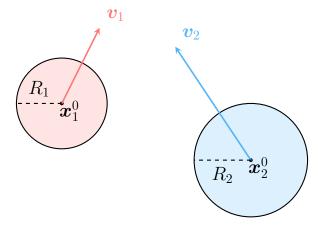
# Calculations

June 2, 2020

# 1 Collision of Two Spherical Particles Moving at Constant Velocities

## 1.1 Time to Collision

Two spherical particles with radii  $R_1$  and  $R_2$ , have initial positions  $\mathbf{x}_1^0$  and  $\mathbf{x}_2^0$  and move with constant velocities  $\mathbf{v}_1$  and  $\mathbf{v}_2$ , respectively. At what time, if at all, will they collide?



The position of particle 1 as a function of time is

$$\boldsymbol{x}_1(t) = \boldsymbol{x}_1^0 + \boldsymbol{v}_1 t,\tag{1}$$

The position of particle 2 as a function of time is identical, i.e.

$$\boldsymbol{x}_2(t) = \boldsymbol{x}_2^0 + \boldsymbol{v}_2 t. \tag{2}$$

Therefore, the distance r(t) between the particles is

$$r(t) = x_1(t) - x_2(t) = x_1^0 + v_1 t - x_2^0 - v_2 t,$$
 (3)

or in explicit vector form

$$\mathbf{r}(t) = \begin{pmatrix} x_1^0 + v_1^x t - x_2^0 + v_2^x t \\ y_1^0 + v_1^y t - y_2^0 + v_2^y t \\ z_1^0 + v_1^z t - z_2^0 + v_2^z t \end{pmatrix} 
= \begin{pmatrix} (x_1^0 - x_2^0) - (v_1^x - v_2^x) t \\ (y_1^0 - y_2^0) - (v_1^y - v_2^y) t \\ (z_1^0 - z_2^0) - (v_1^z - v_2^z) t \end{pmatrix} 
= \begin{pmatrix} \Delta x_0 - \Delta v^x t \\ \Delta y_0 - \Delta v^y t \\ \Delta z_0 - \Delta v^z t \end{pmatrix}.$$
(4)

The square of the norm of r(t) is thus

$$||r||^{2} = (\Delta x_{0} - \Delta v^{x}t)^{2} + (\Delta x_{0} - \Delta v^{x}t)^{2} + (\Delta x_{0} - \Delta v^{x}t)^{2}$$

$$= (\Delta x_{0})^{2} - 2\Delta x_{0}\Delta v^{x}t + (\Delta v^{x})^{2}t^{2} + \cdots$$

$$= (\Delta x_{0})^{2} + (\Delta y_{0})^{2} + (\Delta z_{0})^{2} - 2(\Delta x_{0}\Delta v^{x} + \Delta y_{0}\Delta v^{y} + \Delta z_{0}\Delta v^{z})t + \left((\Delta v^{x})^{2} + (\Delta v^{y})^{2} + (\Delta v^{z})^{2}\right)t^{2}$$

$$= ||\Delta x_{0}||^{2} - 2\langle\Delta x_{0}, \Delta v\rangle t + ||\Delta v||^{2}t^{2}.$$
(5)

The times  $t_{1,2}$  for which the particles collide can be calculated by solving equation 5 for the case

$$||r||^2 = (R_1 + R_2)^2 = R^2,$$
 (6)

i.e. when the distance between the particles is the sum of their radii.

Using the quadratic formula,

$$t_{1,2} = \frac{2\langle \Delta \boldsymbol{x}_{0}, \Delta \boldsymbol{v} \rangle \pm \sqrt{4\langle \Delta \boldsymbol{x}_{0}, \Delta \boldsymbol{v} \rangle^{2} - 4 \|\Delta \boldsymbol{v}\|^{2} \left(\|\Delta \boldsymbol{x}_{0}\|^{2} - R^{2}\right)}}{2 \|\Delta \boldsymbol{v}\|^{2}}$$

$$= \frac{\langle \Delta \boldsymbol{x}_{0}, \Delta \boldsymbol{v} \rangle \pm \sqrt{\langle \Delta \boldsymbol{x}_{0}, \Delta \boldsymbol{v} \rangle^{2} - \|\Delta \boldsymbol{v}\|^{2} \left(\|\Delta \boldsymbol{x}_{0}\|^{2} - R^{2}\right)}}{\|\Delta \boldsymbol{v}\|^{2}}.$$
(7)

The condition for which a collision will happen is therefore

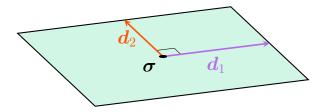
$$\langle \Delta \boldsymbol{x}_0, \Delta \boldsymbol{v} \rangle^2 \ge \|\Delta \boldsymbol{v}\|^2 \left( \|\Delta \boldsymbol{x}_0\|^2 - R^2 \right).$$
 (8)

## 1.2 Veclocity Change

# 2 Collision of a Spherical Particle and a Planar Wall

### 2.1 Definition of a Planar Wall

A plane can be defined by a point and a direction normal to the plane. However, we wish to use only a finite part of the plane. We therefore define a wall using a point  $\sigma$  and two orthogonal vectors  $d_1$  and  $d_2$ :

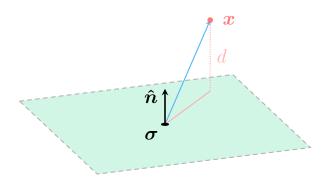


The normal to the wall surface can then be defined as

$$\hat{\boldsymbol{n}} = \frac{\boldsymbol{d}_1 \times \boldsymbol{d}_2}{\|\boldsymbol{d}_1 \times \boldsymbol{d}_2\|}.\tag{9}$$

#### 2.2 Time to Collision

The distance d between a spherical particle and a wall can be calculated as the distance between its center (a point) and the plane of which the wall is a part of. This distance is the projection of the vector  $\mathbf{x} - \boldsymbol{\sigma}$  onto  $\hat{\mathbf{n}}$ :



Using the dot product, it can be written as

$$d = \langle \boldsymbol{x} - \boldsymbol{\sigma}, \hat{\boldsymbol{n}} \rangle, \tag{10}$$

since  $\|\hat{\boldsymbol{n}}\| = 1$ .

The position of the sphere as a function of time is

$$\boldsymbol{x}(t) = \boldsymbol{x}^0 + \boldsymbol{v}t,\tag{11}$$

and thus

$$d = \langle \boldsymbol{x}^0 + \boldsymbol{v}t - \boldsymbol{\sigma}, \hat{\boldsymbol{n}} \rangle$$
  
=  $\langle \boldsymbol{x}^0 - \boldsymbol{\sigma}, \hat{\boldsymbol{n}} \rangle + \langle \boldsymbol{v}, \boldsymbol{\sigma} \rangle t,$  (12)

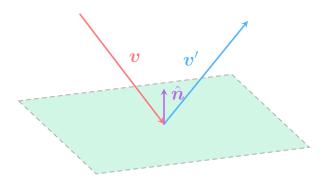
and the solution for d = R becomes

$$t = \frac{R - \langle \boldsymbol{x}^0 - \boldsymbol{\sigma}, \hat{\boldsymbol{n}} \rangle}{\langle \boldsymbol{v}, \hat{\boldsymbol{n}} \rangle}.$$
 (13)

(note that both innerproducts implicitly contain a division by  $\|\hat{\boldsymbol{n}}\|$ , and so the units match)

PROJECTION OF XSIGMA ON D1, D2.

## 2.3 Velocity Change



The projection of  $\boldsymbol{v}$  onto  $\hat{\boldsymbol{n}}$  is

$$\operatorname{proj}_{\hat{\boldsymbol{n}}}\boldsymbol{v} = \langle \boldsymbol{v}, \hat{\boldsymbol{n}} \rangle \hat{\boldsymbol{n}}, \tag{14}$$

and on a direction orthogonal to  $\hat{\boldsymbol{n}}$  is

$$v - \langle v, \hat{n} \rangle \hat{n}$$
. (15)

 $\boldsymbol{v}$  can be reconstructed from these two components,

$$\mathbf{v} = \langle \mathbf{v}, \hat{\mathbf{n}} \rangle \hat{\mathbf{n}} + \mathbf{v} - \langle \mathbf{v}, \hat{\mathbf{n}} \rangle \hat{\mathbf{n}}. \tag{16}$$

Similarly, v' has the  $\hat{n}$  opposite and equal in magnitude to that of v, and the orthogonal component equal to that of v, yielding

$$v' = -\langle v, \hat{n} \rangle \hat{n} + v - \langle v, \hat{n} \rangle \hat{n}$$
  
=  $v - 2\langle v, \hat{n} \rangle \hat{n}$ . (17)