

Generating correct code for your programmers

PLISS 2025 – Part I

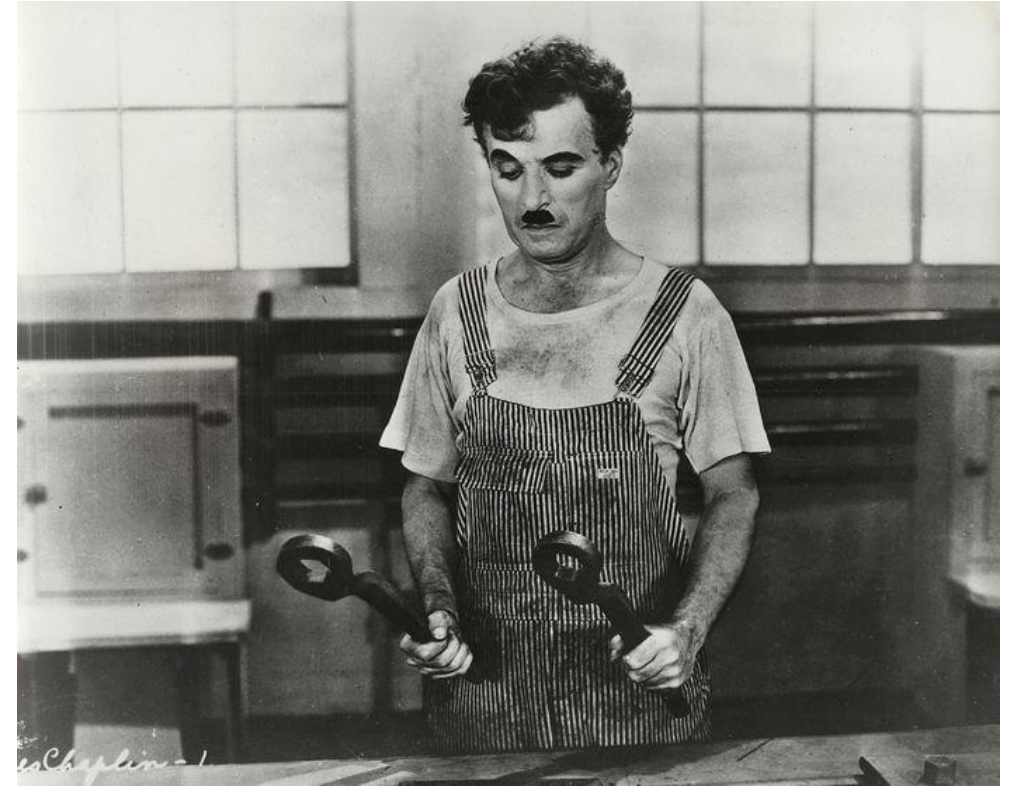
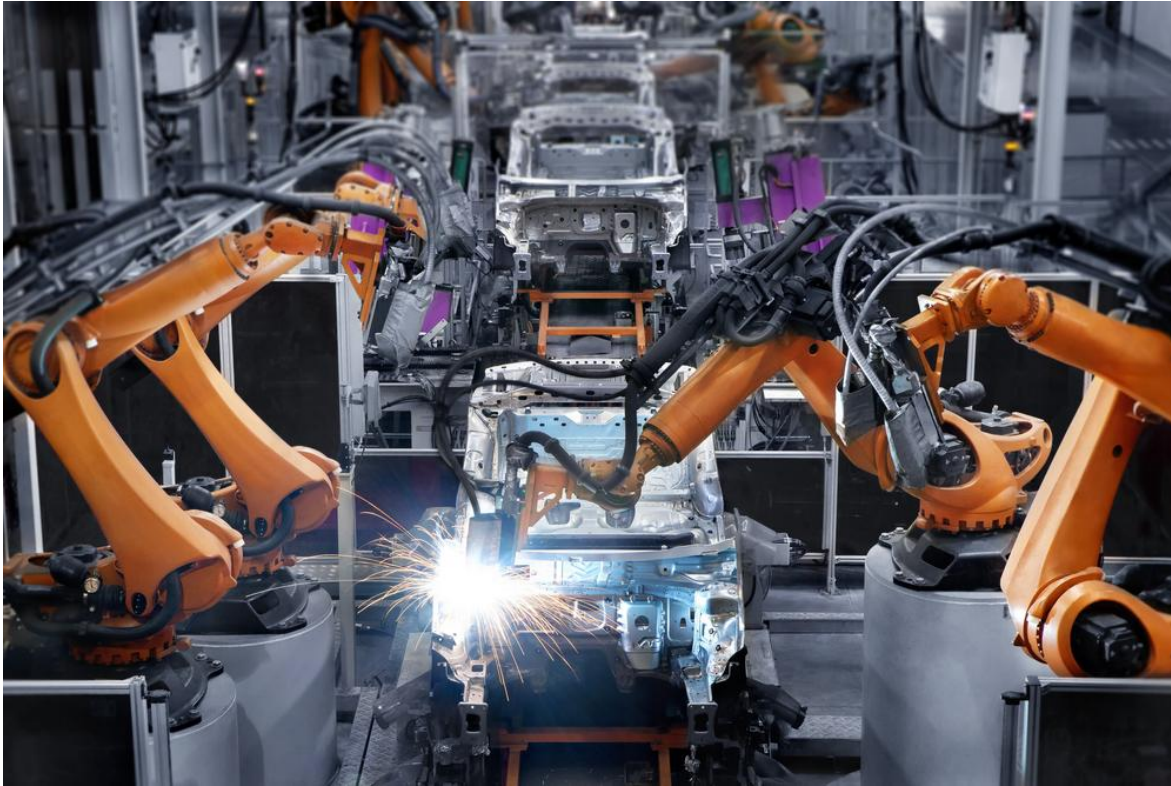
Hila Peleg - Technion



European Research Council
Established by the European Commission

Funded by the European Union (ERC, EXPLOSYN, 101117232). Views and opinions expressed are however those of the author(s) only and do not necessarily reflect those of the European Union or the European Research Council Executive Agency. Neither the European Union nor the granting authority can be held responsible for them.

The goal: Automate ^{some} programming



...in a *correct by construction* way



GitHub
Copilot

```
1 def max_sum_slice(xs):
2     if len(xs) == 0:
3         return None
4
5     max_sum = 0
6     max_sum_index = 0
7     max_sum_slice = []
8
9     for i in range(len(xs)):
10         if sum(xs[:i+1]) > max_sum:
11             max_sum = sum(xs[:i+1])
12             max_sum_index = i
13             max_sum_slice = xs[:i+1]
14
15     return max_sum_slice
```

Specifications go in, code comes out

$\wedge \forall p \in Proc, d \in Disk :$
 $\wedge (d \in disksWritten[p]) \Rightarrow \wedge phase[p] \in \{1, 2\}$
 $\wedge disk[d][p] = dblock[p]$
 $\wedge (phase[p] \in 1, 2) \Rightarrow \wedge (blocksRead[p][d] \neq \{\}) \Rightarrow$
 $(d \in disksWritten[p])$
 $\wedge \neg hasRead(p, d, p)$
 $\wedge \forall p \in Proc :$
 $\wedge (phase[p] = 0) \Rightarrow \wedge dblock[p] = InitDB$
 $\wedge disksWritten[p] = \{\}$
 $\wedge \forall d \in Disk : \forall br \in blocksRead[p]$
 $\wedge br.proc = p$
 $\wedge br.block = disk[d][p]$
 $\wedge (phase[p] \neq 0) \Rightarrow \wedge dblock[p].mbal \in Ballot(p)$
 $\wedge dblock[p].bal \in Ballot(p) \cup \{0\}$
 $\wedge \forall d \in Disk : \forall br \in blocksRead[p]$
 $br.block.mbal < dblock[p].mbal$
 $\wedge (phase[p] \in \{2, 3\}) \Rightarrow (dblock[p].bal = dblock[p].mt)$
 $\wedge output[p] = \text{IF } phase[p] = 3 \text{ THEN } dblock[p].inp \text{ ELSE } dblock[p].mbal$
 $\wedge chosen \in allInput \cup \{NotAnInput\}$
 $\wedge \forall p \in Proc : \wedge input[p] \in allInput$
 $\wedge (chosen = NotAnInput) \Rightarrow (output[p] = dblock[p].mbal)$



```
2 $(function(){cards();});  
3 $(window).on('resize', func  
44 ▼ function cards(){  
45     var width = $(window).  
46     if(width < 750){  
47         cardssmallscreen()  
48     }else{  
49         cardsbigscreen();  
50     }  
51 }  
52 ▼ function cardssmallscreen()  
    var cards = $('<div>.card</div>');  
    var height = 0;  
    for (var i = 0; i < cards.length; i++) {  
        cards[i].height = height;  
        height = height + cards[i].height;  
    }  
    cards.css('height', height);  
}
```

What is program synthesis?

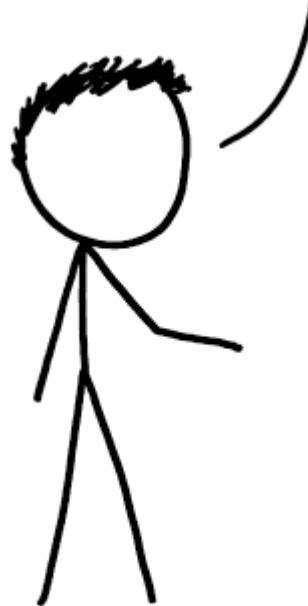
$$\overbrace{\exists p}^{\text{Find a program}} \in \underbrace{\mathcal{L}(G)}_{\text{From a language}}. \overbrace{\forall x. \phi(p, x)}^{\text{A correctness criterion}}$$

How do you find a program?

How do you express correctness?

How do you express correctness?

Specification of intent – the olden days


$$\begin{aligned} &\wedge \forall p \in Proc, d \in Disk : \\ &\quad \wedge (d \in disksWritten[p]) \Rightarrow \wedge phase[p] \in \{1, 2\} \\ &\quad \quad \quad \wedge disk[d][p] = dblock[p] \\ &\quad \wedge (phase[p] \in \{1, 2\}) \Rightarrow \wedge (blocksRead[p][d] \neq \{\}) \Rightarrow \\ &\quad \quad \quad (d \in disksWritten[p]) \\ &\quad \quad \quad \wedge \neg hasRead(p, d, p) \\ &\wedge \forall p \in Proc : \\ &\quad \wedge (phase[p] = 0) \Rightarrow \wedge dblock[p] = InitDB \\ &\quad \quad \quad \wedge disksWritten[p] = \{\} \\ &\quad \quad \quad \wedge \forall d \in Disk : \forall br \in blocksRead \\ &\quad \quad \quad \quad \wedge br.proc = p \\ &\quad \quad \quad \quad \wedge br.block = disk[d][p] \\ &\quad \wedge (phase[p] \neq 0) \Rightarrow \wedge dblock[p].mbal \in Ballot(p) \\ &\quad \quad \quad \wedge dblock[p].bal \in Ballot(p) \cup \{0\} \\ &\quad \quad \quad \wedge \forall d \in Disk : \forall br \in blocksRead \\ &\quad \quad \quad \quad br.block.mbal < dblock[p]. \\ &\quad \wedge (phase[p] \in \{2, 3\}) \Rightarrow (dblock[p].bal = dblock[p].mt \\ &\quad \wedge output[p] = \text{IF } phase[p] = 3 \text{ THEN } dblock[p].inp \text{ E} \\ &\wedge chosen \in allInput \cup \{NotAnInput\} \\ &\wedge \forall p \in Proc : \wedge input[p] \in allInput \\ &\quad \quad \wedge (chosen = NotAnInput) \Rightarrow (output[p] \end{aligned}$$

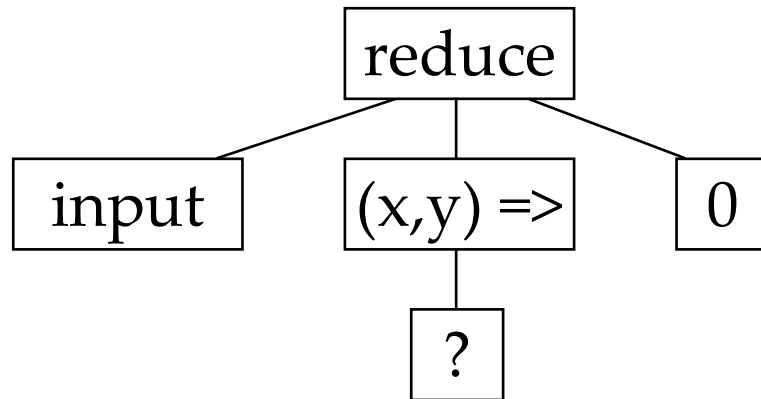
Right-O, here's some code:



Specification of *partial* intent

$$\mathcal{E} = \{l_i \rightarrow \omega_i\}$$

Examples



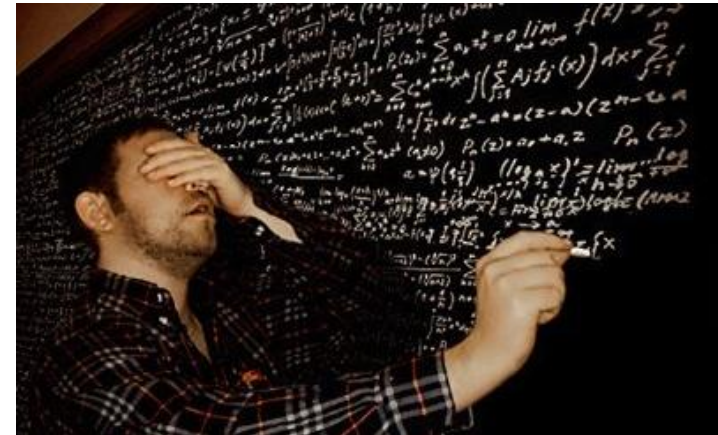
Sketching

```
var inStream:SequenceInputStream = |
var eof:Boolean = false;
var byteCount:Int = 0;
while (!eof) {
  var c:Int = inStream.read()
  if (c == -1)
    eof = true;
  else {
    System.out.print(c.toChar);
    byteCount+=1;
  }
}
```

```
new SequenceInputStream(new FileInputStream(sig), new FileInputStream(sig))
new SequenceInputStream(new FileInputStream(sig), new FileInputStream(body))
new SequenceInputStream(new FileInputStream(body), new FileInputStream(sig))
new SequenceInputStream(new FileInputStream(body), new FileInputStream(body))
new SequenceInputStream(new FileInputStream(sig), System.in)
```

Press 'Ctrl+Space' to show Default Proposals

Types



Logical specifications

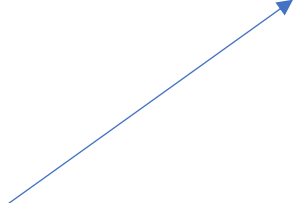
Programming by Example

$$\phi(p, x) = (x = \iota_1 \Rightarrow \llbracket p \rrbracket(x) = \omega_1) \wedge (x = \iota_2 \Rightarrow \llbracket p \rrbracket(x) = \omega_2) \wedge \dots$$

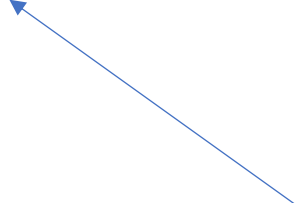
or in other words

$$\mathcal{E} = \{\iota_i \rightarrow \omega_i\}$$

values of all the variables/the
state of the environment

A blue arrow points from the text 'values of all the variables/the state of the environment' to the variable ι_i in the set notation of the equation above.

output of an expression/an effect/
the new state of the environment

A blue arrow points from the variable ω_i in the set notation of the equation above to the text 'output of an expression/an effect/ the new state of the environment'.

Type-Driven Synthesis

$$(\tau_1, \tau_2, \dots, \tau_k) \rightarrow \tau_{out}$$

or in other words,

“Use variables of these types that are in scope to make something of this type”

Eq $a \Rightarrow a \rightarrow [a] \rightarrow \text{Maybe } [a]$

(Fancy-)Type-Driven Synthesis

$$(\tau_1, \tau_2, \dots, \tau_k) \rightarrow \tau_{out}$$

or in other words,

“Use variables of these types that are in scope to make something of this type”

`n:Nat -> x:a -> {List a | len _v = n}`

Sketching

“I already know some of the code for my program”

```
generator int sumB (int x, int y, int z, int bnd) {  
    assert bnd > 0;  
    generator int factor () {  
        return { | x | | y | | z | } * { | x | | y | | z | ?? | };  
    }  
    if (??) { return factor (); }  
    else { return factor () + sumB (x, y, z, bnd-1); } }
```

← An expression that
looks kind of like this

goes here



Shriram

@ShriramKMurthi



Where do you get the properties???

9:07 AM · May 26, 2025

47 Retweets

1K Likes



(next time, I promise)

How do you find a program?

Generic synthesis recipe

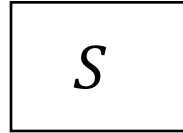
1. Generate a candidate program

- Enumerate trees
 - Top-down
 - Bottom-up
- Traverse automata
- Graph reachability
- Enumerate deduction rules

2. Test against specification

- Run tests
 - Examples
 - Unit
- Encode for SMT solver
- Apply typing rules

Enumerating trees



$$S \rightarrow E$$

$$E \rightarrow E + E$$

$$E \rightarrow E * E$$

$$E \rightarrow [EList]$$

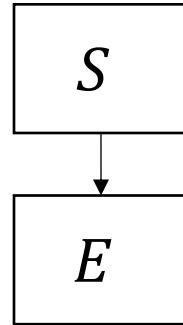
$$EList \rightarrow E \mid EList, E$$

$$E \rightarrow len(E)$$

$$E \rightarrow id$$

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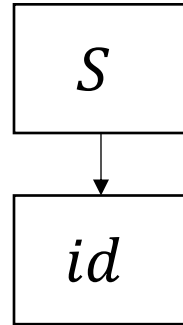
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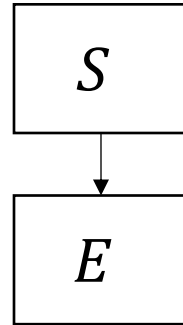
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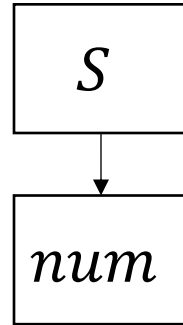
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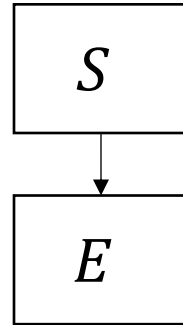
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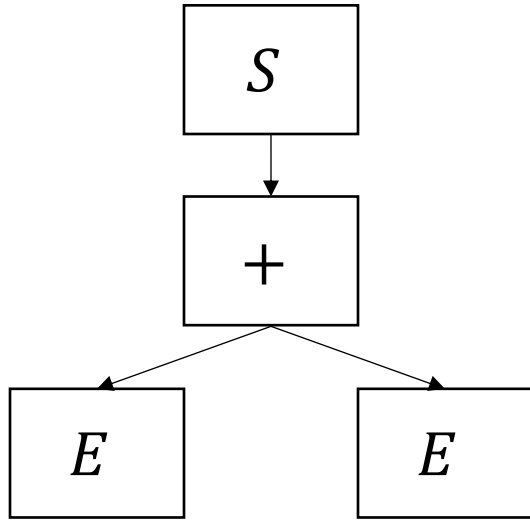
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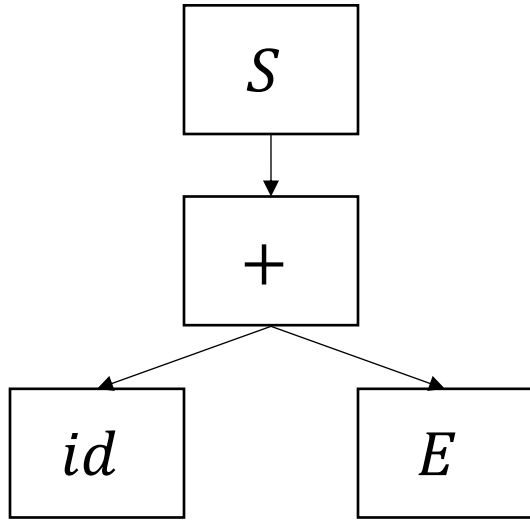
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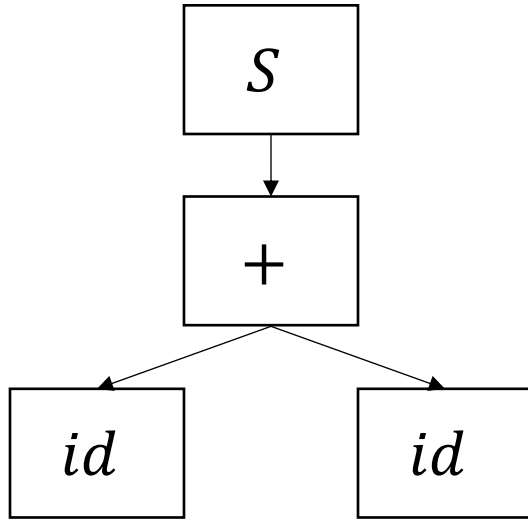
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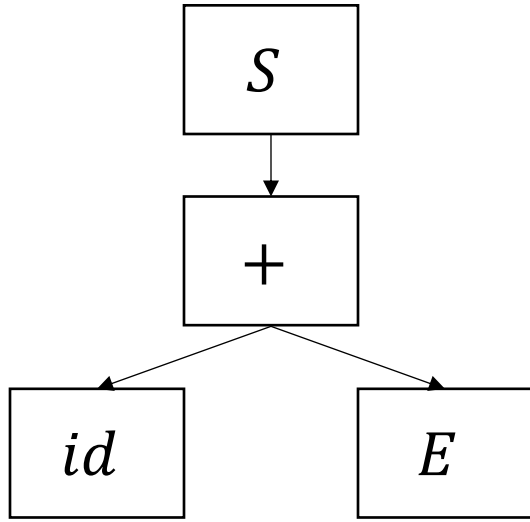
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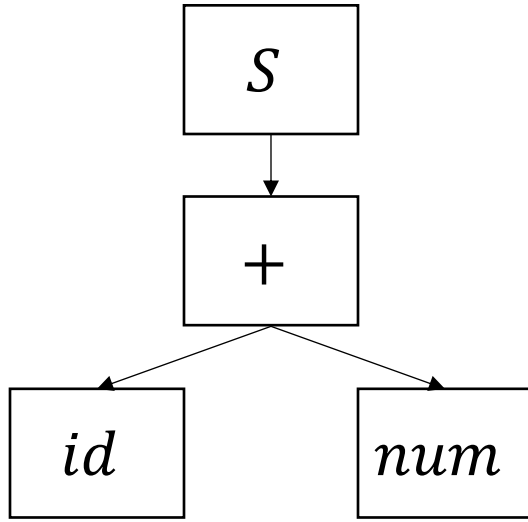
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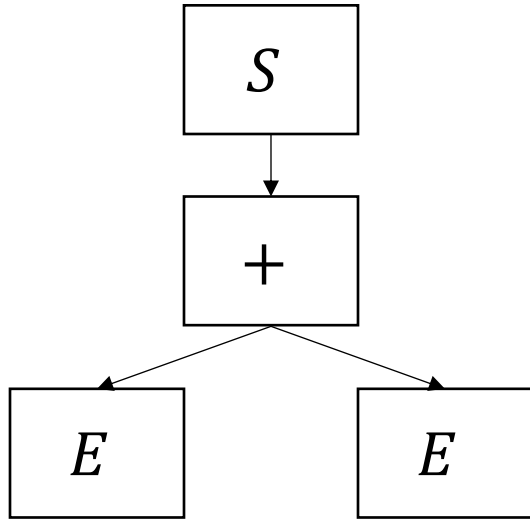
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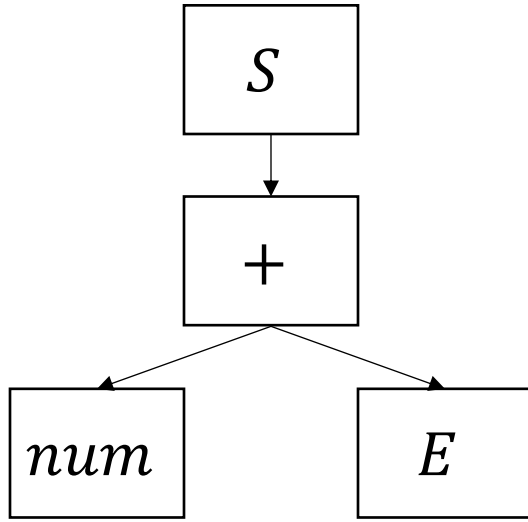
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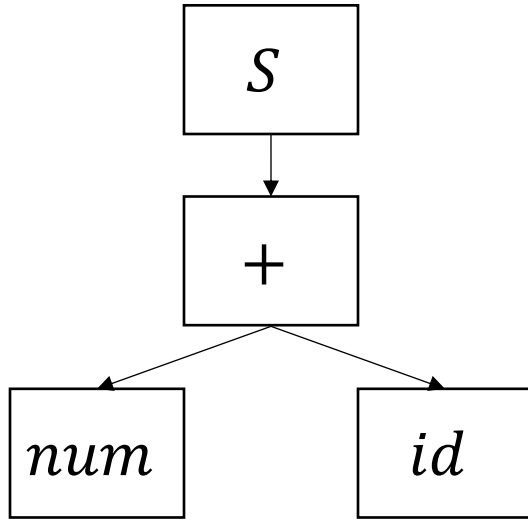
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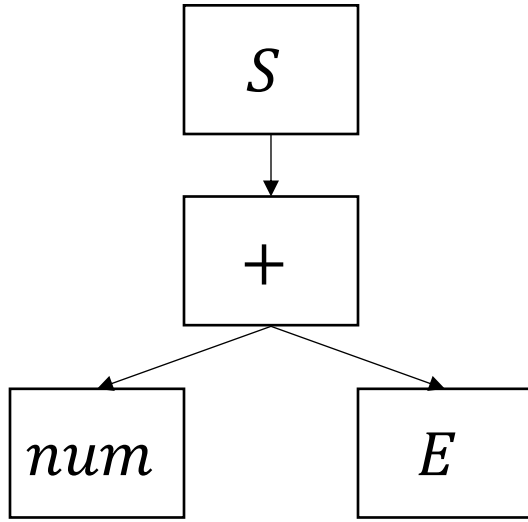
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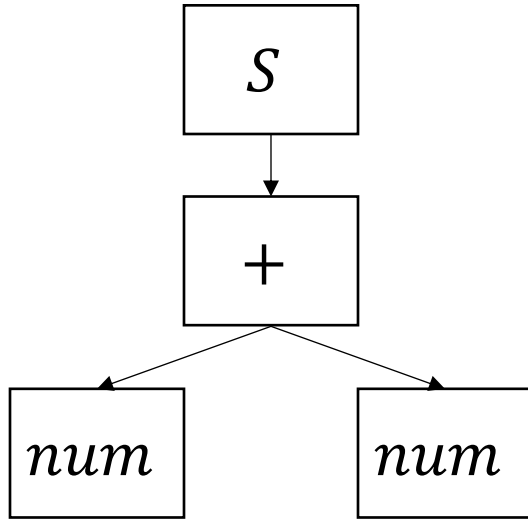
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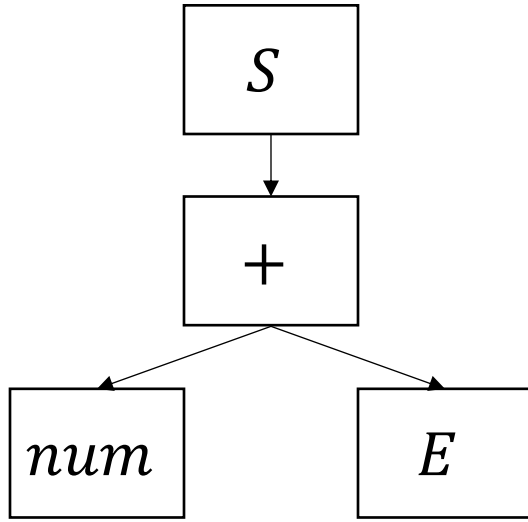
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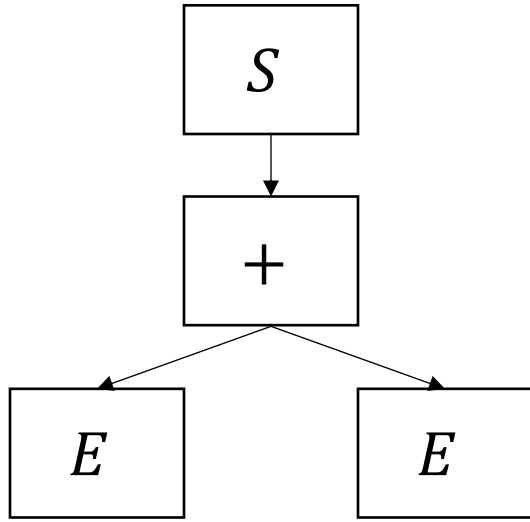
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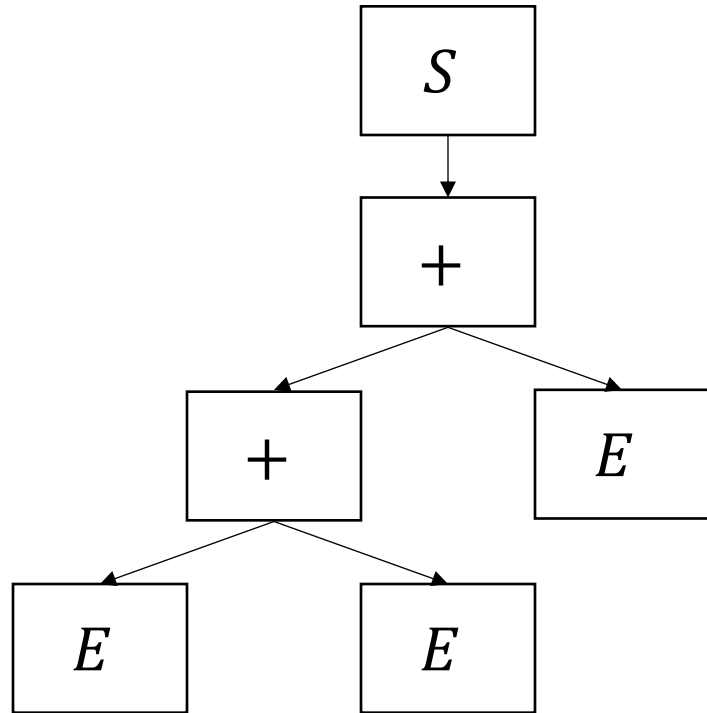
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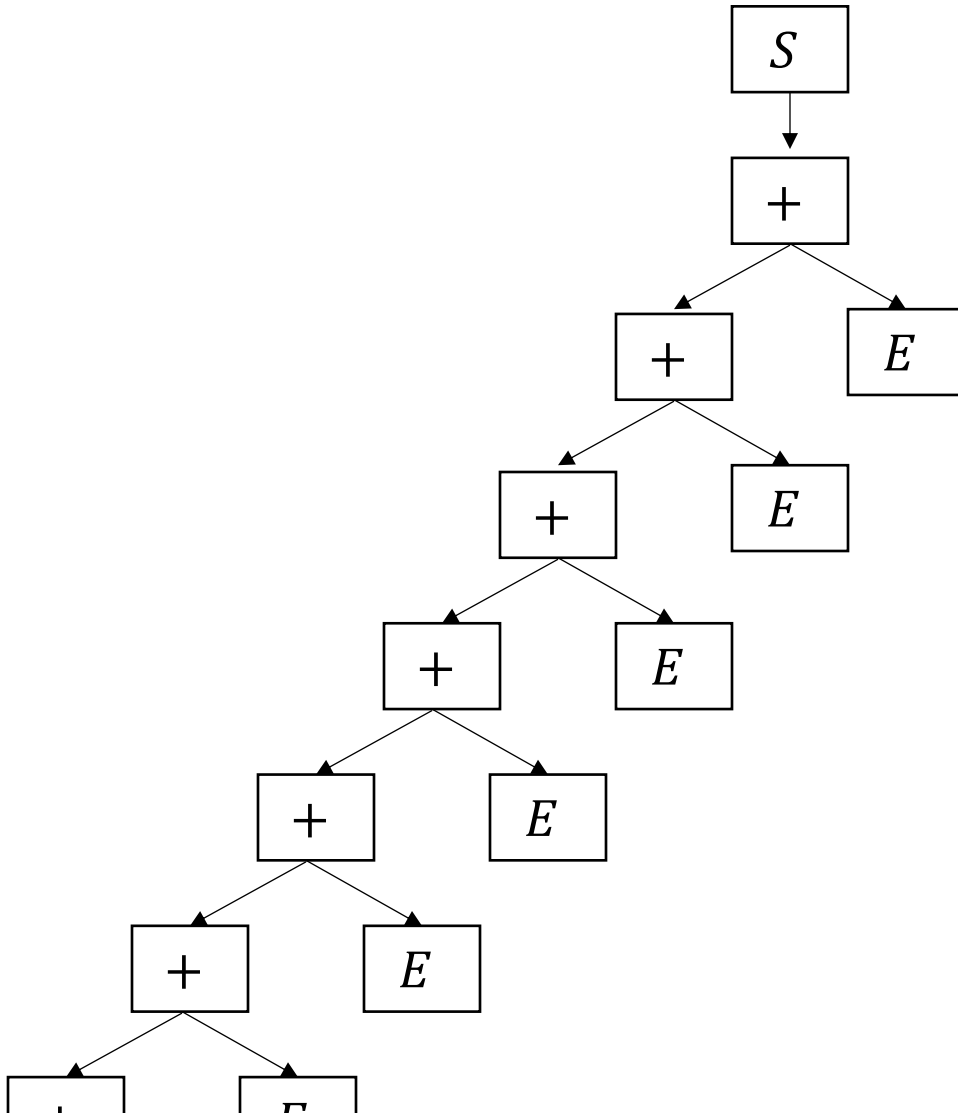
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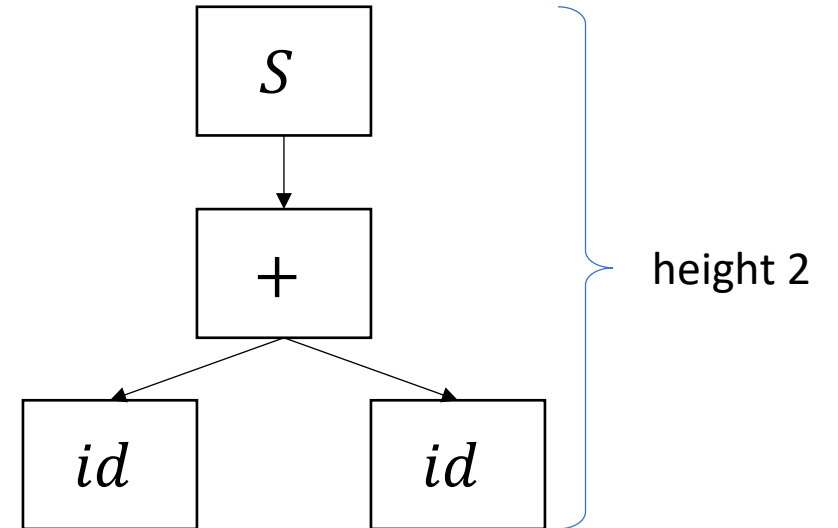
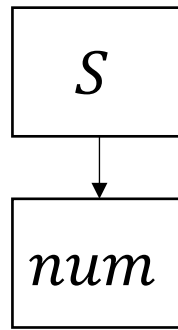
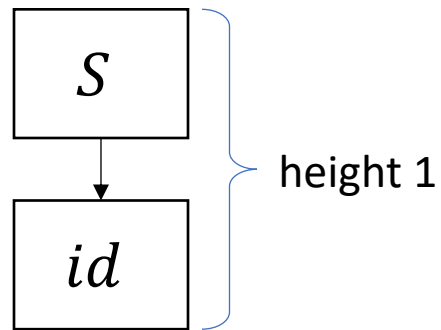
$$E \rightarrow num$$

Enumeration stack overflow


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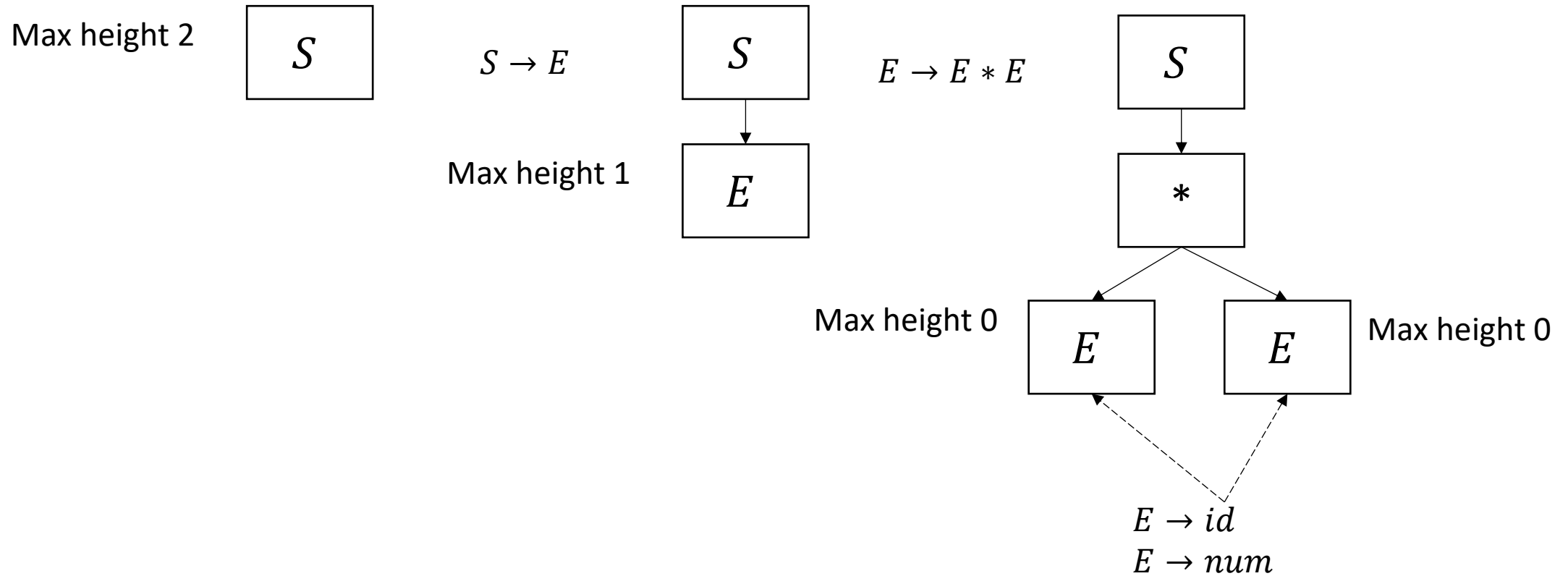
Solution: iterative deepening

- Limit the height of programs being enumerated
- First, all programs of height 0
- then 1
- then 2...

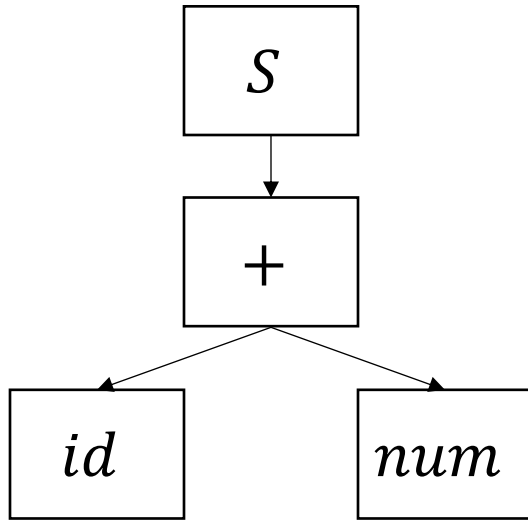


Iterative deepening

To enumerate height 2:

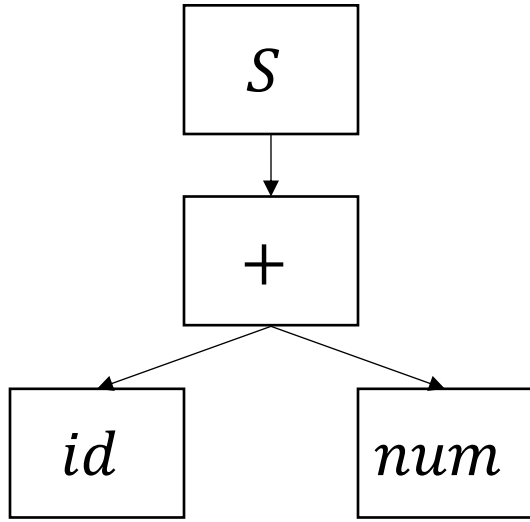


An infinite space

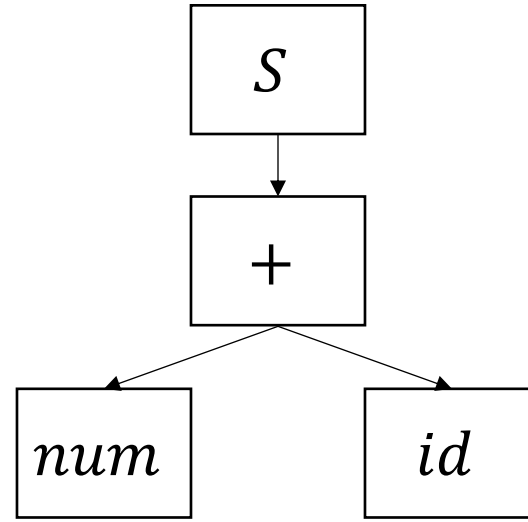


x	+	2
x	+	3
x	+	42
y	+	2
y	+	-3

An infinite space full of redundancy

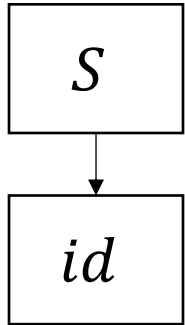


x + 2

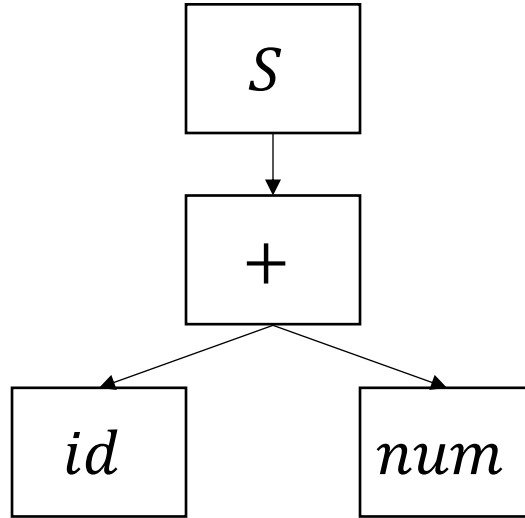


2 + x

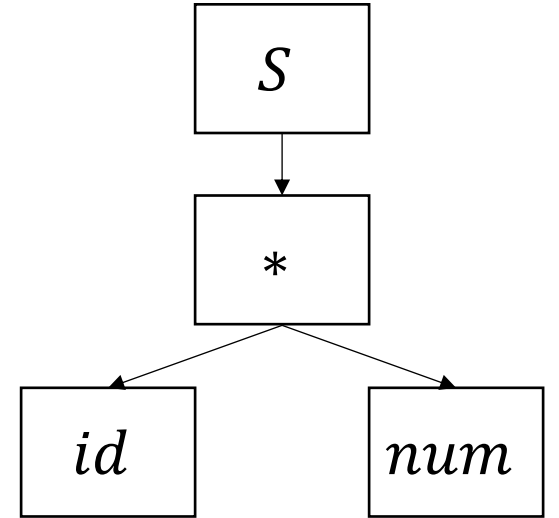
An infinite space full of redundancy



x

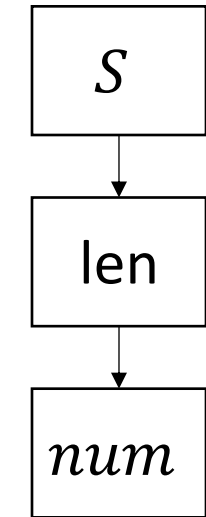


$x \quad + \quad 0$

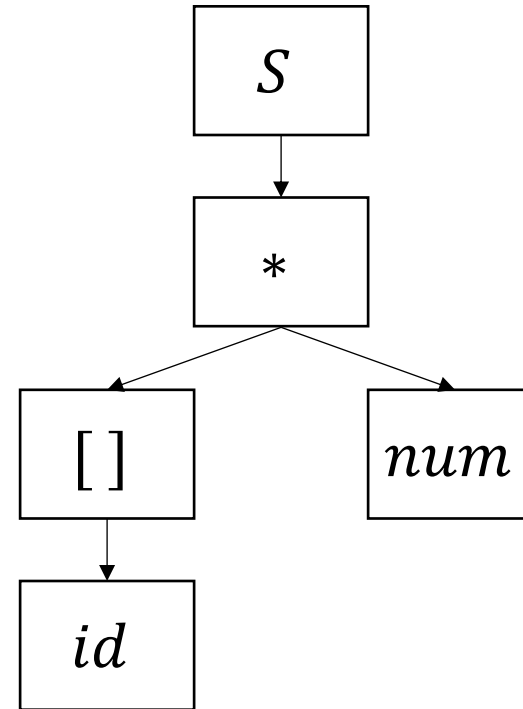


$x \quad * \quad 1$

An infinite space full of bad programs



`len(2)`



`[x] * 1`

Maybe enumerating
the space in full is
bad, actually?

Pruning the space 1: well-typedness

$$\frac{e_1: \text{int} \quad e_2: \text{int}}{e_1 + e_2: \text{int}}$$

$$\frac{e_1: [\tau] \quad e_2: [\tau]}{e_1 + e_2: [\tau]}$$

$$\frac{e_1: \text{int} \quad e_2: \text{int}}{e_1 * e_2: \text{int}}$$

$$\frac{e_1, \dots, e_k: \tau}{[e_1, \dots, e_k]: [\tau]}$$

$$\frac{e: [\tau]}{\text{len}(e): \text{int}}$$

$$\frac{\text{var } x \text{ has type } \tau}{x: \tau}$$

$$\frac{}{\text{num}: \text{int}}$$

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Generic synthesis recipe

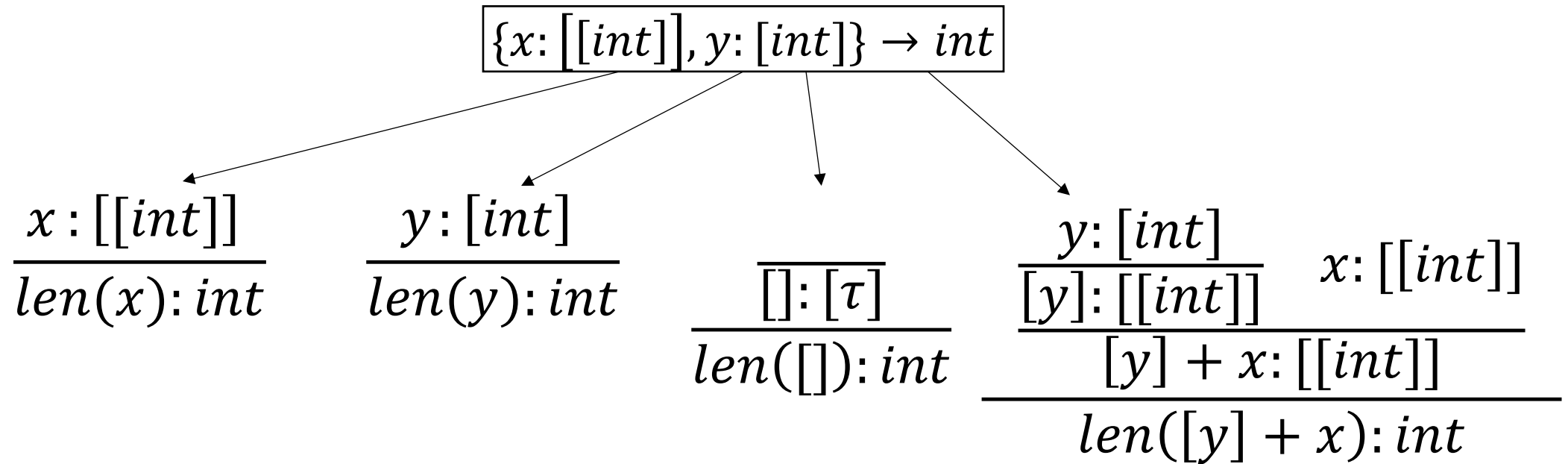
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- Encode for SMT solver
- Apply typing rules

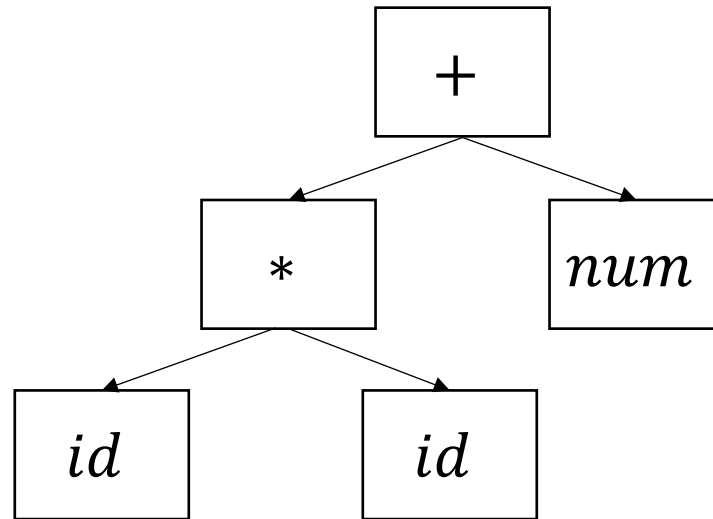
Looking at spec with types



Deductive proof search

What about examples?

What we enumerated was not a concrete program



Can we combine that with examples?

What about examples?

What we enumerated was not a concrete program

Given:

$$\epsilon_1: \{x \mapsto 6, y \mapsto 8\} \rightarrow 49$$

$$\epsilon_2: \{x \mapsto 4, y \mapsto 7\} \rightarrow 29$$

And a (meta) candidate: $(id_1 * id_2) + num$

Can we solve for id_1, id_2, num ?

SMT solvers to the rescue

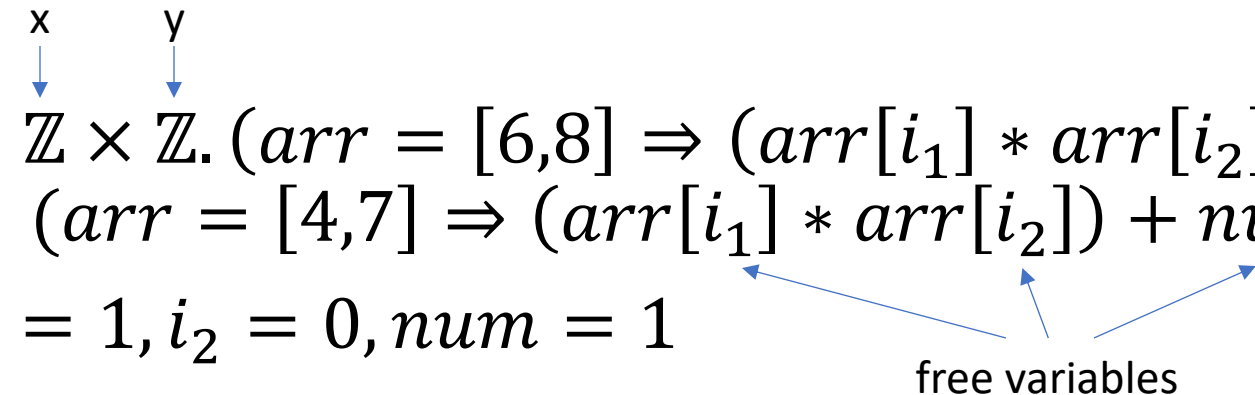
Given:

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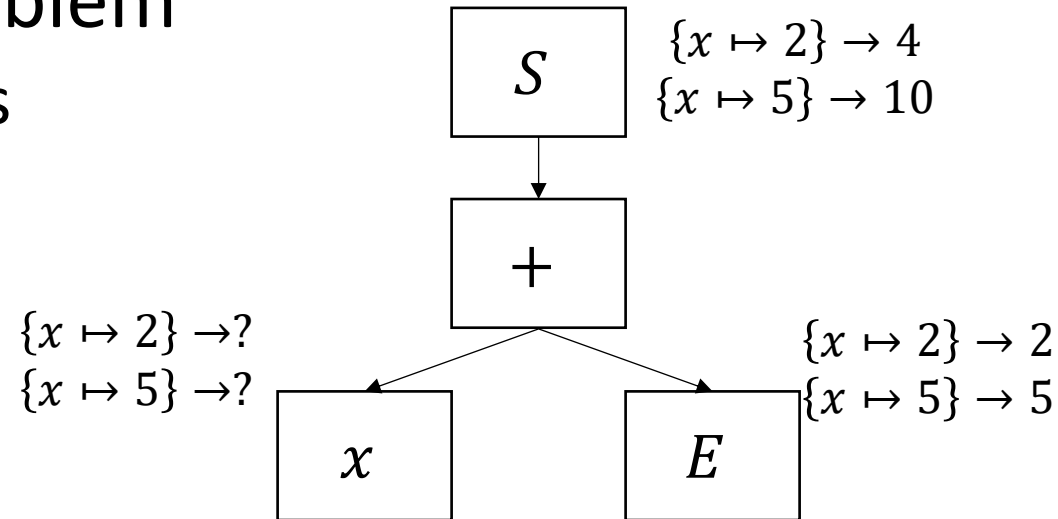
The diagram illustrates the mapping of variables in the formula. Above the formula, 'x' and 'y' have blue arrows pointing down to the indices i_1 and i_2 in the array access expressions $arr[i_1]$ and $arr[i_2]$. Below the formula, the text 'free variables' has three blue arrows pointing up to the variables i_1 , i_2 , and num in the formula.

$$\forall arr \in \mathbb{Z} \times \mathbb{Z}. (arr = [6,8] \Rightarrow (arr[i_1] * arr[i_2]) + num = 49) \wedge$$
$$(arr = [4,7] \Rightarrow (arr[i_1] * arr[i_2]) + num = 29)$$

Model: $i_1 = 1, i_2 = 0, num = 1$

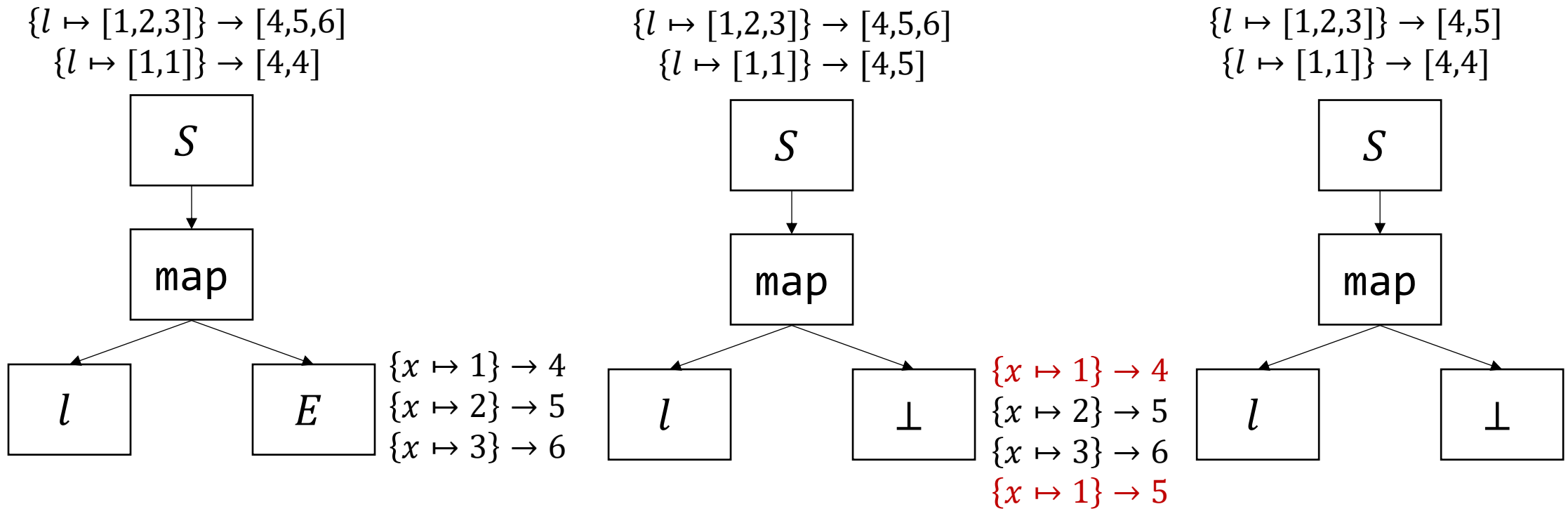
Can we do better?

- Specification \times Semantics of node = Specifications for remaining problem
 - ... sometimes

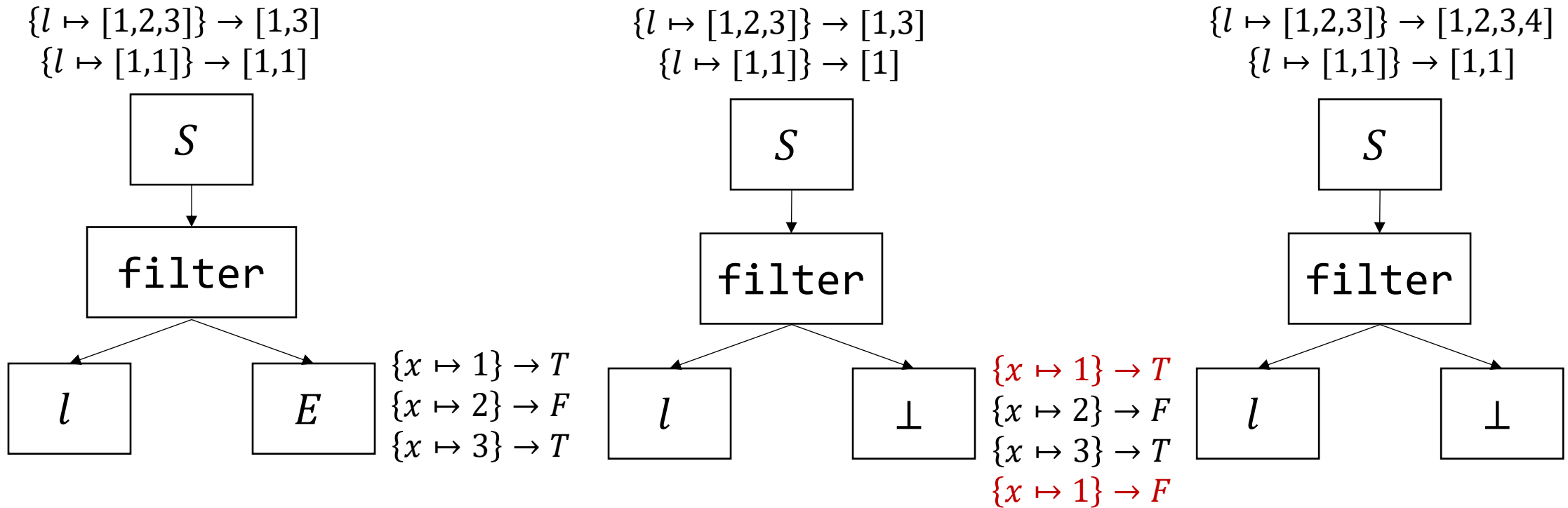


- Called *Example Refinement*

Refinements and higher-order functions



Refinements and higher-order functions



Generic synthesis recipe

1. Generate a candidate program

- Enumerate trees
 - Top-down
 - Bottom-up
- Traverse automata
- Graph reachability
- Enumerate deduction rules

2. Test against specification

- Run tests
 - Examples
 - Unit
- Encode for SMT solver
- Apply typing rules

Enumerative Search

We did great with: Generate programs from the grammar, one by one, and test them on the specification

cough *cough*



Enumerating trees

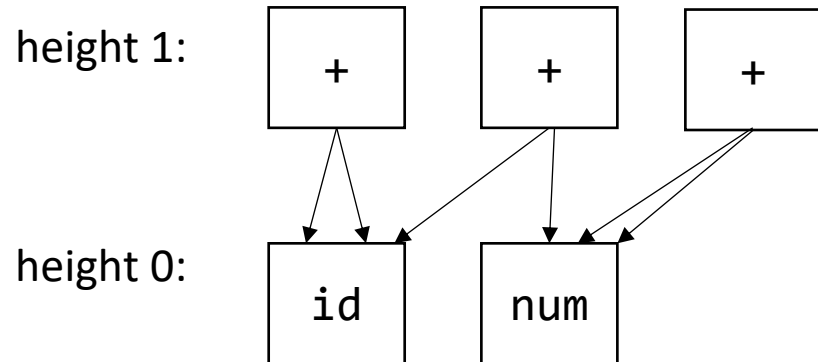
$$\begin{aligned} S &\rightarrow E \\ E &\rightarrow E + E \\ E &\rightarrow E * E \\ E &\rightarrow [EList] \\ EList &\rightarrow E \mid EList, E \\ E &\rightarrow len(E) \\ E &\rightarrow id \\ E &\rightarrow num \end{aligned}$$

height 0:

id

num

Enumerating trees



$$S \rightarrow E$$

$$E \rightarrow E + E$$

$$E \rightarrow E * E$$

$$E \rightarrow [EList]$$

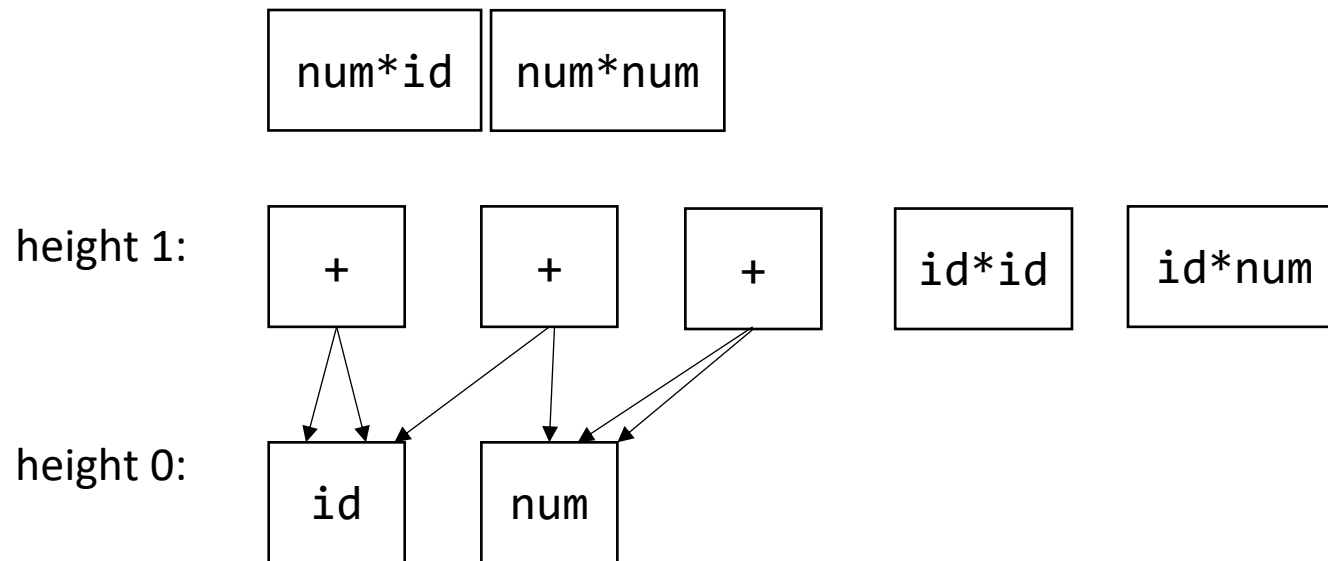
$$EList \rightarrow E \mid EList, E$$

$$E \rightarrow len(E)$$

$$E \rightarrow id$$

$$E \rightarrow num$$

Enumerating trees



$$S \rightarrow E$$

$$E \rightarrow E + E$$

$$E \rightarrow E * E$$

$$E \rightarrow [EList]$$

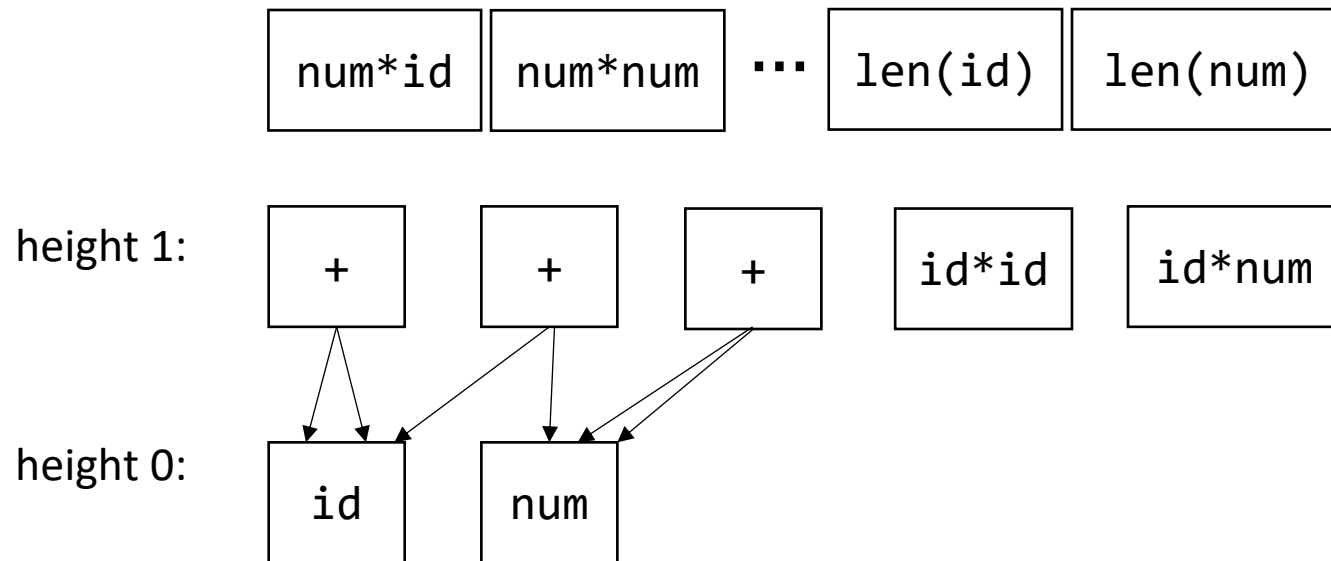
$$EList \rightarrow E \mid EList, E$$

$$E \rightarrow len(E)$$

$$E \rightarrow id$$

$$E \rightarrow num$$

Enumerating trees



$$S \rightarrow E$$

$$E \rightarrow E + E$$

$$E \rightarrow E * E$$

$$E \rightarrow [EList]$$

$$EList \rightarrow E \mid EList, E$$

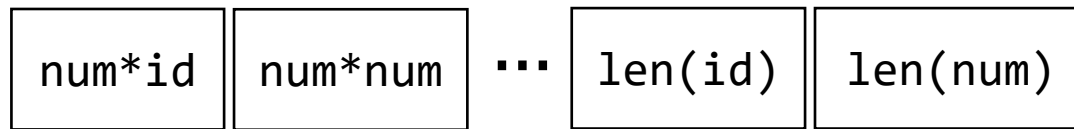
$$E \rightarrow len(E)$$

$$E \rightarrow id$$

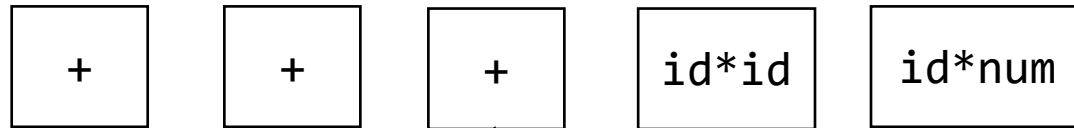
$$E \rightarrow num$$

Enumerating trees

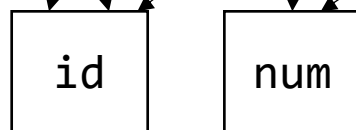
height 2:



height 1:



height 0:



$$S \rightarrow E$$

$$E \rightarrow E + E$$

$$E \rightarrow E * E$$

$$E \rightarrow [EList]$$

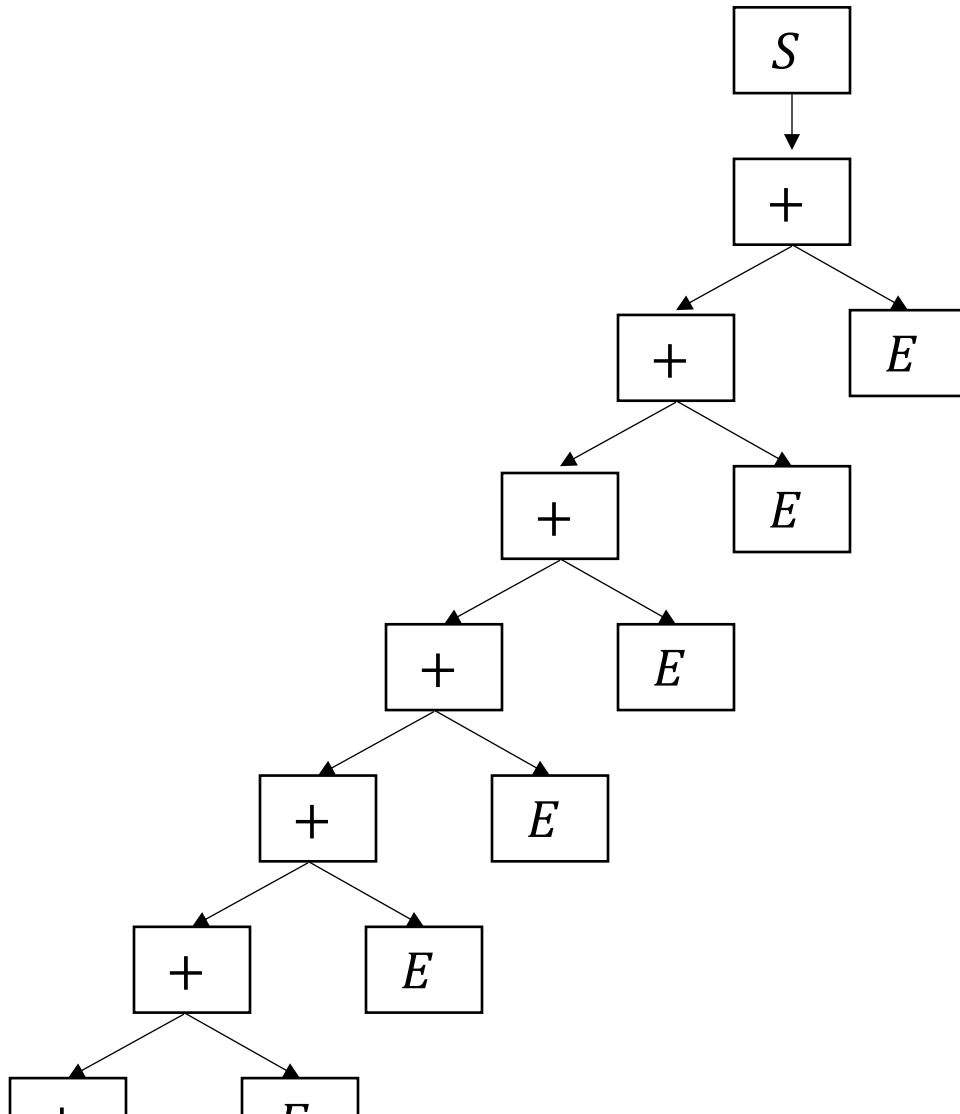
$$EList \rightarrow E \mid EList, E$$

$$E \rightarrow len(E)$$

$$E \rightarrow id$$

$$E \rightarrow num$$

On one hand: no stack overflow



$S \rightarrow E$

$E \rightarrow E + E$

$E \rightarrow E * E$

$E \rightarrow [EList]$

$EList \rightarrow E \mid EList, E$

$E \rightarrow len(E)$

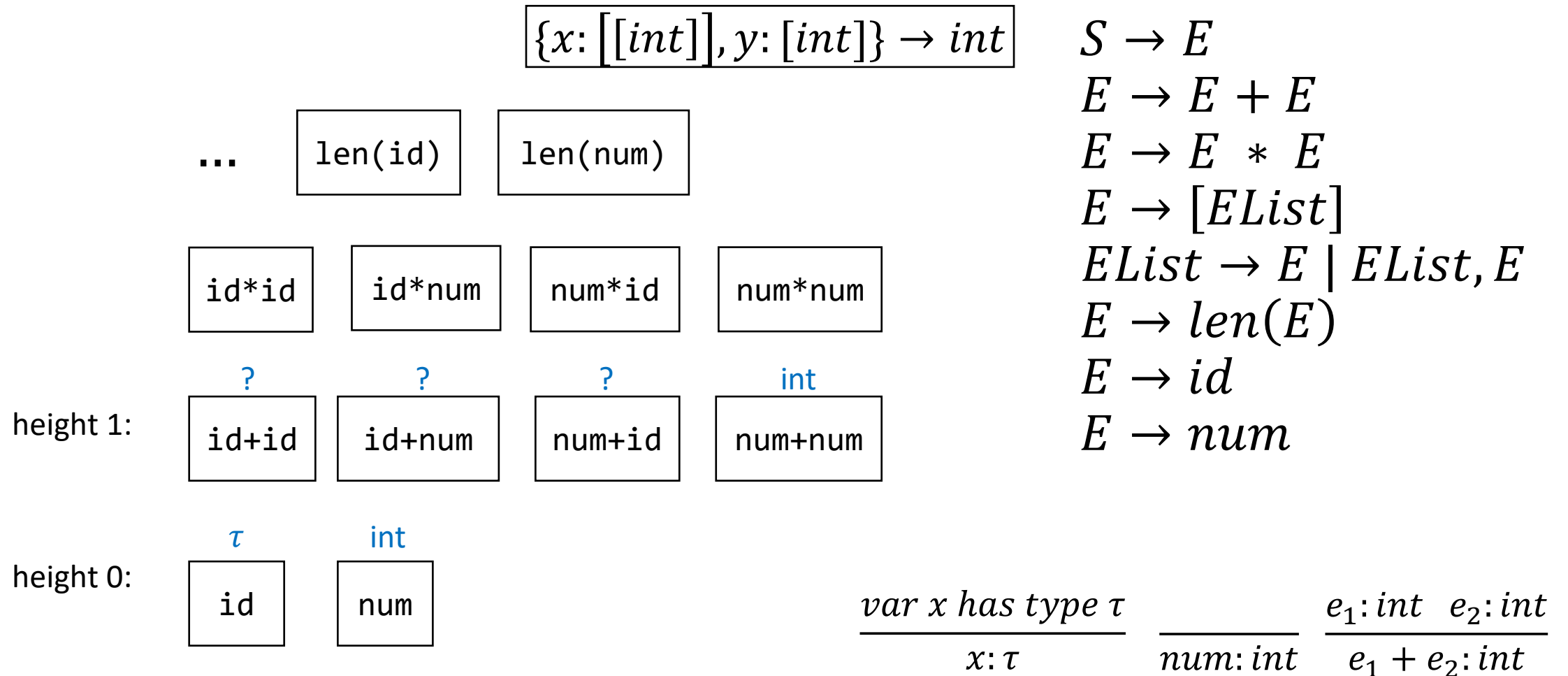
$E \rightarrow id$

$E \rightarrow num$

On the other hand:

A lot of things suddenly got harder

What if we have a type specification?



Generic synthesis recipe

1. Generate a candidate program

- Enumerate trees
 - Top-down
 - Bottom-up
- Traverse automata
- Graph reachability
- Enumerate deduction rules
- Cheat* by looking at spec

2. Test against specification

- Run tests
 - Examples
 - Unit
- Encode for SMT solver
- Apply typing rules

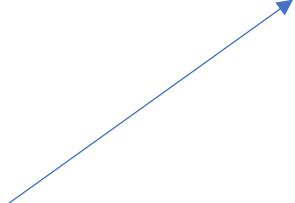
Programming by Example

$$\phi(p, x) = (x = \iota_1 \Rightarrow \llbracket p \rrbracket(x) = \omega_1) \wedge (x = \iota_2 \Rightarrow \llbracket p \rrbracket(x) = \omega_2) \wedge \dots$$

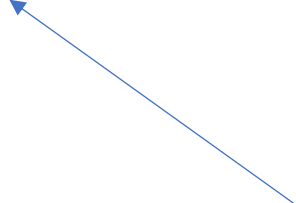
or in other words

$$\mathcal{E} = \{\iota_i \rightarrow \omega_i\}$$

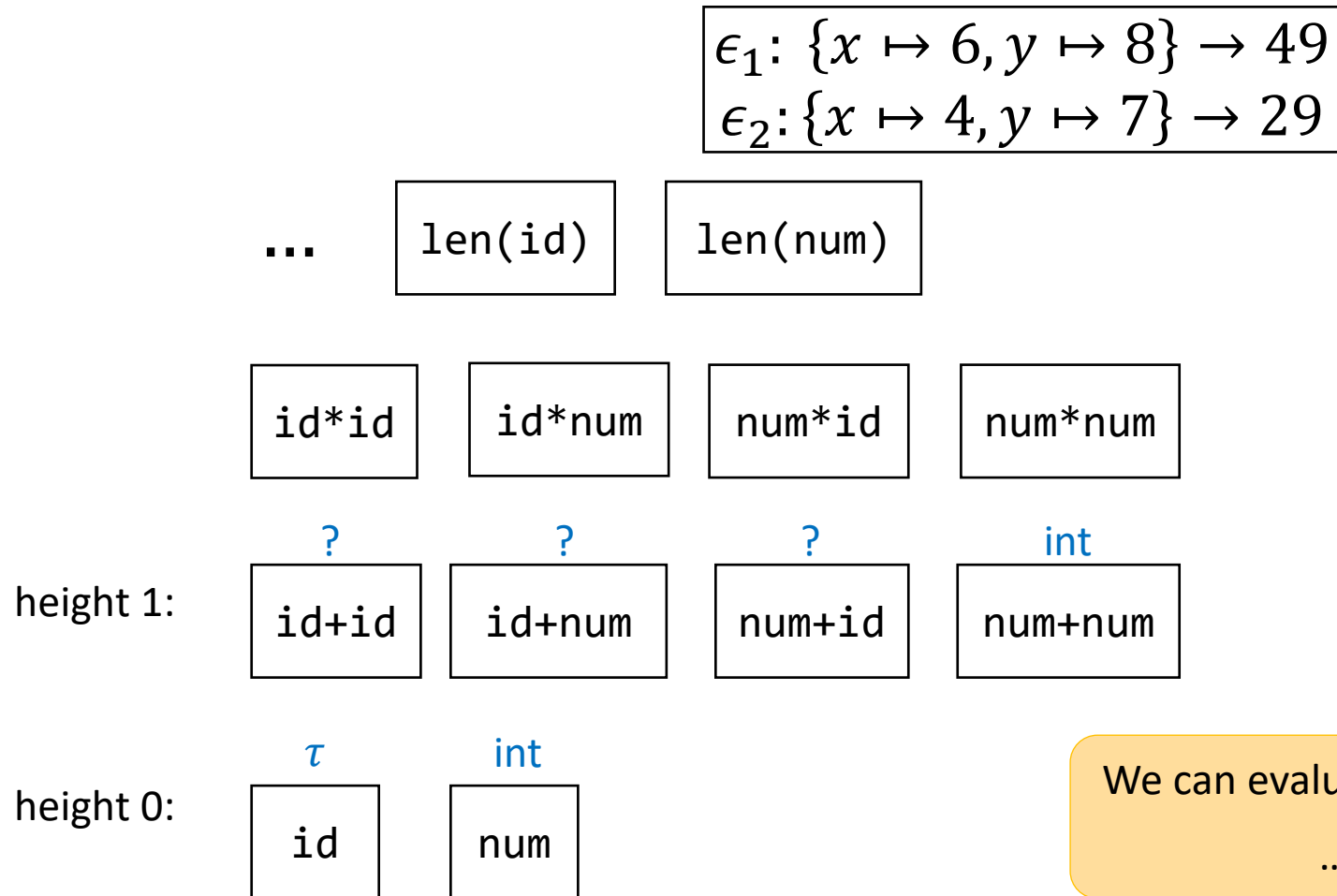
values of all the variables/the
state of the environment

A blue arrow points from the text 'values of all the variables/the state of the environment' to the variable ι_i in the set notation of the equation above.

output of an expression/an effect/
the new state of the environment

A blue arrow points from the variable ω_i in the set notation of the equation above to the text 'output of an expression/an effect/ the new state of the environment'.

Programming by Example

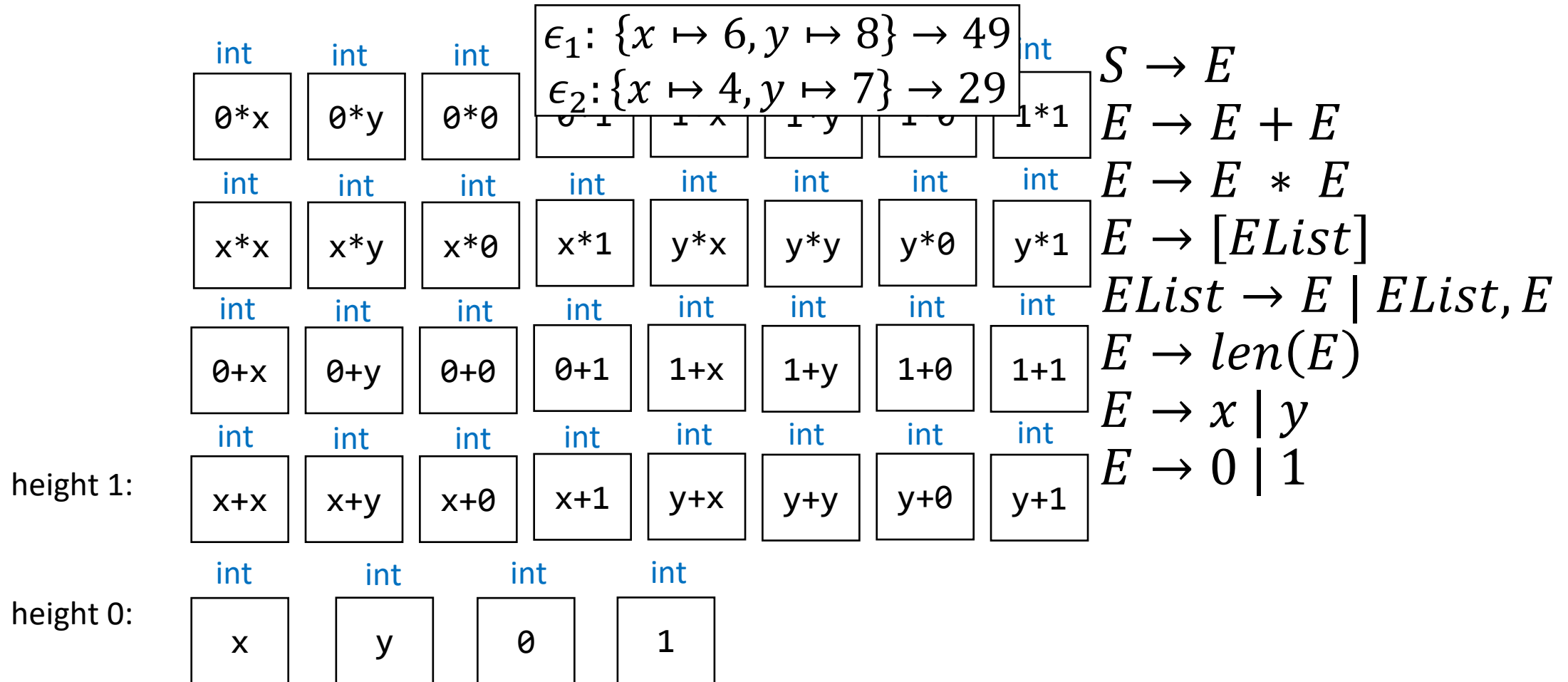


$S \rightarrow E$
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 $E \rightarrow E * E$
 $E \rightarrow [EList]$
 $EList \rightarrow E \mid EList, E$
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 $E \rightarrow num$

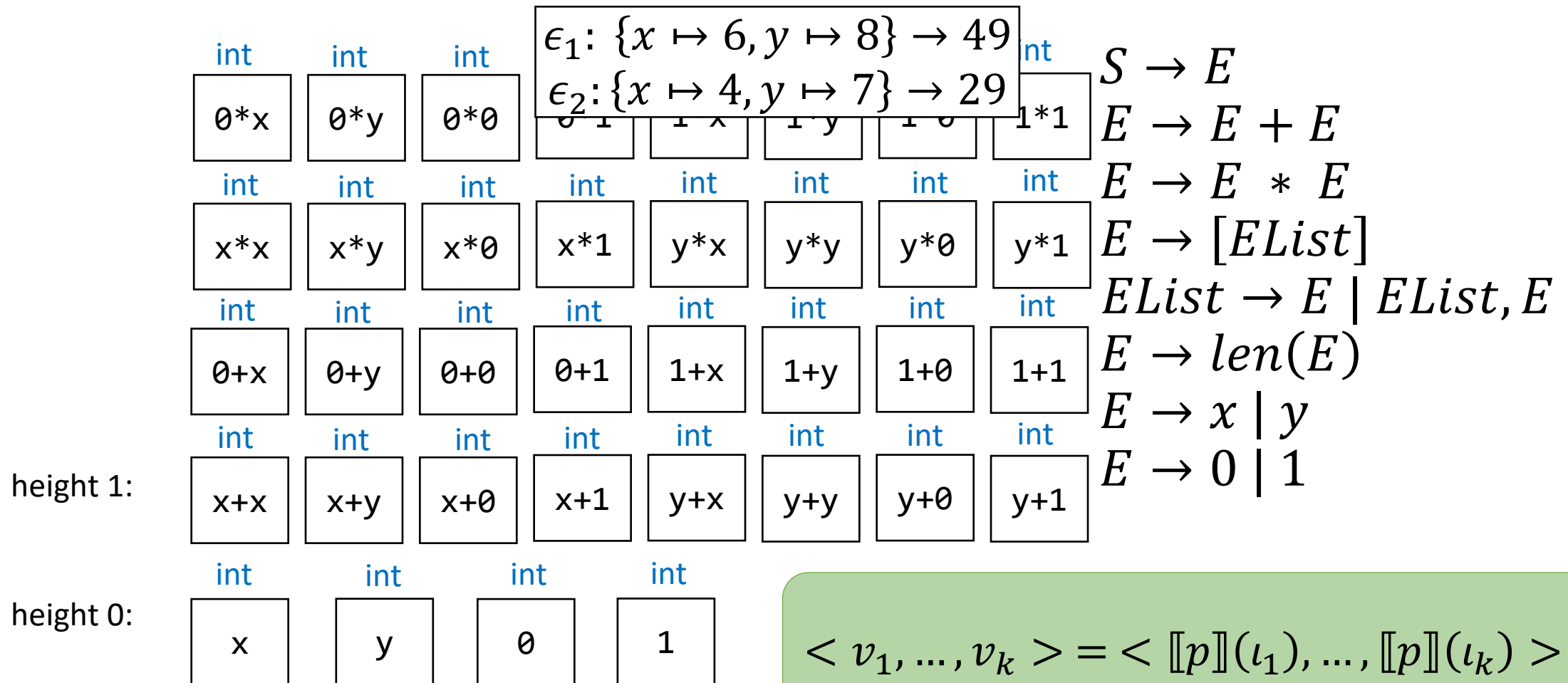
We can evaluate every program!

...almost

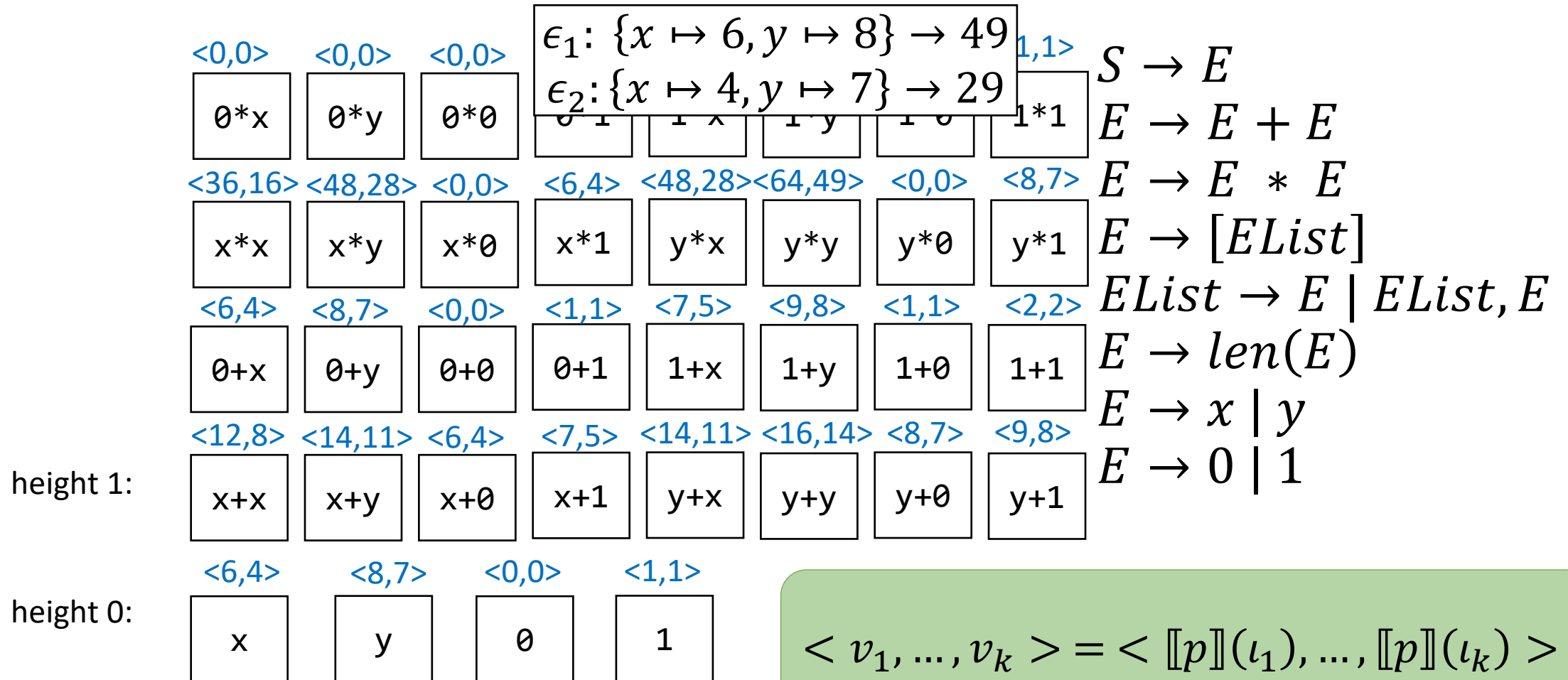
Programming by Example



Programming by Example

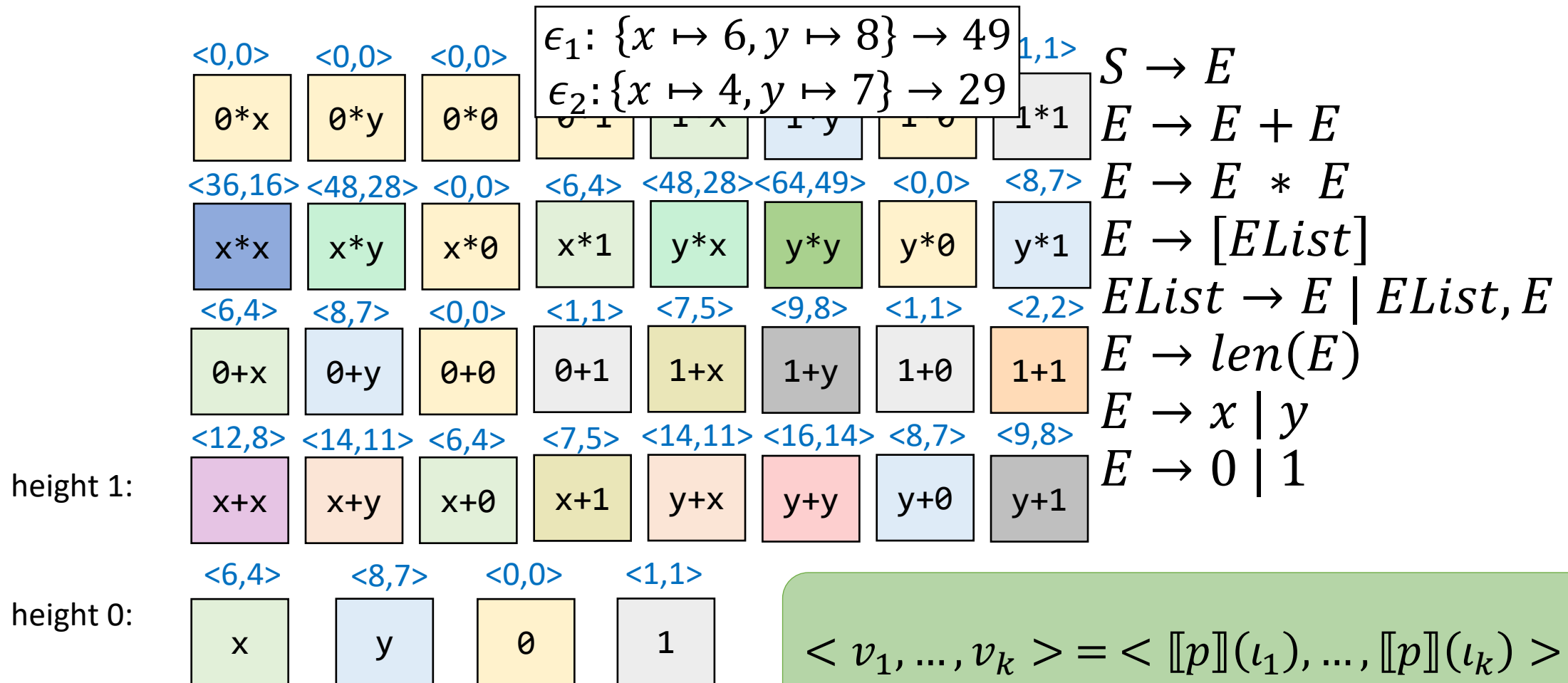


Programming by Example



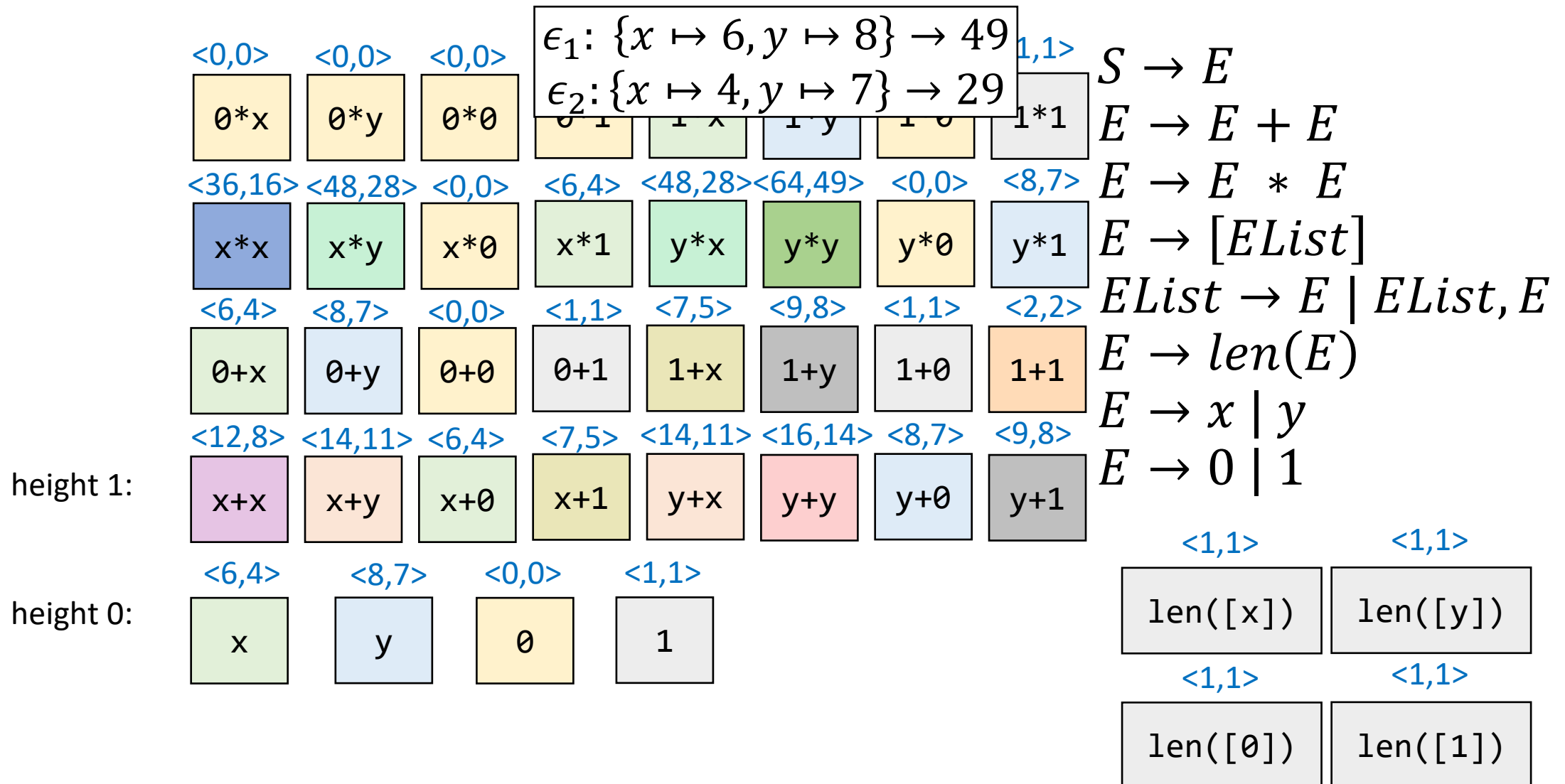
Equivalence classes

[Albarghouthi et al. 2013, Udupa et al. 2013]



Equivalence classes

[Albarghouthi et al. 2013, Udupa et al. 2013]

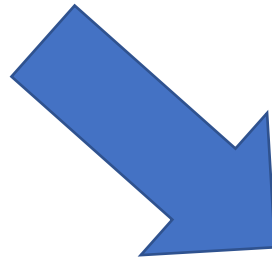


Observational equivalence

[Albarghouthi et al. 2013, Udupa et al. 2013]

Equivalence:

$p_1 \equiv p_2$ i.f.f. for every possible input i ever, $\llbracket p_1 \rrbracket(i) = \llbracket p_2 \rrbracket(i)$

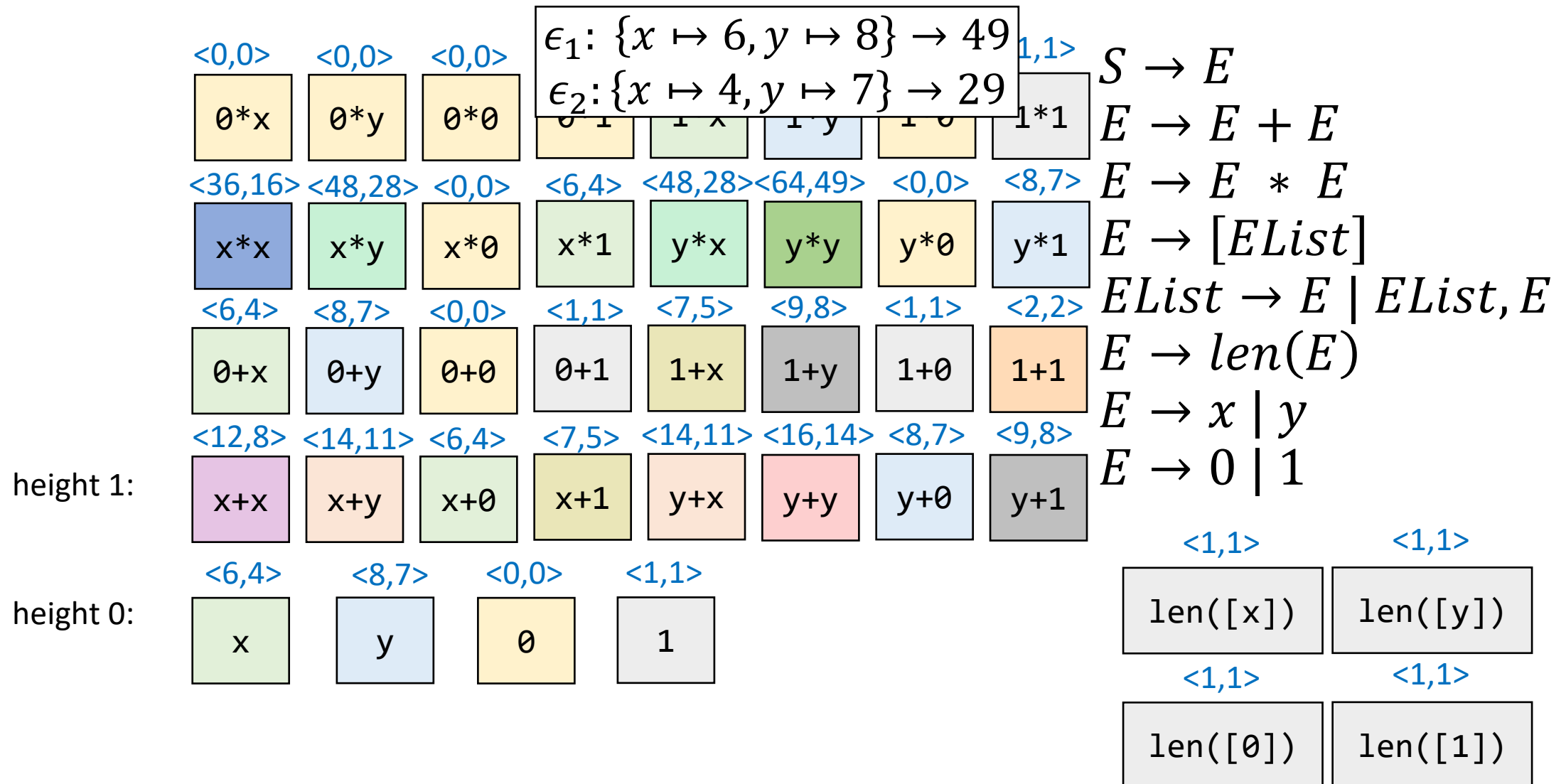


Observational equivalence:

$p_1 \equiv_{OE} p_2$ i.f.f. for every input i the user cares about, $\llbracket p_1 \rrbracket(i) = \llbracket p_2 \rrbracket(i)$

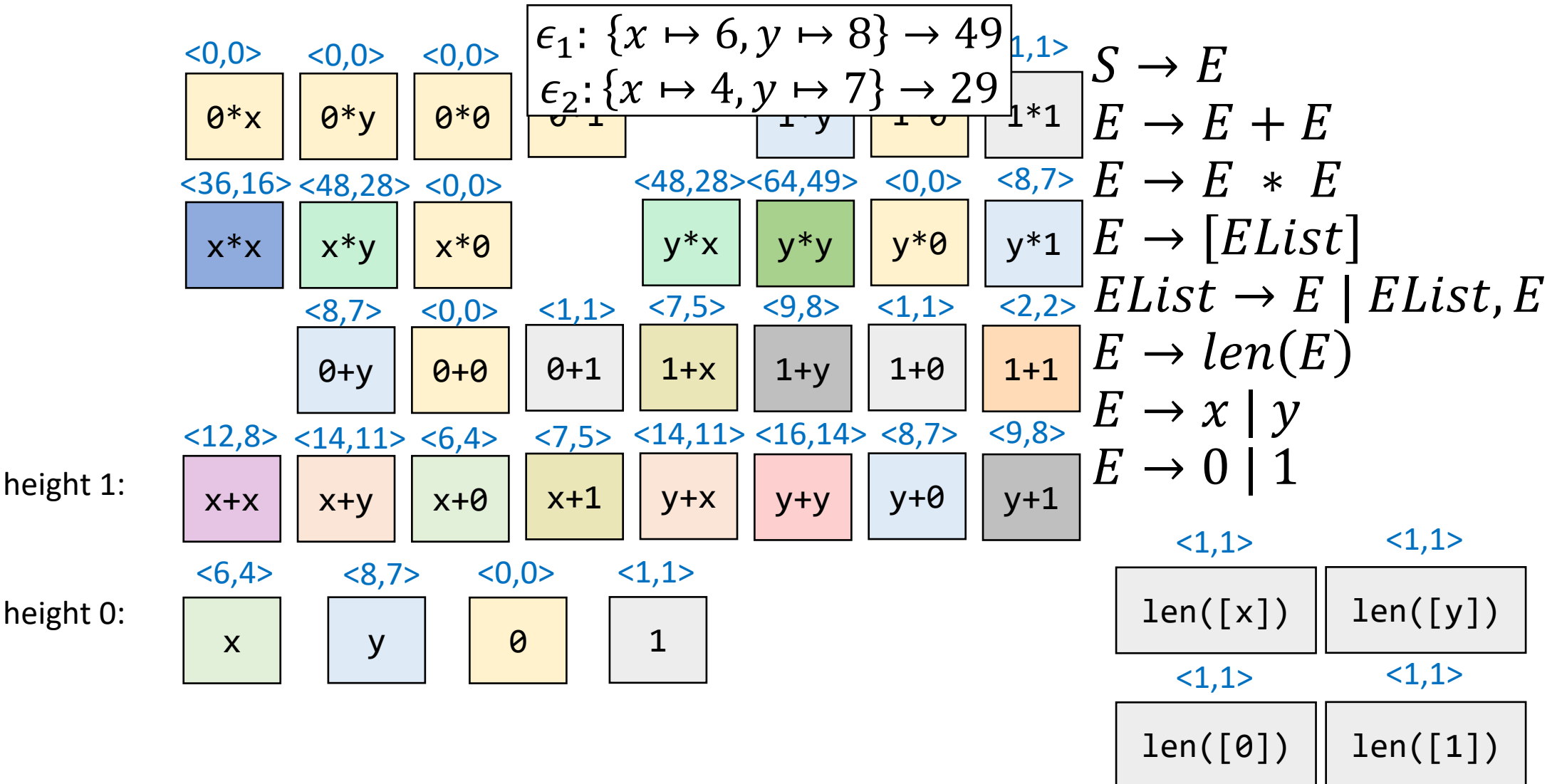
Equivalence classes

[Albarghouthi et al. 2013, Udupa et al. 2013]



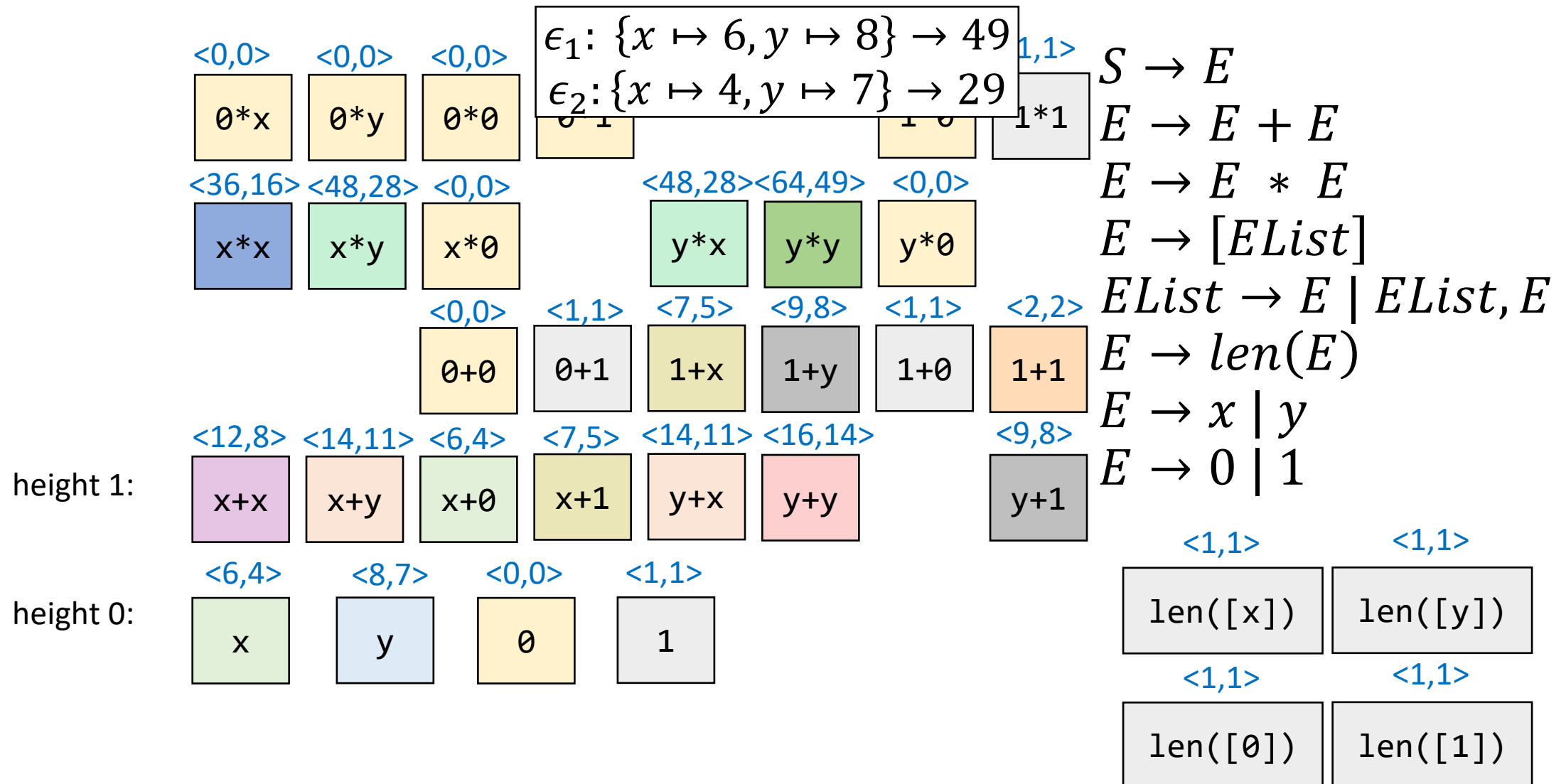
Equivalence classes

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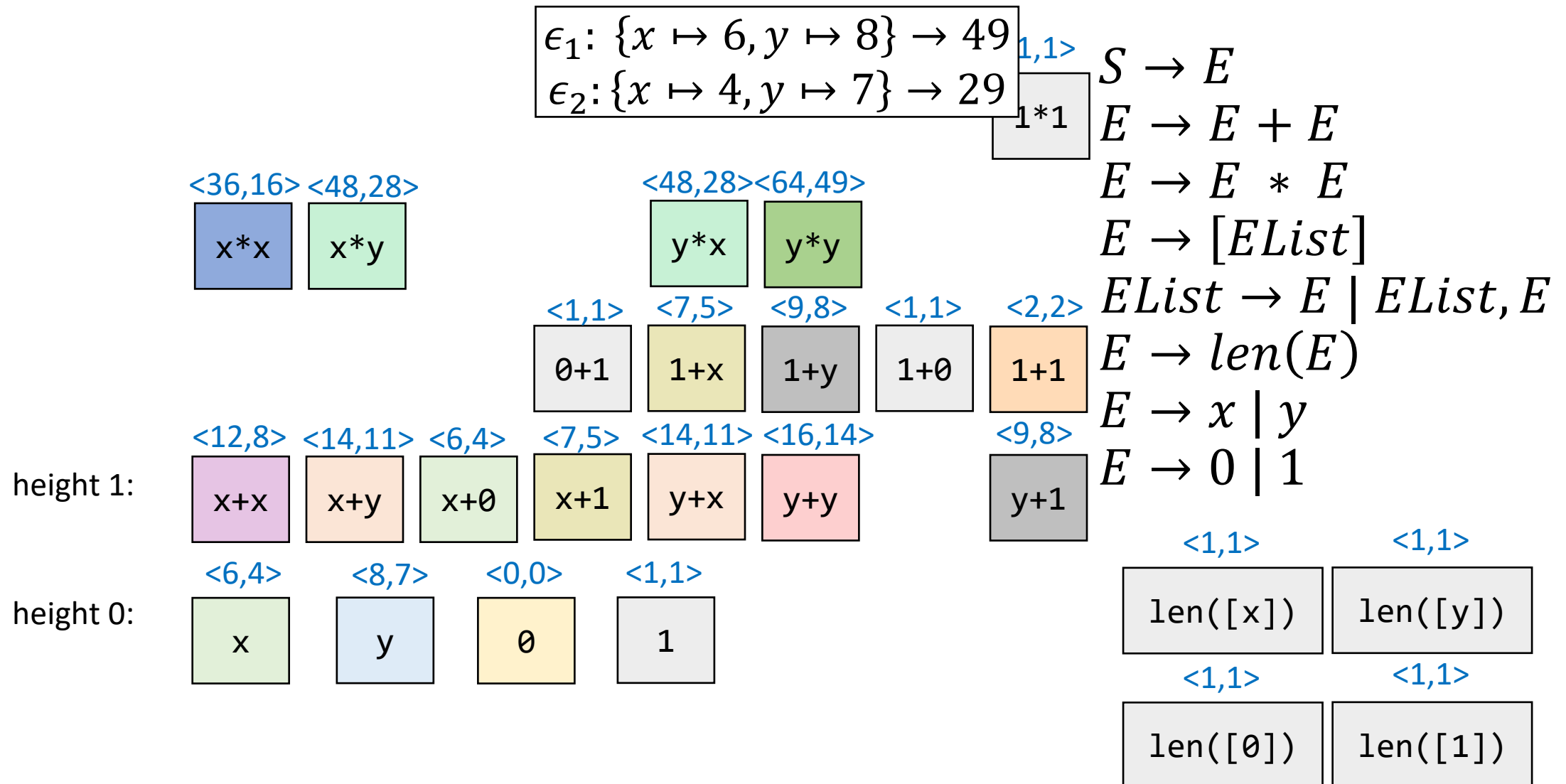
Equivalence classes

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Equivalence classes

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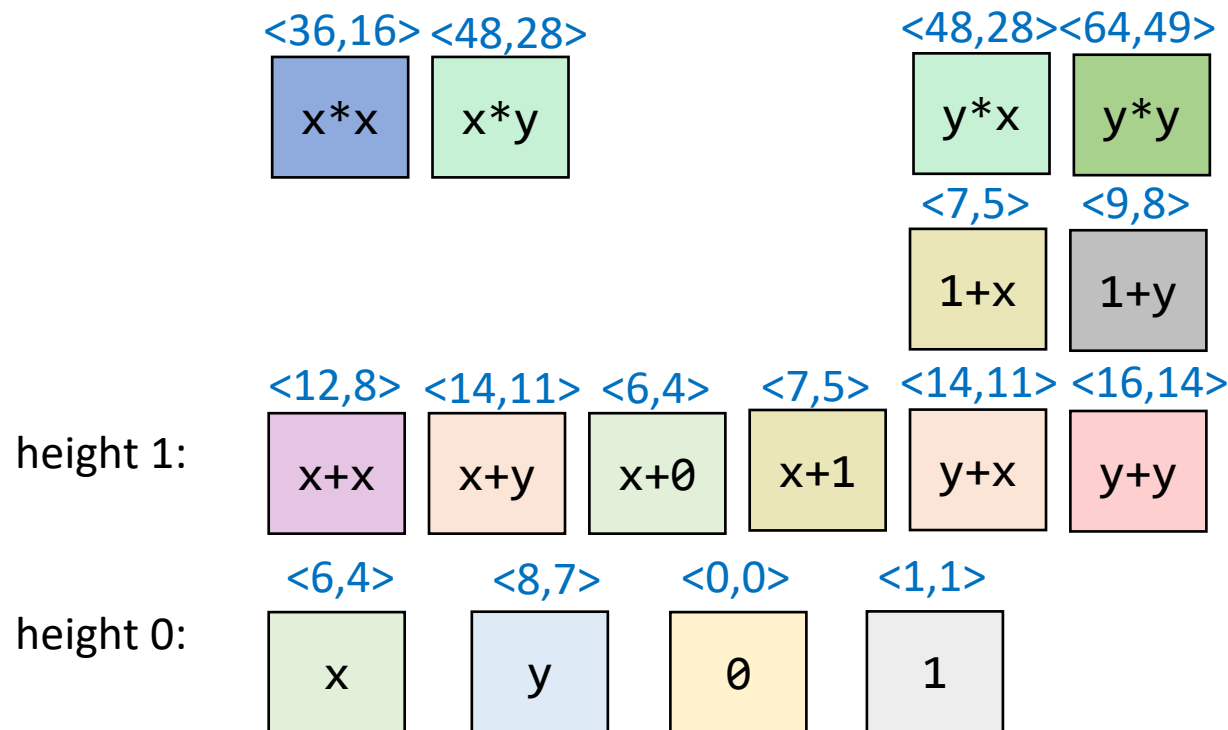


Equivalence classes

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$$\begin{aligned} \epsilon_1 &: \{x \mapsto 6, y \mapsto 8\} \rightarrow 49 \\ \epsilon_2 &: \{x \mapsto 4, y \mapsto 7\} \rightarrow 29 \end{aligned}$$

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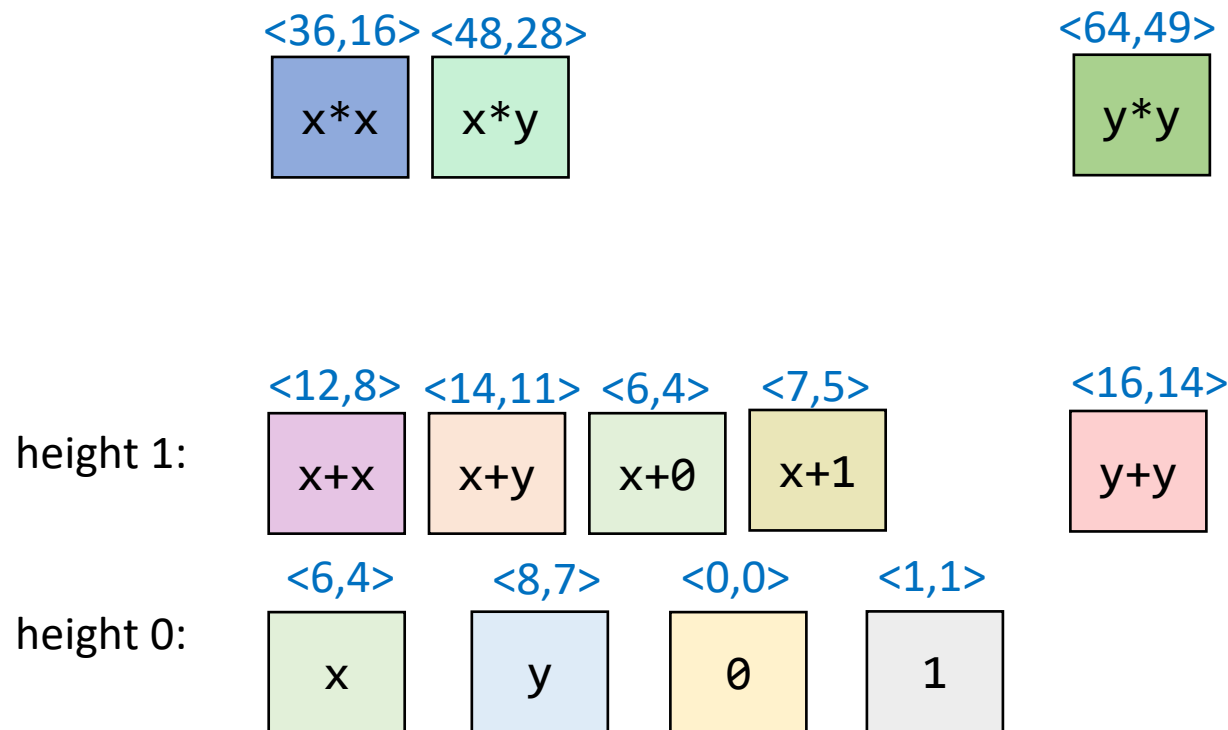


Equivalence classes

[Albarghouthi et al. 2013, Udupa et al. 2013]

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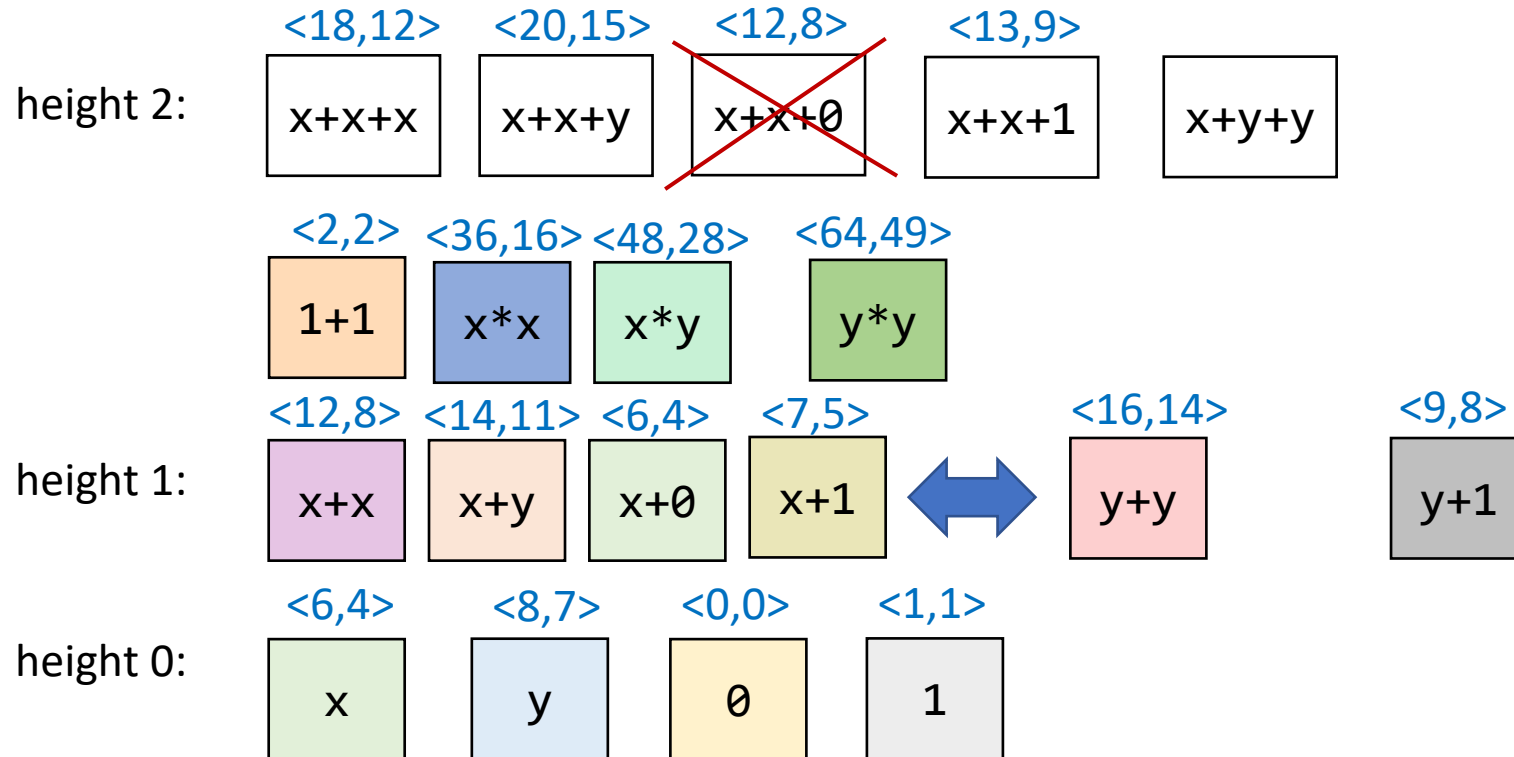
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On the fly

[Albarghouthi et al. 2013, Udupa et al. 2013]

$$\begin{aligned} \epsilon_1: \{x \mapsto 6, y \mapsto 8\} &\rightarrow 49 \\ \epsilon_2: \{x \mapsto 4, y \mapsto 7\} &\rightarrow 29 \end{aligned}$$



$$\begin{aligned} S &\rightarrow E \\ E &\rightarrow E + E \\ E &\rightarrow E * E \\ E &\rightarrow [EList] \\ EList &\rightarrow E \mid EList, E \\ E &\rightarrow len(E) \\ E &\rightarrow x \mid y \\ E &\rightarrow 0 \mid 1 \end{aligned}$$

Pros and cons of bottom-up

Pros:

- Iterative deepening is free
- No need to solver-encode anything

Cons:

- Have to specify literals
- Purity
- OE is very aggressive

Summary

- This time:
 - Program synthesis
 - Types of specification
 - Search algorithms
 - Directions for enumerative search
- Next time:
 - What happens when you give this to people?