Notebook

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Contents

1	Geo	ometry 1
	1.1	Miscellaneous Geometry
	1.2	Convex Hull
2	Dat	a Structures
	2.1	Trie
	2.2	Binary Indexed Tree
	2.3	Lazy Segment Tree
	2.4	Union Find
3	Mat	thematics
	3.1	Matrix
	3.2	Fast Fourier Transform
		Extended Euclidean Algorithm
4	Mis	cellaneous 13
	4.1	vim settings
1	G	Seometry
1.	1 I	Miscellaneous Geometry
		de <bits stdc++.h=""> namespace std;</bits>
	-	ef double type; e EPS = 1e-12;
st	ty	<pre>point { pe x, y; pint(type xp = 0.0, type yp = 0.0) { x = xp; y = yp; } }</pre>

```
point(const point &p) {
        x = p.x;
        y = p.y;
    point operator+ (const point &p) const { return point(x+p.x, y+p.y); }
    point operator - (const point &p) const { return point(x-p.x, y-p.y); }
    point operator* (type c) { return point(c*x, c*y); }
    point operator/ (type c) { return point (x/c, y/c); }
    bool operator < (const point &p) {
        return x < p.x \mid | x = p.x \&\& y < p.y;
    }
};
type \ dot(point \ p, \ point \ q) \quad \{ \ \underline{return} \ p.x*q.x+p.y*q.y; \ \}
type \ dist(point \ p, \ point \ q) \quad \{ \ return \ sqrt(dot(p-q,p-q)); \ \}
type cross(point p, point q) { return p.x*q.y-p.y*q.x; }
point projectInLine(point c, point a, point b) {
    return a + (b-a)*dot(c-a, b-a)/dot(b-a, b-a);
point projectInSegment(point c, point a, point b) {
    point lineP = projectInLine(c, a, b);
    type maxDist = max(dist(a, lineP), dist(b, lineP));
    if (maxDist > dist(a, b)) 
        if (dist(a, c) > dist(b, c)) return b;
        else return a;
    else return lineP;
}
int main() {
    point a(0, 0), b(1, 1), c(1, 0);
    c = projectInSegment(c, a, b);
    printf("%lf %lf\n", c.x, c.y);
1.2
    Convex Hull
// This solves problem E on codeforces gym 101484
#include <bits/stdc++.h>
using namespace std;
typedef long long type;
double EPS = 1e-12;
```

```
struct point {
    type x, y;
    point(type xp = 0, type yp = 0)  {
         x = xp;
         y = yp;
    }
    bool operator < (const point &p) const {</pre>
         return x < p.x | | x = p.x \&\& y < p.y;
    }
};
type cross(point p, point q) { return p.x*q.y-p.y*q.x; }
double side(point a, point b, point c) {
    return cross(a, b) + cross(b, c) + cross(c, a);
}
vector<point> convex_hull(vector<point> p) {
    int n = p.size(), k = 0;
    if (n == 1) return p;
    vector < point > hull(2*n);
    sort(p.begin(), p.end());
    for (int i=0; i< n; i++)
         // use <= when including collinear points
         while (k \ge 2 \&\& (side(hull[k-2], hull[k-1], p[i]) < 0)) k--;
         hull[k++] = p[i];
    }
    for (int i=n-2, t=k+1; i>=0; i--) {
         while (k)=t \&\& (side(hull[k-2], hull[k-1], p[i]) < 0)) k--;
         hull[k++] = p[i];
    }
    hull.resize(k-1);
    return hull;
}
\operatorname{set} < \operatorname{point} > \operatorname{v1}, \operatorname{v2};
int main() {
    int n, m; scanf("%d %d", &n, &m);
    vector < point > h;
    for (int i=0; i< n; i++) {
```

```
int a, b; scanf("%d %d", &a, &b);
        point c = point(a, b);
        v1.insert(c); h.push_back(c);
    for (int i=0; i \le m; i++) {
        int a, b; scanf("%d %d", &a, &b);
        point c = point(a, b);
        v2.insert(c); h.push_back(c);
    h = convex_hull(h);
    if (v1. find(h[0]) != v1.end()) {
        for (int i=0; i< h. size(); i++)
             if (v2.find(h[i]) != v2.end()) {
                 printf("NO\backslashn"); return 0;
    }
    else {
        for (int i=0; i< h. size(); i++)
             if (v1.find(h[i]) != v1.end()) {
                 printf("NO\n"); return 0;
    printf("YES\n");
}
```

2 Data Structures

2.1 Trie

```
const int A = 26;

typedef struct trie {
    struct node {
        int to [A], freq, end;
    };
    struct node t [N];
    int sz = 0;
    int offset = 'a';

    // init trie
    void init() {
        memset(t, 0, sizeof(struct node));
    }
    // insert string
    void insert(char *s, int p = 0) {
        t[p].freq++;
}
```

```
if (*s == 0) {
            t[p].end++;
            return;
        if (t[p].to[*s - offset] == 0)
            t[p].to[*s - offset] = ++sz;
        insert(s+1, t[p].to[*s - offset]);
    }
    // check if string is on trie
    int find (char *s, int p = 0) {
        if (*s == 0)
            return t[p].end;
        if (t[p].to[*s - offset] == 0)
            return false;
        return find (s+1, t[p].to[*s - offset]);
    }
    // count the number of strings that have this prefix
    int count(char *s, int p = 0) {
        if (*s == 0)
            return t[p].freq;
        if (t[p].to[*s - offset] == 0)
            return 0;
        return count (s+1, t[p].to[*s - offset]);
    }
    // erase a string
    int erase (char *s, int p = 0) {
        if (*s = 0 \&\& t[p].end) {
            ---t[p].end;
            return —t[p].freq;
        if ((*s = 0 \&\& t[p].end = 0) || t[p].to[*s - offset] = 0)
            return -1;
        int count = erase(s+1, t[p].to[*s - offset]);
        if (count = 0)
            t[p].to[*s - offset] = 0;
        if (count = -1)
            return -1;
        return —t[p].freq;
} trie;
```

2.2 Binary Indexed Tree

```
int b[N];
int update(int p, int val, int n) {
    for (; p < n; p += p \& -p) b[p] += val;
}
int getsum(int p) {
    int sum = 0;
    for (; p != 0; p -= p \& -p) {
        sum += b[p];
    return sum;
}
2.3
    Lazy Segment Tree
// This solves HORRIBLE on SPOJ
#include <bits/stdc++.h>
using namespace std;
typedef long long lli;
const lli N = 1e5 + 5;
const lli inf = 1791791791;
/* type: 0 = \min
         1 = \max
         2 = \text{sum } */
template <int type> struct seg_tree {
    lli seg[4*N];
    lli lazy[4*N];
    seg_tree() {
        memset(seg, 0, sizeof(seg));
        memset(lazy, 0, sizeof(lazy));
    }
    void do_lazy(lli root, lli ll, lli rl) {
        if (type == 2)
            seg[root] += (rl-ll+1)*lazy[root];
        else
            seg[root] += lazy[root];
        if (ll != rl) {
            lazy[2*root+1] += lazy[root];
            lazy [2*root+2] += lazy [root];
        }
```

```
lazy[root] = 0;
   }
    // sum update
    lli update (lli l, lli r, lli val, lli ll = 0, lli rl = N-1, lli root = 0) {
        do_lazy(root, ll, rl);
        if (r < 11 \mid | 1 > r1) return seg[root];
        if (ll >= l && rl <= r) {
            lazy[root] += val;
            do_lazy(root, ll, rl);
            return seg[root];
        lli update_left = update(l, r, val, ll, (ll+rl)/2, 2*root+1);
        lli update_right = update(1, r, val, (11+r1)/2+1, rl, 2*root+2);
        if (type = 0)
            return seg[root] = min(update_left, update_right);
        if (type = 1)
            return seg[root] = max(update_left, update_right);
        if (type == 2)
            return seg[root] = update_left + update_right;
   }
    lli query(lli l, lli r, lli ll = 0, lli rl = N-1, int root = 0) {
        do_lazy(root, ll, rl);
        if (r < 11 | | 1 > r1) {
            if (type = 0)
                return inf;
            if (type = 1)
                return -inf;
            if (type == 2)
                return 0;
        if (11 >= 1 \&\& rl <= r) return seg[root];
        lli query_left = query(l, r, ll, (ll+rl)/2, 2*root+1);
        lli query_right = query(1, r, (ll+rl)/2+1, rl, 2*root+2);
        if (type = 0)
            return min(query_left , query_right);
        if (type == 1)
            return max(query_left , query_right);
        if (type = 2)
            return query_left + query_right;
   }
};
int main() {
    int t; scanf("%d", &t);
```

```
while (t--) {
        int n, c; scanf("%d %d", &n, &c);
         seg\_tree < 2 > t;
         while (c--) {
             int op, l, r;
             scanf("%d %d %d", &op, &l, &r);
             1 - -; r - -;
             if (op = 0) {
                 int v; scanf("%d", &v);
                 t.update(1, r, v);
             }
             else
                  printf("%lld \n", t.query(l, r));
        }
    }
}
2.4 Union Find
#include <bits/stdc++.h>
using namespace std;
const int N = 5e5 + 5;
int p[N], w[N];
int find(int x) {
    \mathbf{return} \ p[x] = (x \Longrightarrow p[x] ? x : find(p[x]));
}
void join(int a, int b) {
    if ((a = find(a)) = (b = find(b))) return;
    if (w[a] < w[b]) swap(a, b);
    w[a] += w[b];
    p[b] = a;
}
int main() {
    int n;
    scanf("%d", &n);
    for (int i=0; i< n; i++)
        w[p[i] = i] = 1;
    return 0;
}
```

3 Mathematics

3.1 Matrix

```
// This solves problem MAIN74 on SPOJ
#include <bits/stdc++.h>
using namespace std;
const int mod = 1e9 + 7;
template <int n> struct matrix {
    long long mat[n][n];
    matrix () {
        memset (mat, 0, sizeof (mat));
    matrix (long long temp[n][n]) {
        memcpy (mat, temp, size of (mat));
    void identity() {
        memset\ (mat\,,\ 0\,,\ \underline{sizeof}\ (mat\,)\,)\,;
        for (int i=0; i< n; i++)
            mat[i][i] = 1;
    matrix<n> operator* (const matrix<n> &a) const {
        matrix<n> temp;
        for (int i=0; i< n; i++)
             for (int j=0; j< n; j++)
                 for (int k=0; k< n; k++)
                     temp.mat[i][j] += mat[i][k]*a.mat[k][j];
        return temp;
    matrix<n> operator% (long long m) {
        matrix < n > temp (mat);
        for (int i=0; i < n; i++)
             for (int j=0; j< n; j++)
                 temp.mat[i][j] %= m;
        return temp;
    matrix <n> pow(long long e, long long m) {
        matrix<n> temp;
        if (e == 0) {
             temp.identity();
             return temp%m;
        if (e == 1) {
             memcpy (temp.mat, mat, sizeof (temp.mat));
```

```
return temp%m;
        }
        temp = pow(e/2, m);
        if (e \% 2 = 0)
            return (temp*temp)%m;
        else
            return (((temp*temp)\%m)*pow(1, m))\%m;
    }
};
int main() {
    int t;
    scanf("%d", &t);
    while (t--) {
        long long n;
        scanf("%lld", &n);
        matrix <2> m;
        long long temp[2][2] = \{\{1, 1\}, \{1, 0\}\};
        memcpy (m.mat, temp, size of (m.mat));
        m = m.pow(n+2, mod);
        if (n == 0) m. mat [0][0] = 0;
        if (n == 1) m.mat[0][0] = 2;
        printf("%lld \n", m.mat[0][0]);
    return 0;
}
3.2
     Fast Fourier Transform
// This solves VFMUL on SPOJ
#include <bits/stdc++.h>
using namespace std;
#define PI 3.14159265359
const int N = 3e5 + 5;
typedef complex<double> base;
// p[0]*x^0 + p[1]*x + ...
void fft(vector<base> &p, bool inverse) {
    if (p.size() = 1)
        return;
    int n = p.size();
    vector <base> a [2];
    for (int i=0; i< n; i++)
```

```
a[i %2].push_back(p[i]);
    for (int i=0; i<2; i++)
        fft(a[i], inverse);
    double theta = (2*PI/n)*(inverse ? -1 : 1);
    base w(1), wn(cos(theta), sin(theta));
    for (int i=0; i< n/2; i++) {
        p[i] = (a[0][i] + w * a[1][i]) / (base)(inverse ? 2 : 1);
        p[i+n/2] = (a[0][i] - w * a[1][i]) / (base)(inverse ? 2 : 1);
        w = wn;
    }
}
// c ends being a*b
void multiply (vector < int > &a, vector < int > &b, vector < int > &c) {
    vector < base > na(a.begin(), a.end()), nb(b.begin(), b.end());
    int n = 1;
    while (n < max(a.size(), b.size())) n <<= 1;
    n <<= 1;
    na.resize(n); nb.resize(n);
    fft(na, false); fft(nb, false);
    for (int i=0; i< n; i++) {
        na[i] *= nb[i];
    fft (na, true);
    c.resize(n);
    for (int i=0; i< n; i++)
        c[i] = (int)(na[i].real() + 0.5);
}
int main() {
    int t; scanf("%d", &t);
    while (t--) {
        char s1 [N], s2 [N];
        scanf("%s %s", s1, s2);
        int n1 = strlen(s1), n2 = strlen(s2);
        vector < int > a, b, c;
        for (int i=n1-1; i>=0; i--)
            a.push_back(s1[i]-'0');
        for (int i=n2-1; i>=0; i--)
            b. push_back(s2[i]-'0');
        multiply(a, b, c);
```

```
c.resize(2*c.size());
for (int i=0;i<c.size()-1;i++) {
      c[i+1] += c[i]/10;
      c[i] %= 10;
}

int found = 0;
for (int i=c.size()-1;i>=0; i--) {
      if (c[i]!= 0) found = 1;
        if (found) printf("%c", c[i] + '0');
    }
    if (!found) printf("0");
    printf("\n");
}
return 0;
}
```

3.3 Extended Euclidean Algorithm

```
// This solves 10104 on UVa
#include <bits/stdc++.h>
using namespace std;
typedef long long 11;
11 ext(11 a, 11 b, 11 &x, 11 &y) {
    if (a == 0) {
         x = 0;
         y = 1;
         return b;
    }
    ll x1, y1;
    11 \text{ gcd} = \text{ext}(b\%a, a, x1, y1);
    x = y1 - (b/a)*x1;
    y = x1;
    return gcd;
}
int main() {
     while (scanf("%lld %lld", &a, &b) != EOF) {
         11 x, y;
         11 \operatorname{gcd} = \operatorname{ext}(a, b, x, y);
```

```
if (a == b && x > y) swap(x, y);
    printf("%lld %lld %lld \n", x, y, gcd);
}
return 0;
}
```

4 Miscellaneous

4.1 vim settings

```
set ai si noet ts=4 sw=4 sta sm nu rnu inoremap <NL> <ESC>o nnoremap <NL> o inoremap <C-up> <C-o>:m-2<CR> inoremap <C-down> <C-o>:m+1<CR> nnoremap <C-up> :m-2<CR> nnoremap <C-down> :m+1<CR> vnoremap <C-down> :m+1<CR> vnoremap <C-up> :m-2<CR>gv vnoremap <C-down> :m'>+1<CR>gv syntax on colors evening highlight Normal ctermbg=none "No background highlight nonText ctermbg=none
```