## B) Prelab Questions

N/A. There are no prelab questions in this lab.

## C) Problems Encountered

The first problem I encountered was that I didn't realize how to create a 10ms delay subroutine that does nothing other than delay 10ms. Finally, I realized that the simplest thing I could do to delay a program is to load a register with a certain value. I will then decrement that value to take up processor running time.

The second problem I encountered was that I didn't know how to mask away the other bits on the tactile switch port. I had to look closely at Schwartz's hint in the lab document before deciding to use the T-flag like I did in Lab 1.

## D) Future Application

By completing this lab, I have gained the skills to control the GPIO pins on a microcontroller board. In the future, I could use the skills I have gained in this lab to connect and communicate with other hardware extensions. For example, I could possibly use GPIO pins to communicate with a speaker or robot the next time around.

This lab also allowed me to learn the use of delay functions. This is a concept that I could possibly use in high-frequency circuits later in my career.

# E) Schematics

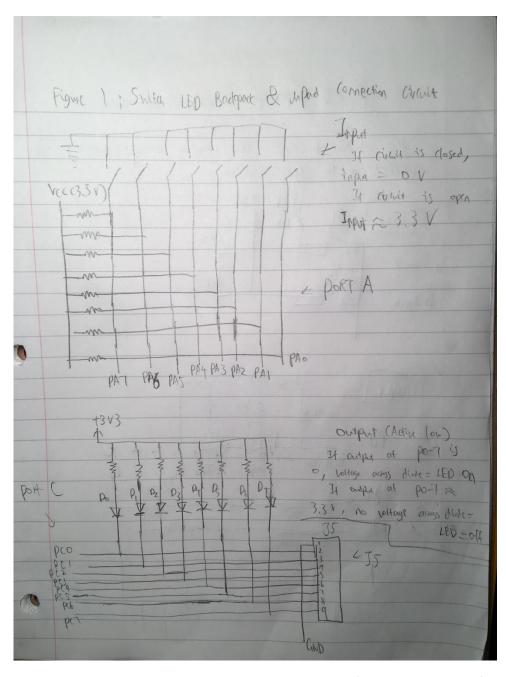


Figure 1: Switch LED Backpack & uPad Connection Circuit (Used in Part A,B,C,D)

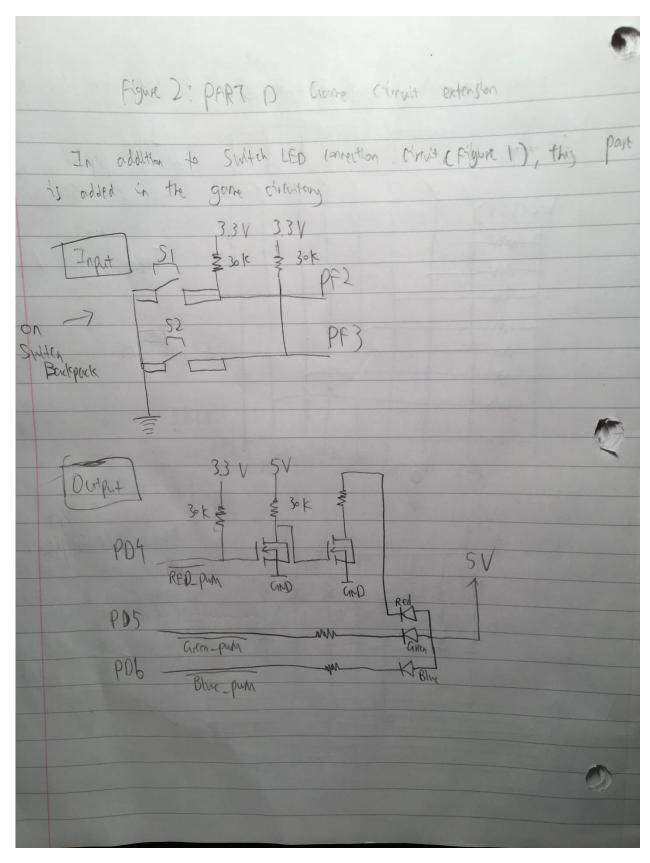


Figure 2: Part D Game Circuitry Extension

## F) Pseudocode/Flowcharts

### Part B Pseudocode:

Initialize PORTA switches to be input

Initialize PORTC LED to be output

LOOP:

Load value at PORTA\_IN to Register 16

Transfer data at Register 16 to PORTC\_OUT

Jump back to LOOP for infinite loop

### Part C Pseudocode

Initialize stack pointer address at 0x3FFF

Load stack pointer address at Y register

Output Y register value to Stack Pointer register

Initialize the last LED at PORTC as output

LOOP ;to do the 10ms delay or multiples of 10ms delay

OUTTGL last LED at PORT C

Call Delay\_10ms or Delay\_100ms subroutine

Back to LOOP (Delay\_10ms or Delay\_100ms)

;the main code basically stop here.

; the rest are just subroutine

Delay\_100ms ;this subroutine multiplies delay\_10ms by 10

Push r16

Load register 16 with 10

Call delay10ms subroutine

```
Decrement r16
Check if r16=0
If not, back to Delay_100ms
Else {
pop r16
ret
         ;return to main routine
}
Delay_10ms ;delay 10 subroutine
push r16
;code start
    1. use two for loops to take up running time.
    2. Basically just load one register with a value
    3. Decrement that register a Set the values to put in the register so it is exactly 10ms delay
    4. and keep running to take up running time
;code ends
pop r16
```

### Part D Pseudocode

Initialize Stack Pointer

ret ;return to main routine

Load Stack Pointer address into Y register

Output Y register value to Stack Pointer register

Load a set of 8 data values that will determine which LED to output in program memory

Initialize PORTC LED as output

Initialize S2 and S1 as input

Initialize Green and Red LED(Port D) as output

```
MAIN
while (S2 is not pressed) { ;while loop to continue game is green or red is not on
        Shift LED towards middle and then outward with delay of 100 ms. Check after every delay to see
if S2 is pressed. One LED goes 0,1,2,3,4,5,6,7,1,2.etc..... Another one goes 7,6,5,4,3,2,1,0,1,2,3,4,5.etc
}
; after the while loop ends ( if somebody have pressed S2), then:.....
if ( (S2 = true) AND (LED 3,4 not on)) {
                Turn on Red LED
                rjmp to RESET
}
else If ((S2=true) AND (LED 3,4 on))
                Turn on Green LED
                rjmp RESET
}
RESET
Read input from S1 to reset game
Back to RESET if red and green LED is still on.
                                                 ;to make sure user reset game.
If S1 is press. Next line of code
```

Back to MAIN

## G) Program Code

### Part B Code

```
/* Lab 1 Part B
  Name: Pengzhao Zhu
  Section#: 112D
  TA Name: Chris Crary
  Description: This Program turns the 8 LED on/off by reading the data at the switch
.include "ATxmega128A1Udef.inc"
                                    ;include the file
.list
                                    ;list it
.org 0x0000
                                    ;start our program here
rjmp MAIN
                                    ; jump to main
                                     ;data segment. not really needed
.dseg
.equ set1=0xFF
                             ;set all for output.used later
                              ;code segment
.cseg
.org 0x200
               ;where we will start the program
MAIN:
sts PORTA_DIRCLR, r16  ;set Port A to be input
                ;load outputs (0xFF) to r17
ldi r17, set1
sts PORTC_DIRSET, r17  ;set Port C to be output
sts PORTC_OUTSET, r16
                       ;turn off all LED (active low LED)
LOOP:
lds r16, PORTA_IN
                      ;load value at input to r16. switch=On, closed circuit. Port A
grounded.
sts PORTC_OUT, r16
                      ;input to output. 0 to output. active low output. LED on
rjmp LOOP
                        ;infinite loop
```

### Part C Code (Delay 10ms)

```
/* Lab 1 Part C
   Name: Pengzhao Zhu
   Section#: 112D
   TA Name: Chris Crary
   Description: This program toggles a LED with a 10ms delay between toggles.
*/
.include "ATxmega128A1Udef.inc"   ;include the file
.list   ;list it
```

```
.org 0x00
                                     ;start the program here
rjmp MAIN
                                     ; jump to main
.equ stack_init=0x3FFF ;initialize stack pointer
MAIN:
ldi YL, low(stack init)
                          ;Load 0xFF to YL
out CPU SPL, YL
                                     ;transfer to CPU_SPL
ldi YL, high(stack_init)
                          ;Load 0x3F to YH
out CPU_SPH, YL
                                     ;transfer to CPU_SPH
ldi r16, 0x80 ;set last LED as output
sts PORTC DIRSET, r16   ;set last LED as output using DIRSET
LOOP:
ldi r17, 0x80
                         ;load r17 with 0x80
sts PORTC OUTTGL, r17
                        ;toggle last LED of PORTC
rcall Delay_10ms
                        ;call delay 10ms subroutine
rjmp LOOP
                        ;infinite loop
Delay_10ms:
               ;delay 10ms subroutine
push r16
                ;push r16
push r17
                ;push r17
ldi r17, 15
                 ;do this loop 15 times. Just need a large number to make sure the delay
is long enough
START:
ldi r16, 0xFF
                ;some value to take up running time
HI:
cpi r16,0
                 ;compare to 0
breq SECOND
                 ;go to second loop if loop one is done
dec r16
                ;dec 16
                ;jump to HI if first loop is not done
rjmp HI
SECOND:
cpi r17, 0
                 ;compare r17 too 0
breq rdone
                 ;if r17=0, we are finished with the subroutine and ready to return to
main code
dec r17
                ;dec r17
rjmp START
                ;start loop one
rdone:
pop r17
                 ;pop r17. restore it
                 ;pop r16. restore it
pop r16
                 ; return to main routine
ret
```

### Part C Code( Delay 100ms, X=10)

```
/* Lab 1 Part C
  Name: Pengzhao Zhu
  Section#: 112D
  TA Name: Chris Crary
  Description: This program toggles a LED with a 100ms delay between toggles.
*/
```

```
.include "ATxmega128A1Udef.inc"
                                    ;include the file
.list
                                    ;list it
.org 0x00
                                    ;start the program here
rjmp MAIN
                                    ; jump to MAIN
.equ stack init=0x3FFF
                        ;initialize stack pointer
MAIN:
ldi YL, low(stack_init)
                          ;Load 0xFF to YL
out CPU SPL, YL
                                     ;transfer to CPU SPL
ldi YL, high(stack init)
                          ;Load 0x3F to YH
out CPU SPH, YL
                                     ;transfer to CPU_SPH
ldi r16, 0x80 ;set last LED as output
sts PORTC_DIRSET, r16   ;set last LED as output using DIRSET
ldi r21, 10 ;initialize how many times i want to mulitply delay 10ms for
LOOP:
ldi r17, 0x80
                         ;load r17 with 0x80
sts PORTC_OUTTGL, r17
                        ;toggle last LED of PORTC
rcall Delay mult
                       ;call delay 100ms subroutine
rjmp LOOP
                        ;infinite loop
Delay_mult:
              ;push r20
push r20
                ; load 9 in r20. it runs it 10 times and the delay will be 10ms.
mov r20, r21
REPEAT:
                 ;call delay_10ms
rcall Delay_10ms
dec r20
                   ;decrement r20. keep the code running
cpi r20, 0
                   ;load 0 to r20
breq DONE
                   ;when it is done, prepare to get back into main routine
rjmp REPEAT
                   ;going back to the place to call delay_10ms again
DONE:
pop r20
                   ;pop r20
                   ;return to main routine
ret
Delay 10ms:
                 ;delay 10ms subroutine
push r16
                 ;push r16
push r17
                 ;push r17
ldi r17, 15
                 ;do this loop 15 times. Just need a large number to make sure the delay
is long enough
START:
ldi r16, 0xFF
                ;some value to take up running time
HI:
cpi r16,0
                 ;compare to 0
breq SECOND
                 ;go to second loop if loop one is done
dec r16
                 ;dec 16
rjmp HI
                 ;jump to HI if first loop is not done
```

```
SECOND:
cpi r17, 0
                 ;compare r17 too 0
breq rdone
                 ;if r17=0, we are finished with the subroutine and ready to return to
main code
dec r17
                 ;dec r17
rjmp START
                 ;start loop one
rdone:
                  ; by the time the code gets back here.
                  ;should be a 10ms delay
pop r17
pop r16
                  ; return to main routine
ret
```

\_\_\_\_\_

#### Part D Code

```
/* Lab 1 Part D
  Name: Pengzhao Zhu
  Section#: 112D
  TA Name: Chris Crary
  Description: This program is game that will turn on the green LED if user wins, or
turn on the red LED if user loses.
                           LEDs will move inward and outward before game the concludes
(win or lose). There is also an option to reset
                           the game after the game concludes
*/
.include "ATxmega128A1Udef.inc"
                                      ;include the file
.list
                                      ;list it
.org 0x00
                                      ;start the program here
rjmp MAIN
                                      ; jump to MAIN
.equ stack init=0x3FFF
                       ;initialize stack pointer
.org 0x200
            ;put table here
Table: .db 0b10000001, 0b01000010, 0b00100100, 0b00011000,0b00100100,
0b01000010,0b10000001,0b000000000 ;load table to turn on LED
.org 0x300
             ;code start here
MAIN:
ldi YL, low(stack_init)
                          ;Load 0xFF to YL
                                     ;transfer to CPU_SPL
out CPU_SPL, YL
ldi YL, high(stack_init)
                          ;Load 0x3F to YH
out CPU_SPH, YL
                                     ;transfer to CPU_SPH
ldi r21, 10 ;initialize how many times i want to mulitply delay_10ms for
ldi r17, 0xFF   ;to turn off all active low LED later
ldi r18, 0b00110000 ;to turn off the red and green
ldi r22, 0b00001100
                       ;set S1 and S2 as input
sts PORTF_DIRCLR, r22
                      ;transfer to PORTF_DIRCLR
ldi r22, 0b00110000
                       ;bit 5 is red, bit 6 is green
                      ;set as input
sts PORTD_DIRSET, r22
sts PORTD_OUTSET, r18 ;to turn off the LED for now. set them as HIGH so they will be off
```

```
LEDLOOP:
ldi ZL, low(Table << 1)</pre>
                      ;load low byte of table to ZL
                      ;load high byte of table to ZH
ldi ZH, high(Table << 1)</pre>
ldi r20, 8
                       ;table counter=8
lds r23, PORTF IN
                                ;if PORTF IN is pressed
bst r23, 3
                                ;if pressed. store bit 3 of r23 into T-flag
brtc PRESS
                                ;if pressed. voltage is 0, so that is why it
breaks if cleared
dec r20
                               ;decrement r20
                               ;if r20=0, start the table over
cpi r20, 0
breq LEDLOOP
                               ;start table over
rjmp LEDSWITCH
                               ;load the next value in table
PRESS:
bst r16, 4  ;store bit 4 of r16 into T-flag
brts GREEN   ;if bit 4 is set, then I win the game
brtc RED ;if bit 4 is not set, then I lose the game
GREEN:
ldi r23, 0b00100000
                  ;low true. load onto r23
sts PORTD_OUTCLR, r23 ;turn on GREEN
           jump to where I will reset the game
rjmp RESET
RED:
rjmp RESET
                 ; jump to where I will reset the game
RESET:
;if pressed. reset game
brtc OFF
brts RESET
                      ;if not pressed. infinite loop
OFF:
sts PORTD OUTSET, r18 ;to turn off all active low LED
rjmp LEDLOOP
                 ;jump to LEDLOOP and start everything over
Delay mult:
         ;push r20
push r20
```

```
;load 9 (r21) in r20. it runs it 10 times and the delay will be 100ms.
mov r20, r21
REPEAT:
rcall Delay_10ms
                    ;call delay_10ms
dec r20
                    ;decrement r20. keep the code running
                   ;load 0 to r20
cpi r20, 0
breq DONE
                   ;when it is done, prepare to get back into main routine
rjmp REPEAT
                    ;going back to the place to call delay 10ms again
DONE:
pop r20
                    ;pop r20
ret
                    ;return to main routine
                 ;delay 10ms subroutine
Delay_10ms:
push r16
                 ;push r16
                 ;push r17
push r17
ldi r17, 15
                 ;do this loop 15 times. Just need a large number to make sure the delay
is long enough
START:
ldi r16, 0xFF
                 ;some value to take up running time
HI:
cpi r16,0
                 ;compare to 0
breq SECOND
                 ;go to second loop if loop one is done
dec r16
rjmp HI
                 ;jump to HI if first loop is not done
SECOND:
cpi r17, 0
                 ;compare r17 too 0
                 ;if r17=0, we are finished with the subroutine and ready to return to
breq rdone
main code
                 ;dec r17
dec r17
                 ;start loop one
rjmp START
rdone:
                 ;by the time the code gets back here.
                 ;should be a 10ms delay
pop r17
pop r16
                  ; return to main routine
ret
```

## H) Appendix WaveForms (new workspace) ø Workspace Settings Window Help Scope 1 🛚 Welcome 👺 Help Single Mode: Repeated Stop ▼ Condition: Fising Auto C1 C2 8192 samples at 160 kHz | 2018-02-03 14:34:42.599 O E E S Y Measurements 💠 Add 🗸 🖛 🗸 🔃 Edit 📰 Show 🖵 Name C1 Frequency 37.566657407 Hz Add Channel Period 26.619349951 ms Channel 1 Offset: 0 V Range: 1 V/div Channel 2 Offset: 0 V Range: 500 mV/div

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Figure 3: Delay\_10ms First Attempt

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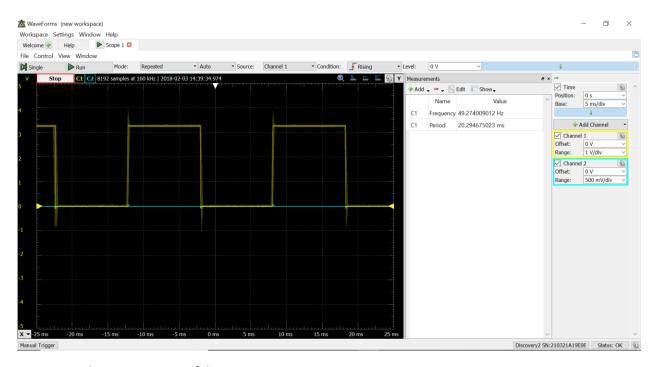


Figure 4: Delay\_10ms Successful Attempt

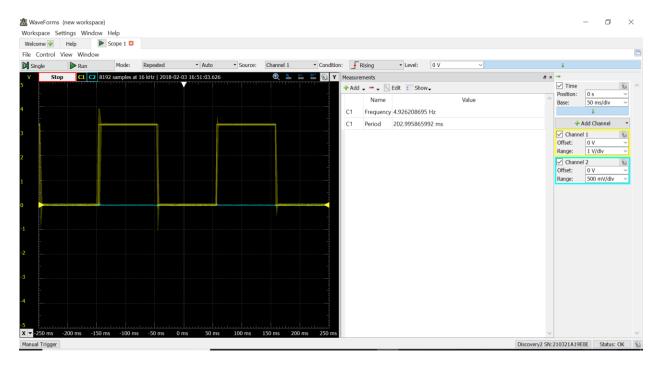


Figure 5: Delay 100ms (X=10 on the Delay10ms Subroutine) Successful Attempt (Part C and D)

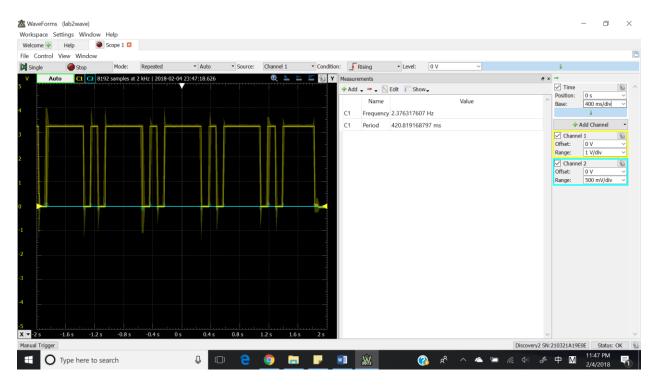


Figure 6: Part D Game Animation Pattern (Waveform of One Pin Only)

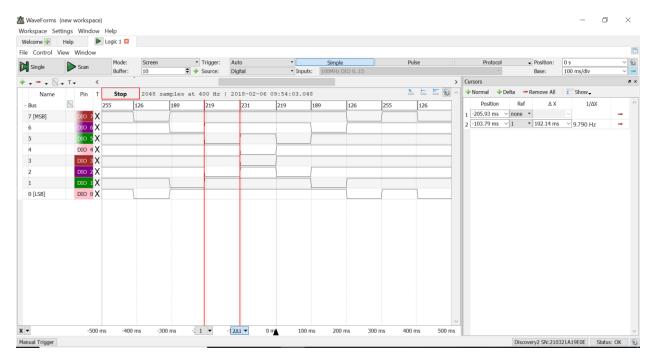


Figure 7: Game D Logic Analyzer Pattern (100ms delay)