Body + Body() + void attach() + void detach() + int refCount() + virtual ~Body() ModelBody # string name # int clock # vector< System * > systems # vector< Flow * > flows # static vector< Model * > models + ModelBody(const string &name="", const int &clock=0) + virtual ~ModelBody() + System & createSystem (const string &name="" const double &value=0.0) FlowBody + bool add(System *s) # System * source + bool add(Flow *f) # System * target + bool remove(System *s) + FlowBody() + bool remove(Flow *f) + FlowBody(System *source, + void eraseModel(Model System *target) ::modelsIterator m) + bool run(int startTime, + FlowBody(const Flow &f) int finalTime) + virtual ~FlowBody() + void reportStatus() + void setSource(System *s) + void setName(const + System * getSource string &name) () const + string getName() const + void setTarget(System *s) + void setClock(const + System * getTarget int &clock) () const + int getClock() const + virtual double executeEquation()=0 + Model::systemsIterator systemsBegin() + Model::systemsIterator systemsEnd() + Model::flowsIterator flowsBegin() + Model::flowsIterator flowsEnd() + Model::modelsIterator modelsBegin() + Model::modelsIterator modelsEnd() + static Model & createModel (const string &name="", const int &clock=0) Exponential Logistic Complex + Exponential() + Complex() + Logistic() + Exponential(System + Complex(System *source, + Logistic(System *source, *source, System *target) System *target) System *target) Exponential(const + Complex(const Flow &f) + Logistic(const Flow &f) Flow &f) + double executeEquation() + double executeEquation() + double executeEquation()

SystemBody

- # string name
- # double value
- + SystemBody(const string &name="", const double &value=0.0)
- + SystemBody(const System &s)
- + virtual ~SystemBody()
- + void setName(const string &name)
- + string getName() const
- + void setValue(const double &value)
- + double getValue() const