

Aula 20

Matrizes simétricas (diagonalização)

Teorema: Toda a matriz simétrica $A(n \times n)$ é ortogonalmente diagonalizável e admite como matriz diagonalizante ortogonal uma matriz cujos colunas são os vetores próprios o.m. de A

$$P^{-1}AP = D \quad P^TAP = D \Rightarrow P^T = P^{-1}$$

Exemplo ①

$A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$, uma matriz simétrica $\Rightarrow A$ é ortogonalmente diagonalizável

- Determine a matriz diagonalizante e ortogonal e a matriz D tal que: $P^TAP = D$

$$\det(\lambda I - A) = \begin{vmatrix} \lambda-1 & -2 \\ -2 & \lambda-1 \end{vmatrix} = 0 \Leftrightarrow (\lambda-1)^2 - 4 = 0 \Leftrightarrow (\lambda-1-2)(\lambda-1+2) = 0 \Leftrightarrow (\lambda-3)(\lambda+1) = 0 \Leftrightarrow \lambda = 3 \vee \lambda = -1$$

$$\lambda I - A = \begin{bmatrix} \lambda-1 & -2 \\ -2 & \lambda-1 \end{bmatrix}$$

$$U_{\lambda=3} = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \in \mathbb{R}^{2 \times 1} : \underbrace{\begin{bmatrix} 2 & -2 \\ -2 & 2 \end{bmatrix}}_{3I-A} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \right\}$$

$$\begin{bmatrix} 2 & -2 & 0 \\ -2 & 2 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$x - y = 0 \Leftrightarrow x = y$$

$$\begin{aligned} U_{\lambda=3} &= \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \in \mathbb{R}^2 : x = y \right\} \\ &= \left\{ \begin{bmatrix} x \\ x \end{bmatrix}, x \in \mathbb{R} \right\} = \left\{ x \begin{bmatrix} 1 \\ 1 \end{bmatrix}, x \in \mathbb{R} \right\} \\ &= \left\langle \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\rangle \end{aligned}$$

$$v_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$U_{\lambda=-1} = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \in \mathbb{R}^2 : \begin{bmatrix} -2 & -2 \\ -2 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \right\}$$

$$\begin{bmatrix} -2 & -2 & 0 \\ -2 & -2 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad x + y = 0 \Rightarrow x = -y$$

$$U_{\lambda=-1} = \left\langle \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\rangle$$

$$v_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

- Vetores próprios associados a valores próprios distintos são ortogonais $\Rightarrow v_1 \cdot v_2 = 0$

$$\text{Seja } \hat{v}_1 = \frac{1}{\|v_1\|} v_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} \end{bmatrix}$$

$$\hat{v}_2 = \frac{1}{\|v_2\|} v_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} \end{bmatrix}$$

$$\text{Seja } P = \begin{bmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \\ \frac{\sqrt{3}}{2} & \frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{\sqrt{3}}{2} \end{bmatrix}$$

$\lambda=3$
 $\lambda=-1$

Assim, $P^T A P = \begin{bmatrix} 3 & 0 \\ 0 & -1 \end{bmatrix}$

(ii) se fizermos ao contrário $\Rightarrow P^T A P = \begin{bmatrix} -1 & 0 \\ 0 & 3 \end{bmatrix}$

Exemplo (2)

$$A = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

Será A diagonalizável? Sim, A é simétrica. Logo, é ortogonalmente diagonalizável. Encontre a matriz diagonalizante ortogonal e a matriz diagonal D, tal que: $P^T A P = D$

$$\lambda I - A = \begin{bmatrix} \lambda & 0 & -1 \\ 0 & \lambda-1 & 0 \\ -1 & 0 & \lambda \end{bmatrix} \quad \det(\lambda I - A) = \begin{vmatrix} \lambda & 0 & -1 \\ 0 & \lambda-1 & 0 \\ -1 & 0 & \lambda \end{vmatrix} = (\lambda-1)^2(\lambda+1)^2 = 0$$

$\Rightarrow \lambda = 1 \vee \lambda = -1$

$$U_{\lambda=1} = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 : \begin{bmatrix} -1 & 0 & -1 \\ 0 & -2 & 0 \\ -1 & 0 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\}$$

$$\begin{bmatrix} -1 & 0 & -1 & | & 0 \\ 0 & -2 & 0 & | & 0 \\ -1 & 0 & -1 & | & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & | & 0 \\ 0 & 1 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \quad x = -z \quad x = 0$$

$$U_{\lambda=1} = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 : x = -z \wedge y = 0 \right\} = \left\{ \begin{bmatrix} -z \\ 0 \\ z \end{bmatrix}, z \in \mathbb{R} \right\}$$

$$= \left\langle \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\rangle$$

$$v_1 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$$U_{\lambda=1} = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 : \begin{bmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\}$$

$$\begin{bmatrix} 1 & 0 & -1 & | & 0 \\ 0 & 0 & 0 & | & 0 \\ -1 & 0 & 1 & | & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -1 & | & 0 \\ 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \quad x = z$$

$$U_{\lambda=1} = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 : x = z \right\}$$

$$= \left\{ \begin{bmatrix} z \\ y \\ z \end{bmatrix}, z, y \in \mathbb{R} \right\} = \left\langle \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\rangle$$

$$v_2 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \quad e \quad v_3 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$v_1 \cdot v_2 = 0$ Vektoren próprios associados a
 $v_1 \cdot v_3 = 0$ valores próprios distintos são ortogonais

$$\hat{v}_1 = \frac{1}{\sqrt{2}} \cdot \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{\sqrt{2}}{2} \\ 0 \\ \frac{\sqrt{2}}{2} \end{bmatrix}$$

$$P = [\hat{v}_1 \mid \hat{v}_2 \mid \hat{v}_3]$$

$$\hat{v}_2 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{3}}{2} \\ 0 \\ \frac{\sqrt{3}}{2} \end{bmatrix}$$

$$\hat{v}_3 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

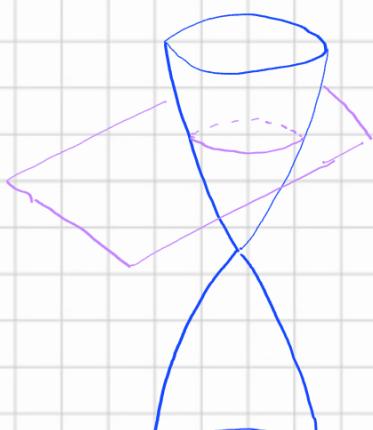
$$= \begin{bmatrix} \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ 0 & 0 & 1 \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \end{bmatrix}$$

$$P^T A P = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

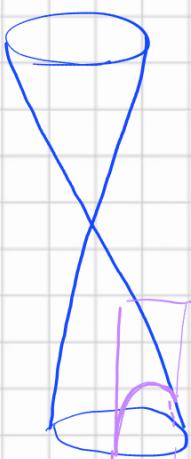
(1) (1) (1) -> Valores próprios

Cónicos

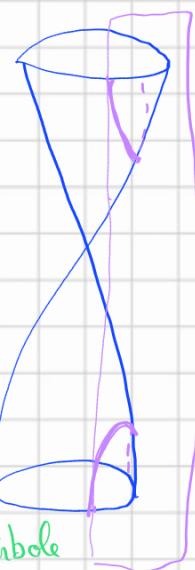
cónica → curvas obtidas pela intersecção de um cone com um plano



Elipse



Parábola



Hiperbola

Equação geral de uma cónica:

$\alpha, \beta, \gamma \in \mathbb{R}$ não simultaneamente nulos e $\delta, \gamma, \mu \in \mathbb{R}$

termos cruzados

$$\alpha x^2 + \beta y^2 + 2\gamma xy + \delta x + \gamma y + \mu = 0$$

$$\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} \alpha & \gamma \\ \gamma & \beta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} \delta & \gamma \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \mu = 0$$

$$X^T A X + B X + \mu = 0$$

matriz simétrica

2×2 , não nula