



## Theorem

Let  $B \subseteq V$ .

$B$  is a basis iff  $\forall \vec{v} \in V$  can be written as a l.c. of vectors in  $B$  in a unique way.

Proof ( $\Leftarrow$ ):

Suppose every vector  $\vec{v}$  in  $V$  can be written as a unique l.c. of vectors in  $B = \{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_n\}$ .

WTS  $B$  is a basis for  $V$

WTS  $B$  is l.t. and  $\text{span}(B) = V$

WTS  $\text{span}(B) = V$ :

$\text{span}(B) \subseteq V$  by def of span

??  
 $V \subseteq \text{span}(B)$

Let  $\vec{v} \in V$ . WTS  $\vec{v} \in \text{span}(B)$

By hyp  $\exists r_1, \dots, r_n$  in  $\mathbb{R}$  s.t.  $\vec{v} = r_1 \vec{b}_1 + \dots + r_n \vec{b}_n$

i.e.  $\vec{v} \in \text{span}(B)$

WTS  $B$  is l.t.:

Suppose  $r_1 \vec{b}_1 + \dots + r_n \vec{b}_n = \vec{0}$ . WTS  $r_1 = r_2 = \dots = r_n = 0$

Note  $\vec{0} = 0\vec{b}_1 + 0\vec{b}_2 + \dots + 0\vec{b}_n$

Since  $\vec{0}$  can be written as a l.c. of  $\vec{b}_i$  uniquely.

Then it must be the case that  $r_1 = r_2 = \dots = r_n = 0$

### Theorem 3.3.7: Rank-nullity Theorem

For any  $n \times m$  matrix  $A$ ,

$$\dim(\text{Ker } A) + \dim(\text{im } A) = m$$

$$\dim(\text{Nul } A) + \dim(\text{col } A) = m$$

$$\text{Ker } T_A = \{ \vec{x} \mid A\vec{x} = \vec{0} \}$$

= solution set to  $A\vec{x} = \vec{0}$

$$\text{e.g. } [A \mid \vec{0}] \sim \left[ \begin{array}{cccc|c} 1 & 2 & 0 & -1 & 0 \\ 0 & 0 & 1 & 5 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

$$\text{Ker } T_A = \left\{ t \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix} + s \begin{pmatrix} 1 \\ 0 \\ -5 \\ 1 \end{pmatrix}, t, s \in \mathbb{R} \right\}$$

$$= \text{span} \left( \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -5 \\ 1 \end{bmatrix} \right)$$

$$I = \left\{ \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ -5 \\ 1 \end{pmatrix} \right\} \text{ is a spanning set for } \text{Ker } T_A$$

By Theorem 3.2.5,  $I$  is also L.I.

$I$  is a basis  $\text{Ker } T_A = \text{Nul } A$

$$\dim \text{Ker } T_A = \dim \text{Nul } A = 2 \quad \# \text{ of non pivot cols in } \text{rref}(A)$$

$$\text{img } T_A = \{ A\vec{x} \mid \vec{x} \in \mathbb{R}^m \} = \text{span}(\vec{a}_1, \dots, \vec{a}_m) = \text{col } A$$

$\{ \vec{a}_1, \dots, \vec{a}_m \}$  is a spanning set for  $\text{img } T_A$

but  $\{ \vec{a}_1, \dots, \vec{a}_m \}$  may not be a basis for  $\text{img } T_A$

e.g.  $[A | \vec{0}] \sim \left[ \begin{array}{cccc|c} 1 & 2 & 0 & -1 & 0 \\ 0 & 0 & 1 & 5 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$

$t=1, s=0 \quad \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix} \quad A \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix} = \vec{0} \quad \left[ \begin{array}{cccc} \frac{1}{\vec{a}_1} & \frac{1}{\vec{a}_2} & \frac{1}{\vec{a}_3} & \frac{1}{\vec{a}_4} \end{array} \right] \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} = \vec{0} \quad \xRightarrow{\text{Theorem 3.8}} \vec{a}_2 = 2\vec{a}_1$

$t=0, s=1 \quad \begin{pmatrix} 1 \\ 0 \\ -5 \\ 1 \end{pmatrix} \quad A \begin{pmatrix} 1 \\ 0 \\ -5 \\ 1 \end{pmatrix} = \vec{0} \quad \vec{a}_4 = -\vec{a}_1 + 5\vec{a}_3$

$\text{span}(\vec{a}_1, \vec{a}_3) = \text{span}(\vec{a}_1, \vec{a}_2, \vec{a}_3, \vec{a}_4) \therefore \vec{a}_2 \text{ and } \vec{a}_4 \text{ is redundant}$

$\{\vec{a}_1, \vec{a}_3\}$  is a basis for  $T_A$

$\left[ \begin{array}{cc|c} 1 & 1 & 1 \\ \vec{a}_1 & \vec{a}_2 & \vec{0} \\ 1 & 1 & 1 \end{array} \right] \sim \left[ \begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right] \Rightarrow r\vec{a}_1 + s\vec{a}_2 = \vec{0} \Rightarrow r=s=0$

$\dim \text{img } T_A = 2 = \# \text{ of pivot cols in } \text{rref}(T_A).$

$\therefore \dim \text{Ker } T_A + \dim \text{img } T_A = m$

$\left( \begin{array}{c} \# \text{ of non-pivot} \\ \text{cols of } \text{rref}(A) \end{array} \right) + \left( \begin{array}{c} \# \text{ of pivot cols} \\ \text{of } \text{rref}(A) \end{array} \right) = \text{total } \# \text{ of cols of } A$

**Theorem:** General Rank Nullity Theorem

Suppose  $V$  and  $W$  are v.s., and  $T: V \rightarrow W$  be a L.T.

$\dim \text{ker } T + \dim \text{img } T = \dim V$

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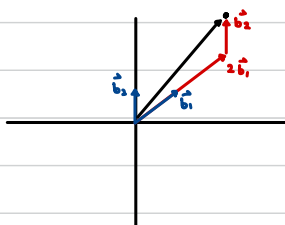
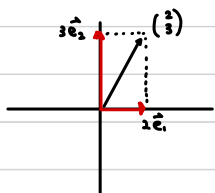
## Ex 1

$$B = \{\vec{e}_1, \vec{e}_2\}$$

$$B = \left\{ \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$$

$$\begin{pmatrix} 2 \\ 3 \end{pmatrix} = 2\vec{e}_1 + 3\vec{e}_2$$

$$\begin{pmatrix} 2 \\ 3 \end{pmatrix} = 2 \begin{pmatrix} 0 \\ 1 \end{pmatrix} + 1 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$



Let  $V$  be a v.s.  $\dim V = n$ . Let  $B = (\vec{b}_1, \dots, \vec{b}_n)$  be an ordered basis for  $V$ .

e.g.  $\mathbb{R}^2 \quad \{\vec{e}_1, \vec{e}_2\} = \{\vec{e}_2, \vec{e}_1\}$

$$\vec{v} = \begin{pmatrix} 2 \\ 3 \end{pmatrix} = 2\vec{e}_1 + 3\vec{e}_2$$

$\mathcal{E} = (\vec{e}_1, \vec{e}_2)$  be an ordered basis

$$\forall \vec{v} \in V, \vec{v} = r_1 \vec{b}_1 + \dots + r_n \vec{b}_n$$

## Def:

$B$  coordinate of  $\vec{v}$  in  $V$  to be

$$[\vec{v}]_B = \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_n \end{bmatrix}$$

e.g.  $V = P_2 = \{a_0 + a_1 x + a_2 x^2 \mid a_1, a_2, a_0 \in \mathbb{R}\}$

$$B_1 = (1, x, x^2), \quad p(x) = 2x + 3x^2 \in P_2$$

$$[p(x)]_{B_1} = \begin{pmatrix} 0 \\ 2 \\ 3 \end{pmatrix}$$

$$= \underbrace{0(1)}_{r_1} + \underbrace{2x}_{r_2} + \underbrace{3x^2}_{r_3}$$

$$B_2 = (x, 1, x^2), \quad p(x) = 2x + 0(1) + 3x^2$$

$$[p(x)]_{B_2} = \begin{pmatrix} 2 \\ 0 \\ 3 \end{pmatrix}$$

e.g. continued...

$\{1, 1+x, 1+x+x^2\}$  is a basis for  $P_2$

$$r_1 + r_2(1+x) + r_3(1+x+x^2) = \vec{0}$$

$$(r_1 + r_2 + r_3) + (r_2 + r_3)x + r_3x^2 = 0 + 0x + 0x^2$$

$$\begin{cases} r_1 + r_2 + r_3 = 0 \\ r_2 + r_3 = 0 \\ r_3 = 0 \end{cases} \Rightarrow \begin{matrix} r_1 = 0 \\ r_2 = 0 \\ r_3 = 0 \end{matrix} \quad \{1, 1+x, 1+x+x^2\} \text{ is a L.I.}$$

$$B_3 = (\overset{\vec{b}_1}{1}, \overset{\vec{b}_2}{1+x}, \overset{\vec{b}_3}{1+x+x^2})$$

$$[p(x)]_{B_3} = \begin{pmatrix} -2 \\ -1 \\ 3 \end{pmatrix}$$

$$2x + 3x^2 = r_1(1) + r_2(1+x) + r_3(1+x+x^2)$$

$$2x + 3x^2 = (r_1 + r_2 + r_3)(1) + (r_2 + r_3)x + r_3x^2$$

$$\begin{cases} r_1 + r_2 + r_3 = 0 \\ r_2 + r_3 = 2 \\ r_3 = 3 \end{cases} \Rightarrow \begin{matrix} r_1 = -2 \\ r_2 = -1 \\ r_3 = 3 \end{matrix}$$

Ex 2

$$V = \mathbb{R}^2 \quad \vec{v} = \begin{pmatrix} 2 \\ 3 \end{pmatrix} \in \mathbb{R}^2$$

$$\mathcal{E} = (\vec{e}_1, \vec{e}_2) \quad \vec{v} = [\vec{v}]_{\mathcal{E}} = \begin{pmatrix} 2 \\ 3 \end{pmatrix} \quad \vec{v} \text{ of a coordinate with respect to } \mathcal{E}.$$

$$B = \left( \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right) \quad [\vec{v}]_B = \begin{pmatrix} -1 \\ 3 \end{pmatrix} \quad \vec{v} = r_1 \vec{b}_1 + r_2 \vec{b}_2$$

$$\begin{pmatrix} 2 \\ 3 \end{pmatrix} = r_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + r_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\underbrace{\begin{bmatrix} 1 & 1 \\ \vec{b}_1 & \vec{b}_2 \\ 1 & 1 \end{bmatrix}}_S \begin{bmatrix} r_1 \\ r_2 \end{bmatrix} = \vec{v}$$

$$\left[ \begin{array}{cc|c} 1 & 1 & 2 \\ 0 & 1 & 3 \end{array} \right] \sim \left[ \begin{array}{cc|c} 1 & 0 & -1 \\ 0 & 1 & 3 \end{array} \right] \Rightarrow \begin{matrix} r_1 = -1 \\ r_2 = 3 \end{matrix}$$

↑  
must get unique solution

$$S[\vec{v}]_B = [\vec{v}]_{\mathcal{E}} \quad T_S : \mathbb{R}^2 \rightarrow \mathbb{R}^2$$
$$\vec{x} \mapsto S\vec{x}$$