

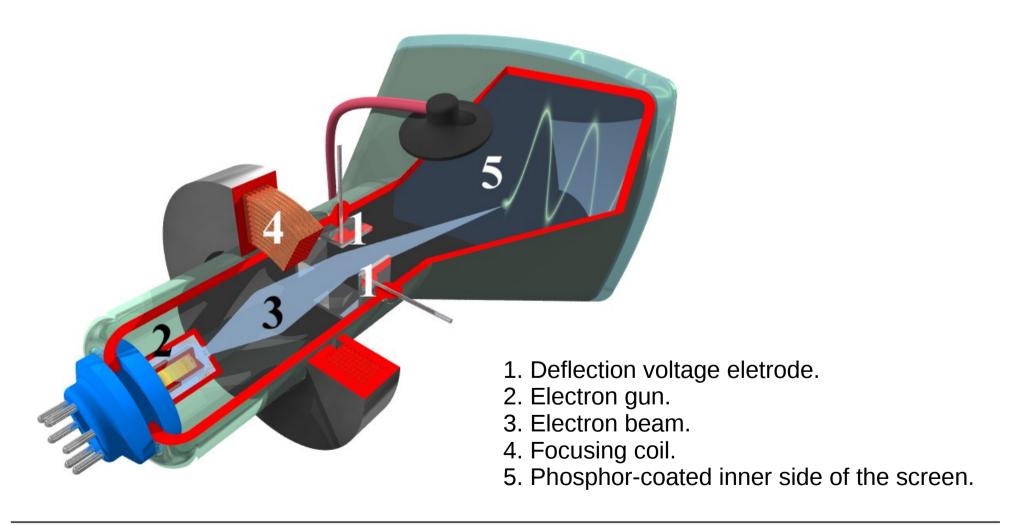
Lecture 2

1107190 - Introdução à Computação Gráfica

Prof. Christian Azambuja Pagot CI / UFPB



Vector Display





Vector Graphics

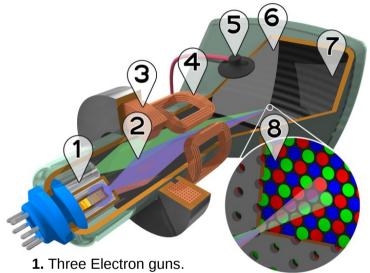


Vectrex video game (video)



Raster Displays

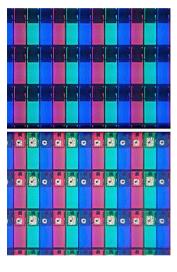
CRT Display



- **2.** Electron beams.
- 3. Focusing coils.
- 4. Deflection coils.
- **5.** Anode connection.
- **6.** Mask for separating beams.
- 7. Phosphor layer.
- **8.** Close-up of the phosphor-coated inner side of the screen.

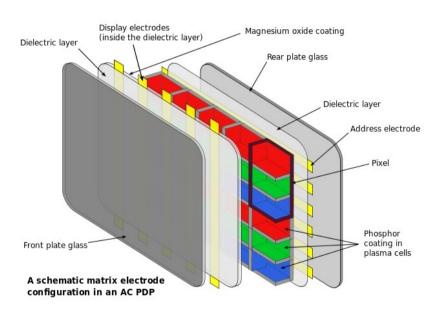
Søren Peo Pedersen (Wikipedia)

LCD Display



Gabelstaplerfahrer (Wikipedia)

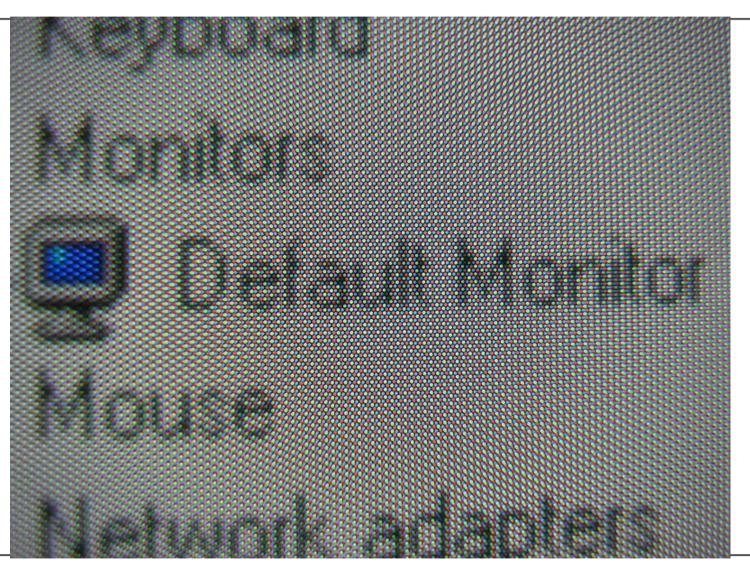
Plasma Display



Jari Laamanen (Wikipedia)

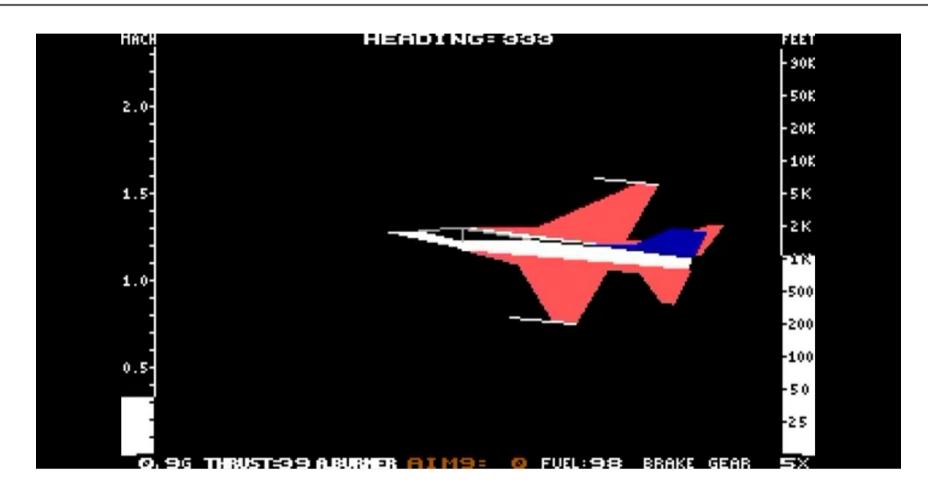


Raster Display





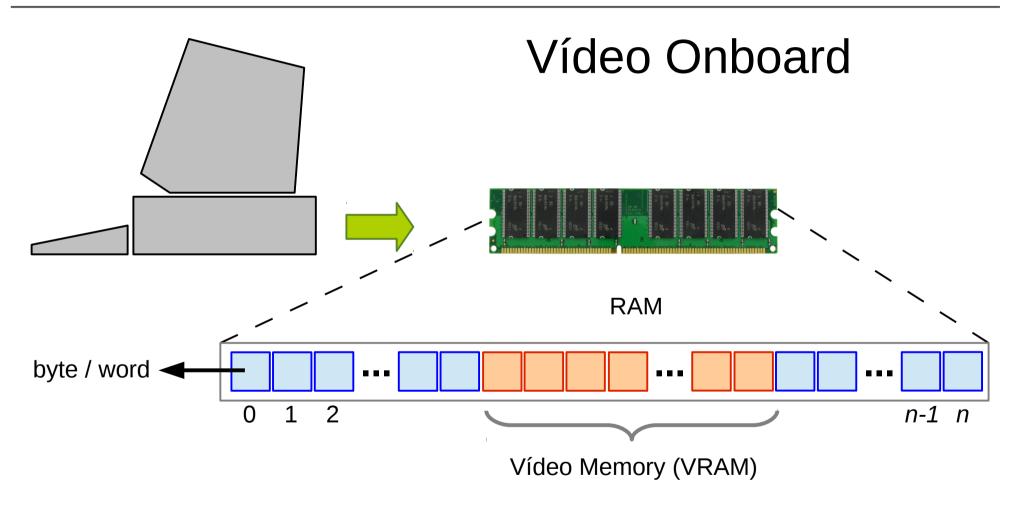
Raster Graphics



Jet 2 (1987) (video)

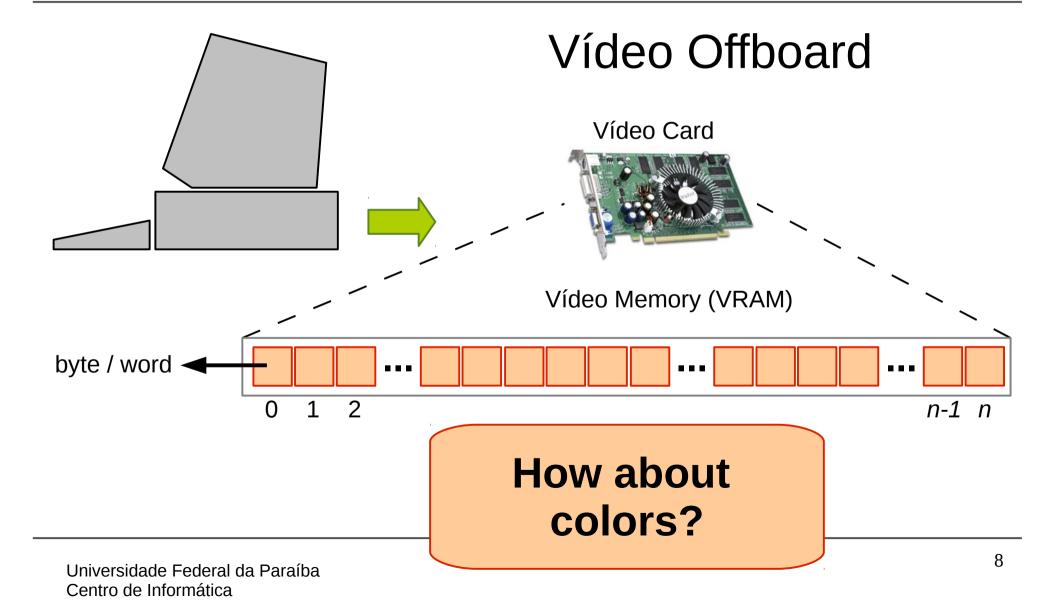


Video Memory





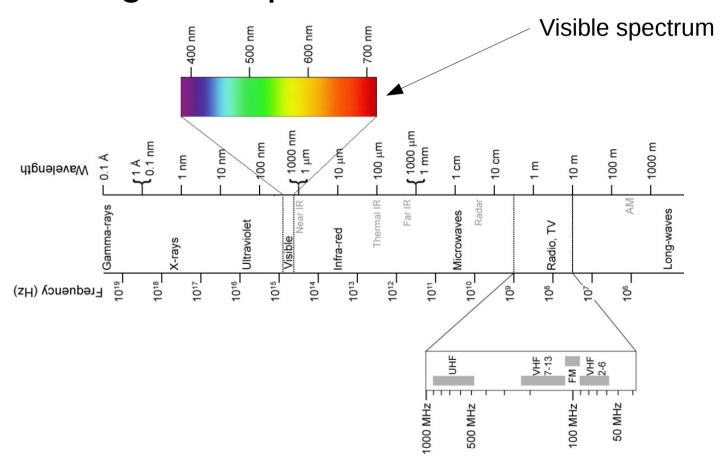
Video Memory





Colors (Quick view)

Electromagnetic spectrum



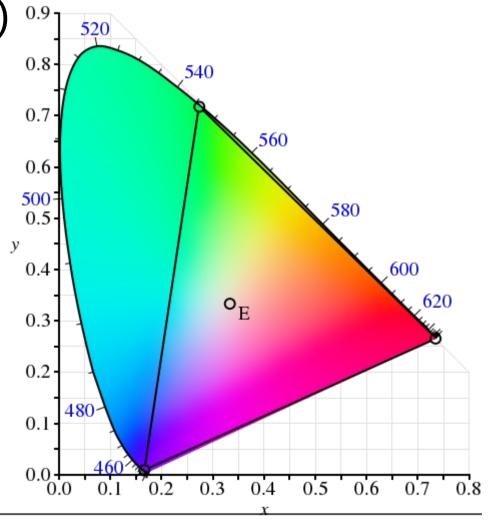


Colors (Quick view)

CIE Color Space (1931)

CIE RGB Color Space

Normally used in computers!

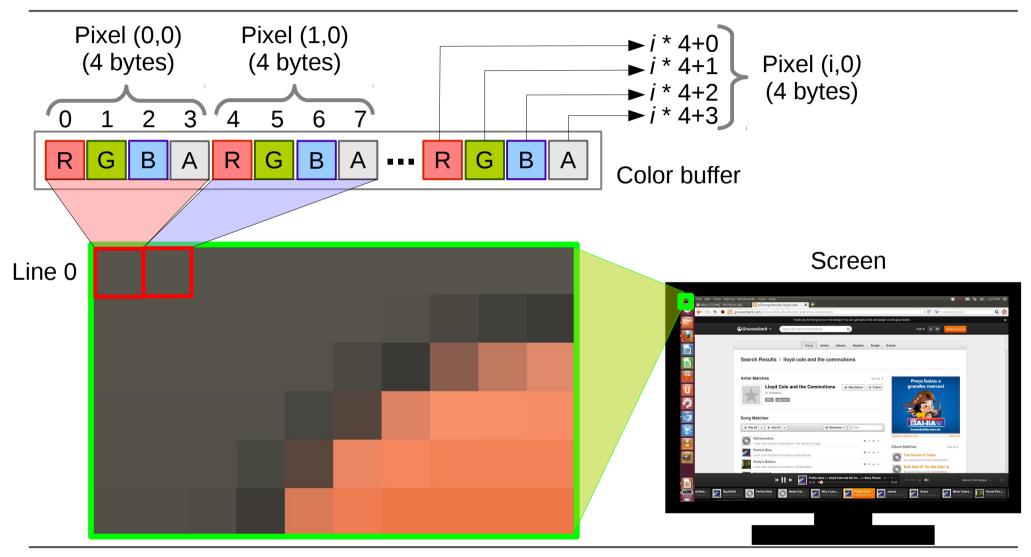




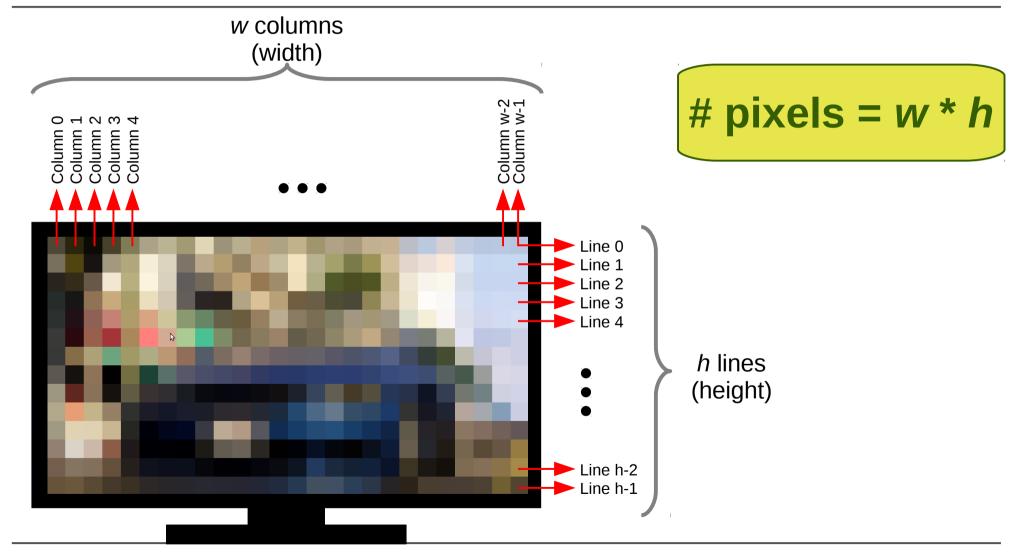
RGB Representation

- The intensity of each component is represented by a number.
- Usually, 8 bits are reserved for each component
 (channel). Thus, each component can present up to
 256 levels of intensity (256³ = ~16 millions of colors).
- An additional channel (alpha) can be used for transparency (RGBA).
- It's not uncommon to have **different** number of **bits** per **channel**.

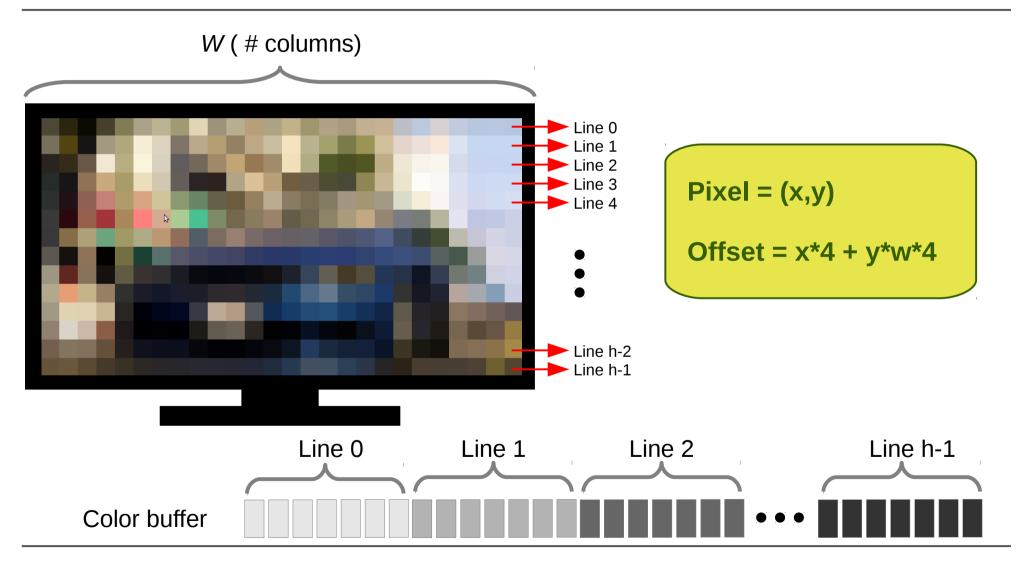






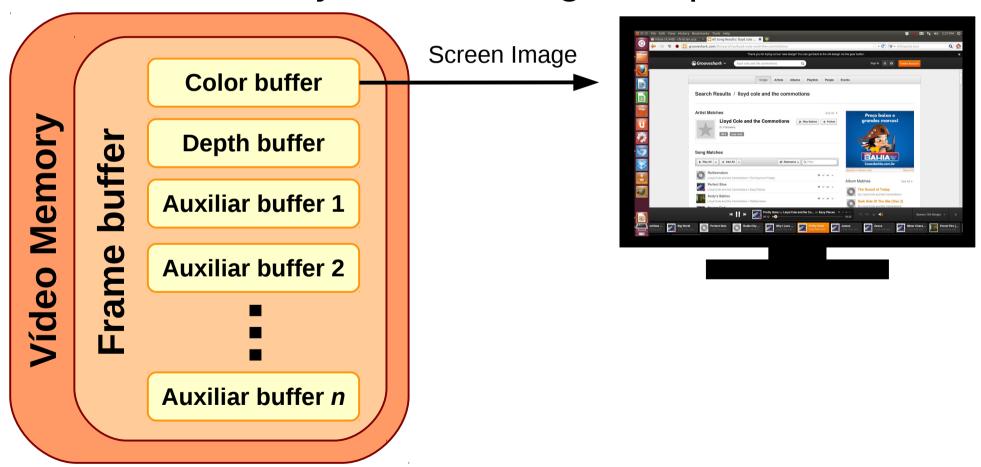








Vídeo memory screen image footprint:



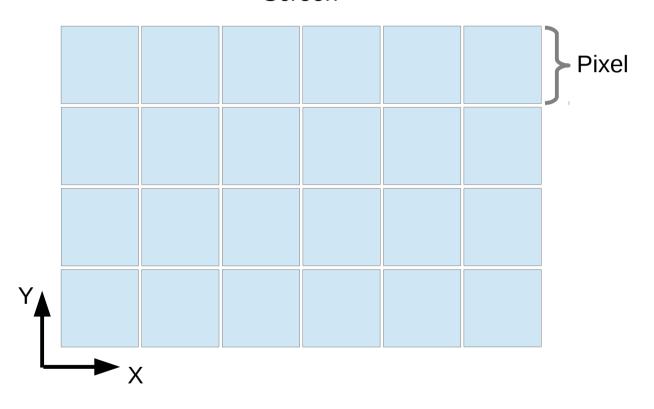


"Approximation of mathematical ('ideal')
 primitives, described in terms of vertices on a
 Cartesian grid, by sets of pixels of the
 appropriate intensity of gray or color."

- Foley et. al

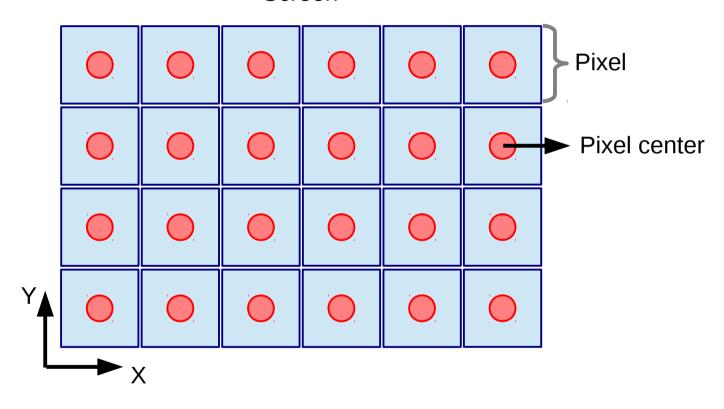


Screen

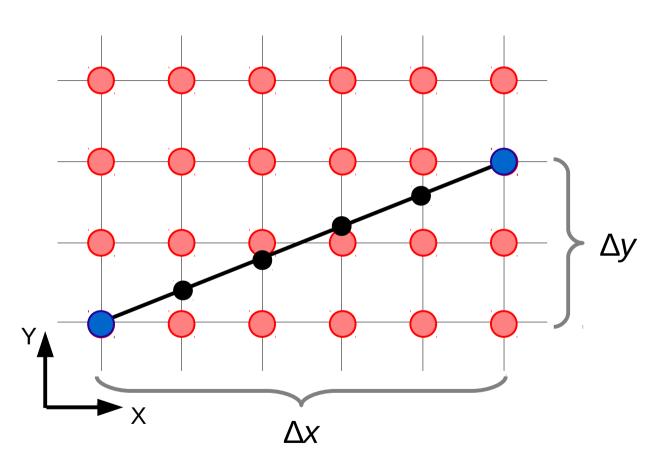




Screen







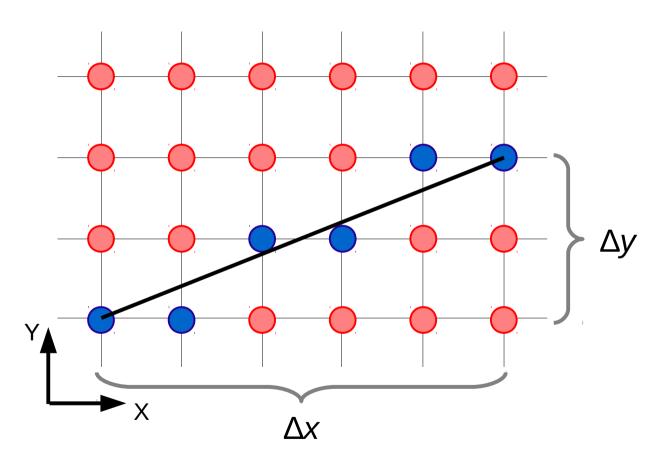
Since Δx is greater Δy :

$$m = \frac{\Delta y}{\Delta x}$$
$$y_i = m x_i + b$$

By incrementing x by 1, we can compute the corresponding y:

1st point:
$$(x_0, mx_0 + b)$$
)
2nd point: $(x_1, mx_1 + b)$)
3rd point: $(x_2, mx_2 + b)$)
.
.
.
nth point: $(x_n, mx_n + b)$)





Since Δx is greater Δy :

$$m = \frac{\Delta y}{\Delta x}$$
$$y_i = m x_i + b$$

By incrementing *x* by 1, we can compute the corresponding *y*:



- Problems with this approach:
 - At each iteration:
 - A floating point multiplication.
 - A floating point addition.
 - A Round operation.

nth point: (x_n, Round(mx_n+ b))



Solution:

- Multiplication can be eliminated:

$$y_{i+1} = m x_{i+1} + b$$

$$y_{i+1} = m(x_i + \Delta x) + b$$

$$y_{i+1} = y_i + m \Delta x$$

- If $\Delta x = 1$:

$$y_{i+1} = y_i + m$$

This is an incremental algorithm.

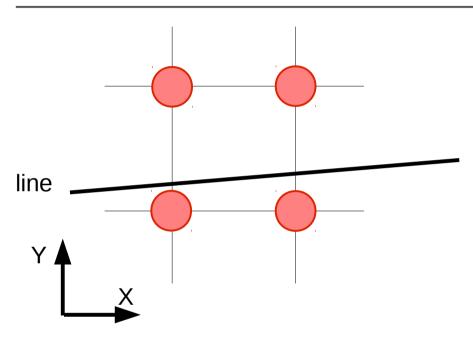
Usually referred as the DDA (digital differential analyzer) algorithm.



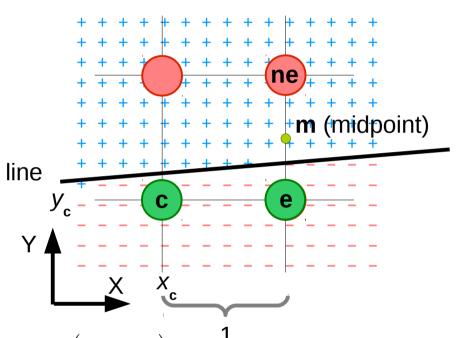
Bresenham Line Algorithm

- Incremental.
- Avoids multiplications and roundings.
- Can be generalized for circles.









$$\mathbf{c} = (x_{\mathbf{c}}, y_{\mathbf{c}})$$

$$\mathbf{e} = (x_{\mathbf{c}} + 1, y_{\mathbf{c}})$$

$$\mathbf{n} = (x_{\mathbf{c}} + 1, y_{\mathbf{c}} + 1)$$

$$\mathbf{m} = (x_{\mathbf{c}} + 1, y_{\mathbf{c}} + \frac{1}{2})$$

Will we have to evaluate a **polynomial** every **pixel**?

Assuming that $0 \le m \le 1$:

$$y = mx + b$$

$$y = \left(\frac{\Delta y}{\Delta x}\right) x + b$$

$$\alpha = \Delta y
\beta = -\Delta x
\gamma = b \cdot \Delta x$$

$$\Phi(x,y) = \alpha x + \beta y + \gamma = 0$$

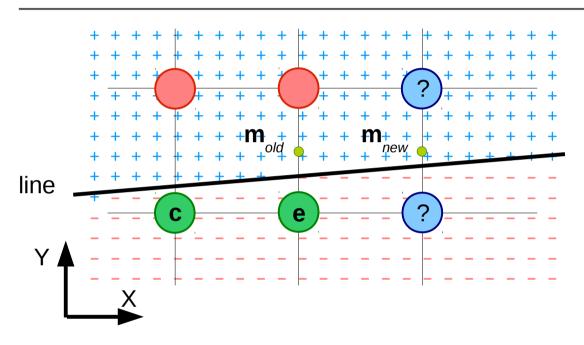
$$\Phi(x,y) = \Delta y \cdot x - \Delta x \cdot y + b \cdot \Delta x = 0$$

$$d = \Phi(\mathbf{m}) \rightarrow Decision variable$$

if
$$(d < 0)$$

next pixel = **ne**
else
next pixel = **e**





$$d_{old} = \Phi(\mathbf{m}_{old}) = \Phi((x_c + 1, y_c + \frac{1}{2}))$$

$$d_{new} = \Phi(\mathbf{m}_{new}) = \Phi((x_c + 2, y_c + \frac{1}{2}))$$

If E is choosen:

$$d_{old} = \alpha \left(x_{c} + 1 \right) + \beta \left(y_{c} + \frac{1}{2} \right) + \gamma$$

$$d_{new} = \alpha \left(x_c + 2 \right) + \beta \left(y_c + \frac{1}{2} \right) + \gamma$$

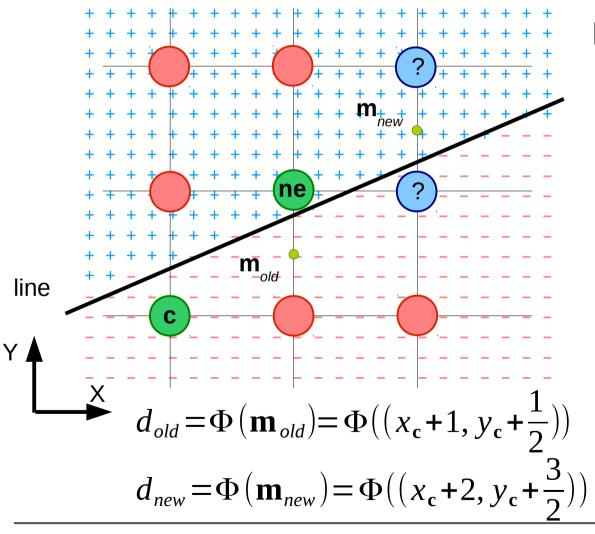
$$d_{new} - d_{old} \rightarrow d_{new} = d_{old} + \alpha$$

Remembering...

$$\Phi(x,y) = \alpha x + \beta y + \gamma$$

$$\alpha = \Delta y
\beta = -\Delta x
\gamma = b \cdot \Delta x$$





If NE is choosen:

$$d_{old} = \alpha \left(x_{c} + 1 \right) + \beta \left(y_{c} + \frac{1}{2} \right) + \gamma$$

$$d_{new} = \alpha \left(x_c + 2\right) + \beta \left(y_c + \frac{3}{2}\right) + \gamma$$

$$d_{new} - d_{old} \rightarrow d_{new} = d_{old} + \alpha + \beta$$

Remembering...

$$\Phi(x,y) = \alpha x + \beta y + \gamma$$

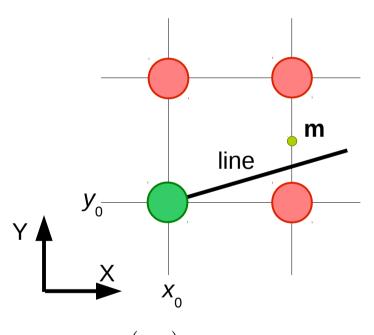
$$\alpha = \Delta y$$

$$\beta = -\Delta x$$

$$\gamma = b \cdot \Delta x$$



• How about the 1st pixel (there is no D_{old} !)?



$$d = \Phi(\mathbf{m})$$

$$= \Phi((x_0 + 1, y_0 + \frac{1}{2}))$$

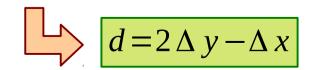
$$d = \Phi(\mathbf{m}) = \alpha(x_0 + 1) + \beta(y_0 + \frac{1}{2}) + \gamma$$

$$d = \Phi(\mathbf{c}) + \alpha + \frac{\beta}{2} \qquad \Phi(\mathbf{c}) = 0$$

$$d = \alpha + \frac{\beta}{2} \qquad \beta = \frac{\Delta y}{\beta}$$

$$d = \Delta y - \frac{\Delta x}{2}$$

$$\Phi(x,y)=0=2\cdot 0=2\Phi(x,y)=2(\alpha x+\beta y+\gamma)$$





The entire algoritm for 0 < m < 1:

```
MidPointLine() {
     int dx = x1 - x0:
    int dy = y1 - x0;
    int d = 2 * dy - dx;
    int incr_e = 2 * dy;
    int incr ne = 2 * (dy - dx);
     int x = x0;
    int \vee = \vee 0;
    PutPixel(x, y, color)
    while (x < x1) {
         if (d <= 0) {
              d += incr e;
              X++;
         } else {
              d += incr_ne;
              χ++;
              y++;
         PutPixel(x, y, color);
```

The **computation** of *d*, now, **involves** only **addition**!

Slopes **outside** the range **[0,1]** can be **handled** by **symmetry**!



Other Rasterization Issues

- How about?
 - Other primitives:
 - Circles.
 - Ellipses.
 - Triangles.
 - Thick lines.
 - Shape of the endpoints.
 - Antialiasing.
 - Line stile.
 - Filling.
 - Etc.