

HW 25 10/6

1. 給定 AR(p) 序列, 求(a)以 lag operators 表示 (令 L 為 lag operator, 滿足 $L y_t = y_{t-1}$)

Lag operator 定義: $L y_t = y_{t-1}$, $L^2 y_t = y_{t-2}$, $L^k y_t = y_{t-k}$

→ 把模型改寫成含 L 的形式, 原式

$$(I) y_t = 1.3y_{t-1} - 0.5y_{t-2} + \varepsilon_t$$

$$\Rightarrow y_t = 1.3L y_t - 0.5L^2 y_t + \varepsilon_t$$

$$\Rightarrow y_t - 1.3L y_t + 0.5L^2 y_t = \varepsilon_t, (1 - 1.3L + 0.5L^2) y_t = \varepsilon_t$$

→ $\varphi(L) = 1 - 1.3L + 0.5L^2$, 因此 AR(2) 模型可寫成 $\varphi(L) y_t = \varepsilon_t$

$$(II) y_t = 1.2y_{t-1} - 0.4y_{t-2} + \varepsilon_t$$

$$y_t = 1.2L y_t - 0.4L^2 y_t + \varepsilon_t$$

$$\Rightarrow y_t - 1.2L y_t + 0.4L^2 y_t = \varepsilon_t$$

$$\Rightarrow (1 - 1.2L + 0.4L^2) y_t = \varepsilon_t$$

→ $\varphi(L) = 1 - 1.2L + 0.4L^2$, 因此 AR(2) 模型可寫成 $\varphi(L) y_t = \varepsilon_t$

$$(III) y_t = 1.2y_{t-1} + 1.2y_{t-2} + \varepsilon_t$$

$$(VI) y_t = 0.7y_{t-1} + 0.25y_{t-2} - 0.175y_{t-3} + \varepsilon_t$$

$$y_t (1 - 1.2L - 1.2L^2) = \varepsilon_t$$

$$y_t (1 - 0.7L - 0.25L^2 + 0.175L^3) = \varepsilon_t$$

$$(IV) y_t = -1.2y_{t-1} + \varepsilon_t$$

$$y_t (1 + 1.2L) = \varepsilon_t$$

(b) 判斷是否為平穩序列 Stationary

→ AR(p)過程平穩 \Leftrightarrow 其特徵方程的根 (in terms of L) 皆滿足 $|z| > 1$.

$$(I) 1 - 1.2L + 0.2L^2 = 0, 1 - 1.2z + 0.2z^2 = 0, z = 1, 0.2 \leftarrow 1, \rightarrow \text{不平穩}$$

$$(II) 1 - 1.2L + 0.4L^2 = 0, z = 0.6 \pm 0.2i, |z| < 0.63 < 1 \rightarrow \text{不平穩}$$

(III) $|-1.2L - 1.2L^2 = 0$, $L = 1.8, -0.6 \rightarrow \text{不平穩}$

(IV) $|+1.2L = 0$, $L = -\frac{1}{1.2} = -0.833$, $|L| < 1 \rightarrow \text{不平穩}$

(V) $|-0.7L - 0.15L^2 + 0.175L^3 = 0$, $L = 1.15, 1.2, -2$, 全部 $|L| > 1 \rightarrow \text{平穩}$

4. $y_t = y_{t-1} + \varepsilon_t$, $\varepsilon_t \sim \text{N}(0, \sigma^2)$ pf y_t 為非定態

平穩序列 (弱良態) 條件: 1. $E(y_t)$ 為常數

2. $\text{Var}(y_t)$ 為常數

3. $\text{Cov}(y_t, y_{t+k})$ 只與 k 有关

$y_t = y_{t-1} + \varepsilon_t$, 代入 $y_{t-1} = y_{t-2} + \varepsilon_{t-1}$ 得 $y_t = y_{t-2} + \varepsilon_{t-1} + \varepsilon_t$

繼續展開, $y_t = y_0 + \sum_i \varepsilon_i$

$E(y_t) = E(y_0) + \sum_i E(\varepsilon_i) = E(y_0) \rightarrow \text{期望值為常數}$

$\text{Var}(y_t) = \text{Var}(\sum_i \varepsilon_i) = \sum_i \text{Var}(\varepsilon_i) = t\sigma^2 \rightarrow$ 隨 $t \uparrow$, $\text{Var} \uparrow$ (線性)

$\text{Cov}(y_t, y_s) = E[(y_t - E(y_t))(y_s - E(y_s))]$

$\because E(y_t) = E(y_s) = E(y_0) \Rightarrow \text{Cov}(y_t, y_s) = E[(y_t - y_0)(y_s - y_0)]$

代入展開式 $y_t - y_0 = \sum_i \varepsilon_i$, $y_s - y_0 = \sum_j \varepsilon_j$

$\therefore \text{Cov}(y_t, y_s) = E\left[\left(\sum_i \varepsilon_i\right)\left(\sum_j \varepsilon_j\right)\right] \because \varepsilon_i \perp \varepsilon_j \text{ iid}, E(\varepsilon_i \varepsilon_j) = \begin{cases} \sigma^2, & i=j \\ 0, & i \neq j \end{cases}$

$\therefore \text{Cov}(y_t, y_s) = \sum_i \sum_j \text{Cov}(\varepsilon_i, \varepsilon_j) = \sum_{i=1}^{\min(t,s)} \sigma^2$

若 $t > s$, $\text{Cov}(y_t, y_s) = s\sigma^2 = \text{Var}(y_s)$

平穩序列應滿足 $\text{Cov}(y_t, y_s) = \delta(t-s)$, 即 t 和 時間差 $t-s$ 有关

but 這裡卻是和 s 有关, 這代表往後 observe 更久 (s 更大), $\text{Cov} \uparrow$,

data 波動幅度 \uparrow , \therefore 此過程為 Non-stationary

5. 給定 y_t 為良態 AR(2) 序列 $y_t = c + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \varepsilon_t$,

其中 $\varepsilon \sim (0, \sigma^2)$, 設 (a) $E(y_t)$ (b) $\text{Var}(y_t)$ (c) $\delta(j)$ (d) $\rho(j)$

(a) $E(y_t)$ 令 $E(y_t) = M$, $M = c + \phi_1 M + \phi_2 M \Rightarrow M(1 - \phi_1 - \phi_2) = c$

$$\Rightarrow E(y_t) = M = \frac{c}{1 - \phi_1 - \phi_2}$$

(b) $\text{Var}(y_t)$ 令 $y_t - M = X_t$, 則 $X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + \varepsilon_t$

利用 Yule-Walker 方程 $\begin{aligned} r(0) &= \phi_1 r(1) + \phi_2 r(2) + \sigma^2 - \textcircled{1} \\ r(1) &= \phi_1 r(0) + \phi_2 r(1) - \textcircled{2} \end{aligned}$

$$\textcircled{1} \quad r(1)(1 - \phi_2) = \phi_1 r(0) \Rightarrow r(1) = \frac{\phi_1}{1 - \phi_2} r(0) \text{ 代入 } \textcircled{1} , r(0) = \phi_1 \frac{\phi_1}{1 - \phi_2} r(0) + \phi_2 r(1) + \sigma^2$$

$$r(2) = \phi_1 r(1) + \phi_2 r(0) \Rightarrow r(0) \left[1 - \frac{\phi_1^2(1 + \phi_2)}{1 - \phi_2} - \phi_2^2 \right] = \sigma^2$$

$$\text{Var}(y_t) = r(0) = \frac{(1 - \phi_2) \sigma^2}{(1 + \phi_2)((1 - \phi_2)^2 - \phi_1^2)}$$

(c) $\delta(j)$ $\delta(j) = \phi_1 \delta(j-1) + \phi_2 \delta(j-2)$, $j \geq 2$

$$\delta(0) , \delta(1) = \frac{\phi_1}{1 - \phi_2} r(0)$$

(d) $\rho(j)$ $\rho(j) = \frac{\delta(j)}{\delta(0)}$, $\rho(j) = \phi_1 \rho(j-1) + \phi_2 \rho(j-2)$, $\rho(0) = 1$

b. $y_t = 1.3 y_{t-1} - 0.5 y_{t-2} + \varepsilon_t$, $\varepsilon_t \sim (0, \sigma^2)$

(a) 以 lag operator 表示式

$$y_t = 1.3 L y_t - 0.5 L^2 y_t + \varepsilon_t \Rightarrow (1 - 1.3L + 0.5L^2) y_t = \varepsilon_t$$

$$\bar{\Phi}(L) y_t = \varepsilon_t , \bar{\Phi}(L) = 1 - 1.3L + 0.5L^2$$

(b) 判斷是否為平穩過程

$$|-1.3 \pm 0.5 \pm^2 = 0, \quad 2 = 0.65 \pm 0.278; \quad |2| = \sqrt{0.65^2 + 0.278^2} = 0.709 < 1$$

\Rightarrow AR(2) model 不平穩

(c) $E(y_t)$

$$\because \text{沒有常數項}, \quad \therefore E(y_t) = 1.3 E(y_{t-1}) - 0.5 E(y_{t-2})$$

$$\therefore E(y_t) = M, \quad M = 1.3M - 0.5M, \quad (1 - 1.3 + 0.5)M = 0 \quad \therefore M = 0, \quad E(y_t) = 0$$

(d) $r(j)$

$$\left\{ \begin{array}{l} r(0) = 1.3 r(1) - 0.5 r(2) + \epsilon^2 \\ r(1) = 1.3 r(0) - 0.5 r(1) \end{array} \right.$$

$$\rightarrow r(1) (1 + 0.5) = 1.3 r(0) \rightarrow r(1) = 0.867 r(0)$$

$$\Rightarrow r(j) = 1.3 r(j-1) - 0.5 r(j-2), \quad j \geq 2$$

(e) Yule-Walker

$$\left\{ \begin{array}{l} r(0) = 1.3 r(1) - 0.5 r(2) + \epsilon^2 \\ r(1) = 1.3 r(0) - 0.5 r(1) \\ r(2) = 1.3 r(1) - 0.5 r(0) \end{array} \right.$$

(f) $\text{Var}(y_t) = \sigma^2$

$$r(1) = \frac{13}{15} r(0)$$

$$r(2) = 1.3 r(1) - 0.5 r(0) = 1.3 (0.867 r(0)) - 0.5 r(0) = 0.6267 r(0)$$

$$r(0) = 1.3(0.867 r(0)) - 0.5(0.6267 r(0)) + 6^2$$

$$r(0) [1 - (1.1271 - 0.31335)] = 6^2$$

$$r(0) = \frac{6^2}{1.1271 - 0.31335} = 5.376^2 \quad , \quad \text{Var}(y_0) = 5.376^2$$