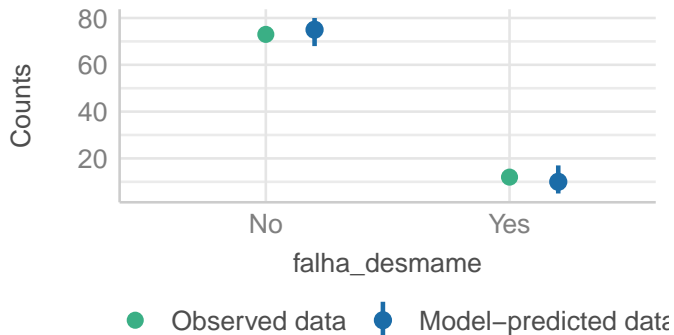


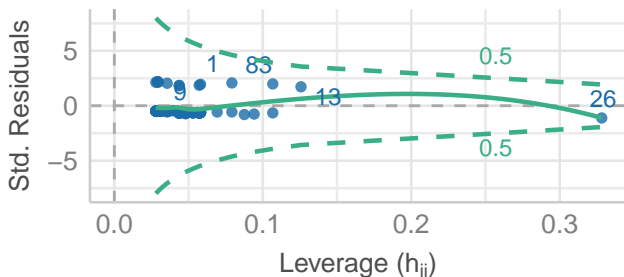
Posterior Predictive Check

Model-predicted intervals should include observed data



Influential Observations

Points should be inside the contour lines



Collinearity

High collinearity (VIF) may inflate parameter uncertainty

