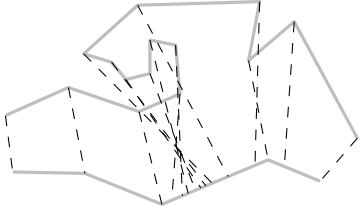


(a) two polylines



(b) corresponding vertices

straight-line trajectories

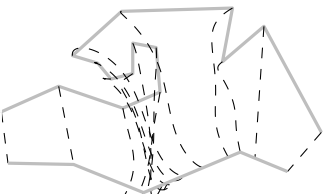
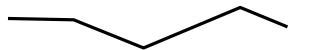
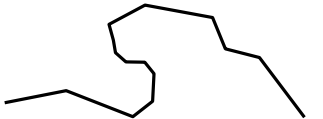
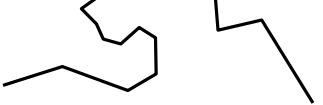
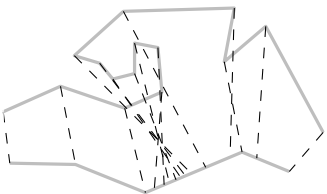
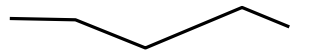
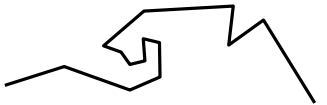
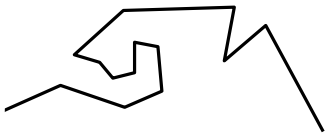
least-squares adjustment

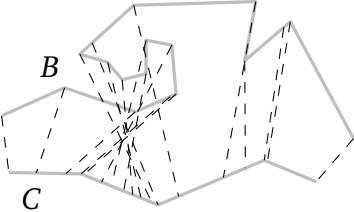
source

 $t = 0.25$ $t = 0.50$ $t = 0.75$

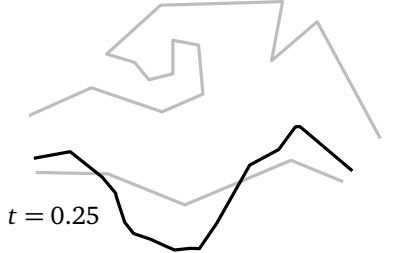
target

trajectories

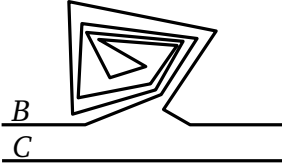




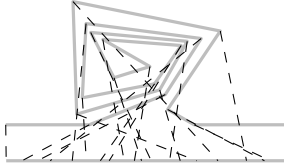
(a) corresponding vertices



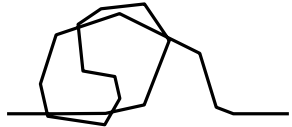
(b) morphing C to B at time $t=0.25$



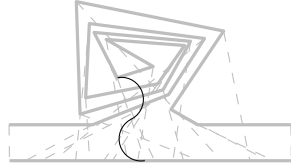
(a) two polylines



(b) corresponding vertices



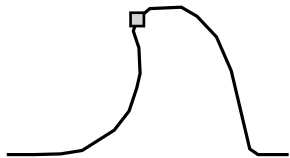
(c) output at time $t = 0.5$



(a) the extra pair of corresponding vertices



(b) $t = 0.83$, with extra corresponding vertices



(c) $t = 0.83$, without extra corresponding vertices