## Designing a Custom AXI-lite Slave Peripheral

LECTURE 9

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## Custom Hardware

#### Custom hardware blocks are used to:

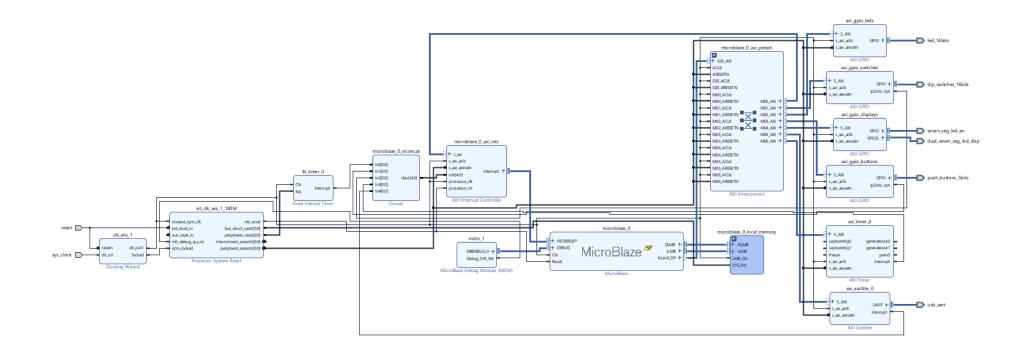
- Delegate to hardware time-critical functions
- Save MicroBlaze resources

#### Two examples will be considered:

- A custom coprocessors with no output ports
- A custom peripheral with output ports

Next lab (lab. 7) will be dedicated to the design and use of a custom peripheral IP – Display Driver.

# Block Design (BD)



### **AXI4** Protocol

#### Consult Vivado AXI Reference Guide and AMBA AXI Protocol Specification

There are three types of AXI4 interfaces:

- **AXI4**: For high-performance memory-mapped requirements.
- **AXI4-Lite**: For simple, low-throughput memory-mapped communication (for example, to and from control and status registers).
- **AXI4-Stream**: For high-speed streaming data.

#### **AXI-Lite:**

- all transactions are of burst length 1
- all data accesses use the full width of the data bus
- AXI4-Lite supports a data bus width of 32-bit or 64-bit
- all accesses are non-modifiable, non-bufferable

GlobalWrite address channelWrite data channelWrite response channelRead address channelRead data channelACLKAWVALIDWVALIDBVALIDARVALIDRVALIDARESETnAWREADYWREADYBREADYARREADYRREADY-AWADDRWDATABRESPARADDRRDATA-AWPROTWSTRB-ARPROTRRESP						
ARESETN AWREADY WREADY BREADY ARREADY RREADY  - AWADDR WDATA BRESP ARADDR RDATA	Global			•		Read data channel
- AWADDR WDATA BRESP ARADDR RDATA	ACLK	AWVALID	WVALID	BVALID	ARVALID	RVALID
	ARESETn	AWREADY	WREADY	BREADY	ARREADY	RREADY
- AWPROT WSTRB - ARPROT RRESP	-	AWADDR	WDATA	BRESP	ARADDR	RDATA
	-	AWPROT	WSTRB	-	ARPROT	RRESP

## AXI4-lite Handshaking Signals

Consistent across the five channels.

Based on a simple "Ready" and "Valid" principle:

- "Ready" is used by the recipient to indicate that it is ready to accept a transfer of a data or address value.
- "Valid" is used to clarify that the data (or address) provided on that channel by the sender is valid so that the recipient can then sample it.

"Assert Ready and wait for Valid"

"Assert Valid and wait for Ready"

"Wait for Ready before asserting Valid"

## Example 1 – Adder with 3 Operands

Import Block Design

Create and Package new IP (CustomCopr)

Add IP

Edit in IP Packager

#### CustomCopr:

- Adds the contents of 3 registers (written by software)
- Puts the result in the 4<sup>th</sup> register (read by software)

Apply options from T6 (Problems and Results)

Generate output products

Create HDL Wrapper

Generate Bitstream

**Export Hardware** 

Launch Vitis

### Vitis

If build errors do appear, update all the makefiles related to the custom IP:





### Correct Makefile

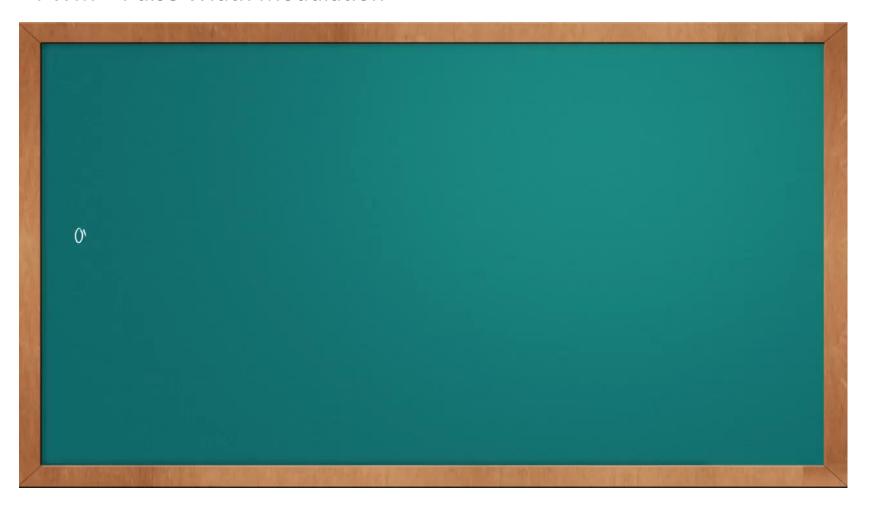
```
COMPILER=
ARCHIVER=
CP=cp
COMPILER FLAGS=
EXTRA COMPILER FLAGS=
LIB=libxil.a
RELEASEDIR=../../lib
INCLUDEDIR=../../include
INCLUDES=-I./. -I${INCLUDEDIR}
INCLUDEFILES=*.h
LIBSOURCES=*.c
OBJECTS = $(addsuffix .o, $(basename $(wildcard *.c)))
ASSEMBLY OBJECTS = $(addsuffix .o, $(basename $(wildcard *.S)))
libs:
          echo "Compiling CustomCopr..."
          $(COMPILER) $(COMPILER FLAGS) $(EXTRA COMPILER FLAGS) $(INCLUDES) $(LIBSOURCES)
          $(ARCHIVER) -r ${RELEASEDIR}/${LIB} ${OBJECTS} ${ASSEMBLY OBJECTS}
          make clean
include:
          ${CP} $(INCLUDEFILES) $(INCLUDEDIR)
clean:
          rm -rf ${OBJECTS} ${ASSEMBLY OBJECTS}
```

## After Correcting the Makefiles

- 1. Clean the projects
- 2. Build the hardware platform
- 3. Analyze the file xparameters.h (correct the main code if necessary)
- 4. Build the software application
- 5. Run the application (source code available on eLearning)

## Example 2 – triple PWM Generator

PWM – Pulse Width Modulation



### PWM

**Frequency** – how many times per second the LED is switched on and off:

Cannot be very slow to avoid flicker

**Resolution** - indicates how many intermediate steps (also called "units") a PWM cycle has:

In 8 bit mode, there are 256 levels of brightness

One easy way to build a PWM generator is to use two counters:

- Counter 1 (s\_clkEnbCnt) limits the frequency of PWM pulses
- Counter 2 (s\_pwmCounter) controls duty-cycle of PWM pulses (pulse width)
   within the chosen resolution
- PWM frequency =
  - = system clock / (resolution \* counter\_1\_MaxValue)

## Lab. 7 — parts 1-3

Direct the display refresh functions to custom hardware

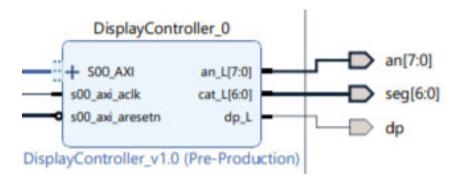
The custom display driver will receive from the MicroBlaze (through AXI-Lite interface):

- Digit enables 8 bits
- Decimal point enables 8 bits
- Digit values 32 bits (8 x 4 bits)

The custom display driver will produce on its outputs:

- an 8 bits
- seg 7 bits
- dp − 1 bit

The original GPIO\_Displays must be deleted



### Final Remarks

At the end of this lecture you should be able to:

- Design custom hardware modules interacting with the MicroBlaze through **AXI-Lite interface**
- write C programs that make use of custom hardware

### To do:

- Construct the considered hardware platforms
- Test the given applications in Vitis