

Class Documentation

MCP23017 Class Reference

```
#include <MCP23017.h>
```

Inherits **wireUtil**< **MCP23017_Register_t** >.

Public Member Functions

- **MCP23017** ()
- void **begin** ()
Initialize the chip at the default address.
- void **pinMode** (uint8_t, uint8_t)
Set the characteristic of the IO pin.
- void **digitalWrite** (uint8_t, bool)
Set the state of an output pin.
- bool **digitalRead** (uint8_t)
Read the state of an input pin.
- void **portMode** (**MCP23017_Port_t**, uint8_t)
Set the characteristic of a port.
- void **writePort** (**MCP23017_Port_t**, uint8_t)
Write a byte to an output port.
- uint8_t **readPort** (**MCP23017_Port_t**)
Read a byte from an input port.
- void **chipMode** (uint8_t)
Set the characteristic of all pins on the chip.
- void **writeChip** (uint16_t)
Write a word to the chip.
- uint16_t **readChip** ()
Read a word from a chip.
- void **setInputPolarity** (bool)
Sets the input polarity of the chip.
- void **setInputPolarity** (**MCP23017_Port_t**, bool)
Set the input polarity of a port.
- void **setInputPolarity** (uint8_t, bool)
Set the input polarity of an individual pin.
- uint8_t **getInterrupt** ()
Get the pin that caused an interrupt.
- uint16_t **getInterruptCapture** ()
Get a snapshot of all the input pins at the last interrupt.
- uint8_t **getInterruptCapture** (**MCP23017_Port_t**)
Get a snapshot of the state of all the pins on a port at the last interrupt.
- void **setInterrupt** (uint8_t, bool)
Set if an input pin will trigger an interrupt on change.

- void **setInterrupt** (uint16_t)
Directly set the interrupt mask for the whole chip.
- void **interruptMirror** (bool)
Set the interrupt pins to mirror each other.
- void **setIntPinMode** (MCP23017_interruptPinMode_t)
Set the electrical characteristic of the interrupt pins.

Additional Inherited Members

Constructor & Destructor Documentation

MCP23017::MCP23017 () [`inline`]

Member Function Documentation

void MCP23017::begin () [`inline`], [`virtual`]

Initialize the chip at the default address.

Reimplemented from `wireUtil< MCP23017_Register_t >` (p.8).

void MCP23017::chipMode (uint8_t *mode*)

Set the characteristic of all pins on the chip.

Parameters:

<i>mode</i>	IO type (INPUT, INPUT_PULLUP, OUTPUT)
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bool MCP23017::digitalRead (uint8_t *pin*)

Read the state of an input pin.

Parameters:

<i>pin</i>	Pin number
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Returns:

State of the pin

void MCP23017::digitalWrite (uint8_t *pin*, bool *state*)

Set the state of an output pin.

Parameters:

<i>pin</i>	Pin number
<i>state</i>	State to set the pin (HIGH, LOW)

uint8_t MCP23017::getInterrupt ()

Get the pin that caused an interrupt.

Returns:

Pin number

uint16_t MCP23017::getInterruptCapture ()

Get a snapshot of all the input pins at the last interrupt.

Returns:

Snapshot of the input registers

uint8_t MCP23017::getInterruptCapture (MCP23017_Port_t *port*)

Get a snapshot of the state of all the pins on a port at the last interrupt.

Parameters:

<i>port</i>	Port to get the snapshot from
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Returns:

Snapshot of the port

void MCP23017::interruptMirror (bool *state*)

Set the interrupt pins to mirror each other.

Parameters:

<i>state</i>	true = both int pins mirror, false = int by port
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void MCP23017::pinMode (uint8_t *pin*, uint8_t *mode*)

Set the characteristic of the IO pin.

Parameters:

<i>pin</i>	Pin number
<i>mode</i>	IO type (INPUT, INPUT_PULLUP, OUTPUT)

void MCP23017::portMode (MCP23017_Port_t *port*, uint8_t *mode*)

Set the characteristic of a port.

Parameters:

<i>port</i>	Port to set (A, B)
<i>mode</i>	IO type (INPUT, INPUT_PULLUP, OUTPUT)

uint16_t MCP23017::readChip ()

Read a word from a chip.

Returns:

A word from the chip

uint8_t MCP23017::readPort (MCP23017_Port_t *port*)

Read a byte from an input port.

Parameters:

<i>port</i>	Port to read from (A, B)
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Returns:

data from the port

void MCP23017::setInputPolarity (bool *state*)

Sets the input polarity of the chip.

Parameters:

<i>state</i>	true = all input pins inverted
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void MCP23017::setInputPolarity (MCP23017_Port_t *port*, bool *state*)

Set the input polarity of a port.

Parameters:

<i>port</i>	Port to set (A, B)
<i>state</i>	true = inverted

void MCP23017::setInputPolarity (uint8_t *pin*, bool *state*)

Set the input polarity of an individual pin.

Parameters:

<i>pin</i>	Pin to set
<i>state</i>	true = inverted

void MCP23017::setInterrupt (uint8_t *pin*, bool *state*)

Set if an input pin will trigger an interrupt on change.

Parameters:

<i>pin</i>	Pin to enable or disable interrupt
<i>state</i>	true = enable, false = disable

void MCP23017::setInterrupt (uint16_t *mask*)

Directly set the interrupt mask for the whole chip.

Parameters:

<i>mask</i>	16 bit mask 1's = enable
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void MCP23017::setIntPinMode (MCP23017_interruptPinMode_t *interruptPinMode*)

Set the electrical characteristic of the interrupt pins.

Parameters:

<i>interruptPinMode</i>	(openDrain, lowOnInt, highOnInt)
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void MCP23017::writeChip (uint16_t *state*)

Write a word to the chip.

Parameters:

<i>state</i>	Word to write
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void MCP23017::writePort (MCP23017_Port_t *port*, uint8_t *state*)

Write a byte to an output port.

Parameters:

<i>port</i>	Port to output to (A, B)
<i>state</i>	Byte to write

The documentation for this class was generated from the following files:

- MCP23017.h
- MCP23017.cpp

wireUtil< REGTYPE > Class Template Reference

Utility base class for reading and writing registers on i2c devices.

#include <wireUtil.h>

Public Member Functions

- void **attachTimeoutHandler** (void(*timeOutHandler)(void))
Attach a function to be called on a read timeout.
- void **attachNACKhandler** (void(*NACKhandler)(uint8_t))
Attach a function to be called on a write NACK.
- bool **getTimeoutFlag** ()
Safe method to read the state of the timeout flag.
- virtual void **begin** ()
- virtual void **begin** (uint8_t)
Initialize the chip at a specific address.
- bool **writeRegister** (REGTYPE, uint8_t)
Write a single register on an i2c device.
- bool **writeRegisters** (REGTYPE, uint8_t *, uint8_t)
Write to a sequence of registers on an i2c device.
- uint8_t **readRegister** (REGTYPE)
Read a single register from an i2c device.
- bool **readRegisters** (REGTYPE, uint8_t *, uint8_t)
Read a number of sequential registers from an i2c device.
- bool **setRegisterBit** (REGTYPE, uint8_t, bool)
Read modify write a bit on a register.

Public Attributes

- unsigned long **timeoutTime**
Amount of time to wait for a successful read.
- bool **timeoutFlag**
Set to true if there is a timeout event, reset on the next read.

Protected Attributes

- uint8_t **address**
Hardware address of the device.

Detailed Description

template<typename REGTYPE>

class wireUtil< REGTYPE >

Utility base class for reading and writing registers on i2c devices.

Template Parameters:

<i>REGTYPE</i>	An initialized enum type that lists the valid registers for the device
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Member Function Documentation

template<typename REGTYPE> void wireUtil< REGTYPE >::attachNACKhandler (void*)(uint8_t) *NACKhandler* [inline]

Attach a function to be called on a write NACK.

Parameters:

<i>NACKhandler</i>	Pointer to a 'void f(uint8_t)' function. This will be passed the Wire status.
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template<typename REGTYPE> void wireUtil< REGTYPE >::attachTimeoutHandler (void*)(void) *timeOutHandler* [inline]

Attach a function to be called on a read timeout.

Parameters:

<i>timeOutHandler</i>	Pointer to a 'void f(void)' function
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template<typename REGTYPE> virtual void wireUtil< REGTYPE >::begin () [virtual]

Reimplemented in **MCP23017** (p.2).

template<typename REGTYPE > void wireUtil< REGTYPE >::begin (uint8_t *address*) [virtual]

Initialize the chip at a specific address.

Parameters:

<i>address</i>	Address of the chip
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template<typename REGTYPE> bool wireUtil< REGTYPE >::getTimeoutFlag () [inline]

Safe method to read the state of the timeout flag.

Returns:

State of the timeout flag

template<typename REGTYPE> uint8_t wireUtil< REGTYPE >::readRegister (REGTYPE reg)

Read a single register from an i2c device.

Parameters:

<i>reg</i>	Register address (from a device specific enum)
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Returns:

Data from the device register, 0 if there is a timeout

template<typename REGTYPE> bool wireUtil< REGTYPE >::readRegisters (REGTYPE reg, uint8_t * buffer, uint8_t len)

Read a number of sequential registers from an i2c device.

Parameters:

<i>reg</i>	First register address (from a device specific enum)
<i>buffer</i>	Array to contain the data read
<i>len</i>	Number of bytes to read

Returns:

true on success, false on timeout

template<typename REGTYPE> bool wireUtil< REGTYPE >::setRegisterBit (REGTYPE reg, uint8_t bit, bool state)

Read modify write a bit on a register.

Parameters:

<i>reg</i>	register to modify
<i>bit</i>	index of the bit to set
<i>state</i>	state of the bit to set

Returns:

true on success

template<typename REGTYPE> bool wireUtil< REGTYPE >::writeRegister (REGTYPE *reg*, uint8_t *data*)

Write a single register on an i2c device.

Parameters:

<i>reg</i>	Register address (from a device specific enum)
<i>data</i>	Data to be written to the device

Returns:

true on success, false if NACK

template<typename REGTYPE> bool wireUtil< REGTYPE >::writeRegisters (REGTYPE *reg*, uint8_t * *buffer*, uint8_t *len*)

Write to a sequence of registers on an i2c device.

Parameters:

<i>reg</i>	First register address (from a device specific enum)
<i>buffer</i>	Array containing the data to be written
<i>len</i>	Number of bytes in the array

Returns:

true on success, false if NACK

Member Data Documentation

template<typename REGTYPE> uint8_t wireUtil< REGTYPE >::address[protected]

Hardware address of the device.

template<typename REGTYPE> bool wireUtil< REGTYPE >::timeoutFlag

Set to true if there is a timeout event, reset on the next read.

template<typename REGTYPE> unsigned long wireUtil< REGTYPE >::timeoutTime

Amount of time to wait for a successful read.

The documentation for this class was generated from the following file:

- **wireUtil.h**

MCP23017.h File Reference

Arduino library for the Microchip MCP23017 IO Expander.

```
#include <Arduino.h>
#include <Wire.h>
#include "utility/wireUtil.h"
```

Classes

- class **MCP23017**

Enumerations

- enum **MCP23017_Register_t** { **IODIRA** = 0x00, **IODIRB** = 0x01, **IPOLA** = 0x02, **IPOLB** = 0x03, **GPINTENA** = 0x04, **GPINTENB** = 0x05, **DEFVALA** = 0x06, **DEFVALB** = 0x07, **INTCONA** = 0x08, **INTCONB** = 0x09, **IOCONA** = 0x0A, **IOCONB** = 0x0B, **GPPUA** = 0x0C, **GPPUB** = 0x0D, **INTFA** = 0x0E, **INTFB** = 0x0F, **INTCAPA** = 0x10, **INTCAPB** = 0x11, **GPIOA** = 0x12, **GPIOB** = 0x13, **OLATA** = 0x14, **OLATB** = 0x15 }
- enum **MCP23017_RegisterGeneric_t** { **IODIR** = 0x00, **IPOL** = 0x02, **GPINTEN** = 0x04, **DEFVAL** = 0x06, **INTCON** = 0x08, **IOCON** = 0x0A, **GPPU** = 0x0C, **INTF** = 0x0E, **INTCAP** = 0x10, **GPIO** = 0x12, **OLAT** = 0x14 }
- enum **MCP23017_Port_t** { **A** = 0x00, **B** = 0x01 }
- enum **MCP23017_interruptPinMode_t** { **openDrain**, **lowOnInt**, **highOnInt** }

Detailed Description

Arduino library for the Microchip MCP23017 IO Expander.

Author:

Keegan Morrow

Version:

0.1.0

Enumeration Type Documentation

enum **MCP23017_interruptPinMode_t**

Enumerator

openDrain
lowOnInt
highOnInt

enum **MCP23017_Port_t**

Enumerator

A
B

enum MCP23017_Register_t

Enumerator

IODIRA
IODIRB
IPOLA
IPOLB
GPINTENA
GPINTENB
DEFVALA
DEFVALB
INTCONA
INTCONB
IOCONA
IOCONB
GPPUA
GPPUB
INTFA
INTFB
INTCAPA
INTCAPB
GPIOA
GPIOB
OLATA
OLATB

enum MCP23017_RegisterGeneric_t

Enumerator

IODIR
IPOL
GPINTEN
DEFVAL
INTCON
IOCON
GPPU
INTF
INTCAP
GPIO
OLAT

wireUtil.h File Reference

Utility base class for reading and writing registers on i2c devices.

```
#include <Arduino.h>
```

```
#include <Wire.h>
```

Classes

- class **wireUtil**< REGTYPE >

Utility base class for reading and writing registers on i2c devices.

Detailed Description

Utility base class for reading and writing registers on i2c devices.

Author:

Keegan Morrow

Version:

1.0.0