



AIM: Towards an Autonomous AI Mathematician

Peng Li

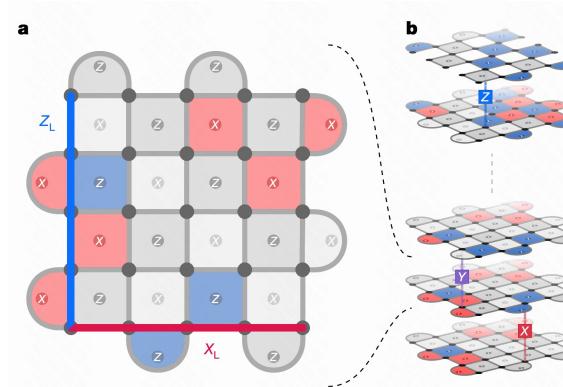
Institute for AI Industry Research (AIR)
Tsinghua University

AI and Scientific Research



清华大学
Tsinghua University

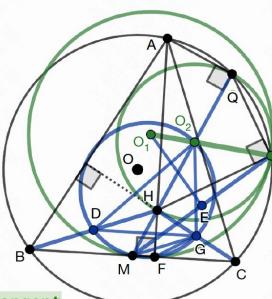
- AI has significantly accelerated scientific progress.



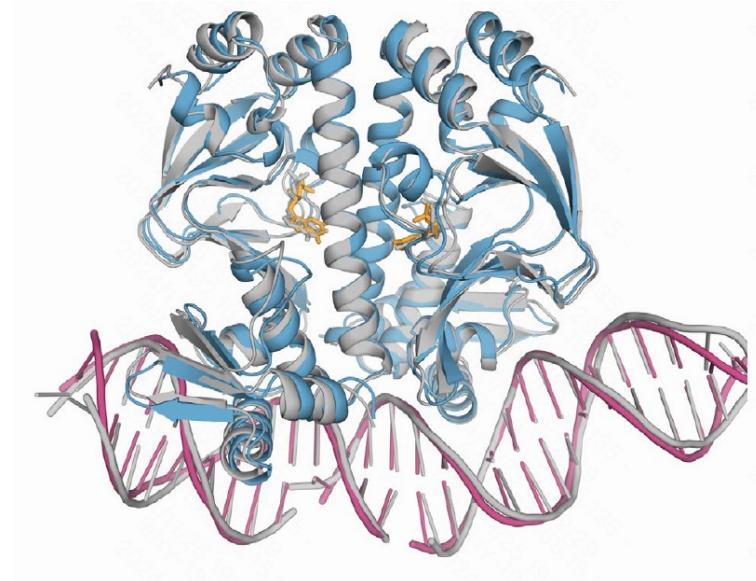
AlphaQuant

Solution

Construct D: midpoint BH [a]
[a], O_2 midpoint HQ $\Rightarrow BQ \parallel O_2D$ [20]
...
Construct G: midpoint HC [b] ...
 $\angle GMD = \angle GO_2D \Rightarrow M O_2 G D$ cyclic [26]
...
[a], [b] $\Rightarrow BC \parallel DG$ [30]
...
Construct E: midpoint MK [c]
..., [c] $\Rightarrow \angle KFC = \angle KO_1E$ [104]
...
 $\angle FKO_1 = \angle FKO_2 \Rightarrow K_1 \parallel K_2$ [109]
[109] $\Rightarrow O_0K$ collinear $\Rightarrow (O_1)(O_2)$ tangent



AlphaGeometry



AlphaFold

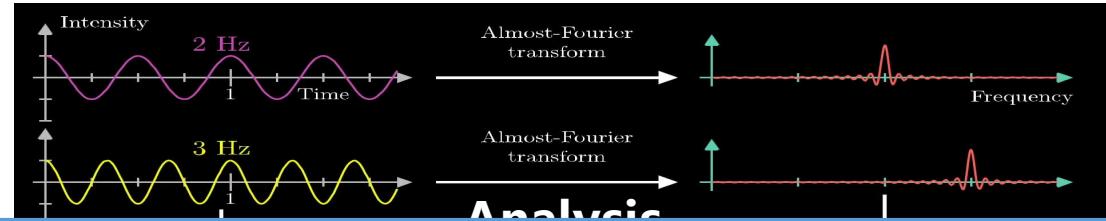
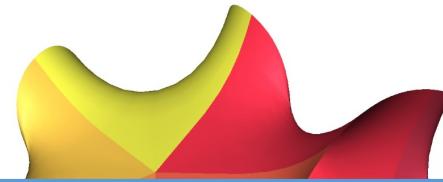
<https://www.nobelprize.org/all-nobel-prizes-2024/>
<https://www.nature.com/articles/s41586-024-07487-w>
<https://www.nature.com/articles/s41586-024-08148-8>
<https://www.nature.com/articles/s41586-023-06747-5>

The Power of Math Research

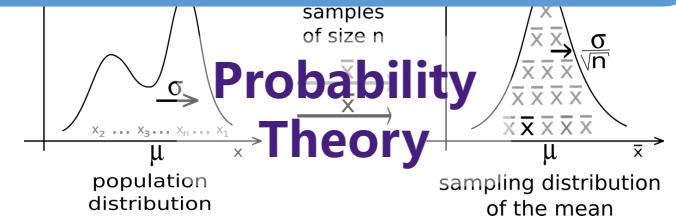
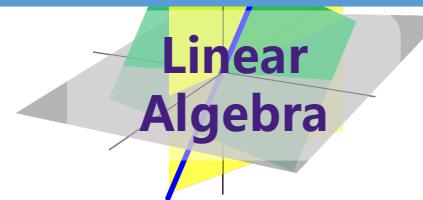
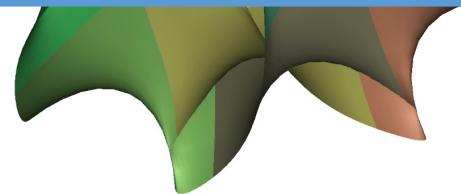


清华大学
Tsinghua University

- Mathematical research carries both deep theoretical and practical value, representing the pinnacle of human intellect.



What sparks when AI meets mathematics?



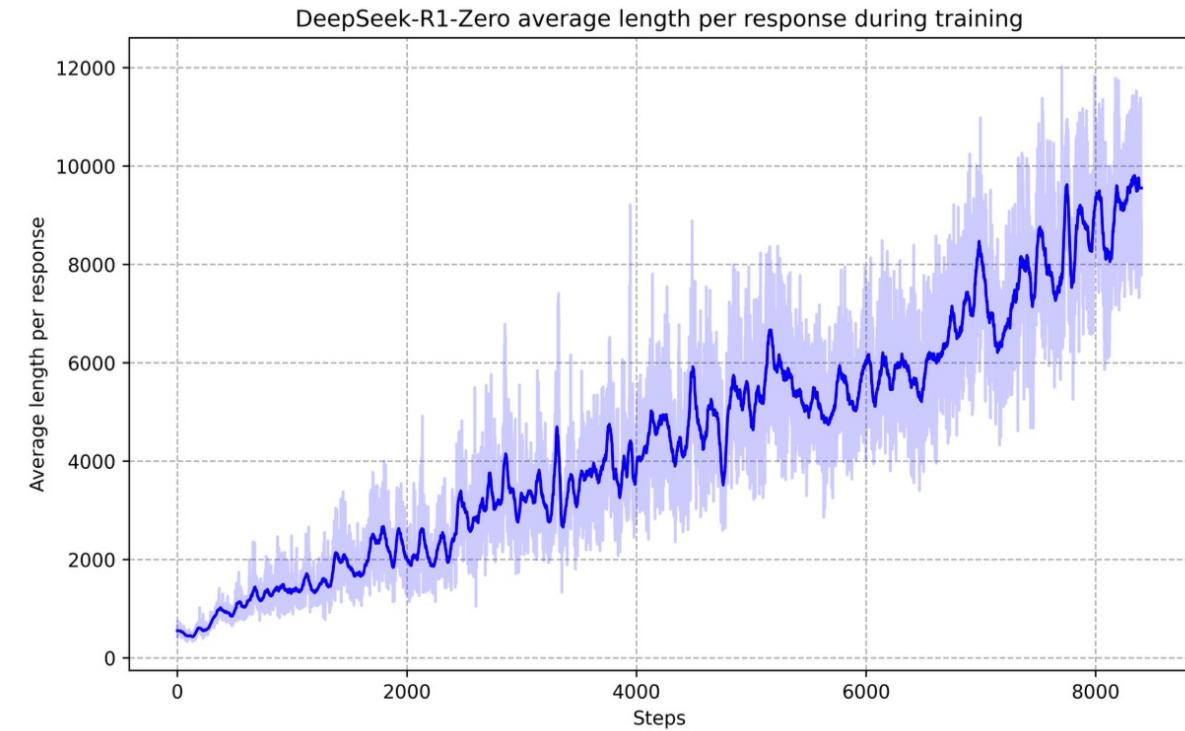
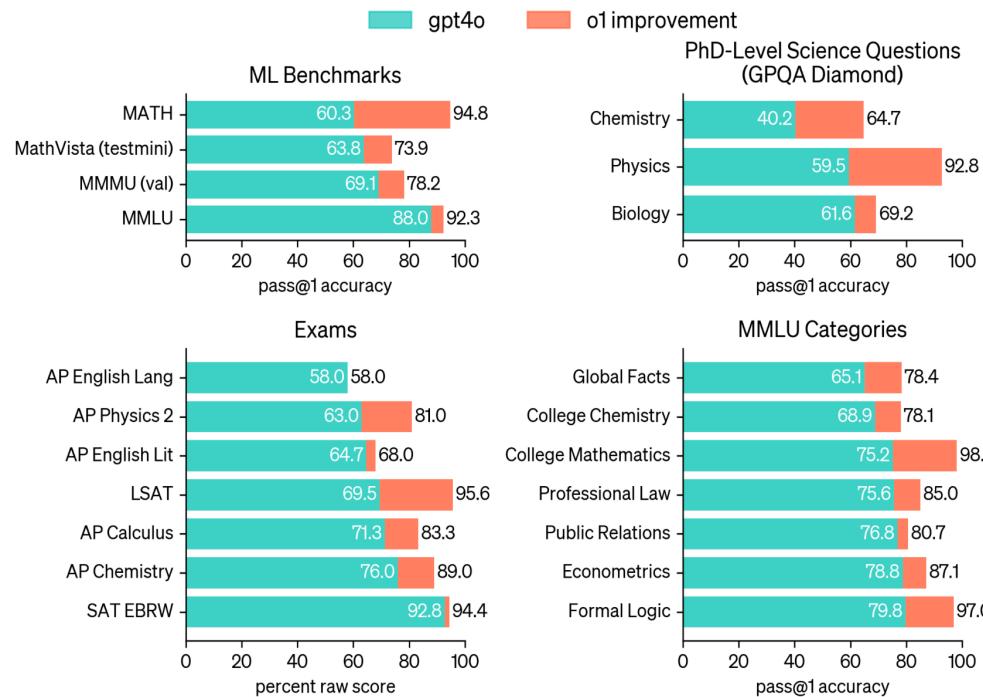
In pursuit of truth and elegance
in nature.

The theoretical foundation
for science and engineering.

Math4AI: A Critical Factor



- Mathematics and code data are now key to advancing the reasoning abilities of large language models.



o1: The first reasoning model trained on math/code tasks, showing across-the-board improvements.

DeepSeek-R1 gains deep reasoning via verifiable math-focused RL training.

AI4Math: Approaching the Peak



- By 2025, top models are projected to score 145/150 on Gaokao math.

Lack of sufficient image understanding capabilities leads to point loss

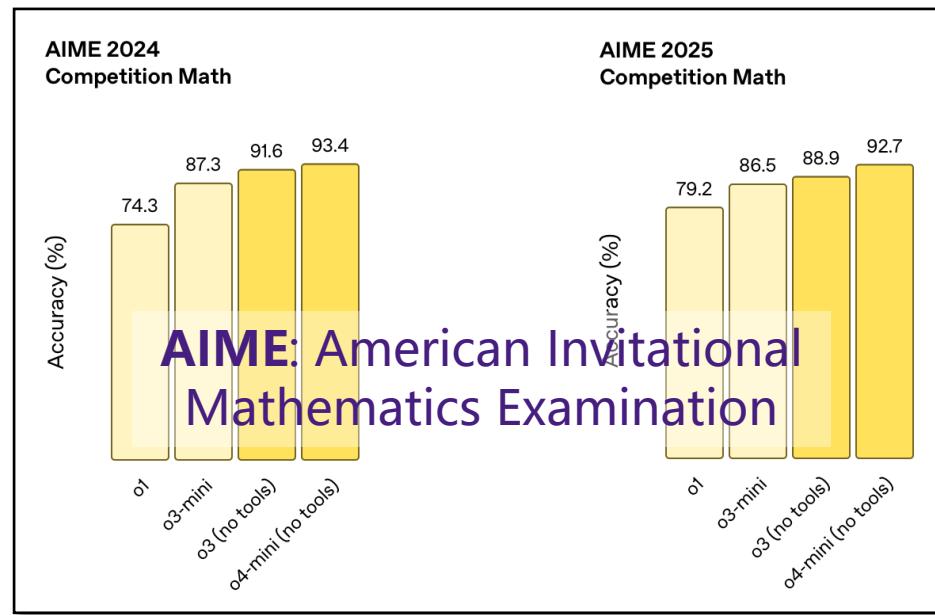
Model	Objective Questions (Text Input)	Single-choice Image Questions	Subjective Questions	Total
Gemini 2.5 pro	68	0	77	145
Doubao-1.5-thinking-vision-pro	68	0	76	144
DeepSeek R1	68	/	76	144
o3	65	0	75	140
Qwen3-235b	68	/	71	139
hunyuan-t1-latest	68	/	68	136
Wenxin X1 Turbo	68	/	66	134

Note: This evaluation consists of three parts: objective questions (text input), Question 6 which is an image-based single-choice question, and subjective questions. The objective questions (text input) section accounts for a total of 68 points, the image-based single-choice question is worth 5 points, and the subjective questions total 77 points. The overall score is 150 points.

AI4Math: Approaching the Peak

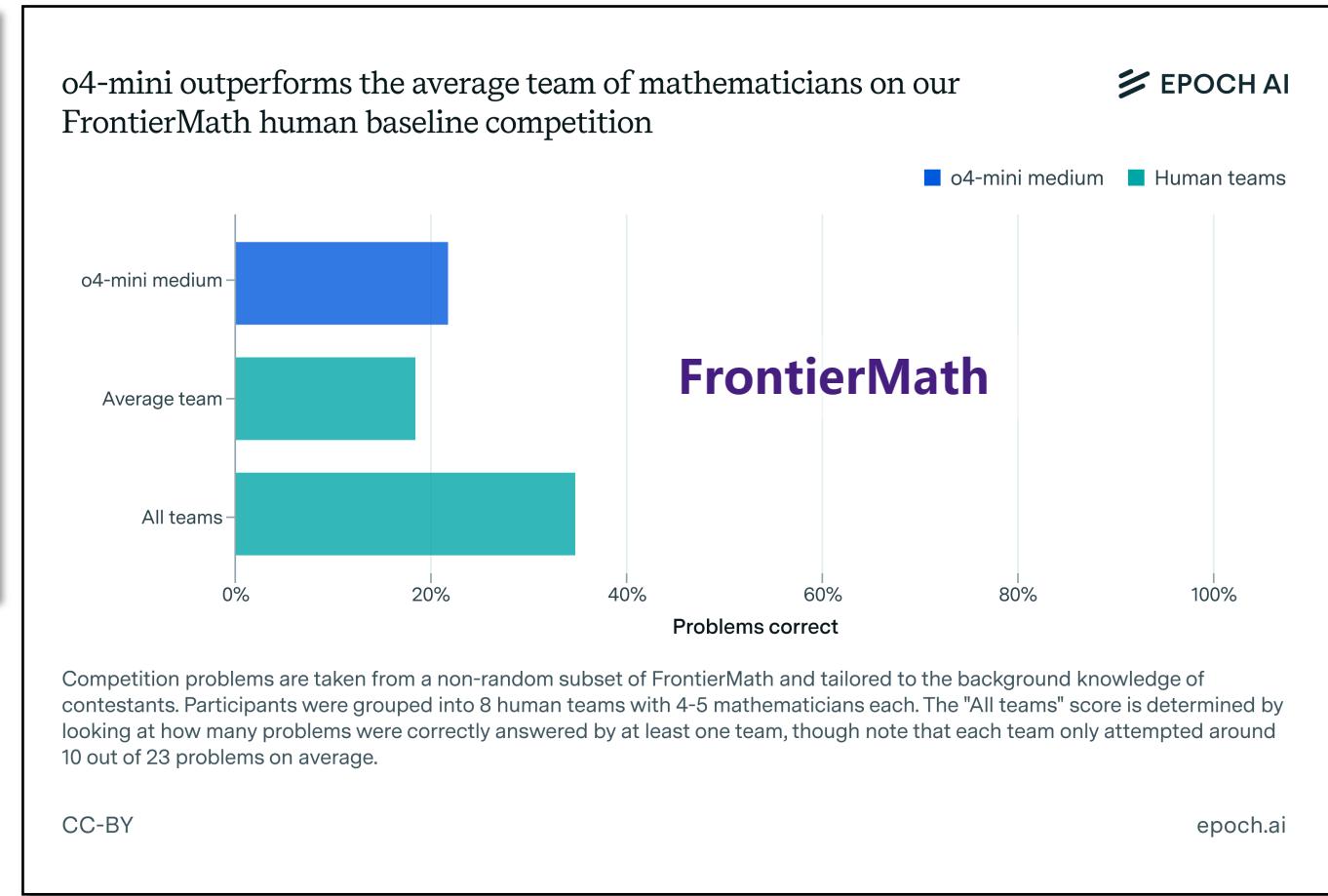


- o4-mini achieves expert-level proficiency on frontier math datasets.



I don't want to add to the hysteria, but in some ways these large language models are already outperforming most of our best graduate students in the world.

-- Ken Ono



AIME: High School Competition



- The AIME dataset derives from a competition (AIME) for high school students that helps select the U.S. team for the IMO.

Problem Structure

- 15 progressively difficult problems
- Answers are integers from 0-999

Limitations

- Predetermined unique solutions
- Focuses primarily on "small" techniques

Problem

The 9 members of a baseball team went to an ice-cream parlor after their game. Each player had a single scoop cone of chocolate, vanilla, or strawberry ice cream. At least one player chose each flavor, and the number of players who chose chocolate was greater than the number of players who chose vanilla, which was greater than the number of players who chose strawberry. Let N be the number of different assignments of flavors to players that meet these conditions. Find the remainder when N is divided by 1000.

Solution 1

Let c be the number of players who choose chocolate, v be the number of players who choose vanilla, and s be the number of players who choose strawberry ice cream. We are given two pieces of information $c, v, s \geq 1$ and $c + v + s = 9$.

By inspection the only solutions for (c, v, s) are $(2, 3, 4), (1, 2, 6), (1, 3, 5)$.

Now we must choose which player chooses which flavor. For the general case (c, v, s) , we begin by choose c of the 9 players who eat chocolate, then we choose v of the $9 - c$ players who eat vanilla, after this the amount of players who eat strawberry is fixed. Therefore the general formula is $\binom{9}{c} \binom{9-c}{v}$.

Therefore our final answer is,

$$\binom{9}{2} \binom{7}{3} + \binom{9}{1} \binom{8}{2} + \binom{9}{1} \binom{8}{3} = 2\boxed{016}.$$

The Challenging FrontierMath



- Authored and endorsed by professional mathematicians (including Terence Tao), FrontierMath exhibits extremely high difficulty.

Core Features

- Authored by professional mathematicians
- Spans major modern mathematical branches
- Requires hours per problem for specialists

Limitations

- Predetermined solutions
- Complexity ceiling below research-grade problems

Construct a degree 19 polynomial $p(x) \in \mathbb{C}[x]$ such that $X := \{p(x) = p(y)\} \subset \mathbb{P}^1 \times \mathbb{P}^1$ has at least 3 (but not all linear) irreducible components over \mathbb{C} . Choose $p(x)$ to be odd, monic, have real coefficients and linear coefficient -19 and calculate $p(19)$.

Answer: 1876572071974094803391179

MSC classification: 14 Algebraic geometry; 20 Group theory and generalizations; 11 Number theory generalizations

Competition v.s. Research



清华大学
Tsinghua University

Key 1: Long Reasoning

Math research requires significantly longer and deeper reasoning.

Volume estimates for unions of convex sets, and the Kakeya set conjecture in three dimensions

Hong Wang* Joshua Zahl †
February 26, 2025

Abstract
We study sets of δ tubes in \mathbb{R}^3 , with the property that not too many inside a common convex set V . We show that the union of tubes from almost maximal volume. As a consequence, we prove that every Kakeya and Hausdorff dimension 3.

Contents	
1	Introduction
1.1	Theorem 1.2 and multi-scale analysis
1.2	Unions of convex sets, and non-clustering
1.3	From Assertions \mathcal{D} and \mathcal{E} to the Kakeya set conjecture
1.4	Proof philosophy, and previous work on the Kakeya set conjecture
1.5	A vignette of the proof
1.6	Tube doubling and Keleti's line segment extension conjecture
1.7	Thanks
2	A sketch of the proof
2.1	Proposition 1.6: Assertions \mathcal{D} and \mathcal{E} are equivalent
2.2	A two-scale grains decomposition
2.3	Refined induction on scales
2.4	Multi-scale structure, Nikishin-Stein-Pisier factorization, and Sticky Kakeya
3	Notation
3.1	Convex sets and shadings
3.2	Table of notation

*Courant Institute of Mathematical Sciences, New York University. New York, NY, USA.
†Department of Mathematics, The University of British Columbia. Vancouver, BC, Canada.

4	Wolff Axioms and Factoring Convex Sets	25
4.1	Definitions: Wolff axioms and covers	25
4.2	Factoring Convex Sets	26
4.3	Convex Sets and the Frostman Slab Wolff Axioms	31
4.4	The Frostman Slab Wolff Axioms and Covers	
5	Factoring tubes into flat prisms	
5.1	A few frequently used Cordoba-type L^2 arguments	
5.1.1	A volume estimate for slabs	
5.1.2	Tangential vs transverse prism intersection	
5.2	Assertions \mathcal{F} , \mathcal{E} , and $\tilde{\mathcal{E}}$ are equivalent	
5.3	Proof of Proposition 5.1: Tubes that factor through flat boxes	
5.4	Proof of Proposition 5.2: Factoring at two scales	
5.5	Tubes organized into slabs	
6	Assertions \mathcal{D} and \mathcal{E} are equivalent	
6.1	Proof of Proposition 6.3: A factoring trichotomy	
7	A two-scale grains decomposition for tubes in \mathbb{R}^3	60
7.1	Broadness	63
7.2	Broadness and the Frostman Slab Wolff axioms	66
7.3	The iteration base case: Guth's grains decomposition	69
7.4	Moves #1, #2, #3: Parallel structure	70
7.5	Using Moves #1, #2, #3 to prove Proposition 7.5	72
8	Moves #1, #2, and #3	74
8.1	Move #1: Replacing grains with longer grains to ensure $c \geq \delta^{\zeta_p} (\#\mathbb{T}_p) / (\#\mathbb{T})$	74
8.2	Move #2: Replacing square grains with longer grains	74
8.3	Move #3: Replacing grains with wider grains with small C_{KT-CW}^{loc}	85
9	A refined induction-on-scales argument	100
10	Sticky Kakeya for tubes satisfying the Katz-Tao Convex Wolff Axioms at every Scale	103
10.1	Nikishin-Stein-Pisier Factorization and the Convex Wolff Axioms	105
11	Multi-scale analysis and the proof of Proposition 1.7	110
12	Tube Doubling	114

Competition v.s. Research



清华大学
Tsinghua University

Key 2: Procedural Rigor

Zero tolerance for errors. Verification is mandatory yet exceptionally costly

Hence if $\mathcal{W}' \subset \mathcal{W}_0$, to compare $\#\left(\bigcup_{W_i \in \mathcal{W}'} \mathcal{U}_0[W_i]\right)$ and $\sum_{W_i \in \mathcal{W}'} \#\mathcal{U}_0[W_i]$,

$$\begin{aligned} \kappa_0 \frac{C_{KT-CW}(\mathcal{U}_0)}{|U|} \sum_{W_i \in \mathcal{W}'} |W_i| &\leq \sum_{W_i \in \mathcal{W}'} \#\mathcal{U}_{i-1}[W_i] = \#\left(\bigsqcup_{W_i \in \mathcal{W}'} \mathcal{U}_{i-1}[W_i]\right) \\ &\leq \#\left(\bigcup_{W_i \in \mathcal{W}'} \mathcal{U}_0[W_i]\right) \leq \sum_{W_i \in \mathcal{W}'} \#\mathcal{U}_0[W_i] \leq \frac{C_{KT-CW}(\mathcal{U}_0)}{|U|} \sum_{W_i \in \mathcal{W}'} |W_i|. \end{aligned} \quad (4.12)$$

A proof fragment of
the 3D Kakeya Set
Conjecture

The equality in (4.12) uses the critical fact that if $i \neq i'$, then $\mathcal{U}_{i-1}[W_i]$ and $\mathcal{U}_{i'-1}[W_{i'}]$ are disjoint.

Case	Validating Process	Duration
Fermat's Last Theorem	The initial proof was presented in 1993, and then a flaw was identified after scrutinized by top mathematicians. The revised proof was finally published in 1995.	~2 years
Poincaré Conjecture	The proof was released in three preprints, and was finally validated by the collaborative effort by geometers and topologists.	~4-5 years

Competition v.s. Research

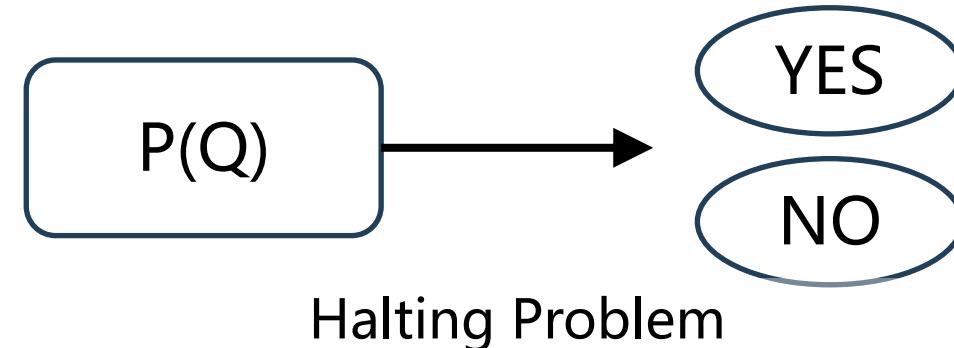


清华大学
Tsinghua University

Key 3: Answer Existence

Competition problems have **known** and **determined** answers

The answers of research problems are **unknown** and **undetermined**



Kurt Gödel

Gödel's First Incompleteness Theorem:

In any consistent formal system that is strong enough to express basic arithmetic, there will always be true statements that the system cannot prove. The system is inherently incomplete.

Gödel's Second Incompleteness Theorem:

Such a system cannot prove its own consistency from within. To establish its consistency, we must rely on methods outside the system.

AI4Math: Formal Proving



清华大学
Tsinghua University

- **Formal proof systems have evolved through decades of research, with institutions worldwide - including DeepSeek and ByteDance - actively advancing this field.**

Pros

- Provides certain symbolic automation
- Guarantees absolute rigor via machine verification

Cons

- Faces severe performance bottlenecks
- Hard to be applied to general research level problems

The screenshot shows a comparison between two theorem provers for a specific mathematical problem:

Lean THEOREM PROVER

```
theorem induction_ineq_nsqlefactn (n : N) (h0 : 4 ≤ n) : n ^ 2 ≤ n ! := sorry
```

Understanding the Problem
We need to show that for any integer $n \geq 4$, the inequality $n^2 \leq n!$ holds. Here, $n!$ denotes the factorial of n , which is the product of all positive integers up to n .

Proof Sketch
To prove this formally, we can use mathematical induction. Here's how the induction would work:
1. **Base Case:** Verify the inequality for $n = 4$.
2. **Inductive Step:** Assume the inequality holds for some $k = 4$, i.e., $k^2 \leq k!$. Then show that it holds for $k + 1$, i.e., $(k + 1)^2 \leq (k + 1)!$.

chain-of-thought by DeepSeek-V3

Lean 4 Proof Structure

```
theorem induction_ineq_nsqlefactn (n : N) (h0 : 4 ≤ n) : n ^ 2 ≤ n ! := by
  have base_case : 4 ^ 2 ≤ 4 ! := by
    sorry
  have inductive_step : ∀ k ≥ 4, k ^ 2 ≤ k ! → (k + 1) ^ 2 ≤ (k + 1) ! := by
    sorry
  have final_proof : ∀ n ≥ 4, n ^ 2 ≤ n ! := by
    sorry
    sorry
```

DeepSeek-Prover-V2-7B

```
lemma inductive_step (n : N) (h0 : 4 ≤ n) (base_case : 4 ^ 2 ≤ 4 !) :
  ∀ k ≥ 4, k ^ 2 ≤ k ! → (k + 1) ^ 2 ≤ (k + 1) ! := by
  sorry
```

Synthesize into Complete Formal Proofs

```
theorem induction_ineq_nsqlefactn (n : N) (h0 : 4 ≤ n) : n ^ 2 ≤ n ! := by
  have base_case : 4 ^ 2 ≤ 4 ! := by
    simp [Nat.factorial]
  have inductive_step : ∀ k ≥ 4, k ^ 2 ≤ k ! → (k + 1) ^ 2 ≤ (k + 1) ! := by
    intro k h1 h2
    simp_all [Nat.factorial]
    nlinarith
  have final_proof : ∀ n ≥ 4, n ^ 2 ≤ n ! := by
    intro n hn
    induction' hn with k hk
    case refl => exact base_case
    case step =>
      apply inductive_step k hk
      exact by assumption
    apply final_proof
    exact h0
```

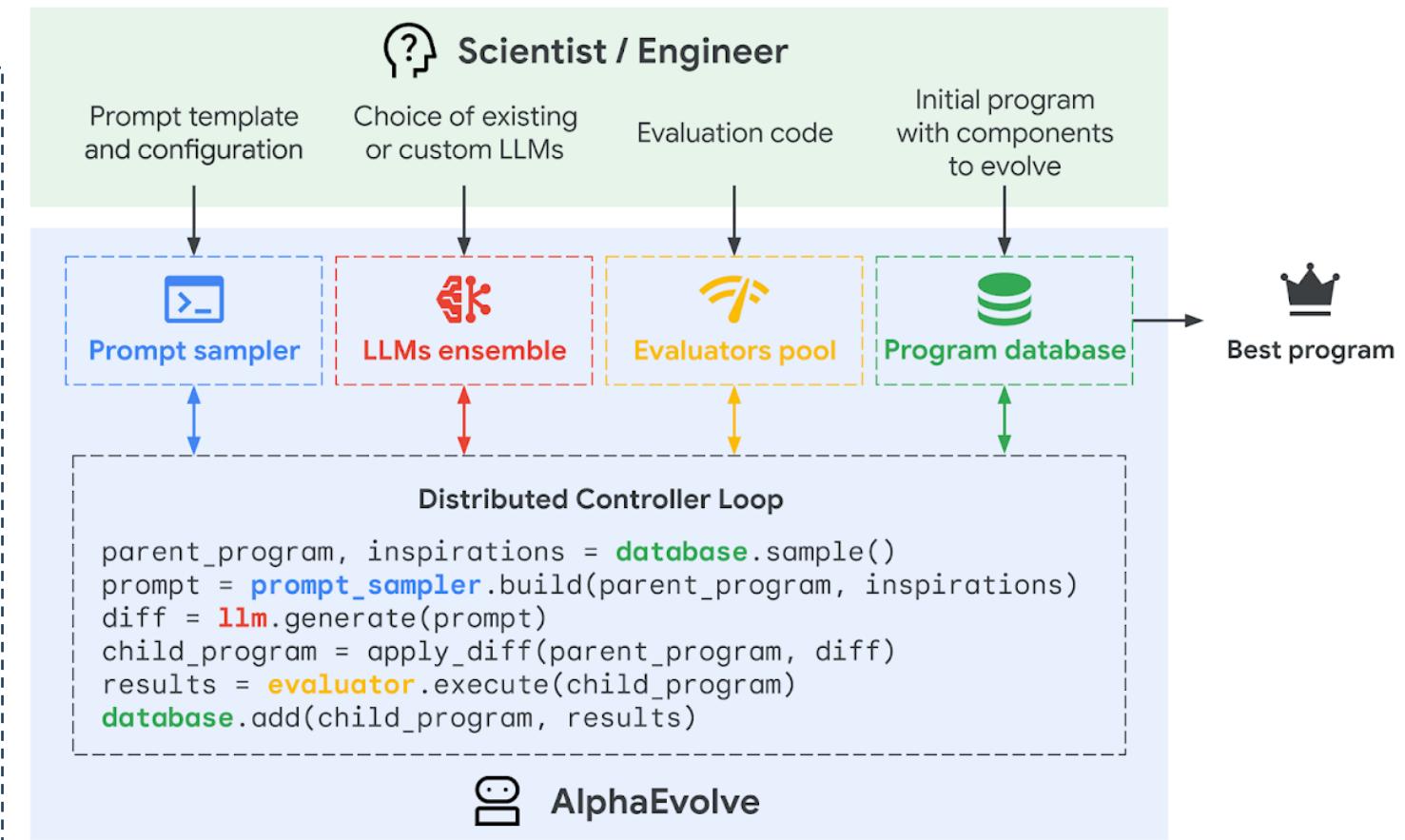
AI4Math: Coding Agent



- Recent studies have begun exploring the potential of using large language models to perform mathematical research tasks.

AlphaEvolve

- Origin:** Launched by Google DeepMind on May 14, 2025
- Nature:** An agent system specialized in algorithmic optimization
- Achievement:** Demonstrated capacity for independent novel discoveries
- Limitation:** Limited to problems amenable to code



AIM: AI Mathematician



清华大学
Tsinghua University

● AIM represents an important step towards automated math research

Competition

- Short reasoning
- Rigor requirement is easily satisfied
- Known existence of the answer
- Deterministic



Research

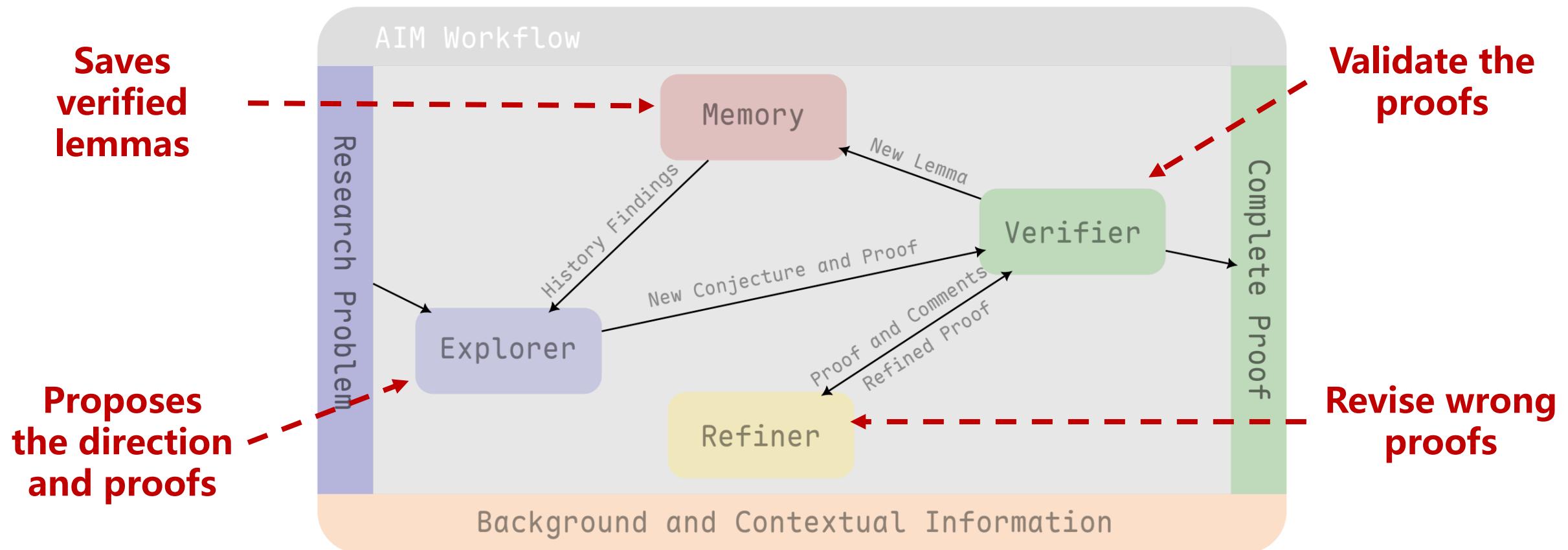
- Long reasoning
- Rigor requirement is hardly satisfied
- Unknown existence of the answer
- Indeterministic

Research Problem	Results of AIM	Selected Proof Steps
Quantum Algorithm Problem (Settled Problem)	AIM effectively completes the problem with a detailed solution process	<p>Multiplied through by $x^{(T-2)}$, cancel terms, and simplify:</p> $\frac{\pi^2}{2} \partial_x U = \frac{\pi^2}{2} \partial_x^2 V \Rightarrow 0 \iff \partial_x U = \partial_x^2 V.$ <p>**Step 2: Spatial Discretization** Discretize ∂_x on a grid with spacing Δx. Approximate ∂_x^2 via finite differences:</p> $\frac{\partial_x^2 u_i}{\Delta x^2} \approx \frac{u_{i+1} - 2u_i + u_{i-1}}{\Delta x^2}.$ <p>Let D_2 be the discretized second derivative matrix. Then $\partial_x = D_2$. The operator becomes:</p> $B = I - D_2.$ <p>**Step 3: Positive Semi-Definite Operator** The matrix $B = D_2$ is positive semi-definite because D_2 is a centred second derivative discretization of a negative definite operator ∂_x^2 along with the boundary nature of the heat equation.</p> <p>**Step 4: Trigonometric Function Analysis** The integral $I = \int_{-K}^K u(x) v(x) dx$ is restricted to $[-K, K]$. The tail term is bounded by:</p> $\int_{ x >K} u(x) ^2 dx = \frac{2}{\pi} \int_{ x >K} \frac{1}{x^2} dx = \frac{2}{\pi} \left(\frac{1}{2} - \arctan(K) \right) \approx \frac{1}{K}$ <p>Since $\frac{1}{K} \leq 1/2$ given $K \geq 1$, Thus, $K = O(1)$.</p> <p>**Step 5: Numerical Discretization** To bound the error, we use a uniform grid with spacing $\Delta x = 0.05$. The ratio between domain size K and grid size is $O(K/\Delta x^2) = O(1/K)$. Since ∂_x and ∂_x^2 are smooth, error of ∂_x^2 is bounded by $O(\Delta x^2)$ and error of ∂_x is bounded by $O(\Delta x)$. The numerical error is bounded by $O(\Delta x)$ due to the uniform grid. The numerical error would only reduce logarithmically, which is asymptotically dominated by $O(\Delta x^2)$.</p> <p>**Outer Integral Contribution** The truncated integral already includes all significant contributions, as the tail contribution is bounded at most by $1/2$. The numerical error $O(\Delta x^2)$ is approximated with $O(\Delta x)^2$ terms, meaning it contributes at most $1/2$. The numerical error $O(\Delta x)$ is approximated with $O(\Delta x)$ terms, meaning it contributes at most $1/2$. The numerical error $O(\Delta x^2)$ dominates the outer integral contribution.</p> <p>**Final Terms** The original proof over $[-K, K]$ requires $O(1/K)$ terms. While adaptive grids in numerical analysis can significantly reduce the number of points required, the adaptive grid only reduces the number of points required by $O(1/K^2)$.</p> <p>**Final Note** Truncation error $O(\Delta x^2)$ + discretization error $O(\Delta x) = O(\epsilon)$. Thus, $O(1/\epsilon^2)$ terms are needed for the proof.</p> <p>[Correct] Variable substitution and equation transformation leads to the LHS lemma. It's right.</p>
Absorbing Boundary Condition (Settled Problem)	AIM provides a substantially complete proof for this problem	<p>**Revised Proof of the a priori estimate** Define the total energy functional:</p> $E(t) = \frac{1}{2} \ u(t)\ _{H^1(\Omega)}^2 + \sum_{k=1}^{\infty} \frac{\alpha_k^2}{k^2} \ v_k(t)\ _{L^2(\Omega)}^2 + \ w(t)\ _{H^1(\Omega)}^2 + \sum_{k=1}^{\infty} \frac{\beta_k^2}{k^2} \ z_k(t)\ _{L^2(\Omega)}^2.$ <p>[Correct] The agent consider the energy method, and derive the correct functional form.</p> <p>**Energy Estimate for $u(t)$ Multiply the t-equation by u and integrate over Ω:</p> $\frac{1}{2} \frac{d}{dt} \ u(t)\ _{L^2(\Omega)}^2 + \ \nabla u(t)\ _{L^2(\Omega)}^2 = \ u(t)\ _{L^2(\Omega)}^2 + \sum_{k=1}^{\infty} \alpha_k^2 u_k(t) \int_{\Omega} u_k \nabla u_k \cdot \partial_\nu u_k d\sigma.$ <p>Apply Young's inequality to the right-hand side:</p> $\sum_{k=1}^{\infty} \alpha_k^2 u_k(t) \int_{\Omega} u_k \nabla u_k \cdot \partial_\nu u_k d\sigma \leq \frac{1}{2} \ u(t)\ _{L^2(\Omega)}^2 + \sum_{k=1}^{\infty} \frac{\alpha_k^2}{2} \int_{\Omega} u_k^2 \nabla u_k ^2 d\sigma.$ <p>Subtract the Young's bound and rearrange:</p> $\frac{1}{2} \frac{d}{dt} \ u(t)\ _{L^2(\Omega)}^2 + \ u(t)\ _{L^2(\Omega)}^2 = \frac{d}{dt} \ u(t)\ _{L^2(\Omega)}^2 + \sum_{k=1}^{\infty} \frac{\alpha_k^2}{2} \ u_k(t)\ _{L^2(\Omega)}^2.$ <p>[Correct] Here, the agent gets the accurate result with the energy method and the application of inequality techniques.</p> <p>**Step 1: Estimates of the Galerkin Approximation** For test functions $v \in V_h$ and $u \in W_h$, the Galerkin approximation satisfy the projected weak form:</p> $\begin{aligned} &\int_{\Omega} \partial_\nu u \cdot v + \int_{\Omega} \nabla u \cdot \nabla v + \int_{\Omega} w \partial_\nu v + \int_{\Omega} g v = \int_{\Omega} u \partial_\nu v + \int_{\Omega} u \nabla w \cdot \nabla v + \int_{\Omega} u g v. \\ &+ \int_{\Omega} \partial_\nu w \cdot v + \int_{\Omega} \nabla w \cdot \nabla v + \int_{\Omega} h v = \int_{\Omega} w \partial_\nu v + \int_{\Omega} w \nabla u \cdot \nabla v + \int_{\Omega} w g v. \end{aligned}$ <p>*Step 2: Formulation of the Projected Equation** For test functions $v \in V_h$ and $u \in W_h$, the Galerkin approximation satisfy the projected weak form:</p> $\begin{aligned} &\int_{\Omega} \partial_\nu u \cdot v + \int_{\Omega} \nabla u \cdot \nabla v + \int_{\Omega} w \partial_\nu v + \int_{\Omega} g v = \int_{\Omega} u \partial_\nu v + \int_{\Omega} u \nabla w \cdot \nabla v + \int_{\Omega} u g v. \\ &+ \int_{\Omega} \partial_\nu w \cdot v + \int_{\Omega} \nabla w \cdot \nabla v + \int_{\Omega} h v = \int_{\Omega} w \partial_\nu v + \int_{\Omega} w \nabla u \cdot \nabla v + \int_{\Omega} w g v. \end{aligned}$ <p>*Step 3: Solves the Galerkin Equation** Substituting $v = \nabla u$ and $w = \nabla w$ into the projected equation yields Galerkin system (A, b) with $b = \sum_{k=1}^{\infty} \beta_k b_k$. The coefficients are smooth in $L^2(\Omega)$, ensuring continuity. By the Cauchy-Lipchitz theorem, unique solution exists on $C^1(\mathbb{T})$.</p> <p>[Correct] The agent gets the accurate solution with the Cauchy-Lipchitz theorem.</p> <p>[Agent] It is better to have more detailed process.</p>
High Contrast Limit (Settled Problem)	AIM completes main proof of the conclusion and produces other correct results	<p>**Step 1: Corrected Test with $v = \nabla \phi_j$ Substituting v into the variational equation:</p> $-\int_{\Omega} \partial_\nu u \cdot \nabla \phi_j + \int_{\Omega} \nabla u \cdot \nabla \phi_j + \int_{\Omega} w \partial_\nu \phi_j + \int_{\Omega} g \phi_j = 0.$ <p>**Step 2: Corrected Test with $v = \nabla \phi_j$ Substituting v into the variational equation:</p> $-\int_{\Omega} \partial_\nu u \cdot \nabla \phi_j + \int_{\Omega} \nabla u \cdot \nabla \phi_j + \int_{\Omega} w \partial_\nu \phi_j + \int_{\Omega} g \phi_j = 0.$ <p>Rearrange and adding absolute value:</p> $ \lambda \int_{\Omega} \partial_\nu u \cdot \nabla \phi_j \leq C \int_{\Omega} \partial_\nu u \nabla \phi_j + \int_{\Omega} w \partial_\nu \phi_j + \int_{\Omega} g \phi_j .$ <p>Using Hölder's inequality and Young's inequality:</p> $\begin{aligned} & \lambda \int_{\Omega} \partial_\nu u \cdot \nabla \phi_j \leq C \int_{\Omega} \partial_\nu u \nabla \phi_j + \int_{\Omega} w \partial_\nu \phi_j + \int_{\Omega} g \phi_j , \\ &\int_{\Omega} \partial_\nu u \nabla \phi_j \leq C \int_{\Omega} \partial_\nu u \nabla \phi_j + \int_{\Omega} w \partial_\nu \phi_j + \int_{\Omega} g \phi_j . \end{aligned}$ <p>*Step 4: Final Estimate** Combining these bounds:</p> $ \lambda \int_{\Omega} \partial_\nu u \cdot \nabla \phi_j \leq 2C \int_{\Omega} \partial_\nu u \nabla \phi_j + \int_{\Omega} w \partial_\nu \phi_j + \int_{\Omega} g \phi_j .$ <p>Dividing by $\lambda \int_{\Omega} \partial_\nu u \cdot \nabla \phi_j$ yields:</p> $ \phi_j \leq \frac{2C}{ \lambda } \int_{\Omega} \partial_\nu u \nabla \phi_j + \int_{\Omega} w \partial_\nu \phi_j + \int_{\Omega} g \phi_j .$ <p>completing the proof with modest constant C.</p> <p>[Correct] Use regularity techniques to derive the correct key conclusions from variational equations.</p> <p>The limit problem (10) is a saddle point problem: Find $(u_m, p_m) \in H^1(\Omega) \times L^2(D_\lambda)$ such that for all $\psi \in H^1(\Omega)$ and $q \in L^2(D_\lambda)$,</p> $\int_{\Omega} \lambda \partial_\nu u_m \cdot \nabla \psi + 2u_m q = \int_{\Omega} \nabla u_m \cdot \nabla \psi + 2u_m q \int_{D_\lambda} \partial_\nu u_m \cdot \nabla \psi + \int_{D_\lambda} q \partial_\nu u_m \cdot \nabla \psi = 0.$ <p>[Agent] Here consider the limited function, but it does not show the detailed derivation of the existence and property of the function.</p>
Homogenization Problem (Open Problem)	AIM provides partially correct conclusions and reasoning, offering instructive guidance	<p>1. Cauchy-Schwarz with uniform constant: Since $Y_T = Y$, ω is a bounded Lipschitz set, the classical Korn with $\omega \in H^1(Y_T)$: $\ u\ _{H^1(Y_T)} \leq C \ u\ _{L^2(Y_T)} + \ u\ _{W^{1,1}(Y_T)}$, for $u \in C_c^\infty(Y_T)$, where $u \rightarrow u$ in $H^1(Y_T)$ and $u \rightarrow u$ in $L^2(Y_T)$, $\lim_{n \rightarrow \infty} p_n(x, t) \rightarrow p(x, t)$, where $p \in C_c^\infty(Y_T \setminus \{0\})$ is the unique solution of the homogenized Landau system with $p_n \rightarrow p$ in $L^2(Y_T \setminus \{0\})$ and $p_n \rightarrow p$ in $H^1(Y_T \setminus \{0\})$. The uniform ellipticity and coercivity of the homogenized operator A is given by the following properties: (i) $\langle A(u), u \rangle \geq c \ u\ _{L^2(Y_T)}^2$ for all $u \in H^1(Y_T)$; (ii) $\langle A(u), u \rangle = \int_{Y_T} \langle A(u), u \rangle dx \geq c \ u\ _{L^2(Y_T)}^2$ for all $u \in C_c^\infty(Y_T)$; (iii) $\langle A(u), u \rangle = \int_{Y_T} \langle A(u), u \rangle dx = 0$ if and only if $u = 0$.</p> <p>(1) In the first place, $\langle A(u), u \rangle = \int_{Y_T} \langle A(u), u \rangle dx = \int_{Y_T} \langle A(u), u \rangle dx = 0$.</p> <p>(2) On the final place, $\langle A(u), u \rangle = \int_{Y_T} \langle A(u), u \rangle dx = \int_{Y_T} \langle A(u), u \rangle dx = 0$.</p> <p>(3) On the material interface $\Gamma = \partial(Y \setminus \{0\}) = \Gamma_1 \cup \Gamma_2 \cup \Gamma_3$, $\langle A(u), u \rangle = \int_{\Gamma} \langle A(u), u \rangle ds = \int_{\Gamma} \langle A(u), u \rangle ds = 0$.</p> <p>(4) $\langle A(y) \cdot x, y \rangle = 0$ is y-periodic, with zero-mean normalization on x and y.</p> <p>The $C^{\infty}(E) = E = \int_E (E \cdot D_x u)^2 + (E \cdot D_y u)^2 + (E \cdot D_z u)^2 + D_x E^2 + D_y E^2 + D_z E^2$ dp</p> <p>[Correct] The accurate convergence of the function space.</p>

Overview of AIM



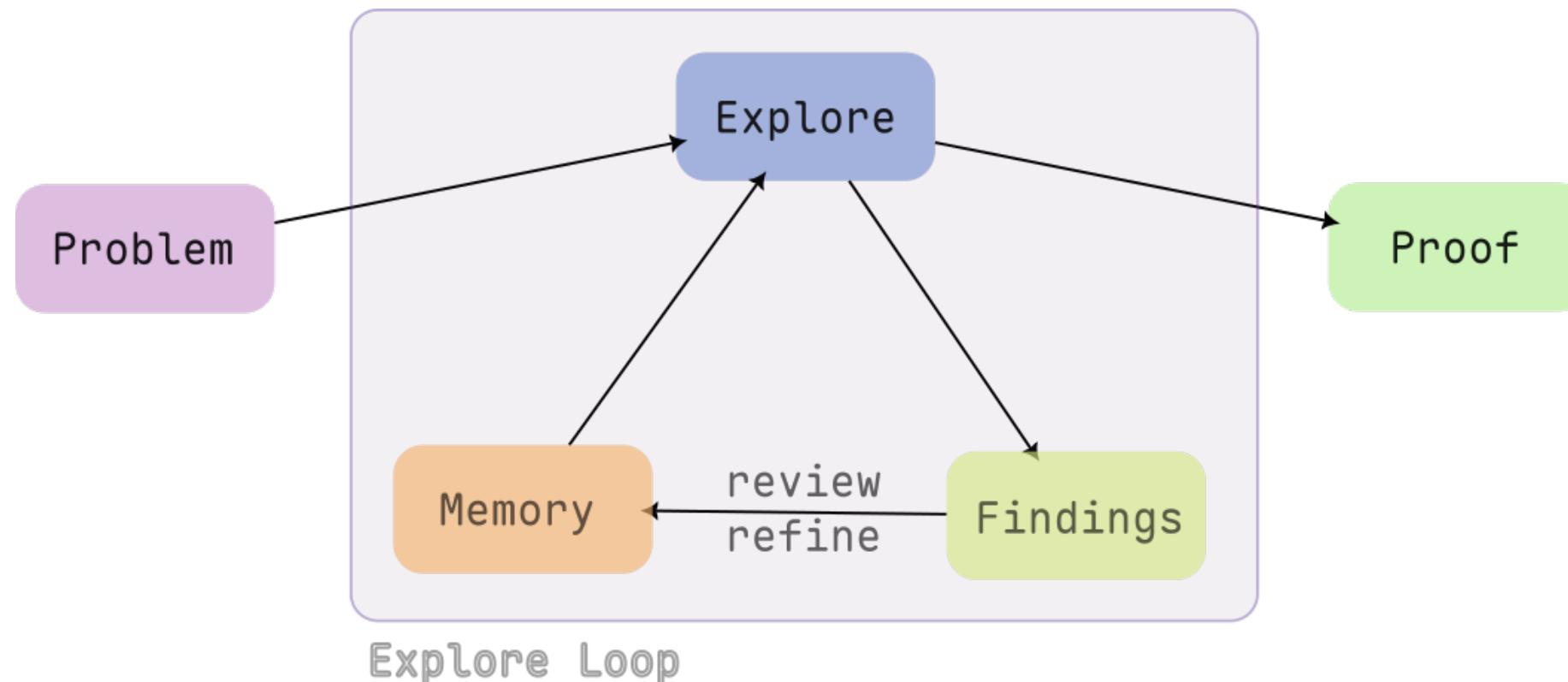
- An LLM-powered agent system specially designed for math research, consisting of three agents (Explorer, Verifier, Refiner) and a Memory.



Long Reasoning: Explore & Memory



- The agents within AIM are tasked with exploring the original problem and documenting their discoveries as lemmas during the process. By iterating this procedure, the exploration progresses further, ultimately achieving problem resolution.

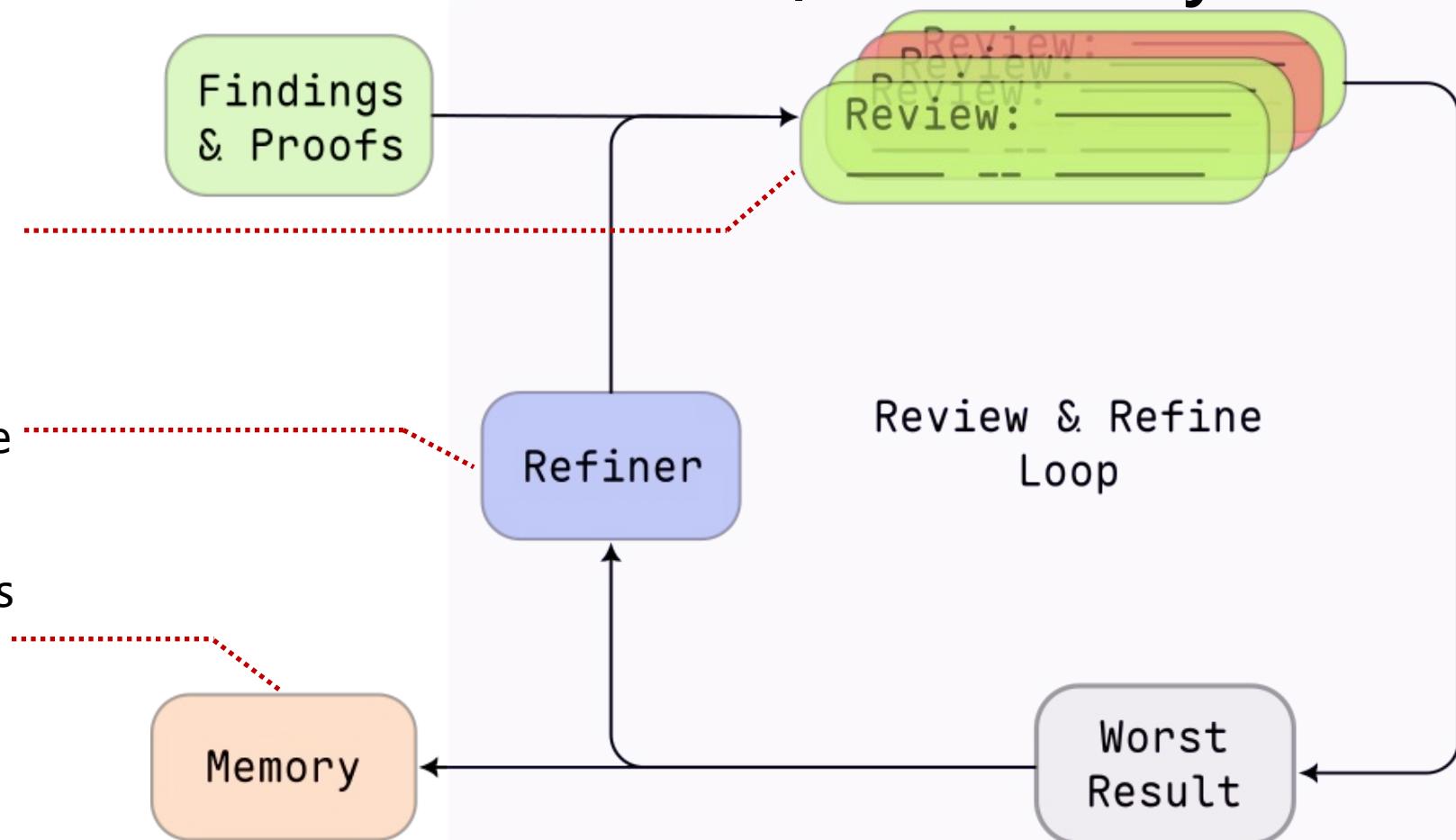


Validation: Pessimistic Verification



- Each new discovery during exploration is repeatedly verified multiple times; if any single verification detects an error, the discovery is deemed incorrect.

- Conducting multiple rounds of self-checking can effectively identify issues
- Erroneous proofs can be analyzed and corrected
- Correct proof conclusions are eventually stored in memory



Agent Design in AIM



- All three agents are guided by meticulously designed prompts, supported by logical processing methods to facilitate collaboration.

Prompt Structure
Instruct _____, _____. _____. 1. _____. 2. _____. 3. _____.
Problem Description ◊_____, _____. _____. _____. </> ◊_____, _____, _____. _____. _____, _____. </>
Memories _____, _____. _____.
Mem ID: 0 _____. _____.
Mem ID: 1 _____. _____, _____, _____. _____, _____.

←--- Define behavior of an agent

Prompt Example

Including task goal, reasoning direction, output format, etc.

You are an expert that is knowledgeable across all domains in math. This time you are asked to help with our frontier math research. Its statement is as follows:

This problem could be difficult and not able to be directly solved, but you can make your contribution with the following instructions:

1. You are required to explore different approaches or directions that might help with our final goal, and write down one interesting finding in your explorations as a new conjecture in your response. DO NOT claim that you can not do this job.

2. Your conjecture must contain the complete definitions required within it, such that it is able to stand alone as an independent lemma, unless it is declared in memory. Do not propose any existing lemmas as your new conjectures. You can directly use them in your explorations.

3. You should wrap your finding inside a latex environment: \begin{conjecture}\end{conjecture}. This conjecture should be equipped with a detailed, complete and rigorous proof. You should explicitly write down every intermediate derivation step in the proof. The corresponding proof should be wrapped in \begin{proof}\end{proof} directly followed by the conjecture.

4. After these components you should also provide the dependency of this conjecture. You need to write down the memory IDs of lemmas used in this conjecture in a JSON array format, and wrap them inside \begin{dependency}\end{dependency}. For example, a dependency of a new conjecture could be \begin{dependency}[0, 3, 4]\end{dependency}. You can use an empty array "[]" when this conjecture does not depend on other lemmas.

More accurately, your response should obey the following format:

```
\begin{conjecture}Your new findings here\end{conjecture}  
\begin{proof}Your proof of the conjecture above\end{proof}  
\begin{dependency}A json array of related memory IDs of this conjecture\end{dependency}  
Moreover, when you think the time is right that you are able to prove the original problem, you can simply state your proof inside \begin{final_proof}\end{final_proof} and evaluate
```

Agent Design in AIM



- All three agents are guided by meticulously designed prompts, supported by logical processing methods to facilitate collaboration.

Prompt Structure
Instruct _____, _____. _____. 1. _____. 2. _____, _____. 3. _____.
Problem Description ◊_____, _____. _____. _____. </> ◊_____, _____, _____. _____. _____, _____. </>
Memories _____, _____. _____. ##### Mem ID: 0 _____. _____. ##### Mem ID: 1 _____. _____, _____, _____. _____, _____.

Define behavior of an agent
←---
Description of the problem
←---

Prompt Example

Information directly related to the task, for each agent it could be:

- Explorer: the statement of the final goal
- Verifier: a conjecture and its proof
- Refiner: a flawed conjecture, proof, and the feedback from the verifier

```
\begin{problem}Question:  
Can we prove: for any  $\delta > 0$ ,  
[  
 \mathbb{P}[n^{-\delta} \mathbb{E}[Y_n] \leq Y_n \leq n^{\delta}] \geq 1 - O(d^{-n})  
 ]  
  
If the second claim is not true, can we prove: for any  $\delta > 0$ ,  
[  
 \mathbb{P}[Y_n \leq n^{2+\delta}] \geq 1 - O(d^{-n})  
 ]  
\end{problem}  
This problem could be difficult and not able to be directly solved, but you can make your contribution with the following instructions:
```

Agent Design in AIM



- All three agents are guided by meticulously designed prompts, supported by logical processing methods to facilitate collaboration.

Prompt Structure
Instruct
_____, _____. _____.
1. _____. 2. _____, _____. 3. _____.
Problem Description
◊_____, _____. _____. _____. </> ◊_____, _____, _____. _____. _____, _____. </>
Memories
_____, _____. _____. ##### Mem ID: 0 _____. _____. ##### Mem ID: 1 _____. _____, _____, _____. _____, _____.

Define behavior of an agent
←--- Description of the problem
←--- Information in memory

Prompt Example

Formatted exploration history in memory

```
### Context and History Explorations

Here is a list of context that we have collected for this problem or our history finding
s during exploration. They serve as the background of the conjecture and proof and can be ac
cepted without controversy as correct.

#### Memory **ID: 1**

\begin{lemma}

There exists a constant  $(A>0)$  and a nonnegative random variable  $(Y)$  such that
\[
\forall k \geq 1: \quad \mathbb{E}[Y^k] \leq k! \cdot A^k,
\]
yet for some  $(t>0)$ ,
\[
\mathbb{P}(Y \geq t) > \exp(-\frac{t}{2A}).
\]
In other words, the bound
\[
\mathbb{P}(Y \geq t) \leq \exp(-\frac{t}{2A})
\]
cannot hold for all  $(t>0)$  under only the moment hypothesis.

**DEPENDENCY**: []
\end{lemma}

#### Memory **ID: 2**
```

Memory Design in AIM



- AIM parses and logs four categories of data from the model's outputs, with a portion of it being structured and fed into later agents' inputs.

Memory type, e.g.,
context, lemma,
conjecture, etc

Textual description
of the memory
content

A complete proof
to this lemma

```
struct MemoryBlock {  
    Memory Type  
  
    Content Description  
  
    Proof: _____.  
    _____, _____.  
  
    MetaData  
};
```

Visible to all these
agents

Saved and discarded
in explorations

All components in the
memory blocks will be
visible in the output

Other metadata of this memory,
e.g., solved tag, num reviews, etc

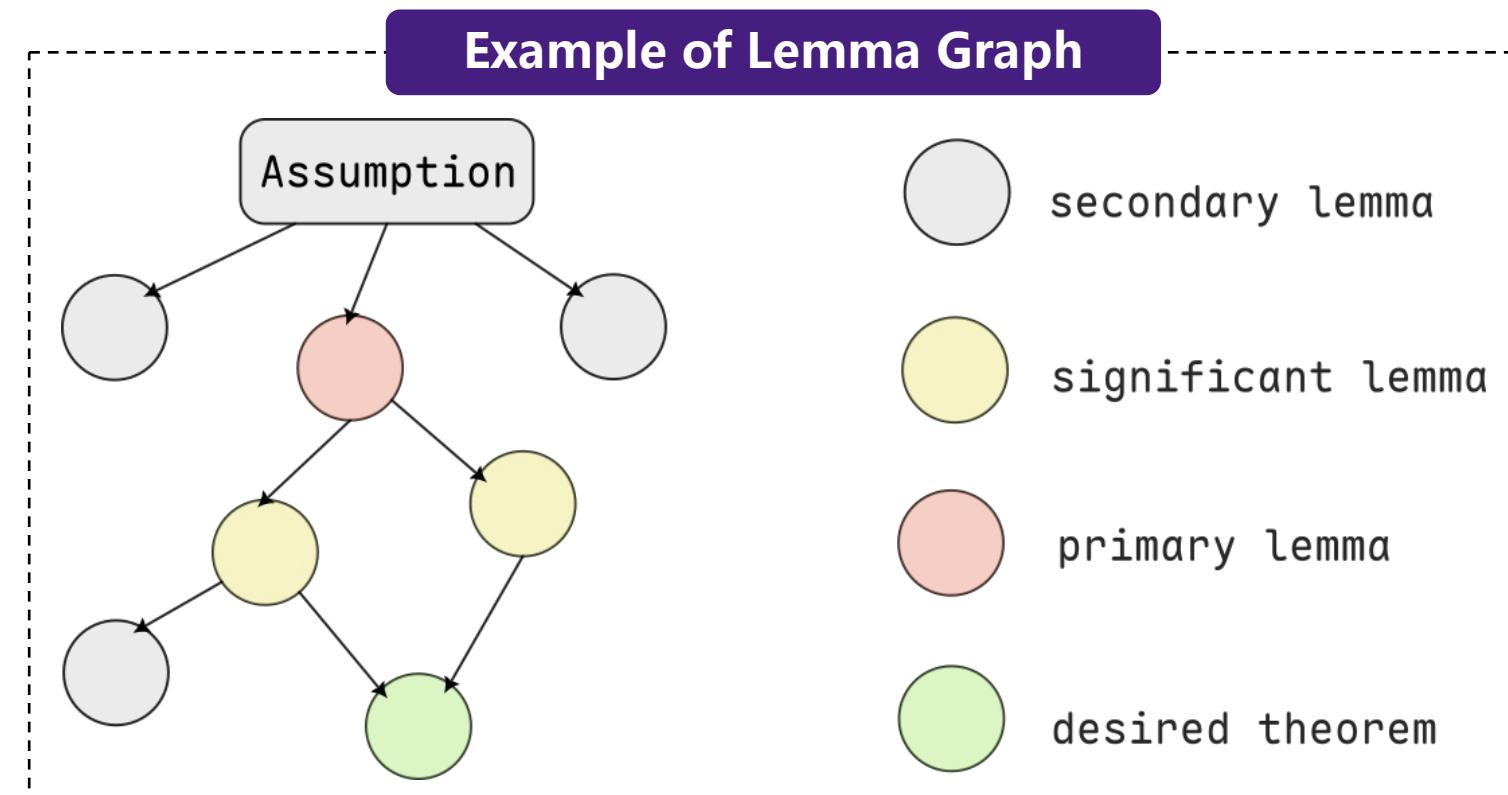
Lemma Graph



- By arranging the lemmas according to their mutual dependencies, the exploration process can be structured into a lemma graph—essentially a directed graph that starts from the initial assumptions.

This brings two critical improvements:

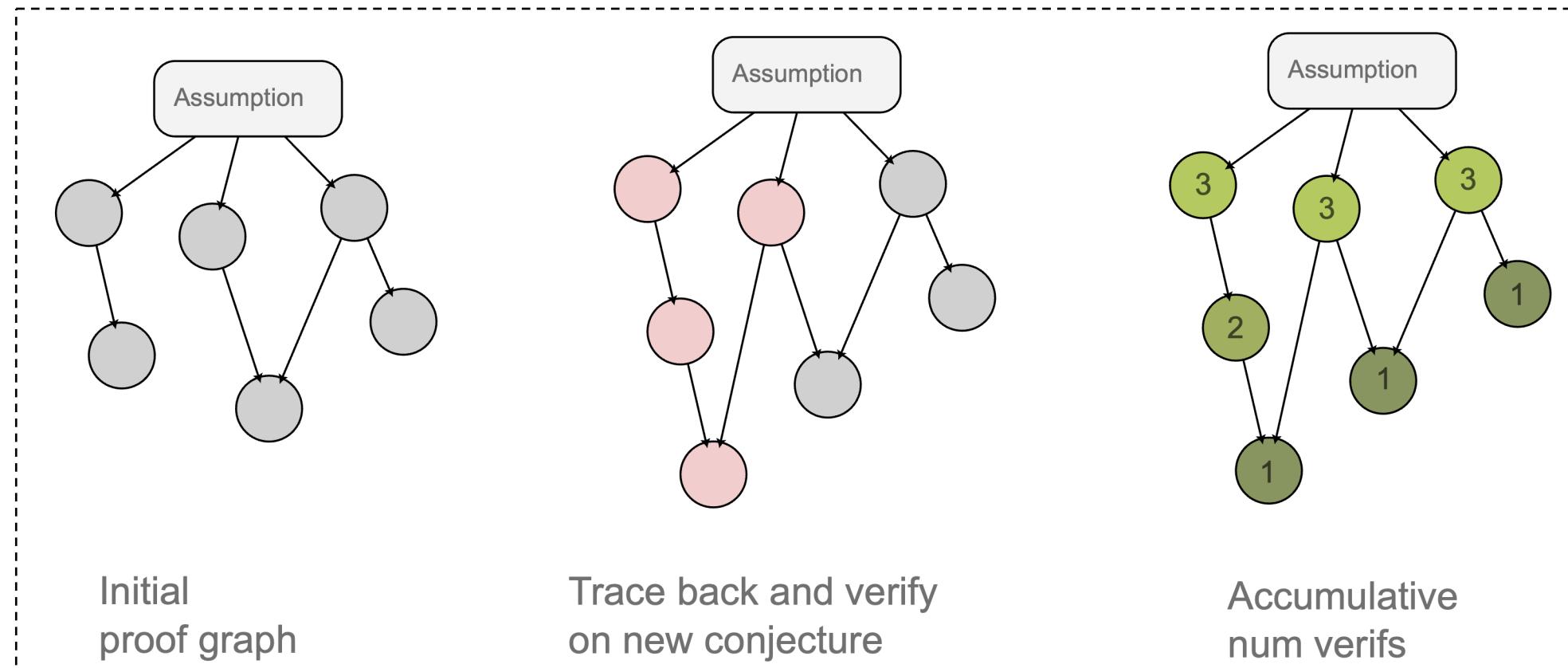
- Easy identification of actual proof path.
- Quantitative assessment of each lemmas. (By calculating the derivations of each node in the graph.)



Dynamic Verification in Lemma Graph



- By dynamically allocating verification resources by the importance of each lemmas, we can further guarantee the reliability while increasing its efficiency.



Initial
proof graph

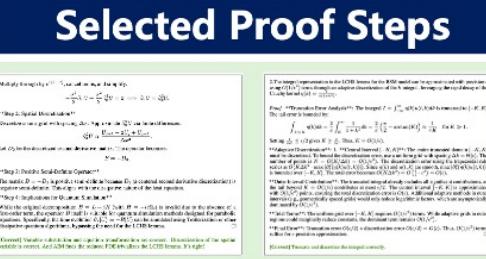
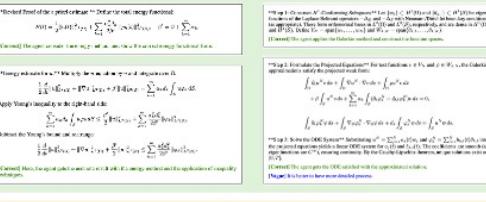
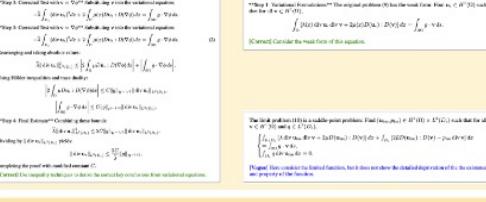
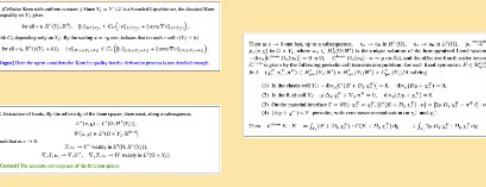
Trace back and verify
on new conjecture

Accumulative
num verifs

Overview of Experiments



- AIM is applied to address four mathematical theory problems, including three settled problems and one open problem.

Research Problem	Results of AIM	Selected Proof Steps
Quantum Algorithm Problem (Settled Problem)	AIM effectively completes the problem with a detailed solution process	
Absorbing Boundary Condition (Settled Problem)	AIM provides a substantially complete proof for this problem	
High Contrast Limit (Settled Problem)	AIM completes main proof of the conclusion and produces other correct results	
Homogenization Problem (Open Problem)	AIM provides partially correct conclusions and reasoning, offering instructive guidance	

Settled Problem

Open Problem

---- DeepSeek-R1

---- DeepSeek-R1

DeepSeek-R1
and o4-mini,
each conducted
one experiment

---- o4-mini

Quantum Algorithm Problem



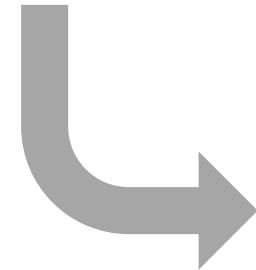
清华大学
Tsinghua University

The Linear Combination of Hamiltonian Simulation (LCHS) method is an efficient approach in scientific computing. Its main idea is to transform non-unitary dynamical problems into linear combinations of Hamiltonian simulation.

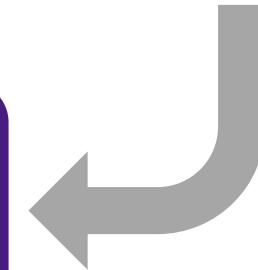
$$\mathcal{T}e^{-\int_0^t A(s) ds} = \int_{\mathbb{R}} \frac{1}{\pi(1+k^2)} \mathcal{T}e^{-i \int_0^t (H(s) + kL(s)) ds} dk$$

The Black-Scholes-Merton (BSM) model is the fundamental mathematical framework used for pricing European options in finance.

$$\frac{\partial V}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} + rS \frac{\partial V}{\partial S} - rV = 0$$



Objective: To simulate the BSM model using the LCHS method, design corresponding quantum algorithms, and analyze the complexity of the algorithms.



AIM correctly applies this method, providing a detailed proof and basically solving this problem

Quantum Algorithm Problem



清华大学
Tsinghua University

Explanation of the LCHS lemma

Lemma (Linear combination of Hamiltonian simulation, LCHS): For $t \in [0, T]$, let $A(t) \in \mathbb{C}^{N \times N}$ be decomposed into Hermitian and anti-Hermitian parts such that $A(t) = L(t) + iH(t)$, where $L(t) = \frac{1}{2}[A(t) + A^\dagger(t)]$ and $H(t) = \frac{1}{2i}[A(t) - A^\dagger(t)]$. Assume that $L(t)$ is positive semi-definite for all $t \in [0, T]$. Denoting the time ordering operator by \mathcal{T} , we have $\mathcal{T} \exp \left\{ - \int_0^t A(s) ds \right\} = \int_{\mathbb{R}} \eta(k) u(t, k) dk$, where $u(t, k)$ is the propagator for a time-dependent Hamiltonian simulation problem such that $u(t, k) = \mathcal{T} \exp \left\{ -i \int_0^t [H(s) + kL(s)] ds \right\}$, and $\eta(k) = \frac{1}{\pi(1+k^2)}$ is the kernel function with respect to k .

System input

BSM model: The PDE in the BSM model is given by

$$\frac{\partial V(S, t)}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} + rS \frac{\partial V}{\partial S} - rV = 0.$$

Boundary conditions are characterized by: $V(0, t) = 0$ for all $0 < t \leq T$; $V(S, t) \rightarrow S - Ke^{-r(T-t)}$ for $S \rightarrow \infty$; $V(S, T) = \max\{S - K, 0\}$.

Explanation of the BSM model

Your tasks are to: Use the idea of LCHS to deal with the BSM model. Design a quantum algorithm to solve the equation. And compute the complexity (query complexity to state preparation oracle and operator oracles, gate complexity, ancilla qubits, (parameters: norm of boundary and initial, T, approximation error ϵ , etc)).

Objective

Quantum Algorithm Problem



- AIM solves the problem by transforming the BSM equation into a heat equation, applying the LCHS lemma to reformulate the problem, and proposing a quantum algorithm. The core steps are as follows:

1	PDE transformation and spatial discretization	Transform the BSM equation into the standard heat equation using variable substitution, and discretize the spatial variables.
2	Operator decomposition and integral discretization	Apply the LCHS lemma to decompose the solution operator of the heat equation into a continuous linear combination of unitary operators. Then, truncate and approximate the continuous integral and discretize it.
3	Quantum algorithm implementation and complexity analysis	Design quantum algorithms using the linear combination of unitaries (LCU) and Hamiltonian simulation techniques, and calculate the complexity.

Quantum Algorithm Problem



AIM explores step by step through a seq. of progressively built lemmas.

Lemma 1: First, AIM transforms the BSM equation into a heat equation, then discretizes the spatial variables, and verifies semi-definiteness. Further, AIM converts it into a form that can utilize the LCHS lemma, with a detailed proof.

1. The Black-Scholes-Merton (BSM) partial differential equation (PDE) can be transformed into the standard heat equation via a logarithmic substitution. Specifically, under the transformation $x = \ln(S/K) + (r - \sigma^2/2)(T - t)$, $\tau = \sigma^2(T - t)/2$, and $V(S, t) = e^{-r(T-t)}U(x, \tau)$, the BSM PDE reduces to:

$$\frac{\partial U}{\partial \tau} = \frac{\partial^2 U}{\partial x^2}.$$

Discretizing this PDE spatially yields a matrix equation $\partial_\tau|U\rangle = -B|U\rangle$, where $B = -\partial_x^2$. The operator B is positive semi-definite and can be directly interpreted as $B = L$, where $L = -\partial_x^2$. While the original Hermitian decomposition $B = L + iH$ (with $H = 0$) trivializes the LCHS lemma, the dissipative nature of B permits alternative quantum simulation methods.

Transform the BSM equation into a heat equation

Proof. **Step 1: Transform BSM to the Heat Equation

Start with the BSM PDE:

$$\frac{\partial V}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} + rS \frac{\partial V}{\partial S} - rV = 0.$$

Apply the substitution $V(S, t) = e^{-r(T-t)}U(x, \tau)$, $x = \ln(S/K) + (r - \sigma^2/2)(T - t)$, and $\tau = \sigma^2(T - t)/2$. Compute derivatives rigorously: $-\partial_t V = e^{-r(T-t)} \left(rU - \frac{\sigma^2}{2} \partial_\tau U - (r - \sigma^2/2) \partial_x U \right)$, $-\partial_S V = e^{-r(T-t)} \partial_x U \cdot \frac{1}{S}$, $-\partial_S^2 V = e^{-r(T-t)} (\partial_x^2 U - \partial_x U) \cdot \frac{1}{S^2}$.

Substitute into the BSM PDE:

$$e^{-r(T-t)} \left[rU - \frac{\sigma^2}{2} \partial_\tau U - (r - \sigma^2/2) \partial_x U + \frac{1}{2} \sigma^2 (\partial_x^2 U - \partial_x U) + r \partial_x U - rU \right] = 0.$$

Multiply through by $e^{r(T-t)}$, cancel terms, and simplify:

$$-\frac{\sigma^2}{2} \partial_\tau U + \frac{\sigma^2}{2} \partial_x^2 U = 0 \implies \partial_\tau U = \partial_x^2 U.$$

Step 2: Spatial Discretization

Discretize x on a grid with spacing Δx . Approximate $\partial_x^2 U$ via finite differences:

$$\partial_x^2 U \approx \frac{U_{j+1} - 2U_j + U_{j-1}}{\Delta x^2}.$$

Let D_2 be the discretized second derivative matrix. The operator becomes:

$$B = -D_2.$$

Step 3: Positive Semi-Definite Operator

The matrix $B = -D_2$ is positive semi-definite because D_2 (a centered second derivative discretization) is negative semi-definite. This aligns with the dissipative nature of the heat equation.

Step 4: Implications for Quantum Simulation

While the original decomposition $B = L + iH$ (with $H = -ic\partial_x$) is invalid due to the absence of a first-order term, the operator B itself is suitable for quantum simulation methods designed for parabolic equations. Specifically, the time evolution $\partial_\tau|U\rangle = -B|U\rangle$ can be simulated using Trotterization or other dissipative quantum algorithms, bypassing the need for the LCHS lemma. □

Discretize spatial variables

[Correct] Variable substitution and equation transformation are correct. Discretization of the spatial variable is correct. And AIM finds the reduced PDE trivializes the LCHS lemma. It's right!

Quantum Algorithm Problem



清华大学
Tsinghua University

AIM explores step by step through a seq. of progressively built lemmas.

Lemma 2: AIM analyzes truncation errors and determines discrete intervals, laying the foundation for constructing quantum algorithms.

2. The integral representation in the LCHS lemma for the BSM model can be approximated with precision ϵ using $O(1/\epsilon^2)$ terms through an adaptive discretization of the k -integral, leveraging the rapid decay of the Cauchy kernel $\eta(k) = \frac{1}{\pi(1+k^2)}$.

Proof. ****Truncation Error Analysis**:** The integral $I = \int_{-\infty}^{\infty} \eta(k)u(t, k)dk$ is truncated to $[-K, K]$. The tail error is bounded by:

$$\int_{|k|>K} \eta(k)dk = \frac{2}{\pi} \int_K^{\infty} \frac{1}{1+k^2} dk = \frac{2}{\pi} \left(\frac{\pi}{2} - \arctan(K) \right) \approx \frac{1}{\pi K} \quad \text{for } K \gg 1.$$

Setting $\frac{1}{\pi K} \leq \epsilon/2$ gives $K \geq \frac{2}{\pi\epsilon}$. Thus, $K = O(1/\epsilon)$.

****Adaptive Discretization**:** 1. ****Central Interval $[-K, K]$ **:** The entire truncated domain $[-K, K]$ must be discretized. To bound the discretization error, use a uniform grid with spacing $\Delta k = \Theta(\epsilon)$. The number of points is $N = O(K/\Delta k) = O(1/\epsilon^2)$. The discretization error using the trapezoidal rule scales as $O(K\Delta k^2 \cdot \max |\partial_k^2(\eta(k)u(t, k))|)$. Since $\eta(k)$ and $u(t, k)$ are smooth, $\max |\partial_k^2(\eta(k)u(t, k))|$ is bounded over $[-K, K]$. The total error becomes $O(K\Delta k^2) = O(\frac{1}{\epsilon} \cdot \epsilon^2) = O(\epsilon)$.

****Outer Interval Contribution**:** The truncated integral already includes all significant contributions, as the tail beyond $K = O(1/\epsilon)$ contributes at most $\epsilon/2$. The central interval $[-K, K]$ is approximated with $O(1/\epsilon^2)$ points, ensuring the total discretization error is $O(\epsilon)$. Additional adaptive methods in outer intervals (e.g., geometrically spaced grids) would only reduce logarithmic factors, which are asymptotically dominated by $O(1/\epsilon^2)$.

****Total Terms**:** The uniform grid over $[-K, K]$ requires $O(1/\epsilon^2)$ terms. While adaptive grids in outer regions could marginally reduce constants, the dominant term remains $O(1/\epsilon^2)$.

****Final Error**:** Truncation error $O(\epsilon/2) +$ discretization error $O(\epsilon/2) = O(\epsilon)$. Thus, $O(1/\epsilon^2)$ terms suffice for ϵ -precision approximation. \square

Analyze truncation error

Determine discrete intervals

Overall error analysis

[Correct] Truncate and discretize the integral correctly.

Quantum Algorithm Problem



AIM explores step by step through a seq. of progressively built lemmas.

AIM combines previous lemmas to construct a quantum algorithm using Hamiltonian simulation and the linear combination of unitary operators (LCU), then calculates its complexity. There are some errors in the complexity calculation, but the core methods are correct.

3. The solution operator for the heat equation derived from the BSM model, $U(\tau) = e^{\tau B}$, can be approximated via the LCHS lemma as a linear combination of Hamiltonian simulations. Specifically, the integral representation $\int_{\mathbb{R}} \eta(k) e^{-ikL\tau} dk$ (where $L = -B$) can be discretized into $M = O(1/\epsilon^2)$ terms with quadrature weights $\eta(k_j) \Delta k$. The total query complexity to the L -oracle is $\tilde{O}(\|L\|T/\epsilon^3)$, where $T = \frac{2\tau}{\sigma^2}$ and the gate complexity scales polynomially with $\|L\|$, T , $1/\epsilon$, and logarithmic factors.

Based on the first lemma, use the LCHS lemma to transform into a continuous integral of unitary operators

Proof:
Step 1: Integral Representation via LCHS From Lemma-0, the solution operator for the heat equation is $U(\tau) = e^{\tau B}$. Let $L = -B$, a positive semi-definite operator. By the LCHS lemma with $H = 0$, we express:

$$e^{\tau B} = \int_{\mathbb{R}} \eta(k) e^{-ikL\tau} dk, \quad \eta(k) = \frac{1}{\pi(1+k^2)}.$$

Step 2: Quadrature Discretization Lemma-1 guarantees the integral can be discretized into $M = O(1/\epsilon^2)$ terms with weights $\eta(k_j)\Delta k$, yielding:

$$e^{\tau B} \approx \sum_{j=1}^M \eta(k_j) \Delta k \cdot e^{-ik_j L\tau}.$$

The truncation and discretization error is $O(\epsilon)$ due to the $O(1/k^2)$ decay of $\eta(k)$.

[Correct] Properly utilizing the LCHS lemma and memory lemmas for problem transformation.

Transform the solution of the equation into a linear combination of unitary operators

Utilize Hamiltonian simulation algorithms

Step 3: Hamiltonian Simulation Costs Each term $e^{-ik_j L\tau}$ requires simulating L for time $t_j = k_j \tau$. Using optimal Hamiltonian simulation algorithms (e.g., quantum signal processing or Taylor series) with query complexity $O(\|L\|t_j + \log(1/\epsilon_{\text{sim}}))$, set $\epsilon_{\text{sim}} = \epsilon/M$ to bound the total simulation error by ϵ . Since $k_j = O(1/\epsilon)$ dominates the quadrature, $t_j = O(\tau/\epsilon)$. The per-term complexity becomes:

$$O(\|L\|\tau/\epsilon + \log(M/\epsilon)) = \tilde{O}(\|L\|\tau/\epsilon).$$

Step 4: Total Query Complexity Summing over $M = O(1/\epsilon^2)$ terms, the total queries to the L -oracle are:

$$\tilde{O}\left(M \cdot \frac{\|L\|\tau}{\epsilon}\right) = \tilde{O}\left(\frac{\|L\|\tau}{\epsilon^3}\right).$$

Expressing in terms of $T = \frac{2\tau}{\sigma^2}$ and absorbing constants:

$$\tilde{O}\left(\frac{\|L\|T}{\epsilon^3}\right).$$

Complexity analysis

Step 5: Ancilla and Gate Complexity The LCU framework requires $\log M = O(\log(1/\epsilon))$ ancilla qubits. Gate complexity inherits $\tilde{O}(M)$ -scaling from the superposition state, augmented by $O(\text{poly}(\log(\|L\|T/\epsilon)))$ factors from simulation subroutines. The dominant terms remain polynomial in $\|L\|$, T , and $1/\epsilon$, with polylogarithmic corrections.

[Error] There are some mistakes about complexity computing. And the calculation process lacks detail.

Homogenization Problem



- **Problem Description:** The homogenization problem for transmission systems requires analyzing the properties of equations and their corresponding solutions under specific physical scale limits. The goal is to ultimately prove the error estimation of solutions, which remains **an open problem**.

$$\begin{cases} \mathcal{L}_{\lambda,\mu} \mathbf{u}_\epsilon = 0 \\ \mathcal{L}_{\tilde{\mu}}(\mathbf{u}_\epsilon, p_\epsilon) = 0 \text{ and } \operatorname{div} \mathbf{u}_\epsilon = 0 \\ \mathbf{u}_\epsilon|_- = \mathbf{u}_\epsilon|_+ \text{ and } \left. \frac{\partial(\mathbf{u}_\epsilon, p_\epsilon)}{\partial \nu_{(\infty, \tilde{\mu})}} \right|_- = \left. \frac{\partial \mathbf{u}_\epsilon}{\partial \nu_{(\lambda, \mu)}} \right|_+ \\ \left. \frac{\partial \mathbf{u}_\epsilon}{\partial \nu_{(\lambda, \mu)}} \right|_{\partial \Omega} = g \in H_{\mathbb{R}}^{-\frac{1}{2}}(\partial \Omega) \quad \text{and} \quad \mathbf{u}_\epsilon|_{\partial \Omega} \in H_{\mathbb{R}}^{\frac{1}{2}}(\partial \Omega), \end{cases}$$

in $\Omega \setminus \overline{D_\epsilon}$, where $\mathcal{L}_{\tilde{\mu}}(\mathbf{u}_\epsilon, p_\epsilon) = \tilde{\mu} \Delta \mathbf{u}_\epsilon + \nabla p_\epsilon$ denotes the Stokes operator with viscosity constant $\tilde{\mu}$ and p_ϵ is the pressure field. Its exterior derivative is defined as $\left. \frac{\partial(u, p)}{\partial \nu_{(\infty, \mu)}} \right|_- := pN + 2\mu D(u)N$.

Now we let $\epsilon \rightarrow 0$, so that the scale of the cell is tend to be zero. We wonder what homogenization equation does the limited solution \mathbf{u}_{lim} satisfies. At the same time, whether the estimate between the original solution and the limited solution has the form $C\epsilon^\alpha \|g\|_{H_{\mathbb{R}}^{-\frac{1}{2}}(\partial \Omega)}$ for some $\alpha \in (0, 1)$.

- AIM correctly applied mathematical theorems and analytical derivations, providing some accurate conclusions and approaches.
- The results are of guiding significance for human mathematicians conducting this research.

6. Error estimate and strong convergence Define the two-scale corrector

$$u_\epsilon^{\text{app}}(x) = u_0(x) + \varepsilon \chi^{D_x u_0(x)}(x/\varepsilon) \text{ in } \Omega_\varepsilon,$$

extended in each D_ε by $Ey + \chi_i^E(y)$. A Céa-lemma-type argument in the perforated domain (again relying on uniform Korn and Stokes inf-sup, Lemma A.1-A.2) yields for some $\alpha \in (0, 1)$

$$\|u_\varepsilon - u_\varepsilon^{\text{app}}\|_{H^1(\Omega_\varepsilon)} \leq C\varepsilon^\alpha \|g\|_{H_{\mathbb{R}}^{-1/2}(\partial \Omega)}.$$

From this one deduces $u_\varepsilon \rightarrow u_0$ strongly in $L^2(\Omega)$ (and even in $H^1(\Omega_\varepsilon)$ up to the corrector).

This completes a fully rigorous derivation of the homogenized elastic limit and the explicit formula for C^{hom} .

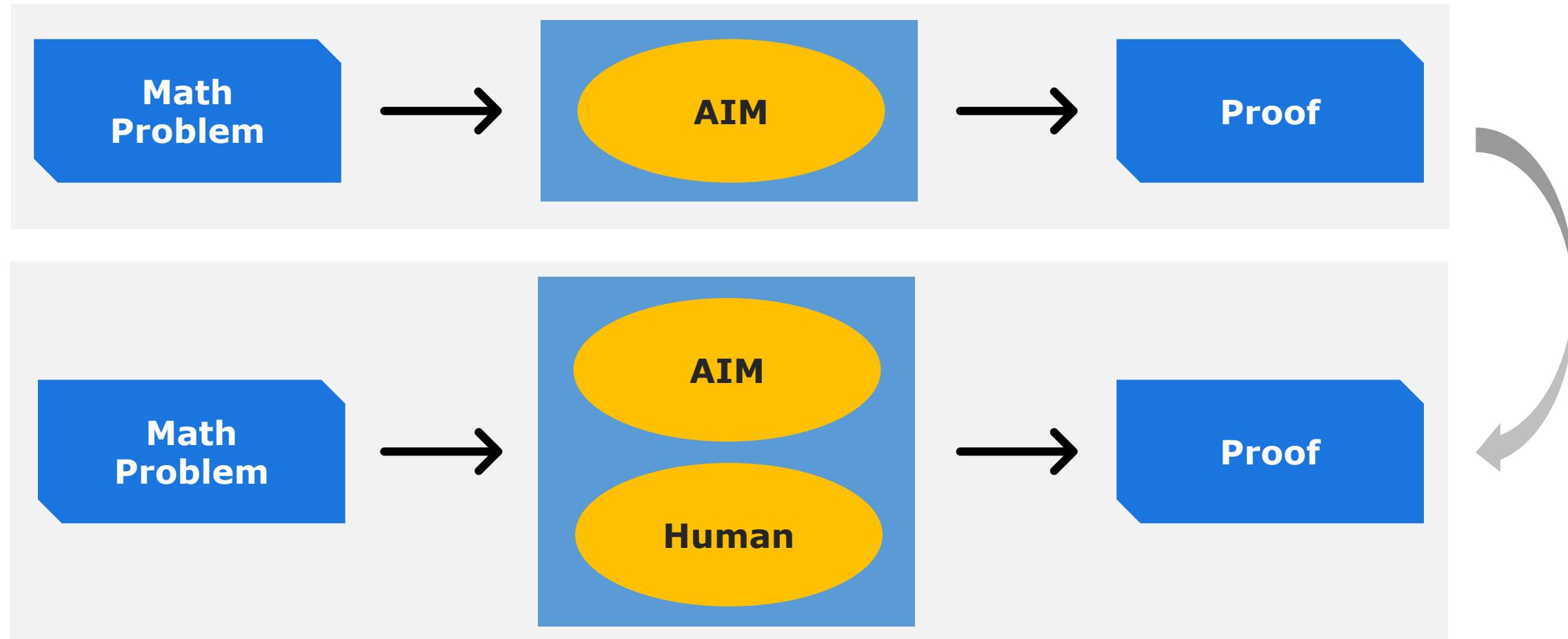
Correct asymptotic expansion approaches and exploration of conclusions.

Human-AI Collaboration



清华大学
Tsinghua University

- **Objective: Solve the Homogenization Problem with minimal human input through human-AI collaboration.**



Human-AI Collaboration



清华大学
Tsinghua University

- AIM contributed significantly to the hardest parts of a 17-page proof.



Green generated by AIM and then formatted manually
Orange manually refined after AIM provided a proof with a high degree of completion
Blue content derived manually
Black basic setup and information of this problem

Human-AI Collaboration



● Subproblem decomposition of the homogenization problem:

Steps	Hardness	Current Status
Two-Scale Expansion	Easy	Humans handle the task
Cell Problem and Homogenization Equation	Medium	A suitable cell problem is manually constructed, and the homogenized equation is derived by hand
Existence and Uniqueness	Hard	With minimal hints, AIM discovers the correct theorem and proof; humans fill in some details
Ellipticity of Operator	Medium	With minimal hints, AIM provides a largely complete proof; humans refine some details
Error Estimation and Control	Hard	With minimal hints, AIM presents the correct proof approach and some steps, which, after human adjustments, led to a complete proof process
Regularity of Cell Problem	Hard	With minimal hints, AIM provides the complete proof

Background: Cell Problem



清华大学
Tsinghua University

In the derivation process of the homogenization equation, the construction of the Cell Problem is a necessary technical step. Specifically, we manually constructed such a Cell Problem as described in the following equation.

$$\nabla \cdot [\lambda \nabla_y \cdot \chi^{ij} I + 2\mu D_y u] = 0 \quad \text{in } Y \setminus \omega$$

$$\nabla \cdot [r^{ij} I + 2\tilde{\mu} D_y \chi^{ij}] = 0 \quad \text{in } \omega$$

$$\nabla_y \cdot \chi^{ij} = 0 \quad \text{in } \omega$$

$$\chi^{ij}|_+ = \chi^{ij}|_- \quad \text{in } \partial\omega$$

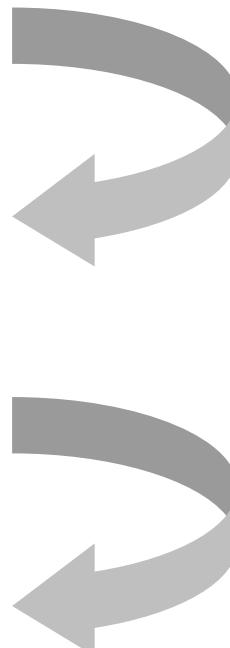
$$[r^{ij} I + 2\tilde{\mu} D\chi^{ij}]N|_- - [\lambda \nabla_y \cdot \chi^{ij} I + 2\mu D\chi^{ij}]N|_+ = 0 \quad \text{in } \partial\omega$$

Subproblem: Regularity of Cell Problem



AIM attempted to derive the error estimation

$$\|u_\epsilon - u_0 - \epsilon \chi\left(\frac{x}{\epsilon}\right) \nabla u_0\|_{H^1(\Omega)} \leq C(\mu, \Omega, \|\chi\|_\infty) \epsilon^{\frac{1}{2}} \|u_0\|_{W^{2,d}(\Omega)}$$



Manual review of the estimation revealed that AIM relied on the following properties without providing proofs

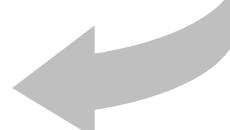
Lemma 4. Let $\Omega \subset \mathbb{R}^d$ be as above, $\chi(y)$ Y -periodic with $\chi \in L^\infty(Y)$, $\nabla_y \chi \in L^2(Y)$, the cut-off of Lemma 8, and S_ϵ the mollifier of Lemma 7. Then for every $u_0 \in H^2(\Omega)$

$$\|\epsilon \chi(x/\epsilon) \eta_\epsilon(\nabla u_0 - S_\epsilon^2(\nabla u_0))\|_{H^1(\Omega)} \leq C \epsilon \|u_0\|_{H^2(\Omega)},$$

where C depends only on Ω , $\|\chi\|_{L^\infty(Y)}$, $\|\nabla \chi\|_{L^2(Y)}$, and the mollifier.

We analyzed that this property is likely correct and applied AIM to prove the regularity

$$\chi \in W^{1,\infty}(Y \setminus \omega) \cup W^{1,\infty}(\omega)$$



Difference Quotient



Schauder Theory



Galerkin Method



Subproblem: Regularity of Cell Problem



Schauder Theory

Lemma 1. Suppose $\Omega = \mathbb{R}^d$, $S = \{x_d = 0\}$, $B_+ = \{x \in B(1) : x_d > 0\}$ and $B_- = \{x \in B(1) : x_d < 0\}$. Here $B(1) = \{\|x\| \leq 1\}$. Consider this equation: for $V \in H_0^1(B(1); \mathbb{R}^d)$

$$(\nabla V : A_1 \nabla \tilde{\chi})_{B_+} + (\nabla V : A_2 \nabla \tilde{\chi})_{B_-} + (\tilde{r}, \nabla \cdot (aV))_{B_-} = 0 \quad (1)$$

$$\nabla \cdot (a \tilde{\chi}) = 0 \quad (2)$$

Here $\tilde{\chi} = D^\alpha \chi$, $\tilde{r} = D^\alpha r$, $|\alpha| \geq 1$ and A_1, A_2 are constant tensors, a is a constant matrix. Then we have for $\forall k \geq 1$

$$\sum_{\pm} \|\chi\|_{H^k(B(\frac{1}{2}), \pm)} \leq C \|\chi\|_{L^2(B(1))}$$

$$\|r\|_{H^k(B(\frac{1}{2}))_-} \leq C \|r\|_{L^2(B(\frac{1}{2}))_-}$$

Lemma 2. Suppose that M is the constant matrix in $\mathbb{R}^{d \times d}$, the following are equivalent :

$$\forall y \in \{y_d = 0\} \quad M_+ x = M_- x$$

$$\exists c \in \mathbb{R}^d, \text{s.t. } M_+ M_- = c e_d^T$$

$$(I - e_d^T e_d) M_+ = (I - e_d^T e_d) M_-$$

Definition 1. A_1, A_2 are the tensor constant, a is the matrix constant. If M satisfies the above Lemma 2 and $\nabla \cdot (aM_- y) = 0$ in $B(t)_-$. Let $l(y) = M_+ y_{y \geq 0} + M_- y_{y \leq 0} + C, q(y) = r(0)$.

We call l, q the piecewise linear solution of the following equation:

$$\nabla \cdot (A_1 \nabla l) = 0 \quad \text{in } R_+^d \quad (6)$$

$$\nabla \cdot (A_2 \nabla l) + a^T \nabla q = 0, \nabla \cdot (al) = 0, \quad \text{in } R_-^d \quad (7)$$

$$l_+ = l_-; \frac{\partial l}{\partial \nu}|_+ - \frac{\partial l}{\partial \nu}|_- = (A_1 M_+) e_d - (A_2 M_- + r(0)) e_d, \quad \text{on } \{x_d = 0\} \quad (8)$$

Suppose that \mathcal{L} is the space of all the piecewise-linear solutions of the above equation. And $\forall (l, q) \in \mathcal{L}$, we define $\zeta(l, q) = (\frac{\partial l}{\partial \nu})_+ - (\frac{\partial l}{\partial \nu})_-$

Lemma 3. A_1, A_2 are the tensor constant, a is the matrix constant.

$$\nabla \cdot (A_1 \nabla \chi) = 0 \quad \text{in } B(1)_+ \quad (9)$$

$$\nabla \cdot (A_2 \nabla \chi) + a^T \nabla r = 0; \nabla \cdot (a \chi) = 0 \quad \text{in } B(1)_- \quad (10)$$

$$\chi_+ = \chi_-; \frac{\partial \chi}{\partial \nu}|_+ - \frac{\partial \chi}{\partial \nu}|_- = g_0, \quad \text{on } B(1) \cap \{x_d = 0\} \quad (11)$$

χ and r are the weak solutions of the above equations. Then for $\forall k \geq 0, \alpha \in [0, 1]$, we have $\sum_{\pm} \|\chi\|_{H^k(B(\frac{1}{2}), \pm)} \leq C(\|\chi\|_{L^2(B(1))} + |g_0|)$.

Lemma 4. A_1, A_2 are the tensor constant, a is the matrix constant.

$$\nabla \cdot (A_1 \nabla \chi) = 0 \quad \text{in } B(1)_+ \quad (12)$$

$$\nabla \cdot (A_2 \nabla \chi) + a^T \nabla r = 0; \nabla \cdot (a \chi) = 0, \quad \text{in } B(1)_- \quad (13)$$

$$\chi_+ = \chi_-; \frac{\partial \chi}{\partial \nu}|_+ - \frac{\partial \chi}{\partial \nu}|_- = g_0, \quad \text{on } B(1) \cap \{x_d = 0\} \quad (14)$$

χ and r are the weak solutions of the above equations. Let $l(y) = (\nabla \chi)_+(y) y_{y \geq 0} + (\nabla \chi)_-(y) y_{y \leq 0} + \chi(0), q(y) = r(0)$.

By Lemma 1 we know that $l_+ = l_-$ and $(I - e_d^T e_d)(\nabla l)_+ = (I - e_d^T e_d)(\nabla l)_-$ on $B(t) \cap \{y_d = 0\}$. So by Lemma 2, we know $(l, q) \in \mathcal{L}$.

Moreover, $\forall y \in B(\frac{1}{2})$ for some $\beta \in (0, 1)$

$$|\chi(y) - l(y)| \leq |\chi(y) - \chi(0) - (\nabla \chi)(0)y| \leq C|y|^{\beta+1}([\chi]_{C^{1,\beta}(B(\frac{1}{2}))}) \leq C|y|^{\beta+1}((\int_{B(1)} |\chi|^2)^{\frac{1}{2}} + |g_0|)$$

and $\forall y \in B(\frac{1}{2})_-$

$$|r - q| \leq C|y|^\beta ([r]_{C^{0,\beta}(B(\frac{1}{2})_-)}) \leq C|y|^\beta (\int_{B(1)_-} |r|^2)^{\frac{1}{2}}$$

Therefore, $\forall y \in B(\frac{1}{2})$ for some $\beta \in (0, 1)$

$$(3) \quad |\chi(y) - l(y)| \leq |\chi(y) - \chi(0) - (\nabla \chi)(0)y| \leq C|\frac{y}{t}|^{\beta+1}([\chi]_{C^{1,\beta}(B(\frac{1}{2}))}) \leq C|\frac{y}{t}|^{\beta+1}((\int_{B(t)} |\chi|^2)^{\frac{1}{2}} + t|g_0|)$$

(4) and $\forall y \in B(\frac{1}{2})_-$

$$(5) \quad |r - q| \leq C|\frac{y}{t}|^\beta ([r]_{C^{0,\beta}(B(\frac{1}{2})_-)}) \leq C|\frac{y}{t}|^\beta (\int_{B(t)_-} |r|^2)^{\frac{1}{2}}$$

Lemma 5. A_1, A_2 are the tensor constant, a is the matrix constant.

$$\nabla \cdot (A_1 \nabla \chi) = 0 \quad \text{in } B(1)_+ \quad (15)$$

$$\nabla \cdot (A_2 \nabla \chi) + a^T \nabla r = 0; \nabla \cdot (a \chi) = 0, \quad \text{in } B(1)_- \quad (16)$$

$$\chi_+ = \chi_-; \frac{\partial \chi}{\partial \nu}|_+ - \frac{\partial \chi}{\partial \nu}|_- = g_0, \quad \text{on } B(1) \cap \{x_d = 0\} \quad (17)$$

χ and r are the weak solutions of the above equations. Moreover, $\forall \rho \in (0, t)$ integrate the above inequalities to get

$$(\int_{B(\rho)} |\chi - l|^2)^{\frac{1}{2}} + \rho|g_0 - \zeta(l, q)| \leq |\frac{\rho}{t}|^{\beta+1} ((\int_{B(t)} |\chi|^2)^{\frac{1}{2}} + t|g_0|)$$

So $\forall (l', q') \in \mathcal{L}$, by the inequality above, we have

$$\inf_{l, q \in \mathcal{L}} (\int_{B(\rho)} |\chi - l|^2)^{\frac{1}{2}} + \rho|g_0 - \zeta(l, q)| \leq C|\frac{\rho}{t}|^{\beta+1} \inf_{l, q \in \mathcal{L}} ((\int_{B(t)} |\chi - l|^2)^{\frac{1}{2}} + t|g_0|)$$

Lemma 6. Suppose $\phi : R_+ \rightarrow R_+$ is a non-decreasing non-negative function satisfying $\phi(\rho) \leq C(\frac{\rho}{t})^\beta \phi(r) + Br^\alpha$, where $\beta > \alpha > 0, C > 0$.

Then $\forall 0 < \rho < r < R, \exists C_1, s.t. \phi(\rho) \leq C_1(\frac{\rho}{t})^\alpha \phi(r) + Br^\alpha$

We adjusted the lemmas from the schauder theory method into a form suitable for the equations of the Cell Problem.

AIM was utilized to complete the schauder theory related lemmas. These contents are input into the model as the "context" section served as a methodological guide for subsequent regularity proofs.

Subproblem: Regularity of Cell Problem



- We transform the problem into the proof of the following theorem.

Theorem 1. Suppose A_1, A_2, a are C^α -Hölder continuous, we set $S_t = B(t) \cap \{x_d = 0\}$. χ, r are the weak solutions of the following equations: for $V \in H_0^1(B(1); R^d)$

$$(\nabla V : A_1 \nabla \chi)_{B_+} + (\nabla V : A_2 \nabla \chi)_{B_-} + (r, \nabla \cdot (a\chi))_{B_-} = 0 \quad (18)$$

$$\nabla \cdot (a\chi) = 0 \quad (19)$$

Please prove $\sum_{\pm} \|\chi\|_{C^{1,\alpha}(B(\frac{1}{2},))} \leq C \|\chi\|_{L^2(B(1))}$.

This is equivalent to prove $\forall \rho \in (0, \frac{1}{4})$, we have

$$\inf_{l,q \in \mathcal{L}} \left(\int_{B(\rho)} |u - l|^2 \right)^{\frac{1}{2}} \leq C \rho^{1+\alpha} \sum \|u\|_{L^2(B(\frac{3}{4}))}$$

Here, (l, q) are the piecewise linear function and $B(\rho)$ is a small ball with any given center of the ball on $S_{\frac{3}{4}}$.

We adjusted the lemmas from the schauder theory method into a form suitable for the equations of the Cell Problem.

We instruct AIM to use schauder theory methods to prove this theorem. Based on feedback from experimental results, we iteratively split the problem and ultimately complete the proof.

Subproblem: Regularity of Cell Problem



- Specifically, the entire problem is divided into the following three parts. AIM progressively completes the proof details for each part. After iterations, AIM provided a process with a high level of completeness and ultimately completed the proof.

1

Perturbation of the Equation

$$\begin{aligned}
 & (\nabla V : A_1^0 \nabla w_t)_{B_+} + (\nabla V : A_2^0 \nabla w_t)_{B_-} + (s_t, \nabla \cdot (a^0 V))_{B_-} = 0 \\
 & \nabla \cdot (a^0 w_t) = 0 \quad \text{in } B(t)_- \\
 & w_t = \chi \quad \text{on } \partial B(t) \quad \text{and} \quad s_t = r \quad \text{on } \partial B(t)_-
 \end{aligned}$$

2

Morrey's Estimate Bootstrap Analysis

$$\begin{aligned}
 \Psi(r) &= \int_{B(r)} |\nabla \chi|^2 + \int_{B(r)_-} |r|^2 \\
 \Psi(\rho) &\leq C\left(\frac{\rho}{t}\right)^d \Psi(t) + Ct^{2\alpha} \Psi(t), \forall 0 < \rho < t < \frac{1}{2}
 \end{aligned}$$

χ is C^β
Hölder continuous

3

Hölder Regularity

$$\begin{aligned}
 \Phi(r) &= \inf_{l,q \in \mathcal{L}} \left\{ \int_{B(r)} |\chi - l|^2 + r^{d+2} |\zeta(l, q)|^2 \right\} \\
 \Phi(\rho) &\leq C\left(\frac{\rho}{t}\right)^{d+2\beta+2} \Phi(t) + Ct^{d+2+\alpha} \Psi\left(\frac{1}{2}\right)
 \end{aligned}$$

$\chi \in C^{1,\alpha}(\overline{B}_{\frac{1}{2}}; R^d), \forall \rho \in (0, \frac{1}{2})$



Beyond expectations

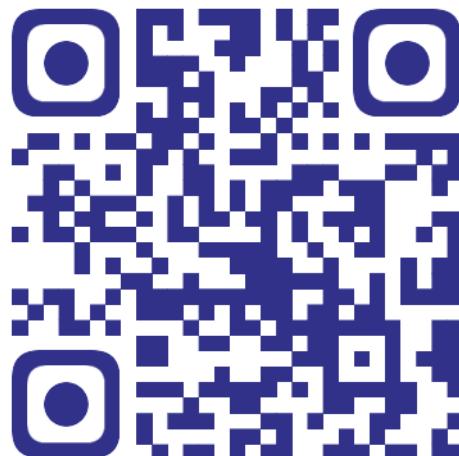
Final Conclusion



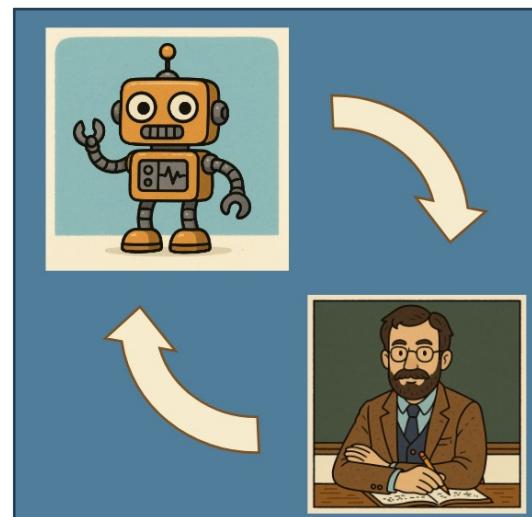
Finally, based on the regularity obtained from the proof, we completed the error control of the homogenization limit.

$$\|u_\varepsilon - u_{\lim}\|_{H^1(\Omega)} \lesssim \varepsilon^{\frac{1}{2}}$$

Here is the error control conclusion between the solution of the original equation and the solution of the homogenized equation.



Full Proof & Insights



Key Takeaway

AI may still be a flawed individual researcher today.

Yet, it can already serve as a valuable research partner—if used wisely.

AIM Online Demo



- We have deployed a web frontend of AIM systems and invited some domain experts to use it and evaluate its performance.

AI Mathematician

Peng Li
ADMIN unlimited

您好, Peng

探索您的数学研究项目

您的研究项目 (48)

Complex structure ... ENDED 7/23/2025
Prove that there exists a complex structure on the six dimensional sphere S^6
引理: 17 39m ago
创建者: 陈嘉熙 删除

Parabolic inductio... SOLVED
Prove that $r_B \circ i_B : T(k) / T^0(k)$ is locally isomorphic to \mathbb{C}^{n+1} .
引理: 8
创建者: 陈起渊

← Homepage

AI Mathematician

Peng Li
ADMIN unlimited

Symplectic foliation

Let M be a compact manifold of dimension 5. There is a foliation \mathcal{F} of dimension 4 manifolds over it. Assume that there is a 2-form ω over M which is non-degenerated on \mathcal{F} , can we prove that $\pi_1(M)$ is non trivial?

Context
When any leaf of the foliation is compact, the theorem can be proved by calculating $\omega \wedge \omega$ as an element in $H^4(M)$. When the integrability of the foliation is dropped, the theorem can be disproved by considering contact manifolds.

创建于 7/15/2025 · 最后活跃 7/15/2025 SOLVED

查看设置

引理列表 (6)

搜索引理...

lemma-1 ● 已证明
Let (M) be a compact, connected, oriented 5 -dimensional manifold, and let (\mathcal{F}) be an oriented foliation of dimension 4 on (M) .
次要 7/15/2025, 3:48:09 PM

lemma-2 ● 待处理
Let (M) be a compact, connected, oriented smooth manifold of dimension $2n+1$, and let (\mathcal{F}) be an oriented foliation of dimension $2n$.

引理详情

lemma-1
状态: ✓ 已证明 重要性: 次要 评审次数: 3 依赖: 无

引理陈述:
Let M be a compact, connected, oriented 5 -dimensional manifold, and let \mathcal{F} be an oriented foliation of dimension 4 on M . Suppose there exists a smooth 2 -form $\omega \in \Omega^2(M)$ such that, for every point $p \in M$, the restriction of ω to the tangent space of the leaf through p ,

$$\omega|_{T_p \mathcal{F}} : T_p \mathcal{F} \times T_p \mathcal{F} \longrightarrow \mathbb{R},$$

Project page →

Some User Feedbacks of AIM



清华大学
Tsinghua University

AIM successfully addressed some group classification, and provides a detailed proof to it.



Symplectic foliation

Let M be on \mathcal{F} , can

theorem-6

状态: ✓ 已证明 重要性: 关键 评审次数: 9 依赖: 1, 3

Context

When a dropped

引理陈述:

Let M be a compact manifold of dimension 5. There is a foliation \mathcal{F} of dimension 4 manifolds over it. Assume that there is a 2-form ω over M which is non-degenerated on \mathcal{F} , can we prove

AIM failed to directly address a research level problem. It exceeded the maximum complexity that can be handled by AIM.



Classify certain finite subgroup of $SO(4)$

Suppose A is a finite subgroup of $SO(4)$. Let l be a real line bundle on $S^3 \setminus Z$ which is isomorphic to $S^3 \setminus Z$. Then A is isomorphic to a subgroup of $SO(4)$.

创建于 7/17/2025 · 最后活跃于 7/17/2025

证明:

We sketch one explicit counter-example, coming from the binary tetrahedral group.

1. Let $\tilde{T} \subset S^3$ be the binary tetrahedral subgroup of order 24, and let

$$A = \tilde{T}/\{\pm 1\} \subset SO(4)$$

be its image under the double covering $S^3 \rightarrow SO(4)$. Inside \tilde{T} there are exactly four cyclic subgroups of order 3.

A hard problem on symplectic foliation. The user omitted a condition in the query, and AIM provides a valid counter example for this problem.



三维空间中管状邻域Z2调和函数的存在性问题

Given any positive integer n , is there a Z2 harmonic function f on $S^3 \setminus N$ such that $|f| = o(n)$ as $r \rightarrow 0$.

This is known to be true if the metric is given by the tri functions. However, for a more general smooth metric

Context

Let (M, g) be a 3-dimensional smooth oriented Riemannian manifold with boundary $\partial M = S^1$. Suppose there is a real line bundle l over M .

lemma-12

状态: 待处理 重要性: 次要 评审次数: 6 依赖: 2, 3, 10

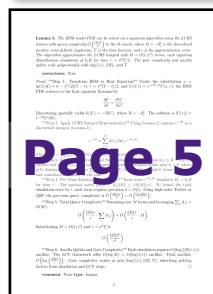
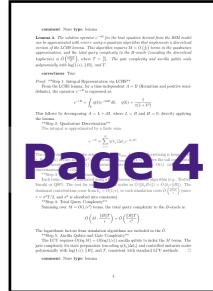
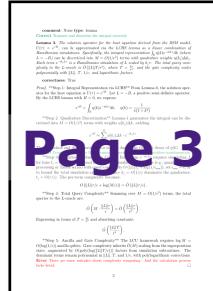
引理陈述:

Let (M, g) be as in Memory ID 0, with tubular neighbourhood $N \cong S^1_s \times D_{r,\theta}$ and real line bundle $l \rightarrow N \setminus K$ of monodromy -1 . Suppose moreover that in local coordinates (s, r, θ) the metric g has the form

Limitation 1: Redundant Exploration



- Currently, AIM often explores in the same direction, presenting a series of similar conjectures and identical lemmas, which increases costs, reduces efficiency, and limits the performance ceiling.

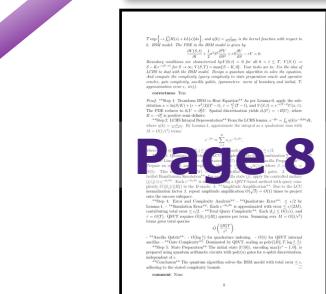
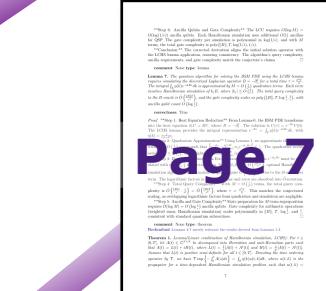
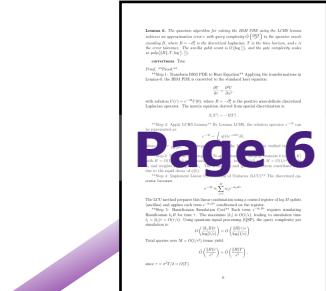


Lemma 4. *The solution operator $e^{-\tau B}$ for the heat equation derived from the BSM model can be approximated with error ϵ using a quantum algorithm that implements a discretized version of the LCHS lemma. This algorithm requires $M = O(\frac{1}{\epsilon^2})$ terms in the quadrature approximation, and the total query complexity to the B -oracle (encoding the discretized Laplacian) is $\tilde{O}\left(\frac{\|B\|T}{\epsilon^3}\right)$, where $T = \frac{2\tau}{\sigma^2}$. The gate complexity and ancilla qubits scale polynomially with $\log(1/\epsilon)$, $\|B\|$, and T .*

Lemma 6. *The quantum algorithm for solving the BSM PDE using the LCHS lemma achieves an approximation error ϵ with query complexity $\tilde{O}\left(\frac{\|B\|T}{\epsilon^3}\right)$ to the operator oracle encoding B , where $B = -\partial_x^2$ is the discretized laplacian, T is the simulation time, and ϵ is the error tolerance. The ancilla qubit count is $O(\log \frac{1}{\epsilon})$, and the gate complexity scales as $\text{poly}(\|B\|, T, \log \frac{1}{\epsilon}, \frac{1}{\epsilon})$.*

Lemma 7. *The quantum algorithm for solving the BSM PDE using the LCHS lemma requires simulating the discretized Laplacian operator $B = -\partial_x^2$ for a total time $\tau = \frac{\sigma^2 T}{2}$. The integral $\int_{\mathbb{R}} \eta(k) e^{-ikB\tau} dk$ is approximated by $M = O(\frac{1}{\epsilon^2})$ quadrature terms. Each term involves Hamiltonian simulation of $k_j B$, where $|k_j| \leq O(\frac{1}{\epsilon})$. The total query complexity to the B -oracle is $\tilde{O}\left(\frac{\|B\|T}{\epsilon^3}\right)$, and the gate complexity scales as $\text{poly}(\|B\|, T, \log \frac{1}{\epsilon}, \frac{1}{\epsilon})$, with ancilla qubit count $O(\log \frac{1}{\epsilon})$.*

Three Similar Lemmas



Limitation 2: Insufficient Understanding of Mathematical Settings



清华大学
Tsinghua University

- The current AIM has limited ability to understand lengthy mathematical setups and background conditions, which can lead to errors in the agent's analysis process.

Then as $\varepsilon \rightarrow 0$ one has, up to a subsequence, $u_\varepsilon \rightharpoonup u_0$ in $H^1(\Omega)$, $u_\varepsilon \rightarrow u_0$ in $L^2(\Omega)$, $p_\varepsilon \xrightarrow{\text{two-scale}} p_1(x, y)$ in $\Omega \times Y_i$, where $u_0 \in H_R^1(\Omega; \mathbb{R}^d)$ is the unique solution of the homogenized Lamé system $-\operatorname{div}_x [C^{\text{hom}} D_x(u_0)] = 0$ in Ω , $C^{\text{hom}} D_x(u_0) \cdot n = g$ on $\partial\Omega$, and the effective fourth-order tensor C^{hom} is given by the following periodic cell transmission problem: for each fixed symmetric $E \in \mathbb{R}_{\text{sym}}^{d \times d}$ find $(\chi_e^E, \chi_i^E, \pi^E) \in H_{\text{per}}^1(Y_e; \mathbb{R}^d) \times H_{\text{per}}^1(Y_i; \mathbb{R}^d) \times L_{\text{per}}^2(Y_i)/\mathbb{R}$ solving

- (1) In the elastic cell Y_e : $-\operatorname{div}_y [C(E + D_y \chi_e^E)] = 0$, $\operatorname{div}_y(Ey + \chi_e^E) = 0$,
- (2) In the fluid cell Y_i : $-\mu \Delta_y \chi_i^E + \nabla_y \pi^E = 0$, $\operatorname{div}_y(Ey + \chi_i^E) = 0$,
- (3) On the material interface $\Gamma = \partial Y_i$: $\chi_e^E = \chi_i^E$, $[C(E + D_y \chi_e^E) \cdot n] = [2\mu D_y \chi_i^E - \pi^E I] \cdot n$,

The lack of understanding of the boundaries of the unit cell here has led to conclusions that do not align with the actual situation

Limitation 3: Lack of Derivation Details



- AIM tends to "skip steps", which is detrimental to both manual and automated verification of the proof and may lead to incorrect proofs.

Step 2: Formulate the Projected Equations For test functions $v \in V_N$ and $\psi \in W_{k,N}$, the Galerkin approximations satisfy the projected weak form:

$$\int_{\Omega} \partial_t u^N v \, dx + \int_{\Omega} \nabla u^N \cdot \nabla v \, dx + \int_{\Omega} \rho u^N v \, dx \\ + \beta \int_S u^N v \, ds + \sum_{k=1}^m \alpha_k \int_S (\partial_t \varphi_k^N - \Delta_S \varphi_k^N) v \, ds = 0,$$

$$\int_S \partial_t \varphi_k^N \psi \, ds + \int_S \nabla_S \varphi_k^N \cdot \nabla_S \psi \, ds + d_k \int_S \varphi_k^N \psi \, ds = \int_S u^N \psi \, ds.$$

Step 3: Solve the ODE System Substituting $u^N = \sum_{j=1}^N a_j(t)w_j$ and $\varphi_k^N = \sum_{l=1}^N b_{k,l}(t)\theta_{k,l}$ into the projected equations yields a linear ODE system for $a_j(t)$ and $b_{k,l}(t)$. The coefficients are smooth (as eigenfunctions are C^∞), ensuring continuity. By the Cauchy-Lipschitz theorem, unique solutions exist on $[0, T]$.

[Correct] The agent gets the ODE satisfied with the approximated solution.

[Vague] It is better to have more detailed process.

The specific derivation and analysis process of the ODE system is not provided here, but the conclusion is correct.

Limitation 4: Rising Demand, Limited Supply



- Actual user demands exhibit considerable diversity and extend substantially beyond the current operational scope of AIM.

User Expectations	AIM Capabilities
Interact with minimal input	Provide a relatively complete problem description
Chinese-language input	English-language input is more effective
Zero tolerance for errors	Is not yet error-free
Capable of solving any problem	Has its own limitations
.....

Outlook: A Bold Bet on Natural Language



- For the first time, large language models performed on a par with gold medallists in the International Mathematical Olympiad (IMO).

The screenshot shows a news article from the journal 'nature'. The header includes links for 'Explore content', 'About the journal', 'Publish with us', and 'Subscribe'. Below the header, the URL 'nature > news > article' and the date '24 July 2025' are visible. The main title of the article is 'DeepMind and OpenAI models solve maths problems at level of top students'. At the bottom of the article preview, there is a small image of a gold medal with the text 'International Mathematical Olympiad' and '2022, Oslo, Norway'.



[DeepMind AI crushes tough maths problems on par with top human solvers](#)

big paradigm shift

But the grades this year hide a “big paradigm shift,” says Thang Luong, a computer scientist at DeepMind in Mountain View, California. The company achieved its previous feats using two artificial intelligence (AI) tools specifically designed to carry out rigorous logical steps in mathematical proofs calculations, called AlphaGeometry and AlphaProof. The process required human experts to first translate the problems’ statements into something similar to a programming

language, and then to translate the AI’s solutions back into English. **This year, everything is natural language, end to end**

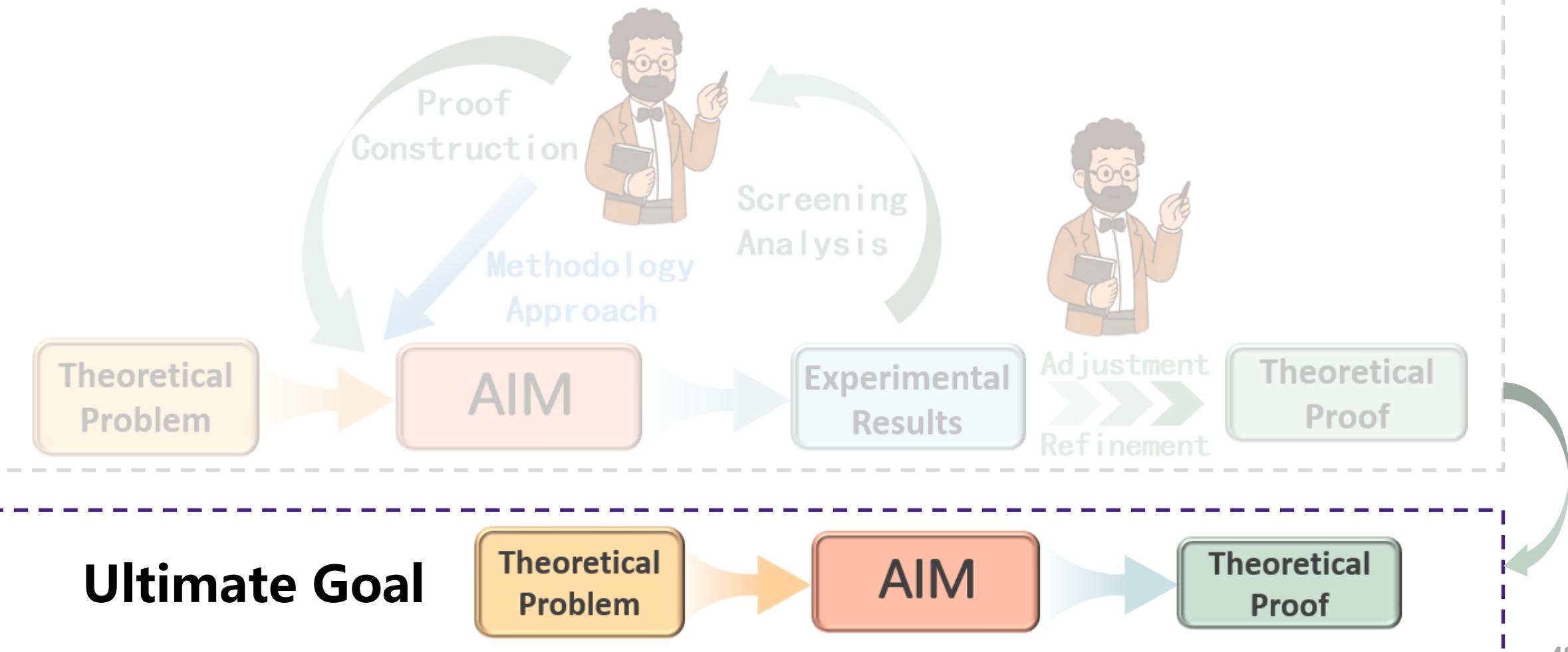
“This year, everything is natural language, end to end,” says Luong. The team employed a large language model (LLM) called DeepThink, which is based on its Gemini system but with some additional developments that made it better and faster at producing mathematical arguments, such as handling multiple chains of thought in parallel. “For a long time, I didn’t think we could go that far with LLMs,” Luong adds.

Outlook: Assistive to Proactive



清华大学
Tsinghua University

Auxiliary Proof + Idea Validation + Open Exploration

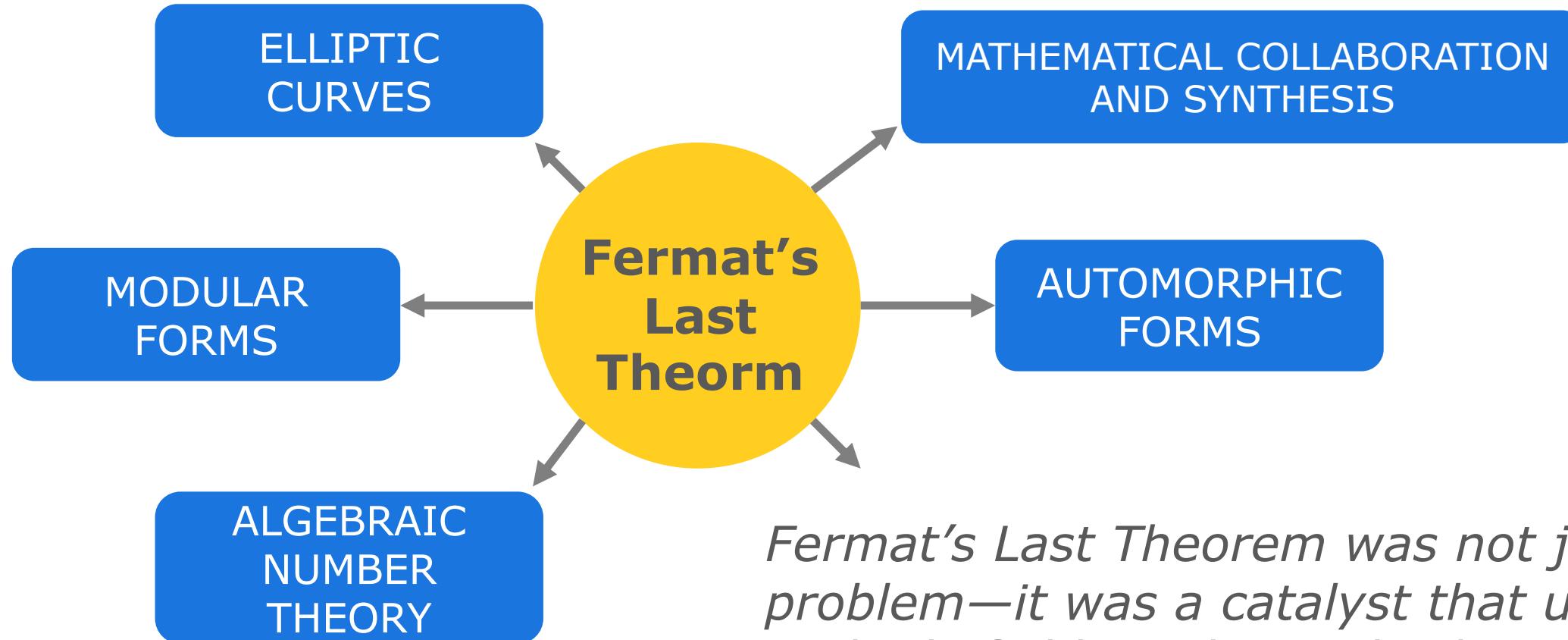


Outlook: Pose New Mathematical Problems



清华大学
Tsinghua University

- Good problems drive mathematics; we expect AIM to help pose them.



Fermat's Last Theorem was not just a problem—it was a catalyst that united multiple fields and gave birth to modern number theory.

Summary



清华大学
Tsinghua University

- Large language models enable greater AI impact in mathematical research.
- Three key characteristics distinguish mathematical research from problem-solving, including long reasoning, procedural rigor, and answer existence.
- We propose the AI mathematician system **AIM**, which has achieved preliminary success on four research-level mathematical problems, showing promising potential.
- In the future, AI will play a more proactive and important role in mathematical research.



Our AIM is AI Mathematician!

