





Teoria dos Grafos e Computabilidade

— Tractability and Intractability —

Silvio Jamil F. Guimarães

Graduate Program in Informatics – PPGINF Laboratory of Image and Multimedia Data Science – IMScience Pontifical Catholic University of Minas Gerais – PUC Minas







Teoria dos Grafos e Computabilidade

— Intractability —

Silvio Jamil F. Guimarães

Graduate Program in Informatics – PPGINF Laboratory of Image and Multimedia Data Science – IMScience Pontifical Catholic University of Minas Gerais – PUC Minas

Algorithm Design

Patterns

- ► Greed.
- ► Divide-and-conquer.
- ► Dynamic programming.
- Duality.

 $O(n \log n)$ interval scheduling. $O(n \log n)$ closest pair of points. $O(n^2)$ edit distance. $O(n^3)$ maximum flow and minimum cuts.

Algorithm Design

Patterns

- ▶ Greed.
- ► Divide-and-conquer.
- ► Dynamic programming.
- Duality.
- Reductions.
- ▶ Local search.
- ► Randomization.

 $O(n \log n)$ interval scheduling. $O(n \log n)$ closest pair of points. $O(n^2)$ edit distance. $O(n^3)$ maximum flow and minimum cuts.

Algorithm Design

Patterns

- ► Greed.
- ► Divide-and-conquer.
- ► Dynamic programming.
- ► Duality.
- ► Reductions.
- ▶ Local search.
- ▶ Randomization.

Anti-patterns

- ► NP-completeness.
- ► PSPACE-completeness.
- ► Undecidability.

 $O(n \log n)$ interval scheduling. $O(n \log n)$ closest pair of points. $O(n^2)$ edit distance.

 $O(n^3)$ maximum flow and minimum cuts.

 $O(n^k)$ algorithm unlikely. $O(n^k)$ certification algorithm unlikely. No algorithm possible.

▶ When is an algorithm an efficient solution to a problem?

► When is an algorithm an efficient solution to a problem?

When its running time is polynomial in the size of the input.

- ▶ When is an algorithm an efficient solution to a problem?
 When its running time is polynomial in the size of the input.
- ► A problem is computationally tractable

if it has a polynomial-time algorithm.

- ▶ When is an algorithm an efficient solution to a problem? When its running time is polynomial in the size of the input.
- ► A problem is computationally tractable

if it has a polynomial-time algorithm.

Polynomial time Probably not Shortest path Longest path Matching 3-D matching Minimum cut Maximum cut 2-SAT 3-SAT Planar four-colour Planar three-colour Bipartite vertex cover Vertex cover Primality testing **Factoring**

Problem Classification

- Classify problems based on whether they admit efficient solutions or not.
- ► Some extremely hard problems cannot be solved efficiently (e.g., chess on an *n*-by-*n* board).

Problem Classification

- ► Classify problems based on whether they admit efficient solutions or not .
- ► Some extremely hard problems cannot be solved efficiently (e.g., chess on an *n*-by-*n* board).
- ► However, classification is unclear for a very large number of discrete computational problems.

Problem Classification

- Classify problems based on whether they admit efficient solutions or not.
- ► Some extremely hard problems cannot be solved efficiently (e.g., chess on an *n*-by-*n* board).
- ► However, classification is unclear for a very large number of discrete computational problems.
- ► We can prove that these problems are fundamentally equivalent and are manifestations of the same problem!







Teoria dos Grafos e Computabilidade

— Reductions —

Silvio Jamil F. Guimarães

Graduate Program in Informatics – PPGINF Laboratory of Image and Multimedia Data Science – IMScience Pontifical Catholic University of Minas Gerais – PUC Minas

Polynomial-Time Reduction

- ► The goal is to express statements of the type

 Problem X is at least as hard as problem Y.
- Use the notion of reductions.

Y is polynomial-time reducible to X ($Y \leq_P X$)

Polynomial-Time Reduction

- ► The goal is to express statements of the type

 Problem X is at least as hard as problem Y.
- ▶ Use the notion of reductions.

Y is polynomial-time reducible to X ($Y \leq_P X$)

if an arbitrary instance of Y can be solved using a polynomial number of standard operations, plus a polynomial number of calls to a black box that solves problem X.

- ▶ $Y \leq_P X$ implies that X is at least as hard as Y.
- ► Such reductions are Cook reductions. Karp reductions allow only one call to the black box that solves *X*.

Claim: If $Y \leq_P X$ and X can be solved in polynomial time, then Y can be solved in polynomial time.

Claim: If $Y \leq_P X$ and X can be solved in polynomial time, then Y can be solved in polynomial time.

Contrapositive: If $Y \leq_P X$ and Y cannot be solved in polynomial time, then X cannot be solved in polynomial time.

- Claim: If $Y \leq_P X$ and X can be solved in polynomial time, then Y can be solved in polynomial time.
- **Contrapositive:** If $Y \leq_P X$ and Y cannot be solved in polynomial time, then X cannot be solved in polynomial time.
- **Informally:** If Y is hard, and we can show that Y reduces to X, then the hardness spreads to X.

Claim: If $Y \leq_P X$ and X can be solved in polynomial time, then Y can be solved in polynomial time.

Contrapositive: If $Y \leq_P X$ and Y cannot be solved in polynomial time, then X cannot be solved in polynomial time.

Informally: If Y is hard, and we can show that Y reduces to X, then the hardness spreads to X.

Purpose. Classify problems according to relative difficulty.

- Claim: If $Y \leq_P X$ and X can be solved in polynomial time, then Y can be solved in polynomial time.
- **Contrapositive:** If $Y \leq_P X$ and Y cannot be solved in polynomial time, then X cannot be solved in polynomial time.
- **Informally:** If Y is hard, and we can show that Y reduces to X, then the hardness spreads to X.

Purpose. Classify problems according to relative difficulty.

▶ If $Y \leq_P X$ and X can be solved in polynomial-time, then Y can also be solved in polynomial time.

Design algorithms

- Claim: If $Y \leq_P X$ and X can be solved in polynomial time, then Y can be solved in polynomial time.
- **Contrapositive:** If $Y \leq_P X$ and Y cannot be solved in polynomial time, then X cannot be solved in polynomial time.
- **Informally:** If Y is hard, and we can show that Y reduces to X, then the hardness spreads to X.

Purpose. Classify problems according to relative difficulty.

- ▶ If $Y \leq_P X$ and X can be solved in polynomial-time, then Y can also be solved in polynomial time.

 Design algorithms
- ▶ If $Y \leq_P X$ and Y cannot be solved in polynomial-time, then X cannot be solved in polynomial time. Establish intractability

- Claim: If $Y \leq_P X$ and X can be solved in polynomial time, then Y can be solved in polynomial time.
- **Contrapositive:** If $Y \leq_P X$ and Y cannot be solved in polynomial time, then X cannot be solved in polynomial time.
- **Informally:** If Y is hard, and we can show that Y reduces to X, then the hardness spreads to X.

Purpose. Classify problems according to relative difficulty.

- ▶ If $Y \leq_P X$ and X can be solved in polynomial-time, then Y can also be solved in polynomial time.

 Design algorithms
- ▶ If $Y \leq_P X$ and Y cannot be solved in polynomial-time, then X cannot be solved in polynomial time. Establish intractability
- ▶ If $X \leq_P Y$ and $Y \leq_P X$, we use notation $X \equiv_P Y$ in order to express the equivalence. Establish equivalence

Polynomial Transformation

Problem X polynomial reduces (Cook) to problem Y if arbitrary instances of problem X can be solved using:

- ► Polynomial number of standard computational steps, plus
- ▶ Polynomial number of calls to oracle that solves problem Y.

Polynomial Transformation

Problem X polynomial reduces (Cook) to problem Y if arbitrary instances of problem X can be solved using:

- ► Polynomial number of standard computational steps, plus
- ▶ Polynomial number of calls to oracle that solves problem Y.

Problem X polynomial transforms (Karp) to problem Y if given any input x to X, we can construct an input y such that x is a yes instance of X iff y is a yes instance of Y.

Polynomial Transformation

Problem X polynomial reduces (Cook) to problem Y if arbitrary instances of problem X can be solved using:

- ► Polynomial number of standard computational steps, plus
- ▶ Polynomial number of calls to oracle that solves problem Y.

Problem X polynomial transforms (Karp) to problem Y if given any input x to X, we can construct an input y such that x is a yes instance of X iff y is a yes instance of Y.

Polynomial transformation is polynomial reduction with just one call to oracle for Y, exactly at the end of the algorithm for X. Almost all previous reductions were of this form.

Reduction Design a fast algorithm for one computational problem, using a supposedly fast algorithm for another problem as a subroutine.

Reduction Design a fast algorithm for one computational problem, using a supposedly fast algorithm for another problem as a subroutine.

- ▶ Use to compare the two problems.
- Even if we don't know whether they can be solved in polynomial time or not,
- ▶ We can learn that either they both can or neither can.
- ► We can also learn that they have a similar structure.

Reduction Design a fast algorithm for one computational problem, using a supposedly fast algorithm for another problem as a subroutine.

- ▶ Use to compare the two problems.
- Even if we don't know whether they can be solved in polynomial time or not,
- ▶ We can learn that either they both can or neither can.
- ► We can also learn that they have a similar structure.

Design a fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine.

 $P_{alg} \leq_P P_{oracle}$

Cook Reduction Design any fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine

$P_{alg} \leq_P P_{oracle}$

Cook Reduction Design any fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine

Karp Reduction The algorithm for P_{alg} calls that for P_{oracle} only once: Yes \Rightarrow Yes & No \Rightarrow No

$P_{alg} \leq_P P_{oracle}$

Cook Reduction Design any fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine

Karp Reduction The algorithm for P_{alg} calls that for P_{oracle} only once: Yes \Rightarrow Yes & No \Rightarrow No

We give a fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine.

$P_{alg} \leq_P P_{oracle}$

Cook Reduction Design any fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine

Karp Reduction The algorithm for P_{alg} calls that for P_{oracle} only once: Yes \Rightarrow Yes & No \Rightarrow No

We give a fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine.

Is there a fast algorithm for P_{alg} ?

$P_{alg} \leq_P P_{oracle}$

Cook Reduction Design any fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine

Karp Reduction The algorithm for P_{alg} calls that for P_{oracle} only once: Yes \Rightarrow Yes & No \Rightarrow No

We give a fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine.

Is there a fast algorithm for P_{alg} ? Is there a fast algorithm for P_{oracle} ?

We give a fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine.

If there is a fast algorithm for
$$P_{alg}$$
?

If there is not a fast algorithm for P_{alg} ?

If there is a fast algorithm for
$$P_{oracle}$$
?

If there is not a fast algorithm for P_{oracle} ?

We give a fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine.

If there is a fast algorithm for P_{alg} ?

If there is not a fast algorithm for P_{alg} ?

If there is a fast algorithm for P_{oracle} ?

then there is a fast algorithm for P_{alg}

If there is not a fast algorithm for P_{oracle} ?

We give a fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine.

If there is a fast algorithm for P_{alg} ?

If there is not a fast algorithm for P_{alg} ?

then there is not a fast algorithm for P_{oracle}

If there is a fast algorithm for P_{oracle} ?

then there is a fast algorithm for P_{alg}

If there is not a fast algorithm for P_{oracle} ?

We give a fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine.

If there is a fast algorithm for P_{alg} ?

???

If there is a fast algorithm for P_{oracle} ?

then there is a fast algorithm for P_{alg}

If there is not a fast algorithm for P_{alg} ?

then there is not a fast algorithm for P_{oracle}

If there is not a fast algorithm for P_{oracle} ?

We give a fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine.

If there is a fast algorithm for P_{alg} ?

???

If there is a fast algorithm for P_{oracle} ?

then there is a fast algorithm for P_{alg}

If there is not a fast algorithm for P_{alg} ?

then there is not a fast algorithm for P_{oracle}

If there is not a fast algorithm for P_{oracle} ?

???

We give a fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine.

We give a fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine.

$$P_{alg}$$
 is at least as easy as P_{oracle} (Modulo polynomial terms.)

We give a fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine.

```
P_{alg} is at least as easy as P_{oracle} (Modulo polynomial terms.)

P_{oracle} is at least as hard as P_{alg} (Modulo polynomial terms.)
```

We give a fast algorithm for P_{alg} using a supposed fast algorithm for P_{oracle} as a subroutine.

$$P_{alg}$$
 is at least as easy as P_{oracle} (Modulo polynomial terms.)

 P_{oracle} is at least as hard as P_{alg} (Modulo polynomial terms.)

The problems have a similar underling structure and it is used to design new Algorithms

Reduction Strategies

- ► Simple equivalence.
- ► Special case to general case.
- ► Encoding with gadgets.

Optimization versus Decision Problems

- ► So far, we have developed algorithms that solve optimization problems.
 - ► Compute the largest flow.
 - ► Find the closest pair of points.
 - ► Find the schedule with the least completion time.

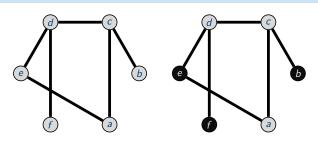
Optimization versus Decision Problems

- ► So far, we have developed algorithms that solve optimization problems.
 - ► Compute the largest flow.
 - ► Find the closest pair of points.
 - ► Find the schedule with the least completion time.
- ► Now, we will focus on decision versions of problems, e.g.,

Is there a flow with value at least k, for a given value of k?

Independent sets

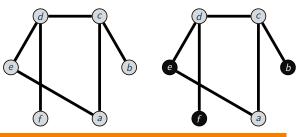
- ▶ A subset $S \subseteq V$ is an independent set if $\forall u, v \in S$ there exist an edge $(u, v) \in E$.
- ▶ Given G and an integer k, is there a subset of vertices $S \subseteq V$ such that $|S| \ge k$, and for each edge at most one of its endpoints is in S?



Independent sets

Let G = (V, E) be an undirected connected graph.

- ▶ A subset $S \subseteq V$ is an independent set if $\forall u, v \in S$ there exist an edge $(u, v) \in E$.
- ▶ Given G and an integer k, is there a subset of vertices $S \subseteq V$ such that $|S| \ge k$, and for each edge at most one of its endpoints is in S?

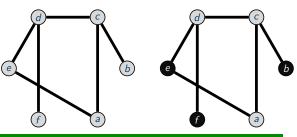


Is there an independent set of size \geq 3? Yes.

Independent sets

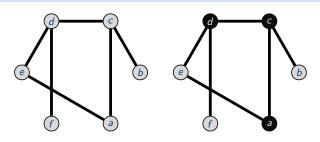
Let G = (V, E) be an undirected connected graph.

- ▶ A subset $S \subseteq V$ is an independent set if $\forall u, v \in S$ there exist an edge $(u, v) \in E$.
- ▶ Given G and an integer k, is there a subset of vertices $S \subseteq V$ such that $|S| \ge k$, and for each edge at most one of its endpoints is in S?

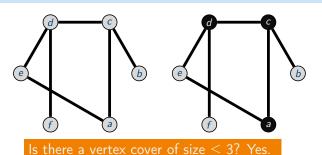


Is there an independent set of size \geq 4? No.

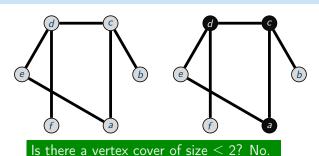
- ▶ A subset $S \subseteq V$ is an vertex cover if $\forall (u, v) \in E$, either $u \in S$ or $v \in S$.
- ► Given a graph G and an integer k, is there a subset of vertices S ⊆ V such that |S| ≤ k, and for each edge, at least one of its endpoints is in S?



- ▶ A subset $S \subseteq V$ is an vertex cover if $\forall (u, v) \in E$, either $u \in S$ or $v \in S$.
- ▶ Given a graph G and an integer k, is there a subset of vertices $S \subseteq V$ such that $|S| \le k$, and for each edge, at least one of its endpoints is in S?

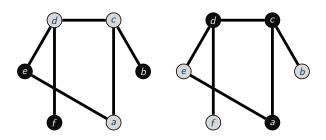


- ▶ A subset $S \subseteq V$ is an vertex cover if $\forall (u, v) \in E$, either $u \in S$ or $v \in S$.
- ► Given a graph G and an integer k, is there a subset of vertices S ⊆ V such that |S| ≤ k, and for each edge, at least one of its endpoints is in S?



Let G = (V, E) be an undirected connected graph, and S a vertex cover of G

As S is a vertex cover of G, then V-S is an independent set.



- ▶ Given an undirected graph G(V, E), a subset $S \subseteq V$ is an independent set if no two vertices in S are connected by an edge.
- ▶ Given an undirected graph G(V, E), a subset $S \subseteq V$ is a vertex cover if every edge in E is incident on at least one vertex in S.

- ▶ Given an undirected graph G(V, E), a subset $S \subseteq V$ is an independent set if no two vertices in S are connected by an edge.
- ▶ Given an undirected graph G(V, E), a subset $S \subseteq V$ is a vertex cover if every edge in E is incident on at least one vertex in S.

_				
TNID	DDD	NIDE	NTOD !	S Tom

INSTANCE Undirected graph G and an integer k

QUESTION Does G contain an independent set of size

VERTEX COVER

INSTANCE Undirected graph G and an integer k

QUESTION Does *G* contain a vertex cover of size

- ▶ Given an undirected graph G(V, E), a subset $S \subseteq V$ is an independent set if no two vertices in S are connected by an edge.
- ▶ Given an undirected graph G(V, E), a subset $S \subseteq V$ is a vertex cover if every edge in E is incident on at least one vertex in S.

INDEPENDENT SET

INSTANCE Undirected graph G and an integer k

at least k?

VERTEX COVER

INSTANCE Undirected graph G and an integer k

QUESTION Does G contain a vertex

cover of size at most k?

- ▶ Given an undirected graph G(V, E), a subset $S \subseteq V$ is an independent set if no two vertices in S are connected by an edge.
- ▶ Given an undirected graph G(V, E), a subset $S \subseteq V$ is a vertex cover if every edge in E is incident on at least one vertex in S.

-	a	3.7	
INDEPENDENT SET		Vertex cover	
INSTANCE	Undirected graph G and an integer k	INSTANCE	Undirected graph G and an integer k
QUESTION	Does <i>G</i> contain an independent set of size at least <i>k</i> ?	QUESTION	Does <i>G</i> contain a vertex cover of size at most <i>k</i> ?

Demonstrate simple equivalence between these two problems.

- ▶ Given an undirected graph G(V, E), a subset $S \subseteq V$ is an independent set if no two vertices in S are connected by an edge.
- ▶ Given an undirected graph G(V, E), a subset $S \subseteq V$ is a vertex cover if every edge in E is incident on at least one vertex in S.

INDEPENDENT SET		VERTEX COVER	
INSTANCE	Undirected graph G and an integer k	INSTANCE	Undirected graph G and an integer k
QUESTION	Does <i>G</i> contain an independent set of size at least <i>k</i> ?	QUESTION	Does <i>G</i> contain a vertex cover of size at most <i>k</i> ?

- ▶ Demonstrate simple equivalence between these two problems.
- \triangleright S is an independent set in G iff V-S is a vertex cover in G.

- ▶ Given an undirected graph G(V, E), a subset $S \subseteq V$ is an independent set if no two vertices in S are connected by an edge.
- ▶ Given an undirected graph G(V, E), a subset $S \subseteq V$ is a vertex cover edge in E is incident on at least one vertex in S.

INDEPENDENT SET		VERTEX COVER	
INSTANCE	Undirected graph G and an integer k	INSTANCE	Undirected graph G and an integer k
QUESTION	Does <i>G</i> contain an independent set of size at least <i>k</i> ?	QUESTION	Does <i>G</i> contain a vertex cover of size at most <i>k</i> ?

- ▶ Demonstrate simple equivalence between these two problems.
- \blacktriangleright S is an independent set in G iff V-S is a vertex cover in G.
- ▶ INDEPENDENT SET \leq_P VERTEX COVER and VERTEX COVER \leq_P INDEPENDENT SET.

Independent Set \equiv_P Vertex Cover

We show S is an independent set iff V - S is a vertex cover

Independent Set \equiv_{P} Vertex Cover

We show S is an independent set iff V - S is a vertex cover

- ► Let S be any independent set.
- ► Consider an arbitrary edge (u, v).
- ▶ S independent $\Rightarrow u \notin S$ or $v \notin S \Rightarrow u \in V S$ or $v \in V S$.
- ► Thus, V S covers (u, v).

Independent Set \equiv_{P} Vertex Cover

We show S is an independent set iff V - S is a vertex cover

- ► Let S be any independent set.
- ► Consider an arbitrary edge (u, v).
- ▶ S independent $\Rightarrow u \notin S$ or $v \notin S \Rightarrow u \in V S$ or $v \in V S$.
- ► Thus, V S covers (u, v).
- ► Let V S be any vertex cover.
- ▶ Consider two nodes $u \in S$ and $v \in S$.
- ▶ Observe that $(u, v) \notin E$ since V S is a vertex cover.
- ► Thus, no two nodes in S are joined by an edge ⇒ S independent set

Given a set U of elements, a collection $S = \{S_1, S_2, \dots, S_m\}$ of subsets of U.

- ▶ A subset $C \subseteq S$ is a set cover if the union of elements of C is equal to U.
- ▶ Given U, S, and an integer k, does there exist a collection of ≤ k of these sets whose union is equal to U?

Given a set U of elements, a collection $S = \{S_1, S_2, \dots, S_m\}$ of subsets of U.

- ▶ A subset $C \subseteq S$ is a set cover if the union of elements of C is equal to U.
- ▶ Given U, S, and an integer k, does there exist a collection of \leq k of these sets whose union is equal to U?

Sample application:

- ► *m* available pieces of software
- ► Set U of *n* capabilities that we would like our system to have
- ▶ The i^{th} piece of software provides the set $S_i \subseteq U$ of capabilities.
- ► The goal is to achieve all *n* capabilities using fewest pieces of software .

Given a set U of elements, a collection $S = \{S_1, S_2, \dots, S_m\}$ of subsets of U.

- ▶ A subset $C \subseteq S$ is a set cover if the union of elements of C is equal to U.
- ▶ Given U, S, and an integer k, does there exist a collection of \leq k of these sets whose union is equal to U?

Sample application:

▶ $U = \{1, 2, 3, 4, 5, 6, 7\}$ and k = 2

$$S_1 = \{3,7\}$$
 $S_4 = \{2,4\}$
 $S_2 = \{3,4,5,6\}$ $S_5 = \{5\}$
 $S_3 = \{1\}$ $S_6 = \{1,2,6,7\}$

Given a set U of elements, a collection $S = \{S_1, S_2, \dots, S_m\}$ of subsets of U.

- ▶ A subset $C \subseteq S$ is a set cover if the union of elements of C is equal to U.
- ▶ Given U, S, and an integer k, does there exist a collection of \leq k of these sets whose union is equal to U?

Sample application:

▶ $U = \{1, 2, 3, 4, 5, 6, 7\}$ and k = 2

$$S_1 = \{3,7\}$$
 $S_4 = \{2,4\}$
 $S_2 = \{3,4,5,6\}$ $S_5 = \{5\}$
 $S_3 = \{1\}$ $S_6 = \{1,2,6,7\}$

Vertex Cover and Set Cover

- ► Set cover is a packing problem: pack as many vertices as possible, subject to constraints (the edges).
- ► Vertex Cover is a covering problem: cover all edges in the graph with as few vertices as possible.
- ► There are more general covering problems.

Vertex Cover and Set Cover

- Set cover is a packing problem: pack as many vertices as possible, subject to constraints (the edges).
- ► Vertex Cover is a covering problem: cover all edges in the graph with as few vertices as possible.
- ► There are more general covering problems.

Set Cover		VERTEX COVER	
INSTANCE	A set U of n elements, a collection S_1, S_2, \ldots, S_m of sub-	INSTANCE	Undirected graph G and an integer k
	sets of U , and an integer k .	QUESTION	Does <i>G</i> contain a vertex cover of size
QUESTION	Is there a collection of $\leq k$ sets in the collection whose union is U ?		

Vertex Cover and Set Cover

- ▶ Set cover is a packing problem: pack as many vertices as possible, subject to constraints (the edges).
- ► Vertex Cover is a covering problem: cover all edges in the graph with as few vertices as possible.
- ► There are more general covering problems.

SET COVED

D	EI COVER	▼ 1 2.	ILLEX COVER
NSTANCE	A set U of n elements, a collection	INSTANCE	Undirected graph G and an integer k
	S_1, S_2, \dots, S_m of subsets of U , and an integer k .	QUESTION	Does <i>G</i> contain a vertex cover of size

QUESTION Is there a collection of < k sets in the collection whose union is U?

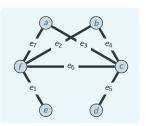
VEDUEV COVED

at most k?

- ▶ Input to Vertex Cover is an undirected graph G = (V, E) with n vertices.
- ► Create an instance of Set Cover in which
 - ▶ k = k, U = E, $S_v = \{e \in E : e \text{ incident to } v\}$

- ▶ Input to Vertex Cover is an undirected graph G = (V, E) with n vertices.
- ► Create an instance of Set Cover in which
 - ▶ k = k, U = E, $S_v = \{e \in E : e \text{ incident to } v\}$
- ► *U* can be covered with fewer than *k* subsets iff *G* has a vertex cover with at most *k* nodes.

- ▶ Input to Vertex Cover is an undirected graph G = (V, E) with n vertices.
- ► Create an instance of Set Cover in which
 - ▶ k = k, U = E, $S_v = \{e \in E : e \text{ incident to } v\}$
- ► *U* can be covered with fewer than *k* subsets iff *G* has a vertex cover with at most *k* nodes.



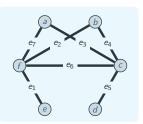
Reducing Vertex Cover to Set Cover

VERTEX COVER \leq_P SET COVER

- ▶ Input to Vertex Cover is an undirected graph G = (V, E) with n vertices.
- ► Create an instance of Set Cover in which

▶
$$k = k$$
, $U = E$, $S_v = \{e \in E : e \text{ incident to } v\}$

► *U* can be covered with fewer than *k* subsets iff *G* has a vertex cover with at most *k* nodes.



$$U = \{1, 2, 3, 4, 5, 6, 7\}$$
 and $k = 2$

$$S_1 = \{3,7\}$$
 $S_4 = \{2,4\}$
 $S_2 = \{3,4,5,6\}$ $S_5 = \{5\}$
 $S_3 = \{1\}$ $S_6 = \{1,2,6,7\}$

Boolean Satisfiability

- ► Abstract problems formulated in Boolean notation.
- ▶ Often used to specify problems, e.g., in Al.

Boolean Satisfiability

- ► Abstract problems formulated in Boolean notation.
- ▶ Often used to specify problems, e.g., in Al.
- ▶ We are given a set $X = \{x_1, x_2, ..., x_n\}$ of n Boolean variables.
- ► Each variable can take the value 0 or 1.
- ▶ A **term** is a variable x_i or its negation $\overline{x_i}$.
- ▶ A clause of length I is a disjunction of I distinct terms $t_1 \lor t_2 \lor \cdots t_I$.
- ▶ A truth assignment for X is a function $\nu: X \to \{0,1\}$.
- ► An assignment satisfies a clause *C* if it causes *C* to evaluate to 1 under the rules of Boolean logic.
- ▶ An assignment satisfies a collection of clauses $C_1, C_2, ..., C_k$ if it causes $C_1 \land C_2 \land \cdots \land C_k$ to evaluate to 1.
 - \triangleright ν is a **satisfying assignment** with respect to $C_1, C_2, \dots C_k$.
 - ▶ set of clauses $C_1, C_2, ..., C_k$ is **satisfiable**.

SAT and 3-SAT

SATISFIABILITY PROBLEM (SAT)

INSTANCE A set of clauses $C_1, C_2, \dots C_k$ over a set $X = \{x_1, x_2, \dots x_n\}$ of

n variables.

QUESTION Is there a satisfying truth assignment for X with respect to C?

SAT and 3-SAT

Satisfiability Problem (SAT)

INSTANCE A set of clauses $C_1, C_2, \dots C_k$ over a set $X = \{x_1, x_2, \dots x_n\}$ of

n variables.

QUESTION Is there a satisfying truth assignment for X with respect to C?

3-Satisfiability Problem (3-SAT)

INSTANCE A set of clauses $C_1, C_2, \dots C_k$ each of length 3 over a set X =

 $\{x_1, x_2, \dots x_n\}$ of n variables.

QUESTION Is there a satisfying truth assignment for X with respect to C?

SAT and 3-SAT

Satisfiability Problem (SAT)

INSTANCE A set of clauses $C_1, C_2, \dots C_k$ over a set $X = \{x_1, x_2, \dots x_n\}$ of n variables.

QUESTION Is there a satisfying truth assignment for X with respect to C?

3-Satisfiability Problem (3-SAT)

INSTANCE A set of clauses $C_1, C_2, ..., C_k$ each of length 3 over a set $X = \{x_1, x_2, ..., x_n\}$ of n variables.

QUESTION Is there a satisfying truth assignment for X with respect to C?

- ► SAT and 3-SAT are fundamental combinatorial search problems.
- ▶ We have to make *n* independent decisions (the assignments for each variable) while satisfying a set of constraints.
- Satisfying each constraint in isolation is easy, but we have to make our decisions so that all constraints are satisfied simultaneously.

3-SAT and Independent Set

▶ We want to prove $3\text{-SAT} \leq_P \text{INDEPENDENT SET}$.

3-SAT and Independent Set

- ▶ We want to prove $3\text{-SAT} \leq_P \text{INDEPENDENT SET}$.
- ► Two ways to think about 3-SAT:
 - 1. Make an independent 0/1 decision on each variable and succeed if we achieve one of three ways in which to satisfy each clause.
 - 2. Choose (at least) one term from each clause. Find a truth assignment that causes each chosen term to evaluate to 1. Ensure that no two terms selected **conflict**, i.e., select x_i and $\overline{x_i}$.

$3-SAT \leq_P INDEPENDENT SET$

Given an instance Φ of 3-SAT, we construct an instance (G, k) of independent set that has an independent set of size k iff Φ is satisfiable.

$3-SAT \leq_P INDEPENDENT SET$

Given an instance Φ of 3-SAT, we construct an instance (G, k) of independent set that has an independent set of size k iff Φ is satisfiable.

$$\Phi = (\overline{x_1} \vee x_2 \vee x_3) \wedge (\overline{x_2} \vee x_1 \vee x_3) \wedge (\overline{x_1} \vee x_2 \vee x_4)$$

$3-SAT \leq_P INDEPENDENT SET$

Given an instance Φ of 3-SAT, we construct an instance (G, k) of independent set that has an independent set of size k iff Φ is satisfiable.

Construction.

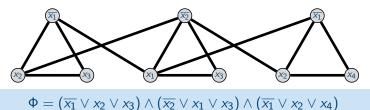
- ► G contains 3 nodes for each clause (k=3), one for each literal.
- ► Connect 3 literals in a clause in a triangle.
- Connect literal to each of its negations.

$3-SAT \leq_P INDEPENDENT SET$

Given an instance Φ of 3-SAT, we construct an instance (G, k) of independent set that has an independent set of size k iff Φ is satisfiable.

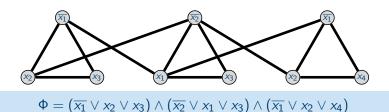
Construction.

- ▶ G contains 3 nodes for each clause (k=3), one for each literal.
- ► Connect 3 literals in a clause in a triangle.
- ► Connect literal to each of its negations.



$3-SAT \leq_P INDEPENDENT SET$

G contains independent set of size $k = |\Phi|$ iff Φ is satisfiable.



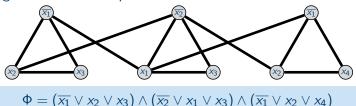
$3-SAT \leq_P INDEPENDENT SET$

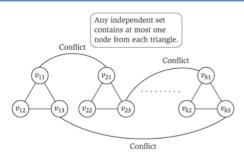
G contains independent set of size $k = |\Phi|$ iff Φ is satisfiable.

\Rightarrow Let S be independent set of size k

- ▶ S must contain exactly one vertex in each triangle.
- Set these literals to true.
- ► Truth assignment is consistent and all clauses are satisfied.

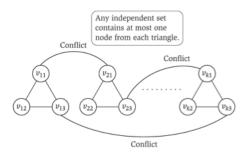
← Given satisfying assignment , select one true literal from each triangle. This is an independent set of size k.



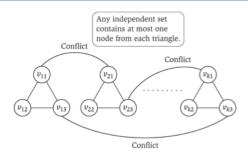


- ► We are given an instance of 3-SAT with *k* clauses of length three over *n* variables .
- ► Construct a graph G = (V, E) with 3k nodes.
 - ► For each clause C_i , $1 \le i \le k$, add a triangle of three nodes v_{i1} , v_{i2} , v_{i3} and three edges to G.
 - ▶ Label each node v_{ij} , $1 \le j \le 3$ with the j-th term in C_i
 - Add an edge between each pair of nodes whose labels correspond to terms that conflict.

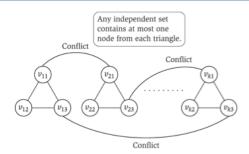
Proving 3-SAT \leq_P Independent Set



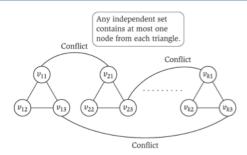
▶ Claim: 3-SAT instance is satisfiable iff G has an independent set of size at least k.



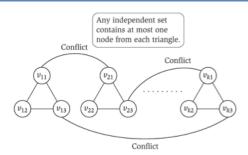
- ► Claim: 3-SAT instance is satisfiable iff *G* has an independent set of size at least *k*.
- ► Satisfiable assignment \rightarrow independent set of size $\geq k$



- ► Claim: 3-SAT instance is satisfiable iff *G* has an independent set of size at least *k*.
- Satisfiable assignment \rightarrow independent set of size $\geq k$ Each triangle in G has at least one node whose label evaluates to 1. These nodes form an independent set of size k. Why?



- ► Claim: 3-SAT instance is satisfiable iff *G* has an independent set of size at least *k*.
- Satisfiable assignment \rightarrow independent set of size $\geq k$ Each triangle in G has at least one node whose label evaluates to 1. These nodes form an independent set of size k. Why?
- Independent set of size $\geq k \rightarrow \text{satisfiable assignment}$



- ► Claim: 3-SAT instance is satisfiable iff G has an independent set of size at least k.
- Satisfiable assignment \rightarrow independent set of size $\geq k$ Each triangle in G has at least one node whose label evaluates to 1. These nodes form an independent set of size k. Why?
- Independent set of size $\geq k \rightarrow$ satisfiable assignment the size of this set is k. How do we construct a satisfying truth assignment from the nodes in the independent set?

Transitivity of Reductions

Basic reduction strategies.

- ► Simple equivalence: INDEPENDENT SET \equiv_P VERTEX COVER.
- ▶ Special case to general case: VERTEX COVER \leq_P SET COVER.
- ▶ Encoding with gadgets: 3-SAT \leq_P INDEPENDENT SET.

Transitivity of Reductions

Basic reduction strategies.

- ▶ Simple equivalence: INDEPENDENT SET \equiv_P VERTEX COVER.
- ▶ Special case to general case: VERTEX COVER \leq_P SET COVER.
- ▶ Encoding with gadgets: $3-SAT \leq_P INDEPENDENT SET$.

If
$$Z \leq_P Y$$
 and $Y \leq_P X$, then $Z \leq_P X$

Transitivity of Reductions

Basic reduction strategies.

- ► Simple equivalence: INDEPENDENT SET \equiv_P VERTEX COVER.
- ▶ Special case to general case: VERTEX COVER \leq_P SET COVER.
- ▶ Encoding with gadgets: $3-SAT \leq_P INDEPENDENT SET$.

If
$$Z \leq_P Y$$
 and $Y \leq_P X$, then $Z \leq_P X$

3-SAT \leq_P INDEPENDENT SET \leq_P VERTEX COVER \leq_P SET COVER







Teoria dos Grafos e Computabilidade

 $-\mathcal{NP}$

Silvio Jamil F. Guimarães

Graduate Program in Informatics – PPGINF Laboratory of Image and Multimedia Data Science – IMScience Pontifical Catholic University of Minas Gerais – PUC Minas

Finding vs. Certifying

- ▶ Is it easy to check if a given set of vertices in an undirected graph forms an independent set of size at least *k*?
- ► Is it easy to check if a particular truth assignment satisfies a set of clauses?

Finding vs. Certifying

- ▶ Is it easy to check if a given set of vertices in an undirected graph forms an independent set of size at least *k*?
- ► Is it easy to check if a particular truth assignment satisfies a set of clauses?
- ► We draw a contrast between finding a solution and checking a solution (in polynomial time).

We have not been able to develop efficient algorithms to solve many decision problems, let us turn our attention to whether we can check if a proposed solution is correct.

- ► Encode input to a computational problem as a finite binary string s of length |s|.
- ► Identify a decision problem X with the set of strings for which the answer is yes,

- ► Encode input to a computational problem as a finite binary string s of length |s|.
- ▶ Identify a decision problem X with the set of strings for which the answer is yes, e.g., $PRIMES = \{2, 3, 5, 7, 11, ...\}$.

- ► Encode input to a computational problem as a finite binary string s of length |s|.
- ▶ Identify a decision problem X with the set of strings for which the answer is yes, e.g., $PRIMES = \{2, 3, 5, 7, 11, ...\}$.
- ▶ An algorithm A for a decision problem receives an input string s and returns $A(s) \in \{\text{yes}, \text{no}\}.$
- ▶ A solves the problem X if for every string s, A(s) = yes iff $s \in X$.

- ► Encode input to a computational problem as a finite binary string s of length |s|.
- ▶ Identify a decision problem X with the set of strings for which the answer is yes, e.g., $PRIMES = \{2, 3, 5, 7, 11, ...\}$.
- ▶ An algorithm A for a decision problem receives an input string s and returns $A(s) \in \{yes, no\}$.
- ▶ A solves the problem X if for every string s, A(s) = yes iff $s \in X$.
- ▶ A has a polynomial running time if there is a polynomial function $p(\cdot)$ such that for every input string s, A terminates on s in at most O(p(|s|)) steps,

- ► Encode input to a computational problem as a finite binary string s of length |s|.
- ▶ Identify a decision problem X with the set of strings for which the answer is yes, e.g., $PRIMES = \{2, 3, 5, 7, 11, ...\}$.
- ▶ An algorithm A for a decision problem receives an input string s and returns $A(s) \in \{yes, no\}$.
- ▶ A solves the problem X if for every string s, A(s) = yes iff $s \in X$.
- ▶ A has a polynomial running time if there is a polynomial function $p(\cdot)$ such that for every input string s, A terminates on s in at most O(p(|s|)) steps, e.g., there is an algorithm such that $p(|s|) = |s|^8$ for PRIMES
- \triangleright \mathcal{P} : set of problems X for which there is a polynomial time algorithm.

Efficient Certification

- \blacktriangleright A checking algorithm for a decision problem X has a different structure from an algorithm that solves X.
- ► Checking algorithm needs input string s as well as a separate certificate string t that contains evidence that $s \in X$.

Efficient Certification

- \blacktriangleright A checking algorithm for a decision problem X has a different structure from an algorithm that solves X.
- ► Checking algorithm needs input string s as well as a separate certificate string t that contains evidence that $s \in X$.
- \blacktriangleright An algorithm B is an efficient certifier for a problem X if
 - 1. B is a polynomial time algorithm that takes two inputs s and t and
 - 2. there is a polynomial function p so that for every string s, we have $s \in X$ iff there exists a string t such that $|t| \le p(|s|)$ and B(s,t) = yes.

Efficient Certification

- ► A checking algorithm for a decision problem *X* has a different structure from an algorithm that solves *X*.
- ► Checking algorithm needs input string s as well as a separate certificate string t that contains evidence that $s \in X$.
- \blacktriangleright An algorithm B is an efficient certifier for a problem X if
 - 1. B is a polynomial time algorithm that takes two inputs s and t and
 - 2. there is a polynomial function p so that for every string s, we have $s \in X$ iff there exists a string t such that $|t| \le p(|s|)$ and B(s,t) = yes.
- ▶ Certifier's job is to take a candidate short proof (t) that $s \in X$ and check in polynomial time whether t is a correct proof.

Certifier does not care about how to find these proofs.



 \mathcal{NP} is the set of all problems for which there exists an efficient certifier .



 ${\cal NP}$ is the set of all problems for which there exists an efficient certifier .

 $3\text{-SAT} \in \mathcal{NP}$

\mathcal{NP}

 \mathcal{NP} is the set of all problems for which there exists an efficient certifier .

 $3\text{-SAT} \in \mathcal{NP}$

$$\Phi = (\overline{x_1} \vee x_2 \vee x_3) \wedge (\overline{x_2} \vee x_1 \vee x_3) \wedge (\overline{x_1} \vee x_2 \vee x_4)$$

Certificate $x_1 = 1, x_2 = 1, x_3 = 0 \text{ and } x_4 = 1$



 \mathcal{NP} is the set of all problems for which there exists an efficient certifier .

3-SAT $\in \mathcal{NP}$ t is a truth assignment; B evaluates the clauses with respect to the assignment.

$$\Phi = (\overline{x_1} \vee x_2 \vee x_3) \wedge (\overline{x_2} \vee x_1 \vee x_3) \wedge (\overline{x_1} \vee x_2 \vee x_4)$$

Certificate $x_1 = 1, x_2 = 1, x_3 = 0 \text{ and } x_4 = 1$



 \mathcal{NP} is the set of all problems for which there exists an efficient certifier .

3-SAT $\in \mathcal{NP}$ t is a truth assignment; B evaluates the clauses with respect to the assignment.

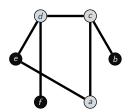
Independent Set $\in \mathcal{NP}$



NP is the set of all problems for which there exists an efficient certifier.

3-SAT $\in \mathcal{NP}$ t is a truth assignment; B evaluates the clauses with respect to the assignment.

Independent Set $\in \mathcal{NP}$

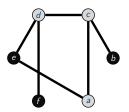




NP is the set of all problems for which there exists an efficient certifier.

3-SAT $\in \mathcal{NP}$ t is a truth assignment; B evaluates the clauses with respect to the assignment.

INDEPENDENT SET $\in \mathcal{NP}$ t is a set of at least k vertices; B checks that no pair of these vertices are connected by an edge.





\mathcal{NP} is the set of all problems for which there exists an efficient certifier .

3-SAT $\in \mathcal{NP}$ t is a truth assignment; B evaluates the clauses with respect to the assignment.

INDEPENDENT SET $\in \mathcal{NP}$ t is a set of at least k vertices; B checks that no pair of these vertices are connected by an edge.

Set Cover $\in \mathcal{NP}$



NP is the set of all problems for which there exists an efficient certifier.

3-SAT $\in \mathcal{NP}$ t is a truth assignment; B evaluates the clauses with respect to the assignment.

INDEPENDENT SET $\in \mathcal{NP}$ t is a set of at least k vertices; B checks that no pair of these vertices are connected by an edge.

Set Cover $\in \mathcal{NP}$

►
$$U = \{1, 2, 3, 4, 5, 6, 7\}$$
 and $k = 2$

$$S_1 = \{3, 7\}$$

$$S_2 = \{3, 4, 5, 6\}$$

$$S_3 = \{1\}$$

$$S_4 = \{2, 4\}$$

$$S_5 = \{5\}$$

$$S_6 = \{1, 2, 6, 7\}$$



\mathcal{NP} is the set of all problems for which there exists an efficient certifier .

- **3-SAT** $\in \mathcal{NP}$ t is a truth assignment; B evaluates the clauses with respect to the assignment.
- **INDEPENDENT SET** $\in \mathcal{NP}$ t is a set of at least k vertices; B checks that no pair of these vertices are connected by an edge.
- **SET COVER** $\in \mathcal{NP}$ t is a list of k sets from the collection; B checks if their union is U.

►
$$U = \{1, 2, 3, 4, 5, 6, 7\}$$
 and $k = 2$

$$S_1 = \{3, 7\}$$

$$S_2 = \{3, 4, 5, 6\}$$

$$S_3 = \{1\}$$

$$S_6 = \{1, 2, 6, 7\}$$

P Decision problems for which there is a

EXP Decision problems for which there is an

 \mathcal{NP} Decision problems for which there is a

poly-time algorithm

exponential-time algorithm

poly-time certifier

 ${\cal P}$ Decision problems for which there is a

EXP Decision problems for which there is an

 \mathcal{NP} Decision problems for which there is a

poly-time algorithm

exponential-time algorithm

poly-time certifier

 $\mathcal{P}\subseteq\mathcal{NP}$

P Decision problems for which there is a

poly-time algorithm

EXP Decision problems for which there is an

exponential-time algorithm

 \mathcal{NP} Decision problems for which there is a

poly-time certifier

▶ $\mathcal{P} \subseteq \mathcal{NP}$ If $X \in P$, then there is a polynomial time algorithm A that solves X. B ignores t and returns A(s). Why is B an efficient certifier?

 ${\cal P}$ Decision problems for which there is a

poly-time algorithm

EXP Decision problems for which there is an

exponential-time algorithm

 \mathcal{NP} Decision problems for which there is a

poly-time certifier

- ▶ $\mathcal{P} \subseteq \mathcal{NP}$ If $X \in P$, then there is a polynomial time algorithm A that solves X. B ignores t and returns A(s). Why is B an efficient certifier?
- ▶ Is $\mathcal{P} = \mathcal{N}\mathcal{P}$ or is $\mathcal{N}\mathcal{P} \mathcal{P} \neq \emptyset$.

P Decision problems for which there is a

poly-time algorithm

EXP Decision problems for which there is an

exponential-time algorithm

 \mathcal{NP} Decision problems for which there is a

poly-time certifier

- ▶ $\mathcal{P} \subseteq \mathcal{NP}$ If $X \in P$, then there is a polynomial time algorithm A that solves X. B ignores t and returns A(s). Why is B an efficient certifier?
- ▶ Is $\mathcal{P} = \mathcal{NP}$ or is $\mathcal{NP} \mathcal{P} \neq \emptyset$.

One of the major unsolved problems in computer science

P Decision problems for which there is a

poly-time algorithm

EXP Decision problems for which there is an

exponential-time algorithm

NP Decision problems for which there is a

poly-time certifier

- ▶ $\mathcal{P} \subseteq \mathcal{NP}$ If $X \in P$, then there is a polynomial time algorithm A that solves X. B ignores t and returns A(s). Why is B an efficient certifier?
- ▶ Is $\mathcal{P} = \mathcal{NP}$ or is $\mathcal{NP} \mathcal{P} \neq \emptyset$.

One of the major unsolved problems in computer science

 \triangleright $\mathcal{NP} \subseteq EXP$

P Decision problems for which there is a

poly-time algorithm

EXP Decision problems for which there is an

exponential-time algorithm

NP Decision problems for which there is a

poly-time certifier

- ▶ $\mathcal{P} \subseteq \mathcal{NP}$ If $X \in P$, then there is a polynomial time algorithm A that solves X. B ignores t and returns A(s). Why is B an efficient certifier?
- ▶ Is $\mathcal{P} = \mathcal{N}\mathcal{P}$ or is $\mathcal{N}\mathcal{P} \mathcal{P} \neq \emptyset$.

One of the major unsolved problems in computer science

- $ightharpoonup \mathcal{NP} \subseteq \mathit{EXP}$. Consider any problem X in \mathcal{NP} .
 - \blacktriangleright By definition, there exists a poly-time certifier C(s, t) for X.
 - ▶ To solve input s, run C(s, t) on all strings t with $|t| \le p(|s|)$.
 - ► Return yes, if C(s, t) returns yes for any of these.

A decision problem belongs to the class $\mathcal P$ if there is a solution algorithm with a running time that is polynomial in the input size

$\overline{\mathcal{P}}$ vs. \mathcal{NP}

A decision problem belongs to the class $\mathcal P$ if there is a solution algorithm with a running time that is polynomial in the input size

A decision problem belongs to the class \mathcal{NP} if we can check whether a given solution leads to 'yes' can be done in polynomial time with respect to the size of (x,y).

A decision problem belongs to the class $\mathcal P$ if there is a solution algorithm with a running time that is polynomial in the input size

Class \mathcal{P} – Class of decision problems, for which there exists a Deterministic Turing Machine that can solve any instance in polynomial time.

A decision problem belongs to the class \mathcal{NP} if we can check whether a given solution leads to 'yes' can be done in polynomial time with respect to the size of (x,y).

A decision problem belongs to the class $\mathcal P$ if there is a solution algorithm with a running time that is polynomial in the input size

Class \mathcal{P} – Class of decision problems, for which there exists a Deterministic Turing Machine that can solve any instance in polynomial time.

A decision problem belongs to the class \mathcal{NP} if we can check whether a given solution leads to 'yes' can be done in polynomial time with respect to the size of (x,y).

Class \mathcal{NP} – Class of decision problems, for which there exists a Non- Deterministic Turing Machine that can solve any yes instance in polynomial time. The machine guesses a yes solution and then verifies that it is a yes solution



Never tell to an expert in Computational Complexity – tractability – that you think that \mathcal{NP} stands for Non Polynomial

 \mathcal{NP} STANDS for Non-deterministic Polynomial

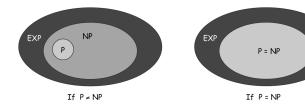
Does P = NP? [Cook 1971, Edmonds, Levin, Yablonski, Gödel]

Does P = NP? [Cook 1971, Edmonds, Levin, Yablonski, Gödel]

Is the decision problem as easy as the certification problem?

Does $P = \mathcal{NP}$? [Cook 1971, Edmonds, Levin, Yablonski, Gödel]

Is the decision problem as easy as the certification problem?



$\overline{\mathcal{P}}$ vs. $\overline{\mathcal{NP}}$

Does $P = \mathcal{NP}$? [Cook 1971, Edmonds, Levin, Yablonski, Gödel]

Is the decision problem as easy as the certification problem?



- If yes Efficient algorithms for 3-COLOR, TSP, FACTOR, SAT, · · · .
- If no No efficient algorithms possible for 3-COLOR, TSP, SAT, · · · .

Does $\mathcal{P} = \mathcal{NP}$? [Cook 1971, Edmonds, Levin, Yablonski, Gödel]

Is the decision problem as easy as the certification problem?



- If yes Efficient algorithms for 3-COLOR, TSP, FACTOR, SAT, · · · .
- If no No efficient algorithms possible for 3-COLOR, TSP, SAT,

Consensus opinion on P = NP? Probably no .

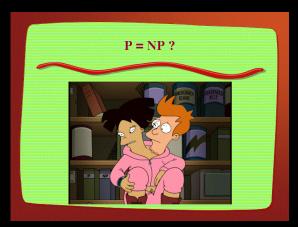
$\overline{\mathcal{P}}$ vs. $\mathcal{N}\mathcal{P}$

The Simpson's: P = NP?



Copyright © 1990, Matt Groening

Futurama: P = NP?



Copyright © 2000, Twentieth Century Fox







Teoria dos Grafos e Computabilidade

— \mathcal{NP} -Complete —

Silvio Jamil F. Guimarães

Graduate Program in Informatics – PPGINF Laboratory of Image and Multimedia Data Science – IMScience Pontifical Catholic University of Minas Gerais – PUC Minas

▶ What are the hardest problems in \mathcal{NP} ?

- ▶ What are the hardest problems in \mathcal{NP} ?
- ▶ A problem X is \mathcal{NP} -Complete if
 - 1. $X \in \mathcal{NP}$ and
 - 2. for *every* problem $Y \in \mathcal{NP}$, $Y \leq_P X$.

- ▶ What are the hardest problems in \mathcal{NP} ?
- ▶ A problem X is \mathcal{NP} -Complete if
 - 1. $X \in \mathcal{NP}$ and
 - 2. for *every* problem $Y \in \mathcal{NP}$, $Y \leq_P X$.
- ▶ Suppose X is \mathcal{NP} -Complete. Then X can be solved in polynomial-time iff $\mathcal{P} = \mathcal{NP}$.

- ▶ What are the hardest problems in \mathcal{NP} ?
- ▶ A problem X is \mathcal{NP} -Complete if
 - 1. $X \in \mathcal{NP}$ and
 - 2. for *every* problem $Y \in \mathcal{NP}$, $Y \leq_P X$.
- ▶ Suppose X is \mathcal{NP} -Complete. Then X can be solved in polynomial-time iff $\mathcal{P} = \mathcal{NP}$.

Corollary: If there is any problem in \mathcal{NP} that cannot be solved in polynomial time, then no \mathcal{NP} -Complete problem can be solved in polynomial time.

- ▶ What are the hardest problems in \mathcal{NP} ?
- ▶ A problem X is \mathcal{NP} -Complete if
 - 1. $X \in \mathcal{NP}$ and
 - 2. for *every* problem $Y \in \mathcal{NP}$, $Y \leq_P X$.
- ▶ Suppose X is \mathcal{NP} -Complete. Then X can be solved in polynomial-time iff $\mathcal{P} = \mathcal{NP}$.

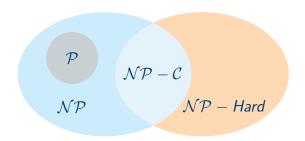
Corollary: If there is any problem in \mathcal{NP} that cannot be solved in polynomial time, then no \mathcal{NP} -Complete problem can be solved in polynomial time.

- ▶ Are there any \mathcal{NP} -Complete problems?
 - 1. Perhaps there are two problems X_1 and X_2 in \mathcal{NP} such that there is no problem $X \in \mathcal{NP}$ where $X_1 \leq_P X$ and $X_2 \leq_P X$.
 - 2. Perhaps there is a sequence of problems X_1, X_2, X_3, \ldots in \mathcal{NP} , each strictly harder than the previous one.

- ▶ A problem X is \mathcal{NP} -Hard if
 - 1. for every problem $Y \in \mathcal{NP}$, $Y \leq_P X$.

- ▶ A problem X is \mathcal{NP} -Hard if
 - 1. for *every* problem $Y \in \mathcal{NP}$, $Y \leq_P X$.
- ▶ A problem X is \mathcal{NP} -Complete if
 - 1. $X \in \mathcal{NP}$ and
 - 2. for *every* problem $Y \in \mathcal{NP}$, $Y \leq_P X$.

- ▶ A problem X is \mathcal{NP} -Hard if
 - 1. for *every* problem $Y \in \mathcal{NP}$, $Y \leq_P X$.
- ▶ A problem X is \mathcal{NP} -Complete if
 - 1. $X \in \mathcal{NP}$ and
 - 2. for *every* problem $Y \in \mathcal{NP}$, $Y \leq_P X$.



CIRCUIT SATISFIABILITY

► Cook-Levin Theorem CIRCUIT SATISFIABILITY is \mathcal{NP} -Complete.

CIRCUIT SATISFIABILITY

- ightharpoonup Cook-Levin Theorem CIRCUIT SATISFIABILITY is $\mathcal{NP} ext{-}\mathsf{Complete}.$
- ► A circuit K is a labelled, directed acyclic graph such that
 - 1. the **sources** in K are labelled with constants (0 or 1) or the name of a distinct variable (the **inputs** to the circuit).
 - 2. every other node is labelled with one Boolean operator \land , \lor , or \neg .
 - 3. a single node with no outgoing edges represents the **output** of K.

CIRCUIT SATISFIABILITY

INSTANCE A circuit *K*.

QUESTION Is there a truth assignment to the inputs that causes the output to have value 1?

▶ Take an arbitrary problem $X \in \mathcal{NP}$ and show that

▶ Take an arbitrary problem $X \in \mathcal{NP}$ and show that

- ► Claim we will not prove: any algorithm that takes a fixed number *n* of bits as input and produces a yes/no answer
 - 1. can be represented by an equivalent circuit and
 - 2. if the running time of the algorithm is polynomial in n, the size of the circuit is a polynomial in n.

▶ Take an arbitrary problem $X \in \mathcal{NP}$ and show that

- ► Claim we will not prove: any algorithm that takes a fixed number *n* of bits as input and produces a yes/no answer
 - 1. can be represented by an equivalent circuit and
 - 2. if the running time of the algorithm is polynomial in *n*, the size of the circuit is a polynomial in *n*.
- ▶ To show $X \leq_P \text{CIRCUIT SATISFIABILITY}$, given an input s of length n, we want to determine whether $s \in X$ using a black box that solves CIRCUIT SATISFIABILITY.

▶ Take an arbitrary problem $X \in \mathcal{NP}$ and show that

- ► Claim we will not prove: any algorithm that takes a fixed number *n* of bits as input and produces a yes/no answer
 - 1. can be represented by an equivalent circuit and
 - 2. if the running time of the algorithm is polynomial in *n*, the size of the circuit is a polynomial in *n*.
- ▶ To show $X \leq_P \text{CIRCUIT SATISFIABILITY}$, given an input s of length n, we want to determine whether $s \in X$ using a black box that solves CIRCUIT SATISFIABILITY.
- ▶ What do we know about *X*?

▶ Take an arbitrary problem $X \in \mathcal{NP}$ and show that

- ► Claim we will not prove: any algorithm that takes a fixed number *n* of bits as input and produces a yes/no answer
 - 1. can be represented by an equivalent circuit and
 - 2. if the running time of the algorithm is polynomial in n, the size of the circuit is a polynomial in n.
- ▶ To show $X \leq_P \text{CIRCUIT SATISFIABILITY}$, given an input s of length n, we want to determine whether $s \in X$ using a black box that solves CIRCUIT SATISFIABILITY.
- ▶ What do we know about X? It has an efficient certifier $B(\cdot, \cdot)$.

▶ Take an arbitrary problem $X \in \mathcal{NP}$ and show that

$X \leq_P \text{CIRCUIT SATISFIABILITY}$.

- ► Claim we will not prove: any algorithm that takes a fixed number *n* of bits as input and produces a yes/no answer
 - 1. can be represented by an equivalent circuit and
 - 2. if the running time of the algorithm is polynomial in *n*, the size of the circuit is a polynomial in *n*.
- ▶ To show $X \leq_P \text{CIRCUIT SATISFIABILITY}$, given an input s of length n, we want to determine whether $s \in X$ using a black box that solves CIRCUIT SATISFIABILITY.
- ▶ What do we know about X? It has an efficient certifier $B(\cdot, \cdot)$.
- ▶ To determine whether $s \in X$, we ask

Is there a string t of length p(n) such that B(s,t) = yes?'

▶ To determine whether $s \in X$, we ask

Is there a string t of length p(|s|) such that B(s,t) = yes?

- ► To determine whether $s \in X$, we ask

 Is there a string t of length p(|s|) such that B(s,t) = yes?
- ▶ View $B(\cdot, \cdot)$ as an algorithm on n + p(n) bits.
- ▶ Convert B to a polynomial-sized circuit K with n + p(n) sources.
 - 1. First *n* sources are hard-coded with the bits of s.
 - 2. The remaining p(n) sources labelled with variables representing the bits of t.

Proving CIRCUIT SATISFIABILITY is $\mathcal{NP} ext{-}\mathsf{Complete}$

- To determine whether $s \in X$, we ask

 Is there a string t of length p(|s|) such that B(s,t) = yes?
- ▶ View $B(\cdot, \cdot)$ as an algorithm on n + p(n) bits.
- ▶ Convert B to a polynomial-sized circuit K with n + p(n) sources.
 - 1. First *n* sources are hard-coded with the bits of *s*.
 - 2. The remaining p(n) sources labelled with variables representing the bits of t
- $ightharpoonup s \in X$ iff there is an assignment of the input bits of K that makes K satisfiable.

Example of Transformation to CIRCUIT SATISFIABILITY

▶ Does a graph *G* on *n* nodes have a two-node independent set?

Example of Transformation to CIRCUIT SATISFIABILITY

- ▶ Does a graph G on n nodes have a two-node independent set?
- s encodes the graph G with $\binom{n}{2}$ bits.
- ▶ *t* encodes the independent set with *n* bits.
- Certifier needs to check if
 - 1. at least two bits in t are set to 1 and
 - 2. no two bits in t are set to 1 if they form the ends of an edge (the corresponding bit in s is set to 1).

Proving Other Problems \mathcal{NP} -Complete

If Y is \mathcal{NP} -Complete and $X \in \mathcal{NP}$ such that $Y \leq_P X$, then X is \mathcal{NP} -Complete.

Proving Other Problems NP-Complete

If Y is \mathcal{NP} -Complete and $X \in \mathcal{NP}$ such that $Y \leq_P X$, then X is \mathcal{NP} -Complete.

▶ Given a new problem X, a general strategy for proving that X is \mathcal{NP} -Complete can be defined as follows

Proving Other Problems \mathcal{NP} -Complete

If Y is \mathcal{NP} -Complete and $X \in \mathcal{NP}$ such that $Y \leq_P X$, then X is \mathcal{NP} -Complete.

- ▶ Given a new problem X, a general strategy for proving that X is \mathcal{NP} -Complete can be defined as follows
 - 1. Prove that $X \in \mathcal{NP}$.
 - 2. Select a problem Y known to be \mathcal{NP} -Complete
 - 3. Prove that $Y \leq_P X$.

Proving Other Problems \mathcal{NP} -Complete

If Y is \mathcal{NP} -Complete and $X \in \mathcal{NP}$ such that $Y \leq_P X$, then X is \mathcal{NP} -Complete.

- ▶ Given a new problem X, a general strategy for proving that X is \mathcal{NP} -Complete can be defined as follows
 - 1. Prove that $X \in \mathcal{NP}$.
 - 2. Select a problem Y known to be $\mathcal{NP} ext{-}\mathsf{Complete}$
 - 3. Prove that $Y \leq_P X$
- ▶ If we use Karp reductions , we can refine the strategy:
 - 1. Prove that $X \in \mathcal{NP}$.
 - 2. Select a problem Y known to be \mathcal{NP} -Complete.
 - 3. Consider an arbitrary instance s_Y of problem Y. Show how to construct, in polynomial time, an instance s_X of problem X such that
 - (a) If $s_Y \in Y$, then $s_X \in X$ and
 - (b) If $s_X \in X$, then $s_Y \in Y$.

\mathcal{NP} -Completeness

