

Getting Started with the Stochastic Conflict Model

By Scott D. Peckham

Introduction

The Stochastic Conflict Model was developed for Kimetrica/AIR, with funding from the DARPA World Modelers program. It is an open-source model, written entirely in Python, and distributed on GitHub as a Python package. The package includes the model itself, a set of utilities, documentation, a graphical user interface (GUI), and a Jupyter notebook that shows how to use the model and its GUI. While there are several ways to run the model as explained in the section: [Different Ways to Run the Model](#), the GUI is the simplest.

While the model was written so that it can be used for any region on Earth (i.e., for any geographic bounding box), it has so far only been applied to a region that spans the Greater Horn of Africa. The phrase “Horn of Africa” refers to the countries: Djibouti, Eritrea, Ethiopia, Somalia (and the de facto country, Somaliland). The phrase “Greater Horn of Africa” additionally includes the countries: Kenya, Uganda, Sudan, and South Sudan. The region spanned by the model (using defaults) fully contains the Greater Horn of Africa countries, as well as some piece of the following countries: Congo, Tanzania, Rwanda, Burundi, Yemen, Saudi Arabia, Egypt, and others. The section titled [Examples for the Greater Horn of Africa](#) contains several images generated using different parameter settings.

This getting started guide is a shortened version of the full **User’s Guide**, which contains full mathematical and implementation details, information on containerization, a comparison to the Forest-Fire Model, and many more examples and images. This guide consists of the following sections:

- [Conceptual Overview of the Model](#)
- [Explanation of Key Model Parameters](#)
- [Explanation of Other Model Parameters](#)
- [Explanation of Model Output Parameters](#)
- [Different Ways to Run the Model](#)
- [Examples for the Greater Horn of Africa](#)
- [Comparison to ACLED Data](#)
- [Preparing Input Grids for the Model](#)
- [Conclusions and Future Work](#)
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- [References – Wikipedia](#)

Conceptual Overview of the Model

The Stochastic Conflict Model is loosely based on a cellular automaton model known as the “Forest-fire model” (Drossel and Schwabl, 1992; Forest-fire Model, 2021) which is a very simple model for how forest fires emerge and spread. Conflicts have some similarities to forest fires in that they are **triggered** by random events, they **spread** spatially to other grid cells, and they are eventually **resolved**. Due to these broad similarities, the Forest-fire model served as the inspiration for the current model, even though that model is much simpler. The complete User’s Guide provides a brief review of the Forest-fire model in Appendix 1, and also a list of papers in the section References – Forest-Fire Model.

The Stochastic Conflict Model is **stochastic** (i.e., it uses probability theory and random variables), **dynamic** (i.e., the model state evolves in time), **geospatial** (i.e., the model domain is a grid), and **data-driven**. It is also **mechanistic**, in the sense that it explicitly simulates the important processes of conflict emergence, spreading and resolution. (Note that machine learning models do not represent these mechanisms.) Its main purpose is to help the modeler understand the mechanics of conflict and how each of these processes and various indicators influence the dynamic character of a conflict. The model can exhibit a very wide range of behaviors, depending on the values of its input parameters and input grids. It consists of the following 4 key components.

1. Unrest - The Potential for Conflict to Emerge. For each geospatial grid cell, we define a variable called **unrest**, which is intended to quantify the potential for conflict within that grid cell. This is a composite variable or **index** that is a function of one or more **indicator** variables. Here, we define an **indicator** to be any variable that may help to quantify a *qualitative property* of an object or system, but that by itself provides only an indirect or insufficient measure of that property. There are many indicator variables that can be used (and have been used) in an effort to quantify the potential for conflict and to predict the emergence of conflict. These can be roughly grouped into the following categories.

- (1) **climatic conditions** (e.g. rainfall amount, drought, flooding, heat-wave, sea-level rise)
- (2) **economic conditions** (e.g. food shortage, food prices, unemployment, income disparity, resource richness, inflation rate, GDP/capita, crop failure),
- (3) **social conditions** (e.g. population count, population density, population growth, quality of life, standard of living, infant mortality rate, “identity group” mixture, education, access to health care, change in ethnic mix, maybe due to migration, land cover change, deforestation, “youth bulge”, disasters, urbanization)
- (4) **geographic conditions** (e.g. distance to border, distance to capital, remoteness)
- (5) **political conditions** (e.g. time to next election, polarization, regime change, assassination of a leader, ethnic cleansing)
- (6) **historical conditions** (e.g. time since the last conflict)

Note: We do not expect for all of these variables to be equally important in determining the degree of unrest. Previous modeling work in Ethiopia used a machine-learning algorithm and

found that population density, the amount of rainfall, and land cover change were among the most important indicators. Note that these 3 indicators may be less dominant in other countries.

Note: Machine-learning algorithms/models are one method than can be used to create a grid of “unrest” values for a given region from various indicators.

Note: In the forest-fire analogy, unrest might correspond to the degree of “flammability”, “combustibility”, “dryness” or “fuel availability” (e.g. biomass). In the forest fire model, however, “flammability” is a boolean property -- it is 1 if there is a tree in the grid cell and 0 if there isn’t. See Combustibility and Flammability (2021).

2. Trigger Events - The Initiation of Conflict. For each grid cell, there is a probability that some event will occur that initiates or sparks a conflict. (And that initial conflict may escalate or de-escalate, depending largely on how it is handled and the power discrepancy between the parties.) Conflicts are initiated as a result of negative interactions between people. This simple fact helps to explain the strong correlation between the occurrence of conflicts and population count or density. Let $p(i)$ denote the probability that a conflict is initiated in a grid cell with index i . We then expect that $p(i)$ will be an increasing function of --- and likely proportional to --- $U(i)$, the degree of unrest in the i th grid cell.

Note: This also differs from the forest-fire model of Drossel and Schwabl (1992). In that model, every grid cell has the same probability of a trigger event such as a lightning strike. In this model, we expect this probability to vary spatially (and also in time) and to depend on the degree of unrest. (Of course, unquenched campfires and discarded cigarettes can also trigger a forest fire, but these are not naturally-occurring events. Since they are caused by people, the probability of these types of trigger events would increase with the population count of a grid cell.)

3. Connectivity - The Potential for Conflict to Spread. For each geospatial grid cell, we also compute a measure of connectivity that is used to quantify the potential for a conflict in one cell to spread to other grid cells. This is also a composite variable or index that is treated as a function of one or more indicator variables. The indicator variables can characterize two distinct types of connectivity:

(1) **Local / Geographic Connectivity** (geospatial or physical; e.g. transportation network accessibility, road density, topographic roughness, travel times)

(2) **Nonlocal / Electronic Connectivity** (access to nonlocal information; e.g. access to devices: cell phone, TV, radio, internet/broadband. Also social media usage, newspapers.

The widespread use of cell phones and social media has led to a dramatic increase in “electronic connectivity”. It is often viewed as the key factor in the “Arab Spring” phenomenon. See Arab Spring (2021). Note that electronic connectivity may have either a positive or negative impact on the spreading (e.g. when the family of someone who was killed calls for peaceful demonstrations, conflict may be reduced).

Note: It appears that the **communication** between people in different grid cells (near or far) is the primary mechanism by which conflict spreads. So connectivity is really getting at the ability to communicate between cells.

Note: The standard forest-fire model includes only local (nearest neighbor) connectivity, and does not allow any type of nonlocal connectivity.

Note: While TVs, radios and newspapers allow people to **receive** information, they are much less likely to be used by people to **send** information to others. This is in sharp contrast with telephones (cell or land-line), and internet access which allow two-way communication. In order for information to spread from one cell to another, it has to first be received by some means and then sent or forwarded via two-way communication. Perhaps we should therefore distinguish between the degree to which people in a grid cell **receive** information electronically (by TV, radio, newspaper, phone, internet), and the degree to which they **send** it electronically (only by phone & internet). The time it takes for a person to act on information received (e.g. forward it, organize a protest, write about it) should probably also be taken into account.

4. Conflict Duration - The Persistence of Conflict. Conflicts eventually get resolved, and therefore have a finite (but possibly long) duration. This can be modeled in various ways. One of the simplest is to treat the duration of each conflict event as an independent, random variable drawn from some distribution that takes only positive values. For example, random variables from a geometric distribution (Geometric Distribution, 2021) are positive integers and could be used to determine duration as one or more discrete time intervals. Lee et al. (2020b) discuss conflict duration in terms of “virulence”.

In the current version of the model, we generate a Bernoulli random variable (parameter p) in each time interval to determine whether the conflict in a grid cell ends in that time interval. Bernoulli random variables (Bernoulli Distribution, 2021) have only 2 possible values: 1 with probability, p , and 0 with probability, $(1-p)$. As is well-known in probability theory, it follows that the conflict durations then have a Geometric distribution with the same parameter, p .

Explanation of Key Model Parameters

The following parameters can be changed in the model’s configuration file, using a text editor, or in the model’s GUI. Here, the “long name” (in bold) is followed by the “key name” (in parentheses) that is used in the config file.

Number of timesteps (`n_steps`): The number of timesteps for which to run the model. The duration of a single timestep is determined by the `time_units` parameter. Model runtime is proportional to `n_steps`. (Type: Integer, Default value: 100)

Unrest grid file (`U_file`): A spatial grid of values (2D array) that gives a measure of the “unrest”, or potential for conflict to emerge, in each grid cell. It can depend on indicators such as

population count, average rainfall rate, and many others. It is fixed for each model run for a given region. It must be in GeoTIFF format, and all grids must have same dimensions and bounding box. If no grid is specified, a uniform (constant-valued grid) is used. (Type: String, Default value: ./input_files/Horn_of_Africa_GPW-v4_pop_count_2020_450sec.tif)

Local connectivity grid file (C1_file): This is a spatial grid of values (2D array) that gives a measure of the "local connectivity", or potential for conflict to spread, in each grid cell. It may depend on indicators such as accessibility, road density, etc. It is fixed for each model run for a given region. It must be in GeoTIFF format, and all grids must have same dimensions and bounding box. If no grid is specified, a uniform (constant-valued grid) is used. (Type: String, Default value: blank space).

Nonlocal connectivity grid file (C2_file): This is a spatial grid of values (2D array) that gives a measure of the "nonlocal connectivity", or potential for conflict to spread to distant grid cells, in each grid cell. It depends on indicators such as internet and cell phone access. It is fixed for each model run for a given region. It must be in GeoTIFF format, and all grids must have same dimensions and bounding box. If no grid is specified, a uniform (constant-valued grid) is used. (Type: String, Default value: blank space).

Conflict emergence factor (c_emerge): This is a proportionality factor that is multiplied by values in the normalized unrest grid (U) to get the probability that conflict emerges in a given grid cell in the current timestep. (Type: Float, Min: 0.0, Max: 1.0, Default Value: 0.005).

Conflict local spreading factor (c_spread): This is a proportionality factor that is multiplied by values in the normalized local connectivity grid (C1) to get the probability that conflict spreads from a given grid cell to its nearest neighbors in the current timestep. (Type: Float, Min: 0.0, Max: 1.0, Default Value: 0.2).

Conflict nonlocal spreading factor (c_spread2): This is a proportionality factor that is multiplied by values in the normalized nonlocal connectivity grid (C2) to get the probability that conflict spreads from a given grid cell to remote grid cells in the current timestep. (Type: Float, Min: 0.0, Max: 1.0, Default Value: 0.0).

Conflict resolution probability (p_resolve): The probability that the conflict in any grid cell will be resolved in the current timestep. (Type: Float, Min: 0.0, Max: 1.0, Default Value: 0.47).

Start date (start_date): The start date for the simulation, in the standard form: YYYY-MM-DD. Time is measured from this date. (Type: String, Default Value: 2021-01-01.)

Time units (time_units): The amount of time that corresponds to one timestep. The parameters c_emerge, c_spread, c_spread2, and p_resolve are used to compute the probability that conflict will emerge, spread (locally or nonlocally) or be resolved in this amount of time. (Type: String [days, weeks, or months], Default value: days).

Explanation of Other Model Parameters

The Stochastic Conflict Model is set up with defaults that correspond to the Greater Horn of Africa, which has the geographic bounding box: (min_lat = -5, min_lon = 25.0, max_lat = 25.0, max_lon = 55.0) and dimensions: (n_cols = 240, n_rows = 240) . This region spans 30 degrees of latitude and 30 degrees of longitude. However, the model can be applied to any geographic bounding box if the necessary input grids are available for that region.

The xsize of a model grid cell in arcseconds is given by $3600 * (\text{max_lon} - \text{min_lon}) / \text{n_cols}$, where max_lon and min_lon have units of degrees. Similarly, the ysize of a model grid cell in arcseconds is given by $3600 * (\text{max_lat} - \text{min_lat}) / \text{n_rows}$, where max_lat and min_lat have units of degrees. (Default Values: xsize = 450 arcseconds, ysize = 450 arcseconds. This corresponds to about 13.89 km near the equator.)

The following parameters can be changed in the model's configuration file, using a text editor. Here, the "long name" (in bold) is followed by the "key name" (in parentheses) that is used in the config file.

Number of columns (n_cols): The number of columns in the model grid. (Type: Integer, Min: 100, Max: 2000, Default Value: 240).

Number of rows (n_rows): The number of rows in the model grid. (Type: Integer, Min: 100, Max: 2000, Default Value: 240).

Minimum latitude (min_lat): The minimum latitude (south edge) of the model's geographic bounding box. The default bounding box values are for the Greater Horn of Africa. If GeoTIFF files are provided for U_file, C1_file, and/or C1_file, they must span this same bounding box. (Type: Float, Min: -90.0, Max: 90.0, Default value: -5.0, Unit: degrees east).

Note: Use positive values north of the equator and negative values south of the equator.

Maximum latitude (max_lat): The maximum latitude (north edge) of the model's geographic bounding box. The default bounding box values are for the Greater Horn of Africa. If GeoTIFF files are provided for U_file, C1_file, and/or C1_file, they must span this same bounding box. (Type: Float, Min: -90.0, Max: 90.0, Default Value: 25.0, Unit: degrees east.)

Note: Use positive values north of the equator and negative values south of the equator.

Minimum longitude (min_lon): The minimum longitude (west edge) of the model's geographic bounding box. The default bounding box values are for the Greater Horn of Africa. If GeoTIFF files are provided for U_file, C1_file, and/or C1_file, they must span this same bounding box. (Type: Float, Min: -180.0, Max: 180.0, Default value: 25.0, Unit: degrees north).

Note: Use positive values east of the prime meridian and negative values west of it.

Maximum longitude (max_lon): The maximum longitude (east edge) of the model's geographic bounding box. The default bounding box values are for the Greater Horn of Africa. If GeoTIFF files are provided for U_file, C1_file, and/or C2_file, they must span this same bounding box. (Type: Float, Min: -180.0, Max: 180.0, Default value: 55.0, Unit: degrees north).

Note: Use positive values east of the prime meridian and negative values west of it.

Explanation of Model Output Parameters

Note: The two primary outputs of the Stochastic Conflict Model are saved as a time-indexed set of geospatial grids spanning the modeled region, called a “grid stack”. By default, these grid stacks are saved in the folder “~/outputs”. Each model run generates one grid stack for the “conflict presence” variable and another for the “conflict_IDs” variable (used for better visualizations). In addition, each grid stack is saved in two different file formats:

- (1) RTS (RiverTools Sequence) format, row-major order, IEEE binary, 4-byte floats, with georeferencing in an RTI (RiverTools Information) header file, and
- (2) NetCDF format, with standardized metadata, closely following the CF (Climate and Forecasting) Conventions.

The RTS format is a simple, efficient, binary format that is easy to read into a variety of applications.

The following parameters can be changed in the model’s configuration file, using a text editor. Here, the “long name” (in bold) is followed by the “key name” (in parentheses) that is used in the config file.

Option to allow overwriting existing output files (OVERWRITE_OK): Set this to 1 to allow existing output files with the same filename to be overwritten, and 0 otherwise. If set to zero, numbers will be inserting in the existing filename before the extension. For example, conflict.rts, conflict_1.rts, conflict_2.rts. Note that all output files will be converted to movies after each model run, so it is usually better to set this to 1. (Type: Integer, Min: 0, Max: 1, Default Value: 1).

Conflict presence output file (out_file): The filename (with path) of an output file that stores a grid stack of time-indexed grids that contain zeros and ones. A grid cell has the value 1 if it is experiencing conflict at that time and has the value 0 otherwise. This filename must end in ".rts", but output will also be stored in NetCDF format with the same filename but extension "_2D.nc". (Type: String, Default Value: ~/output/conflicts.rts).

Conflict IDs output file (IDs_file): The filename (with path) of an output file that stores a grid stack of time-indexed grids that contain long-integer IDs. All grid cells that obtained conflict by spreading from the same initial conflict are assigned the same unique ID number to allow visualization. This filename must end in ".rts", but output will also be stored in NetCDF format with the same filename but extension "_2D.nc". An ID of 0 is assigned to grid cells with no conflict, and an ID of 10000000 is assigned to grid cells for which there is no unrest (i.e., no potential for conflict), such as lake and ocean grid cells. (Type: String, Default Value: ~/output/conflict_IDs.rts).

Option to create MP4 movies (CREATE_MP4_MOVIES): Set this to 1 to create MP4-format movies from model output files at the end of the simulation, or 0 to not create them. (Type: Integer, Min: 0, Max: 1, Default Value: 1).

Option to create WEBM movies (CREATE_WEBM_MOVIES): Set this to 1 to create WEBM-format movies from model output files at the end of the simulation, or 0 to not create them. (Type: Integer, Min: 0, Max: 1, Default Value: 1). The WEBM format supports opacity.

Opacity of media files (opacity): This determines the opacity to apply to the visualization files so that they will not obscure city names and boundaries in a Causemos basemap. A value of 1.0 corresponds to completely opaque (not transparent at all). (Type: Float, Min: 0.0, Max: 1.0, Default Value: 0.7).

Conflict presence movie w/o opacity: This filename is auto-generated from the “Conflict presence output file” filename (see above) by changing the filename extension of that NetCDF file to “.mp4”. The grid stack in the NetCDF file is converted to a set of color images that are saved as a movie in MP4 format. Movie files are saved in the “~/media/movies” folder.

Conflict presence movie w/ opacity: This filename is auto-generated from the “Conflict presence output file” filename (see above) by changing the filename extension of that NetCDF file to “.webm”. The grid stack in the NetCDF file is converted to a set of color images with the specified opacity (see above) that are saved as a movie in WEBM format. Note that the WEBM movie format supports opacity while the MP4 format does not. Opacity allows the movie to be displayed over a backdrop map that shows country borders and cities, as in Causemos, to simplify interpretation. Movie files are saved in the “~/media/movies” folder.

Conflict IDs movie w/o opacity: This filename is auto-generated from the “Conflict IDs output file” filename (see above) by changing the filename extension of that NetCDF file to “.mp4”. The grid stack in the NetCDF file is converted to a set of color images that are saved as a movie in MP4 format. Movie files are saved in the “~/media/movies” folder.

Conflict IDs movie w/ opacity: This filename is auto-generated from the “Conflict IDs output file” filename (see above) by changing the filename extension of that NetCDF file to “.webm”. The grid stack in the NetCDF file is converted to a set of color images with the specified opacity (see above) that are saved as a movie in WEBM format. Note that the WEBM movie format supports opacity while the MP4 format does not. Opacity allows the movie to be displayed over a backdrop map that shows country borders and cities, as in Causemos, to simplify interpretation. Movie files are saved in the “~/media/movies” folder.

Different Ways to Run the Model

The Stochastic Conflict Model is distributed as an open-source Python package in a GitHub repository at:

https://github.com/peckhams/stochastic_conflict_model/

Instructions for installing the Python package are given in **Appendix 1** of a Jupyter notebook that is included with the package in the *notebooks* folder. The URL for that notebook is:

https://github.com/peckhams/stochastic_conflict_model/blob/main/notebooks/Conflict_Introduction.ipynb

The model reads its parameters from a configuration file that has the filename extension “.cfg”. This is a simple text file with key-value pairs that can be edited with any plain text editor. Three examples are given in a folder called “input_files” that is included in the Python package.

Jupyter Notebook GUI

The Jupyter notebook includes a graphical user interface (GUI), with sliders and text boxes, for running the model. Values entered or selected in the GUI are written to the model's configuration file. You then click the Run button to run the model. Model output can also be visualized within the notebook with special graphics routines that are included with the package. The next two images show the input and output panels of the tabbed GUI.

Stochastic Conflict Model User Interface

The screenshot displays the 'Inputs' tab of the Stochastic Conflict Model User Interface. The interface features two tabs at the top: 'Inputs' (active) and 'Outputs'. Below the tabs, the following parameters are configured:

- N_time_steps:** 100
- Grid ncols:** 240
- Grid nrows:** 240
- Unrest Grid File:** input_files/Horn_of_Africa_GPW-v4_pop_count_2020_450sec.tif
- Connectivity File 1:** input_files/Horn_of_Africa_GPW-v4_pop_count_2020_450sec.tif
- Connectivity File 2:** (none, uniform)
- Emergence factor:** 0.005 (slider at the left end)
- Local spreading factor:** 0.200 (slider at approximately 20% of the range)
- Nonlocal spreading factor:** 0.000 (slider at the left end)
- Resolution probability:** 0.400 (slider at approximately 40% of the range)
- Status:** Ready.
- Run button:** A grey button labeled 'Run' is located at the bottom right.

Stochastic Conflict Model User Interface

Inputs	Outputs
GUI-created cfg file:	<input type="text" value="input_files/gui_conflict.cfg"/>
Conflict RTS File:	<input type="text" value="~/output/conflicts.rts"/>
Conflict IDs RTS File:	<input type="text" value="~/output/conflict_IDs.rts"/>
Create MP4 movies?	<input type="radio"/> No (saved in ~/media/movies)
Create WEBM movies?	<input type="radio"/> No (saved in ~/media/movies)

Note: You may need to create the media and output directories in your home directory.

Terminal Prompt (Mac or Linux)

Assuming the Python package has been installed, the model can be run from a terminal prompt with the following commands. If you have installed the package in a conda environment called “conflict”, first switch to that environment with: “conda activate conflict”, then type:

```
% cd stochastic_conflict_model
% python conflict --cfg_file './input_files/conflict.cfg'
```

Python Prompt

Assuming the Python package has been installed, the model can be run from a Python prompt. First, open a terminal window. If you have installed the package in a conda environment called “conflict”, next switch to that environment by typing: “conda activate conflict”. Finally, start a Python command-line session by typing “python”, and then type the following commands at the Python prompt:

```
>>> import os
>>> src_dir = '~/stochastic_conflict_model'
>>> os.chdir( src_dir )

>>> from conflict.model import conflict
>>> c = conflict.conflict()

>>> cfg_file = 'input_files/conflict.cfg'
>>> c.run_model( cfg_file=cfg_file )
```

As a container with Dojo/Causemos

The Stochastic Conflict Model has been published in Causemos, from Uncharted. Causemos aggregates model predictions to administrative zones, so results for countries not fully contained in the model's geographic bounding box may be misleading. For details, go to: <https://causemos.uncharted.software>. Note that a login is required. See Appendix 2 of the complete User's Guide for details on how the model was containerized and then annotated with Dojo from Jataware.

Examples for the Greater Horn of Africa

In this section we illustrate some of the behavior that the model can exhibit with a few specific examples for the ***Greater Horn of Africa region***. For each of these examples, a ***GPW-v4 population count*** grid is used for both the unrest grid, U, and connectivity grid, C1. See Figure 1. See the complete User's Guide for many additional examples.

Note that the GPW-v4 data set has large nodata regions for the country of Egypt, which affects the top left part of the model's default domain. This issue is explained at: <https://sedac.uservoice.com/knowledgebase/articles/799203-why-does-egypt-look-different-than-the-rest-of-nor>.

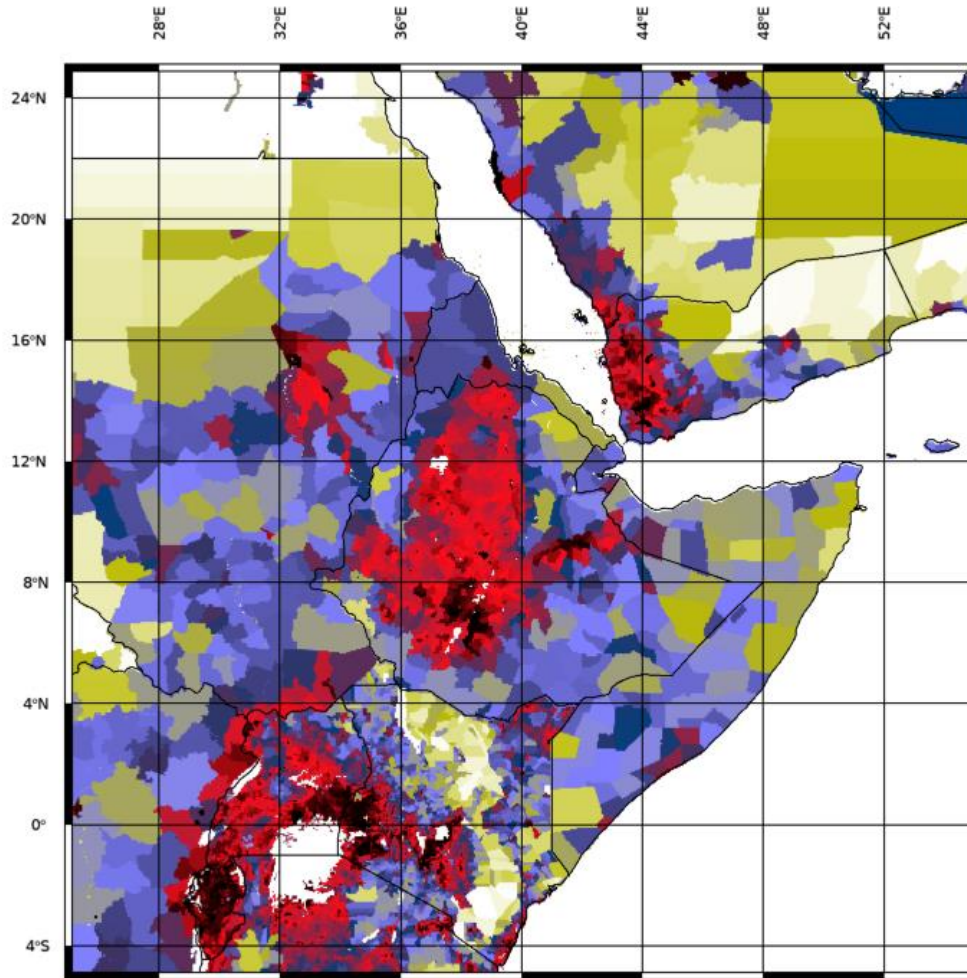


Figure 1. Color image for the GPW-v4 population count grid with a “Stern special” color table. Here, white and yellow indicate low values and red and black indicate high values. Notice the high populations in Ethiopia and Sudan (middle), around Lake Victoria (bottom left: Uganda, Kenya, Tanzania, Burundi, and Rwanda) and the southwest part of the Arabian Peninsula (Saudi Arabia and Yemen). The ocean, lakes and nodata regions (top) are all white. Polygons show true resolution of source data, typically much coarser than the 30-arcsec resolution of the data set.

Example with No Spreading

Here, the U grid set equal to the population count (GPW v4).

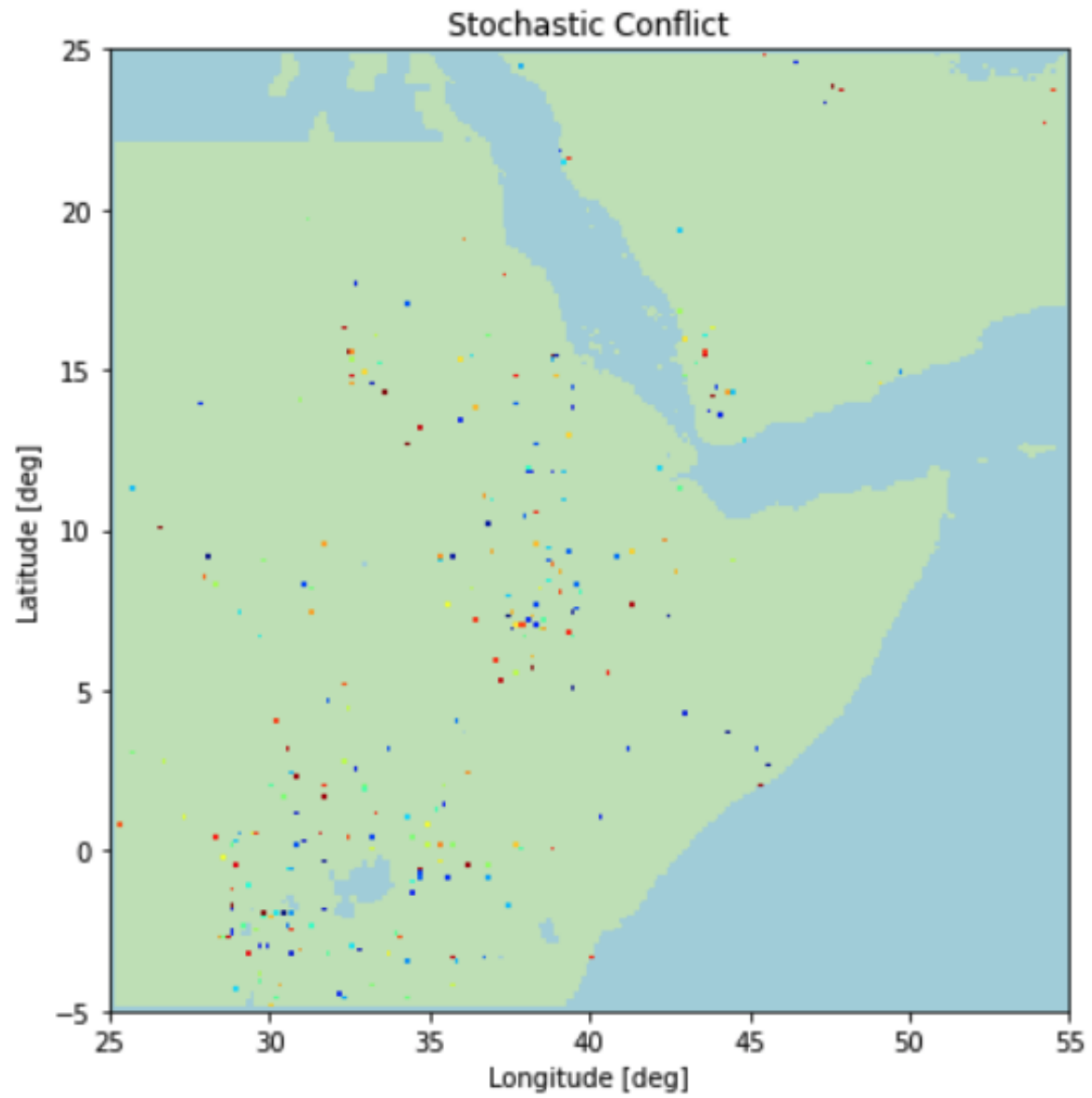


Figure 2. No spreading, $ce=0.1$, $cs1=0$, $cs2=0$, $pr=0.1$, $n=100$).

Examples with Local Spreading Only

This first example has a fairly high probability of conflict emergence ($ce = 0.4$), a small amount of local spreading ($cs1 = 0.04$), no nonlocal spreading ($cs2 = 0$), and a conflict resolution probability of 0.3. The average size and total number of conflict clusters both decrease as the probability of conflict resolution increases.

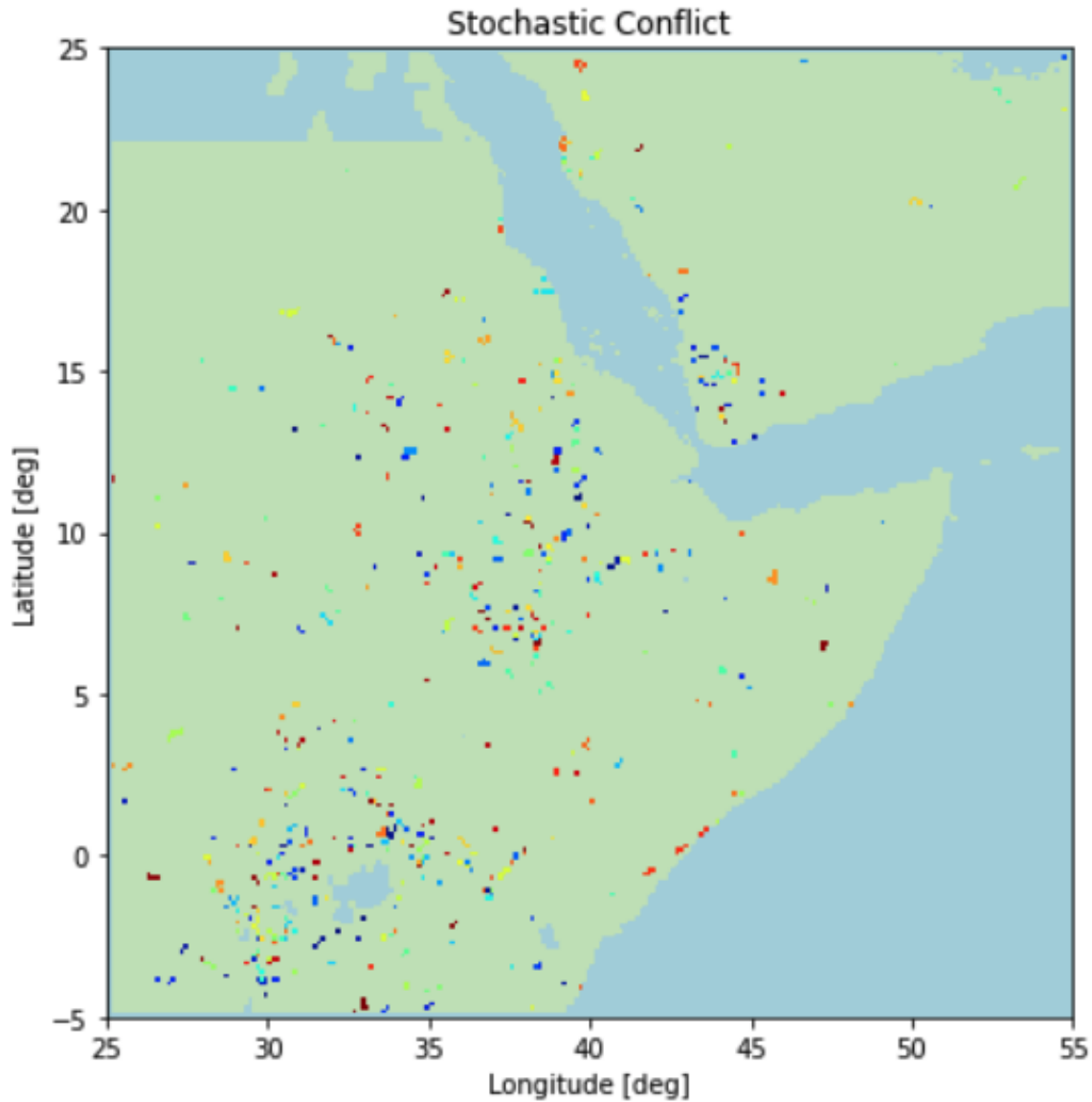


Figure 3. Local spreading, with $ce = 0.4$, $cs1 = 0.04$, $cs2 = 0$, $pr = 0.3$, $n=100$.

The example shown in Figure 4 has a small probability of conflict emergence ($ce = 0.05$), a significant probability of local spreading ($cs1 = 0.3$), no nonlocal spreading ($cs2 = 0$) and a resolution probability, pr , of 0.5.

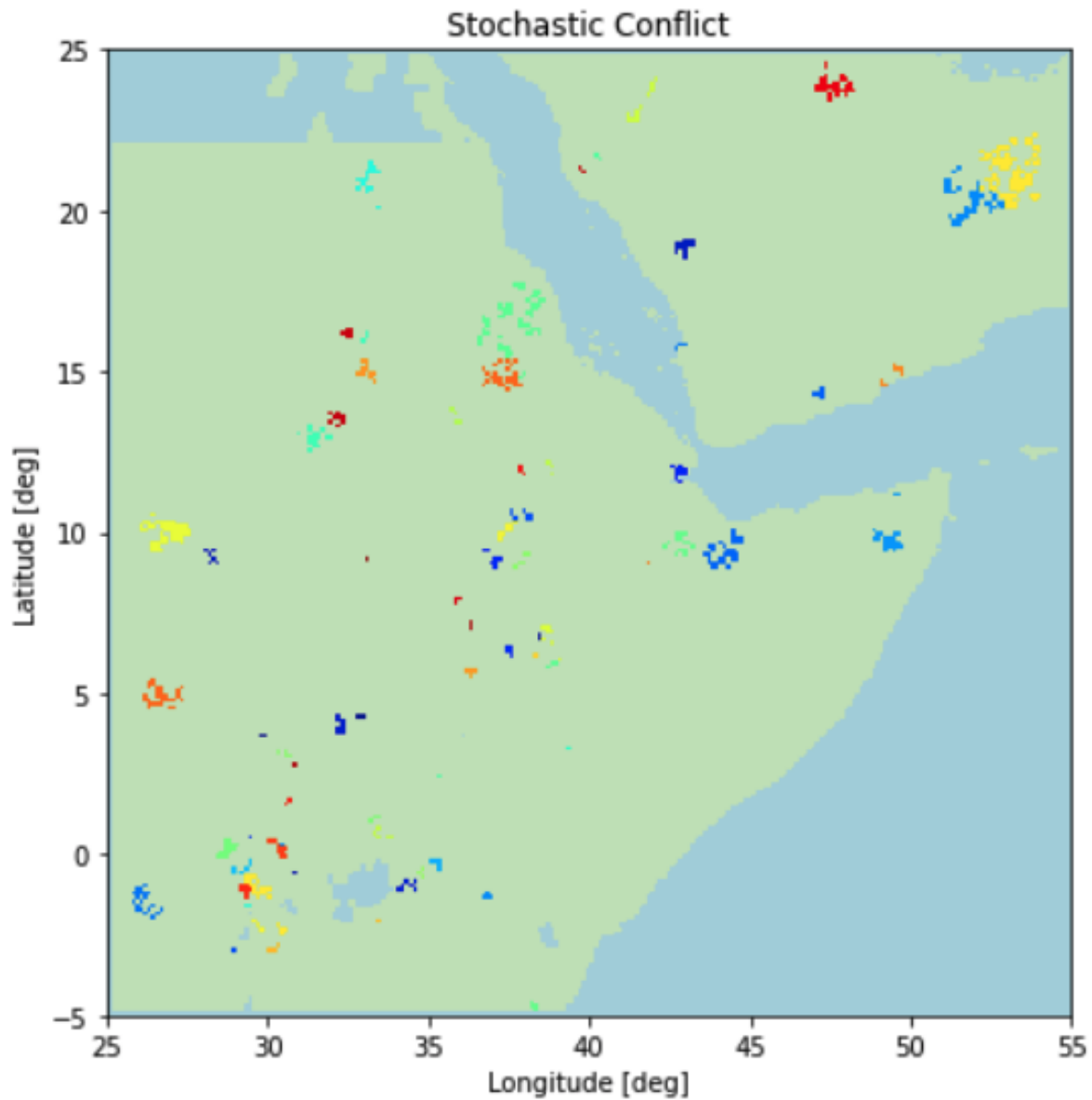


Figure 4. Local spreading, with $ce = 0.03$, $cs1 = 0.2$, $cs2 = 0$, $pr = 0.5$, $n=100$.

Example with Nonlocal Spreading Only

U = C1 = Population Count, $ce = 0.001$, $cs1 = 0$, $cs2=1$, Variable pr

Figure 5 shows a case with a very small probability of conflict emergence ($ce = 0.001$), no local spreading ($cs1 = 0$), and certain nonlocal spreading ($cs2 = 1$).

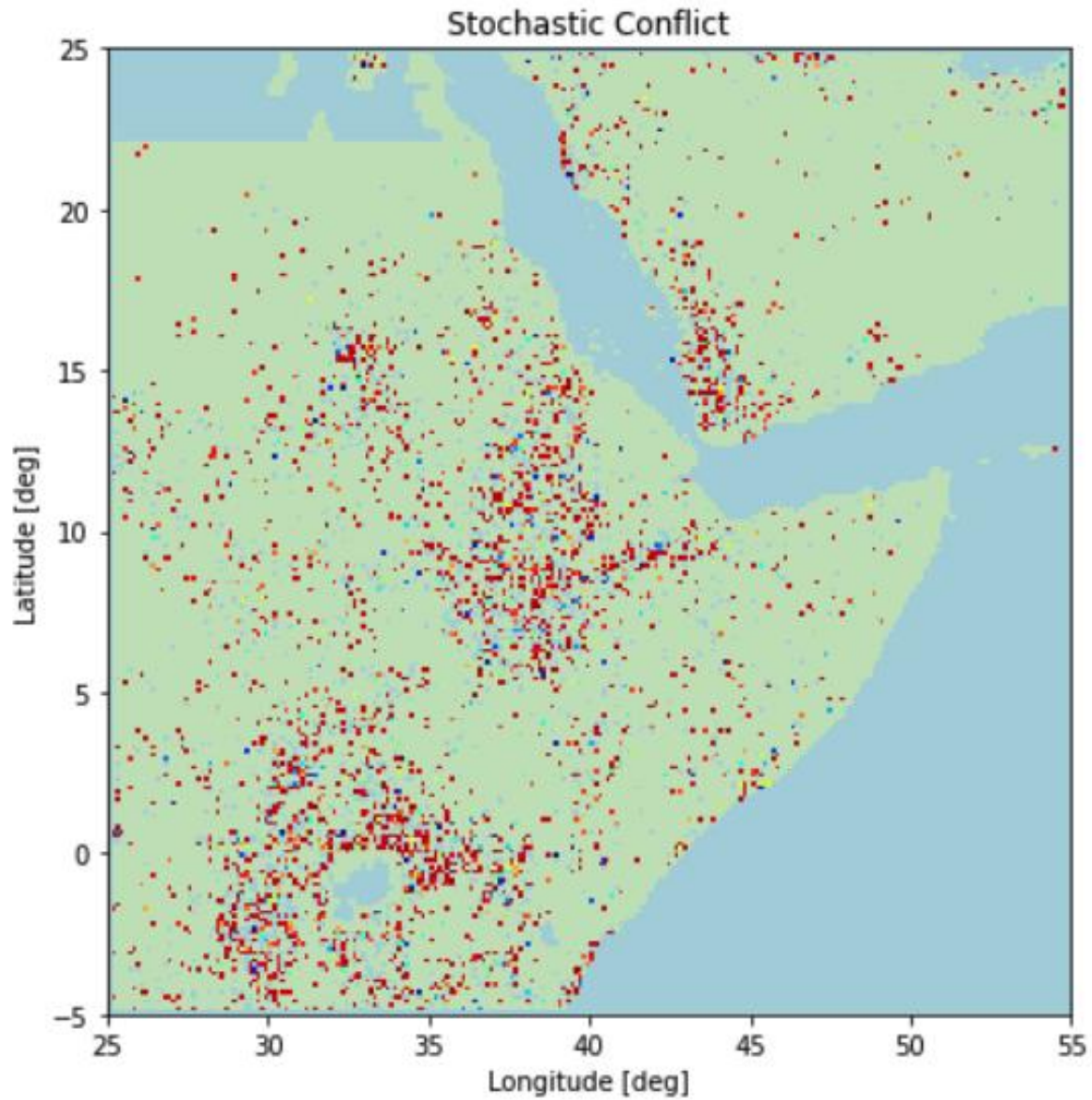


Figure 5. Nonlocal spreading only, with $ce=0.1$, $cs1=0$, $cs2=0.5$, $pr=0.1$, $n=100$.

Example with Local and Nonlocal Spreading

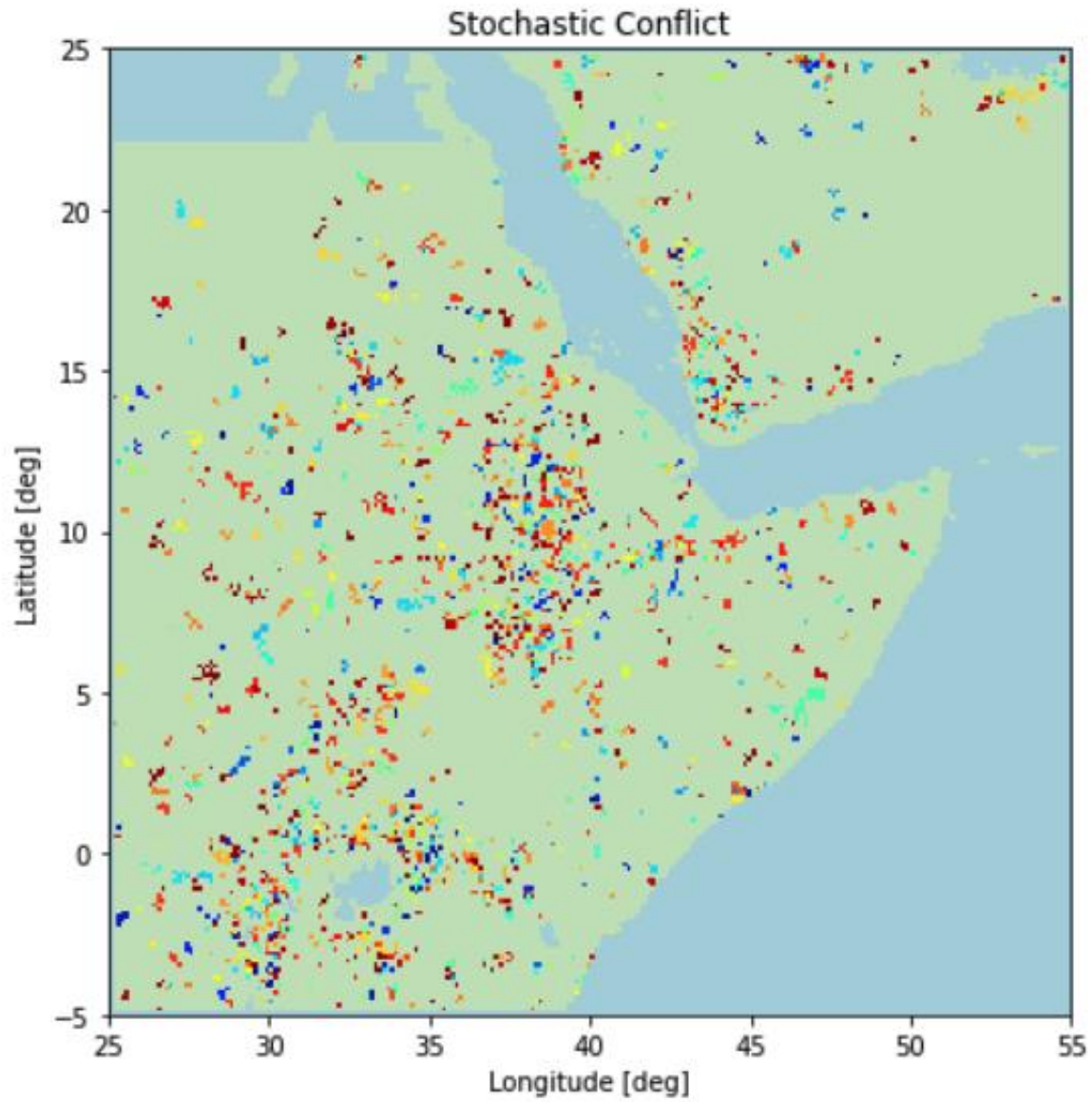


Figure 6. Local & nonlocal spreading ($ce=0.2$, $cs1=0.1$, $cs2=0.1$, $pr=0.4$, $n=100$).

Example with U = Inverse Distance to Border ($ce = 0.01$, $cs2=0$, $pr=0.6$)

The figure in this section was generated by using a grid of inverse distance to own border as the Unrest grid file and a small conflict emergence factor. See the section: Preparing Input Grids for the Model for details.

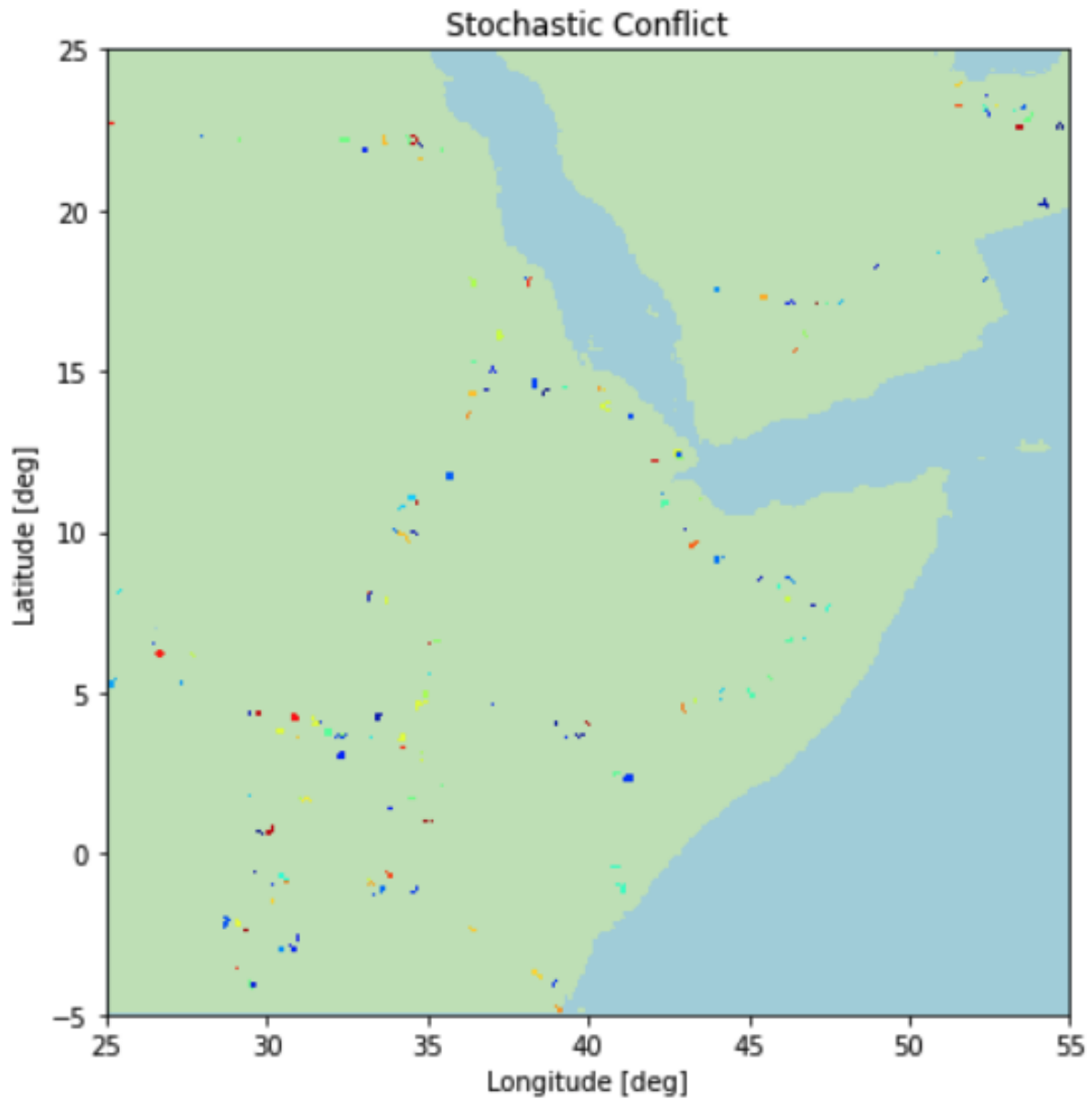


Figure 7. Inverse distance ($ce=0.01$, $cs1=0.1$, $cs2=0$, $pr=0.6$, $n=100$). Small local spreading.

Comparison to ACLED Data

ACLED (Armed Conflict Location and Event Data, acleddata.com) is one of the best-available sources of data for global conflicts, and in could, in principle, be used to calibrate the Stochastic Conflict Model (SCM). The ACLED data set is distributed as a very large CSV file or Excel spreadsheet. The SCM Python package contains a folder called “conflict/utlis” that includes a collection of utilities that were written to perform various lower-level tasks. Among these there is a file called “acled.py” that provides Python functions for working with ACLED data. It includes a function called “save_acled_data_to_grid” that reads ACLED data for the years 1997 to 2019 and creates a geospatial grid stack of reported fatalities or conflict events, where each grid has the totals for a given month and year. It uses the latitude and longitude associated with each conflict to place it in the appropriate grid cell. ACLED conflicts may be reported for specific locations, cities, or administrative zones of various sizes, but in all cases the recorded latitude and longitude is for the centroid of that region. Because of this, it is unfortunately not possible to capture the actual geospatial extent of the conflict for comparison to results from the Stochastic Conflict Model. In addition, the total number of fatalities associated with a conflict are spread evenly over the duration of the conflict. For example, the estimated number of deaths in the Eritrean-Ethiopian War is 100,000, but they occurred in a broad region near the border town of Badme between Feb. 2, 1999 and June 29, 1999 (73 nonconsecutive days), so there are 73 ACLED entries (rows) that report 1369 deaths (100,000/73). Figure 8 shows an image created by applying the acled.py utility to the geographic bounding box of the Greater Horn of Africa.

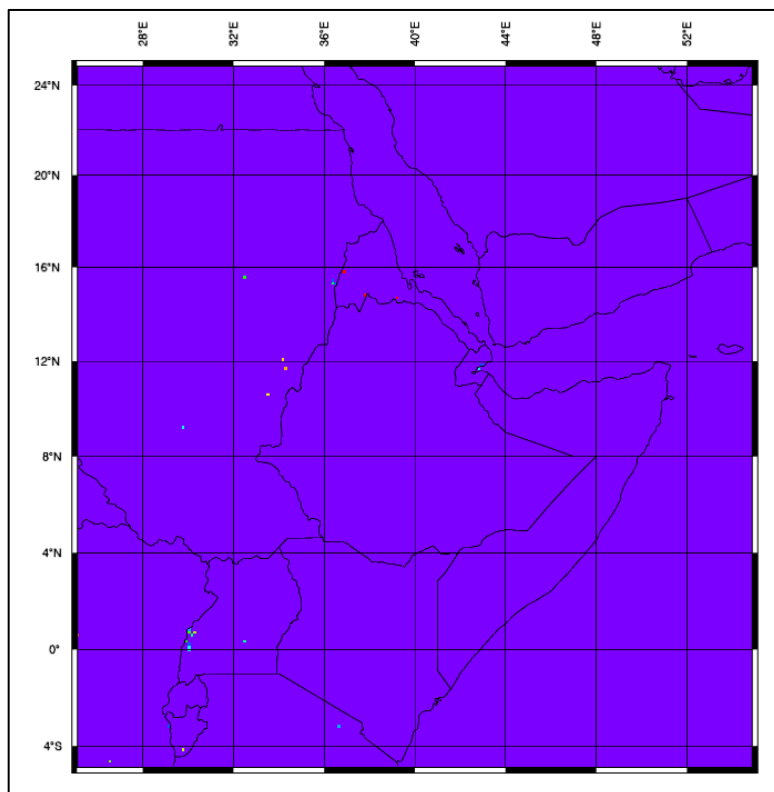


Figure 8. ACLED conflicts (collapsed to points) for April 1999. Red dots near the center are close to the contested border town of Badme. See Eritrean-Ethiopian War (2022). Other dots can be seen near the border between Uganda and Democratic Republic of the Congo, and the border between Ethiopia and Sudan/South Sudan.

Preparing Input Grids for the Model

The Stochastic Conflict Model is set up to accept geospatial grids of unrest (U_file), local connectivity (C1_file) and nonlocal connectivity (C2_file) in GeoTIFF format. Unfortunately, it is difficult to find suitable gridded data for most indicators of interest. Virtually all available data sets are provided as spreadsheets for administrative zones as opposed to geospatial grids, and therefore have a fairly coarse spatial resolution. Those that are available as geospatial grids were derived from data for administrative zones via spatial interpolation and have similarly low spatial resolution. Another issue is that when higher-resolution data sets are available, they are often either proprietary or have restricted access due to privacy or security concerns. For use in the model, gridded data must be converted to GeoTIFF format. This can be done using widely available GIS tools. In Python, for example, the well-known **gdal** package can be used. Here we mention a few of the most promising data sets that are available.

Gridded Population of the World, Version 4 (NASA). This global, gridded data set was created by applying a spatial interpolation algorithm to population count data (people per grid cell) for sub-national administrative zones. While it is available with a spatial resolution of 30 arc-seconds (roughly 1 km near the equator), and can easily be aggregated to coarser resolutions, the actual, much coarser spatial resolution is readily apparent and administrative boundaries are clearly visible. It is available for the following years: 2005, 2010, 2015, and 2020. The 2020 data is used as the default for both the unrest and local connectivity grids. The Stochastic Conflict Model package includes a module: `conflict/utils/geotiff.py` that provides a function called “`regrid_geotiff()`” that can be used to create grids for the model region at different resolutions. More information on this data set is available at:

<https://cmr.earthdata.nasa.gov/search/concepts/C1597158029-SEDAC.html>.

Note that this data set has large nodata regions for the country of Egypt, which affects the top part of the model’s default domain. This issue is explained at:

<https://sedac.uservoice.com/knowledgebase/articles/799203-why-does-egypt-look-different-than-the-rest-of-nor>.

Inverse Distance to Own Country’s Border. The Stochastic Conflict Model package includes a module: `conflict/utils/distance_to_border.py` that uses a grid of ISO country codes at 0.1-degree resolution (360 arcseconds, roughly 11.1 km) to create two grids: Distance to own border and Inverse distance to own border. The inverse distance is defined as: $d_{inv} = \exp(-6 * d)$, so that it is 1 for grid cells on a country’s border (excluding ocean borders) and decreases rapidly with distance away from the border. Conflicts between nations often occur along their common border and near population centers. This grid can therefore be used in the determination of the Unrest grid, U. See Figure 9, and Figure 7 in the Examples section.

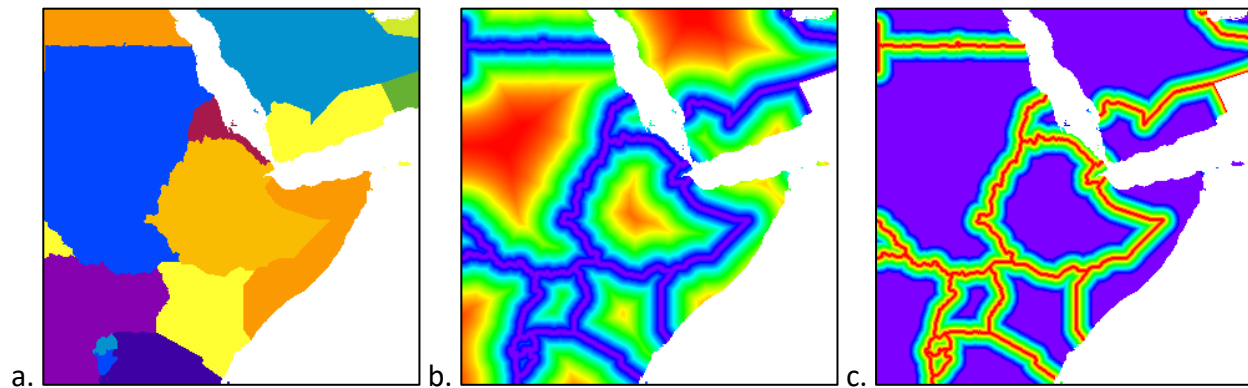


Figure 9. (a) Color image of ISO country codes. (b) Distance to own country's border, d. (c) Inverse distance to own country's border: $\exp(-6 * d)$. In (b) and (c), high values are red and low values are blue and purple. Distance and inverse distance computed by the module: `conflict/utlis/distance_to_border.py`.

PRIO-GRID 2.0. While this data set provides global, gridded data for numerous indicator variables and a range of years, the spatial resolution is only half a degree (30 arcminutes) or 1800 arcseconds. So, the entire global grid has only 720 columns (longitude) and 360 rows (latitude). While this data set includes the indicator “Distance to own borders”, it has a much lower spatial resolution (0.5 degree) than what can be computed with the utility described in the last section (0.1 degree). Many other indicators of interest are included, such as: Precipitation total, Proportion of main crop growing season experience drought, Nightlights (mean), and Travel time to nearest urban center (average), Child malnutrition (average), and Infant mortality rate (average). Population count data from GPW-v4 is also included. See: <https://grid.prio.org/> and Tollefsen et al. (2012).

GeoIP Data (Internet Access). This interesting global data set provides geolocation metadata (e.g., latitude and longitude) for registered IP addresses worldwide. It includes both the older IPv4 and newer IPv6 addresses. While a coarser-resolution version of this data set (GeoLite) is available for free, the high-resolution data must be purchased from MaxMind, the company that produced it. This data set could be used to create a geospatial grid for the indicator “Internet access”, which could then be used as the nonlocal connectivity grid (C2_file) for the model. Note, however, that the geolocation associated with an IP address is often that of the internet service provider, as opposed to that of the household (end-user). While internet access and use in Africa is growing steadily, most people still do not have access.

<https://www.maxmind.com/en/geoip2-services-and-databases>.

<https://www.r-bloggers.com/2014/09/mapping-every-ipv4-address/>.

Wealth/Poverty Data as a Surrogate for Internet Access. It has been shown by a Pew Research Center (PWC, 2016) study that there is a high correlation (0.87) between internet access and wealth. Lee and Braithwaite (2009) have developed a machine-learning method for producing high-resolution poverty/wealth maps and applied it to 25 countries in sub-Saharan Africa. It may therefore be possible to estimate internet access (on a geospatial grid) by using geospatial poverty maps. The resulting grid could then be used for the nonlocal connectivity grid (C2_file) in the model.

Conclusions and Future Work

The Stochastic Conflict Model simulates the three fundamental processes associated with conflicts --- namely emergence, spread, and resolution --- as a stochastic, spatial process. It has been set up in such a way that the probabilities associated with each process can vary geospatially and in time by providing the model with gridded data for unrest, local connectivity, and nonlocal connectivity. It can be shown that the model is a type of Markov process, which is a type of stochastic process where the next state of the system depends only on the previous state. The special case of no spreading (only emergence and resolution) is mathematically tractable and analytic results for this case are given in Appendix 3 of the complete User's Guide. Simulation results match theoretical predictions for this special case, which provides assurance that the model has been implemented correctly. Analytical (closed-form) results for the general case with spreading (either local or nonlocal) are not yet available. However, both visual assessment of simulations and results from Markov theory suggest that in most cases the model evolves from its initial condition to a statistical steady-state (invariant distribution) condition. Visually, this means that for any fixed set of model parameters, a particular spatial pattern emerges that is typically different than what is observed for another fixed set of parameters. The spatial patterns differ in various ways, including the average size of the conflict clusters, the separation distance between clusters and the appearance of areas without conflict (i.e., voids). The wide variety of possible patterns is illustrated in the section titled Examples for the Greater Horn of Africa (in the complete User's Guide). Of course, some of these patterns are expected to differ considerably from what is observed, but they illustrate the breadth of scenarios that the model can simulate.

The model is quite fast, even for relatively large spatial grids. This is due to the use of a Python package called numpy (Numerical Python), careful vectorization of all computations with numpy commands to avoid spatial for loops and the fact that model writes its output efficiently to files in binary format. The model uses random numbers from a Bernoulli distribution, using numpy's random number generator module, `numpy.random`.

The model is very easy to use, particularly when using the Jupyter notebook GUI that is included with the Python package. It can also be run at an OS terminal prompt or a Python prompt. While the GUI is currently hard-wired to run the model for the Greater Horn of Africa region, it is easily adapted to run for any geographic bounding box by changing parameters in its configuration file.

The model can be run in a Docker container, and this was demonstrated using the Dojo software developed by Jataware. Results from Dojo, including detailed annotation of inputs and outputs, were successfully imported into Causemos, developed by Uncharted. Appendix 2 of the complete User's Guide provides complete details on setting up and running the model in a Docker container with Dojo.

Despite very encouraging results, the full potential of the model has not yet been realized due to the difficulty associated with obtaining high-resolution, gridded data for:

- (1) relevant indicators for generating the input grids (U_file, C1_file, C2_file) and
- (2) actual, geospatial conflict data for calibrating and verifying the model.

Future work will focus on addressing these issues, by pursuing the ideas described in the section titled: Preparing Input Grids for the Model. It is also possible to use output from machine-learning models (such as those developed by Kimetrica) for generating grids of unrest, local connectivity, and nonlocal connectivity.

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