



THE UNIVERSITY OF
MELBOURNE

COMP 90048

Declarative Programming

Workshop 9 (week10)

2019 semester 1

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Tutorial : Tue 18:15 - 19:15 221 Bouverie St, room B113

Wed 17:15 - 18:15 201 Bouverie St, room B132





Outline

1. Higher order predicates
2. All solutions
 - 2a. Setof and Bagof
 - 2b. Making Use of the Backtracking Features
3. Constraint Programming
4. More on Arithmetic and prolog problem solving (not in slides)

1. Higher Order Predicate

- Predicates that take other predicates as arguments
- **call/1**: `call(:Goal)`
 - to invoke prolog predicate dynamically
 - Example: `call(write("hello"))`.
 - Example: `X = write("hello"), call(X)`.
- **call/N**: `call(:Goal, Arg1, Arg2 ...)`
 - Partial application for `:Goal`, with `Arg1, Arg2 ...` being the rest of the arguments
 - Example: `call(plus(1), 2, X)`
- **apply/2**: `apply(:Goal, [Arg1, Arg2...])`
 - Example: `apply(plus(1), [2, X])`.

1. Higher Order Predicate

- **maplist/3:** `maplist(:Goal, List1, List2)`
 - For each pair of element A and B with A from List1, B from List2, do `call(:Goal, A, B)`
 - Example: `maplist(plus(1), [1,2,3], Result).`
 - Example: `head([E|_], E).`
`maplist(head, [[1,2,3],[4,5,6],[7,8,9]], Result).`
- **maplist/2:** `maplist(:Goal, List)`
 - For each element from List1 apply goal successively until the end of list of goal fails
 - Example: `even_list(List) :- length(List, Len), Len mod 2 == 0.`
`maplist(even_list, [[1,2],[3,4,5]]).`

1. Higher Order Predicate

The SWI Prolog builtin predicate `maplist/2` is analogous to the `map/3` predicate defined in lectures, but with one less argument.

The query

```
sort([write('pear+'),write('apple')],A),maplist(call,A).
```

- Fails with no output.

- Produces output

pear+apple

then fails.

- Produces output

pear+apple

then succeeds with

```
A = [write(apple), write('pear+').]
```

- Produces output

applepear+

then succeeds with

```
A = [write(apple), write('pear+').]
```

- Single quote sign denotes atom in Prolog
- 'apple' is equivalent with apple in atomic form
- 'pear+' is not the same as pear+ so quotes remain to indicate the form as atom
- A: sort compound terms `write('pear+')` and `write('apple')` by rule of functor > arity > alphabetical order of corresponding arguments
- Maplist: perform call to each element in list equivalent to `call(write('apple'))`, `call(write('pear+'))`.



2. All Solutions

2a. setof and bagof

- Group all solutions generated by Prolog backtracking mechanism into list of solutions
- **bagof/3:** `bagof(+Template, :Goal, -Bag)`
 - Backtracking on all free variables
 - succeeds if Bag is the list of all instances of Template for which the Goal holds true, if there is no solutions found then it fails
 - Example: `bagof((Front, Back), append(Front, Back, [1,2,3]), Bag).`
 - Example: `bagof(Front, Back^append(Front, Back, [1,2,3]), Bag).`
 - Example: `bagof(X, (member(X, [1,2,2]), X > 1), Bag).`
- **setof/3:** `setof(+Template, :Goal, -Bag)`
 - Bag list is sorted with no duplicates
 - Example: `setof(X, (member(X, [1,2,2]), X > 1), Set).`

2. All Solutions

With the facts

```
win(rock,scissors).  
win(scissors,paper).  
win(paper,rock).
```

The query

```
setof(W-L,win(W,L),S).
```

- ☐ Fails.
- ☐ Succeeds with

```
S = [rock-scissors, scissors-paper, paper-rock].
```

- ☐ Succeeds with

```
S = [paper-rock, rock-scissors, scissors-paper].
```

- ☐ Succeeds with

```
S = rock-scissors ;  
S = scissors-paper ;  
S = paper-rock.
```

setof instantiate a list to contain all backtracked solutions and sort them by term comparison rule and remove duplicates

2. All Solutions

2b. Making Use of the Backing Features

- Example1: Path finding problem
 - A map is described as in the **edge** predicate
 - It describes all the direction that relates two points together
 - this predicate describes possible **moves from one state to another**
 - Each atom a, b, c ... represents a **state** (the point of location)

```
a - b - c
  |   |
d - e - f
  |   |   |
g  h - i
```

```
edge(a, east, b).
edge(b, west, a).
edge(b, south, d).
edge(b, east, c).
edge(c, west, b).
edge(c, south, e).
edge(d, north, b).
edge(d, east, e).
edge(d, south, g).
edge(e, west, d).
edge(e, north, c).
edge(e, east, f).
edge(e, south, h).
edge(f, west, e).
edge(f, south, i).
edge(g, north, d).
edge(h, north, e).
edge(h, east, i).
edge(i, west, h).
edge(i, north, f).
```


2. All Solutions

2b. Making Use of the Backing Features

- Example1: to find all the possible paths that connect from a starting point to an ending point

a - b - c
| |
d - e - f
| | |
g h - i

`path(Start, Start, [], _).`

`path(Start, End, [Move | Moves], Histories) :-`

`edge(Start, Move, Next),` Explore one move at a time, see what
is the next possible point

`\+member(Next, Histories),` Make sure that this next possible point
has not been visited yet

`path(Next, End, Moves, [Next | Histories]).`

Recursively generate the rest of the paths
from this next possible point to the target
point

2. All Solutions

2b. Making Use of the Backing Features

- Example2: Two containers problem

move(+Starting_state, -Next_state, +One_move)

```
move([Big, _], [Small, S], ([Big, 0], [Small, S]), empty(Big)).
move([Big, B], [Small, _], ([Big, B], [Small, 0]), empty(Small)).
move([Big, _], [Small, S], ([Big, Big], [Small, S]), fill(Big)).
move([Big, B], [Small, _], ([Big, B], [Small, Small]), fill(Small)).
move([Big, B], [Small, S], ([Big, B_new], [Small, S_new]), pour(Big,
Small)) :-
    pour(Small, B, S, B_new, S_new).
move([Big, B], [Small, S], ([Big, B_new], [Small, S_new]), pour(Small,
Big)) :-
    pour(Big, S, B, S_new, B_new).
```

2. All Solutions

2b. Making Use of the Backing Features

- Example2: Two containers problem
- **State** is represented as ([Big_capacity, Big_volume), ([Small_capacity, Small_volume])
- empty, fill, pour are **possible movements** that can transit from one state to another
- The move predicates **describes the starting and ending state that each of these movement** act on

2. All Solutions

2b. Making Use of the Backing Features

- **Example2: Get 4 L of water in the big container and both start with empty**

```
explore_moves(State0, State0, [], _).  
explore_moves(State_current, State_final, [Current_move | Other_moves], State_logs)  
:-  
    move(State_current, State_next, Current_move),  
    \+member(State_next, State_logs),  
    explore_moves(State_next, State_final, Other_moves, [State_next | State_logs]).  
  
containers(Moves) :- explore_moves([5, 0], [3, 0]), ([5, 4], [3, _]), Moves, [([5, 0],  
[3, 0])].
```

3. Constraint Programming

Finite Domain Constraints:

```
sudoku(Rows) :-  
  length(Rows, 9), maplist(same_length(Rows), Rows),  
  append(Rows, Vs), Vs ins 1..9,  
  maplist(all_distinct, Rows),  
  transpose(Rows, Columns),  
  maplist(all_distinct, Columns),  
  Rows = [A,B,C,D,E,F,G,H,I],  
  blocks(A, B, C), blocks(D, E, F), blocks(G, H, I).  
  blocks([], [], []).  
  blocks([A,B,C|Bs1], [D,E,F|Bs2], [G,H,I|Bs3]) :-  
  all_distinct([A,B,C,D,E,F,G,H,I]),  
  blocks(Bs1, Bs2, Bs3).
```

- A finite set of variables over a domain
 - X ins 1..9
- A finite set of constraints:
 - consistency constraint:
 - All row/col/block same length
 - Global constraint:
 - No duplicates in row/col/block
- Search techniques:
 - Backtracking



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Thank you

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