# 12. Matrix Factorization

# Cheng Peng

#### Lecture Note for MAT325 Numerical Analysis

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# 1 Introduction

In linear algebra, a matrix factorization is a factorization of a matrix into a product of matrices. There are differences in factorizing a matrix for different purposes. Among various ways of factorization, **lower-upper** (LU) factorization is the basic and is useful in solving linear systems. Although LU factorization works for any  $m \times n$  matrix, it is common to factorize square matrix. In this note, we only discuss LU for square matrices.

Let A be the  $n \times n$  matrix

$$A_{n \times n} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}$$

A is said to have a LU-decomposition if there exists matrices L and U with the following properties:

1. L is a  $n \times n$  lower triangular matrix with all diagonal entries being 1.

$$L_{n \times n} = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ l_{21} & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ l_{n1} & l_{n2} & \cdots & 1 \end{bmatrix}$$

2. U is a  $n \times n$  matrix in some echelon form.

$$U_{n \times n} = \begin{bmatrix} u_{11} & u_{12} & \cdots & u_{1n} \\ 0 & u_{22} & \cdots & u_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & u_{nn} \end{bmatrix}$$

3. A = LU.

$$A_{n\times n} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix} = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ l_{21} & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ l_{n1} & l_{n2} & \cdots & 1 \end{bmatrix} \times \begin{bmatrix} u_{11} & u_{12} & \cdots & u_{1n} \\ 0 & u_{22} & \cdots & u_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & u_{nn} \end{bmatrix} = L_{n\times n} \times U_{n\times n}$$

# 2 Elementary and Permutation Matrices

Any **elementary matrix**, which we often denote by E, is obtained from applying **one** row operation to the **identity matrix** of the same size.

**Examples** Consider the resulting matrices after row operations to the identity matrix.

1. Adding one row to the other row:  $R_1 + R_2 \rightarrow R_2$ 

$$E_1 = \left[ \begin{array}{rrr} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{array} \right]$$

2. Multiplying a scalar to a row:  $3 \times R2 \rightarrow R_2$ 

$$E_2 = \left[ \begin{array}{rrr} 1 & 0 & 0 \\ 1 & 3 & 0 \\ 0 & 0 & 1 \end{array} \right]$$

3. Multiplying a scalar to a Row and then adding it to the other row:  $5 \times R_1 + R_3 \rightarrow R_3$ 

$$E_3 = \left[ \begin{array}{rrr} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 5 & 0 & 1 \end{array} \right]$$

4. Switching two rows:  $R_1 \leftrightarrow R_2$ :

$$E_3 = \left[ \begin{array}{rrr} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{array} \right]$$

The elementary matrix obtained from switching two rows is commonly called **permutation matrix**.

To perform any of the first three row-operations on a matrix A, it suffices to take the product (left-multiplication)

# $E \times A$ , where E is the elementary matrix obtained by using the desired row operation on the identity matrix.

Note that row operations (row switching) were used in matrix inversion and triangulation.

**Example 1**: Consider the triangulation problem:

$$A = \left[ \begin{array}{rrr} 1 & 4 & 1 \\ 2 & 3 & 3 \\ 3 & 2 & 5 \end{array} \right]$$

**Solution**: The following three steps will complete the triangulation.

(1).  $-2 \times R_1 + R_2 \to R_2$ :

$$A = \begin{bmatrix} 1 & 4 & 1 \\ 2 & 3 & 3 \\ 3 & 2 & 5 \end{bmatrix} \xrightarrow{-2 \times R_1 + R_2 \to R_2} A_1 = \begin{bmatrix} 1 & 4 & 1 \\ 0 & -5 & 1 \\ 3 & 2 & 5 \end{bmatrix}, E_1 = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Note that

$$E_1 \times A = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 4 & 1 \\ 2 & 3 & 3 \\ 3 & 2 & 5 \end{bmatrix} = \begin{bmatrix} 1 & 4 & 1 \\ 0 & -5 & 1 \\ 3 & 2 & 5 \end{bmatrix}$$

(2).  $-3 \times R_1 + R_3 \to R_3$ :

$$A_{1} = \begin{bmatrix} 1 & 4 & 1 \\ 0 & -5 & 1 \\ 3 & 2 & 5 \end{bmatrix} \xrightarrow{-3 \times R_{1} + R_{3} \to R_{3}} A_{2} = \begin{bmatrix} 1 & 4 & 1 \\ 0 & -5 & 1 \\ 0 & -10 & 2 \end{bmatrix}, E_{2} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix}$$

Note also that

$$E_2 \times E_1 \times A = E_2 \times A_1 = \left[ \begin{array}{ccc} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{array} \right] \times \left[ \begin{array}{ccc} 1 & 4 & 1 \\ 0 & -5 & 1 \\ 3 & 2 & 5 \end{array} \right] \ = \ \left[ \begin{array}{ccc} 1 & 4 & 1 \\ 0 & -5 & 1 \\ 0 & -10 & 2 \end{array} \right] = A_2$$

(3).  $-2 \times R_1 + R_3 \to R_3$ :

$$A_2 = \begin{bmatrix} 1 & 4 & 1 \\ 0 & -5 & 1 \\ 0 & -10 & 2 \end{bmatrix} \xrightarrow{-3 \times R_1 + R_3 \to R_3} A_3 = \begin{bmatrix} 1 & 4 & 1 \\ 0 & -5 & 1 \\ 0 & 0 & 0 \end{bmatrix}, E_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix}$$

We note similarly that

$$E_3 \times E_2 \times E_1 \times A = E_3 \times A_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 4 & 1 \\ 0 & -5 & 1 \\ 0 & -10 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 4 & 1 \\ 0 & -5 & 1 \\ 0 & 0 & 0 \end{bmatrix} = A_3$$

Next, we look at the product of the three (lower angular) elementary matrices.

$$E = E_3 \times E_2 \times E_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 1 & -2 & 1 \end{bmatrix}$$

Several important observations help develop algorithms to perform the LU factorization.

- 1. All elementary matrices that are based on the forward row operations (NOT the row-swapping) are lower triangular matrices (and are obviously non-singular).
- 2. The product of all **lower triangular matrices** will also be a **lower triangular matrix**. This can easily be proved by the definition of matrix multiplication.
- 3. The product of elementary matrices is **non-singular** (i.e., the determinant is NOT equal to zero).
- 4. The inverse of a **lower triangular matrix** (if exists) is also a lower triangular. This is also obvious from the process of finding the inverse of a function

In the above example,  $A_3$  is an upper triangular matrix (special echelon form). We now rewrite the row operations in the following

$$E \times A = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 1 & -2 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 4 & 1 \\ 2 & 3 & 3 \\ 3 & 2 & 5 \end{bmatrix} = \begin{bmatrix} 1 & 4 & 1 \\ 0 & -5 & 1 \\ 0 & 0 & 0 \end{bmatrix} = A_3$$

This implies that

$$A = \begin{bmatrix} 1 & 4 & 1 \\ 2 & 3 & 3 \\ 3 & 2 & 5 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 1 & -2 & 1 \end{bmatrix}^{-1} \times \begin{bmatrix} 1 & 4 & 1 \\ 0 & -5 & 1 \\ 0 & 0 & 0 \end{bmatrix} = E^{-1} \times A_3$$

Let  $L = E^{-1}$  (lower triangular matrix) and  $U = A_3$ . Then A = LU! For a  $3 \times 3$  matrix, we need to perform 3(3-1)/2 = 3 row operations, which means, we need to take the product 3 elementary matrices to obtain the upper triangular matrix  $A_3$ . The calculation of E is tedious and time-consuming. However, we can use the R function Gauss. Elimination() on an arguments matrix to get E.

$$\begin{bmatrix} 1 & 4 & 1 & \vdots & 1 & 0 & 0 \\ 2 & 3 & 3 & \vdots & 0 & 1 & 0 \\ 3 & 2 & 5 & \vdots & 0 & 0 & 1 \end{bmatrix} \xrightarrow{\text{Gaussian Row Elimination}} \begin{bmatrix} 1 & 4 & 1 & \vdots & 1 & 0 & 0 \\ 0 & -5 & 1 & \vdots & -2 & 1 & 0 \\ 0 & 0 & 0 & \vdots & 1 & -2 & 1 \end{bmatrix}$$

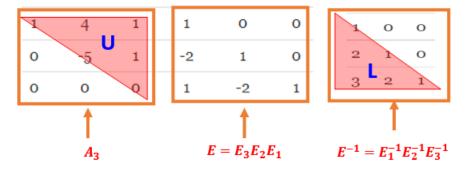
Using the code we developed in the earlier note to find the  $E = E_3 E_2 E_1$  (order is important!)

```
id = intersect(non.0, (i+1):n)[1] # vector of common row ID in the
                                                # lower triangular part of the matrix.
             if(!is.na(id)){
                                  # if the common vector is not empty, do row-swapping!
             tempi = AO[i,]
                                                # put the i-th row in a place-holder
             AO[i,] = AO[id,]
                                                # row swapping
             AO[id,] = tempi
             ###
                                                # updating permutation matrix
             \#tempP = P[i,]
             \#P[i,] = P[id,]
             \#P[id,] = tempP
      }
     #~~
      if(A0[i,i] != 0){
                           # AO[i,i] is in the denominator of recursive equation
         for(j in (i+1):n){  # to make the augmented matrix in the row echelon form
            \#cat("\n\n j =", j, ".")
            AO[j,] = AO[j,] - (AO[j,i]/AO[i,i])*AO[i,]
      }
     }
  ΑO
}
```

A=matrix(c(1,4,1,2,3,3,3,2,5), nrow=3, byrow = TRUE) Gauss.Elimination(A=A)

```
[,1] [,2] [,3] [,4] [,5] [,6]
##
## [1,]
           1
                4
                         1
                               0
                     1
## [2,]
           0
                         -2
                               1
                                    0
               -5
                     1
## [3,]
                              -2
           0
               0
                     0
                          1
```

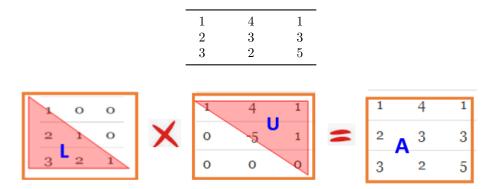
pander(LU)



```
A=matrix(c(1,4,1,2,3,3,3,2,5), nrow=3, byrow = TRUE)
B=cbind(A, diag(rep(1,3)))
C = Gauss.Elimination(B)
U = C[,1:3]
L = solve(C[,4:6])
LU = L%*%U
```

1	4	1
2	3	3
3	2	5

pander(A)



# 3 LU Factorization Algorithm

It took three elementary row operations to obtain the lower triangular matrix in the above special 3times3 matrix. In general, for an  $n \times n$  matrix, we need n(n-1)/2 forward row operations (excluding row-swapping) to get the upper triangular matrix.

# 3.1 Row Operations with Row Swapping

As explained in the illustrative example, we can apply the Gaussian elimination method to the extended augmented matrix to obtain the product of the elementary matrices induced from the corresponding row operations if no row-swapping is involved. To be more specific, let

$$A_{n \times n} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix},$$

we define an extended augmented matrix in the following

$$A_{n\times n}^{0} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} & | & 1 & 0 & \cdots & 0 \\ a_{21} & a_{22} & \cdots & a_{2n} & | & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots & | & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} & | & 0 & 0 & \cdots & 1 \end{bmatrix},$$

After finishing the Gaussian elimination, we have upper triangular and lower triangular matrices that are similar to those in the example.

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# 3.2 Row Operations with Row-swapping

When the row operation involves row-swapping (permutations), say,  $P_1, P_2, \dots, P_k$ , we need to calculate  $P = P_k \times P_{k-1} \times \dots \times P_2 \times P_1$ . Then we can apply the Gaussian elimination to PA to factorize it into the product of an upper triangular matrix and a lower triangular matrix.

Note that, the linear system AX = B is equivalent to linear system PAX = B since P involves only row-swapping.

#### Properties of Permutation Matrix. Let P be a permutation matrix, then

- 1. The inverse of P exists.
- 2. The inverse of P is equal to the transpose of P.  $P^{-1} = P^{T}$ .

## 3.3 LU ALgorithm

```
INPUT: The input n-by-m matrix A
OUTPUT: L, U, P (if P = I, no permutation involved)
STEP 1: Initialization:
       n = \#rows,
        AO = [A,I]
                         (extended augmented matrix)
                         (n-by-n)
        P = I
STEP 2: FOR i = 1 TO n DO:
                               (running through pivot elements)
        STEP 3: IF A[i,i] = 0 for some i DO:
                row-swapping and updating P
                ENDIF
        STEP 4: FOR j = 1 TO n DO:
                AO[j,] = AO[j,] - (AO[j,i]/AO[i,i])*AO[i,]
                ENDFOR
        ENDFOR
STEP 5: Extract P, U = AO[,1:n], L = inverse of AO[, (n+1):2n]
STEP 6: RETURN A, P, PA, L, U.
```

#### R function for LU factorization

```
LU = function(A){
 # Input A: an n-by-m matrix
 n = dim(A)[1]
                     # number of rows
 A0 = cbind(A, diag(rep(1,n))) # Extended augmented matrix
 P = diag(rep(1,n)) # identity matrix for permutation
 for(i in 1:(n-1)){
                     # iterator fo pivot element AO[i,i]
                     # i = 1, 2, \ldots, n-1
        #-----#
       if(AO[i,i] == 0){
          non.0 = which(AO[,i] != 0)
                                    # which() equiv to find() in MATLAB
            \#cat("\n\n\ i =",i, ", non.0 =", non.0,". (i+1):n =", (i+1):n, ".")
            id = intersect(non.0, (i+1):n)[1] # vector of common row ID in the
                                          # lower triangular part of the matrix.
```

```
if(!is.na(id)){  # if the common vector is not empty, do row-swapping!
             tempi = AO[i,]
                                               # put the i-th row in a place-holder
             AO[i,] = AO[id,]
                                               # row swapping
             AO[id,] = tempi
             ###
                                               # updating permutation matrix
             tempP = P[i,]
             P[i,] = P[id,]
             P[id,] = tempP
           }
          }
       if (AO[i,i] != 0) { # AO[i,i] is in the denominator of recursive equation
       for(j in (i+1):n){ # to make the augmented matrix in the row echelon form
            \#cat("\n\n j =", j, ".")
            AO[j,] = AO[j,] - (AO[j,i]/AO[i,i])*AO[i,]
       }
   }
 PA = P%*%A
 U = AO[,1:n]
 L = solve(A0[, (n+1):(2*n)])
  A = A
 list(A = A, P = P, PA = PA, L = L, U = U)
}
```

#### Example 2

## [4,]

##

0

0 -1

1

```
A=matrix(c(0,0,-1, 1, 1, 1, -1, 2, -1, -1, 2, 0, 1, 2, 0, 2), ncol = 4, byrow = TRUE)
P = matrix(c(0,1,0,0,0,0,0,1,0,0,1,0,1,0,0,0), ncol = 4, byrow = TRUE)
LU(A)
## $A
        [,1] [,2] [,3] [,4]
## [1,]
        0
              0
                  -1
## [2,]
          1
                1
                    -1
                          0
## [3,]
         -1
               -1
                     2
## [4,]
          1
               2
##
## $P
##
        [,1] [,2] [,3] [,4]
## [1,]
           0
               1
                     0
## [2,]
           0
                0
                     0
                          1
## [3,]
                          0
           0
                0
                     1
## [4,]
           1
                0
                     0
                          0
##
## $PA
##
        [,1] [,2] [,3] [,4]
                          2
## [1,]
          1
               1
                   -1
## [2,]
           1
                2
                    0
                          2
## [3,]
         -1
               -1
                    2
                          0
```

```
## $L
##
         [,1] [,2] [,3] [,4]
##
   [1,]
                        -1
   [2,]
             1
                               0
                   0
                         0
##
##
   [3,]
            -1
                   0
                         1
                               0
   [4,]
             1
                   1
                         0
                               0
##
##
## $U
         [,1] [,2] [,3] [,4]
##
##
   [1,]
             1
                   1
                        -1
   [2,]
             0
                   1
                         1
                               0
             0
                   0
                               2
   [3,]
##
                         1
             0
                               3
   [4,]
                         0
```

# 4 Benefit of LU Factorization

Suppose that A has been factored into the triangular form A = LU, where L is lower triangular and U is upper triangular. Then we can solve for x more easily by using a two-step process.

- Let y = Ux and solve the lower triangular system Ly = b for y. Since L is triangular, determining y from this equation requires only  $O(n^2)$  operations.
- Once y is known, the upper triangular system Ux = y requires only an additional  $O(n^2)$  operations to determine the solution x.

Solving a linear system Ax = b in factored form means that the number of operations needed to solve the system Ax = b is reduced from  $O(n^3/3)$  to  $O(2n^2)$ .

# 5 Chapter 6 HW: Part II

6.5.1 1(a).

6.5.7(b) and (d): Using the code in the note or writing your code to solve these two linear systems.

6.5.9 (a) and (c): Using the code in the note or writing your code to factorize these two matrices.