

# Scalable Distributed Topologies

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MEIC SDLE 2021

# Graphs

Scalable  
Distributed  
Topologies

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A graph  $G(V, E)$  can be defined by a set of vertices, and a set of edges that connect pairs of vertices. For instance, a path  $G(V = \{a, b, c, d\}, E = \{(a, b), (b, c), (c, d)\})$  can be made into a ring by adding one edge connecting its ends  $E = E \cup \{(d, a)\}$ .

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- Graphs can be directed or undirected (in which case edges are bi-directional).

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- A Simple Graph is an undirected graph with no loops and no more than one edge between any two different vertices.

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- Having an edge  $(x, y)$ , we say that those vertices are adjacent (or neighbours).
- A Weighted Graph is obtained by assigning a weight to each edge.
- Path is a sequence of vertices,  $\dots, v_i, v_{i+1}, \dots$ , with edges connecting them  $(v_i, v_{i+1}) \in E$ .

# Graphs

## Walk, Trail, Path

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**Walk** Edges and vertices can be repeated

**Trail** Only vertices can be repeated

**Path** No repeated vertices or edges



# Graphs

More topologies

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- Complete Graph. Each pair of vertices has an edge connecting them. In a sub-graph we might find a clique with that property.

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- Star. A “central” vertice and many leaf nodes connected to center

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- Planar Graph. Vertices and edges can be drawn in a plane and no two edges intersect. E.g. Rings and Trees are planar.

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In a network context, graphs with cycles allow multi-path routing. This can be more robust but data handling can become more complex. Thus, distributed algorithms often construct trees to avoid cycles, while others try to work under multi-path.

- Connected Component. Maximal connected subgraph of  $G$ .

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More concepts

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- Connected Component. Maximal connected subgraph of  $G$ .
- Degree of  $v_i$ . Number of adjacent vertices to  $v_i$ . In directed graphs there is in-degree and out-degree.



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- Distance  $d(v_i, v_j)$ . Length of the shortest path connecting those nodes.
- Eccentricity of  $v_i$ .  $ecc(v_i) = \max(\{d(v_i, v_j) | v_j \in V\})$ .
- Diameter.  $D = \max(\{ecc(v_i) | v_i \in V\})$
- Radius.  $R = \min(\{ecc(v_i) | v_i \in V\})$

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- Radius.  $R = \min(\{ecc(v_i) | v_i \in V\})$
- Center.  $\{v_i | ecc(v_i) == R\}$
- Periphery.  $\{v_i | ecc(v_i) == D\}$

- How big is the center of a tree?

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## Questions

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- How big is the center of a tree?
- How big is the center of a path?

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- How big is the center of a path?
- How big is the periphery of a ring? and the center?

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- How big is the center of a tree?
- How big is the center of a path?
- How big is the periphery of a ring? and the center?
- How to compute eccentricities?