



Sec 3.1 Reading

Def 3.1.1: Image of a Function

The image of a function consists of all the values the function takes in its target space. If f is a function from X to Y , then

$$\begin{aligned}\text{image}(f) &= \{f(x) : x \in X\} \\ &= \{b \in Y : b = f(x), \text{ for some } x \in X\}\end{aligned}$$

Ex 1

Describe the image of the L.T.

$$T(\vec{x}) = A\vec{x} \quad \text{from } \mathbb{R}^2 \text{ to } \mathbb{R}^3, \quad \text{where } A = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix}$$

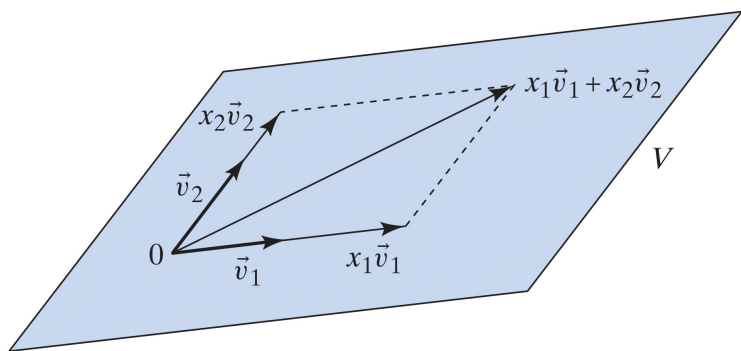
The image of T consists of all vectors of the form

$$\begin{aligned}T \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} &= \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \\ &= x_1 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}\end{aligned}$$

that is, all linear combinations of the column vectors of A ,

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \quad \text{and} \quad \vec{v}_2 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$\text{Image}(T)$ is the plane V spanned by \vec{v}_1 and \vec{v}_2 .



Def 3.1.2: Span

Consider the vectors $\vec{v}_1, \dots, \vec{v}_m$ in \mathbb{R}^n . The set of all linear combinations $c_1\vec{v}_1 + \dots + c_m\vec{v}_m$ of the vectors $\vec{v}_1, \dots, \vec{v}_m$ is called their **span**:

$$\text{Span}(\vec{v}_1, \dots, \vec{v}_m) = \{ c_1\vec{v}_1 + \dots + c_m\vec{v}_m \mid c_1, \dots, c_m \in \mathbb{R} \}$$

Theorem 3.1.3: Image of a L.T.

The image of a L.T. $T(\vec{x}) = A\vec{x}$ is the **span** of the column vectors of A . We denote the image of T by $\text{im}(T)$ or $\text{im}(A)$.

Proof:

$$T(\vec{x}) = A\vec{x} = \begin{bmatrix} | & & | \\ \vec{v}_1 & \dots & \vec{v}_m \\ | & & | \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_m \end{bmatrix} = x_1\vec{v}_1 + \dots + x_m\vec{v}_m$$

This shows that the $\text{image}(T)$ consists of all linear comb. of the column vectors $\vec{v}_1, \dots, \vec{v}_m$ of matrix A .

Thus $\text{im}(T)$ is the span of the vectors $\vec{v}_1, \dots, \vec{v}_m$

Theorem 3.1.4: Properties of the Image

The image of a L.T. $T: \mathbb{R}^m \rightarrow \mathbb{R}^n$ has the following properties.

- (i) $\vec{0} \in \mathbb{R}^n$ is in the image of T .
- (ii) The image of T is closed under addition. If \vec{v}_1 and \vec{v}_2 are in the image of T , then so is $\vec{v}_1 + \vec{v}_2$.
- (iii) The image of T is closed under scalar multiplication. If $\vec{v} \in \text{img } T$ and $k \in \mathbb{R}$, then $k\vec{v} \in \text{img } T$.

Proof

- (i) $\vec{0} = A\vec{0} = T(\vec{0})$
- (ii) There exist vectors \vec{w}_1 and \vec{w}_2 in \mathbb{R}^m s.t. $\vec{v}_1 = T(\vec{w}_1)$ and $\vec{v}_2 = T(\vec{w}_2)$. Then $\vec{v}_1 + \vec{v}_2 = T(\vec{w}_1) + T(\vec{w}_2) = T(\vec{w}_1 + \vec{w}_2)$, so that $\vec{v}_1 + \vec{v}_2$ is in the $\text{img } T$.
- (iii) If $\vec{v} = T(\vec{w})$, then $k\vec{v} = kT(\vec{w}) = T(k\vec{w})$

Ex 2

Consider an $n \times n$ matrix A . Show that $\text{im}(A^2)$ is a subset of $\text{img } A$.

$$\text{Let } \vec{b} = A^2 \vec{v} = AA\vec{v}.$$

$$\begin{aligned}\vec{b} &= A(A\vec{v}) \\ &= A\vec{w}, \quad \vec{w} = A\vec{v}\end{aligned}$$

Thus \vec{b} is in the $\text{img } A$.

Def 3.1.5: Kernel

The **kernel** of a L.T. $T(\vec{x}) = A\vec{x}$ from \mathbb{R}^m to \mathbb{R}^n consists of **all zeroes** of the transformation, that is, the **solutions** of the equation $T(\vec{x}) = A\vec{x} = \vec{0}$.

Note:

For a L.T. $T: \mathbb{R}^m \rightarrow \mathbb{R}^n$,

- (i) $\text{im } T = \{T(\vec{x}) \mid \vec{x} \in \mathbb{R}^m\}$ is a subset of the target space \mathbb{R}^n of T
- (ii) $\text{Ker } T = \{\vec{x} \in \mathbb{R}^m \mid T(\vec{x}) = \vec{0}\}$ is a subset of the domain \mathbb{R}^m of T .

Theorem 3.1.6: Properties of the Kernel

Consider a L.T. $T: \mathbb{R}^m \rightarrow \mathbb{R}^n$

- (i) The zero vector $\vec{0}$ in \mathbb{R}^m is in $\text{Ker } T$
- (ii) The Kernel is **closed under addition**.
- (iii) The Kernel is **closed under scalar multiplication**

Theorem 3.1.7: When is $\text{Ker}(A) = \{\vec{0}\}$?

- (i) Consider an $n \times m$ matrix A . Then $\text{Ker}(A) = \{\vec{0}\}$ iff $\text{rank}(A) = m$.
- (ii) Consider an $n \times m$ matrix A . If $\text{Ker}(A) = \{\vec{0}\}$, then $m \leq n$. Equivalently, if $m > n$, then there are nonzero vectors in $\text{Ker}(A)$.
- (iii) For a square matrix A , we have $\text{Ker}(A) = \{\vec{0}\}$ iff A is invertible.

Note:

For an $n \times n$ matrix A , the following statements are equivalent.

- (i) A is invertible
- (ii) The linear system $A\vec{x} = \vec{b}$ has a unique solution \vec{x} , $\forall \vec{b} \in \mathbb{R}^n$
- (iii) $\text{rref}(A) = I_n$
- (iv) $\text{rank}(A) = n$
- (v) $\text{im}(A) = \mathbb{R}^n$
- (vi) $\text{Ker}(A) = \{\vec{0}\}$