## Best linear predictor: matrix version

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Let M(n,k) denote the linear space of all matrix of dimension  $n \times k$ .

Suppose we have random vectors  $(\mathbf{y}(\omega), \mathbf{z}(\omega))'$ . We know additionally that  $\mathbf{y} \in M(n, 1)$  and  $\mathbf{z} \in M(k, 1)$  and these vectors have finite mean and variance. Denote their mean by

$$\begin{bmatrix} \mu_y \\ \mu_z \end{bmatrix}$$

and their variance matrix by

$$\begin{bmatrix} \Sigma_{yy} & \Sigma_{yz} \\ \Sigma_{zy} & \Sigma_{zz} \end{bmatrix}$$

We define the **best linear predictor** of y given z as the random variable w such that

$$\mathbf{w}^* = \alpha^* + \beta^* (\mathbf{z} - \mu_z)$$

where  $\alpha^* \in M(n,1)$  and  $\beta^* \in M(n,k)$  solve the minimization problem

$$\min_{\alpha,\beta} \mathbf{E} \left[ \|\mathbf{y} - \alpha - \beta(\mathbf{z} - \mu_z)\|^2 \right]$$

You can solve it either by using calculus – which can be cumbersome if you're not used to matrix derivatives – or by noting that the minimand is a squared norm generated by the inner product

$$\langle \mathbf{y}, \mathbf{w} \rangle := \mathbf{E}[\mathbf{w}'\mathbf{y}]$$

of all vectors of the type  $\mathbf{y} - \mathbf{w}$  where  $\mathbf{w} = \alpha + \beta(\mathbf{z} - \mu_z)$  for some  $\alpha, \beta$ .

Let  $\epsilon := \mathbf{y} - \mathbf{w}^*$  denote the residual of the minimization problem. Then  $\epsilon$  must be orthogonal (by Hilbert's projection theorem) to every  $\mathbf{w} = \alpha + \beta(\mathbf{z} - \mu_z)$ .

Taking  $\beta = 0$ , we see that  $\mathbf{w}^*$  must satisfy

$$0 = \langle \mathbf{y} - \mathbf{w}^*, \alpha \rangle = \mathbf{E} \left[ \alpha' \mathbf{y} \right] - \mathbf{E} \left[ \alpha' \alpha^* \right]$$

for all vectors  $\alpha \in M(n,1)$ . Taking these to be the elements of the canonical basis, we conclude that

$$\alpha^* = \mu_y$$

Now take  $\alpha = 0$ . The orthogonality condition now implies that for any  $\beta \in M(n,k)$ ,

$$0 = \langle \mathbf{y} - \beta^* (\mathbf{z} - \mu_z), \beta(\mathbf{z} - \mu_z) \rangle = \mathbf{E} \left[ (\mathbf{z} - \mu_z)' \beta' y \right] - \mathbf{E} \left[ (\mathbf{z} - \mu_z)' \beta' \beta^* (\mathbf{z} - \mu_z) \right]$$

Use the properties of the trace - namely, that it's linear and that matrix multiplication commutes inside it - and of the expectation operator to conclude that

$$\operatorname{tr}\left(\beta'\mathbf{E}\left[\mathbf{y}(\mathbf{z}-\mu_z)'\right]\right) = \operatorname{tr}\left(\beta'\beta^*\mathbf{E}\left[\left(\mathbf{z}-\mu_z\right)\left(\mathbf{z}-\mu_z\right)'\right]\right)$$

note that  $\mathbf{E}[\mathbf{y}(\mathbf{z} - \mu_z)'] = \Sigma_{yz}$  and  $\mathbf{E}[(\mathbf{z} - \mu_z)(\mathbf{z} - \mu_z)'] = \Sigma_{zz}$ . The equation above then implies that

$$\operatorname{tr}(\beta' \Sigma_{yz}) = \operatorname{tr}(\beta' \beta^* \Sigma_{zz})$$

should hold for all matrices  $\beta \in M(n,k)$ . That implies, <sup>1</sup>

$$\Sigma_{yz} = \beta^* \Sigma_{zz}$$

which in turn yields  $\beta^* = \Sigma_{yz} \Sigma_{zz}^{-1}$  whenever  $\Sigma_{zz}$  has an inverse. In that case, the BLP is

$$\mathbf{w}^* = \mu_y + \Sigma_{yz} \Sigma_{zz}^{-1} (\mathbf{z} - \mu_z) \tag{1}$$

## 1 Appendix: the Trace operator

- let A(i,j) denote the entry (i,j) of any matrix
- Let A be a  $m \times n$  matrix. The trace is defined as

$$trA = \sum_{i=1}^{\min\{m,n\}} A(i,i)$$

in other words, it's just the sum of elements in the main diagonal.

- Some properties of the trace:
  - 1. tr(A+B) = tr(A) + tr(B) whenever A and B have similar dimensions

<sup>&</sup>lt;sup>1</sup>See the appendix on the trace operator for details.

- 2. tr(kA) = k tr(A) for all scalars k
- 3. tr(AB) = tr(BA) whenever dimensions are such that both multiplications make sense

Curiosity: any operation tr that satisfies the properties above is equal to tr (modulo multiplication by a constant)

• The trace and expectation operators commute:

$$tr(\mathbf{E}A) = \mathbf{E}(trA)$$

• Suppose  $A \in M(m,n)$  and you want to select element (i,j) from it. Note that

$$A(i,j) = e_i' A \varepsilon_j = tr(e_i' A \varepsilon_j) = tr(\varepsilon_j e_i' A)$$

where  $e_i$  is the i-th element in the canonical basis of  $R^m$  and  $\varepsilon_j$  is the j-th element of the canonical basis of  $R^n$ .

Hence for any (i,j), letting  $B = \varepsilon_j e_i' \in M(n,m)$  we have

$$A(i,j) = \operatorname{tr}(BA)$$

• This implies that if A and  $\tilde{A}$  are fixed  $m \times n$  matrices, and

$$\operatorname{tr}(BA) = \operatorname{tr}(B\tilde{A})$$

holds for every  $B \in M(n, m)$ , then

$$A = \tilde{A}$$