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1. 19.1-3 Binary Representation of Binomial Heaps

There are  $\binom{n}{k}$  binary  $k$ -strings containing exactly  $j$  1's. And since there are also  $\binom{n}{k}$  nodes per level of a binomial tree, there must be  $k$  ones per node per level of a tree when counting the lowest node as 0.

Since binomial trees have defined sizes, ie they either have 1,4,8,16 ... nodes,  $2^0, 2^1, 2^2, 2^3 \dots$ , a node of degree  $k$  will have subtrees of size  $2^0 + 2^1 + 2^2 + \dots + 2^{k-1} = 2^k - 1$ , therefore it will have  $k$  1's in it's binary representation.

2. 19.2-5 Binomial-Heap-Minimum

Binomial-Heap-Minimum may not work as coded. If all of the nodes in the heap have value  $\infty$ , then Binomial-Heap-Minimum will return NULL, even though there are elements in the Heap.

It can be altered to account for this by,

```
y ← head[H] // This sets a default return value
x ← head[H]
min ← ∞
while x ≠ NIL
  do if key[x] < min
    do if key[x] < min
      then min ← key[x]
          y ← x
      x ← sibling[x]
return y
```

This way if there is an element  $< \infty$  we will select it, otherwise we'll return the first value.

3. 19.2-6 Binomial-Heap-Delete

We can alter Binomial-Heap-Delete to work in the case where there is no representation for  $-\infty$ .

Binomial-Heap-Delete(H,x)

```

y = Binomial-Heap-Extract-Min(H)
Binomial-Heap-Decrease-Key(H,x, y-1)
Binomial-Heap-Extract-Min(H)
Binomial-Insert(y)

```

In this manner the key  $x$  always has the lowest value. It simply requires two deletes and an insert, all of which can be done in  $\mathbf{O}(\lg n)$

4. Minimum spanning tree with binomial heaps

A binomial heap can be used to manage both the edge and vertex list. For the edge list the operations are straightforward. Extracting the minimum-weight edge is simply Binomial-Heap-Extract-Min, and  $E_i \leftarrow E_i \cup E_j$  is the Union operation.

Vertex operations are slightly more complicated. Once we extract an edge from the edge list we need to determine which heaps the endpoints belong in. This requires a new operation to search the heap looking for elements. For example, once we extract the minimum-weight edge  $(u, v)$  from  $E_i$ , we have to determine which  $V_i$  and  $V_j$ ,  $u$  and  $v$  belong in. After this we can reuse the union operation to merge  $V_i$  and  $V_j$  if necessary.

The runtime of this algorithm should be  $E \lg(E)$ , since we require approx.  $E$  Extract-Min operations which happen in  $E$  time.