

Software Development Environment

**Zynq
Vivado 2018.3 Version**

Objectives

➤ After completing this module, you will be able to:

- Understand the basic concepts of the Eclipse IDE in SDK
- List SDK features
- Identify the GNU tools functionality
- List steps in creating a software application
- State when address management is needed
- Describe the object file sections
- Describe what a linker script does

Outline

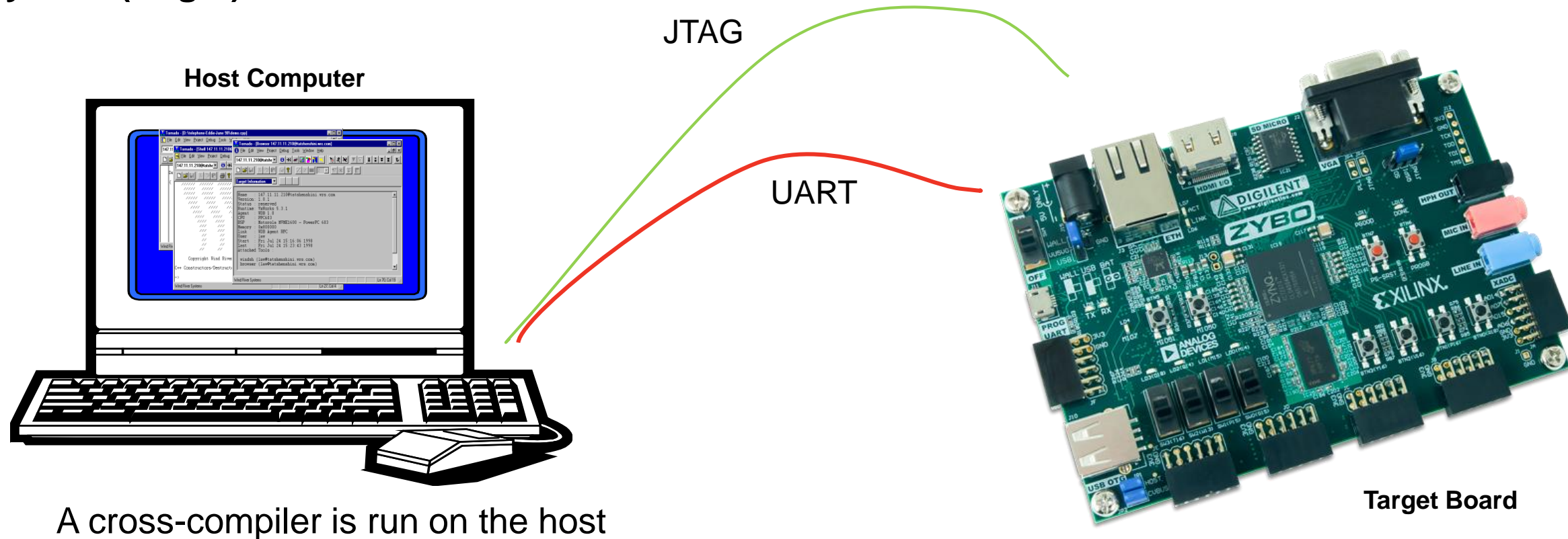
- ***Introduction***
- **SDK Development Environment**
- **SDK Project Creation**
- **GNU Development Tools: GCC, AS, LD, Binutils**
- **Software Settings**
 - Software Platform Settings
 - Compiler Settings
- **Address Management**
- **Object File Sections**
- **Linker Script**
- **Summary**

Desktop versus Embedded

- **Desktop development: written, debugged, and run on the same machine**
- **OS loads the program into the memory when the program has been requested to run**
- **Address resolution takes place at the time of loading by a program called the loader**
 - The loader is included in the OS
- **The programmer glues into one executable file called ELF**
 - Boot code, application code, RTOS, and ISRs
 - Address resolution takes place during the *gluing* stage
- **The executable file is downloaded into the target system through different methods**
 - Ethernet, serial, JTAG, BDM, ROM programmer

Embedded versus Desktop

- Development takes place on one machine (host) and is downloaded to the embedded system (target)



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Eclipse/CDT Frameworks of SDK

➤ Builder framework

- Compiles and Links Source files
- Default Build options are specified when application is created: Choice of Debug, Release, Profile configurations
- User can custom build options later when developing application
- Build types: Standard Make, Managed Make

➤ Launch framework

- Specifies what action needs to be taken: Run (+ Profile) application or Debug application
- In SDK, this is akin to the Target Connection settings

➤ Debug framework

- Launches debugger(gdb), loads application and begins debug session
- Debug views show information about state of debug session

➤ Search framework

- Helps development of application

➤ Help System

- Online help system; context-sensitive



Workspaces and Perspectives

➤ Workspace

- Location to store preferences & internal info about projects
- Transparent to users
- Source files not stored under Workspace

➤ Views, Editors

- Basic user interface element

➤ Perspectives

- Collection of functionally related views
- Layout of views in a perspective can be customized according to user preference

Views

- Eclipse Platform views: Navigator view, Tasks view, Problems view
- Debug views: Stack view, Variables view
- C/C++ views: Projects view, Outline view

Problems Console Properties

0 errors, 0 warnings, 0 infos

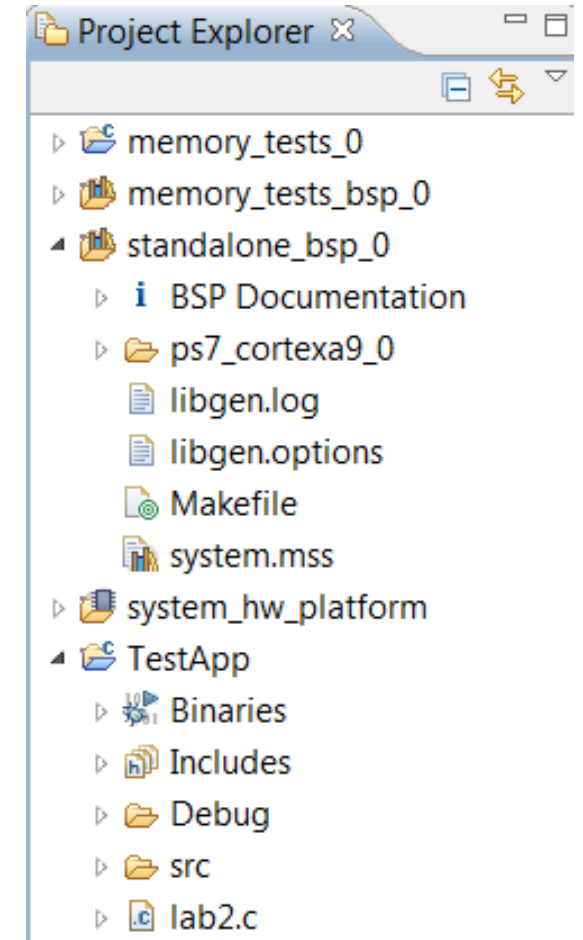
	Description	Resource	In Folder	Location

C/C++ Project View

- Hierarchical list of the workspace projects in a hierarchical format
- Double-click to open a file
- Right-click the project to access its properties

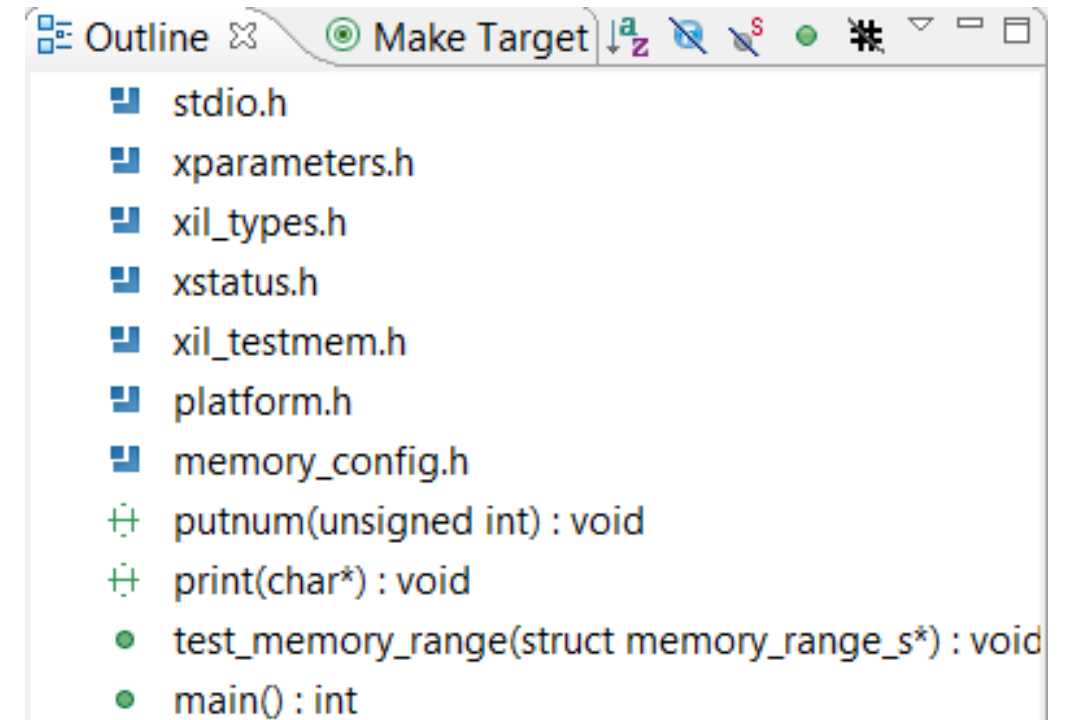
Software Applications
Software BSP

Hardware Description
Software Applications



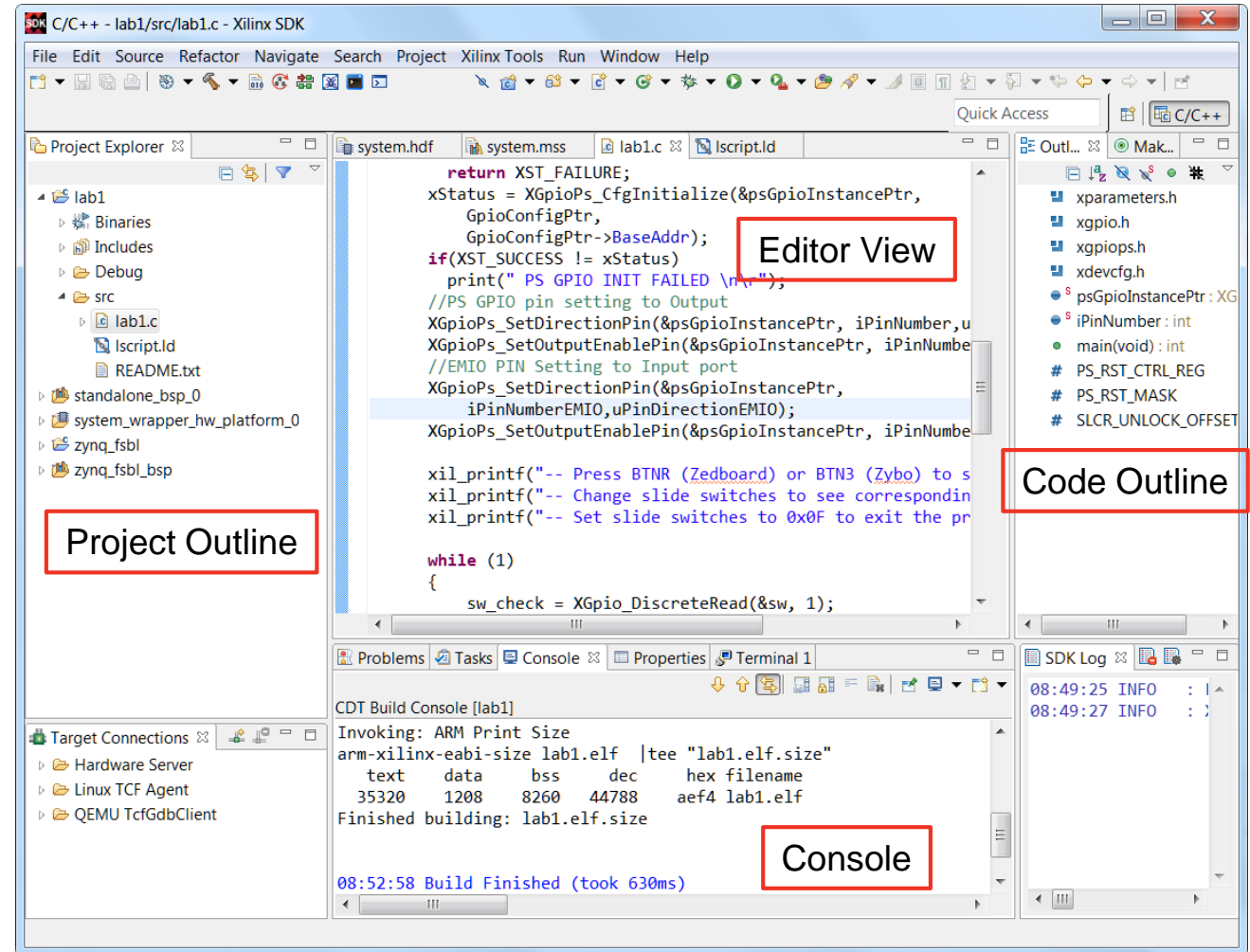
Outline View

- Displays an outline of the structured file that is currently open in the editor
- The contents of the outline view are editor specific
- Content type is indicated by the icon
- For a C source, icons represent
 - *#define* statements
 - Include files
 - Function calls
 - Declarations
- Selecting a symbol will navigate to the same in the editor window



C/C++ Perspective

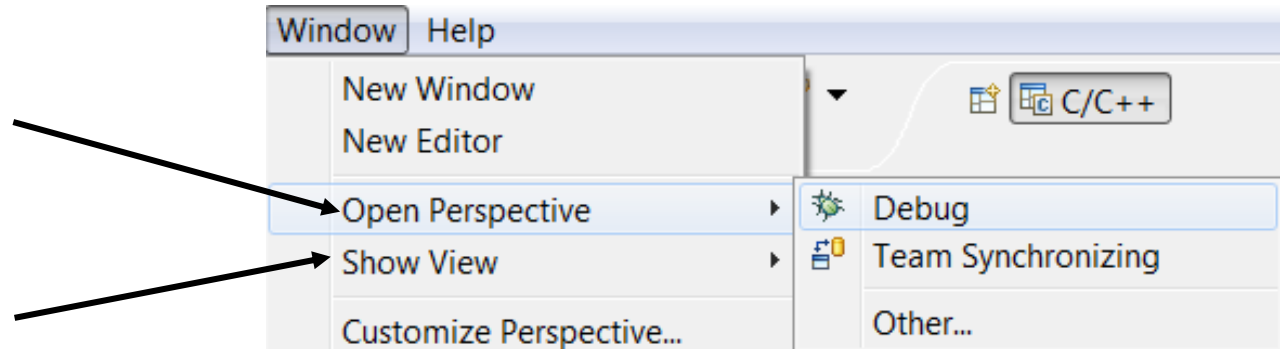
- C/C++ project outline displays the elements of a project with file decorators (icons) for easy identification
- C/C++ editor for integrated software creation
- Code outline displays elements of the software file under development with file decorators (icons) for easy identification
- Problems, Console, Properties view lists output information associated with the software development flow



Opening Perspectives and Views

- To open a Perspective, use
 - Window → Open Perspective

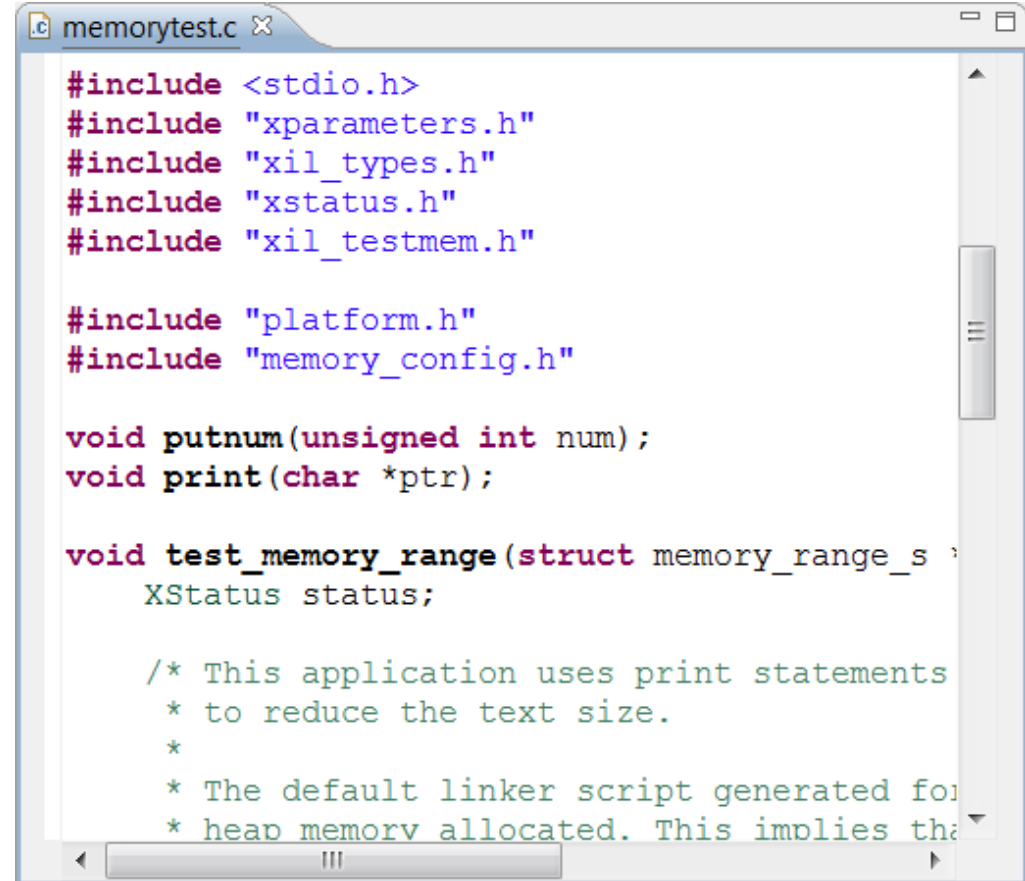
- To open a view, use
 - Window → Show View
 - If the view is already present in the current perspective, the view is highlighted



Editor

➤ Syntax Highlighting

- bracket matching
- syntax coloring
- content assist
- refactoring
- keyboard shortcuts



The screenshot shows a code editor window titled 'memorytest.c'. The code is written in C and features syntax highlighting: preprocessor directives are in purple, keywords are in red, identifiers and variables are in black, and comments are in green. The code includes several header files, defines two functions, and contains a multi-line comment.

```
#include <stdio.h>
#include "xparameters.h"
#include "xil_types.h"
#include "xstatus.h"
#include "xil_testmem.h"

#include "platform.h"
#include "memory_config.h"

void putnum(unsigned int num);
void print(char *ptr);

void test_memory_range(struct memory_range_s ,
    XStatus status;

    /* This application uses print statements
     * to reduce the text size.
     *
     * The default linker script generated for
     * heap memory allocated. This implies the
```

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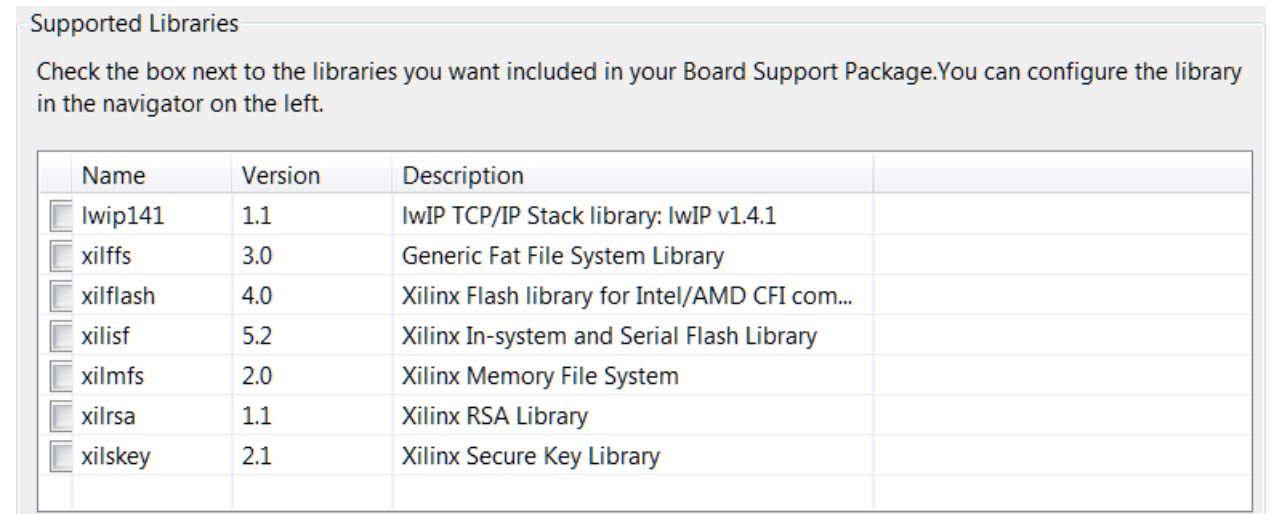
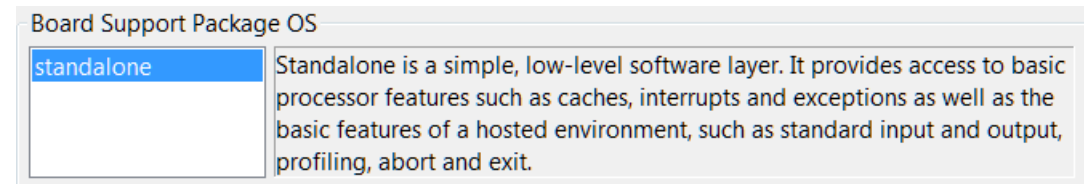
Launching SDK

➤ Launch SDK

- Standalone
 - Choose workspace, choose Hardware Platform Specification
- In Vivado
 - **File> Export Hardware**
 - **File > Launch SDK**
- Exporting
 - A Hardware Description File HDF file is first generated
 - A hardware platform specification project is then automatically created
 - The software application (and board support package) then can be created and associated with the hardware platform

Creating a Board Support Package

- The Board Support Package provides software services based on the processor and peripherals that make up the processor system
- Can be automatically created when creating Application project
- Can be created standalone
- Must be attached to a Hardware Platform
 - File > New > Board Support Package
 - Select appropriate OS support
 - Third-party operating systems are supported with the appropriate BSP selection
 - Select required libraries support



Creating a Software Application Project

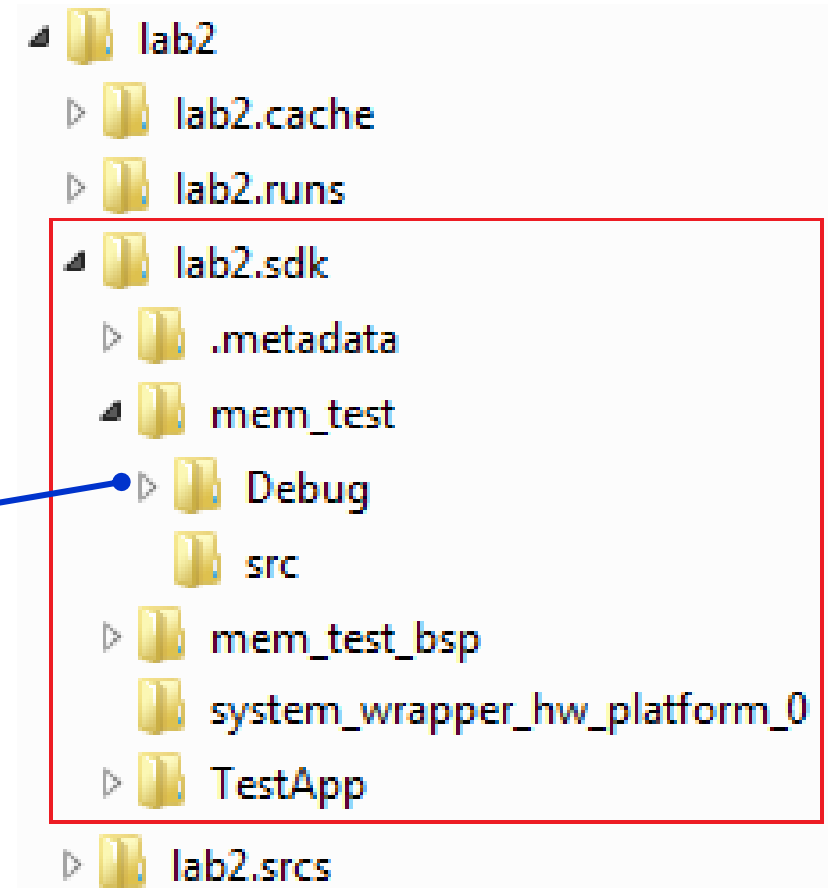
- **SDK supports multiple software application projects**
- **A software project is attached to a BSP project**
- **Sample applications are provided**
 - Great for quick test of hardware
 - Peripheral Tests
 - Starting point to base your own application on
- **Typically an Empty Application is opened to begin a non-standard project**

Available Templates:

- Peripheral Tests
- Dhrystone
- Empty Application
- Hello World**
- IwIP Echo Server
- Memory Tests
- RSA Authentication App
- SREC Bootloader
- SREC SPI Bootloader
- Xilkernel POSIX Threads Demo
- Zynq DRAM tests
- Zynq FSBL

Directory Structure

- SDK projects are placed in the application directory that was specified when SDK was launched
- Each project may have multiple directories for system files and configurations
- Configurations are property tool option permutations of the software application. Each configuration has project properties set depending on needs. An ELF file is generated for each
 - Release configuration
 - Debug configuration
 - Profile configuration
- A Debug configuration is created by default

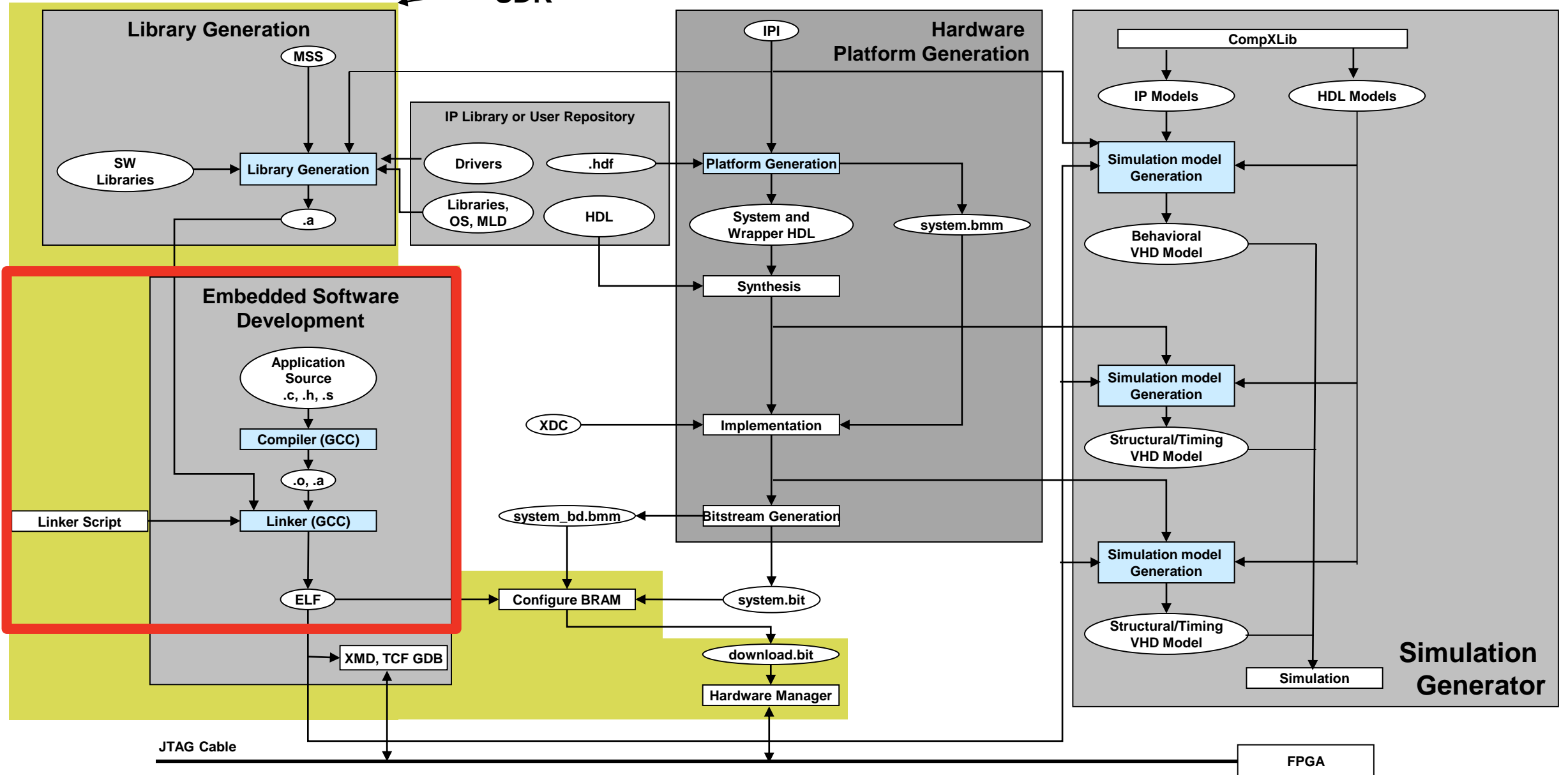


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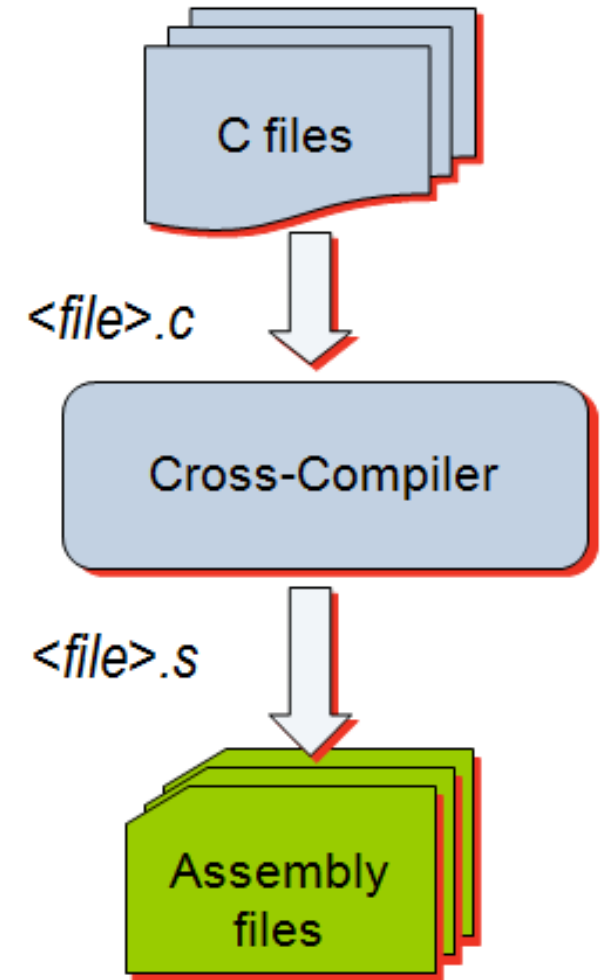
Embedded Tool Flow (SDK)

SDK



GNU Tools: GCC

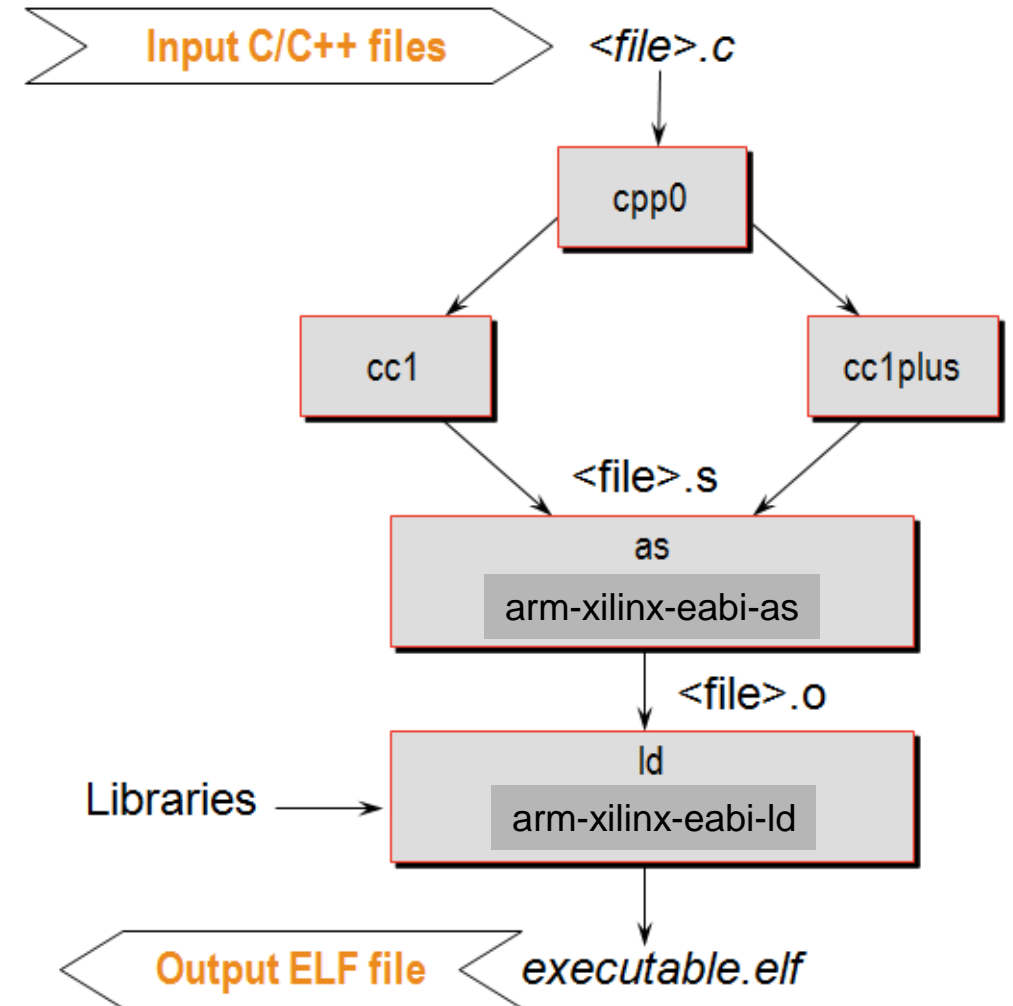
- GCC translates C source code into assembly language
- GCC also functions as the user interface to the GNU assembler and to the GNU linker, calling the assembler and the linker with the appropriate parameters
- Supported cross-compilers:
 - GNU GCC (arm-xilinx-eabi-gcc)
- Command line only; uses the settings set through the GUI



GNU Tools: GCC

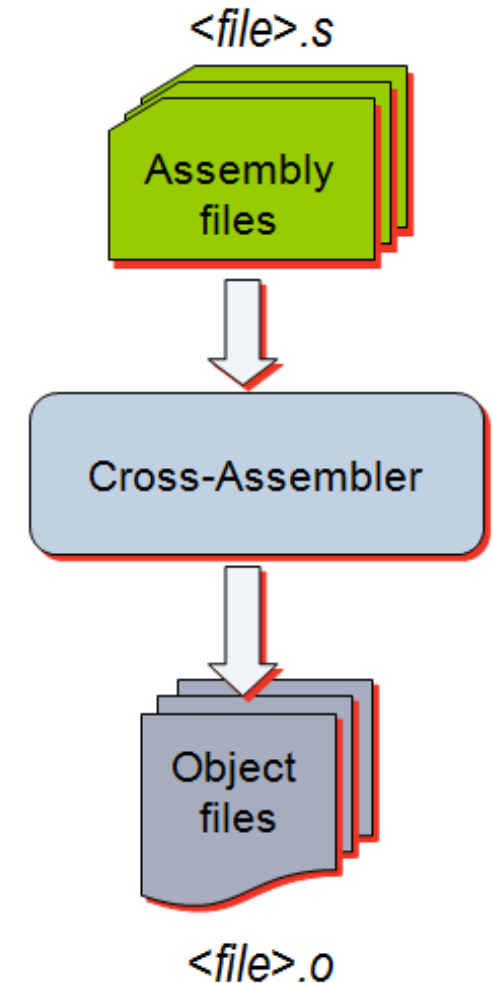
➤ Calls four different executables

- Preprocessor (cpp0)
 - Replaces all macros with definitions defined in the source and header files
- Language specific c-compiler
 - cc1 C-programming language
 - cc1plus C++ language
- Assembler
 - arm-xilinx-eabi-as
- Linker
 - arm-xilinx-eabi-ld



GNU Tools: AS

- **Input: Assembly language files**
 - File extension: `.s`
- **Output: Object code**
 - File extension: `.o`
 - Contains
 - Assembled piece of code
 - Constant data
 - External references
 - Debugging information
- **Typically, the compiler automatically calls the assembler**
- **Use the `-Wa` switch if the source files are assembly only and want to use the gcc**



GNU Tools: LD

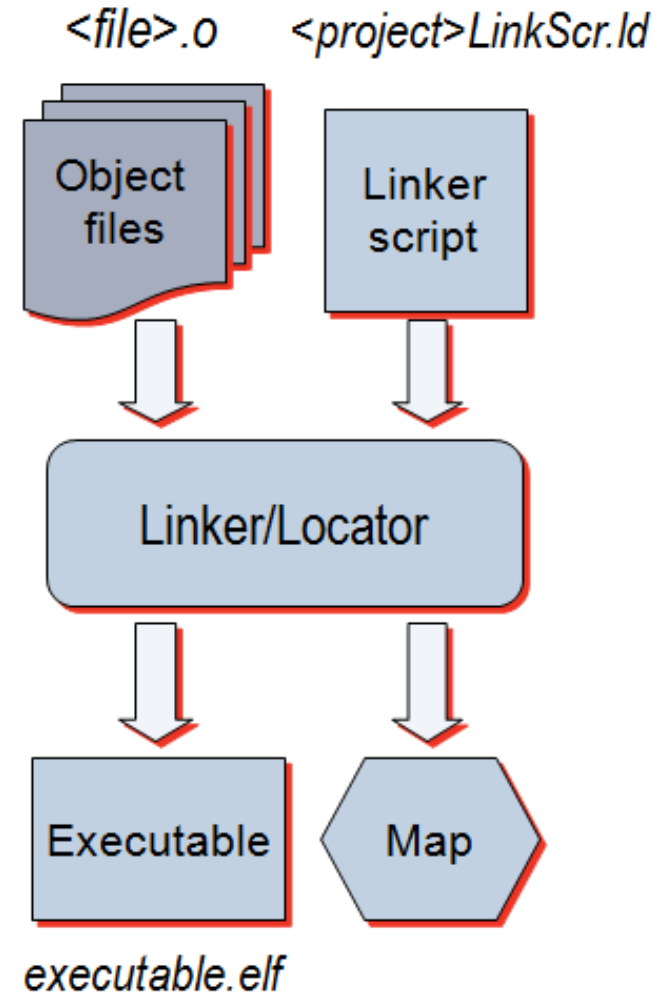
➤ Linker

➤ Inputs:

- Several object files
- Archived object files (library)
- Linker script (mapfile)

➤ Output:

- Executable image (.ELF)
- Map file



GNU Utilities

➤ AR Archiver

- Create, modify, and extract from libraries
- Used in SDK to combine the object files of the Board Support Package (BSP) in a library
- Used in SDK to extract object files from different libraries

➤ Object Dump

- Display information from object files and executables
 - Header information, memory map
 - Data
 - Disassemble code

Object Dump

Display summary information from the section headers

arm-xilinx-eabi-objdump -h executable.elf

TestApp.elf: file format elf32-littlearm

Sections:

Idx	Name	Size	UMA	LMA	File off	Algn
0	.text	00001950	00100000	00100000	00008000	2**2
	CONTENTS, ALLOC, LOAD, READONLY, CODE					
1	.init	00000018	00101950	00101950	00009950	2**2
	CONTENTS, ALLOC, LOAD, READONLY, CODE					
2	.fini	00000018	00101968	00101968	00009968	2**2
	CONTENTS, ALLOC, LOAD, READONLY, CODE					
3	.rodata	00000098	00101980	00101980	00009980	2**2
	CONTENTS, ALLOC, LOAD, READONLY, DATA					
4	.data	000000af	001019af	001019af	000099af	2**2
	CONTENTS, ALLOC, LOAD, DATA					
5	.eh_frame	00000004	00101f54	00101f54	00009f54	2**2
	CONTENTS, ALLOC, LOAD, READONLY, DATA					
6	.bss	0000005c	00101f58	00101f58	00009f58	2**2
	ALLOC					
7	.mmu_tbl	0000a04c	00101fb4	00101fb4	00009fb4	2**0
	CONTENTS, ALLOC, LOAD, READONLY, DATA					
8	.init_array	00000008	0010c000	0010c000	00014000	2**2
	CONTENTS, ALLOC, LOAD, DATA					

Section Name

Section Size

Virtual Memory Address

Loadable Memory Address

Byte alignment

Offset from the beginning of the section header table

Object Dump

Dumping the source and assembly code

arm-xilinx-eabi-objdump -S executable.elf

Memory
location

Machine Language
Instruction

C code
instruction

Assembly
instruction

```
int main (void)
{
    1003bc:      e92d4800      push    {fp, lr}
    1003c0:      e28db004      add     fp, sp, #4
    1003c4:      e24dd030      sub     sp, sp, #48      ; 0x30
    XGpio dip, push;
    int i, psb_check, dip_check;

    //xil_printf("-- Start of the Program --\r\n");

    XGpio_Initialize(&dip, XPAR_DIP_DEVICE_ID);
    1003c8:      e24b3020      sub     r3, fp, #32
    1003cc:      e1a00003      mov     r0, r3
    1003d0:      e3a01000      mov     r1, #0
    1003d4:      eb000326      bl      101074 <XGpio_Initialize>
    XGpio_SetDataDirection(&dip, 1, 0xffffffff);
    1003d8:      e24b3020      sub     r3, fp, #32
    1003dc:      e1a00003      mov     r0, r3
    e3a01001      mov     r1, #1
    e3e02000      mun     r2, #0
    eb00024e      bl      100d28 <XGpio_SetDataDirection>

    XGpio_Initialize(&push, XPAR_PUSH_DEVICE_ID);
```

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Minimal Required Services

➤ C language standard services

- C language construct services
- *stdin* and *stdout*
- Math library
- *malloc*

➤ Processor support requires these services

- Interrupt
- Cache
- Language environment support

Accessing Software Platform Properties

- Select the created board support package in the Project Explorer view
- Xilinx Tools > Board Support Package Settings
- Sets all of the software BSP related options in the design
- Has multiple forms selection
 - Overview
 - Standalone
 - Drivers
 - CPU
- As individual Standalone services are selected a configurable menu selection item will appear

standalone_bsp_1

OS Type: *standalone*

OS Version: 5.1

Target Hardware

Hardware Specification: C:\xup\embedded\2015_2_zynq_labs\lab5\lab5.sdk\system_wrapper_hw_platform_3\system.hdf

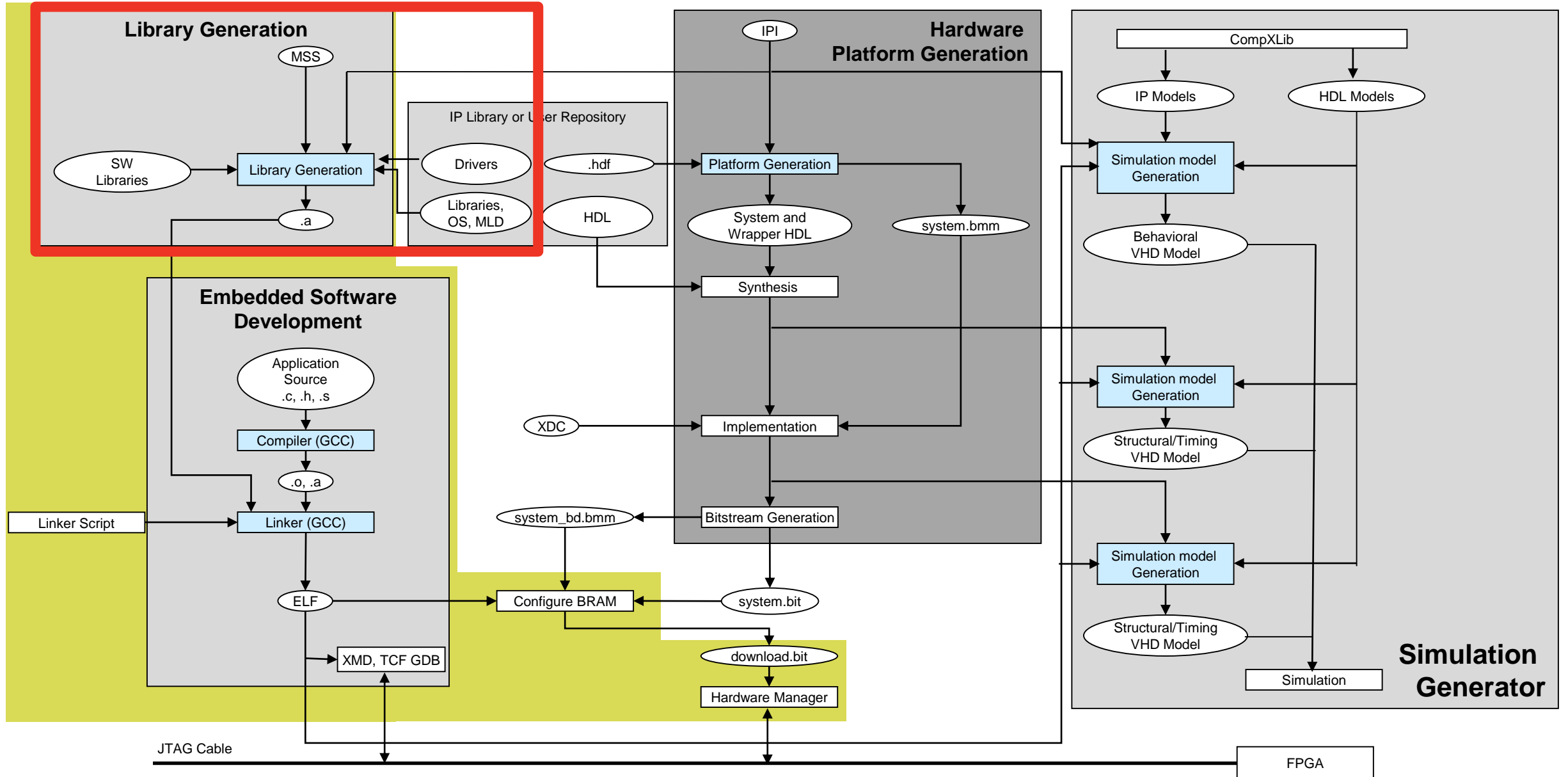
Processor: ps7_cortexa9_0

Supported Libraries

Check the box next to the libraries you want included in your Board Support Package. You can configure the library in the navigator on the left.

Name	Version	Description
<input checked="" type="checkbox"/> lwip141	1.1	IwIP TCP/IP Stack library: lwIP v1.4.1
<input type="checkbox"/> xilffs	3.0	Generic Fat File System Library
<input type="checkbox"/> xilflash	4.0	Xilinx Flash library for Intel/AMD CFI com...
<input type="checkbox"/> xilisf	5.2	Xilinx In-system and Serial Flash Library
<input type="checkbox"/> xilmfs	2.0	Xilinx Memory File System
<input type="checkbox"/> xilrsa	1.1	Xilinx RSA Library
<input type="checkbox"/> xilskey	2.1	Xilinx Secure Key Library

Embedded Tool Flow (SDK)



Library Generation Flow (in SDK)

➤ Input files → MSS

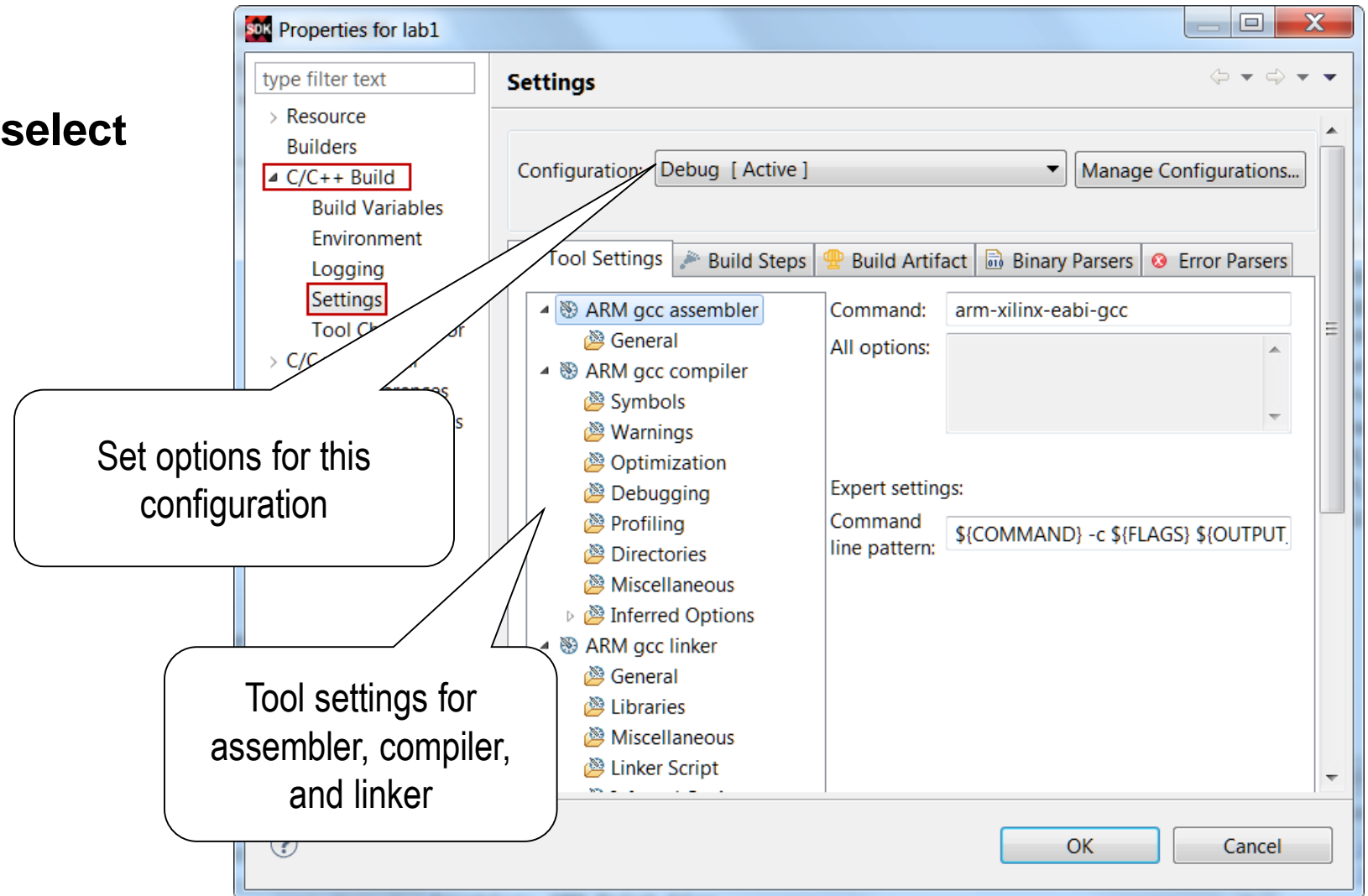
- Output files → libc.a, libXil.a, libm.a
- Library generator is generally the first tool run to configure libraries and device drivers
 - The MSS file defines the drivers associated with peripherals, standard input/output devices, and other related software features
- Library generator configures libraries and drivers with this information and produces an archive of object files:
 - libc.a - Standard C library
 - libXil.a - Xilinx library
 - libm.a - Math functions library

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C/C++ Build Settings

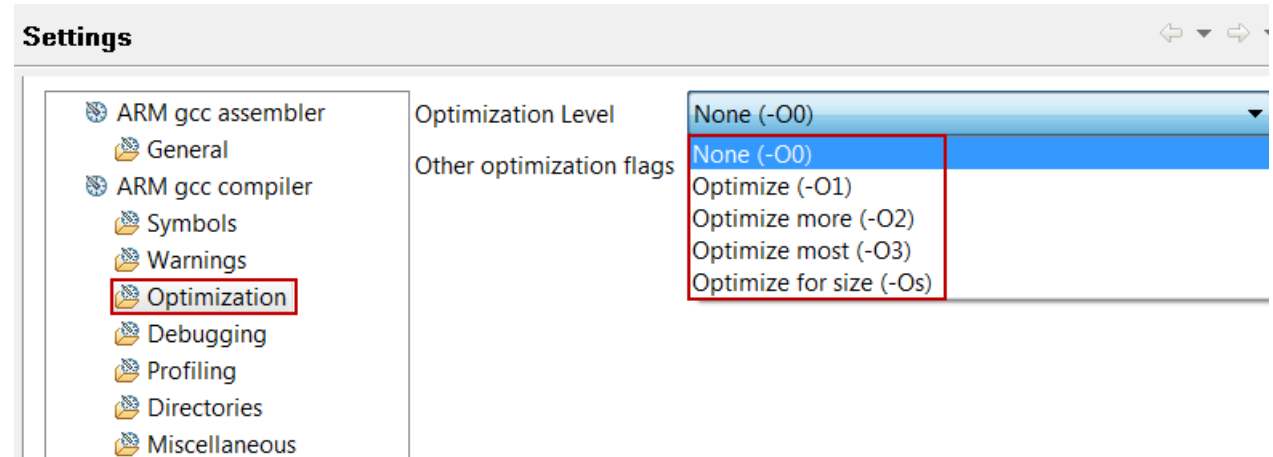
- Right-click the top level of an application project and select **C/C++ Build Settings**
- Most-accessed properties are in the **C/C++ Build** panel **Settings** tab
- Each configuration has its own properties



Debug/Optimization Properties

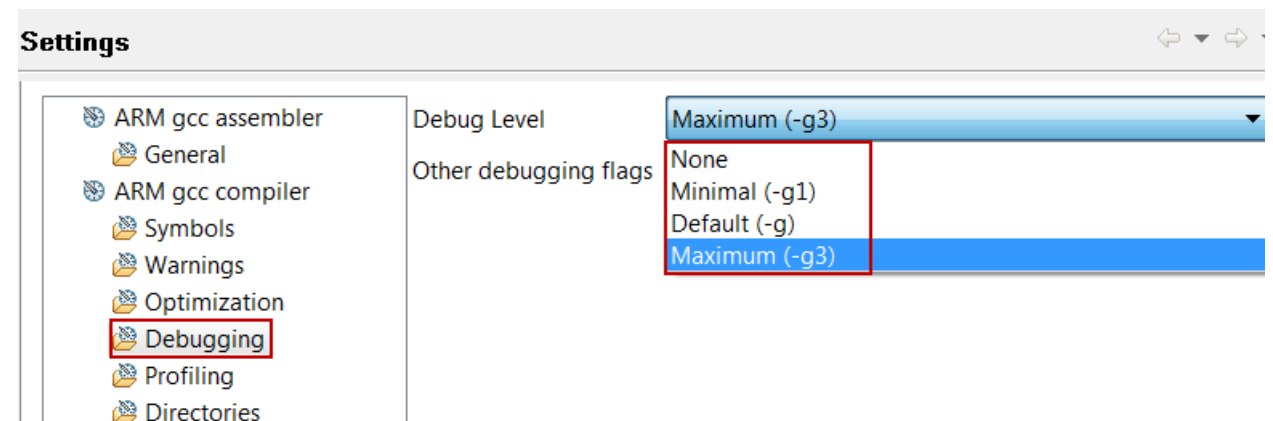
► Compiler optimization level

- None
- Low
- Medium
- High
- Size Optimized



► Enable debug symbols in executable

- Necessary for debugging
- Set optimization level to none if possible



Miscellaneous Compiler Properties

➤ Define symbols for conditional compiling

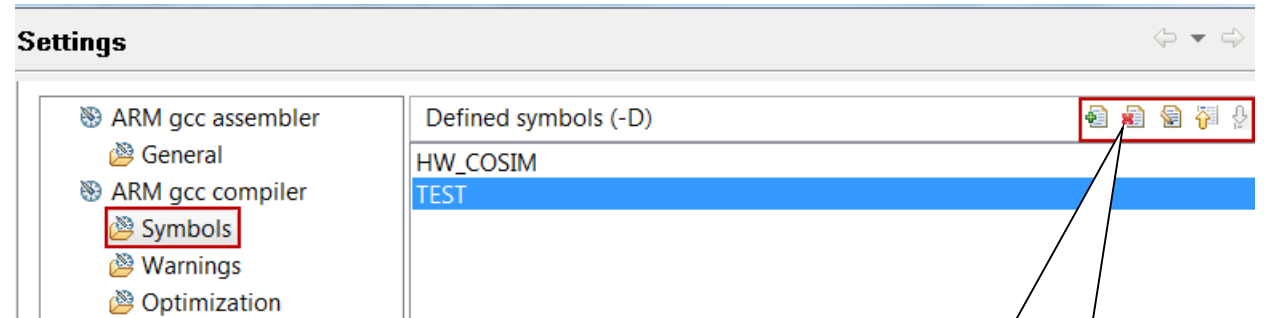
- Add
- Delete
- Edit

➤ References C source

```
#ifdef symbol  
conditional statements  
#endif
```

➤ Passed to compiler as –*D* option

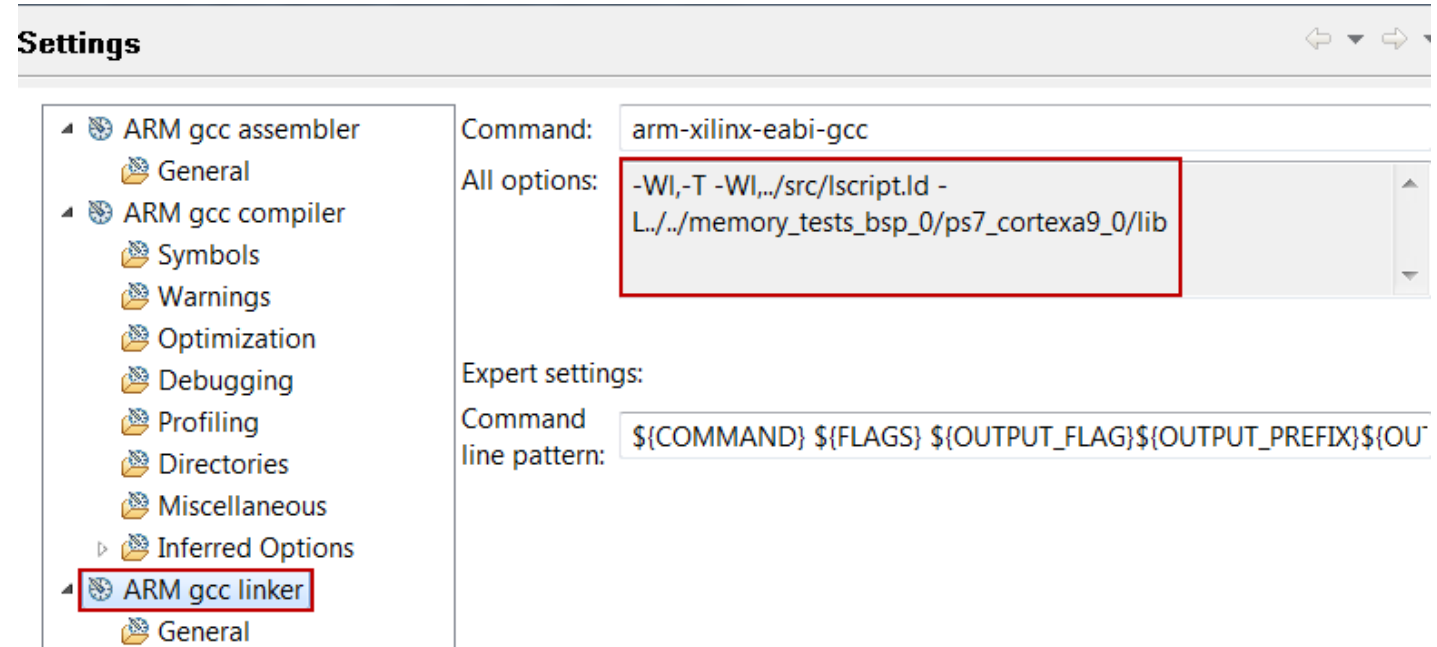
➤ Other compiler options are available



Add, Delete, Edit
Icons

Linker Properties

- The Root panel displays properties for the selected configuration
- Shown are the linker options for the Debug configuration
- Default settings are fine for simple applications



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Address Management

➤ **Embedded processor design requires you to manage the following:**

- Address map for the peripherals
- Location of the application code in the memory space
 - Block RAM
 - External memory (Flash, DDR3, SRAM)

➤ **Memory requirements for your programs are based on the following:**

- The amount of memory required for storing the instructions
- The amount of memory required for storing the data associated with the program

Standard ARM Programming Model

➤ Processing system and programmable logic look the same

- AMBA® and AXI interfaces
- Memory-mapped I/O
- Register access

➤ Consistency for PS and PL = ease of use

➤ Memory map usage: total of 4 GB

- 1 GB: DDR RAM
- 2 GB: dedicated to PL peripherals
- 1 GB: PS peripherals, OCM, external flash

Start Address	Size	Description
0x0000_0000	1GB	External DDR RAM
0x4000_0000	2GB	Custom Peripherals (Programmable Logic including PCIe)
0xE000_0000	256MB	PS I/O Peripherals
0xF800_0000	32MB	Fixed Internal Peripherals (Timers, Watchdog, DMA, Interconnect)
0xFC00_0000	64MB	Flash Memory
0xFFFC_0000	256KB	On-Chip Memory

Programmer's View of Programmable Logic

➤ Programmable logic (PL) memory map

- 2 GB total space
 - 1 GB for each AXI master: GP0, and GP1
- Accessible from any processing system (PS) master
 - Either Cortex-A9 CPU
 - PS DMA engine
 - PS peripheral DMA engine
 - Ethernet
 - USB
 - SD/SDIO

Custom Peripheral

Start Address	Description
0x4000_0000	Accelerator #1 (Video Scaler)
0x6000_0000	Accelerator #2 (Video Object Identification)
0x8000_0000	Peripheral #1 (Display Controller)

Code Snippet

```
int main() {  
  
    int *data = 0x1000_0000;  
    int *accel1 = 0x4000_0000;  
  
    // Pure SW processing  
    Process_data_sw(data);  
  
    // HW Accelerator-based processing  
    Send_data_to_accel(data, accel1);  
    process_data_hw(accel1);  
    Recv_data_from_accel(data, accel1);  
}
```

Address Map: I/O Peripherals (Zynq AP SoC)

Register Base Address	Description
E000_0000, E000_1000	UART Controllers 0, 1
E000_2000, E000_3000	USB Controllers 0, 1
E000_4000, E000_5000	I2C Controllers 0, 1
E000_6000, E000_7000	SPI Controllers 0, 1
E000_8000, E000_9000	CAN Controllers 0, 1
E000_A000	GPIO Controller
E000_B000, E000_C000	Ethernet Controllers 0, 1
E000_D000	Quad-SPI Controller
E000_E000	Static Memory Controller (SMC)
E010_0000, E010_1000	SDIO Controllers 0, 1
E020_0000	IOP Bus Configuration

Address Map: SLCR Registers (Zynq AP SoC)

Register Base Address	Description
F800_0000	SLCR write protection lock and security
F800_0100	Clock control and status
F800_0200	Reset control and status
F800_0300	APU control
F800_0400	TrustZone control
F800_0500	CoreSight SoC debug control
F800_0600	DDR DRAM controller
F800_0700	MIO pin configuration
F800_0800	MIO parallel access
F800_0900	Miscellaneous control
F800_0A00	On-chip memory (OCM) control
F800_0B00	I/O buffers for MIO pins (GPIOB) and DDR pins (DDRIOB)

Address Map: PS Registers (Zynq AP SoC)

Register Base Address	Description
F800_1000, F800_2000	Triple timer counter 0, 1
F800_3000	DMAC when secure
F800_4000	DMAC when non-secure
F800_5000	System watchdog timer (SWDT)
F800_6000	DDR DRAM controller
F800_7000	Device configuration interface (DevC)
F800_8000	AXI_HP 0 high performance AXI interface w/ FIFO
F800_9000	AXI_HP 1 high performance AXI interface w/ FIFO
F800_A000	AXI_HP 2 high performance AXI interface w/ FIFO
F800_B000	AXI_HP 3 high performance AXI interface w/ FIFO
F800_C000	On-chip memory (OCM)
F800_D000	Reserved
F880_0000	CoreSight debug control

Address Map: CPU Private Bus Registers

Register Base Address	Description
F890_0000 to F89F_FFFF	Top-level interconnect configuration and Global Programmers View (GPV)
F8F0_0000 to F8F0_00FC	SCU control and status
F8F0_0100 to F8F0_01FF	Interrupt controller CPU
F8F0_0200 to F8F0_02FF	Global timer
F8F0_0600 to F8F0_06FF	Private timers and private watchdog timers
F8F0_1000 to F8F0_1FFF	Interrupt controller distributor
F8F0_2000 to F8F0_2FFF	L2-cache controller

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Object File Sections

➤ What is an object file?

- An object file is an assembled piece of code
 - Machine language:
`li r31,0 = 0x3BE0 0000`
- Constant data
- There may be references to external objects that are defined elsewhere
- This file may contain debugging information

Object File Sections

Sectional layout of an object or an executable file

.text

Text section

.rodata

Read-only data section

.sdata2

Small read-only data section (less than eight bytes)

.sbss2

Small read-only uninitialized data section

.data

Read-write data section

.sdata

Small read-write data section

.sbss

Small uninitialized data section

.bss

Uninitialized data section

Sections Example

```
int ram_data[10] = {0,1,2,3,4,5,6,7,8,9};    /* DATA */

const int rom_data[10] = {9,8,7,6,5,4,3,2,1}; /* RODATA */

int I;    /* BSS */

main(){

    ...
    I = I + 10;  /* TEXT */
    ...

}
```

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- *Linker Script*
- Summary

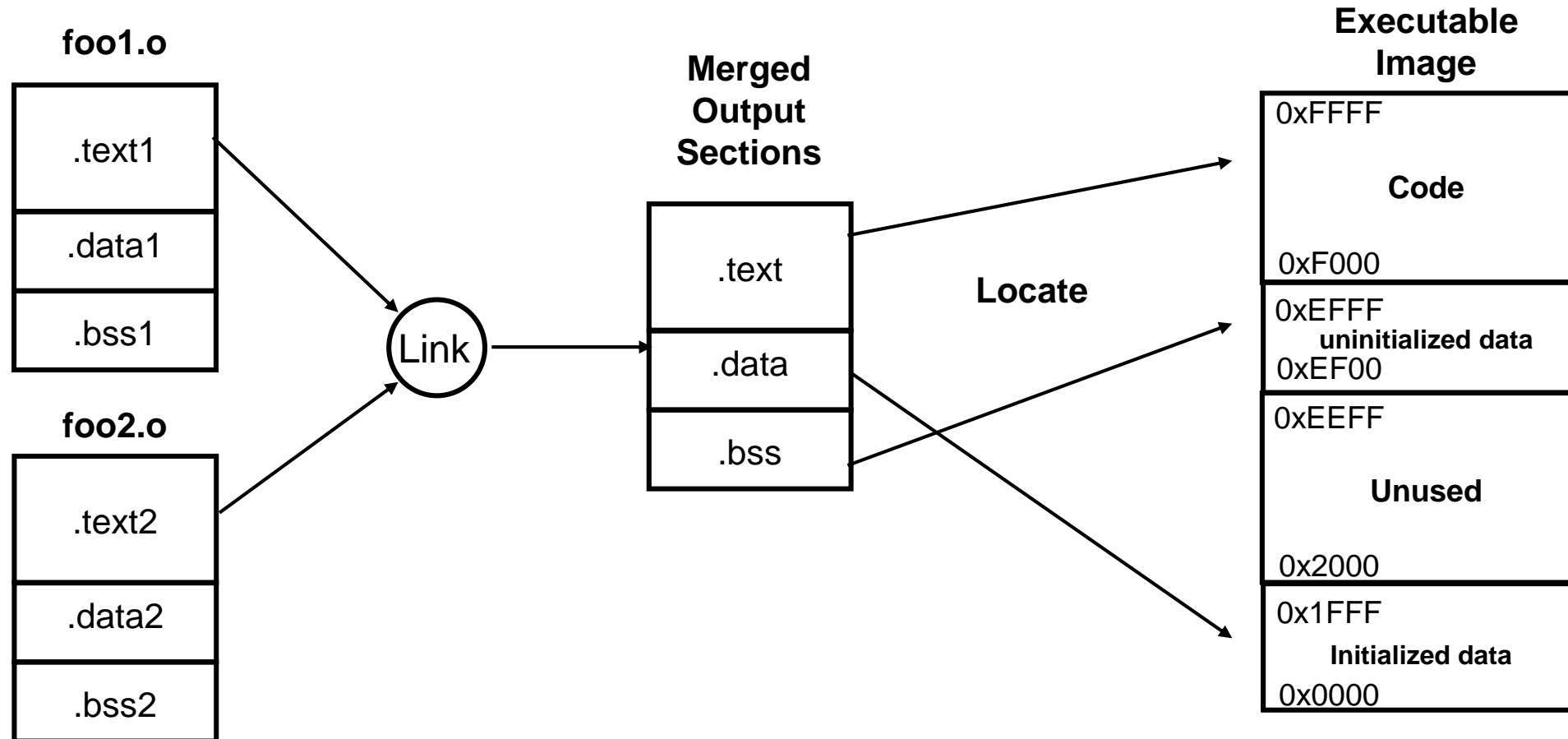
Linker Script

➤ Linker script controls the linking process

- Map the code and data to a specified memory space
- Set the entry point to the executable
- Reserve space for the stack

➤ Required if the design contains a discontinuous memory space

Linker and Locator Flows



Linker Script Generator GUI

- Table-based GUI allows you to define the memory space for code and data sections
- Launch from Xilinx Tools
 - > Generate Linker Script, or from the C/C++ perspective, right-click on <project>
 - > Generate Linker Script
- The tool will create a new linker script (the old script is backed up)

The screenshot displays the Linker Script Generator GUI with two tabs: 'Basic' and 'Advanced'. The 'Basic' tab is active, showing fields for 'Place Code Sections in:', 'Place Data Sections in:', 'Place Heap and Stack in:', 'Heap Size:', and 'Stack Size:'. The 'Advanced' tab is also visible, showing 'Code Section Assignments', 'Data Section Assignments', and 'Heap and Stack Section Assignments'.

Basic Tab:

- Place Code Sections in: ps7_dds_0_S_AXI_BASEADDR
- Place Data Sections in: ps7_dds_0_S_AXI_BASEADDR
- Place Heap and Stack in: axi_bram_ctrl_0_S_AXI_BASEADDR
- Heap Size: 1 KB
- Stack Size: 1 KB

Advanced Tab:

Output Settings

Project: TestApp

Output Script: bs_1\lab4\lab1.sdk\SDK\SDK_Export\TestApp\src\lscript.ld [Browse]

Modify project build settings as follows: Set generated script on all project build configurations

Hardware Memory Map

Memory	Base Address	Size
ps7_dds_0_S_AXI_BASEADDR	0x00100000	511...
ps7_ram_0_S_AXI_BASEADDR	0x00000000	192...
ps7_ram_1_S_AXI_BASEADDR	0xFFFF0000	~63...
axi_bram_ctrl_0_S_AXI_BASEADDR	0xBE810000	8 KB

Code Section Assignments

Section	Assigned Memory
.text	ps7_dds_0_S_AXI_BASEADDR

Data Section Assignments

Section	Assigned Memory
.rodata	ps7_dds_0_S_AXI_BASEADDR
.rodata1	ps7_dds_0_S_AXI_BASEADDR
.sdata2	ps7_dds_0_S_AXI_BASEADDR
.sbss2	ps7_dds_0_S_AXI_BASEADDR
.data	ps7_dds_0_S_AXI_BASEADDR
.data1	ps7_dds_0_S_AXI_BASEADDR
.fixup	ps7_dds_0_S_AXI_BASEADDR
.sdata	ps7_dds_0_S_AXI_BASEADDR
.sbss	ps7_dds_0_S_AXI_BASEADDR
.bss	ps7_dds_0_S_AXI_BASEADDR

Heap and Stack Section Assignments

Section	Assigned Memory	Assigned Size
Heap	axi_bram_ctrl_0_S_AXI_BASEADDR	1 KB
Stack	axi_bram_ctrl_0_S_AXI_BASEADDR	1 KB

Outline

- Introduction
- SDK Development Environment
- SDK Project Creation
- GNU Development Tools: GCC, AS, LD, Binutils
- Software Settings
 - Software Platform Settings
 - Compiler Settings
- Address Management
- Object File Sections
- Linker Script
- ***Summary***

Summary

- **Software development for an embedded system in FPGA imposes unique challenges due to unique hardware platform**
- **SDK provides many rich perspectives which enable ease of accessing information through related views**
- **GNU tools are used for compiling C/C++ source files, linking, creating executable output, and debugging**
- **Software platform settings allow inclusion of software library support**
- **Compiler settings provide switches including compiling, linking, debugging, and profiling**

Summary

- **Embedded processor design requires you to manage**
 - Peripheral address space
 - Memory address space to store data and instructions
 - Internal block memory
 - External memory
- **Linker script is required when the software segments do not reside in a contiguous memory space**