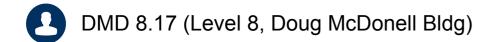


# COMP90038 Algorithms and Complexity

Lecture 24: Some Revision (with thanks to Harald Søndergaard)

#### **Toby Murray**







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#### **COMPLEXITY ANALYSIS**

# Time Complexity



ode

 $n \rightarrow \infty$  g(n)

Measure input size by natural number n
 Measure input size by natural number n
 Measure input size by natural number n
 It(n) ∈ O(g(n))
 Component to the component of the component to the component t

•  $O(g(n)), \Omega(g(n)), \Theta(g(n))$ 

Hov

G

Asym

#### $O, \Omega, \Theta$



What this tells us about how f(n) relates to O(g(n)),  $\Omega(g(n))$  and O(g(n))

• 
$$\lim_{n\to\infty} \frac{f(n)}{g(n)} = \begin{cases} 0 & f \text{ grows asymptotically slower than } g \\ c & f \text{ and } g \text{ have same order of growth} \\ \infty & f \text{ grows asymptotically faster than } g \end{cases}$$

$$f(n) \in \Theta(g(n))$$

# Analysing Recursive Algorithms



function 
$$F(n)$$
  
if  $n = 0$  then return 1  
else return  $F(n-1) \cdot n$ 

Basic operation: multiplication

We express the cost recursively (as a recurrence relation)

$$M(0) = 0$$

$$M(n) = 1$$

Need to express M(n) in **closed form** (i.e. non-recursively)

Try: "telescoping" aka "backward substitution"

# Telescoping (aka Backward Substitution)



$$M(n) = M(n-1) + 1$$

$$M(0) = 0$$

What is M(n-1)?

$$M(n-1) = M((n-1)-1) + 1$$
$$= M(n-2) + 1$$

$$M(n) = (M(n-2) + 1) + 1$$

$$= M(n-2) + 2$$

$$= (M(n-3) + 1) + 2$$

$$= M(n-3) + 3$$
...
$$= M(n-n) + n$$

$$= M(0) + n$$

$$= n$$

#### **Closed form:**

$$M(n) = n$$

#### **Complexity:**

$$M(n) \in \Theta(n)$$

#### The Master Theorem



- (A proof is in Levitin's Appendix B.)
- For integer constants  $a \ge 1$  and b > 1, and function f with  $f(n) \in \Theta(n^d)$ ,  $d \ge 0$ , the recurrence

$$T(n) = aT(n/b) + f(n)$$

(with T(1) = c) has solutions, and

$$T(n) = \begin{cases} \Theta(n^d) & \text{if } a < b^d \\ \Theta(n^d \log n) & \text{if } a = b^d \\ \Theta(n^{\log_b a}) & \text{if } a > b^d \end{cases}$$

Note that we also allow a to be greater than b.



#### **SORTING ALGORITHMS**

# Properties of Sorting Algorithms



- A Sorting algorithm is:
  - in-place if it does not require additional memory except, perhaps, for a few units of memory
  - stable if it preserves the relative order of elements with identical keys
  - input-insensitive if its running time is fairly independent of input properties other than size

#### Example: Selection Sort



```
function SelSort(A[\cdot], n)

for i \leftarrow 0 to n-2 do

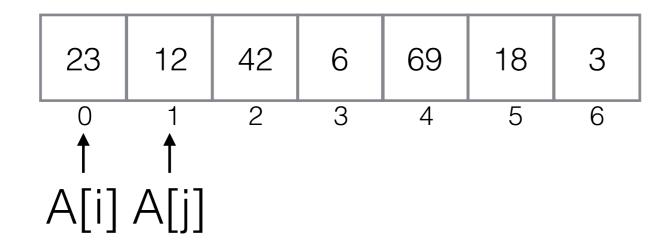
min \leftarrow i

for j \leftarrow i+1 to n-1 do

if A[j] < A[min] then

min \leftarrow j

swap A[i] and A[min]
```



min: 6

#### Example: Selection Sort



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function SelSort(A[\cdot], n)

for i \leftarrow 0 to n-2 do

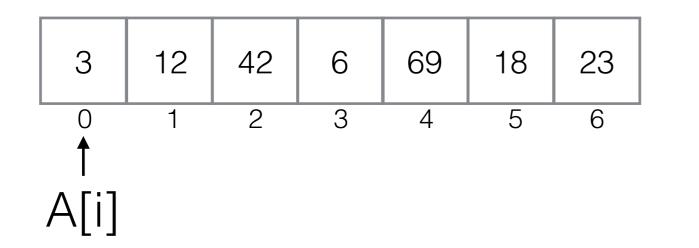
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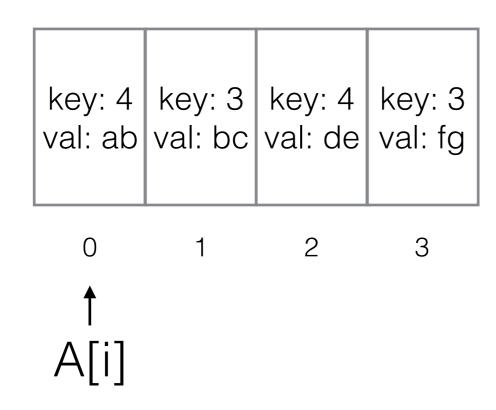
min: 6

# Properties of Selection Sort MELBOURNE

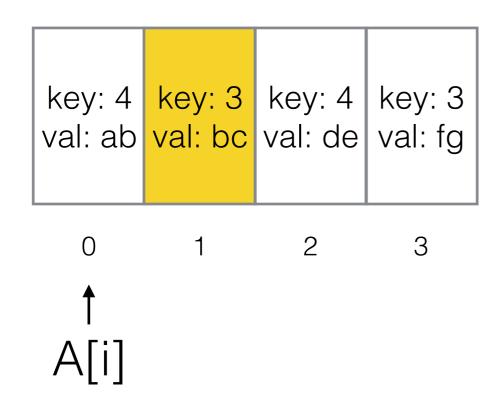


- While running time is quadratic, selection sort makes only about *n* exchanges.
- So: selection sort is a good algorithm for sorting small collections of large records.
- In-place? yes
- Stable?
- Input-insensitive? yes

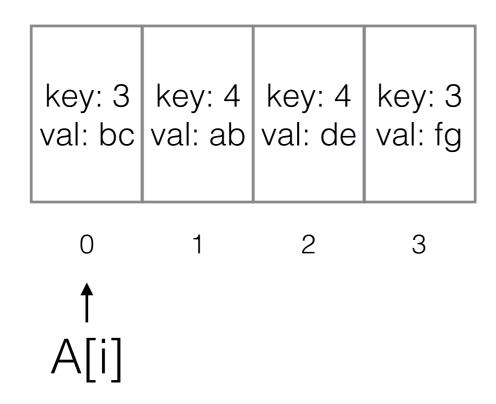




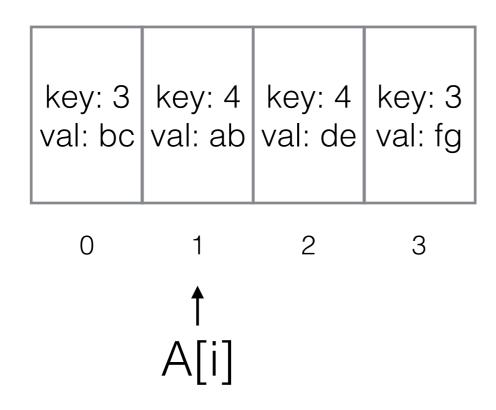




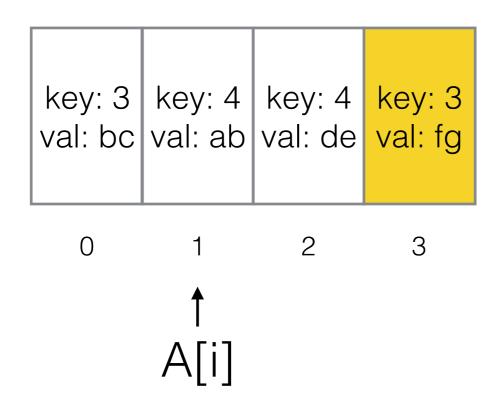




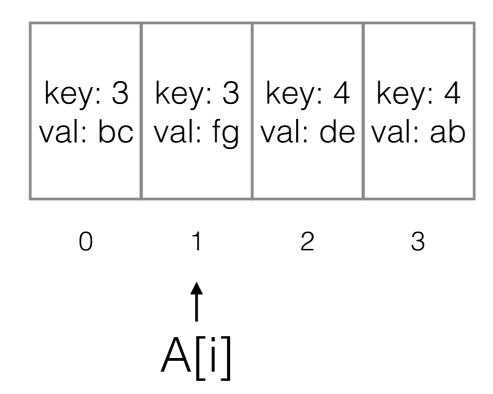












the relative order of the two "4" records has changed!

# Properties of Selection Sort MELBOURNE



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#### Insertion Sort



- Sorting an array A[0]..A[n 1]:
- To sort A[0] .. A[i] first sort A[0] .. A[i-1], then insert A[i] in its proper place

```
function INSERTIONSORT(A[\cdot], n)

for i \leftarrow 1 to n-1 do

v \leftarrow A[i]

j \leftarrow i-1

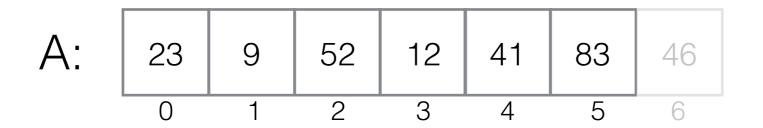
while j \geq 0 and v < A[j] do

A[j+1] \leftarrow A[j]

j \leftarrow j-1

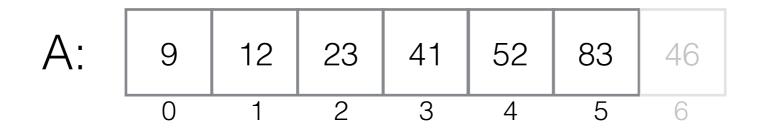
A[j+1] \leftarrow v
```



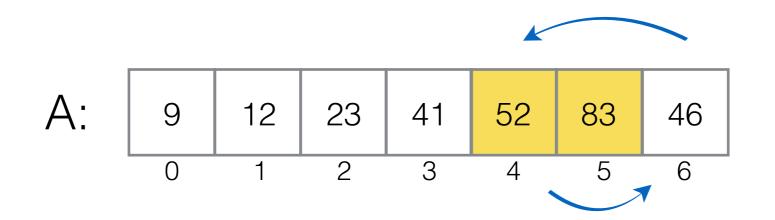


Sort first n-1 items

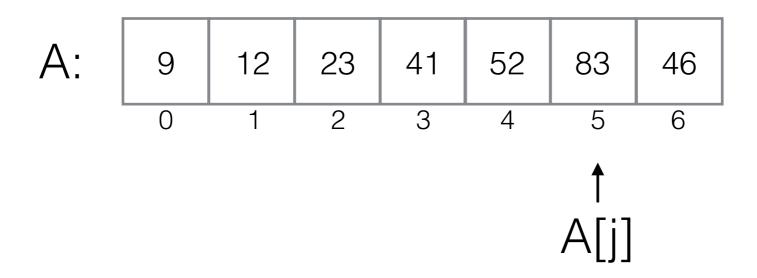




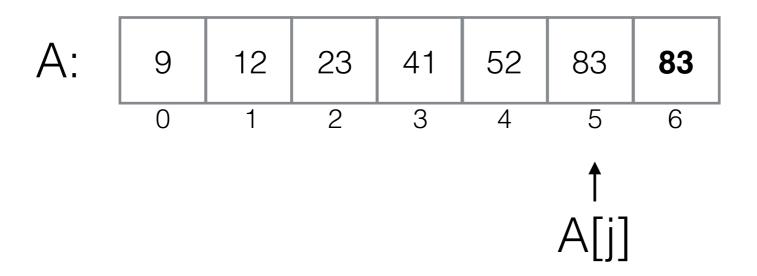




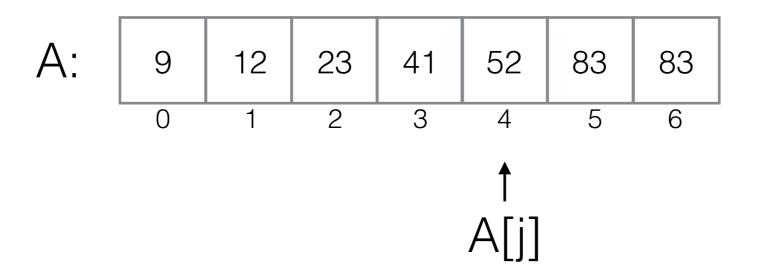




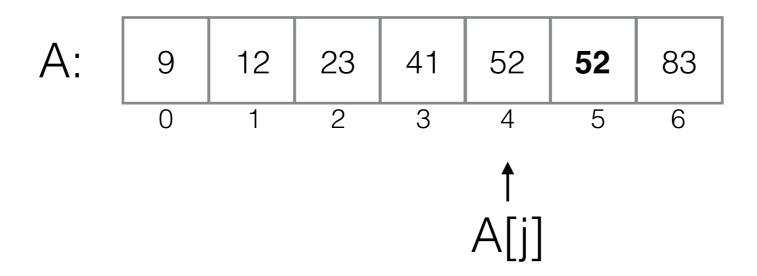




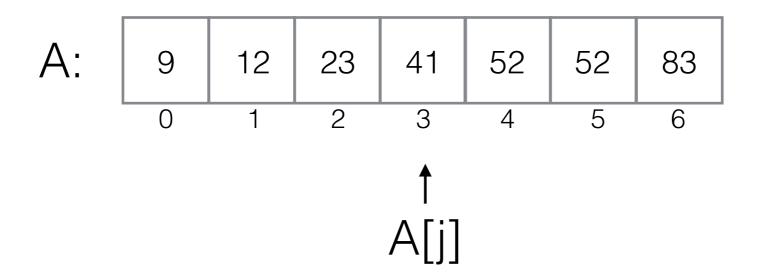




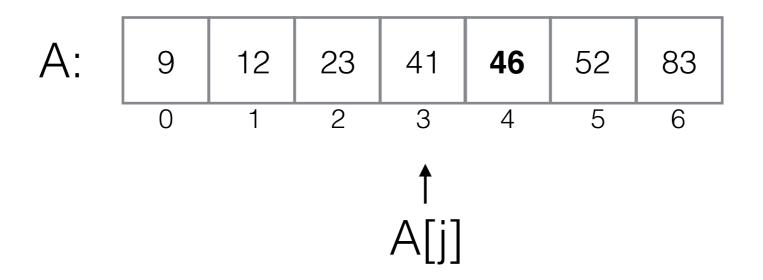




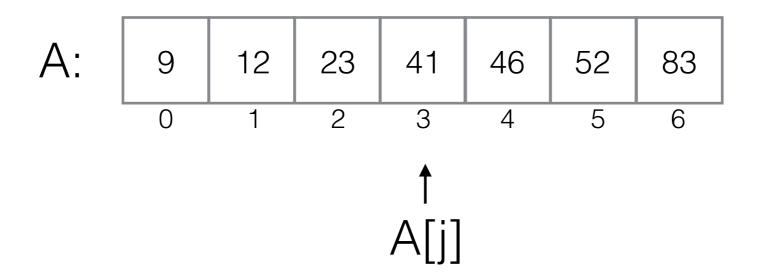












# Complexity of Insertion Sort MELBOURNE



- The for loop is traversed n 1 times. In the ith round, the test v < A[i] is performed i times, in the worst case.
- Hence the worst-case running time is

$$\sum_{i=1}^{n-1} \sum_{i=0}^{i-1} 1 = \sum_{i=1}^{n-1} i = \frac{(n-1)n}{2}$$

What does input look like in the worst case?

# Properties of Insertion Sort



- Easy to understand and implement.
- Average-case and worst-case complexity both quadratic.
- However, linear for almost-sorted input.
- Some cleverer sorting algorithms perform almost-sorting and then let insertion sort take over.
- Very good for small arrays (say, a couple of hundred elements).
- In-place? yes
- Stable?

#### Insertion Sort Stability



key: 4 val: ab	key: 3 val: bc	key: 4 val: de	key: 3 val: fg
0	1	2	3

#### Insertion Sort Stability



key: 3 val: bc	key: 4 val: ab	key: 4 val: de	key: 3 val: fg			
0	1	2	3			

#### Insertion Sort Stability



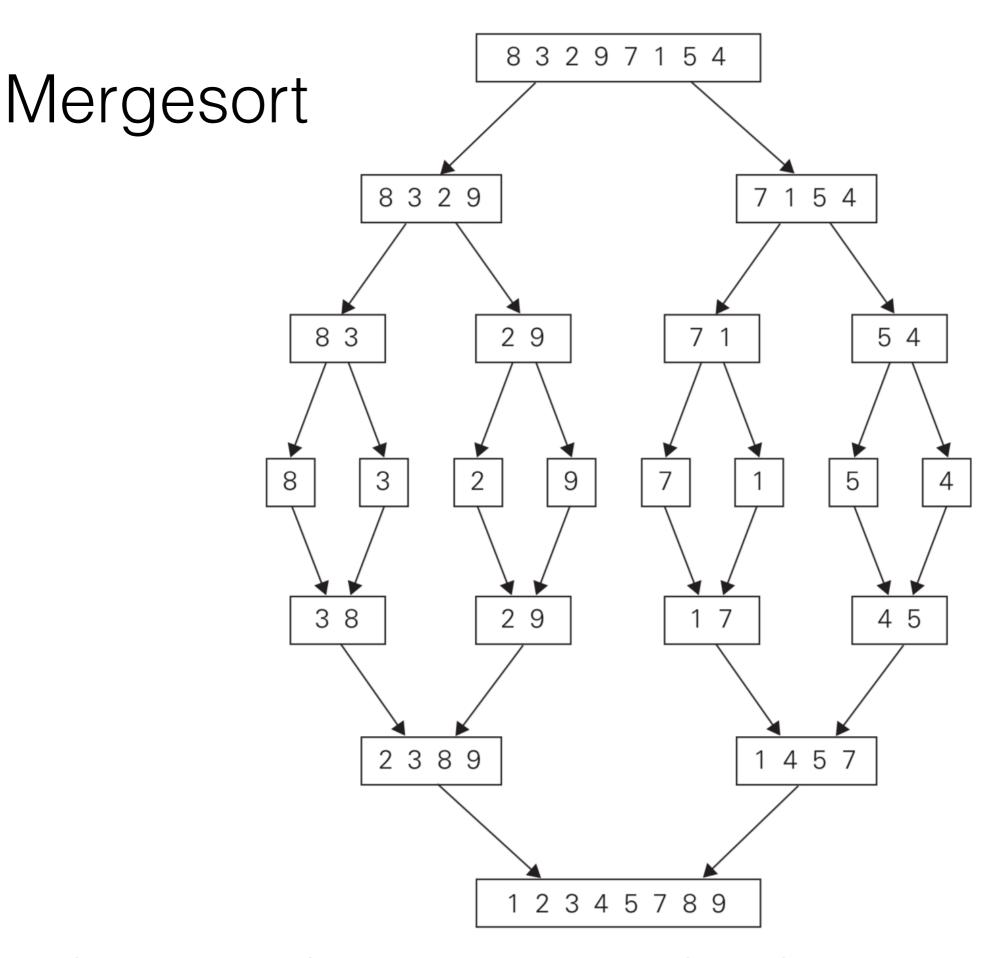
key: 3	key: 3	key: 4	key: 4
val: bc	val: fg	val: ab	val: de
0	1	2	

Stable

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# Mergesort: Analysis



- How many comparisons will MERGE need to make in the worst case, when given arrays of size [n/2] and [n/2]?
- If the largest and second-largest elements are in different arrays, then n – 1 comparisons. Hence the cost equation for Mergesort is

$$C(n) = \begin{cases} 0 & \text{if } n < 2\\ 2C(n/2) + n - 1 & \text{otherwise} \end{cases}$$

• By the Master Theorem,  $C(n) \in \Theta(n \log n)$ .

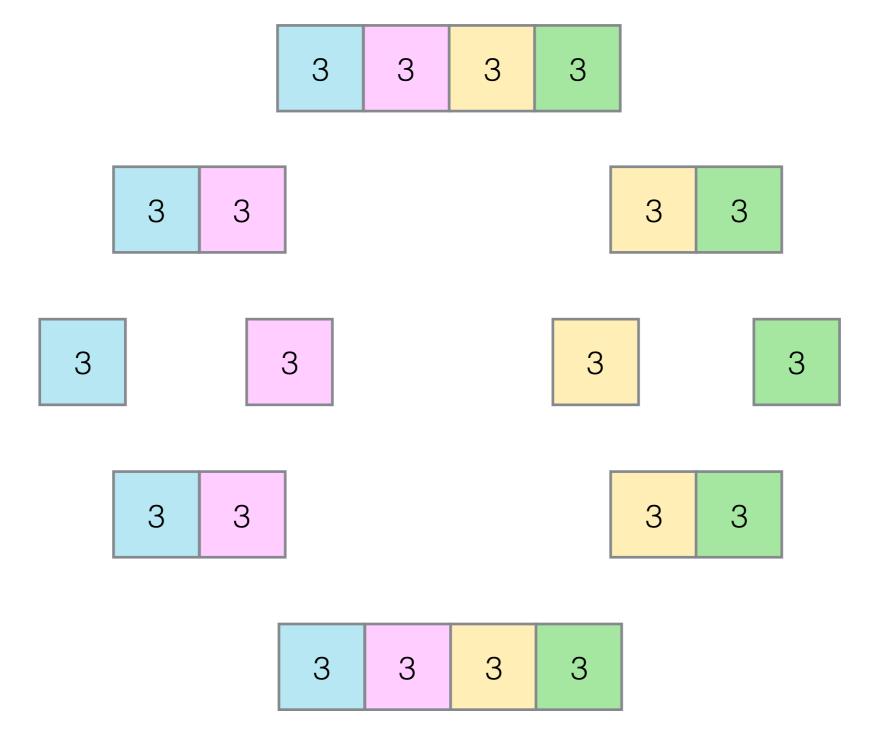
# Mergesort: Properties



- For large n, the number of comparisons made tends to be around 75% of the worst-case scenario.
- Is mergesort stable?
- Is mergesort in-place?
- If comparisons are fast, mergesort ranks between quicksort and heapsort (covered next week) for time, assuming random data.
- Mergesort is the method of choice for linked lists and for very large collections of data.

#### Mergesort: Stability





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#### Quicksort



- Quicksort takes a divide-and-conquer approach that is different to mergesort's.
- It uses the partitioning idea from QuickSelect, picking a pivot element, and partitioning the array around that, so as to obtain this situation:

$$A[0] \dots A[s-1]$$
  $A[s]$   $A[s] \dots A[n-1]$  all are  $\leq A[s]$  all are  $\geq A[s]$ 

- The element A[s] will be in its final position (it is the (s + 1)th smallest element).
- All that then needs to be done is to sort the segment to the left, recursively, as well as the segment to the right.

#### Quicksort



Very short and elegant:

```
procedure Quicksort(A[\cdot], lo, hi)

if lo < hi then

s \leftarrow \text{Partition}(A, lo, hi)

Quicksort(A, lo, s - 1)

Quicksort(A, s + 1, hi)
```

Initial call: Quicksort(A, 0, n – 1).



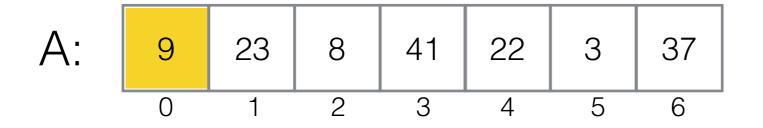
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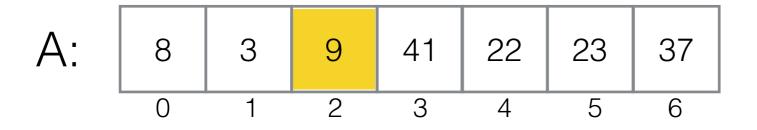
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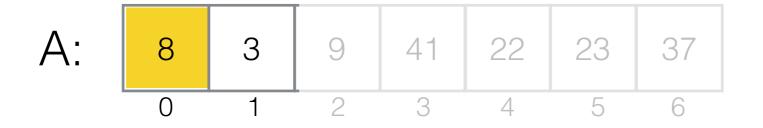
Quicksort(A, s + 1, hi)
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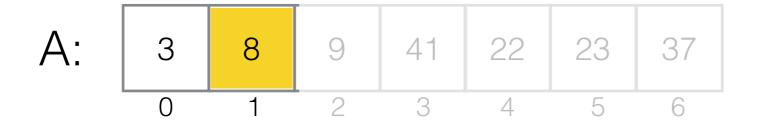
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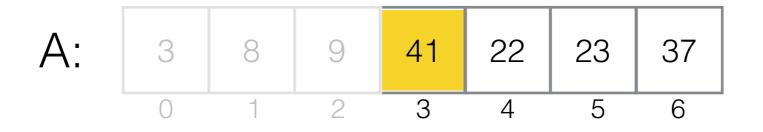
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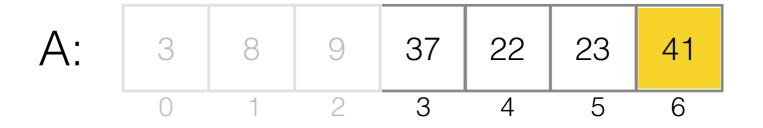
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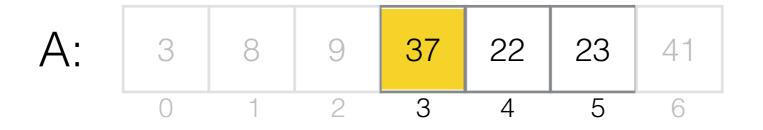
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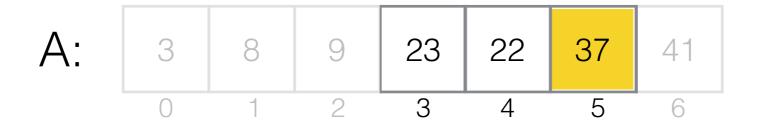
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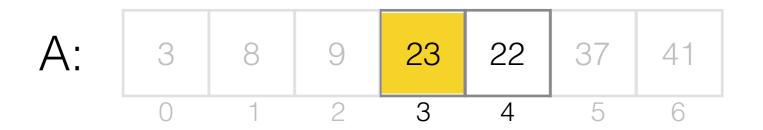
Quicksort(A, s + 1, hi)
```





```
procedure Quicksort(A[\cdot], lo, hi)

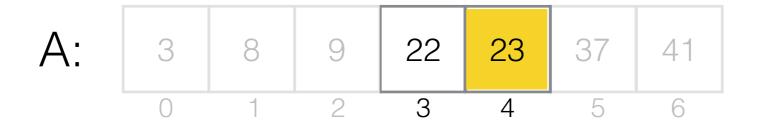
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#### Quicksort Analysis: Best Case Analysis



 The best case happens when the pivot is the median; that results in two sub-tasks of equal size.

$$C_{best}(n) = \begin{cases} 0 & \text{if } n < 2 \\ 2C_{best}(n/2) + n & \text{otherwise} \end{cases}$$

The 'n' is for the n key comparisons performed by Partition.

 By the Master Theorem, C<sub>best</sub>(n) ∈ Θ(n log n), just as for mergesort, so quicksort's best case is (asymptotically) no better than mergesort's worst case.

#### Quicksort Analysis: Worst Case Analysis



- The worst case happens if the array is already sorted.
- In that case, we don't really have divide-andconquer, because each recursive call deals with a problem size that has only been decremented by 1:

$$C_{worst}(n) = \begin{cases} 0 & \text{if } n < 2 \\ C_{worst}(n-1) + n & \text{otherwise} \end{cases}$$

• That is,  $C_{worst}(n) = n + (n - 1) + \cdots + 3 + 2 \in \Theta(n^2)$ .

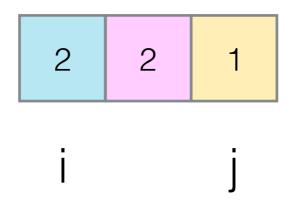
# Quicksort Properties



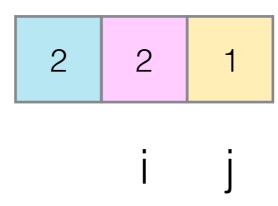
- With these (and other) improvements, quicksort is considered the best available sorting method for arrays of random data.
- A major reason for its speed is the very tight inner loop in PARTITION.
- Although mergesort has a better performance guarantee, quicksort is faster on average.
- In the best case, we get ⌈log2 n⌉ recursive levels. It can be shown that on random data, the expected number is 2 log<sub>e</sub> n ≈ 1.38 log<sub>2</sub> n. So quicksort's average behaviour is very close to the best-case behaviour.
- Is quicksort stable?
- Is it in-place?

yes

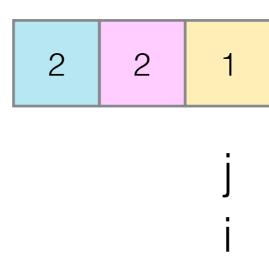




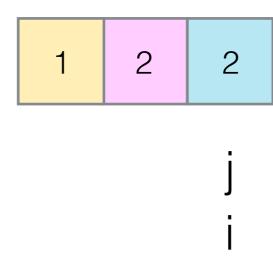














1 2 2





This is where we finished



This is where we started

Not stable

## Quicksort Properties



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