

INTELIGÊNCIA COMPUTACIONAL - 2021.2

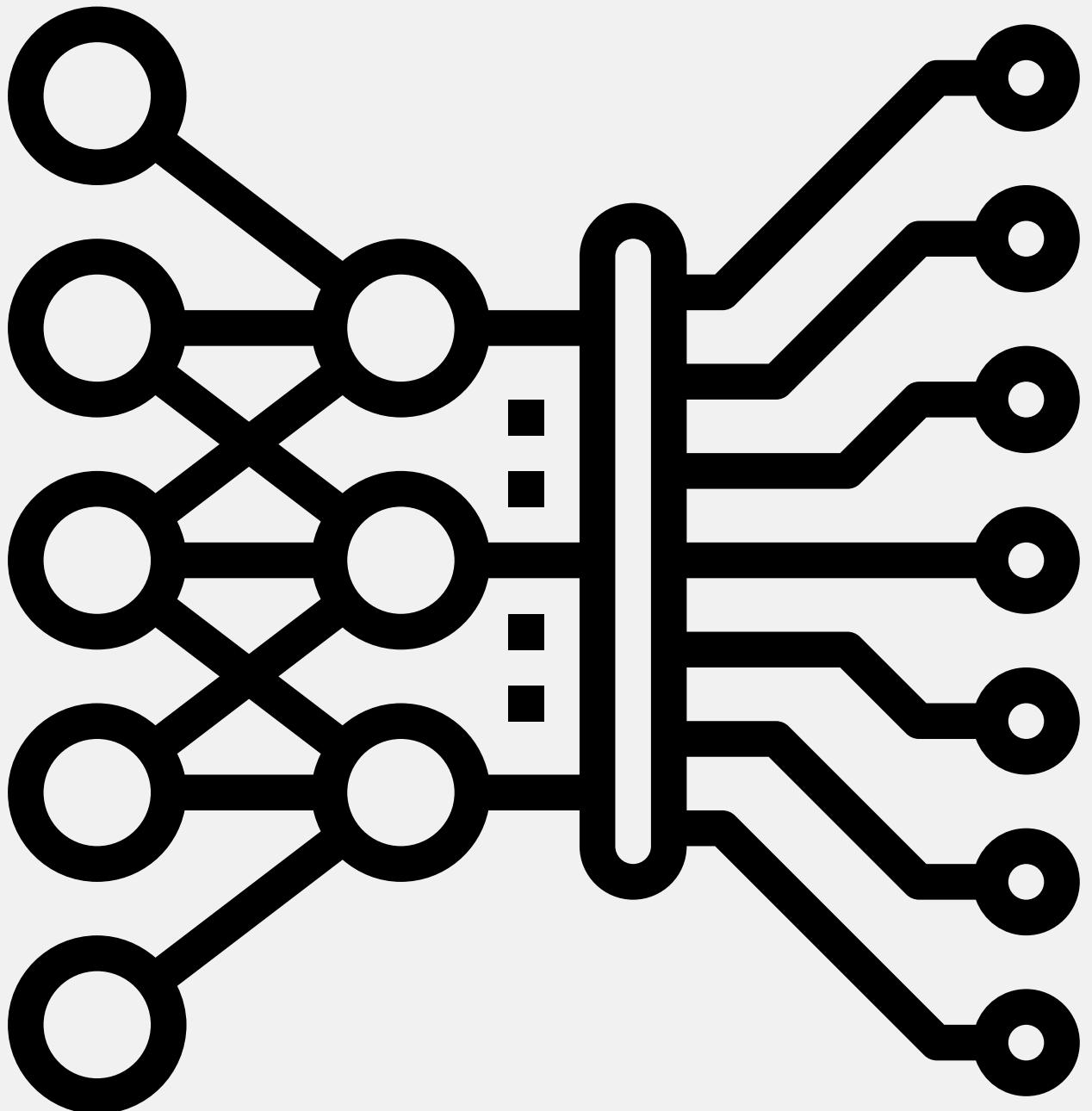
# Exercício 7: Redes Neurais

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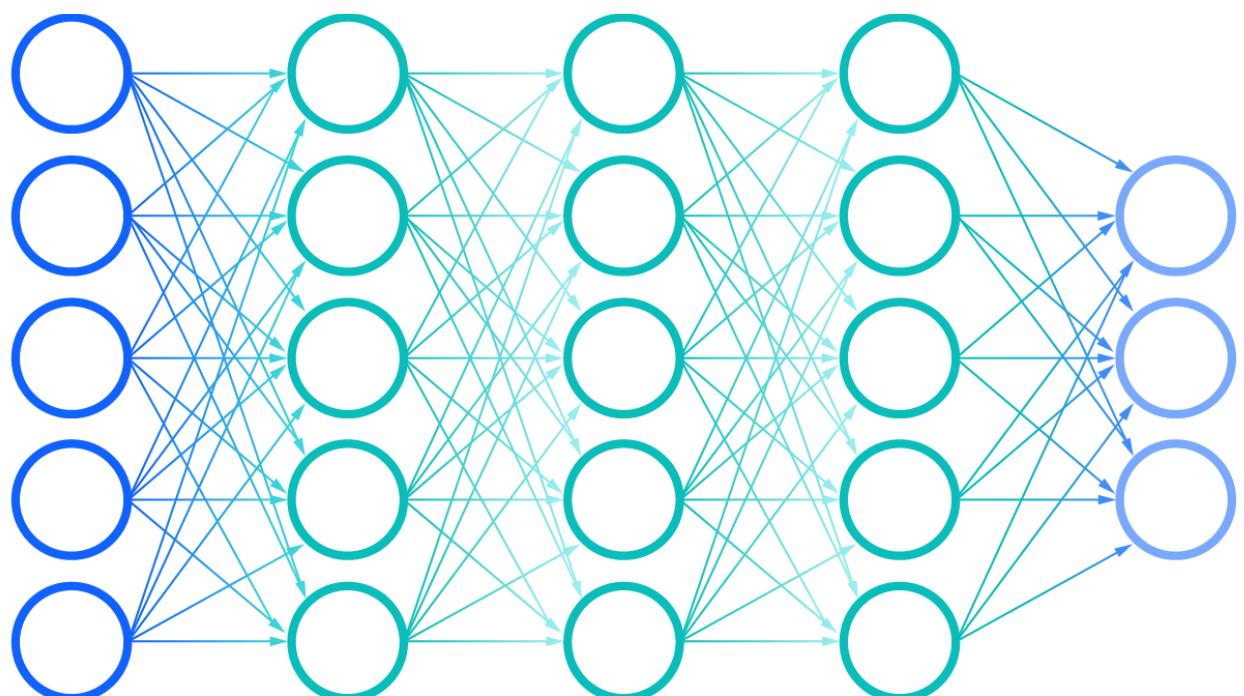
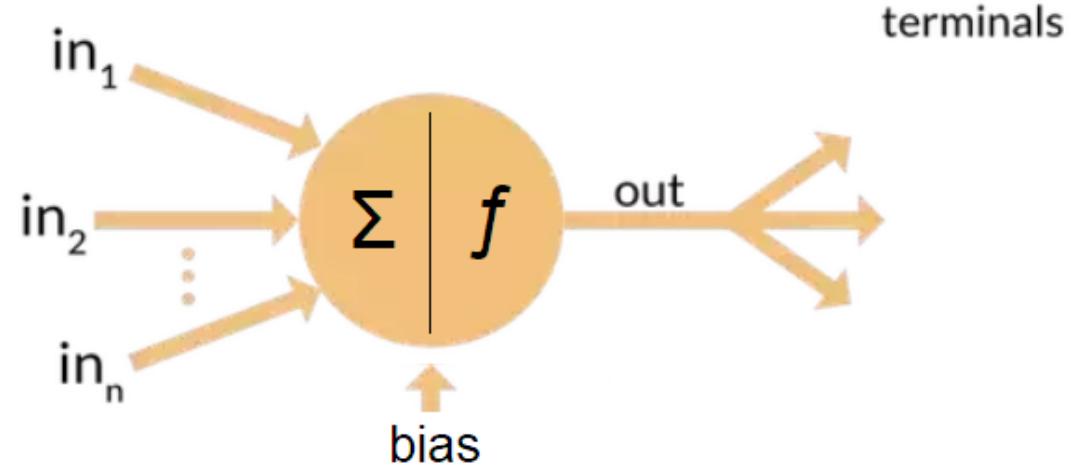
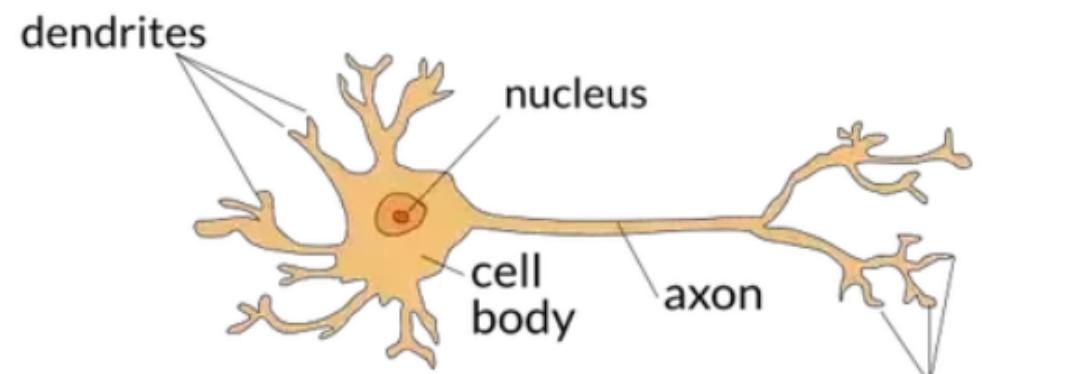
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# Definição



Inspirada nos neurônios biológicos

Formadas por 4 componentes básicos

Demandam grande desempenho computacional

Backbone do Deep Learning

Pode ser usado em diferentes problemas

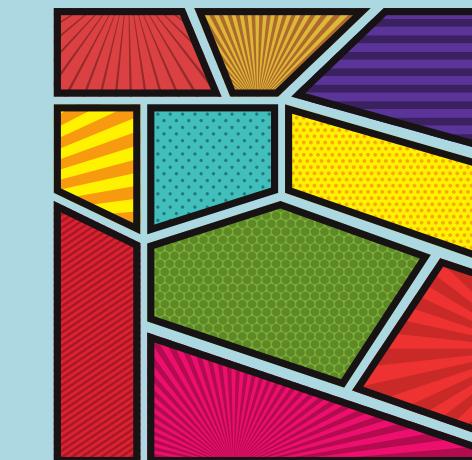
# Algumas aplicações



**Descobrimento de novas drogas**



**Previsões em séries temporais**



**Criação artística**

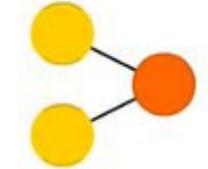
**Outros: visão computacional, NLP, reconhecimento de voz, etc...**

*A mostly complete chart of*  
**Neural Networks**

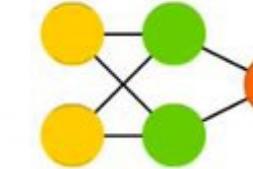
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- (○) Backfed Input Cell
- (●) Input Cell
- (△) Noisy Input Cell
- (●) Hidden Cell
- (○) Probabilistic Hidden Cell
- (△) Spiking Hidden Cell
- (●) Output Cell
- (●) Match Input Output Cell
- (●) Recurrent Cell
- (○) Memory Cell
- (△) Different Memory Cell
- (●) Kernel
- (○) Convolution or Pool

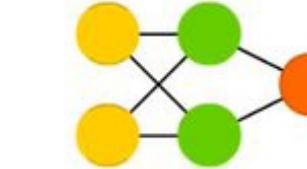
Perceptron (P)



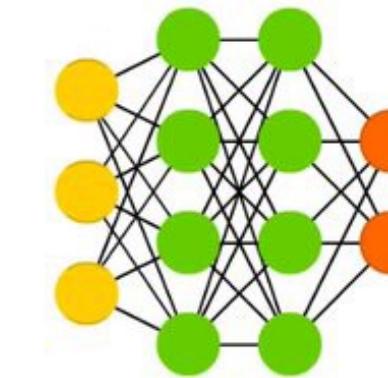
Feed Forward (FF)



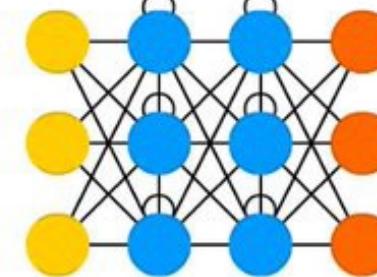
Radial Basis Network (RBF)



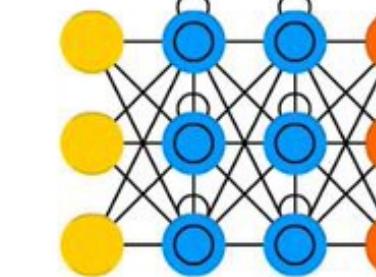
Deep Feed Forward (DFF)



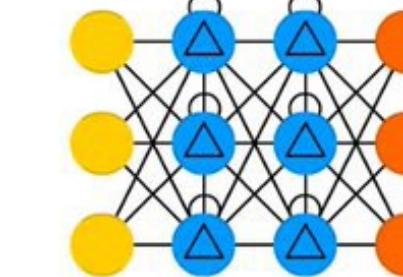
Recurrent Neural Network (RNN)



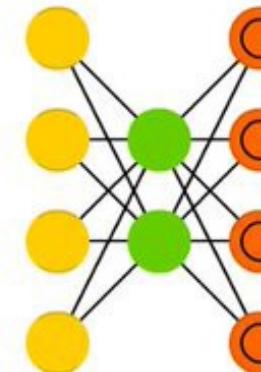
Long / Short Term Memory (LSTM)



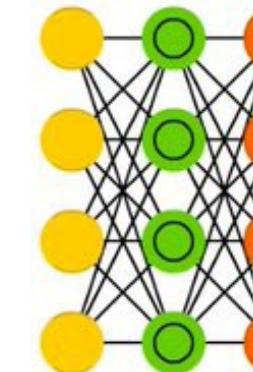
Gated Recurrent Unit (GRU)



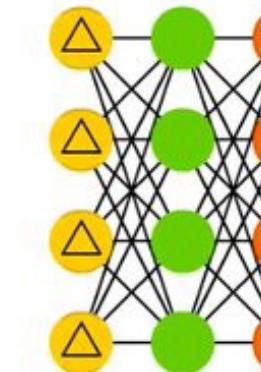
Auto Encoder (AE)



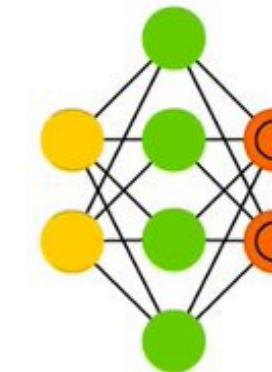
Variational AE (VAE)



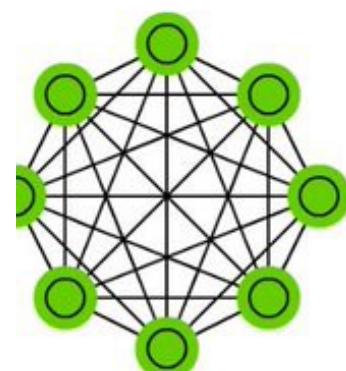
Denoising AE (DAE)



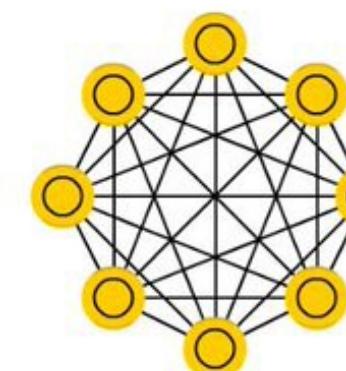
Sparse AE (SAE)



Markov Chain (MC)



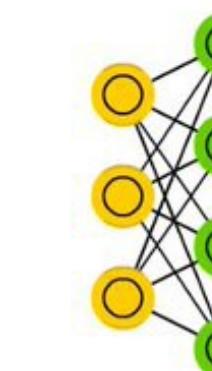
Hopfield Network (HN)



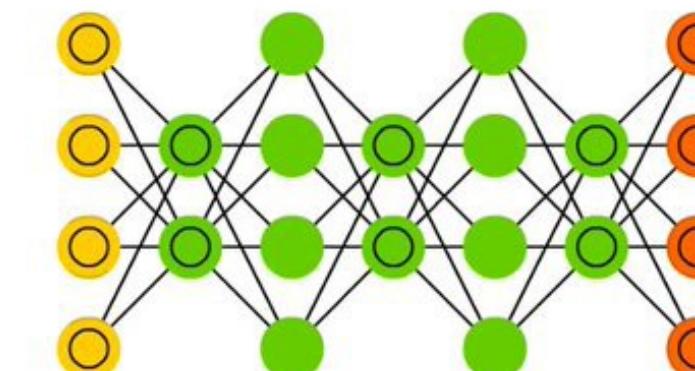
Boltzmann Machine (BM)



Restricted BM (RBM)

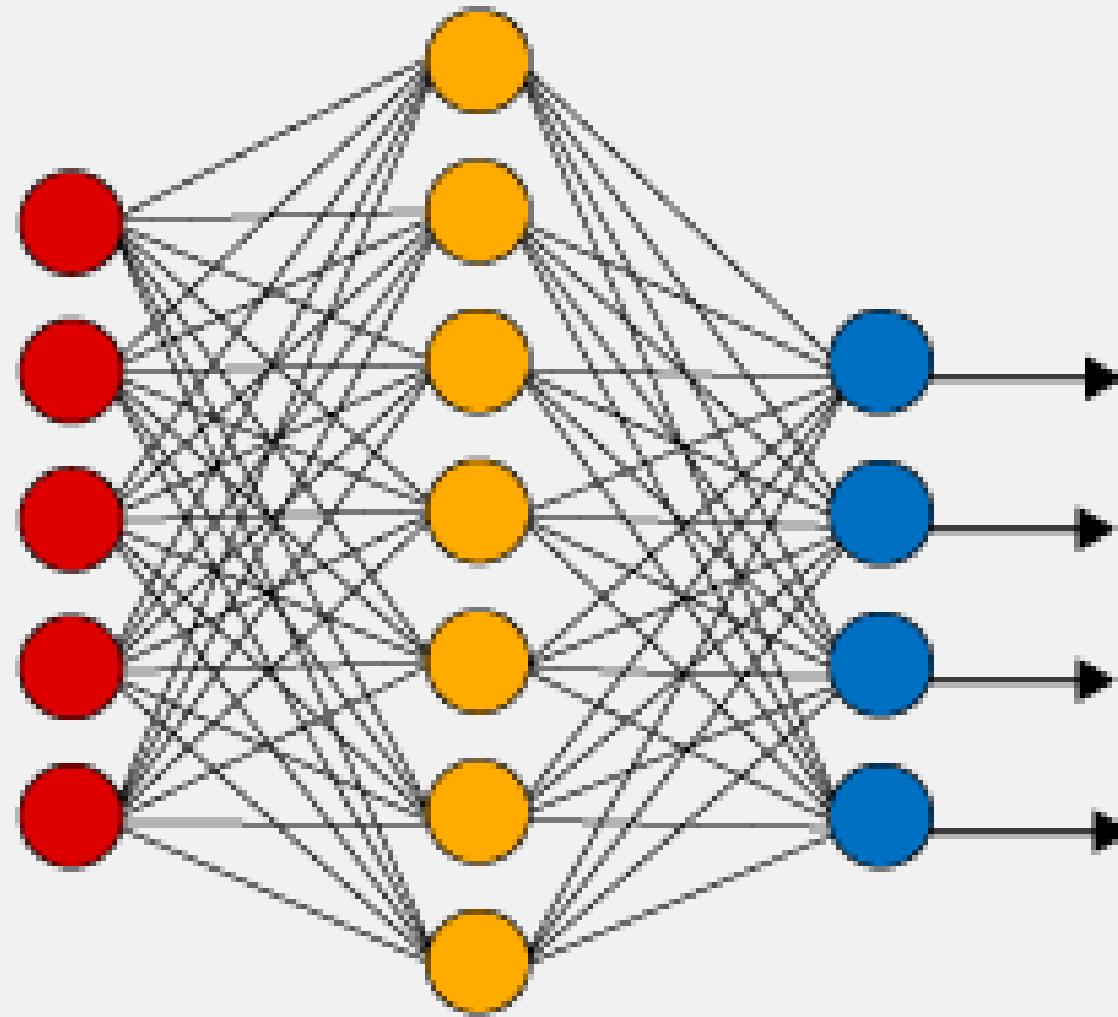


Deep Belief Network (DBN)



# Simple NN vs Deep Learning NN

Simple Neural Network

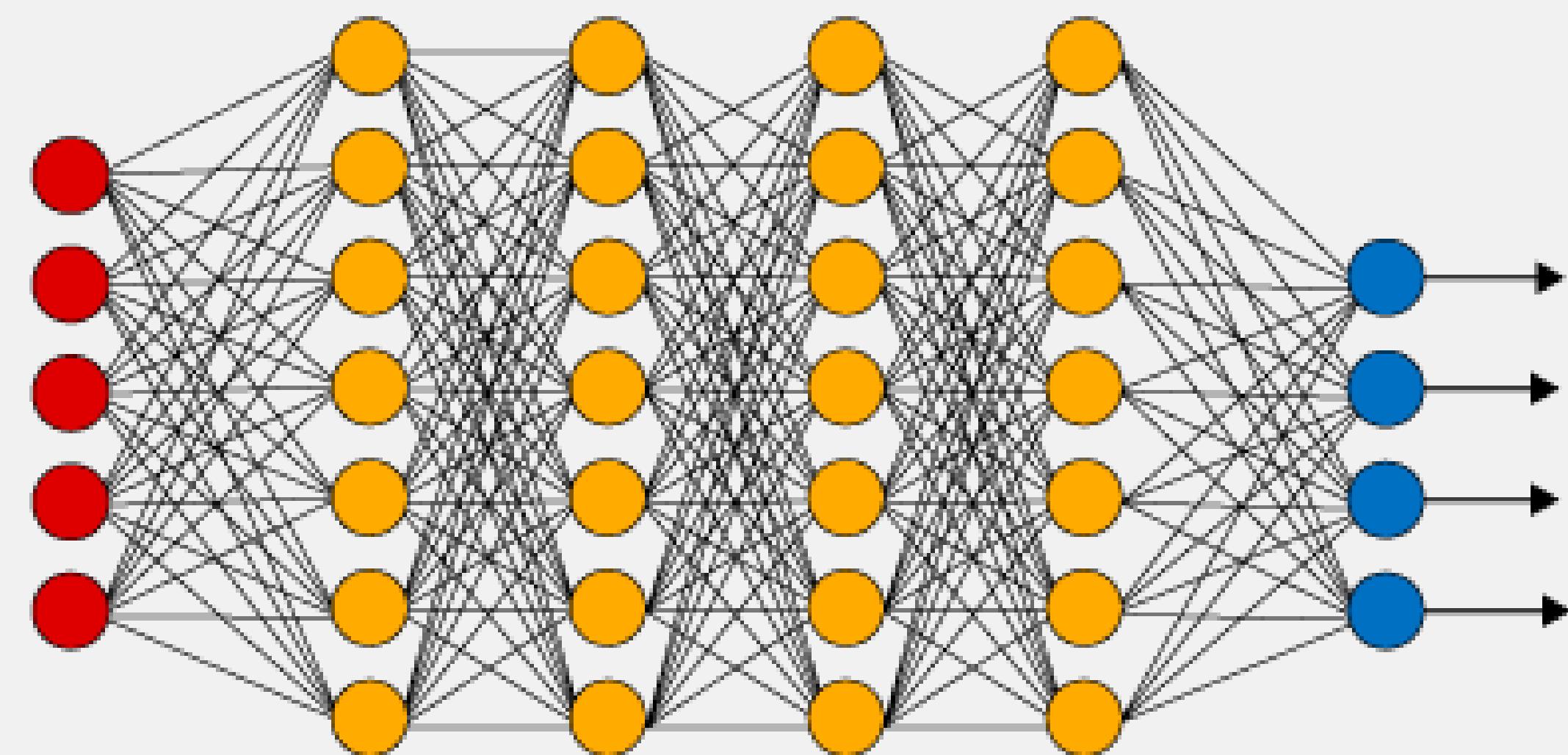


● Input Layer

● Hidden Layer

● Output Layer

Deep Learning Neural Network

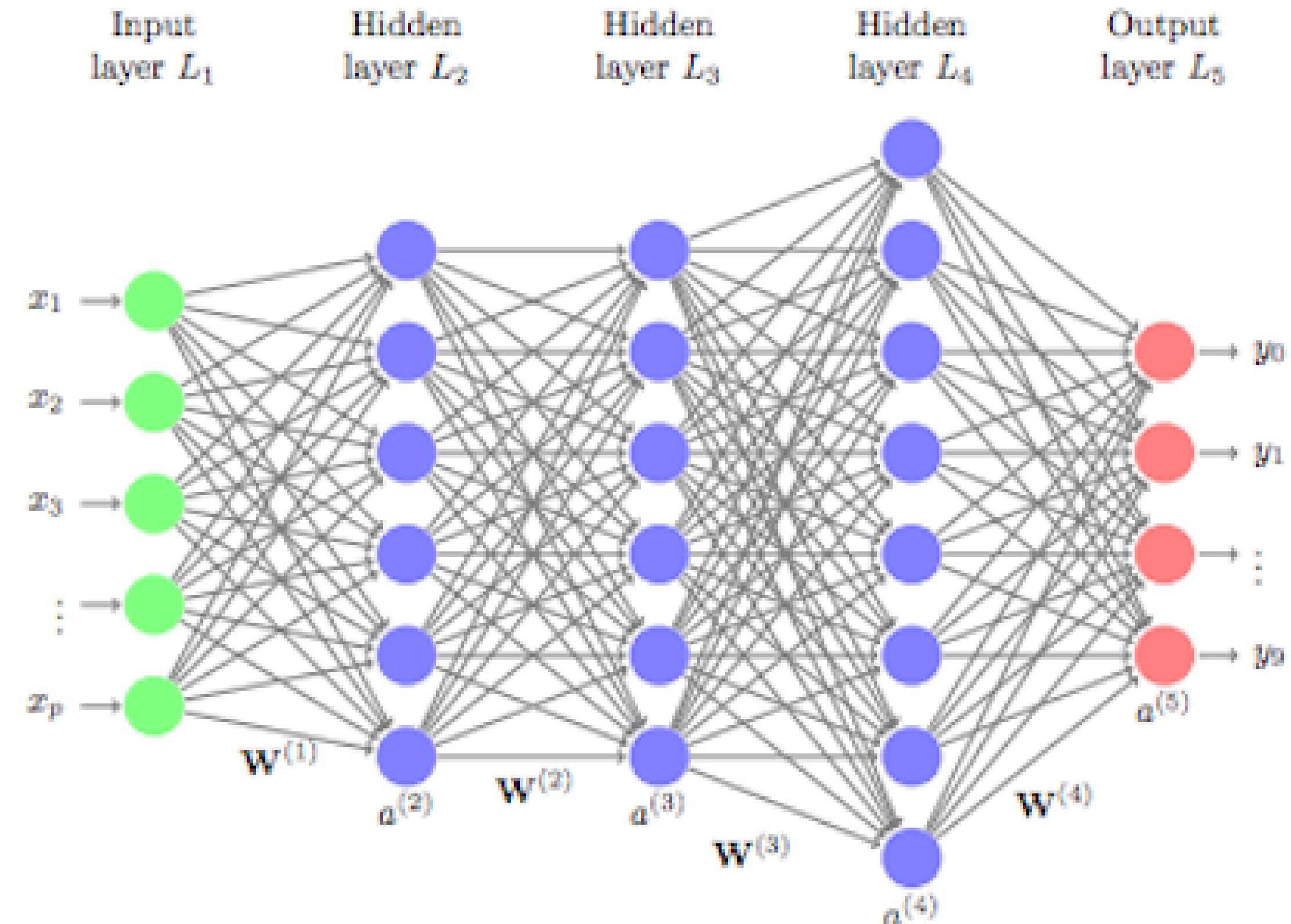


# Feedforward Neural Net (FFNN)

Útil para problemas de classificação e regressão

Pode substituir a maioria dos algoritmos tradicionais de ML

Treinamento rápido, e portanto é o modelo mais comum de ser encontrado



# Treinamento Feedforward

1) Inicialização dos pesos entre as camadas



2) Colocar cada variável de entrada nos neurônios de entrada



3) Forward-propagation



4) Comparar a previsão com o valor real e medir o erro



7) Finaliza uma época



6) Atualização do pesos



5) Backpropagation

# Inicialização de pesos

Inicialização normal

$$w \approx N(0, \sigma)$$

# Inicialização de pesos

Inicialização Xavier Glorot  
(uniforme)

$$w \approx \mathcal{U} \left[ -\sqrt{\frac{6}{\text{in+out}}}, \sqrt{\frac{6}{\text{in+out}}} \right]$$

# Inicialização de pesos

Inicialização He  
(uniforme)

$$w \approx \mathcal{U}\left[-\sqrt{\frac{6}{\text{in}}}, \sqrt{\frac{6}{\text{in}}}\right]$$

# Treinamento Feedforward

1) Inicialização dos pesos entre as camadas



2) Colocar cada variável de entrada nos neurônios de entrada



3) Forward-propagation



4) Comparar a previsão com o valor real e medir o erro



7) Finaliza uma época

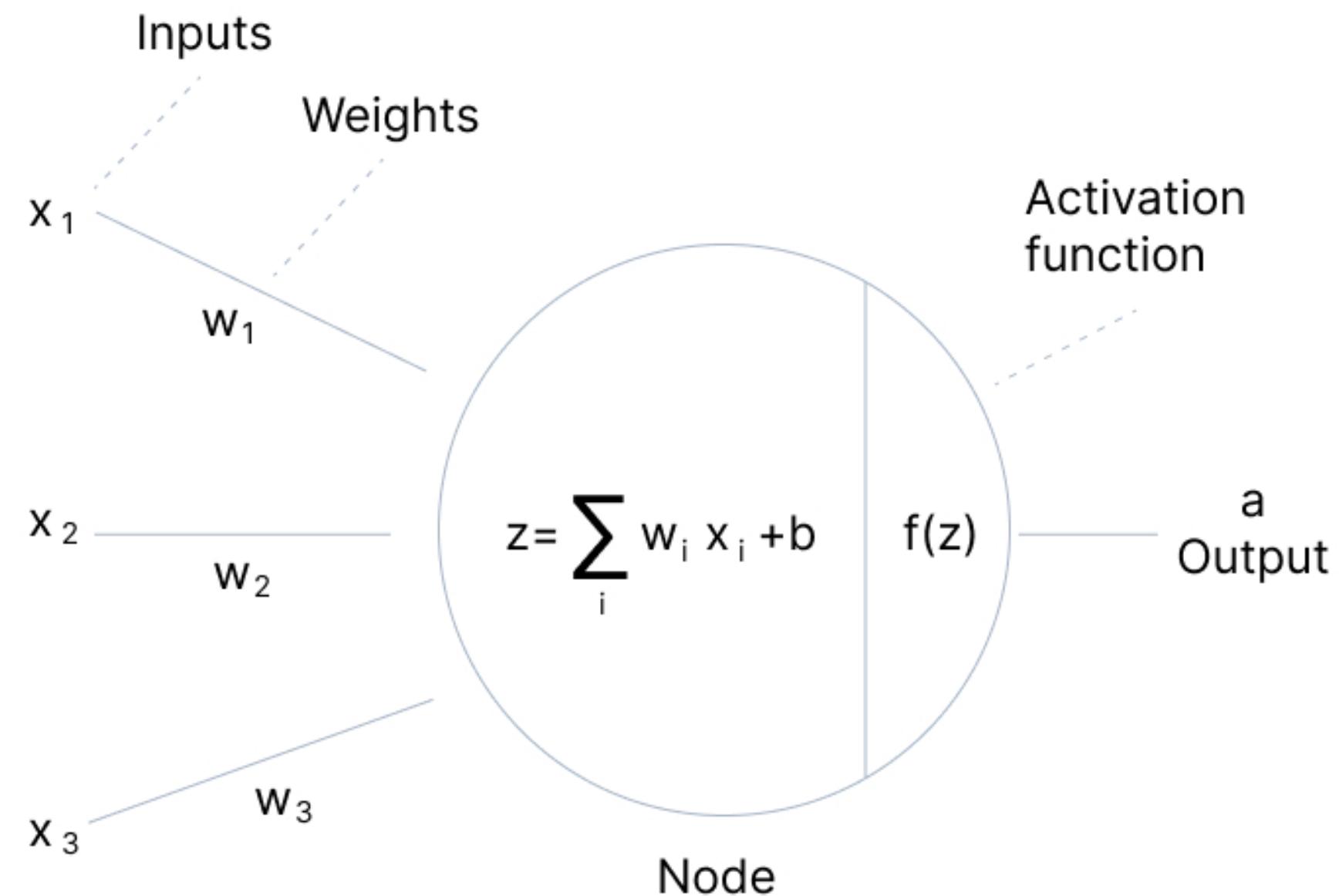


6) Atualização do pesos



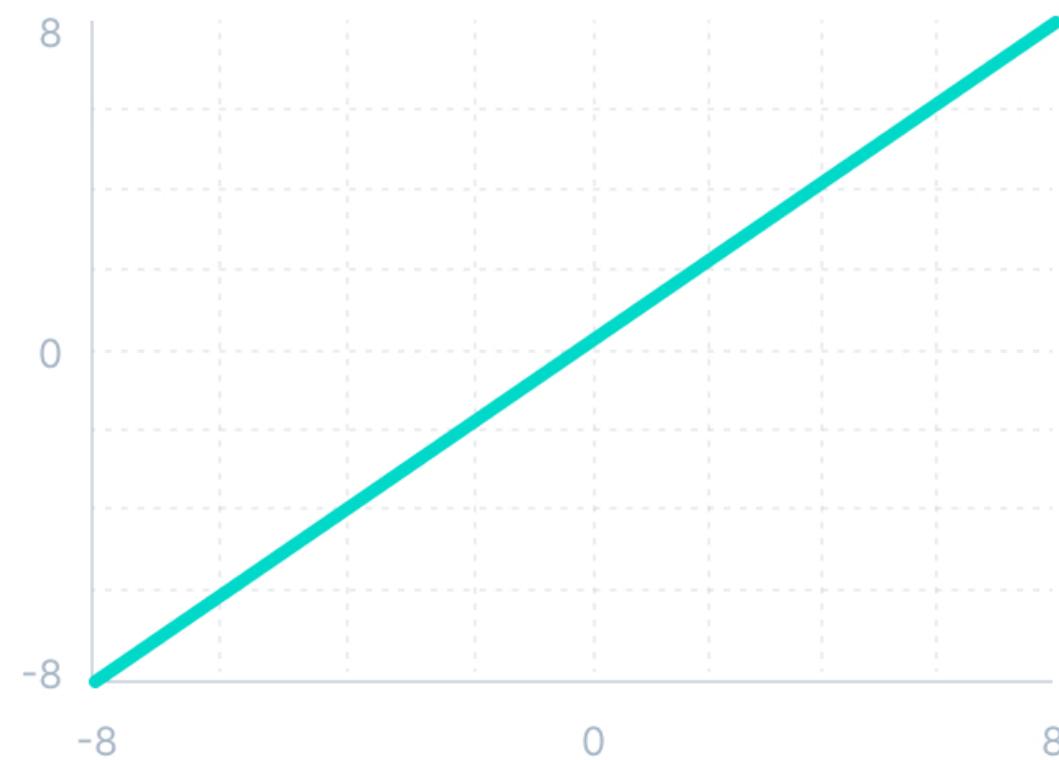
5) Backpropagation

# Função de ativação



# Funções de ativação lineares

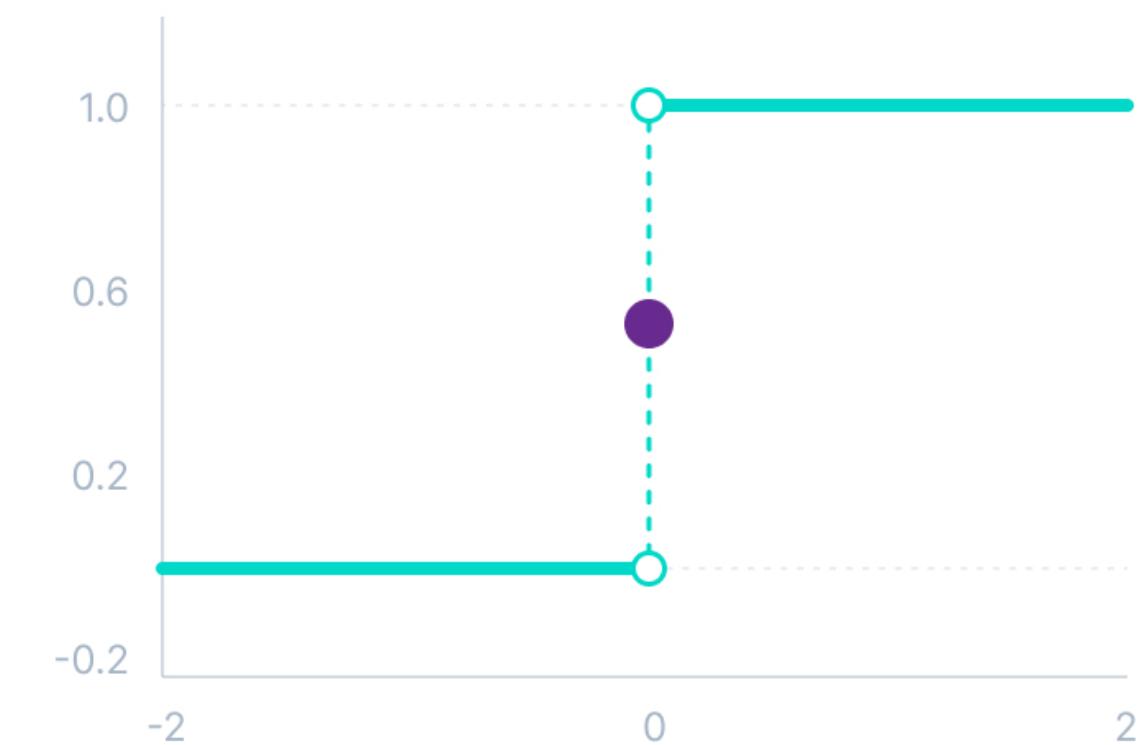
**Linear Activation Function**



*Linear*

$$f(x) = x$$

**Binary Step Function**

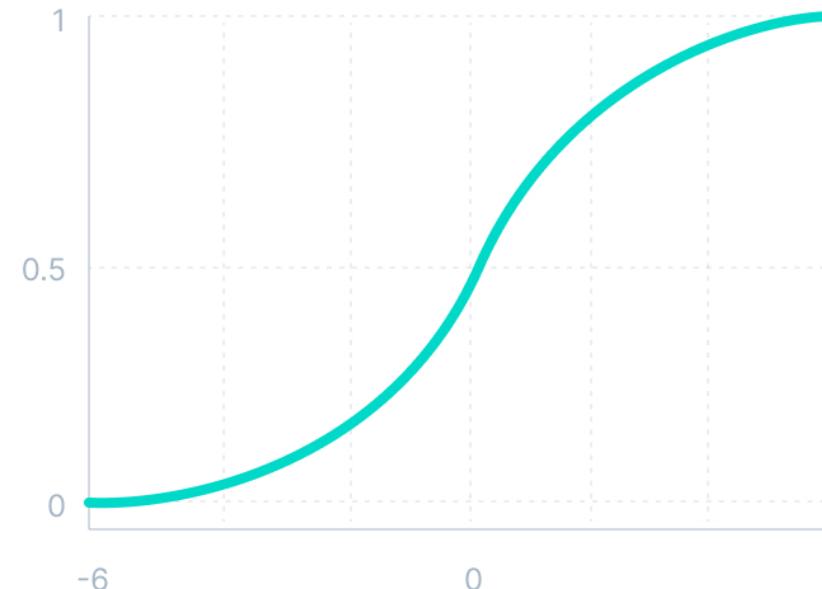


*Binary step*

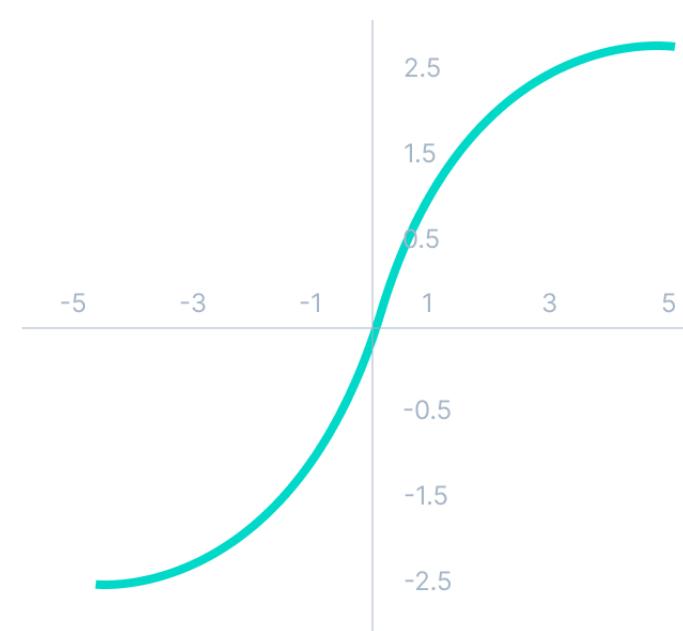
$$f(x) = \begin{cases} 0 & \text{for } x < 0 \\ 1 & \text{for } x \geq 0 \end{cases}$$

# Funções de ativação não-lineares

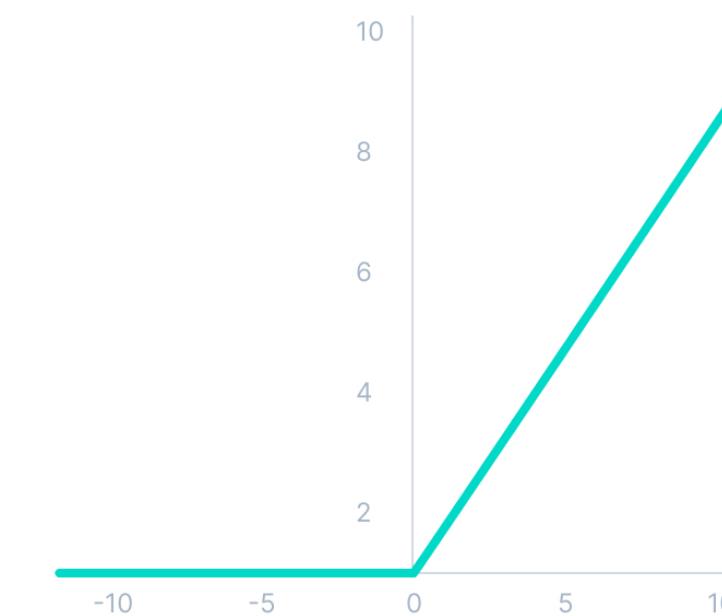
Sigmoid / Logistic



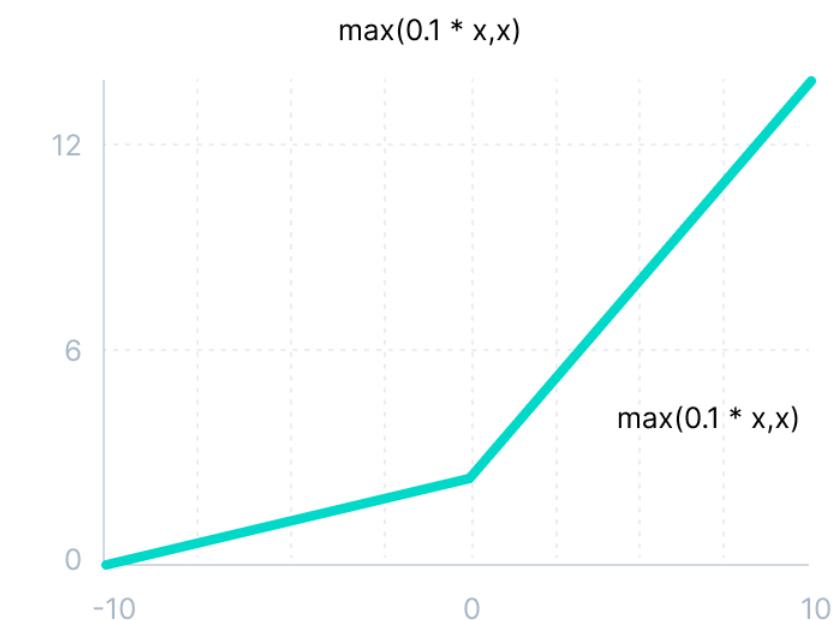
Tanh



ReLU



Leaky ReLU



*Sigmoid / Logistic*

$$f(x) = \frac{1}{1 + e^{-x}}$$

*Tanh*

$$f(x) = \frac{(e^x - e^{-x})}{(e^x + e^{-x})}$$

*ReLU*

$$f(x) = \max(0, x)$$

*Leaky ReLU*

$$f(x) = \max(0.1x, x)$$

Outras: Parametric ReLU, ELU, Softmax, Swish, GELU, SELU...

# Treinamento Feedforward

1) Inicialização dos pesos entre as camadas



2) Colocar cada variável de entrada nos neurônios de entrada



3) Forward-propagation



4) Comparar a previsão com o valor real e medir o erro



7) Finaliza uma época

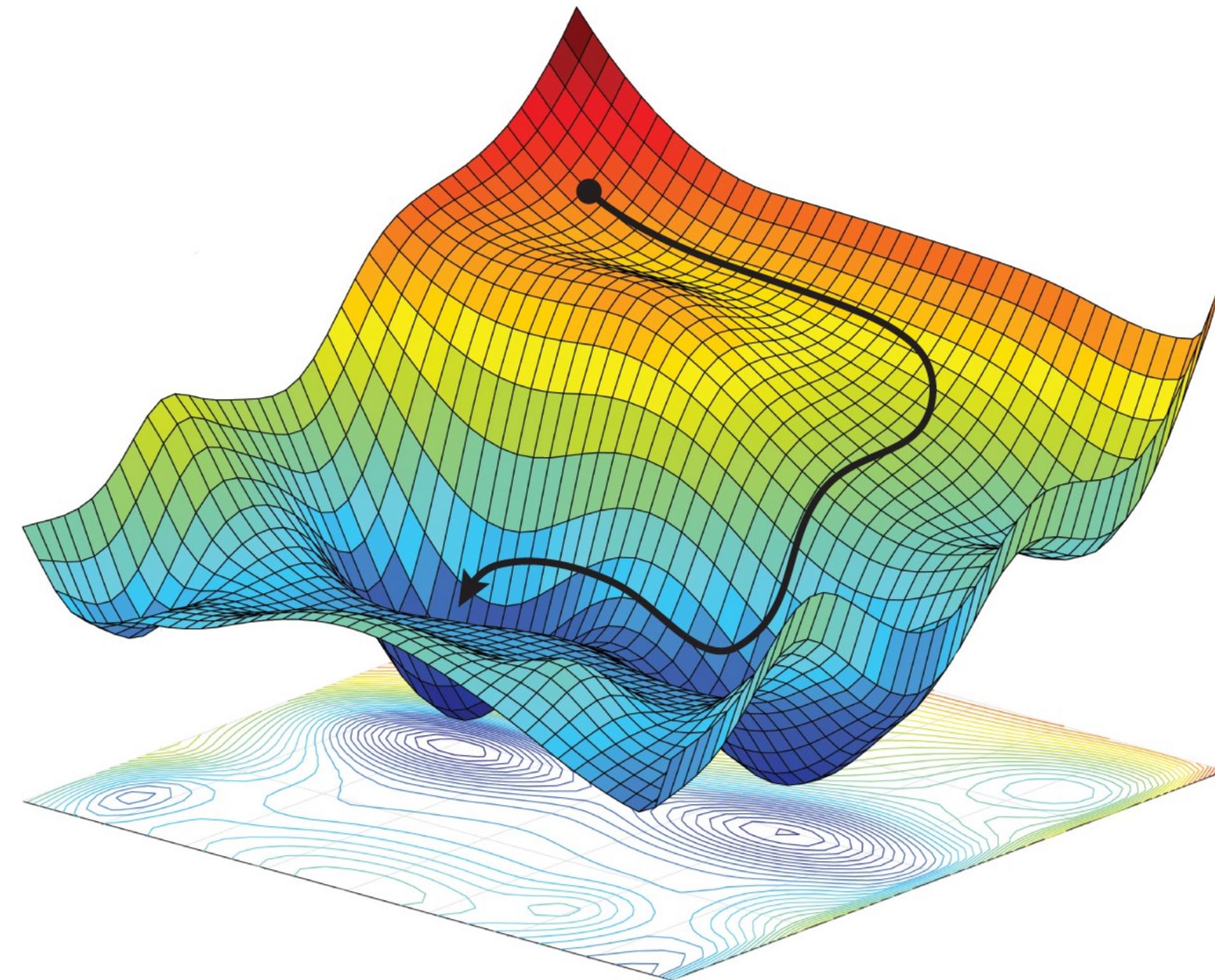


6) Atualização do pesos

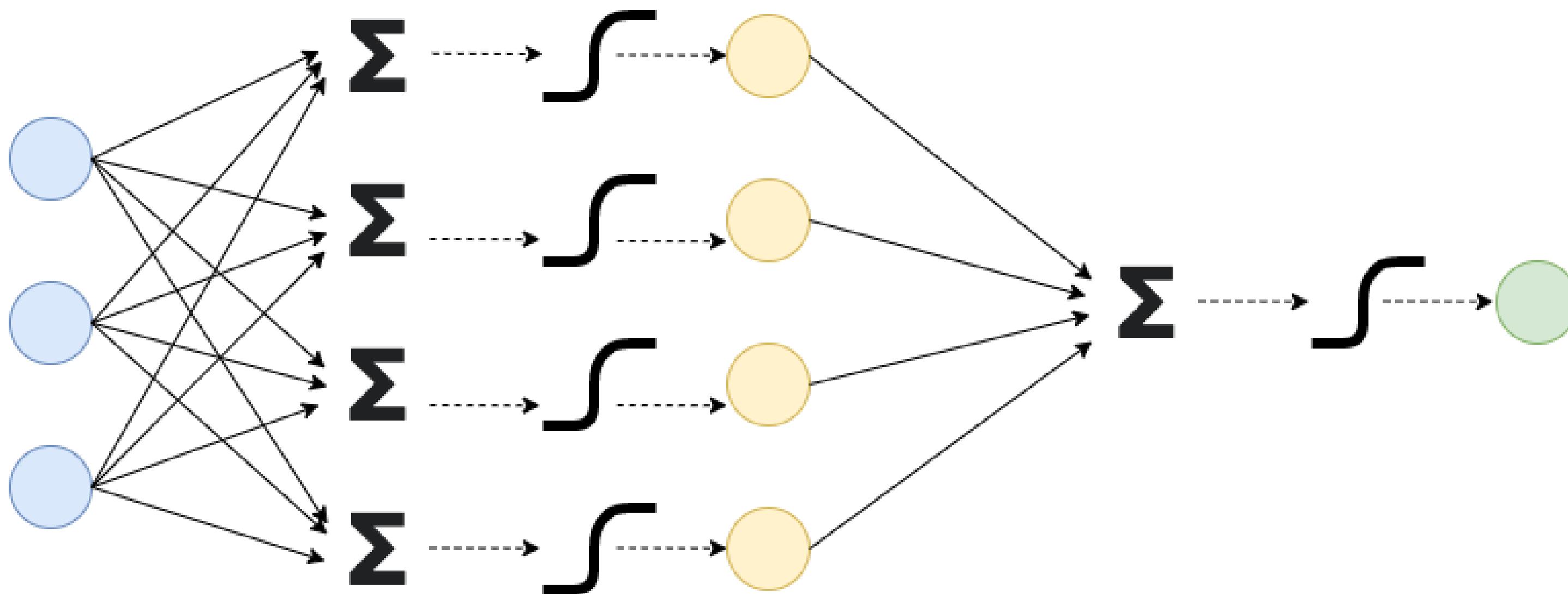


5) Backpropagation

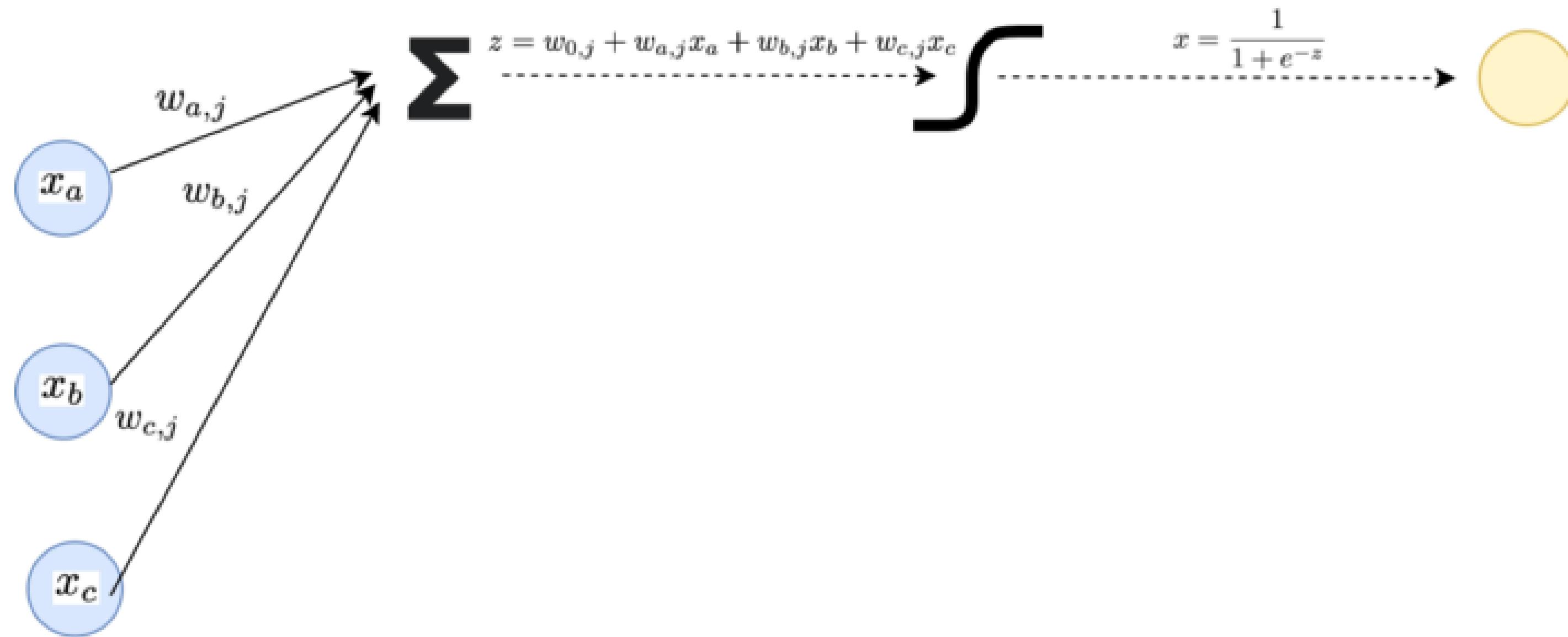
# Backpropagation



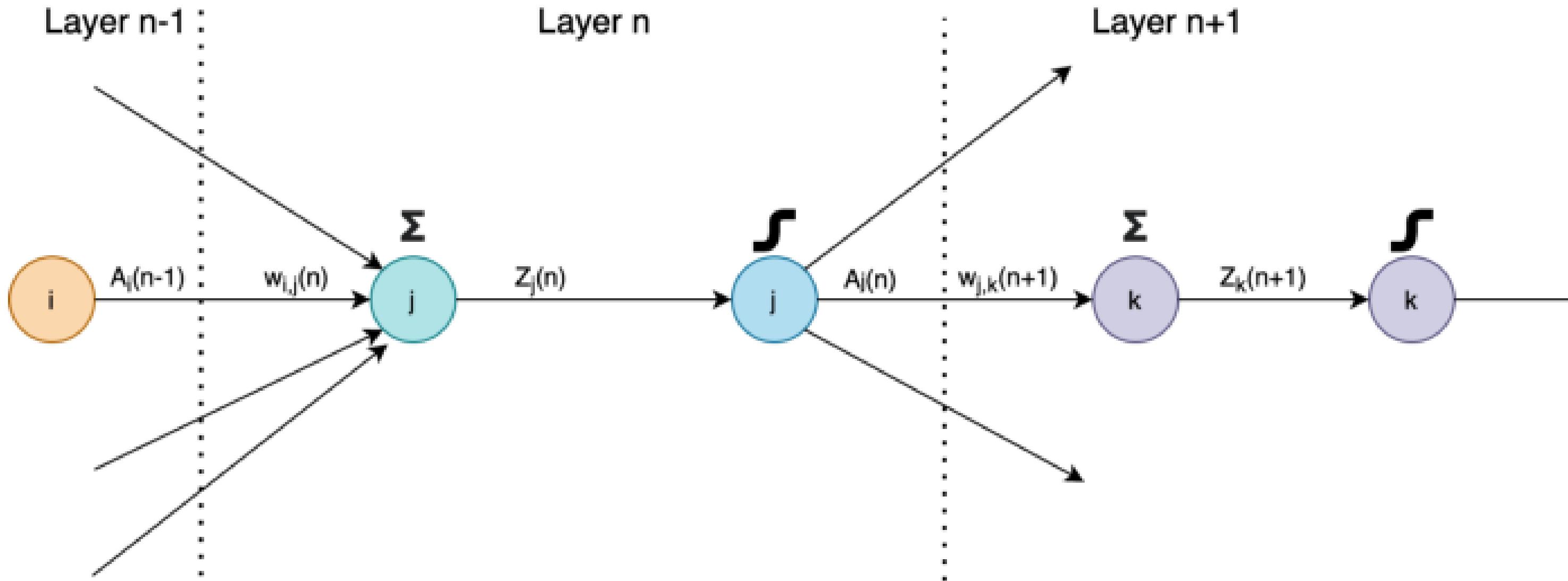
# Backpropagation



# Backpropagation



# Backpropagation



$$w_{i,j} \leftarrow w_{i,j} - a \frac{\partial E(D, \mathbf{w})}{\partial w_{i,j}}$$

# Treinamento Feedforward

1) Inicialização dos pesos entre as camadas



2) Colocar cada variável de entrada nos neurônios de entrada



3) Forward-propagation



4) Comparar a previsão com o valor real e medir o erro



7) Finaliza uma época

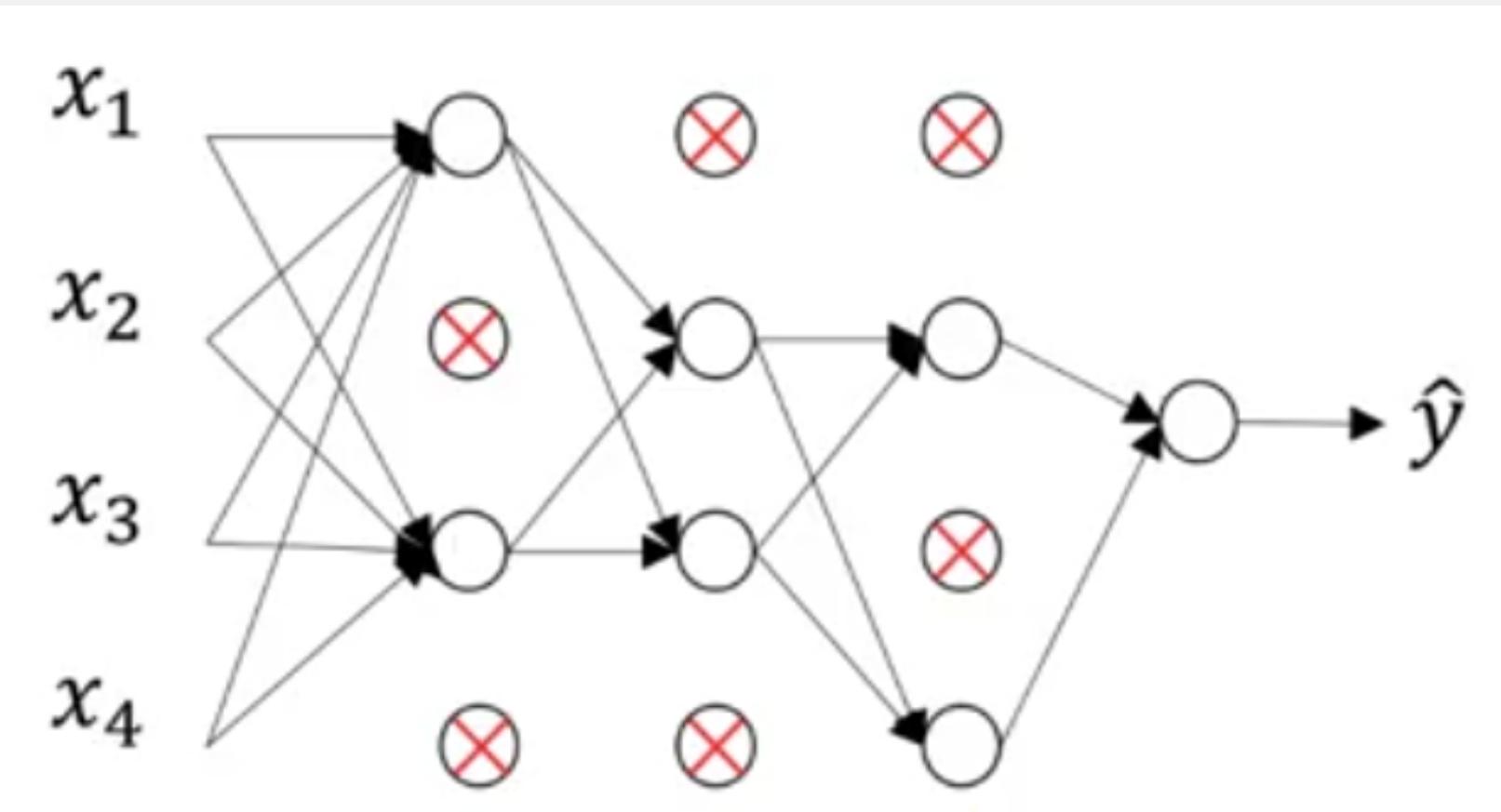
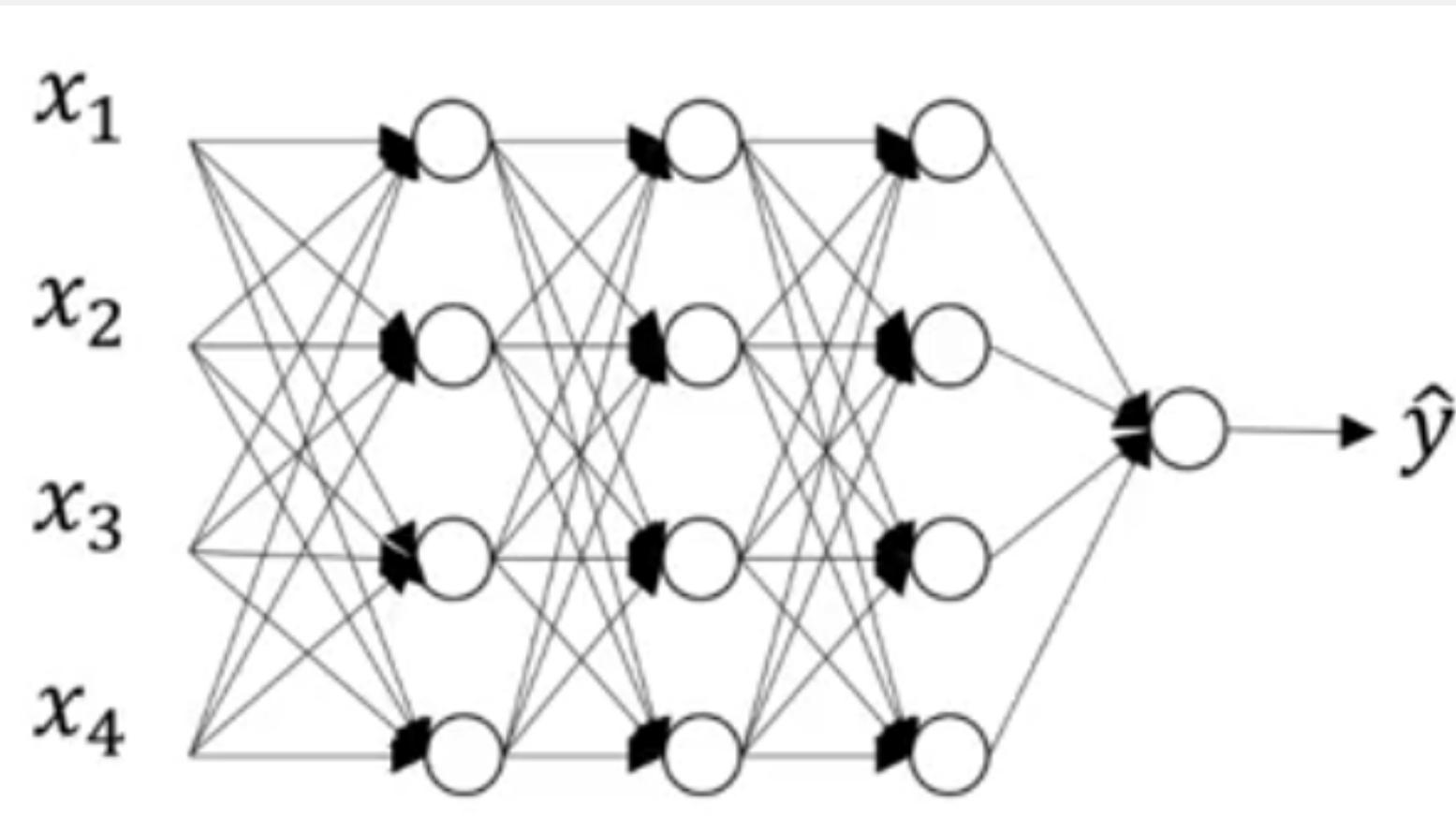


6) Atualização do pesos

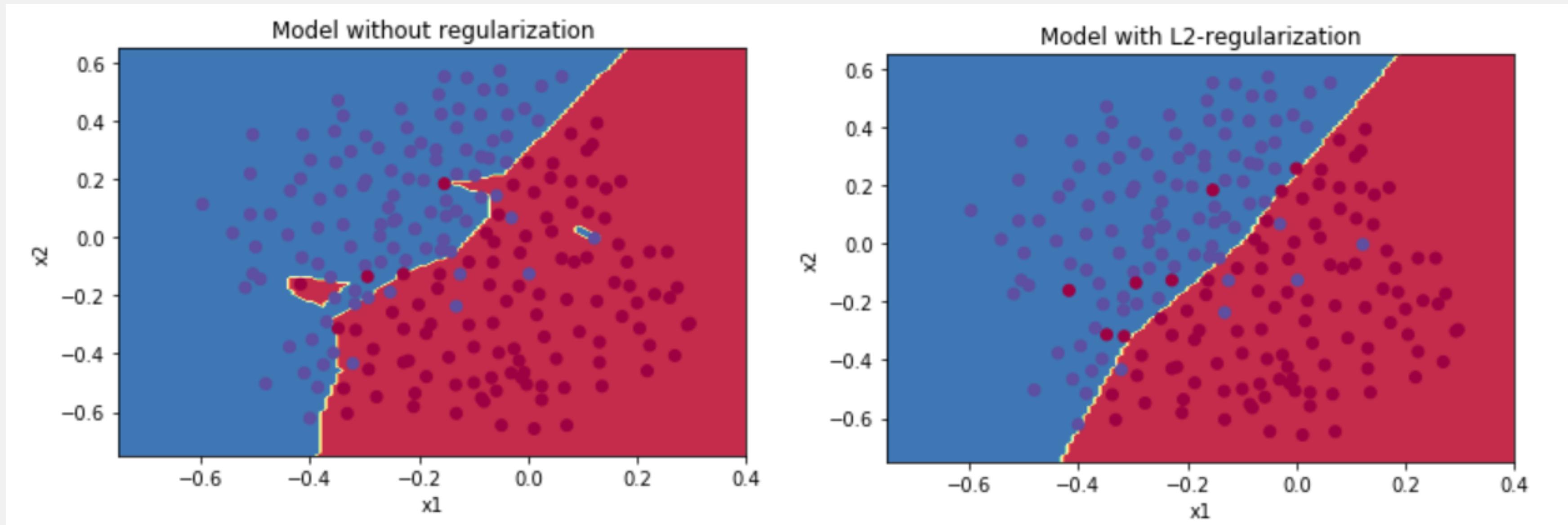


5) Backpropagation

# Regularizadores



# Regularizadores



# Diversos algoritmos

Além do feedforward

Recurrent Neural Net

Autoencoder

Convolutional Neural Net

Generative Adversarial Network

Entre outros....

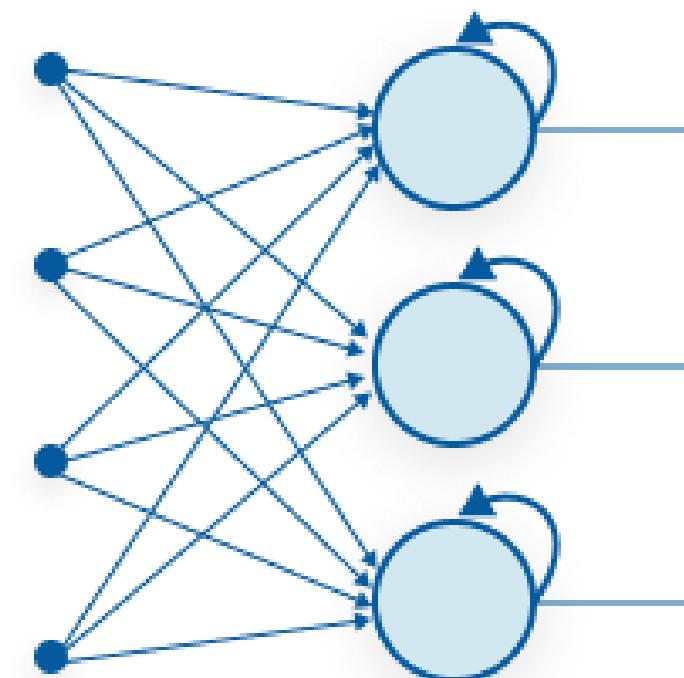
# Recurrent Neural Net (RNN)

Sequências

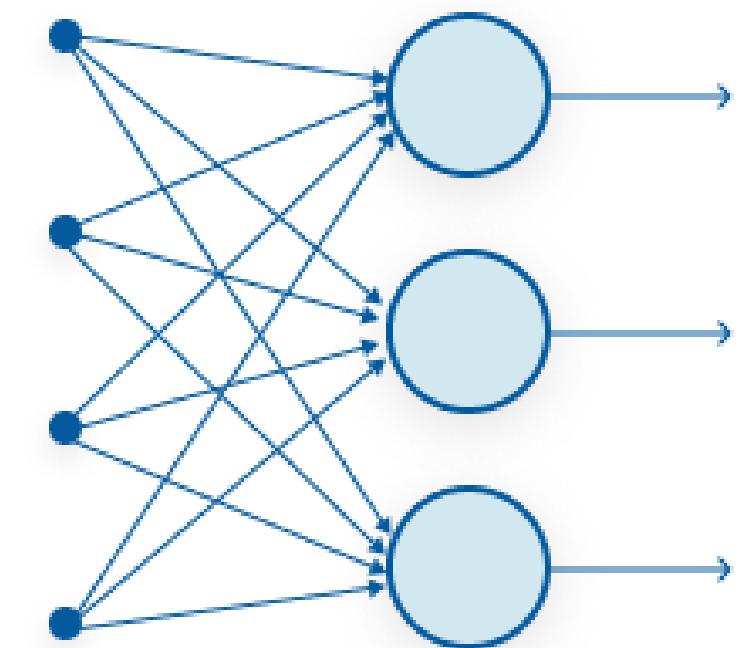
Série temporal

Treinamento mais lento e pesado

Recurrent Neural Network structure

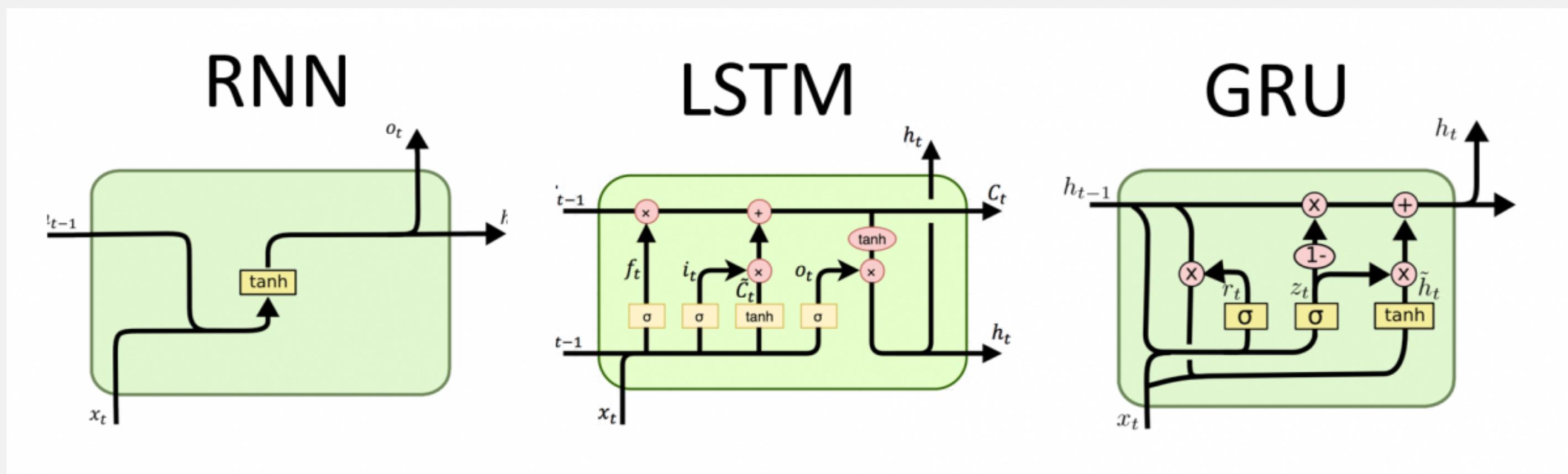
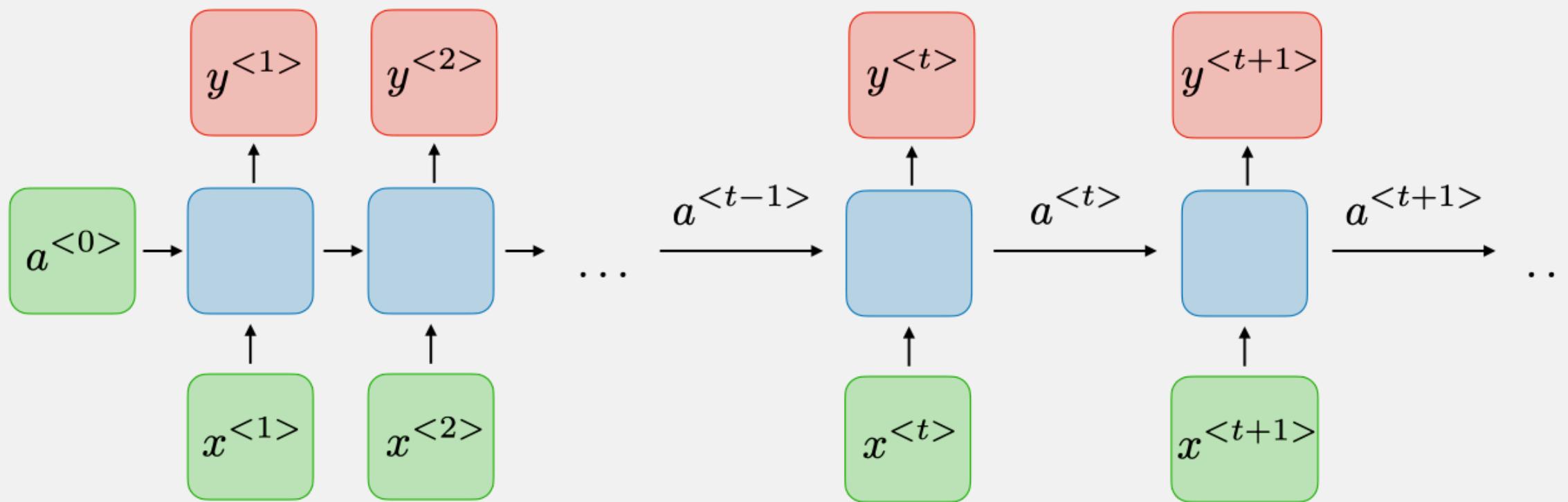


Recurrent Neural Network

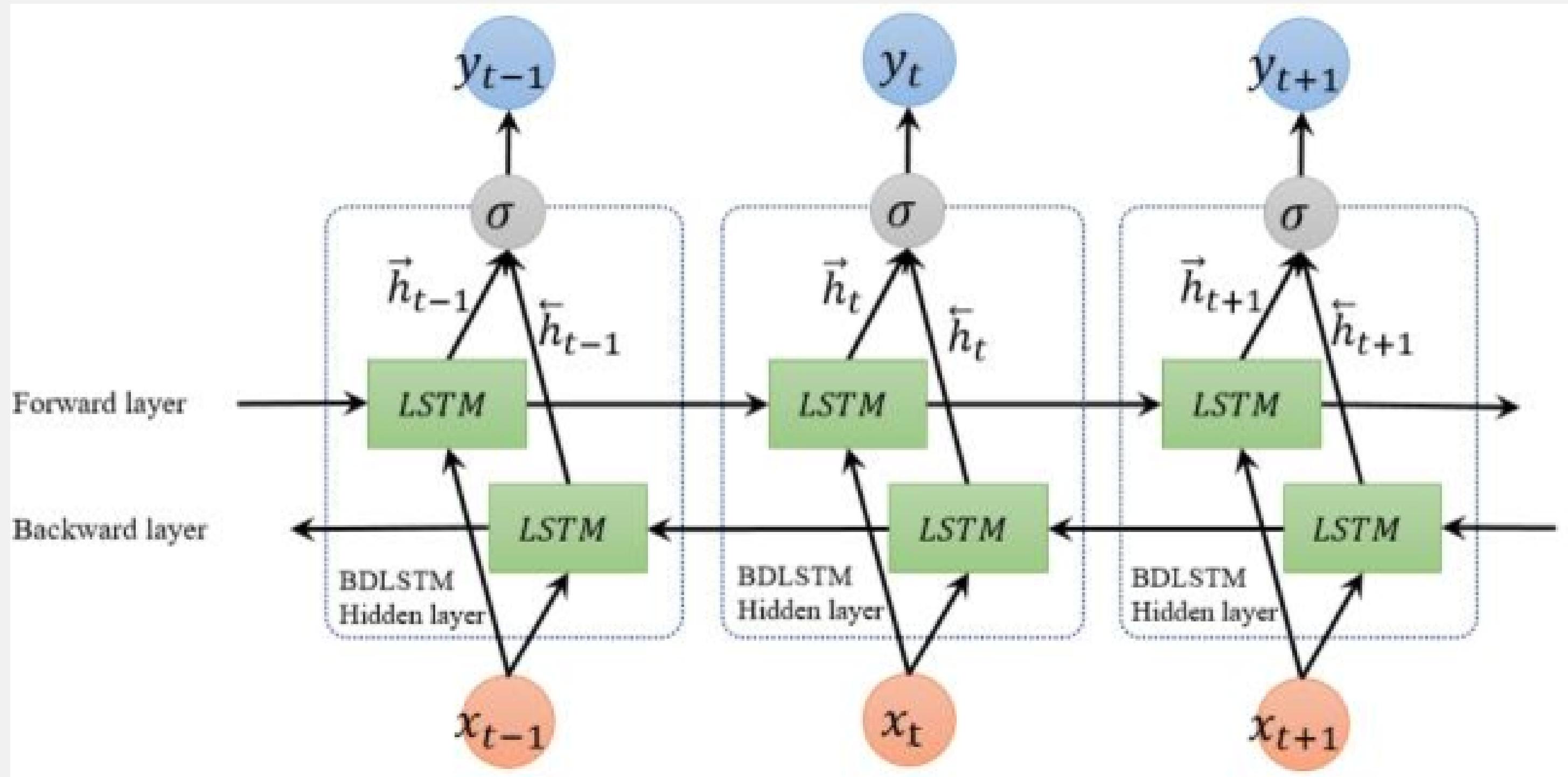


Feed-Forward Neural Network

# Recurrent Neural Net (RNN)



# Recurrent Neural Net (RNN)

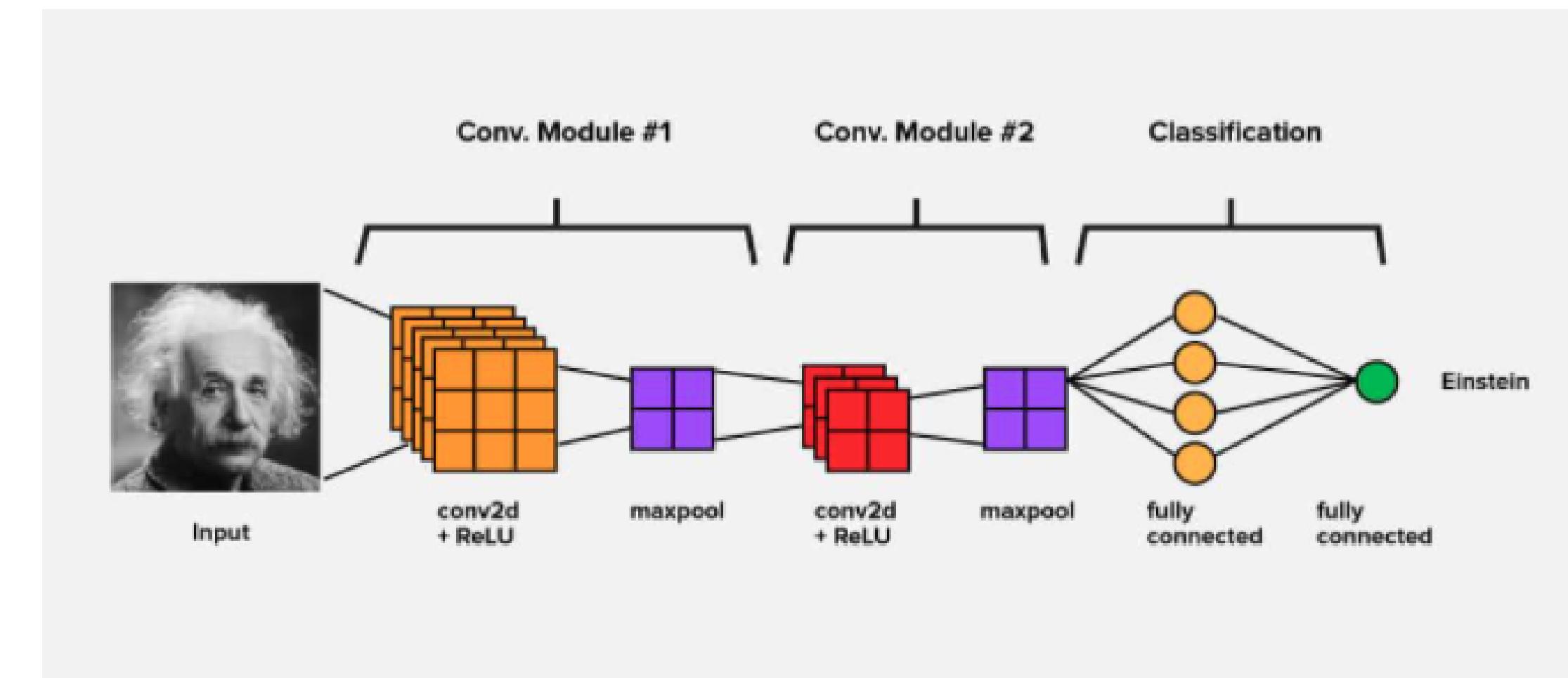


# Convolutional Neural Net (CNN)

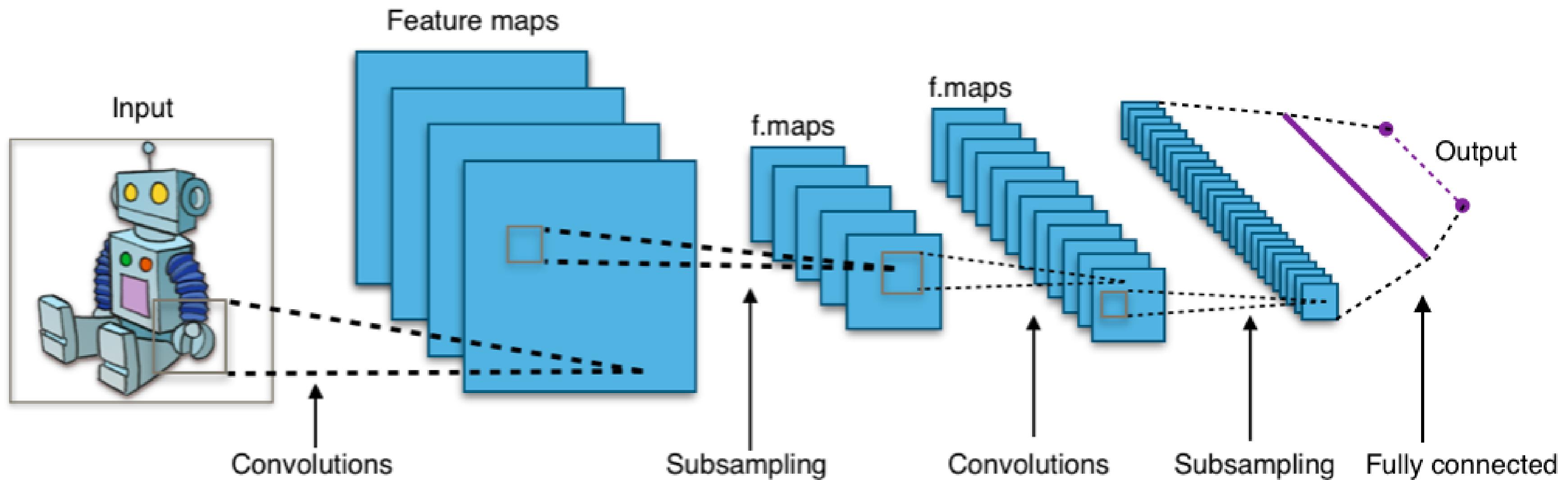
Usada para resolver a maioria dos problemas com Deep Learning

Feedforward ou recurrent

Principal arquitetura para trabalhar com imagens

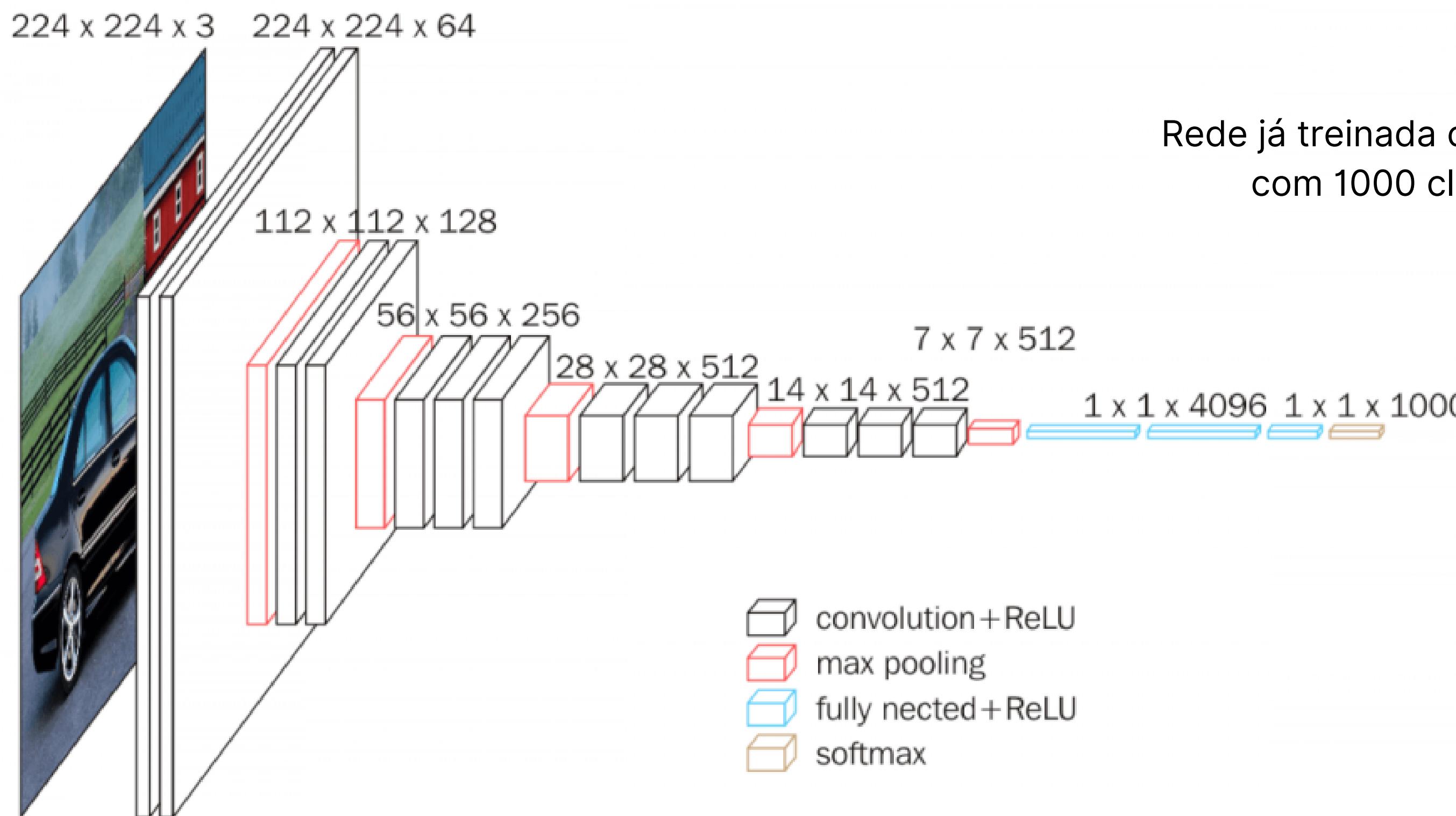


# Convolutional Neural Net (CNN)



# Convolutional Neural Net (CNN)

## Fine-tuning

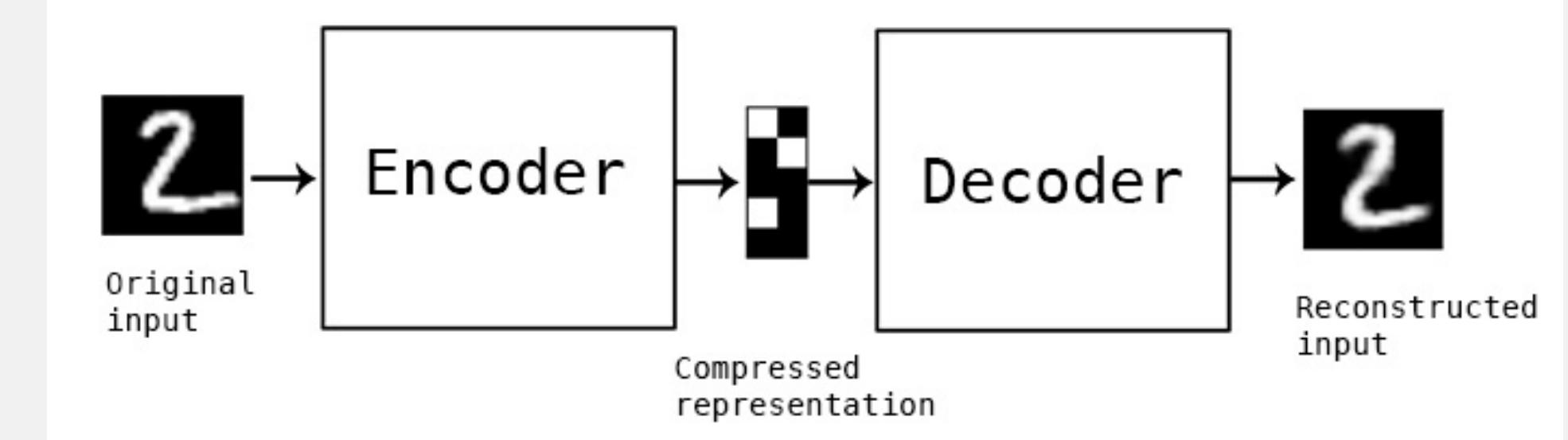


# Autoencoders

Compressão e Codificação

Decodificação mais próxima do *input original*

Redução de dimensionalidade ao aprender a ignorar o ruído dos dados



# Autoencoders

$$\phi : \mathcal{X} \rightarrow \mathcal{F}$$

$$\psi : \mathcal{F} \rightarrow \mathcal{X}$$

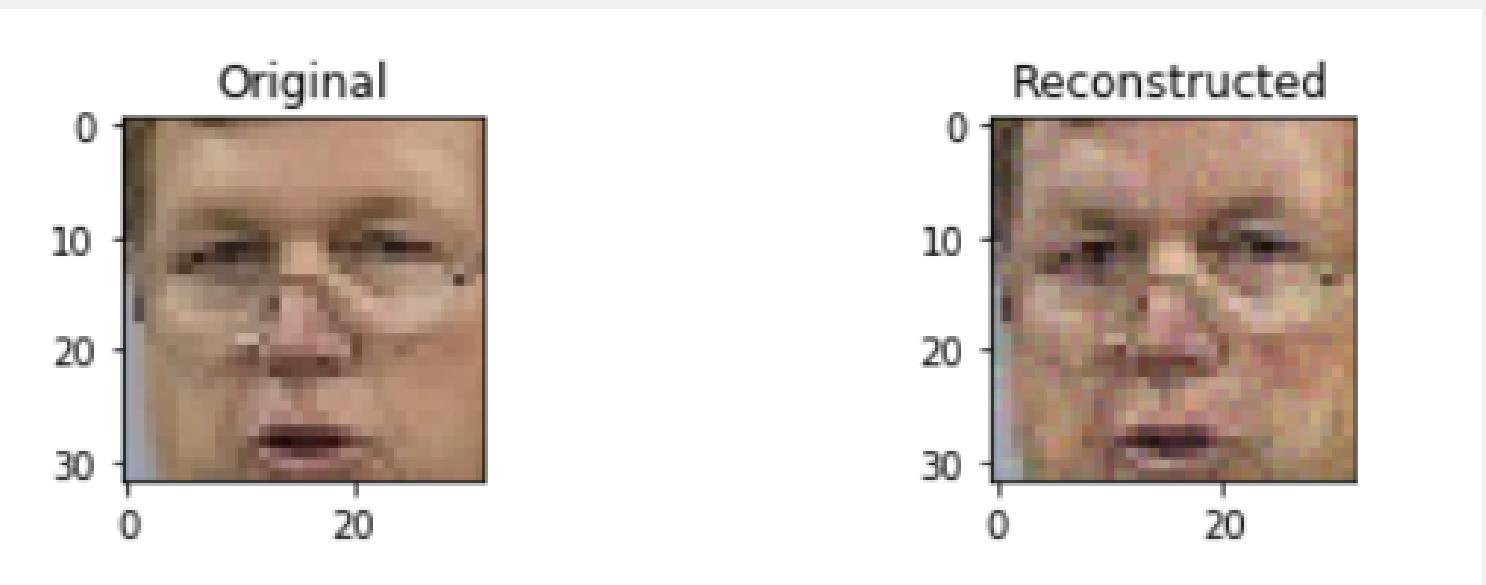
$$\mathbf{h} = \sigma(\mathbf{Wx} + \mathbf{b})$$

$$\mathbf{x}' = \sigma'(\mathbf{W}'\mathbf{h} + \mathbf{b}')$$

$$\mathcal{L}(\mathbf{x}, \mathbf{x}') = \|\mathbf{x} - \mathbf{x}'\|^2 = \|\mathbf{x} - \sigma'(\mathbf{W}'(\sigma(\mathbf{Wx} + \mathbf{b})) + \mathbf{b}')\|^2$$

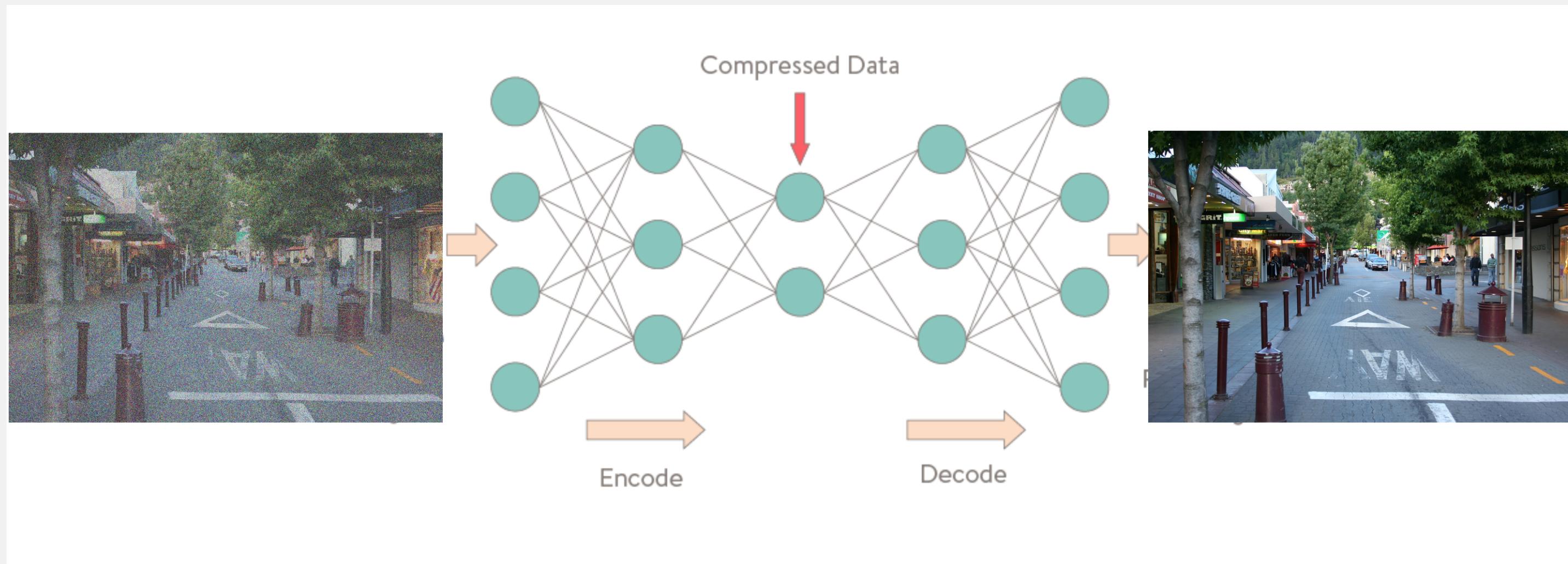
# Autoencoders

```
1 from keras.layers import Dense, Flatten, Reshape, Input, InputLayer
2 from keras.models import Sequential, Model
3
4 def build_autoencoder(img_shape, code_size):
5     # The encoder
6     encoder = Sequential()
7     encoder.add(InputLayer(img_shape))
8     encoder.add(Flatten())
9     encoder.add(Dense(code_size))
10
11    # The decoder
12    decoder = Sequential()
13    decoder.add(InputLayer((code_size,)))
14    decoder.add(Dense(np.prod(img_shape)))
15    decoder.add(Reshape(img_shape))
16
17    return encoder, decoder
```



# Autoencoders

**Exemplo - Reduzir ruídos de imagens (*Image Denoising*)**



# Generative adversarial network

Dado um set de treino, aprende a gerar dados novos similares ao set de treino

Duas redes neurais competem entre si em uma espécie de *jogo de soma zero*

Uso: GAN pode gerar novas fotos que se parecem autênticas a observadores humanos. *Deepfakes*



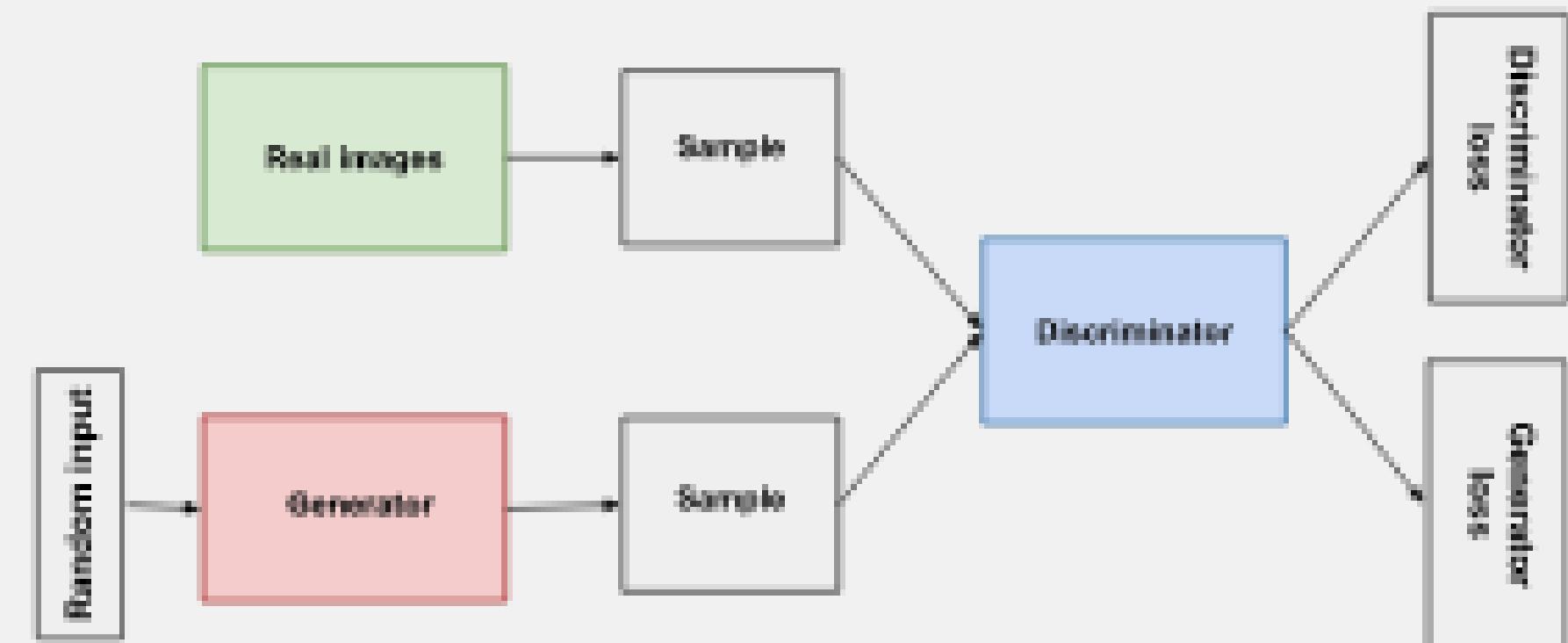
**Essa imagem foi gerada pelo StyleGAN baseado na análise de um retrato**

# Generative adversarial network

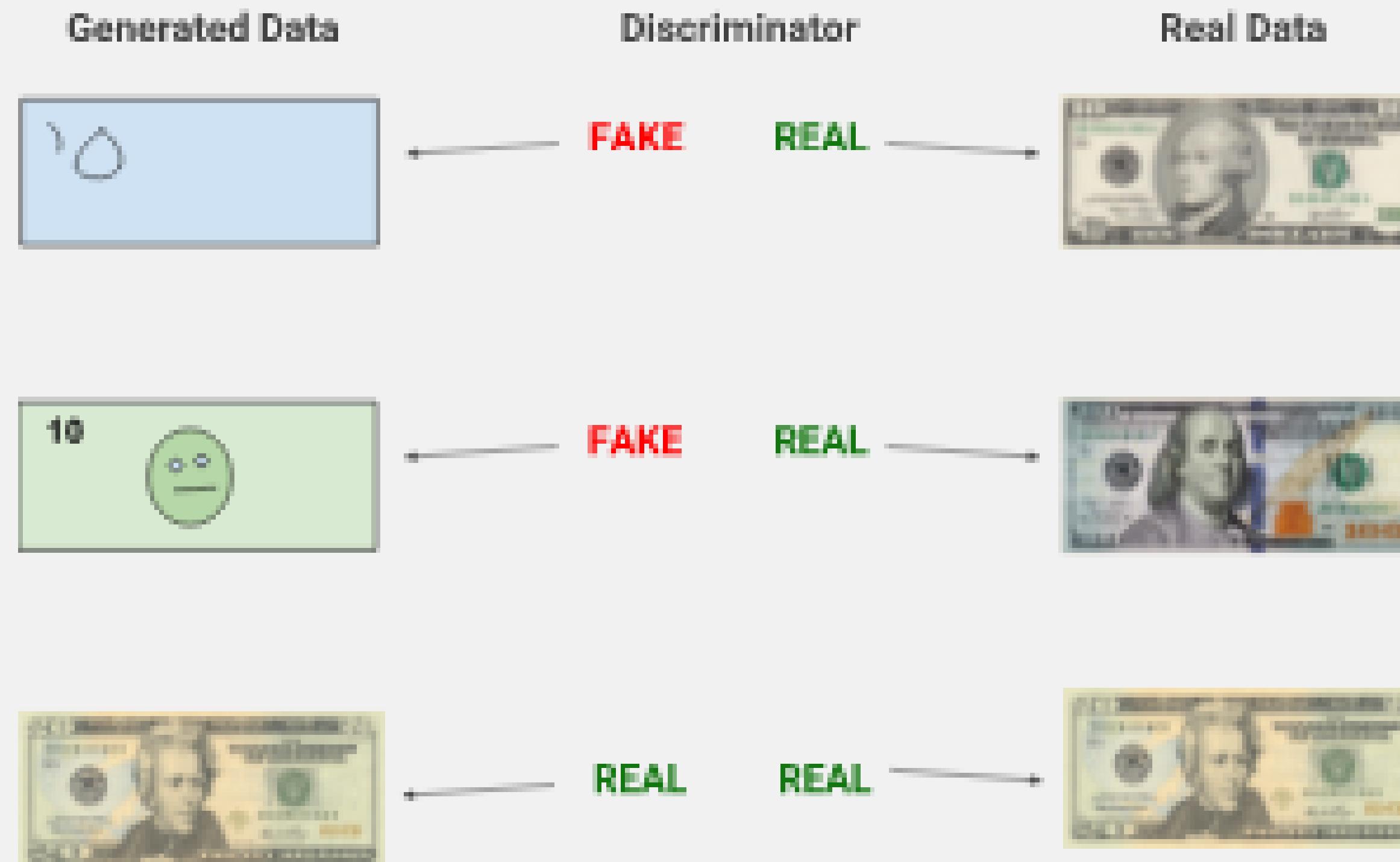
# O GAN possui duas partes:

**Gerador:** aprende a gerar dados plausíveis. As instâncias passam a ser exemplos negativos de treino para o discriminador.

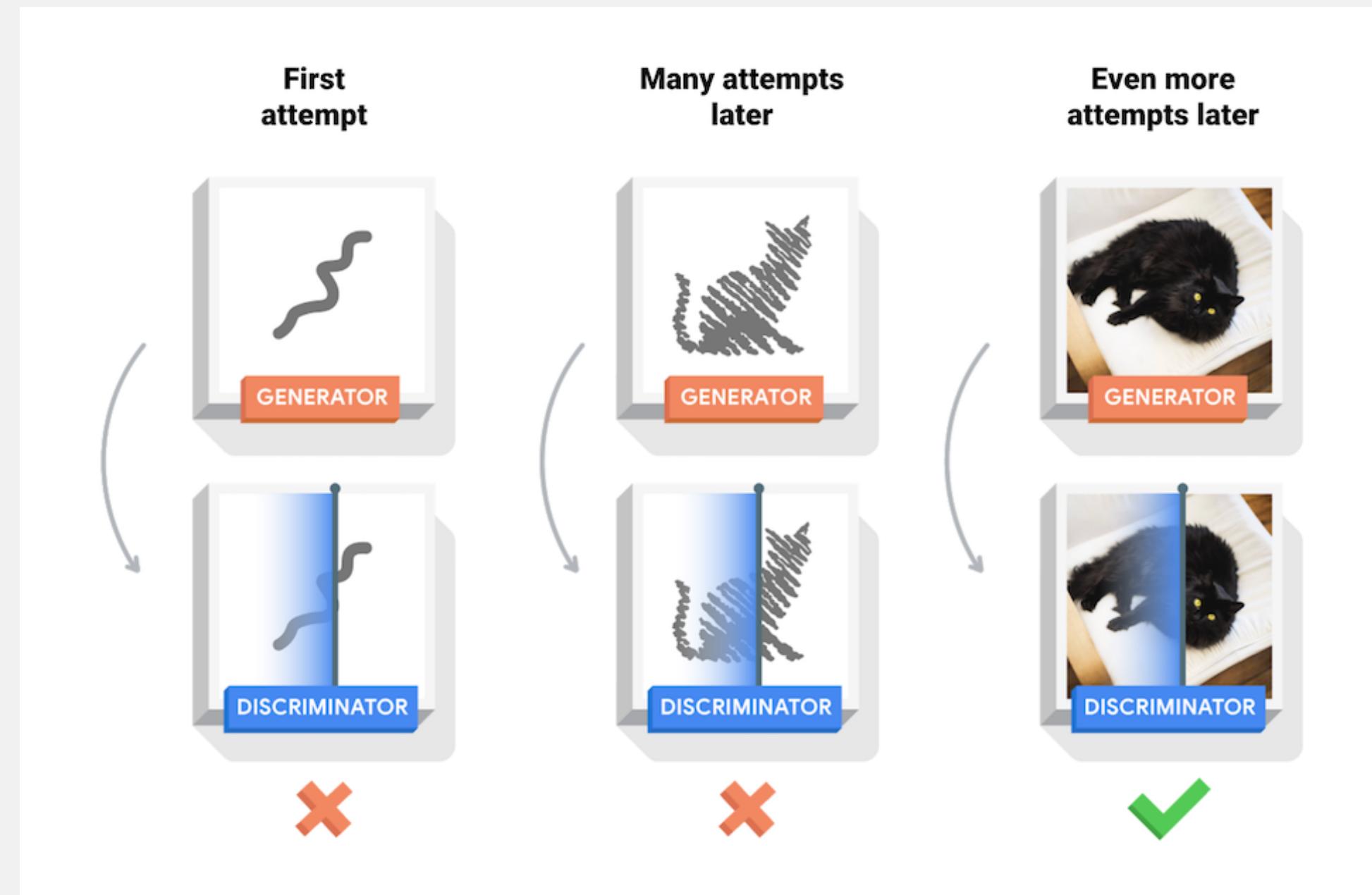
**Discriminador:** distingue o dado falso (advindo do gerador) do dado real. O discriminador penaliza o gerador de produzir dados não-plausíveis



# Generative adversarial network



# Generative adversarial network



# Referências bibliográficas

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