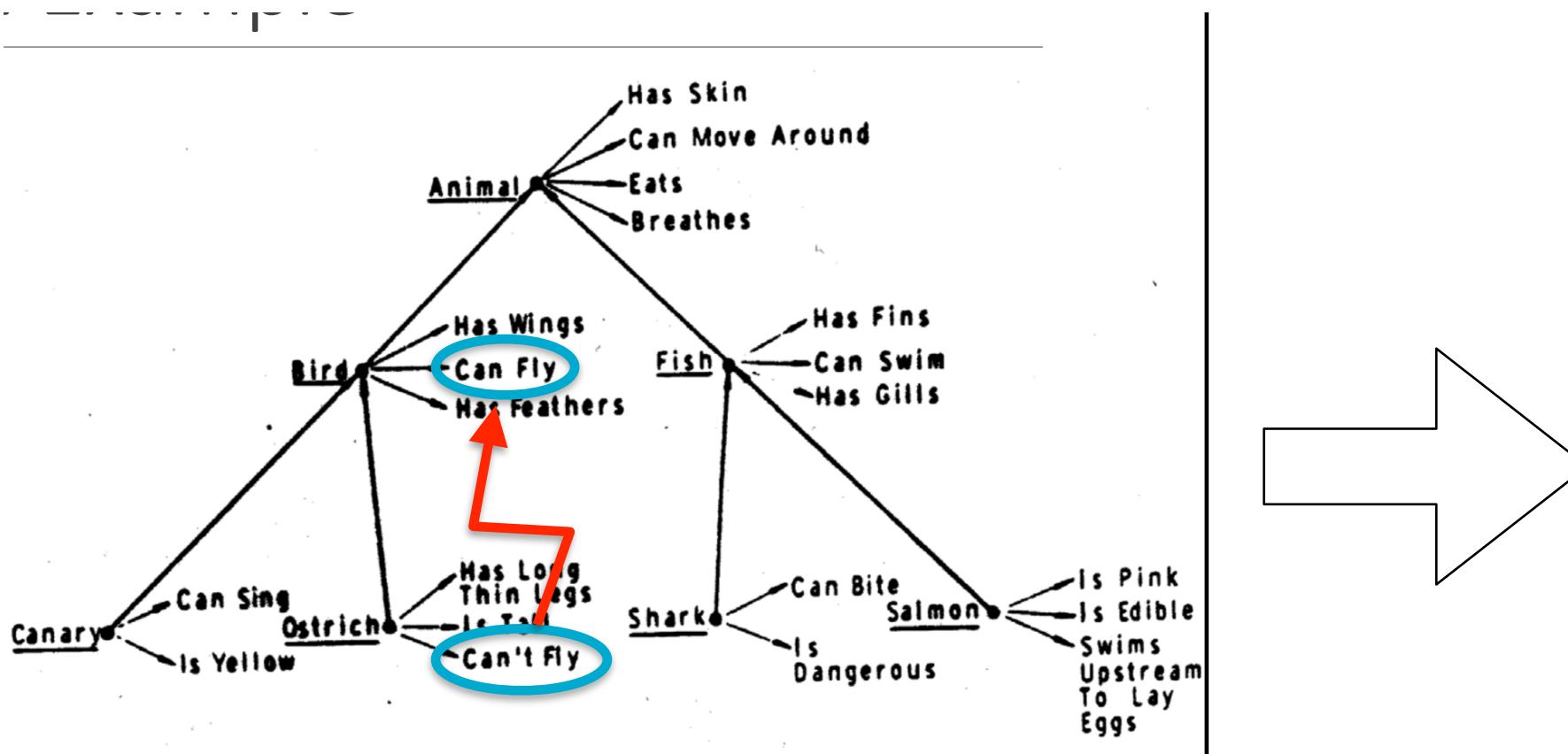
AlphaGeometry, AlphaProof, LLM-modulo, ...

Relational

Ontology

Neuro-Symbolic

Classical Logic and Logic Programming Semantics

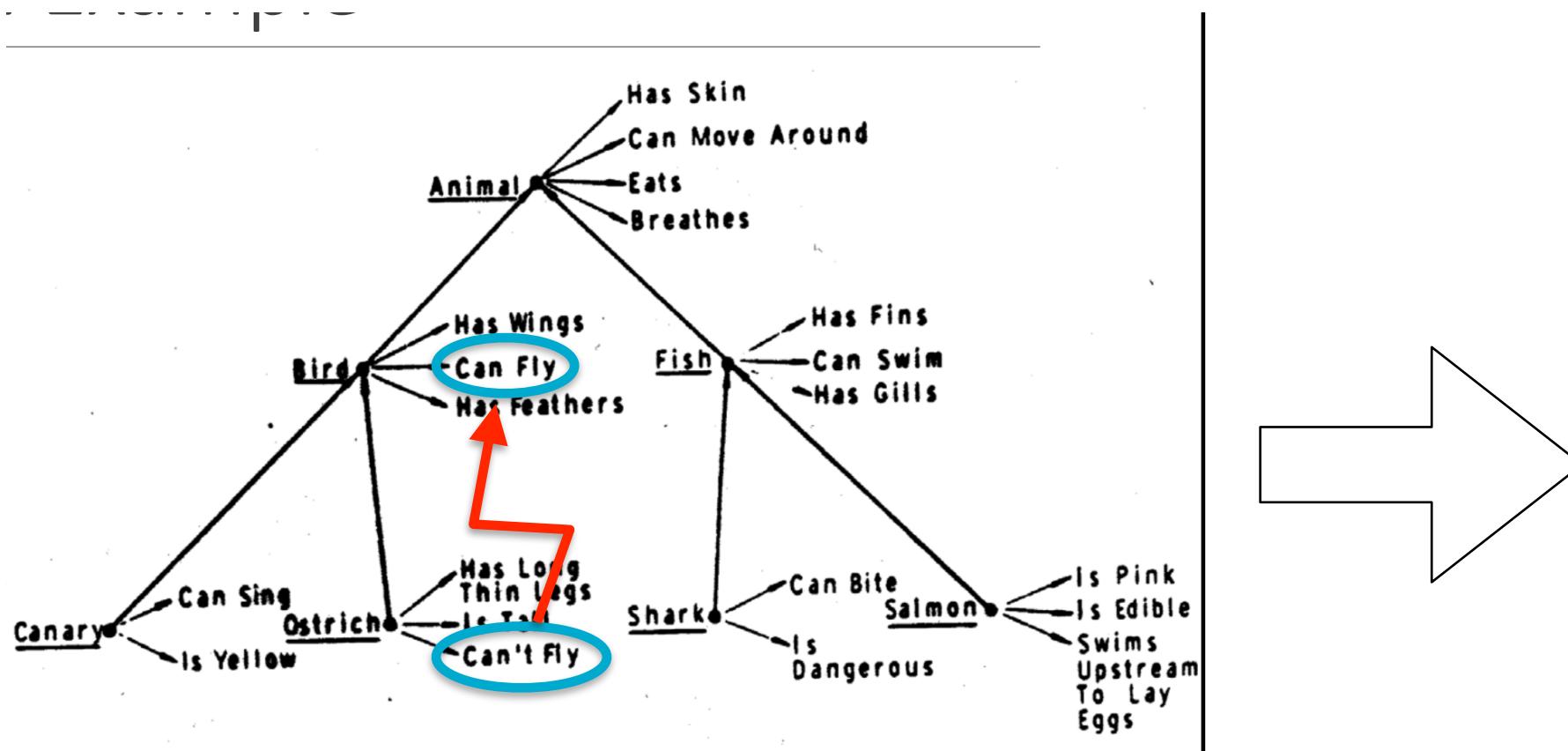


If X is a bird
then X is an animal

If X is a bird and
 X is *not* an ostrich
then X can fly

Tweety is a bird
(Tweety is an ostrich)

Classical Logic and Logic Programming Semantics



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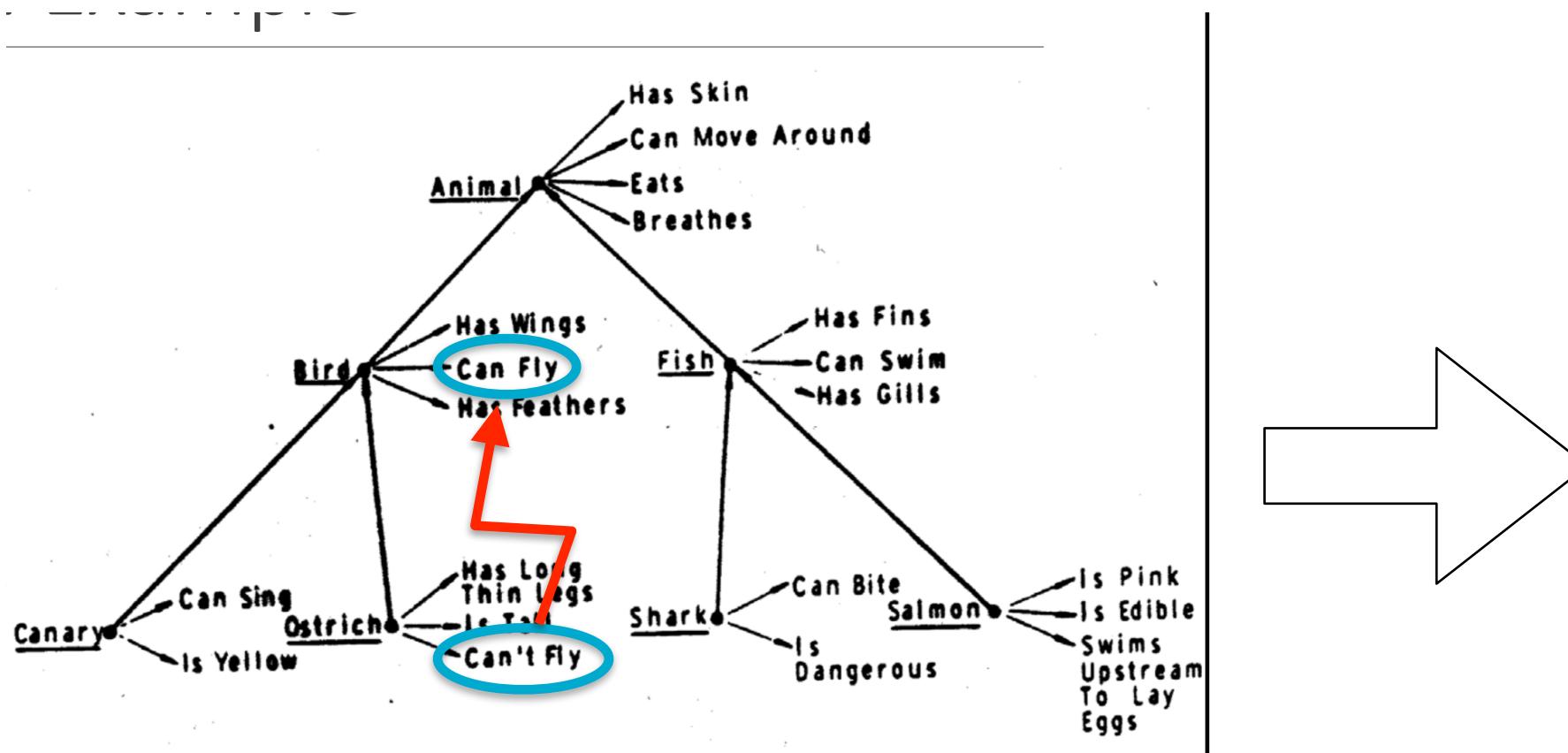
Classical (Open-World) Entailment

Non-Monotonic (Closed-World)

“Constraint” view

“Provability” view
Logic Programming

Classical Logic and Logic Programming Semantics



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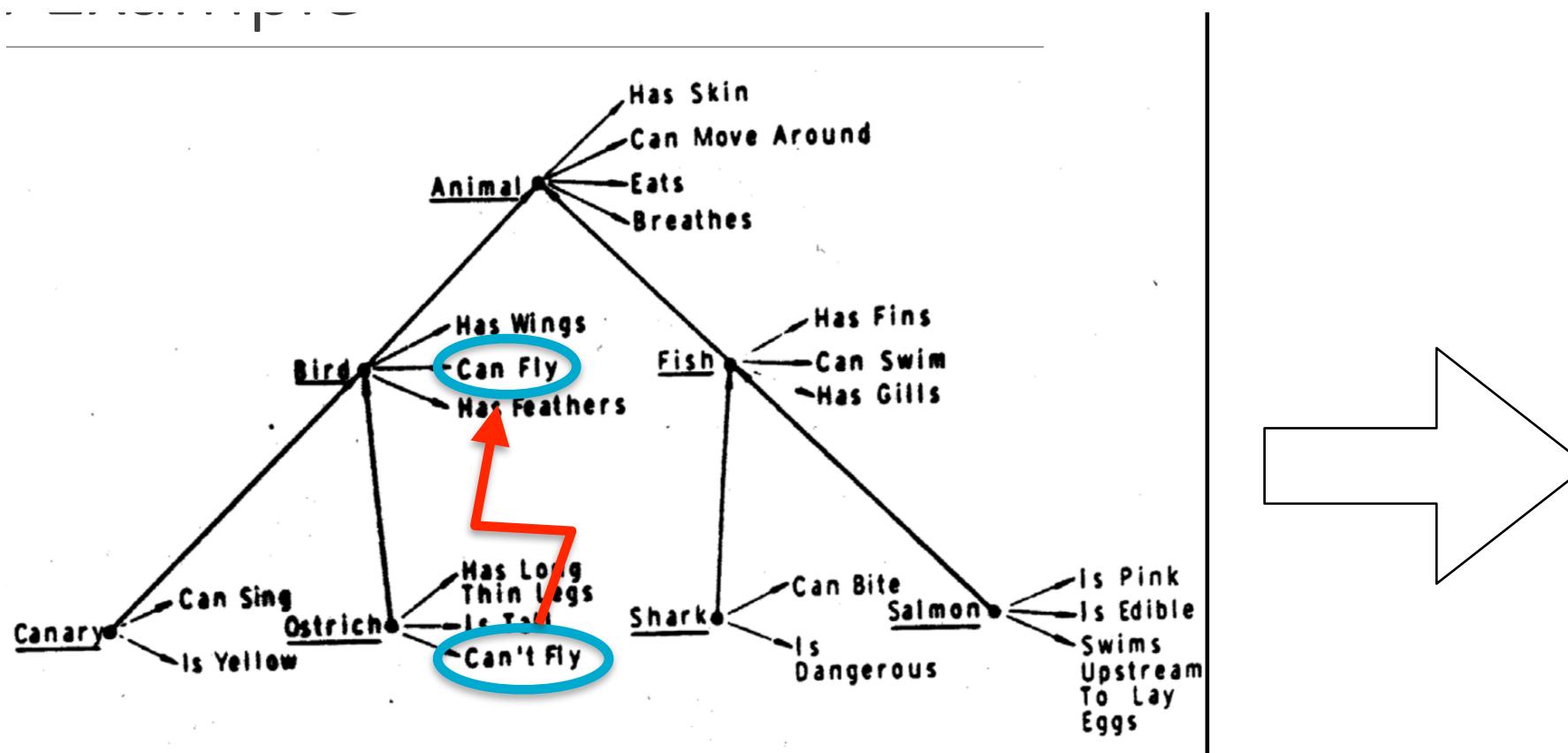
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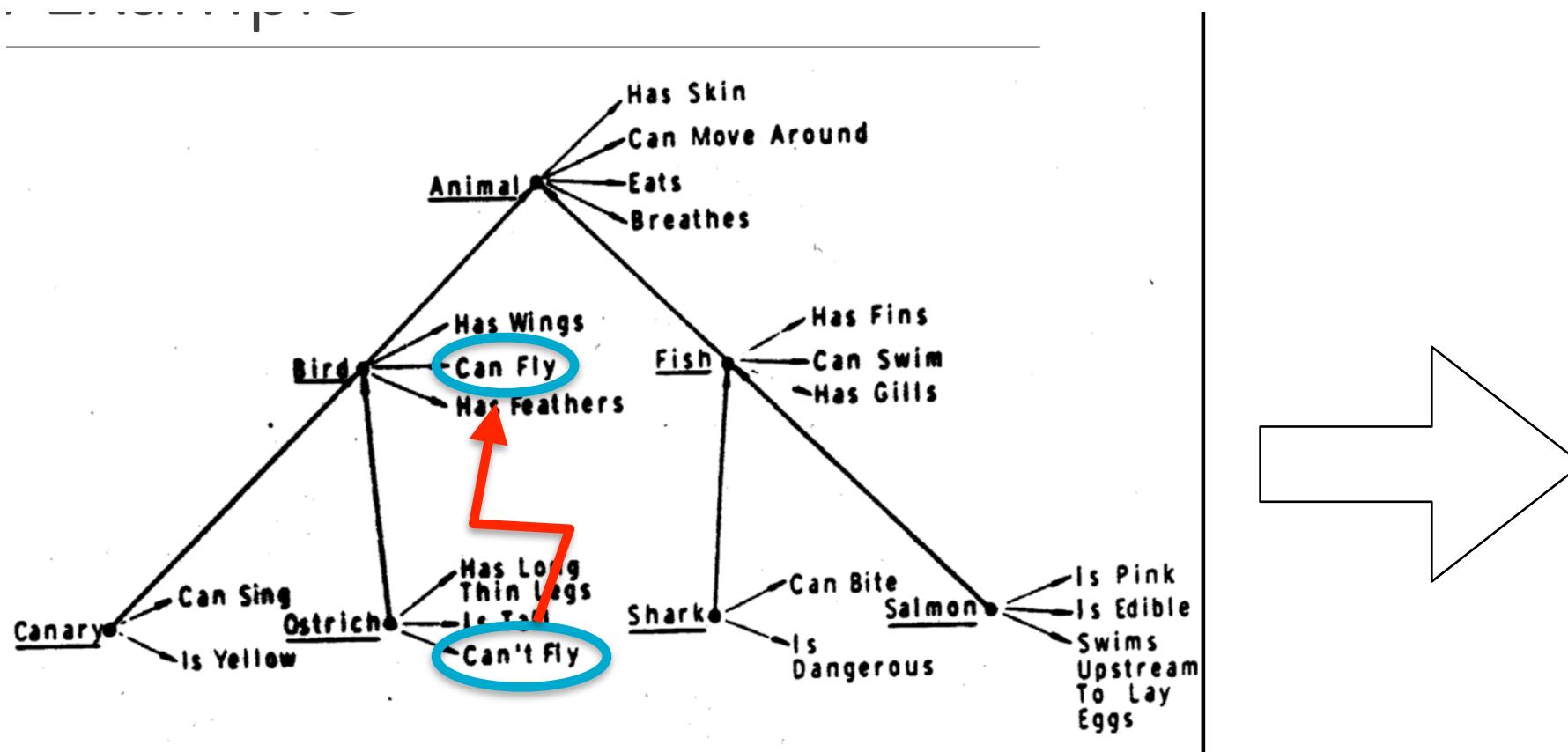
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Logic Programming

Classical Logic and Logic Programming Semantics



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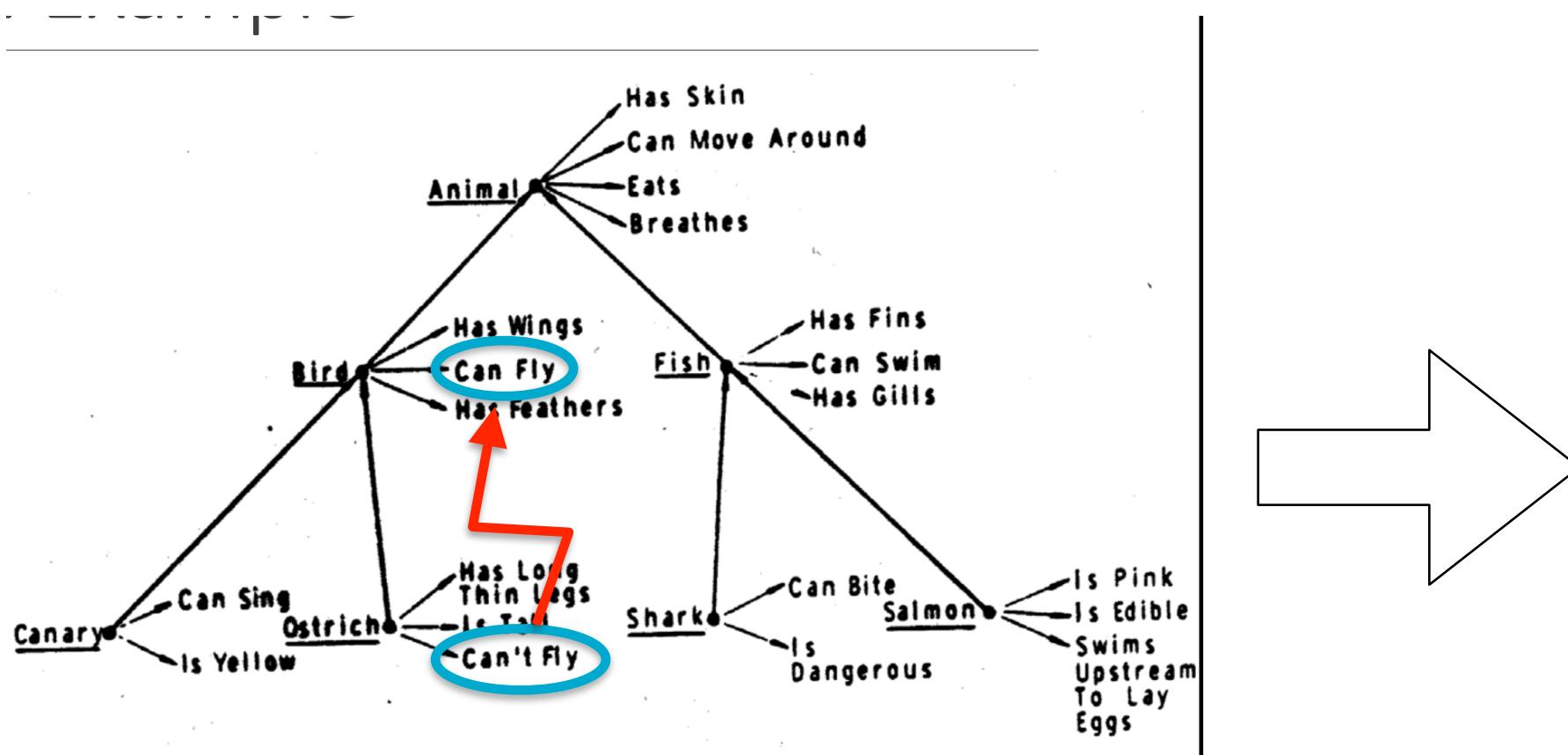
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Non-Monotonic (Closed-World)

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“Provability” view
Logic Programming



Probabilistic Logic Programs



Facts

cat(tom).

Rules

drinks(X, milk) :- cat(X).

Tom is a cat

If X is a cat then X drinks milk

Default Negation

innocent(X) :- cat(X), **not** guilty(X).

*If X is a cat and X is not guilty
then X is innocent*

flies(X) :- bird(X), **not** abnormal(X).

... @ Time

(Fusemate)

thirsty(X) @ T+1 :-

thirsty(X) @ T,

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*If X is thirsty at time T and
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then X is thirsty at time T+1*

Probabilities

0.8 :: cat(tom).

0.5 :: drinks(X, milk) :- cat(X).

Operational

Top-Down Inference

Bottom-Up Inference

Exact inference/sampling

Parameter Learning

Structure Learning

Distributions

(Fusemate)

nr_siblings(X) ~ [[0, 0.05], [1, 0.10], ... [5, 0.10]]

:- cat(X).

Queries

?- thirsty(tom) @ T |

thirsty(tom) @ 2, drink(tom, milk) @ 5.

Probabilistic Logic Programs



Facts	cat(tom).	<i>Tom is a cat</i>
Rules	drinks(X, milk) :- cat(X).	<i>If X is a cat then X drinks milk</i>
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Dynamic Data Structures and Distributions

Drawing without replacement

```
urn([r(1), r(2), g(1)]) @ 0.          %% Initially two red and one green distinguishable balls
draw ~ Balls @ T :-                   %% Draw a ball uniformly if urn is not empty
  urn(Balls) @ T,
  Balls \= [].
urn(Balls -- [B]) @ T+1 :-             %% Drawing a ball removes it from urn
  urn(Balls) @ T,
  draw = B @ T.
some(red) @ T :- draw=r(_) @ T.       %% Abstract from ball id, color only
some(green) @ T :- draw=g(_) @ T.
```

Queries

```
?- some(green) @ 0.
% 0.333333
```

```
?- some(green) @ 1 | some(red) @ 0.
% 0.5 conditional query
```

```
?- some(C1) @ 1, some(C2) @ 2 | some(red) @ 0. % Non-ground conditional query, two solutions:
% 0.5 :: [C1 = red, C2 = green]
% 0.5 :: [C1 = green, C2 = red]
```

Dynamic Data Structures and Distributions

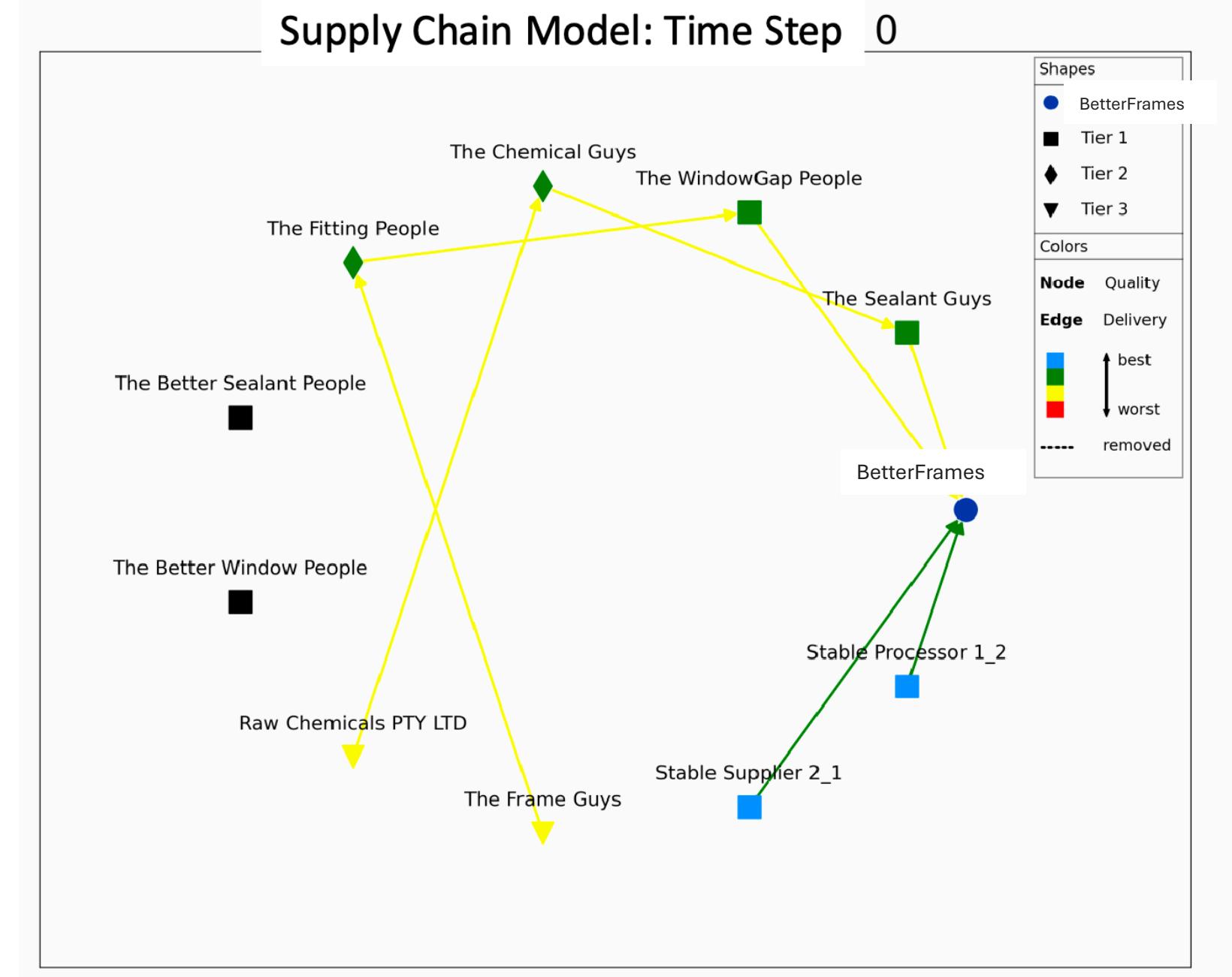
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Queries

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% 0.5 :: [C1 = red, C2 = green]  
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```

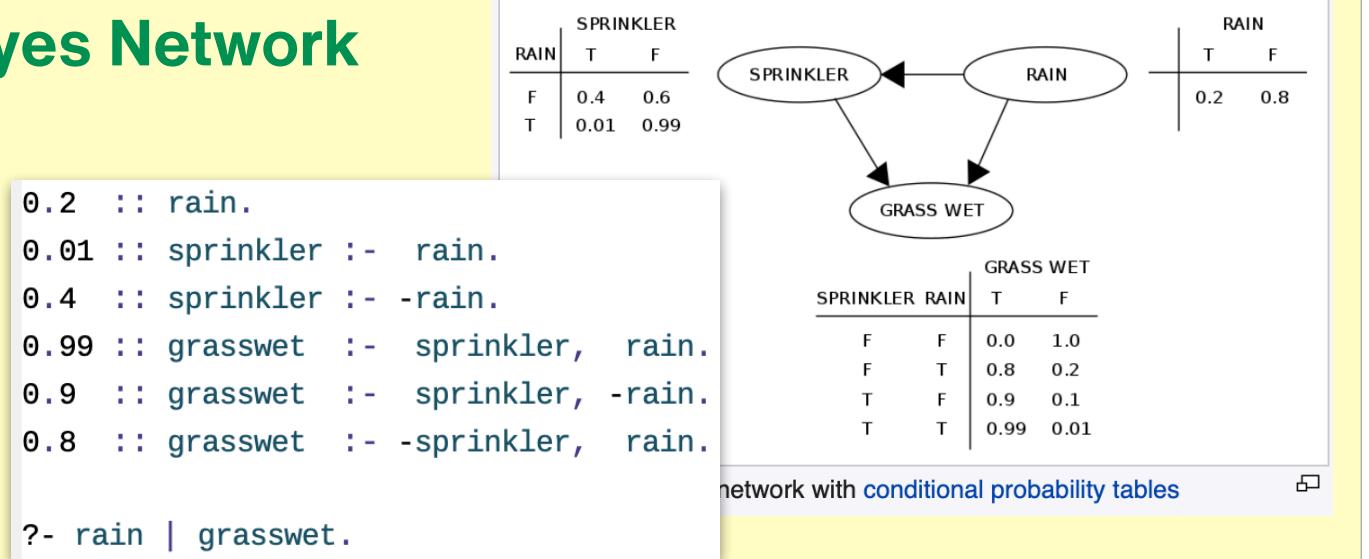
D61 Supply Chain Risk Assessment Application



Probabilistic Logic Programming (Fusemate)

Probabilistic Logic Programming (Fusemate)

Bayes Network



Probabilistic Logic Programming (Fusemate)

Bayes Network

RAIN	SPRINKLER	
SPRINKLER	T	F
F	0.4	0.6
T	0.01	0.99

RAIN	T	F
SPRINKLER	0.2	0.8

GRASS WET

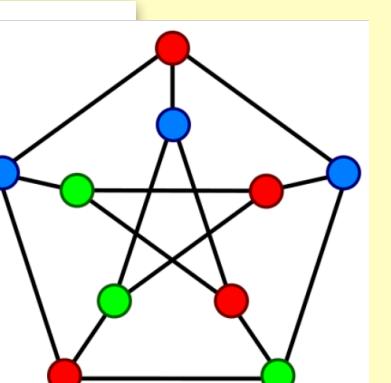
SPRINKLER	RAIN	GRASS WET	
		T	F
F	F	0.0	1.0
	T	0.8	0.2
T	F	0.9	0.1
	T	0.99	0.01

network with conditional probability tables

```
0.2 :: rain.  
0.01 :: sprinkler :- rain.  
0.4 :: sprinkler :- -rain.  
0.99 :: grasswet :- sprinkler, rain.  
0.9 :: grasswet :- sprinkler, -rain.  
0.8 :: grasswet :- -sprinkler, rain.  
  
?- rain | grasswet.
```

NP-Complete Search Problems

```
color(X) in [r, g, b] :- node(X).  
node(1). node(2). node(3). node(4).  
noncol :- color(X)=r, color(Y)=r, edge(X,Y).  
noncol :- color(X)=g, color(Y)=g, edge(X,Y).  
noncol :- color(X)=b, color(Y)=b, edge(X,Y).  
edge(1,2). edge(2,3). edge(3,1).  
  
edge(4,1).  
edge(4,2).  
%edge(4,3).  
  
%% \+ noncol is true iff there is a coloring  
?- \+ noncol, color(1)=c1, color(2)=c2, color(3)=c3, color(4)=c4.
```



Logical variables X for domain objects

Probabilistic Logic Programming (Fusemate)

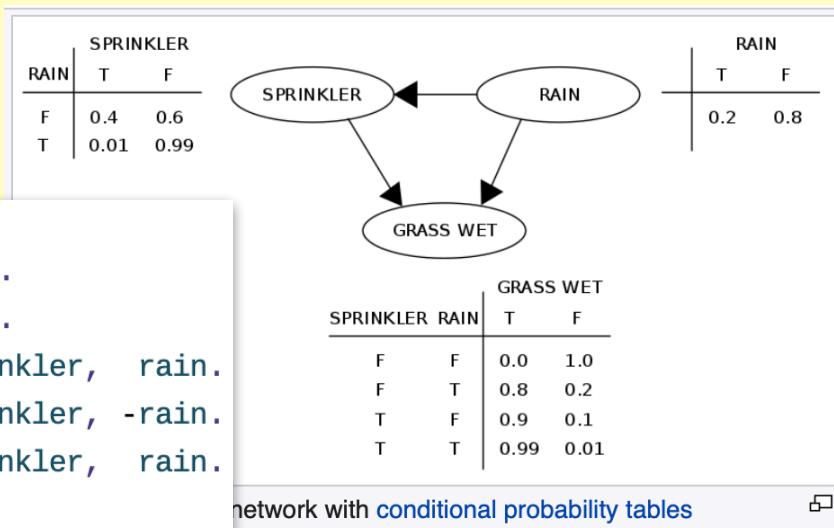
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Logical variables X for domain objects

Time

```

%% Some "random" blockages
block(1) @ 2.
block(2) @ 3.

```



```

prob(0).
(0.5 :: prob(K+1) + prob(K)) @ N+1 :-
    prob(K) @ N,
    \+ bl(K) @ N.
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%% ?- prob(K) @ 4.
0.0625 :: prob(0) @ 4
0.3750 :: prob(1) @ 4
0.43750 :: prob(2) @ 4
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Probabilistic Logic Programming (Fusemate)

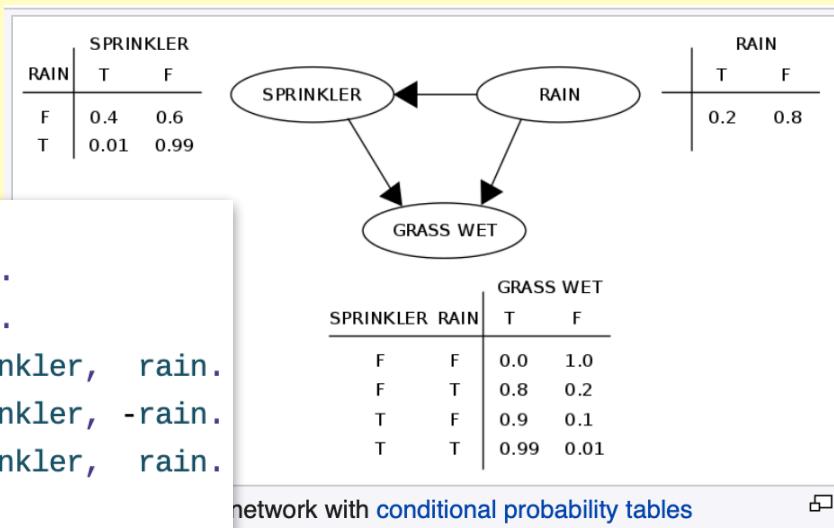
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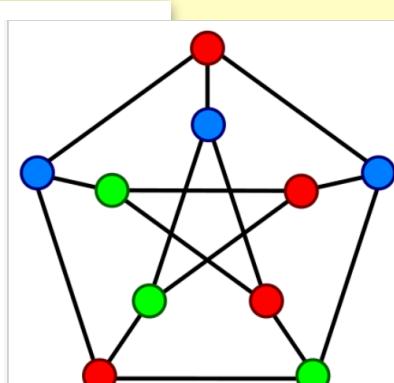
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```



Logical variables X for domain objects

Hidden Markov Models

Observation (E_t)	
sun	0.2
cloud	0.8

E ₀	X ₀	X ₁	X ₂	X ₃	X ₄	-
umbrella	sun	sun	cloud	cloud	cloud	-
umbrella	sun	cloud	cloud	cloud	cloud	-
umbrella	cloud	cloud	cloud	cloud	cloud	-
umbrella	cloud	cloud	cloud	cloud	cloud	?

Probabilistic Logic Programming (Fusemate)

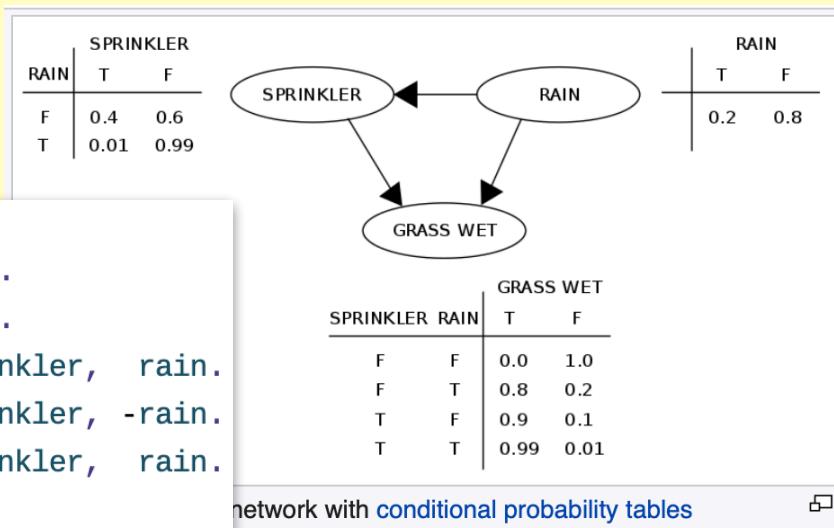
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?- rain | grasswet.

```



NP-Complete Search Problems

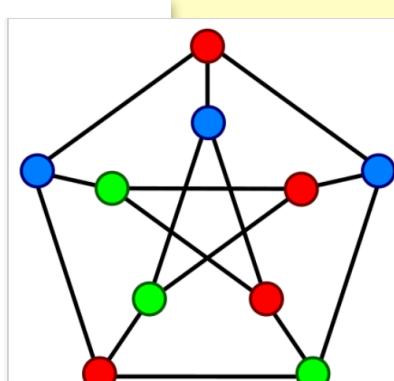
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Logical variables X for domain objects

Time

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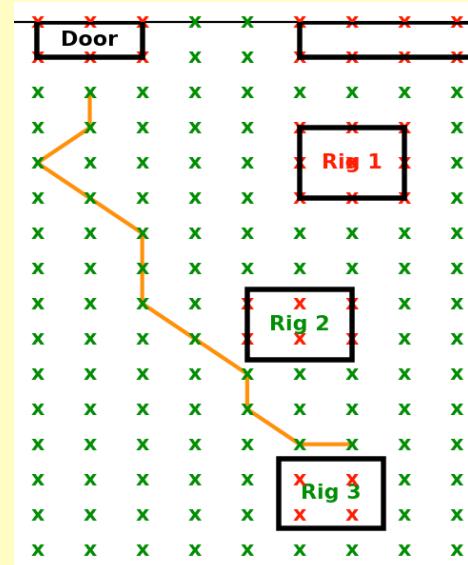


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0.0625 :: prob(4) @ 4

```

Algorithms



Probabilistic A*

Hidden Markov Models

Observation (E_t)	
伞 (Umbrella)	0.2
太阳 (Sun)	0.8

X_0	X_1	X_2	X_3	X_4	-
☀	☀	☁	☁	☁	-
☂	☂	☂	☂	☂	?
E_0	E_1	E_2	E_3		

Probabilistic Logic Programming (Fusemate)

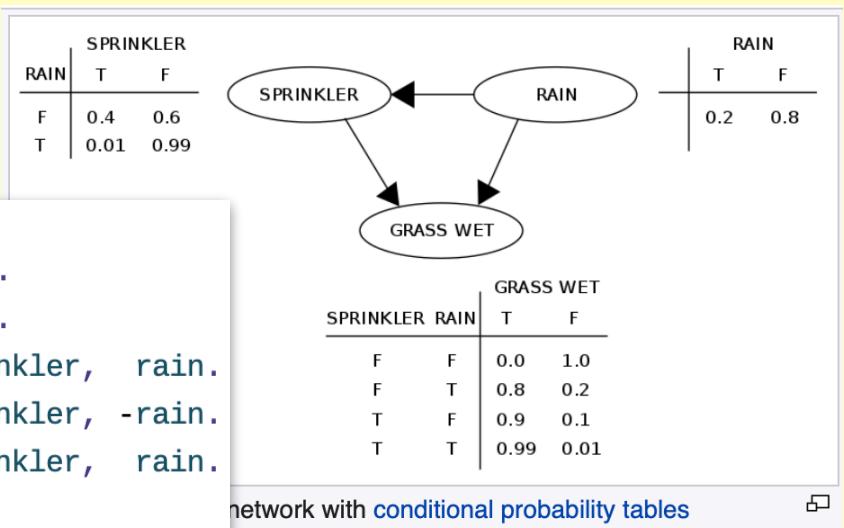
Bayes Network

```

0.2 :: rain.
0.01 :: sprinkler :- rain.
0.4 :: sprinkler :- -rain.
0.99 :: grasswet :- sprinkler, rain.
0.9 :: grasswet :- sprinkler, -rain.
0.8 :: grasswet :- -sprinkler, rain.

?- rain | grasswet.

```



NP-Complete Search Problems

```

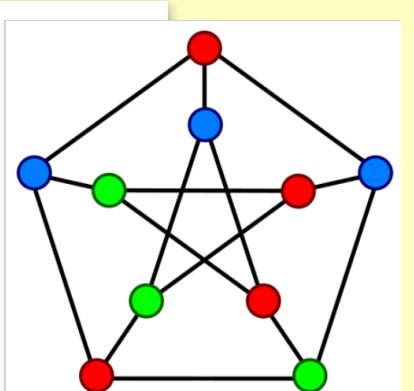
color(X) in [r, g, b] :- node(X).
node(1). node(2). node(3). node(4).
noncol :- color(X)=r, color(Y)=r, edge(X,Y).
noncol :- color(X)=g, color(Y)=g, edge(X,Y).
noncol :- color(X)=b, color(Y)=b, edge(X,Y).
edge(1,2). edge(2,3). edge(3,1).

edge(4,1).
edge(4,2).
%edge(4,3).

% \+ noncol is true iff there is a coloring
?- \+ noncol, color(1)=C1, color(2)=C2, color(3)=C3, color(4)=C4.

```

Logical variables X for domain objects



Time

```

% Some "random" blockages
block(1) @ 2.
block(2) @ 3.

```

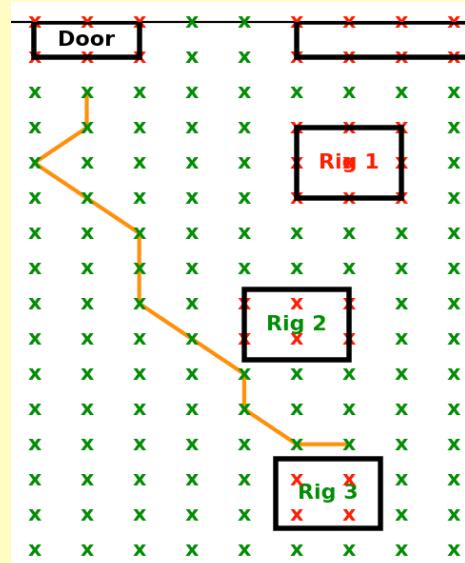


```

prob(0).
(0.5 :: prob(K+1) + prob(K)) @ N+1 :-
    prob(K) @ N,
    \+ bl(K) @ N.           %% ?- prob(K) @ 4.
prob(K) @ N+1 :-
    prob(K) @ N,
    bl(K) @ N.
0.0625 :: prob(0) @ 4
0.3750 :: prob(1) @ 4
0.43750 :: prob(2) @ 4
0.0625 :: prob(3) @ 4
0.0625 :: prob(4) @ 4

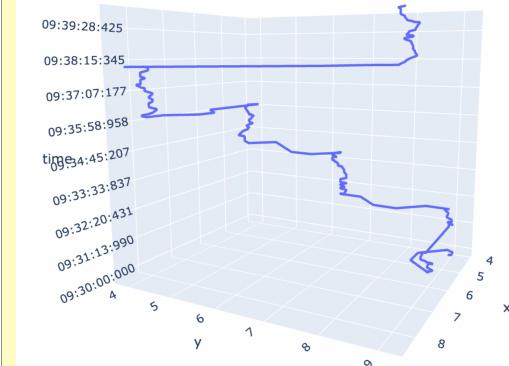
```

Algorithms

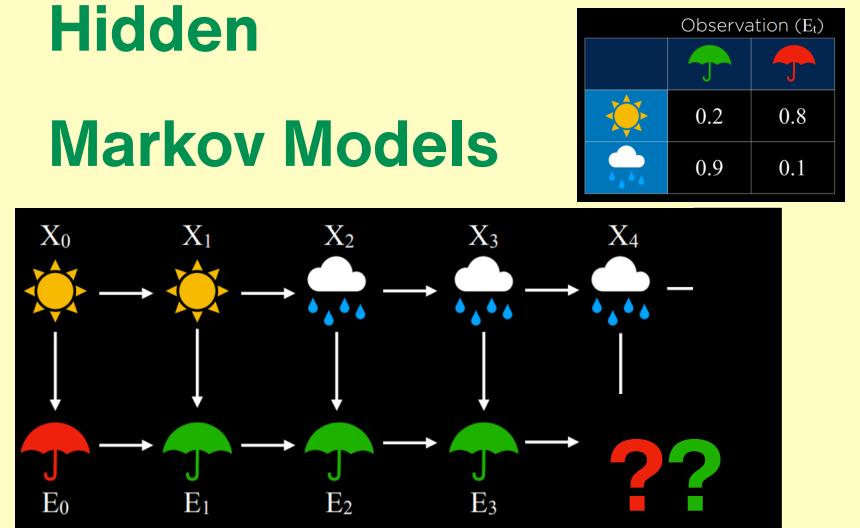


Probabilistic A*

Simulation by Sampling



Hidden Markov Models



Probabilistic Logic Programming (Fusemate)

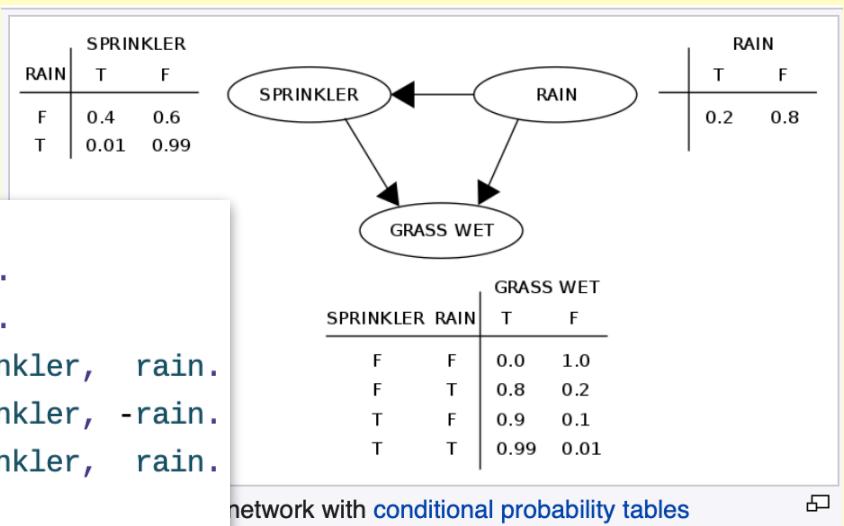
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0.9 :: grasswet :- sprinkler, -rain.
0.8 :: grasswet :- -sprinkler, rain.

?- rain | grasswet.

```



NP-Complete Search Problems

```

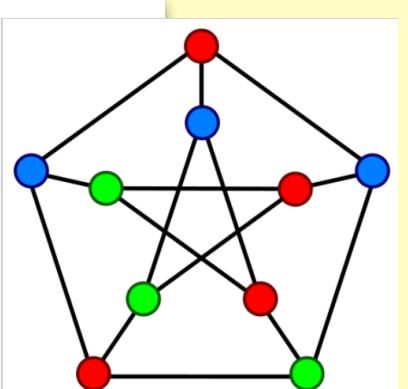
color(X) in [r, g, b] :- node(X).
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noncol :- color(X)=g, color(Y)=g, edge(X,Y).
noncol :- color(X)=b, color(Y)=b, edge(X,Y).
edge(1,2). edge(2,3). edge(3,1).

edge(4,1).
edge(4,2).
%edge(4,3).

% \+ noncol is true iff there is a coloring
?- \+ noncol, color(1)=C1, color(2)=C2, color(3)=C3, color(4)=C4.

```

Logical variables X for domain objects



Time

```

% Some "random" blockages
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block(2) @ 3.

```

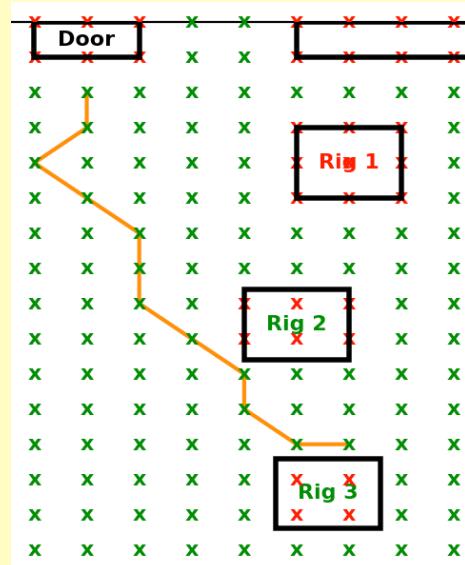


```

prob(0).
(0.5 :: prob(K+1) + prob(K)) @ N+1 :-
    prob(K) @ N,
    \+ bl(K) @ N.           %% ?- prob(K) @ 4.
prob(K) @ N+1 :-               0.0625 :: prob(0) @ 4
    prob(K) @ N,             0.3750 :: prob(1) @ 4
    bl(K) @ N.               0.43750 :: prob(2) @ 4
                                0.0625 :: prob(3) @ 4
                                0.0625 :: prob(4) @ 4

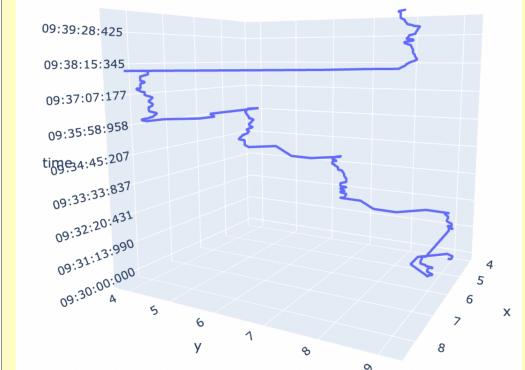
```

Algorithms



Probabilistic A*

Simulation by Sampling



Hidden Markov Models

Observation (E_t)	
伞 (Umbrella)	0.2
太阳 (Sun)	0.8

X_0	X_1	X_2	X_3	X_4	-
☀	☀	☁	☁	☁	-
☂	☂	☂	☂	☂	??

Expressivity: full history (non-Markovian); random variables are first-class citizens

Fusemate Probabilistic Logic Programming System

Implementation in Python

(From earlier versions in Scala)

Two-way interface Python <-> Fusemate

Python data structures available in Fusemate

Logic program can be written as Python functions

Efficient probabilistic inference

Default negation via well-founded model

Rules cannot change past states

Two-phase inference algorithm

- Phase 1 “grounding”
 - Removal of first-order variables
 - > Bayes-net like program (may contain cycles)
 - Phase 2 inference/sampling
 - Top-down variable elimination with caching of results

Strong Python integration

```
def weather_0():
    return {'rainy': 0.5, 'sunny': 0.5}

def weather_Tp1(weather_T):
    return {'rainy': {'rainy': 0.8, 'sunny': 0.2},
            'sunny': {'rainy': 0.2, 'sunny': 0.8}}\n[weather_T]

def obs_T(weather_T):
    return {'rainy': {'shop': 0.8, 'clean': 0.2},
            'sunny': {'shop': 0.2, 'walk': 0.8}}\n[weather_T]
```

Fusemate Probabilistic Logic Programming System

Implementation in Python

(From earlier versions in Scala)

Two-way interface Python <-> Fusemate

Python data structures available in Fusemate

Logic program can be written as Python functions

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Two-phase inference algorithm

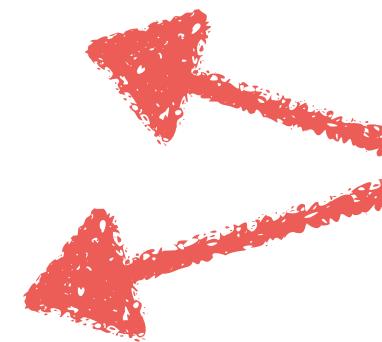
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 - > Bayes-net like program (may contain cycles)
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Strong Python integration

```
def weather_0():
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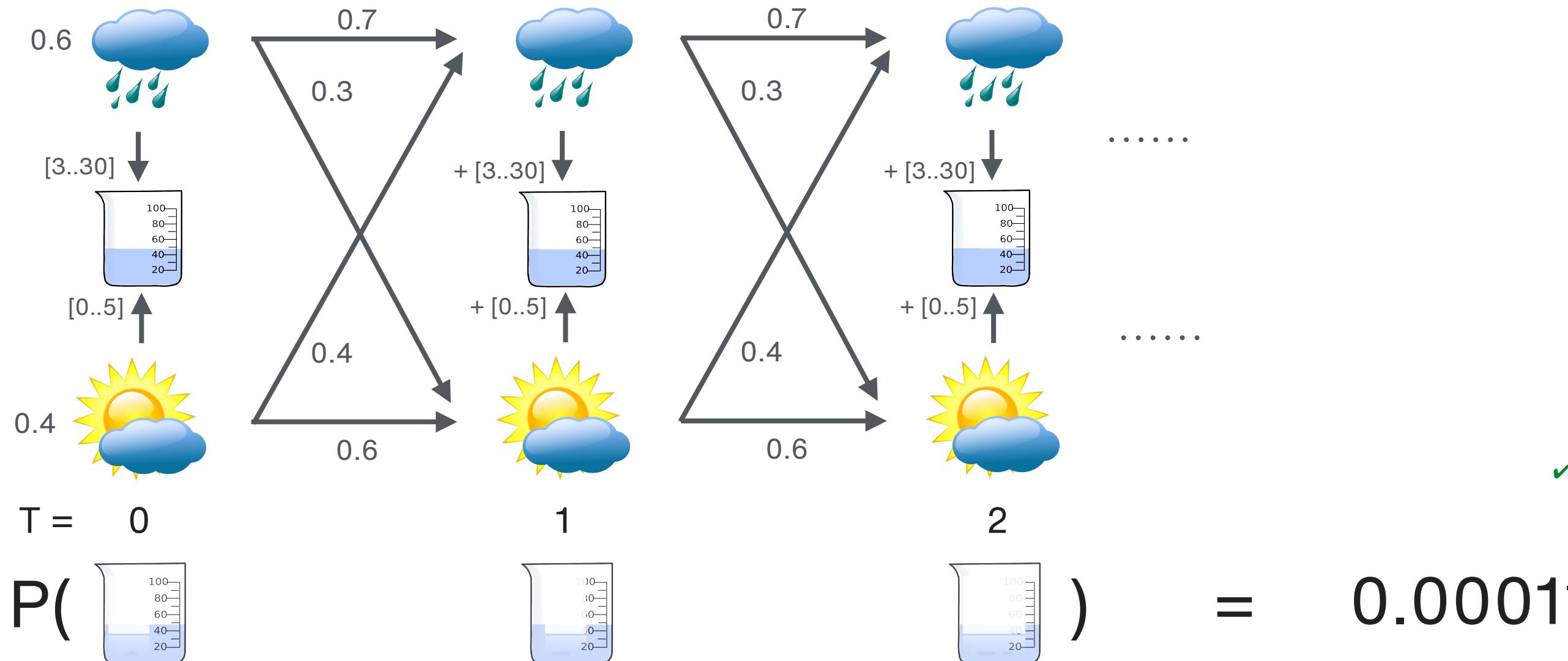
def weather_Tp1(weather_T):
    return {'rainy': {'rainy': 0.8, 'sunny': 0.2},
            'sunny': {'rainy': 0.2, 'sunny': 0.8}}\n[weather_T]

def obs_T(weather_T):
    return {'rainy': {'shop': 0.8, 'clean': 0.2},
            'sunny': {'shop': 0.2, 'walk': 0.8}}\n[weather_T]
```

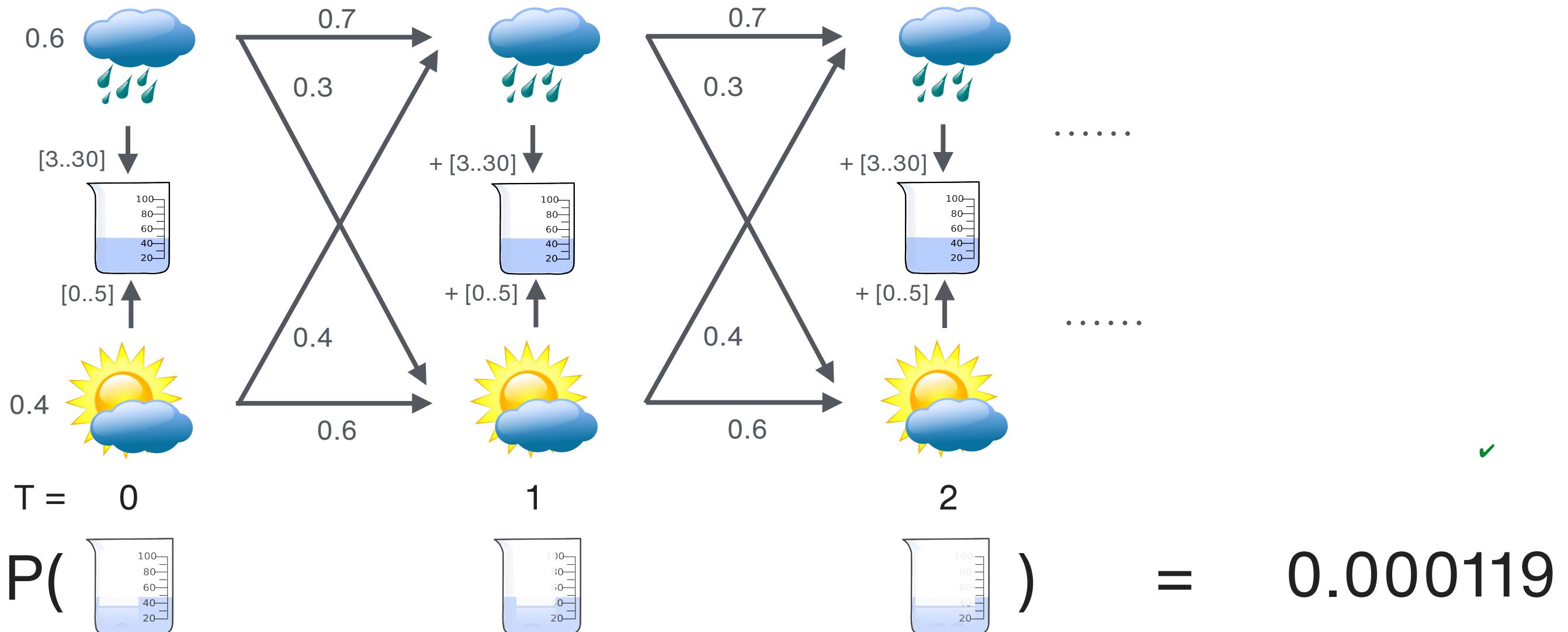


Contribution:
“Inconsistency Pruning”
for better efficiency

Fusemate Inconsistency Pruning



Fusemate Inconsistency Pruning



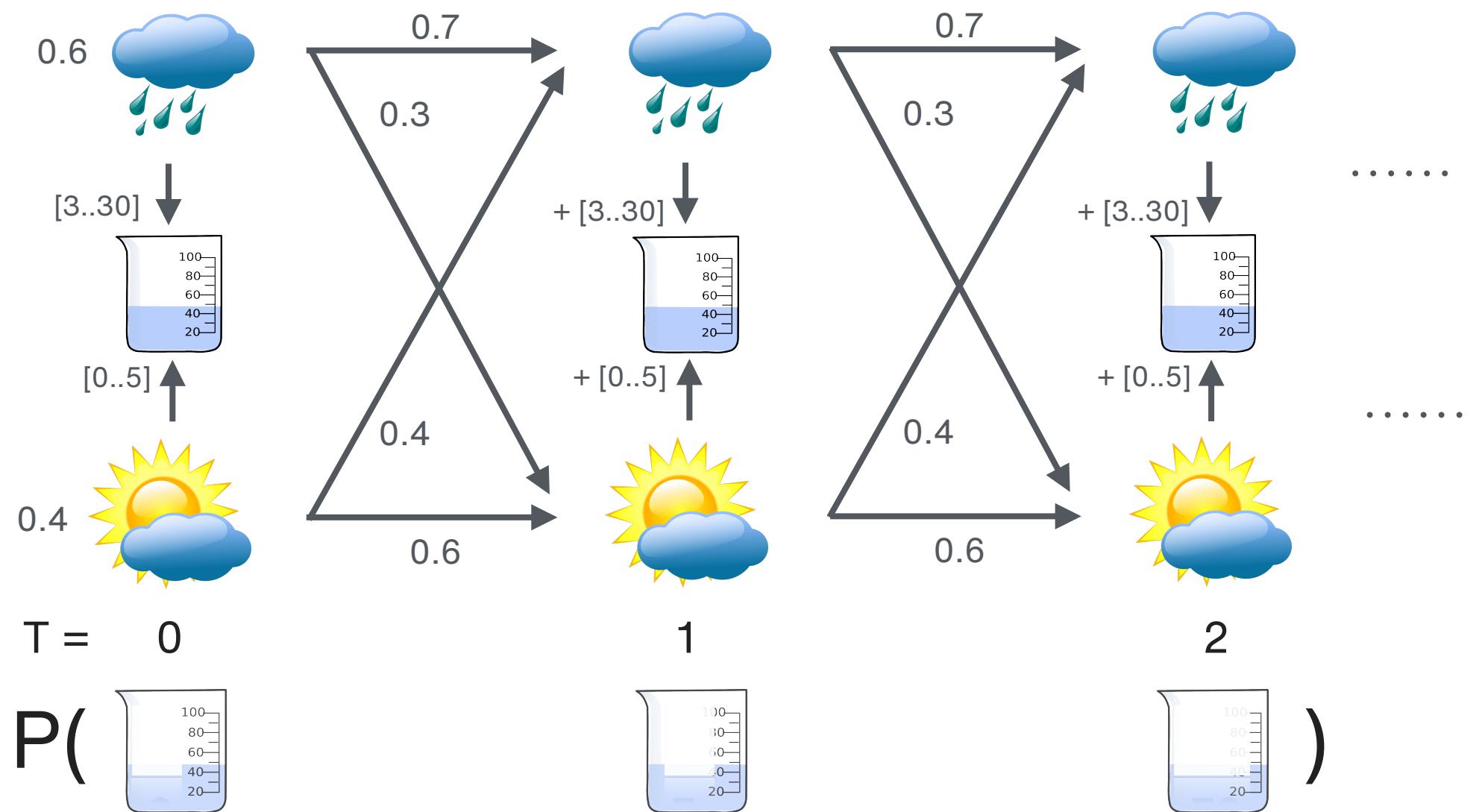
$\text{state} \sim [[\text{rainy}, 0.6], [\text{sunny}, 0.4]] @ 0.$

$\text{state} \sim [[\text{rainy}, 0.7], [\text{sunny}, 0.3]] @ T+1 :-$
 $\text{state}=\text{rainy} @ T.$

$\text{obs} \sim [R+3..R+30] @ T :-$
 $\text{state}=\text{rainy} @ T, T > 0, \text{obs}=R @ T-1.$

?- $\text{obs}=0 @ 0, \text{obs}=4 @ 1, \text{obs}=20 @ 2.$

Fusemate Inconsistency Pruning

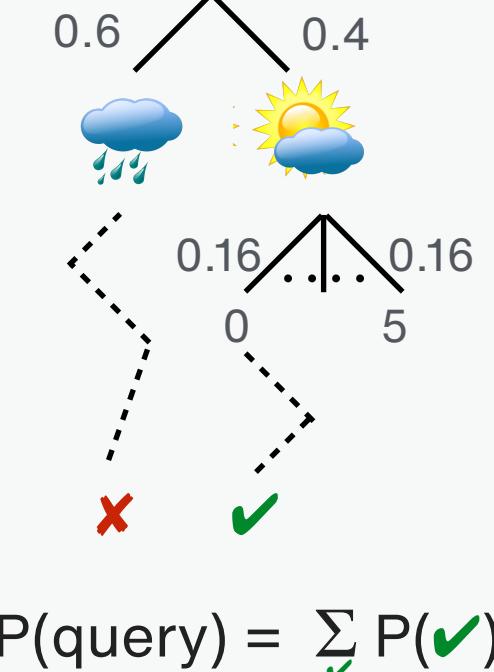


$\text{state} \sim [[\text{rainy}, 0.6], [\text{sunny}, 0.4]] @ 0.$

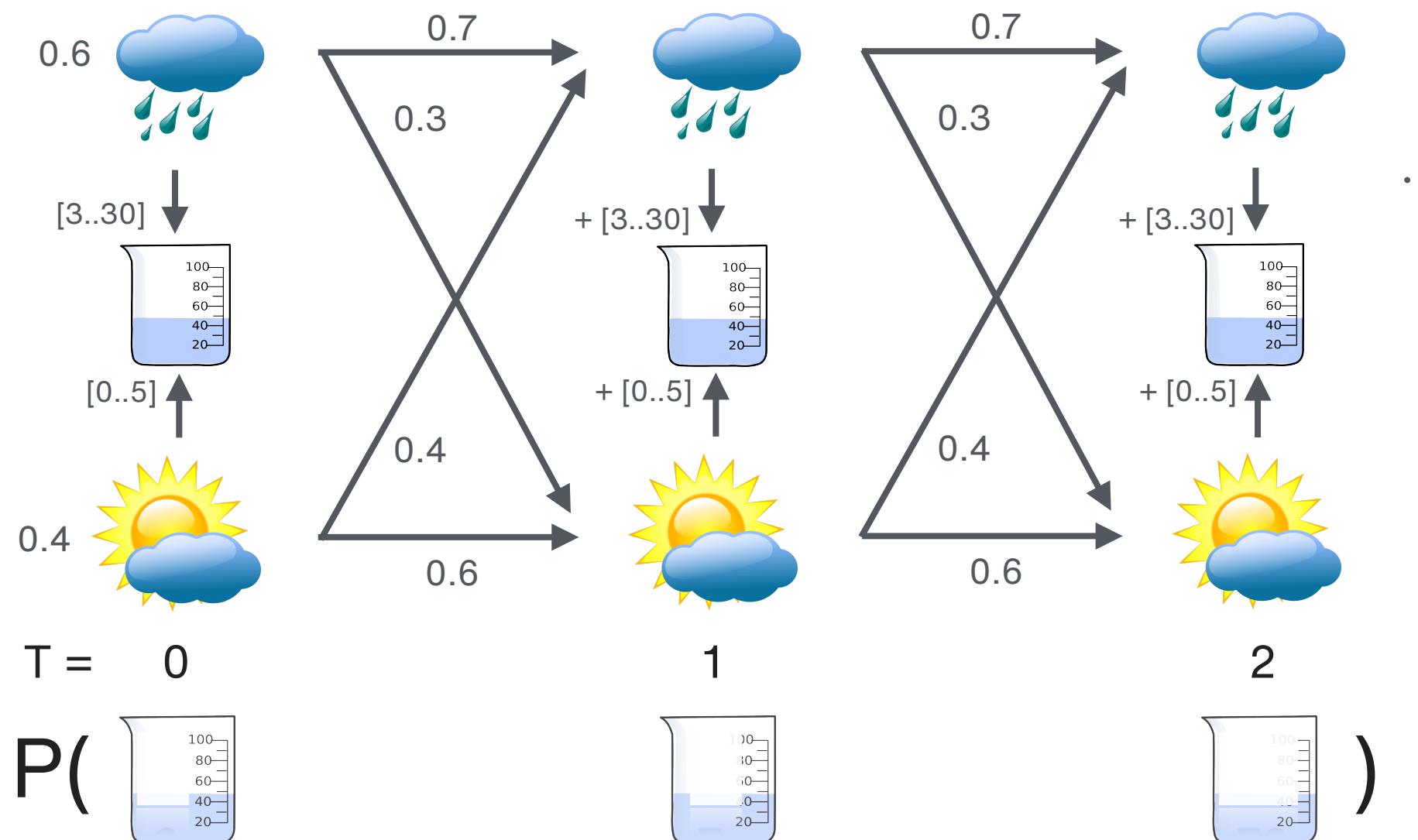
$\text{state} \sim [[\text{rainy}, 0.7], [\text{sunny}, 0.3]] @ T+1 :-$
 $\text{state}=\text{rainy} @ T.$

$\text{obs} \sim [R+3..R+30] @ T :-$
 $\text{state}=\text{rainy} @ T, T > 0, \text{obs}=R @ T-1.$
 $?- \text{obs}=0 @ 0, \text{obs}=4 @ 1, \text{obs}=20 @ 2.$

Distribution Semantics



Fusemate Inconsistency Pruning



```

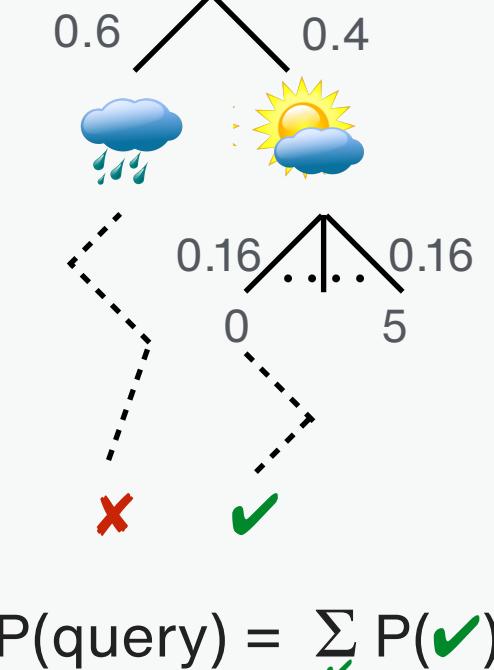
state ~ [[rainy, 0.6], [sunny, 0.4]] @ 0.
state ~ [[rainy, 0.7], [sunny, 0.3]] @ T+1 :-  

    state=rainy @ T.
obs ~ [R+3..R+30] @ T :-  

    state=rainy @ T, T > 0, obs=R @ T-1.
?- obs=0 @ 0, obs=4 @ 1, obs=20 @ 2.

```

Distribution Semantics

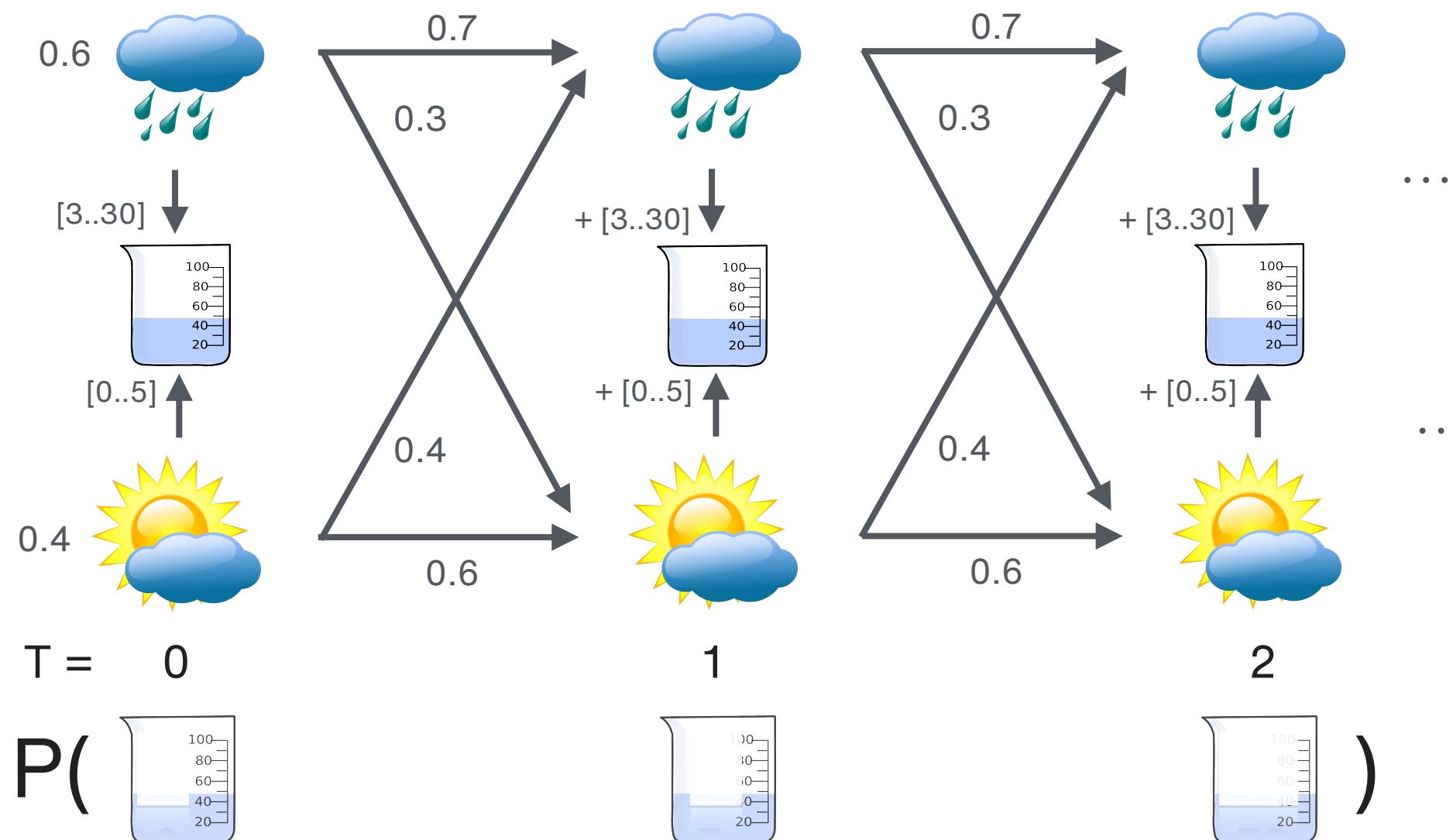


$$0.000119$$

Computing query success probabilities

- (1) Program grounding (\approx Bayes net)
- (2) Query probability (marginal probability by var. elim.)

Fusemate Inconsistency Pruning

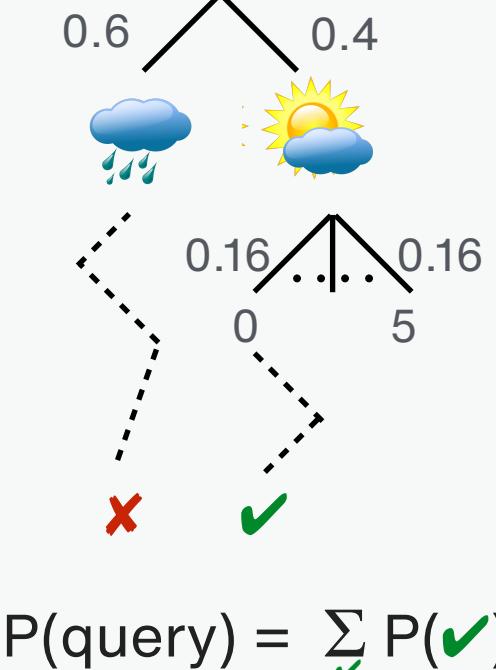


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 $\text{state}=\text{rainy} @ T, T > 0, \text{obs}=R @ T-1.$
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Distribution Semantics



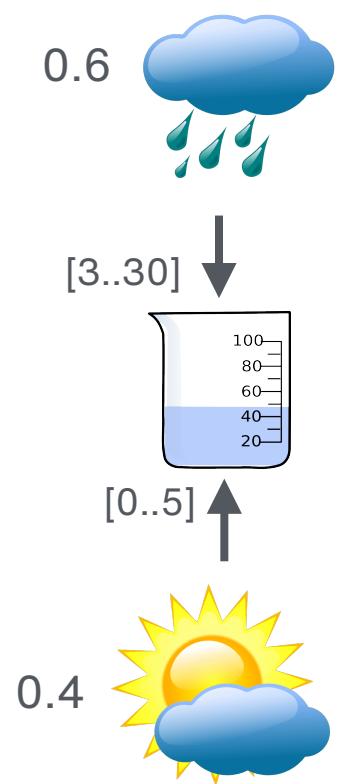
$$P(\text{query}) = \sum_{\checkmark} P(\checkmark) = 0.000119$$

Computing query success probabilities

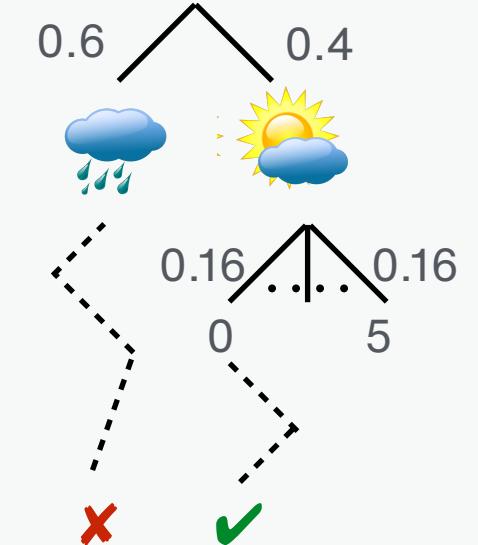
- (1) Program grounding (\approx Bayes net)
- (2) Query probability (marginal probability by var. elim.)

Naive (1): too many rules (quadratic in this case)
Solution: “Inconsistency Pruning”

Efficiency by Inconsistency Pruning



Distribution Semantics



(Already grounded) program rules $T = 0$

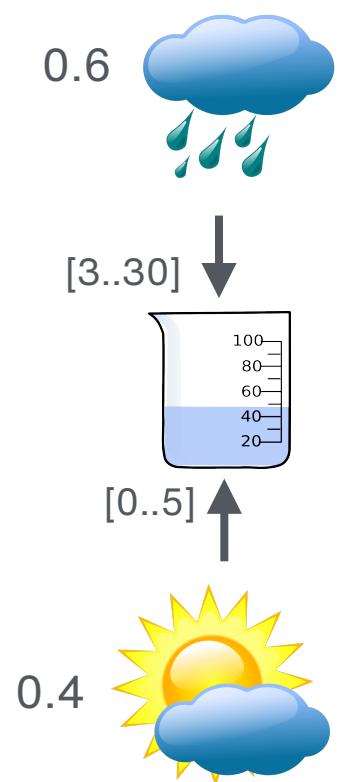
state ~ [[rainy, 0.6], [sunny, 0.4]] @ 0.

obs ~ [3..30] @ 0 :- state=rainy @ 0.

obs ~ [0..5] @ 0 :- state=sunny @ 0.

?- obs=0 @ 0, obs=2 @ 1, obs=20 @ 2.

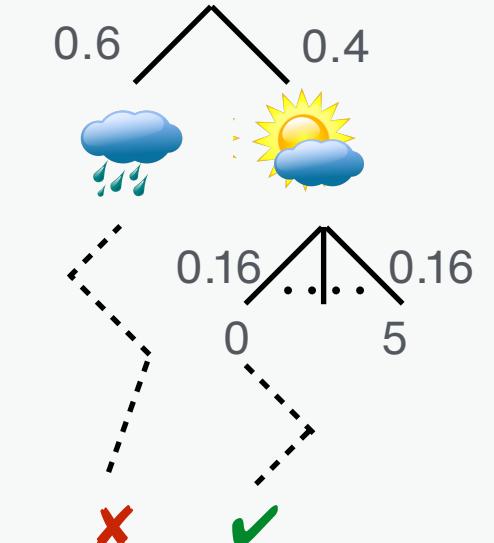
Efficiency by Inconsistency Pruning



In increasing time order:

- Ground out program over current domain
- Query regression, inconsistency pruning
- Extend current domain with \cup heads

Distribution Semantics



$$P(\text{query}) = \sum P(\checkmark)$$

(Already grounded) program rules $T = 0$

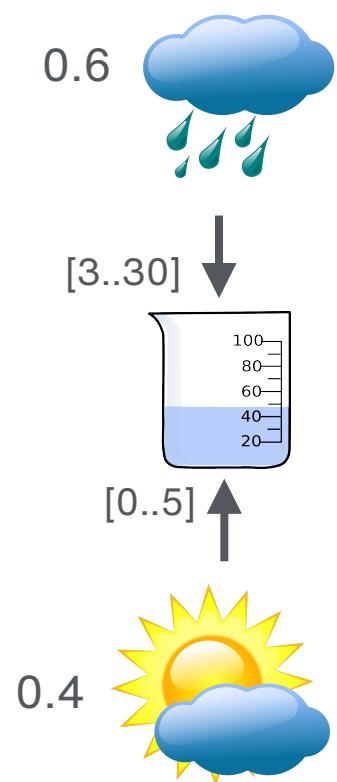
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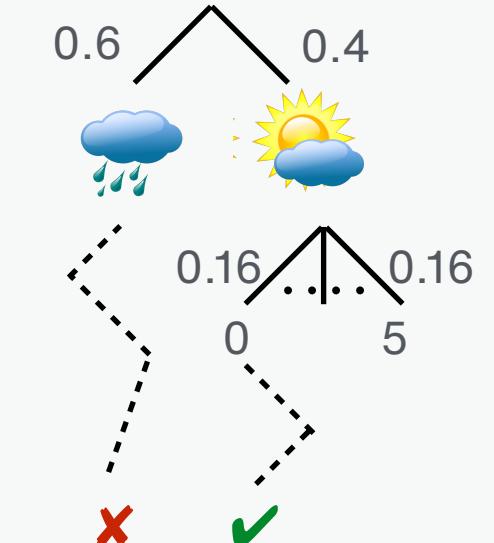
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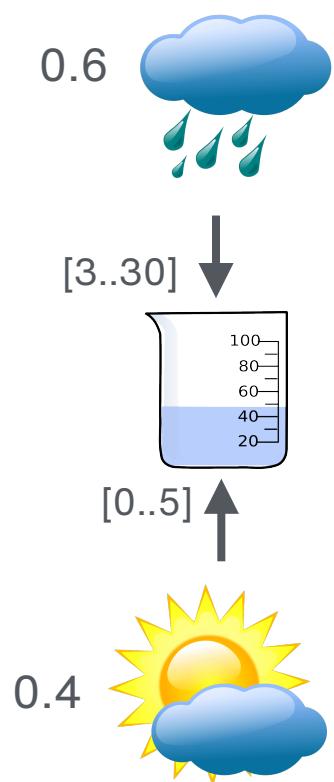
obs ~ [3..30] @ 0 :- state=rainy @ 0.

obs ~ [0..5] @ 0 :- state=sunny @ 0.

Strengthen query by regression

?- obs=0 @ 0, obs=2 @ 1, obs=20 @ 2, state=sunny @ 0.

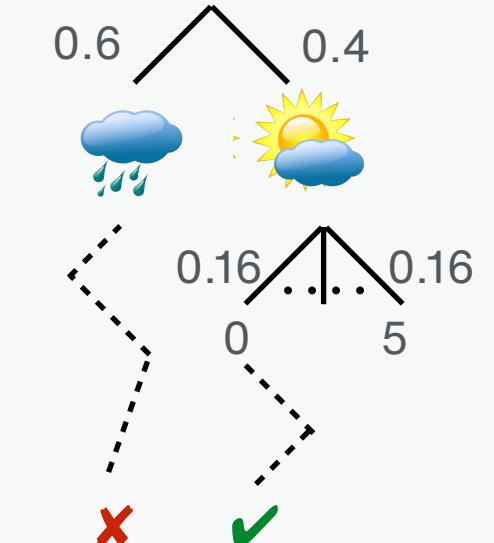
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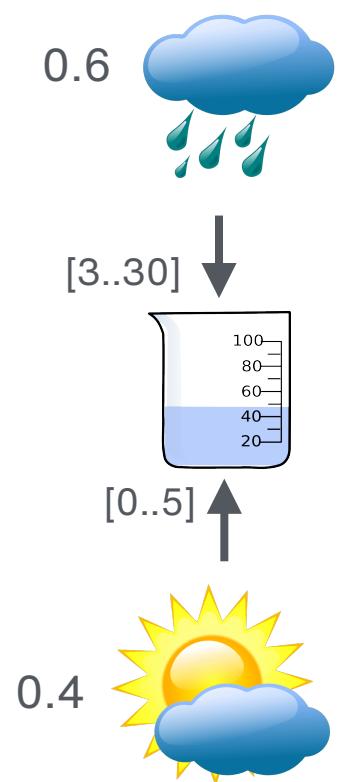
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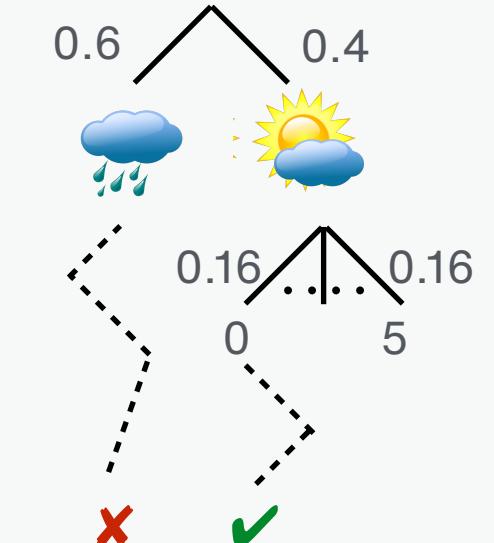
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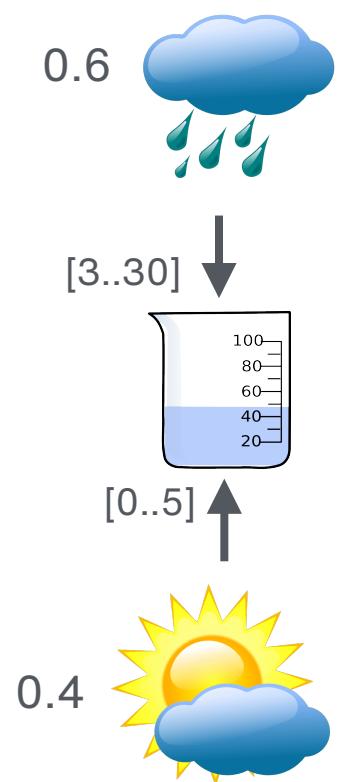
~~obs ~ [3..30] @ 0 :- state=rainy @ 0.~~ IP pruning

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Strengthen query by regression

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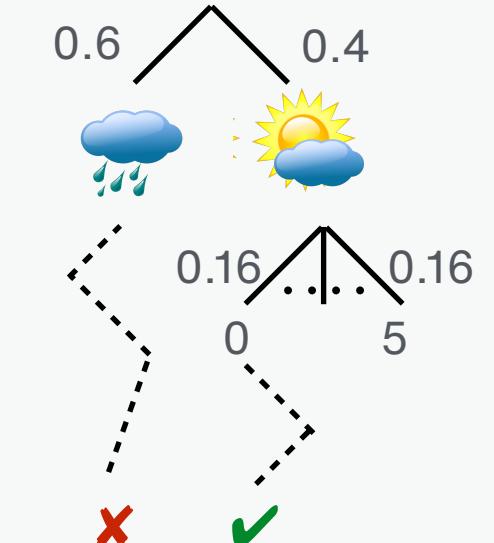
Efficiency by Inconsistency Pruning



In increasing time order:

- Ground out program over current domain
- Query regression, inconsistency pruning
- Extend current domain with \cup heads

Distribution Semantics



$$P(\text{query}) = \sum P(\checkmark)$$

(Already grounded) program rules $T = 0$ →

state ~ [[rainy, 0.6], [sunny, 0.4]] @ 0.

~~obs ~ [3..30] @ 0 :- state = rainy @ 0.~~ IP pruning

obs ~ [0..5] @ 0 :- state = sunny @ 0.

Domain after $T = 0$

state = rainy @ 0.

state = sunny @ 0.

obs = 0 @ 0.

obs = 1 @ 0.

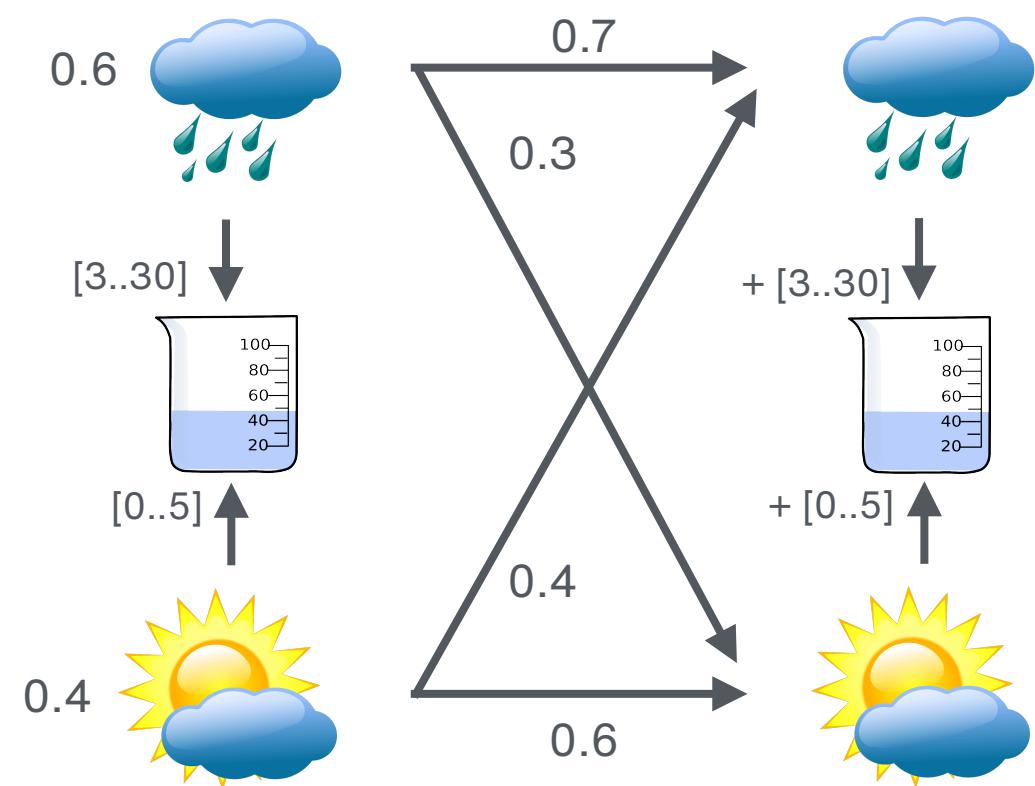
:

obs = 5 @ 0.

Strengthen query by regression

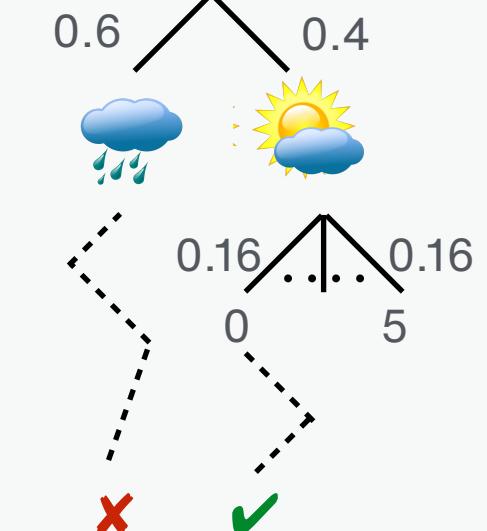
?- obs=0 @ 0, obs=2 @ 1, obs=20 @ 2, state=sunny @ 0.

Efficiency by Inconsistency Pruning



- In increasing stratification order:
- Ground out program over current domain
 - Query regression, inconsistency pruning
 - Extend current domain with \cup heads

Distribution Semantics



$$P(\text{query}) = \sum P(\checkmark)$$

Domain T = 1

`obs = 0 @ 0.`

`obs = 1 @ 0.`

`:`

`obs = 5 @ 0.`

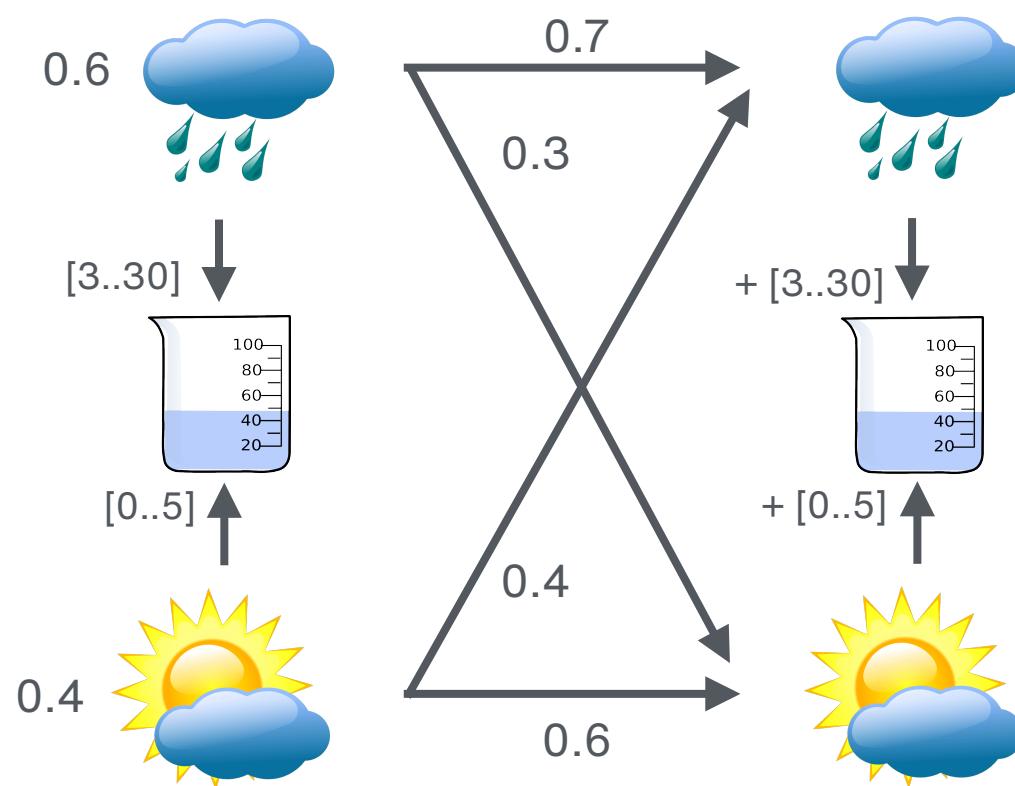
`state = rainy @ 1.`

`state = sunny @ 1.`

`?- obs=0 @ 0, obs=4 @ 1, obs=20 @ 2, state=sunny @ 0.`

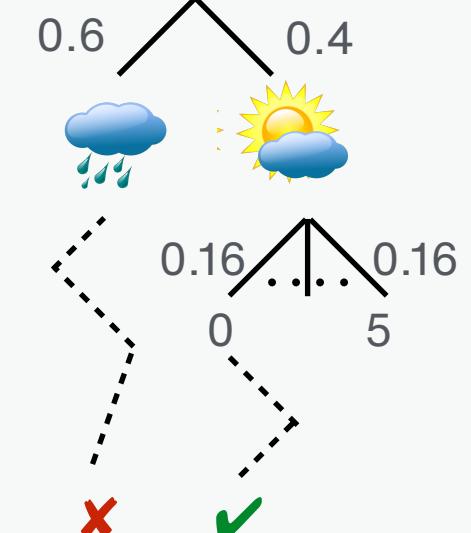
`obs ~ [R+3..R+30] @ T :-
state=rainy @ T,
T > 0,
obs=R @ T-1.`

Efficiency by Inconsistency Pruning



- In increasing stratification order:
- Ground out program over current domain
 - Query regression, inconsistency pruning
 - Extend current domain with \cup heads

Distribution Semantics



$$P(\text{query}) = \sum P(\checkmark)$$

Domain $T = 1$

```
obs = 0 @ 0.
obs = 1 @ 0.
:
obs = 5 @ 0.
state = rainy @ 1.
state = sunny @ 1.
```



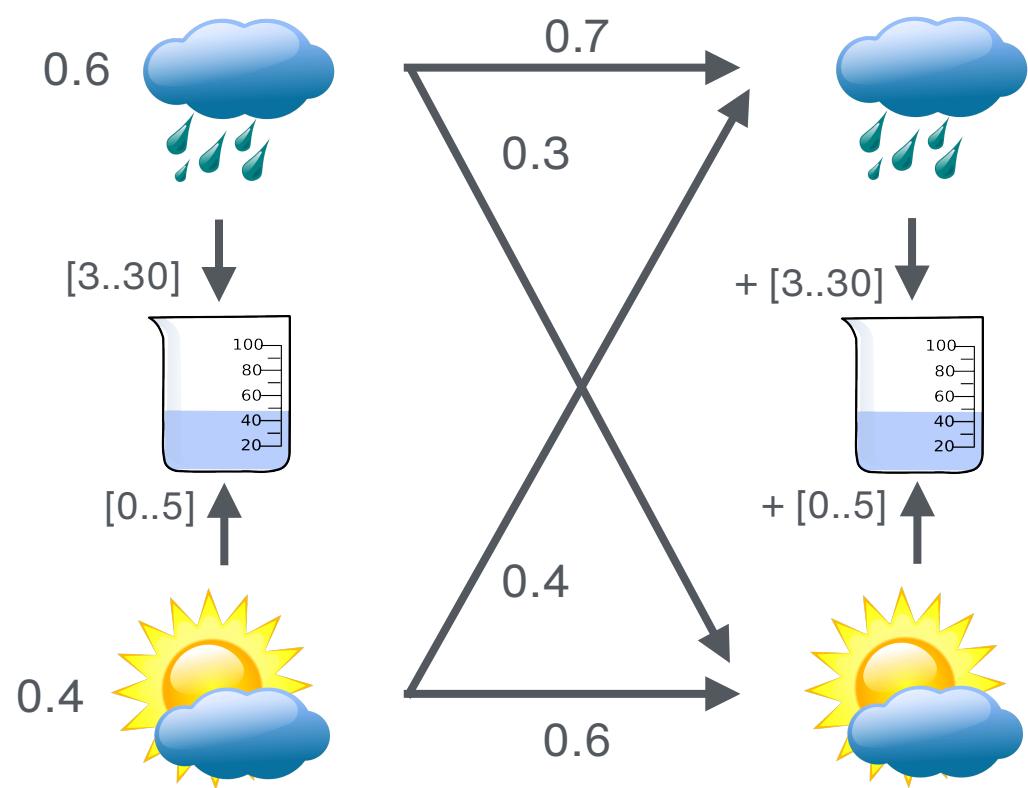
Grounded program rules $T = 1$

```
obs ~ [3..30] @ 1 :- state=rainy @ 1, obs=0 @ 0.
obs ~ [4..31] @ 1 :- state=rainy @ 1, obs=1 @ 0.
:
obs ~ [0..5] @ 1 :- state=sunny @ 1, obs=0 @ 0.
obs ~ [1..6] @ 1 :- state=sunny @ 1, obs=1 @ 0.
:
```

```
obs ~ [R+3..R+30] @ T :-
    state=rainy @ T,
    T > 0,
    obs=R @ T-1.
```

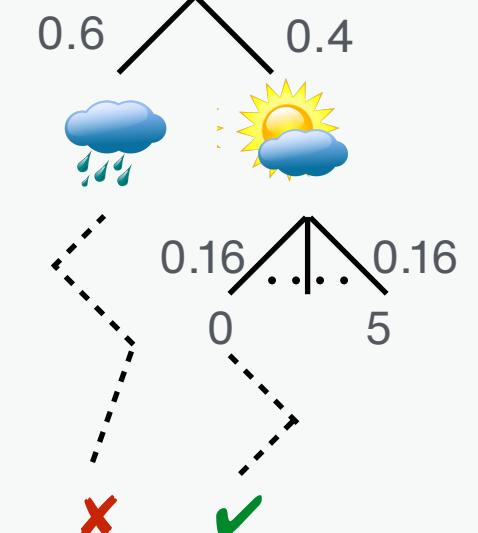
?- obs=0 @ 0, obs=4 @ 1, obs=20 @ 2, state=sunny @ 0.

Efficiency by Inconsistency Pruning



- In increasing stratification order:
- Ground out program over current domain
 - Query regression, inconsistency pruning
 - Extend current domain with \cup heads

Distribution Semantics



$$P(\text{query}) = \sum P(\checkmark)$$

Domain $T = 1$

$\text{obs} = 0 @ 0.$

$\text{obs} = 1 @ 0.$

:

$\text{obs} = 5 @ 0.$

$\text{state} = \text{rainy} @ 1.$

$\text{state} = \text{sunny} @ 1.$



Grounded program rules $T = 1$

$\text{obs} \sim [3..30] @ 1 :- \text{state}=\text{rainy} @ 1, \text{obs}=0 @ 0.$

$\text{obs} \sim [4..31] @ 1 :- \text{state}=\text{rainy} @ 1, \text{obs}=1 @ 0.$

:

$\text{obs} \sim [0..5] @ 1 :- \text{state}=\text{sunny} @ 1, \text{obs}=0 @ 0.$

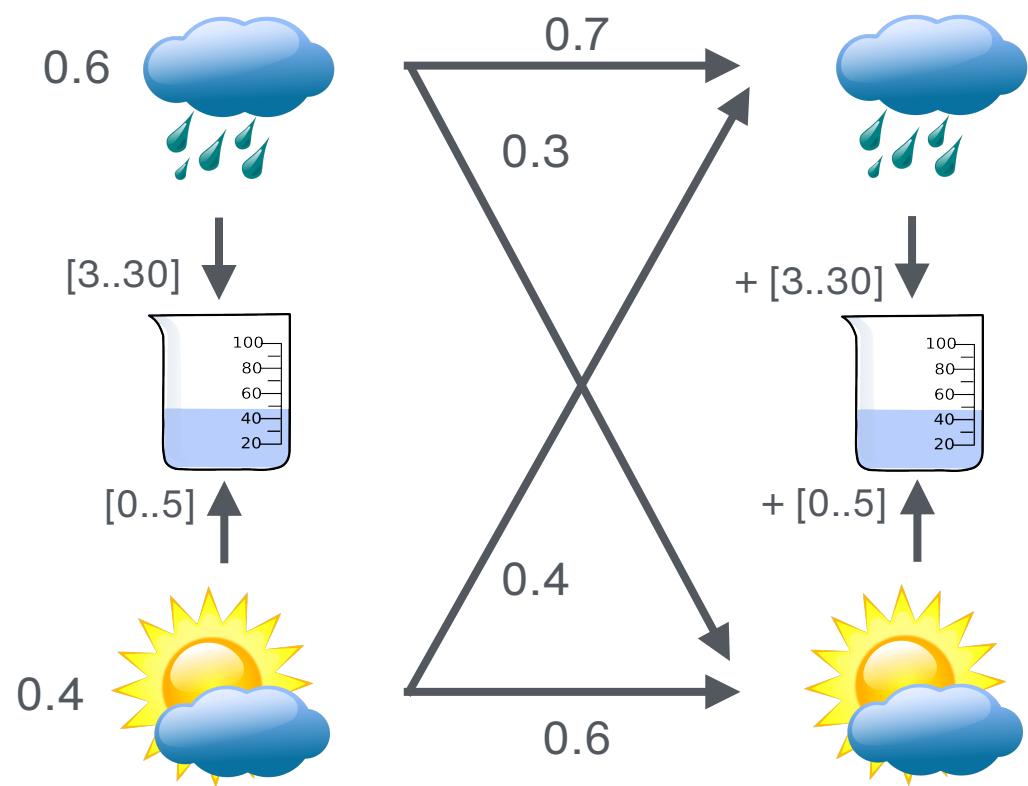
$\text{obs} \sim [1..6] @ 1 :- \text{state}=\text{sunny} @ 1, \text{obs}=1 @ 0.$

:

$\text{obs} \sim [R+3..R+30] @ T :-$
 $\text{state}=\text{rainy} @ T,$
 $T > 0,$
 $\text{obs}=R @ T-1.$

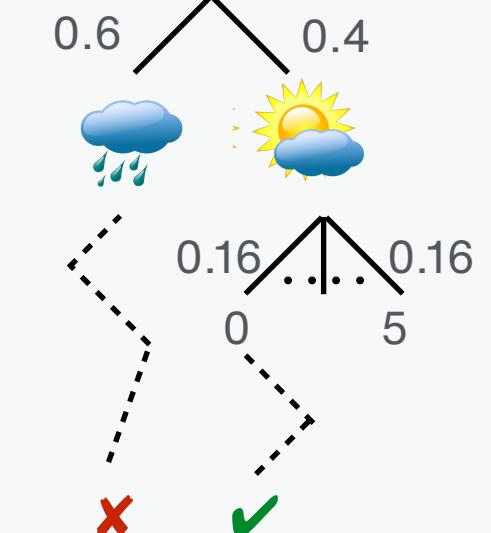
?- $\text{obs}=0 @ 0, \text{obs}=4 @ 1, \text{obs}=20 @ 2, \text{state}=\text{sunny} @ 0.$

Efficiency by Inconsistency Pruning



- In increasing stratification order:
- Ground out program over current domain
 - Query regression, inconsistency pruning
 - Extend current domain with \cup heads

Distribution Semantics



$$P(\text{query}) = \sum P(\checkmark)$$

Domain $T = 1$



Grounded program rules $T = 1$

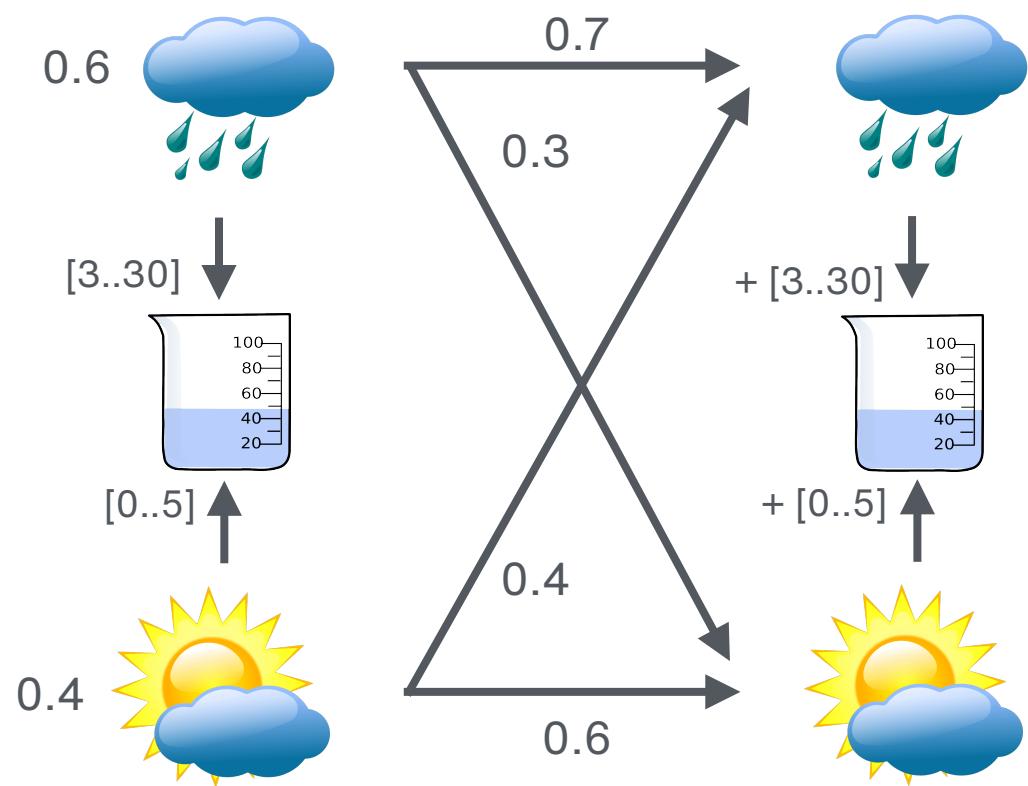
```
obs = 0 @ 0.  
obs = 1 @ 0.  
:  
obs = 5 @ 0.  
state = rainy @ 1.  
state = sunny @ 1.
```

```
obs ~ [3..30] @ 1 :- state=rainy @ 1, obs=0 @ 0.  
obs ~ [4..31] @ 1 :- state=rainy @ 1, obs=1 @ 0.  
:  
obs ~ [0..5] @ 1 :- state=sunny @ 1, obs=0 @ 0.  
obs ~ [1..6] @ 1 :- state=sunny @ 1, obs=1 @ 0.  
:
```

```
obs ~ [R+3..R+30] @ T :-  
state=rainy @ T,  
T > 0,  
obs=R @ T-1.
```

?- obs=0 @ 0, obs=4 @ 1, obs=20 @ 2, state=sunny @ 0.

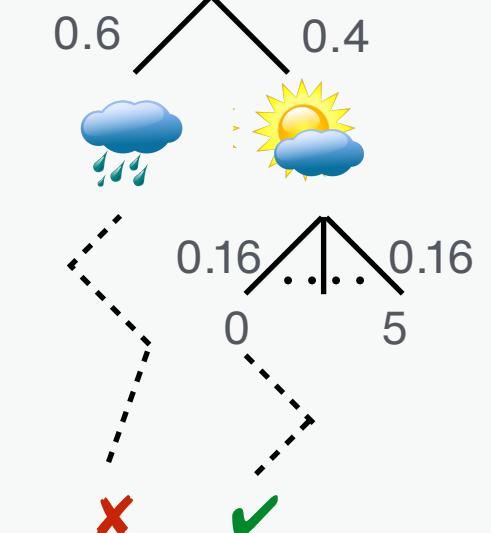
Efficiency by Inconsistency Pruning



In increasing stratification order:

- Ground out program over current domain
- Query regression, inconsistency pruning
- Extend current domain with \cup heads

Distribution Semantics



$$P(\text{query}) = \sum P(\checkmark)$$

Domain $T = 1$

$\text{obs} = 0 @ 0.$

$\text{obs} = 1 @ 0.$

:

$\text{obs} = 5 @ 0.$

$\text{state} = \text{rainy} @ 1.$

$\text{state} = \text{sunny} @ 1.$



Grounded program rules $T = 1$

$\text{obs} \sim [3..30] @ 1 :- \text{state} = \text{rainy} @ 1, \text{obs} = 0 @ 0.$

~~$\text{obs} \sim [4..31] @ 1 :- \text{state} = \text{rainy} @ 1, \text{obs} = 1 @ 0.$~~

IP

$\text{obs} \sim [0..5] @ 1 :- \text{state} = \text{sunny} @ 1, \text{obs} = 0 @ 0.$

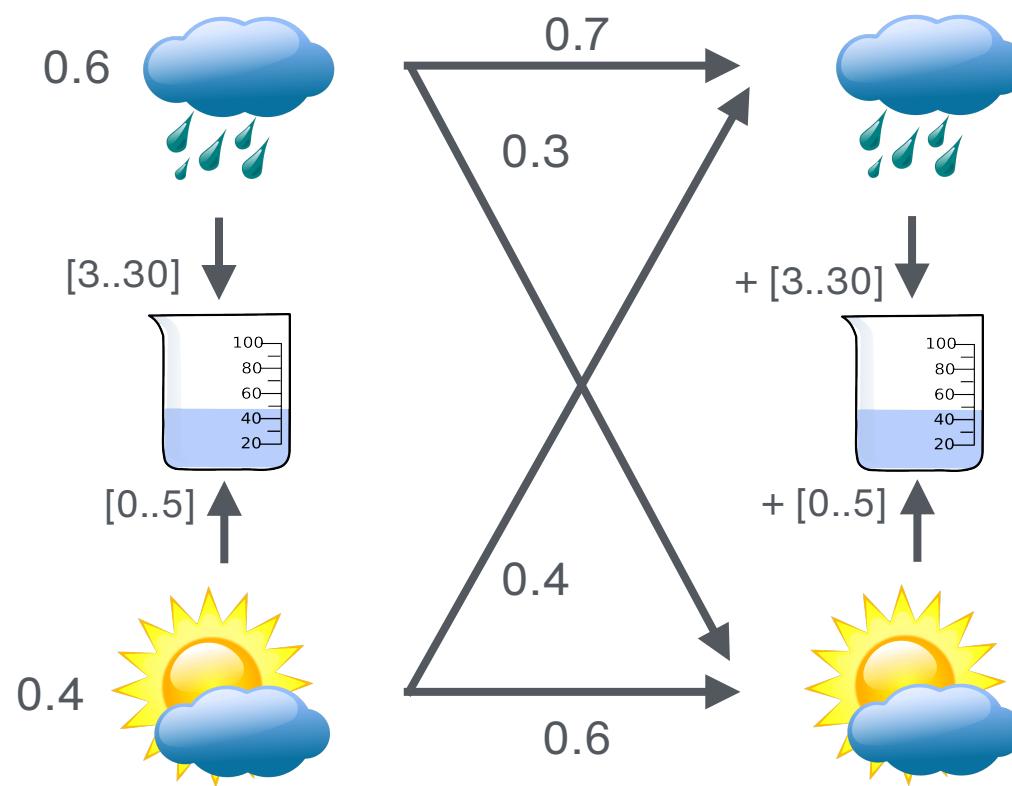
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IP

$\text{obs} \sim [R+3..R+30] @ T :-$
 $\text{state} = \text{rainy} @ T,$
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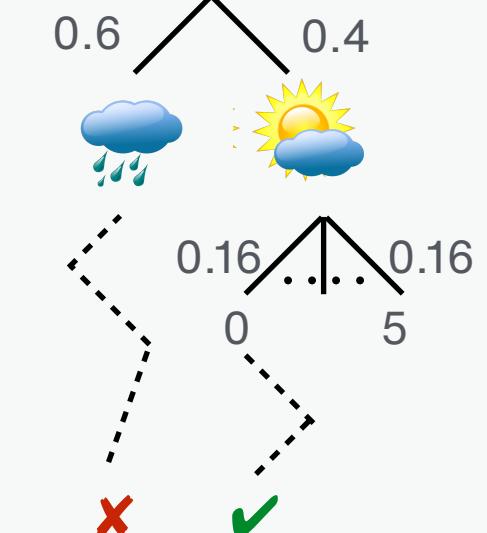
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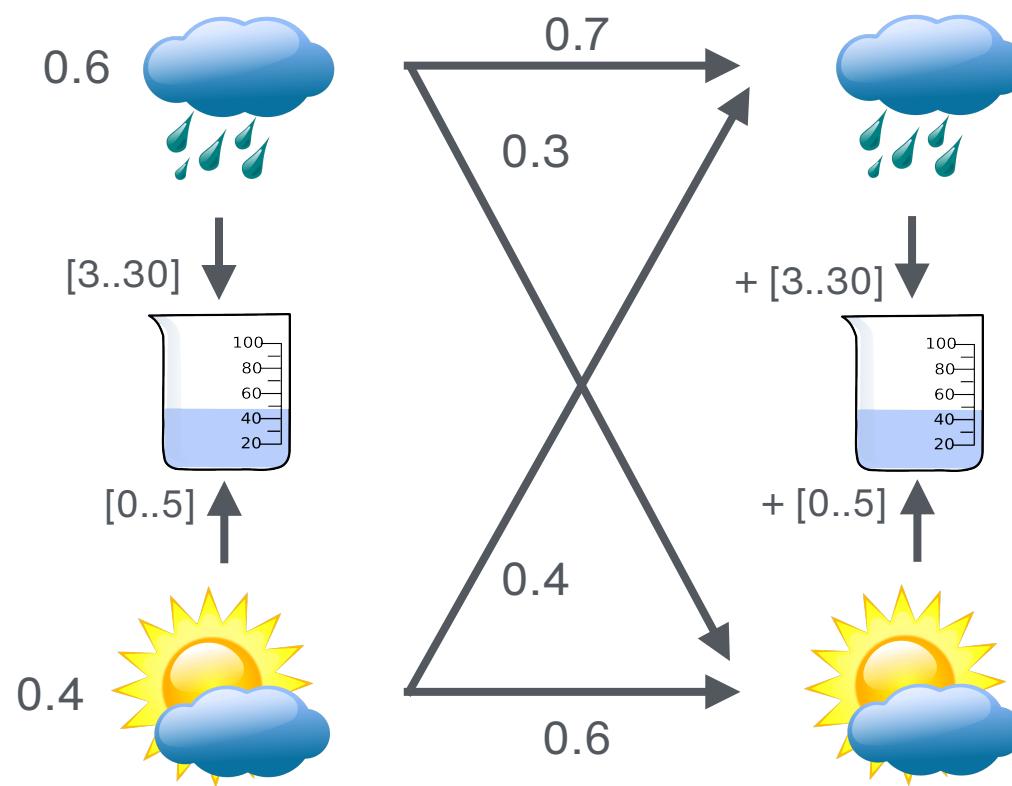
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IP

Inconsistency pruning: $62 \rightarrow 2$ rules

?- $\text{obs} = 0 @ 0, \text{obs} = 4 @ 1, \text{obs} = 20 @ 2, \text{state} = \text{sunny} @ 0.$

Efficiency by Inconsistency Pruning



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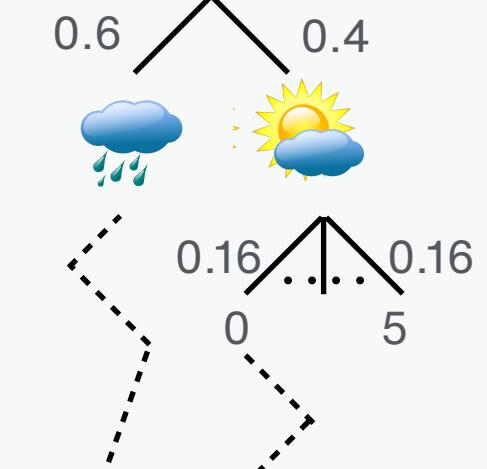
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Experimental Evaluation 1 - Hidden Markov Model

Runtime Results Fusemate vs ProbLog

Rainy/sunny example from above

% Queries for N=3

% Sunny

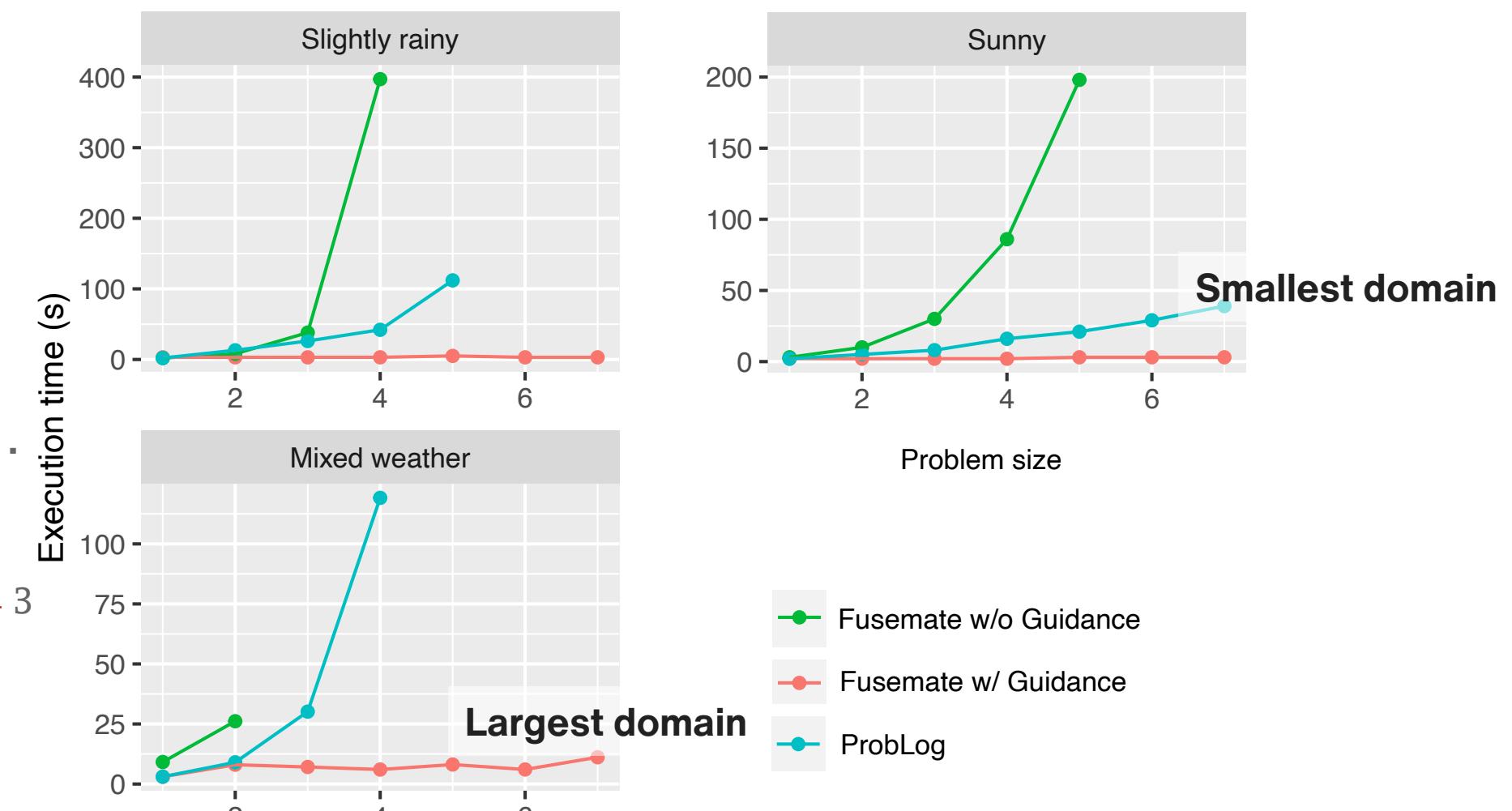
?-state=X @ 3 | obs=0 @ 1, obs=0 @ 2, obs=0 @ 3.

% Rainy

?-state=X @ 3 | obs=4 @ 1, obs=8 @ 2, obs=12 @ 3

% Mixed

state=X @ 3 | obs=0 @ 1, obs=4 @ 2, obs=24 @ 3.



Experimental Evaluation 1 - Hidden Markov Model

Runtime Results Fusemate vs ProbLog

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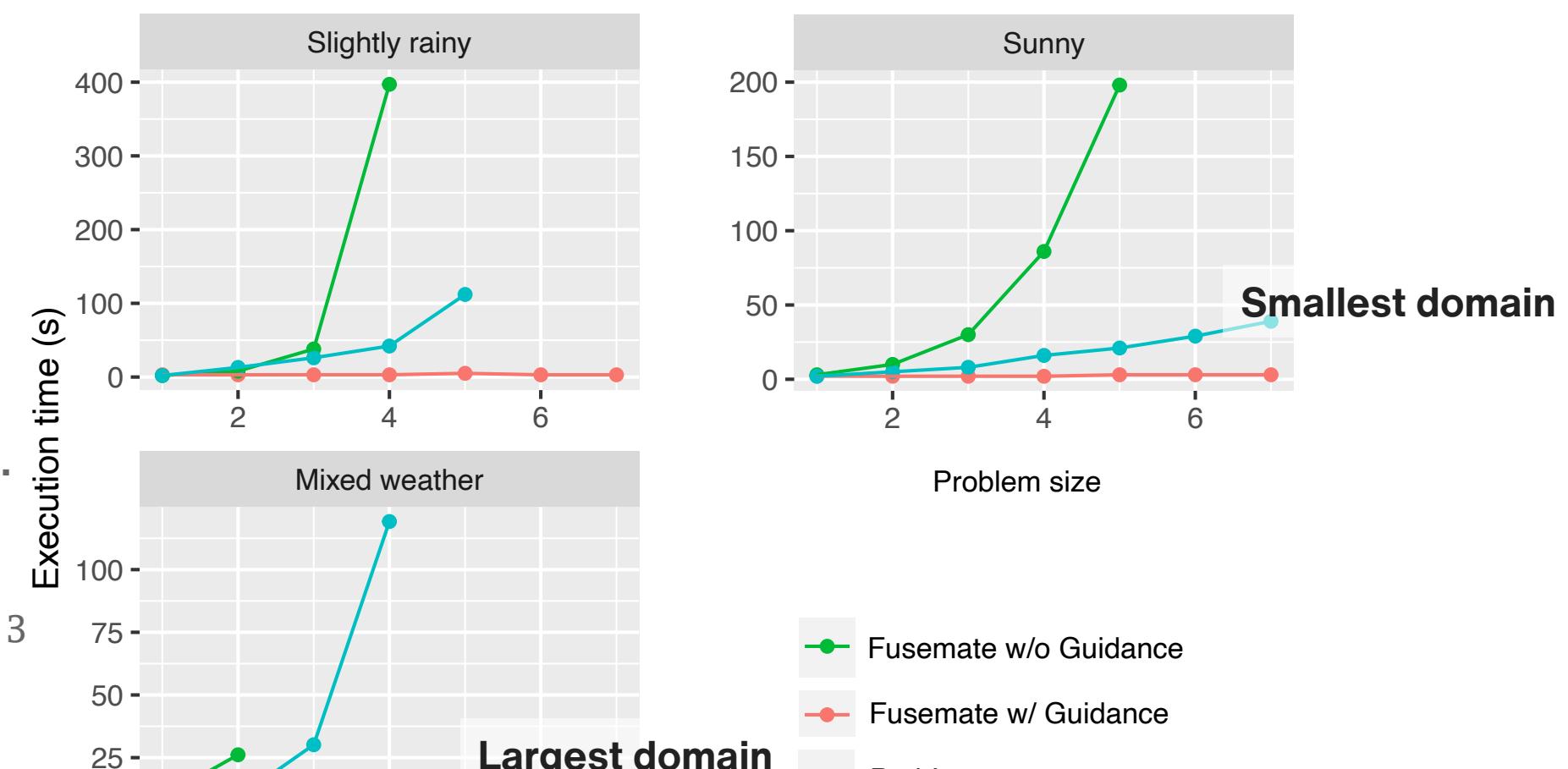
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Grounding vs Inference - Mixed Weather

N	Fusemate #ground rules		ProbLog		
	query-guided	unguided	total time	grounding time	#ground rules
2	2200	6500	9.0	8.3	53
3	2270	12900	30	19	276
4	2300	21400	119	33	499
5	2400	32000		50	682
6	2470	45000		65	839
7	2500	60000		95	1068

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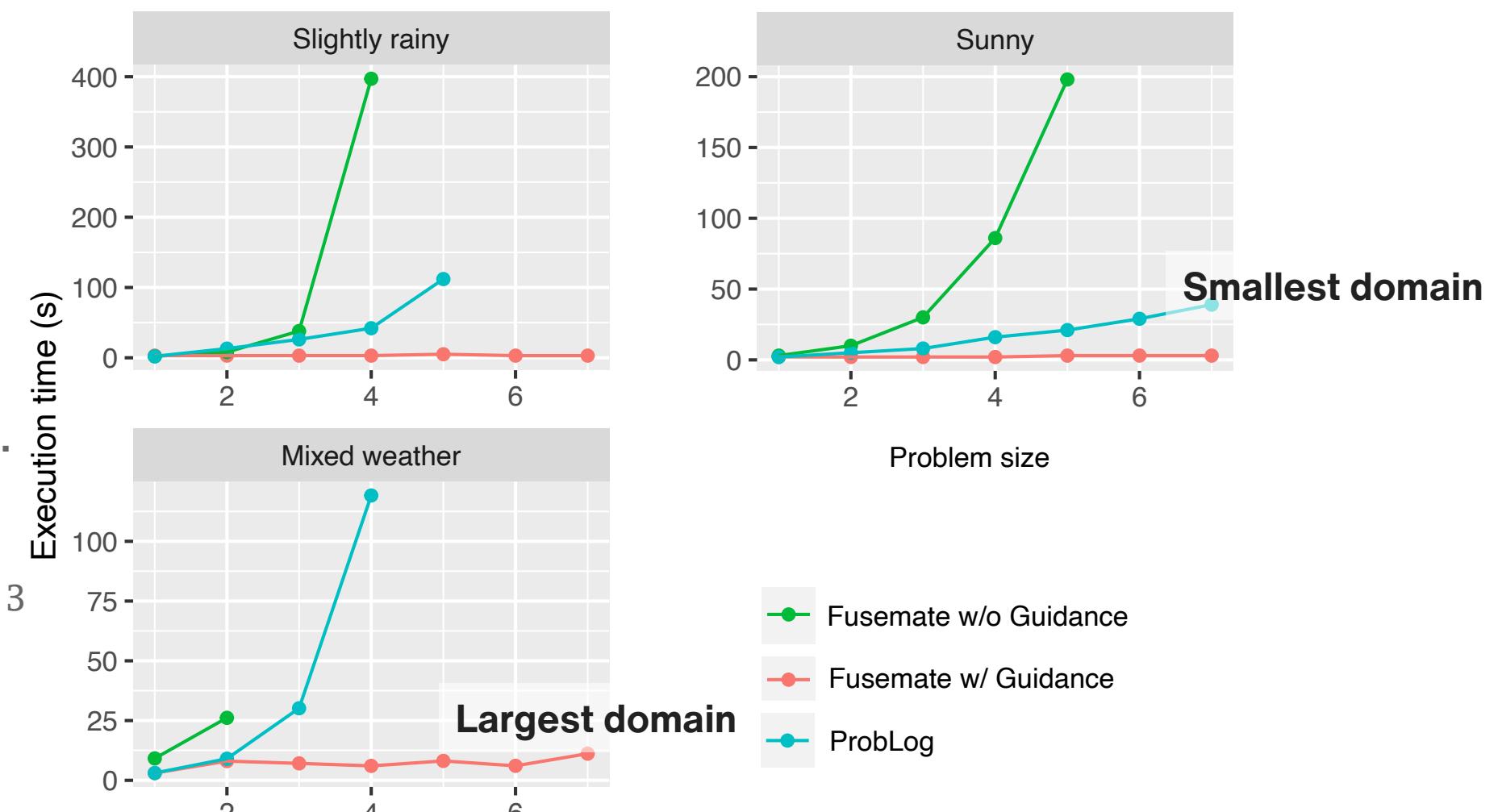
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Fusemate:

Improved grounding pays off
Inference engine implements UNA

ProbLog:

Grounding OK?

Bottleneck inference component?

Experimental Evaluation 2 - Markov Model

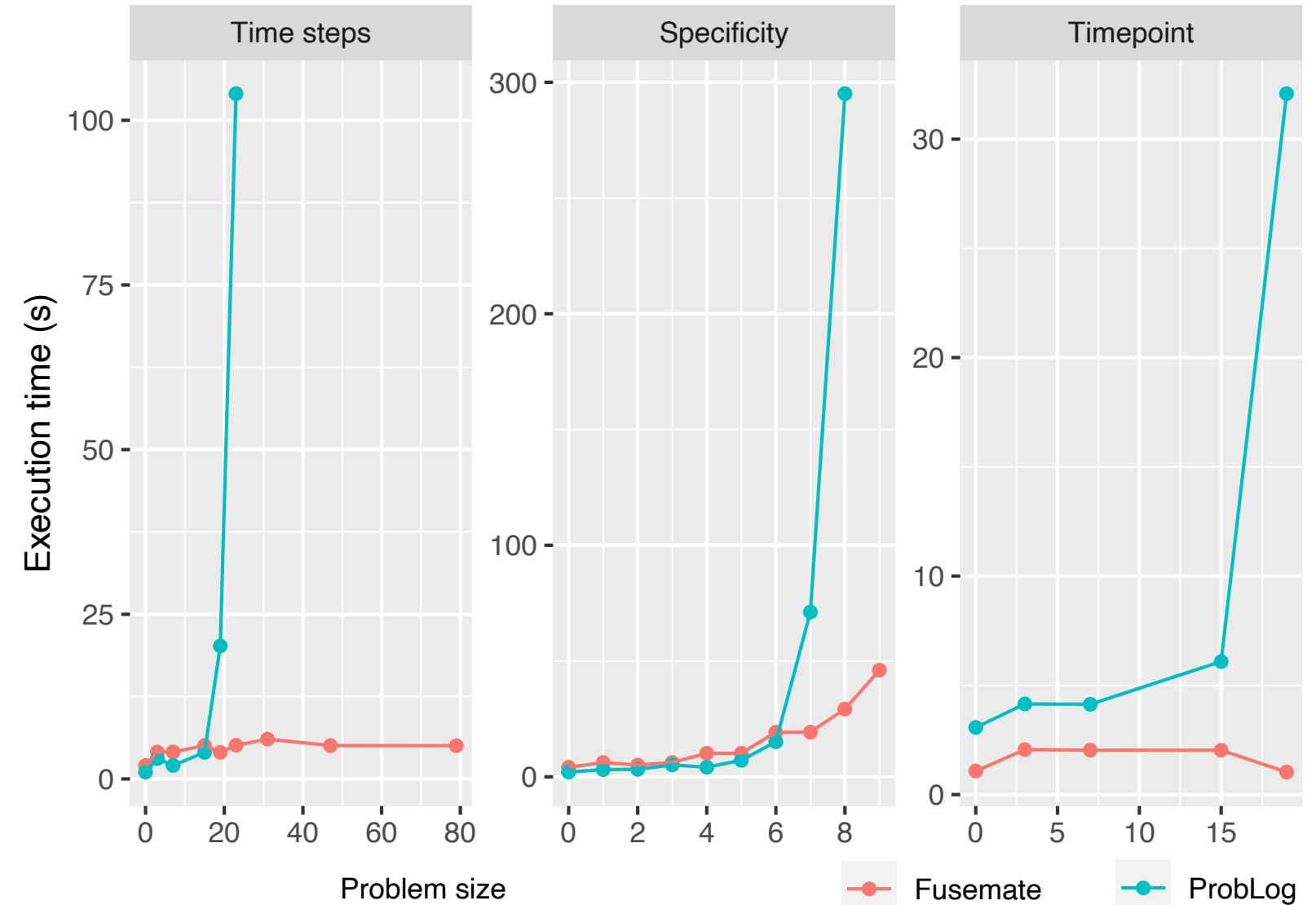
Runtime Results Fusemate vs ProbLog

```
%% Markov Model
in ~ [a, b, c] @ 0.
in ~ [[a, 0.9], [b, 0.05],
      [c, 0.05]] @ T+1 :- in=a @ T.
in ~ [[a, 0.7], [c, 0.3]] @ T+1 :- in=b @ T.
in ~ [[a, 0.8], [c, 0.2]] @ T+1 :- in=c @ T.
```

```
%% Time steps N = 20
?- in=a@0, in=a@1, ..., in=a@20.
```

```
%% Specificity, N = 7
?- in=a@0, in=a@1, in=L2@2, ..., in=L8 @ 8.
```

```
%% Timepoint, N = 20
?- in=a@23.
```

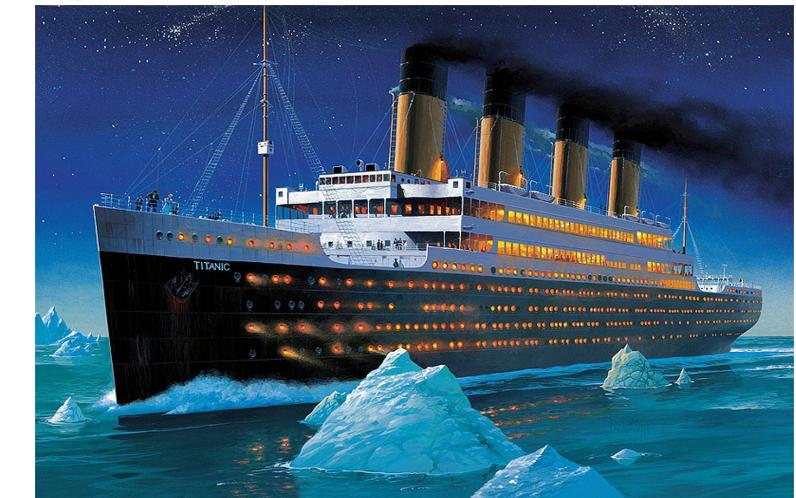


(ProbLog code from ProbLog tutorial web page)

Learning (Largely TBD in Fusemate)

Probability parameters learning

MLE, EM



Learning the structure of logic programs

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Probabilistic Version [Riguzzi 2015]

Logic programs from tabular data

Probabilistic version of CART

Probabilistic decision lists [2017]

FOLD-RM [Gupta et al, ICLP 2023]

CON-FOLD [McGinness and B, ICLP 2024]

= FOLD-RM with confidence values

Very short explanations

	PassengerId	Survived	Pclass	Title	Sex	Age	SibSp	Parch	STON/OBS
0	1	False	3	Mr	male	22	1	0	
1	2	True	1	Mrs	female	38	1	0	
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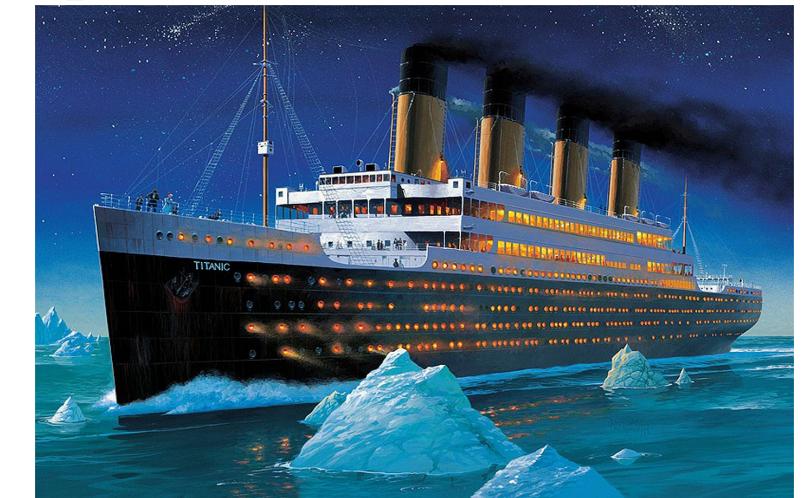
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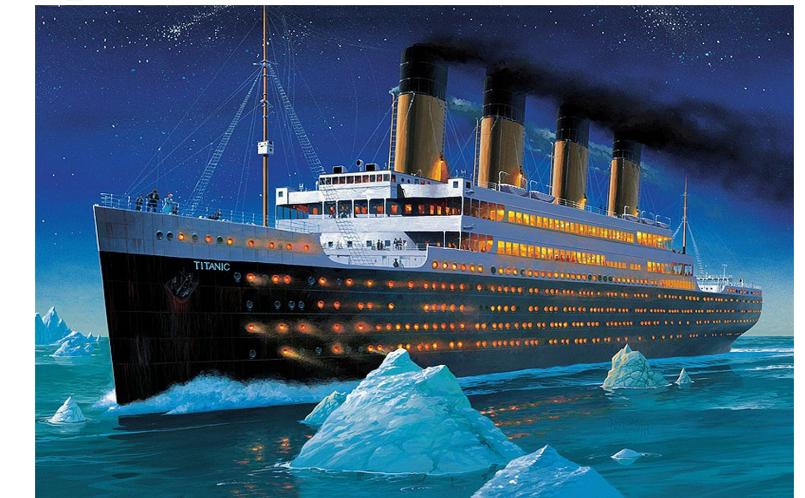
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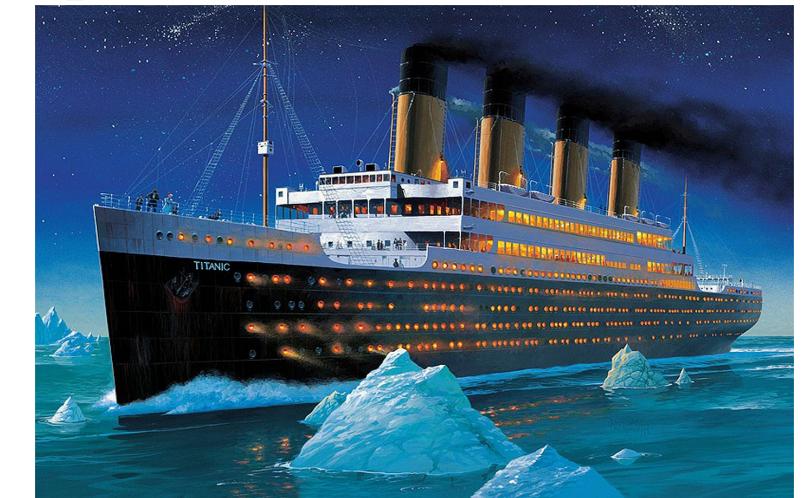
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Part 1

- Probabilistic
- Logic
- Programming
- **Fusemate Implementation**

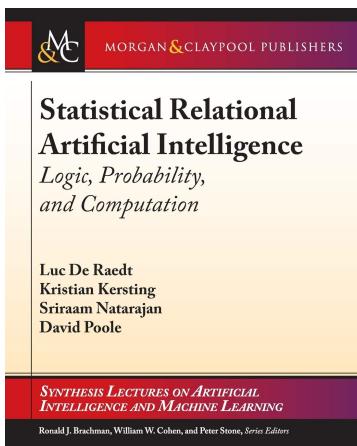
Part 2

- **LLMs + Logic (Programming)**
- **Neural Networks + Logic (Programming)**

Statistics/NN/LLM+ Logic Combinations

StarAI =
RelationalAI/Logic +
Learning + Statistics (1980s)

Fusemate



LLMs + Logic

Augmented Language Models: a Survey

Grégoire Mialon* et al

gmialon@meta.com

See below

NeSy =
Neural Networks + Symbolic Reasoning

Neural-Symbolic Learning and Reasoning:
A Survey and Interpretation

Tarek R. Besold et al

Department of Computer Science, City, University of London

TAREK-R.BESOLD@CITY.AC.UK

Position: LLMs Can't Plan,
But Can Help Planning in LLM-Modulo Frameworks

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NeSy + StarAI ?

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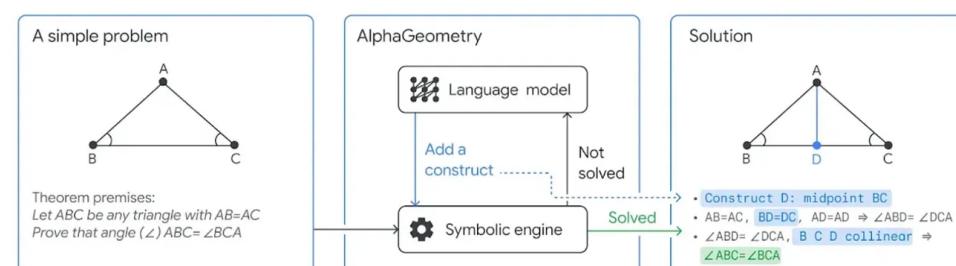
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DeepProbLog - see below

AlphaZero -> AlphaGeometry, AlphaProof

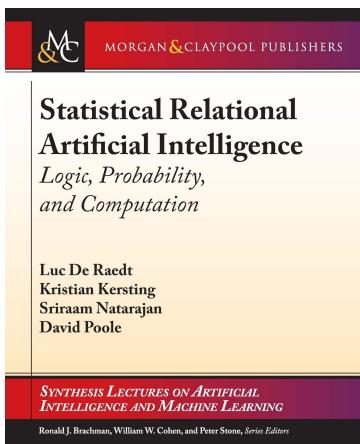


Lachlan's PhD - "AlphaPhysics"

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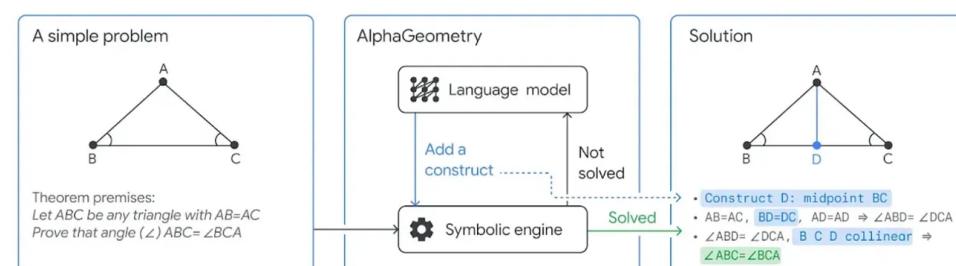
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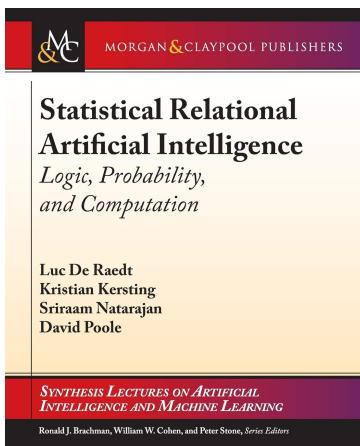


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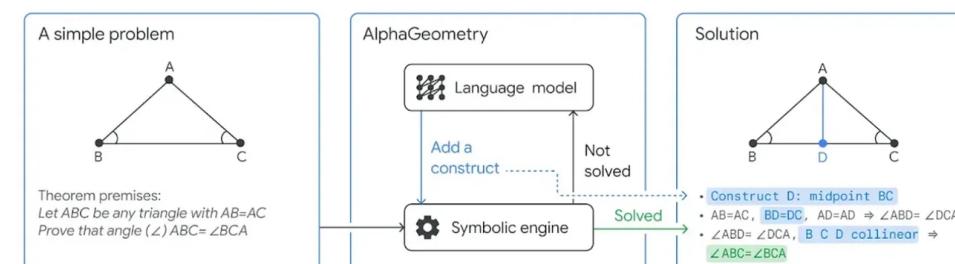
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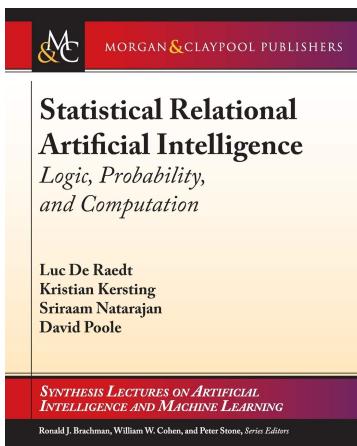


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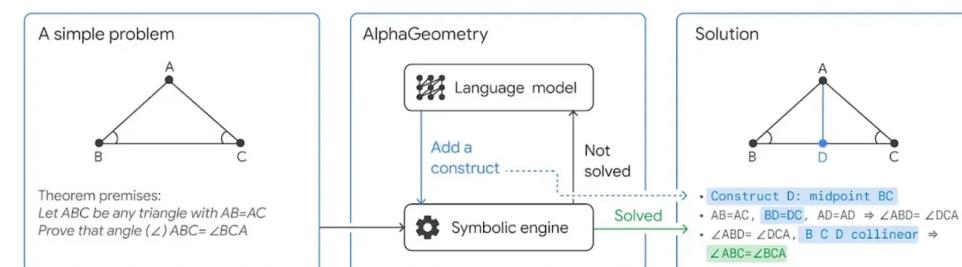
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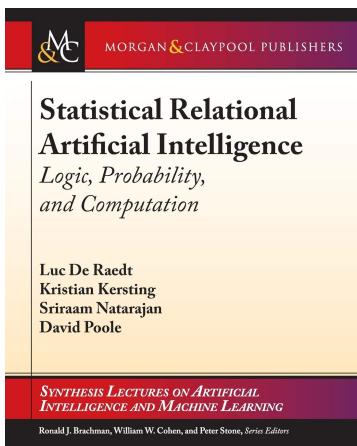


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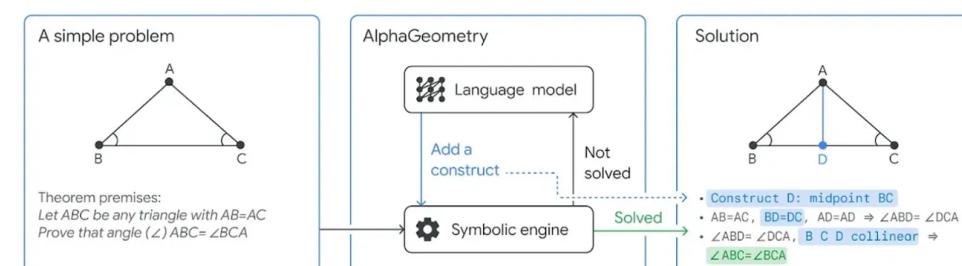
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LLM + Logic: LLMs Are Logic Reasoners?

Task LLM with Reasoning

ProntoQa [Saparov and He, 2023]

Synthetic Data

Varying redundancy (distractors)

Varying length of reasoning chains

Each composite number is not liquid. Every composite number is a fraction. Every composite number is a number. Negative numbers are not large. Every fraction is large. Each fraction is a real number. Fractions are integers. Integers are temperate. Each number is slow. Each even number is loud. Even numbers are natural numbers. Alex is an even number. Alex is a composite number.

True or false: Alex is large.

Prompt Engineering

In-prompt training one/view shot

Chain-of-thought “explain your reasoning”

Instruct LLM to use strategies

(backward/forward/SOS - own work)

Self-critique

Explainability?

LLM explanation can be nonsense

Correctness and Scalability?

More complex logic, e.g. quantifiers

Planning task, see Subbarao Kambhampati

Reasoning at all?

Or lookup?

LLM + Logic: Hierarchical Combination

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Example 3.1:

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[McGinness, B., LPAR 2024]

Each integer is not fruity.
Negative numbers are brown.
Wren is an integer.

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Translation errors?

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Neural Networks + Symbolic Reasoning

DeepProbLog

Neural probabilistic logic programming in DeepProbLog

[Manhaeve et al, AIJ, 2021]

Inference

Query - does the following hold true?

addition(**3**, **5**, 8)

addition(**3**, **8**), addition(**2**, **5**, 63)

Use backward chaining with

NN classifier for probabilistic facts

Returns query probability

Learning

End-to-end differentiable

-> back propagation modulo background knowledge

Here: learns digit image classifier from addition examples

Backward Chaining

?- addition(**3**, **5**, 8)

addition(X, Y, Z) :- digit(X, N1), digit(Y, N2), Z is N1+N2.

0.8 :: digit(**0**, 0); 0.1 :: digit(**0**, 1).

0.2 :: digit(**1**, 0); 0.6 :: digit(**1**, 1).

...

Hard
constraint

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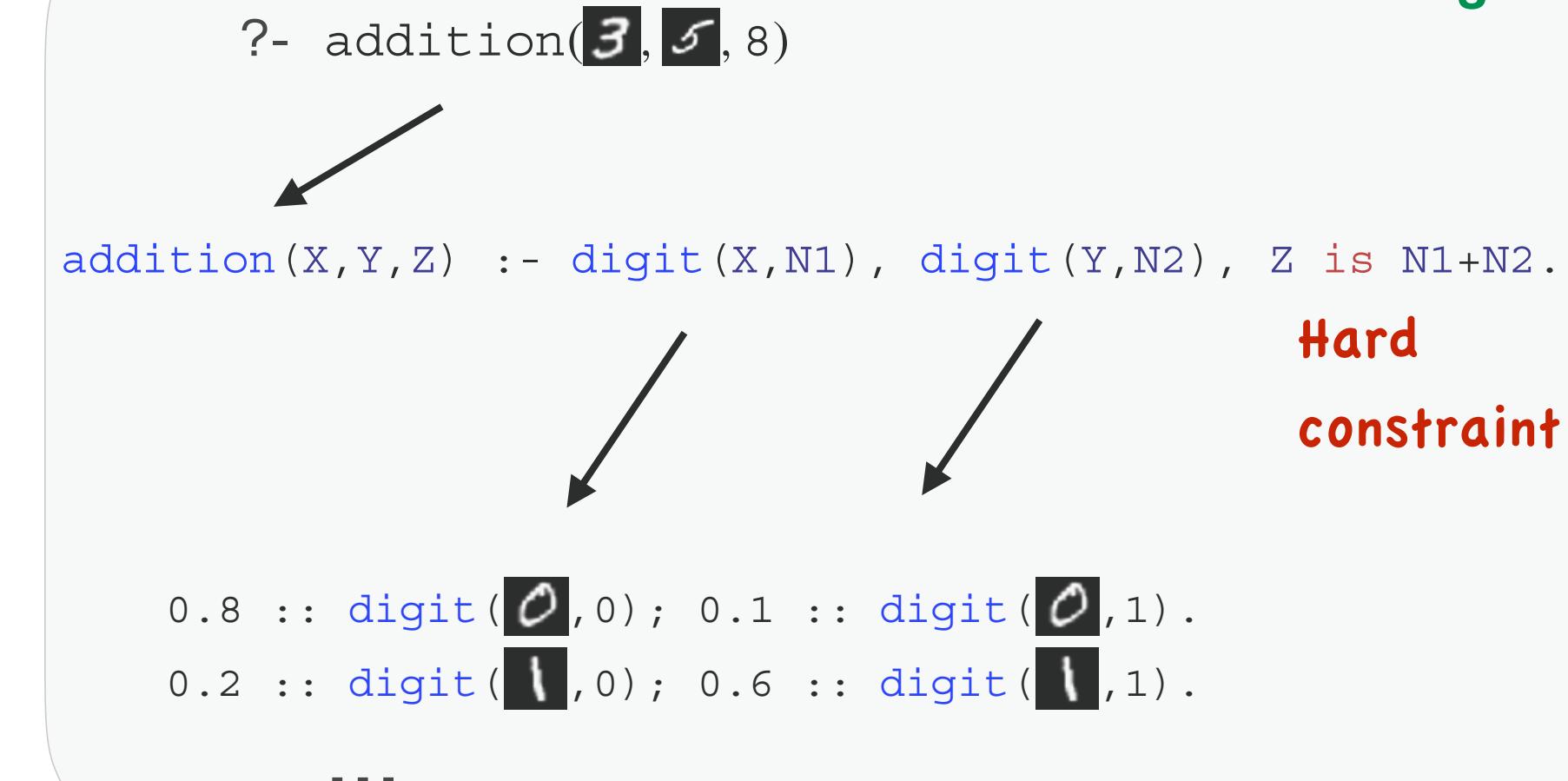
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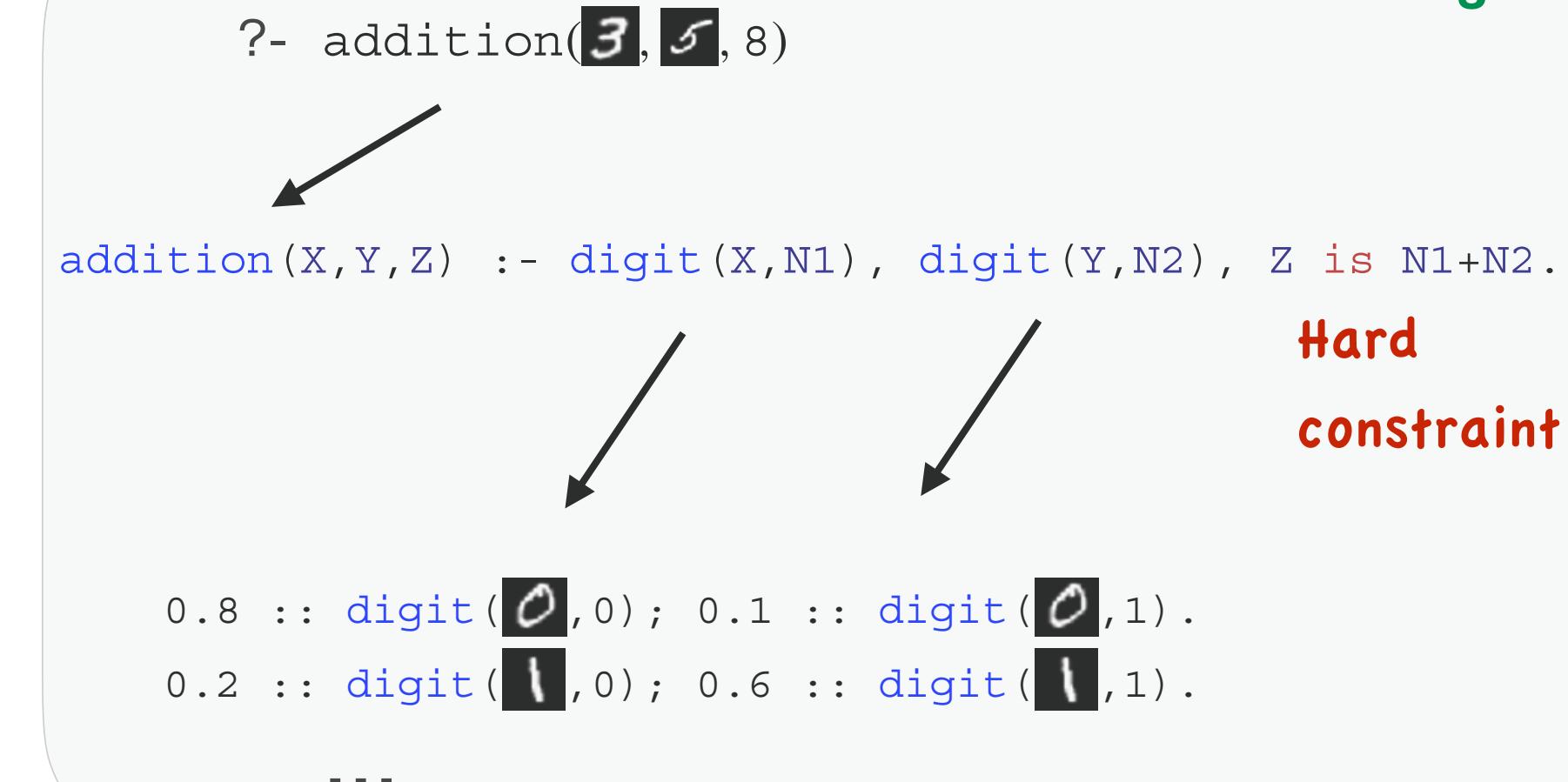
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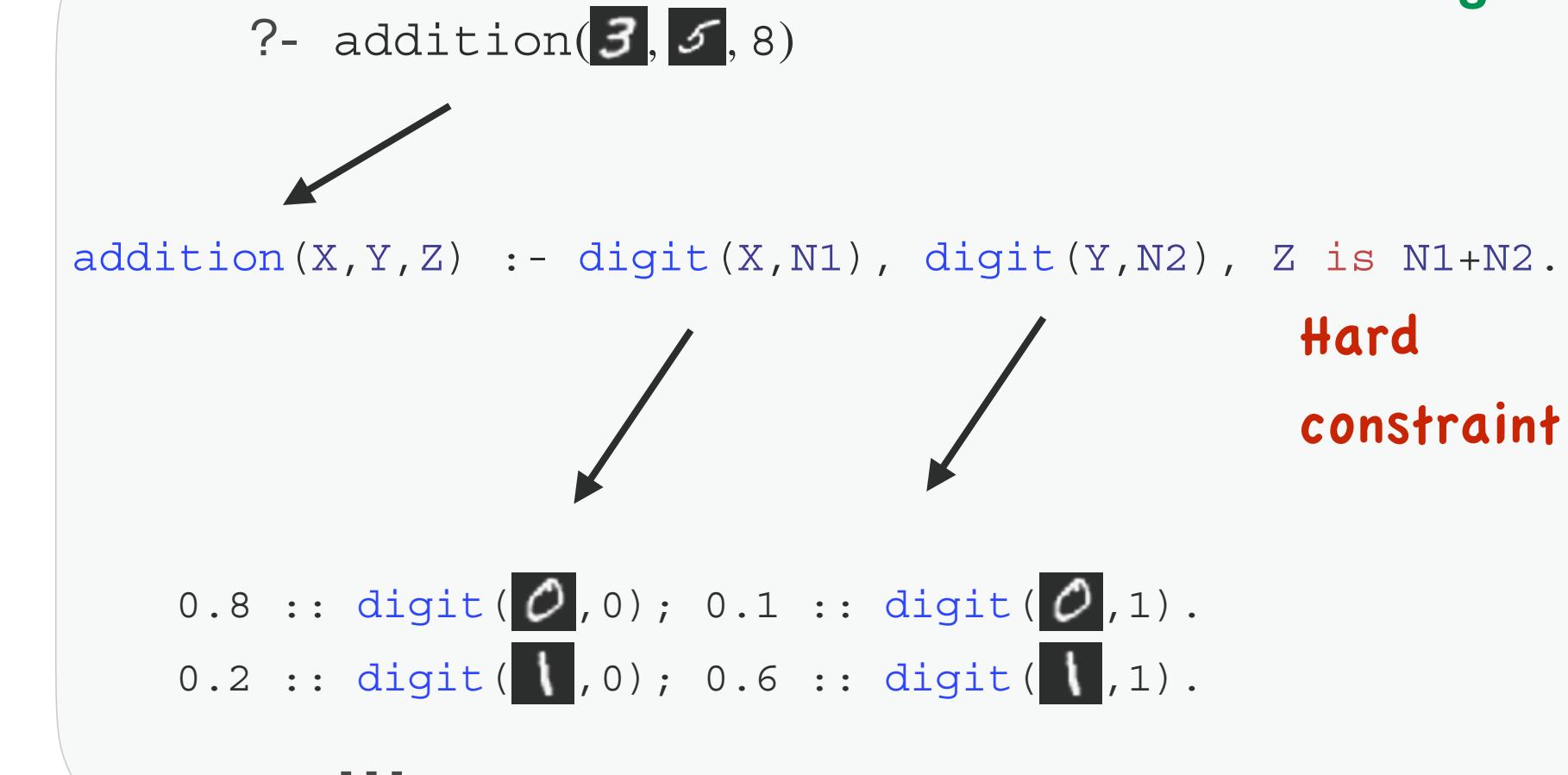
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“Strong” coupling
Counterpart LLM modulo?

Neural Networks + Symbolic Reasoning

Many More Architectures

- *Differentiable Theorem Proving* [Rocktäschel]

```
parentOf(HOMER, BART).  
grandfatherOf(X, Y) :- fatherOf(X, Z), parentOf(Z, Y).  
grandfatherOf(ABE, Q)? {Q/LISA}, {Q/BART}
```

Reasoning in embedding space:

Example: unify $\mathbf{v}_{\text{grandfatherOf}}(\mathbf{X}, \mathbf{v}_{\text{BART}})$ with $\mathbf{v}_{\text{grandpaOf}}(\mathbf{v}_{\text{ABE}}, \mathbf{v}_{\text{BART}})$

$$\Psi = \{\mathbf{X}/\mathbf{v}_{\text{ABE}}\}, \quad \tau = \min(e^{-\|\mathbf{v}_{\text{grandfatherOf}} - \mathbf{v}_{\text{grandpaOf}}\|_2}, e^{-\|\mathbf{v}_{\text{BART}} - \mathbf{v}_{\text{BART}}\|_2})$$

- *Semantic Probabilistic Layers for Neuro-Symbolic Learning* [Ahmed et al NeurIPS, 2022]
Logic constraints at the output layer, e.g. exclusivity constraints for classification
- *FFNSL: Feed-Forward Neural-Symbolic Learner* [Cunnington, Law, Lobo, Russo 2023]
- *Encodings of logic within NNs*
- *Logic Tensor Networks*
- *Neural Datalog over time*

Conclusions

Fusemate

- Probabilistic Logic Programming system
- Good
 - Expressivity, good Python interface, reasonably optimized for intended use case (HMM-ish)
- Needs work
 - Documentation, efficiency

LMM + Logic

- Current focus of research and D61 applications for “Explainability”
 - ML/LLM -> generate solution candidates
 - Probabilistic logic -> validate/complete solution candidates