



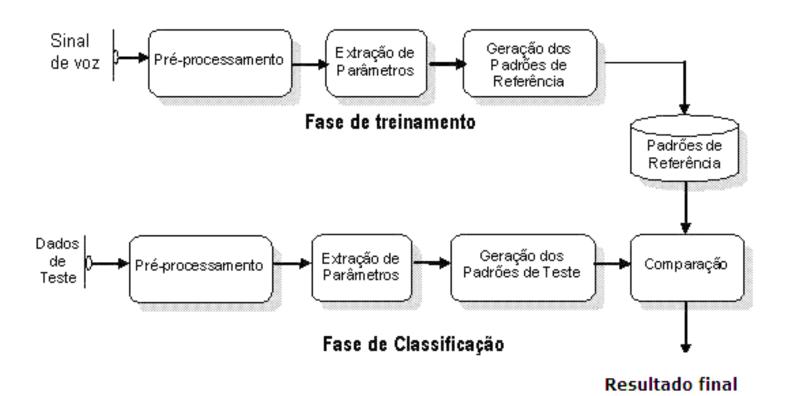
Processamento Digital de Sinais de Voz

Pré-processamento de Sinais de Voz



Análise de sinais de voz a curto intervalo de tempo

Sistema geral de Classificação



Pré-processamento

- Filtragem
- Divisão em quadros/segmentação
- o Pré-ênfase
- Janelamento
 - Retangular
 - Hamming
 - Hanning
 - Blackman

Filtragem

- Limitação da largura de faixa → economia na energia espectral;
- Redução de ruído de fundo
- Realce de frequências
- Retirada de sinais indesejáveis -> sinais interferentes; eliminação dos 60 Hz (sinais biomédicos, por ex.)

Segmentação/Divisão em quadros

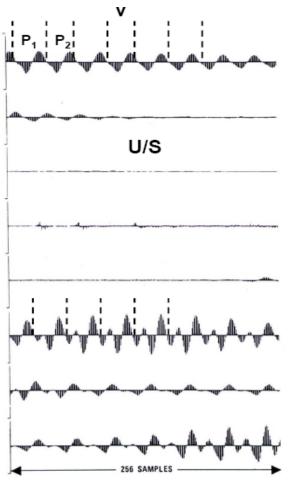


Fig. 4.1 Samples of a typical speech waveform (8 kHz sampling rate).

- 8 kHz sampled speech (bandwidth < 4 kHz)
- properties of speech change with time
 - excitation goes from voiced to unvoiced
 - peak amplitude varies with the sound being produced
 - pitch varies within and across voiced sounds
 - periods of silence where background signals are seen
- the key issue is whether we can create simple time-domain processing methods that enable us to measure/estimate_speech representations reliably and accurately.

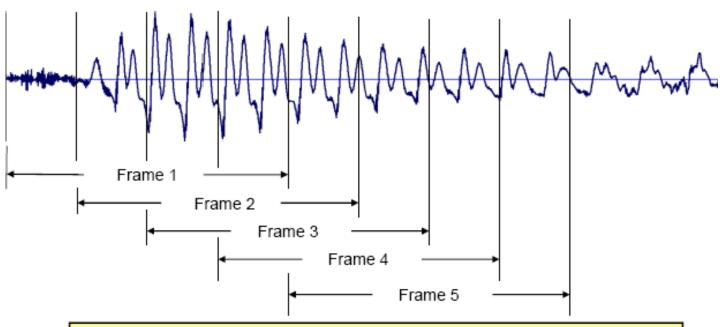
Fundamental Assumptions

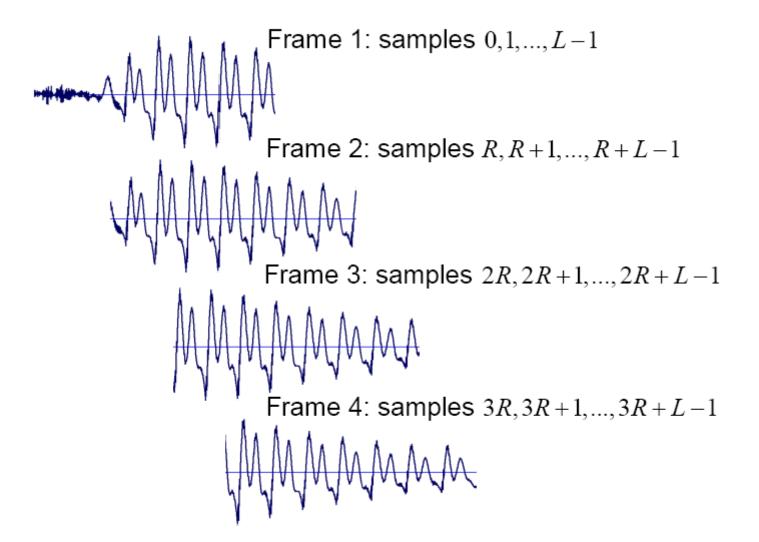
- properties of the speech signal change relatively slowly with time (5-10 sounds per second)
 - over very short (5-20 msec) intervals => uncertainty due to small amount of data, varying pitch, varying amplitude
 - over medium length (20-100 msec) intervals => uncertainty due to changes in sound quality, transitions between sounds, rapid transients in speech
 - over long (100-500 msec) intervals => uncertainty
 due to large amount of sound changes
- there is always uncertainty in short time measurements and estimates from speech signals

Compromise Solution

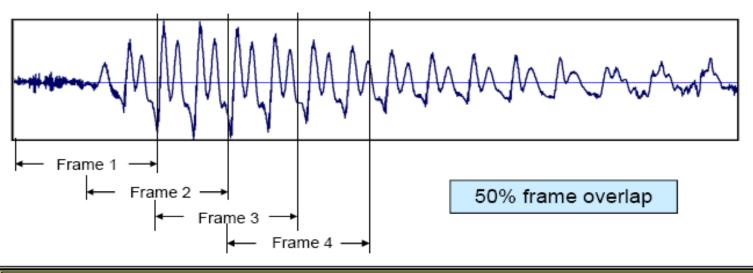
- "short-time" processing methods => short segments of the speech signal are "isolated" and "processed" as if they were short segments from a "sustained" sound with fixed (non-time-varying) properties
 - this short-time processing is <u>periodically repeated</u> for the duration of the waveform
 - these short analysis segments, or "<u>analysis frames</u>" almost always <u>overlap</u> one another
 - the results of short-time processing can be a single number (e.g., an estimate of the pitch period within the frame), or a set of numbers (an estimate of the formant frequencies for the analysis frame)
 - the end result of the processing is a new, time-varying sequence that serves as a new representation of the speech signal

Frame-by-Frame Processing in Successive Windows



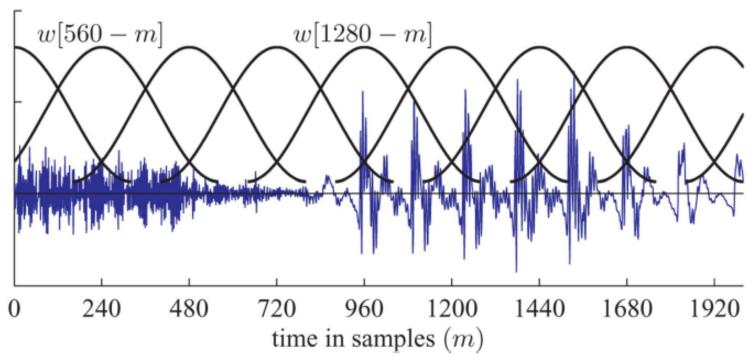


Frame-by-Frame Processing in Successive Windows



- Speech is processed frame-by-frame in overlapping intervals until entire region of speech is covered by at least one such frame
- Results of analysis of individual frames used to derive model parameters in some manner
- Representation goes from time sample $x[n], n = \dots, 0, 1, 2, \dots$ to parameter vector $\mathbf{f}[m], m = 0, 1, 2, \dots$ where n is the time index and m is the frame index.

Frames and Windows



 $F_{S} = 16,000 \text{ samples/second}$

L = 641 samples (equivalent to 40 msec frame (window) length)

R = 240 samples (equivalent to 15 msec frame (window) shift)

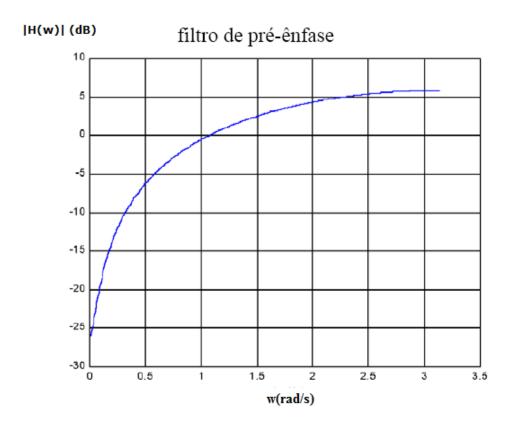
Frame rate of 66.7 frames/second

Pré-ênfase

- Proporciona compensação das perdas durante a passagem do sinal pelo trato vocal e pela radiação nos lábios (cerca de -6dB/oitava).
- Para solucionar esse problema é aplicado um filtro, de resposta de aproximadamente +6dB/oitava.
- Pode ser implementada, como uma operação digital no sinal amostrado, através de um filtro FIR de primeira ordem.
- Função de transferência do filtro: $H_p(z) = 1 a_p z^{-1}$

$$s_p(n) = s(n) - 0.95.s(n-1).$$
 (Valor típico de $a_p = 0.95$)

Função de transferência – filtro de préênfase (a=0.95)



Consiste de um filtro derivador, realçando as altas frequências.

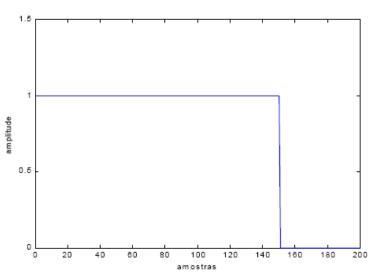
- Sinal de voz características estatísticas variam fortemente com o tempo, só podendo ser considerado estacionário em trechos muito pequenos - da ordem de dezenas de milissegundos - para efeito de obtenção de parâmetros.
- Segmentação consiste em particionar o sinal de voz em segmentos, selecionados por janelas ou quadros de duração perfeitamente definida.
- A estimação espectral, na prática, é sempre feita em um trecho finito do sinal - Janelamento.

- Principais funções janela para a aplicação em processamento de voz:
 - Janela retangular: atribui igual peso a todas as amostras;
 - o janelas Hamming e von Hann: atribuem pesos às amostras conforme a seguinte equação:

$$w[n] = \lambda + (1 - \lambda)\cos(2\pi n/(N - 1))$$

w[n] - função janela e N - número de pontos da janela.

Janela retangular



Janela retangular para *N*=150.

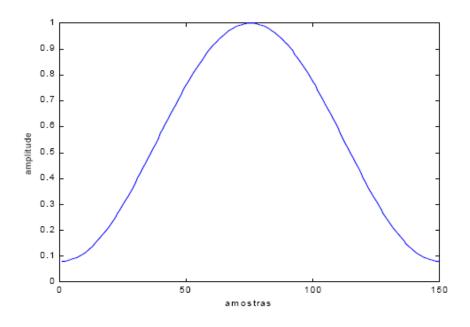
Dá o mesmo peso para todas as amostras.

Empregada no método da AMDF (Average Magnitude Difference Function), para detecção do *pitch*.

É o tipo de janela mais simples, sendo expressa pela seguinte função:

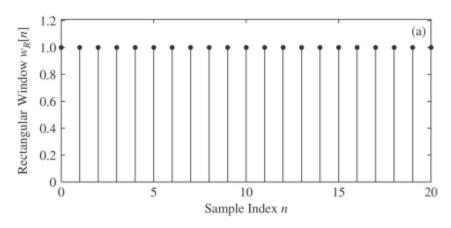
$$w(n) = \begin{cases} 1, \text{ para } 0 < n \le N \\ 0, \text{ para } n > N \end{cases}$$

Janela de Hamming

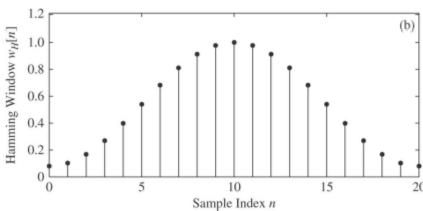


$$w(n) = \begin{cases} 0.54 - 0.46\cos\left(\frac{2\pi n}{N-1}\right), \text{ para } 0 \le n \le N-1 \\ 0, \text{ para } n \ge N \end{cases}$$

Janelas Retangular e Hamming



L = 21 samples



$$\tilde{w}_H[n] = 0.54 \tilde{w}_R[n] - 0.46 * \cos(2\pi n / (L-1)) \tilde{w}_R[n]$$

Janela de Hamming

$$H(e^{j\Omega T}) = \frac{\sin(\Omega LT/2)}{\sin(\Omega T/2)} e^{-j\Omega T(L-1)/2}$$

-100

O primeiro zero ocorre em f=Fs/L=1/(LT) (or $\Omega=(2\pi)/(LT)$) \rightarrow frequência de corte nominal do filtro 'passabaixas' equivalente.

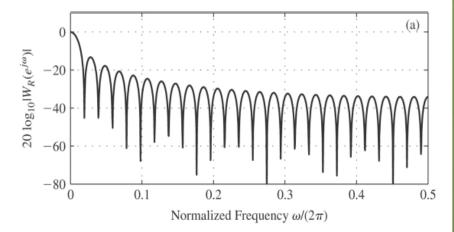
2,5 2 - 1,5 - 1,5 - 1,5 -

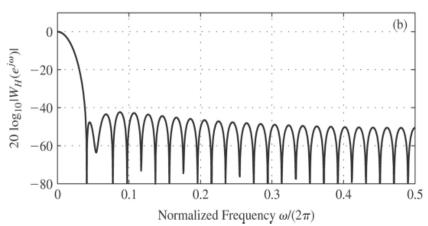
Pulso Retangular Centrado

100

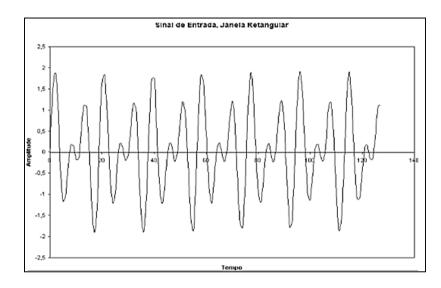
Resposta em frequência das Janelas Retangular (WR) e Hamming (WH)

- Resposta em magnitude da WR e WH;
- Largura de faixa da WR é o dobro da WH;
- atenuação de mais de 40 dB para HW fora da faixa de passagem versus 14 dB para RW;
- Atenuação na faixa de rejeição é independente do comprimento (L) da janela;
- L → deve conter ao menos um período de pitch; deve manter a estacionaridade.

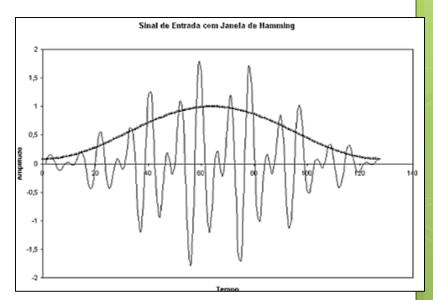




Exemplo

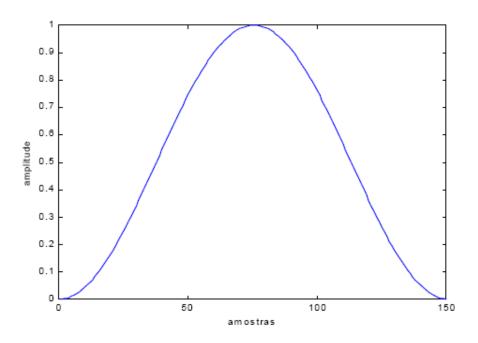


Janela retangular → interrupção repentina → vazamento no espectro



Janela de Hanning

$$w(n) = \begin{cases} 0.5 - 0.5 \cos\left(\frac{2\pi n}{N+1}\right), \text{ para } 0 \le n \le N - 1\\ 0, \text{ para } n \ge N \end{cases}$$



Janela Retangular

Fugas espectrais alterando o espectro do sinal

Janela de Hamming

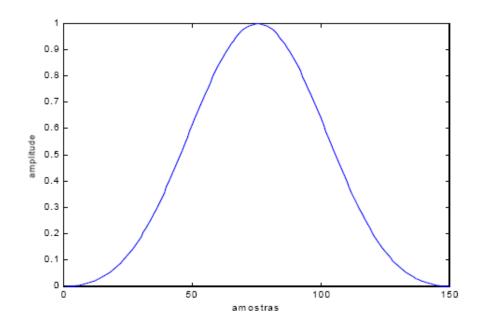
 Apresenta um lóbulo principal de amplitude bastante superior a dos lóbulos secundários – manutenção das características espectrais do centro do quadro e a eliminação das transições abruptas das extremidades.

Janela de Hanning

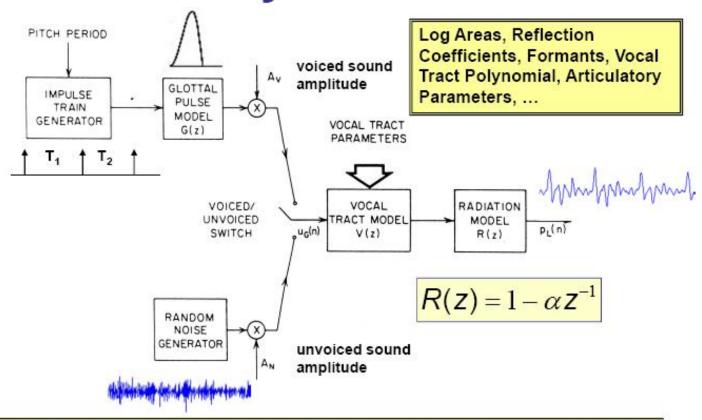
 Similar ao efeito da janela de Hamming, porém proporciona um reforço menor nas amostras do centro e uma suavização maior nas amostras da extremidade.

Janela de Blackman

$$w(n) = \begin{cases} 0,42 - 0.5\cos\left(\frac{2\pi n}{N-1}\right) + 0.8\cos\left(\frac{4\pi n}{N-1}\right), \text{ para } 0 \le n \le N-1\\ 0, \text{ para } n \ge N \end{cases}$$

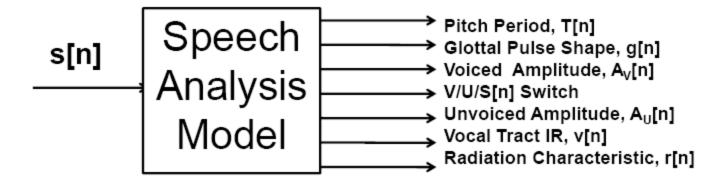


General Synthesis Model



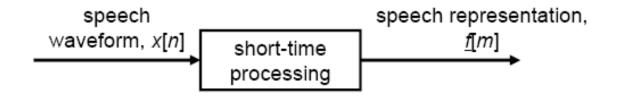
Pitch Detection, Voiced/Unvoiced/Silence Detection, Gain Estimation, Vocal Tract Parameter Estimation, Glottal Pulse Shape, Radiation Model

General Analysis Model



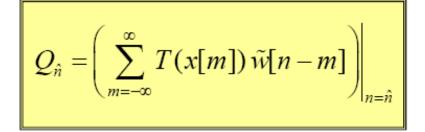
- All analysis parameters are time-varying at rates commensurate with information in the parameters;
 - We need algorithms for estimating the analysis parameters and their variations over time

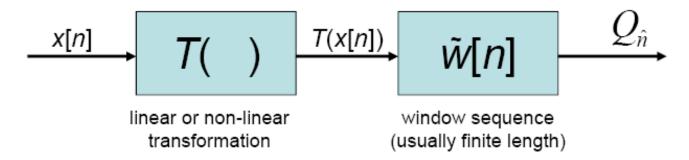
Short-Time Processing



- $\Box x[n]$ = samples at 8000/sec rate; (e.g. 2 seconds of 4 kHz bandlimited speech, x[n], $0 \le n \le 16000$)
- $\Box \vec{f}[m] = \{f_1[m], f_2[m], ..., f_L[m]\} = \text{vectors at 100/sec rate}, \ 1 \le m \le 200,$ L is the size of the analysis vector (e.g., 1 for pitch period estimate, 12 for autocorrelation estimates, etc)

Generic Short-Time Processing





• $Q_{\hat{n}}$ is a sequence of **local weighted average values** of the sequence T(x[n]) at time $n = \hat{n}$

Short-Time Energy

$$E = \sum_{m=-\infty}^{\infty} x^2[m]$$

- -- this is the long term definition of signal energy
- -- there is little or no utility of this definition for time-varying signals

$$E_{\hat{n}} = \sum_{m=\hat{n}-L+1}^{\hat{n}} x^{2}[m] = x^{2}[\hat{n}-L+1] + ... + x^{2}[\hat{n}]$$

-- short-time energy in vicinity of time \hat{n}

$$T(x) = x^2$$

 $\tilde{w}[n] = 1$ $0 \le n \le L - 1$
 $= 0$ otherwise

Computation of Short-Time Energy

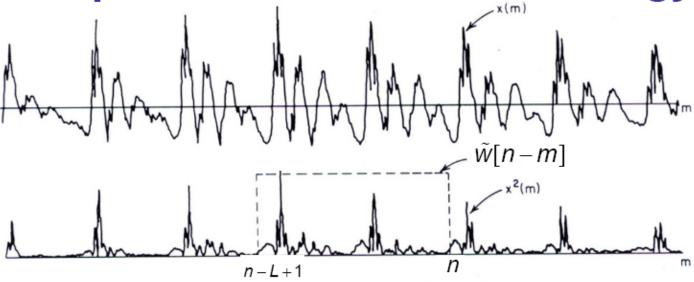
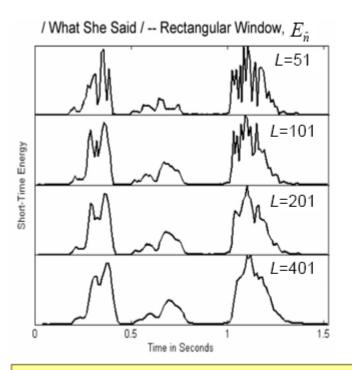
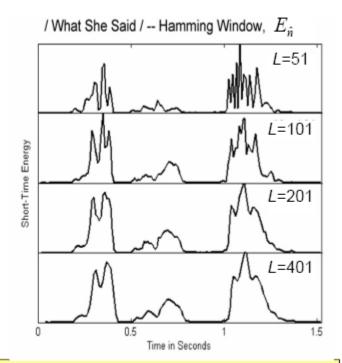


Fig. 4.2 Illustration of the computation of snort-time energy.

- window jumps/slides across sequence of squared values, selecting interval for processing
- what happens to $E_{\hat{n}}$ as sequence jumps by 2,4,8,...,L samples ($E_{\hat{n}}$ is a lowpass function—so it can be decimated without lost of information; why is $E_{\hat{n}}$ lowpass?)
- effects of decimation depend on L; if L is small, then $E_{\hat{n}}$ is a lot more variable than if L is large (window bandwidth changes with L!)

Short-Time Energy using RW/HW





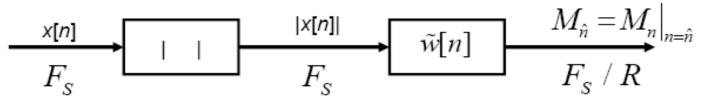
- as L increases, the plots tend to converge (however you are smoothing sound energies)
- short-time energy provides the basis for distinguishing voiced from unvoiced speech regions, and for medium-to-high SNR recordings, can even be used to find regions of silence/background signal

Short-Time Magnitude

- short-time energy is very sensitive to large signal levels due to x²[n] terms
 - consider a new definition of 'pseudo-energy' based on average signal magnitude (rather than energy)

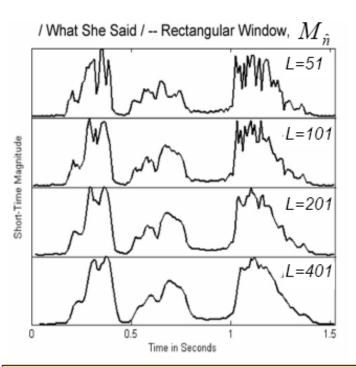
$$M_{\hat{n}} = \sum_{m=-\infty}^{\infty} |x[m]| \tilde{w}[\hat{n}-m]$$

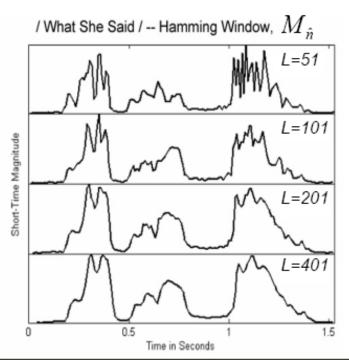
 weighted sum of magnitudes, rather than weighted sum of squares



computation avoids multiplications of signal with itself (the squared term)

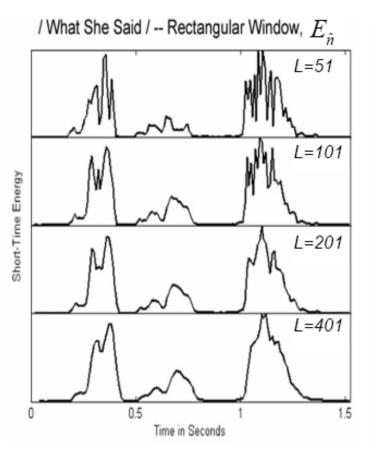
Short-Time Magnitudes

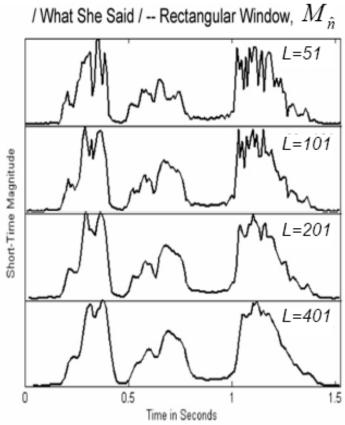




- differences between E_n and M_n noticeable in unvoiced regions
- dynamic range of M_n ~ square root (dynamic range of E_n) => level differences between voiced and unvoiced segments are smaller
- E_n and M_n can be sampled at a rate of 100/sec for window durations of 20 msec or so => efficient representation of signal energy/magnitude

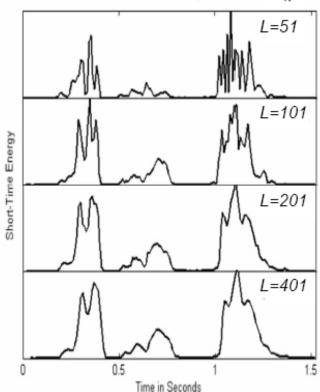
Short Time Energy and Magnitude— Rectangular Window



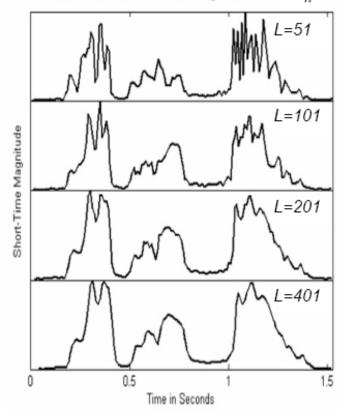


Short Time Energy and Magnitude— Hamming Window

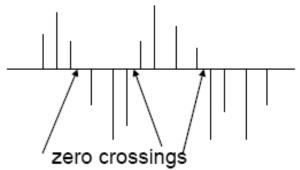




/ What She Said / -- Hamming Window, $M_{\hat{n}}$



Short-Time Average ZC Rate



zero crossing => successive samples have different algebraic signs

- zero crossing rate is a simple measure of the 'frequency content' of a signal—especially true for narrowband signals (e.g., sinusoids)
- sinusoid at frequency F₀ with sampling rate F_S has F_S/F₀ samples per cycle with two zero crossings per cycle, giving an average zero crossing rate of

 z_1 =(2) crossings/cycle x (F_0/F_S) cycles/sample

 $z_1=2F_0/F_S$ crossings/sample (i.e., z_1 proportional to F_0)

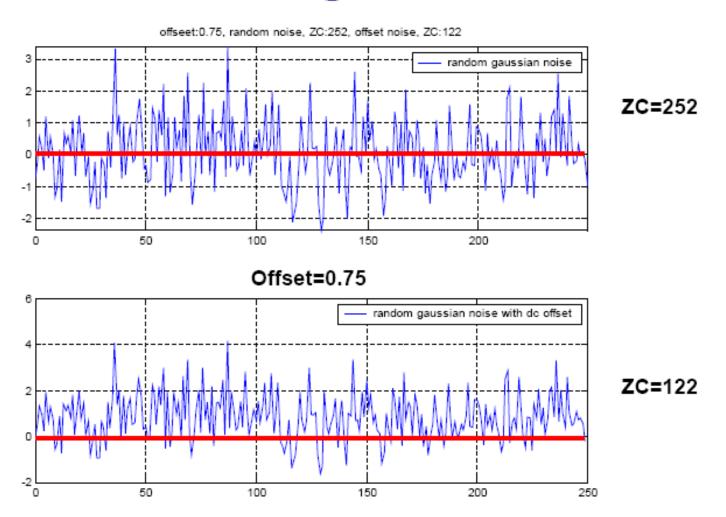
 $z_M = M (2F_0 / F_S)$ crossings/(M samples)

Sinusoid Zero Crossing Rates

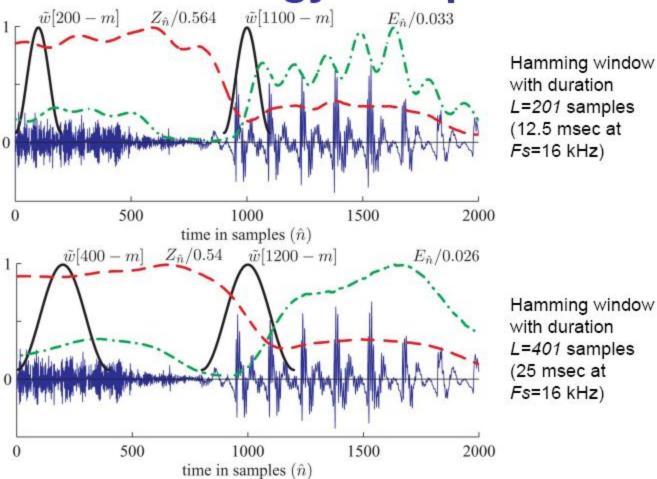
Assume the sampling rate is $F_s = 10,000 \text{ Hz}$

- 1. $F_0 = 100$ Hz sinusoid has F_S / $F_0 = 10,000/100 = 100$ samples/cycle; or $z_1 = 2/100$ crossings/sample, or $z_{100} = 2/100*100 = 2$ crossings/10 msec interval
- 2. $F_0 = 1000$ Hz sinusoid has F_S / $F_0 = 10,000/1000 = 10$ samples/cycle; or $z_1 = 2/10$ crossings/sample, or $z_{100} = 2/10*100 = 20$ crossings/10 msec interval
- 3. $F_0 = 5000$ Hz sinusoid has F_S / $F_0 = 10,000$ / 5000 = 2 samples/cycle; or $z_1 = 2$ / 2 crossings/sample, or $z_{100} = 2$ / 2*100 = 100 crossings/10 msec interval

Zero Crossings for Noise



ZC and Energy Computation



ZC Rate Definitions

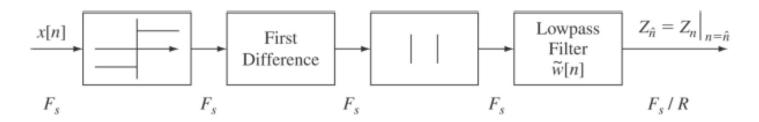
$$Z_{\hat{n}} = \frac{1}{2L_{\text{eff}}} \sum_{m=\hat{n}-L+1}^{\hat{n}} |\operatorname{sgn}(x[m]) - \operatorname{sgn}(x[m-1]) |\tilde{w}[\hat{n}-m]$$

$$\operatorname{sgn}(x[n]) = 1 \qquad x[n] \ge 0$$

$$= -1 \qquad x[n] < 0$$

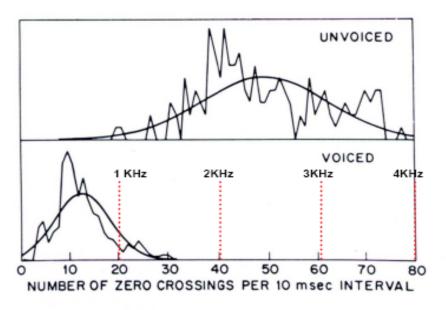
□ simple rectangular window:

$$\tilde{w}[n] = 1$$
 $0 \le n \le L - 1$
= 0 otherwise $L_{\text{eff}} = L$



Same form for $Z_{\hat{n}}$ as for $E_{\hat{n}}$ or $M_{\hat{n}}$

ZC Rate Distributions



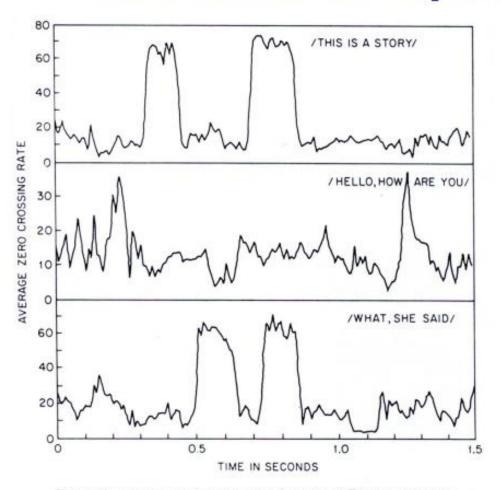
Unvoiced Speech: the dominant energy component is at about 2.5 kHz

Voiced Speech: the dominant energy component is at about 700 Hz

Fig. 4.11 Distribution of zero-crossings for unvoiced and voiced speech.

- for voiced speech, energy is mainly below 1.5 kHz
- for unvoiced speech, energy is mainly above 1.5 kHz
- mean ZC rate for unvoiced speech is 49 per 10 msec interval
- mean ZC rate for voiced speech is 14 per 10 msec interval

ZC Rates for Speech



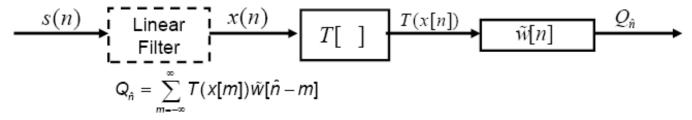
- 15 msec windows
- 100/sec
 sampling rate on
 ZC computation

Fig. 4.12 Average zero-crossing rate for three different utterances.

Issues in ZC Rate Computation

- for zero crossing rate to be accurate, need zero DC in signal => need to remove offsets, hum, noise => use bandpass filter to eliminate DC and hum
- can quantize the signal to 1-bit for computation of ZC rate
- can apply the concept of ZC rate to bandpass filtered speech to give a 'crude' spectral estimate in narrow bands of speech (kind of gives an estimate of the strongest frequency in each narrow band of speech)

Summary of Simple Time Domain Measures



Energy:

$$E_{\hat{n}} = \sum_{m=\hat{n}-L+1}^{\hat{n}} x^2 [m] \tilde{w} [\hat{n} - m]$$

- \square can downsample E_n at rate commensurate with window bandwidth
- 2. Magnitude:

$$M_{\hat{n}} = \sum_{m=\hat{n}-L+1}^{\hat{n}} |x[m]| \tilde{w}[\hat{n}-m]$$

3. Zero Crossing Rate:

$$\begin{split} Z_{\hat{n}} &= z_1 = \frac{1}{2L} \sum_{m=\hat{n}-L+1}^{\hat{n}} \left| \text{sgn}(x[m]) - \text{sgn}(x[m-1]) \right| \tilde{w}[\hat{n}-m] \\ \text{where } \text{sgn}(x[m]) &= 1 \quad x[m] \geq 0 \\ &= -1 \ x[m] < 0 \end{split}$$

Short-Time Autocorrelation

-for a deterministic signal, the autocorrelation function is defined as:

$$\Phi[k] = \sum_{m=-\infty}^{\infty} x[m] x[m+k]$$

-for a random or periodic signal, the autocorrelation function is:

$$\Phi[k] = \lim_{L \to \infty} \frac{1}{(2L+1)} \sum_{m=-L}^{L} x[m]x[m+k]$$

- if x[n] = x[n+P], then $\Phi[k] = \Phi[k+P]$, \Rightarrow the autocorrelation function preserves periodicity
- -properties of $\Phi[k]$:
 - 1. $\Phi[k]$ is even, $\Phi[k] = \Phi[-k]$
 - 2. $\Phi[k]$ is maximum at k = 0, $|\Phi[k]| \le \Phi[0]$, $\forall k$
 - 3. Φ [0] is the signal energy or power (for random signals)

Periodic Signals

- for a periodic signal we have (at least in theory) Φ[P]=Φ[0] so the period of a periodic signal can be estimated as the first non-zero maximum of Φ[k]
 - this means that the autocorrelation function is a good candidate for speech pitch detection algorithms
 - it also means that we need a good way of measuring the short-time autocorrelation function for speech signals

Short-Time Autocorrelation

- a reasonable definition for the short-time autocorrelation is:

$$R_{\hat{n}}[k] = \sum_{m=-\infty}^{\infty} x[m] \, \tilde{w}[\hat{n} - m] \, x[m+k] \, \tilde{w}[\hat{n} - k - m]$$

- select a segment of speech by windowing
- 2. compute deterministic autocorrelation of the windowed speech

$$R_{\hat{n}}[k] = R_{\hat{n}}[-k]$$
 - symmetry
= $\sum_{m=-\infty}^{\infty} x[m]x[m-k] \left[\tilde{w}[\hat{n}-m]\tilde{w}[\hat{n}+k-m]\right]$

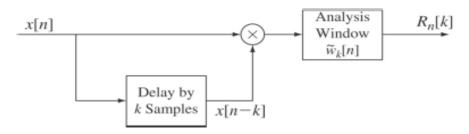
- define filter of the form

$$\tilde{W}_k[\hat{n}] = \tilde{W}[\hat{n}] \tilde{W}[\hat{n} + k]$$

- this enables us to write the short-time autocorrelation in the form:

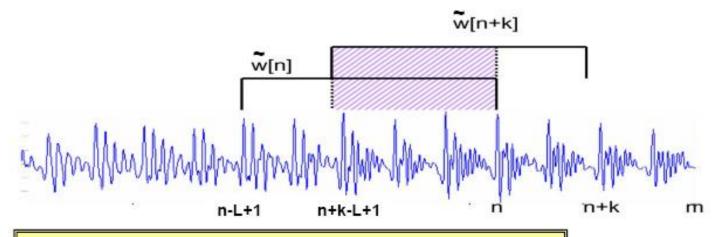
$$R_{\hat{n}}[k] = \sum_{m=-\infty}^{\infty} x[m] x[m-k] \tilde{w}_{k}[\hat{n}-m]$$

- the value of $\tilde{w}_{\hat{n}}[k]$ at time \hat{n} for the k^{th} lag is obtained by filtering the sequence $x[\hat{n}]x[\hat{n}-k]$ with a filter with impulse response $\tilde{w}_{k}[\hat{n}]$



Short-Time Autocorrelation

$$R_{\hat{n}}[k] = \sum_{m=-\infty}^{\infty} \left[x[m] \tilde{w}[\hat{n} - m] \right] \left[x[m+k] \tilde{w}[\hat{n} + k - m] \right]$$



- $\Rightarrow L$ points used to compute $R_{\hat{a}}[0]$;
- $\Rightarrow L k$ points used to compute $R_{\hat{n}}[k]$;

Examples of Autocorrelations

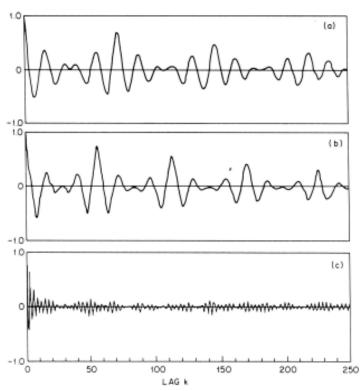


Fig. 4.24 Autocorrelation function for (a) and (b) voiced speech; and (c) unvoiced speech, using a rectangular window with N=401.

- autocorrelation peaks occur at k=72, 144, ... => 140 Hz pitch
- Φ(P)<Φ(0) since windowed speech is not perfectly periodic
- over a 401 sample window (40 msec of signal), pitch period changes occur, so P is not perfectly defined

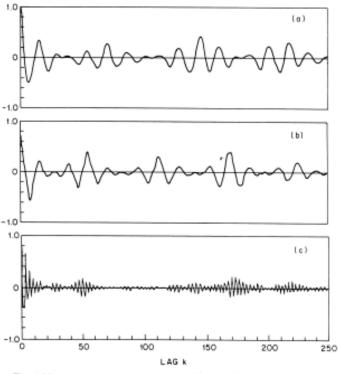
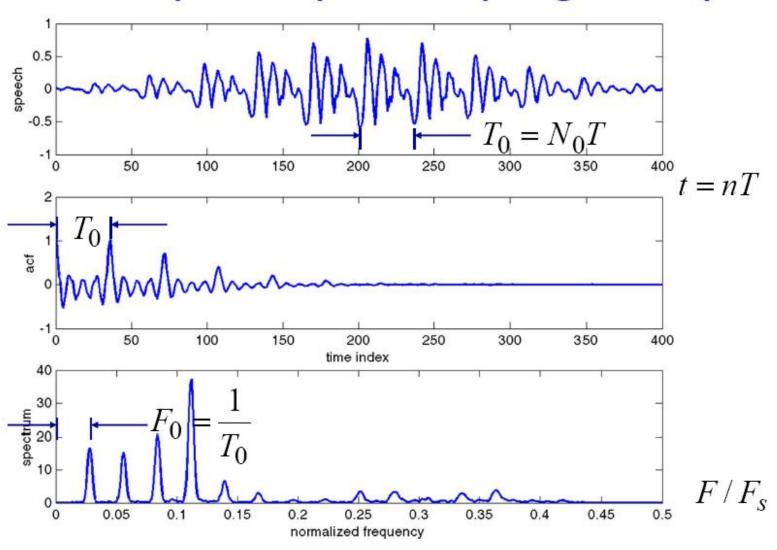


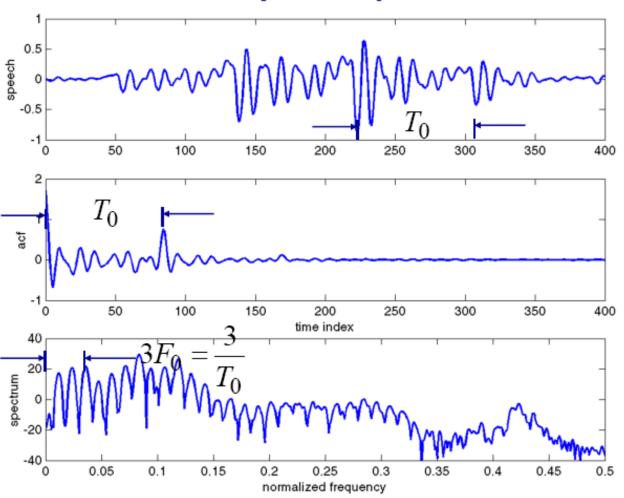
Fig. 4.25 Autocorrelation functions for (a) and (b) voiced speech; and (c) unvoiced speech, using a Hamming window with N = 401.

- much less clear estimates of periodicity since HW tapers signal so strongly, making it look like a non-periodic signal
- · no strong peak for unvoiced speech

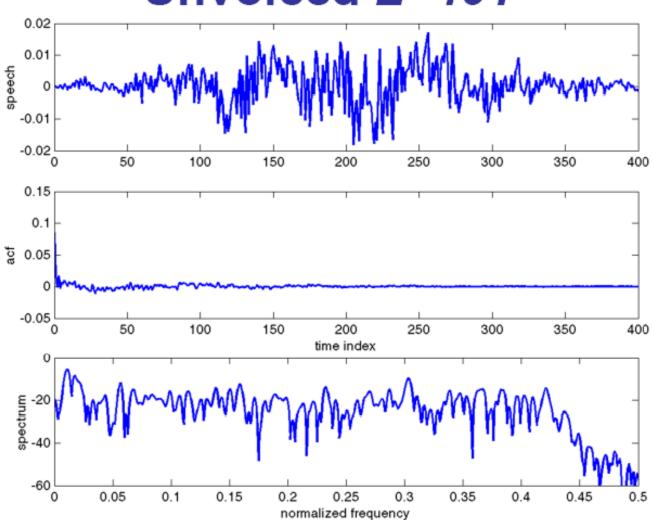
Voiced (female) L=401 (magnitude)



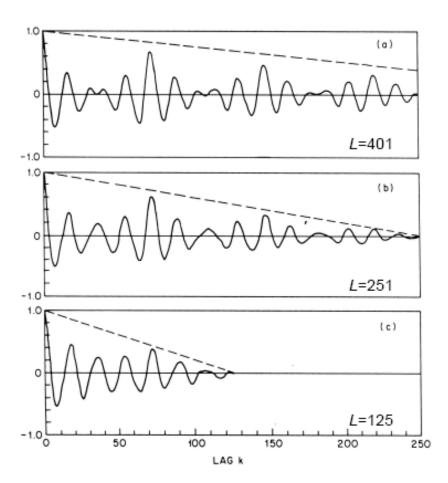
Voiced (male) *L*=401







Effects of Window Size



- choice of L, window duration
 - small L so pitch period almost constant in window
 - large L so clear periodicity seen in window
 - as k increases, the number of window points decrease, reducing the accuracy and size of $R_n(k)$ for large k => have a taper of the type R(k)=1-k/L, |k|<L shaping of autocorrelation (this is the autocorrelation of size L rectangular window)
- allow L to vary with detected pitch periods (so that at least 2 full periods are included)

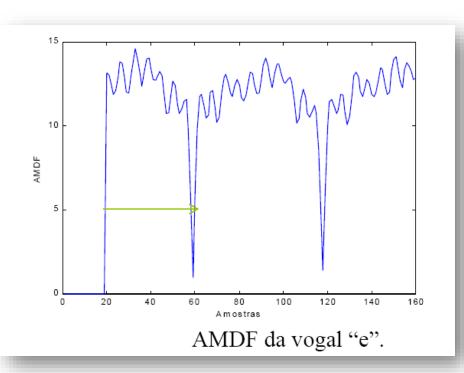
AMDF

AMDF - Average Magnitude Difference Function

O Diferença entre o sinal original e o sinal deslocado de τ amostras.

$$AMDF(\tau) = \frac{1}{N} \sum_{j=1}^{k} |s(j) - s(j + \tau)|,$$

AMDF - Exemplo



- Para o cálculo do pitch, usa-se a janela retangular, filtra passa-baixas em 800 Hz, para eliminar sinais de alta frequência.
- Identifica se o sinal é vozeado ou não.
- Identifica os valores mínimos da AMDF.

AMDF

A AMDF considera a idéia de que se o sinal (neste trabalho o sinal de voz), s(n), é periódico de período P, a seqüência d(n), definida como [2]

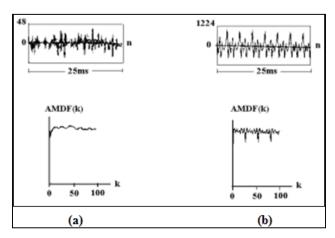
$$d(n) = s(n) - s(n+k),$$

é zero para $k=0,+P,-P,+2P,-2P,\ldots$

Tomando-se pequenos intervalos do sinal, correspondentes à voz, d(n) será mínimo a intervalos múltiplos do período mas, dificilmente, será zero.

A definição da AMDF é dada pela equação

$$AMDF(k) = \frac{1}{F} \sum_{n=0}^{k_{max}-1} |s(n) - s(n+k)|, \qquad k = 0, 1, 2, ..., k_{max}.$$



O período de pitch será o primeiro mínimo da função AMDF>

AMDF para segmento (a) surdo; (b) sonoro.

Short-Time AMDF

- belief that for periodic signals of period P, the difference function d[n] = x[n] x[n-k]
- will be approximately zero for $k=0,\pm P,\pm 2P,...$ For realistic speech signals, d[n] will be small at k=P--but not zero. Based on this reasoning. the short-time Average Magnitude Difference Function (AMDF) is defined as:

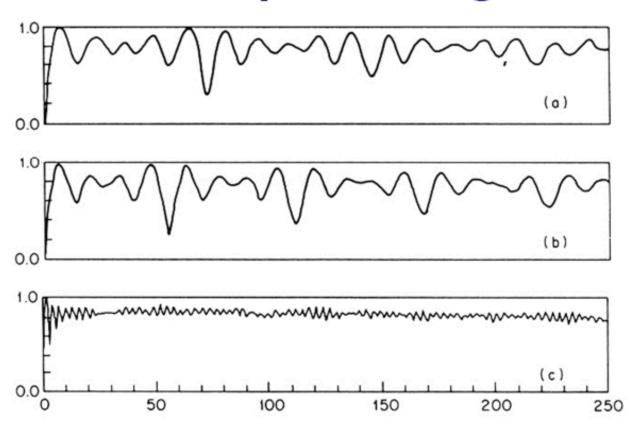
$$\gamma_{\hat{n}}[k] = \sum_{m=-\infty}^{\infty} |x[\hat{n}+m]\tilde{w}_1[m] - x[\hat{n}+m-k]\tilde{w}_2[m-k]|$$

- with $\tilde{w}_1[m]$ and $\tilde{w}_2[m]$ being rectangular windows. If both are the same length, then $\gamma_{\hat{n}}[k]$ is similar to the short-time autocorrelation, whereas if $\tilde{w}_2[m]$ is longer than $\tilde{w}_1[m]$, then $\gamma_{\hat{n}}[k]$ is similar to the modified short-time autocorrelation (or covariance) function. In fact it can be shown that

$$\gamma_{\hat{n}}[k] \approx \sqrt{2}\beta[k] \left[\hat{R}_{\hat{n}}[0] - \hat{R}_{\hat{n}}[k]\right]^{1/2}$$

-where $\beta[k]$ varies between 0.6 and 1.0 for different segments of speech.

AMDF for Speech Segments



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