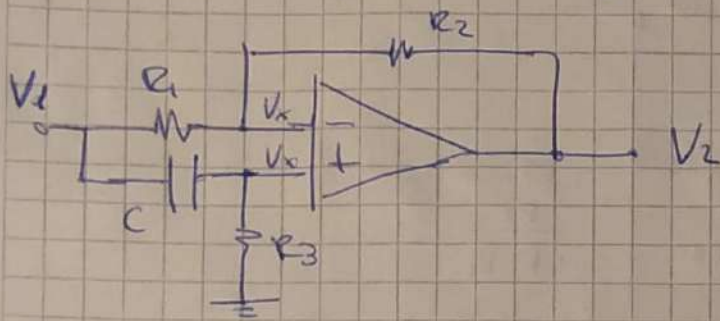


TS 1 (Eger 2 TPL)



$$V^+ = V^- = V_x$$

$$I_{R1} = I_{R2}$$

$$I_c = I_{e3}$$

$$\frac{V_1 - V_x}{R_1} = \frac{V_x - V_2}{R_2}$$

$$(V_1 - V_x) s_c = \frac{V_x}{R_3}$$

$$\frac{V_1}{R_1} - \frac{V_x}{R_1} = \frac{V_x}{R_2} - \frac{V_2}{R_2}$$

$$V_1 s_c = V_x \left(\frac{1}{R_3} + s_c \right) = V_x \left(\frac{s_c R_3 + 1}{R_3} \right)$$

$$V_1 = V_x \left(1 + \frac{1}{s_c R_3} \right)$$

$$\frac{V_1}{R_1} - \frac{V_1}{R_1 + \frac{R_1}{s_c R_3}} - \frac{V_1}{R_2 + \frac{R_2}{s_c R_3}} = -\frac{V_2}{R_2}$$

$$\frac{V_1}{1 + \frac{1}{s_c R_3}} = V_x = V_1 \cdot \frac{s_c R_3}{s_c R_3 + 1}$$

$$\frac{1}{V_1} \left(-\frac{R_2}{R_1} + \frac{R_2}{R_1 + \frac{R_1}{s_c R_3}} + \frac{R_2}{R_2 + \frac{R_2}{s_c R_3}} \right) = \frac{V_2}{V_1}$$

$$\frac{V_1}{R_1} - \frac{V_x}{R_1} = \frac{V_x}{R_2} - \frac{V_2}{R_2}$$

$$\frac{V_2}{R_2} = \frac{V_x}{R_1} + \frac{V_x}{R_2} - \frac{V_1}{R_1}$$

$$\frac{V_2}{R_2} = V_1 \left[\frac{s_c R_3}{s_c R_3 R_1 + R_1} + \frac{s_c R_3}{s_c R_3 R_2 + R_2} - \frac{1}{R_1} \right]$$

$$-\frac{R_2}{R_1} + \frac{R_2}{s_c R_3 R_1 + R_1} + \frac{1}{\frac{s_c R_3 + 1}{s_c R_3}} = \frac{V_2}{V_1}$$

$$-\frac{R_2}{R_1} + \frac{s_c R_3 R_2}{s_c R_3 R_1 + R_1}$$

$$\frac{V_2}{V_1} = \frac{s_c R_3 R_2}{s_c R_3 R_1 + R_1} + \frac{s_c R_3 R_1}{s_c R_3 R_2 + R_2} - \frac{R_2}{R_1}$$

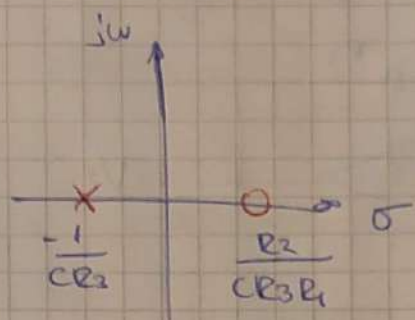
$$\frac{V_2}{V_1} = \frac{s_c R_3 R_2}{s_c R_3 R_1 + R_1} + \frac{s_c R_3 R_1}{s_c R_3 R_2 + R_2} - \frac{s_c R_3 + R_2}{s_c R_3 R_1 + R_1}$$

$$\frac{V_2}{V_1} = \frac{s_c R_3 R_2 - R_2}{s_c R_3 R_1 + R_1} = \frac{s - \frac{R_2}{c R_3 R_1}}{s + \frac{1}{c R_3}}$$

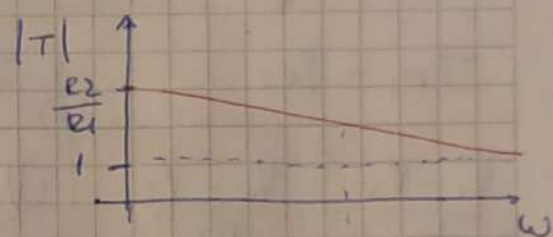
$$T = \frac{V_2}{V_1} = \frac{S - \frac{R_2}{CR_3 R_1}}{S + \frac{1}{CR_3}}$$

para Cero: $S = \frac{R_2}{CR_3 R_1}$
 polo: $S = -\frac{1}{CR_3}$

$$T(j\omega) = \frac{j\omega - \frac{R_2}{CR_3 R_1}}{j\omega + \frac{1}{CR_3}}$$

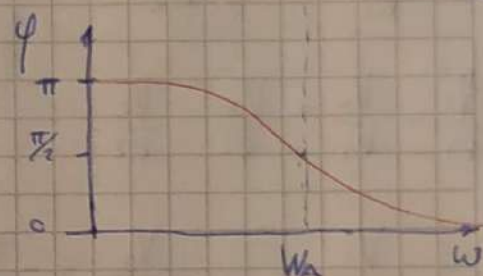


$$|T(j\omega)| = \frac{\sqrt{\omega^2 + \left(\frac{R_2}{CR_3 R_1}\right)^2}}{\sqrt{\omega^2 + \left(\frac{1}{CR_3}\right)^2}}$$



$$\varphi(\omega) = \arctan\left(\frac{\omega}{-\frac{R_2}{CR_3 R_1}}\right) - \arctan\left(\frac{\omega}{\frac{1}{CR_3}}\right)$$

$$\varphi(\omega) = \arctan\left(\frac{\omega CR_3 R_1}{-R_2}\right) - \arctan(\omega CR_3)$$



2) transferencia normalizada

$$T = \frac{SCR_3 - \frac{R_2}{R_1}}{SCR_3 + 1} = \frac{s - \frac{R_2}{R_1}}{s + 1}$$

$$s = SCR_3 = \frac{s}{\frac{1}{CR_3}} = \frac{s}{\omega_A}$$

$$\omega_A = C \cdot \frac{1}{CR_3} = \frac{1}{R_3} = C \omega_A$$

$$\omega_A = \frac{1}{CR_3}$$

Solo uso por frec. no veo beneficio
 en usar impedancia tambien
 aunque se podría usar $R_3=1$

ω_A es la frecuencia a la que la Fase es $\pi/2$ si $R_2=R_1$

El circuito sirve para corregir cominientos de fase y
 evitar la distorsión por retardo.