

Comparison between machine learning techniques to predict sand/geomembrane interface shear strength

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Article

Keywords

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Abstract

Geomembranes (GM) have been extensively used for waterproofing applications, and often they are in contact with soil materials or other geosynthetics for mechanical protection. Strength evaluation at the interface between the GM and the contact material is fundamental to ensure a good design that guarantees a low probability of this interface failure. This paper analyses and compares four Artificial Neural Network (ANN) models (varying the number of inputs and hidden layers) and the Random Forest (RF) technique to predict sand/GM interface shear strength based on 495 results from previous investigations. All models were optimized with the Differential Evolution (DE) algorithm. The Coefficient of Determination (R^2) and root mean squared error ($RMSE$) were set as evaluation criteria for the accuracy of the developed models. The results show that RF performs best as a prediction tool for the data analysed. Data correlation and RF feature importance analysis were also conducted, establishing GM asperity height as the most significant variable for the collected data. The results show the great potential of Machine Learning applications for predicting the interface shear strength between sand and geomembranes in geotechnical engineering constructions.

1. Introduction

Geosynthetics have emerged as a widely used solution for solving geotechnical challenges in civil engineering projects. Geomembranes (GM) are mainly used as a waterproofing system due to their low permeability and good mechanical behaviour (Koerner, 2012), establishing effective control and management of liquids, minimizing the possibility of infiltration. In this context, it is crucial to establish a sufficient interface shear strength between the geosynthetic and the surrounding soil to ensure the strength and integrity of these structures and prevent potential failures (Moraci et al., 2014). This interface shear strength is often quantified by determining the friction angle, which can be evaluated through various laboratory tests such as direct shear, ring shear, pull-out, or inclined plane tests (Palmeira, 2009; Moraci et al., 2014; Cen et al., 2018).

Various researchers performed multiple investigations using a variety of soil and geomembranes to assess the interface resistance. The results have shown that relevant several influential factors affect the strength parameters in

addition to the type of test employed. These factors include geomembrane characteristics, such as type, thickness and asperity height, or soil type, and external conditions like applied normal stresses and contact area (Izgin, 1997; Wasti & Özübüyük, 2001; Palmeira et al., 2002; Rebelo, 2003; Aguiar, 2008; Pitanga et al., 2009; Moraci et al., 2014; Alzahrani, 2017; Sánchez, 2018; Lashkari & Jamali, 2021; Araújo et al., 2022; Khan & Latha, 2023; Costa Junior et al., 2023).

Machine learning (ML), which is related to Artificial Intelligence (AI), is a computational technique capable of evaluating and learning from prior information (data mining) to forecast or categorize a response, employing algorithms and statistical calculations without complicated programming. AI has gained attention in civil engineering due to its versatility, simplicity of application, and ability to solve complex problems (Lu et al., 2012; Shahin, 2013; Evangelista Junior & Afanador-García, 2016; Dede et al., 2019; Huang et al., 2019; Evangelista Junior & Almeida, 2021; Lagaros & Plevris, 2022; Xu et al., 2023; Silva et al., 2023, Lima et al., 2023a) and has great potential to predict the interface shear strength between geosynthetics and other materials.

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Several papers can be found in the last recent years regarding Artificial Intelligence and geosynthetics, (Kumari & Dutta, 2019; Raja & Shukla, 2021; Pant & Ramana, 2022; Ali et al., 2022; Raja et al., 2022; Tan et al., 2022; Hasthi et al., 2022; Li et al., 2025). However, although previous studies for soil-geosynthetic interface behaviour assessment with ML techniques, many of them have less than 400 laboratory results and just used one type of test (Debnath & Dey, 2017; Chao et al., 2021, 2023; Ali et al., 2022; Pant & Ramana, 2022). In this manner, it is important to evaluate how a dataset from different types of experiments can improve the prediction of the interface shear strength between geomembrane and other materials such as sand.

This paper evaluates and compares the results of two ML methodologies: (i) four different Artificial Neural Network (ANN) architectures and (ii) non-linear Random Forest (RF) approach to predict the interface friction angle between sand and geomembrane. The Differential Evolution optimization algorithm was conducted in both methods. The analysis was carried out using an input parameters data collection comprised of 495 samples obtained from three different laboratory tests conducted in previous studies (manufacturer company, scientific papers, Master dissertations and PhD-thesis) produced in seven countries. The idea of using different type of tests is trying to improve the ML learning process. Two statistical metrics, the R^2 and RMSE, were used to establish the best accurate prediction model between ANN and RF. Additionally, Pearson's linear correlation and non-linear RF feature importance were conducted evaluating the main impact factors in soil-GM shear strength interface for the collected data.

2. Machine learning algorithms used

In the literature, there are studies developed for predicting soil-geosynthetic interface resistance using ANN (Debnath & Dey, 2017; Chao et al., 2021, 2023; Ali et al., 2022)

and RF (Pant & Ramana, 2022). However, these only focused on the use of one type of test with limited data and did not compare the techniques herein applied. In this study the evaluation and comparison between the two methodologies is apply to define the best prediction algorithm.

2.1 Artificial Neural Network (ANN)

An ANN corresponds to a computational model developed by algorithms which mimic biological neuronal characteristics (Fausett, 1994; Basheer & Hajmeer, 2000; Shahin et al., 2009). Multi-Layer Perceptron (MLP) is one of the most widely used architectures in ANNs, where neurons are organized into input, hidden layers, and output (Shahin et al., 2008). Figure 1 shows a general architecture for an MLP network.

Another significant feature of ANN is the learning rule that establishes the training process. The Backpropagation (BP) training algorithm is one of the most widely method applied (Soleimanbeigi & Hataf, 2006) and has been used in this investigation.

2.2 Random Forest (RF)

RF is a supervised ML algorithm developed by Breiman (2001) that combines the Decision Trees methodology with regression and is trained using the bootstrap aggregating (bagging) method (Géron, 2019). According to Pant & Ramana (2022), RF is built upon the concept of bagging decision trees, where multiple subsamples are generated from the original dataset.

As shown in Figure 2, the training input is divided using the k-fold cross-validation technique in each subsample. One part of the division derives the regression function from a new training dataset for each decision tree. The other omitted part, known as out-of-bag (OOB), is used to evaluate the accuracy of each subsample.

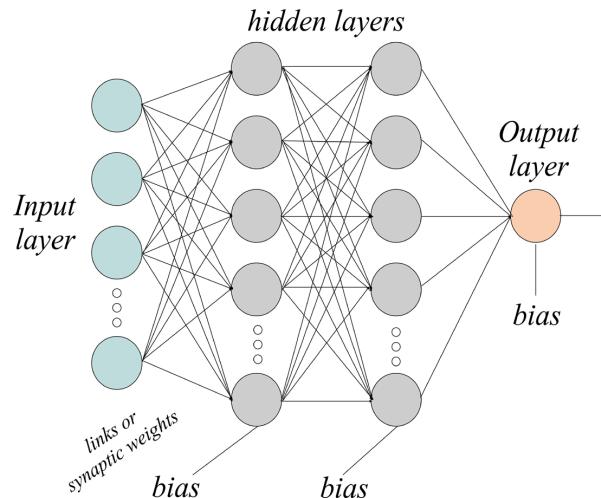


Figure 1. Multilayer Perceptron Network general architecture.



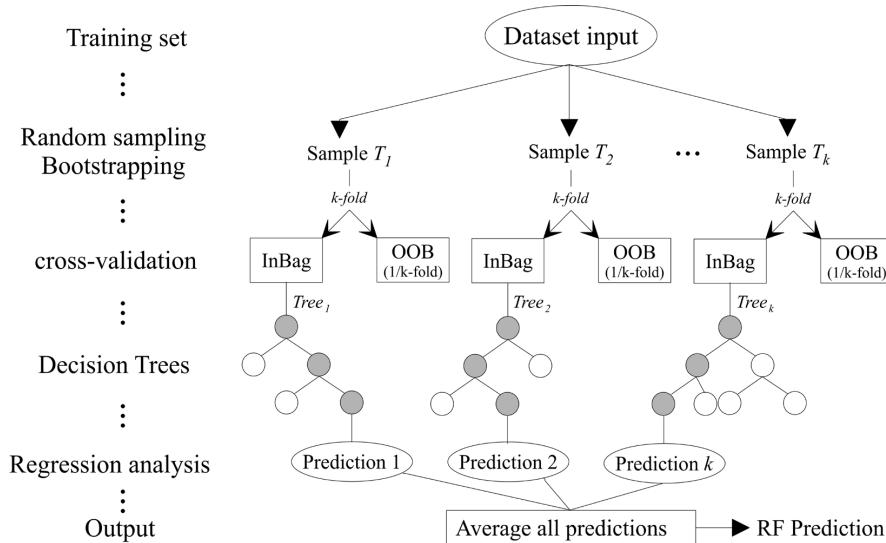


Figure 2. RF model architecture.

2.3 Hyperparameter optimisation (HPO) – Differential Evolution (DE)

In machine learning, certain parameters are used during training control as a portion of the learning, analysis, and outcome prediction. However, some parameters are set beforehand and remain constant during model training. These parameters are known as hyperparameters, which can be optimized to significantly improve the performance of the chosen model algorithm (Hutter et al., 2019; Lima et al., 2023b). The optimization algorithm aims to identify the optimal hyperparameters values (best combination) for prediction analysis.

Differential Evolution (DE) is a heuristic optimization algorithm based on the theory of species evolution known as Evolutionary Algorithms (EA). First introduced by Storn & Price (1996), DE optimizes nonlinear and non-differentiable functions and a full description of the DE workflow is presented in Atangana Njock et al. (2023). Figure 3 shows the optimization process in both ML-implemented techniques used in this study.

3. Data mining and correlation

Considering that the selected ML methodologies correspond to a supervised learning type, it is necessary to have input data and known result values. Based on this, a search was conducted for laboratory test results evaluating the interface strength between sand and geomembrane. Four hundred sixty samples were collected from previous research available in the literature, and an additional 35 samples were provided by a geomembrane manufacturer. The reference data were chosen considering the most common detailed information in each study regarding twelve influencing parameters as input: (1) applied normal stress, (2) coefficient of curvature,

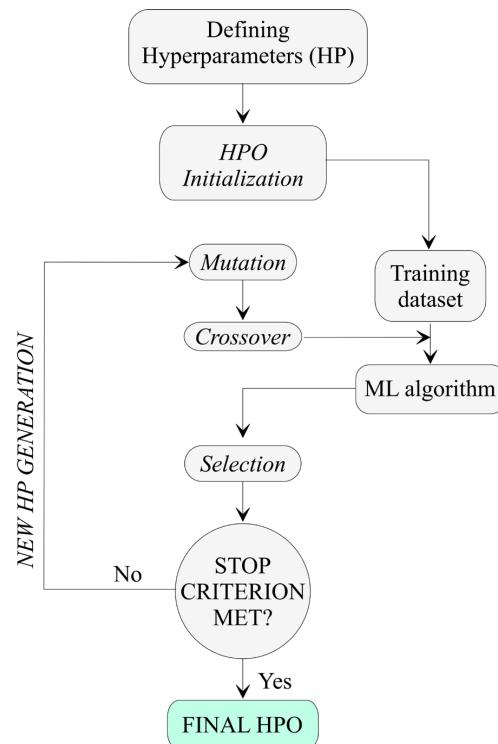


Figure 3. Flowchart of DE-ML algorithm implementation.

(3) contact area, (4) displacement rate, (5) GM asperity height, (6) GM thickness, (7) median grain size, (8) sand density index, (9) soil friction angle, (10) soil unit mass, (11) type of implemented test (Conventional Direct Shear – *CDS*, Medium Direct Shear – *MDS*, or Inclined Plane – *IP*), and (12) uniformity coefficient. Figure 4 shows the location of the selected studies and their respective reference.



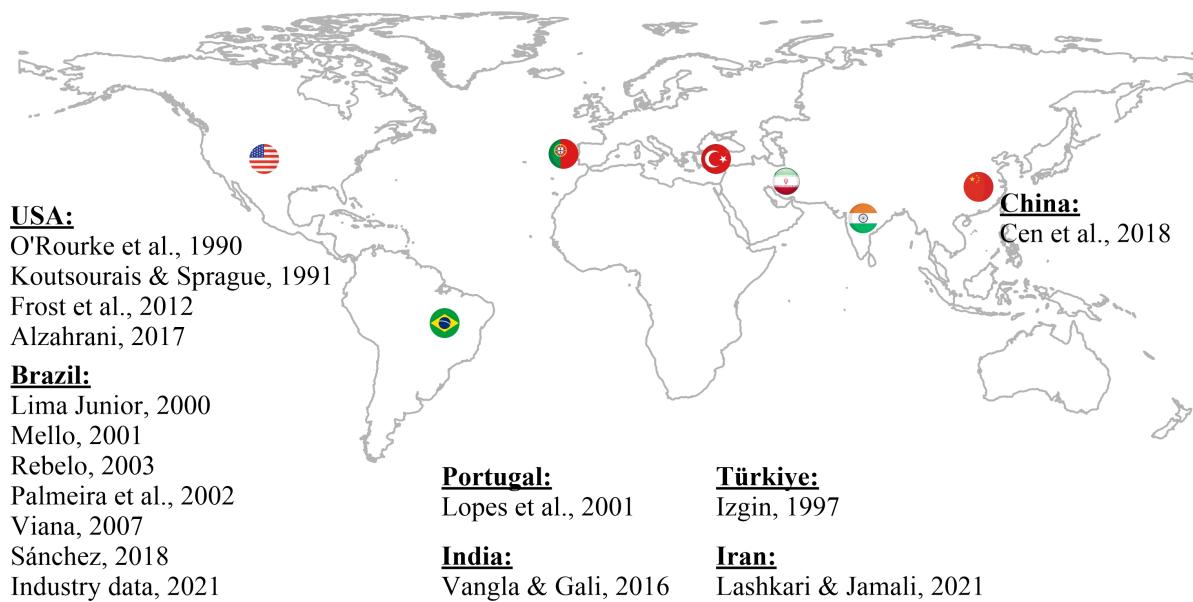


Figure 4. Dataset reference location. Source: O'Rourke et al. (1990), Koutsourais & Sprague (1991), Frost et al. (2012), Alzahrani (2017), Lima Junior (2000), Mello (2001), Rebelo (2003), Palmeira et al. (2002), Viana (2007), Sánchez (2018), Industry Data (2021), Lopes et al. (2001), Izgin (1997), Vangla & Gali (2016), Lashkari & Jamali (2021) and Cen et al. (2018).

Table 1. Statistical information of influence parameters.

	Parameter	Min	Max	Mean	σ_{STD}	CV
Input						
R_d	Displacement rate (mm/min)	0.10	3.00	1.11	0.67	0.60
σ_n	Normal stress (kPa)	1.00	300.00	43.59	48.77	1.12
A_c	Contact area (cm ²)	36.00	9024.00	1521.00	2994.94	1.97
t	GM thickness (mm)	0.50	3.00	1.68	0.45	0.27
A_h	GM asperity h (mm)	0.00	1.71	0.18	0.45	2.48
I_d	Sand relative density (%)	20.80	98.00	57.83	24.43	0.42
γ	Soil unit weight (kN/m ³)	14.5	29.4	15.5	2.9	1.8
C_c	Coefficient of curvature	0.80	1.68	1.03	0.37	0.36
C_u	Uniformity coefficient	1.11	46.80	2.82	5.92	2.09
D_{50}	Median grain size (mm)	0.17	3.08	0.58	0.60	1.04
ϕ_s	Friction angle of soil (°)	25.30	49.50	38.30	4.99	0.13
Type of test						
Output						
δ'	Friction angle interface (°)	7.50	64.50	28.20	7.32	0.26

Legend: see List of symbols and abbreviations.

Table 1 shows the statistical data of the influencing parameters used. The statistical information of the collected data reveals a wide distribution for each parameter, enabling a better characterization and analysis for different soil and geomembrane conditions. This is reflected in the high coefficient of variation (CV) values for some parameters, such as normal stress and contact area (significant variability due

to the type and conditions of test execution), asperity height (from smooth to rough GM with maximum values of 1.71 mm), and uniformity coefficient (associated with a wide range of variety in the type of used sand). It is essential to point out that the “Test Type” parameter was defined with values of 0 or 1. A value of 1 was assigned when CDS, MDS or IP tests were conducted.



3.1 Linear data correlation

The Pearson correlation coefficient (ρ_r) is a statistical measure used to quantify the strength and direction of the linear relationship between two variables. It is calculated based on the covariance of the variables, normalized by the product of their standard deviations. The coefficient can assume values ranging from -1 to $+1$. A value close to zero indicates little or no linear correlation, while values closer to the extremes represent stronger correlations. A positive coefficient signifies that both variables tend to increase or decrease together (direct relationship), whereas a negative coefficient indicates that one variable tends to increase as the other decreases (inverse relationship) (Schober et al., 2018). The correlation between the influencing factors and the interface shear strength obtained from laboratory tests is shown in Figure 5, with each independent parameter's specific relationship expressed in the bottom row.

According to the correlation analysis, the asperity height of the geomembrane (A_h) has the strongest correlation with the interface strength ($\rho_r=0.64$). This behaviour is aligned with the results of various studies where an increase in geomembrane roughness leads to an increase in interface strength (Stark et al., 1996; Lopes et al., 2001; Frost et al., 2012; Araújo et al., 2022; Costa Junior et al., 2023).

The sand properties also show significantly correlation to the interface strength, but with less proportion. On the

other hand, the mean particle diameter D_{50} ($\rho_r=-0.24$) and the coefficient of curvature C_c ($\rho_r=-0.11$) show an inversely proportional relation to interface shear strength, differing from some research outcomes where it was observed a direct influence of soil properties according just to the laboratory test results (Izgin & Wasti, 1998; Lopes et al., 2001; Costa e Lopes, 2001; Afonso, 2009; Choudhary & Krishna, 2016; Markou & Evangelou, 2018; Cen et al., 2018). Conversely, the contact area exhibits a weaker correlation value ($\rho_r=-0.07$), which is opposing to some authors' conclusions who found out that the interface friction angle presented variable behaviour across different box sizes, indicating that the contact area plays a significant role in determining the friction angle (Izgin & Wasti, 1998; Wasti & Özدüzgün, 2001; Hsieh & Hsieh, 2003; Reyes Ramirez & Gourc, 2003; Gourc & Reyes Ramírez, 2004; Aguiar, 2008; Pitanga et al., 2009; Moraci et al., 2014). The observed differences between the experimental investigations and the linear correlation can be attributed to the fact that the linear correlation calculations do not consider the influence of other variables affecting the interface friction angle.

There is an even weaker correlation observed between geomembrane thickness ($\rho_r=-0.04$) and interface friction angle. This finding is consistent with the studies conducted by Lima Junior (2000) and Sánchez (2018), who also reported a lack of direct influence between geosynthetic thickness and interface shear strength in their laboratory investigations.

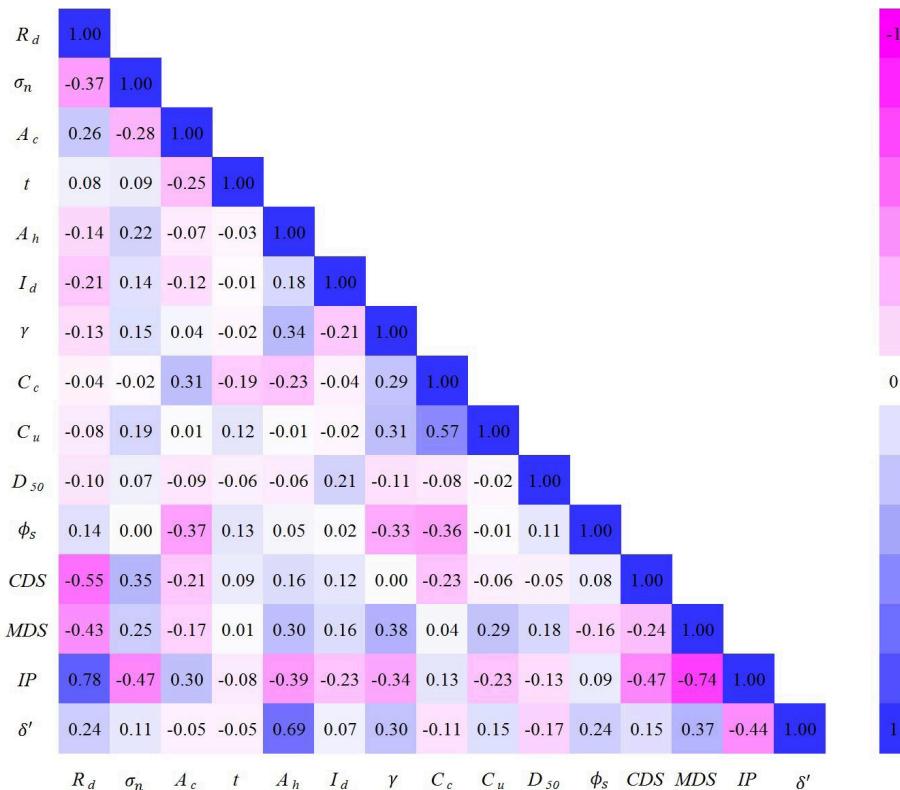


Figure 5. Pearson correlation heatmap between parameters and interface laboratory results.



Based on the correlation values, it can be inferred that the *MDS* test has a more significant and direct impact on determining the interface friction angle, likely linked to higher shear strength results (Hsieh et al., 2002). Conversely, the *IP* test, despite its high correlation value, outlined a negative sign which suggests that lower values of the interface friction angle may be obtained when this test is conducted. Moraci et al. (2014) and Pavanello et al. (2021) mentioned that the interface strength values for low stresses obtained in *IP* tests are lower than those obtained in direct shear tests.

4. Model development and implementation

4.1 ANN architecture

Before initiating the neural network training process, it is crucial to establish its architecture. In this research, four distinct ANN models were developed for comparison, with variations in the number of neurons in the input layer. Specifically, two models had 14 neurons in the input layer, representing all influential parameters. The other two models excluded the nominal parameter (test type) and the two parameters with the weakest correlation, namely contact area (A_c) and GM thickness (t), resulting in nine neurons in the input layer. The models differed in the number of hidden layers, ranging from one to two. The output layer consisted of a single neuron representing the interface shear strength.

The selection of the HPO corresponds to the number of hidden neurons, activation function type (logistic sigmoid, hyperbolic tangent, or ReLU function), learning rate, and momentum coefficient (Yu & Zhu, 2020; Silva et al., 2023). The activation function is fundamental in defining a neuron's output, as it transforms the aggregated weighted inputs into a specific level that governs the neuron activation. The learning rate controls the step size during weight updates, where excessively high values may induce oscillatory behaviour and harder convergence, while excessively low values demand an increased number of iterations. The momentum coefficient incorporates prior weight increments from previous iterations to improve learning and avoid local minima, however, excessive momentum may lead to overshoot minima, whereas low values yield slow convergence. Optimal tuning of those aforementioned hyperparameters is therefore critical to ensure stable, efficient, and accelerated neural network training (Diaz et al., 2017; Lima et al., 2023b).

The hyperparameters were defined based on the lowest coefficient of determination (R^2), obtained using the optimization algorithm (DE) in combination with the Back-Propagation algorithm. All models used the ReLU activation function, which was the most efficient among the three activation functions studied (Glorot et al., 2011). Table 2 details the value of HPO for each defined model. The four selected models correspond to the networks with the best analysis results obtained for one and two hidden layers. It is noticed that the higher the number of hidden layers, the best the predictions. However, previous analysis showed that the improvement of the predicted values for larger amounts of hidden layers did not increase much compared to the quantities herein used. Therefore, these numbers were selected once they demanded shorter processing time.

4.2 RF approach

Non-linear analysis approaches were evaluated using the RF methodology, examining the influence of parameter correlation methods on the prediction analysis. The RF model was optimized using the DE algorithm, where the following hyperparameters and its amount optimized were established: the number of decision trees (103), the maximum depth of each tree (30), and the minimum number of samples per split node (4).

4.3 Training and testing process

In various ML techniques, the learning of the model is developed in the training phase. Using the total data in this stage could lead to generalisation errors; therefore, a testing phase is included to check the model performance. The data must be split into training and testing sets to perform the analysis. A commonly used training/test ratio is 70/30% or 80/20% respectively (Jeremiah et al., 2021). In this study, both ANN and RF models adopted a random distribution data of 80% for training and 20% for testing.

4.4 Software implementation

The ANN and RF models described previously were implemented and executed using the Machine Learning module of the Tyche software (Tyche, 2023) developed at the Computational Methods and Artificial Intelligence Laboratory (LAMCIA) of the University of Brasilia; the software also includes hyperparameter optimization (HPO) strategies.

Table 2. ANN HPO values.

Model	No. Inputs	No. Hidden layers	No. Hidden neurons	Learning rate	Momentum coefficient
1	9	1	60	9.25	0.70
2	9	2	44/42	61.89	0.50
3	14	1	30	0.003	0.98
4	14	2	71/342	2.33	0.30



The codes have been successfully utilized by other studies (Oliveira et al., 2019; Borges et al., 2020; Evangelista Junior & Almeida, 2021; Chaves et al., 2023; Lima et al., 2023a, b; Silva et al., 2023).

4.5 Performance metrics criteria

The performance of the ANN and RF models was validated using statistical analysis by comparing the predicted values with the actual results in the dataset of the Sand-GM shear strength interface. This procedure is carried out for both the training and testing phase. The Coefficient of Determination (R^2) and the Root Mean Squared Error ($RMSE$) were used as evaluation methods for the models, which are given in Equation 1 and Equation 2, respectively. Error-values close to 0 and R^2 close to 1 outline a better model performance.

$$R^2 = 1 - \frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{\sum_{i=1}^n (y_i - \bar{y})^2} \quad (1)$$

$$RMSE = \sqrt{\frac{1}{n} * \sum_{i=1}^n (y_i - \hat{y}_i)^2} \quad (2)$$

where n is the number of data, y_i is the observed value, \hat{y}_i the predicted value and \bar{y} the mean of the observed values.

5. Results and discussions

5.1 Model performance assessment

Once the predicted values are computed in each model and phase (training and testing), they can be compared to the actual values obtained from the laboratory tests gathered in the reference data. These comparisons are presented graphically in Figure 6 and Figure 7 and are also summarized in Table 3. The regression line in the centre of the graphs represents the relationship between the two data sets. The proximity of the data points to the trend line indicates a high R^2 value, which is a better accuracy of the model predictions. For ANN model

(Figure 6a-d and Figure 7a-d), the sequence of the numbers is: number of input parameters, number of neurons in each hidden layer (according to Table 2, models 1 and 3 have one hidden layers and model 2 and 4 with two hidden layers), and the amount of output parameter.

As observed in the results, for this study, using a higher number of inputs leads to greater accuracy (higher R^2 and lower $RMSE$) in the predicted data according to the compared statistical criteria for the ANN models. Incorporating GM thickness, type of test, and contact area into the analysis enhances the model's learning process, even though these parameters may exhibit low linear correlation or correspond to nominal values. The two-layer model shows a better learning process, as the R^2 value is higher than the one-layer model. A similar condition was observed by Ali et al. (2022), who evaluated and compared three ANN models varying the number of neurons, algorithms, and hidden layers for predicting the pull-out capacity of geosynthetic reinforced soil. It is also possible to observe that the RF methodology indicated a better performance between the input parameters and the interface interaction compared to the ANN models.

According to the results, the ANN model with 14 inputs with two hidden layers and the nonlinear model of the RF methodology demonstrate the highest accuracy in predicting the sand-GM interface shear strength values. From a statistical perspective, both models outlined reasonable predictions. However, the random forest model obtained the higher R^2 value and lower $RMSE$ in training and testing sets.

The percentages of residual values exceeding $\pm 5^\circ$, which represents the difference between the predicted and actual friction angles, were calculated for each phase to also validate the model accuracy. The ANN model shows 4% and 11.6% for the training and testing data set, respectively, while the RF model showed 3% and 8.1% for the training and testing data set, respectively. This relation indicates that for the used data, the later methodology (RF) is more accurate. Figure 8 and Figure 9 displays the frequency histograms of the aforementioned residual values. The disparities between predicted and actual values may stem from the statistical variability in the collected data for the various parameters utilized. This variability enhances the training process of the network (or other ML techniques). However, the model incorporates correlation factors between each data point to establish a response, which can result in outcome variations.

Table 3. Performance results of all ML models.

ML Algorithm	Model	Description	Training		Testing	
			R^2	$RMSE$	R^2	$RMSE$
ANN	1	1 h-layer, 9 inputs	0.871	2.49	0.734	3.50
	2	2 h-layer, 9 inputs	0.888	2.32	0.721	3.61
	3	1 h-layer, 14 inputs	0.916	2.00	0.780	3.22
	4	2 h-layer, 14 inputs	0.919	1.92	0.852	3.36
Linear analysis	1	Linear approach	0.630	4.25	0.630	5.07
RF	1	Non-linear approach	0.930	1.94	0.920	2.09



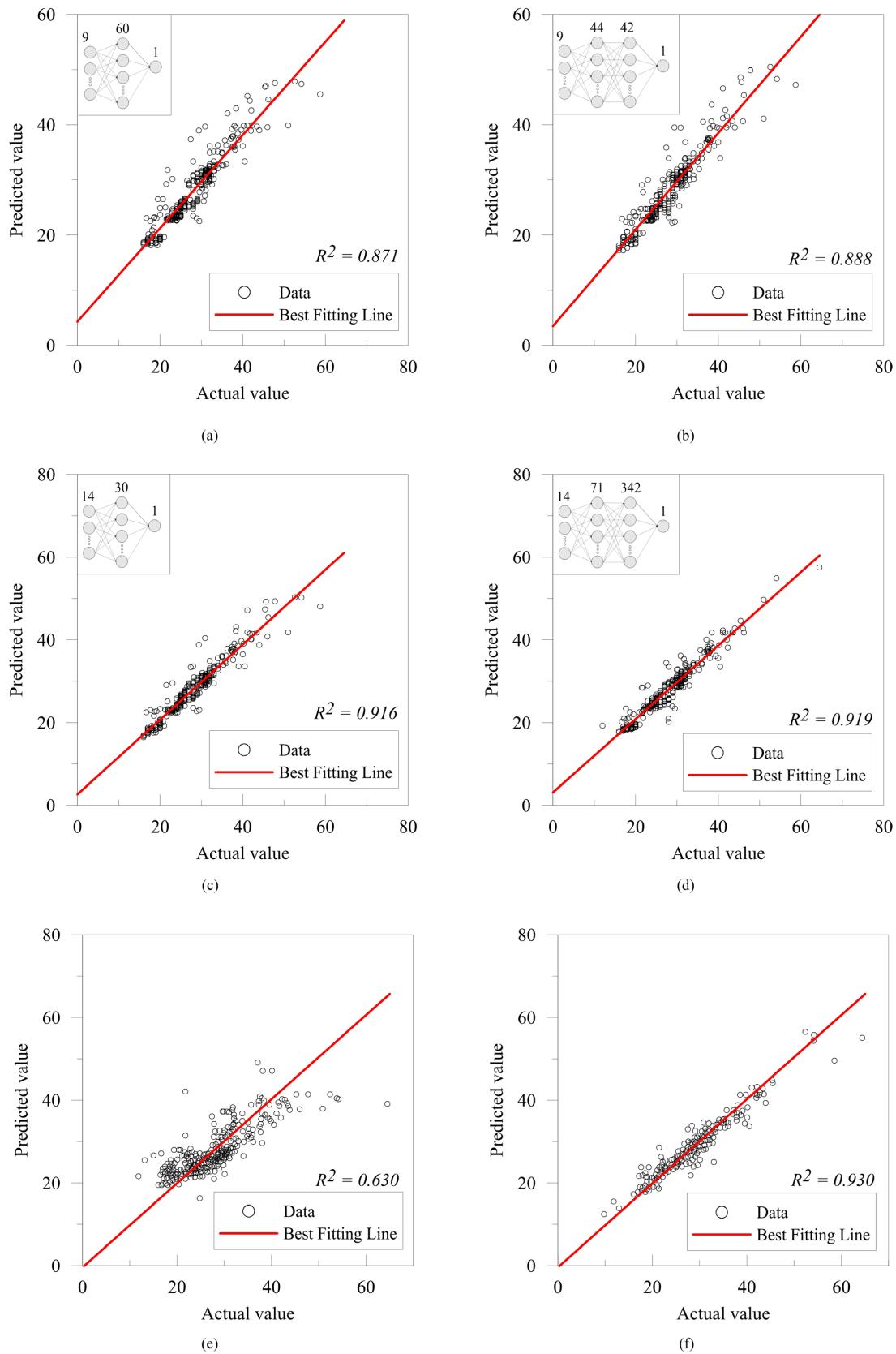


Figure 6. Actual and predicted interface friction angle between geomembrane and sand values for training dataset in each model: (a) Model ANN 9-60-1; (b) Model ANN 9-44-42-1; (c) Model ANN 14-30-1; (d) Model ANN 14-71-342-1; (e) linear analysis and (f) Model RF non-linear.



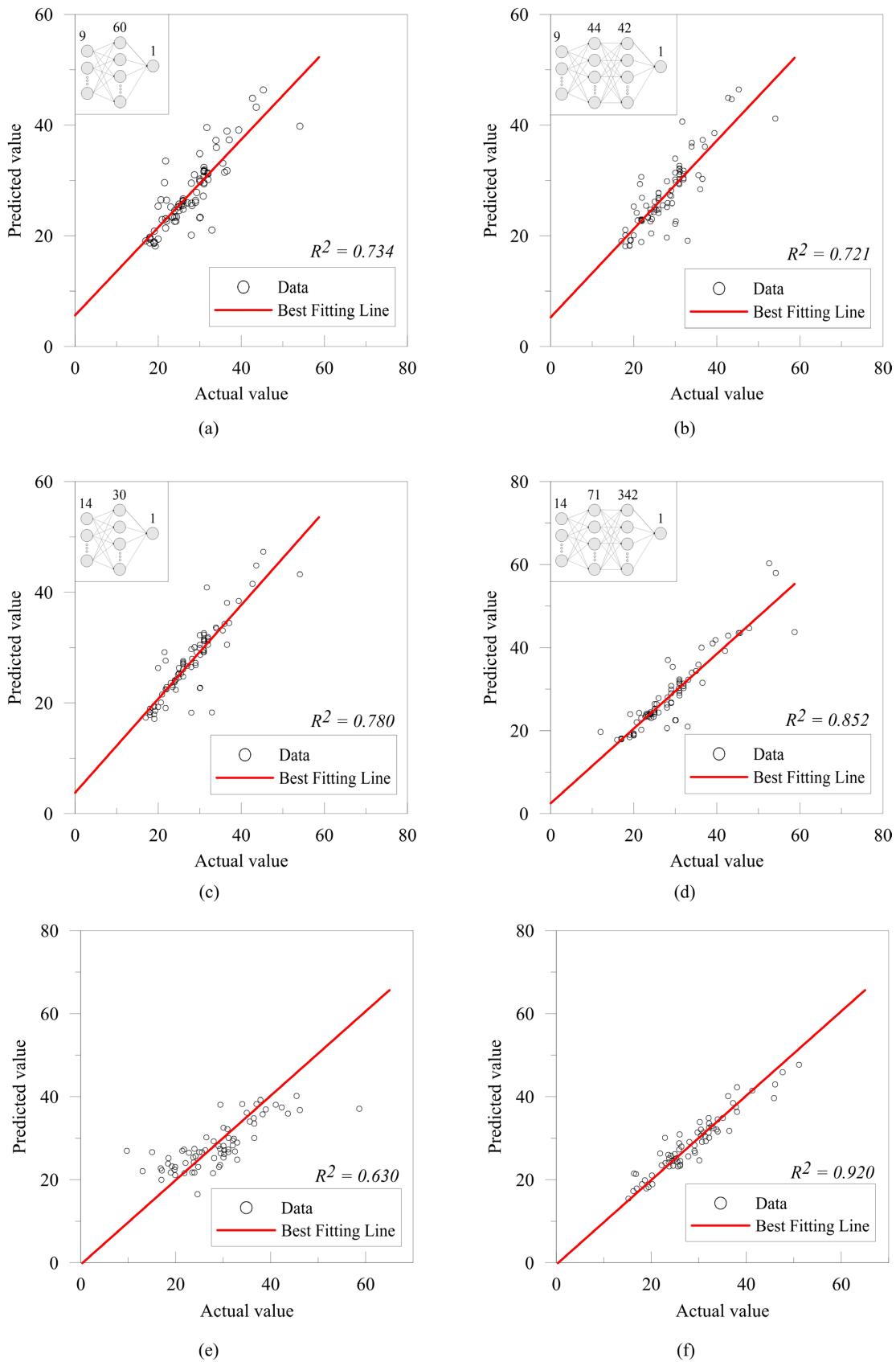


Figure 7. Actual and predicted values for testing dataset in each model: (a) Model ANN 9-60-1; (b) Model ANN 9-44-42-1; (c) Model ANN 14-30-1; (d) Model ANN 14-71-342-1; (e) linear analysis and (f) Model RF non-linear.



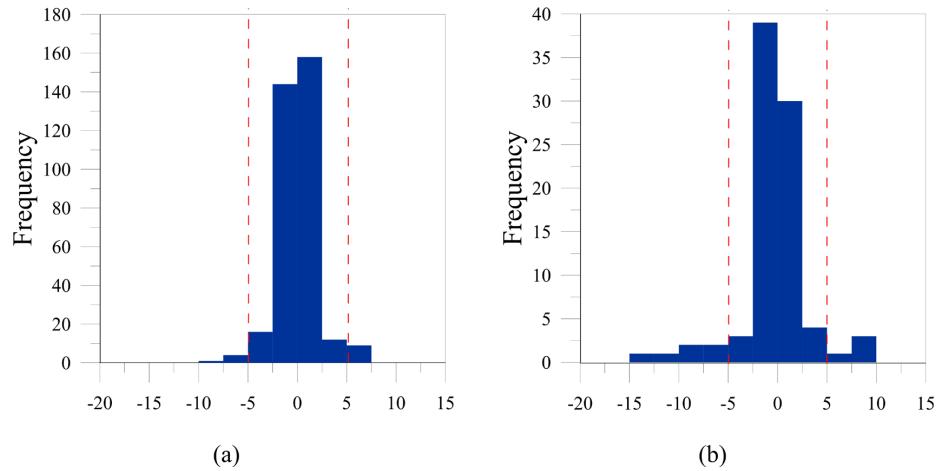


Figure 8. Histogram of residual values for ANN model: (a) Training set; (b) Testing set.

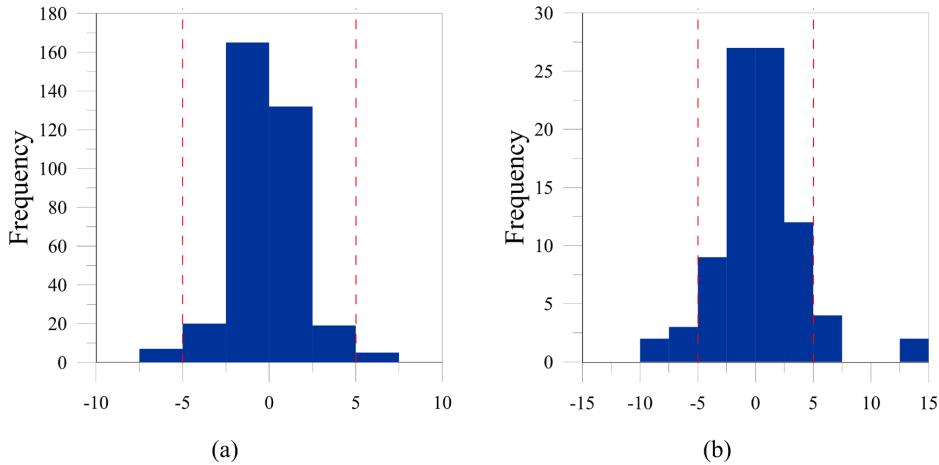


Figure 9. Histogram of residual values for RF model: (a) Training set; (b) Testing set.

A greater quantity of samples could enhance the network's training phase, potentially leading to increased accuracy in residual values (Chao et al., 2021; Hasthi et al., 2022).

5.2 Feature importance analysis

The random forest algorithm can evaluate the significance of a variable by examining the impact on prediction error. In contrast, the OOB data for that variable is randomly permuted and keeps other variables unchanged (Liaw & Wiener, 2002) and the variable values are shuffled randomly for the OOB observations to determine the importance of a specific predictor. The difference between the misclassification rates of the modified and original OOB data, divided by the standard error, quantifies the variable's importance. This analysis helps identify the main factors influencing the model's predictions (Nyongesa, 2020). This method, known as permutation feature importance, directly estimate the influence of each predictor

by observing how randomly reshuffling the variable affects the model's performance. The relative importance factors of the variables range from 0% to 100%, with the most crucial variable always having a relative importance of 100%. In order to compare these results to the Pearson's heatmap matrix, the latter values were considered only in modulus, since RF analysis outlines only positive values. It is important to point out that it is not recommended to normalize Pearson's Heatmap matrix values once they already vary from 0 to 1 in modulus, and they were just adjusted to be presented as a percentage. As the linear coefficient is calculating between each variable (not considering others), the only way of having a value equal to one is when the variable's coefficient is calculated with itself.

Figure 10 illustrates the decreasing importance of variables in the sand-GM interface shear strength for the 14 influencing parameters evaluated by RF and Pearson's Matrix Heatmap. It can be seen that, except for the asperity height, normal stress and sand relative density, the values presented by the



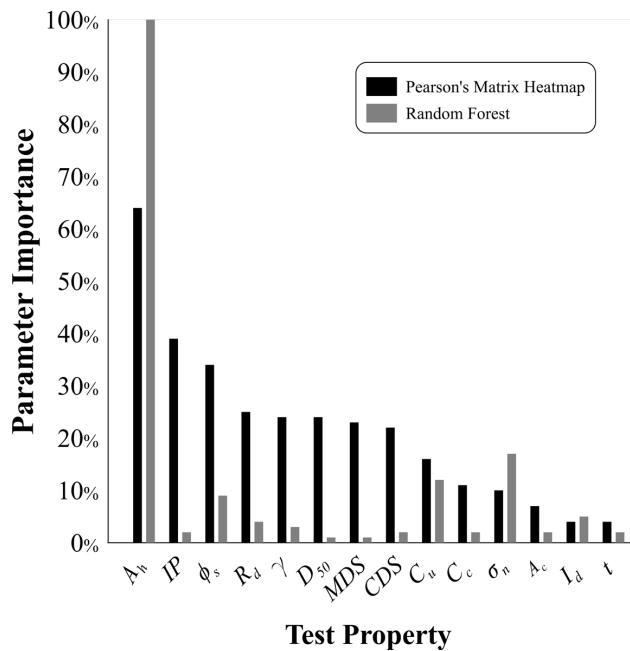


Figure 10. Importance of influential parameters.

Pearson matrix are much higher than the ones presented by the Random Forest analysis. This is attributed to the fact that the Pearson matrix is calculated based on a direct relation between the analysed property and the interface shear strength, which is different from the Random Forest method herein used. Similar to the ρ_r , the RF analysis revealed that the asperity height of the geomembrane exhibited the strongest impact on the interface shear strength, which is consistent with the results obtained in previous studies conducted by Stark et al. (1996), Lopes et al. (2001), Frost et al. (2012), Bacas et al. (2015), Cen et al. (2018), Aratijo et al. (2022) and Costa Junior et al. (2023). In all these cases, there was an increment of the interface friction angle values for textured GM comparing with smooth GM due to the fact that the asperities block soil movement over the geomembrane.

According to the RF method, the applied normal stress was the second parameter ranked in terms of importance regarding the interface shear strength due to the need of higher shear stress to generate the interface failure (Negussey et al., 1989; Dove & Frost, 1999; Fleming et al., 2006; Sharma et al., 2007; Fox & Thielmann, 2014; Sánchez, 2018; Lashkari & Jamali, 2021; Afzali-Nejad et al., 2017; Chen et al., 2021; Khan & Latha, 2023). However, this was not observed in the Person's matrix, where the second most influential parameter was soil friction angle. The presented values showed that both factors influence on the results and the differences can also be attributed to how each method calculates this influence.

Overall, the results displayed that the soils properties such as soil friction angle (ϕ_s), Soil median grain size (D_{50}), Uniformity Coefficient (C_u), Coefficient of Curvature (C_c), Relative density (I_d) and specific weight (γ) have an influence on the interface shear strength and this is in accordance with

other investigations related to laboratory measurements (Costa e Lopes, 2001; Afonso, 2009; Choudhary & Krishna, 2016; Markou & Evangelou, 2018; Cen et al., 2018; Lashkari & Jamali, 2021; Ari & Akbulut, 2022; Khan & Latha, 2023). Among the soil properties (ϕ_s , γ , I_d , D_{50} , C_u and C_c), the Pearson's heatmap matrix indicated that ϕ_s , γ and D_{50} have the highest influence on the interface strength while the Random Forest analysis outlined C_u , ϕ_s , and I_d . Even though the observed differences, it can be noticed that the soil friction angle, soil relative density (related to the value of γ) and the grain size distribution have medium influence on the interface shear strength. The laboratory tests have shown this trend, but the analysis herein performed could quantify these effects comparing the different properties.

Regarding experiment settings, when observing the obtained values for the type of test, IP test has the higher influence for both methods herein utilized and the other two type of tests (CDS and MDS) presented slightly differences on the shear resistance depending on the used test. On the other hand, displacement rate (R_d) presented a high influence on the interface shear strength based on the Pearson's matrix heat map and this influence was lower considering the RF analysis. This test configuration does influence the result over conducted laboratory tests as presented by the literature (Moraci et al., 2014; Carbone et al., 2015; Pavanello et al., 2021).

Both Machine Learning and linear regression methods outlined a very low influence of the geomembrane thickness (t) and contact area (A_c) on the interface resistance (Dove & Frost, 1999; Lima Junior, 2000; Wasti & Özدüzgün, 2001; Hsieh & Hsieh, 2003; Aguiar, 2008; Pitanga et al., 2009; Moraci et al., 2014; Sánchez, 2018). In order to assess if these properties influence on the interface, ML analysis were performed with and without them in the dataset. The results showed that despite the low linear correlation and higher data dispersion of these properties, including them in the analysis improved the model's ability to train the utilized data.

6. Conclusions

This study evaluated the use of two ML methodologies for predicting interface shear strength values between sand and GM. The dataset included 495 samples with 14 influencing parameters and interface friction angle results from laboratory tests. Four ANN models with varying inputs and hidden layers and a RF model following a nonlinear approach were implemented. Based on the relationship between predicted and actual values, the evaluation criteria utilized two statistical measures, R^2 and $RMSE$. The findings indicated the following conclusions:

- Overall, both Machine Learning methodologies (Random Forest and Artificial Neural Network) proved to be suitable for predicting interface friction angle results based on the collected data considering different types of experiments;



- Linear correlation (Pearson's coefficient) and the non-linear RF approach showed similar results for several influential factors on the interface shear strength, and the differences found are likely due to how each method does the calculation. The data analysis revealed that the GM asperity height had the most significant impact on interface shear strength. Soil properties and applied normal stress also found with considerable influence. The aforementioned is consistent with laboratory results obtained in different studies. The use of more data may improve the training and analysis of ML methodologies;
- The ANN model consisting of 14 inputs and two hidden layers exhibited the best predicted accuracy compared to the other three architectures for the analysed data. More hidden layers generated similar R^2 value but with more computational consuming time on the training and prediction process. Furthermore, the non-linear RF model demonstrated the highest accuracy in predicting interface strength values, slightly outperforming the ANN model.

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Declaration of interest

The authors have no conflicts of interest to declare. All co-authors have observed and affirmed the contents of the paper and there is no financial interest to report.

Authors' contributions

Anderson Villamil: conceptualization, data curation, visualization, writing – original draft. Abenezer Tefera Tanga: conceptualization, data curation, visualization, writing – original draft. Gregório Luís Silva Araújo: formal analysis, funding acquisition, investigation, methodology, project administration, resources. Francisco Evangelista Junior: supervision, validation, software writing – review & editing.

Data availability

Data generated and analysed in the course of the current study are not publicly available due to copyrights.

Declaration of use of generative artificial intelligence

This work was prepared with the assistance of generative artificial intelligence (GenAI) ChatGPT and Tyche software, with the aim of translation and for improving the quality of texts, data analysis and results, respectively. The entire process of using this tool was supervised, reviewed and when necessary edited by the authors. The authors assume full responsibility for the content of the publication that involved the aid of GenAI.

List of symbols and abbreviations

n	Number of samples, data (dimensionless)
t	Geomembrane thickness (mm)
\bar{y}	Mean actual value
y_i	Actual value
\hat{y}_i	Expected or predicted value
A_c	Contact area (cm^2)
A_h	Geomembrane asperity height (mm)
AI	Artificial Intelligence
ANN	Artificial Neural Network
BP	Backpropagation
C_c	Coefficient of curvature (dimensionless)
CDS	Conventional Direct Shear test
C_u	Uniformity coefficient (dimensionless)
CV	Coefficient of Variation
DE	Differential Evolution
D_{50}	Soil median grain size (mm)
EA	Evolutionary Algorithms
GM	Geomembrane(s)
HPO	Hyperparameter Optimisation
I_d	Sand relative density (%)
IP	Inclined Plane test
MDS	Medium Direct Shear test
ML	Machine Learning
MLP	Multi-Layer Perceptron
OOB	Out-Of-Bag
R_d	Displacement rate of the test (mm/min)
R^2	Coefficient of Determination
R^2	Coefficient of Determination
ReLU	Rectified Linear Unit function
RF	Random Forest
RMSE	Root Mean Squared Error
γ	Soil unit weight (kN/m^3)
δ'	Friction angle interface ($^\circ$)
ρ_r	Pearson correlation coefficient
σ_n	Normal stress (kPa)
σ_{STD}	Standard deviation (dimensionless)
ϕ_s	Friction angle of soil ($^\circ$)

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