Medical Imaging Analysis
Image Registration

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1 Introduction

Image registration is the procedure consisting of aligning an unregistered image (also called moving image) into a template image (also called fixed image) via a geometric transformation. This problem is usually addressed as presented in Fig. 1. An iterative procedure takes place to infer the geometric transformation (parametric or non-parametric) via an optimizer, which maximizes the similarity between the two images.

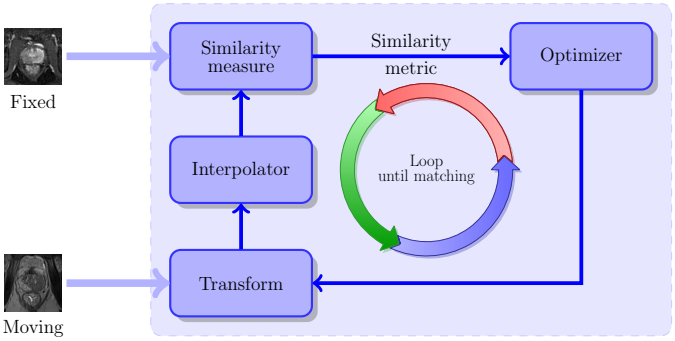

Figure 1: Typical framework involved to solve the registration problem.

The aim of this lab is to be familiar with the different components of a typical image registration framework. A fully working registration framework is provided in the Matlab files attached, implementing a rigid registration algorithm which minimises the sum of squared distances (SSD). The figure
In this lab you will learn:

- Understand the concept and components of an image registration framework.
- Modify the framework to incorporate:
  - Mutual Information metric as a new similarity metric.
  - Affine transformation.
  - Multi-resolution framework.

2 Registration framework

Read and understand the Matlab files provided and answer the following issues:

- Identify each of the components of an image registration framework, state their type and where they can be found (file name and aprox line number).

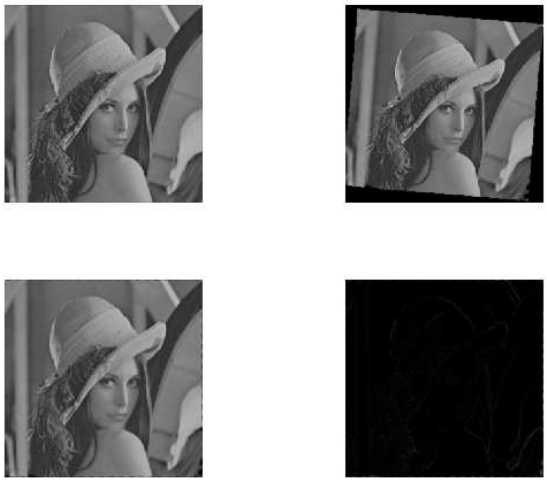

Figure 2: Example of image registration using SSD and an affine transformation. Fixed and moving images (top row) and registered moving and its difference with fixed (bottom row)

- What is the function of the `scale` vector?
- Why is Gaussian smoothing used?
- Where is the center of rotation of the transformation?

3 Similarity metric. Mutual information

Add a new similarity metric to framework: Mutual information. Implement the Mutual Information metric, you can only use the Matlab function to compute an histogram of an image, (imhist).

4 Transformation. Affine transformation

Modify the framework to be able to deal with full affine 2D transformations. Justify how you initialise the transformation.

5 Multi-resolution.

Implement the above modifications in a multi-resolution registration framework. The number of resolutions should be a parameter of the framework, discuss how each resolution is initialised. Justify the benefits of multi-resolution in terms of computation time and/or accuracy of the final result, compared to a single resolution.

Submission

Report and source files containing: (no more than 7 pages)

- Report:
  - Explanation of the registration framework and its components.
  - Description of the implementation aspects requested in Sections 1-5.
  - Registration results using lena2.png and lenag4.png as Fixed and lena3.png and lena1.png as moving images with the different combinations of the registration framework: different metrics, transformations and multi-resolution levels. For selected (representative) cases, plot the metric against iterations, computation time, registration results and final error (propose a quantitative error measure).
  - Discuss the results: are they what you were expecting if not explain why.
  - Detail the problems found in the assignment and/or your opinion on the development.
- Source code in Matlab containing
  - Mutual Information similarity metric.
  - Affine transformation.
  - Multi-resolution.