

# PPT 14

ALJABAR LINEAR



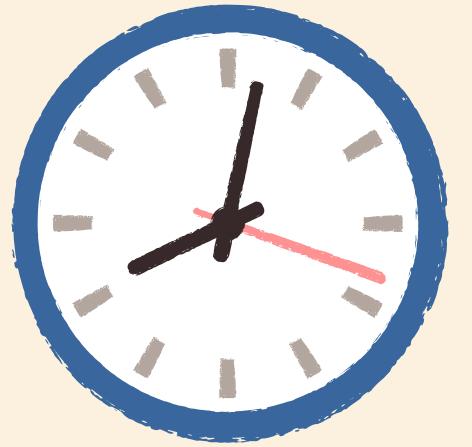
# Lesson Outline

INNER PRODUCT

BASIS ORTHONORMAL

GRAM SCHMIT

KOORDINAT BASIS BARU



# INNER PRODUCT

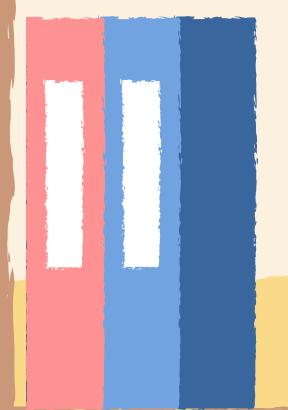
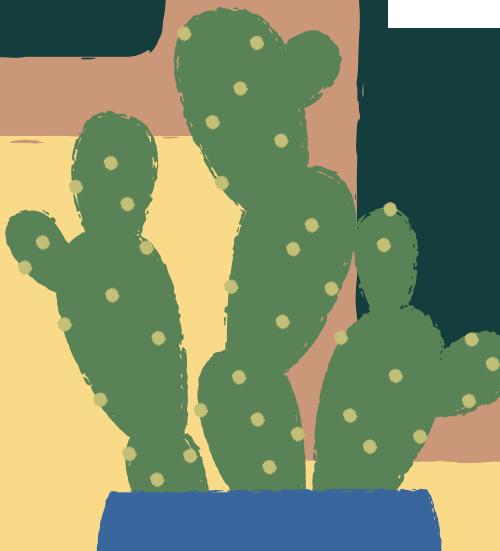


# INNER PRODUCT??



Hasil kali dalam pada ruang vektor nyata  $V$  adalah suatu fungsi  $\langle \cdot, \cdot \rangle : V \times V \rightarrow \mathbb{R}$  yang mengaitkan suatu bilangan real  $\langle u, v \rangle$  pada setiap pasangan vektor  $u$  dan  $v$  dalam  $V$  dan memenuhi aksioma-aksioma berikut untuk semua vektor  $u, v, w \in V$  dan semua skalar  $k \in \mathbb{R}$

1.  $\langle u, v \rangle = \langle v, u \rangle$  [aksiom simetris]
2.  $\langle u + v, w \rangle = \langle u, w \rangle + \langle v, w \rangle$  [aksiom penjumlahan]
3.  $\langle ku, v \rangle = k\langle u, v \rangle$  [aksiom homogenitas]
4.  $\langle v, v \rangle \geq 0$  dan  $\langle v, v \rangle = 0$  jika dan hanya jika  $v = 0$  [aksiom positif]





$$\begin{aligned}\langle \vec{u}, \vec{v} \rangle &= \vec{u} \cdot \vec{v} \\ &= u_1 v_1 + u_2 v_2 + \dots + u_n v_n\end{aligned}$$

karena aksioma  $\langle u, v \rangle$  memenuhi perkalian dot dari 2 vektor, maka:

$$\begin{aligned}\langle u, v \rangle &= u \cdot v \\ &= U_1 V_1 + U_2 V_2 + \dots + U_n V_n\end{aligned}$$



Namun, dalam beberapa aplikasi, kita mungkin perlu memodifikasi hasil kali dalam ini dengan memberi BOBOT berbeda pada setiap komponen. Misalnya, mungkin ada kasus di mana beberapa elemen dari vektor memiliki pengaruh lebih besar atau lebih kecil dibandingkan yang lain.

Oleh karena itu, kita memperkenalkan bobot  $w_1, w_2, \dots, w_n$

misal  $w_1, w_2, \dots, w_n$   $\xrightarrow{\text{diketahui}} \oplus$  dinamakan bobot

mt:

$$\langle \vec{u}, \vec{v} \rangle = w_1 u_1 v_1 + w_2 u_2 v_2 + \dots + w_n u_n v_n$$

$\xrightarrow{\text{diketahui}}$  hasil kali dalam Euclidian yg diboboti dgn bobot  $w_1, w_2, \dots, w_n$

contoh 47:  $\vec{u} = (u_1, u_2)$  }  $\vec{v} = (v_1, v_2)$  }  $\vec{w} = (\bar{u}, \bar{v})$  }  $\vec{r} = (r_1, r_2)$  }  $\vec{u}, \vec{v}$  lebih fleksibel dibandingkan  $\vec{u}, \vec{v}$   
 $\vec{u}, \vec{v}$  bisa bukan matriks pers. liner  
 $\vec{u}, \vec{v}$  pd  $\mathbb{R}^2$ , buktikan!  
bahwa hasil kali dalam Euclidis  
yg dibuktikan:

$$\langle \vec{u}, \vec{v} \rangle = 3u_1v_1 + 2u_2v_2$$

menyatuhi 4 aksiom pd hal 175  
 $\rightarrow$  polanya sama

① ruas kiri  $\Rightarrow \langle \vec{u}, \vec{v} \rangle = 3u_1v_1 + 2u_2v_2$

ruas kanan  $\Rightarrow \langle \vec{r}, \vec{u} \rangle = 3u_1v_1 + 2u_2v_2$

$\Rightarrow$  ruas kiri = ruas kanan, mk aksioma 1 terpenuhi

②  $\langle \vec{u} + \vec{v}, \vec{w} \rangle = \langle \vec{u}, \vec{w} \rangle + \langle \vec{v}, \vec{w} \rangle$

Kiri  $\Rightarrow \langle \vec{u} + \vec{v}, \vec{w} \rangle = 3(u_1 + v_1)w_1 + 2(u_2 + v_2)w_2$

$$= 3u_1w_1 + 3v_1w_1 + 2u_2w_2 + 2v_2w_2$$

$$= 3u_1w_1 + 2u_2w_2 + 3v_1w_1 + 2v_2w_2$$

Kanan  $\Rightarrow \langle \vec{u}, \vec{w} \rangle + \langle \vec{v}, \vec{w} \rangle$

$$= 3u_1w_1 + 2u_2w_2 + 3v_1w_1 + 2v_2w_2$$

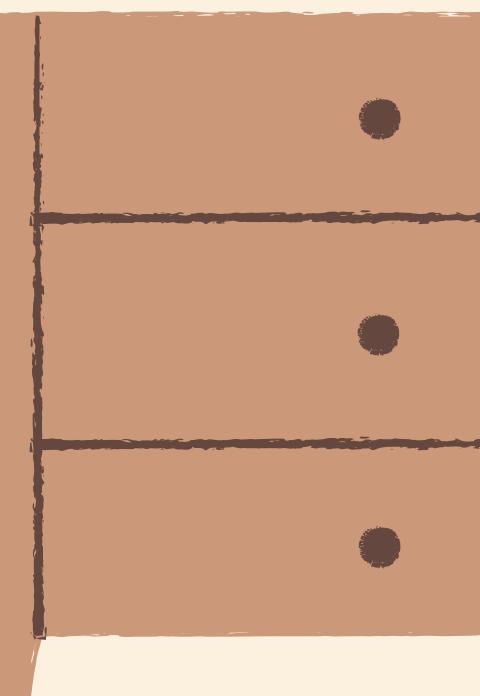
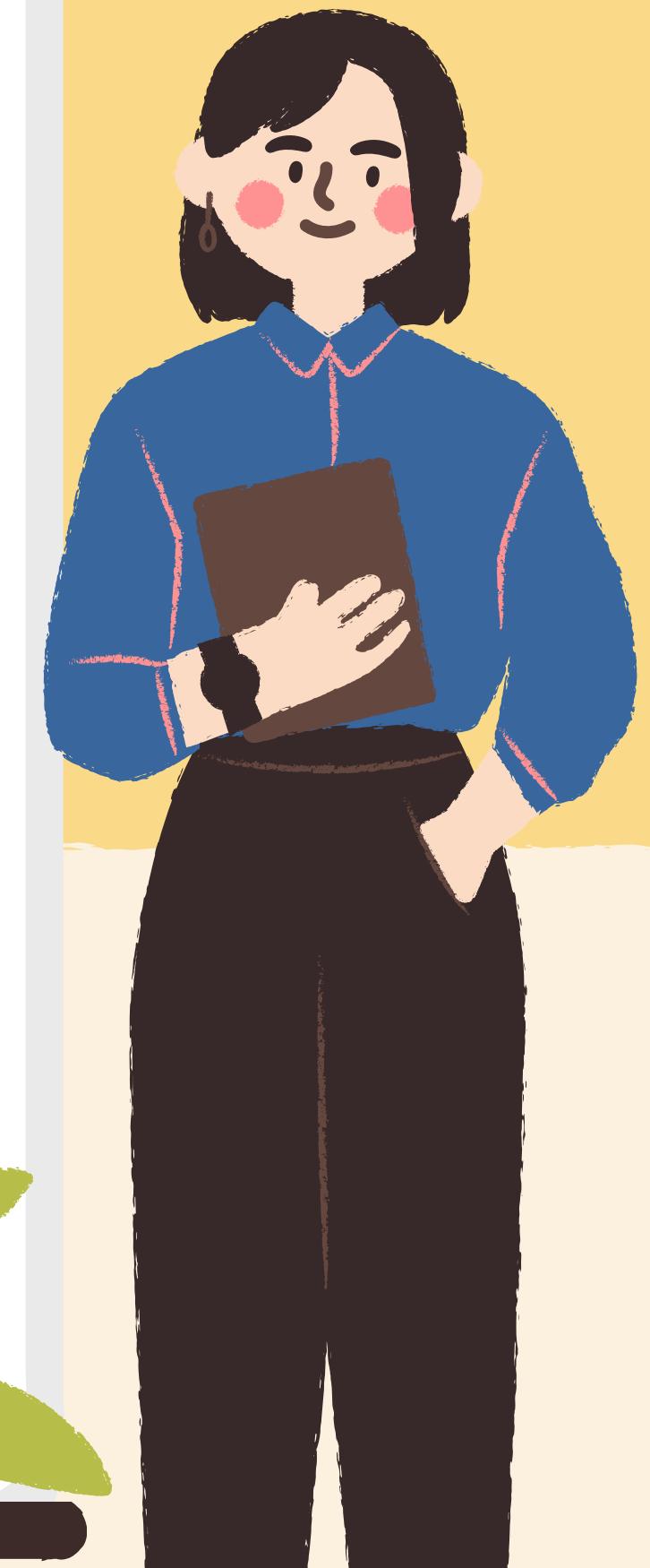
Kiri = Kanan  $\Rightarrow$  mk aksioma 2 terpenuhi

③  $\langle k\vec{u}, \vec{w} \rangle = k \langle \vec{u}, \vec{w} \rangle$

Kiri  $\Rightarrow \langle k\vec{u}, \vec{w} \rangle = 3k\bar{u}_1w_1 + 2k\bar{u}_2w_2$

Kanan  $\Rightarrow k \langle \vec{u}, \vec{w} \rangle = k(3u_1w_1 + 2u_2w_2)$   
 $= 3ku_1w_1 + 2ku_2w_2$

Kiri = Kanan  $\Rightarrow$  mk aksioma 3 terpenuhi





→  $\text{kanan} \rightsquigarrow 4.22$  (b)

$$\begin{aligned}\textcircled{4} \quad \langle \bar{v}, \bar{v} \rangle &= 3 v_1 v_1 + 2 v_2 v_2 \\ &= 3 v_1^2 + 2 v_2^2\end{aligned}$$

jelas bahwa  $3 v_1^2 + 2 v_2^2 \geq 0$

selanjutnya  $\langle \bar{v}, \bar{v} \rangle = 3 v_1^2 + 2 v_2^2 = 0$  jika  $v_1 = v_2 = 0$

contoh qq: no what buku

$$\bar{u} = \begin{bmatrix} u_1 & u_2 \\ u_3 & u_4 \end{bmatrix} \quad \bar{v} = \begin{bmatrix} v_1 & v_2 \\ v_3 & v_4 \end{bmatrix}$$

rumus berikut mendefinisikan hasil kali dalam pd  $M_{2,2}$

$$\langle \bar{u}, \bar{v} \rangle = u_1 v_1 + u_2 v_2 + u_3 v_3 + u_4 v_4$$

$$\|\bar{u}\| = \sqrt{u_1^2 + u_2^2 + u_3^2 + u_4^2}$$

misal:

$$\bar{u} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \quad \bar{v} = \begin{bmatrix} -1 & 0 \\ 3 & 2 \end{bmatrix}$$

mk:

$$\begin{aligned}\langle \bar{u}, \bar{v} \rangle &= 1(-1) + 2(0) + 3(3) + 4(2) \\ &= 16\end{aligned}$$

contoh so:

$$P = a_0 + a_1 x + a_2 x^2$$

$$q = b_0 + b_1 x + b_2 x^2$$

mk hasil kali dalam pd  $P_2$  adalah :

$$\langle P, q \rangle = a_0 b_0 + a_1 b_1 + a_2 b_2$$

$$\|P\| = \sqrt{a_0^2 + a_1^2 + a_2^2}$$



$$\begin{aligned} \cdot) \|\bar{u}\| &= \langle \bar{u}, \bar{u} \rangle^{\frac{1}{2}} \rightarrow \text{if ada bobot} \\ &= \langle \bar{u}, \bar{u} \rangle^{\frac{1}{2}} \\ &= \sqrt{\bar{u} \cdot \bar{u}} \\ &= \sqrt{u_1^2 + u_2^2} \quad \} \rightarrow \text{if } \neq \text{ bobot } \langle \text{biasa} \rangle \end{aligned}$$

◦ jarak antar 2 vektor  $\bar{u} \times \bar{v} \Rightarrow d(\bar{u}, \bar{v}) = \|\bar{u} - \bar{v}\|$

◦ aturan ketaksamaan Cauchy - Schwarz

$$\langle \bar{u}, \bar{v} \rangle^2 \leq \langle \bar{u}, \bar{u} \rangle \cdot \langle \bar{v}, \bar{v} \rangle \quad \begin{matrix} \text{ada bobot} \rightarrow \\ \neq \text{bobot} \end{matrix} \rightarrow = \sqrt{(u_1 - v_1)^2 + (u_2 - v_2)^2}$$

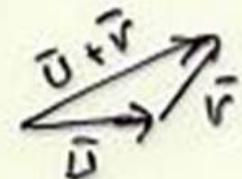
sifat dasar panjang

$$\|\bar{u}\| \geq 0$$

$$\|\bar{u}\| = 0 \quad \text{if} \quad \bar{u} = 0$$

$$\|k\bar{u}\| = |k| \|\bar{u}\|$$

$$\|\bar{u} + \bar{v}\| \leq \|\bar{u}\| + \|\bar{v}\|$$



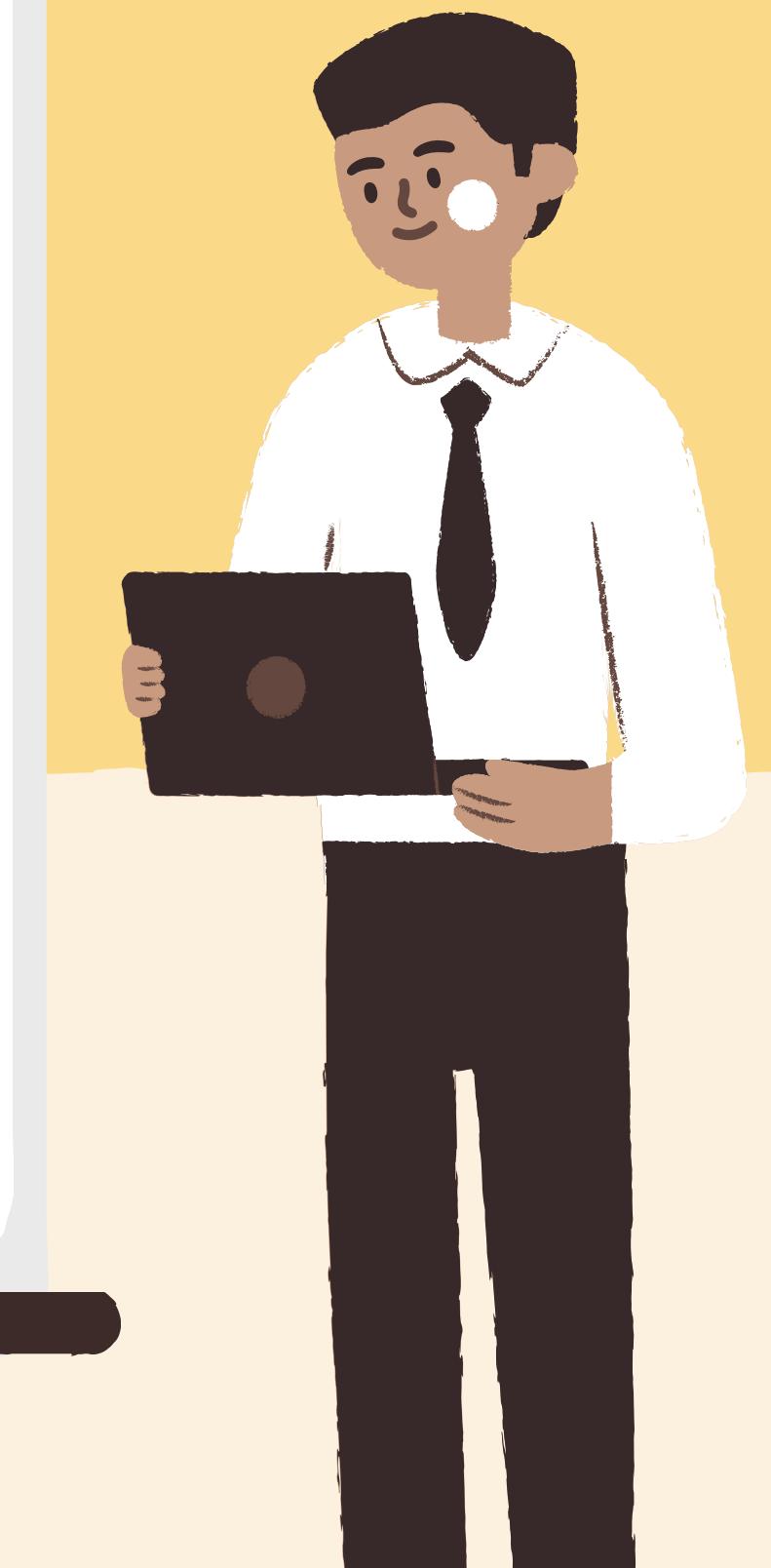
sifat dasar jarak

$$\langle \bar{u}, \bar{v} \rangle \geq 0$$

$$d(\bar{u}, \bar{v}) = 0 \quad \text{if} \quad \bar{u} = \bar{v}$$

$$d(\bar{u}, \bar{v}) = d(\bar{v}, \bar{u})$$

$$d(\bar{u}, \bar{v}) \leq d(\bar{u}, \bar{w}) + d(\bar{w}, \bar{v})$$





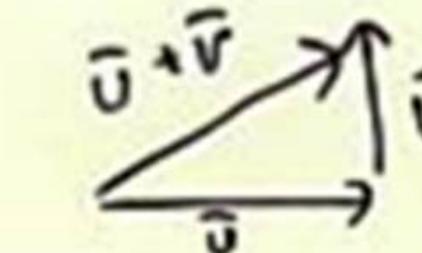
o) Sudut antara  $\bar{u} \times \bar{v}$

$$\cos \theta = \frac{\langle \bar{u}, \bar{v} \rangle}{\|\bar{u}\| \cdot \|\bar{v}\|}$$

o)  $\bar{u} \times \bar{v}$  saling  $\perp$  if  $\Rightarrow \langle \bar{u}, \bar{v} \rangle = 0$

o) If  $\bar{u} \perp \bar{v}$ , then:

$$\|\bar{u} + \bar{v}\|^2 = \|\bar{u}\|^2 + \|\bar{v}\|^2$$



Contoh 55 :

$$\bar{u} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \bar{v} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

pola  $\langle \bar{u}, \bar{v} \rangle = 3 u_1 v_1 + 2 u_2 v_2$



Contoh 55 :

$$\vec{u} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \vec{v} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

pola  $\langle \vec{u}, \vec{v} \rangle = 3 u_1 v_1 + 2 u_2 v_2$

$$\begin{aligned}\|\vec{u}\| &= \langle \vec{u}, \vec{u} \rangle^{1/2} \\ &= (3 \cdot 1 \cdot 1 + 2 \cdot 0 \cdot 0)^{1/2} \\ &= (3 \cdot 1 \cdot 1 + 2 \cdot 0 \cdot 0)^{1/2} \\ &= \sqrt{3}\end{aligned}$$

$$\begin{aligned}d(\vec{u}, \vec{v}) &= \|\vec{u} - \vec{v}\| \\ &= \langle \overset{\vec{u}}{\cancel{\vec{u}-\vec{v}}}, \overset{\vec{u}}{\cancel{\vec{u}-\vec{v}}} \rangle^{1/2} \\ &= (3 \cdot 1 \cdot 1 + 2 \cdot 0 \cdot 0)^{1/2} \quad \begin{array}{l} U_1 = U_1 - V_1 \\ = 1 - 0 \\ = 1 \end{array} \\ &= (3 \cdot 1 \cdot 1 + 2 \cdot -1 \cdot -1)^{1/2} \quad \begin{array}{l} U_2 = U_2 - V_2 \\ = 0 - 1 \\ = -1 \end{array} \\ &= (3 + 2)^{1/2} \\ &= \sqrt{5}\end{aligned}$$





**Example 2** Let  $\mathbb{R}^4$  have the Euclidean inner product. Find the cosine of the angle  $\theta$  between the vectors  $u = (4, 3, 1, -2)$  and  $v = (-2, 1, 2, 3)$ .

*Solution.* We leave it for the reader to verify that

$$\|u\| = \sqrt{30}, \quad \|v\| = \sqrt{18}, \quad \text{and} \quad \langle u, v \rangle = -9$$

so that

$$\cos \theta = \frac{\langle u, v \rangle}{\|u\|\|v\|} = -\frac{9}{\sqrt{30}\sqrt{18}} = -\frac{3}{2\sqrt{15}}$$

INNER PRODUCT dikatakan ORTHOGONAL, jika:

$$\langle u, v \rangle = 0$$

Example 3 If  $M_{2,2}$  has the inner product of Example 7 in the preceding section, then the matrices

$$U = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \quad \text{and} \quad V = \begin{bmatrix} 0 & 2 \\ 0 & 0 \end{bmatrix}$$

are orthogonal, since

$$\langle U, V \rangle = 1(0) + 0(2) + 1(0) + 1(0) = 0$$



**Definition.** Let  $W$  be a subspace of an inner product space  $V$ . A vector  $u$  in  $V$  is said to be *orthogonal to  $W$*  if it is orthogonal to every vector in  $W$ , and the set of all vectors in  $V$  that are orthogonal to  $W$  is called the *orthogonal complement of  $W$* .

**Theorem 6.2.6.** If  $A$  is an  $m \times n$  matrix, then:

- (a) The nullspace of  $A$  and the row space of  $A$  are orthogonal complements in  $\mathbb{R}^n$  with respect to the Euclidean inner product.
- (b) The nullspace of  $A^T$  and the column space of  $A$  are orthogonal complements in  $\mathbb{R}^m$  with respect to the Euclidean inner product.





**Example 6** Let  $W$  be the subspace of  $\mathbb{R}^5$  spanned by the vectors

$$w_1 = (2, 2, -1, 0, 1), \quad w_2 = (-1, -1, 2, -3, 1),$$

$$w_3 = (1, 1, -2, 0, -1), \quad w_4 = (0, 0, 1, 1, 1)$$

Find a basis for the orthogonal complement of  $W$ .



**Example 6** Let  $W$  be the subspace of  $\mathbb{R}^5$  spanned by the vectors

$$\begin{aligned}w_1 &= (2, 2, -1, 0, 1), & w_2 &= (-1, -1, 2, -3, 1), \\w_3 &= (1, 1, -2, 0, -1), & w_4 &= (0, 0, 1, 1, 1)\end{aligned}$$

Find a basis for the orthogonal complement of  $W$ .

$$A = \begin{bmatrix} 2 & 2 & -1 & 0 & 1 \\ -1 & -1 & 2 & -3 & 1 \\ 1 & 1 & -2 & 0 & -1 \\ 0 & 0 & 1 & 1 & 1 \end{bmatrix}$$

and by part (a) of Theorem 6.2.6 the nullspace of  $A$  is the orthogonal complement of  $W$ . In Example 4 of Section 5.5 we showed that

$$v_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad \text{and} \quad v_2 = \begin{bmatrix} -1 \\ 0 \\ -1 \\ 0 \\ 1 \end{bmatrix}$$

form a basis for this nullspace. Expressing these vectors in the same notation as  $w_1$ ,  $w_2$ ,  $w_3$ , and  $w_4$ , we conclude that the vectors

$$v_1 = (-1, 1, 0, 0, 0) \quad \text{and} \quad v_2 = (-1, 0, -1, 0, 1)$$

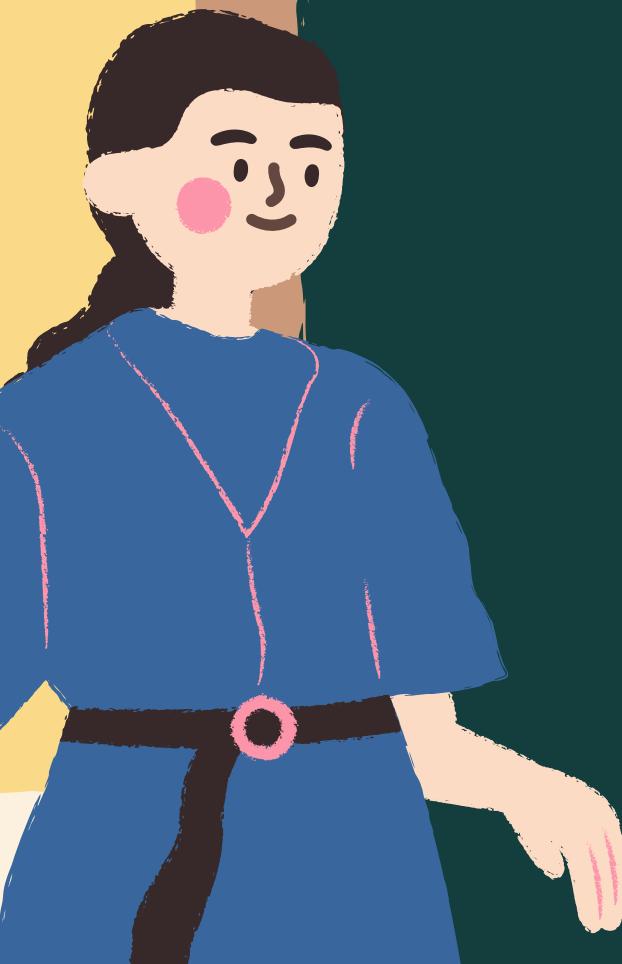
form a basis for the orthogonal complement of  $W$ . As a check, the reader may want to verify that  $v_1$  and  $v_2$  are orthogonal to  $w_1$ ,  $w_2$ ,  $w_3$ , and  $w_4$  by calculating the necessary dot products.

BASIS  
ORTHO  
NORMAL



# BASIS ORTHONORMAL

- Cara menentukan basis
  - Cari basis sendiri → basis baru
  - Dari vektor-vektor yang ada → basis dari vektor-vektor lama
- Ortonormal
  - Ortogonal
  - Tiap vektor normanya(panjangnya) 1
- Normalisasi → proses membagi V dengan panjangnya  $\|V\|$  agar normanya 1



**Example I** Let

$$u_1 = (0, 1, 0), \quad u_2 = (1, 0, 1), \quad u_3 = (1, 0, -1)$$

and assume that  $\mathbb{R}^3$  has the Euclidean inner product. It follows that the set of vector  $S = \{u_1, u_2, u_3\}$  is orthogonal since  $\langle u_1, u_2 \rangle = \langle u_1, u_3 \rangle = \langle u_2, u_3 \rangle = 0$ .

**Example I** Let

$$u_1 = (0, 1, 0), \quad u_2 = (1, 0, 1), \quad u_3 = (1, 0, -1)$$

and assume that  $\mathbb{R}^3$  has the Euclidean inner product. It follows that the set of vectors  $S = \{u_1, u_2, u_3\}$  is orthogonal since  $\langle u_1, u_2 \rangle = \langle u_1, u_3 \rangle = \langle u_2, u_3 \rangle = 0$ .

If  $v$  is a nonzero vector in an inner product space, then by part (c) of Theorem 6.2.2 the vector

$$\frac{1}{\|v\|}v$$

has norm 1, since

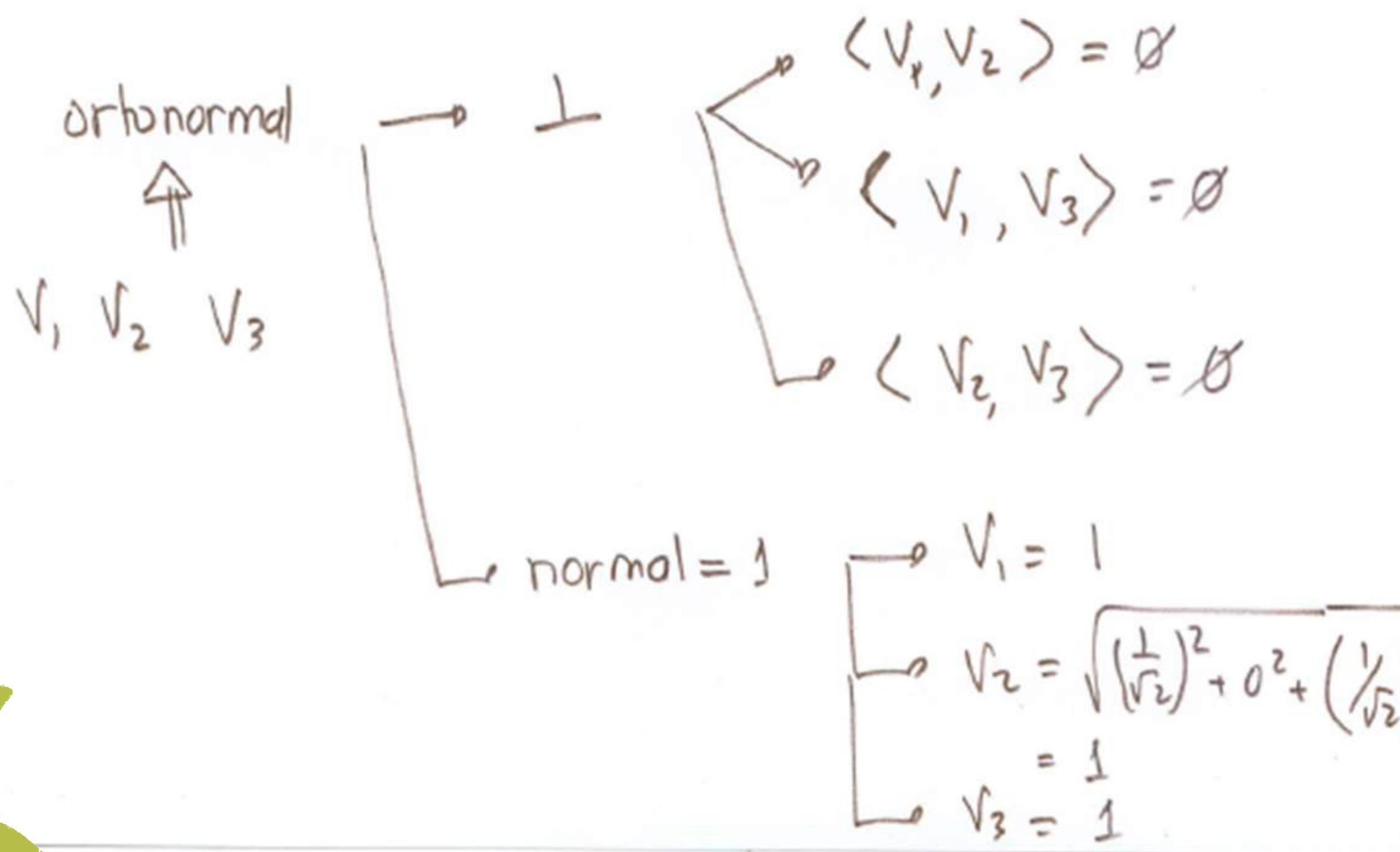
$$\left\| \frac{1}{\|v\|}v \right\| = \left| \frac{1}{\|v\|} \right| \|v\| = \frac{1}{\|v\|} \|v\| = 1$$

The process of multiplying a nonzero vector  $v$  by the reciprocal of its length to obtain a vector of norm 1 is called *normalizing*  $v$ . An orthogonal set of nonzero vectors can always be converted to an orthonormal set by normalizing each of its vectors.

$$V_1 = \frac{U_1}{|U_1|} = \frac{(0, 1, 0)}{1} = (0, 1, 0)$$

$$V_2 = \frac{U_2}{|U_2|} = \frac{(1, 0, 1)}{\sqrt{2}} = \left(\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}\right)$$

$$V_3 = \frac{U_3}{|U_3|} = \frac{(1, 0, -1)}{\sqrt{2}} = \left(\frac{1}{\sqrt{2}}, 0, -\frac{1}{\sqrt{2}}\right)$$



**Example 2** The Euclidean norms of the vectors in Example 1 are

$$\|u_1\| = 1, \quad \|u_2\| = \sqrt{2}, \quad \|u_3\| = \sqrt{2}$$

Consequently, normalizing  $u_1$ ,  $u_2$ , and  $u_3$  yields

$$v_1 = \frac{u_1}{\|u_1\|} = (0, 1, 0), \quad v_2 = \frac{u_2}{\|u_2\|} = \left( \frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}} \right),$$

$$v_3 = \frac{u_3}{\|u_3\|} = \left( \frac{1}{\sqrt{2}}, 0, -\frac{1}{\sqrt{2}} \right)$$

We leave it for you to verify that the set  $S = \{v_1, v_2, v_3\}$  is orthonormal by showing

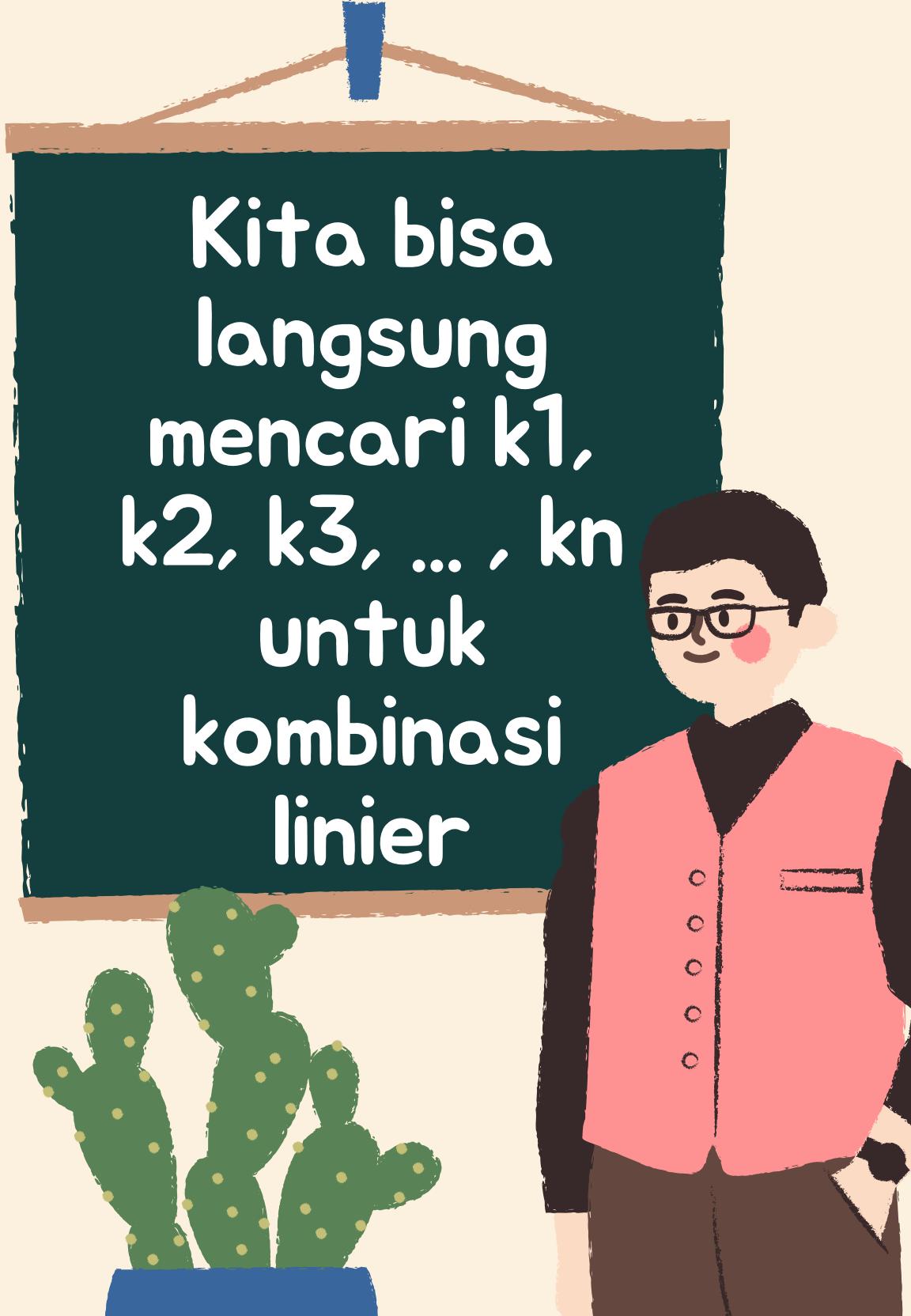
That  $\langle v_1, v_2 \rangle = \langle v_1, v_3 \rangle = \langle v_2, v_3 \rangle = 0$

$$\|v_1\| = \|v_2\| = \|v_3\| = 1$$

# Keuntungan Orthonormal

Theorem 6.3.1. If  $S = \{v_1, v_2, \dots, v_n\}$  is an orthonormal basis for an inner product space  $V$ , and  $u$  is any vector in  $V$ , then

$$u = \langle u, v_1 \rangle v_1 + \langle u, v_2 \rangle v_2 + \dots + \langle u, v_n \rangle v_n$$



Kita bisa langsung mencari  $k_1, k_2, k_3, \dots, k_n$  untuk kombinasi linier



teorema 2.3 :

$\rightarrow S = \{\bar{v}_1, \bar{v}_2, \dots, \bar{v}_n\}$  ~ basis ortonormal

nyatakan bahwa vektor  $\bar{u}$  adalah kombinasi linier dr vektor  $\in S$ , mt:

$$\Rightarrow \bar{u} = k_1 \bar{v}_1 + k_2 \bar{v}_2 + \dots + k_n \bar{v}_n$$

$$\langle \bar{u}, \bar{v}_1 \rangle \quad \langle \bar{u}, \bar{v}_2 \rangle$$

$$\langle \bar{u}, \bar{v}_n \rangle$$

$k_1, k_2, \dots, k_n$

bisa dicari

spt ini,  $k_n$

$\bar{v}_1, \bar{v}_2, \dots, \bar{v}_n$  saling  $\perp$

$\|\bar{v}_1, \bar{v}_2, \dots, \bar{v}_n\| = 1$

contoh 6.2:

$$\bar{v}_1 = (0, 1, 0) \quad \bar{v}_2 = (-\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}) \quad \bar{v}_3 = (\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}})$$

$S = \{\bar{v}_1, \bar{v}_2, \bar{v}_3\}$  ~ basis ortonormal  $\rightarrow$  orthogonal

$\rightarrow$  norma = 1

nyatakan  $\bar{u} = (1, 1, 1)$  sbg kombinasi linier dr himp. S

$$\bar{v}_1 = (0, 1, 0) \quad \bar{v}_2 = (-\frac{1}{\sqrt{5}}, 0, \frac{2}{\sqrt{5}}) \quad \bar{v}_3 = (\frac{2}{\sqrt{5}}, 0, \frac{1}{\sqrt{5}})$$

$S = \{\bar{v}_1, \bar{v}_2, \bar{v}_3\}$  y ~ basis orthonormal  $\rightarrow$  orthogonal  
 $\rightarrow$  normal = 1

nyatalkon  $\bar{u} = (1, 1, 1)$  sbg kombinasi linier dr himp. S

$$\bar{u} = k_1 \bar{v}_1 + k_2 \bar{v}_2 + k_3 \bar{v}_3$$

$$k_1 = \langle \bar{u}, \bar{v}_1 \rangle = 1 \quad ; \quad k_2 = \langle \bar{u}, \bar{v}_2 \rangle = -\frac{1}{\sqrt{5}} ; \quad k_3 = \langle \bar{u}, \bar{v}_3 \rangle = \frac{2}{\sqrt{5}}$$

maka:  $\bar{u} = \bar{v}_1 - \frac{1}{\sqrt{5}} \bar{v}_2 + \frac{2}{\sqrt{5}} \bar{v}_3$

4.26

e) basis ortonormal

contoh 63 :

$$\bar{v}_1 = (0, 1, 0)$$

o merentang

o. bebas linier

o saling  $\perp$   
norma = 1

$$\bar{v}_2 = (\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}) \quad \bar{v}_3 = (\frac{1}{\sqrt{2}}, 0, -\frac{1}{\sqrt{2}})$$

o merentang  $\rightarrow \bar{u} = k_1 \bar{v}_1 + k_2 \bar{v}_2 + k_3 \bar{v}_3$

o bebas linier  $\rightarrow 0 = k_1 \bar{v}_1 + k_2 \bar{v}_2 + k_3 \bar{v}_3$

jawab:

o merentang

$\rightarrow$  mis:  $\bar{u} = (1, 2, 3)$ , mt

$$k_1 = \langle \bar{u}, \bar{v}_1 \rangle = 2$$

$$k_2 = \langle \bar{u}, \bar{v}_2 \rangle = \frac{4}{\sqrt{2}}$$

$$k_3 = \langle \bar{u}, \bar{v}_3 \rangle = -\frac{2}{\sqrt{2}}$$

$$mt \Rightarrow (1, 2, 3) = 2 \bar{v}_1 + \frac{4}{\sqrt{2}} \bar{v}_2 - \frac{2}{\sqrt{2}} \bar{v}_3$$

mis:  $\bar{u} = (2, 2, 2)$ , mt

$$k_1 = 2$$

$$k_2 = \frac{4}{\sqrt{2}}$$

$$k_3 = 0$$

$$mt \Rightarrow (2, 2, 2) = 2 \bar{v}_1 + \frac{4}{\sqrt{2}} \bar{v}_2$$

bebas linier

$\rightarrow 0 = (0, 0, 0)$ , mt

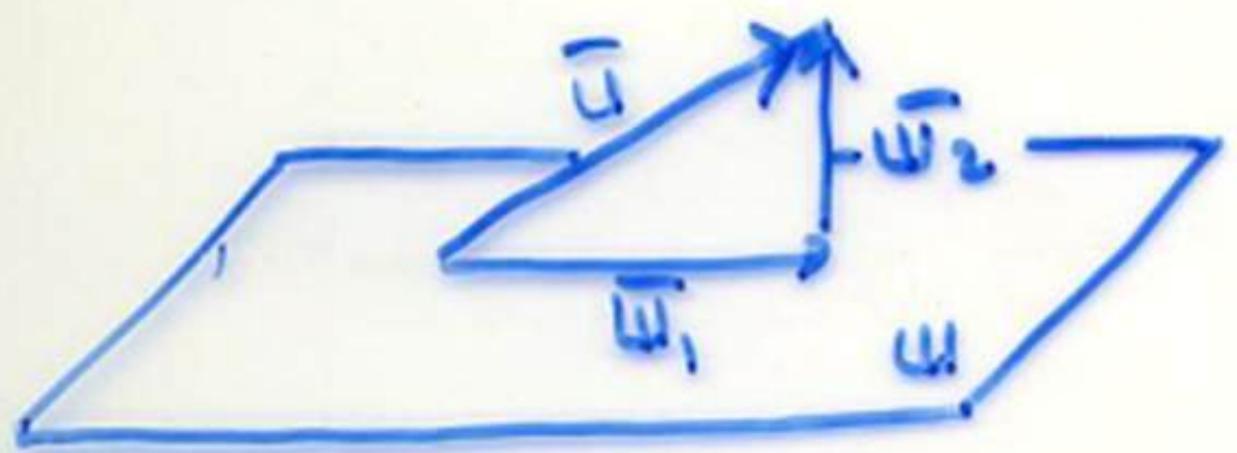
$$k_1 = 0$$

$$k_2 = 0$$

$$k_3 = 0$$

$$mt \Rightarrow (0, 0, 0) = 0 \bar{v}_1 + 0 \bar{v}_2 + 0 \bar{v}_3$$

•) proyección



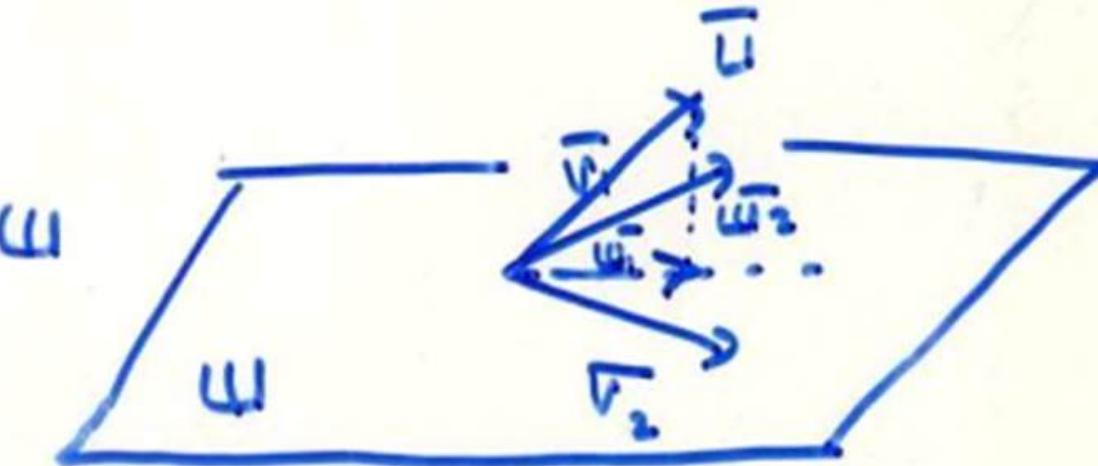
$$u = \bar{w}_1 + \bar{w}_2$$

$\bar{w}_1$   $\square_{10}$  proyección ortogonal de  $u$  pd  $\mathbb{W}$   
 $\square_0 \text{ Proy}_{\mathbb{W}} u = \langle u, v_1 \rangle v_1 + \langle u, v_2 \rangle v_2 + \dots + \langle u, v_n \rangle v_n$

$\bar{w}_2$   $\square_{10}$  comp.  $u$  yg ortogonal thp  $\mathbb{W}$   
 $\bar{u} - \text{Proy}_{\mathbb{W}} u = \bar{u} - \langle \bar{u}, v_1 \rangle v_1 - \langle \bar{u}, v_2 \rangle v_2 - \dots - \langle \bar{u}, v_n \rangle v_n$

contoh 69 :

$$\begin{aligned}\bar{v}_1 &= \langle 0, 1, 0 \rangle \\ \bar{v}_2 &= \left\langle -\frac{4}{5}, 0, \frac{3}{5} \right\rangle\end{aligned}$$



① Proyeksi ortogonal  $\bar{u} = \langle 1, 1, 1 \rangle$  pd  $W$  adalah :

$$\begin{aligned}\text{proj}_W \bar{u} &= \text{Proj}_W \bar{u} = \langle \bar{u}, \bar{v}_1 \rangle \bar{v}_1 + \langle \bar{u}, \bar{v}_2 \rangle \bar{v}_2 \\ &= \bar{v}_1 + -\frac{1}{5} \bar{v}_2 \\ &= \langle 0, 1, 0 \rangle + \left\langle \frac{4}{25}, 0, -\frac{3}{25} \right\rangle \\ &= \left\langle \frac{4}{25}, 1, -\frac{3}{25} \right\rangle\end{aligned}$$

?

komp  $\bar{U}$  yg ortogonal thp  $W$  adalah :

$$\begin{aligned}\bar{U}_2 &= \bar{U} - \text{proy}_W \bar{U} = (1, 1, 1) - \left(\frac{4}{25}, 1, -\frac{3}{25}\right) \\ &= \left(\frac{21}{25}, 0, \frac{28}{25}\right)\end{aligned}$$

$\bar{U}_2 \rightarrow$  orthogonal thp  $\bar{V}_1$  &  $\bar{V}_2$

$\bar{U}_2 \perp$  thp setiap vektor pd  $W$  yg di rentang  $\bar{V}_1$  &  $\bar{V}_2$

4.27

Teorema 2.6:

- ~ setiap ruang hasil kali dalam berdimensi berhingga tak nol mempunyai sebuah basis ortonormal.
- ~  $S = \{\bar{U}_1, \bar{U}_2, \bar{U}_3, \dots, \bar{U}_n\}$  ~ basis biana  $\Rightarrow$  di ket
- ~  $P = \{\bar{V}_1, \bar{V}_2, \bar{V}_3, \dots, \bar{V}_n\}$  ~ basis ortonormal  
~ yg dicari:

# GRAM SCHMIT



# GRAM-SCHMIT

contoh 65:

terapkan proses Gram Schmit u mentransfor -  
masukan basis

$$U_1 = (1, 1, 1)$$

$$U_2 = (0, 1, 1)$$

$$U_3 = (0, 0, 1)$$

} ke dlm basis orthonormal  
 $\begin{matrix} \uparrow \sqrt{3} \\ U_1, U_2, U_3 \end{matrix}$

Metode ini  
digunakan  
untuk :  
Mencari basis  
orthonormal





contoh 65:

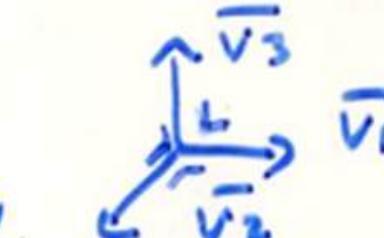
terapkan proses Gram Schmit u mentransfor -  
masikan basis

$$\bar{U}_1 = (1, 1, 1)$$

$$\bar{U}_2 = (0, 1, 1)$$

$$\bar{U}_3 = (0, 0, 1)$$

} ke dlm basis ortonormal



sol:

$$S = \{\bar{U}_1, \bar{U}_2, \bar{U}_3\} \rightarrow \text{basis biasa}$$

$$B = \{\bar{v}_1, \bar{v}_2, \bar{v}_3\} \rightarrow \text{basis ortonormal yg akan dicari}$$

langkah 1  $\rightarrow \bar{v}_1 = \frac{\bar{U}_1}{\|\bar{U}_1\|} = \frac{(1, 1, 1)}{\sqrt{3}} = \left(\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}\right)$

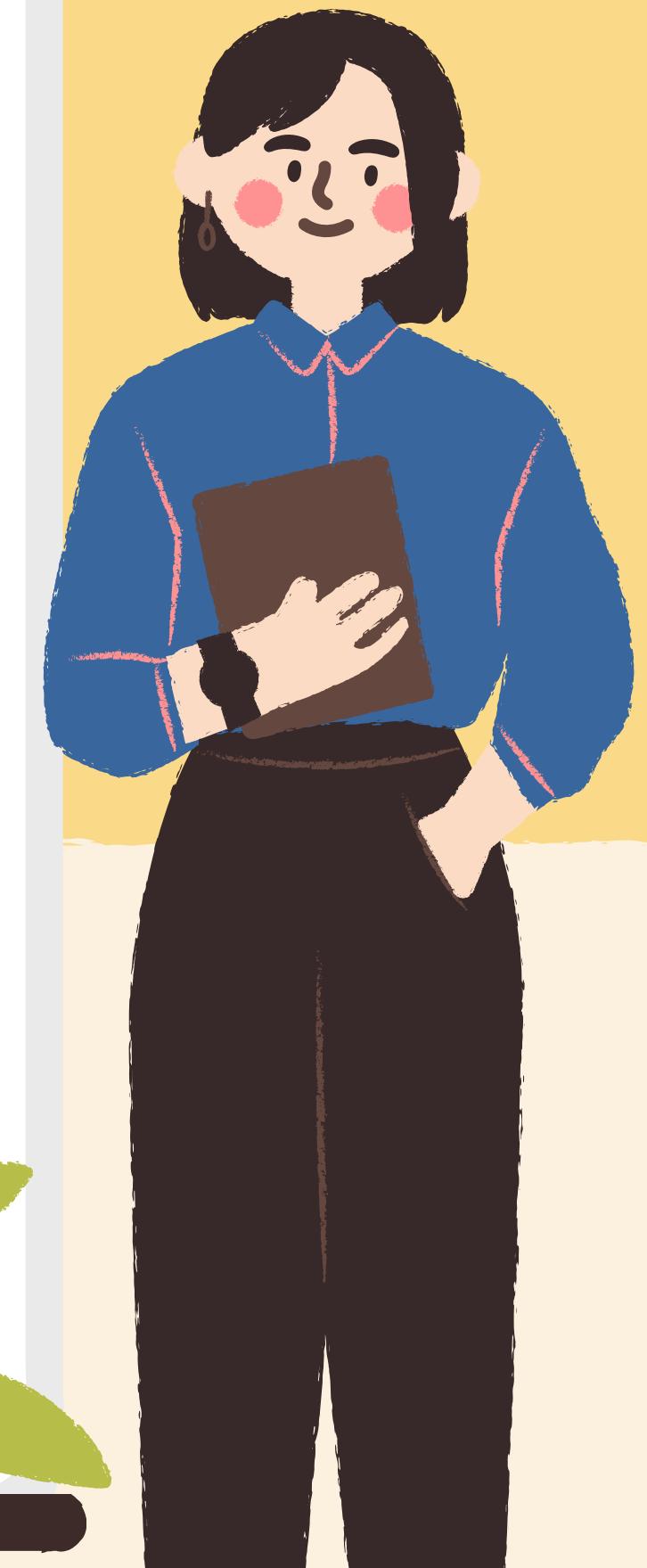
langkah 2  $\rightarrow \bar{U}_2 - \text{Proy}_{\bar{v}_1} \bar{U}_2 = \bar{U}_2 - \langle \bar{U}_2, \bar{v}_1 \rangle \bar{v}_1$   
 $= (0, 1, 1) - \frac{3}{\sqrt{3}} \left(\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}\right)$   
 $= \left(-\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}\right)$   
mt  $\rightarrow \bar{v}_2 = \frac{\bar{U}_2 - \text{Proy}_{\bar{v}_1} \bar{U}_2}{\|\bar{U}_2 - \text{Proy}_{\bar{v}_1} \bar{U}_2\|}$   
 $= \frac{3}{\sqrt{6}} \left(-\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}\right)$   
 $= \left(-\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right)$

langkah 3  $\rightarrow \bar{U}_3 - \text{Proy}_{\bar{V}_2} \bar{U}_3 = \bar{U}_3 - \langle \bar{U}_3, \bar{V}_1 \rangle \bar{V}_1 - \langle \bar{U}_3, \bar{V}_2 \rangle \bar{V}_2$   
 $= (0, 0, 1) - \frac{1}{\sqrt{3}} (1, 1, 1) - \frac{1}{\sqrt{2}} (-1, 1, 1)$   
 $= (0, -1, 1)$

Rk:  
 $\bar{V}_3 = \frac{\bar{U}_3 - \text{Proy}_{\bar{V}_2} \bar{U}_3}{\|\bar{U}_3 - \text{Proy}_{\bar{V}_2} \bar{U}_3\|} = \frac{1}{\sqrt{2}} (0, -1, 1) = (0, -\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$

$\therefore \bar{V}_1, \bar{V}_2, \bar{V}_3$  membentuk basis orthonormal  $\mathbb{R}^3$

$$V_1 = \frac{U_1}{\|U_1\|} = \frac{(1, 1, 1)}{\sqrt{3}} = \left( \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}} \right)$$





$$V_2 = \frac{U_2 - \langle U_2, V_1 \rangle V_1}{|U_2 - \langle U_2, V_1 \rangle V_1|}$$

$$U_2 - \langle U_2, V_1 \rangle \cdot V_1 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} - \frac{2}{\sqrt{3}} \begin{pmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{pmatrix}$$
$$= \begin{pmatrix} -\frac{2}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{pmatrix}$$

$$V_2 = \frac{(-\frac{2}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}})}{\frac{\sqrt{6}}{3}} = \frac{3}{\sqrt{6}} (-\frac{2}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}})$$
$$= (-\frac{2}{\sqrt{6}}, \frac{1}{\sqrt{6}}, \frac{1}{\sqrt{6}})$$

$$V_3 = \frac{U_3 - \langle U_3, V_1 \rangle V_1 - \langle U_3, V_2 \rangle V_2}{\| \dots \dots \dots \dots \|}$$

$$V_3 = (0, 0, 1) - \frac{1}{\sqrt{3}} \left( \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}} \right) - \frac{1}{\sqrt{6}} \left( -\frac{2}{\sqrt{6}}, \frac{1}{\sqrt{6}}, \frac{-1}{\sqrt{6}} \right)$$

$$V_3 = \frac{(0, -\frac{1}{2}, \frac{1}{2})}{\| \dots \dots \|}$$

$$V_3 = \sqrt{2} (0, -\frac{1}{2}, \frac{1}{2})$$

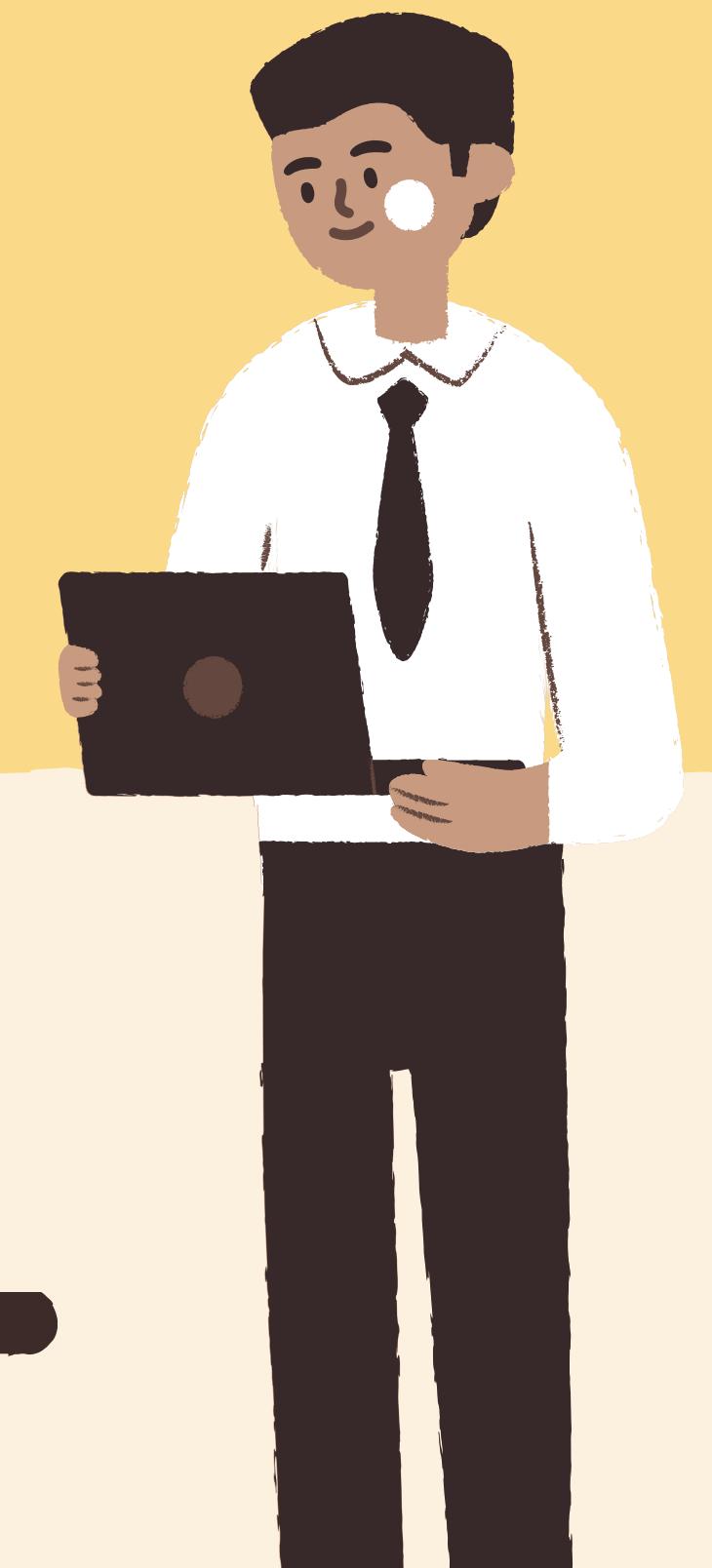
$$V_3 = (0, -\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$$



Terapkan proses Gram Schimt untuk mentransformasikan basis  $u_1, u_2, u_3$  ke dalam basis ortonormal.

$u_1$	=	-4	8	2
$u_2$	=	7	-3	6
$u_3$	=	6	-3	7

## CONTOH SOAL



Terapkan proses Gram Schimt untuk mentransformasikan basis  $u_1, u_2, u_3$  ke dalam basis ortonormal.

$u_1$	=	-4	8	2
$u_2$	=	7	-3	6
$u_3$	=	6	-3	7

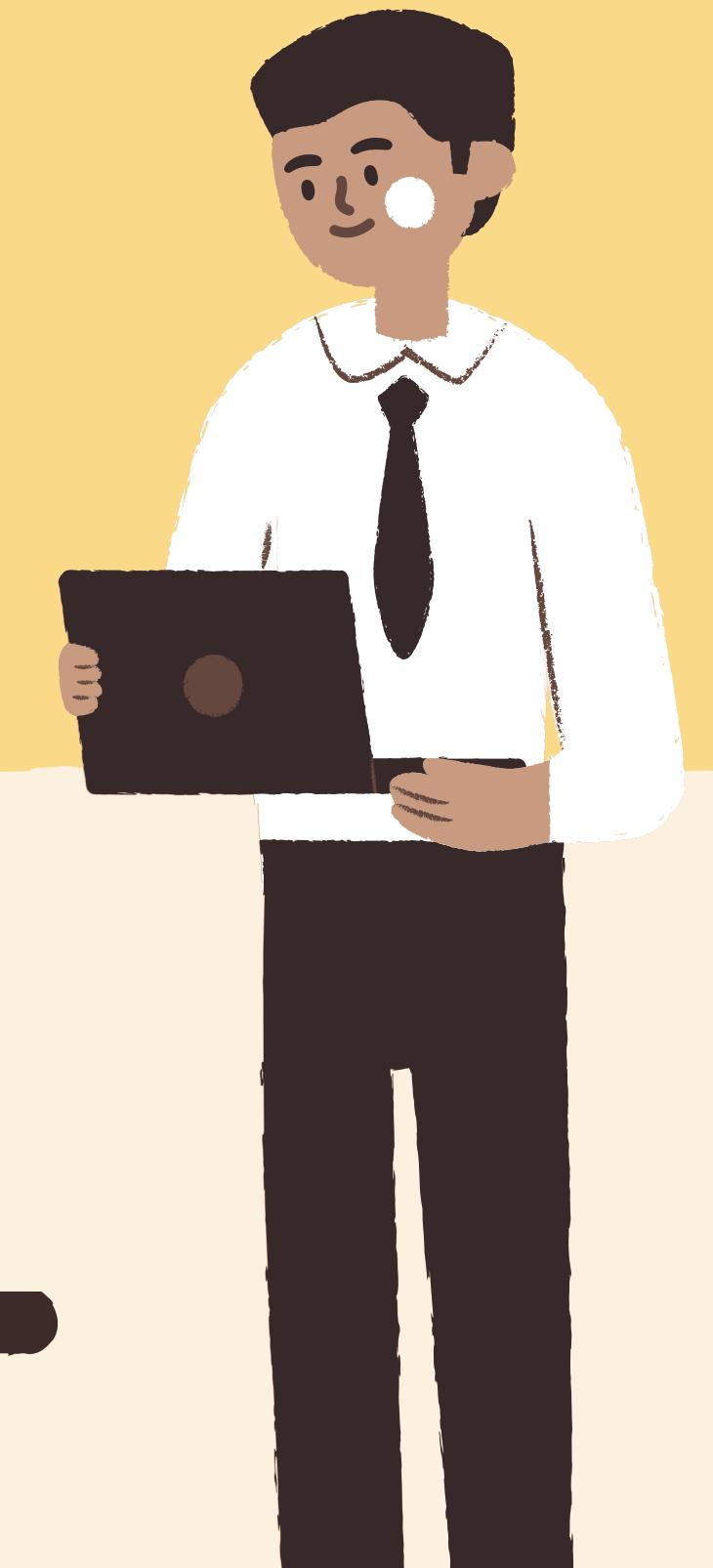
$$v_1 = \frac{u_1}{|u_1|}$$
$$|u_1| = 9.17$$
$$v_1 = \boxed{-0.44 \quad 0.87 \quad 0.22}$$

## CONTOH SOAL



# CONTOH SOAL

$$v_2 = \frac{u_2 - \langle u_2, v_1 \rangle \cdot v_1}{|u_2 - \langle u_2, v_1 \rangle \cdot v_1|}$$
$$\langle u_2, v_1 \rangle = -4.37$$
$$\begin{array}{l} u_2 - \langle u_2, v_1 \rangle \cdot v_1 \\ \hline \end{array} = \begin{array}{ccc} 5.08 & 0.80 & 6.96 \end{array}$$
$$|u_2 - \langle u_2, v_1 \rangle \cdot v_1| = 8.65$$
$$V_2 = \begin{array}{ccc} 0.59 & 0.09 & 0.80 \end{array} \quad |v_2| = 0.998098$$



# CONTOH SOAL



$v_3 =$	$\frac{u_3 - \langle u_3, v_2 \rangle v_2 - \langle u_3, v_1 \rangle v_1}{ u_3 - \langle u_3, v_2 \rangle v_2 - \langle u_3, v_1 \rangle v_1 }$
$\langle u_3, v_2 \rangle =$	8.87
$\langle u_3, v_2 \rangle V_2 =$	<b>5.23      0.80      7.10</b>
$\langle u_3, v_1 \rangle =$	-3.71
$\langle u_3, v_1 \rangle V_1 =$	<b>1.63      -3.23      -0.82</b>
$u_3 - \langle u_3, v_2 \rangle v_2 - \langle u_3, v_1 \rangle v_1 =$	<b>-0.86      -0.57      0.72</b>
$ u_3 - \langle u_3, v_2 \rangle v_2 - \langle u_3, v_1 \rangle v_1 $	<b>1.26</b>
$v_3$	<b>-0.68      -0.45      0.57</b>
	$ v_3  = 0.994887$



## 6.5 Orthogonal matrix ; change of Basis

Orthogonal matrix :

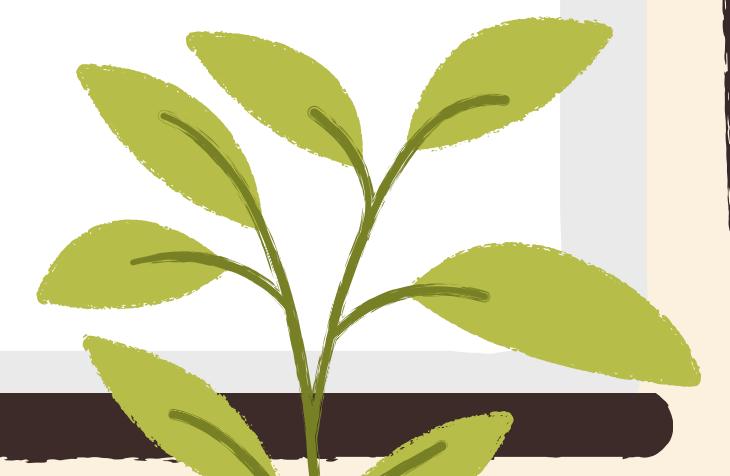
$$\begin{cases} A \cdot A^T = A^T \cdot A = I \\ A^{-1} = A^T \end{cases}$$

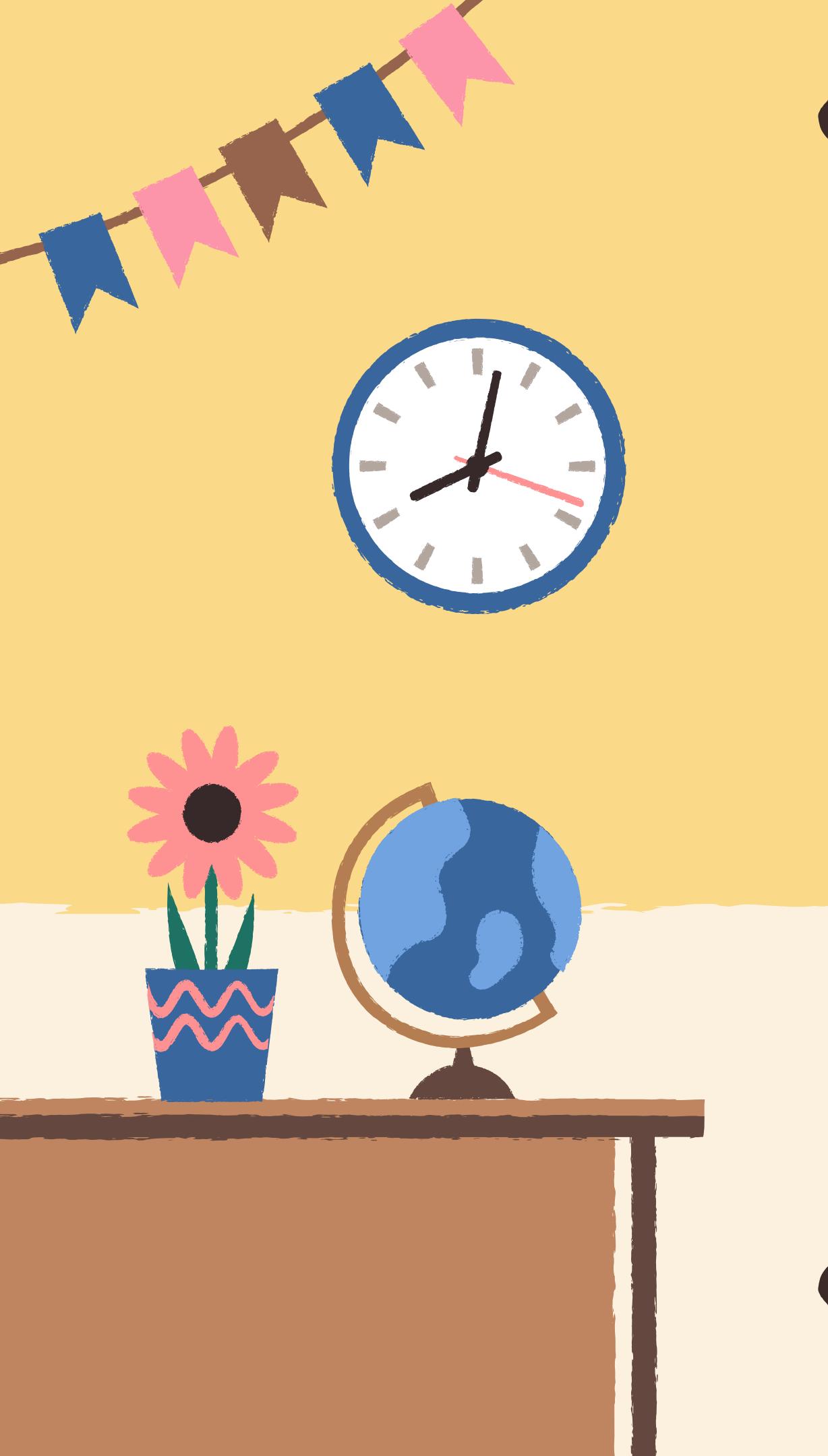
**Example 1** The matrix

$$A = \begin{bmatrix} \frac{3}{7} & \frac{2}{7} & \frac{6}{7} \\ -\frac{6}{7} & \frac{3}{7} & \frac{2}{7} \\ \frac{2}{7} & \frac{6}{7} & -\frac{3}{7} \end{bmatrix}$$

is orthogonal, since

$$A^T A = \begin{bmatrix} \frac{3}{7} & -\frac{6}{7} & \frac{2}{7} \\ \frac{2}{7} & \frac{3}{7} & \frac{6}{7} \\ \frac{6}{7} & \frac{2}{7} & -\frac{3}{7} \end{bmatrix} \begin{bmatrix} \frac{3}{7} & \frac{2}{7} & \frac{6}{7} \\ -\frac{6}{7} & \frac{3}{7} & \frac{2}{7} \\ \frac{2}{7} & \frac{6}{7} & -\frac{3}{7} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$





# TEOREMA

**Theorem 6.5.1.** *The following are equivalent for an  $n \times n$  matrix  $A$ .*

- (a)  *$A$  is orthogonal.*
- (b) *The row vectors of  $A$  form an orthonormal set in  $R^n$  with the Euclidean inner product.*
- (c) *The column vectors of  $A$  form an orthonormal set in  $R^n$  with the Euclidean inner product.*

Contoh :

Show that

$$A = \begin{bmatrix} \frac{4}{5} & 0 & -\frac{3}{5} \\ -\frac{9}{25} & \frac{4}{5} & -\frac{12}{25} \\ \frac{12}{25} & \frac{3}{5} & \frac{16}{25} \end{bmatrix}$$

is an orthogonal matrix by

- (a) calculating  $A^T A$
- (b) using part (b) of theorem 6.5.1
- (c) using part (c) of theorem 6.5.1



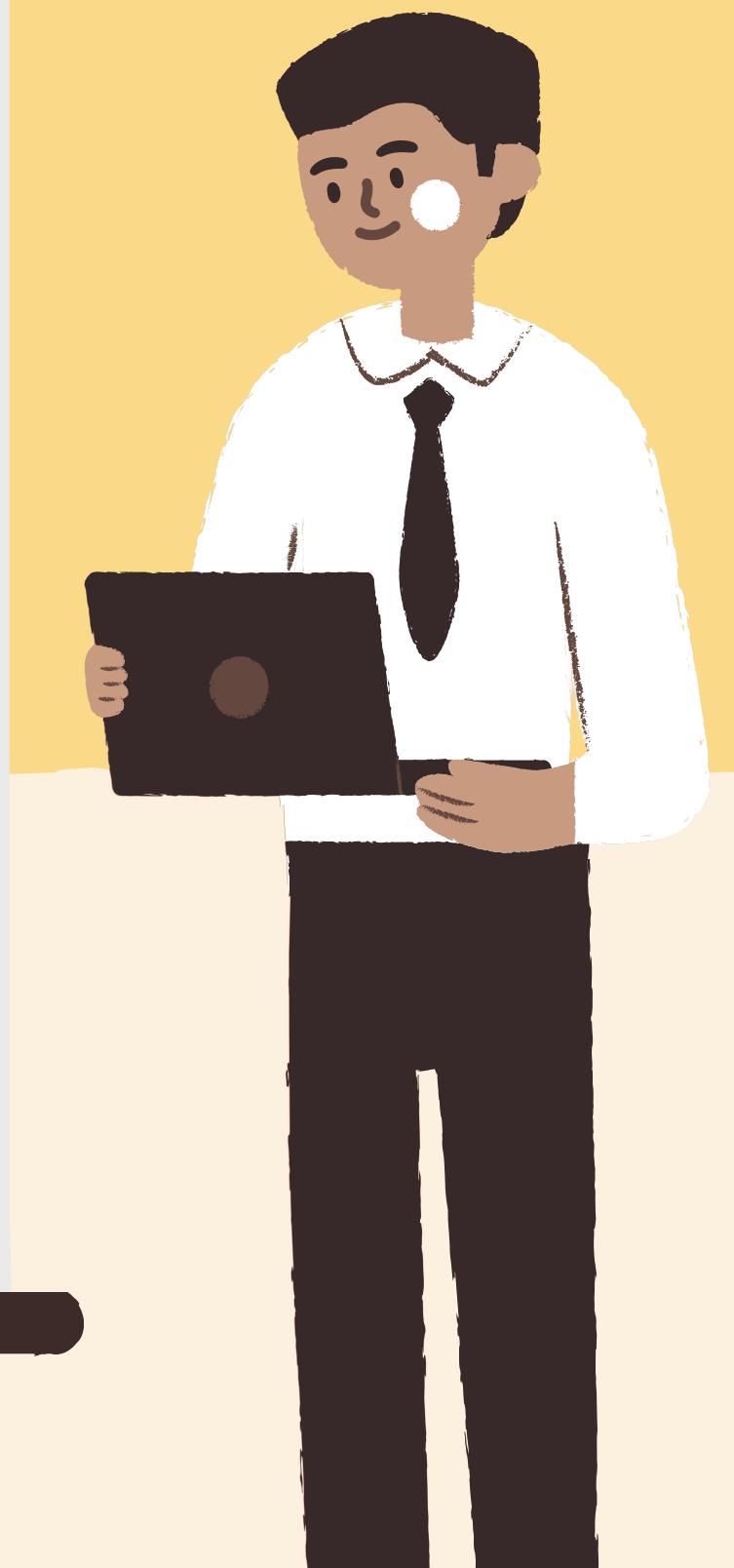
Jawab :

(a)  $A^T \cdot A$

$$= \begin{bmatrix} \frac{4}{5} & -\frac{9}{25} & \frac{12}{25} \\ 0 & \frac{9}{5} & \frac{3}{5} \\ -\frac{3}{5} & -\frac{12}{25} & \frac{16}{25} \end{bmatrix} \cdot \begin{bmatrix} \frac{4}{5} & 0 & -\frac{3}{5} \\ -\frac{9}{25} & \frac{3}{5} & -\frac{12}{25} \\ \frac{12}{25} & \frac{3}{5} & \frac{16}{25} \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

## CONTOH SOAL





(b) row vektor membentuk orthonormal

$$r_1 = \left\{ \frac{4}{5}, 0, -\frac{3}{5} \right\}$$

$$r_2 = \left( -\frac{9}{5}, \frac{4}{5}, -\frac{12}{25} \right)$$

$$r_3 = \left( \frac{12}{25}, \frac{3}{5}, \frac{16}{25} \right)$$

(c) column vektor membentuk orthonormal

$$C_1 = \begin{bmatrix} \frac{4}{5} \\ -\frac{9}{25} \\ \frac{12}{25} \end{bmatrix}$$

$$C_2 = \begin{bmatrix} 0 \\ \frac{4}{5} \\ \frac{3}{5} \end{bmatrix}$$

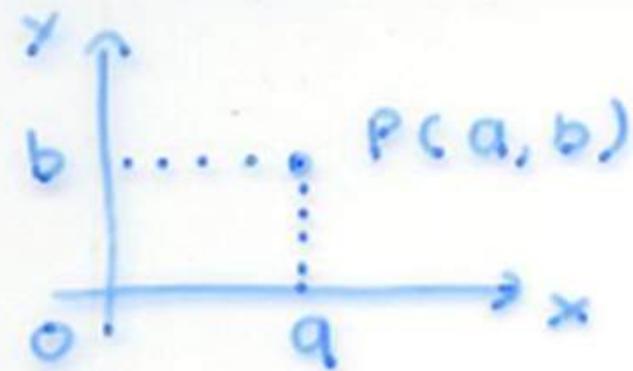
$$C_3 = \begin{bmatrix} -\frac{3}{5} \\ -\frac{12}{25} \\ \frac{16}{25} \end{bmatrix}$$

# KOORDINAT BASIS BARU

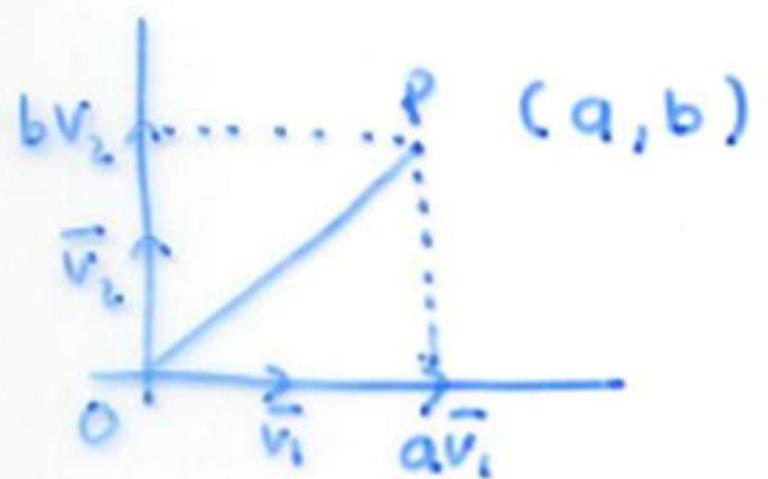


## 4.10 Koordinat, perubahan basis

- basis berhubungan erat dgn koordinat
- koordinat biasa  $\rightarrow P(a,b)$  dlm koordinat basis  $(x,y)$

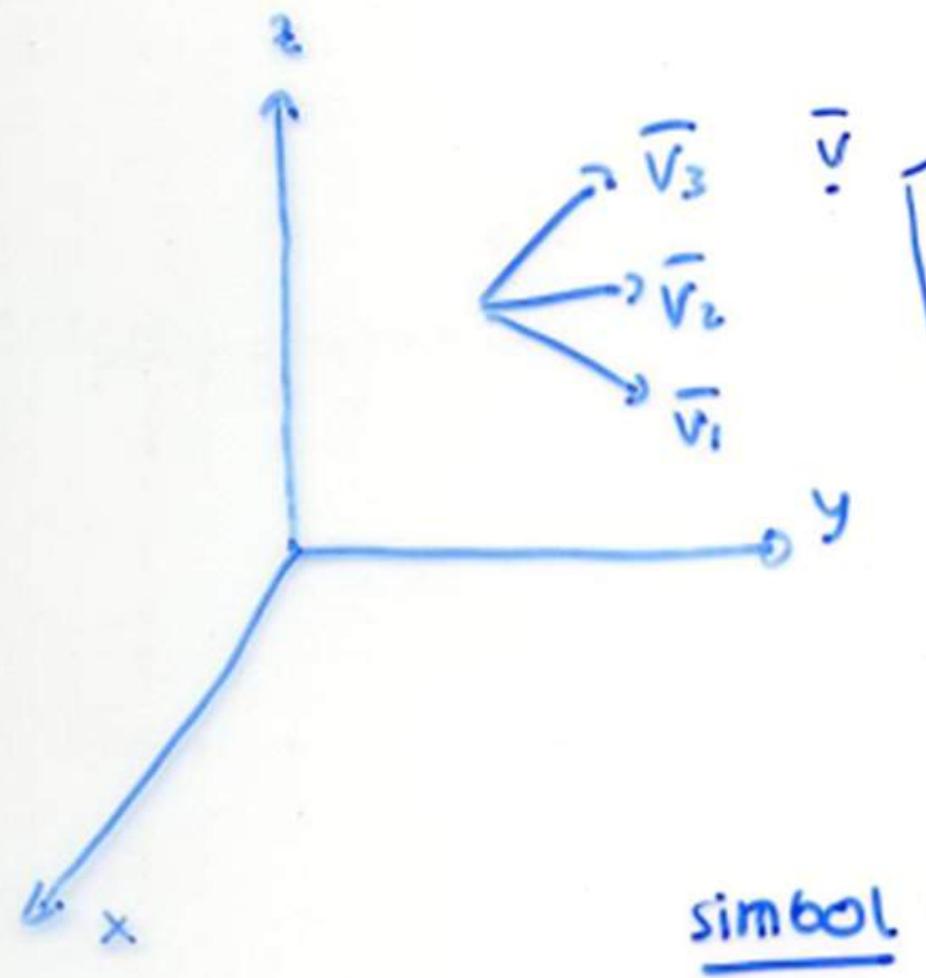


- koordinat vektor  $\rightarrow P(a,b)$  dlm koordinat vektor basis  $s = \{\vec{v}_1, \vec{v}_2\}$



$$\overline{OP} = a\vec{v}_1 + b\vec{v}_2$$

titik  $(a,b) \Rightarrow$  koordinat  $P$   
yg relatif thp basis  $s = \{\vec{v}_1, \vec{v}_2\}$



simbol ?

$[B]_s$  = matrix transisi dr  
basis baru ( $s$ ) ke  
basis lama ( $Q$ )  
=  $[\bar{v}_1 \bar{v}_2 \bar{v}_3]$

$[B]_Q$  = matrix transisi dr  
basis lama ( $Q$ ) ke  
basis baru ( $s$ )  
=  $([B]_s)^{-1}$

① koordinat  $\bar{v}$  thp basis  
baru  $s = [\bar{v}_1, \bar{v}_2, \bar{v}_3]$  jk  
koordinat  $\bar{v}$  thp  
basis lama  $Q = [x \ y \ z]$  diket

② koordinat  $\bar{v}$  thp basis  
lama  $Q = [x \ y \ z]$  jk  
koordinat  $\bar{v}$  thp basis  
baru  $s = [\bar{v}_1, \bar{v}_2, \bar{v}_3]$  diket

$[\bar{v}]_s$  = koordinat  $\bar{v}$  thp  
basis baru  $s = [\bar{v}_1, \bar{v}_2, \bar{v}_3]$

$[\bar{v}]_Q$  = koordinat  $\bar{v}$  thp  
basis lama  $Q = [x \ y \ z]$

Eximus:

$$[B]_s \cdot [\bar{V}]_s = [\bar{V}]_Q$$

$$[\bar{V}]_s = [B]_Q \cdot [\bar{V}]_Q$$

$$= ([B]_s)^{-1} \cdot [\bar{V}]_Q$$

contoh:

basis baru  $s = \{\bar{v}_1, \bar{v}_2, \bar{v}_3\}$

$$\bar{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \quad \bar{v}_2 = \begin{bmatrix} 2 \\ 9 \\ 0 \end{bmatrix} \quad \bar{v}_3 = \begin{bmatrix} 3 \\ 3 \\ 4 \end{bmatrix}$$

$$[B]_s = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 9 & 3 \\ 1 & 0 & 4 \end{bmatrix}$$

Pertanyaan:

a) Cari koordinat  $[\bar{v}]_s = \begin{bmatrix} 5 \\ -1 \\ 9 \end{bmatrix}$  thp basis  $s = \{\bar{v}_1, \bar{v}_2, \bar{v}_3\}$  baru

⇒ cari  $[\bar{v}]_s$

b) Cari koordinat  $[\bar{v}]_s = \begin{bmatrix} -1 \\ 3 \\ 2 \end{bmatrix}$  thp basis  $s = \{x, y, z\}$  lama

⇒ cari  $[\bar{v}]_s$



جواب:

a)

$$[B]_s [\bar{v}]_s = [\bar{v}]_Q$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 2 & 9 & 3 \\ 1 & 0 & 4 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}_s = \begin{bmatrix} 5 \\ -1 \\ 9 \end{bmatrix}$$

$$\begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}_s = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$$

$$\therefore [\bar{v}]_s = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$$



$$b) [\beta]_s [\bar{v}]_s = [\bar{v}]_Q$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 2 & 9 & 3 \\ 1 & 0 & 4 \end{bmatrix} \begin{bmatrix} -1 \\ 3 \\ 2 \end{bmatrix} = \begin{bmatrix} 11 \\ 31 \\ 2 \end{bmatrix}$$

$$\therefore [\bar{v}]_Q = \begin{bmatrix} 11 \\ 31 \\ 2 \end{bmatrix}$$

contoh:

$$\text{basis baru } S = \{\bar{v}_1, \bar{v}_2\}$$

$$\bar{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \bar{v}_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$[\beta]_s = \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix}$$

Pertanyaan :

a) Cari koordinat  $[\vec{v}]_Q = \begin{bmatrix} 7 \\ 2 \end{bmatrix}$  terhadap  
basis baru  $s = \{\vec{v}_1, \vec{v}_2\}$

$\Rightarrow$  cari  $[\vec{v}]_s$

Jwb:

$$[S]_s \quad [\vec{v}]_s = [\vec{v}]_Q$$

$$[\vec{v}]_s = ([S]_s)^{-1} \cdot [\vec{v}]_Q$$

$$= \begin{bmatrix} -1 & 2 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 7 \\ 2 \end{bmatrix}$$

$$\therefore [\vec{v}]_s = \begin{bmatrix} -3 \\ 5 \end{bmatrix}$$

Cari koordinat  $[\bar{v}]_s = \begin{bmatrix} -3 \\ 5 \end{bmatrix}$  thp basis lama

=> cari  $[\bar{v}]_Q$

Jwb:

$$[B]_s [\bar{v}]_s = [\bar{v}]_Q$$

$$\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} -3 \\ 5 \end{bmatrix} = \begin{bmatrix} ? \\ ? \end{bmatrix}$$

$$\therefore [\bar{v}]_Q = \begin{bmatrix} ? \\ ? \end{bmatrix}$$

PR 4.10

2.b

8

10

# TUGAS!!!!

- Tugas Kelompok →
  - cari 2 soal dan jawaban di internet yang berhubungan dengan materi ppt ini
  - Tulis alamat internetnya
  - Di kirim ke elearning, terakhir →
    - Minggu depan
- Format → subject →
  - Alin-B-melati
  - Bentuk → ppt → informasi nama kelompok + anggota



TERIMA KASIH!!!!