





Teoria dos Grafos e Computabilidade

— Greedy graph algorithms —

Silvio Jamil F. Guimarães

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Graphs

- Model pairwise relationships (edges) between objects (nodes or vertices).
- ▶ Undirected graph G = (V, E): set V of nodes and set E of edges, where $E \subseteq V \times V$. Elements of E are unordered pairs.
- ▶ Directed graph G = (V, E): set V of nodes and set E of edges, where $E \subseteq V \times V$. Elements of E are ordered pairs.

Applications of Graphs

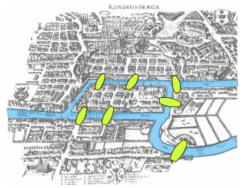
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- ▶ Problems involving graphs have a rich history dating back to Euler.

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Teoria dos Grafos e Computabilidade

— Shortest Paths —

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Shortest Path Problem

- ▶ G = (V, E) is a connected directed graph. Each edge e has a length $I_e \ge 0$.
- ▶ V has n nodes and E has m edges.
- ► Length of a path *P* is the sum of lengths of the edges in *P*.
- ► Goal is to determine the shortest path from some start node *s* to each node in *V*.
- Aside: If G is undirected, convert to a directed graph by replacing each edge in G by two directed edges.

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- Aside: If *G* is undirected, convert to a directed graph by replacing each edge in *G* by two directed edges.

SHORTEST PATHS

INSTANCE A directed graph G(V, E), a function $I : E \to \mathbb{R}^+$, and a node $s \in V$

SOLUTION A set $\{P_u, u \in V\}$, where P_u is the shortest path in G from s to u.

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2 foreach u \in S do store distance d[u] = \infty;
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d'(v) = \min_{e = (u,v): u \in S} d[u] + W(e) \text{ is as small as possible;}
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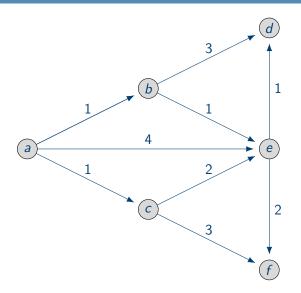
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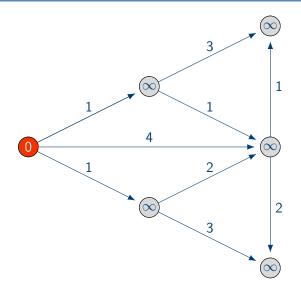
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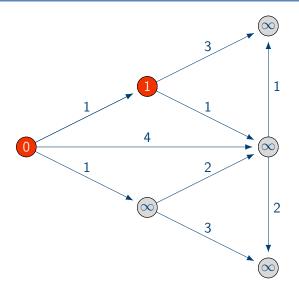
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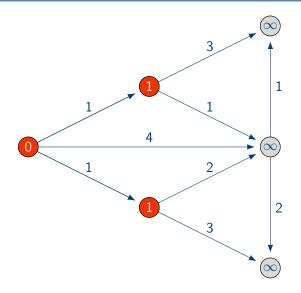
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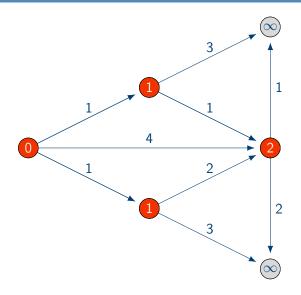
► Can modify algorithm to compute the shortest paths themselves: record the predecessor u that minimizes d'(v).

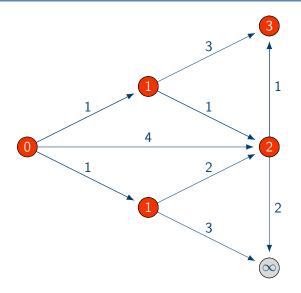


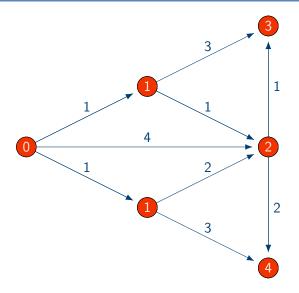










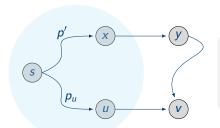


Proof of Correctness

- ▶ Let P_u be the shortest path computed for a node u.
- ▶ Claim: P_u is the shortest path from s to u.
- ▶ Prove by induction on the size of *S*.
 - ▶ Base case: |S| = 1. The only node in S is s.
 - Inductive step: we add the node v to S. Let u be the v's predecessor on the path P_v. Could there be a shorter path P from s to v?

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The alternate s - v path P through x and y already too long by the time it had left the set S

Comments about Dijkstra's Algorithm

- ► Algorithm cannot handle negative edge lengths.
- ▶ Union of shortest paths output form a tree. Why?

Algorithm: Shortest path algorithm – Dijkstra

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Algorithm: Shortest path algorithm — Dijkstra input : A graph G = (V, E), a weight map W and a source node s. output: The distances of the vertices from s1 Let S be the set of explored nodes; 2 foreach $u \in S$ do store distance $d[u] = \infty$; 3 Initially d[s] = 0 and S = s; 4 while $S \neq V$ do 5 | Select a node $v \notin S$ with at least one edge from S for which $d'(v) = \min_{e = (u,v): u \in S} d[u] + W(e) \text{ is as small as possible;}$ 6 | Add v to S and define d[v] = d'[v]; 7 end

- ▶ How many iterations are there of the while loop? n-1.
- ▶ In each iteration, for each node $v \notin S$, compute $\min_{e=(u,v),u\in S} d(u) + l_e$.

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- ▶ In each iteration, for each node $v \notin S$, compute $\min_{e=(u,v),u\in S} d(u) + I_e$.
- ► Running time **per iteration** is .

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- ▶ How many iterations are there of the while loop? n-1.
- ▶ In each iteration, for each node $v \notin S$, compute $\min_{e=(u,v),u\in S} d(u) + l_e$.
- Running time per iteration is O(m), yielding an overall running time of O(nm).

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- ▶ Store the minima d'(v) for each node $v \in V S$ in a **priority queue**.
- ▶ Determine the next node v to add to S using EXTRACTMIN.
- ▶ After adding v, for each neighbour w of v, compute $d(v) + l_{(v,w)}$.
- ▶ If $d(v) + l_{(v,w)} < d'(w)$, update w's key using CHANGEKEY.

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- ▶ If $d(v) + l_{(v,w)} < d'(w)$, update w's key using CHANGEKEY.
- ▶ How many times are EXTRACTMIN and CHANGEKEY invoked? n-1 and m times, respectively. Total running time is $O(m \log n)$.

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— Minimum Spanning Trees —

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Network Design

- ► Connect a set of nodes using a set of edges with certain properties.
- ► Input is usually a graph and the desired network (the output) should use subset of edges in the graph.
- ► Example: connect all nodes using a cycle of shortest total length.

Network Design

- ► Connect a set of nodes using a set of edges with certain properties.
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- ► Example: connect all nodes using a cycle of shortest total length. This problem is the NP-complete traveling salesman problem.

Minimum Spanning Tree (MST)

- ▶ Given an undirected graph G = (V, E) with a cost $c_e > 0$ associated with each edge $e \in E$.
- ► Find a subset T of edges such that the graph (V, T) is connected and the cost $\sum_{e \in T} c_e$ is as small as possible.

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INSTANCE An undirected graph G = (V, E) and a function $c : E \to \mathbb{R}^+$

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- ▶ Claim: If T is a minimum-cost solution to this network design problem then (V, T) is a tree.
- ▶ A subset T of E is a spanning tree of G if (V, T) is a tree.

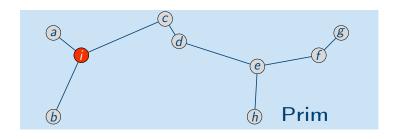
► Template: process edges in some order. Add an edge to *T* if tree property is not violated.

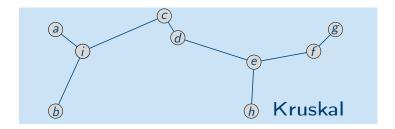
- ► Template: process edges in some order. Add an edge to *T* if tree property is not violated.
 - **Increasing cost order** *Process edges in increasing order of cost. Discard an edge if it creates a cycle.*
 - **Dijkstra-like** Start from a node s and grow T outward from s: add the node that can be attached most cheaply to current tree.
 - **Decreasing cost order** Delete edges in order of decreasing cost as long as graph remains connected.

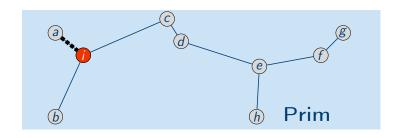
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- ► Which of these algorithms works?

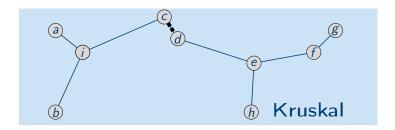
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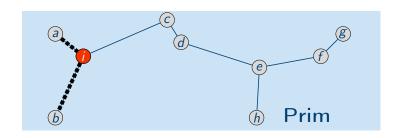
 Discard an edge if it creates a cycle. Kruskal's algorithm
 - Dijkstra-like Start from a node s and grow T outward from s: add the node that can be attached most cheaply to current tree. Prim's algorithm
 - Decreasing cost order Delete edges in order of decreasing cost as long as graph remains connected. Reverse-Delete algorithm
- ▶ Which of these algorithms works? All of them!

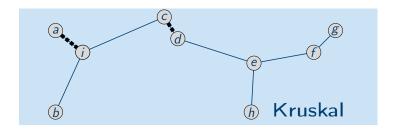


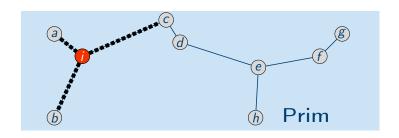


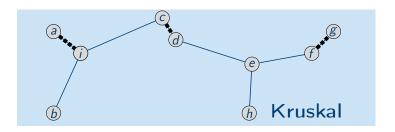


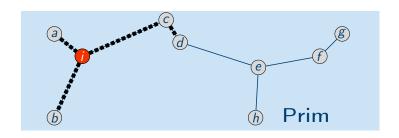


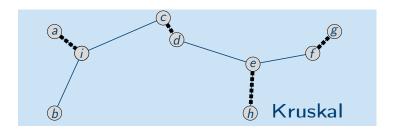


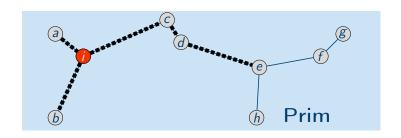


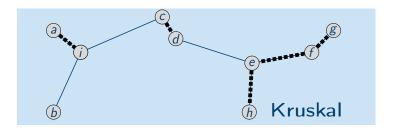




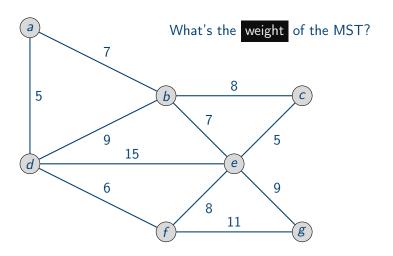




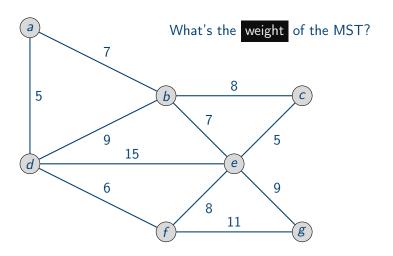




Example of Prim's Algorithm

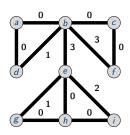


Example of Kruskal's Algorithm

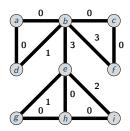


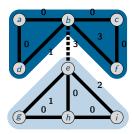
A cut in a graph G = (V, E) is a set of edges whose removal disconnects the graph (into two or more connected components).

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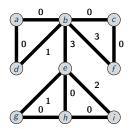


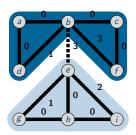
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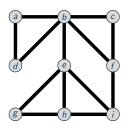


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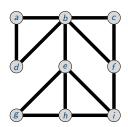


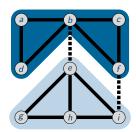


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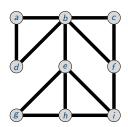


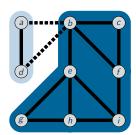
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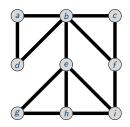


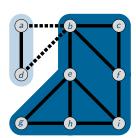
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- ▶ cut(S) is a cut because deleting the edges in cut(S) disconnects S from V S.





Cut Property

► When is it safe to include an edge in an MST?

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- ► Claim: every MST contains *e*.
- ▶ Proof: exchange argument. If a supposed MST T does not contain e, show that there is a tree with smaller cost than T that contains e.

Using the Cut Property

- ▶ Let *F* be the set of all edges that satisfy the cut property.
- ▶ Is the graph induced by *F* connected ?
- ► Can the graph induced by F contain a cycle?
- ► How many edges can F contain?

Using the Cut Property

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- ▶ Is the graph induced by *F* connected ? Yes.
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- ▶ How many edges can F contain? n-1
- ► *F* is the unique MST.
- ► Kruskal's and Prim's algorithms compute *F* efficiently.

Optimality of Kruskal's Algorithm

- ► Kruskal's algorithm:
 - ► Start with an empty set *T* of edges.
 - ▶ Process edges in *E* in non decreasing order of cost.
 - ► Add the next edge *e* to *T* only if adding *e* does not create a cycle.
- ► Claim: Kruskal's algorithm outputs an MST.

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- ► Claim: Kruskal's algorithm outputs an MST.
 - 1. For every edge e added, demonstrate the existence of S and V-S such that e and S satisfy the cut property.
 - 2. Prove that the algorithm computes a spanning tree.

Optimality of Prim's Algorithm

- \triangleright Prim's algorithm: Maintain a tree (S, U)
 - ▶ Start with an **arbitrary** node $s \in S$ and $U = \emptyset$.
 - ▶ Add the node *v* to *S* and the edge *e* to *U* that minimize

$$\min_{e=(u,v),u\in S,v\not\in S}c_e\equiv\min_{e\in\operatorname{cut}(S)}c_e.$$

- ▶ Stop when S = V.
- Claim: Prim's algorithm outputs an MST.

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- ▶ Stop when S = V.
- ► Claim: Prim's algorithm outputs an MST.
 - 1. Prove that every edge inserted satisfies the cut property.
 - 2. Prove that the graph constructed is a spanning tree.

Cycle Property

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Cycle Property

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- ▶ Let C be any cycle in G and let e = (v, w) be the most expensive edge in C.
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Optimality of the Reverse-Delete Algorithm

- \blacktriangleright Reverse-Delete algorithm: Maintain a set E' of edges.
 - ▶ Start with E' = E.
 - ▶ Process edges in non increasing order of cost.
 - ▶ Delete the next edge e from E' only if (V, E') is connected after removal.
 - Stop after processing all the edges.
- ► Claim: the Reverse-Delete algorithm outputs an MST.

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 - ► Stop after processing all the edges.
- ▶ Claim: the Reverse-Delete algorithm outputs an MST.
 - 1. Show that every edge deleted belongs to no MST.
 - 2. Prove that the graph remaining at the end is a spanning tree.

Comments on MST Algorithms

- ► To handle multiple edges with the same weight, perturb each length by a random infinitesimal amount.
- ► Any algorithm that constructs a spanning tree by including edges that satisfy the cut property and deleting edges that satisfy the cycle property will yield an MST!







Teoria dos Grafos e Computabilidade

— Implementation —

Silvio Jamil F. Guimarães

Graduate Program in Informatics – PPGINF Laboratory of Image and Multimedia Data Science – IMScience Pontifical Catholic University of Minas Gerais – PUC Minas

Implementing Prim's Algorithm

- ▶ Maintain a tree (S, U).
 - ▶ Start with an arbitrary node $s \in V$ and $U = \emptyset$.
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- ▶ Stop when S = V.
- ▶ Sorting edges takes $O(m \log n)$ time.
- ► Implementation is very similar to Dijkstra's algorithm.
- ▶ Maintain S and store attachment costs $a(v) = \min_{e \in \text{cut}(S)} c_e$ for every node $v \in V S$ in a priority queue.
- ▶ At each step, extract minimum *v* from priority queue and update the attachment costs of the neighbours of *v*.
- ▶ Total of n-1 EXTRACTMIN and m CHANGEKEY operations, yielding a running time of $O(m \log n)$.

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- ▶ Process edges in *E* in increasing order of cost.
- ▶ Add the next edge *e* to *T* only if adding *e* does not create a cycle.
- ▶ Sorting edges takes $O(m \log n)$ time.
- ▶ Key question: "Does adding e = (u, v) to T create a cycle?"
 - ▶ Maintain set of connected components of *T*.
 - ► FIND(u): return the name of the connected component of *T* that *u* belongs to.
 - ▶ UNION(A, B): merge connected components A and B.
- ► Answering the question: Adding e creates a cycle if and only if FIND(u) = FIND(v). If not, execute UNION(FIND(u), FIND(v)).

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- ► We will show two implementations of UNION-FIND:
 - ► Each FIND takes *O*(1) time, *k* invocations of UNION take *O*(*k* log *k*) time in total.
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- ▶ Total running time of Kruskal's algorithm is $O(m \log n)$.







Teoria dos Grafos e Computabilidade

— Huffman code —

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How do we know when the next symbol begins?

Use a separation symbol (like the pause in Morse), or make sure that there is no ambiguity by ensuring that no code is a prefix of another one

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$$2*fa + 2*fe + 3*fk + 2*fl + 4*fu = 2.4 G$$
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```
Algorithm: Huffman code input: A set S of elements with their frequencies. output: A prefix tree 

1 if S = 2 then 
2 | return a tree with root and 2 leaves; 3 else 
4 | let y and z be lowest-frequency letters in S; 5' = S; 6 remove y and z from S'; 7 insert new letter w in S' with f_w = f_y + f_z; 8 = T' = Huffman(S'); 9 = T' = Huffman(S'); 10 return T'; 11 end
```