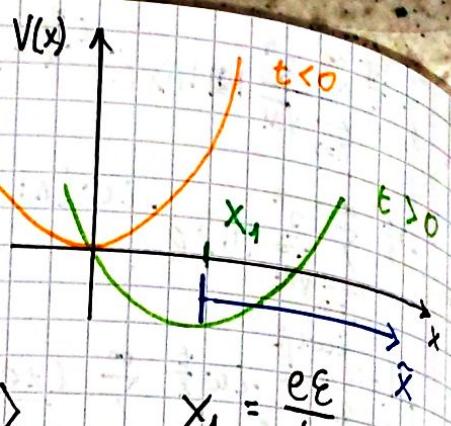


$$H(t) = \begin{cases} t < 0; \frac{p^2}{2m} + \frac{1}{2} kx^2 = H \\ t > 0; \frac{p^2}{2m} + \frac{1}{2} kx^2 - e\epsilon_x = \tilde{H} \end{cases}$$



$$|\Psi, 0\rangle = |0\rangle \rightarrow a|\Psi, 0\rangle = 0$$

$$|\Psi, t\rangle = ? \rightarrow \tilde{a}|\Psi, 0\rangle = -\frac{x_1}{\sqrt{2}x_0} |\Psi, 0\rangle$$

$$x_1 = \frac{e\epsilon}{h}$$

Utrajuli smo se z koherentnimi stanji: (ostanjo loherentna tudi složi cas)

$$|z\rangle = z|z\rangle$$

$$|z, t\rangle = e^{-\frac{i\omega t}{2}} |z e^{-i\omega t}\rangle$$

$$\langle x \rangle = \sqrt{2}x_0 \operatorname{Re} z$$

$$|\Psi_z(x)\rangle = \frac{1}{\sqrt{\pi x}} e^{-\frac{(x - \sqrt{2}\epsilon_0 P_{0z})^2}{2x_0}} e^{\frac{i\sqrt{2}p_0 \ln z}{\hbar} x}$$

gaussov
valovni
puket

Pogljimo si:

$$z(t)$$

$$z(0) = -\frac{x_1}{\sqrt{2}x_0}$$

$$z(t) = -\frac{x_1}{\sqrt{2}x_0} e^{-i\omega t}$$

$$\langle x, t \rangle = ?$$

$$\langle \tilde{x}, t \rangle = \sqrt{2}x_0 \operatorname{Re}(z(t)) =$$

$$= \sqrt{2}x_0 \operatorname{Re}\left(-\frac{x_1}{\sqrt{2}x_0} e^{-i\omega t}\right) = -x_0 \cos(\omega t)$$

$$\tilde{x} = x - x_1$$

$$x = \tilde{x} + x_1$$

Upoštevamo povezano med x in \tilde{x} :

$$\langle x, t \rangle = -x_1 \cos(\omega t) + x_1 = \underline{x_1(1 - \cos(\omega t))}$$

To pa dobimo tudi v glasicienem
primeru

[2D Harmonic oscillator]

$$H = \frac{p^2}{2m} + \frac{1}{2} \omega_x x^2 + \frac{1}{2} \omega_y y^2 \quad p^2 = (\vec{p})^2$$

$$\vec{p} = (p_x, p_y) = (-i\hbar \frac{\partial}{\partial y}, -i\hbar \frac{\partial}{\partial x}) = -i\hbar \vec{V}$$

$$p^2 = p_x^2 + p_y^2$$

Tako lahko Hamiltonian razstavimo na dva dela:

$$H = H_x + H_y$$

Separacija spremenljivih

$$\Psi(x, y) = f(x) \chi(y)$$

$$H_x f_n(x) = E_n^x f_n(x)$$

$$H_y \chi_m(y) = E_m^y \chi_m(y)$$

$$\Rightarrow H f_n(x) \chi_m(y) = (E_n^x + E_m^y) f_n(x) \chi_m(y)$$

V Diracovem zapisu je to:

$$H |n\rangle_x |m\rangle_y = (E_n^x + E_m^y) |n\rangle_x |m\rangle_y$$

↑
prostor x
↑
obligato

OZ.

$$H |n m\rangle = (E_n^x + E_m^y) |n m\rangle$$

Se nanaša ↑ ↑ Se nanaša na
na x y

Sporazimo kako se resi LHO za 1D:

$$H_x |n\rangle_x = \hbar \omega_x (n_x + \frac{1}{2}) |n\rangle_x ; \quad \omega_x = \sqrt{\frac{\omega_x}{m}}$$

$$H_y |n_y\rangle = \hbar \omega_y (n_y + \frac{1}{2}) |n_y\rangle ; \quad \omega_y = \sqrt{\frac{\omega_y}{m}}$$

Oznaka:

$$|n\rangle_x = |n_x\rangle$$

Tako je celotno:

$$H|n_x n_y\rangle = \hbar(\omega_x(n_x + \frac{1}{2}) + \omega_y(n_y + \frac{1}{2}))|n_x n_y\rangle$$

To vse velja $\omega_x > 0$ in $\omega_y > 0$

Pogojmo si primer $\omega_x > 0$ in $\omega_y = 0$

$$H_y = \frac{p_y^2}{2m} + 0; \text{ Konstanten potencial}$$

(resitve so svari valovi)

$$p_y e^{i\omega_y y} = \hbar q_y e^{i\omega_y y}$$
$$\Rightarrow H_y e^{i\omega_y y} = \frac{\hbar^2 q_y^2}{2m} e^{i\omega_y y}$$

q_y ... Valovni vektor ki karakterizira
svari val

$$H_y |q_y\rangle = \frac{\hbar^2 q_y^2}{2m} |q_y\rangle$$

Tako je 2D problem:

$$H|n_x q_y\rangle = \left[\hbar\omega_x(n_x + \frac{1}{2}) + \frac{\hbar^2 q_y^2}{2m} \right] |n_x q_y\rangle$$

Vzimimo se na splošen primer $\omega_x > 0$ in $\omega_y > 0$

Pogojmo si izotropni harmonski oscilator $\omega_x = \omega_y = \omega$

$$H = \frac{p^2}{2m} + \frac{1}{2}\omega(x^2 + y^2) = \frac{p^2}{2m} + \frac{1}{2}\omega r^2$$

$\underbrace{r^2}_{r^2}$

Odvisek kc od oddajnik
od izhodišča amplitud kc od
polarnega kvanta

$$H|n_x n_y\rangle = \hbar\omega(n_x + n_y + 1)|n_x n_y\rangle$$



$|20\rangle, |102\rangle, |111\rangle$

$|101\rangle, |110\rangle \rightarrow$ Degenerirano vezjeno

$|00\rangle$

$|\alpha|10\rangle + |\beta|01\rangle$

Stanje

Pokažimo, da $|10\rangle$ in $|10\rangle$ res tvorita 2D bazo prostora vseh

funkcij, ki imajo energijo $2\hbar\omega$

$$H(\alpha|10\rangle + \beta|01\rangle) = \alpha H|10\rangle + \beta H|01\rangle = 2\hbar\omega(\alpha|10\rangle + \beta|01\rangle)$$

$|10\rangle$ $|01\rangle$

Tudi lin. komb. je lastna funkcija z isto energijo ✓

Torej: $H = \frac{p^2}{2m} + V(r)$

V smeri simetrijske osi potenciala se ohranja vrtlina kolicina. To se zapise s komutatorjem kot:

$$[H, L_z] = 0 ; L_z = xP_y - yP_x = -i\hbar \frac{\partial}{\partial p}$$

Ker operatorja komutirata lahko naredimo lastne funkcije oben hkrati.

Kateri linearne kombinacije lastnih stanj H so lastne funkcije L_z ?

Poglejmo to za 2x degenerirano 1. vzvijeno stanje.

$$L_z |\Psi\rangle = \lambda |\Psi\rangle$$

$$-i\hbar \frac{\partial}{\partial p} \Psi(p) = \lambda \Psi(p) \quad \begin{matrix} \text{Resimo diferencialno} \\ \text{enacbu} \end{matrix}$$

$$-i\hbar \Psi'(p) - \lambda \Psi(p) = 0 \Rightarrow \Psi(p) = C e^{i \frac{\lambda \omega p}{\hbar}}$$

Robni pogoj: $\Psi(p) = \Psi(p+2\pi)$ $\Rightarrow \frac{\lambda}{\hbar} = m \in \mathbb{Z}$

Tako so lastne funkcije:

$$\Psi(p) = C e^{im\omega p}$$

L_z normalizacija:

$$\int_0^{2\pi} |\Psi(p)|^2 dp = 1$$

$$\Psi(p) = \frac{1}{\sqrt{2\pi}} e^{im\omega p}$$

Pokažimo, da $|10\rangle$ in $|11\rangle$ res tvorita 2D bazo prostora vseh funkcij, ki imajo energijo $2\hbar\omega$

$$H(\alpha|10\rangle + \beta|11\rangle) = \alpha H|10\rangle + \beta H|11\rangle = 2\hbar\omega(\alpha|10\rangle + \beta|11\rangle)$$

$$\underbrace{2\hbar\omega|10\rangle}_{\text{zravn.}} \quad \underbrace{2\hbar\omega|11\rangle}_{\text{zravn.}}$$

Tudi lin. komb. je lastna funkcija, z isto energijo ✓

Torej: $H = \frac{p^2}{2m} + V(r)$

V smeri simetrijske osi potenciala se ohranja vrtilna kolicina. To se zapise s komutatorjem kot:

$$[H, L_z] = 0 ; L_z = xP_y - yP_x = -i\hbar \frac{\partial}{\partial r}$$

Ker operatorja komutirata lahko najdemo lastne funkcije oben hkrati.

Kateri linearne kombinacije lastnih stanj H so lastne funkcije L_z ?

Pogojimo to za 2x degenerirano 1. vzbujeno stanje.

$$L_z |\Psi\rangle = \lambda |\Psi\rangle$$

$$-i\hbar \frac{\partial}{\partial r} \Psi(r) = \lambda \Psi(r)$$

Resimo diferencialno enačbo

\uparrow

$$-i\hbar \Psi'(r) - \lambda \Psi(r) = 0 \Rightarrow \Psi(r) = C e^{i \frac{\lambda \omega r}{\hbar}}$$

Robni pogoj: $\Psi(r) = \Psi(r+2\pi) \Rightarrow \frac{\lambda}{\hbar} = m \in \mathbb{Z}$

Tako so lastne funkcije:

$$\Psi(r) = C e^{im\omega r}$$

\rightarrow Iz normalizacije:
 $\int_0^{2\pi} |\Psi(r)|^2 dr = 1$

$$\Psi(r) = \frac{1}{\sqrt{2\pi}} e^{im\omega r}$$

$$\Psi_{10}(x, y) = \alpha \Psi_{10}(x, y) + \beta \Psi_{01}(x, y)$$

$$\Psi_{10}(x, y) = \Psi_1(x) \cdot \Psi_0(y)$$

$$\Psi_{01}(x, y) = \Psi_0(x) \cdot \Psi_1(y)$$

Zanima nas:

$$\Psi_0(x) = \frac{1}{\sqrt{4\pi x_0^2}} e^{-\frac{x^2}{2x_0^2}}$$

$$\Psi_1(x) = ?$$

$$a^\dagger |0\rangle = |1\rangle$$

$$\Rightarrow \frac{1}{\sqrt{2}} \left(\frac{x}{x_0} - i \frac{p}{p_0} \right) \Psi_0(x) = \Psi_1(x); \quad p_x = -i\hbar \frac{d}{dx}, \quad p_0 = \frac{\hbar}{x_0}$$

Tajči je:

$$\Psi_1(x) = \frac{1}{\sqrt{2}} \frac{1}{\sqrt{\pi x_0^2}} \left[\frac{x}{x_0} e^{-\frac{x^2}{2x_0^2}} - i \frac{1}{p_0} \left(-i\hbar \left(\frac{-2x}{2x_0^2} \right) e^{-\frac{x^2}{2x_0^2}} \right) \right] =$$

$$= \frac{1}{\sqrt{4\pi x_0^2}} e^{-\frac{x^2}{2x_0^2}} \left[\frac{x}{x_0} + \frac{x_0}{\hbar} \frac{x}{x_0^2} \right] =$$

$$x_0 = \sqrt{\frac{\hbar}{m\omega}} = y_0$$

$$= \sqrt{2} \frac{x}{x_0} \Psi_0(x)$$

Tako tako zapisemo Ψ_{10} in Ψ_{01} kot:

$$\begin{aligned} \Psi_{10}(x, y) &= \frac{1}{\sqrt{\pi x_0^2}} \left[\sqrt{2} \frac{x}{x_0} e^{-\frac{x^2}{2x_0^2}} \right] \frac{1}{\sqrt{4\pi x_0^2}} e^{-\frac{y^2}{2x_0^2}} = \\ &= \frac{\sqrt{2}}{\sqrt{\pi x_0^2}} \frac{x}{x_0} e^{-\frac{1}{2x_0^2}(x^2+y^2)} \end{aligned}$$

V polarnih koordinatah torej:

$$\Psi_{10}(r, \phi) = \sqrt{\frac{2}{\pi x_0^2}} \frac{r \cos \phi}{x_0} e^{-\frac{1}{2x_0^2} r^2} = \cos \phi F(r)$$

Rabimo dabit
e^{iφ}

$$\Psi_{10}(r, \phi) = \dots = \sin \phi F(r)$$

$$1 \cdot \cos \varphi + i \sin \varphi = e^{i\varphi} \quad (m=1)$$

$$1 \cdot \cos \varphi - i \sin \varphi = e^{-i\varphi} \quad (m=-1)$$

$$|m=1\rangle = 1 \cdot |10\rangle + i|01\rangle \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{Ta dva VF nista}$$

$$|m=-1\rangle = 1 \cdot |10\rangle - i|01\rangle \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{Normalizirani}$$

$$\left| \frac{1}{\sqrt{2}} \right|^2 + \left| \frac{i}{\sqrt{2}} \right|^2 = 1$$

Torej:

$$|m=1\rangle = \frac{1}{\sqrt{2}}(|10\rangle + i|01\rangle)$$

$$|m=-1\rangle = \frac{1}{\sqrt{2}}(|10\rangle - i|01\rangle)$$

Dруг postopek za to, ko je preprostejši in ni treba nic "vrdati"

$$|\psi\rangle = \alpha|10\rangle + \beta|01\rangle$$

$$\langle n_x n_y | n'_x n'_y \rangle = \delta_{n_x n'_x} \delta_{n_y n'_y}$$

$$L_z |\psi\rangle = \lambda |\psi\rangle$$

$$L_z(\alpha|10\rangle + \beta|01\rangle) = \lambda(\alpha|10\rangle + \beta|01\rangle)$$

$$\cdot \langle 10|, \langle 01|$$

Projiciramo to
stanje na
 $|10\rangle$ in $|01\rangle$

$$\underbrace{\langle 10 |}_{10} \alpha L_z |10\rangle + \underbrace{\langle 01 |}_{10} \beta L_z |01\rangle = \lambda \alpha$$

Sistem linearnih enačb

$$\underbrace{\langle 01 |}_{10} \alpha L_z |10\rangle + \underbrace{\langle 01 |}_{10} \beta L_z |01\rangle = \lambda \beta$$

Problem lastnih
vrednosti in
lastnih vektorjev

$$\begin{pmatrix} \langle 10 | L_z | 10 \rangle & \langle 10 | L_z | 01 \rangle \\ \langle 01 | L_z | 10 \rangle & \langle 01 | L_z | 01 \rangle \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \lambda \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$$

\uparrow
Matrični elementi
Operatorja L_z

$$L_z = xP_y - yP_x = -i\hbar \frac{\partial}{\partial p}$$

Problem lahko rešimo tako da zapisemo x in a in a^\dagger

$$H = \hbar\omega (a_x^\dagger a_x + \frac{1}{2}) + \hbar\omega (a_y^\dagger a_y + \frac{1}{2})$$

$$\begin{aligned} & 1D HO \\ & X = \frac{x_0}{\sqrt{2}}(a + a^\dagger) \quad x = \frac{x_0}{\sqrt{2}} \\ & P = \frac{p_0}{\sqrt{2}i}(a - a^\dagger) \quad p = \frac{p_0}{\sqrt{2}} \end{aligned}$$

Torej lahko zapisemo:

$$x = \frac{x_0}{\sqrt{2}}(a_x + a_x^\dagger) \quad y = \frac{x_0}{\sqrt{2}}(a_y + a_y^\dagger)$$

$$P_x = \frac{p_0}{\sqrt{2}i}(a_x - a_x^\dagger) \quad P_y = \frac{p_0}{\sqrt{2}i}(a_y - a_y^\dagger)$$

= in sestavimo L_z :

$$\begin{aligned} L_z &= \frac{x_0}{\sqrt{2}} \frac{p_0}{\sqrt{2}i} (a_x + a_x^\dagger)(a_y - a_y^\dagger) - \frac{x_0}{\sqrt{2}} \frac{p_0}{\sqrt{2}i} (a_y + a_y^\dagger)(a_x - a_x^\dagger) = \\ &= \frac{\hbar}{2i} \left[a_x a_y - \cancel{a_x a_x^\dagger} + \cancel{a_x^\dagger a_y} - \cancel{a_x^\dagger a_x^\dagger} - \cancel{a_y a_x} + \cancel{a_y a_x^\dagger} - \cancel{a_y^\dagger a_x} + \cancel{a_y^\dagger a_x^\dagger} \right] = \\ &\stackrel{\frac{\partial^2}{\partial x \partial y} = \frac{\partial^2}{\partial y \partial x}}{=} [a_x, a_y] = [a_x, a_y^\dagger] = \dots = 0 \quad \text{komutirajo} \\ &= \frac{\hbar}{2i} [-2a_x a_y^\dagger + 2a_x^\dagger a_y] = \frac{\hbar}{i} (a_x^\dagger a_y - a_x a_y^\dagger) \end{aligned}$$

Sedaj lahko izračunamo matrične elemente:

$$\langle 10 | L_z | 10 \rangle = \langle 10 | \frac{\hbar}{i} (a_x^\dagger a_y - a_x a_y^\dagger) | 10 \rangle =$$

$$\stackrel{\text{Dopolj na}}{=} \frac{\hbar}{i} \langle 10 | (a_x^\dagger a_y | 10 \rangle - a_x a_y^\dagger | 10 \rangle) =$$

$$a_x^\dagger a_y | 10 \rangle = a_x^\dagger a_y | 1 \rangle_x | 0 \rangle_y =$$

$$= (a_x^\dagger | 1 \rangle_x) (a_y | 0 \rangle_y) = \sqrt{2}|2\rangle \cdot 0 = 0$$

$$= \frac{\hbar}{i} \langle 10 | (0 - 101) \rangle = -\frac{i}{\hbar} \langle 10 | 01 \rangle = 0$$

$$\langle 10 | 01 \rangle = \langle 1 | 0 \rangle_x \langle 0 | 1 \rangle_y = 0 \cdot 0 = 0$$

Pogledimo si ēe:

$$L_z |10\rangle = \frac{\hbar}{i} (-101)$$

$$\Rightarrow \langle 01|L_z|10\rangle = -\frac{\hbar}{i} \langle 01|01\rangle = i\hbar$$

$$L_z |01\rangle = \frac{\hbar}{i} (\alpha_x^\dagger \alpha_y - \alpha_x \alpha_y^\dagger) |01\rangle = \frac{\hbar}{i} (|10\rangle - 0) = \frac{\hbar}{i} |10\rangle$$

je zadnja dva elementa data torcji:

$$\langle 10|L_z|01\rangle = \frac{\hbar}{i} \langle 10|10\rangle = -i\hbar$$

$$\langle 01|L_z|01\rangle = \frac{\hbar}{i} \langle 01|10\rangle = 0$$

Torcji imamo problem diagonalizacije matrice:

$$\begin{bmatrix} 0 & -i\hbar \\ i\hbar & 0 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \lambda \begin{bmatrix} \alpha \\ \beta \end{bmatrix}$$

Diagonalizirajmo tu matricu

$$\det \begin{bmatrix} 0-\lambda & -i\hbar \\ i\hbar & 0-\lambda \end{bmatrix} = 0 = \lambda^2 + (-\hbar)^2 = \lambda^2 - \hbar^2 \Rightarrow \lambda_{1,2} = \pm \hbar$$

Poiscimo se lastne vektorje

$$\begin{bmatrix} -\hbar & -i\hbar \\ i\hbar & -\hbar \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = 0 \quad \begin{aligned} -\alpha - i\beta &= 0 \Rightarrow \alpha = i\beta \Rightarrow 2|\beta|^2 = 1 \\ i\alpha - \beta &= 0 \quad \underline{\beta - \beta = 0} \quad \beta = \pm \frac{1}{\sqrt{2}} \end{aligned}$$

Da dobimo enotično rešitev
Uporabimo se normalizacijo

$$|\alpha|^2 + |\beta|^2 = 1$$

$$\text{Torej je } N_1 = \begin{bmatrix} -i\beta \\ \beta \end{bmatrix} = \begin{bmatrix} -\frac{i}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

Ponovimo še za λ_2 :

$$\begin{bmatrix} \hbar & -i\hbar \\ i\hbar & \hbar \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = 0 \rightarrow \alpha = -i\beta \xrightarrow[\text{norm.}]{+} \begin{bmatrix} i\beta \\ \beta \end{bmatrix}$$

$$N_2 = \begin{bmatrix} \frac{i}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

Za L_2 vemo: $L_2 |lm\rangle = \hbar m |lm\rangle$

Lastne vrednosti $|1\rangle = \frac{1}{\sqrt{2}} (-i|10\rangle + |01\rangle)$
operatorja VK

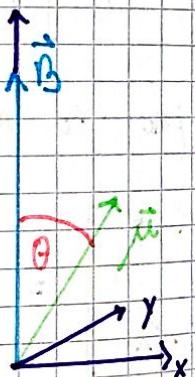
$$= | -1\rangle = \frac{1}{\sqrt{2}} (i|10\rangle + |01\rangle)$$

To je od zadnjic zamaljen rezultat za fazo ($-i$). To je matematički drugačen rezultat, ampak je fizikalno čisto enako.

[Kvantni ekvivalent precesijskega momenta duži mag. polja]

~~Vzorec:~~ $H = -\vec{\mu} \cdot \vec{B}; \vec{\mu} = \mu_B \frac{\vec{L}}{\hbar}$

$$\underline{H = \gamma \vec{L} \cdot \vec{B}}$$



Za $L=1$ ustvarjuje 3D Hilbertov prostor:

$$L^2 |lm\rangle = \hbar^2 l(l+1) |lm\rangle$$

$$L_z |lm\rangle = \hbar m |lm\rangle$$

Baza:

$$|111\rangle$$

$$|110\rangle$$

$$|11-1\rangle$$

$m=1$ $L_z |11\rangle = \hbar |11\rangle$ "kvare v smere z"

$$\hat{L}_z |11\rangle = \hbar |11\rangle \quad \hat{L} = (L_x, L_y, L_z)$$

Torej *Zacetni pogoj*

$$\hat{L} \cdot \hat{n} |\Psi, 0\rangle = \hbar |\Psi, 0\rangle$$

$$|\Psi, t\rangle = ?$$

$$|11,0\rangle = \alpha |11\rangle + \beta |10\rangle + \gamma |1-1\rangle$$

Na začiatku Ichliu zapísme normálo ($f = 0^\circ$)

$$\hat{n} = \begin{bmatrix} \sin\theta \cos\phi \\ \sin\theta \sin\phi \\ \cos\theta \end{bmatrix} = \begin{bmatrix} \sin\theta \\ 0 \\ \cos\theta \end{bmatrix}$$

Izviednotimo:

$$\vec{L} \cdot \hat{n} = L_x \sin\theta + L_z \cos\theta$$

Torej:

$$(L_x \sin\theta + L_z \cos\theta) (\alpha |11\rangle + \beta |10\rangle + \gamma |1-1\rangle) \approx \hbar (\alpha |11\rangle + \beta |10\rangle + \gamma |1-1\rangle)$$

To je späť problem lastních vredností ktoré je lastná vrednosť (cm) določená z začiatkum pogojem.

Vypočítame (s podobno výsledkom ako a in a[†] pri LHO):

$$L_{\pm} = L_x \pm i L_y$$

$$L_x = \frac{L_+ + L_-}{2}$$

$$L_y = \frac{L_+ - L_-}{2i}$$

$$L_{\pm} |lm\rangle = \hbar \sqrt{l(l+1) - m(m \mp 1)} |l, m \mp 1\rangle$$

To staníme obstarajú

$$L_x |11\rangle = \frac{L_+ + L_-}{2} |11\rangle = \frac{1}{2} \hbar (\sqrt{2-2} |12\rangle + \sqrt{2-0} |10\rangle) \quad l; m = -l, \dots, l$$

$$L_x |10\rangle = \frac{\hbar}{2} (\sqrt{2} |11\rangle + \sqrt{2} |1-1\rangle) = \frac{\sqrt{2}}{2} \hbar (|11\rangle + |1-1\rangle)$$

$$L_x |1-1\rangle = \frac{\hbar}{2} (\sqrt{2} |10\rangle) = \frac{\sqrt{2}}{2} \hbar |10\rangle$$

$$L_2 |11\rangle = \hbar |11\rangle$$

$$L_2 |10\rangle = 0$$

$$L_2 |1-1\rangle = -\hbar |1-1\rangle$$

To je sedaj konč stranskihga rezuma, vseeno se razlikuje.

$$\sin \theta \frac{\sqrt{2}}{2} \hbar (\alpha |10\rangle + \beta |11\rangle + \gamma |1-1\rangle) +$$

$$+ \cos \theta \hbar (\alpha |11\rangle + \gamma |1-1\rangle) = \hbar (\alpha |11\rangle + \beta |10\rangle + \gamma |1-1\rangle)$$

Iz tega lahko dobimo vse 3 enačbe (zradi ortogonalnosti)

$$|10\rangle : \sin \theta \frac{\sqrt{2}}{2} \hbar (\alpha + \gamma) = \hbar \beta$$

$$|11\rangle : \sin \theta \frac{\sqrt{2}}{2} \hbar \beta + \cos \theta \alpha = -\hbar \alpha$$

$$|1-1\rangle : \sin \theta \frac{\sqrt{2}}{2} \hbar \beta - \gamma \cos \theta \hbar = -\hbar \gamma$$

To so že enačbe iz
dolocitev lastnega
vektorja.

$$\beta = \sin \theta \frac{\sqrt{2}}{2} (\alpha + \gamma)$$

$$\sin \theta = 2 \sin \frac{\theta}{2} \cos \frac{\theta}{2}$$

$$\alpha = \frac{-\sin \theta \frac{\sqrt{2}}{2}}{\cos \theta - 1} - \beta = \beta \frac{\frac{\sqrt{2}}{2} \sin \frac{\theta}{2} \cos \frac{\theta}{2}}{2 \sin^2 \frac{\theta}{2}} =$$

$$1 + \cos \theta = 2 \cos^2 \frac{\theta}{2}$$

$$\gamma = \frac{\sin \theta \frac{\sqrt{2}}{2}}{\cos \theta + 1} \beta =$$

$$1 - \cos \theta = 2 \sin^2 \frac{\theta}{2}$$

$$= \frac{\sqrt{2} \sin \frac{\theta}{2} \cos \frac{\theta}{2}}{2 \cos^2 \frac{\theta}{2}} = \frac{\sqrt{2}}{2} \operatorname{tg} \frac{\theta}{2} \beta$$

Torej

$$|\Psi, 0\rangle = \frac{\sqrt{2}}{2} \left(\operatorname{tg} \frac{\theta}{2} \beta |11\rangle + \beta |10\rangle + \frac{\sqrt{2}}{2} \operatorname{tg} \frac{\theta}{2} \beta |1-1\rangle \right)$$

|β| pa dobijmo iz normalizacije:

$$\left(\frac{1}{2} \operatorname{ctg}^2 \frac{\theta}{2} + 1 + \frac{1}{2} \operatorname{tg}^2 \frac{\theta}{2} \right) |\beta|^2 = 1$$

$$\text{Torz: } \frac{\cos^4 \frac{\theta}{2} + 2\sin^2 \frac{\theta}{2} \cos^2 \frac{\theta}{2} + \sin^4 \frac{\theta}{2}}{2\sin^2 \frac{\theta}{2} \cos^2 \frac{\theta}{2}} = \frac{\left(\cos^2 \frac{\theta}{2} + \sin^2 \frac{\theta}{2}\right)^2}{2\sin^2 \frac{\theta}{2} \cos^2 \frac{\theta}{2}} = \frac{1}{2\sin^2 \frac{\theta}{2} \cos^2 \frac{\theta}{2}}$$

$$\Rightarrow \beta = \sqrt{2} \sin \frac{\theta}{2} \cos \frac{\theta}{2}$$

Torž imamo na zacetku:

$$|\psi_0\rangle = \cos^2 \frac{\theta}{2} |11\rangle + \sqrt{2} \sin \frac{\theta}{2} \cos \frac{\theta}{2} |10\rangle + \sin^2 \frac{\theta}{2} |1-1\rangle$$

Rabimo časovni razvoj. Nagluži ga dobimo kot razvoj po lastnih stanjih Hamiltoniana.

Torž so 1. stanja L_z tudi: 1. stanja H

$$H = \lambda \vec{L} \cdot \vec{B} = \lambda B L_z$$

$\uparrow \vec{B} = (0, 0, B)$

$$L_z |lm\rangle = \hbar m |lm\rangle$$

$$H|11\rangle = \lambda B \hbar |11\rangle \quad H|10\rangle = 0 |10\rangle \quad H|1-1\rangle = -\lambda B \hbar |1-1\rangle$$

Tako bič tčav zapisemo časovni razvoj:

$$|\psi_t\rangle = \cos^2 \frac{\theta}{2} e^{-i\lambda B t} |11\rangle + \sqrt{2} \sin \frac{\theta}{2} \cos \frac{\theta}{2} |10\rangle + \sin^2 \frac{\theta}{2} e^{i\lambda B t} |1-1\rangle$$

Pošljemo izhisciti, kaj pomeni ta valovna funkcija.

$$\langle \vec{l}, t \rangle = ?$$

$$\langle L_z, t \rangle = \langle \psi_t | L_z | \psi_t \rangle =$$

$$L_z |\psi_t\rangle = \cos^2 \frac{\theta}{2} e^{-i\lambda B t} \hbar |11\rangle + 0 - \hbar \sin^2 \frac{\theta}{2} e^{i\lambda B t} |1-1\rangle$$

$$\langle L_z, t \rangle = \hbar \left(\cos^4 \frac{\theta}{2} - \sin^4 \frac{\theta}{2} \right) = \hbar \left(\cos^2 \frac{\theta}{2} - \sin^2 \frac{\theta}{2} \right) \left(\cos^2 \frac{\theta}{2} + \sin^2 \frac{\theta}{2} \right) =$$

$\Rightarrow \hbar \cos \theta$

$$\langle L_x, t \rangle = \left\langle \frac{L_+ + L_-}{2}, t \right\rangle = \frac{1}{2} \langle L_+, t \rangle + \frac{1}{2} \langle L_-, t \rangle =$$

← com. conj
tega

$$= \operatorname{Re}(\langle L_+, t \rangle)$$

$$\langle L_y, t \rangle = \left\langle \frac{L_+ - L_-}{2i}, t \right\rangle = \frac{1}{2i} [\langle L_+, t \rangle - \langle L_-, t \rangle] =$$

$$= \operatorname{Im}(\langle L_+, t \rangle)$$

$$\langle L_+, t \rangle = \langle \Psi, t | L_+ | \Psi, t \rangle$$

$$L_+ |\Psi, t \rangle = 0 + 2 \sin \frac{\theta}{2} \cos \frac{\theta}{2} \hbar |11\rangle + \hbar \sqrt{2} \sin^2 \frac{\theta}{2} e^{i \lambda B t} |10\rangle$$

$$L_+ |11\rangle = \hbar \sqrt{2} |10\rangle$$

$$L_+ |10\rangle = \sqrt{2} \hbar |11\rangle$$

$$\Rightarrow \langle L_+, t \rangle = 2 \cos^2 \frac{\theta}{2} \sin \frac{\theta}{2} e^{i \lambda B t} \hbar + 2 \hbar \sin^2 \frac{\theta}{2} \cos \frac{\theta}{2} e^{-i \lambda B t} =$$

$$= 2 \hbar e^{i \lambda B t} \cos^2 \frac{\theta}{2} \sin \frac{\theta}{2} (\cos^2 \theta/2 + \sin^2 \theta/2) =$$

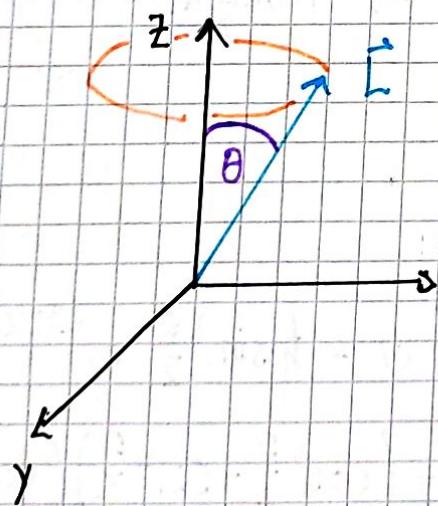
$$= 2 \hbar \sin \theta e^{i \lambda B t}$$

Tako luhko dobimo L_x in L_y

$$\langle L_x, t \rangle = \operatorname{Re} \langle L_+, t \rangle = \hbar \cos(\lambda B t) \sin \theta$$

$$\langle L_y, t \rangle = \operatorname{Im} \langle L_+, t \rangle = \hbar \sin(\lambda B t) \sin \theta$$

Vektori \mathbf{L} soj precesira po stožcu:



To je hotilasino za vrtilo kolicino. Temu se v kvantni

reže Larmorjeva precesija.

x Vrtilna kolicina precesira ω_L
Larmorjevo frekvenco

$$\omega_L = \lambda B$$

1 Kaj pa bi nam dala meritve L_z ?

Razvijimo VF po lastnih stanjih ~~meritev~~ operatorju, kar že imamo.
Možne vrednosti so lastne vrednosti operatorja. Verjetnost pa je koeficient pred.

L_z	$ C_m ^2$	$\psi_{ob \ t+dt}$
\hbar	$\cos^4 \frac{\theta}{2}$	$ 11\rangle$
0	$2\cos^2 \frac{\theta}{2} \sin^2 \frac{\theta}{2}$	$ 10\rangle$
$-\hbar$	$\sin^4 \frac{\theta}{2}$	$ 1-1\rangle$

Kaj se zgodi z delom takoj po meritri?

Meritev kolapsira VF torej je valovna funkcija le tisto stanje, ki ustreza lastni vrednosti, ki smo jo izmerili.

Če želimo izmeriti prizakovano vrednost to ne moremo nato narediti več meritev. Če naredimo več zaporednih merit na enem delcu dobimo vedno tisto kar smo prvo izmerili zaradi kolapsa valovne funkcije.

Zato moramo vsajšči z začeti ob $t=0$ z novo generiranim začetnim stanjem.

$$\bar{L}_z = \hbar \cos^4 \frac{\theta}{2} + 0 - \hbar \sin^4 \frac{\theta}{2} = \dots = \hbar \cos \theta$$

Torej je prizakovana vrednost $\langle L_z, t \rangle$ povprečje neodvisnih meritev.

Spin

$$H = \frac{\vec{p}^2}{2m} + \lambda(p_x S_y - p_y S_x); \quad S = \frac{1}{2}$$

$$\vec{p} = (p_x, p_y) \text{ 2D}$$

Rosbova ~~Postupitv~~
Slabopitv

Rešujemo

$$H|\psi\rangle = E|\psi\rangle$$

$$[H, \vec{p}] = ?$$

✓

v drugem podprostoru
torej redno komutira

$$[H, p_x] = \left[\frac{p_x^2}{2m} + \frac{p_y^2}{2m} + \lambda(p_x S_y - p_y S_x), p_x \right] = 0$$

=

Potem lahko iščemo stanje z lastnim stanji \vec{p} :

$$\vec{p}|\tilde{u}\rangle = \hbar\tilde{u}|\tilde{u}\rangle$$

$$\Psi_{\tilde{u}}(\vec{r}) = e^{i\tilde{u} \cdot \vec{r}}$$

$$\vec{p} = -i\hbar\nabla$$

Torej zaradi komutiranja H in \vec{p} lahko iščemo rešitev z produktom nastankom:

$$|\psi\rangle = |\tilde{u}\rangle |x\rangle$$

Kojujoči del

Spinski del

$$\left[\frac{\vec{p}^2}{2m} + \lambda(p_x S_y - p_y S_x) \right] |\tilde{u}\rangle |\psi\rangle = E |\tilde{u}\rangle |\psi\rangle =$$

$$*\left(\frac{\vec{p}^2}{2m} |\tilde{u}\rangle \right) |\chi\rangle + \lambda(p_x |\tilde{u}\rangle)(S_y |\psi\rangle) - \lambda(p_y |\tilde{u}\rangle)(S_x |\psi\rangle) =$$

$$*\frac{\hbar^2 \tilde{u}^2}{2m} |\tilde{u}\rangle |\chi\rangle + \lambda(t_{hx} |\tilde{u}\rangle S_y |\psi\rangle) - \lambda(t_{hy} |\tilde{u}\rangle S_x |\psi\rangle) = E |\tilde{u}\rangle |\chi\rangle$$

Dobimo:

$$\frac{\hbar^2 h^2}{2m} |\chi\rangle + \lambda \hbar (h_x S_y |\chi\rangle - h_y S_x |\chi\rangle) = E |\chi\rangle$$

Torijski zavadi $[H, \hat{p}] = 0$ smo problem iz 2D dim na 2D problem v spinshem

prostorn.

$$S = \frac{1}{2}$$

$$|\frac{1}{2}, \frac{1}{2}\rangle = |\uparrow\rangle$$

$$|\frac{1}{2}, -\frac{1}{2}\rangle = |\downarrow\rangle$$

$$S_x = \frac{S_+ + S_-}{2}$$

$$S_y = \frac{S_+ - S_-}{2i}$$

Torej je nastavlj za $|\chi\rangle$ lin komb.:

$$|\chi\rangle = \alpha |\uparrow\rangle + \beta |\downarrow\rangle$$

$$S_z |\uparrow\rangle = 0 \quad \text{N}$$

$$S_z |\downarrow\rangle = \hbar \sqrt{\frac{1}{2} \cdot \frac{3}{2} + \frac{1}{2} \cdot \frac{1}{2}} = \hbar \sqrt{\frac{5}{4}} = \hbar \sqrt{\frac{5}{2}}$$

$$S_+ |\uparrow\rangle = \hbar |\downarrow\rangle$$

$$S_- |\downarrow\rangle = 0$$

Tako:

$$S_x |\uparrow\rangle = \frac{\hbar}{2} |\downarrow\rangle$$

$$S_x |\downarrow\rangle = \frac{\hbar}{2} |\uparrow\rangle$$

$$S_y |\uparrow\rangle = \frac{\hbar}{2i} |\downarrow\rangle$$

$$S_y |\downarrow\rangle = \frac{\hbar}{2i} |\uparrow\rangle$$

$$\Rightarrow \frac{\hbar^2 h^2}{2m} (\alpha |\uparrow\rangle + \beta |\downarrow\rangle) + \lambda \hbar \left(h_x \frac{\hbar}{2i} (-\alpha |\downarrow\rangle + \beta |\uparrow\rangle) - h_y \frac{\hbar}{2} (\alpha |\downarrow\rangle + \beta |\uparrow\rangle) \right) = \\ = E (\alpha |\uparrow\rangle + \beta |\downarrow\rangle)$$

Iz izjemnega koeficienta dobimo dve linearni enačbi:

$$\frac{\hbar^2 h^2}{2m} \alpha + \lambda \hbar \beta \left(h_x \frac{\hbar}{2i} - h_y \frac{\hbar}{2} \right) = E \alpha$$

$$\frac{\hbar^2 h^2}{2m} \beta + \lambda \hbar \alpha \left(-h_x \frac{\hbar}{2i} - h_y \frac{\hbar}{2} \right) = E \beta$$

To je problem lastnih vrednosti:

$$\begin{pmatrix} \frac{\hbar^2 h^2}{2m} & \frac{\lambda \hbar^2}{2} \left(\frac{h_x}{i} - h_y \right) \\ -\frac{\lambda \hbar^2}{2} \left(h_x + h_y \right) & \frac{\hbar^2 h^2}{2m} \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = E \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$$

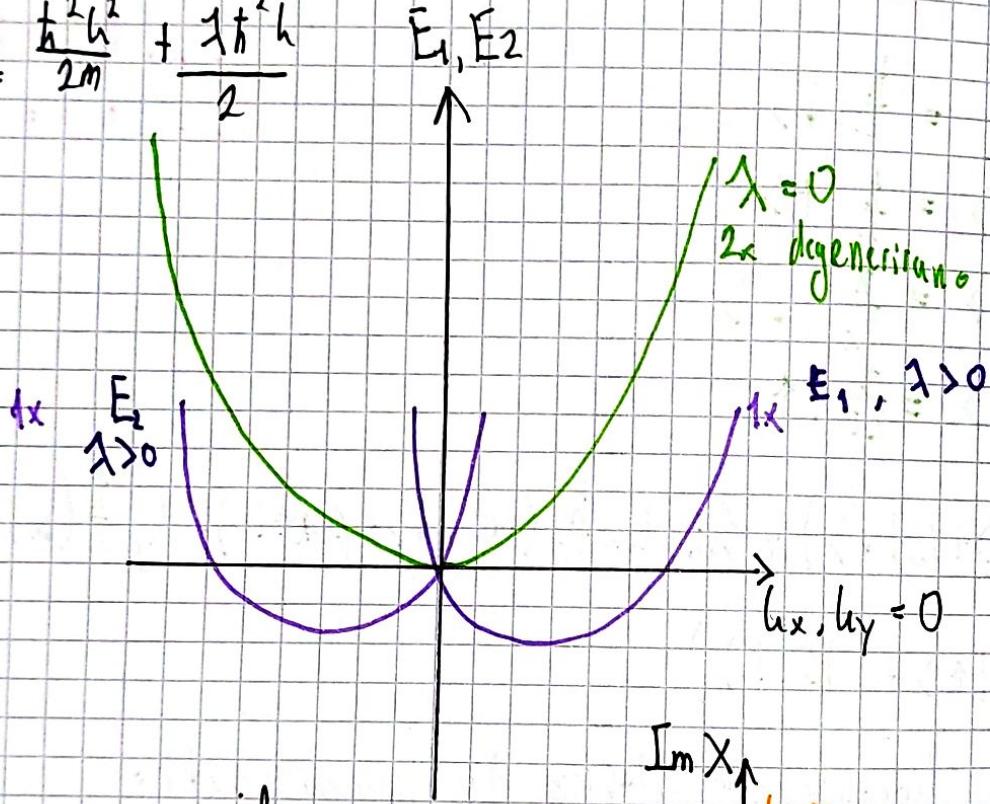
$$\begin{vmatrix} \frac{\hbar^2 k^2}{2m} - E & \frac{1}{2} \hbar^2 \left(\frac{k_x}{i} - k_y \right) \\ \frac{1}{2} \hbar^2 \left(-\frac{k_x}{i} - k_y \right) & \frac{\hbar^2 k^2}{2m} - E \end{vmatrix} = 0$$

$$\left(\frac{\hbar^2 k^2}{2m} - E \right)^2 + \underbrace{\frac{1}{4} \hbar^4 \left(\frac{k_x}{i} - k_y \right) \left(\frac{k_x}{i} + k_y \right)}_{-k_x^2 - k_y^2 = -k^2} =$$

$$= \left(\frac{\hbar^2 k^2}{2m} - E - \frac{1}{2} \hbar^2 k \right) \left(\frac{\hbar^2 k^2}{2m} + E + \frac{1}{2} \hbar^2 k \right)$$

$$\Rightarrow E_1 = \frac{\hbar^2 k^2}{2m} - \frac{1}{2} \hbar^2 k$$

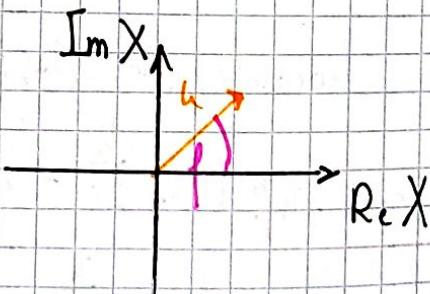
$$E_2 = \frac{\hbar^2 k^2}{2m} + \frac{1}{2} \hbar^2 k$$



$$k_x + i k_y = X = k e^{i\phi}$$

$$\frac{k_x}{i} - k_y = \frac{1}{i} (k_x - i k_y) = (k e^{-i\phi}) \cdot \frac{1}{i}$$

$$-\frac{k_x}{i} - k_y = -\frac{1}{i} e^{i\phi} k$$



$$\text{Toys zu } E_1$$

$$\begin{pmatrix} \frac{\lambda h^2 \alpha}{2} & \frac{\lambda h^2}{\hbar^2} \frac{1}{i} h e^{-i\phi} \\ \frac{\lambda h^2}{\hbar^2} \frac{1}{i} h e^{-i\phi} & \beta \end{pmatrix} = 0$$

$$\lambda h^2 \left(\frac{h}{2} \alpha + \frac{h}{2i} e^{-i\phi} \beta \right) = 0 \Rightarrow \beta = -i\alpha e^{i\phi}$$

in
 $|\alpha|^2 + |\beta|^2 = 1$

$$\Leftrightarrow E_1 \Rightarrow \frac{|\uparrow\rangle - i e^{i\phi} |\downarrow\rangle}{\sqrt{2}}$$

Za E_2 pa na hitro

$$E_2 \Rightarrow \frac{|\uparrow\rangle + i e^{i\phi} |\downarrow\rangle}{\sqrt{2}}$$

$$\begin{aligned} \alpha |\uparrow\rangle + \beta |\downarrow\rangle &= \cos \frac{\theta}{2} |\uparrow\rangle + \sin \frac{\theta}{2} e^{i\phi} |\downarrow\rangle \\ |\alpha|^2 + |\beta|^2 &= 1 \end{aligned}$$

Blochova sfera

$\alpha \in \mathbb{R}$ in $\alpha \geq 0$ (*) Razberimo α, β za nas primer

$$\cos \frac{\theta}{2} = \frac{1}{\sqrt{2}} \Rightarrow \theta = \frac{\pi}{2}$$

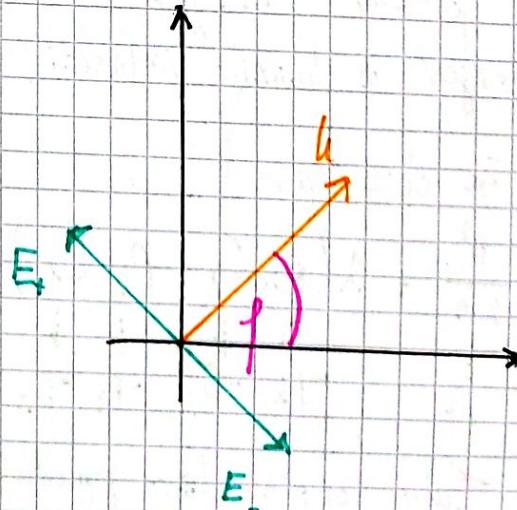
$$\frac{i}{\sqrt{2}} e^{i\phi} = \sin \frac{\theta}{2} e^{i\phi}$$

$$ie^{i\phi} = e^{i\phi} \Rightarrow \phi = f + \frac{\pi}{2}$$

Za drugo stanje pa podobno:

$$\theta = \frac{\pi}{2}$$

$$\phi = f - \frac{\pi}{2}$$



[Rečimo isto nalogu z Paulijevimi matrikumi]

$$\alpha | \uparrow \rangle + \beta | \downarrow \rangle \rightarrow \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$$

Deklarationsform zu Spin $\frac{1}{2}$
präferen; postopac pa zu
öffnen Spin

$$\vec{S} = (S_x, S_y, S_z) = \frac{\hbar}{2}(\beta_x, \beta_y, \beta_z)$$

$$\beta_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \beta_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \beta_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Prezisimo Hamiltonian \mathcal{H} Paulijevići metričkami:

$$H = \frac{p^2}{2m} \cancel{I}_2 + \frac{\lambda \hbar}{2} (p_x \delta_y - p_y \delta_x)$$

2×2 identiteta her p

Me delijo en spine

Kot zadnjic uporabimo nastavek $|N\rangle = |\bar{h}\rangle |X\rangle$

$$\Rightarrow H = \frac{\hbar^2 k^2}{2m} + \frac{\lambda \hbar}{2} (\hbar k_x \partial_y - \hbar k_y \partial_x) =$$

$$= \begin{pmatrix} \frac{\hbar^2 h^2}{2m} & \frac{\lambda \hbar^2}{2} (-ih_x - h_y) \\ \frac{\lambda \hbar^2}{2m} (ih_x - h_y) & \frac{\hbar^2 h^2}{2m} \end{pmatrix}$$

Resovali bi problem $H|\psi\rangle = E|\psi\rangle$ in dobimo spet problem lastnih vektorjev in lastnih vrednosti, ki smo ga tudi zadnjic dobili.

[Poglymo įc. obrat. išsa]

$$H = \frac{p^2}{2m} + \lambda(p_x S_y - p_y S_x)$$

Obra:

$$-P_x \quad -S_y \quad -P_y \quad -S$$

Tako smo na listu pogledali invariantne

Dobjimo si to invarianto se formalno:

$$H = \frac{p^2}{2m} + \frac{\lambda\hbar}{2}(p_x \partial_y - p_y \partial_x)$$

$$T = i \partial_y K$$

Operator obrata casa

T je unitaren

Operator kompleksne
konjugacije

$$\langle T\phi | T\psi \rangle = \langle \phi | \psi \rangle^*$$

$$K|\tilde{h}\rangle = |-\tilde{h}\rangle$$

$$K e^{i\tilde{h} \cdot \vec{r}} = e^{-i\tilde{h} \cdot \vec{r}}$$

$$K \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} \alpha^* \\ \beta^* \end{pmatrix}$$

Da je H formalno invarianten na obrat casa mora veljati:

$$[H, T] = 0 \Rightarrow HT = TH$$

$$TH \quad \left[i \partial_y K \left(\frac{p^2}{2m} + \frac{\lambda\hbar}{2} (p_x \partial_y - p_y \partial_x) \right) \right] = i \partial_y \left(\frac{p^2}{2m} + \frac{\lambda\hbar}{2} (-p_x(-\partial_y)K - (-p_y)(\partial_x)K) \right)$$

$$\text{---} \quad \begin{matrix} \nearrow p_x = -i\hbar \frac{\partial}{\partial x} \\ \searrow p_y = -i\hbar \frac{\partial}{\partial y} \end{matrix}$$

$$p^2 = -\frac{\hbar^2}{m} \nabla^2 \in \mathbb{R}$$

$$\begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$= i \partial_y \left(\frac{p^2}{2m} + \frac{\lambda\hbar}{2} (-p_x(-\partial_y) - (-p_y)(\partial_x)) \right) K = (*)$$

Velja:

$$\{\partial_\alpha, \partial_\beta\} = 2 \delta_{\alpha\beta}$$

$$\Rightarrow \partial_x \partial_y + \partial_y \partial_x = 0$$

$$K \partial_y = \partial_y^* K = (-\partial_y) K$$

$$i \partial_y \cdot \partial_y = \partial_y \cdot i \partial_y$$

$$i \partial_y \cdot \partial_x = -\partial_x \cdot i \partial_y$$

$$(*) = \left(\frac{p^2}{2m} + \frac{\lambda\hbar}{2} (p_x \partial_y - (-p_y)(-\partial_x)) \right) i \partial_y K = HT$$

Tanj:

$$H|\psi\rangle = E|\psi\rangle$$

$$HT|\psi\rangle = TH|\psi\rangle = TE|\psi\rangle = ET|\psi\rangle$$

$T|\psi\rangle$ tudi lastno stanje

Ali sta b dr lastni stanji isti?

$$T^2 = (i\beta_y \mathbf{K})(i\beta_y \mathbf{K}) = i\beta_y (-i)(-\beta_y) \mathbf{K}^2 = -\beta_y^2 = -I$$

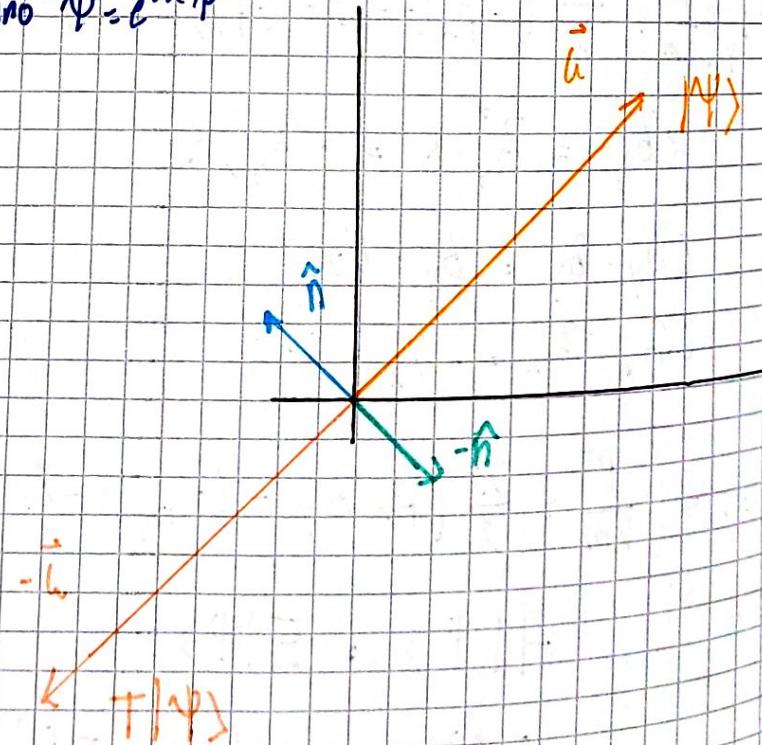
$$\langle \Psi | +\Psi \rangle = \langle T\Psi | T^2 \Psi \rangle^* = \langle T\Psi | -\Psi \rangle^* = \\ = \langle -\Psi | T\Psi \rangle = -\langle \Psi, T\Psi \rangle = 0$$

Torej sta stanji ortogonalni. Torej če imamo H invarianten na T^2 in

$T^2 = -I$ dobimo lahko z aplikiranjem T še drugo stanje. Temu se

oce Kramersova degeneracija (Kramersov dvolet).

$$T \left(\frac{|N\rangle + ie^{i\phi}|L\rangle}{\sqrt{2}} \right) \Rightarrow T e^{i\vec{L} \cdot \vec{r} / \left(\frac{ie}{\sqrt{2}} \alpha \right)} = i\beta_y e^{-i\vec{L} \cdot \vec{r} / \left(\frac{-ie \cdot i}{\sqrt{2}} \right)} = \\ |L\rangle \quad \alpha > 0 \in \mathbb{R} \quad \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \\ = e^{-i\vec{L} \cdot \vec{r} / \left(\frac{-ie}{\sqrt{2}} \right)} = e^{-i\vec{L} \cdot \vec{r} / \left(\frac{1}{\sqrt{2}} (-\frac{1}{\sqrt{2}} + ie^{i\phi}) \right)} = \\ \text{Tb lahko ker} \quad \text{Fizikalno } N = e^{i\alpha} N \\ = e^{-i\vec{L} \cdot \vec{r} / \left(\frac{1}{\sqrt{2}} (-\frac{ie}{\sqrt{2}}) \right)}$$

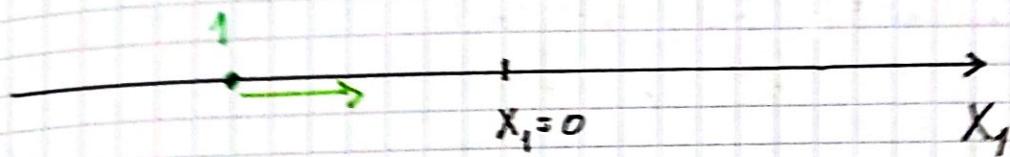


[Dva delca, ki se čutita]

$$1D: H = \frac{p_i^2}{2m} - \frac{\lambda \delta(x_i) \vec{S}_1 \cdot \vec{S}_2}{\hbar^2} ; S_1 = \frac{1}{2}$$

$$S_2 = 1$$

• 2



a) Pogledimo si rezultantno stanje

$$\vec{S} = \vec{S}_1 + \vec{S}_2 \Rightarrow S^2 = S_1^2 + S_2^2 + 2S_1 \cdot S_2 \quad S_2 = S_{12} + S_{22}$$

$$\Rightarrow \vec{S}_1 \cdot \vec{S}_2 = \frac{1}{2}(S^2 - S_1^2 - S_2^2)$$

To vstavimo v H :

$$H = \frac{p_i^2}{2m} - \frac{\lambda}{2\hbar^2} \delta(x_i) (S^2 - S_1^2 - S_2^2)$$

$$\Rightarrow [H, S^2] = [H, S_1^2]; [H, S_1^2] = [H, S_2^2] = 0$$

$$[S^2, S_1^2] = [S^2, S_2^2] = [S_1^2, S_2^2] = 0 \quad H, S_1^2, S_2^2, S^2$$

$$[S_1^2, S_2^2] = [S_1^2, S_1^2] = 0 \quad \text{Slupaj homotrijo}$$

$$[S_2^2, S_2^2] = 0$$

1. delec 2. delec 1. in 2. delec dogorov ter S_1 konst.

$$|1\rangle = |\frac{1}{2} \frac{1}{2}\rangle \quad |11\rangle \quad |11\rangle |11\rangle = |1\rangle |11\rangle$$

$$|1\rangle = |\frac{1}{2} - \frac{1}{2}\rangle \quad |10\rangle \quad |1\rangle |10\rangle = |1\rangle |0\rangle$$

$$+ \quad + \quad |1 - 1\rangle \quad |1\rangle |1 - 1\rangle = |1\rangle | - 1\rangle$$

$$S_1 \quad S_{12} \quad S_2 \quad S_{22}$$

2D

3D

$$|1\rangle |11\rangle = |1\rangle |11\rangle$$

$$|1\rangle |10\rangle = |1\rangle |0\rangle$$

$$|1\rangle |1 - 1\rangle = |1\rangle | - 1\rangle$$

$$|1\rangle |10\rangle$$

$$|1\rangle |1 - 1\rangle$$

pripravljalna baza: lastna za

$$2 \cdot 3 = 6D \quad S_1^2, S_{12}, S_2^2, S_{22}$$

$$S_1^2 |\uparrow\rangle |10\rangle = \hbar^2 \frac{1}{2} (\frac{1}{2} + 1) |\uparrow\rangle |10\rangle = \frac{3}{4} \hbar^2 |\uparrow\rangle |10\rangle$$

Izberimo hwo z dobrim blupnim spinom

$$S^2, S_x, S_1^2, S_2^2$$

$$S_1, S_2 \Rightarrow S = |S_1 - S_2|, \dots, |S_1 + S_2|$$

$$\frac{1}{2}, \frac{3}{2}$$

$|S_1 S_2 S S_z\rangle$ dogovor $|SS_z\rangle$ kur S_1 in S_2 horst

$$\Rightarrow |\frac{1}{2} 1 \frac{1}{2} -\frac{1}{2}\rangle = |\frac{1}{2} -\frac{1}{2}\rangle$$

$$|\frac{1}{2} 1 \frac{1}{2} \frac{1}{2}\rangle = |\frac{1}{2} \frac{1}{2}\rangle$$

$$|\frac{1}{2} 1 \frac{3}{2} -\frac{3}{2}\rangle = |\frac{3}{2} -\frac{3}{2}\rangle$$

$$|\frac{1}{2} 1 \frac{3}{2} -\frac{1}{2}\rangle = |\frac{3}{2} -\frac{1}{2}\rangle$$

$$|\frac{1}{2} 1 \frac{3}{2} \frac{1}{2}\rangle = |\frac{3}{2} \frac{1}{2}\rangle$$

$$|\frac{1}{2} 1 \frac{3}{2} \frac{3}{2}\rangle = |\frac{3}{2} \frac{3}{2}\rangle$$

Torej rezultira $H|\psi\rangle = E|\psi\rangle$, z nastavkom $|\psi\rangle = |\phi\rangle |SS_z\rangle$

$$H|\phi\rangle |SS_z\rangle = E|\phi\rangle |SS_z\rangle$$

$$\left[\frac{p_1^2}{2m} - \frac{\lambda}{2\hbar^2} J(x_1) (S^2 - S_1^2 - S_2^2) \right] |\phi\rangle |SS_z\rangle = E|\phi\rangle |SS_z\rangle$$

$$\left(\frac{p_1^2}{2m} |\phi\rangle \right) |SS_z\rangle - \frac{\lambda}{2\hbar^2} J(x_1) |\phi\rangle |SS_z\rangle = E|\phi\rangle |SS_z\rangle$$

$$S^2 |SS_z\rangle = \hbar^2 S(S+1) |SS_z\rangle$$

$$S_1^2 |SS_z\rangle = \frac{3}{4} \hbar^2 |SS_z\rangle$$

$$S_2^2 |SS_z\rangle = 2\hbar^2 |SS_z\rangle$$

$$\left(\frac{p_1^2}{2m} |\phi\rangle \right) |SS_z\rangle - \frac{\lambda}{2\hbar^2} \delta(x_1) |\phi\rangle \left[\hbar^2 S(S+1) - \underbrace{\hbar^2 S_1(S_1+1) - \hbar^2 S_2(S_2+1)}_{-11/4 \hbar^2} \right] |SS_z\rangle =$$

$$= E |SS_z\rangle |\phi\rangle$$

$$\left(\frac{p_1^2}{2m} \right) |\phi\rangle + \frac{\lambda}{2} \delta(x_1) \left(\frac{11}{4} - S(S+1) \right) |\phi\rangle = E |\phi\rangle$$

Rješimo pravzaprav dva problema:

$$H_{3/2} = \frac{p_1^2}{2m} - \frac{\lambda}{2} \delta(x_1) \rightarrow \begin{array}{l} \text{vezano stanje} \\ (4x \text{ degeneracija}) \end{array}$$

$$H_{1/2} = \frac{p_1^2}{2m} + \lambda \delta(x_1)$$

Pogledimo sijalna stanja:

$$E > 0 : S_{3/2} = \begin{pmatrix} r_{3/2} & \cdot \\ t_{3/2} & \cdot \end{pmatrix}$$

$$S_{1/2} = \begin{pmatrix} r_{1/2} & \cdot \\ t_{1/2} & \cdot \end{pmatrix}$$

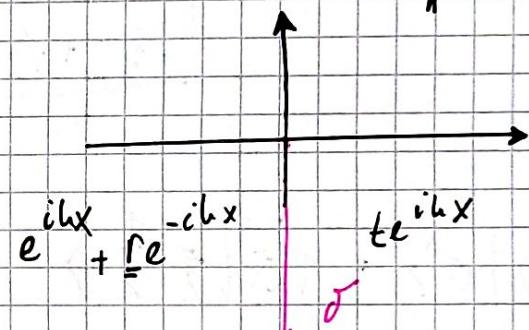
Od zacetka šemestru:

$$H = \frac{p^2}{2m} - \lambda \delta(x)$$

$$E_0 = -\frac{\hbar^2 \lambda^2}{2m}, \quad \lambda = \frac{m\lambda}{\hbar^2}$$

$$|\psi_0\rangle = \sqrt{\lambda} e^{-\lambda|x|}$$

$$E > 0 : u = \frac{\sqrt{2m}E}{\hbar^2}$$



$$S = \frac{1}{\lambda + i\hbar} \begin{pmatrix} -\lambda, i\hbar \\ i\hbar, -\lambda \end{pmatrix}$$

Tačk so sijalna stanja (vpučni val iz leve) pri energiji: $E > 0$:

$$S = \frac{3}{2} : (e^{i\lambda x_1} + r_{3/2} e^{-i\lambda x_1}) \left| \frac{3}{2} S_z \right\rangle \quad \underline{t_{3/2} e^{i\lambda x_1} \left| \frac{3}{2} S_z \right\rangle}$$

λ_2

$$S = \frac{1}{2} : (e^{i\lambda x_1} + r_{1/2} e^{-i\lambda x_1}) \left| \frac{1}{2} S_z \right\rangle \quad \underline{t_{1/2} e^{i\lambda x_1} \left| \frac{1}{2} S_z \right\rangle}$$

Tačk imamo 4 $\Rightarrow E > 0$ 12 sijalnih stanja (še 6 za val iz desne) in $E < 0$ vezana stanja. To je celotna baza naloge problema.

Rešujemo problem sisanja ko delce 1 prihaja z $E > 0$ iz leve mimo delca 2 $S_{2z} = 0$

$$\Rightarrow e^{i\hbar x_1} |\uparrow\rangle |0\rangle ; \hbar = \sqrt{\frac{2mE}{\hbar^2}}$$



Rabimo faktoriti med bazama. To naredimo z Clebsch-Gordanovimi koeficienti.

$1 \times \frac{1}{2}$	$\boxed{\frac{3}{2}}$			
	$\boxed{\frac{3}{2}}$	$\boxed{\frac{3}{2}}$	$\boxed{\frac{1}{2}}$	$\boxed{\frac{1}{2}}$
$+1 \quad +\frac{1}{2}$	1	$-\frac{1}{2}$	$+\frac{1}{2}$	
	$+1 \quad -\frac{1}{2}$	$\frac{1}{3} \quad \frac{2}{3}$	$\frac{3}{2} \quad \frac{1}{2}$	
	$0 \quad +\frac{1}{2}$	$\frac{2}{3} \quad -\frac{1}{3}$	$-\frac{1}{2} \quad -\frac{1}{2}$	
	$0 \quad -\frac{1}{2}$	$\frac{2}{3} \quad \frac{1}{3}$	$\frac{1}{3} \quad \frac{3}{2}$	
	$-1 \quad +\frac{1}{2}$	$\frac{1}{3} \quad -\frac{2}{3}$	$-\frac{2}{3} \quad -\frac{3}{2}$	
	$-1 \quad -\frac{1}{2}$	1		

$$|\uparrow\rangle |0\rangle = \sqrt{\frac{2}{3}} \left| \frac{3}{2} \frac{1}{2} \right\rangle - \sqrt{\frac{1}{3}} \left| \frac{1}{2} \frac{1}{2} \right\rangle$$

$$\sqrt{\frac{2}{3}} \left(e^{i\hbar x_1} + r_{3/2} e^{-i\hbar x_1} \right) \left| \frac{3}{2} \frac{1}{2} \right\rangle - \sqrt{\frac{1}{3}} \left(e^{i\hbar x_1} + r_{1/2} \right) \left| \frac{1}{2} \frac{1}{2} \right\rangle \leftarrow \text{Vpadni in odbiti}$$

$$\sqrt{\frac{2}{3}} t_{3/2} e^{i\hbar x_1} \left| \frac{3}{2} \frac{1}{2} \right\rangle - \sqrt{\frac{1}{3}} t_{1/2} e^{i\hbar x_1} \left| \frac{1}{2} \frac{1}{2} \right\rangle \leftarrow \text{Prepuščeni}$$

Vprašanje in meritre delamo bolj v produktivni formi hot v bazi z dobrim skupnim spinom. Svet uporabimo tabele, da transformiramo na

$$\left| \frac{3}{2} \frac{1}{2} \right\rangle = \sqrt{\frac{1}{3}} |\downarrow\rangle |1\rangle + \sqrt{\frac{2}{3}} |\uparrow\rangle |0\rangle$$

$$\left| \frac{1}{2} \frac{1}{2} \right\rangle = \sqrt{\frac{2}{3}} |\downarrow\rangle |1\rangle + \sqrt{\frac{1}{3}} |\uparrow\rangle |0\rangle$$

$$\sqrt{\frac{2}{3}} \left(e^{i\omega x_1} + r_{3/2} e^{-i\omega x_1} \right) \left[\sqrt{\frac{1}{3}} |1\rangle\langle 1\rangle + \sqrt{\frac{2}{3}} |1\rangle\langle 0\rangle \right] - \sqrt{\frac{1}{3}} \left(e^{i\omega x_1} + r_{1/2} e^{-i\omega x_1} \right).$$

$$+ \left[\sqrt{\frac{2}{3}} |1\rangle\langle 1\rangle - \sqrt{\frac{1}{3}} |1\rangle\langle 0\rangle \right]$$

$$\downarrow$$

$$\left[\frac{\sqrt{2}}{3} \left(e^{i\omega x_1} + r_{3/2} e^{-i\omega x_1} \right) - \frac{\sqrt{2}}{3} \left(e^{i\omega x_1} + r_{1/2} e^{-i\omega x_1} \right) \right] |1\rangle\langle 1\rangle +$$

$$+ \left[\frac{2}{3} \left(e^{i\omega x_1} + r_{3/2} e^{-i\omega x_1} \right) + \frac{1}{3} \left(e^{i\omega x_1} + r_{1/2} e^{-i\omega x_1} \right) \right] |1\rangle\langle 0\rangle \quad r_{11}$$

$$e^{i\omega x_1} |1\rangle\langle 0\rangle + e^{-i\omega x_1} \left(\frac{\sqrt{2}}{3} r_{3/2} - \frac{\sqrt{2}}{3} r_{1/2} \right) |1\rangle\langle 1\rangle + e^{-i\omega x_1} \left(\frac{2}{3} r_{3/2} + \frac{1}{3} r_{1/2} \right) |1\rangle\langle 0\rangle$$

za $x_1 < 0$

$$e^{i\omega x_1} \left(\frac{\sqrt{2}}{3} t_{3/2} - \frac{\sqrt{2}}{3} t_{1/2} \right) |1\rangle\langle 1\rangle + e^{i\omega x_1} \left(\frac{2}{3} t_{3/2} + \frac{1}{3} t_{1/2} \right)$$

$t_{\downarrow\uparrow}$

$t_{\uparrow\uparrow}$

Ubistvu elementi
12x12 matrice

Vrijimo lako 4 razlike vrijednosti:

$$R_{\downarrow\uparrow} = |r_{\downarrow\uparrow}|^2 = \left| \frac{\sqrt{2}}{3} r_{3/2} - \frac{\sqrt{2}}{3} r_{1/2} \right|^2 = \frac{2}{9} |r_{3/2}|^2 + \frac{2}{9} |r_{1/2}|^2 - 2 \operatorname{Re}(r_{3/2}^* r_{1/2}) \cdot \frac{2}{9}$$

$$R_{\uparrow\downarrow} = |r_{\uparrow\downarrow}|^2 = \left| \frac{2}{3} r_{3/2} + \frac{1}{3} r_{1/2} \right|^2 = \frac{4}{9} |r_{3/2}|^2 + \frac{1}{9} |r_{1/2}|^2 + \frac{4}{9} \operatorname{Re}(r_{3/2}^* r_{1/2})$$

$$T_{\downarrow\uparrow} = |t_{\downarrow\uparrow}|^2 = \dots$$

$$T_{\uparrow\downarrow} = |t_{\uparrow\downarrow}|^2 = \dots$$

↑
Interferencijski členi

Če bi gledali celotno odbojnost: $R = R_{\downarrow\uparrow} + R_{\uparrow\downarrow} = \frac{2}{3} |r_{3/2}|^2 + \frac{1}{3} |r_{1/2}|^2$

Podobno za celotno prepustnost: $T = \frac{2}{3} |t_{3/2}|^2 + \frac{1}{3} |t_{1/2}|^2$

Priverimo če res velja $T+R = 1$

$$T+R = \frac{2}{3} \underbrace{\left(|r_{3/2}|^2 + |t_{3/2}|^2 \right)}_1 + \frac{1}{3} \underbrace{\left(|r_{1/2}|^2 + |t_{1/2}|^2 \right)}_1 = 1$$

Iz pogoja za vnitarnost Sipalne matrike.

To smo izpeljali brez da bi lije upoštevali delto; torej šisto splošno.

Teorija Motnje

[Anharmonski linearni oscilator]

$$H = \underbrace{\frac{p^2}{2m}}_{H_0} + \underbrace{\frac{1}{2} \hbar \omega^2 x^2}_{H'} + \lambda x^4$$

$$H_0 |n\rangle^0 = E_n^0 |n\rangle^0$$

$$E_n^0 = \hbar \omega \left(\frac{1}{2} + n \right); \quad n = 0, 1, 2, \dots$$

} Nemoten oscilator

$$E_n + E_n^0 + \underbrace{\langle n | H' | n \rangle^0}_{} + \dots$$

Dogovor:

1. red teorije motnje
2. nedegenerirana stanja

$$|n\rangle^0 \Rightarrow |n\rangle$$

Nekatere lastnosti stanja nemotenega.

$$X = \frac{x_0}{\sqrt{2}} (a^\dagger + a)$$

$$X^2 = \frac{x_0^2}{2} (a^\dagger + a)^2$$

$$\langle n | \lambda x^4 | n \rangle = \lambda \langle x^2 n | x^2 n \rangle$$

$$x^2 = \frac{x_0^2}{2} (a^{+2} + aa^+ + a^+ a + a^2) =$$

$$= \frac{x_0^2}{2} (a^{+2} + 1 + 2a^+ a + a^2)$$

$$|x^2 n\rangle = \cancel{4}|x^2 n\rangle$$

$$= \frac{x_0^2}{2} (|a^{+2}|n\rangle + 1|n\rangle + 2a^+ a|n\rangle + a^2|n\rangle =$$

$$= \frac{x_0^2}{2} (\sqrt{(n+1)(n+2)}|n+2\rangle + |n\rangle + 2n|n\rangle + \sqrt{n(n-1)}|n-2\rangle)$$

$$\Rightarrow \lambda \langle x^2 n | x^2 n \rangle = \lambda \frac{x_0^4}{4} [(n+1)(n+2) + (2n+1)^2 + n(n-1)] =$$

$$= \lambda \frac{x_0^4}{4} [n^2 + 3n + 2 + 4n^2 + 4n + 1 + n^2 - n] =$$

$$= \lambda \frac{x_0^4}{4} [6n^2 + 6n + 3] = \frac{3}{4} x_0^4 \lambda [2n^2 + 2n + 1] =$$

$$= \frac{3x_0^4 \lambda}{4} [2n^2 + 2n + 1]$$

Toreg so energije v prvem redu popravljajo:

$$E_n = \hbar\omega(n + \frac{1}{2}) + \frac{3x_0^4}{4} \lambda [2n^2 + 2n + 1]$$

$$E_{n+1} - E_n = \hbar\omega + \propto n$$

Vodilni atom v \vec{E}

$$H = H_0 + H'$$

$$= \frac{p^2}{2m} - \frac{e^2}{4\pi\epsilon_0 r} - eEz$$

Unali bazo

$$|lm\rangle |n5\rangle$$

Naredimo perturbacijo
popravki 1. reda

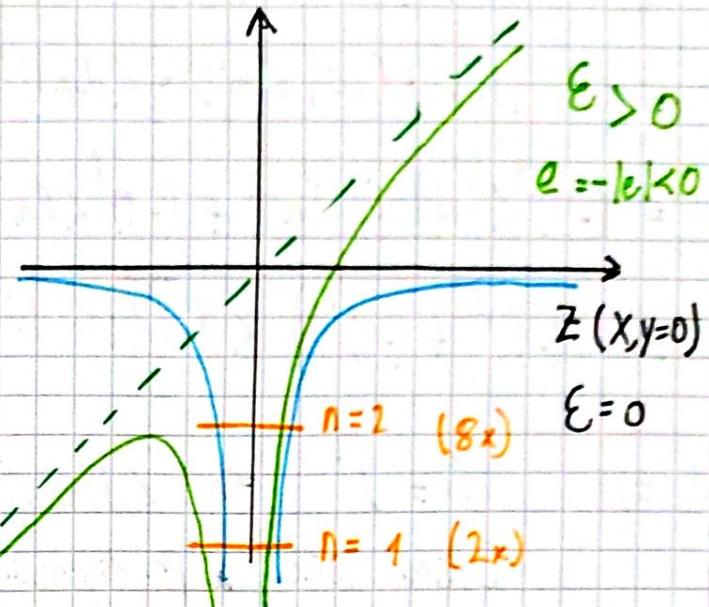
$$|00\rangle$$

$$|11\rangle$$

$$|10\rangle$$

$$|1-1\rangle$$

$$\begin{matrix} & |00\rangle & |11\rangle & |10\rangle & |1-1\rangle \\ \langle 00| & 0 & 0 & M & 0 \\ \langle 11| & 0 & 0 & 0 & 0 \\ \langle 10| & M^* & 0 & 0 & 0 \\ \langle 1-1| & 0 & 0 & 0 & 0 \end{matrix}$$



Hacemo racionali cim Manj matricnih elementov zato uporabimo delno fundamentalne in lahko hitro ugotavimo, da jih je veliko enakih 0.

$$1) [H', L_z] = 0, [H, L_z] = 0 \Rightarrow \langle l'm' | H' | l'm' \rangle = 0 \quad \text{za } m \neq m'$$

$$2) p: \vec{r} \rightarrow -\vec{r}$$

$$p^2 \psi(\vec{r}) = \lambda^2 \psi(\vec{r}) = \psi(\vec{r}) ; \quad \lambda = \pm 1$$

$$[H_0, P] = 0$$

$$\{ H', P \} = 0$$

$$3) \Psi_{nlm}(\vec{r}) = R_{nl}(r) Y_{lm}(\theta, \varphi)$$

$$P Y_{lm}(\theta, \varphi) = (-i)^l Y_{lm}(\theta, \varphi)$$

$$\langle l'm' | \{H', P\} | l'm' \rangle = 0$$

$$= \langle l'm' | H'P + PH' | l'm' \rangle = \langle l'm' | H'P | l'm' \rangle + \langle l'm' | PH' | l'm' \rangle.$$

$$= (-1)^l \langle l'm' | H' | l'm' \rangle + (-1)^l \langle l'm' | H' | l'm' \rangle =$$

$$= ((-1)^l + (-1)^l) \langle l'm' | H' | l'm' \rangle$$

$$\Rightarrow l = l' \Rightarrow \langle l'm' | H' | l'm' \rangle = 0$$

Dobimo nicle za po diagonali:

Zracinajmo tisto kar ostane:

$$M = \langle 001 | H' | 100 \rangle = \int dx dy dz R_{20}^* Y_{00}(\theta, \phi) R_{21}(r) Y_{10}(\theta, \phi) (-e \epsilon_z)$$

$$= \int_0^\infty r^2 dr \int_0^\pi d\theta \int_0^{2\pi} d\phi 6 \sin \theta \frac{2}{(2r_B)^{3/2}} \left(1 - \frac{r}{2r_B}\right) e^{-r/2r_B} \frac{1}{\sqrt{4\pi}} \frac{1}{\sqrt{3}} \frac{1}{(2r_B)^{3/2}} \frac{r}{r_B} e^{-r/2r_B}$$

$$\cdot \frac{\sqrt{3}}{4\pi} \cos \theta (-e \epsilon_z \cos \theta) =$$

$$= -\frac{e \epsilon_z}{(2r_B)^3} \frac{2}{4\pi} \int_0^\infty r^2 dr \left(1 - \frac{r}{2r_B}\right) e^{-r/2r_B} \frac{r^2}{r_B} e^{-r/2r_B} \int_{-1}^1 d(\cos \theta) \cos^2 \theta \int_0^{2\pi} d\phi =$$

$$= -\frac{2}{3} \frac{e \epsilon_z}{(2r_B)^3} \int_0^\infty d\left(\frac{r}{r_B}\right) r_B \left(\frac{r}{r_B}\right)^2 \left(1 - \frac{r}{2r_B}\right) e^{-\frac{r}{r_B}} \left(\frac{r}{r_B}\right)^2 r_B =$$

$$= -\frac{e \epsilon_z}{12} r_B \int_0^\infty du \left(u^4 - \frac{1}{2} u^5\right) e^{-u} = -\frac{e \epsilon_z}{12} r_B \left(\Gamma(3) - \frac{1}{2} \Gamma(4)\right)$$

$$= -2e \epsilon z r_B 2 \cdot \left(-\frac{3}{2}\right) = \underline{\underline{3e \epsilon z r_B}}$$

lubo smo zapisali matriko motnje, ki jo moramo sedaj diagonalizirati.
lubo Naredimo tudi bločno.

$$|00\rangle |10\rangle |11\rangle |1-1\rangle$$

$$\begin{bmatrix} \langle 00| & M \\ \langle 10| & M^* \\ \langle 11| & \\ \langle 1-1| & \end{bmatrix} = \begin{bmatrix} 0 & M \\ M^* & 0 \\ & 0 \\ & 0 \end{bmatrix}$$

$$\text{že diag } \lambda_{1,2} = 0$$

lastna vektorja sta $|11\rangle, |1-1\rangle$

Te dve stanji torj ne
čutita motnje.

$$\det \begin{pmatrix} -\lambda & M \\ M & -\lambda \end{pmatrix} = \lambda^2 - M^2 = 0 \Rightarrow \lambda_{3,4} = \pm M$$

$$i) \lambda = -M = 3|e|E_B$$

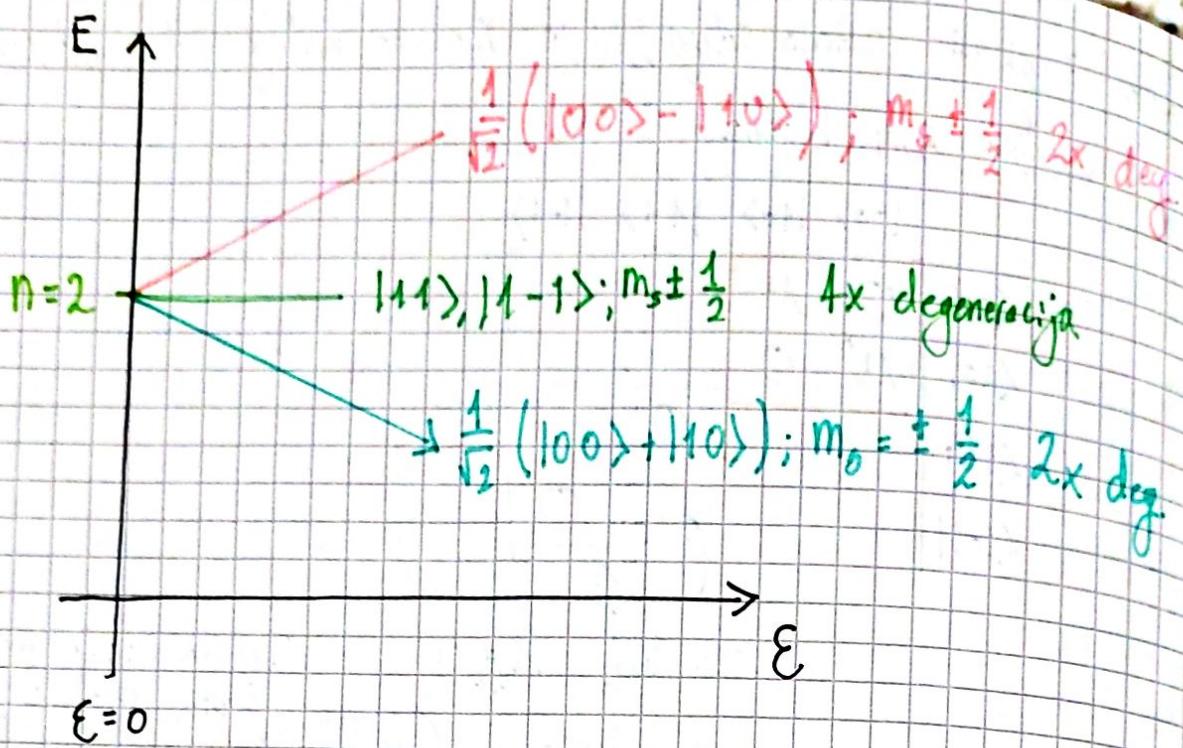
$$\begin{pmatrix} M & M \\ M & M \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} \alpha \\ -\alpha \end{pmatrix} \Rightarrow \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

Torej je lastno stanje $\frac{1}{\sqrt{2}} (|00\rangle - |10\rangle)$

$$ii) \lambda = M = -3|e|E_B$$

$$\begin{pmatrix} -M & M \\ M & -M \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \alpha = \beta$$

Torej je lastno stanje $\frac{1}{\sqrt{2}} (|00\rangle + |10\rangle)$



Rečimo: $\frac{1}{\sqrt{2}} (|100\rangle - |110\rangle) \equiv |-\rangle$

$$\frac{1}{\sqrt{2}} (|100\rangle + |110\rangle) \equiv |+\rangle$$

Izračunajmo:

$$\begin{aligned} \langle - | z | - \rangle &= \frac{1}{\sqrt{2}} (\langle 001 | - \langle 101 |) \otimes \frac{1}{\sqrt{2}} (|100\rangle - |110\rangle) = \\ &= \frac{1}{2} (- \langle 001 | z | 10\rangle - \langle 101 | z | 00\rangle) = \\ &= \frac{1}{2} (- \langle 001 | z | 10\rangle - \langle 001 | z | 10\rangle^*) = - \text{Re}(\langle 001 | z | 10\rangle) = \end{aligned}$$

četiri
vezanih
člana potekao

(Zaradi pomožnega
brzih let in lili z)

$$\langle 001 | H' | 10\rangle = 3eE r_B$$

$$\langle 001 | z | 10\rangle = \frac{1}{eE} \langle 001 | H' | 10\rangle = - 3r_B$$

$$= + r_B$$

Drugi se pa premaline ravno v nasprotno smer

$$\langle + | r_B | + \rangle = - 3r_B$$