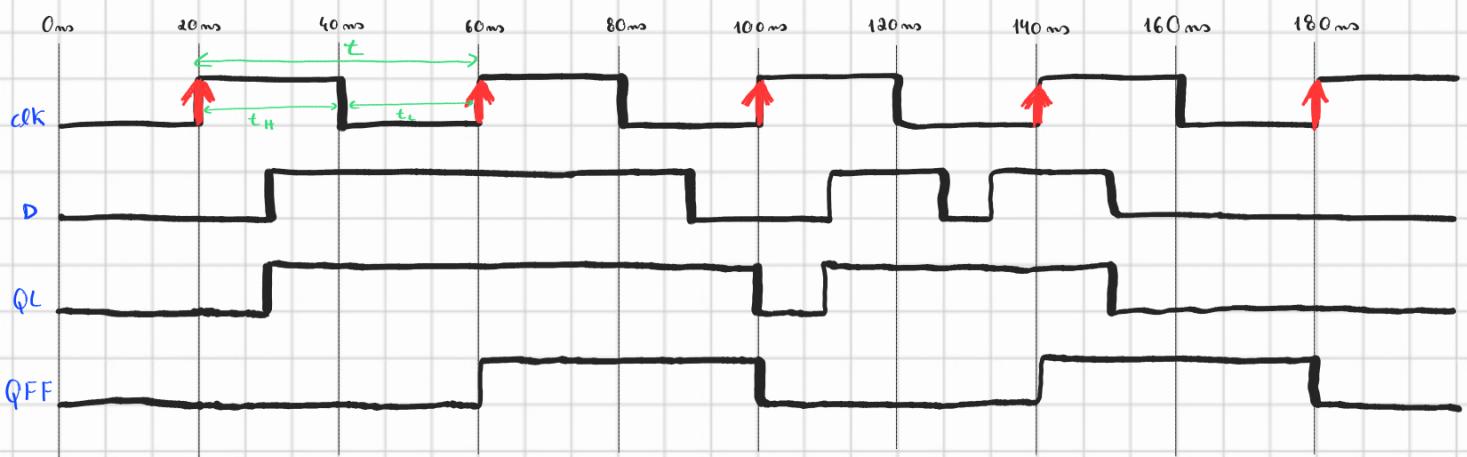


Aula 09 - 10

1



$$t_p = t_H + t_L \quad , \quad t_H = t_L = 20 \text{ ms} \Rightarrow t_p = 40 \text{ ms}$$

$$f = \frac{1000}{40} = 25 \text{ MHz}$$

$$\text{duty cycle} = \frac{t_H}{t_p} \times 100\% = \frac{20}{40} \times 100\% = 50\%$$

2

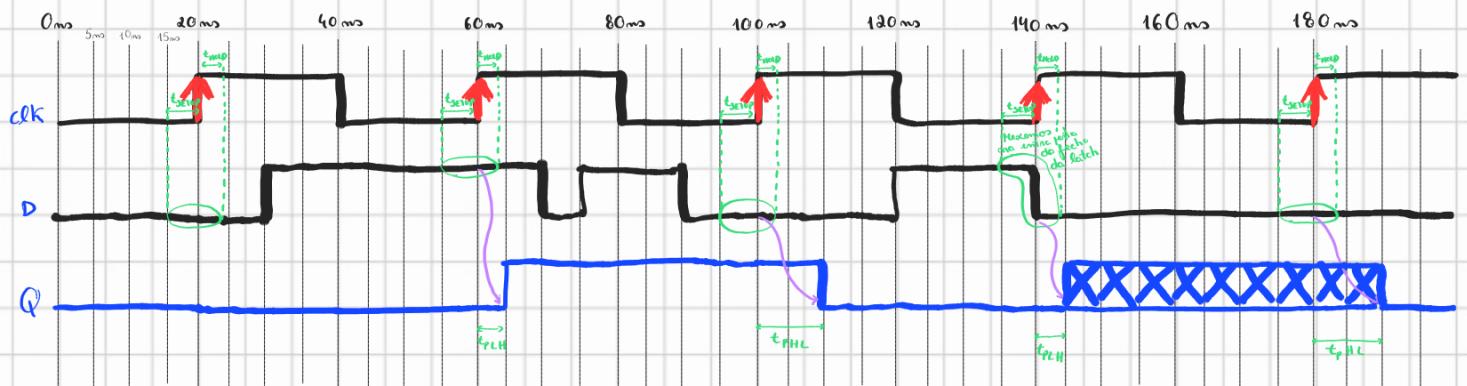
a) Negative-edge-triggered



b) Positive-edge-triggered

c) D Latch

3



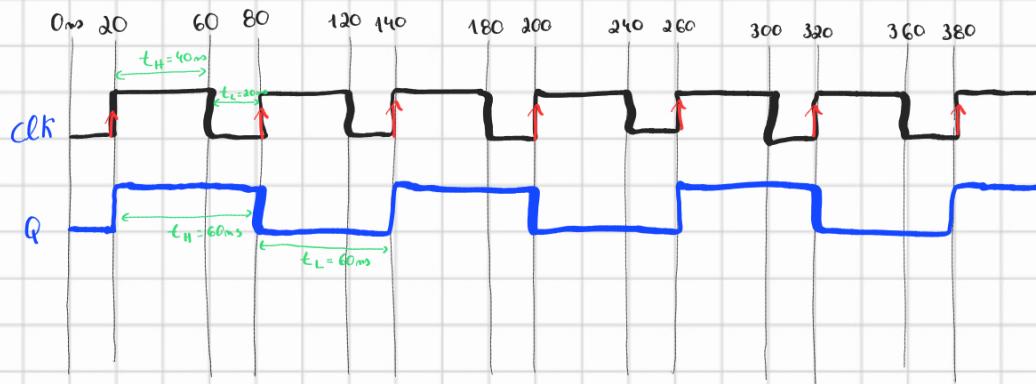
$$t_{\text{setup}} = 5 \text{ ms}$$

$$t_{\text{hold}} = 3 \text{ ms}$$

$$t_{\text{PHL}} = 10 \text{ ms}$$

$$t_{\text{PLH}} = 5 \text{ ms}$$

4



Sinais posicionados

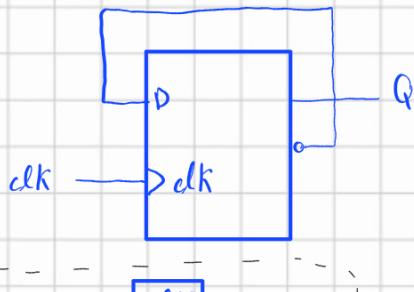
 $T \rightarrow \text{período}$ 

$$f = \frac{1}{T}$$

$$T = 1\text{ns} \Rightarrow f = \frac{1}{1 \times 10^{-9}} = 1 \times 10^9 = 1\text{GHz}$$

$$T = 1\text{\mu s} \Rightarrow f = \frac{1}{1 \times 10^{-6}} = 1 \times 10^6 = 1\text{MHz}$$

$$T = 10\text{ms} \Rightarrow f = \frac{1}{10 \times 10^{-3}} = 10 \times 10^3 = 10\text{MHz}$$



O circuito é um divisor de frequências por um fator de 2 \Rightarrow o período é o dobro do CLK ($Q^t = \bar{Q}$)

$$t_p = t_H + t_L = 60\text{ms}$$

$$f = \frac{1000}{t_p} = \frac{1000}{60} \approx 16,6\text{ MHz}$$

$$\text{duty cycle} = \frac{t_H}{t_p} \times 100\% = \frac{40}{60} \times 100\% \approx 66,6\%$$

$$t_p = t_H + t_L = 60 + 60 = 120\text{ ms}$$

$$f = \frac{1000}{t_p} = \frac{1000}{120} \approx 8,3\text{ MHz}$$

$$\text{duty cycle} = \frac{t_H}{t_p} \times 100\% = \frac{60}{120} \times 100\% = 50\%$$

$$t_{\text{SETUP}} = 5\text{ ms}$$

$$t_{\text{PHL}} = 15\text{ ms}$$

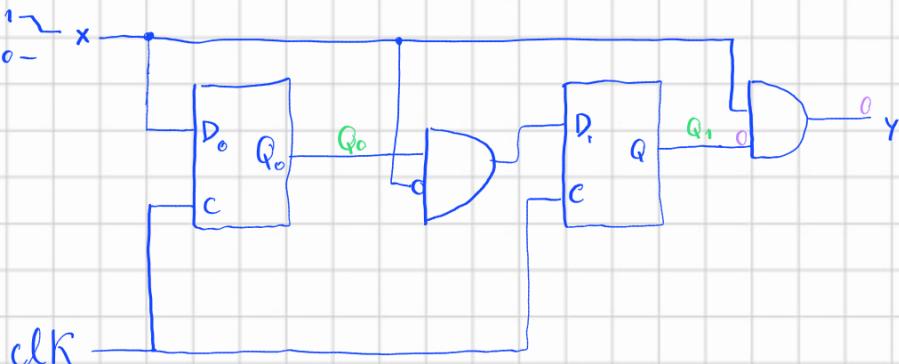
$$t_{\text{HOLD}} = 3\text{ ms}$$

$$t_{\text{PLH}} = 10\text{ ms}$$

$$\begin{aligned} t_{\text{min}} &= t_{\text{SETUP}} + \text{Max}(t_{\text{PHL}}, t_{\text{PLH}}) \\ &= 5 + 15 = 20\text{ ms} \end{aligned}$$

$$f_{\text{max}} = \frac{1000}{t_{\text{min}}} = \frac{1000}{20} = 50\text{ MHz}$$

5



- a) Inputs: CLK, X
Outputs: Y

b) $Y = x \cdot Q_1$

c) $Q_1^+ = \bar{x} \cdot Q_0$
 $Q_0^+ = x$

d) Mealy

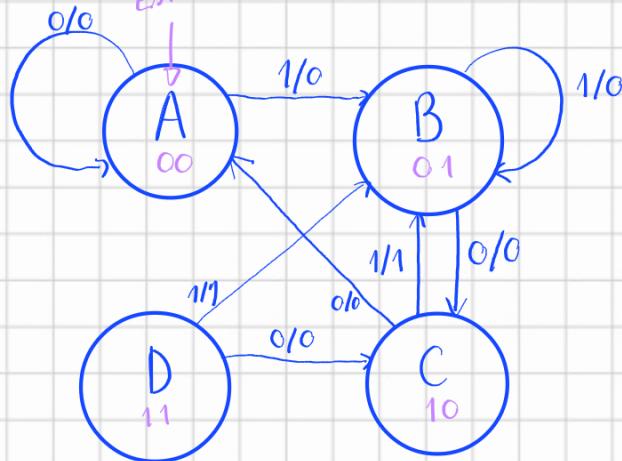
e)

	Q_1	Q_0	x	Q_1^+	Q_0^+	Y	
A	0	0	0	0	0	0	A
	0	0	1	0	1	0	A
B	0	1	0	1	0	0	B
	0	1	1	0	1	0	B
C	1	0	0	0	0	0	C
	1	0	1	0	1	1	C
D	1	1	0	1	0	0	D
	1	1	1	0	1	1	D

Este estado
nunca acontece

Estado Inicial

f)



Legenda: x/Y

g) O circuito deteta a sequência 101 aceitando sobreponção

h)

$$t_{\text{Setup}} = 15 \text{ ms}$$

$$t_{\text{Hold}} = 5 \text{ ms}$$

$$t_{\text{p HL}} = 25 \text{ ms}$$

$$t_{\text{p LH}} = 20 \text{ ms}$$

$$f = 20 \text{ MHz}$$

$$f(\text{MHz}) = \frac{1000}{t(\text{ms})} \Leftrightarrow t = \frac{1000}{20} \text{ ms} \Leftrightarrow t = 50 \text{ ms}$$

$$t = t_{\text{Setup}} + t_{\text{HL}} + t_{\text{gate}}$$

$$\Leftrightarrow 50 = 15 + 25 + t_{\text{gate}}$$

$$\Leftrightarrow t_{\text{gate}} = 10 \text{ ms}$$

Conversor de binário para Gray

$$\begin{aligned} Q_0^+ &= X \\ Q_1^+ &= Q_0 \end{aligned}$$

$$\begin{aligned} Y_0 &= X \oplus Q_0 \quad \Rightarrow \text{Mealy machine!} \\ Y_1 &= Q_0 \oplus Q_1 \\ Y_2 &= Q_1 \end{aligned}$$

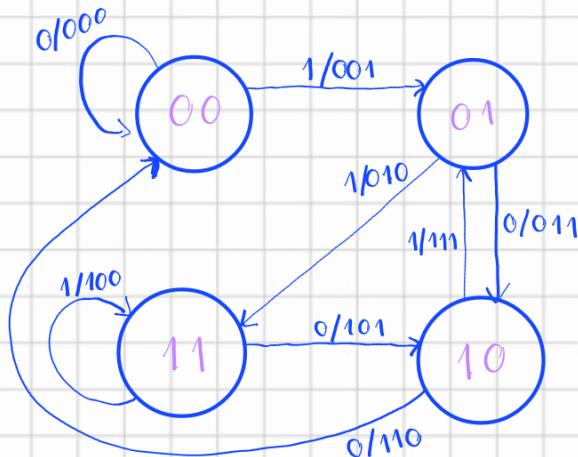
Q_1	Q_0	X	Q_1^+	Q_0^+	Y_2	Y_1	Y_0	
0	0	0	0	0	0	0	0	-0
0	0	1	0	1	0	0	1	-1
0	1	0	1	0	0	1	1	-2
0	1	1	1	1	0	1	0	-3
1	0	0	0	0	1	1	0	-4
1	0	1	0	1	1	1	1	-5
1	1	0	1	0	1	0	1	-6
1	1	1	1	1	1	0	0	-7

Código em binário

Gray Code



Quanto a imprimir os resultados



Legenda: $X / Y_2 \ Y_1 \ Y_0$

→ Conversor de binário para Gray

- 0 "x" é a entrada

- Por exemplo:

Estado = "10" q₁ q₀ → Estado seguinte = "X01"
X = "1" q₁, q₀

Binário = "101" → Gray = "111"
↓ ↓ ↓
Y₃ Y₂ Y₁

retina - se é
mais significativa
de menor

$$t_{\text{setup}} = 15 \text{ ns}$$

$$t_{\text{HOLD}} = 5 \text{ ns}$$

$$t_{\text{PHL}} = 25 \text{ ns}$$

$$t_{\text{PLH}} = 20 \text{ ns}$$

$$t_{\text{gate}} = 10 \text{ ns}$$

for clk

$$t_{\text{min}} = 15 + 25 = 40$$

$$f_{\text{max}} = \frac{1}{t} = \frac{1}{40 \text{ ns}} = \frac{1}{40 \times 10^{-9}} = 4 \times 10^8 = 400 \text{ MHz}$$

