



$t = 0$



$t = 0.25$



$t = 0.5$

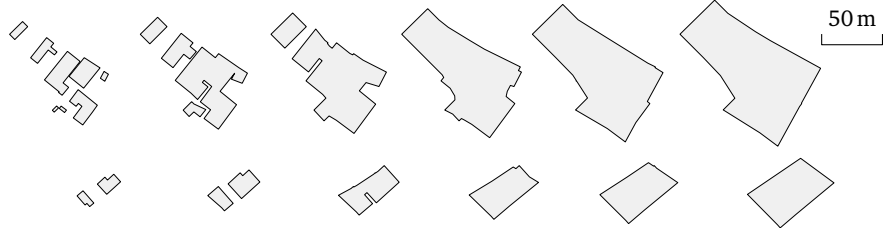


$t = 0.75$



$t = 1$

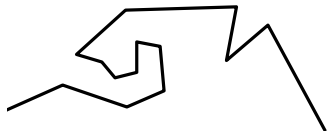
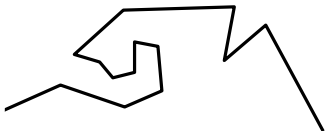
20 km
└─┘



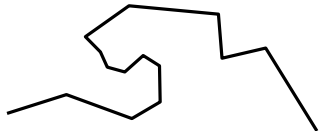
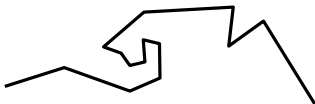
morphing based on
straight-line trajectories

morphing based on
least-squares adjustment

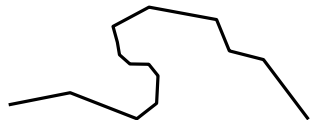
source



$t = 0.25$



$t = 0.50$



$t = 0.75$



target

