

QUBO.jl



A tale of implementation and benchmarking of a Quantum Optimization Ecosystem in Julia

Pedro Maciel Xavier

[PRESENTER]



Purdue University
Federal University of Rio de Janeiro

ISMP 2024 □ July 22, 2024 □ Montreal, Canada



Pedro Rippert
PUC-Rio, PSR



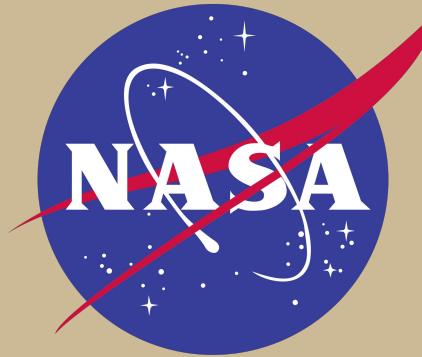
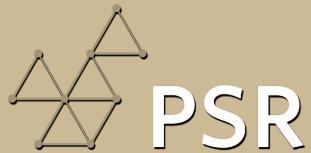
Joaquim Diás Caroia
PSR



Nelson Maculan
UFRJ



David E. Bernal Neira
Purdue University
USRA
NASA Quantum AI Lab



QUBO: Quadratic Unconstrained Binary Optimization

$$\begin{array}{ll} \min & \mathbf{x}' \mathbf{Q} \mathbf{x} + \boldsymbol{\ell}' \mathbf{x} + c \\ \text{s.t.} & \mathbf{x} \in \{0, 1\}^n \end{array}$$

OBJECTIVE FUNCTION
BINARY VARIABLES

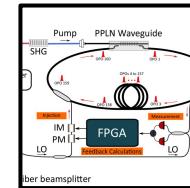
QUBO: Quadratic Unconstrained Binary Optimization

$$\min \quad \mathbf{x}' \mathbf{Q} \mathbf{x} + \ell' \mathbf{x} + c$$

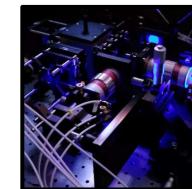
OBJECTIVE FUNCTION

$$\text{s.t. } \mathbf{x} \in \{0, 1\}^n$$

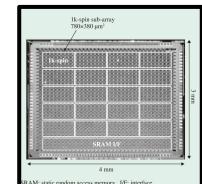
BINARY VARIABLES



P. L. McMahon et al., 2016

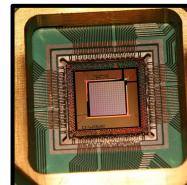


Microsoft Research

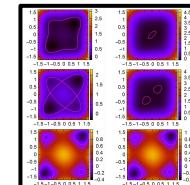


Hitachi, Yamaoka et al.

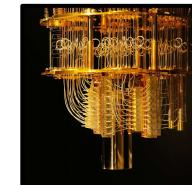
Quantum Variational Annealing, Digital Annealing, Quantum Eigensolver, Quantum Coherent Ansatz, Iterative Machine, CMOS
Variational Alternating Optimization Ising Machine, Analog Bifurcation Simulated Annealing...
Annealing, Bifurcation



D-Wave



Toshiba, Goto et al., 2019



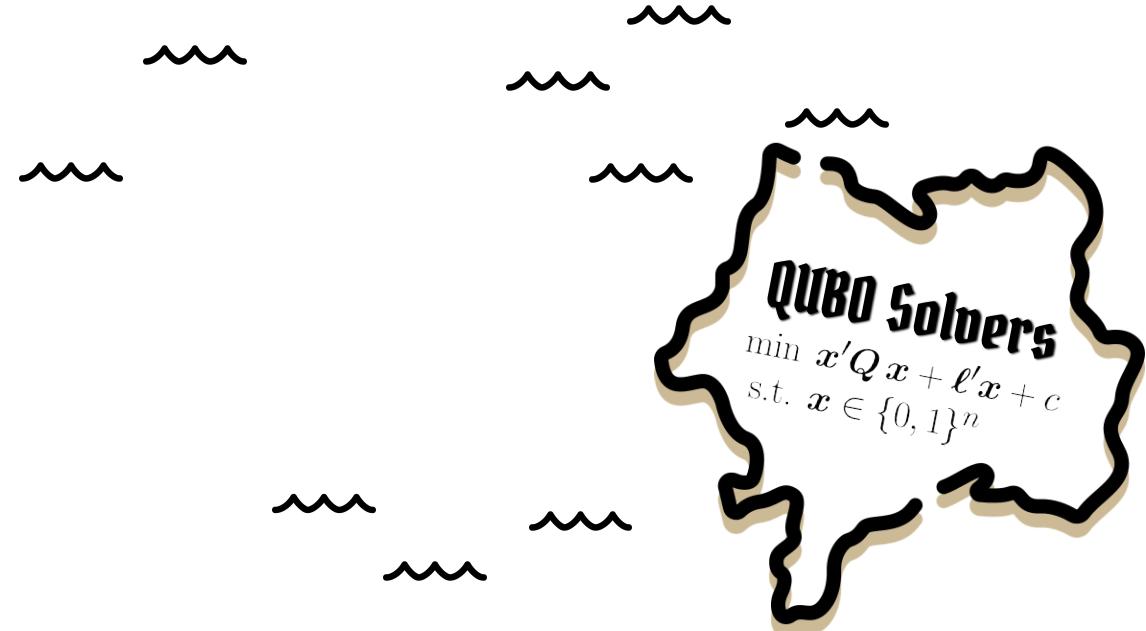
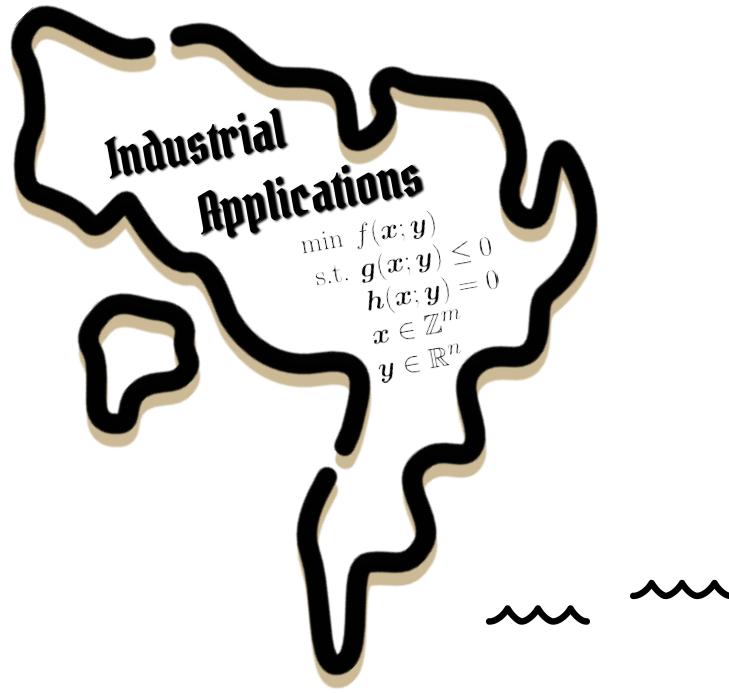
IBM



Fujitsu



Our Goal





Our Goal





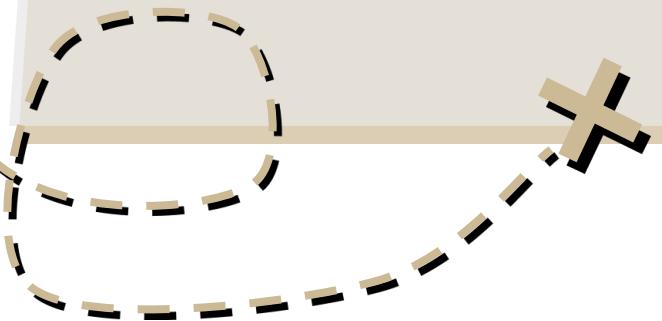
Tasks



Tasks

Access Solvers

- Common software Interface





Tasks

Access Solvers

- Common software Interface

Reformulate Models

- Mathematical Programming Compiler

Solution Overview

JuMP Model
(MINLP)

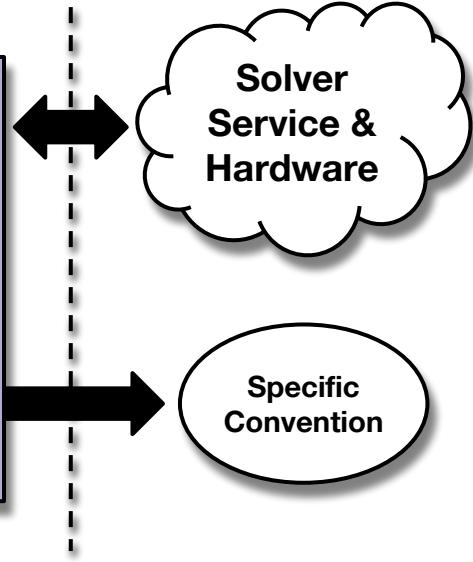
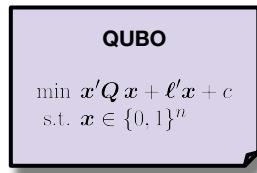
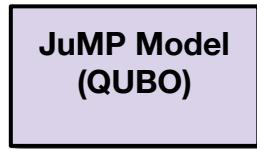
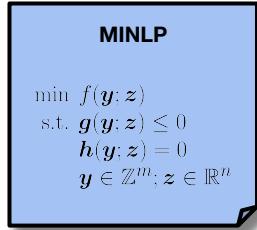
MINLP

$$\begin{aligned} & \min f(\mathbf{y}; \mathbf{z}) \\ \text{s.t. } & g(\mathbf{y}; \mathbf{z}) \leq 0 \\ & h(\mathbf{y}; \mathbf{z}) = 0 \\ & \mathbf{y} \in \mathbb{Z}^m, \mathbf{z} \in \mathbb{R}^n \end{aligned}$$

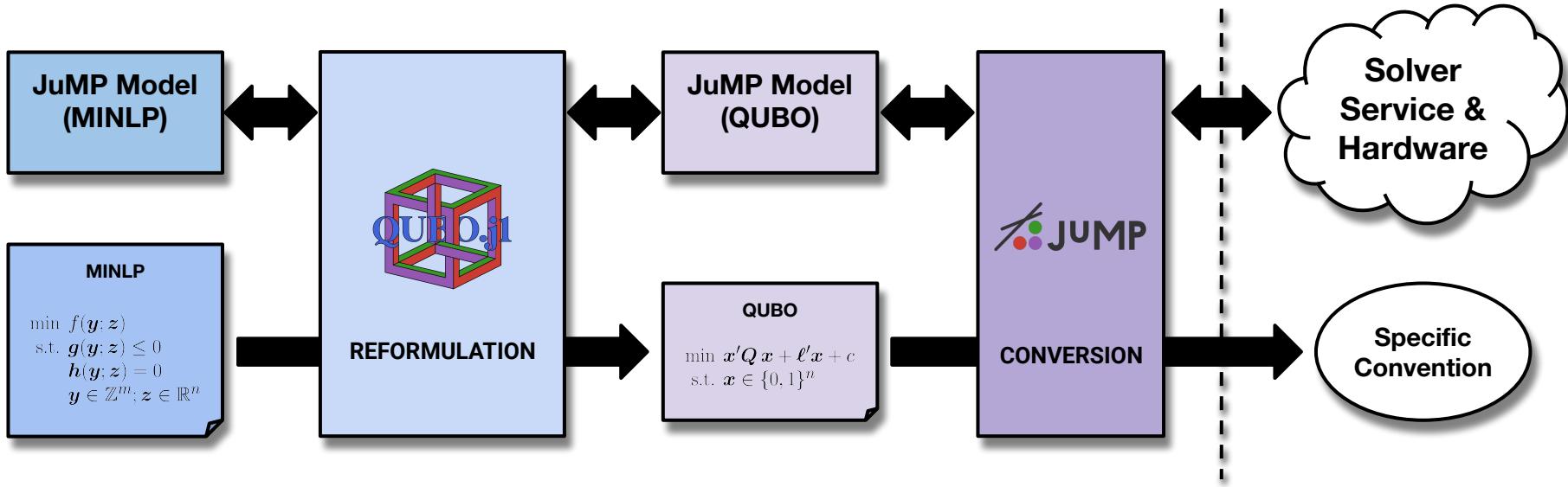
Solver
Service &
Hardware

Specific
Convention

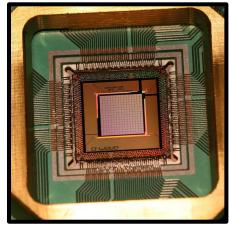
Solution Overview



Solution Overview



Integrating an heterogeneous Solver Landscape



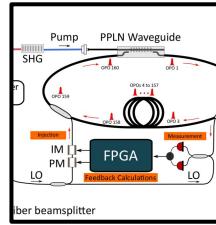
D-Wave



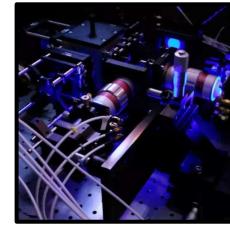
Fujitsu



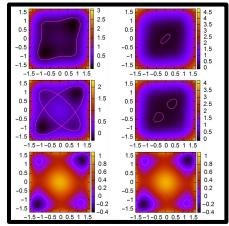
IBM



P. L. McMahon et al., 2016

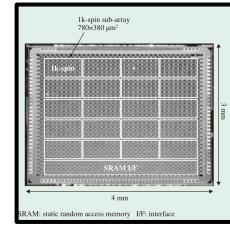


Microsoft Research



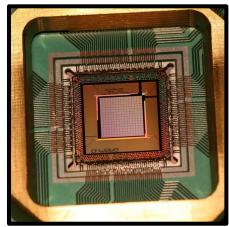
Toshiba, Goto et al., 2019

Quantum Annealing, Digital Annealing, Variational Quantum Eigensolver, Quantum Alternating Optimization Ansatz, Coherent Ising Machine, Analog Iterative Machine, Simulated Bifurcation Machine, CMOS Annealing...



Hitachi, Yamaoka et al.

Integrating an heterogeneous Solver Landscape



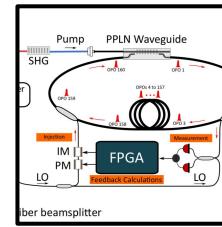
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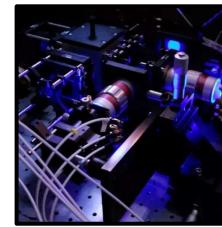
Fujitsu



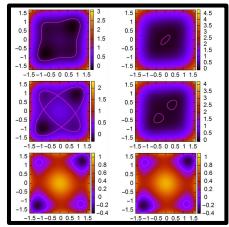
IBM



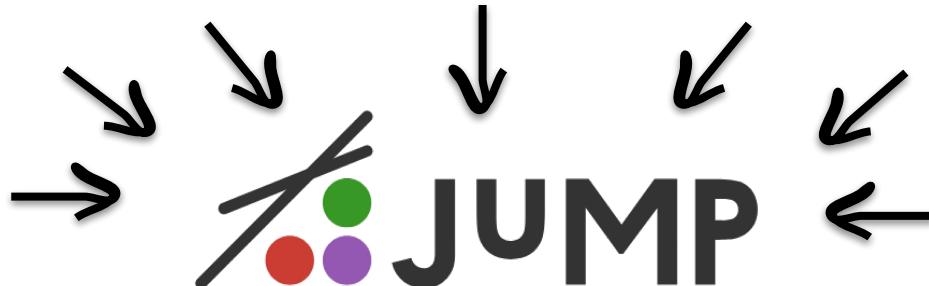
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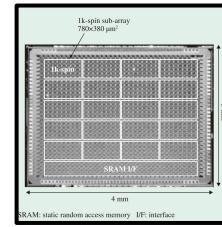
Microsoft Research



Toshiba, Goto et al., 2019



Julia Mathematical Programming



Hitachi, Yamaoka et al.

A Common Solver Interface



```
using JuMP
using QiskitOpt # IBM Qiskit Optimization

model = Model(QiskitOpt.QAOA.Optimizer)

@variable(model, x[1:n], Bin)
@objective(
    model,
    Min,
    x' * Q * x + ℓ' * x + c
)

optimize!(model)

@show objective_value(model)
@show value.(x)
```

```
using JuMP
using DWave # DWave Quantum Annealing

model = Model(DWave.Optimizer)

@variable(model, x[1:n], Bin)
@objective(
    model,
    Min,
    x' * Q * x + ℓ' * x + c
)

optimize!(model)

@show objective_value(model)
@show value.(x)
```

```
using JuMP
using PySA # NASA Parallel Tempering

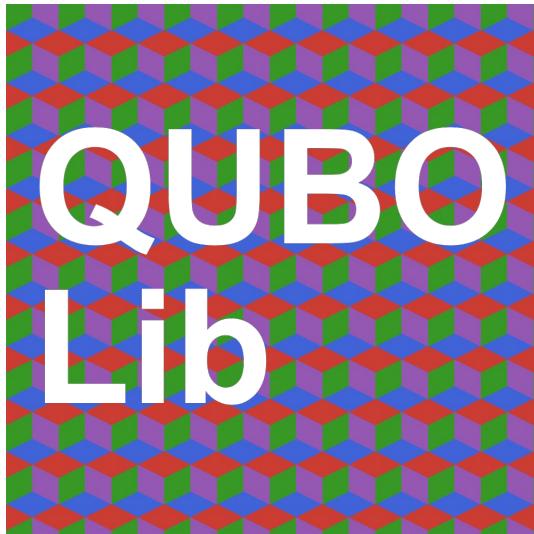
model = Model(PySA.Optimizer)

@variable(model, x[1:n], Bin)
@objective(
    model,
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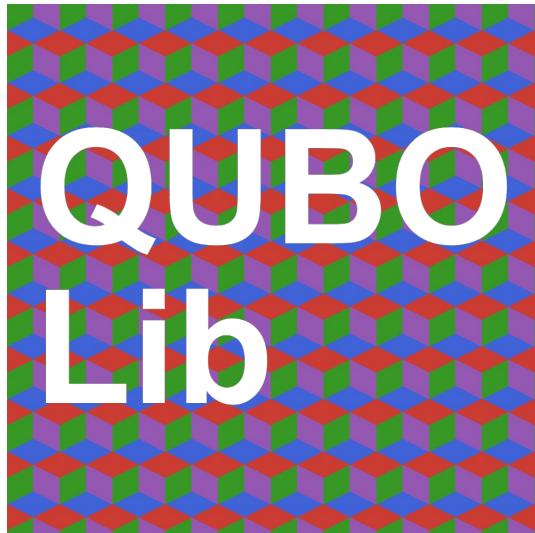
optimize!(model)

@show objective_value(model)
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```

Testing and Benchmarking Solvers



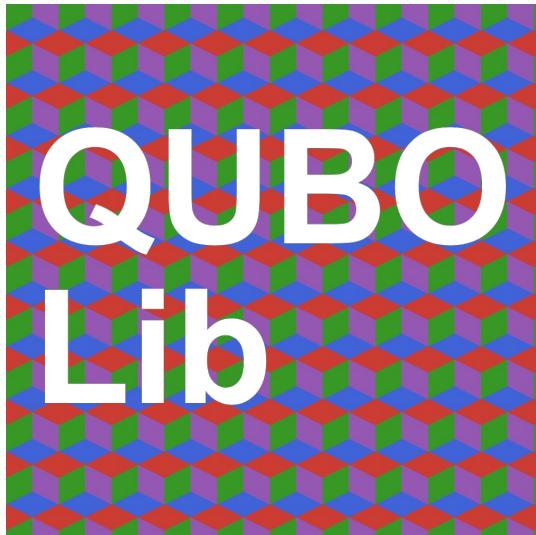
Testing and Benchmarking Solvers



Sources Summary		
Collection	Instances	Size Range
arXiv:2103.008464 (3R3X)	2300	16 - 4096
arXiv:1903.100928 (3R3X)	3200	16 - 4096
arXiv:1903.100928 (5R5X)	307	24 - 24576
qplib*	23	120 - 1225

*QPLIB: A Library of Quadratic Programming Instances, Mathematical Programming Computation, 2018

Testing and Benchmarking Solvers



```
● ● ●

QUBOLib.load_index() do index
    db = QUBOLib.database(index)
    df = DBInterface.execute(
        db,
        """
        SELECT instance FROM Instances
        WHERE dimension < 100 AND quadratic_density < 0.5;
        """,
        ) |> DataFrame

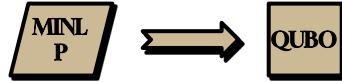
    codes = collect(Int, df[!, :instance])

    @info "Running DWave Neural"
    QUBOLib.run!(
        index, DWave.Neal.Optimizer, codes; solver = "dwave-neal"
    )

    @info "Running DWave (Quantum)"
    QUBOLib.run!(
        index, DWave.Optimizer, codes; solver = "dwave"
    )
end
```



$$\begin{aligned} \min \quad & f(\mathbf{y}; \mathbf{z}) \\ \text{s.t. } & g_i(\mathbf{y}; \mathbf{z}) \in S_i \\ & \mathbf{y} \in \mathbb{Z}^m; \mathbf{z} \in \mathbb{R}^n \end{aligned}$$



VARIABLE ENCODING

$$\begin{aligned} \min \quad & f(\mathbf{y}; \mathbf{z}) \\ \text{s.t. } & g_i(\mathbf{y}; \mathbf{z}) \in S_i \\ & \mathbf{y} \in \mathbb{Z}^m; \mathbf{z} \in \mathbb{R}^n \end{aligned}$$

$$\begin{aligned} \min \quad & f(\mathbf{x}) \\ \text{s.t. } & g_i(\mathbf{x}) \in S_i \\ & \mathbf{x} \in \{0, 1\}^k \end{aligned}$$



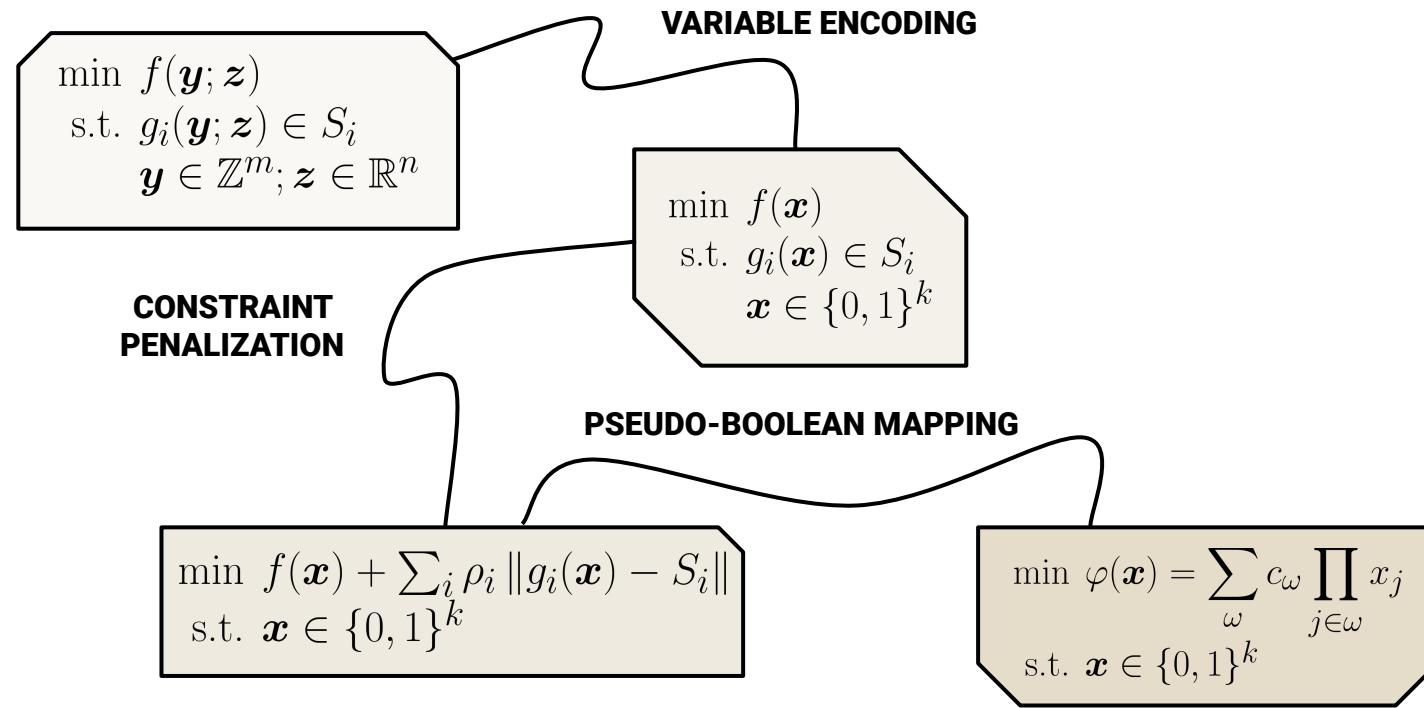
VARIABLE ENCODING

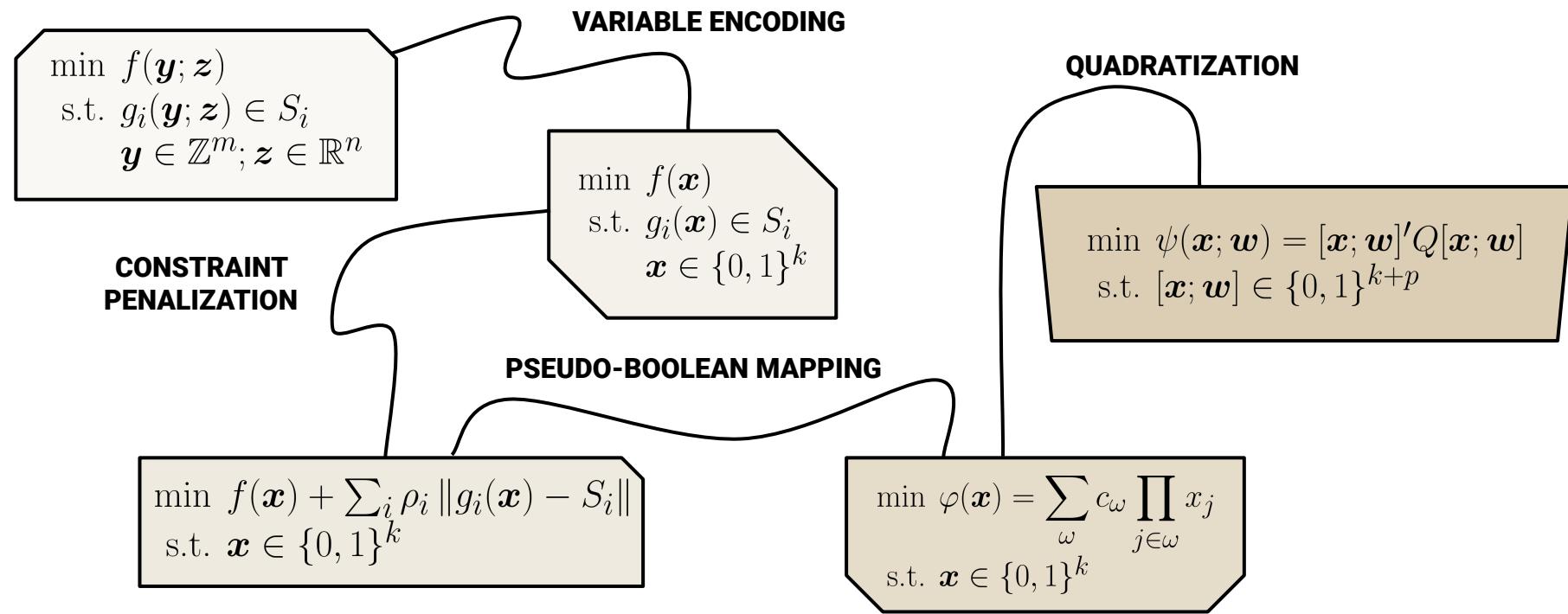
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CONSTRAINT PENALIZATION

$$\begin{aligned} \min \quad & f(\mathbf{x}) + \sum_i \rho_i \|g_i(\mathbf{x}) - S_i\| \\ \text{s.t. } & \mathbf{x} \in \{0, 1\}^k \end{aligned}$$





A Compiler for Mathematical Programming

C, C++, Julia, Rust...

AMPL, JuMP, Pyomo...

A Compiler for Mathematical Programming

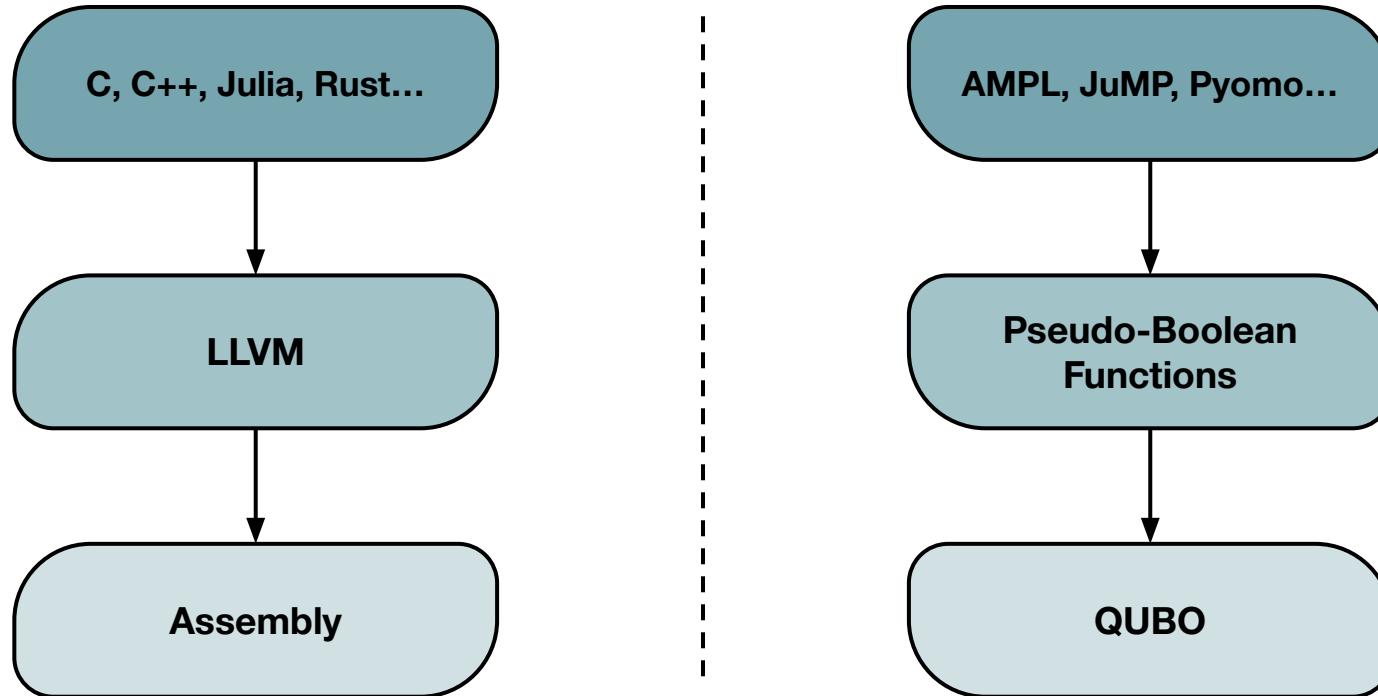
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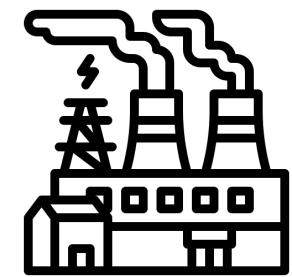
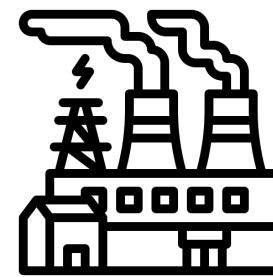
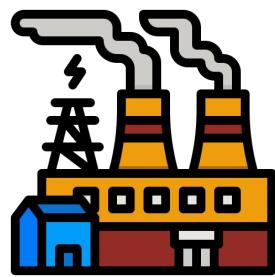
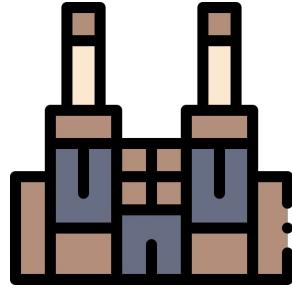
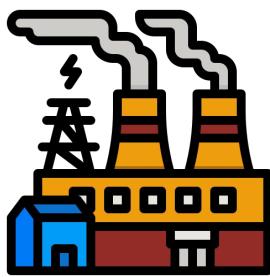
Assembly

QUBO

A Compiler for Mathematical Programming



Example: Generation capacity expansion



Example: Generation capacity expansion

$$\min_{\mathbf{g}, \mathbf{u}, \mathbf{x}} \sum_t \mathbf{c}' \mathbf{g}^{(t)} + \mathbf{i}' \mathbf{x}$$

$$\text{s.a. } \sum_j g_j^{(t)} = d^{(t)} \quad \forall t$$

$$g_j^{(t)} \leq u_j^{(t)} G_j^{\text{(max)}} \quad \forall j, t$$

$$u_j^{(t)} \leq x_j \quad \forall j, t$$

$$g_j^{(t)} \in [0, G_j^{\text{(max)}}] \quad \forall j, t$$

$$u_j^{(t)} \in \{0, 1\} \quad \forall j, t$$

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Example: Generation capacity expansion

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$$\text{s.a. } \sum_j g_j^{(t)} = d^{(t)} \quad \forall t$$

BALANCE

$$g_j^{(t)} \leq u_j^{(t)} G_j^{\max} \quad \forall j, t$$

$$u_j^{(t)} \leq x_j \quad \forall j, t$$

$$g_j^{(t)} \in [0, G_j^{\max}]$$

OPERATION

$$u_j^{(t)} \in \{0, 1\} \quad \forall j, t$$

$$x_j \in \{0, 1\} \quad \forall j$$



Example: Generation capacity expansion

$$\min_{\mathbf{g}, \mathbf{u}, \mathbf{x}} \sum_t \mathbf{c}' \mathbf{g}^{(t)} + \mathbf{i}' \mathbf{x}$$

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UNIT COMMITMENT

$$u_j^{(t)} \leq x_j \quad \forall j, t$$

$$g_j^{(t)} \in [0, G_j^{(\max)}] \quad \forall j, t$$

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UNIT COMMITMENT

$$x_j \in \{0, 1\} \quad \forall j$$



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$$g_j^{(t)} \in [0, G_j^{(\max)}] \quad \text{INVESTMENT} \quad \forall j, t$$

$$u_j^{(t)} \in \{0, 1\} \quad \forall j, t$$

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Example: Generation capacity expansion

$$\begin{array}{ll}\text{min}_{\mathbf{g}, \mathbf{u}, \mathbf{x}} & \text{OPERATION} \quad \text{INVESTMENT} \\ \sum_t \mathbf{c}' \mathbf{g}^{(t)} + \mathbf{i}' \mathbf{x} & \\ \text{s.a. } \sum_j g_j^{(t)} = d^{(t)} & \forall t \quad \text{BALANCE} \\ g_j^{(t)} \leq u_j^{(t)} G_j^{(\max)} & \forall j, t \quad \text{UNIT COMMITMENT} \\ u_j^{(t)} \leq x_j & \forall j, t \quad \text{INVESTMENT} \\ g_j^{(t)} \in [0, G_j^{(\max)}] & \forall j, t \quad \text{OPERATION} \\ u_j^{(t)} \in \{0, 1\} & \forall j, t \quad \text{UNIT COMMITMENT} \\ x_j \in \{0, 1\} & \forall j \quad \text{INVESTMENT}\end{array}$$



Example: Generation capacity expansion

OPERATION	INVESTMENT
$\min_{\mathbf{g}, \mathbf{u}, \mathbf{x}} \sum_t \mathbf{c}' \mathbf{g}^{(t)} + \mathbf{i}' \mathbf{x}$	
s.a. $\sum_j g_j^{(t)} = d^{(t)} \quad \forall t$ <div style="display: flex; justify-content: space-around; width: 100%;"> BALANCE </div>	
$g_j^{(t)} \leq u_j^{(t)} G_j^{(\max)} \quad \forall j, t$ <div style="display: flex; justify-content: space-around; width: 100%;"> UNIT COMMITMENT </div>	
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$x_j \in \{0, 1\} \quad \forall j$ <div style="display: flex; justify-content: space-around; width: 100%;"> INVESTMENT </div>	



REFORMULATION

$$\rho_{balance} \left(\sum_t \left(\sum_j g_j^{(t)} - d^{(t)} \right)^2 \right)$$

$$\rho_{invest} \left(\sum_{j,t} \left(g_j^{(t)} + s_{UB} - x_j G_j^{(\max)} \right)^2 \right)$$

$$g_j^{(t)} = \alpha \sum_k 2^k y_{k,j}^{(t)} \text{ s.t. } y_{k,j}^{(t)} \in \{0, 1\}$$

Example: Generation capacity expansion

OPERATION	INVESTMENT
$\min_{\mathbf{g}, \mathbf{u}, \mathbf{x}} \sum_t \mathbf{c}' \mathbf{g}^{(t)} + \mathbf{i}' \mathbf{x}$	
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$x_j \in \{0, 1\} \quad \forall j$	INVESTMENT



```

1  using JuMP
2  using PySA
3
4  model = Model(PySA.Optimizer)
5
6  @variable(model, 0 ≤ g[1:T,j=1:n] ≤ Gmax[j])
7  @variable(model, u[1:T,1:n], Bin)
8  @variable(model, x[1:n], Bin)
9
10 @objective(model, Min, sum(c'g[t,:] for t=1:T) + i'x)
11
12 @constraint(model, [t=1:T], sum(g[t,:]) = d[t])
13 @constraint(model, [t=1:T,j=1:n], g[t,j] ≤ u[t,j] * Gmax[j])
14 @constraint(model, [t=1:T,j=1:n], u[t,j] ≤ x[j])
15
16 optimize!(model)
17
18 @show objective_value(model)
19 @show value.(x)

```

snappyf.com

Example: Generation capacity expansion

OPERATION	INVESTMENT
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```

snappyf.com

Example: Generation capacity expansion

OPERATION	INVESTMENT
$\min_{\mathbf{g}, \mathbf{u}, \mathbf{x}} \sum_t \mathbf{c}' \mathbf{g}^{(t)} + \mathbf{i}' \mathbf{x}$	
	BALANCE
s.a. $\sum_j g_j^{(t)} = d^{(t)} \quad \forall t$	
	UNIT COMMITMENT
$g_j^{(t)} \leq u_j^{(t)} G_j^{(\max)} \quad \forall j, t$	
	INVESTMENT
$u_j^{(t)} \leq x_j \quad \forall j, t$	
	OPERATION
$g_j^{(t)} \in [0, G_j^{(\max)}] \quad \forall j, t$	
	UNIT COMMITMENT
$u_j^{(t)} \in \{0, 1\} \quad \forall j, t$	
	INVESTMENT
$x_j \in \{0, 1\} \quad \forall j$	



```

1  using JuMP
2  using PySA
3
4  model = Model(PySA.Optimizer)

6  @variable(model, 0 ≤ g[1:T,j=1:n] ≤ Gmax[j])
7  @variable(model, u[1:T,1:n], Bin)
8  @variable(model, x[1:n], Bin)
9
10 @objective(model, Min, sum(c'g[t,:] for t=1:T) + i'x)
11
12 @constraint(model, [t=1:T], sum(g[t,:]) = d[t])
13 @constraint(model, [t=1:T,j=1:n], g[t,j] ≤ u[t,j] * Gmax[j])
14 @constraint(model, [t=1:T,j=1:n], u[t,j] ≤ x[j])
15
16 optimize!(model)
17
18 @show objective_value(model)
19 @show value.(x)

```

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Example: Generation capacity expansion

OPERATION	INVESTMENT
$\min_{\mathbf{g}, \mathbf{u}, \mathbf{x}} \sum_t \mathbf{c}' \mathbf{g}^{(t)} + \mathbf{i}' \mathbf{x}$	
	BALANCE
s.a. $\sum_j g_j^{(t)} = d^{(t)} \quad \forall t$	
	UNIT COMMITMENT
$g_j^{(t)} \leq u_j^{(t)} G_j^{(\max)} \quad \forall j, t$	
	INVESTMENT
$u_j^{(t)} \leq x_j \quad \forall j, t$	
	OPERATION
$g_j^{(t)} \in [0, G_j^{(\max)}] \quad \forall j, t$	
	UNIT COMMITMENT
$u_j^{(t)} \in \{0, 1\} \quad \forall j, t$	
	INVESTMENT
$x_j \in \{0, 1\} \quad \forall j$	



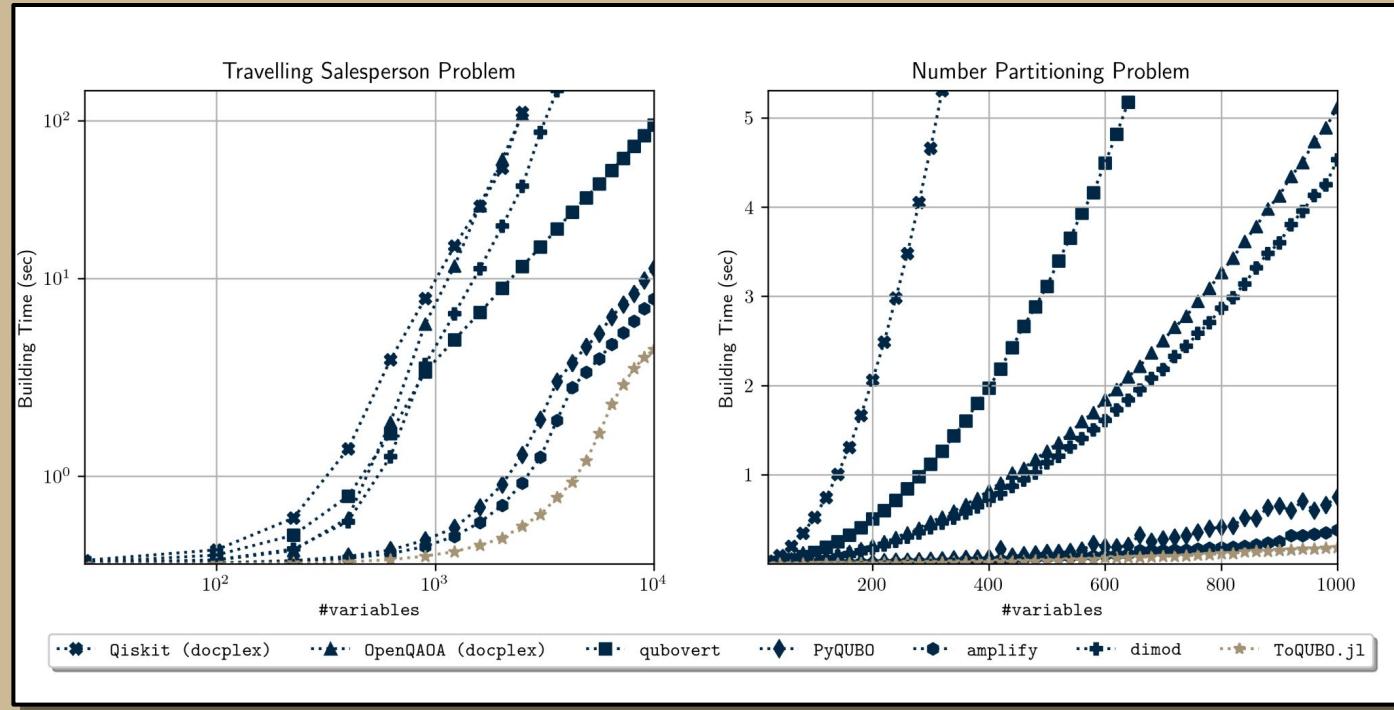
```

1 using JuMP, QUBO
2 using PySA
3
4 model = Model() → ToQUBO.Optimizer(PySA.Optimizer))
5
6 @variable(model, 0 ≤ g[1:T,j=1:n] ≤ Gmax[j])
7 @variable(model, u[1:T,1:n], Bin)
8 @variable(model, x[1:n], Bin)
9
10 @objective(model, Min, sum(c'g[t,:] for t=1:T) + i'x)
11
12 @constraint(model, [t=1:T], sum(g[t,:]) = d[t])
13 @constraint(model, [t=1:T,j=1:n], g[t,j] ≤ u[t,j] * Gmax[j])
14 @constraint(model, [t=1:T,j=1:n], u[t,j] ≤ x[j])
15
16 optimize!(model)
17
18 @show objective_value(model)
19 @show value.(x)

```

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Reformulation Performance



Qualitative Analysis

CITATION ALERT

Towards an Automatic Framework for Solving Optimization Problems with Quantum Computers, arXiv:2406.12840, 2024

TABLE I: Comparing the support provided by of proposed framework and existing libraries and framework in each step of quantum optimization.

✓ indicates that the corresponding action is performed automatically.

✗ signifies that a proper function is available for implementing the step.

✗ indicates that the method is not fully supported.

+ denotes that logarithmic encoding is also compatible with bases different from two.

* signifies that the encoding techniques can be exploited only for constraints translation.

† indicates that the polynomial reduction is implemented by exploiting the corresponding qubovert function.

Supports for each step		Existing Libraries						Existing Frameworks		Proposed Framework
		pyqubo [31]	qubovert [32]	dimod [33]	Qiskit [34]	fixstars [35]	openQAOA [36]	AutoQUBO [37]	QUBO.jl [38]	
Floating Encoding		✗	✗	✗	✗	✗	✗	✗	✓	✓
Integer Encoding	Logarithmic [39]	✓	✓	✓	✓	✓*	✗	✗	✓	✓+
	Unitary [39]	✓	✓	✗	✗	✓*	✗	✗	✓	✓
	Dictionary [39]	✓	✗	✗	✗	✗	✗	✗	✓	✓
	Domain-Wall [40]	✓	✗	✗	✗	✗	✗	✗	✓	✓
	Bounded-Coeff [41]	✗	✗	✗	✗	✗	✗	✗	✓	✓
Penalty Functions	Arithmetic [42]	✗	✗	✗	✗	✓*	✗	✗	✓	✓
	Equality [22] [21]	✗	✓	✓	✓	✓	✓	✗	✓	✓
	Inequality [22]	✗	✓	✓	✓	✓	✓	✗	✓	✓
	Boolean [22]	✓	✓	✓	✗	✓	✗	✗	✗	✓
Penalty Weight	UB positive [43]	✗	✗	✗	✗	✗	✗	✗	✗	✓
	MQC [43]	✗	✗	✓	✗	✗	✗	✗	✗	✓
	VLM [44]	✗	✗	✗	✗	✗	✗	✓	✗	✓
	MOMC [43]	✗	✗	✗	✗	✗	✗	✗	✗	✓
	MOC [43]	✗	✗	✗	✗	✗	✗	✗	✗	✓
	UB Naive [45], [46]	✗	✗	✗	✓	✗	✗	✓	✓	✓
	UB posiform [45], [46]	✗	✗	✗	✗	✗	✗	✓	✗	✓
Polynomial Reduction		✓	✓	✓	✗	✓	✗	✓	✓	✓†
Solvers	Dwave QA	✓	✗	✓	✗	✓	✗	✓	✓	✓
	QAOA	✗	✗	✗	✓	✗	✓	✗	✓	✓
	VQE	✗	✗	✗	✓	✗	✓	✗	✓	✓
	GAS	✗	✗	✗	✓	✗	✗	✗	✗	✓
Solution Decoding		✓	✓	✓	✓	✓	✓	✓	✓	✓
Check Constraints		✓	✓	✓	✗	✓	✗	✓	✓	✓
Penalty Update	Sequential [47]	✗	✗	✗	✗	✗	✗	✗	✗	✓
	Scaled [47]	✗	✗	✗	✗	✗	✗	✗	✗	✓
	Binary search [47]	✗	✗	✗	✗	✗	✗	✗	✗	✓



Conclusions & Future Work

MAIN TAKEAWAYS

- ❑ ***QUBO.jl gives OR practitioners a smooth experience for accessing advanced hardware***
- ❑ ***Provides tools & infrastructure for benchmarking novel optimization technologies***



Conclusions & Future Work

MAIN TAKEAWAYS

- ❑ *QUBO.jl gives OR practitioners a smooth experience for accessing advanced hardware*
- ❑ *Provides tools & infrastructure for benchmarking novel optimization technologies*

NEXT STEPS

- ❑ *Set up benchmarking service and use results to guide reformulation*
- ❑ *Expand Reformulation Library and Solver support*
- ❑ *Investigate architecture-oriented compilation*



Thanks!

pmacielx@purdue.edu
pedrox@cos.ufrj.br

