

CS/ECE 374 P30

Abhay Varmaraja, Jiawei Tang, Pengxu Zheng

TOTAL POINTS

85 / 100

QUESTION 1

1 30.A. **25 / 25**

✓ - **0 pts** Correct

- **18.75 pts** IDK

- **25 pts** Blank or says the language is decidable

- **20 pts** Says the language is undecidable, but reduction is missing or completely incorrect (for example, reduces in the wrong direction)

- **15 pts** Says the language is undecidable; reduction is on the right track but misses some key step

- **10 pts** Says the language is undecidable, reduction is correct, but proof is missing or incorrect

- **5 pts** Says the language is decidable, reduction is correct, but one direction of the proof is missing or incorrect

- **1 pts** One typo or minor omission

- **3 pts** Two typos or minor omissions

QUESTION 2

2 30.B. **10 / 25**

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- **10 pts** Says the language is decidable, algorithm is correct, but brief justification of algorithm is missing or incorrect.

- **1 pts** One typo or minor omission

- **3 pts** Two typos or minor omissions

💡 After you construct the DFS from the NFS, you have to find cycle in the DFS (the strongly

connected components) first, because there might be cycles occurring among non-accepting states, leading the result to be incorrectly infinite.

QUESTION 3

3 30.C. **25 / 25**

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QUESTION 4

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Submitted by:

- **«Pengxu Zheng»**: «pzheng5»
- **«Jiawei Tang»**: «jiaweit2»
- **«Abhay Varmaraja»**: «abhaymv2»

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Solution:

30.A. (Proof template borrowed from Discussion 12b. solution)

This language is not decidable. For the sake of the contradiction, we assume there exists an algorithm $DecideL1(< M, N >)$ that correctly decides the language L_1 . Then we try to solve the halting problem as follows:

$DecideHalt(<M, N, w>)$:

Encode the following Turing Machine M_1 :

$M_1(x)$:

run M on any input w

return TRUE

Encode the following NFA N_1 :

$N_1(x)$:

Let N have only one starting state with no accepting states and no transitions

return TRUE

if $DecideL1(< M_1, N_1 >)$:

return TRUE

return FALSE

With no accepting states, $L(N_1)$ is essentially the empty set.

We prove the above reduction correct as follows:

Suppose M halts on input w :

Then M_1 accepts any input strings.

Thus, $L(M_1) = \Sigma^* = \overline{L(N_1)}$.

Therefore, $DecideL1$ accepts $<M_1, N_1>$.

Therefore, $DecideHalt$ correctly accepts $<M, w>$.

Suppose M doesn't halt on input w :

Then M_1 diverges on any input strings.

Thus, $L(M_1) = \emptyset = L(N_1) \neq \overline{L(N_1)}$.

Therefore, $DecideL1$ rejects $<M_1, N_1>$.

Therefore, $DecideHalt$ correctly rejects $<M, w>$.

In both cases, *DecideHalt* is correctly decided. However, this contradicts with Turing's theory that the halting problem is never decidable. Therefore, we conclude that the language L_1 is not decidable.

30.B.

This language is decidable. We propose the algorithm to decide L_2 as follows:

We use the powerset construction method introduced earlier to convert NFA N to a DFA named G . G can be viewed as a directed graph with its states being vertices and transitions being edges. After that, we apply DFS to conduct cycle detection on G . If a cycle was found, then we can conclude that there exist an infinite number of transitions (a "self-loop" on a state, or some states that point toward their preceding states, for example) in N , which indicates that the language $L(N)$ is infinite. We conclude the language $L(N)$ is finite otherwise.

30.C. (Discussed with Hengzhi Yuan's Group)

This language is decidable. We propose the algorithm to decide L_3 as follows:

We first construct 2 DFAs for the given input R and N and name the new DFAs G_r and G_n , accordingly. We let the newly created DFAs to accept whatever the input R and N accept, respectively. We then create a new DFA named G to be the product construction of G_r and G_n , which its vertices and edges are the combinations of states and transitions of G_r and G_n , respectively. G now becomes a directed graph. We now apply BFS on the starting state of G to all reachable vertices. For every vertex traversed, we examine if a specific state's composition, say, q_r and q_n , both belong to (or both don't belong to) the set of corresponding accepting states that originate from G_r and G_n , respectively. If that condition is true, then we conclude that $L(G_r) = L(G_n)$, which further implies $L(R) = L(N)$, and vice versa if there exists any combination of q_r and q_n such that either one of the composition fails to belong to the same set of states (in G_r and G_n) with the other.

30.D. (Proof template borrowed from Discussion 12b. solution)

This language is not decidable. For the sake of the contradiction, we assume there exists an algorithm *DecideL4*($\langle M \rangle$) that correctly decides the language L_4 . Then we try to solve the halting problem as follows:

DecideHalt($\langle M, w \rangle$):

 Encode the following Turing Machine M_1 :

$M_1(x)$:

 run M on any input w

 return TRUE

 if *DecideL4*($\langle M_1 \rangle$):

 return TRUE

 return FALSE

We prove the above reduction correct as follows:

 Suppose M halts on input w :

 Then M_1 accepts any input strings.

 Thus, $L(M_1) = \Sigma^*$ that must include some words of even length.

 Therefore, *DecideL4* accepts $\langle M_1 \rangle$.

 Therefore, *DecideHalt* correctly accepts $\langle M, w \rangle$.

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 Suppose M halts on input w :

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 Thus, $L(M_1) = \Sigma^*$ that must include some words of even length.

 Therefore, *DecideL4* accepts $\langle M_1 \rangle$.

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Suppose M doesn't halt on input w :

Then M_1 diverges on any input strings.

Thus, $L(M_1) = \emptyset$, which further implies that $L(M_1)$ must not include any words of even length.

Therefore, *DecideL4* rejects $\langle M_1 \rangle$.

Therefore, *DecideHalt* correctly rejects $\langle M, w \rangle$.

In both cases, *DecideHalt* is correctly decided. However, this contradicts with Turing's theory that the halting problem is never decidable. Therefore, we conclude that the language L_4 is not decidable.

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