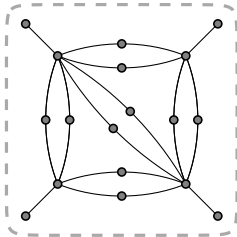
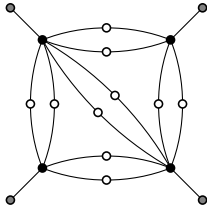
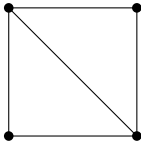


# PLANAR VERTEX COVER

# AREA AGGREGATION SEQUENCE



**(a)**  $G_A = (V_A, E_A)$

**(b)** Start map

**(c)** Goal map

