



深度学习基础





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深度学习简史



前馈神经网络



神经网络的训练



卷积神经网络



循环神经网络

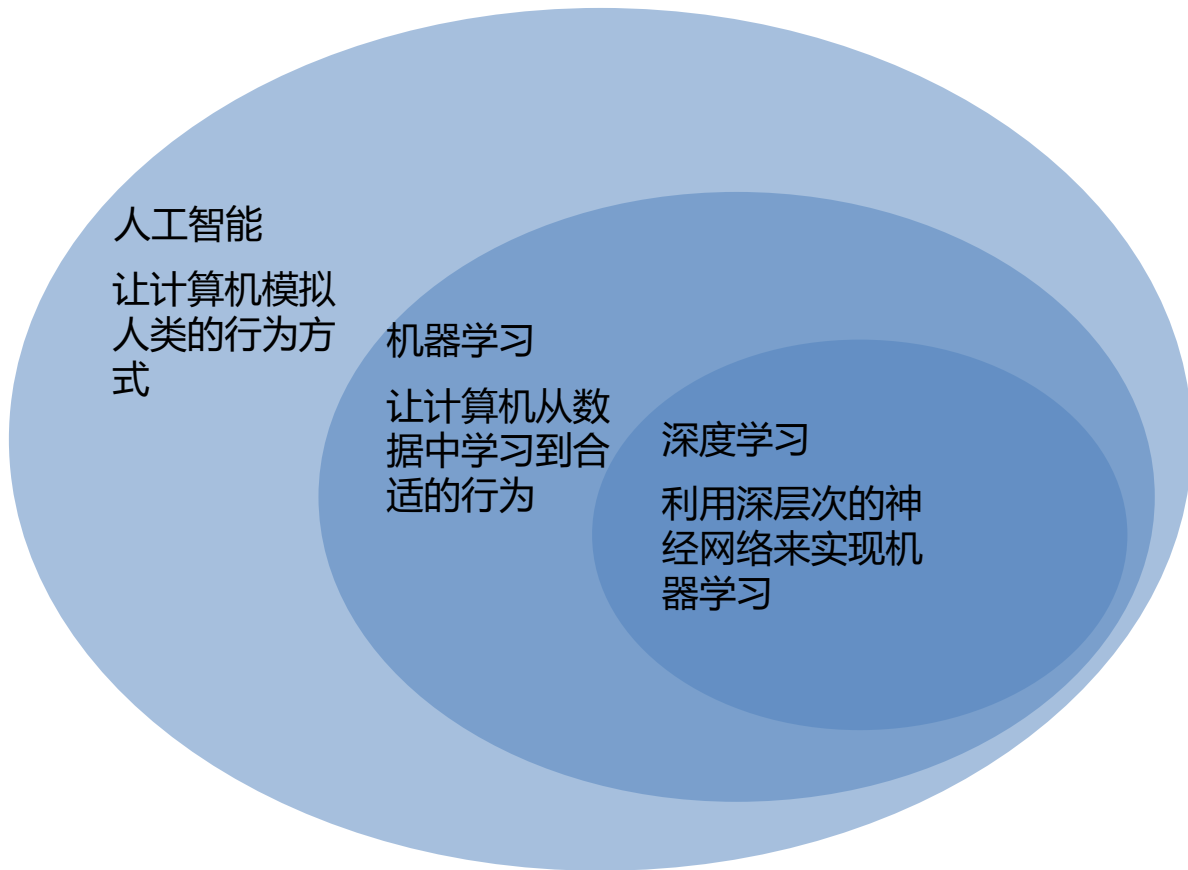


自编码器





什么是深度学习





深度学习简史

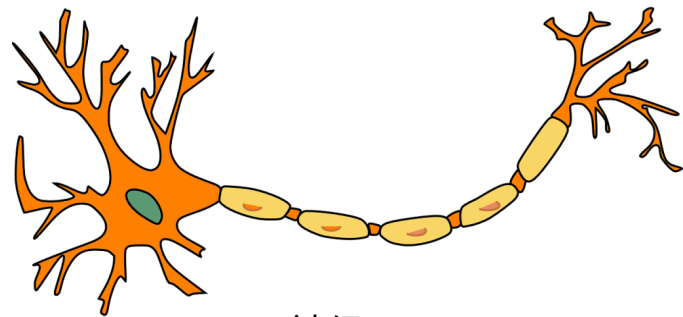
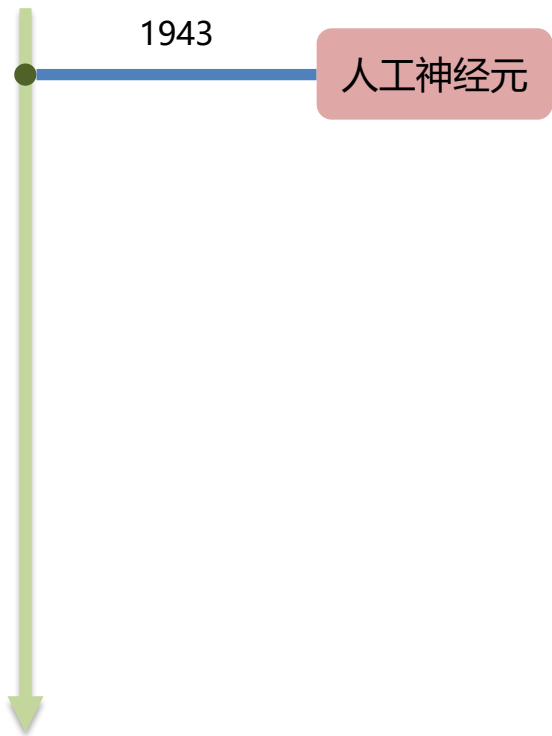
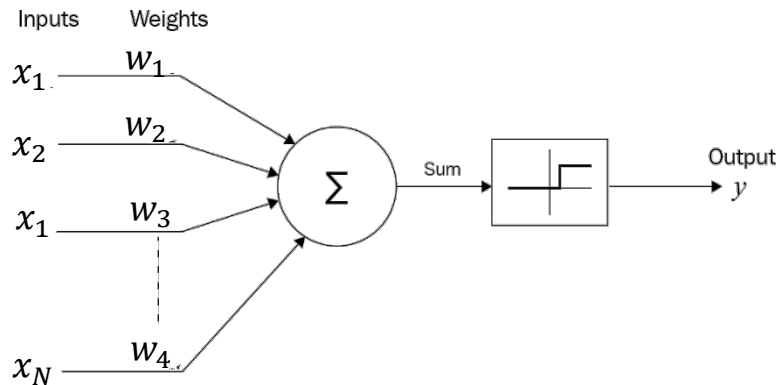


Image credit

神经元



McCulloch-Pitts 神经元





深度学习简史

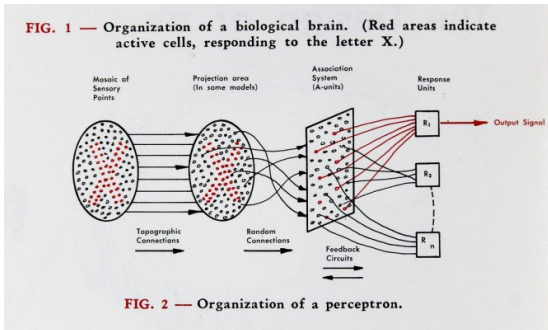
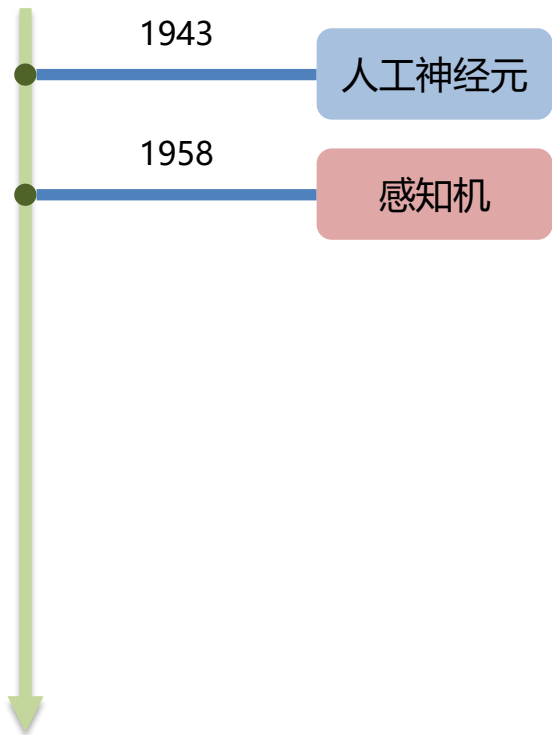


Image credit

感知机 (Perceptron)



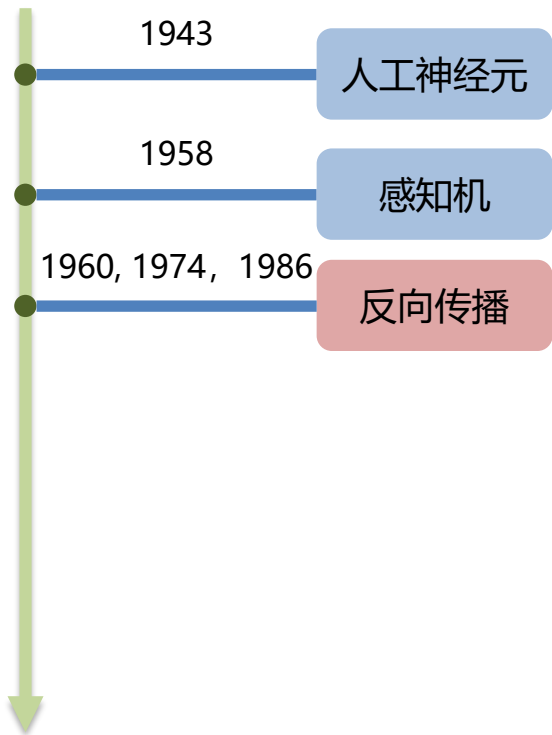
Image credit

Frank Rosenblatt





深度学习简史



Gradient Theory of Optimal Flight Paths

HENRY J. KELLEY[†]

Grumman Aircraft Engineering Corp.
Bethpage, N. Y.

An analytical development of flight performance optimization according to the method of gradients or "method of steepest descent" is presented. Construction of a minimizing sequence of flight paths by a stepwise process of descent along the local gradient direction is described as a computational scheme. Numerical application of the technique is illustrated in a simple example of orbital transfer via solar sail propulsion. Successive approximations to minimum time planar flight paths from Earth's orbit to the orbit of Mars are presented for cases corresponding to free and fixed boundary conditions on terminal velocity components.

Beyond regression : new tools for prediction and analysis in the behavioral sciences

Author: [Paul J. Werbos](#)

Dissertation: Ph. D. Harvard University 1975

Edition/Format: Thesis/dissertation : Thesis/dissertation : English [View all editions and formats](#)

Learning representations by back-propagating errors

David E. Rumelhart*, Geoffrey E. Hinton†
& Ronald J. Williams*

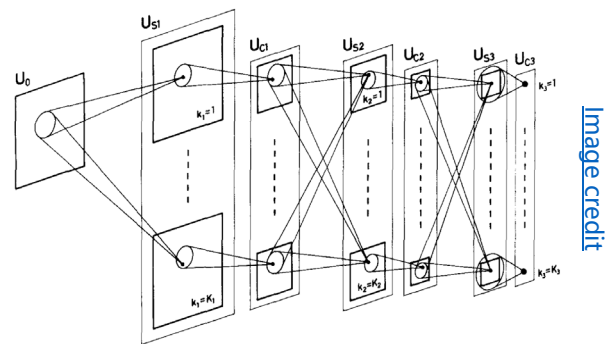
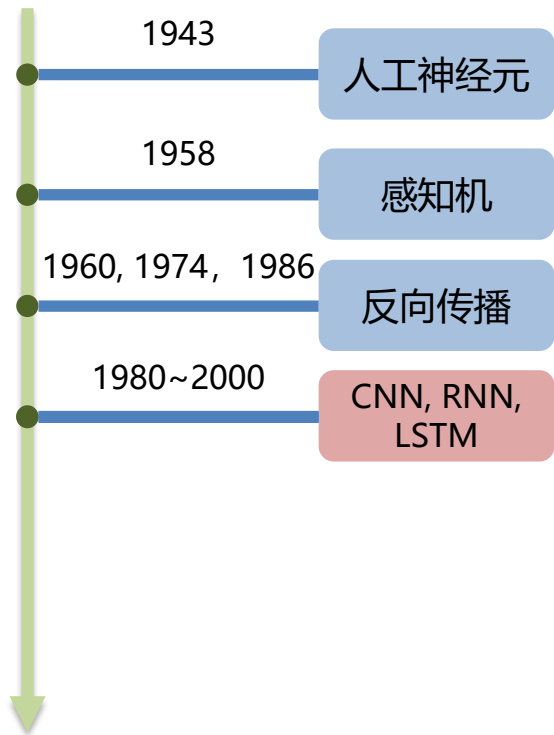
* Institute for Cognitive Science, C-015, University of California,
San Diego, La Jolla, California 92093, USA

† Department of Computer Science, Carnegie-Mellon University,
Pittsburgh, Philadelphia 15213, USA

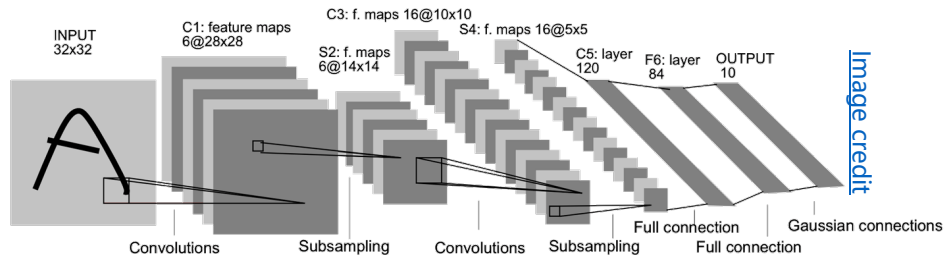




深度学习简史



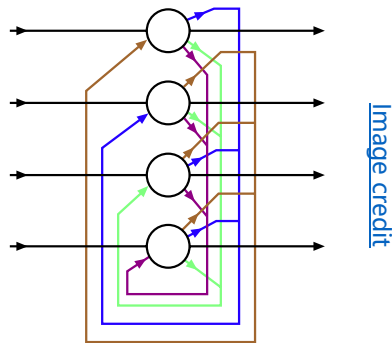
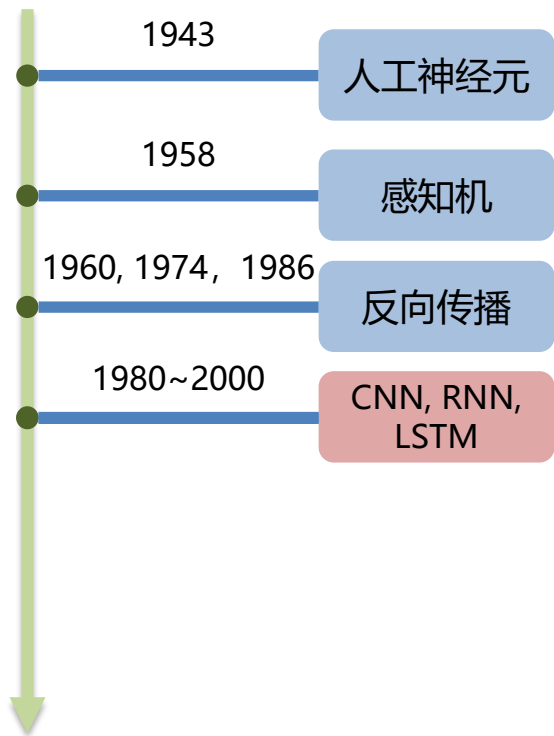
Neocognitron, 1980 (CNN的雏形)



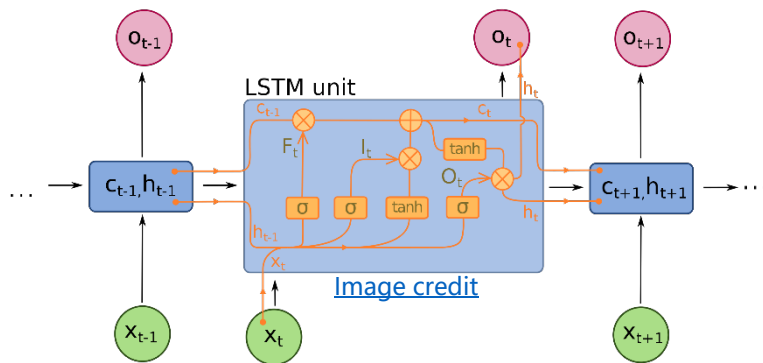
LeNet-5, 1989



深度学习简史



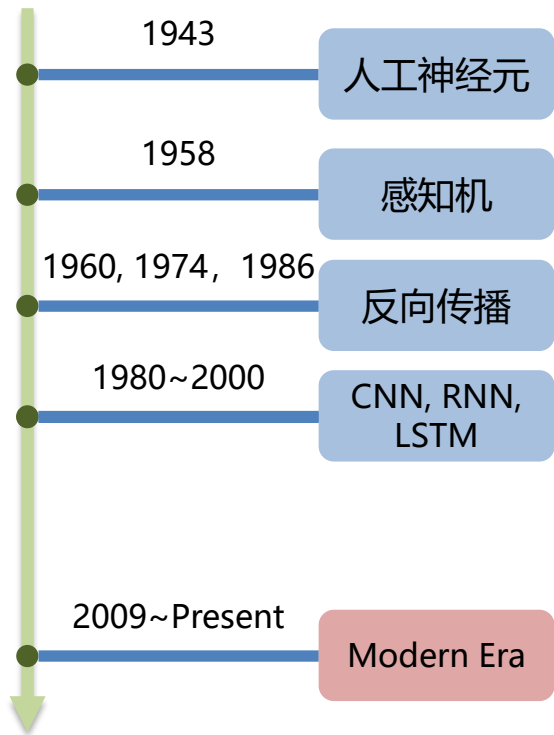
早期的RNN: Hopfield Network, 1982



LSTM, 1997



深度学习简史



这些技术已经存在数十年，
但是深度学习直到近些年
才真正受到大家的关注。





深度学习简史

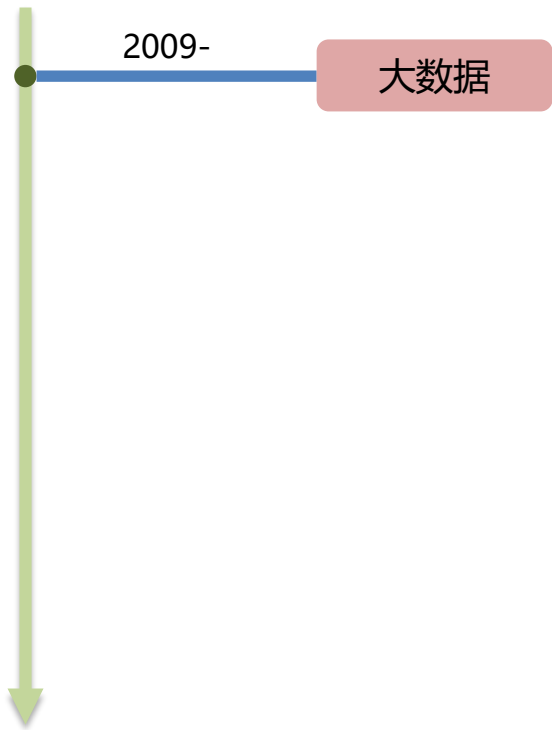


Image credit

ImageNet 数据集, 2009

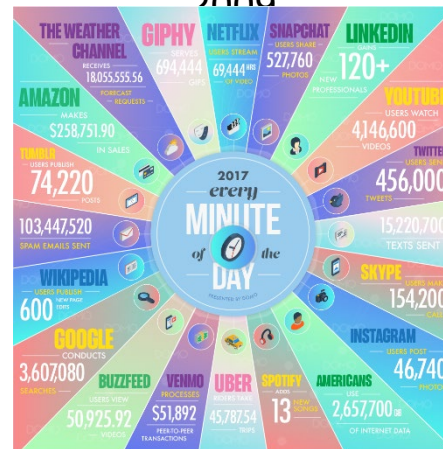


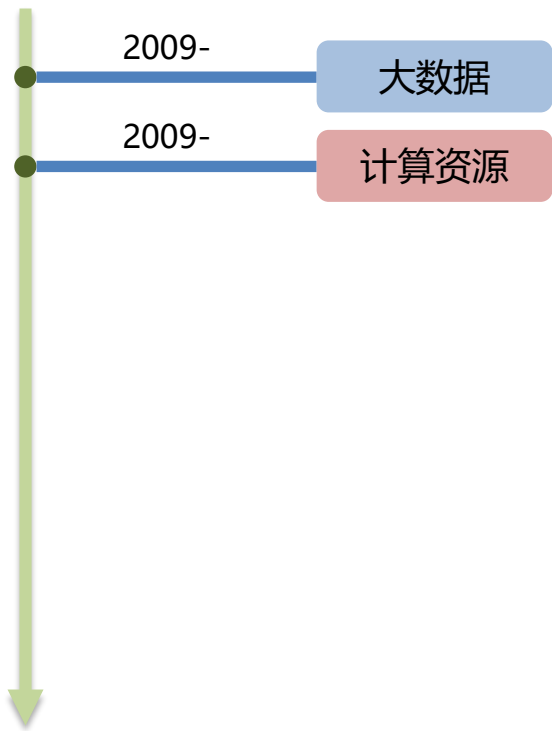
image credit

我们每分每秒都在产生大量的数据

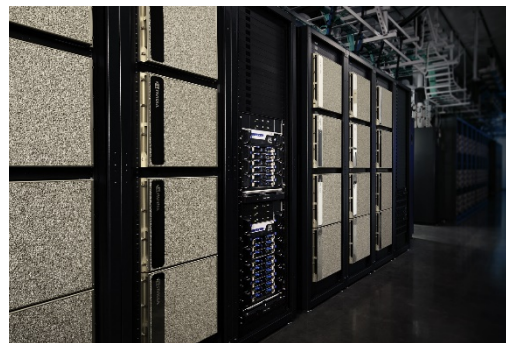




深度学习简史



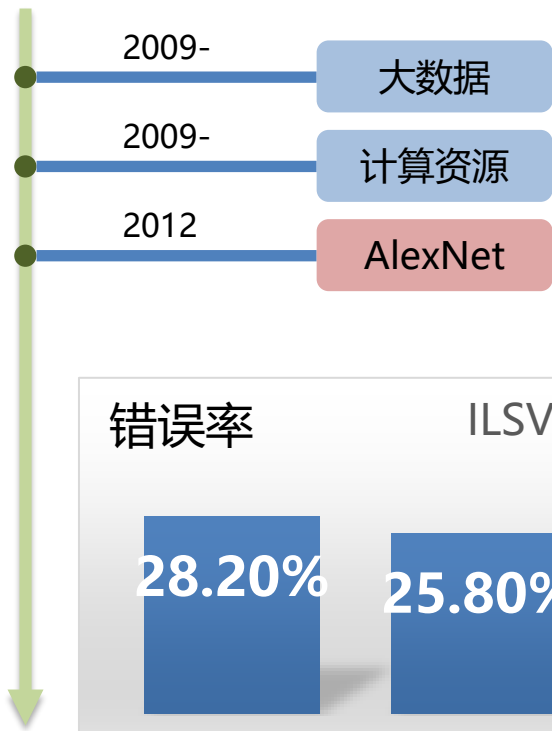
GPU开始被用来训练神经网络



GPU集群



深度学习简史

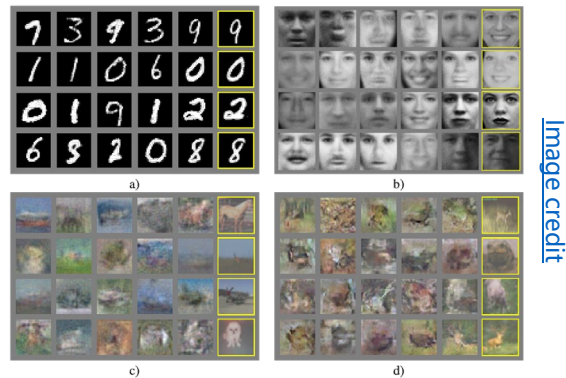
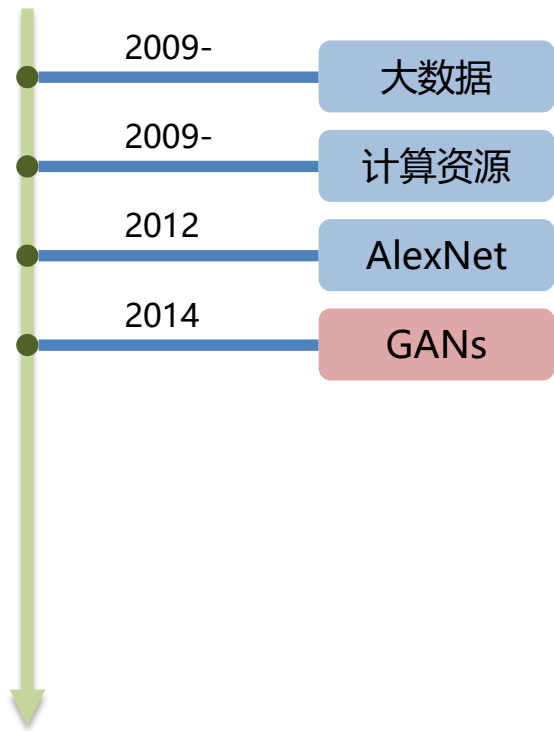


ImageNet Large Scale
Visual Recognition
Challenge





深度学习简史



由GANs生成的图片

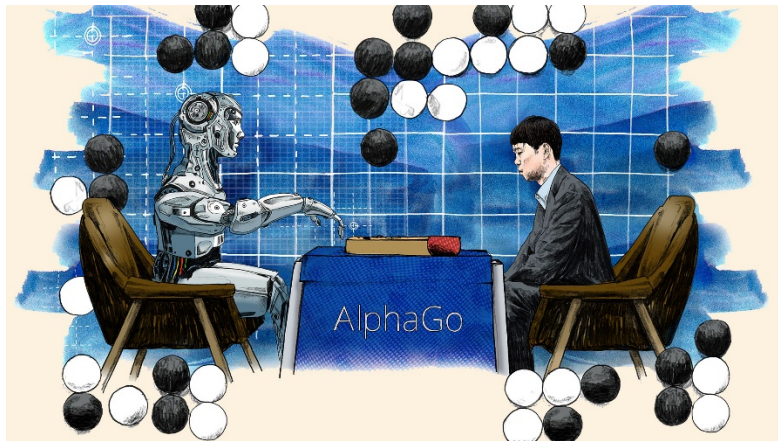
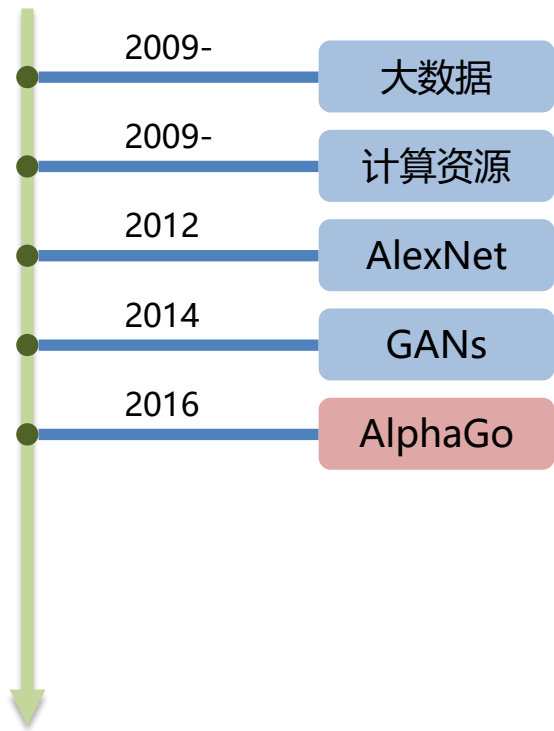


基于GANs的风格转换





深度学习简史



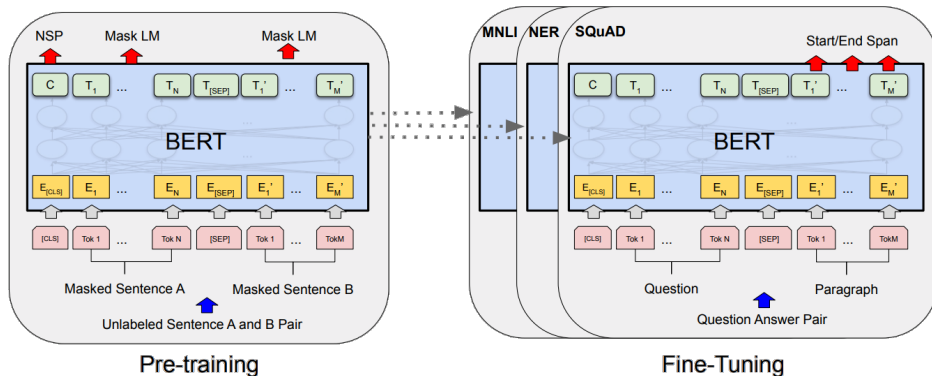
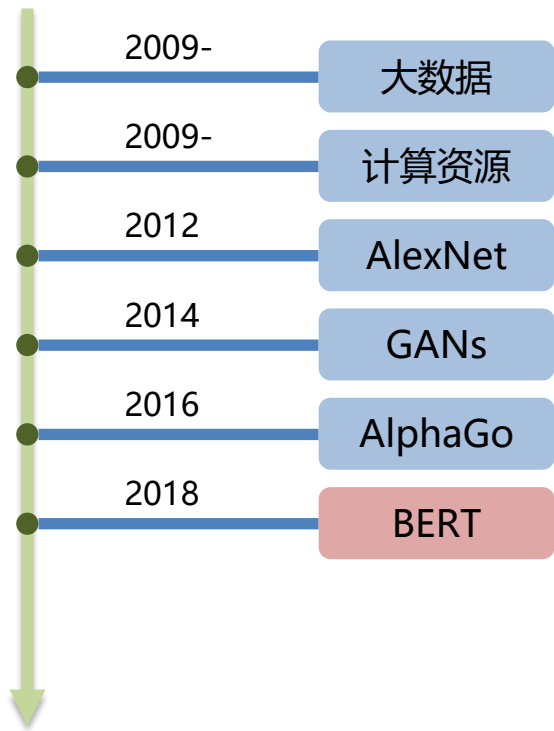
[Image credit](#)

AlphaGo 战胜最顶尖的人类围棋手





深度学习简史



[Image credit](#)

System	MNLI-(m/mm)	QQP	QNLI	SST-2	CoLA	STS-B	MRPC	RTE	Average
	392k	363k	108k	67k	8.5k	5.7k	3.5k	2.5k	-
Pre-OpenAI SOTA	80.6/80.1	66.1	82.3	93.2	35.0	81.0	86.0	61.7	74.0
BiLSTM+ELMo+Attn	76.4/76.1	64.8	79.8	90.4	36.0	73.3	84.9	56.8	71.0
OpenAI GPT	82.1/81.4	70.3	87.4	91.3	45.4	80.0	82.3	56.0	75.1
BERT _{BASE}	84.6/83.4	71.2	90.5	93.5	52.1	85.8	88.9	66.4	79.6
BERT _{LARGE}	86.7/85.9	72.1	92.7	94.9	60.5	86.5	89.3	70.1	82.1

Table 1: GLUE Test results, scored by the evaluation server (<https://gluebenchmark.com/leaderboard>). The number below each task denotes the number of training examples. The “Average” column is slightly different than the official GLUE score, since we exclude the problematic WNLI set.⁸ BERT and OpenAI GPT are single-model, single task. F1 scores are reported for QQP and MRPC, Spearman correlations are reported for STS-B, and accuracy scores are reported for the other tasks. We exclude entries that use BERT as one of their components.





深度学习简史



Image credit

“Fathers of the Deep Learning Revolution”

ACM A.M. Turing Award





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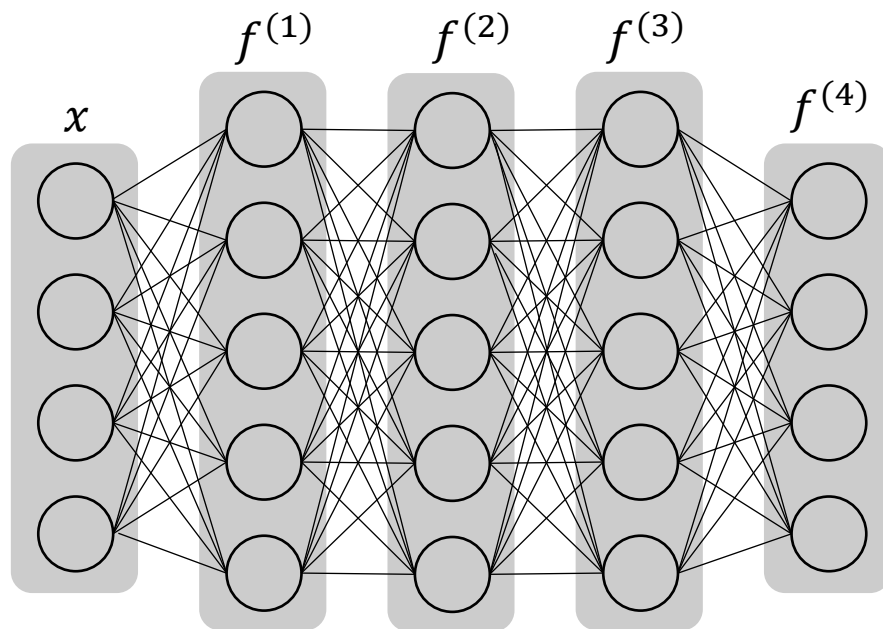


自编码器



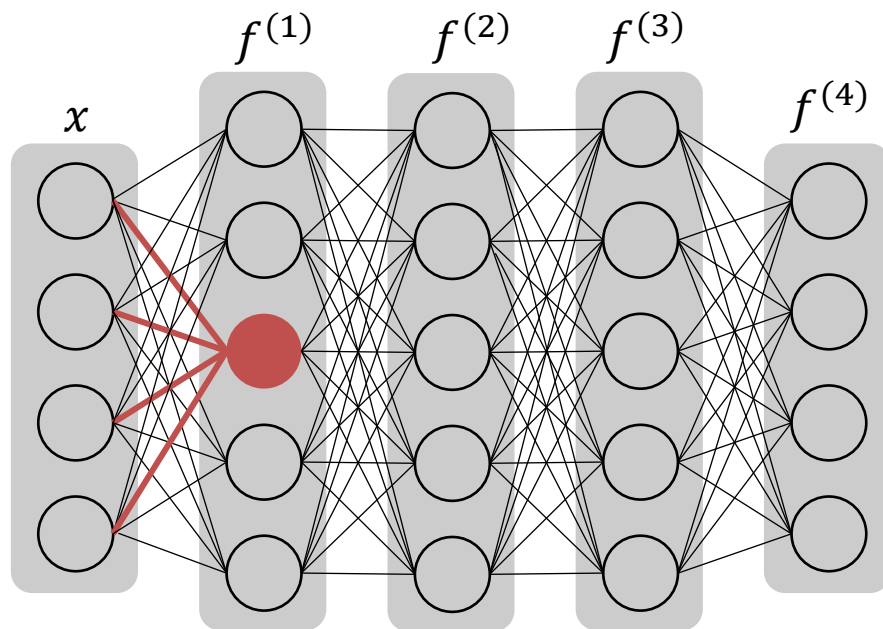


前馈神经网络



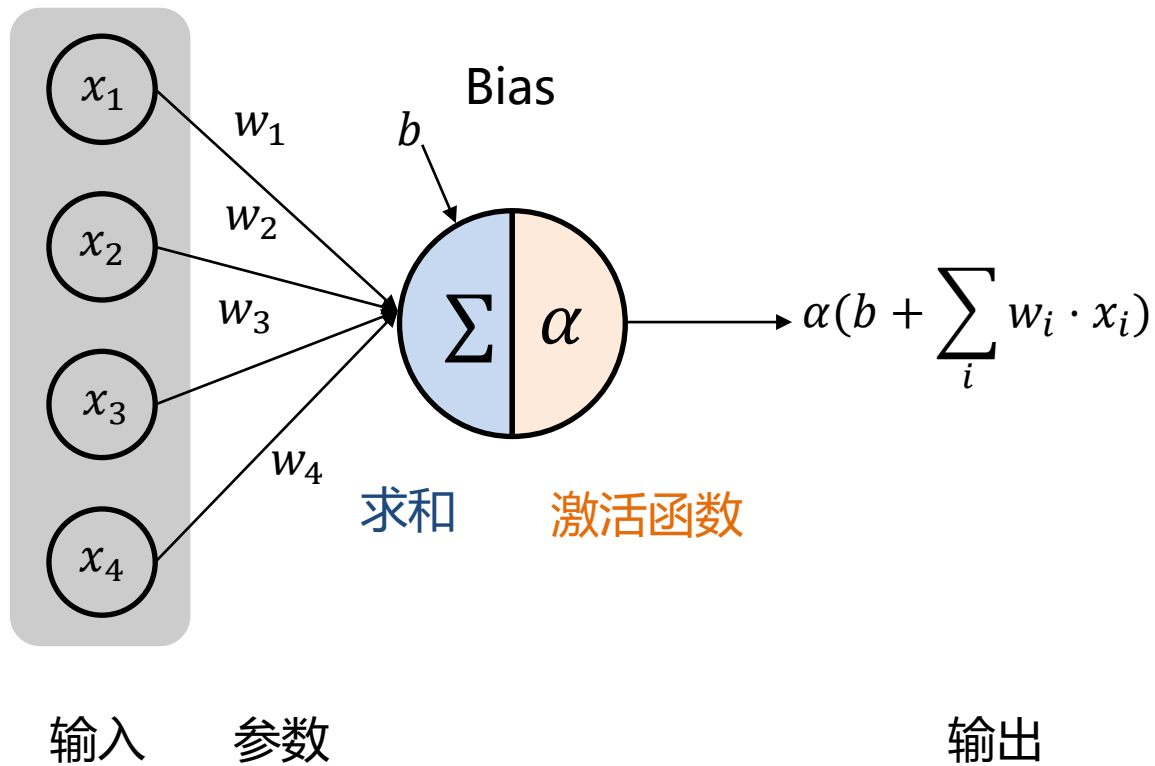


前馈神经网络



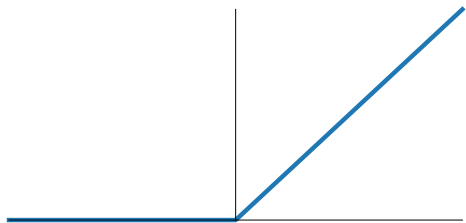


人工神经元

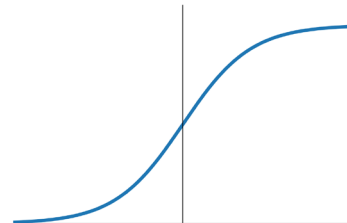




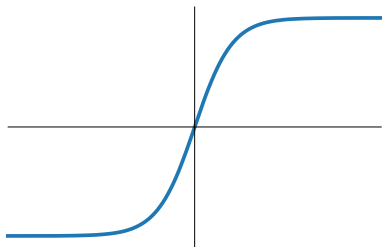
激活函数



$$\text{ReLU}(z) = \max\{0, z\}$$



$$\sigma(z) = \frac{1}{1 + \exp(-z)}$$

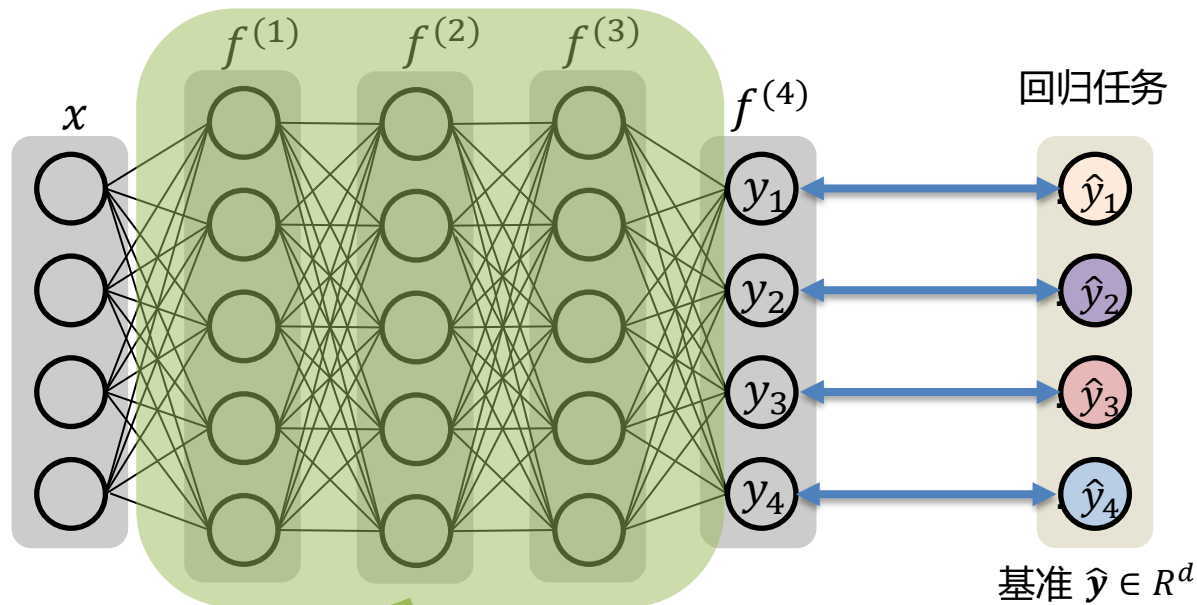


$$\tanh(z) = \frac{2}{1 + \exp(-2z)} - 1$$





输出层以及损失函数



损失函数

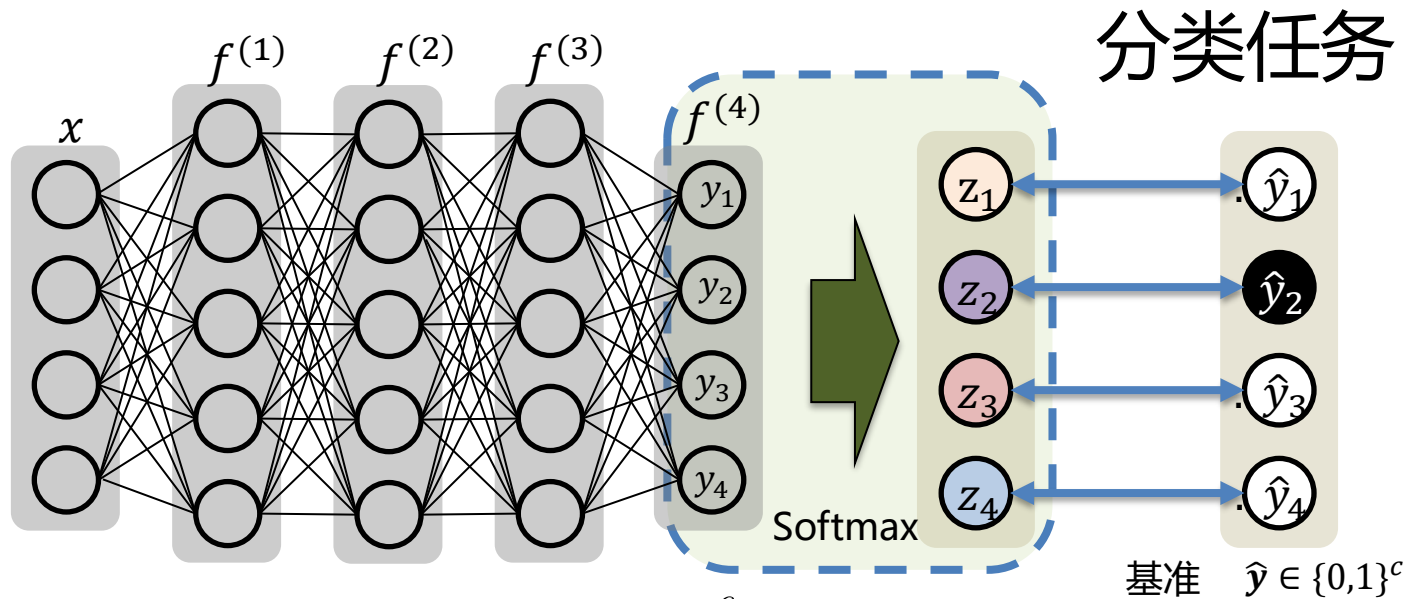
$$\ell(\mathbf{y}, \hat{\mathbf{y}}) = \|\mathbf{y} - \hat{\mathbf{y}}\|_2^2$$
$$\mathcal{L}(\mathbf{W}) = \frac{1}{n} \sum_{i=1}^n \ell(\mathbf{y}^{(i)}, \hat{\mathbf{y}}^{(i)})$$

第*i*个训练
样本





输出层以及损失函数



损失函数

$$\ell(\mathbf{z}, \hat{\mathbf{y}}) = - \sum_{j=1}^c \hat{y}_j \log z_j$$

$$\mathcal{L}(\mathbf{W}) = \frac{1}{n} \sum_{i=1}^n \ell(\mathbf{z}^{(i)}, \hat{\mathbf{y}}^{(i)})$$





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自编码器





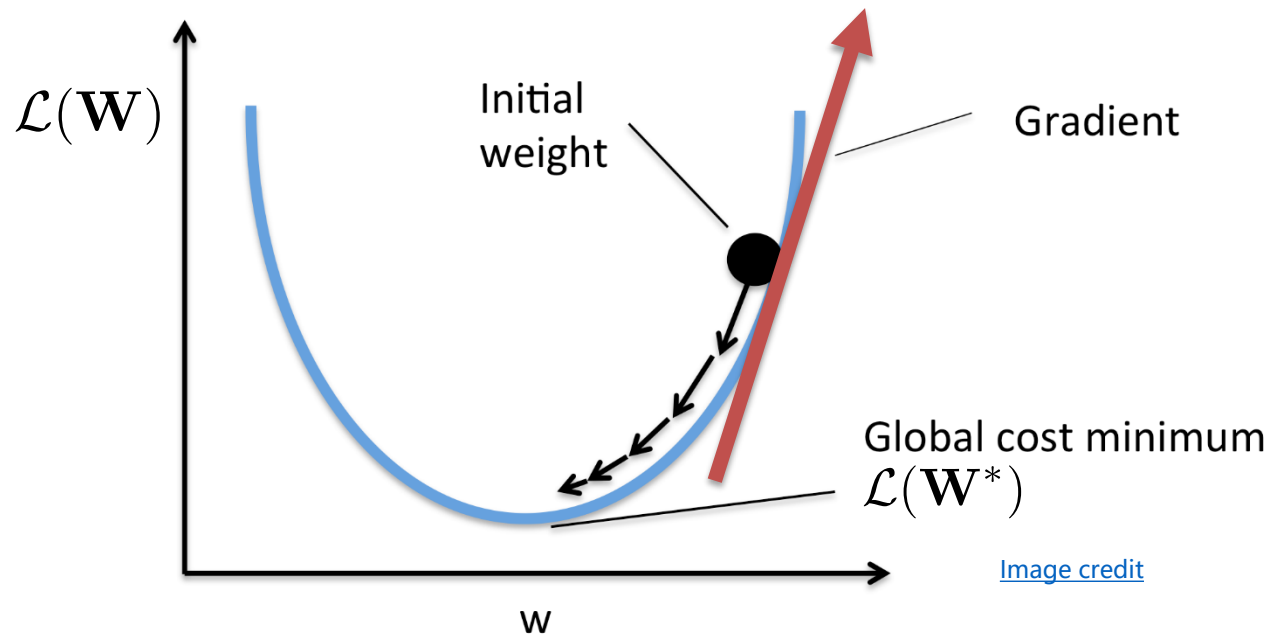
优化的目标

$$\mathcal{L}(\mathbf{W}) = \frac{1}{n} \sum_{i=1}^n \ell \left(\mathbf{y}^{(i)}, \hat{\mathbf{y}}^{(i)} \right)$$





梯度下降法




$$\mathbf{W}_{n+1} \leftarrow \mathbf{W}_n - \eta \nabla \mathcal{L}(\mathbf{W}_n)$$

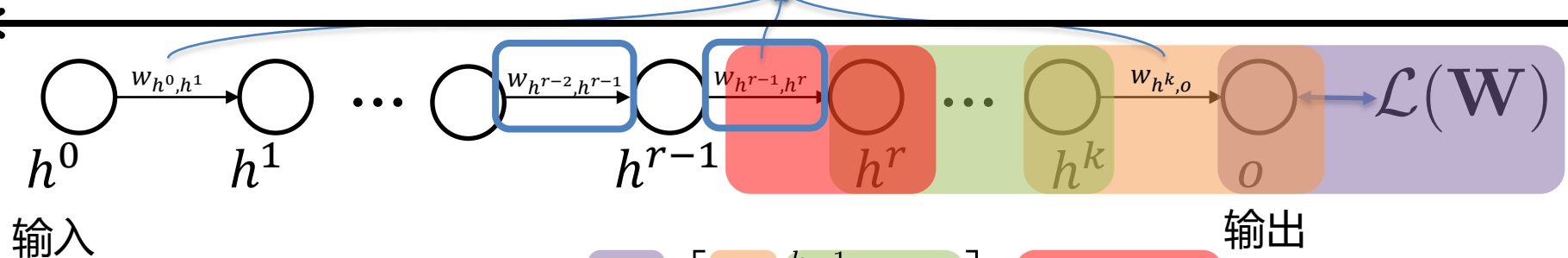


反向传播

考虑每一层只有一个神经元的情况

参数

从后往前依次计算  高效



$$\frac{\partial \mathcal{L}}{\partial w_{(h^{r-1}, h^r)}} = \frac{\partial \mathcal{L}}{\partial o} \cdot \left[\frac{\partial o}{\partial h^k} \prod_{i=r}^{k-1} \frac{\partial h^{i+1}}{\partial h^i} \right] \cdot \frac{\partial h^r}{\partial w_{(h^{r-1}, h^r)}}$$

$$\frac{\partial \mathcal{L}}{\partial w_{(h^{r-2}, h^{r-1})}} = \frac{\partial \mathcal{L}}{\partial o} \cdot \left[\frac{\partial o}{\partial h^k} \prod_{i=r}^{k-1} \frac{\partial h^{i+1}}{\partial h^i} \right] \cdot \frac{\partial h^r}{\partial h^{r-1}} \cdot \frac{\partial h^{r-1}}{\partial w_{(h^{r-2}, h^{r-1})}}$$

不需要重复计算

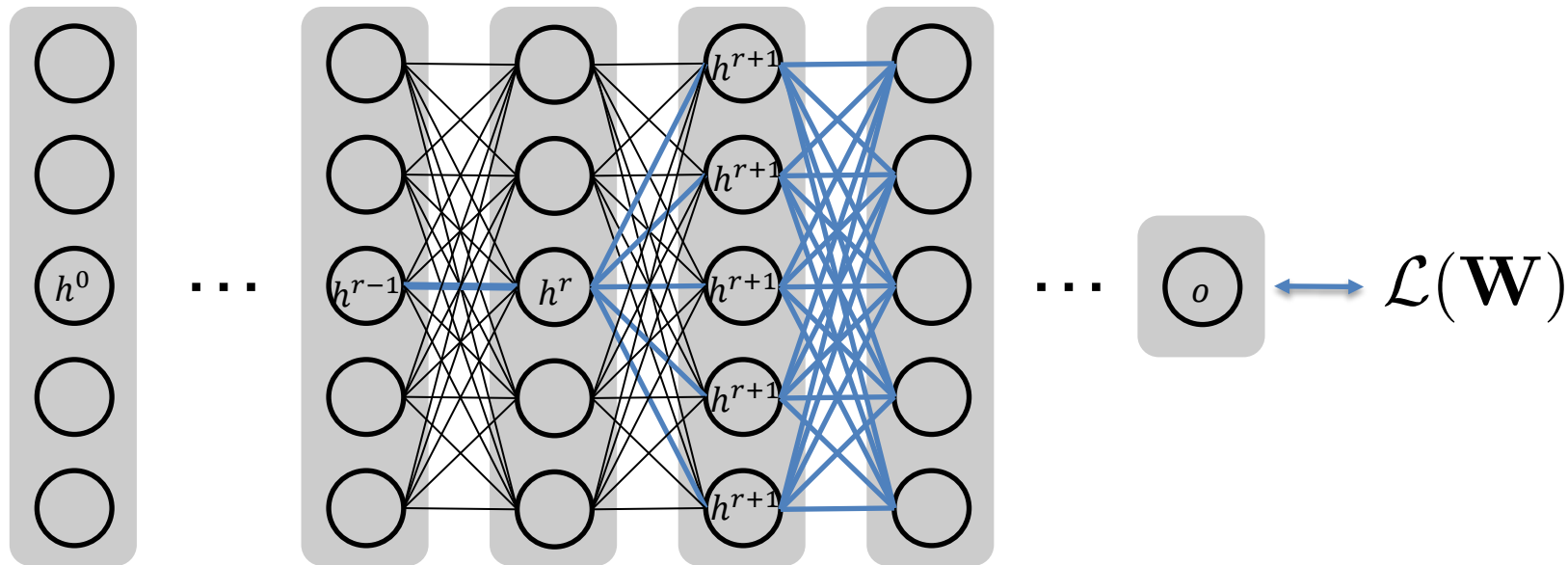
需要额外计算





反向传播

考虑每一层都有多个神经元的情况



更为复杂，但是原理和单个神经元的情况类似



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神经网络的训练



卷积神经网络



循环神经网络

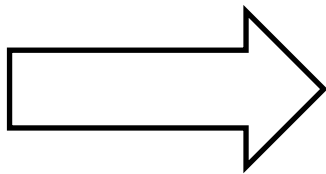
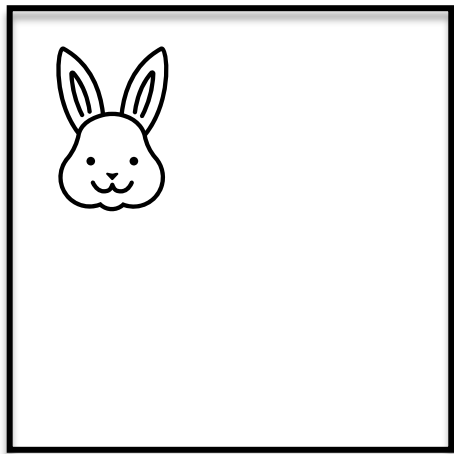


自编码器





图像分类

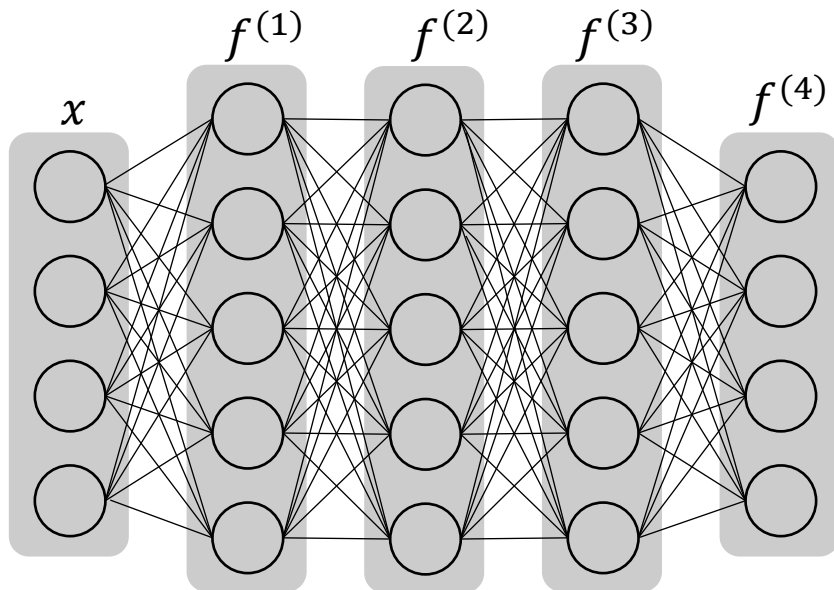
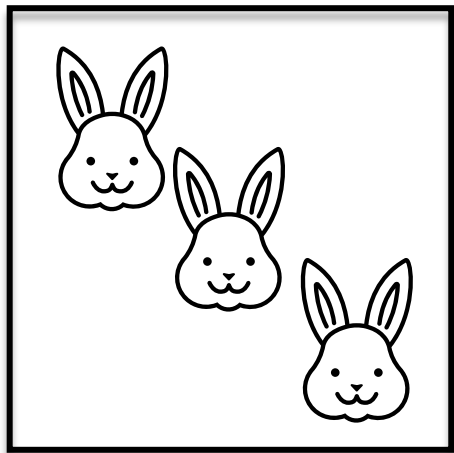


兔子?





图像分类

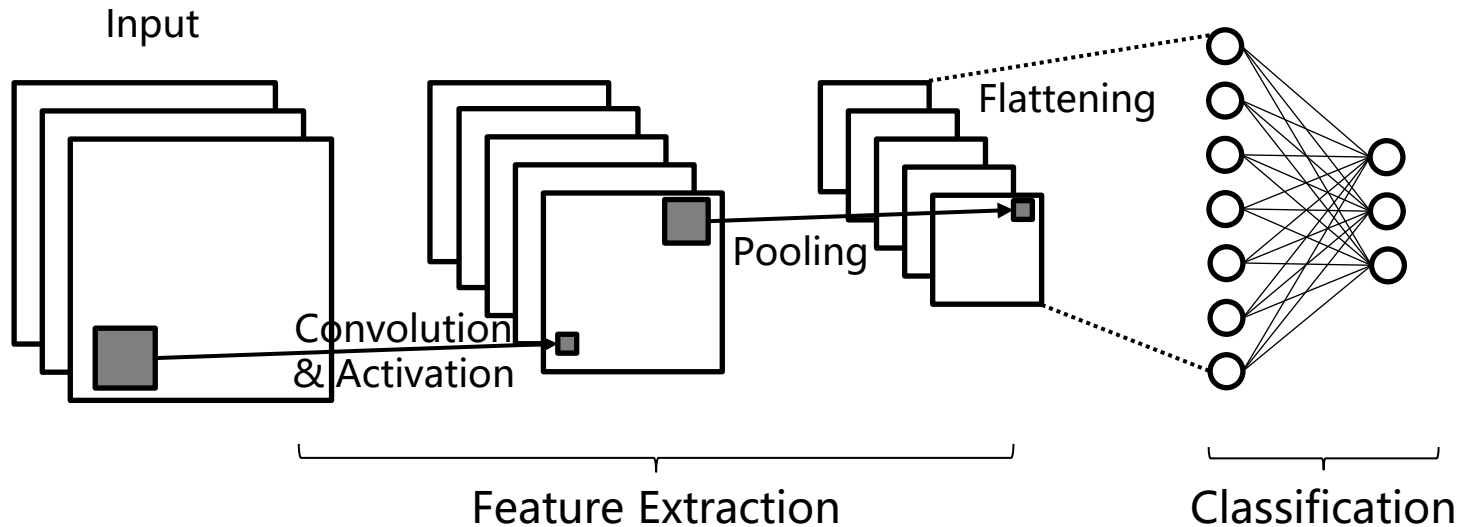


兔子?





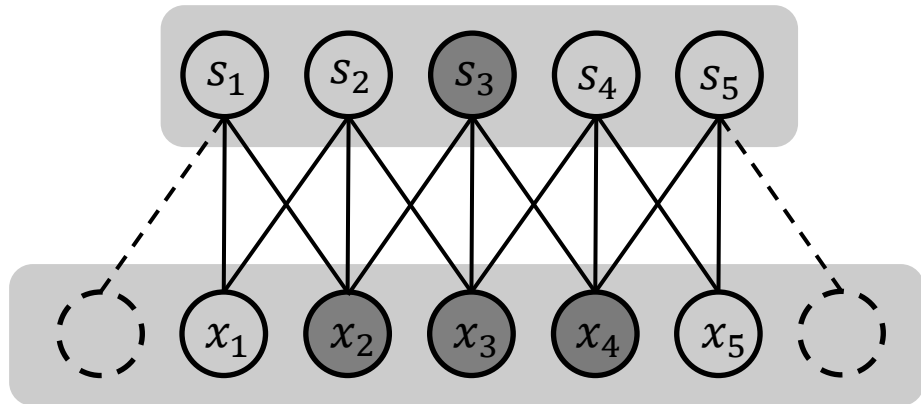
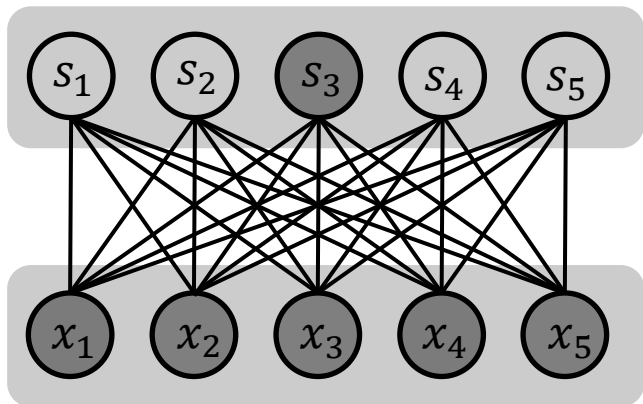
卷积神经网络



- 卷积操作
- 池化操作

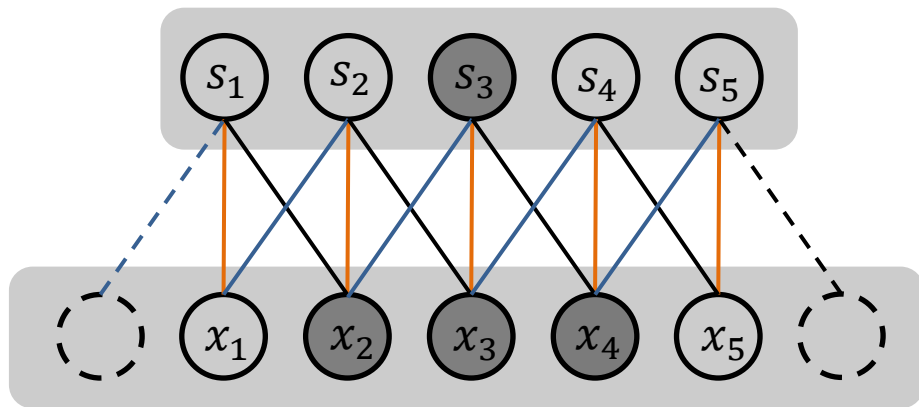


卷积操作：稀疏连接

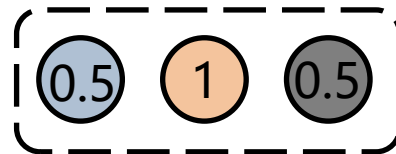




卷积操作：参数共享

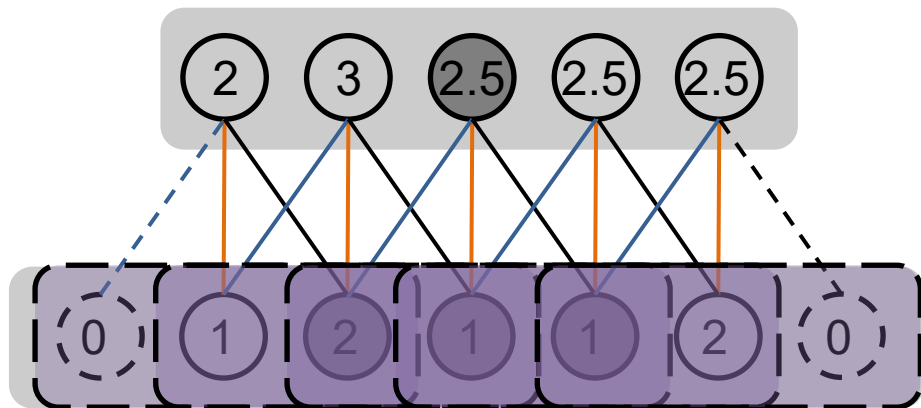


卷积核

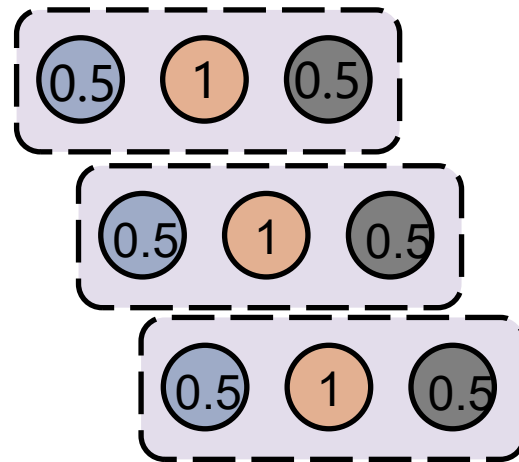




卷积操作

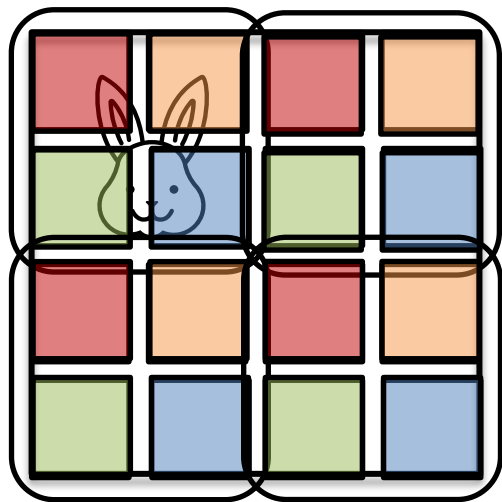


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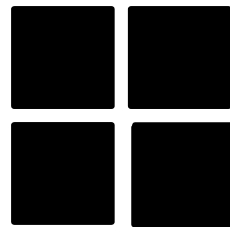
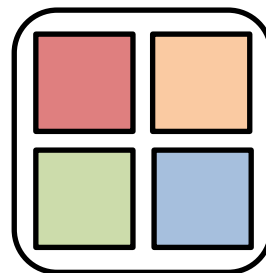


二维卷积操作



输入

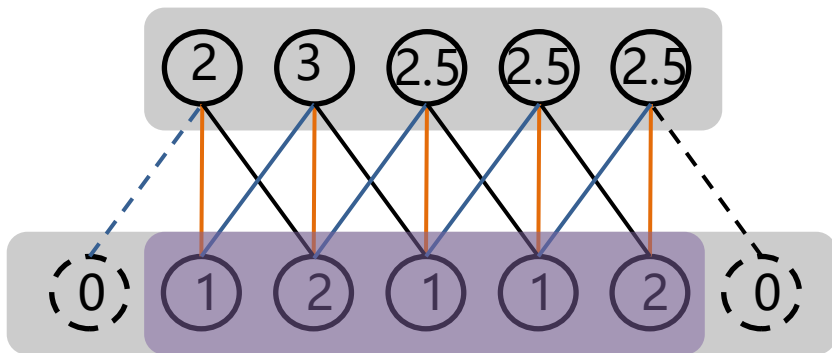
卷积核



输出

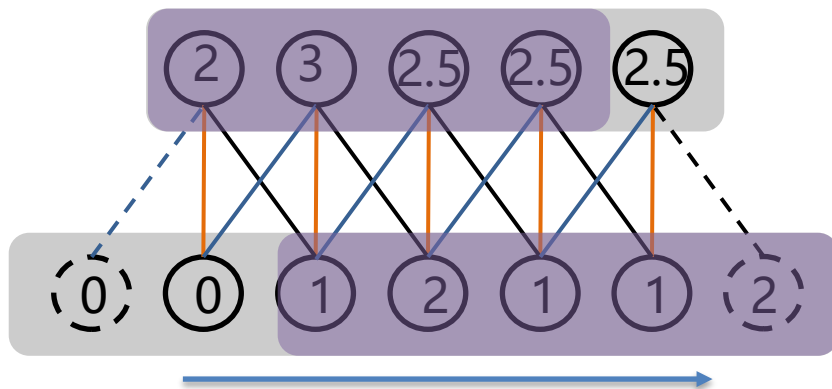


卷积操作：平移等变



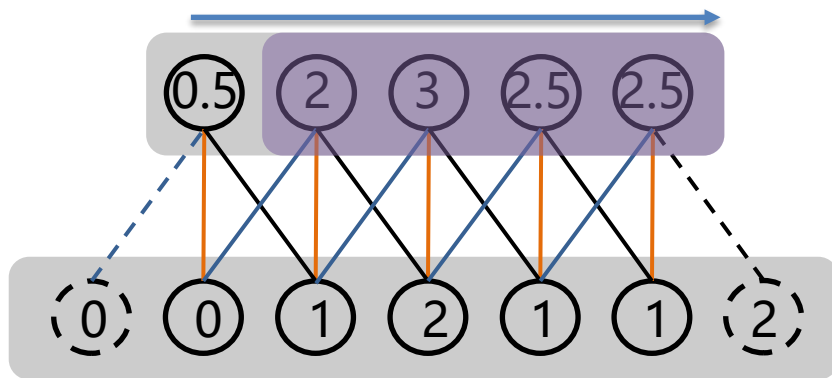


卷积操作：平移等变

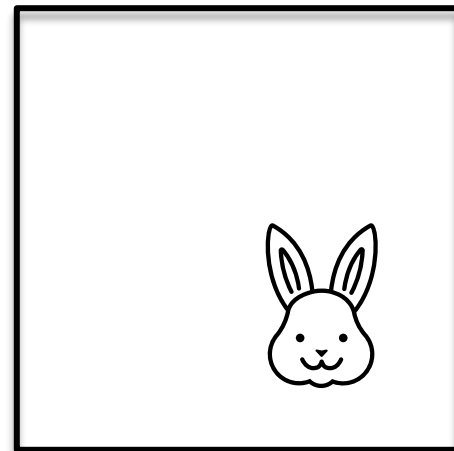
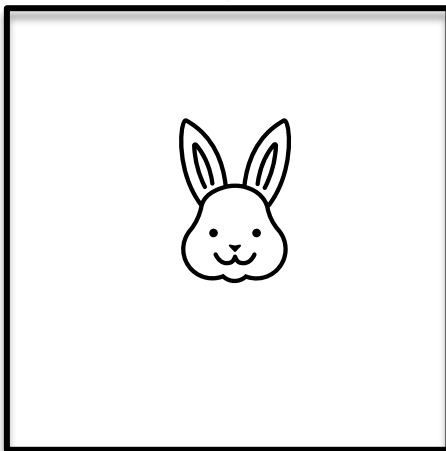
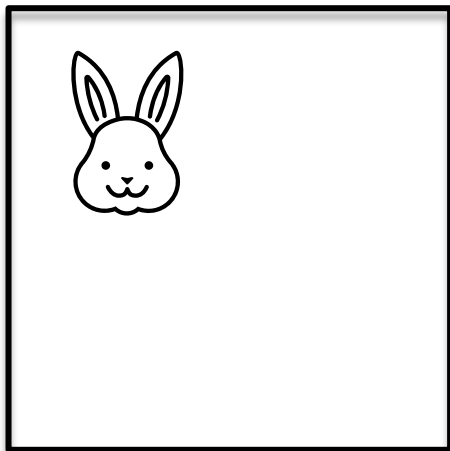
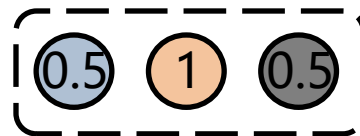




卷积操作：平移等变

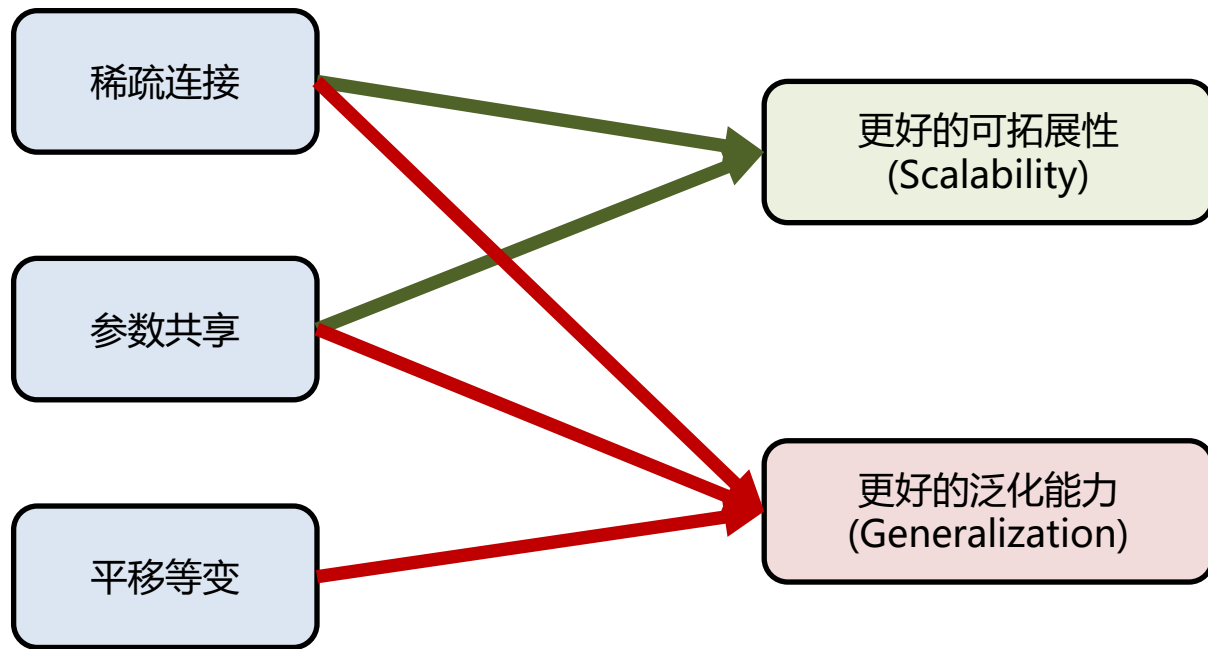


卷积核



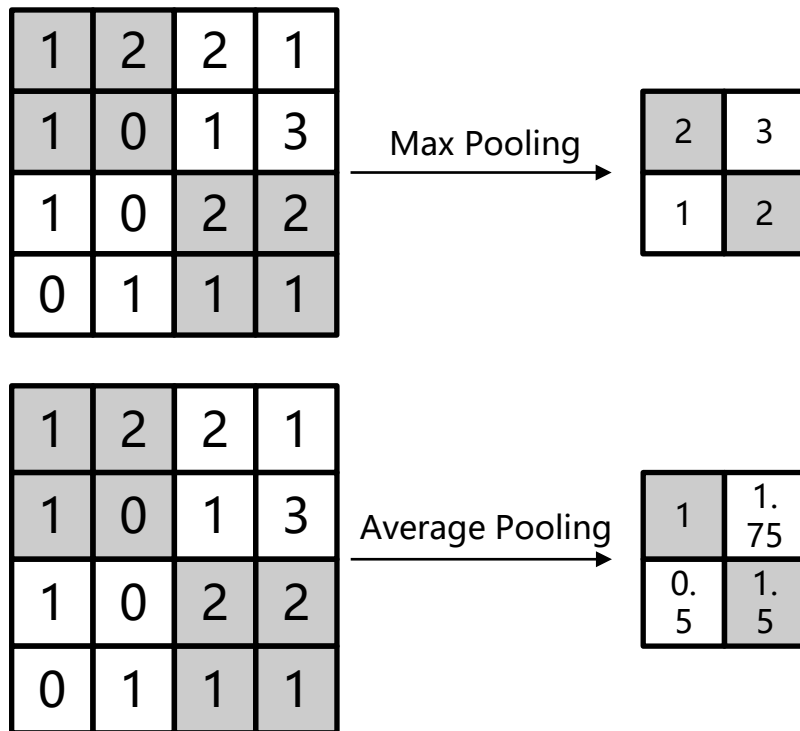


卷积操作的性质总结



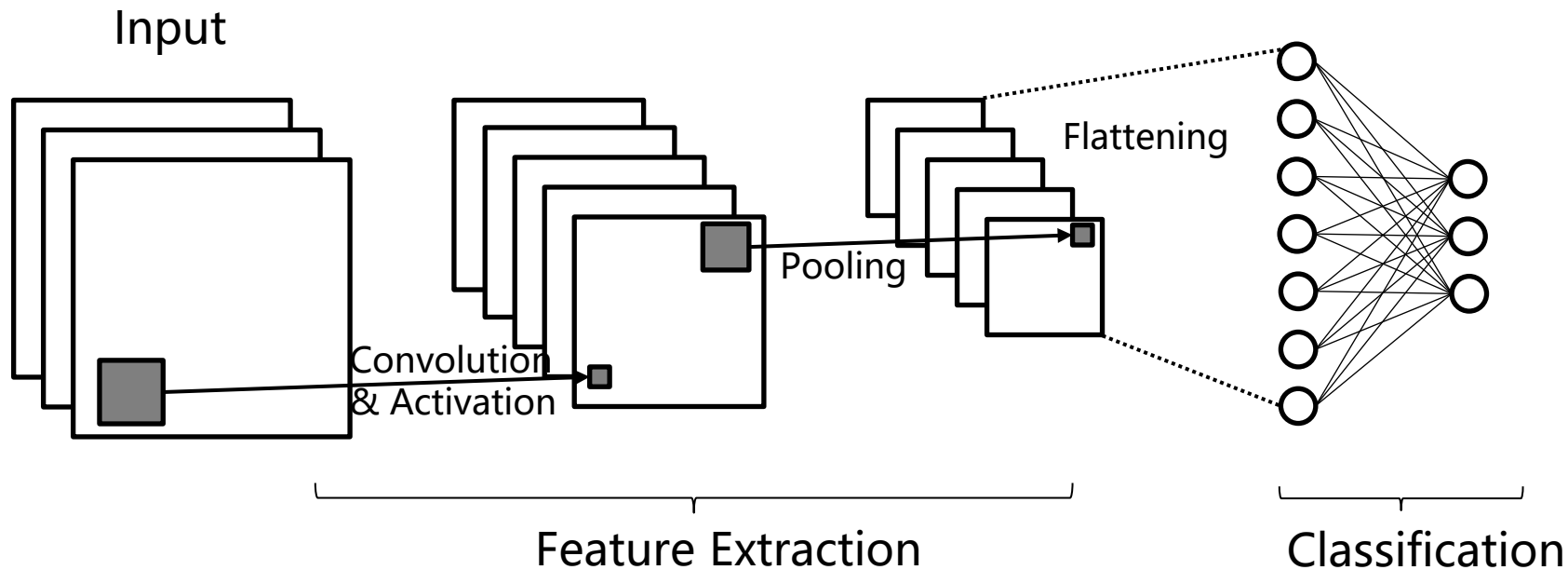


池化操作





卷积神经网络的整体框架





目录



深度学习简史



前馈神经网络



神经网络的训练



卷积神经网络



循环神经网络



自编码器



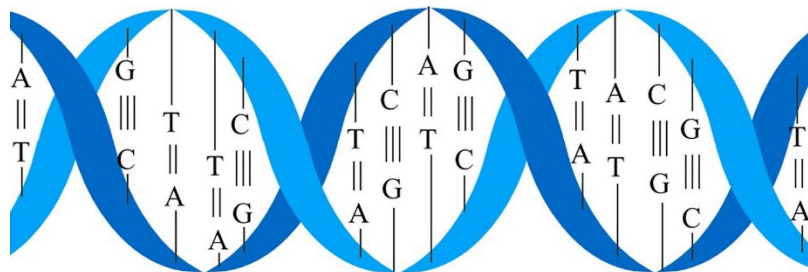


序列数据

I went to Yellowstone National Park last summer...



[Image credit](#)



[Image credit](#)





序列数据上的任务



输入

模型



机器翻译

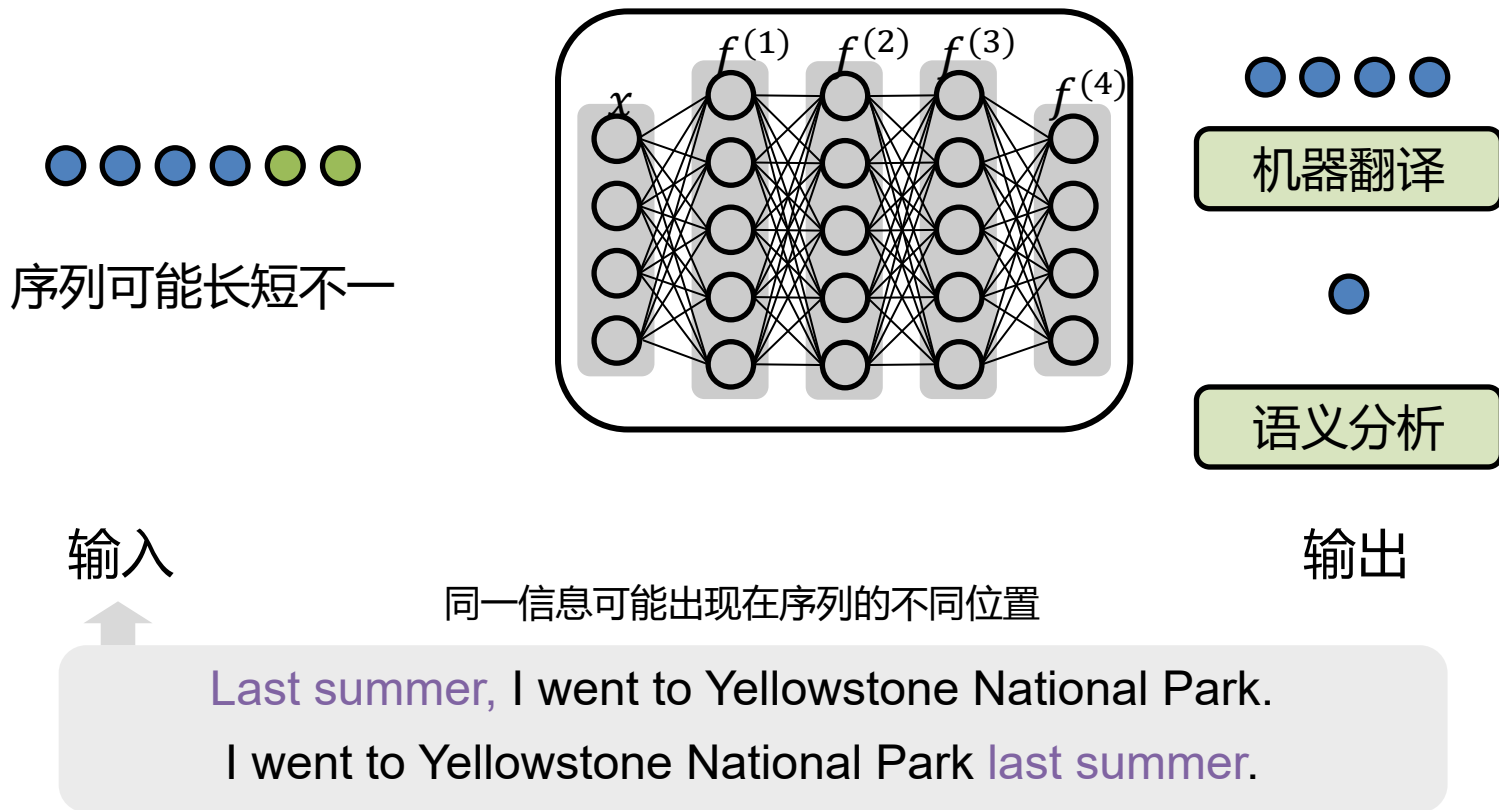


语义分析

输出

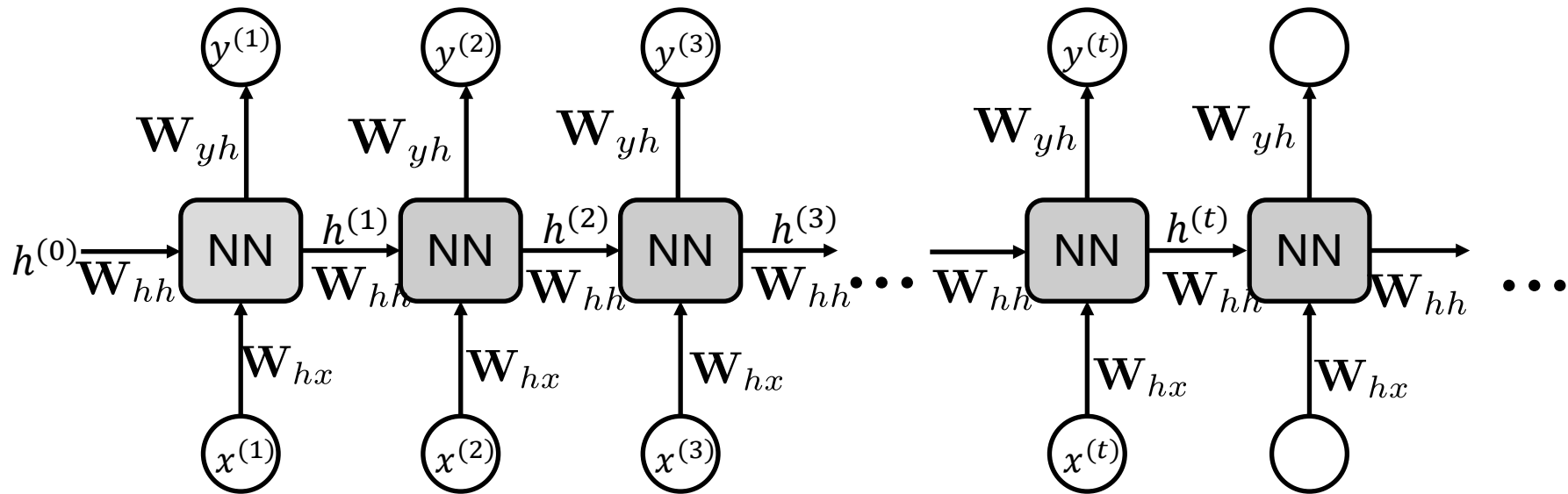


可以用前馈网络处理序列数据吗





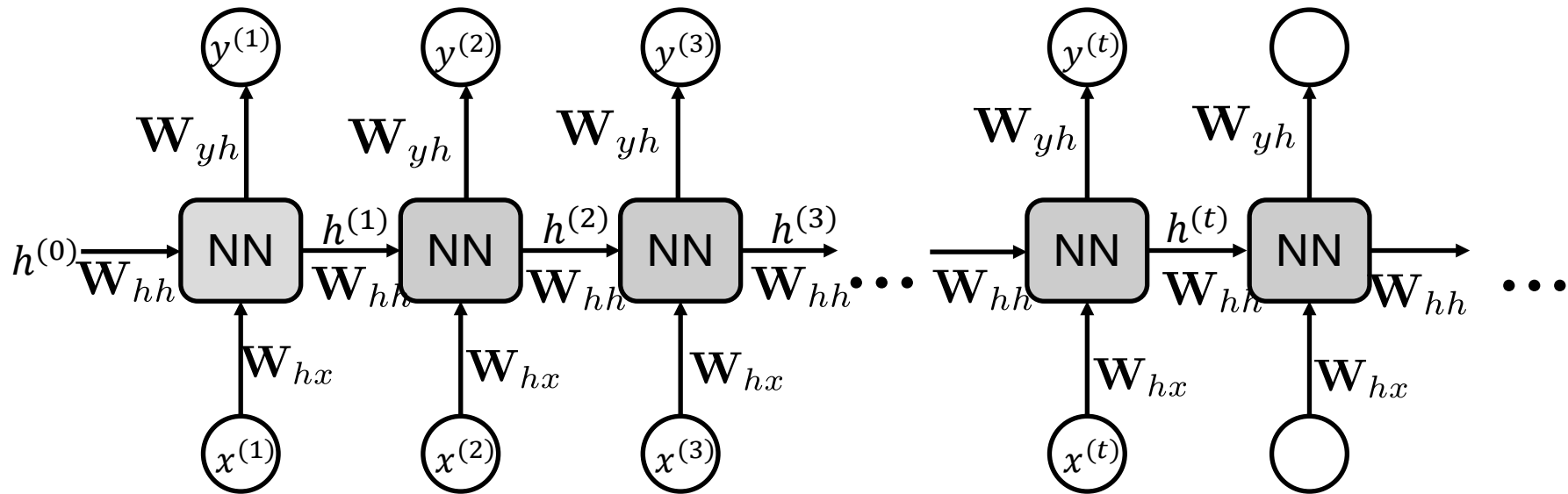
循环神经网络



$$h^{(i)} = \alpha_h \left(W_{hh} \cdot h^{(i-1)} + W_{hx} x^{(i-1)} + b_h \right)$$
$$y^{(i)} = \alpha_y \left(W_{yh} h^{(i)} + b_y \right)$$



循环神经网络



Last summer, I went to Yellowstone National Park.

I went to Yellowstone National Park last summer.



循环神经网络的性质

处理不同长度的序列

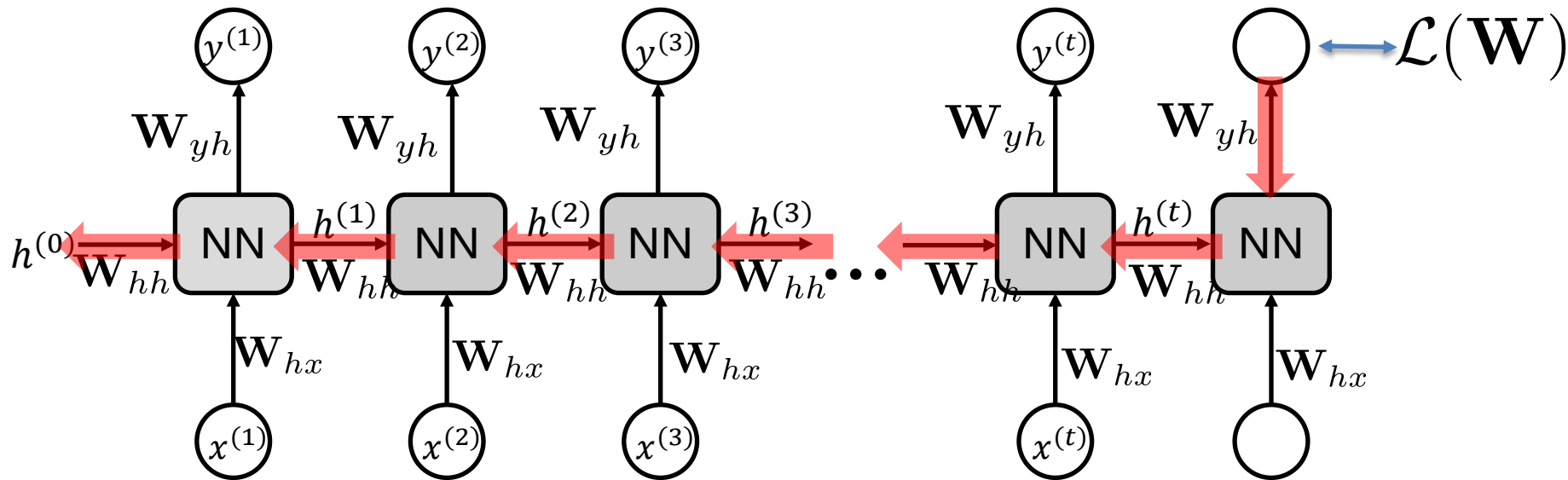
捕捉序列的顺序信息

参数共享





梯度消失与梯度爆炸



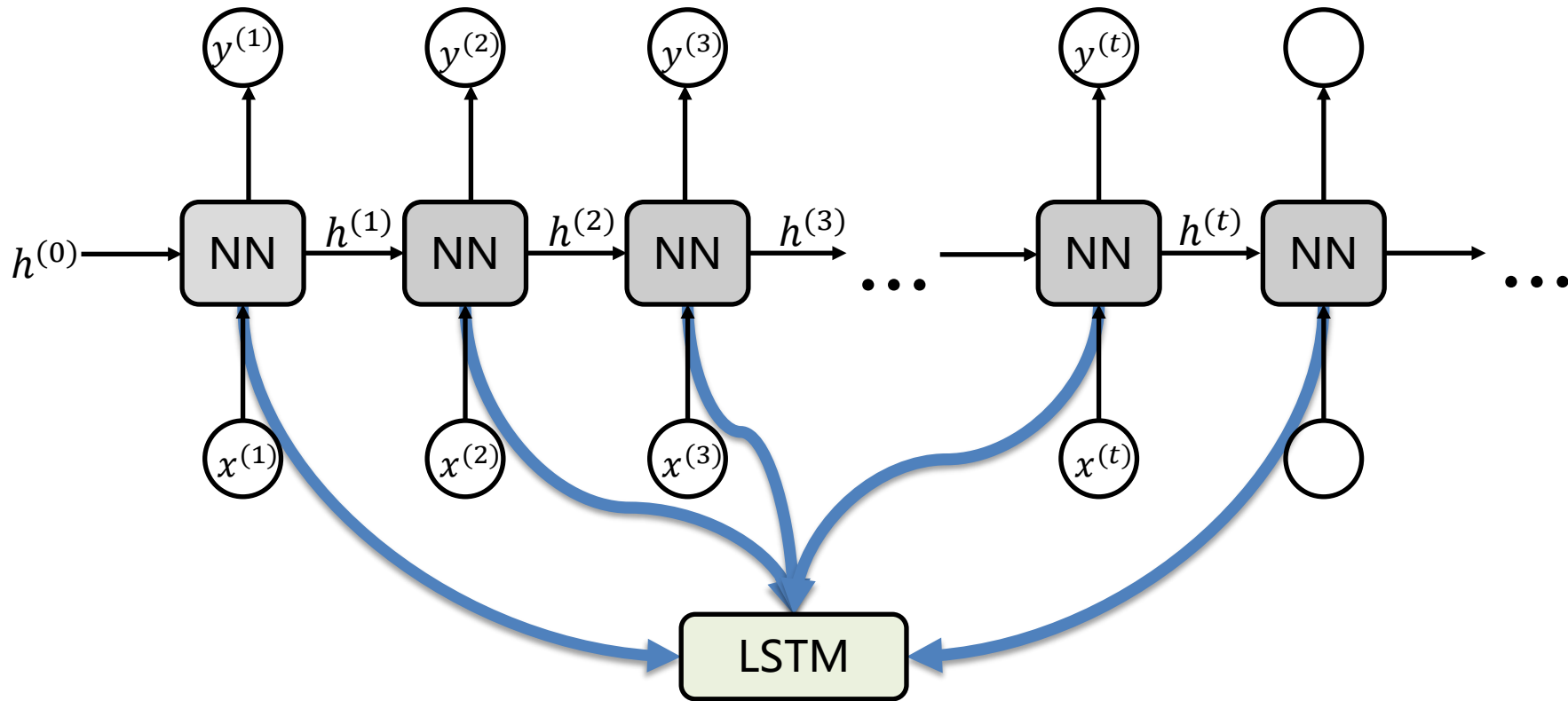
$$h^{(i)} = \alpha_h \left(W_{hh} \cdot h^{(i-1)} + W_{hx} x^{(i-1)} + b_h \right)$$

算梯度的过程涉及到了 W_{hh} 的连续相乘



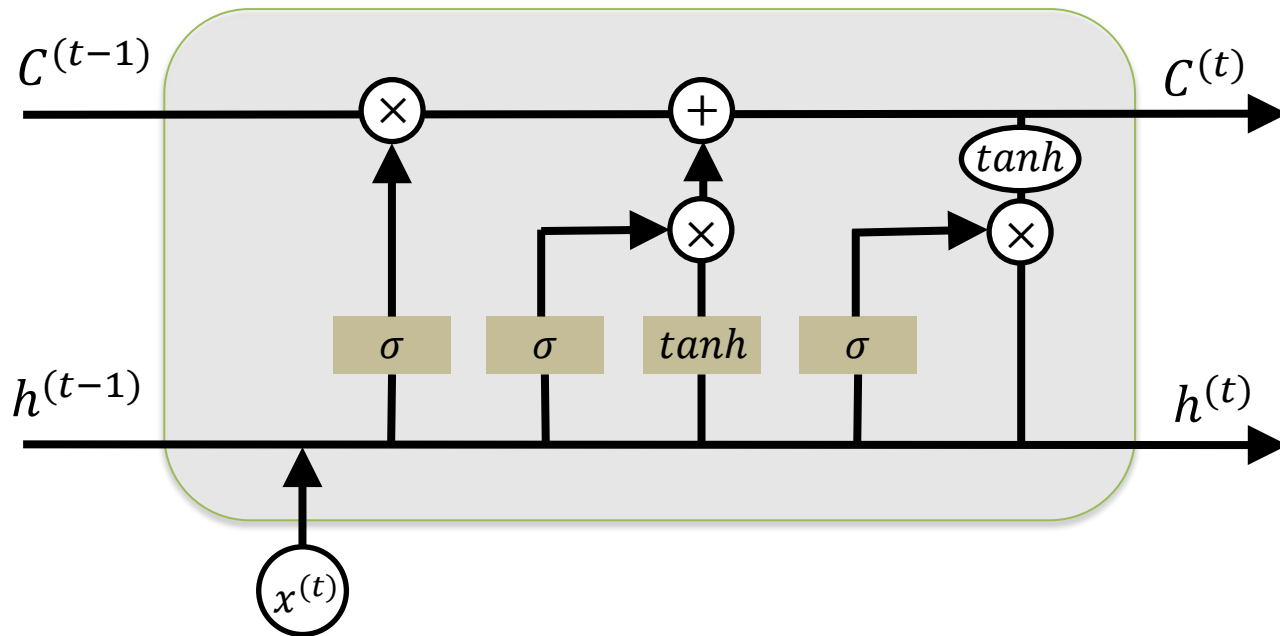


Long Short Term Memory (LSTM)



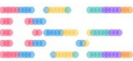


LSTM



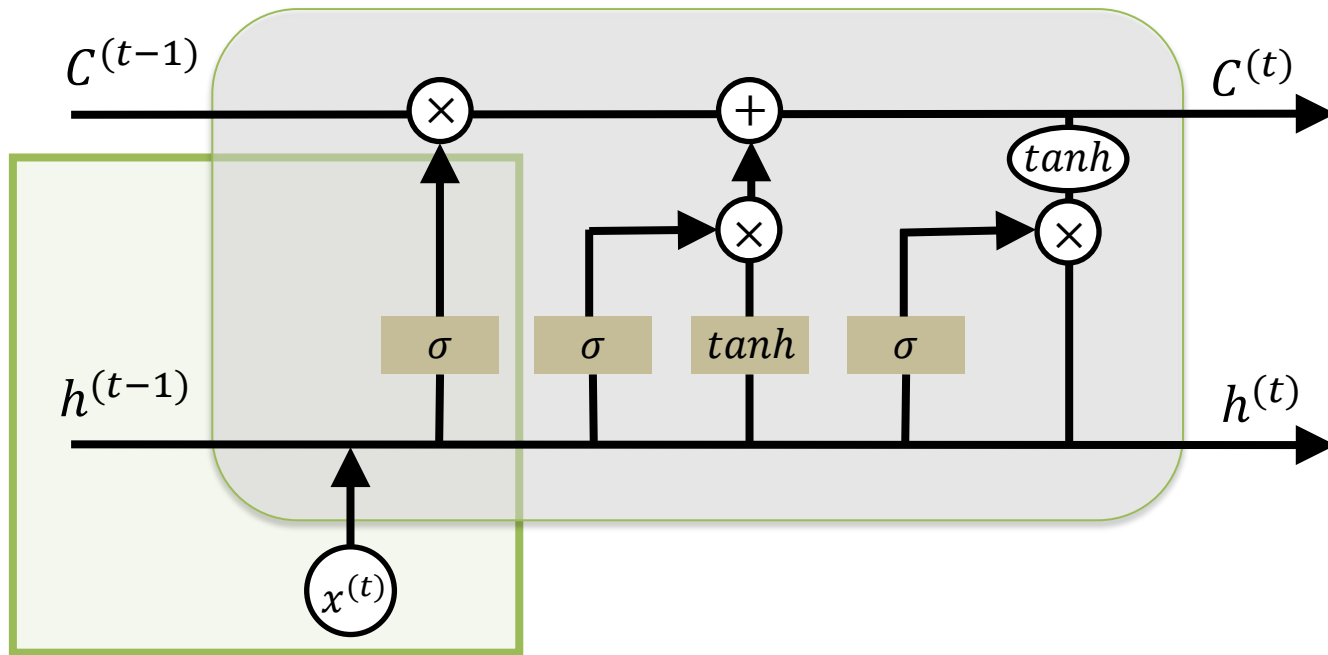
单元状态 (Cell State) : $C^{(t)}$

隐藏状态 (Hidden State): $h^{(t)}$





LSTM: 遗忘门

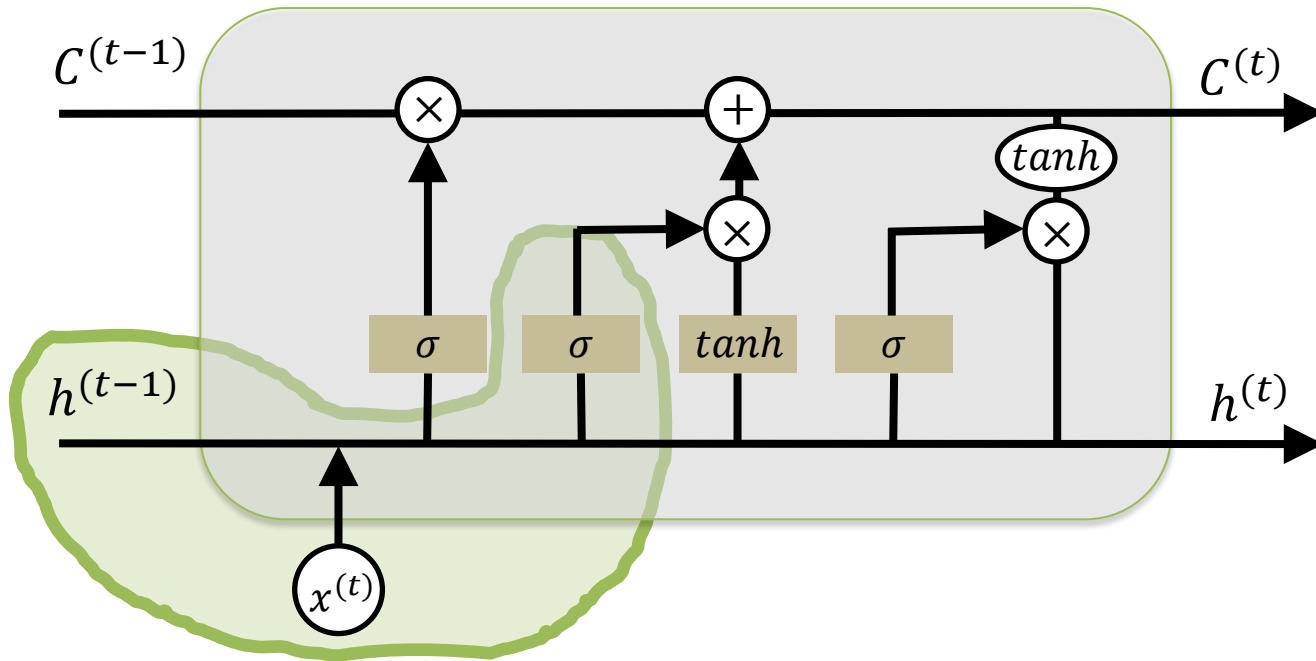


$$f_t = \sigma \left(W_f \cdot x^{(t)} + U_f \cdot h^{(t-1)} + b_f \right)$$





LSTM: 输入门

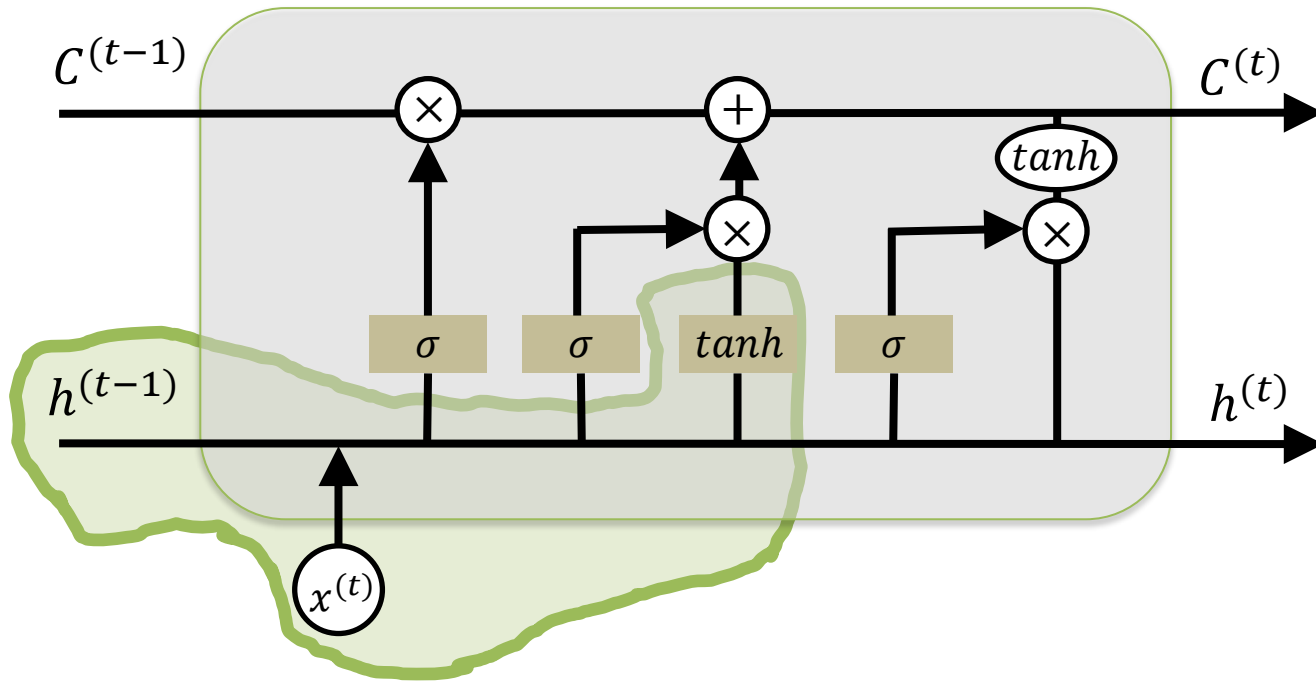


$$i_t = \sigma \left(W_i \cdot x^{(t)} + U_i \cdot h^{(t-1)} + b_i \right)$$





LSTM: 候选值

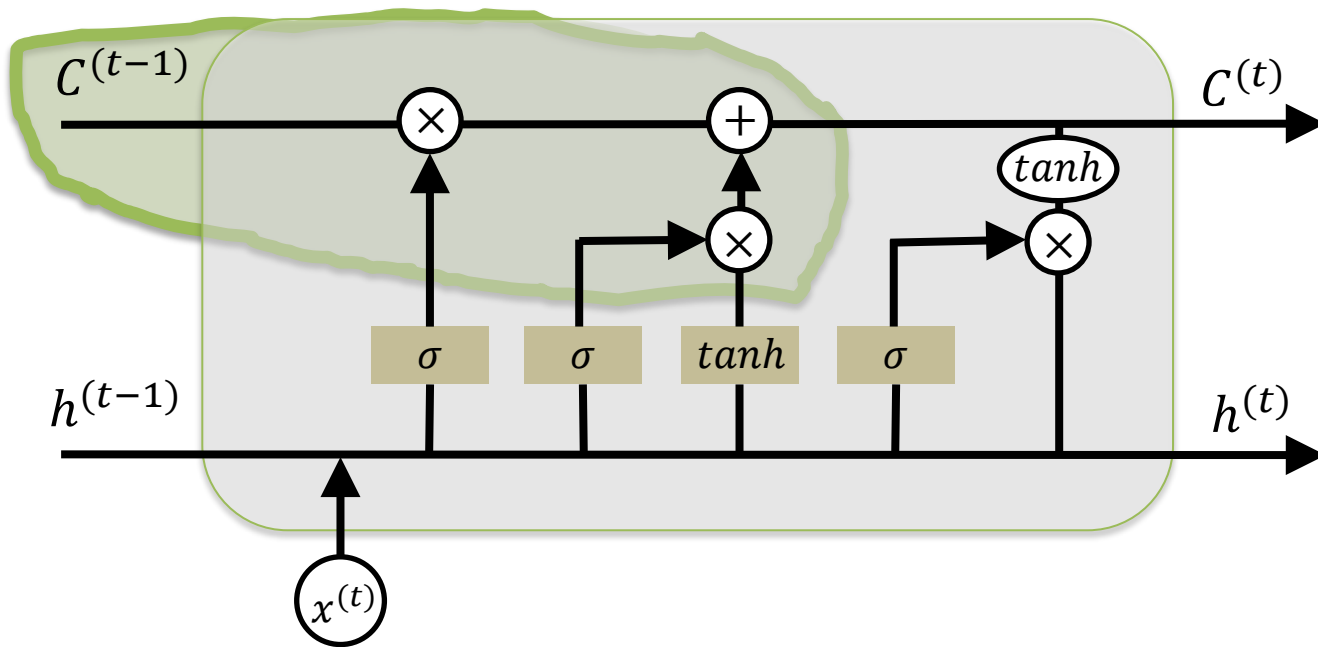


$$\tilde{C}^{(t)} = \tanh \left(\mathbf{W}_c \cdot \mathbf{x}^{(t)} + \mathbf{U}_c \cdot \mathbf{h}^{(t-1)} + \mathbf{b}_c \right)$$





LSTM: 新的单元状态

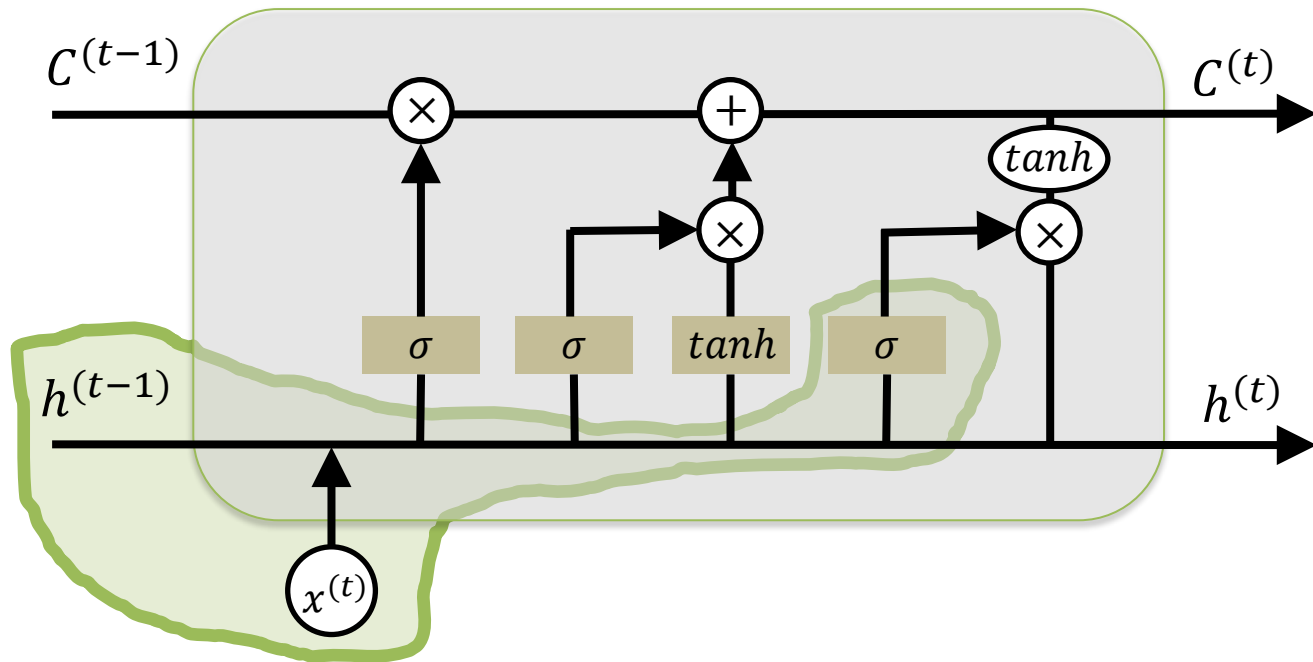


$$C^{(t)} = f_t \odot C^{(t-1)} + i_t \odot \tilde{C}^{(t)}$$





LSTM: 输出门

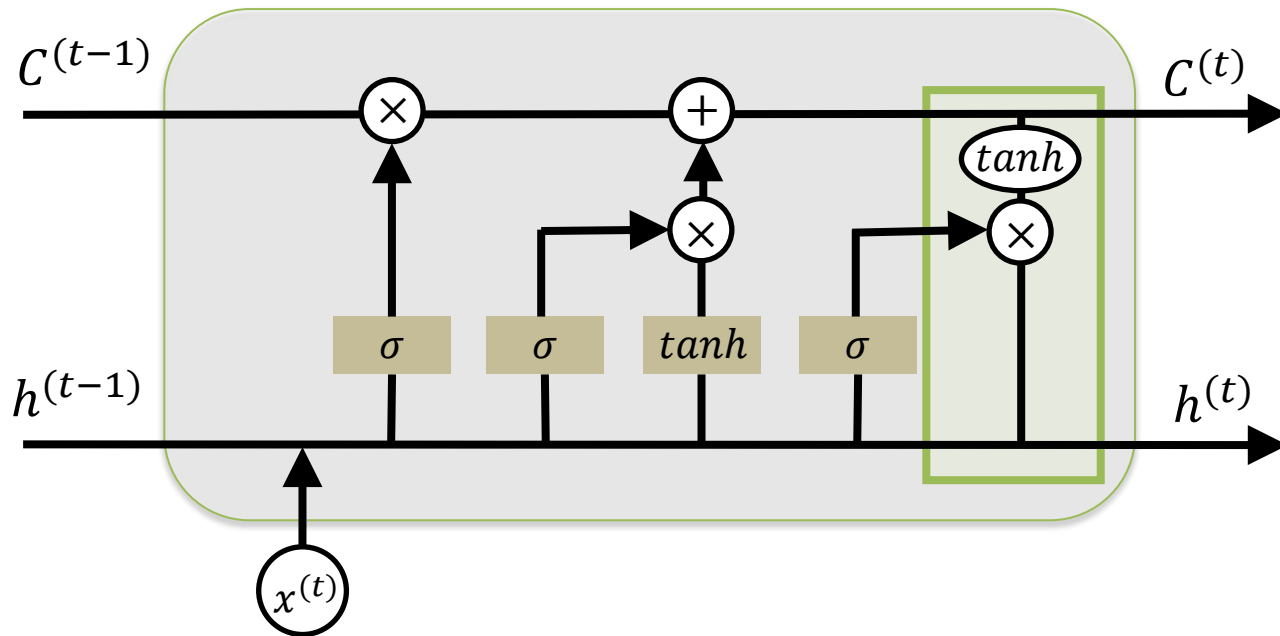


$$o_t = \sigma \left(W_o \cdot x^{(t)} + U_o \cdot h^{(t-1)} + b_o \right)$$

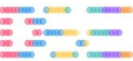




LSTM

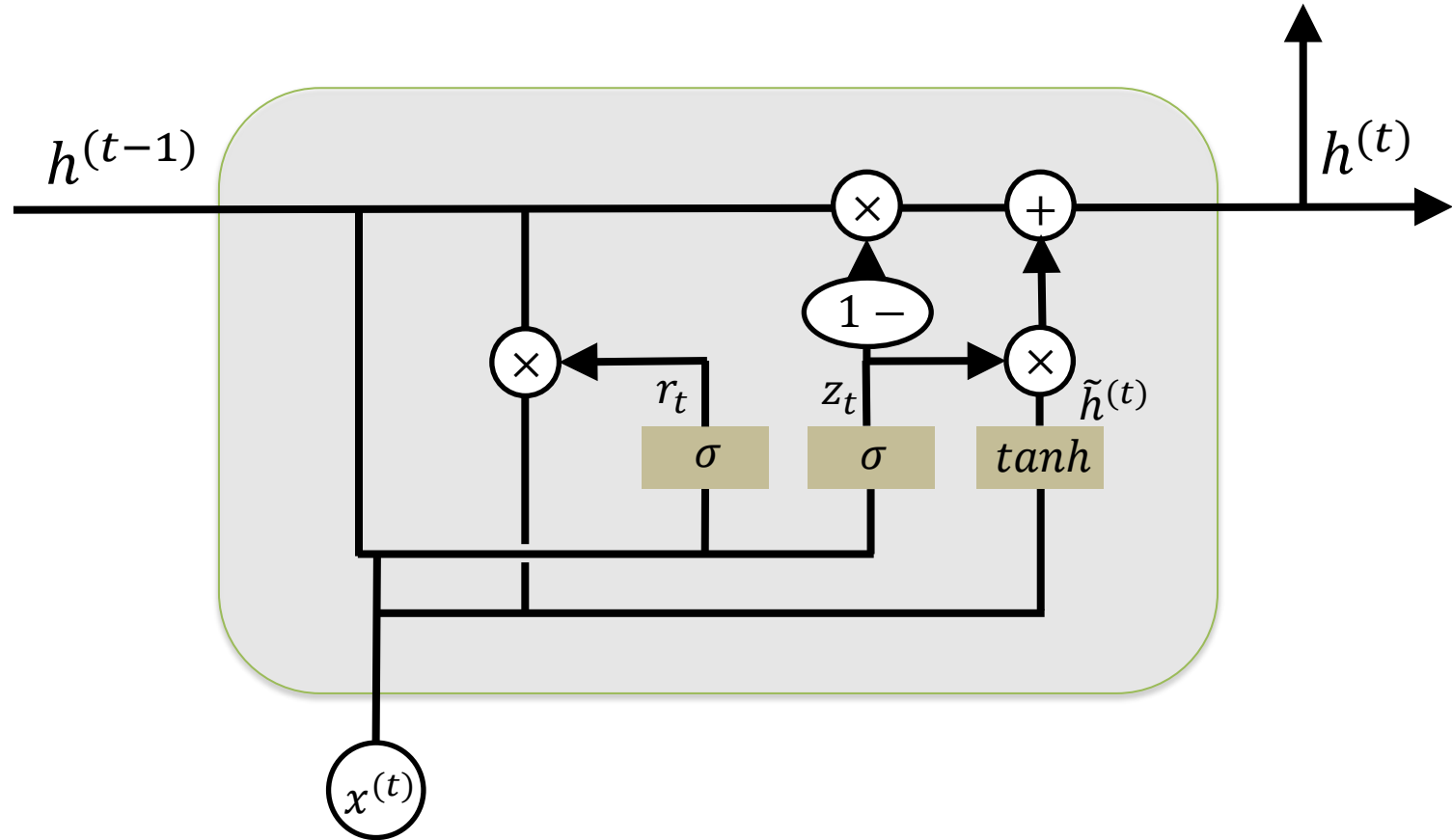


$$h^{(t)} = o_t \odot \tanh \left(C^{(t)} \right)$$





Gated Recurrent Unit (GRU)





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深度学习简史



前馈神经网络



神经网络的训练



卷积神经网络



循环神经网络



自编码器

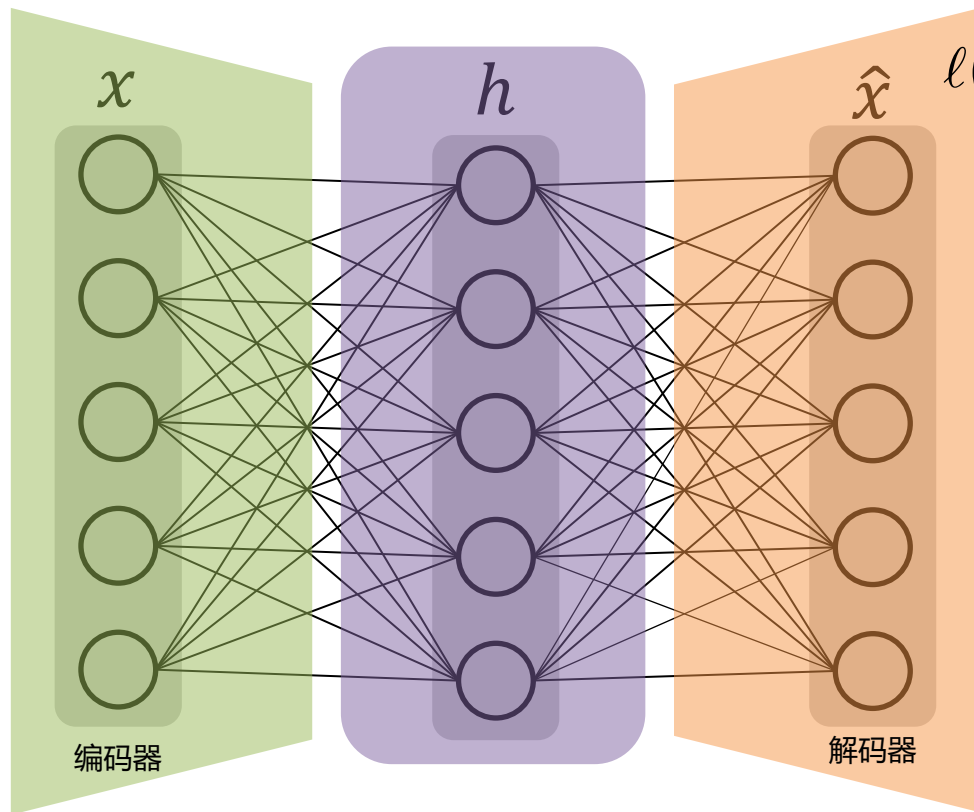




自编码器

无监督学习

编码器和解码器都可以用神经网络建模



$$\ell(\mathbf{x}, \hat{\mathbf{x}}) = \|\mathbf{x} - \hat{\mathbf{x}}\|_2^2$$

损失函数
的一个例子

重建

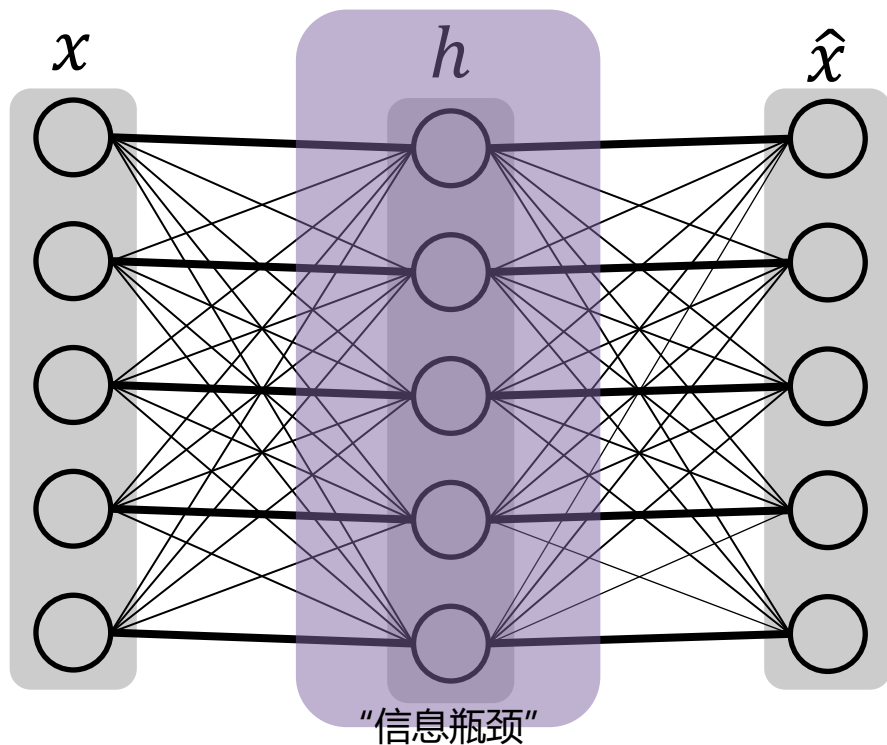
目标: h 能很好地编码 x 中的信息





自编码器

无监督学习

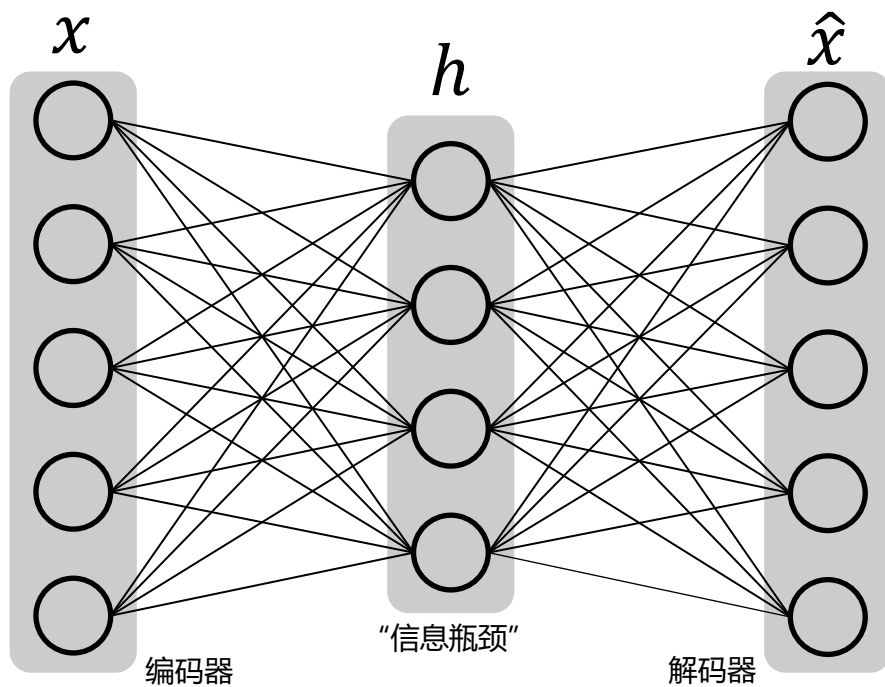


目标： h 能很好地编码 x 中的信息



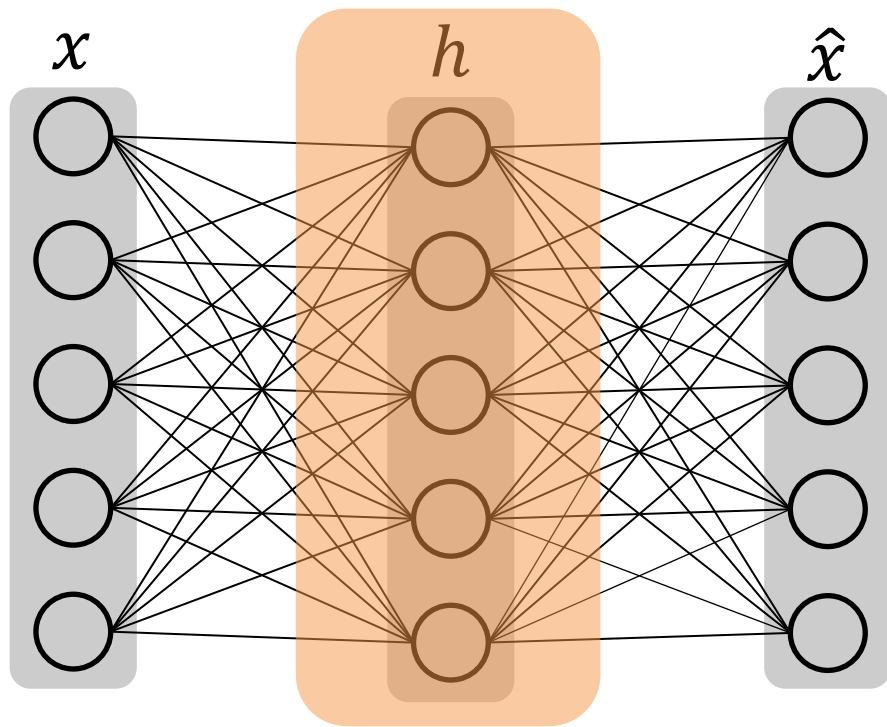


欠完备自编码器





正则化自编码器



$$\Omega(\mathbf{h}) = \|\mathbf{h}\|_2$$





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深度学习简史



前馈神经网络



神经网络的训练



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自编码器



感谢聆听 !
Thanks for Listening

