

MCP23017 Library

Keegan Morrow
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MCP23017

Arduino library for the Microchip **MCP23017** IO Expander

Hierarchical Index

Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

wireUtil< REGTYPE, DATATYPE >	13
wireUtil< MCP23017_Register_t, uint8_t >	13
MCP23017	3

Class Index

Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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File Index

File List

Here is a list of all files with brief descriptions:

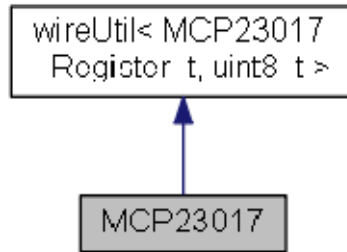
src/MCP23017.cpp	17
src/MCP23017.h (Arduino library for the Microchip MCP23017 IO Expander)	17
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Class Documentation

MCP23017 Class Reference

```
#include <MCP23017.h>
```

Inheritance diagram for MCP23017:



Public Member Functions

- **MCP23017** ()
- void **begin** ()
Initialize the chip at the default address.
- uint8_t **addressIndex** (uint8_t a)
Get the hardware address from the logical address of the chip.
- void **pinMode** (uint8_t, uint8_t)
Set the characteristic of the IO pin.
- void **digitalWrite** (uint8_t, bool)
Set the state of an output pin.
- bool **digitalRead** (uint8_t)
Read the state of an input pin.
- void **portMode** (MCP23017_Port_t, uint8_t)
Set the characteristic of a port.
- void **writePort** (MCP23017_Port_t, uint8_t)
Write a byte to an output port.
- uint8_t **readPort** (MCP23017_Port_t)
Read a byte from an input port.
- void **chipMode** (uint8_t)
Set the characteristic of all pins on the chip.
- void **writeChip** (uint16_t)
Write a word to the chip.
- uint16_t **readChip** ()
Read a word from a chip.
- void **setInputPolarity** (bool)
Sets the input polarity of the chip.
- void **setInputPolarity** (MCP23017_Port_t, bool)
Set the input polarity of a port.

- void **setInputPolarity** (uint8_t, bool)
Set the input polarity of an individual pin.
- uint8_t **getInterrupt** ()
Get the pin that caused an interrupt.
- uint16_t **getInterruptCapture** ()
Get a snapshot of all the input pins at the last interrupt.
- uint8_t **getInterruptCapture** (MCP23017_Port_t)
Get a snapshot of the state of all the pins on a port at the last interrupt.
- void **setInterrupt** (uint8_t, bool)
Set if an input pin will trigger an interrupt on change.
- void **setInterrupt** (MCP23017_Port_t, bool)
Set interrupt enable on a port.
- void **setInterrupt** (uint16_t)
Directly set the interrupt mask for the whole chip.
- void **interruptMirror** (bool)
Set the interrupt pins to mirror each other.
- void **setIntPinMode** (MCP23017_interruptPinMode_t)
Set the electrical characteristic of the interrupt pins.

Additional Inherited Members

Constructor & Destructor Documentation

MCP23017::MCP23017 ()[inline]

Member Function Documentation

uint8_t MCP23017::addressIndex (uint8_t a)[inline]

Get the hardware address from the logical address of the chip.

Parameters:

<i>a</i>	Logical address of the chip
----------	-----------------------------

Returns:

Hardware address of the chip

void MCP23017::begin ()[inline], [virtual]

Initialize the chip at the default address.

Reimplemented from `wireUtil< MCP23017_Register_t, uint8_t > (p.14)`.

Here is the call graph for this function:



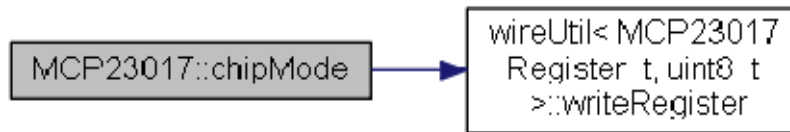
void MCP23017::chipMode (uint8_t mode)

Set the characteristic of all pins on the chip.

Parameters:

<i>mode</i>	IO type (INPUT, INPUT_PULLUP, OUTPUT)
-------------	---------------------------------------

Here is the call graph for this function:



bool MCP23017::digitalRead (uint8_t pin)

Read the state of an input pin.

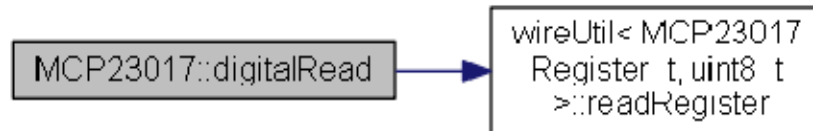
Parameters:

<i>pin</i>	Pin number
------------	------------

Returns:

State of the pin

Here is the call graph for this function:



void MCP23017::digitalWrite (uint8_t pin, bool state)

Set the state of an output pin.

Parameters:

<i>pin</i>	Pin number
<i>state</i>	State to set the pin (HIGH, LOW)

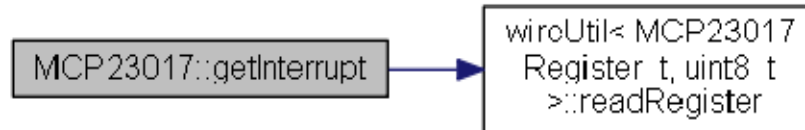
uint8_t MCP23017::getInterrupt ()

Get the pin that caused an interrupt.

Returns:

Pin number

Here is the call graph for this function:



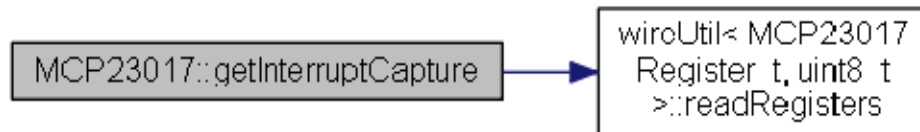
uint16_t MCP23017::getInterruptCapture ()

Get a snapshot of all the input pins at the last interrupt.

Returns:

Snapshot of the input registers

Here is the call graph for this function:



uint8_t MCP23017::getInterruptCapture (MCP23017_Port_t port)

Get a snapshot of the state of all the pins on a port at the last interrupt.

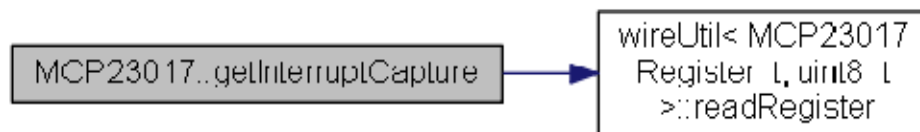
Parameters:

<i>port</i>	Port to get the snapshot from
-------------	-------------------------------

Returns:

Snapshot of the port

Here is the call graph for this function:



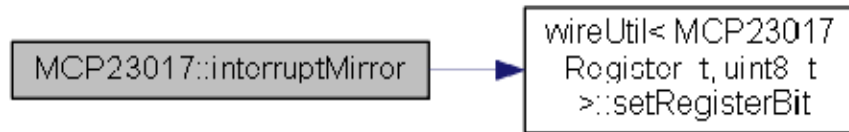
void MCP23017::interruptMirror (bool *state*)

Set the interrupt pins to mirror each other.

Parameters:

<i>state</i>	true = both int pins mirror, false = int by port
--------------	--

Here is the call graph for this function:



void MCP23017::pinMode (uint8_t *pin*, uint8_t *mode*)

Set the characteristic of the IO pin.

Parameters:

<i>pin</i>	Pin number
<i>mode</i>	IO type (INPUT, INPUT_PULLUP, OUTPUT)

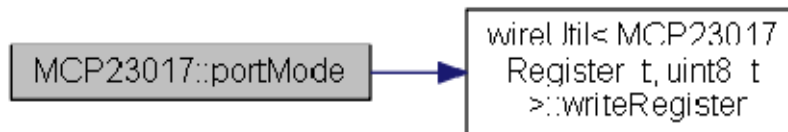
void MCP23017::portMode (MCP23017_Port_t *port*, uint8_t *mode*)

Set the characteristic of a port.

Parameters:

<i>port</i>	Port to set (A, B)
<i>mode</i>	IO type (INPUT, INPUT_PULLUP, OUTPUT)

Here is the call graph for this function:



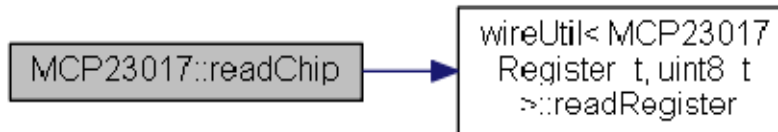
uint16_t MCP23017::readChip ()

Read a word from a chip.

Returns:

A word from the chip

Here is the call graph for this function:



uint8_t MCP23017::readPort (MCP23017_Port_t port)

Read a byte from an input port.

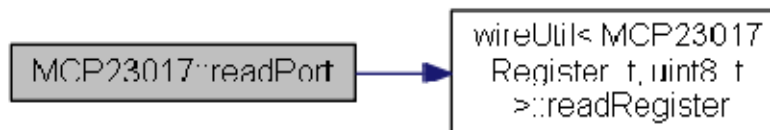
Parameters:

<i>port</i>	Port to read from (A, B)
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Returns:

data from the port

Here is the call graph for this function:



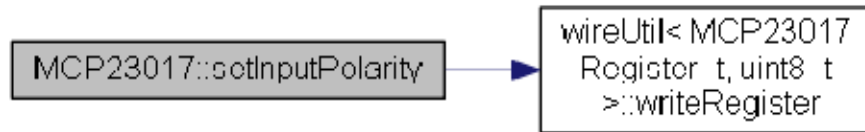
void MCP23017::setInputPolarity (bool *state*)

Sets the input polarity of the chip.

Parameters:

<i>state</i>	true = all input pins inverted
--------------	--------------------------------

Here is the call graph for this function:



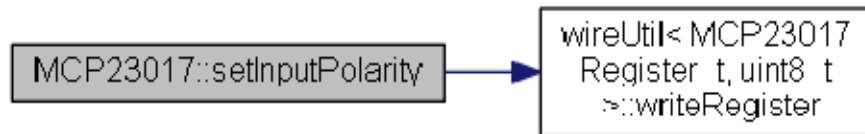
void MCP23017::setInputPolarity (MCP23017_Port_t *port*, bool *state*)

Set the input polarity of a port.

Parameters:

<i>port</i>	Port to set (A, B)
<i>state</i>	true = inverted

Here is the call graph for this function:



void MCP23017::setInputPolarity (uint8_t *pin*, bool *state*)

Set the input polarity of an individual pin.

Parameters:

<i>pin</i>	Pin to set
<i>state</i>	true = inverted

void MCP23017::setInterrupt (uint8_t *pin*, bool *state*)

Set if an input pin will trigger an interrupt on change.

Parameters:

<i>pin</i>	Pin to enable or disable interrupt
<i>state</i>	true = enable, false = disable

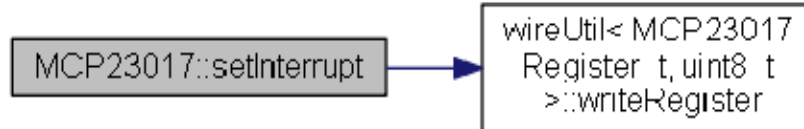
void MCP23017::setInterrupt (MCP23017_Port_t *port*, bool *state*)

Set interrupt enable on a port.

Parameters:

<i>port</i>	Port to set
<i>state</i>	

Here is the call graph for this function:



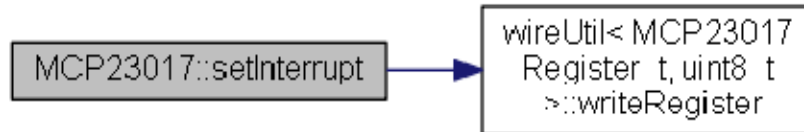
void MCP23017::setInterrupt (uint16_t *mask*)

Directly set the interrupt mask for the whole chip.

Parameters:

<i>mask</i>	16 bit mask 1's = enable
-------------	--------------------------

Here is the call graph for this function:



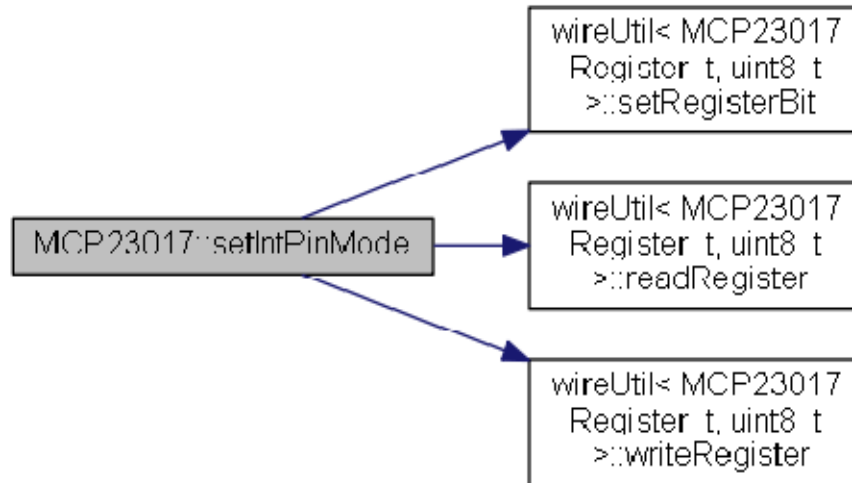
void MCP23017::setIntPinMode (MCP23017_interruptPinMode_t *interruptPinMode*)

Set the electrical characteristic of the interrupt pins.

Parameters:

<i>interruptPinMode</i>	(openDrain, lowOnInt, highOnInt)
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Here is the call graph for this function:



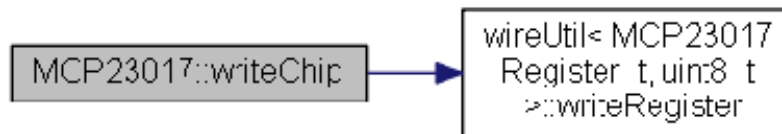
void MCP23017::writeChip (uint16_t *state*)

Write a word to the chip.

Parameters:

<i>state</i>	Word to write
--------------	---------------

Here is the call graph for this function:



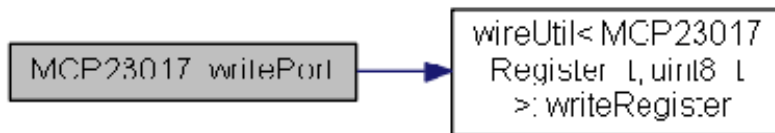
void MCP23017::writePort (MCP23017_Port_t *port*, uint8_t *state*)

Write a byte to an output port.

Parameters:

<i>port</i>	Port to output to (A, B)
<i>state</i>	Byte to write

Here is the call graph for this function:



The documentation for this class was generated from the following files:

- src/MCP23017.h
- src/MCP23017.cpp

wireUtil< REGTYPE, DATATYPE > Class Template Reference

Utility base class for reading and writing registers on i2c devices.

#include <wireUtil.h>

Public Member Functions

- void **attachTimeoutHandler** (void(*timeOutHandler)(void))
Attach a function to be called on a read timeout.
- void **attachErrorHandler** (void(*errorHandler)(uint8_t))
Attach a function to be called on a write NACK.
- bool **getTimeoutFlag** ()
Safe method to read the state of the timeout flag.
- virtual void **begin** ()
- virtual void **begin** (uint8_t)
Initialize the chip at a specific address.
- bool **writeRegister** (REGTYPE, DATATYPE)
Write a single register on an i2c device.
- bool **writeRegisters** (REGTYPE, DATATYPE *, uint8_t)
Write to a sequence of registers on an i2c device.
- DATATYPE **readRegister** (REGTYPE)
Read a single register from an i2c device.
- bool **readRegisters** (REGTYPE, DATATYPE *, uint8_t)
Read a number of sequential registers from an i2c device.
- bool **setRegisterBit** (REGTYPE, uint8_t, bool)
Read modify write a bit on a register.

Public Attributes

- unsigned long **timeoutTime**
Amount of time to wait for a successful read.
- bool **timeoutFlag**
Set to true if there is a timeout event, reset on the next read.

Protected Attributes

- uint8_t **address**
Hardware address of the device.
-

Detailed Description

template<typename REGTYPE, typename DATATYPE = uint8_t>

class wireUtil< REGTYPE, DATATYPE >

Utility base class for reading and writing registers on i2c devices.

Template Parameters:

<i>REGTYPE</i>	An initialized enum type that lists the valid registers for the device
<i>DATATYPE</i>	= uint8_t Data type (register size) supports uint8_t, uint16_t, uint32_t

Member Function Documentation

template<typename REGTYPE, typename DATATYPE = uint8_t> void wireUtil< REGTYPE, DATATYPE >::attachErrorHandler (void*)(uint8_t) *errorHandler* [inline]

Attach a function to be called on a write NACK.

Parameters:

<i>errorHandler</i>	Pointer to a 'void f(uint8_t)' function. This will be passed the Wire status.
---------------------	---

template<typename REGTYPE, typename DATATYPE = uint8_t> void wireUtil< REGTYPE, DATATYPE >::attachTimeoutHandler (void*)(void) *timeOutHandler* [inline]

Attach a function to be called on a read timeout.

Parameters:

<i>timeOutHandler</i>	Pointer to a 'void f(void)' function
-----------------------	--------------------------------------

template<typename REGTYPE, typename DATATYPE = uint8_t> virtual void wireUtil< REGTYPE, DATATYPE >::begin () [virtual]

Reimplemented in **MCP23017** (p.5).

template<typename REGTYPE , typename DATATYPE > void wireUtil< REGTYPE, DATATYPE >::begin (uint8_t *address*) [virtual]

Initialize the chip at a specific address.

Parameters:

<i>address</i>	Address of the chip
----------------	---------------------

```
template<typename REGTYPE, typename DATATYPE = uint8_t> bool wireUtil< REGTYPE, DATATYPE >::getTimeoutFlag () [ inline ]
```

Safe method to read the state of the timeout flag.

Returns:

State of the timeout flag

```
template<typename REGTYPE, typename DATATYPE > DATATYPE wireUtil< REGTYPE, DATATYPE >::readRegister (REGTYPE reg)
```

Read a single register from an i2c device.

Parameters:

<i>reg</i>	Register address (from a device specific enum)
------------	--

Returns:

Data from the device register, 0 if there is a timeout

```
template<typename REGTYPE, typename DATATYPE> bool wireUtil< REGTYPE, DATATYPE >::readRegisters (REGTYPE reg, DATATYPE * buffer, uint8_t len)
```

Read a number of sequential registers from an i2c device.

Parameters:

<i>reg</i>	First register address (from a device specific enum)
<i>buffer</i>	Array to contain the data read
<i>len</i>	Number of bytes to read

Returns:

true on success, false on timeout

```
template<typename REGTYPE, typename DATATYPE > bool wireUtil< REGTYPE, DATATYPE >::setRegisterBit (REGTYPE reg, uint8_t bit, bool state)
```

Read modify write a bit on a register.

Parameters:

<i>reg</i>	register to modify
<i>bit</i>	index of the bit to set
<i>state</i>	state of the bit to set

Returns:

true on success

```
template<typename REGTYPE, typename DATATYPE> bool wireUtil< REGTYPE,
DATATYPE >::writeRegister (REGTYPE  reg, DATATYPE  data)
```

Write a single register on an i2c device.

Parameters:

<i>reg</i>	Register address (from a device specific enum)
<i>data</i>	Data to be written to the device

Returns:

true on success, false if NACK

```
template<typename REGTYPE, typename DATATYPE> bool wireUtil< REGTYPE,
DATATYPE >::writeRegisters (REGTYPE  reg, DATATYPE *  buffer, uint8_t  len)
```

Write to a sequence of registers on an i2c device.

Parameters:

<i>reg</i>	First register address (from a device specific enum)
<i>buffer</i>	Array containing the data to be written
<i>len</i>	Number of bytes in the array

Returns:

true on success, false if NACK

Member Data Documentation

```
template<typename REGTYPE, typename DATATYPE = uint8_t> uint8_t wireUtil<
REGTYPE, DATATYPE >::address[protected]
```

Hardware address of the device.

```
template<typename REGTYPE, typename DATATYPE = uint8_t> bool wireUtil< REGTYPE,
DATATYPE >::timeoutFlag
```

Set to true if there is a timeout event, reset on the next read.

```
template<typename REGTYPE, typename DATATYPE = uint8_t> unsigned long wireUtil<
REGTYPE, DATATYPE >::timeoutTime
```

Amount of time to wait for a successful read.

The documentation for this class was generated from the following file:

- src/utility/**wireUtil.h**

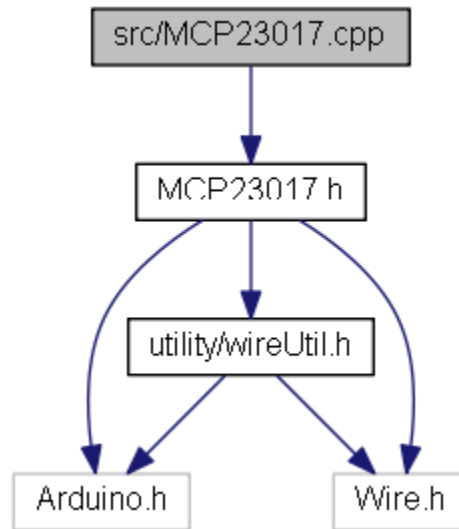
File Documentation

README.md File Reference

src/MCP23017.cpp File Reference

```
#include "MCP23017.h"
```

Include dependency graph for MCP23017.cpp:



src/MCP23017.h File Reference

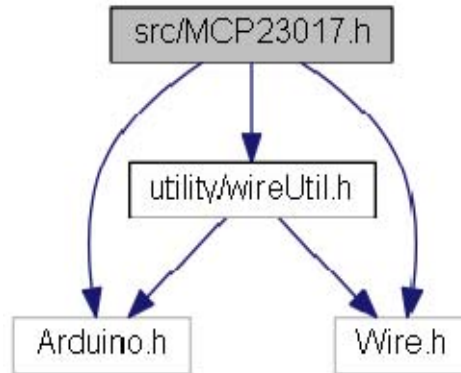
Arduino library for the Microchip **MCP23017** IO Expander.

```
#include <Arduino.h>
```

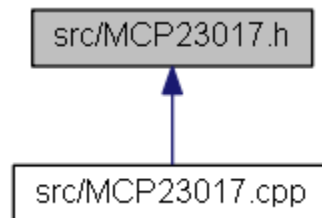
```
#include <Wire.h>
```

```
#include "utility/wireUtil.h"
```

Include dependency graph for MCP23017.h:



This graph shows which files directly or indirectly include this file:



Classes

- class **MCP23017**

Enumerations

- enum **MCP23017_Register_t** { **IODIRA_r** = 0x00, **IODIRB_r** = 0x01, **IPOLA_r** = 0x02, **IPOLB_r** = 0x03, **GPINTENA_r** = 0x04, **GPINTENB_r** = 0x05, **DEFVALA_r** = 0x06, **DEFVALB_r** = 0x07, **INTCONA_r** = 0x08, **INTCONB_r** = 0x09, **IOCONA_r** = 0x0A, **IOCONB_r** = 0x0B, **GPPUA_r** = 0x0C, **GPPUB_r** = 0x0D, **INTFA_r** = 0x0E, **INTFB_r** = 0x0F, **INTCAPA_r** = 0x10, **INTCAPB_r** = 0x11, **GPIOA_r** = 0x12, **GPIOB_r** = 0x13, **OLATA_r** = 0x14, **OLATB_r** = 0x15 }
- enum **MCP23017_RegisterGeneric_t** { **IODIR_r** = 0x00, **IPOL_r** = 0x02, **GPINTEN_r** = 0x04, **DEFVAL_r** = 0x06, **INTCON_r** = 0x08, **IOCON_r** = 0x0A, **GPPU_r** = 0x0C, **INTF_r** = 0x0E, **INTCAP_r** = 0x10, **GPIO_r** = 0x12, **OLAT_r** = 0x14 }
- enum **MCP23017_Port_t** { **PORT_A** = 0x00, **PORT_B** = 0x01 }
- enum **MCP23017_interruptPinMode_t** { **openDrain**, **lowOnInt**, **highOnInt** }

Detailed Description

Arduino library for the Microchip **MCP23017** IO Expander.

Author:

Keegan Morrow

Version:

0.1.1

Enumeration Type Documentation

enum MCP23017_interruptPinMode_t

Enumerator:

openDrain	
lowOnInt	
highOnInt	

enum MCP23017_Port_t

Enumerator:

PORT_A	
PORT_B	

enum MCP23017_Register_t

Enumerator:

IODIRA_r	
IODIRB_r	
IPOLA_r	
IPOLB_r	
GPINTENA_r	
GPINTENB_r	
DEFVALA_r	
DEFVALB_r	
INTCONA_r	
INTCONB_r	
IOCONA_r	
IOCONB_r	
GPPUA_r	
GPPUB_r	
INTFA_r	
INTFB_r	
INTCAPA_r	
INTCAPB_r	
GPIOA_r	
GPIOB_r	
OLATA_r	
OLATB_r	

enum MCP23017_RegisterGeneric_t

Enumerator:

IODIR_r	
IPOL_r	
GPINTEN_r	
DEFVAL_r	
INTCON_r	

IOCON_r	
GPPU_r	
INTF_r	
INTCAP_r	
GPIO_r	
OLAT_r	

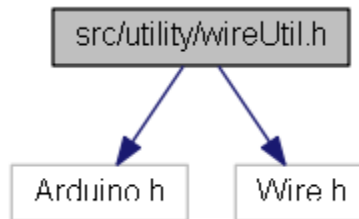
src/utility/wireUtil.h File Reference

Utility base class for reading and writing registers on i2c devices.

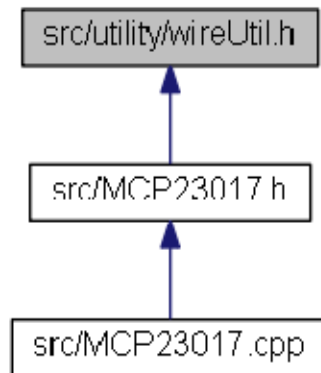
```
#include <Arduino.h>
```

```
#include <Wire.h>
```

Include dependency graph for wireUtil.h:



This graph shows which files directly or indirectly include this file:



Classes

- class **wireUtil**< REGTYPE, DATATYPE >

Utility base class for reading and writing registers on i2c devices.

Detailed Description

Utility base class for reading and writing registers on i2c devices.

Author:

Keegan Morrow

Version:

1.1.2