

Naloga na str. 71

Poves pod
lastno težo.

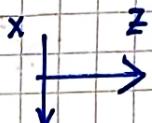
$$\vec{M} \approx EI(-\ddot{y}, \dot{x}, 0)$$

$$F_x = -EI_x^{(3)} + F_z \dot{x}$$

$$F_y = -EIy^{(3)} + F_z \dot{y}$$

$$EI_x^{(4)} - F_z \ddot{x} - F_z \dot{x} - K_x = 0$$

$$EI_y^{(4)} - F_z \ddot{y} - F_z \dot{y} - K_y = 0$$



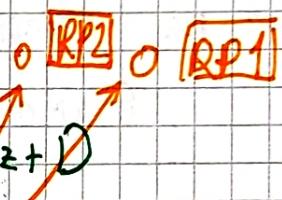
Pri nas:

$$EI_x^{(4)} - F_z \ddot{x} - F_z \dot{x} - K_x = 0 ; K_x = \frac{mg}{L}$$

ni sile v smeri z

$$\Rightarrow x^{(4)} = \alpha ; \alpha = \frac{mg}{LEI}$$

$$\text{To lahko zelo hitro rešimo: } x = \frac{\alpha}{24} z^4 + A z^3 + B z^2 + C z + D$$



Robni pogoj:

$$1. x(z=0) = 0$$

$$2. \dot{x}(z=0) = 0 \quad \left. \begin{array}{l} \text{ne bi veljalo če bi} \\ \text{bilo nujno upo} \end{array} \right\}$$

$$3. M_i(z=L) = 0 \Rightarrow \ddot{x}(z=L) = 0 \quad \text{in} \quad \ddot{y}(z=L) = 0$$

$$4. F_x(z=L) = 0 \Rightarrow x^{(3)}(z=L) = 0$$

$$F_y(z=L) = 0 \Rightarrow y^{(3)}(z=L) = 0$$

$$\dot{x} = \frac{\alpha}{6} z^3 + 3A z^2 + 2B z$$

$$\ddot{x} = \frac{\alpha}{2} z^2 + 6A z + 2B \Rightarrow 0 = \frac{\alpha}{2} L^2 + 6AL + 2B \Rightarrow B = \frac{-\alpha}{4} L^2 + \frac{\alpha L^2}{2}$$

$$x^{(3)} = \alpha z + 6A \Rightarrow \alpha L = -6A$$

$$\Rightarrow B = + \frac{\alpha L^2}{4}$$

$$\Rightarrow A = -\frac{\alpha L}{6}$$

$$\Rightarrow x = \frac{\alpha}{24} z^4 - \frac{\alpha L}{6} z^3 + \frac{\alpha L^2}{3} z^2$$

$$F_x = -EIx^{(3)} \quad x^{(3)} \Big|_{z=0} = -\frac{\alpha L^2}{6} z + \cancel{\frac{\alpha}{L^2} L^2}$$

$$F_x = EI\alpha L = EI L \frac{mg}{EI\alpha} = mg \quad \left. \begin{array}{l} \text{Sila na desni presek} \\ (\text{v smeri naraščanja polja}) \end{array} \right\}$$

Poglejmo se navore:

$$\vec{M}(z=0) = EI(-\ddot{y}(z=0), \ddot{x}(z=0), 0) \quad \text{se dogaja v ravnini}$$

$$\vec{M} = EI \frac{\alpha}{2} L^2 \hat{e}_y = \frac{EI}{2} \frac{mg}{L\alpha} L^2 \hat{e}_y$$

$$\Rightarrow \vec{M}(z=0) = \frac{L}{2} mg \hat{e}_y$$

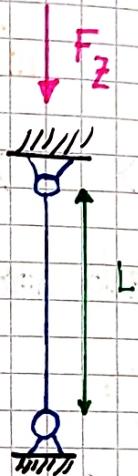
Naloga na stvari: [Eulerjeva nestabilnost]

Startamo iz:

$$EIx^{(4)} - F_z \ddot{x} - \dot{F_z} \dot{x} - K_x = 0$$

↑ uer se F_z ne spreminja
 Vzdolž z

$$= -F_z$$



$$v = \ddot{x}$$

$$EI\ddot{v} + |F_z|v = 0 \quad / : EI$$

Vzamemo rešitev/nastavek:

$$\ddot{v} + \frac{|F_z|}{EI} v = 0 \quad v = A' \sin(\omega z) + B' \cos(\omega z) = \ddot{x}$$

$$x = D \sin(\omega z) + C \cos(\omega z) + A + Bz$$

Robni pogoji:

$$i) x(0) = 0$$

$$ii) x(L) = 0$$

$$iii) \ddot{x}(0) = 0 \quad (\text{ni navorov})$$

$$iv) \ddot{x}(L) = 0 \quad (\text{ni navorov})$$

$$i) A + C = 0 \quad \left. \begin{array}{l} \\ \end{array} \right\} A = 0$$

$$iii) C\omega^2 = 0 \Rightarrow C = 0 \quad \left. \begin{array}{l} \\ \end{array} \right\} C = 0$$

$$x = D \sin(\omega z) + Bz$$

$$ii) D \sin(\omega L) + BL = 0$$

$$iv) -D\omega^2 \sin(\omega L) = 0$$

$$\sin(\omega L) = 0$$

$$\omega = \frac{n\pi}{L}$$

Samo $n=1$ je fizikalni mode. Ostalo bi bilo ostala vpetja na polovici.
Izčimo tipi:

$$x = D \sin\left(\frac{z\pi}{L}\right)$$

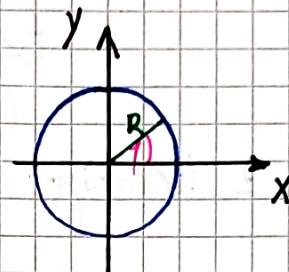
$$\frac{\sigma}{L} = \sqrt{\frac{|F_z|}{EI}}$$

$$|F_z| = \frac{EI\pi^2}{L^2}$$

Izračunajmo še moment I:

$$I = \int x^2 dS$$

$$I = 4 \int_0^R \int_0^{\frac{\pi}{2}} r^2 \cos^2 \varphi r dr d\varphi = \pi \frac{R^4}{4}$$

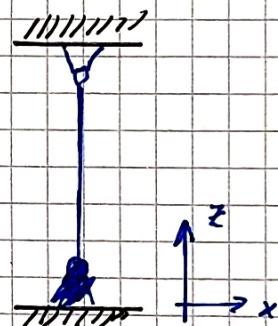


Nalogu isto kot prej le Asimetrično vpetje

Vzamemo lahko rešitev od prej. Le ročni pogoji se spremenijo.

Ročni pogoji so taki:

$$x = A + Bz + C \cos(\omega z) + D \sin(\omega z)$$



$$\textcircled{1} \quad x(0) = 0 \quad ; \quad \textcircled{1} \quad A + C = 0 \Rightarrow A = -C$$

$$\textcircled{2} \quad x(L) = 0 \quad ; \quad \textcircled{3} \quad 0 = \omega D - B \Rightarrow B = \omega D$$

$$\textcircled{3} \quad \dot{x}(0) = 0 \quad ; \quad \textcircled{2} \quad -\frac{B}{\omega} \sin(\omega L) + C \cos(\omega L) + BL - C = 0$$

$$\textcircled{4} \quad \ddot{x}(L) = 0 \quad ; \quad \textcircled{4} \quad -\omega^2 D \sin(\omega L) - \omega^2 C \cos(\omega L) = 0$$

Torej:

$$\textcircled{2} \Rightarrow \det \begin{vmatrix} -\omega^2 D \sin(\omega L) & -\omega^2 C \cos(\omega L) \\ D(\sin(\omega L) - \omega L) & C(\cos(\omega L) - 1) \end{vmatrix} = 0$$

$$\det = -h^2 \sin(hL) [\cos(hL) - 1] + h^2 \cos(hL) [\sin(hL) - hL] = 0$$

$$\sin(hL) [\cos(hL) - 1] = \cos(hL) [\sin(hL) - hL]$$

$$\operatorname{tg}(hL) [\cos(hL) - 1] = \sin(hL) - hL$$

$$\sin(hL) - \operatorname{tg}(hL) = \sin(hL) - hL$$

$$\operatorname{tg}(hL) = hL$$

To ūsimmo 2 iteraciju arctan na kalkulatorju. $hL \approx 4,49$.

Naloga na str. 76

$$EI \ddot{x}^{(4)} - F_z \ddot{x} - \dot{F}_z \dot{x} - K_x = -g \frac{d^2 x}{dt^2}$$

$$EI \ddot{x}^{(4)} = -g \frac{d^2 x}{dt^2}$$

Rešujmo:

$$\ddot{x}^{(4)} + \frac{g}{EI} \frac{d^2 x}{dt^2} = 0$$



Vzemimo časovni nastavek:

$$u(z,t) = v(z) e^{-i\omega t}$$

$$\Rightarrow V^{(4)} e^{-i\omega t} - \frac{g}{EI} V \omega^2 e^{-i\omega t} = 0$$

$$V^{(4)} - \frac{g}{EI} V = V^{(4)} - \alpha^4 V = 0$$

Resitev so eksponenti oz.:

$$V = A \operatorname{sh} \alpha z + B \operatorname{ch} \alpha z + C \sin \alpha z + D \cos \alpha z$$

Robni pogoji:

i) $v(0) = 0 \Rightarrow B + D = 0 \quad \boxed{D = -B}$

ii) $\dot{v}(0) = 0 \Rightarrow A\alpha + C\alpha = 0 \quad \boxed{C = -A}$

iii) $\ddot{v}(L) = 0 \Rightarrow A\alpha^2 \operatorname{sh} \alpha L + B\alpha^2 \operatorname{ch} \alpha L - C\alpha^2 \sin \alpha L - D\alpha^2 \cos \alpha L = 0$

iv) $V^{(3)}(L) = 0 \Rightarrow A\alpha^3 \operatorname{ch} \alpha L + B\alpha^3 \operatorname{sh} \alpha L - C\alpha^3 \cos \alpha L + D\alpha^3 \sin \alpha L = 0$

$$A(\operatorname{sh} \alpha L + \sin \alpha L) + B(\operatorname{ch} \alpha L + \cos \alpha L) = 0$$

$$A(\operatorname{ch} \alpha L + \cos \alpha L) + B(\operatorname{sh} \alpha L - \sin \alpha L) = 0$$

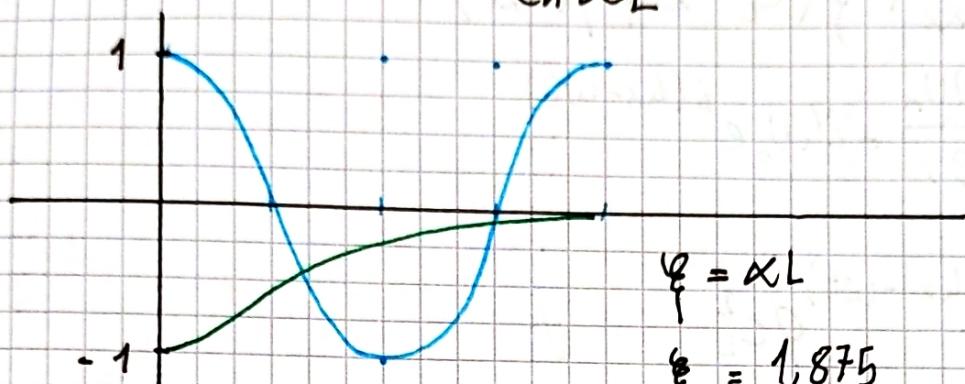
Zahtevamo $\det = 0$, da ima sistem rešitve:

$$\operatorname{sh}^2 \alpha L - \sin^2 \alpha L - \operatorname{ch}^2 \alpha L - \cos^2 \alpha L - 2 \operatorname{ch} \alpha L \cos \alpha L = 0$$

$$\text{Uporabimo: } \sin^2 + \cos^2 = 1 \quad sh^2 - ch^2 = 1$$

$$-2 - 2ch\alpha L \cos \alpha L = 0$$

$$\Rightarrow \cos \alpha L = \frac{-1}{ch \alpha L}$$



$$\varphi = \alpha L$$

$$\varphi_0 = 1,875$$

$$\varphi_1 = 4,694$$

$$\varphi_2 = 7,855$$

$$\varphi_n = \frac{(2n+1)}{2} \pi$$

Poglejmo sedaj še frekvence:

$$\alpha^4 = \frac{s}{EI} \omega^2 \quad \omega = \pm \sqrt{\left(\frac{E}{L}\right)^2 \frac{EI}{s}}$$

$$= \pm \left(\frac{E}{L}\right)^2 \sqrt{\frac{EI}{s}}$$

Duloga na str. 82

$$Z = \frac{P}{V} \quad \dots \text{impedanca}$$

Koliko tlaka rabimo, da "dodamo" hitrost V ?

Imejmo tlaci ni val v x smeri:

$$\vec{u} = \vec{u}_0 e^{i(\omega t - kx)}$$

Mi imamo za longitudinalni val odmike v x in div v x:

$$Z = \frac{B_{xx}}{V_x}$$

$$\cancel{Z_{xx}} = 2g, \quad$$

$$Z_{ij} = 2gC_T^2 u_{ij} + g(C_L^2 - 2C_T^2) u_{hh} \delta_{ij} \quad \text{edini neničlen}$$

$$Z_{xx} = 2gC_T^2 u_{xx} + g(C_L^2 - 2C_T^2)(u_{xx}) =$$

$$U_{xx} = \frac{\partial U_x}{\partial x} = ikU_0 e^{i(kx - \omega t)}$$

$$= ikU_0 e^{i(kx - \omega t)} g C_L^2$$

$$V_x = \frac{\partial U_x}{\partial t} = -i\omega U_0 e^{i(kx - \omega t)}$$

Dobimo tak vmesen rezultat:

$$Z = \frac{kg C_L^2}{\omega}$$

Tu upoštevamo še:

$$\omega^2 = k^2 C_L^2$$

In dobimo:

$$Z = g C_L ; \quad C_L^2 = \frac{E(1-\beta)}{g(1+\beta)(1-2\beta)}$$

$$Z = \frac{\sqrt{3} \sqrt{E(1-\beta)}}{\sqrt{(1+\beta)(1-2\beta)}}$$

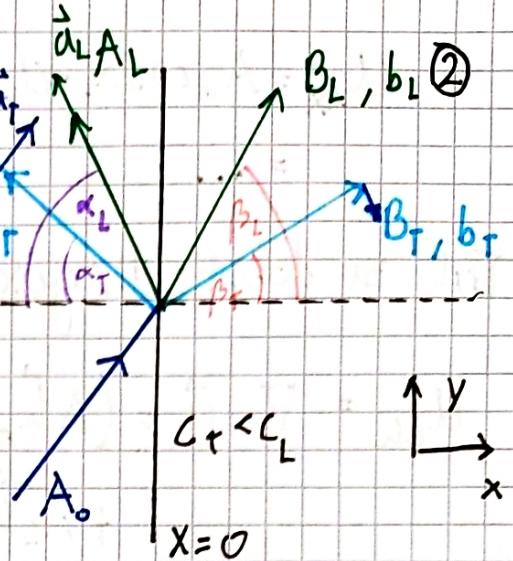
Za transverzalno (vzumes Z_{xy}) pride pa $Z = g C_L$.

Naloga na str. 83

$$\vec{U}_1 = (A_0 \vec{a}_0 e^{i\omega_0 \vec{r}} + A_T \vec{a}_T e^{i\omega_T \vec{r}} + A_L \vec{a}_L e^{i\omega_L \vec{r}}) e^{-i\omega t} \quad (1)$$

$$\vec{U}_2 = (B_T \vec{b}_T e^{iq_T \vec{r}} + B_L \vec{b}_L e^{iq_L \vec{r}}) e^{-i\omega t}$$

To enačimo na meji $X=0$:



$$A_0 \vec{a}_0 e^{i\omega_0 y} + A_T \vec{a}_T e^{i\omega_T y} + A_L \vec{a}_L e^{i\omega_L y} =$$

$$= B_T \vec{b}_T e^{iq_T y} + B_L \vec{b}_L e^{iq_L y}$$

$$\Rightarrow u_{0y} = u_{Ty} = u_{Ly} = q_T y = q_L y$$

Upoštevajmo disperzijo!
reflucijo!

Tako dobimo odbojni zakon:

$$\frac{\sin \alpha_0}{c_{1L}} = \frac{\sin \alpha_T}{c_{1T}} = \frac{\sin \alpha_L}{c_{1L}} = \frac{\sin \beta_T}{c_{2T}} = \frac{\sin \beta_L}{c_{2L}}$$

Poglejmo sedaj amplitudce odbitega valovanja če drugega sredstva

sploh ni.

$$\beta_{ix} = 0 ! \quad \text{ni sile na meji prehoda}$$

Zapisemo Hookeov zakon:

$$\beta_{xx} = 2\beta c_T^2 u_{xx} + \beta(c_L^2 - 2c_T^2) u_{uu}$$

$$\beta_{yx} = 2\beta c_T^2 u_{yx}$$

$$u_{xx} = \frac{\partial u_x}{\partial x}$$

$$u_x = A_0 \cos \alpha_0 e^{i\omega_0 \cdot \vec{r}} - A_L \cos \alpha_L e^{i\omega_L \cdot \vec{r}} +$$

$$+ A_T \sin \alpha_T e^{i\omega_T \cdot \vec{r}}$$

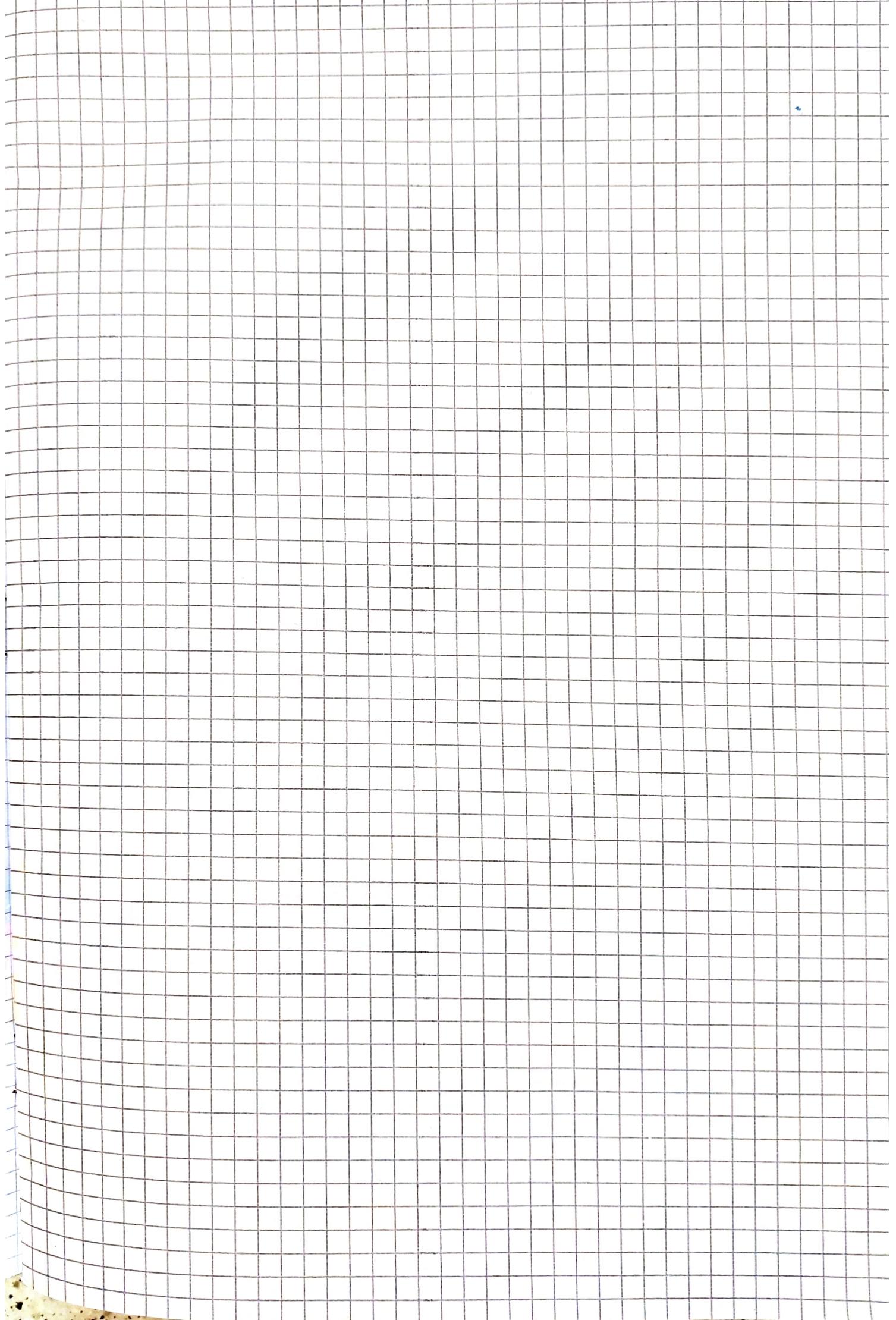
$$u_y = A_0 \sin \alpha_0 e^{i\omega_0 \cdot \vec{r}} + A_L \sin \alpha_L e^{i\omega_L \cdot \vec{r}} + A_T \cos \alpha_T e^{i\omega_T \cdot \vec{r}}$$

$$U_{xx} = A_0 \cos^2 \chi_0 \cdot \tilde{c}_{h_0} e^{i \tilde{\chi}_0 \cdot \vec{r}} + A_L \cos^2 i \chi_0 e^{i \tilde{\chi}_L \cdot \vec{r}} - A_T \sin \alpha_r \cos \alpha_q e^{i \tilde{\chi}_T \cdot \vec{r}}$$

= ...

Tisk za dobit divergencu:

$$U_{hh} = \nabla \cdot \vec{U} = (\tilde{A} \tilde{h}_0 \cdot \tilde{a}_0 e^{i \tilde{\chi}_0 \cdot \vec{r}} + \underbrace{A_T h_T \cdot \tilde{a}_T e^{i \tilde{\chi}_T \cdot \vec{r}}}_{\text{---}} + A_L h_L \cdot \tilde{a}_L e^{i \tilde{\chi}_L \cdot \vec{r}}) e^{-i \omega t}$$



Naloga na str. 25

$$\Gamma = \oint \vec{v} \cdot d\vec{l} = \int (\nabla \times \vec{v}) \cdot d\vec{S} = \int \vec{\omega} \cdot d\vec{S}$$

$$\Gamma = 2\pi r v \Rightarrow v(r) = \frac{\Gamma}{2\pi r}$$

Biot-Savart:

$$\nabla \times \vec{H} = \vec{j}$$

$$\vec{H}(\vec{r}) = \frac{1}{4\pi} \int d^3 r' \frac{\vec{j}(\vec{r}') \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$

$$\tan \varphi = \frac{l}{g}$$

$$\frac{-dl}{\cos^2 \varphi} = \frac{dl}{g}$$

$$\frac{r}{g} = \frac{1}{\cos \varphi}$$

Analogija:

$$\nabla \times \vec{v} = \vec{\omega}$$

$$\vec{v}(\vec{r}) = \frac{1}{4\pi} \int d^3 r' \frac{\vec{\omega}(\vec{r}') \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} =$$

Samo konstanta

$$= \frac{1}{4\pi} \int \vec{\Gamma}(\vec{r}') \cdot d\vec{l}' \times (\vec{r} - \vec{r}') =$$

$$= \frac{\Gamma}{4\pi} \int \frac{d\vec{l}' \cos \varphi}{|\vec{r} - \vec{r}'|^2} = \frac{\Gamma}{4\pi} \left(-\left(\frac{r}{g}\right)^2 \cdot \frac{dl}{g} \right) =$$

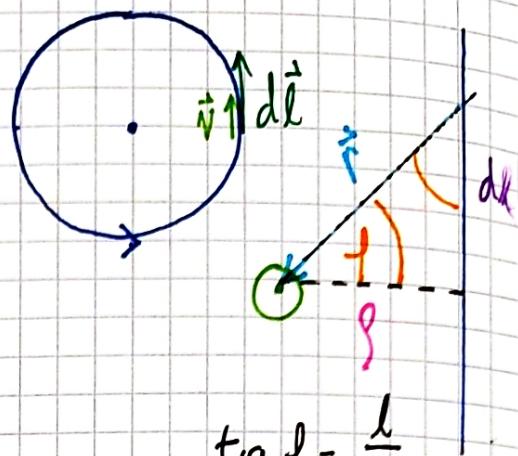
$$= \frac{\Gamma}{4\pi g} \int \frac{-g dl \cos \varphi}{\cos^2 \varphi r^2} =$$

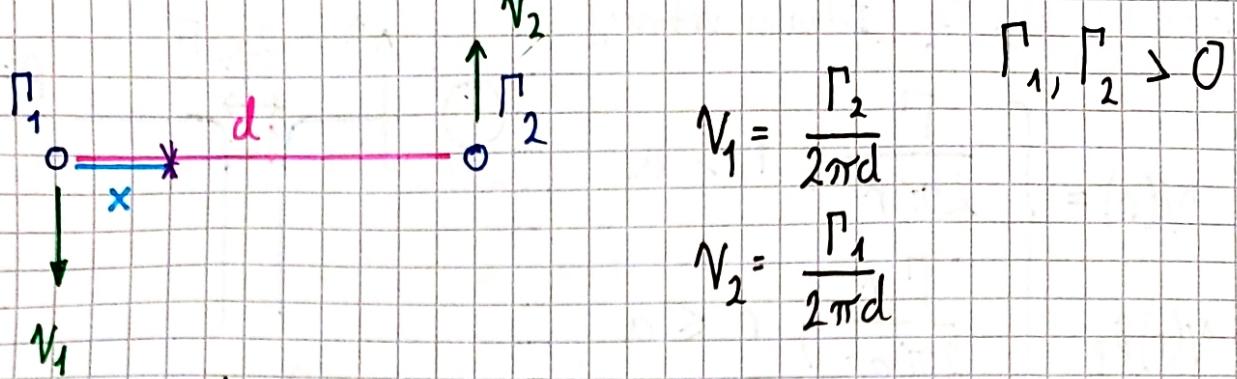
$$= \frac{\Gamma}{4\pi} \int_{-\pi/2}^{\pi/2} \frac{\cos \varphi}{g} d\varphi = \frac{\Gamma}{4\pi g} \sin \varphi \Big|_{-\pi/2}^{\pi/2} =$$

$$= \frac{\Gamma}{2\pi g}$$

Top

Side





$$N_1 = \frac{\Gamma_2}{2\pi d}$$

$$N_2 = \frac{\Gamma_1}{2\pi d}$$

$$\Gamma_1, \Gamma_2 > 0$$

$$N_1 = \omega x \quad \Gamma_2 = 2\pi d \omega x$$

$$N_2 = \omega(d-x) \quad \Gamma_1 = 2\pi d \omega - 2\pi \omega x$$

$$\begin{aligned} \cancel{\Gamma_1} &= 2\pi d \cdot \cancel{\frac{\Gamma_2}{2\pi d x}} - 2\pi \cancel{\frac{\Gamma_2}{2\pi d x}} x \\ \Gamma_1 &= \cancel{\frac{\Gamma_2}{x}} - \cancel{\frac{\Gamma_2}{d}} x \end{aligned}$$

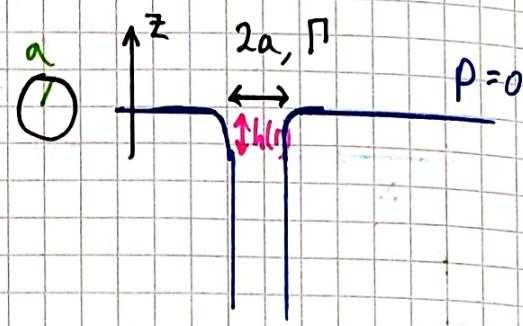
$$\begin{aligned} \Gamma_1 &= 2\pi d^2 \omega - 2\pi d x \omega \\ \Gamma_2 &= 2\pi d \omega x \end{aligned} \quad \Downarrow :$$

$$\frac{\Gamma_1}{\Gamma_2} = \frac{d-x}{x} \quad \frac{\Gamma_1}{\Gamma_2} x = d-x \Rightarrow x = \frac{d}{\frac{\Gamma_1}{\Gamma_2} + 1}$$

$$\omega = \frac{\Gamma_2}{2\pi d} \cdot \frac{\frac{\Gamma_1}{\Gamma_2} + 1}{d} \Rightarrow \omega = \frac{\Gamma_1 + \Gamma_2}{2\pi d^2}$$

Naloga na str. 26 [Idealni vtinec]

$$V(r) = \begin{cases} \frac{\Gamma}{2\pi r}; & r > a \\ \frac{\Gamma r}{2\pi a^2}; & r \leq a \end{cases}$$



$$\omega a = \frac{\Gamma}{2\pi a}$$

i) $r > a : \nabla \times \vec{V} = 0$

Složen Bernoulli;

$$\omega = \frac{\Gamma}{2\pi r a^2}$$

$$V = \frac{\Gamma r}{2\pi a^2}$$

$$\Rightarrow 0 = \rho g h(r) + \frac{1}{2} \rho V^2 = \rho g h + \frac{1}{2} \rho \frac{\Gamma^2}{2\pi^2 r^2}$$

$$\rightarrow h = - \frac{\Gamma^2}{8\pi^2 g r^2}$$

ii) $r < a : \nabla \times \vec{V} = 2\vec{\omega}$

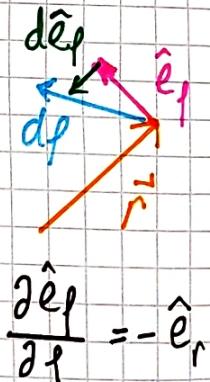
Ne moremo uporabit Bernoullija (zatokovnice je pa vse itak konstantno in nunn nič ne da)

Rješujemo Eulerjero:

$$\rho \frac{\partial \vec{V}}{\partial t} + \rho (\vec{V} \cdot \nabla) \vec{V} = -\nabla p + \rho \vec{g}$$

$$(\vec{V} \cdot \nabla) \vec{V} = (V(r) \hat{e}_r \cdot \nabla) V(r) \hat{e}_r = \frac{1}{r} \frac{\partial (V(r) \hat{e}_r)}{\partial r} = \frac{1}{r} \rho^2 \frac{d \hat{e}_r}{dr},$$

$$= -\frac{V^2(r)}{r} \hat{e}_r$$



$$-\rho \omega^2 r \hat{e}_r = -\nabla p - \rho g \hat{e}_z \quad \rightarrow \rho g h = C(r)$$

$$Z: 0 = -\frac{\partial p}{\partial z} - \rho g \Rightarrow p = -\rho g z + C(r)$$

$$P = \rho g (h(r) - z)$$

To enačbo za z smer bi lahko reproducirali tudi z uporabo Bernoullijeve en. Za vrtincnico:

$$\frac{1}{2} \rho v^2 + \rho g h + 0 = \frac{1}{2} \rho v^2 + \rho g z + p$$

$$p = \rho g (h - z)$$

Poglejmo še za r smer:

$$p: -\rho w^2 r = -\frac{\partial p}{\partial r} = -\rho g \frac{\partial h}{\partial r} \Rightarrow \frac{\partial h}{\partial r} = \frac{w^2}{g} r$$

$$h = \int \frac{w^2}{g} r dr = \frac{w^2}{2g} r^2 + \hat{C} = *$$

Določimo še konstanto takoj da zlepimo visine:

$$\frac{w^2}{2g} a^2 + \hat{C} = -\frac{\Gamma^2}{8\pi^2 g a^2}$$

$$\frac{\Gamma^2 a^2}{4\pi^2 a^2 2g} + \hat{C} = -\frac{\Gamma^2}{8\pi^2 g a^2}$$

$$* = -\frac{\Gamma^2}{8\pi^2 g a^2} \left(2 - \frac{r^2}{a^2} \right)$$

Naloga na str. 31 [točkast izvir in točkast dipol] 3D

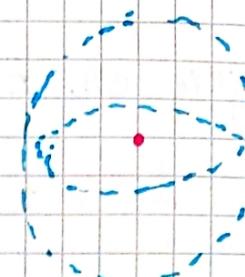
Izvir:

$$\phi(\vec{r}) = -\frac{a}{4\pi r}$$

$$\vec{V}(\vec{r}) = \nabla \phi = \frac{a}{4\pi r^2} \frac{\vec{r}}{r}$$

Preverimo, če je a izdatnost z Gauss izrekom:

$$\oint \vec{V} \cdot d\vec{S} = \frac{a}{4\pi r^2} 4\pi r^2 = a$$



Točkast dipol:

$$\phi(\vec{r}) = -\frac{a}{4\pi |\vec{r} - \Delta Z \hat{e}_z|} + \frac{a}{4\pi |\vec{r} + \Delta Z \hat{e}_z|}$$

$$= -\frac{a}{4\pi} \left(\frac{1}{\sqrt{x^2 + y^2 + (z - \Delta Z)^2}} - \frac{1}{\sqrt{x^2 + y^2 + (z + \Delta Z)^2}} \right)$$

$$= -\frac{a}{4\pi} \left(\frac{1}{\sqrt{x^2 + y^2 + z^2 + \Delta Z^2 - 2z \cdot \Delta Z}} - \right.$$

$$- \left. \frac{1}{\sqrt{x^2 + y^2 + z^2 + \Delta Z^2 + 2z \cdot \Delta Z}} \right) = \begin{matrix} \Delta Z \ll |\vec{r}| = r \\ \Delta Z^2 \approx 0 \end{matrix}$$

$$= -\frac{a}{4\pi} \left(\frac{1}{r \sqrt{1 - \frac{2z \Delta Z}{r}}} - \frac{1}{r \sqrt{1 + \frac{2z \Delta Z}{r^2}}} \right) \approx$$

$$\approx -\frac{a}{4\pi r} \left(1 + \frac{z \Delta Z}{r^2} - 1 + \frac{z \Delta Z}{r^2} \right) \approx -\frac{az \cdot 2\Delta Z}{4\pi r^3} =$$

$$= -\frac{P_z z}{4\pi r^3} \Rightarrow \phi(\vec{r}) = -\frac{\vec{P} \cdot \vec{r}}{4\pi r^3}$$

✓ Splošnem pa:

$$\vec{\nabla}^2 \phi = 0$$

$$\phi(r, \theta, \varphi) = -\frac{1}{4\pi} \sum_{l=0}^{\infty} \sum_{m=-l}^l [A_{lm} r^l + B_{lm} r^{-(l+1)}] \sqrt{\frac{4\pi}{2l+1}} Y_{lm}(\theta, \varphi)$$

Naloga na str. 32 [podobno a je za vrtinec in 2D]

$$\nabla^2 \phi = 0; \phi(r, \varphi)$$

v cilindričnih koordinatah

$$\nabla^2 = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \varphi^2}$$

Izvir:

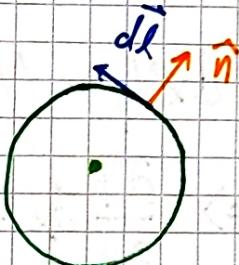
Iščemo $\phi = \phi(r) = \begin{cases} \phi = \text{konst.} & \text{hitrostna polje niz} \\ \phi = \ln r & (\text{nezanimivo}) \end{cases}$

$$\nabla^2(\ln r) = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{1}{r} \right) = 0$$

$$\phi = \frac{Q}{2\pi} \ln r$$

$$\Rightarrow \vec{v} = \frac{Q}{2\pi r} \hat{e}_r = \frac{Q}{2\pi r} \hat{e}_r$$

$$\oint \vec{v} \cdot d\vec{l} = 2\pi \frac{Q}{2\pi} = Q$$



Vrtinec:

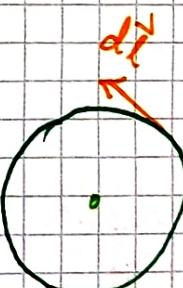
$$\phi \propto \varphi$$

$$\phi = \frac{\Gamma}{2\pi} \varphi$$

$$\vec{v} = \nabla \phi = \hat{e}_\varphi \frac{\partial \phi}{\partial \varphi} = \frac{\Gamma}{2\pi r} \hat{e}_\varphi$$

$$\oint \vec{v} \cdot d\vec{l} = 2\pi r v = \frac{\Gamma}{2\pi r} 2\pi r = \Gamma$$

$$\nabla = \hat{e}_r \frac{\partial}{\partial r} + \hat{e}_\varphi \frac{\partial}{\partial \varphi}$$



Kompleksni potencial v 2D (?)

$$\left. \begin{array}{l} \nabla \cdot \vec{V} = 0 \\ \vec{V} = \nabla \phi \end{array} \right\} \nabla^2 \phi = 0$$

Uvedemo tokovno funkcijo Ψ

$$N_x = \frac{\partial \Psi}{\partial y} \quad N_y = -\frac{\partial \Psi}{\partial x}$$

Tokovnica:

$$\frac{dx}{dy} = \frac{N_x}{N_y}$$

$$dx N_y - N_x dy \rightarrow N_y dx - N_x dy = 0$$

$$\Rightarrow \frac{\partial \Psi}{\partial x} dx + \frac{\partial \Psi}{\partial y} dy = 0 \Rightarrow \underline{\underline{d\Psi = 0}}$$

Ψ je konst. na tokovnici

$$\boxed{\frac{\partial \phi}{\partial x} = \frac{\partial \Psi}{\partial y}}$$

Cauchy-Riemannov sistem

$$\boxed{\frac{\partial \phi}{\partial y} = -\frac{\partial \Psi}{\partial x}}$$

kompleksna
analitična
funkcija

$$\downarrow \quad W(z) = \phi(z) + i\Psi(z); \quad z = x + iy$$

Odvodi v kompleksnem so enaki v vse smere neodvisni od smere odvajanja.
To je def. analitične kompleksne funkcije.

$$\frac{dw}{dz} = \frac{\partial \phi}{\partial x} + i \frac{\partial \Psi}{\partial x} = N_x - i N_y$$

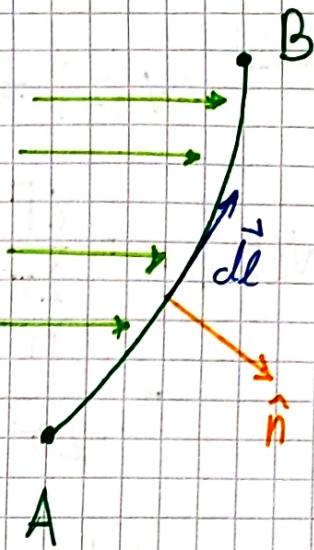
$$\operatorname{Re}\left(\frac{dw}{dz}\right) = N_x$$

$$\frac{dw}{dz} = \frac{\partial \phi}{\partial y} + i \frac{\partial \Psi}{\partial y} = -i N_y + N_x$$

$$\operatorname{Im}\left(\frac{dw}{dz}\right) = -N_y$$

Pretok skozi vrvuljo:

$$\begin{aligned}
 Q &= \int_A^B \vec{v} \cdot \hat{n} dl = \\
 &= \int_A^B \left(\frac{\partial \Psi}{\partial y} n_x - \frac{\partial \Psi}{\partial x} n_y \right) dl = \\
 &= \int \left(\frac{\partial \Psi}{\partial y} \frac{dy}{dl} + \frac{\partial \Psi}{\partial x} \frac{dx}{dl} \right) dl = \\
 &= \int \left(\frac{\partial \Psi}{\partial y} dy + \frac{\partial \Psi}{\partial x} dx \right) = \int d\Psi \\
 &= \underline{\underline{\Psi(B) - \Psi(A)}}
 \end{aligned}$$



$$\begin{aligned}
 dl &= (dx, dy) \\
 \hat{n} &= \frac{(dy, -dx)}{dl}
 \end{aligned}$$

Pretok podan z Im delom.

Uganimo potenciala za izvir in vrtinec:

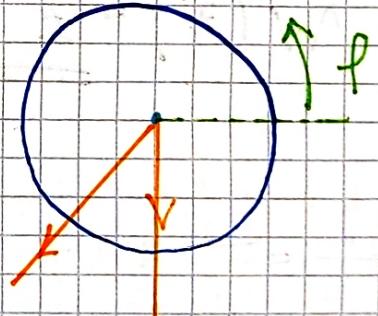
$$\text{Izvir: } W(z) = \frac{Q}{2\pi} \ln z$$

$$\begin{aligned}
 W(z) &= \frac{Q}{2\pi} \ln(re^{i\phi}) = \frac{Q}{2\pi} \left[\ln r + i\phi \right] = \\
 &= \frac{Q}{2\pi} [\ln r + i\phi]
 \end{aligned}$$

Izračunajmo pretok s točkovo funkcijo

$$Q = \Psi(2\pi) - \Psi(0)$$

$$\underline{\underline{Q}}$$



Vrtinec:

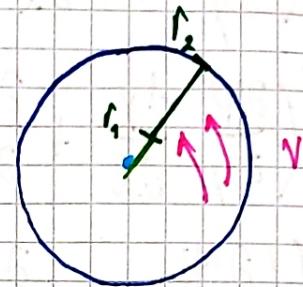
$$W(z) = -\frac{i\pi}{2\pi} \ln z$$

$$\begin{aligned} W(z) &= -\frac{i\pi}{2\pi} [\ln r + i\phi] = \\ &= \frac{\pi}{2\pi} [-i \ln r + \phi] \end{aligned}$$

Poglejmo povezah med r_1 in r_2 :

$$Q = -\frac{\pi}{2\pi} \ln \frac{r_1}{r_2} = \frac{\pi}{2\pi} \ln \frac{r_2}{r_1}$$

To je ubistvu rotacija za 90° z množenjem s kompleksnim številom i.



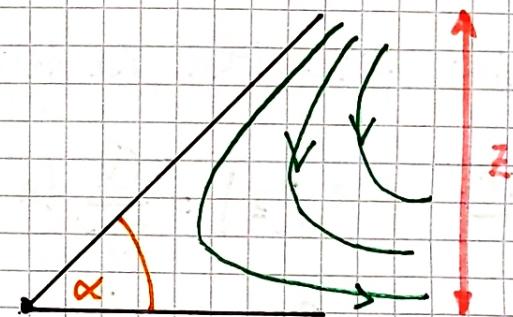
Naloga na str. 38

$$f(z) = z^{\frac{\pi}{\alpha}}$$

$$\begin{aligned} W'(z') &= W(z(z')) = \\ &= W(z'^{\frac{1}{\alpha}}) = \end{aligned}$$

$$W'(z') = z'^{\frac{1}{\alpha}}$$

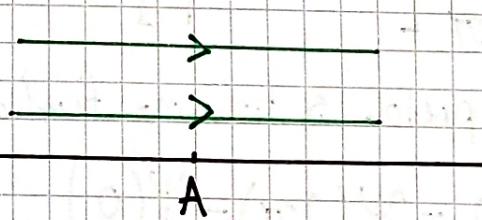
$$\begin{aligned} \frac{dw}{dz} &= \frac{\partial \phi}{\partial x} + i \frac{\partial \psi}{\partial x} \\ &= V_0 \end{aligned}$$



A

$f(z)$

Postavimo preslikati na neko trivialno območje



Tu je $W(z) = V_0 \cdot z$

(odrajamo in dobimo \tilde{V}_0 konstanto)

Zapišimo v polarni obliki, da preverimo hitrostno polje.

$$z' = r e^{i\phi}$$

$$W'(z') = r^{\frac{\pi}{\alpha}} e^{i \frac{1\pi}{\alpha}} = r^{\frac{\pi}{\alpha}} \left(\cos \frac{1\pi}{\alpha} + i \sin \frac{1\pi}{\alpha} \right)$$

$\underbrace{\quad}_{\phi}$

$$\vec{V} = \nabla \phi$$

$$\vec{V}_r \cdot \alpha \nabla \left(r^{\pi/\alpha} \cos \frac{l\pi}{\alpha} \right) = \frac{\partial}{\partial r} \left(r^{\pi/\alpha} \cos \frac{l\pi}{\alpha} \right) =$$

$$= \frac{\pi}{\alpha} r^{\pi/\alpha - 1} \cos \frac{l\pi}{\alpha}$$

$$N_y \propto \frac{\partial}{\partial \rho} \left(r^{\pi/\alpha} \cos \frac{l\pi}{\alpha} \right) = r^{\pi/\alpha - 1} \frac{\pi}{\alpha} \sin \frac{l\pi}{\alpha}$$

Naloga na str. 40

$$W''(z'') = W'(z'(z'')) = z''$$

$$= W(z(z'(z''))) =$$

$$= u(z(z'(z''))) = b = a^{\pi/\alpha}$$

$$-u \left(z''^{\pi/\alpha} + \frac{b^2}{z''^{\pi/\alpha}} \right) = z'$$

$$-a^{\pi/\alpha} z''^{\pi/\alpha} + \frac{a^2}{z''^{\pi/\alpha}} =$$

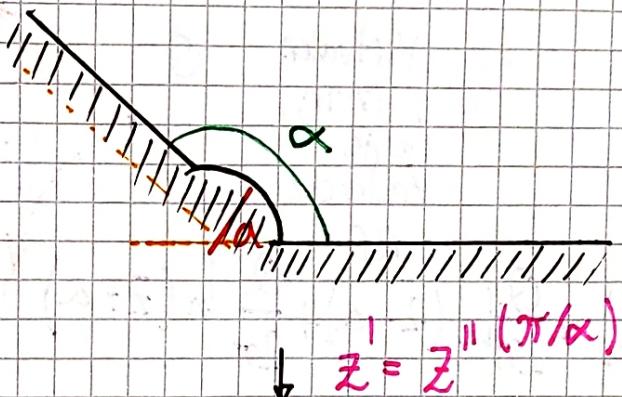
$$= (re^{ip})^{\pi/\alpha} + \frac{a^{2\pi/\alpha}}{(re^{ip})^{\pi/\alpha}} = z$$

$$= (re^{ip})^{\pi/\alpha} + a^{2\pi/\alpha} (re^{-ip})^{-\pi/\alpha} =$$

$$= r^{\pi/\alpha} (\cos(\pi p/\alpha) + i \sin(\pi p/\alpha)) + a^{2\pi/\alpha} r^{-\pi/\alpha} (\cos(\pi p/\alpha) - i \sin(\pi p/\alpha))$$

$$= \cos(\pi p/\alpha) (r^{\pi/\alpha} + a^{2\pi/\alpha} r^{-\pi/\alpha}) + i \sin(\pi p/\alpha) (r^{\pi/\alpha} - a^{2\pi/\alpha} r^{-\pi/\alpha})$$

$$\text{Tehovnica: } \sin\left(\frac{\pi p}{\alpha}\right) \left(r^{\pi/\alpha} - a^{2\pi/\alpha} r^{-\pi/\alpha}\right) = \text{const.}$$



$$z = z' + \frac{b^2}{z'}$$

$$z = z' + \frac{b^2}{z'}$$

Zanima nas hitrost:

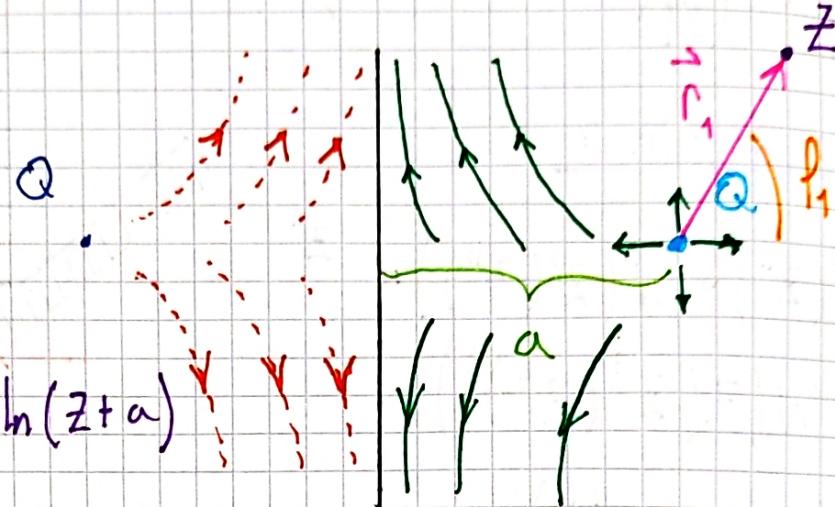
$$V_p = \left(\frac{1}{r} \frac{\partial}{\partial \rho} \dots \right) = -\frac{1}{r} \sin\left(\frac{\pi f}{\alpha}\right) \left(r^{\frac{\pi}{\alpha}} + a^{2\frac{\pi}{\alpha}} r^{-\frac{\pi}{\alpha}} \right) \frac{\pi}{\alpha}$$

$$V_r = \cos\left(\frac{\pi f}{\alpha}\right) \left(\frac{\pi}{\alpha} r^{\frac{\pi}{\alpha}-1} - a^{2\frac{\pi}{\alpha}} \frac{\pi}{\alpha} r^{-\frac{\pi}{\alpha}-1} \right)$$

Naloga na str. 45

Virtualen
izvir,
da je
zadosten
RP

$$W(z) = \frac{Q}{2\pi} \ln(z-a) + \frac{Q}{2\pi} \ln(z+a)$$



↑ dva točkasta izvira

$$W(z) = \frac{Q}{2\pi} \ln(r_1 e^{if_1}) + \frac{Q}{2\pi} \ln(r_2 e^{if_2}) \quad \left. \begin{array}{l} \\ V_x = 0 \end{array} \right\}$$

$$= \frac{Q}{2\pi} (\ln r_1 + if_1 + \ln r_2 + if_2)$$

$$\phi = \operatorname{Re}(w) = \frac{Q}{2\pi} (\ln r_1 + \ln r_2) = \frac{Q}{2\pi} \left(\ln \sqrt{(x-a)^2 + y^2} + \ln \sqrt{(x+a)^2 + y^2} \right)$$

$$\vec{V} = \nabla \phi = \left(\hat{e}_x \frac{\partial}{\partial x}, \hat{e}_y \frac{\partial}{\partial y} \right) =$$

$$= \frac{Q}{2\pi} \left(\frac{1}{\sqrt{(x-a)^2 + y^2}} \frac{2(x-a)}{2\sqrt{(x-a)^2 + y^2}} + \frac{2(x+a)}{2((x+a)^2 + y^2)}, \right.$$

$$\left. \frac{2y}{2((x-a)^2 + y^2)} + \frac{2y}{2((x+a)^2 + y^2)} \right) =$$

$$= \frac{Q}{2\pi} \left(\frac{x-a}{(x-a)^2 + y^2} + \frac{x+a}{(x+a)^2 + y^2}, \frac{y}{(x-a)^2 + y^2} + \frac{y}{(x+a)^2 + y^2} \right)$$

Silo izracunamo preko Bernoullija:

$$F_x = -P \int dS$$

V neshunicnosti

na steni

$$\cancel{P + \frac{1}{2} \rho v^2} = P_0 + \frac{1}{2} \rho v_0^2$$
$$P = -\frac{1}{2} \rho v^2$$

Pri $x=0$:

$$v^2 = \left(\left(\frac{-a}{(-a)^2+y^2} + \frac{a}{a^2+y^2} \right)^2 + \left(\frac{y}{(-a)^2+y^2} + \frac{y}{a^2+y^2} \right)^2 \right) \frac{Q^2}{4\pi^2} =$$
$$= \frac{y^2 Q^2}{(a^2+y^2)^2 \pi^2}$$

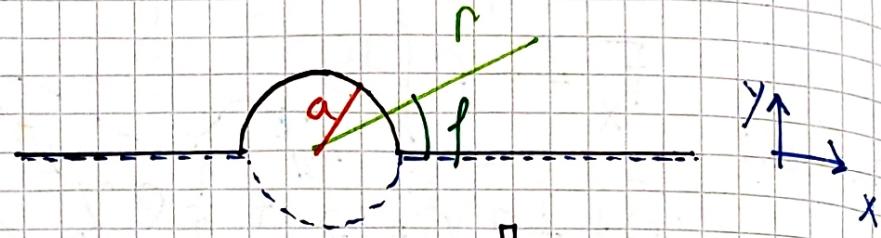
Torej je \cancel{H} : $P = -\frac{1}{2} \rho \frac{Q^2 y^2}{\pi^2 (a^2+y^2)^2}$

$$\frac{F_x}{l} = - \int_{-\infty}^{\infty} P dy = \frac{1}{2} \rho \frac{Q^2}{\pi^2} 2 \int_0^{\infty} \frac{y^2 dy}{(a^2+y^2)^2} = \frac{\rho Q^2}{\pi^2} \left(\left[-\frac{y}{2(a^2+y^2)} \right]_0^{\infty} + \frac{1}{2a} \arctg \frac{y}{a} \right) =$$
$$= \frac{\rho Q^2}{4\pi a} \left(0 + \frac{1}{2a} \frac{\pi}{2} - 0 - 0 \right) = \underline{\underline{\frac{\rho Q^2}{4\pi a}}}$$

Naloga na str. 46

$$W(z) = V_0 \left(z + \frac{a^2}{z} \right) +$$

obdeljanje



$$+ -i \underbrace{\frac{\Gamma}{2\pi}}_{\text{potencial}} \ln z = V_0 \left(r e^{i\phi} + \frac{a^2}{r} e^{-i\phi} \right) - i \frac{\Gamma}{2\pi} (\ln r + i\phi) =$$

vrtenca

$$= V_0 \left(r \cos \phi + i r \sin \phi + \frac{a^2}{r} \cos \phi - \frac{a^2}{r} i \sin \phi \right) - i \frac{\Gamma}{2\pi} \ln r + \frac{\Gamma}{2\pi} \phi$$

$$\vec{V} = \left(V_0 \cos \phi - \frac{a^2}{V_0 r^2} \cos \phi \right) \hat{e}_r + \frac{1}{r} \left(-V_0 r \sin \phi - \frac{a^2}{r} \sin \phi + \frac{\Gamma}{2\pi} \right) \hat{e}_\phi$$

$$\vec{V}(r=a, \phi) = \left(\frac{\Gamma}{2\pi a} - 2 \sin \phi \right) \hat{e}_\phi$$

$$\frac{F_x}{l} = - \int_0^{2\pi} p \cos \phi r d\phi$$

$$\frac{F_y}{l} = - \int p \sin \phi r d\phi$$

Tak iz Bernoullija:

$$p + \frac{1}{2} \rho v^2 = \frac{1}{2} \rho V_0^2$$

$$p = \frac{1}{2} \rho (V_0^2 - v^2)$$

$$p = \frac{1}{2} \rho \left(V_0^2 - \frac{\Gamma^2}{4\pi^2 a^2} - 4 V_0^2 \sin^2 \phi + \frac{2 \Gamma V_0}{\pi a} \sin \phi \right)$$

$$F_x = 0 \quad \left. \right\} \quad \text{Vsi členi so niheli pri integriranju}$$

$$\frac{F_y}{l} = - \int_0^{2\pi} p \sin \phi r d\phi = - \frac{1}{2} \rho \frac{2\Gamma V_0}{\pi a} \int_0^{2\pi} \sin^2 \phi d\phi = - \underline{\underline{\Gamma \rho V_0}}$$

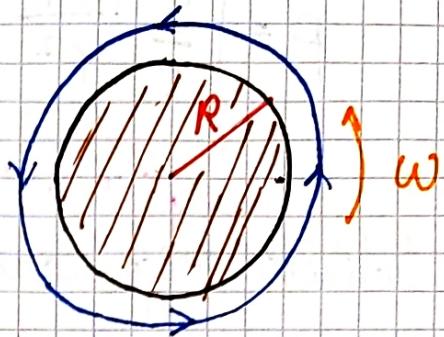
Viskozne tehocine

Naloga na str. 51

$$\text{N.S. } \rho \frac{\partial \vec{v}}{\partial t} + \rho (\vec{v} \cdot \nabla) \vec{v} = -\nabla p + \eta \nabla^2 \vec{v}$$

$\downarrow v_0 \text{ Stacionarno}$

$$\vec{v} = V(r) \hat{e}_r$$



$$\nabla \times \vec{v} = \left(\frac{1}{r} \frac{\partial V_z}{\partial r} - \frac{\partial V_r}{\partial z} \right) \hat{e}_r +$$

$$\nabla \nabla \cdot = \nabla^2 + \nabla \times \nabla \times$$

$$+ \left(\frac{\partial V_r}{\partial z} - \frac{\partial V_z}{\partial r} \right) \hat{e}_\theta +$$

+

$$+ \left(\frac{1}{r} \frac{\partial (rV_r)}{\partial r} - \frac{1}{r} \frac{\partial V_r}{\partial z} \right) \hat{e}_z = \frac{1}{r} \frac{\partial (rV_r)}{\partial r} \hat{e}_z$$

0

$$\nabla \times \nabla \times \vec{v} = - \frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (rV_r)}{\partial r} \right) \hat{e}_r$$

$$(\vec{v} \cdot \nabla) \vec{v} = V \frac{1}{r} \frac{\partial}{\partial r} (V \cdot \hat{e}_r) = V \frac{1}{r} (V (1 - \hat{e}_r)) = - \frac{V^2}{r} \hat{e}_r$$

Ločimo na dve enačbi, za relevantni smeri:

$$\text{f smer: } -\eta \frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (rV_r)}{\partial r} \right) = 0$$

$$\text{f smer: } \rho \frac{V^2}{r} = \frac{\partial p}{\partial r}$$

$$\Rightarrow \frac{1}{r} \frac{\partial (rV_r)}{\partial r} = A$$

$$\frac{\partial (rV_r)}{\partial r} = Ar$$

$$rV_r = \frac{Ar^2}{2} + B \rightarrow V = \frac{Ar}{2} + \frac{B}{r}$$

$$A = 0 \text{ ker } V(r \rightarrow \infty) = 0$$

$$V \cdot R = B$$

$$WR^2 = B$$

||

$$V = \frac{WR^2}{r}$$

hot vratinčna
nit

$$P = \int \frac{\rho}{r} \frac{\omega^2 R^4}{r^2} dr = -\frac{\rho \omega^2 R^4}{2r^2} + P_0$$

~~integracija~~
konstanta

$$\uparrow P = M \cdot \omega$$

S kolikšno močjo moramo vrteći gred?

$$\beta_{ij}^v = 2\eta v_{ij}$$

$$\beta_{rp} = 2\eta v_{rp}$$

$$\Rightarrow \beta_{rp} = 2\eta \frac{1}{2} \left(-\frac{\omega R^2}{r^2} - \frac{\omega R^2}{r^2} \right) = -2\eta \frac{\omega R^2}{r^2}$$

Torej:

$$P = M \cdot \omega$$

$$dM = dF_g \cdot R = \beta_{rp} \cdot dSR = \beta_{rp} R^2 L dp$$

$$\frac{M}{L} = \beta_{rp} R^2 \int_0^{2\pi} dp = \beta_{rp} R^2 2\pi = 4\pi \eta \omega R^2$$

$$\frac{P}{L} = -4\pi \eta \omega^2 R^2$$

Sedaj pa zapišimo še disipitano moč (in vidimo, da je enako).

$$P = \int dV \beta_{ij} v_{ij} = 2\pi \int_R^\infty r dr L 2\eta v_{ij} \cdot v_{ij} = 2\pi \int_R^\infty r dr L (v_{rr}^2 + v_{pp}^2 + 2v_{rp}^2)$$

Vsota kvadratov

Vse z komp.

$$= 2\pi \int_R^\infty r dr 2\eta L 2 \left(\frac{1}{2} \left(-2 \frac{\omega R^2}{r^2} \right) \right)^2 =$$

so nizelne

$$= 8\pi\eta L w^2 R^4 \int_R^\infty \frac{1}{r^3} dr = 4\pi\eta L R^4 w^2 \frac{1}{R^2} =$$

$$= 4\pi\eta L R^2 w^2 \Rightarrow \frac{P}{L} = 4\pi\eta w^2 R^2$$

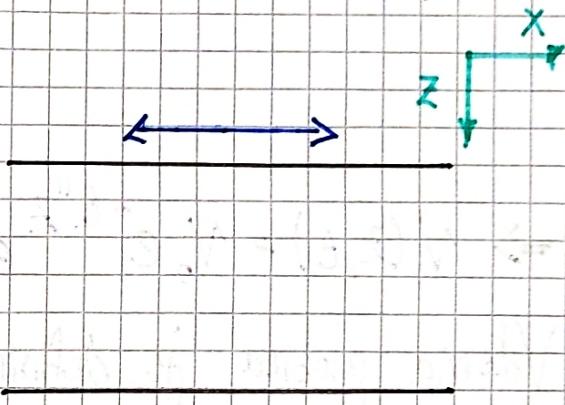
dissipacija je pozitivno definirna!

Prij smo izračunali moč na gred (gred zgrabi moč) in ne moč na tekočino.

Analoga na str. 54

$$\vec{V} = V(z, t) \hat{e}_x$$

$$\rho \frac{\partial \vec{V}}{\partial t} + \rho (\vec{V} \cdot \nabla) \vec{V} = -\nabla p + \eta \nabla^2 \vec{V}$$



Premislimo člene in zapisemo enačbe za x in y smer:

$$\rho i \vec{V} \hat{e}_x = \eta \frac{\partial^2 V}{\partial z^2} \hat{e}_x \rightarrow \rho \frac{\partial V}{\partial t} = \eta \frac{\partial^2 V}{\partial z^2}$$

in vzamemo nastavek ravnega vala: $V(z, t) = A e^{i(hz - \omega t)}$

ker mi valovna enačba (ampulu difuzijsku) bomo dobili kompleksni k.

$$\Rightarrow -\rho i \frac{A}{m} i \omega e^{i(hz - \omega t)} = -\eta \frac{A}{m} h^2 e^{i(hz - \omega t)}$$

$$i \rho \omega = \eta h^2 \quad \text{disperzijska retacija}$$

Pozor!

$$h^2 = \frac{i \rho \omega}{\eta}$$

$$\Rightarrow h = \pm e^{i\pi/4} \sqrt{\frac{\rho \omega}{\eta}} = \pm \left(\sin\left(\frac{\pi}{4}\right) + i \cos\left(\frac{\pi}{4}\right) \right) \sqrt{\frac{\rho \omega}{\eta}} =$$

$$= \pm \left(\frac{\sqrt{2}}{2} + i \frac{\sqrt{2}}{2} \right) \sqrt{\frac{\rho \omega}{\eta}} = \pm \frac{\sqrt{2}}{2} (1+i) \sqrt{\frac{\rho \omega}{\eta}} = \pm \frac{1}{\sqrt{2}} (1+i) \sqrt{\frac{\rho \omega}{\eta}} =$$

$$= \pm (h' + i h'')$$

$$V(z,t) = Ae^{i((k'+ik'')z - \omega t)} + Be^{i[-(k'+ik'')z - \omega t]} =$$

$$= Ae^{(ik'-k')z - i\omega t} + Be^{(-ik'+k'')z - i\omega t} =$$

$$= Ae^{-k''z} e^{i(k_z - \omega t)} + Be^{k''z} e^{-i(k_z + \omega t)}$$

\parallel gic proti 0
0

$$Ae^{i(k_z - \omega t)} = V_0 e^{-i\omega t}$$

$$\Rightarrow A = V_0$$

V neskončnosti ne smem divergirati
(če bi bili plošči neskončno narazen)
(če sta pa blizje je pa vseeno majhen)

$$\Rightarrow V(z,t) = V_0 e^{-k''z} e^{i(k_z z - \omega t)}$$

Vdorna globina je definirana tu z k'' (iz oblike enaice):

$$L = \frac{1}{k''} = \sqrt{\frac{n}{\rho \omega}} - \frac{1}{\frac{\sqrt{2}}{2}} = \sqrt{\frac{2n}{\rho \omega}}$$

$$df(z) = k'z = \sqrt{\frac{\rho \omega}{2n}} z$$

↑
linearen

} profil vdorne globine