Basic Maths for Non-mathematicians

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$$\int_{a}^{b} f(x) dx = \lim_{\Delta x \to 0} \sum_{k=1}^{N} f(x_{k}) \Delta x$$

$$(AB)^{\top} = B^{\top} A^{\top} \qquad \mathbb{R}^{n} \xrightarrow{T} \mathbb{R}^{m}$$

$$\vec{v} = \sum_{i=1}^{n} \alpha_{i} \hat{e}_{i}$$

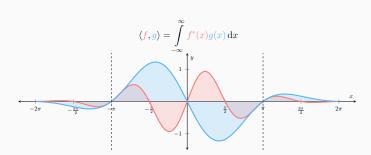
$$\frac{df}{dx} = \lim_{\Delta x \to 0} \frac{f(x + \Delta x) - f(x)}{\Delta x} \qquad A = Q^{\Lambda} Q^{-1}$$

$$\operatorname{Rot}(\theta) = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} \int_{a}^{b} f(x) dx = F(b) - F(a)$$

$$T(\alpha \vec{u} + \beta \vec{v}) = \alpha T(\vec{u}) + \beta T(\vec{v}) \quad \langle \hat{e}_{i}, \hat{e}_{j} \rangle = \delta_{ij}$$



Chapter 9: General Vector Spaces



Let us review some properties of the space \mathbb{R}^n , some of them we already used implicetly without giving them too much thought.

Relating to vector-vector addition:

• The addition of any two vectors $\vec{u}, \vec{v} \in \mathbb{R}^n$ yields a vector $\vec{w} = \vec{u} + \vec{v}$ that is also in \mathbb{R}^n .

For
$$\vec{u}=\begin{pmatrix}1\\2\\-1\end{pmatrix}$$
 and $\vec{v}=\begin{pmatrix}-1\\3\\0\end{pmatrix}$ (both in \mathbb{R}^3),

$$\vec{w} = \vec{u} + \vec{v} = \begin{pmatrix} 0 \\ 5 \\ -1 \end{pmatrix} \in \mathbb{R}^3.$$

Relating to vector-vector addition:

• Vector addition is commutative: $\vec{v} + \vec{u} = \vec{u} + \vec{v}$.

Example

For the same vectors as before:

$$\vec{u} + \vec{v} = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} + \begin{pmatrix} -1 \\ 3 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 + (-1) \\ 2 + 3 \\ -1 + 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 5 \\ -1 \end{pmatrix}.$$

$$\vec{v} + \vec{u} = \begin{pmatrix} -1 \\ 3 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} = \begin{pmatrix} -1 + 1 \\ 3 + 2 \\ 0 + (-1) \end{pmatrix} = \begin{pmatrix} 0 \\ 5 \\ -1 \end{pmatrix}.$$

Relating to vector-vector addition:

• Vector addition is assosiative: $\vec{v} + (\vec{u} + \vec{w}) = (\vec{u} + \vec{v}) + \vec{w}$.

For
$$\vec{a} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$
, $\vec{b} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$, $\vec{c} = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$:
$$\vec{a} + (\vec{b} + \vec{c}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{bmatrix} 0 \\ -1 \end{pmatrix} + \begin{pmatrix} 3 \\ 1 \end{pmatrix} \end{bmatrix}$$

$$= \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 3 \\ 0 \end{pmatrix} = \begin{pmatrix} 4 \\ 0 \end{pmatrix}.$$

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$$\begin{pmatrix} \vec{a} + \vec{b} \end{pmatrix} + \vec{c} = \begin{bmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ -1 \end{pmatrix} \end{bmatrix} + \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 \\ -1 \end{pmatrix} + \begin{pmatrix} 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 \\ 0 \end{pmatrix}.$$

Relating to vector-vector addition:

• The zero vector $\vec{0}$ is unique and has the property that $\vec{v} + \vec{0} = \vec{v}$ for any vector $\vec{v} \in \mathbb{R}^n$.

Example

$$\begin{pmatrix} 4 \\ -1 \\ 0 \\ 3 \\ -6 \\ 2 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 4 \\ -1 \\ 0 \\ 3 \\ -6 \\ 2 \end{pmatrix}$$

Relating to vector-vector addition:

• Any vector $\vec{v} \in \mathbb{R}^n$ has an opposite vector $(-\vec{v}) \in \mathbb{R}^n$ such that $\vec{v} + (-\vec{v}) = \vec{0}$.

Example

$$\begin{pmatrix} 4 \\ -1 \\ 0 \\ 3 \\ -6 \\ 2 \end{pmatrix} + \begin{pmatrix} -4 \\ 1 \\ 0 \\ -3 \\ 6 \\ -2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Relating to scalar-vector product:

• Any scale by $\alpha \in \mathbb{R}$ of a vector $\vec{v} \in \mathbb{R}^n$ is also in \mathbb{R}^n .

Example

$$-3 \cdot \begin{pmatrix} 1 \\ -1 \\ 2 \\ 0 \\ -1 \\ 3 \\ -2 \end{pmatrix} = \begin{pmatrix} -3 \\ 3 \\ -6 \\ 0 \\ 3 \\ -9 \\ 6 \end{pmatrix}$$

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Relating to scalar-vector product:

• Scalar-vector multiplication is associative: $\alpha \left(\beta \vec{v} \right) = \left(\alpha \beta \right) \vec{v}$.

$$-3\begin{bmatrix} 2 \begin{pmatrix} 1 \\ -4 \\ 5 \end{pmatrix} \end{bmatrix} = -3\begin{pmatrix} 2 \\ -8 \\ 10 \end{pmatrix} = \begin{pmatrix} -6 \\ 24 \\ -30 \end{pmatrix}$$
$$(-3 \cdot 2)\begin{pmatrix} 1 \\ -4 \\ 5 \end{pmatrix} = -6\begin{pmatrix} 1 \\ -4 \\ 5 \end{pmatrix} = \begin{pmatrix} -6 \\ 24 \\ -30 \end{pmatrix}.$$

Relating to scalar-vector product:

• Scalar-vector multiplication is distributive in respect to scalar addition: $(\alpha + \beta) \vec{v} = \alpha \vec{v} + \beta \vec{v}$.

$$(5-2) \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} = 3 \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} = \begin{pmatrix} 6 \\ -3 \\ 0 \end{pmatrix}.$$

$$5 \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} - 2 \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} = \begin{pmatrix} 10 \\ -5 \\ 0 \end{pmatrix} - \begin{pmatrix} 4 \\ -2 \\ 0 \end{pmatrix} = \begin{pmatrix} 6 \\ -3 \\ 0 \end{pmatrix}.$$

Relating to scalar-vector product:

• Scalar-vector multiplication is distributive in respect to vector addition: $\alpha(\vec{v} + \vec{u}) = \alpha \vec{v} + \alpha \vec{u}$.

$$5 \begin{bmatrix} \begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix} + \begin{pmatrix} 0 \\ 2 \\ -1 \end{pmatrix} \end{bmatrix} = 5 \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 5 \\ 5 \\ 10 \end{pmatrix}.$$

$$5 \begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix} + 5 \begin{pmatrix} 0 \\ 2 \\ -1 \end{pmatrix} = \begin{pmatrix} 5 \\ -5 \\ 15 \end{pmatrix} + \begin{pmatrix} 0 \\ 10 \\ -5 \end{pmatrix} = \begin{pmatrix} 5 \\ 5 \\ 10 \end{pmatrix}.$$

Relating to scalar-vector product:

• The scalar $\alpha=1$ is neutral in respect to scalar-vector products: $1\vec{v}=\vec{v}$.

$$\begin{pmatrix}
 1 \\
 3 \\
 2 \\
 6 \\
 -5 \\
 7 \\
 -4
 \end{pmatrix} = \begin{pmatrix}
 1 \\
 3 \\
 2 \\
 6 \\
 -5 \\
 7 \\
 -4
 \end{pmatrix}$$

Abstract Vector Spaces

These properties are somewhat obvious on \mathbb{R}^n . However, many times it is worthwhile to use more abstract vector spaces, which can help us model diverse physical and theoretical systems, since once a construct behaves as a vector space, it is a relatively simple process to apply to it all the analysis tools learned so far.

We will not bother here with the formal definition of a vector space¹, but look at one example, which we will later expand on: the space of all real functions $f: \mathbb{R} \to \mathbb{R}$.

http://www.math.niu.edu/beachy/courses/240/06spring/vectorspace.html.

¹For such definition, see here:

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• For each real function f(x) there exists an opposite function (-f)(x) = -f(x), for which

$$f(x) + (-f(x)) = f(x) - f(x) = 0 = z(x).$$

Components (temp name)

Recall that a vector in \mathbb{R}^n can be written using its component in any basis, e.g. the standard basis vectors $\{\hat{e}_1,\hat{e}_2,\dots,\hat{e}_n\}$:

$$\vec{v} = v_1 \hat{e}_1 + v_2 \hat{e}_2 + \dots + v_n \hat{e}_n.$$

How can we "decompose" a function in a similar way?

The **Dirac delta function** comes in handy.

The Dirac Delta Function

Loosely speaking, we can define the Dirac delta function as

$$\delta(x) = \begin{cases} \infty, & x = 0 \\ 0, & x \neq 0. \end{cases}$$