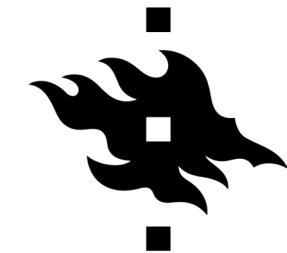


ARVE: Augmented Reality Applications in Vehicle to Edge Networks

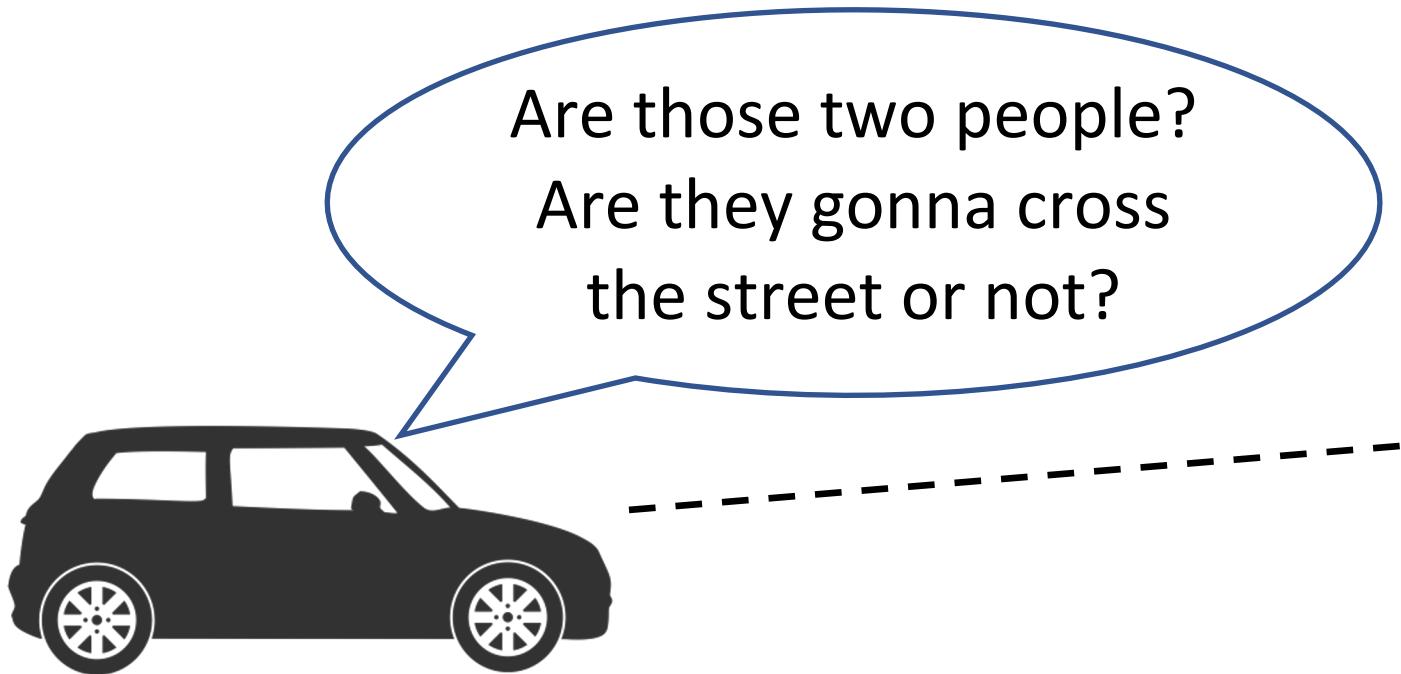
Pengyuan Zhou, Wenxiao Zhang, Tristan Braud,
Pan Hui, Jussi Kangasharju



HELSINGIN YLIOPISTO
HELSINGFORS UNIVERSITET
UNIVERSITY OF HELSINKI



Hazards of self-driving



Hazards of self-driving

BIZ & TECH // BUSINESS

After Uber accident, fewer people want self-driving cars

 David R. Baker | Aug. 16, 2018 | Updated: Aug. 16, 2018 4 a.m.

[f](#) [t](#) [e](#) [...](#) [3](#)



1 of 3

A Cruise self-driving car is tested last year on 11th Street in San Francisco.
Photo: Paul Chinn / The Chronicle 2017

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Report finds 'worrisome' levels of lead, arsenic in some baby foods

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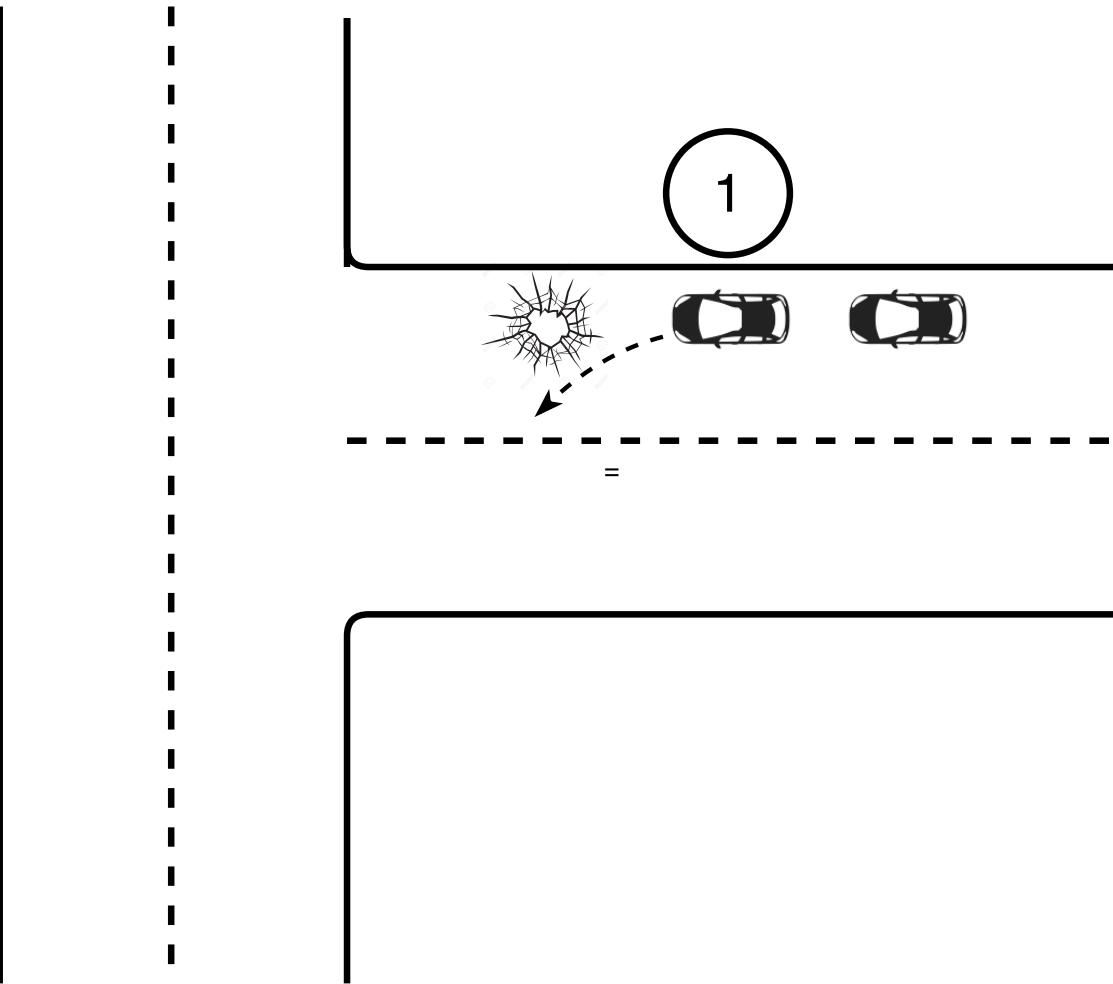
Hazards of self-driving



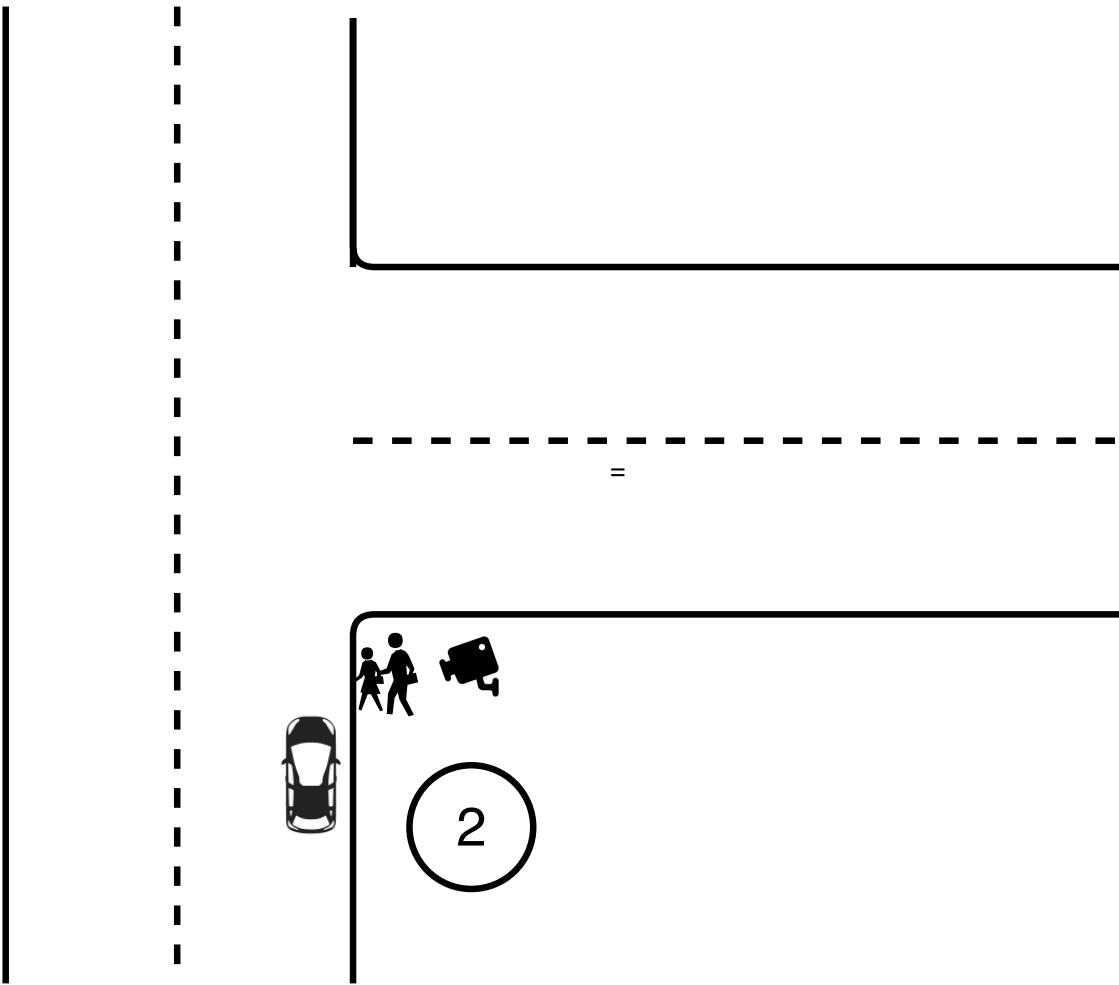
AR-HUD

- more realistic
- more information
- faster to learn

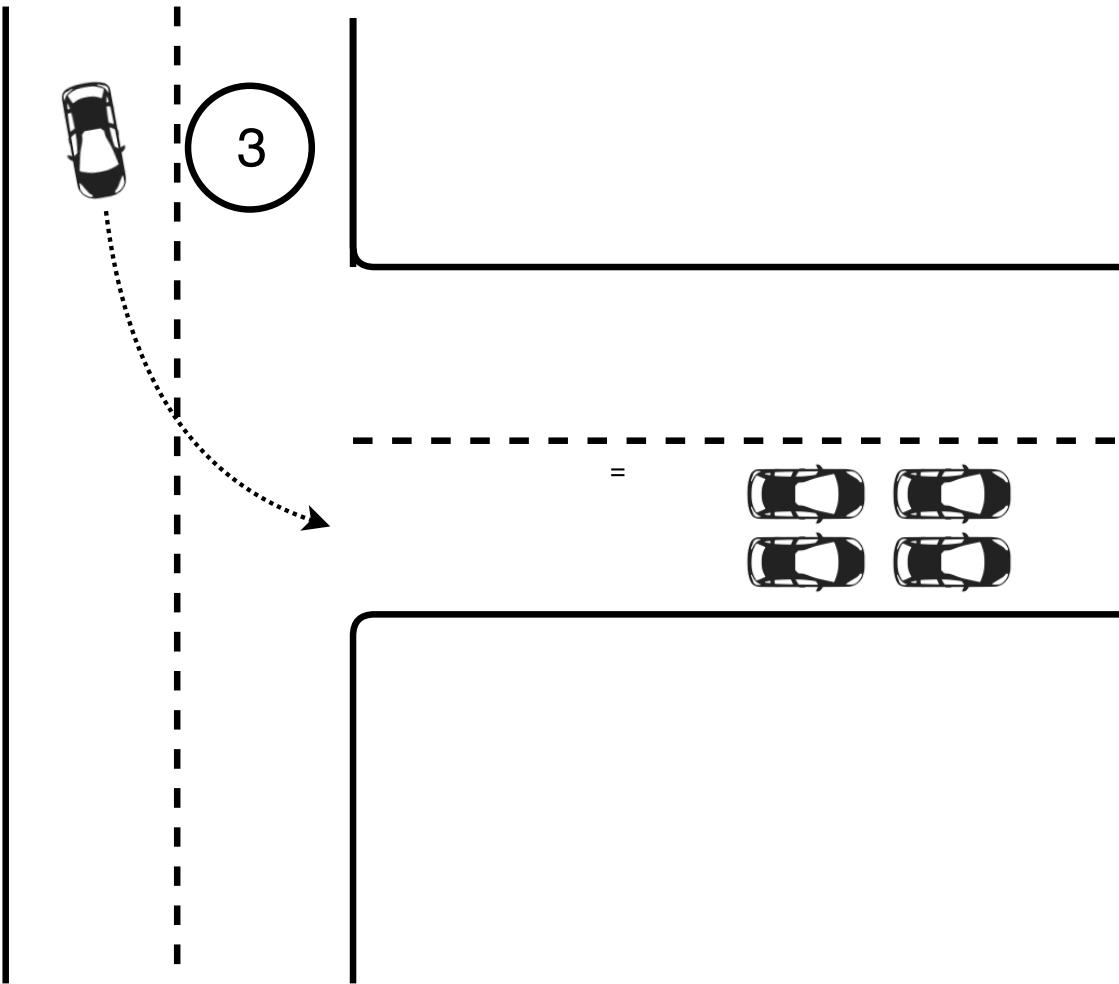
Hazards of self-driving



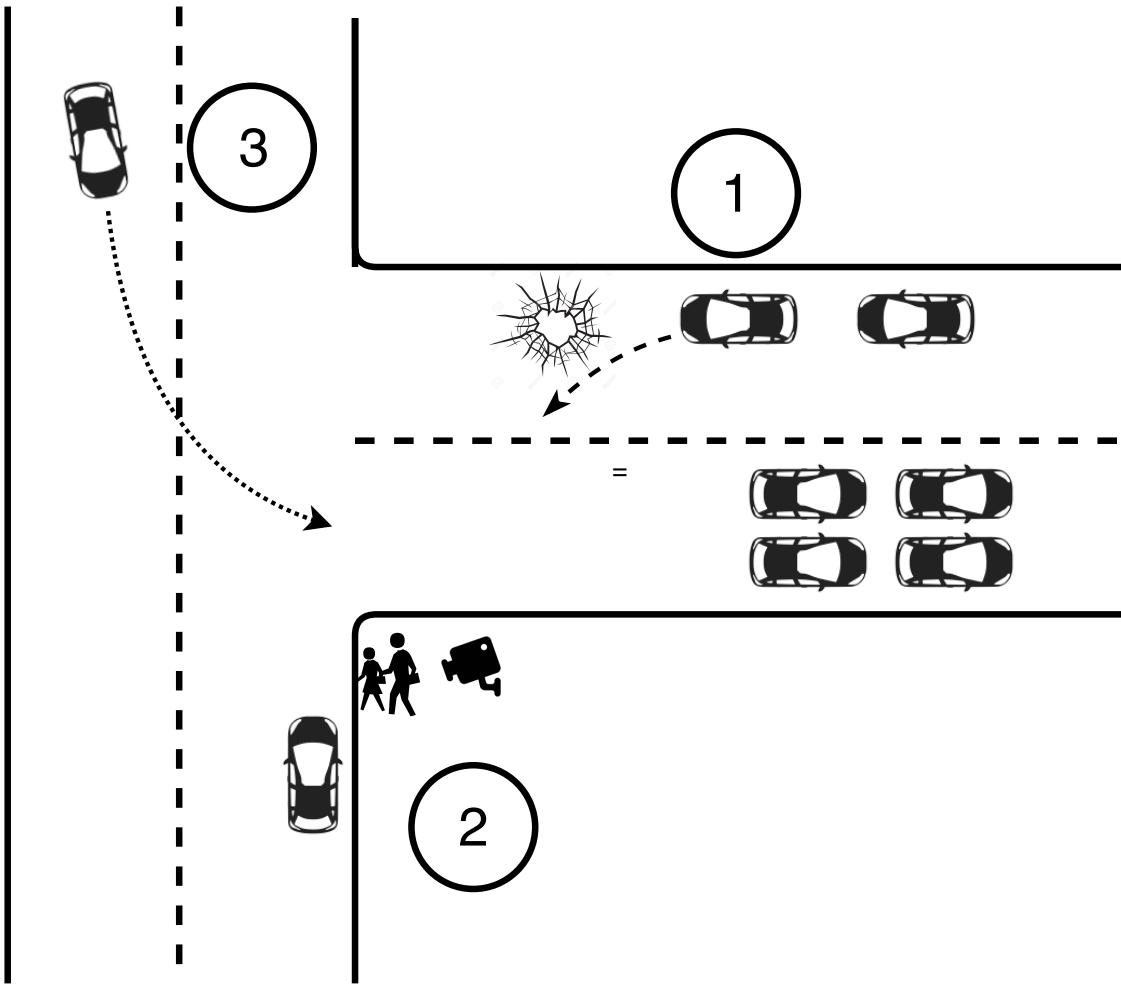
Hazards of self-driving



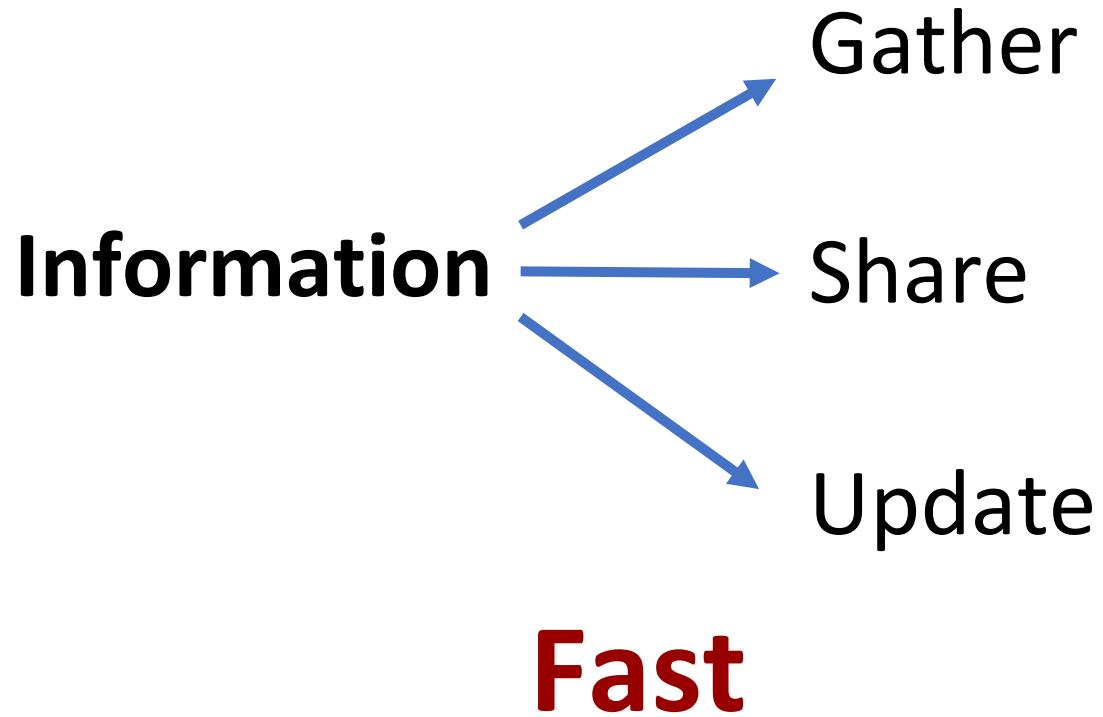
Hazards of self-driving



Hazards of self-driving



Challenges



Challenges

Cloud?

Smart Vehicle?

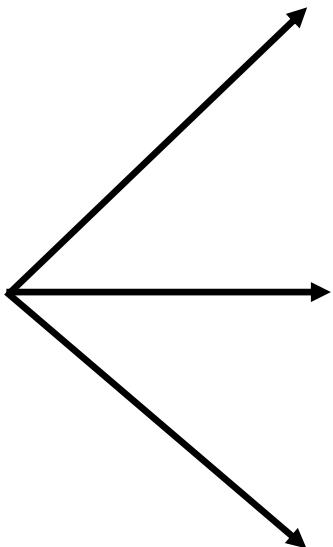
Or

EDGE

Pros and Cons

Solution	Pros	Cons
Edge	<ol style="list-style-type: none">1. Large view2. Small delay	Delicate design
Cloud	Global view	Large delay
Smart Vehicle	Fast computation	Narrow view

Why Edge?



Delay:
as small as possible

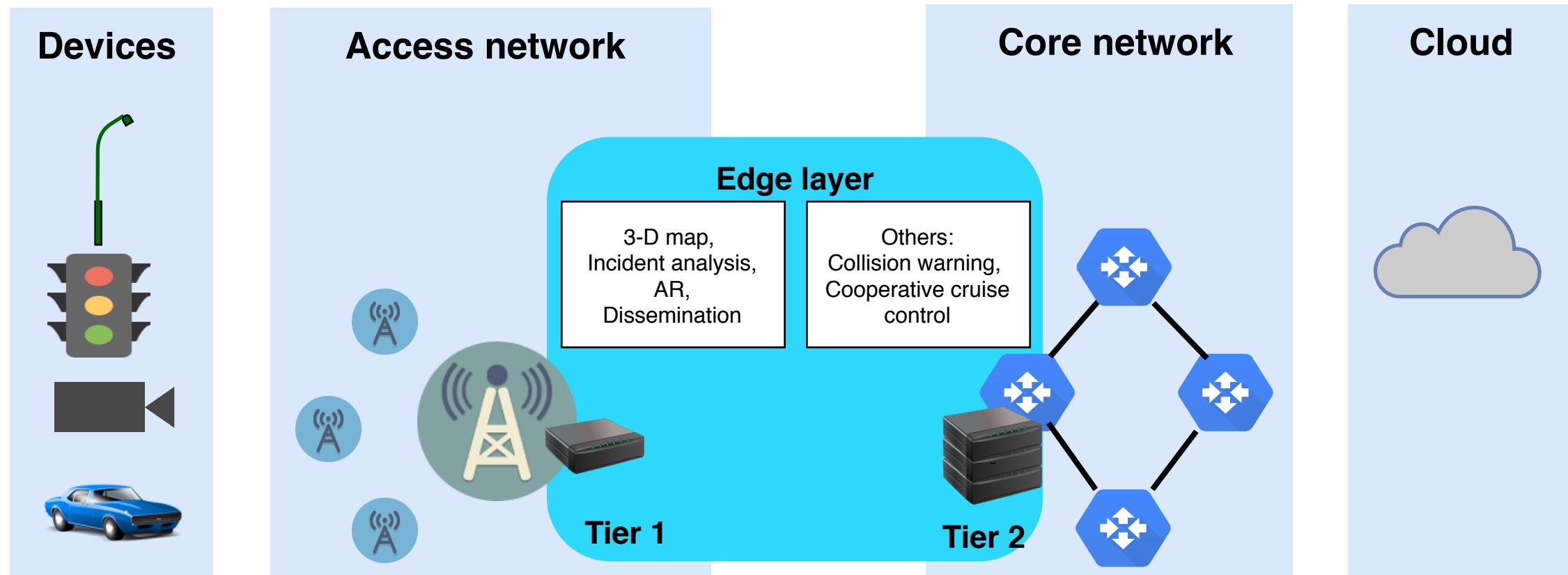
View:
large enough

Processing:
sufficient

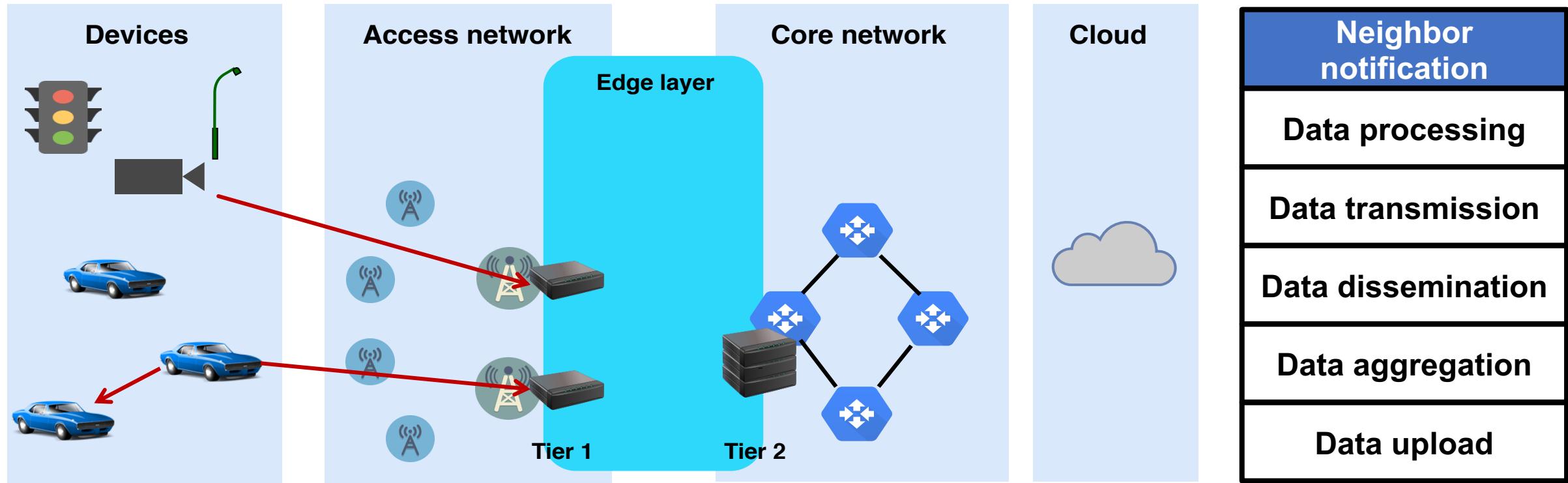
Vehicle to Edge (V2E)

- System Architecture
- Deployment/Placement
- Communication Model

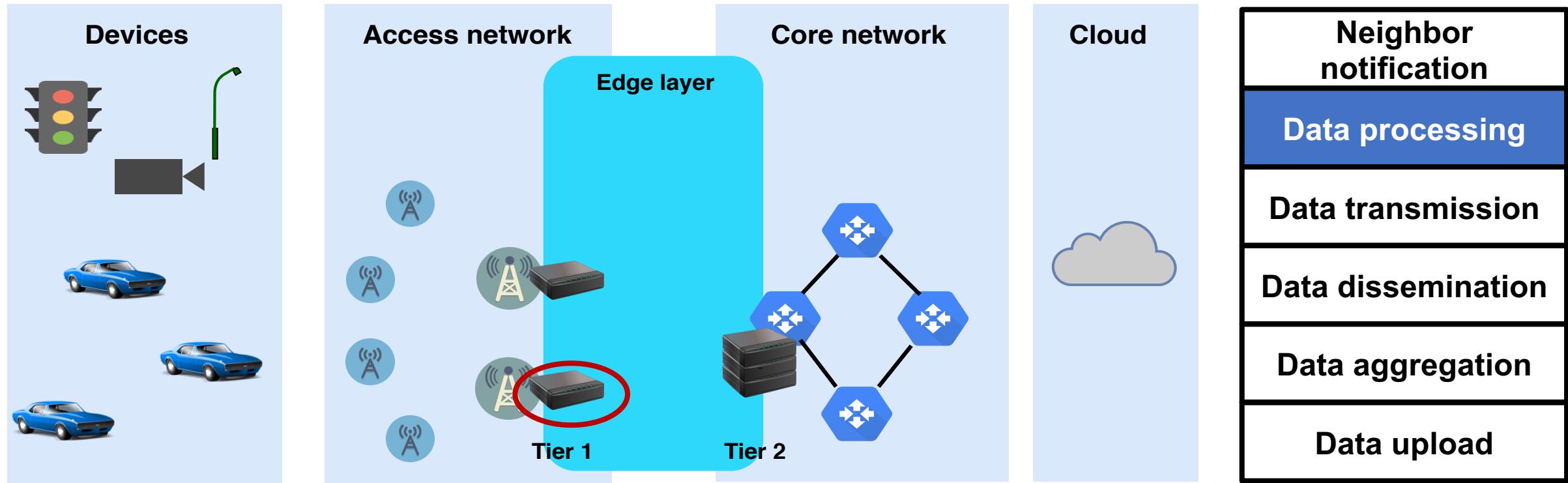
System Architecture



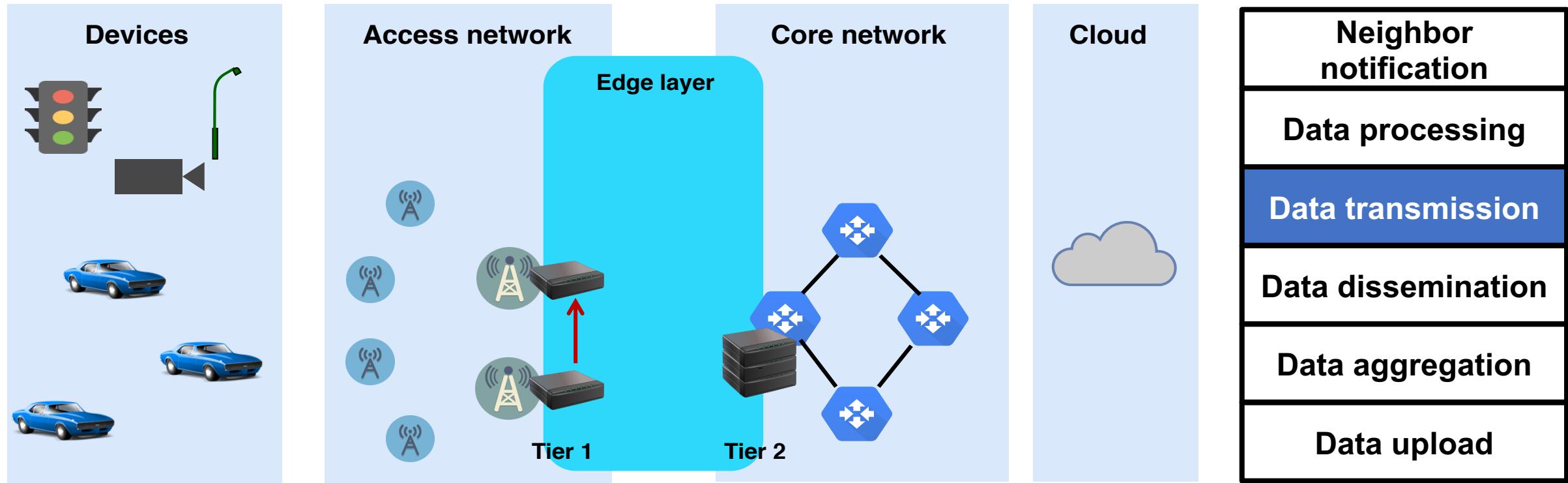
Communication Model



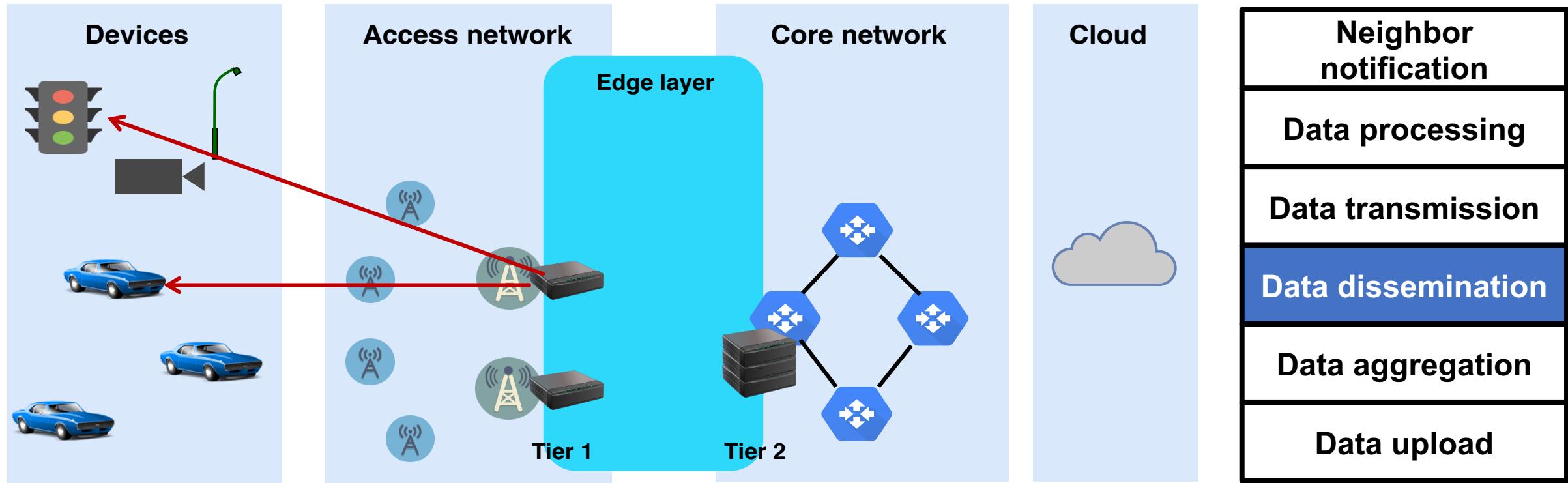
Communication Model



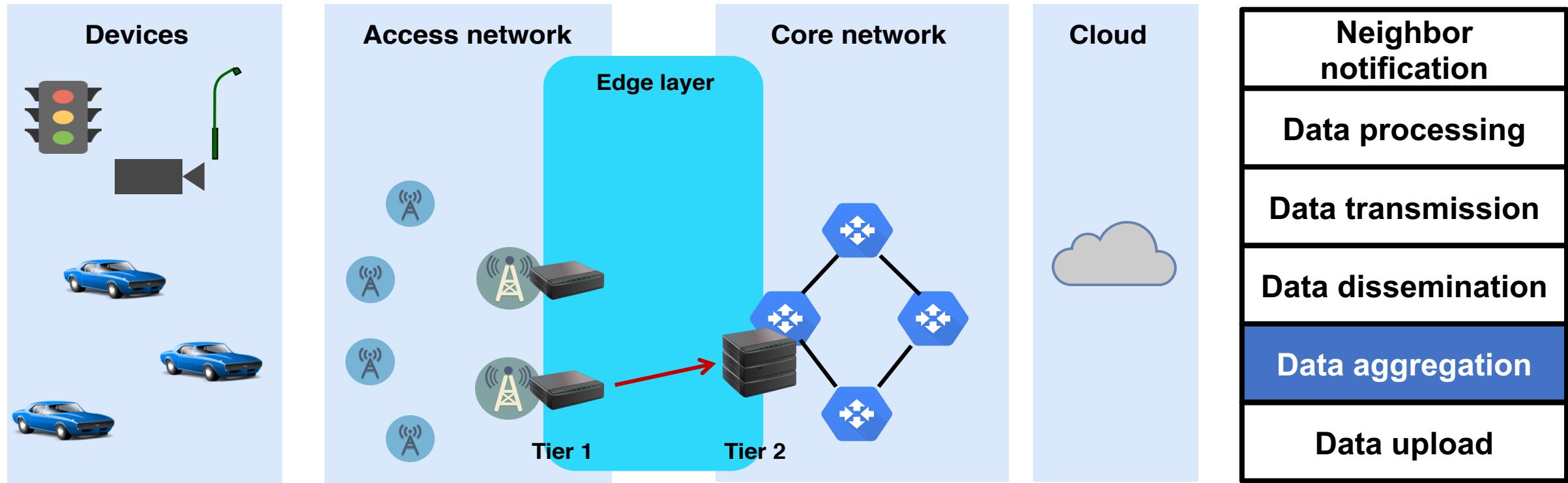
Communication Model



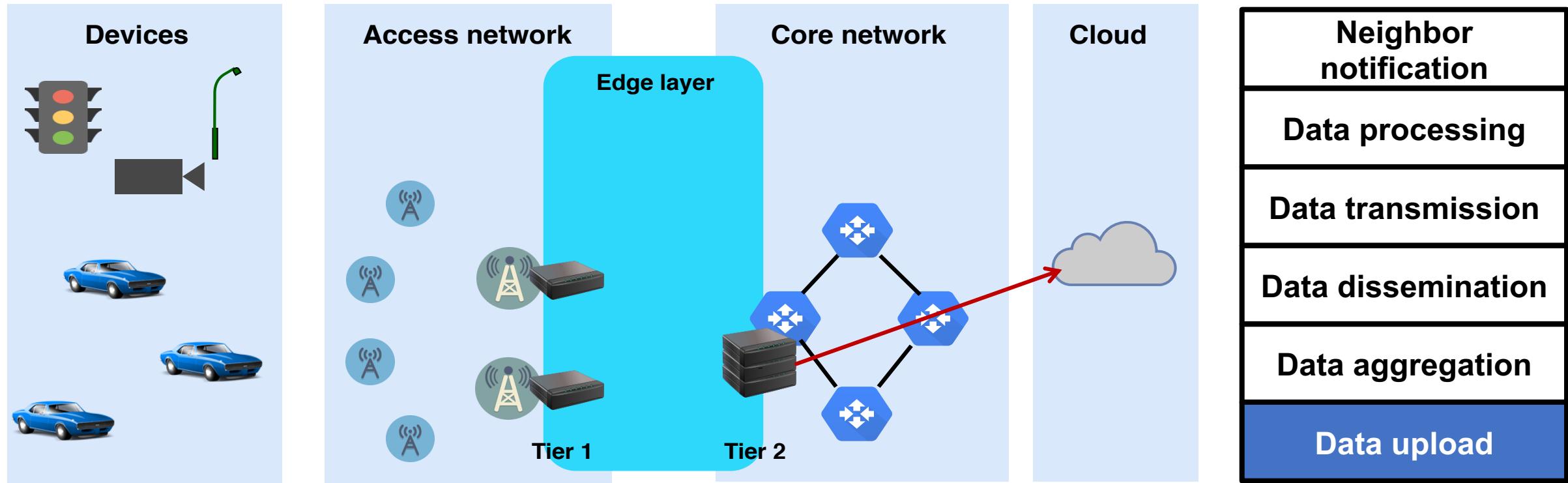
Communication Model



Communication Model



Communication Model



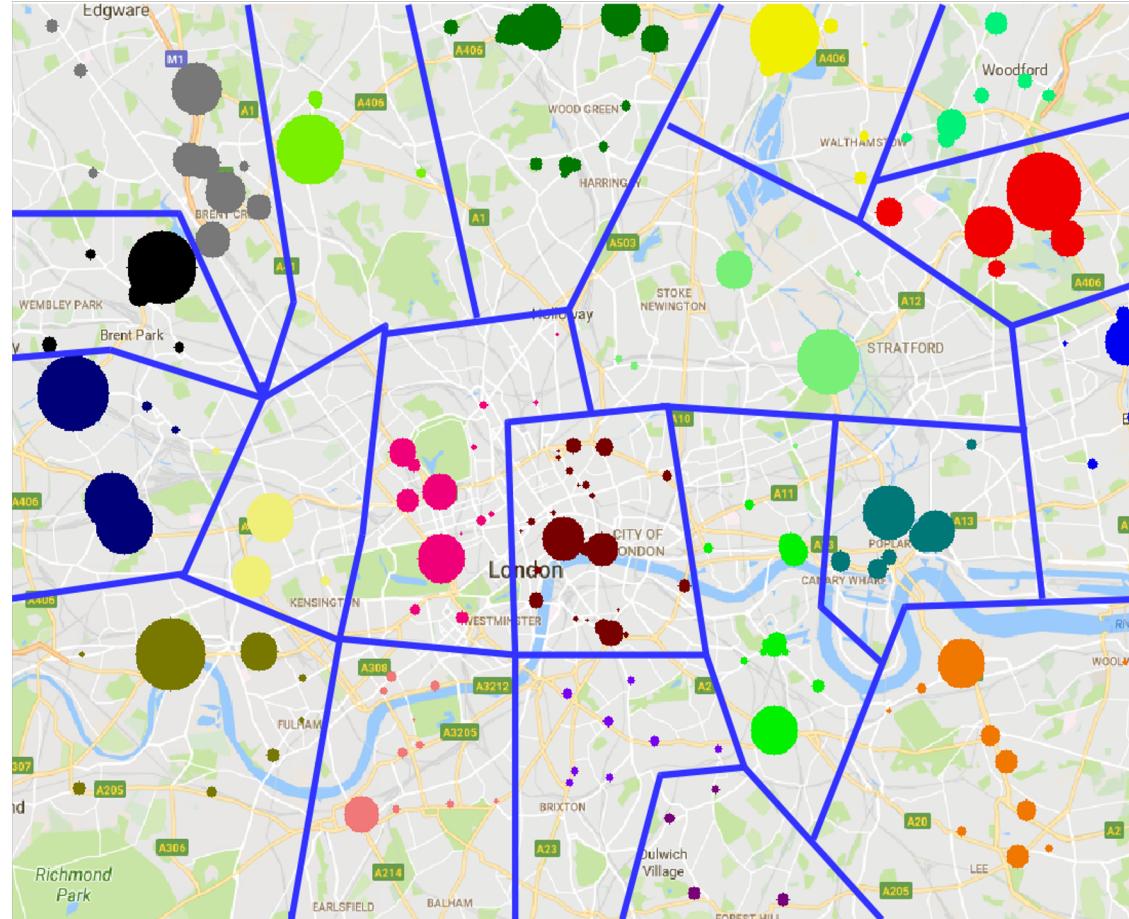
ES Deployment



<https://unwiredlabs.com>

22041 LTE Base Stations in selected area of London,
1538 with radius larger than 3000m

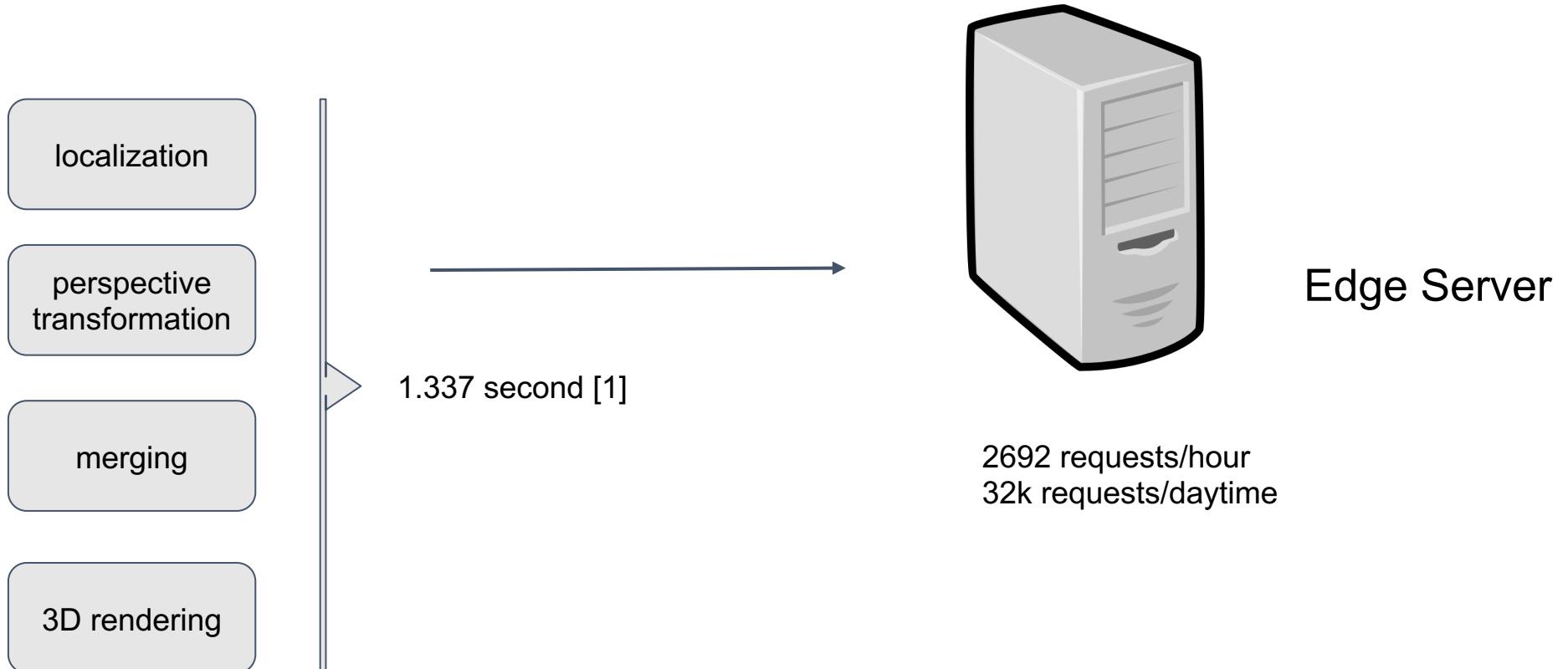
ES Placement



<https://data.gov.uk/dataset/gb-road-traffic-counts>

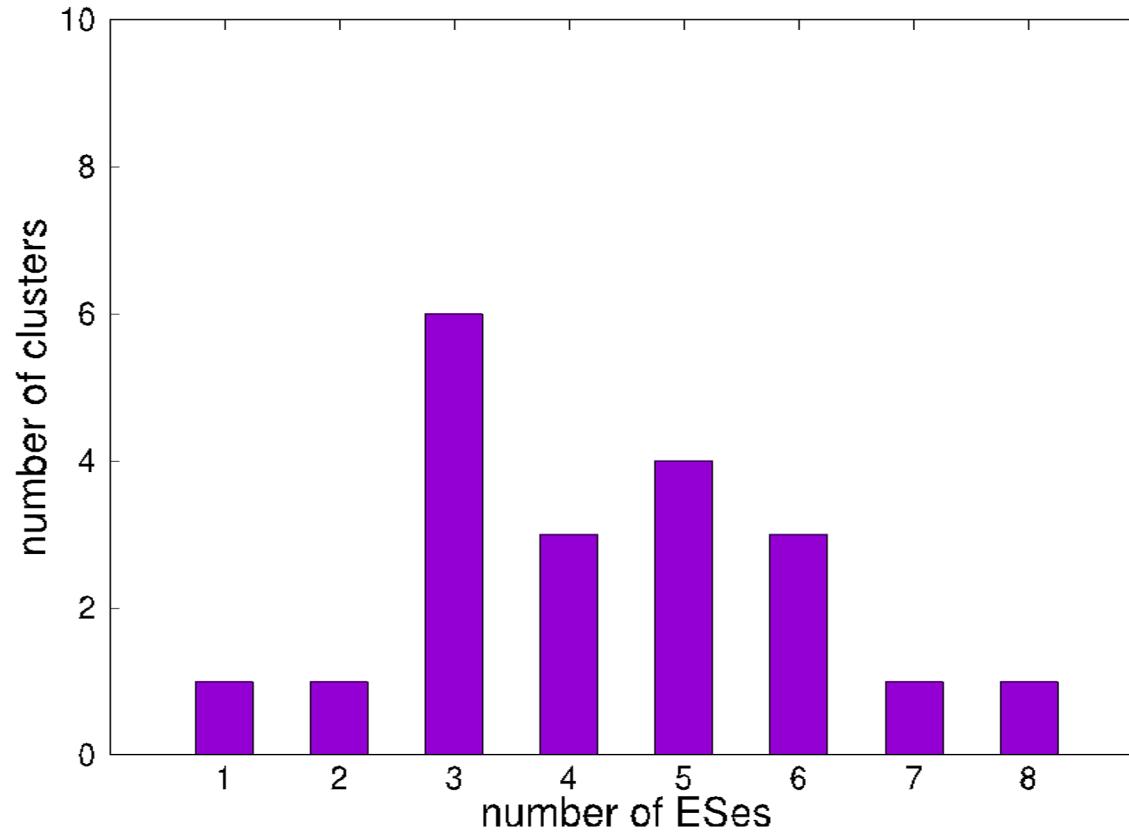
Traffic distribution in selected area of London

ES Placement



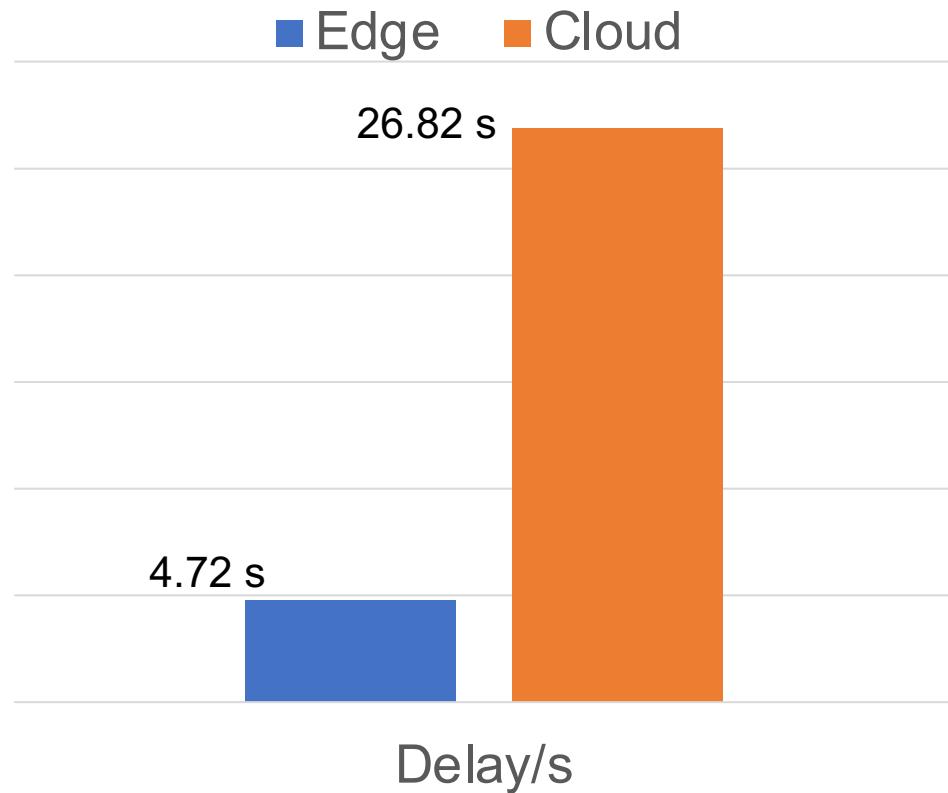
[1] Hang Qiu et al. 2017. Augmented Vehicular Reality: Enabling Extended Vision for Future Vehicles. In Proceedings of the 18th International Workshop on Mobile Computing Systems and Applications. ACM, 67–72.

ES Demand



90 Edge Servers needed in 26x20 km central London

Delay

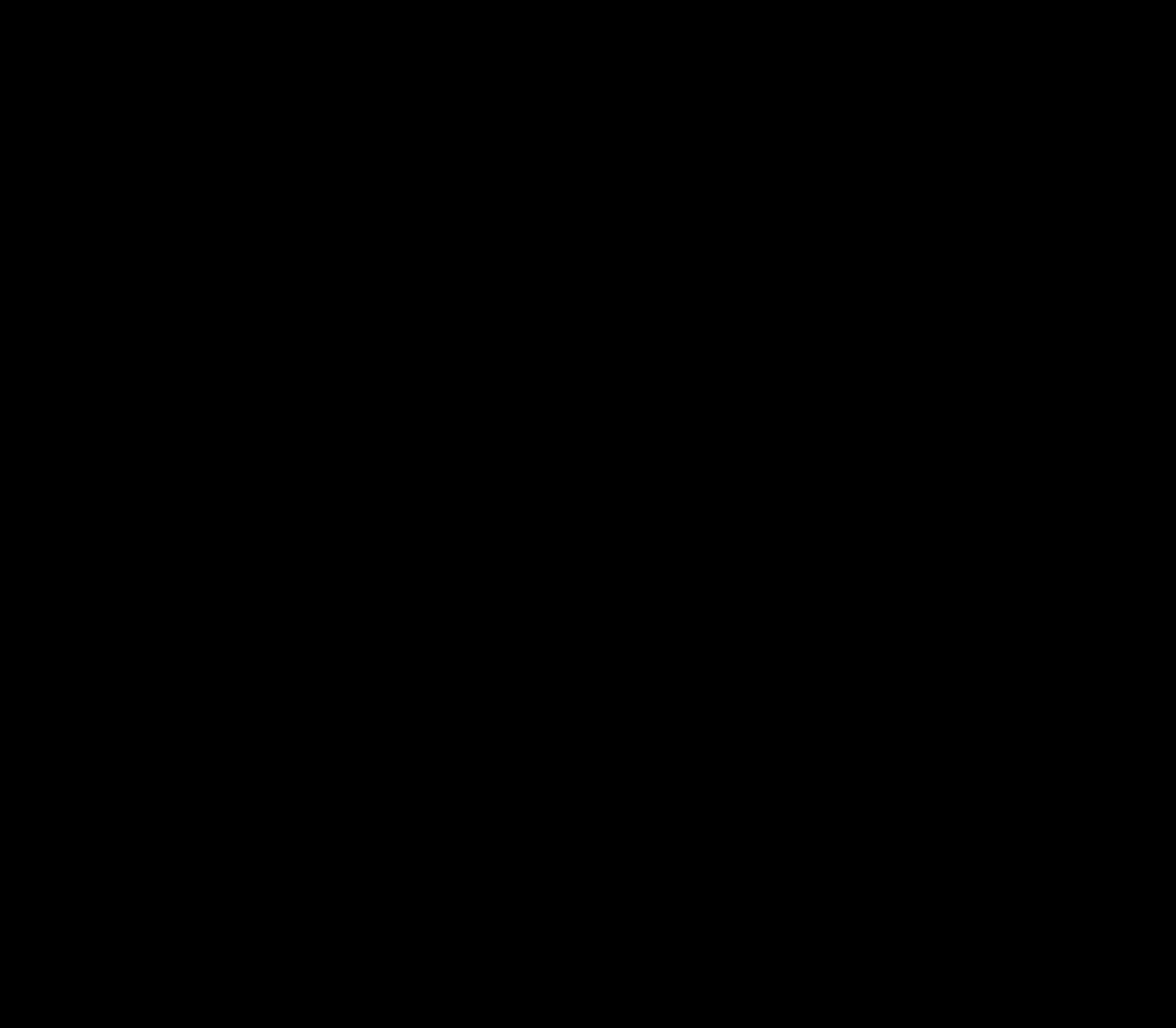


Point cloud data size: 14.75 MB (720p)

- **Edge:** uplink bandwidth between vehicle and LTE base station achieves on average 25 Mbps[1]
- **Cloud:** taking Google Cloud Platform as an example, the average uplink bandwidth is 4.4 Mbps[2]

[1] <https://www.4g.co.uk/how-fast-is-4g/>
[2] https://testmy.net/hoststats/google_cloud

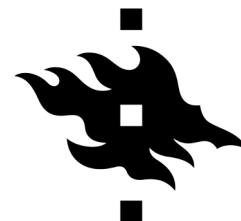
Demo



Thank You!

Q & A

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UNIVERSITY OF HELSINKI



CleanSky - EU FP7 Marie Curie Initial Training Network