



$t = 0$



$t = 0.25$



$t = 0.5$

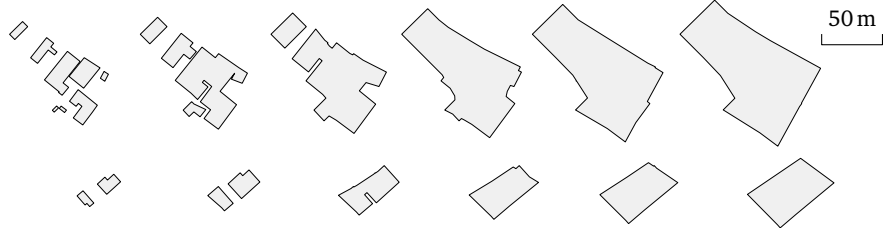


$t = 0.75$



$t = 1$

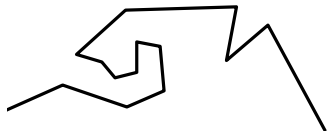
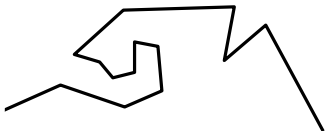
20 km
└─┘



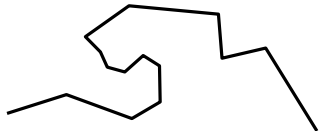
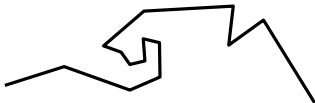
Morphing based on
straight-line trajectories

Morphing based on
least-squares adjustment

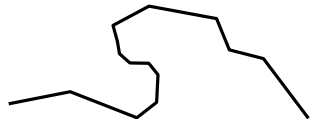
Source



$t = 0.25$



$t = 0.50$



$t = 0.75$



Target

