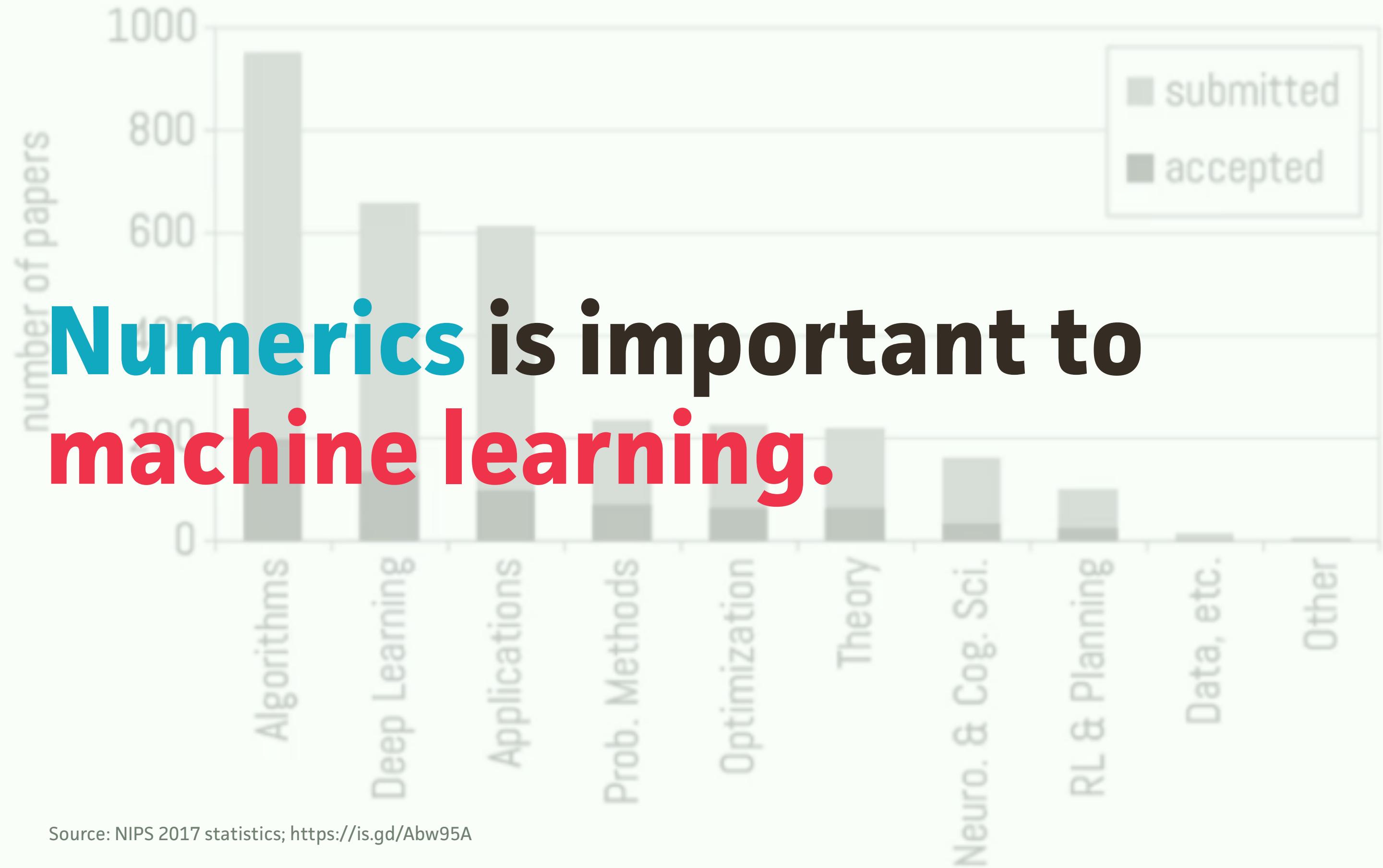


# PROBABILISTIC NUMERICS: NANO-MACHINE-LEARNING

Michael A Osborne, @maosbot



# Which numerics problems have you needed solved in the last month?

1. Linear algebra.
2. Optimisation.
3. Global optimisation.
4. Integration.
5. Ordinary differential equations.

Tabula terræ Nouæ Zembla,  
in qua fretum sinusq; WAIGATS,  
item ora littoralis TARTARIAE atq;  
RUSSIAE, ad urbem usq; KILDEINAM  
prescribitur adhac CURSUS quem inde  
naues in redditu tenent securus septentrionale  
littus et TRAIECTUS  
prope fretum WAIGATS ad Rusie  
cram et ad promontorium CANDENOS,  
atq; fauces usq; MARIS ALBI.  
AUTHORE GERHARDO DE VEER.



**Numerics allows  
computation-fuelled  
expeditions beyond the  
analytic frontier.**

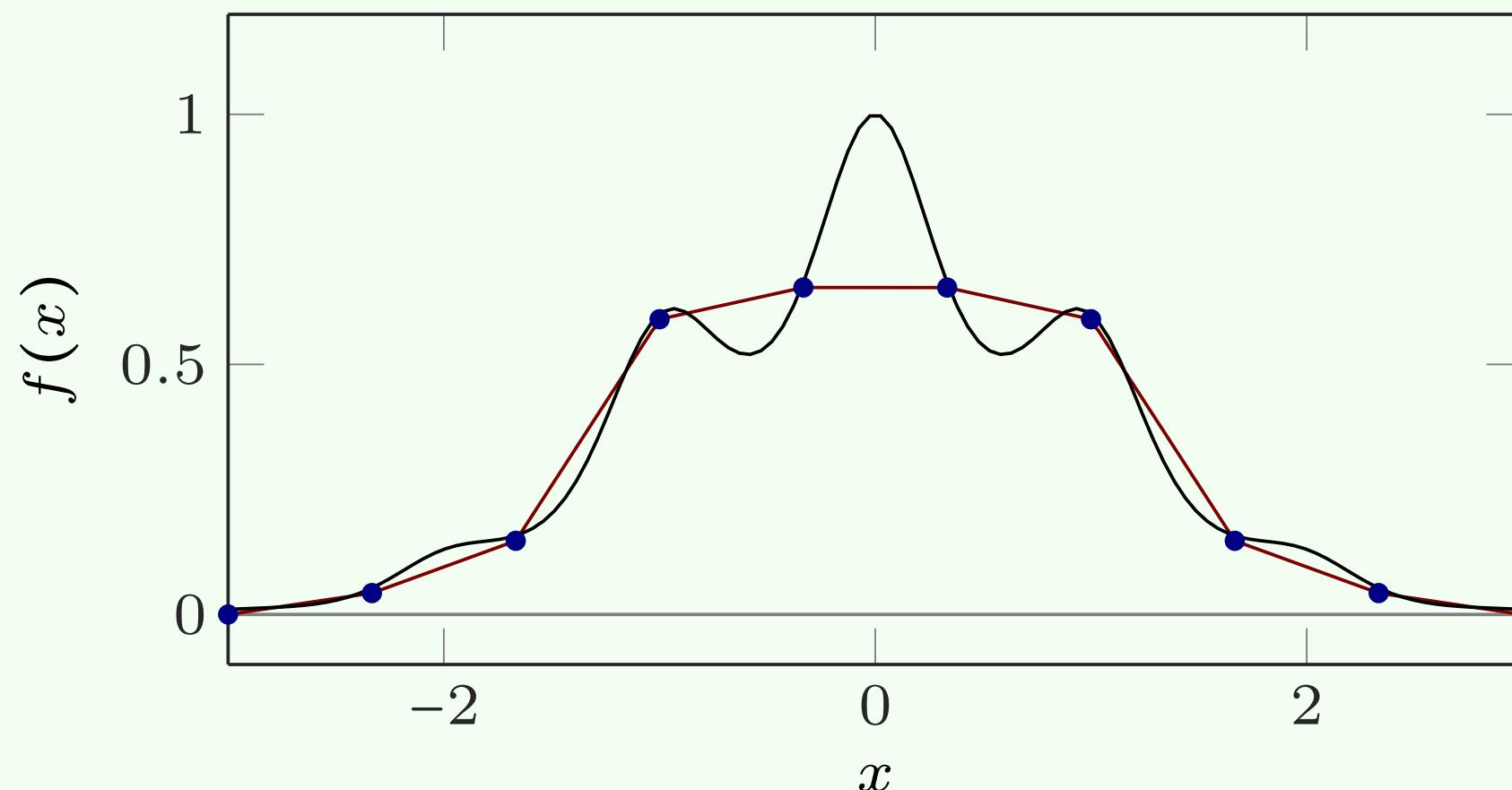
**The answer to a  
numeric problem can  
only be approximated,**

e.g.

$$F = \int_{-3}^3 f(x) dx$$

for

$$f(x) = \exp\left(-(\sin(3x))^2 - x^2\right).$$



Machine learning treats  
algorithms as agents.

Probabilistic numerics treats  
numeric algorithms as agents.

```
9 import numpy as np
10 import platform
11 import subprocess
12 import nlopt
13 from sklearn.utils import check_random_state
14 from scipy.stats import beta, norm
15
16
17 class RobotArm:
18     def __init__(self):
19         self.name = 'RobotArm Simulator'
20         self.state = np.array([0, 0])
21
22     def abs_pos(self, jt_angle):
23         assert jt_angle.ndim == 1, 'jt_angle has to be one dimensional'
24         assert len(jt_angle) == 3, 'jt_angle has to have 3 inputs'
25
26         if platform.system() == 'Darwin':
27             args = str('./robot_arm ' + str(jt_angle[0]) + ' ' + str(jt_angle[1]) + ' ' + str(jt_angle[2]))
28             proc = subprocess.Popen(args, shell=True, stdout=subprocess.PIPE)
29         elif platform.system() == 'Windows':
30             args = str('robot_arm.exe ' + str(jt_angle[0]) + ' ' + str(jt_angle[1]) + ' ' + str(jt_angle[2]))
31             proc = subprocess.Popen(args, stdout=subprocess.PIPE)
32
33         output = proc.stdout
34         for line in output:
35             output = line
36         proc.kill()
37
38         return np.array([float(out) for out in output.split()])
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```

# As motivation:

1. numeric **error** is significant;
2. numeric methods are **generic**;
3. our numerics problems **tax**  
**our computation.**



An agent receives data, predicts, & then makes decisions.

# In integration:

**data** = ? ;  
**predictand** = ?; &  
**decisions** = ?.

The graph shows a function  $f(x)$  plotted against  $x$ . A grey line represents the predictand, which is a smooth curve. Blue dots represent the data points, which are discrete points on the curve. Red question marks are placed above the data points and between them, symbolizing uncertainty or missing information. The x-axis has tick marks at 0, 2, and 1. The y-axis has tick marks at 0, 0.5, and 1.

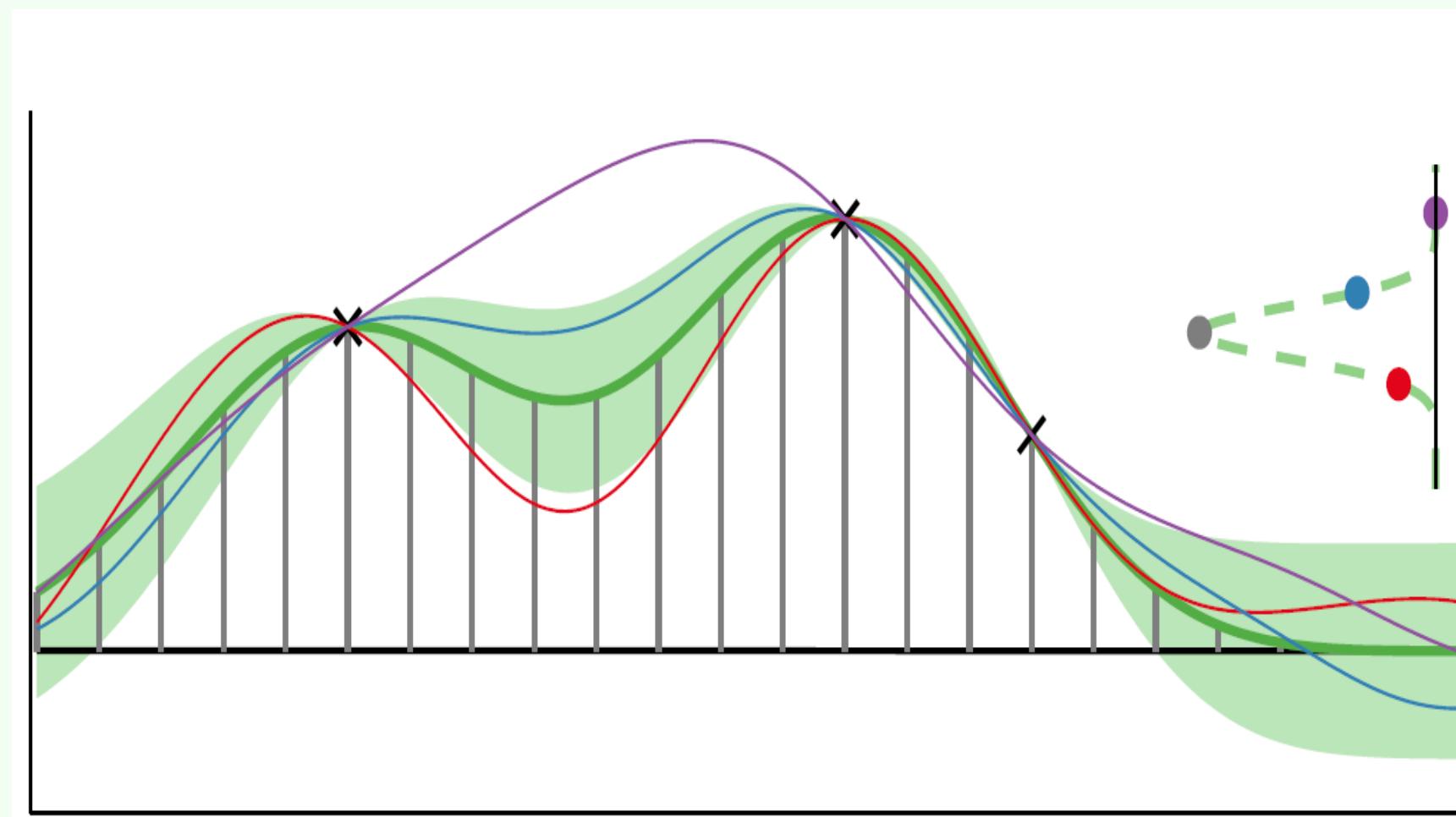
# In integration:

**data = evaluations;**  
**predictand = integral; &**  
**decisions = locations.**

$f(x)$

$x$

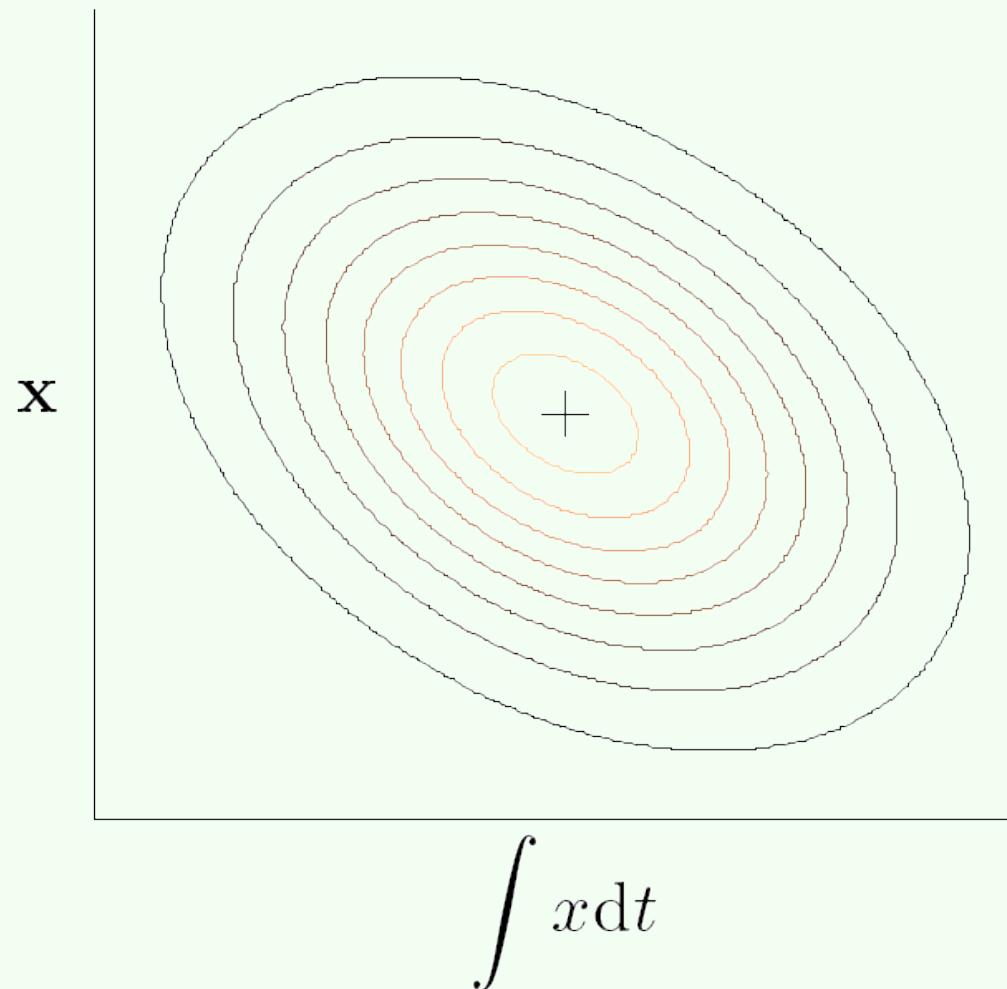
**Bayesian  
quadrature is  
probabilistic  
numerics for  
integration.**

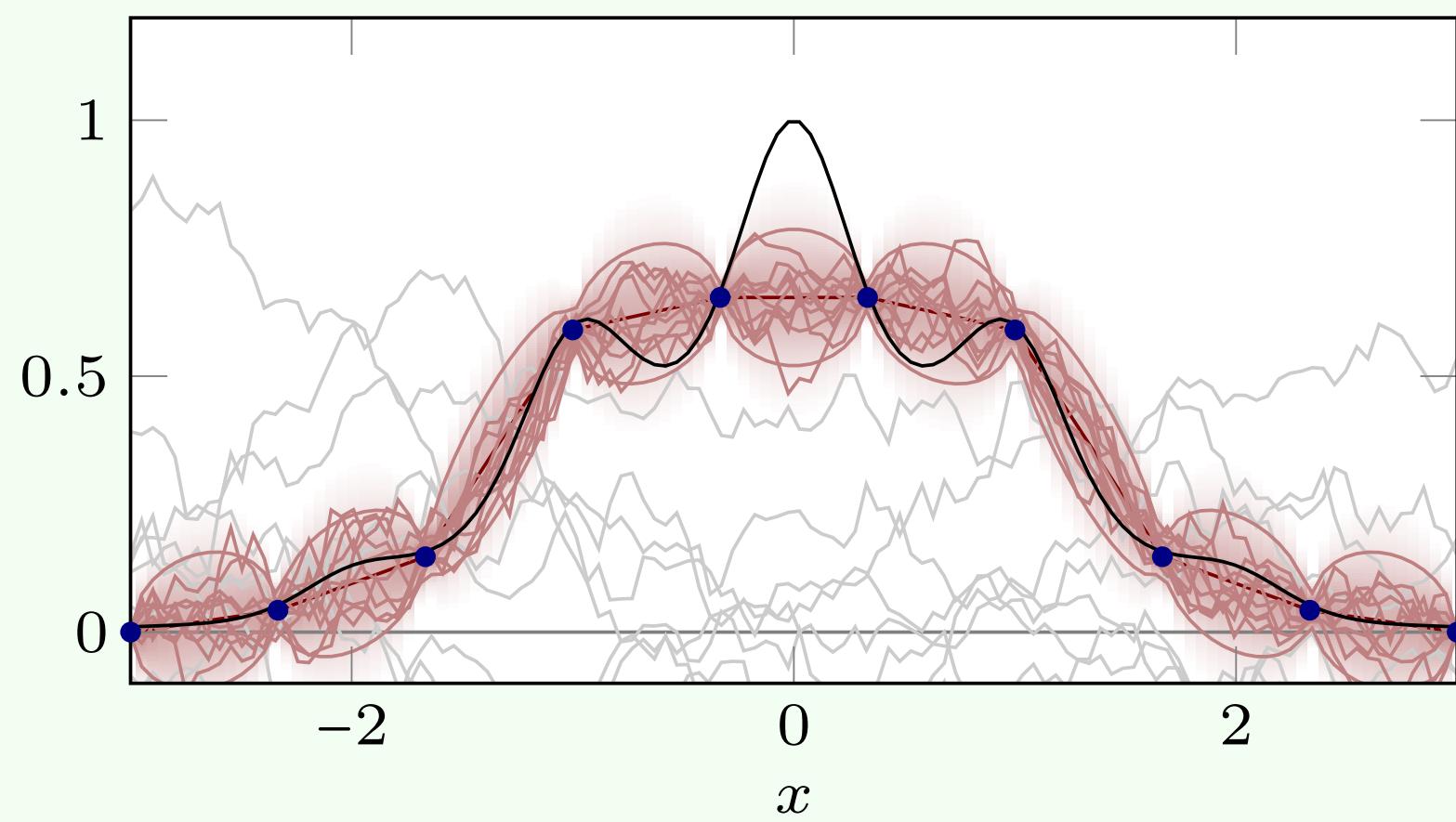
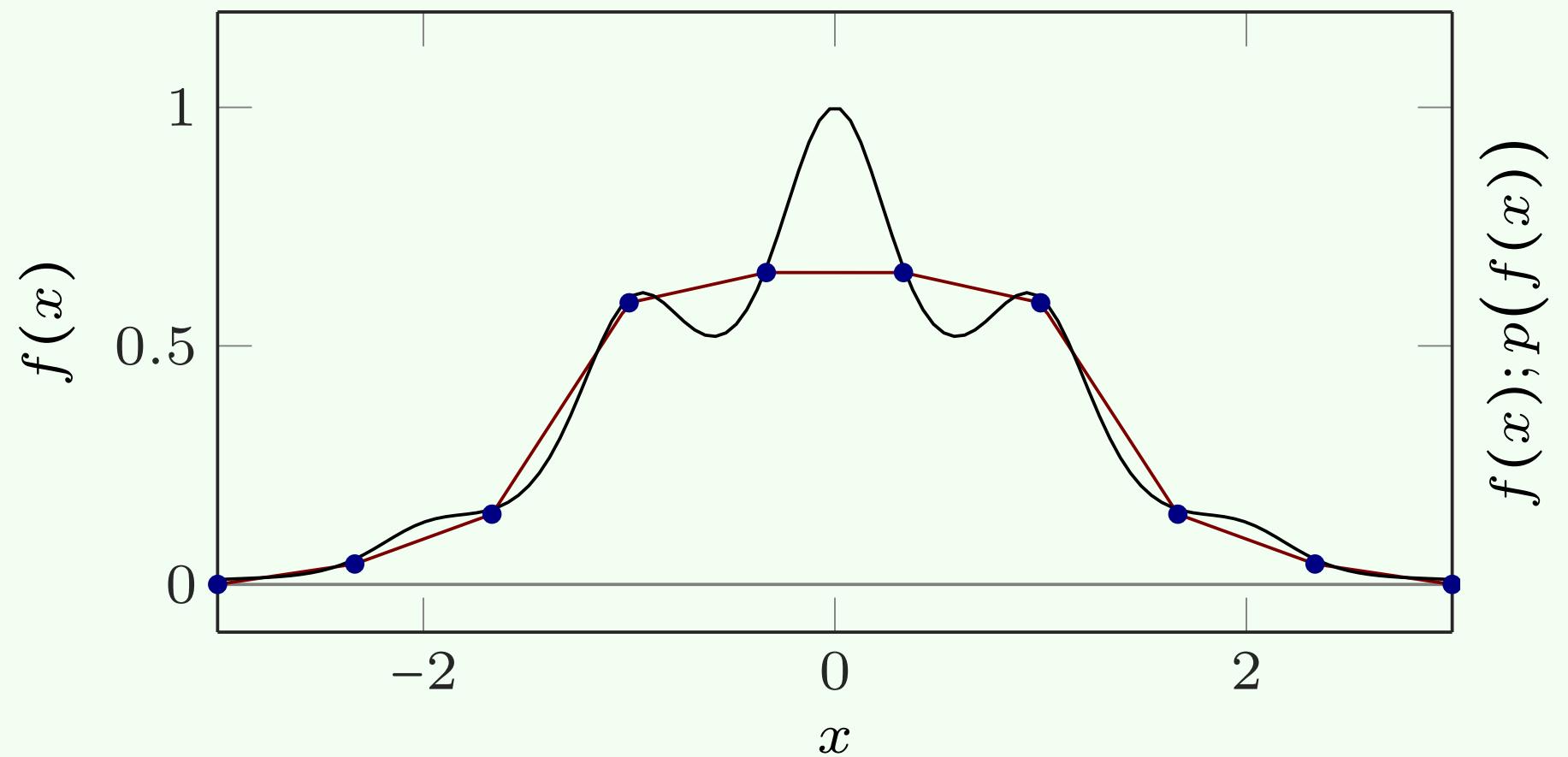




An agent is defined by  
its prior and  
loss function.

**With a Gaussian process prior for the integrand, the integral is joint Gaussian.**





The trapezoidal rule is the posterior mean estimate for the integral

$$F = \int_a^b f(x) dx$$

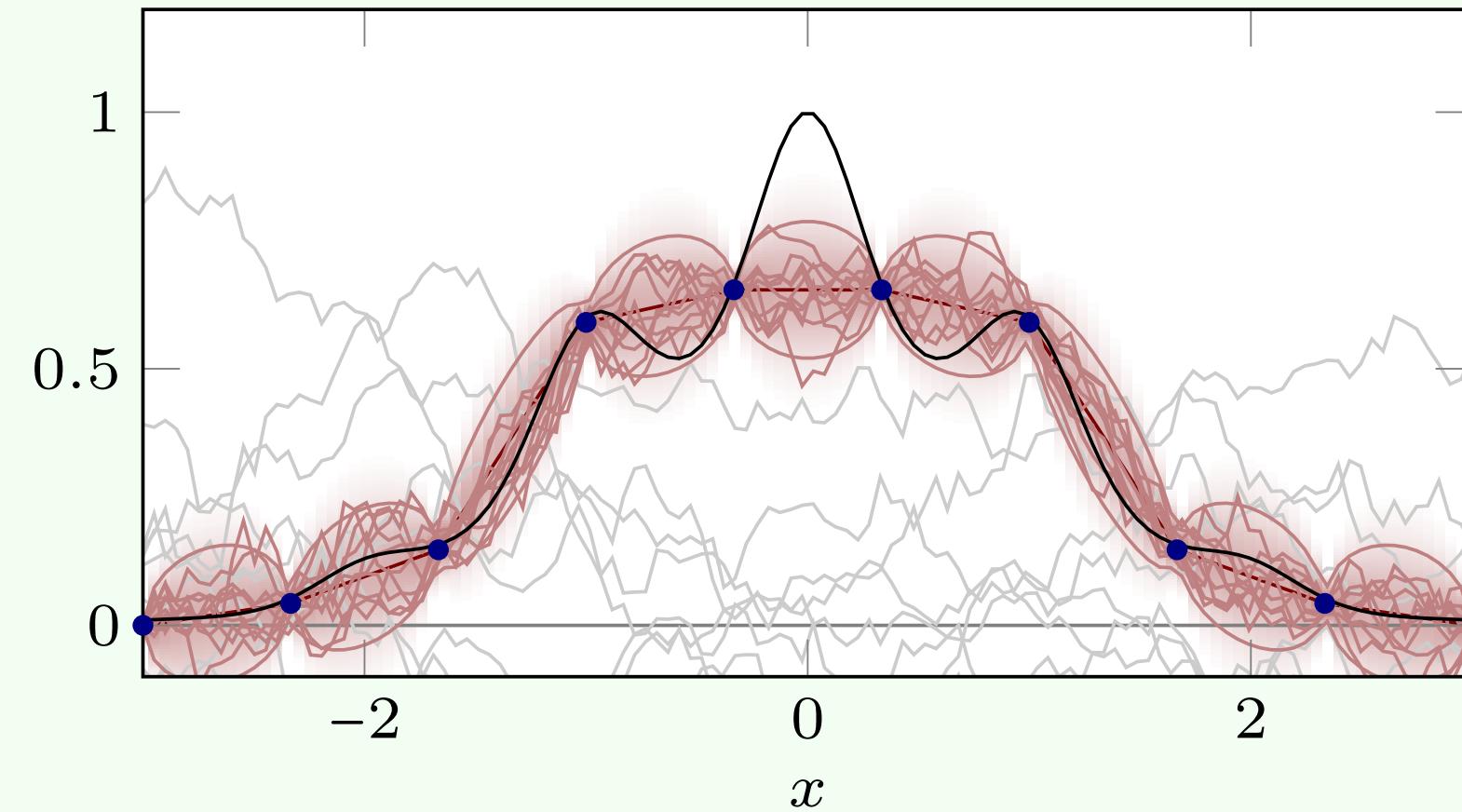
under any centered Wiener process prior

$$p(f) = \mathcal{GP}(f; 0, k)$$

with

$$k(x, x') = \theta^2 (\min(x, x') - \chi)$$

for arbitrary  $\theta \in \Re_+$  and  $\chi < a \in \Re$ .



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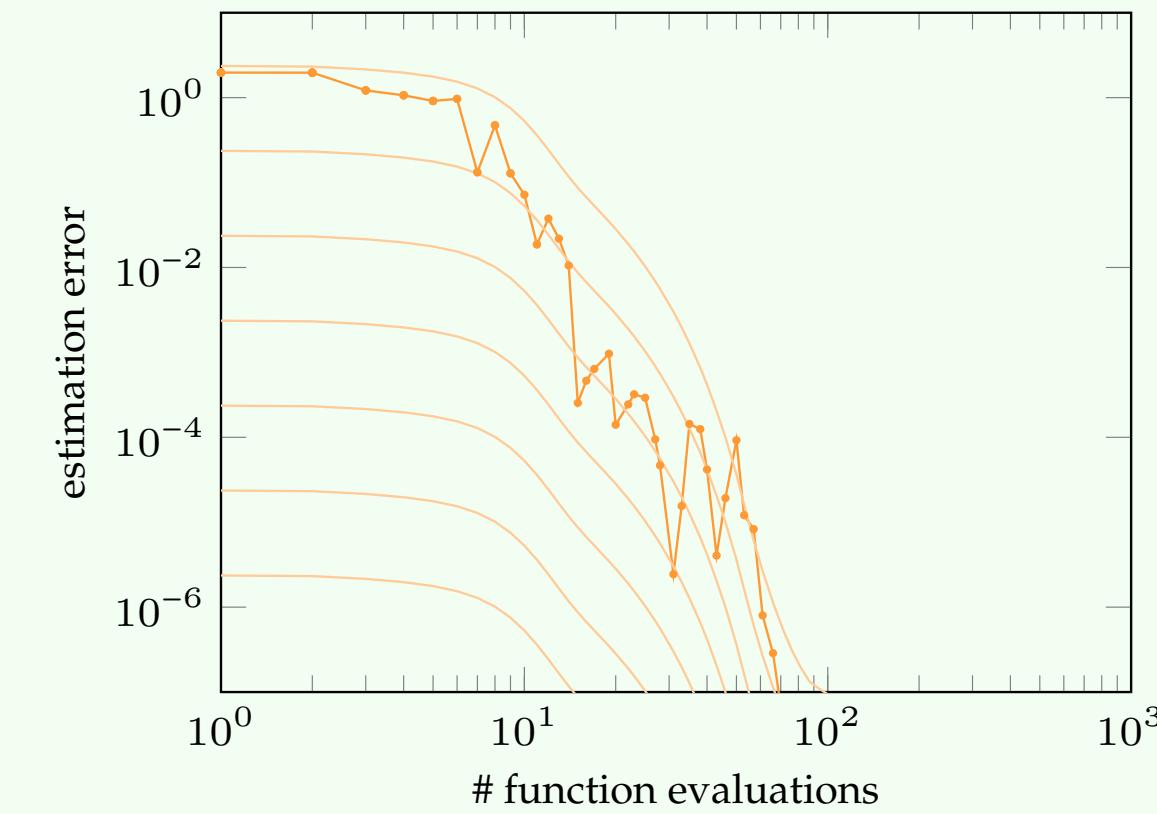
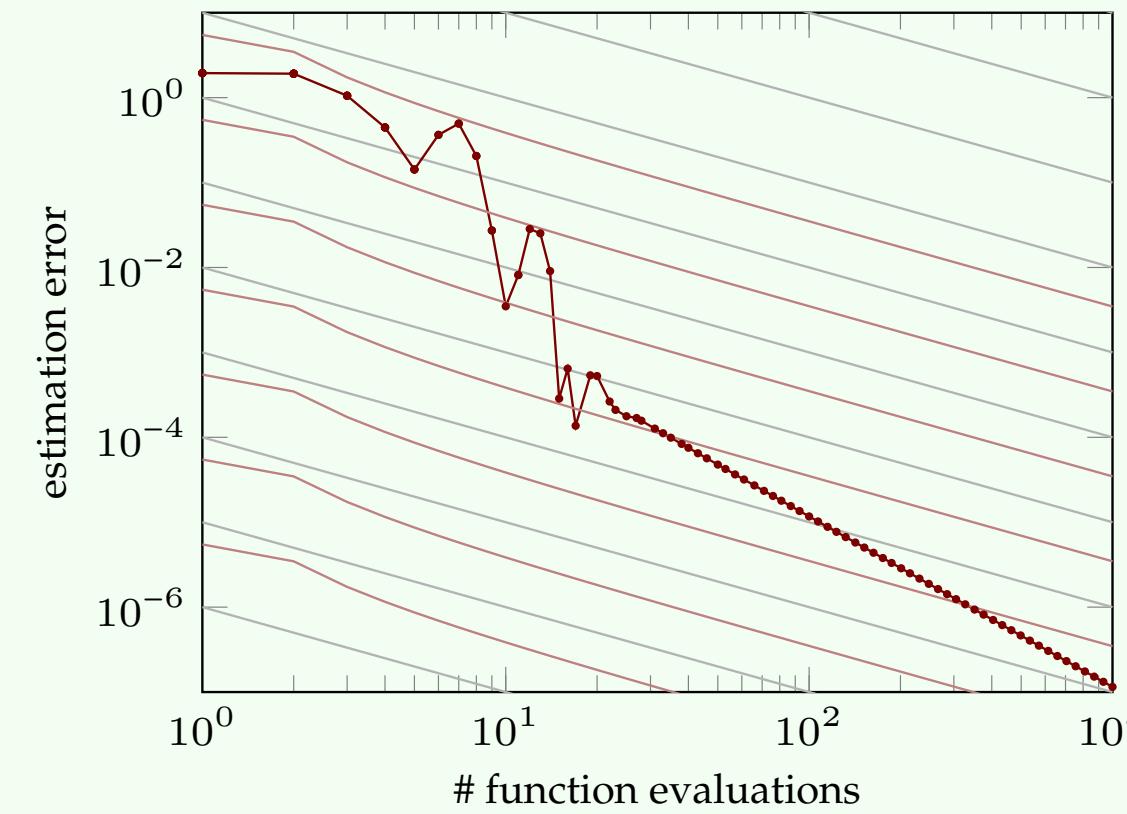
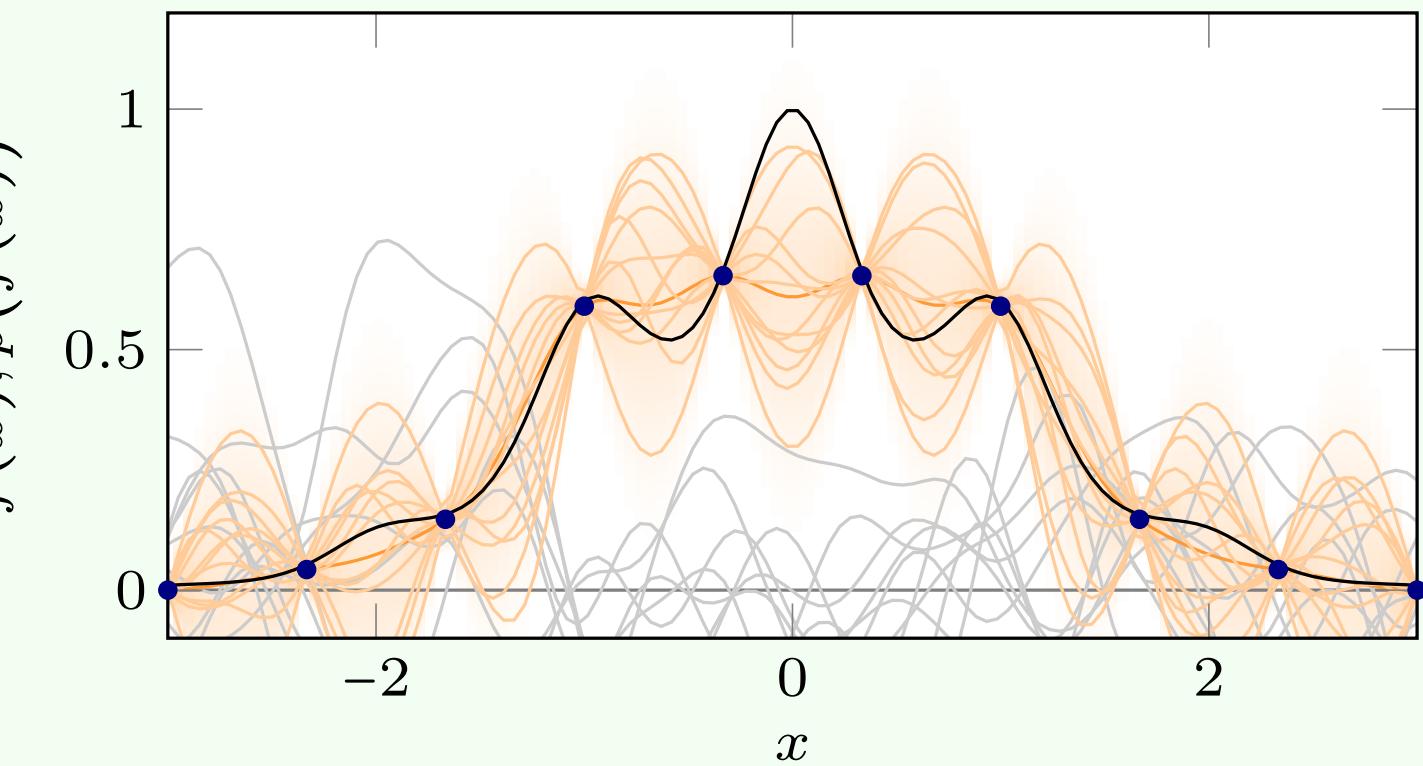
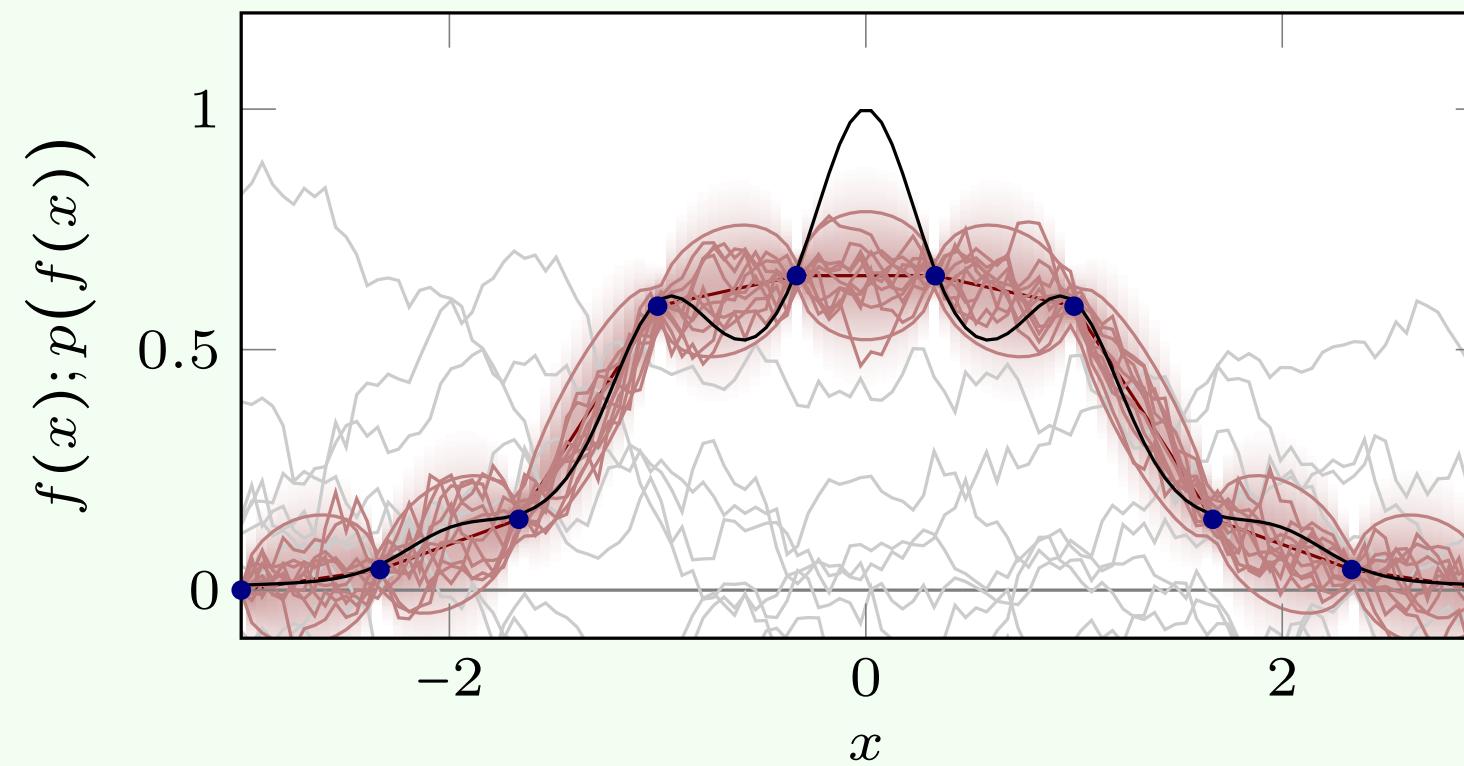
```
1 procedure INTEGRATE(@ $f$ ,  $a$ ,  $b$ ,  $N$ ,  $\theta$ )
2    $\delta := (b - a)/(N - 1)$                                      // choose step size
3    $x \leftarrow a, y_1 = f(a), m \leftarrow 0, v \leftarrow 0,$            // initialise
4   for  $i = 2, \dots, N$  do
5      $x \leftarrow x + \delta$                                          // step
6      $y_i \leftarrow f(x)$                                            // evaluate
7      $m \leftarrow m + \delta/2(y_{i-1} + y_i)$                          // update estimate
8      $v \leftarrow v + \delta^3/12$                                        // update error estimate
9   end for
10  return  $\mathbb{E}(F) = m, \text{var}(F) = \theta^2 v$                    // probabilistic output
11 end procedure
```

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```
1 procedure INTEGRATE(@ $f$ ,  $a$ ,  $b$ ,  $N$ ,  $\theta$ )
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6      $y_i \leftarrow f(x)$                                       // evaluate
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8      $v \leftarrow v + \delta^3/12$                                 // update error estimate
9   end for
10  return  $\mathbb{E}(F) = m, \text{var}(F) = \theta^2 v$            // probabilistic output
11 end procedure
```

The trapezoid rule is Bayesian quadrature.



# Quiz: The convergence rate of the trapezoid rule is $\mathcal{O}(N^{-1})$ : what is the rate of Monte Carlo?

1.  $\mathcal{O}(\exp(-N))$
2.  $\mathcal{O}\left(\exp\left(-N^{-\frac{1}{2}}\right)\right)$
3.  $\mathcal{O}(N^{-1})$
4.  $\mathcal{O}(N^{-\frac{1}{2}})$

# Quiz: The convergence rate of the trapezoid rule is $\mathcal{O}(N^{-1})$ : what is the rate of Monte Carlo?

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2.  $\mathcal{O}\left(\exp\left(-N^{-\frac{1}{2}}\right)\right)$
3.  $\mathcal{O}(N^{-1})$
4.  $\mathcal{O}(N^{-\frac{1}{2}})$  - **arguably the worst possible rate.**

# Monte Carlo **is also** Bayesian quadrature.

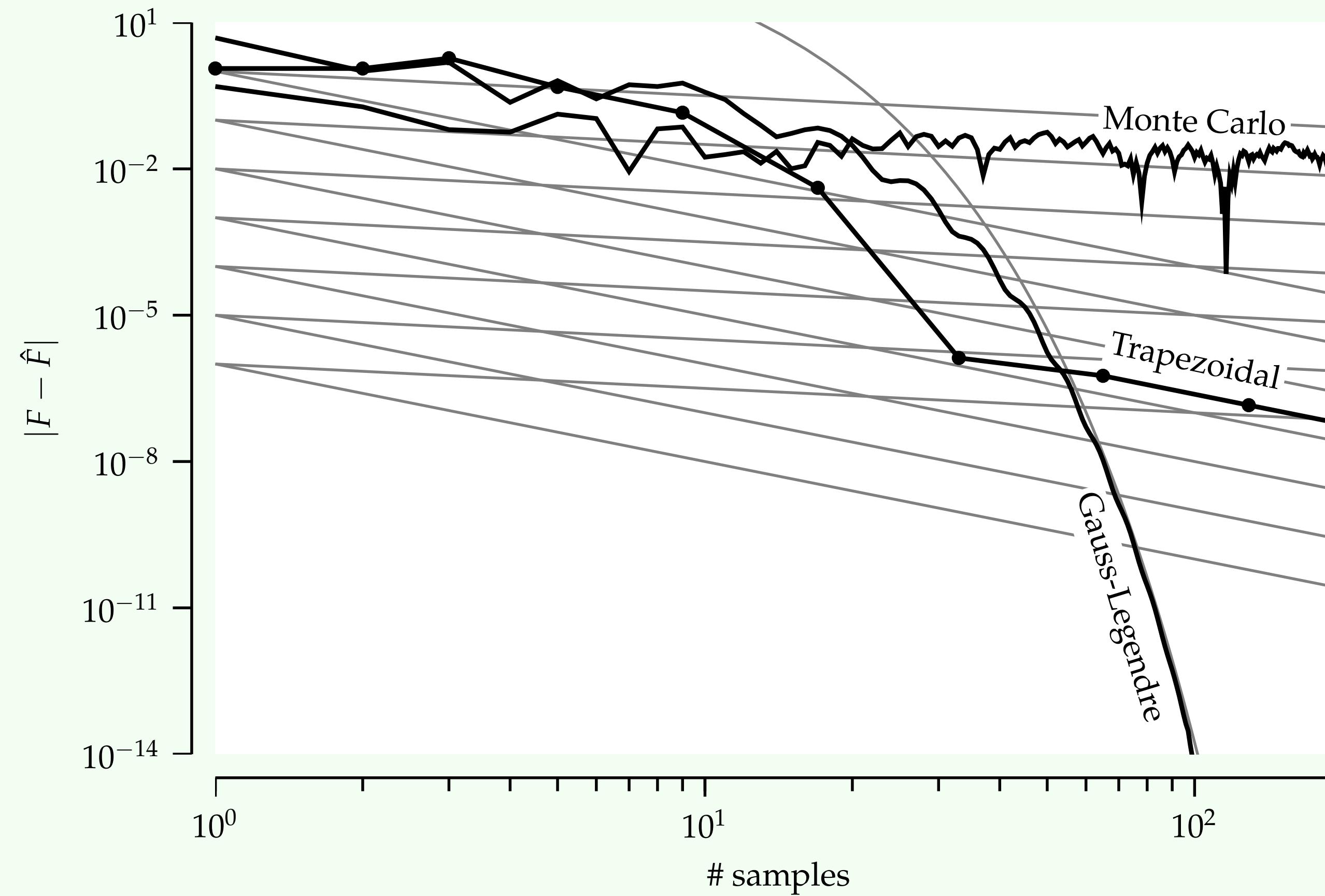
The Monte Carlo estimate

$$\int f(x) p(x) dx \simeq \frac{1}{N} \sum_{i=1}^N f(x_i)$$

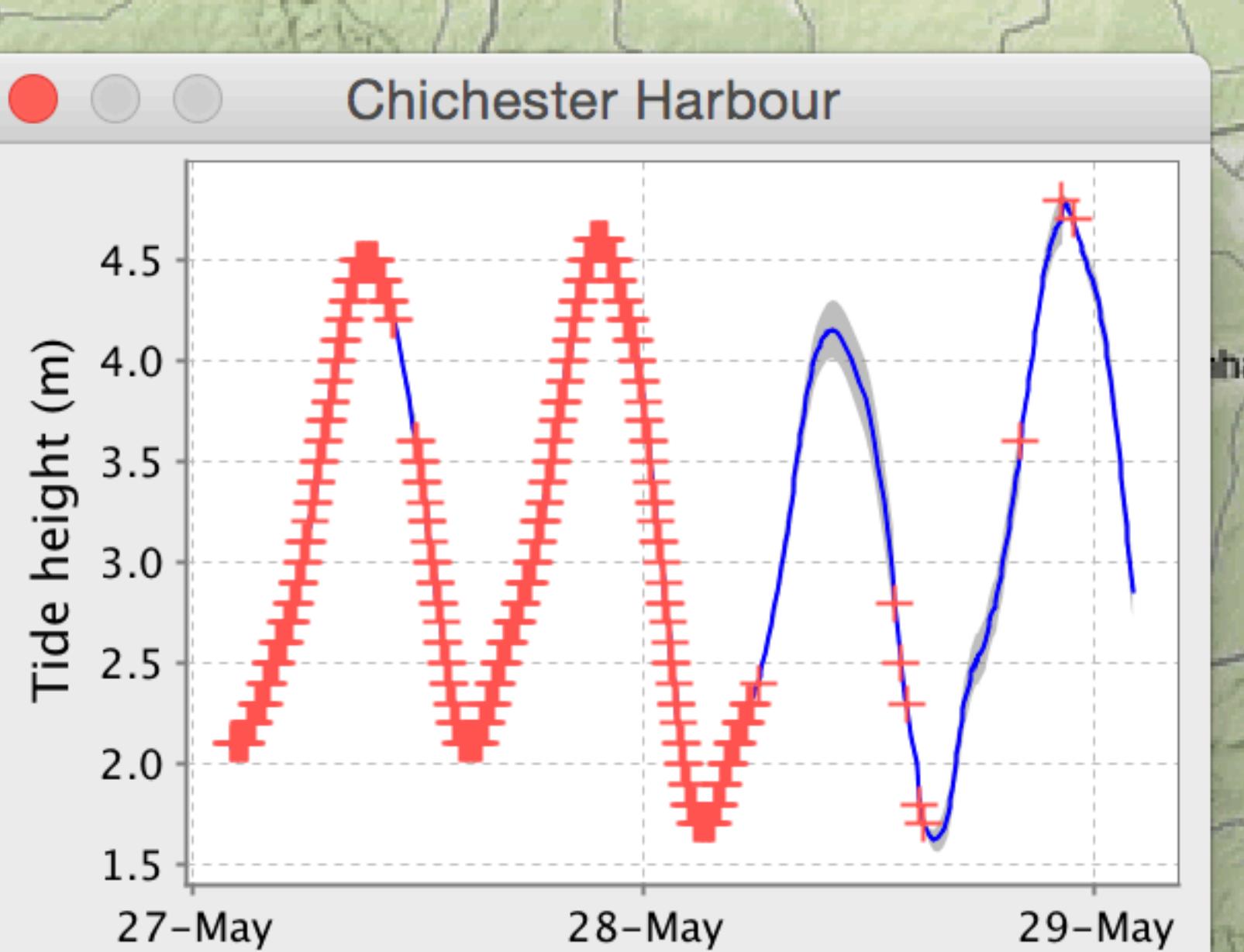
is maximum a-posteriori under the (improper) prior

$$p(f) = \lim_{c \rightarrow 0} \mathcal{GP}(0, \theta^2 \mathbb{I}(x = x') + c^{-1})$$

for  $\mathbb{I}$  the indicator function and with arbitrary  $\theta \in \Re_+$ . The corresponding posterior standard deviation estimate on the integral,  $\theta(b - a)/\sqrt{N}$ , matches the convergence rate of the Monte Carlo estimator.

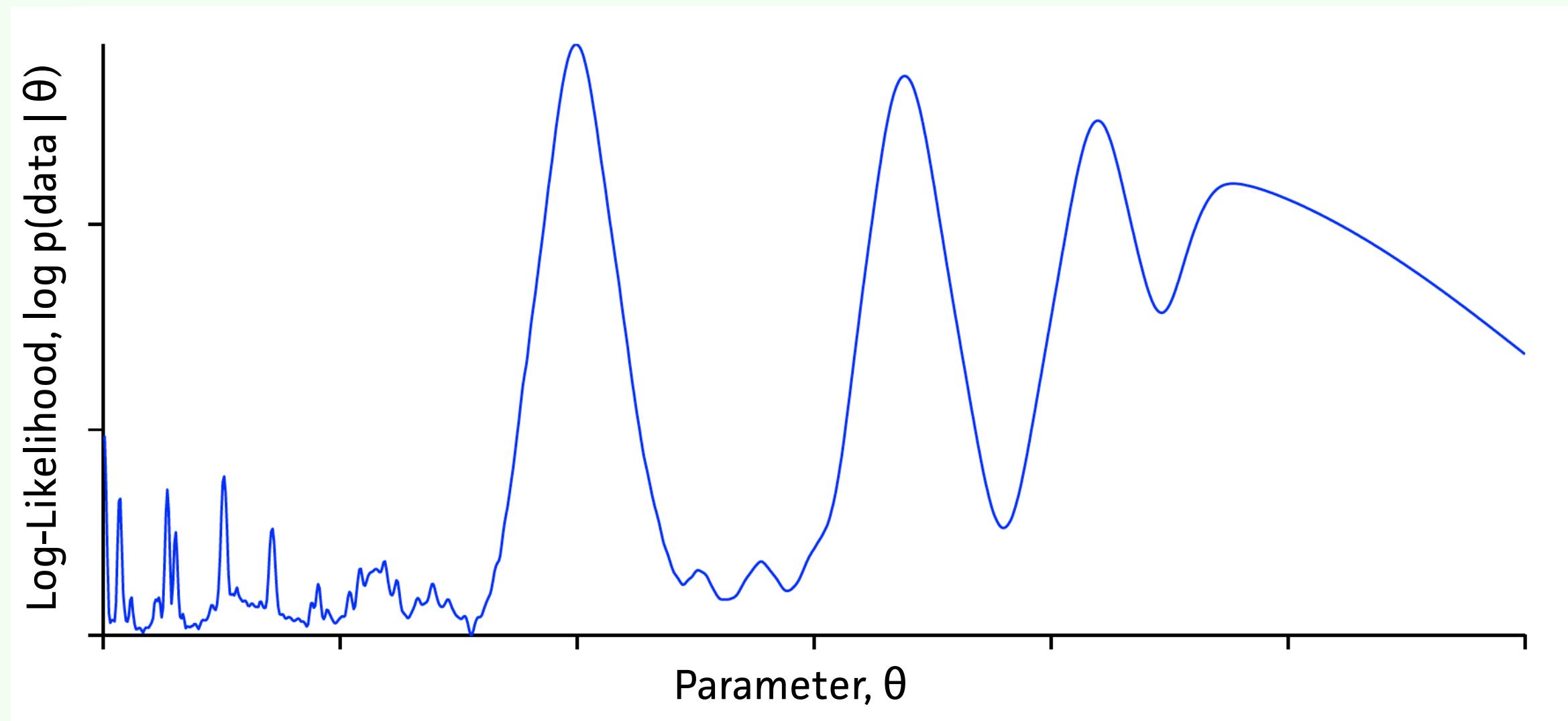


**Quadrature is  
often required to  
manage model  
parameters.**



**Managing parameters**  $\theta$  requires the **model evidence**,

$$p(\text{data}) = \int p(\text{data} \mid \theta) p(\theta) d\theta.$$

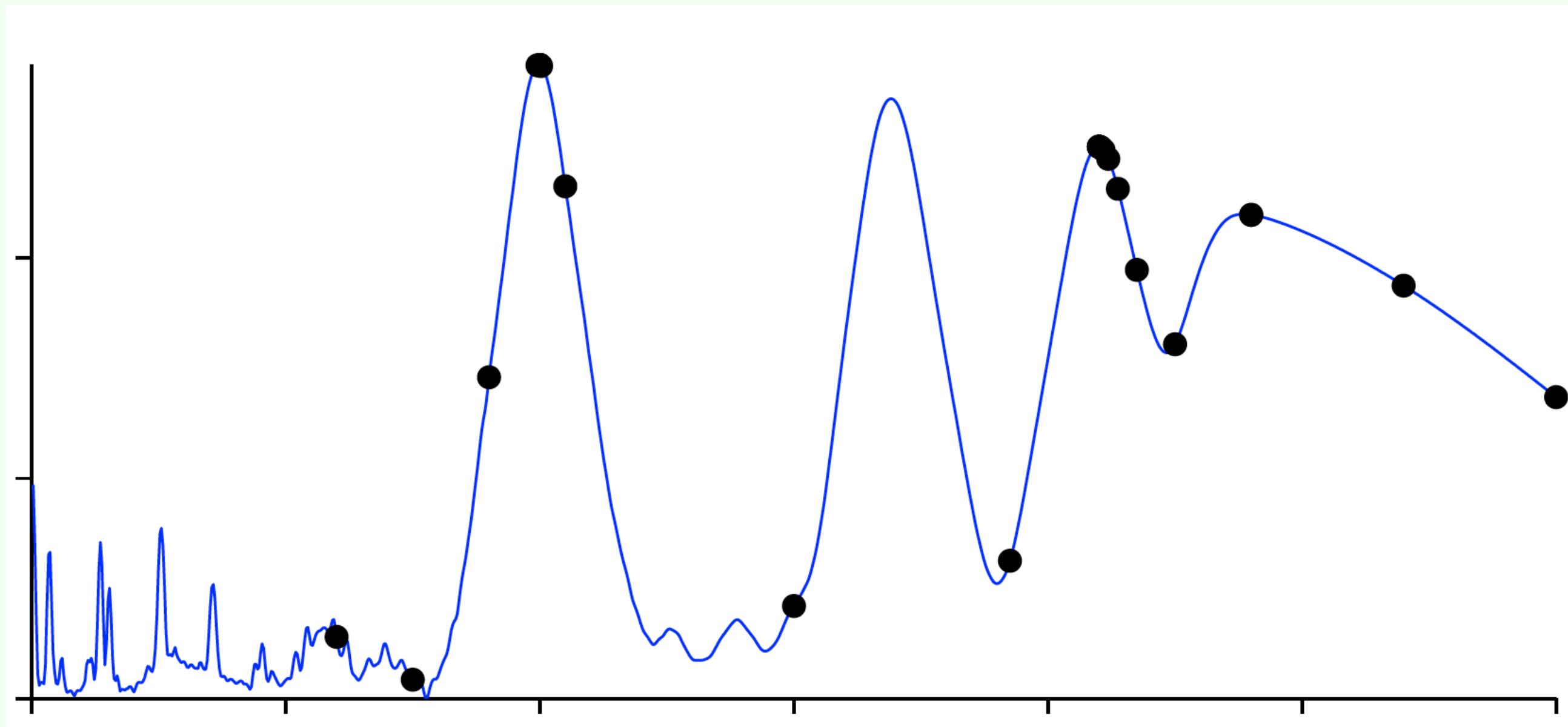


QUADRATURE

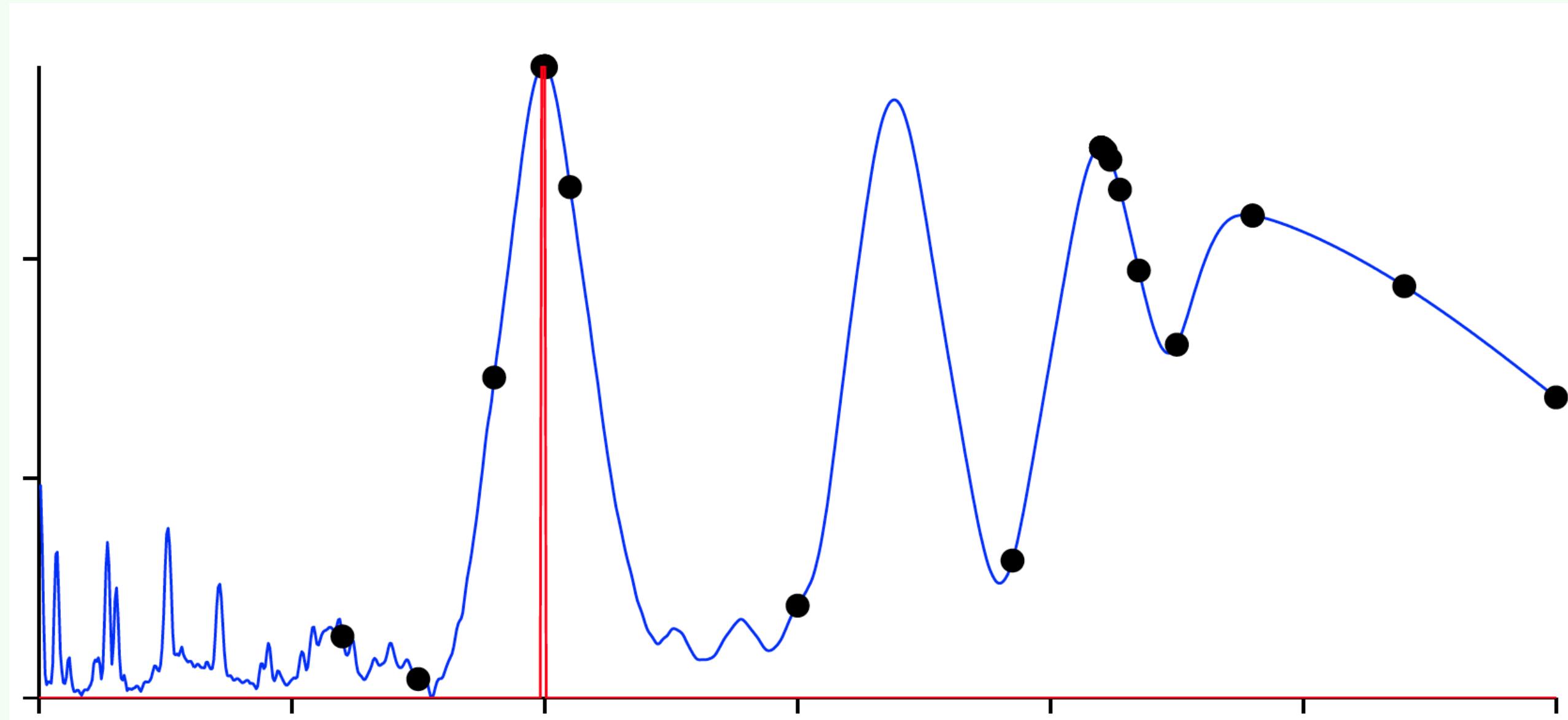
IS HARD.

Parameter,  $\theta$

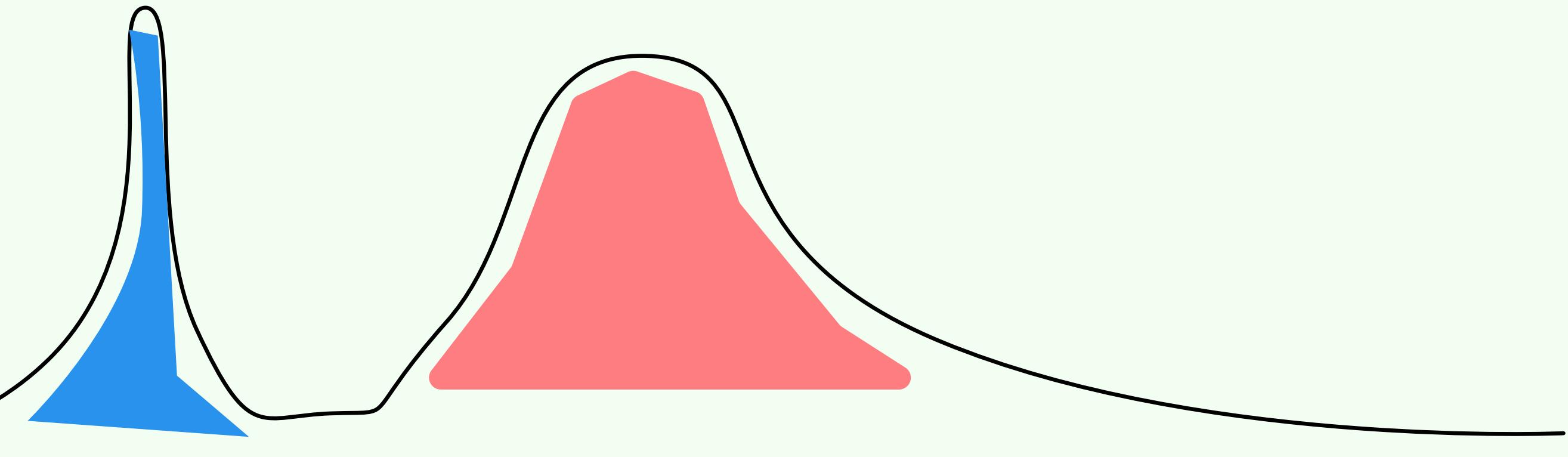
**Optimisation** (maximum likelihood, training) is often used in the place of quadrature.



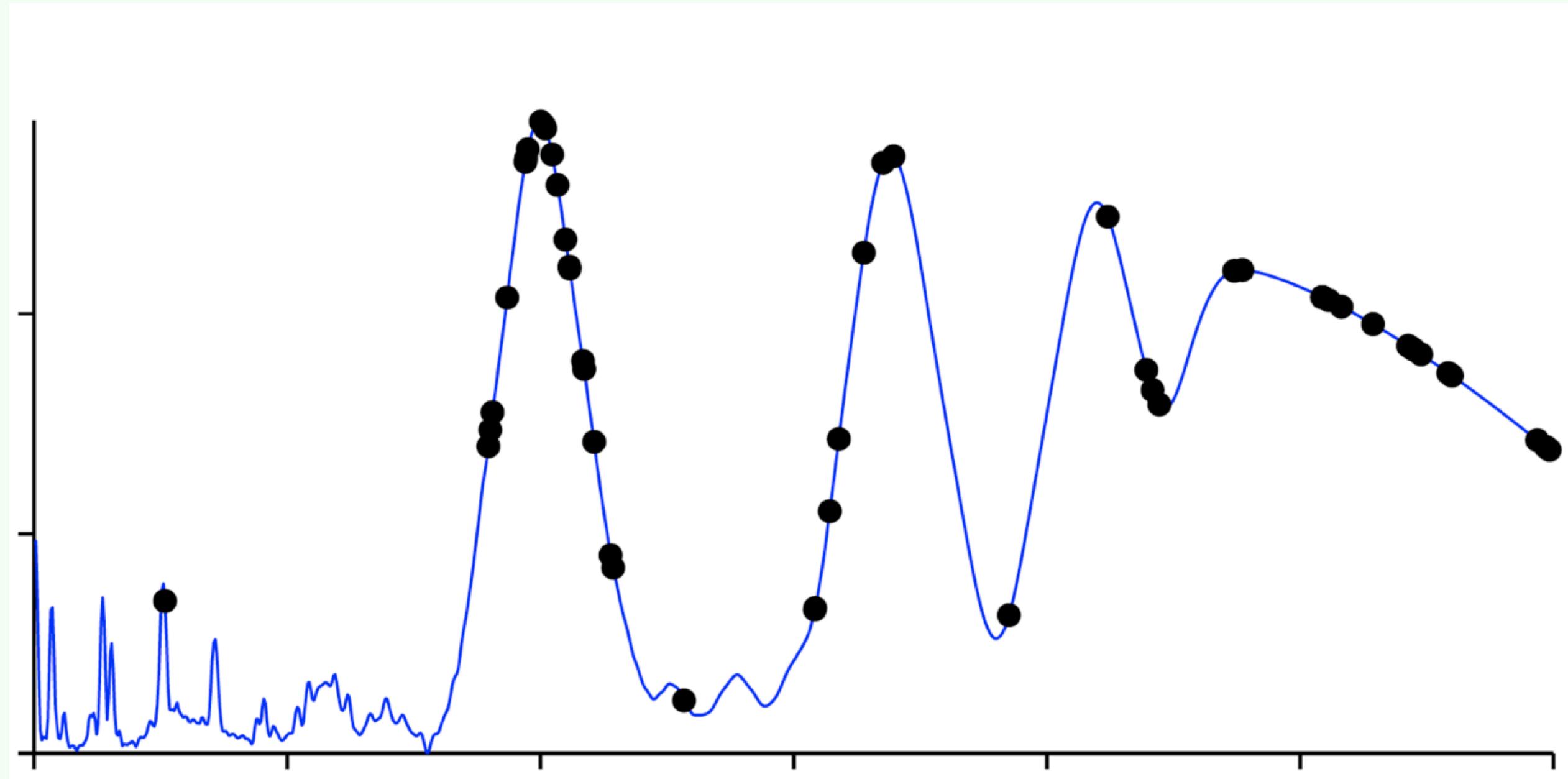
This approximates as  $p(\text{data}) \simeq \int p(\text{data} \mid \theta) \delta(\theta - \theta_{\max}) \, d\theta$ .



If optimising, **flat optima** are often a better representation of the integral than **narrow optima**.

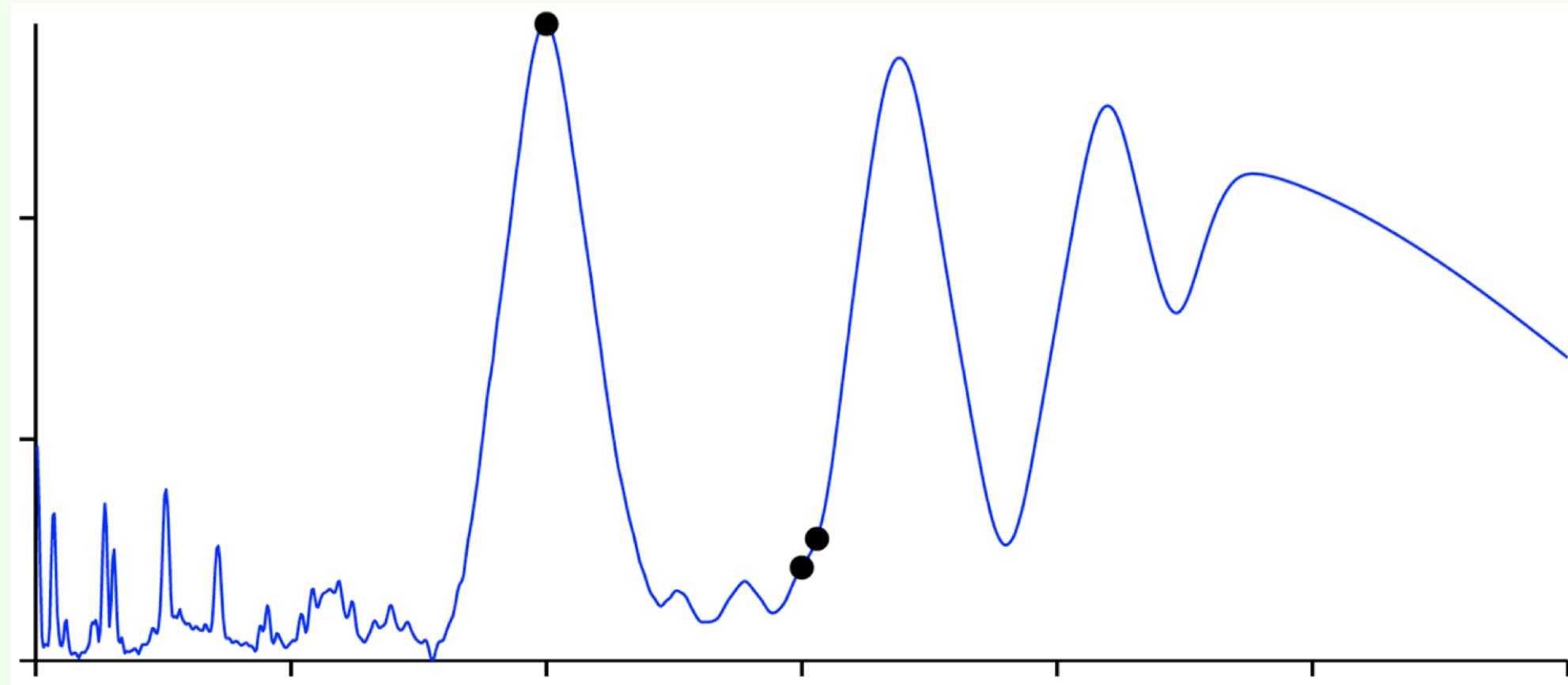


**Monte Carlo** has revolutionised Bayesian inference.

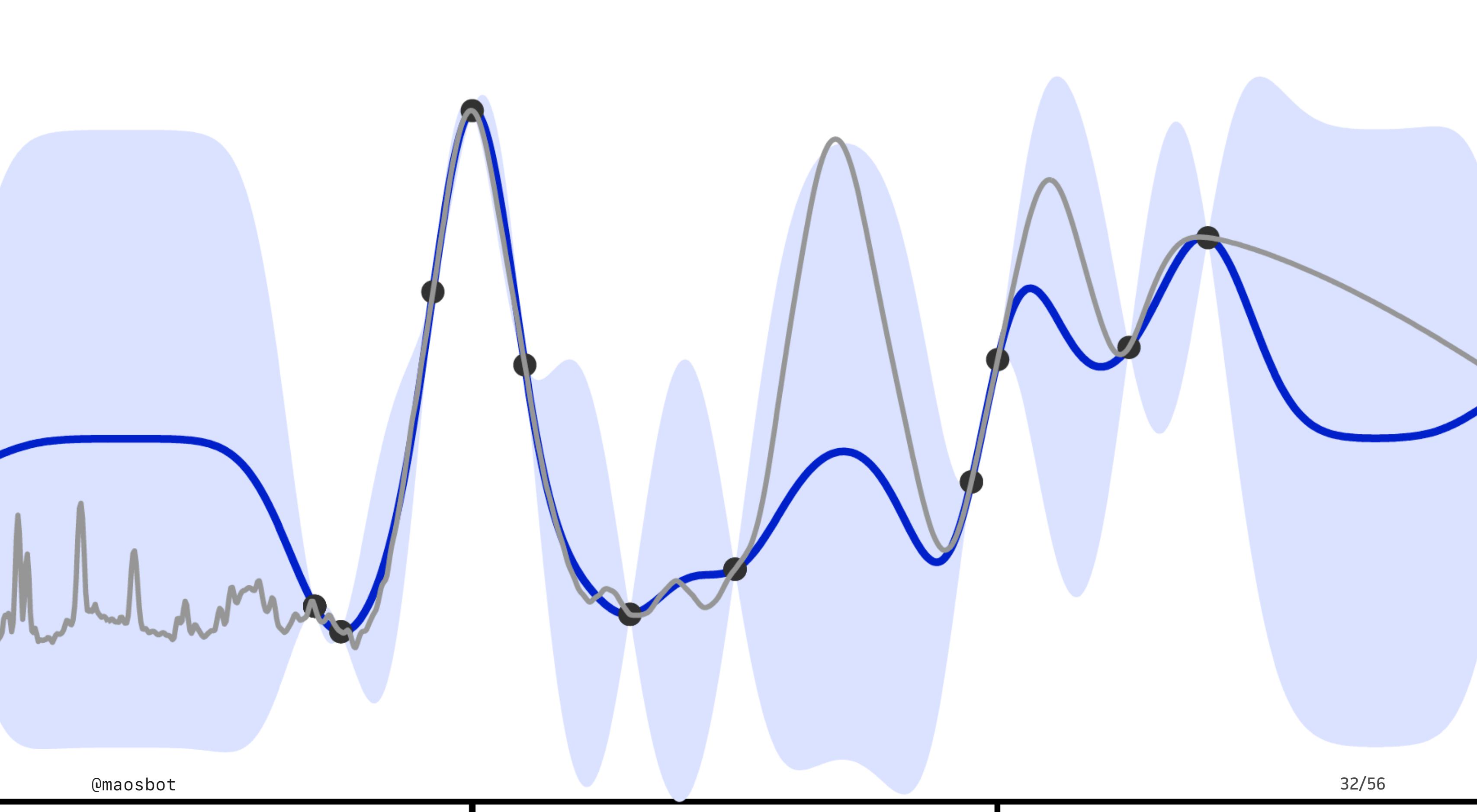


Monte Carlo estimators,  $\int f(x) p(x) dx \simeq \frac{1}{N} \sum_{i=1}^N f(x_i)$ ,

**ignore relevant information.**



O'Hagan, A. (1987). Monte Carlo is Fundamentally Unsound. *Journal of the Royal Statistical Society. Series D (The Statistician)*.



```
ea = params[0]
wa = params[2:3]
secw, sesw = np.sqrt(ea)*np.cos(wa), np.sqrt(ea)*np.sin(wa)
```

We often have **relevant prior knowledge**: like the problem's **source code**.

```
bx, by = af.baseline_m(df.time, pv_base, df.px, df.py, nthr)
px, py = af.am_model_em(df.time, np.r_[pv_base, pv_1, pv_2], 2, 1)
mx, my = 1e6*(bx+px), 1e6*(by+py)
```

```
ea = params[0]
```

```
wa = params[2:3]
```

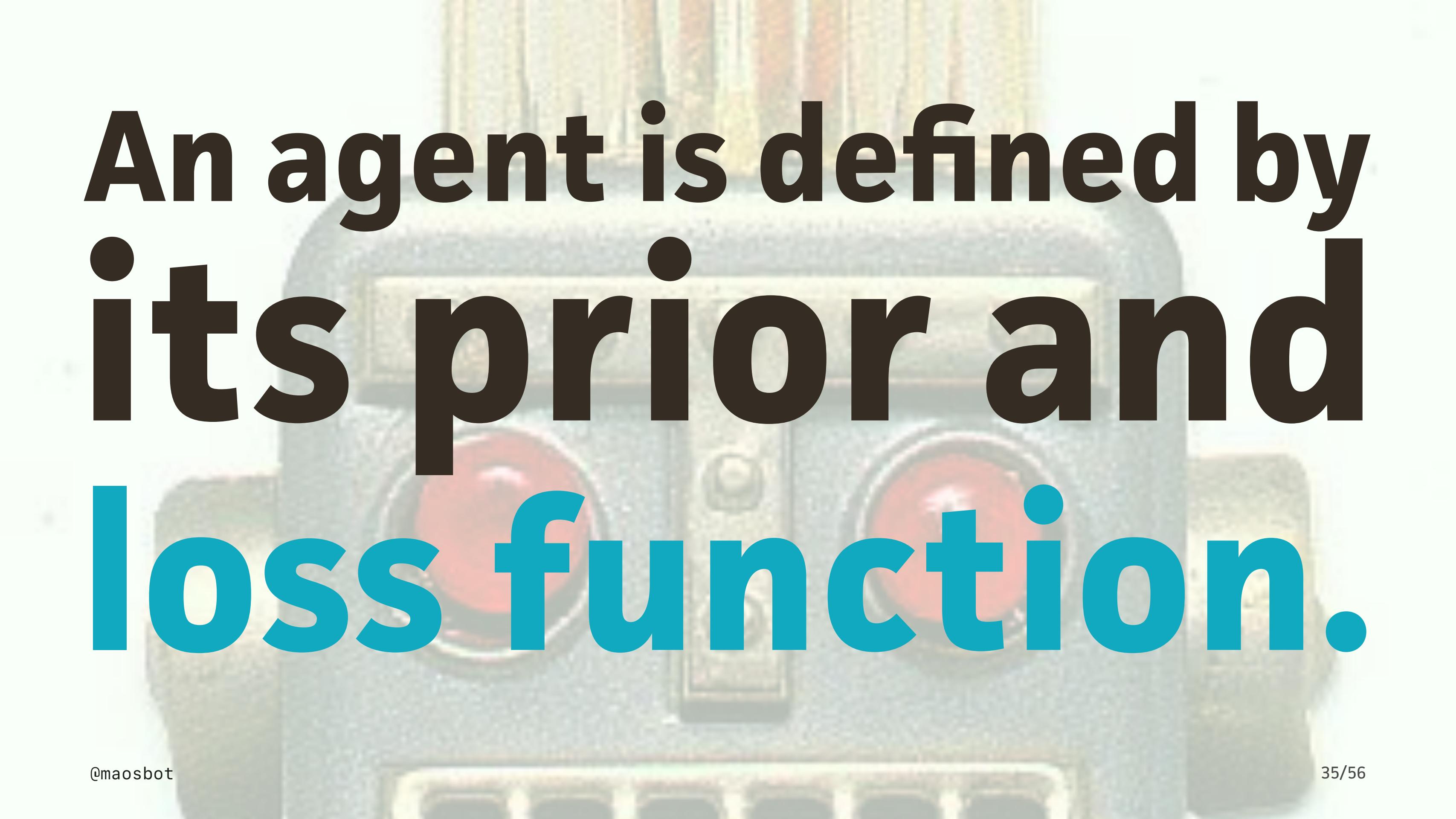
```
secw, sesw = np.sqrt(ea)*np.cos(wa), np.sqrt(ea)*np.sin(wa)
```

The perfect prior  
is intractable.

```
bx, by = af.baseline_m(df.time, pv_base, df.px, df.py, nthr)
```

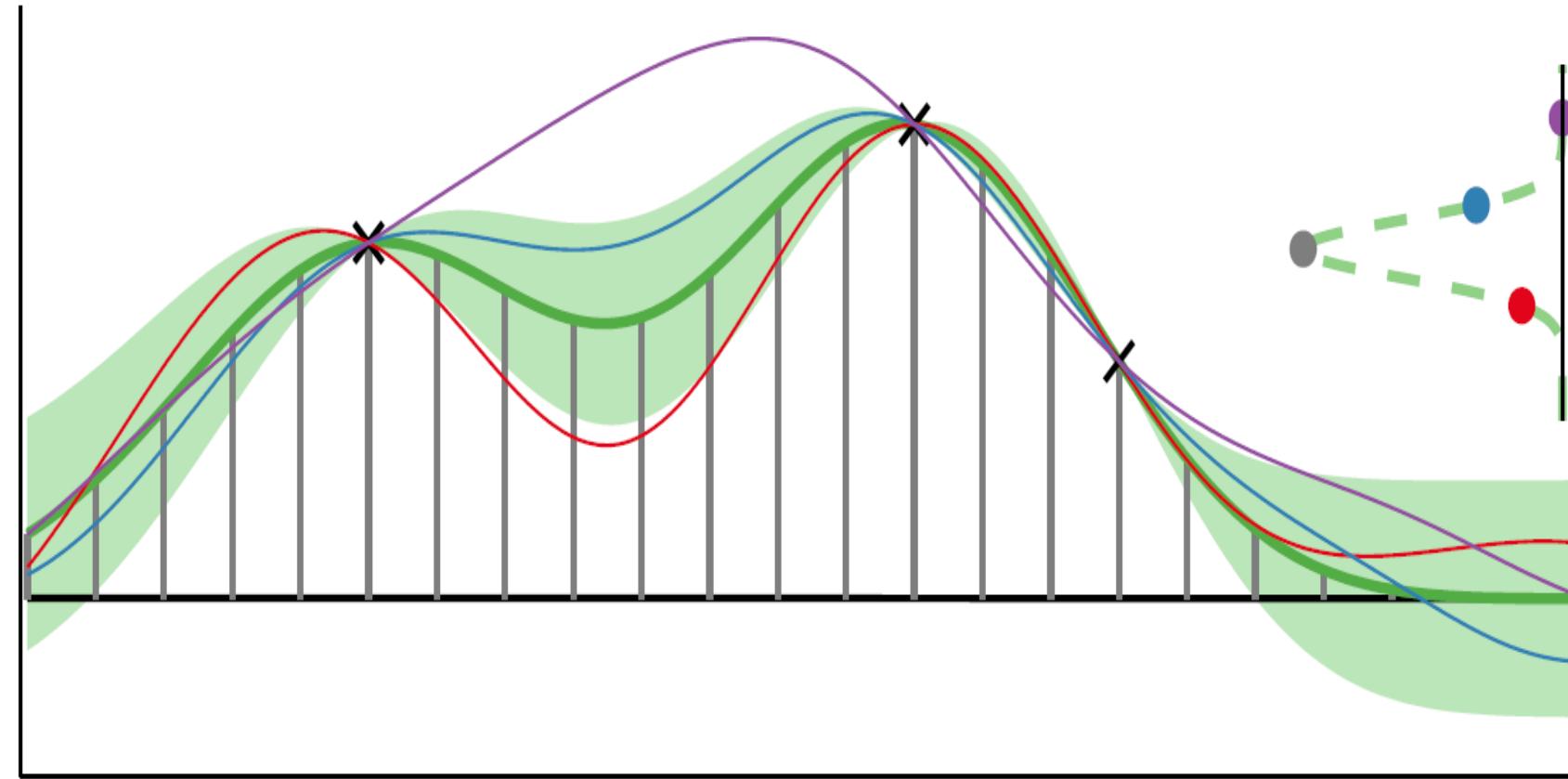
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```

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```

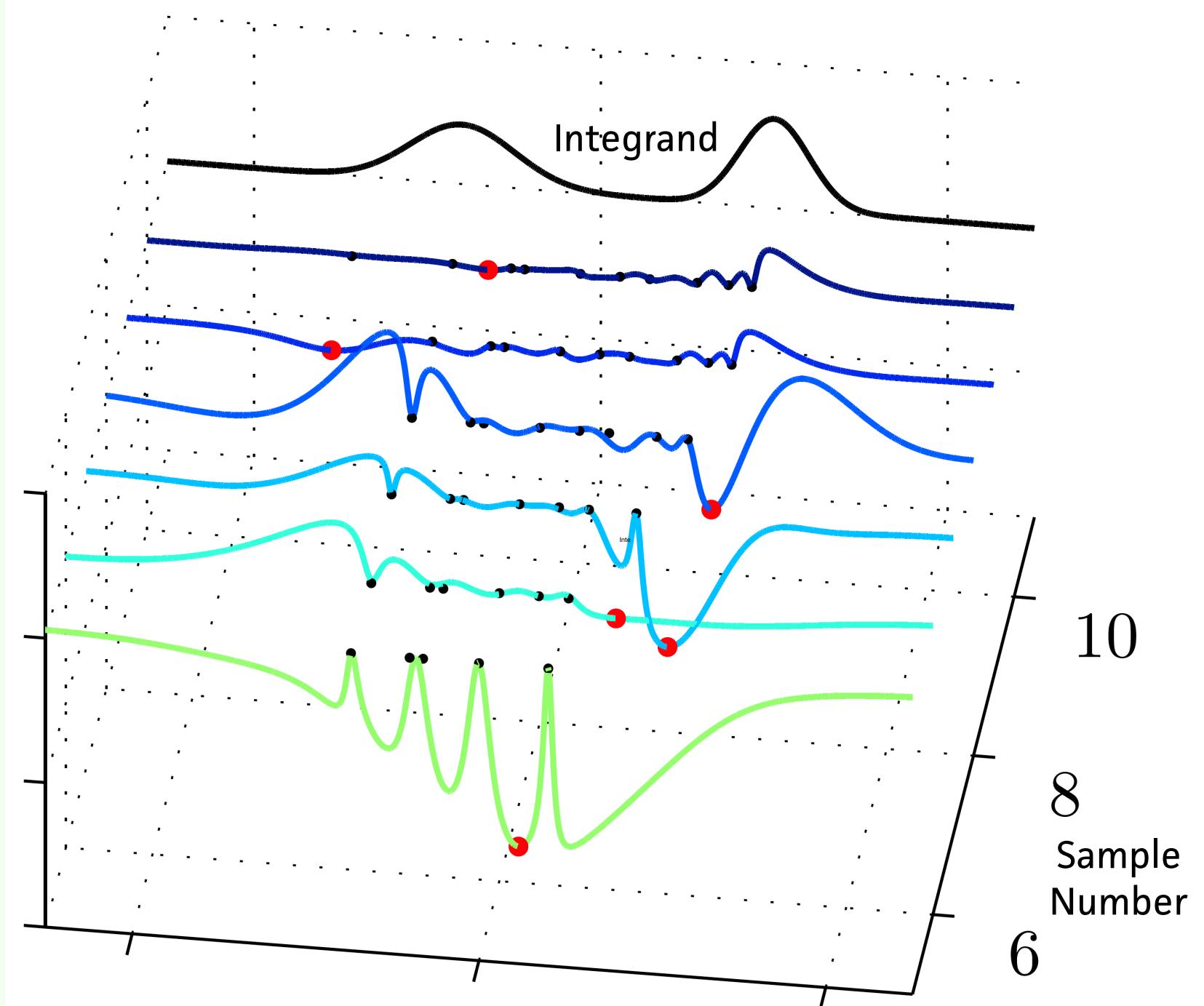


An agent is defined by  
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loss function.

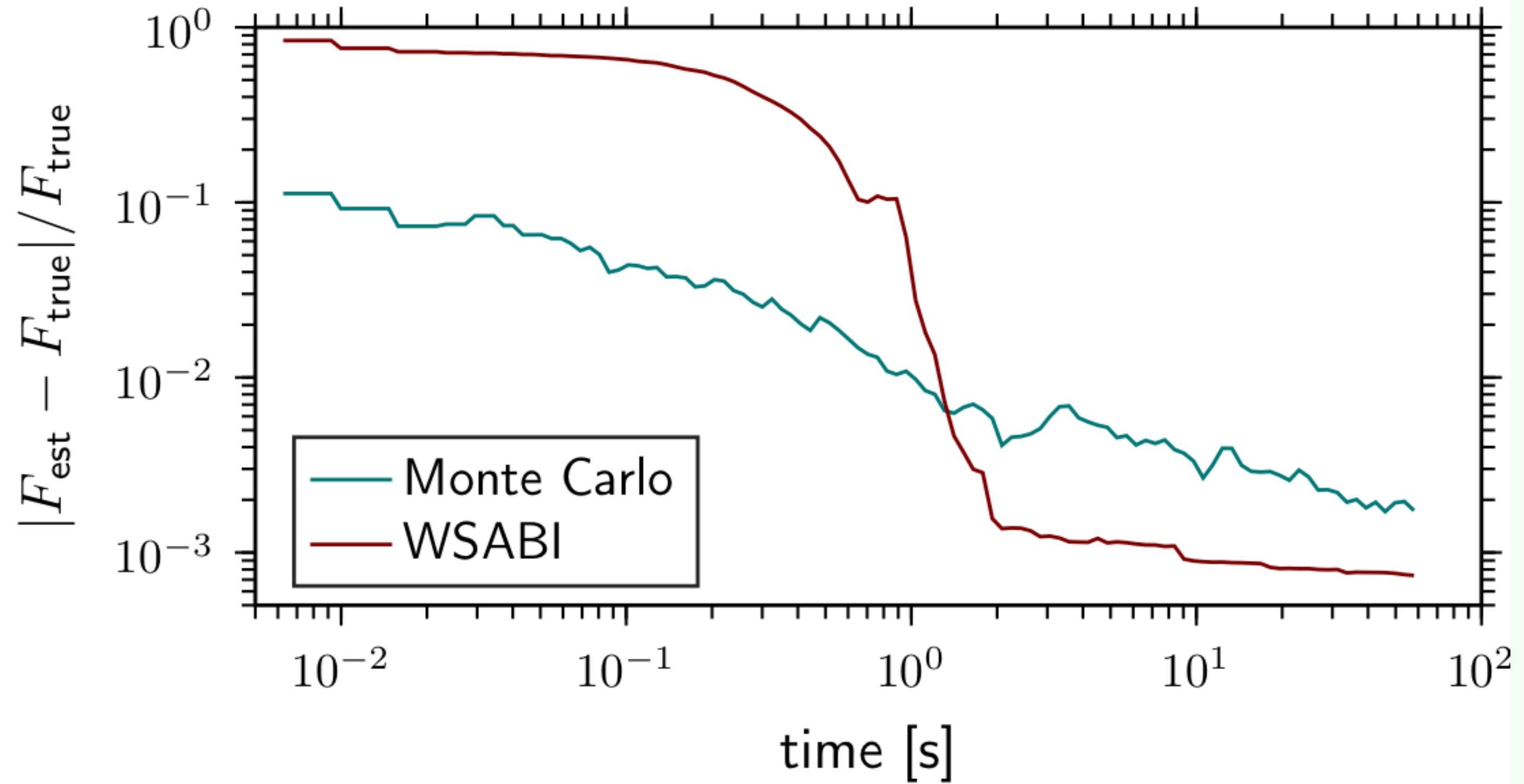
A natural loss  
function for  
quadrature is the  
uncertainty in  
the integral.



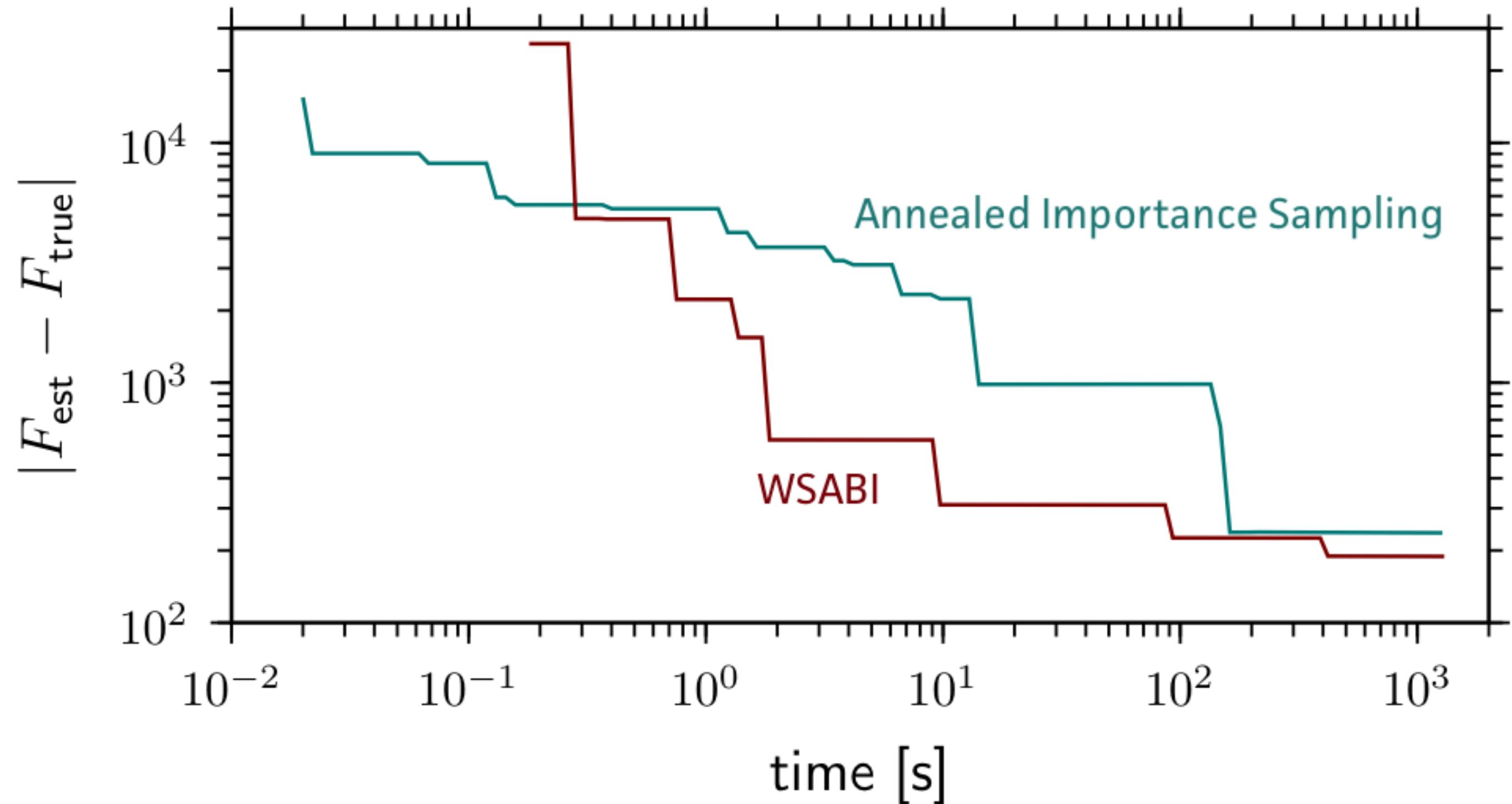
**WSABI** uses a loss  
that is the  
**uncertainty in**  
**the integrand.**



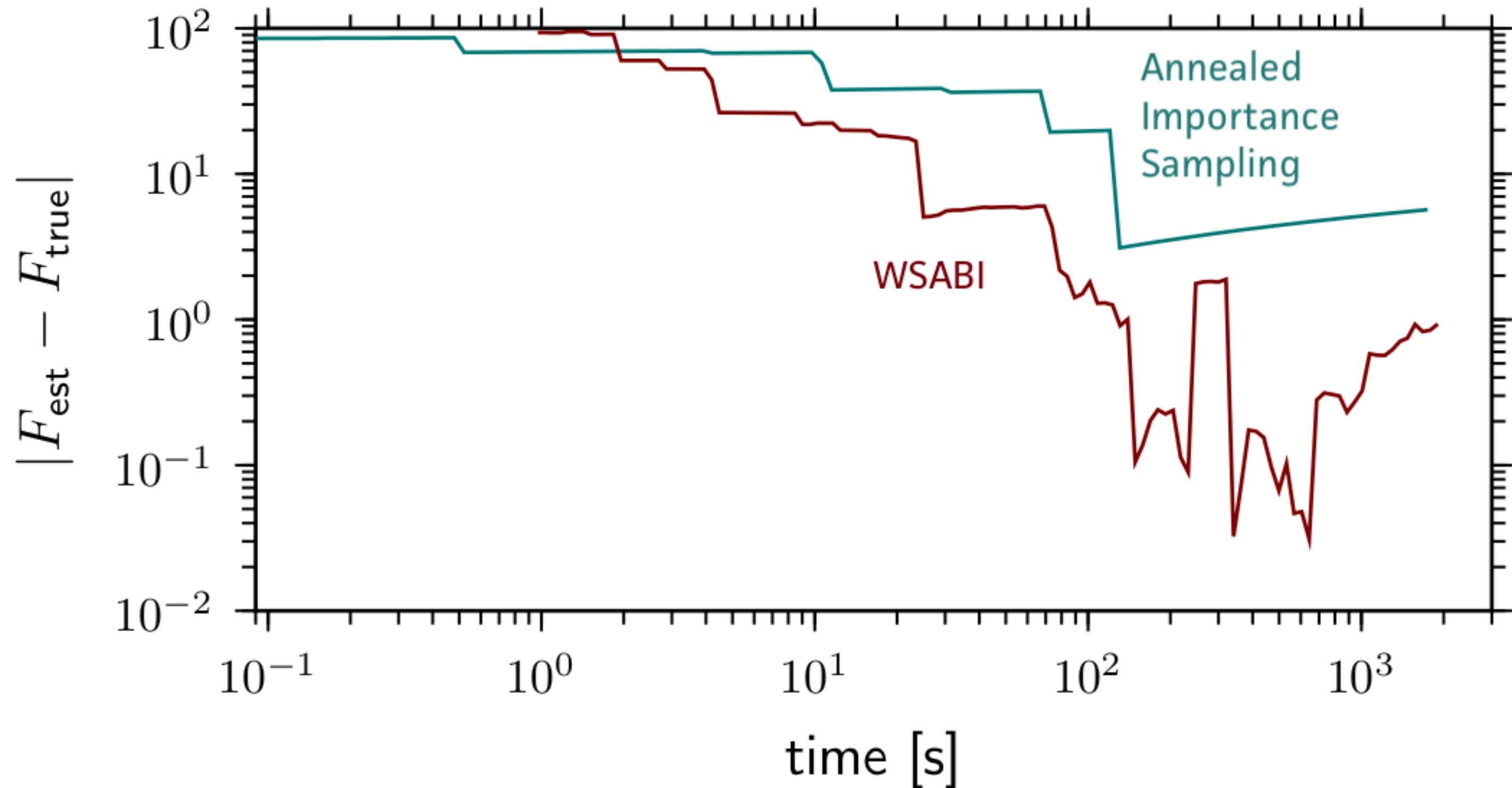
# synthetic (moG)



# yacht hydrodynamics



# GP classification, graph



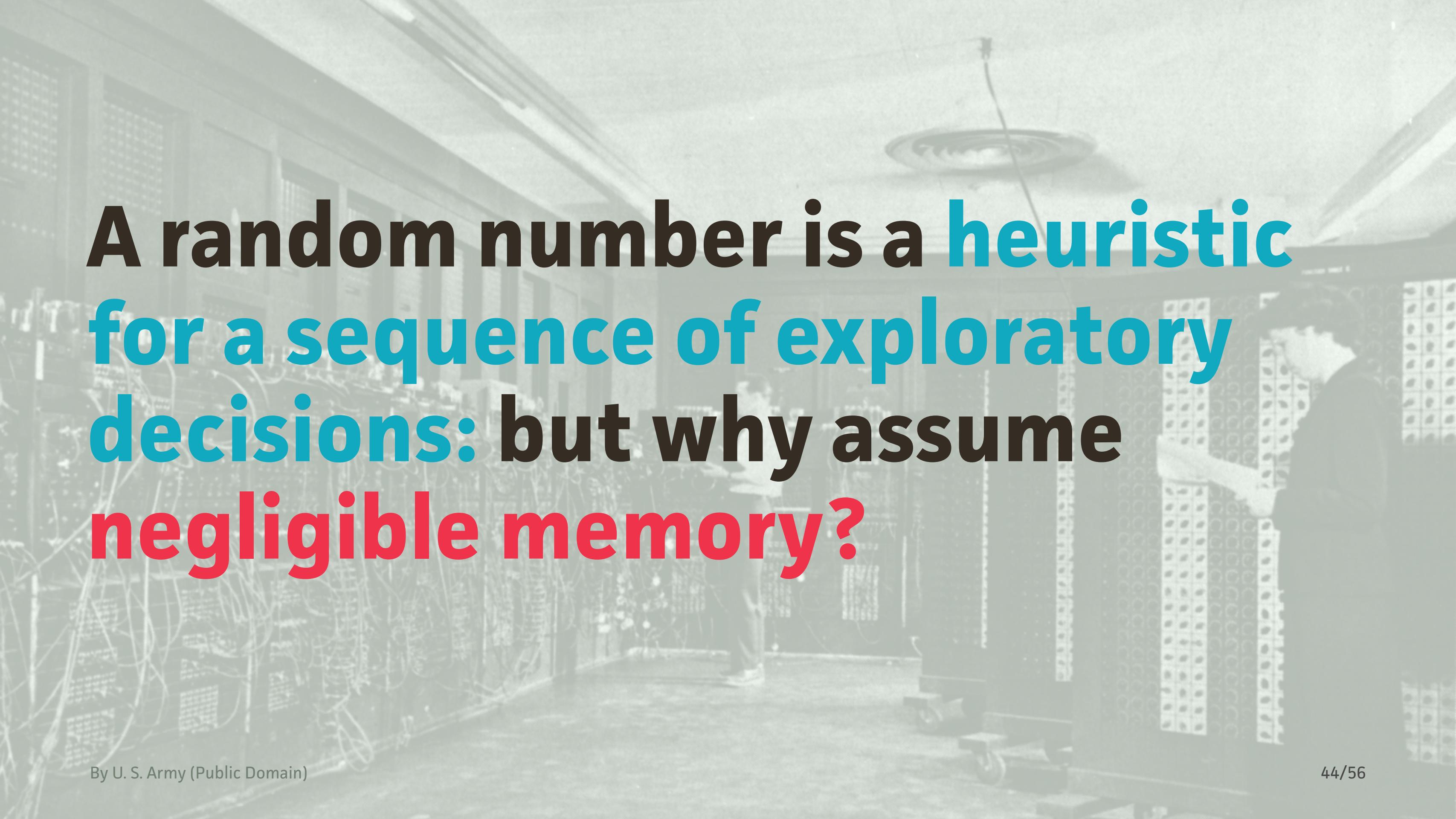
**Overhead  
can set you  
free.**



A RANDOM  
NUMBER IS  
A DECISION.



A random number assumes a  
completely flat expected loss.

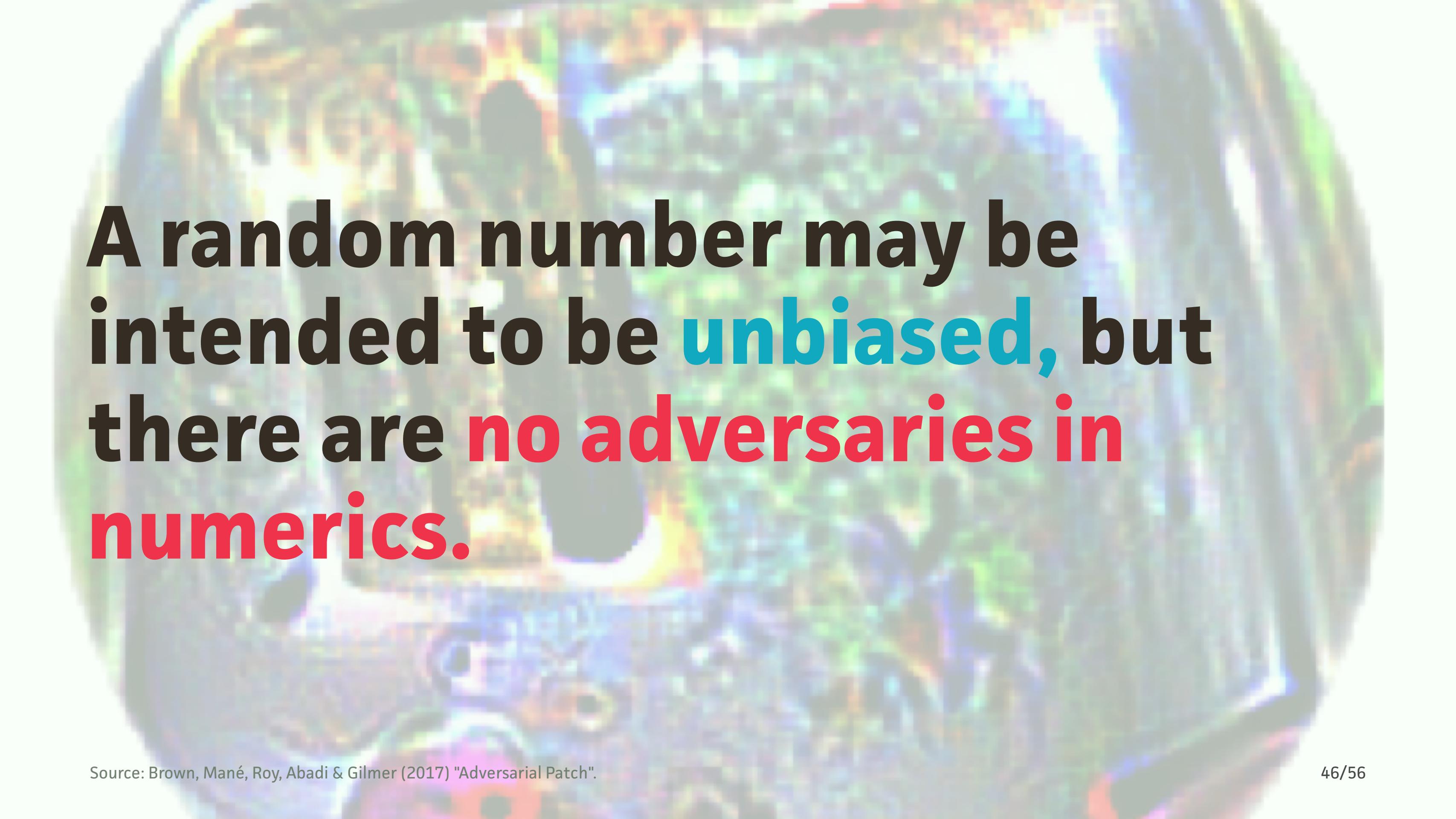


A random number is a **heuristic**  
**for a sequence of exploratory**  
**decisions: but why assume**  
**negligible memory?**



# Using random numbers makes your algorithm **unimprovable**.

Source: By Jake Archibald from London, England - Sebastian Vettel - Ferrari - Halo, CC BY 2.0. References: Henderson et al. "Deep Reinforcement Learning that Matters" (2017); Islam et al. "Reproducibility of Benchmarked Deep Reinforcement Learning Tasks for Continuous Control" (2017); Colas, Sigaud, and Oudeyer. "How Many Random Seeds? Statistical Power Analysis in Deep Reinforcement Learning Experiments" (2018); Mania, Guy, and Recht. "Simple random search provides a competitive approach to reinforcement learning" (2018).



A random number may be intended to be **unbiased**, but there are **no adversaries** in numerics.

# Quiz: which of these sequences is **random**?

1. 6224441111111144444333333
2. 1693993751058209749445923078
3. 7129042634726105902083360448
4. 10001111101111111001010000

# Quiz: which of these sequences is random?

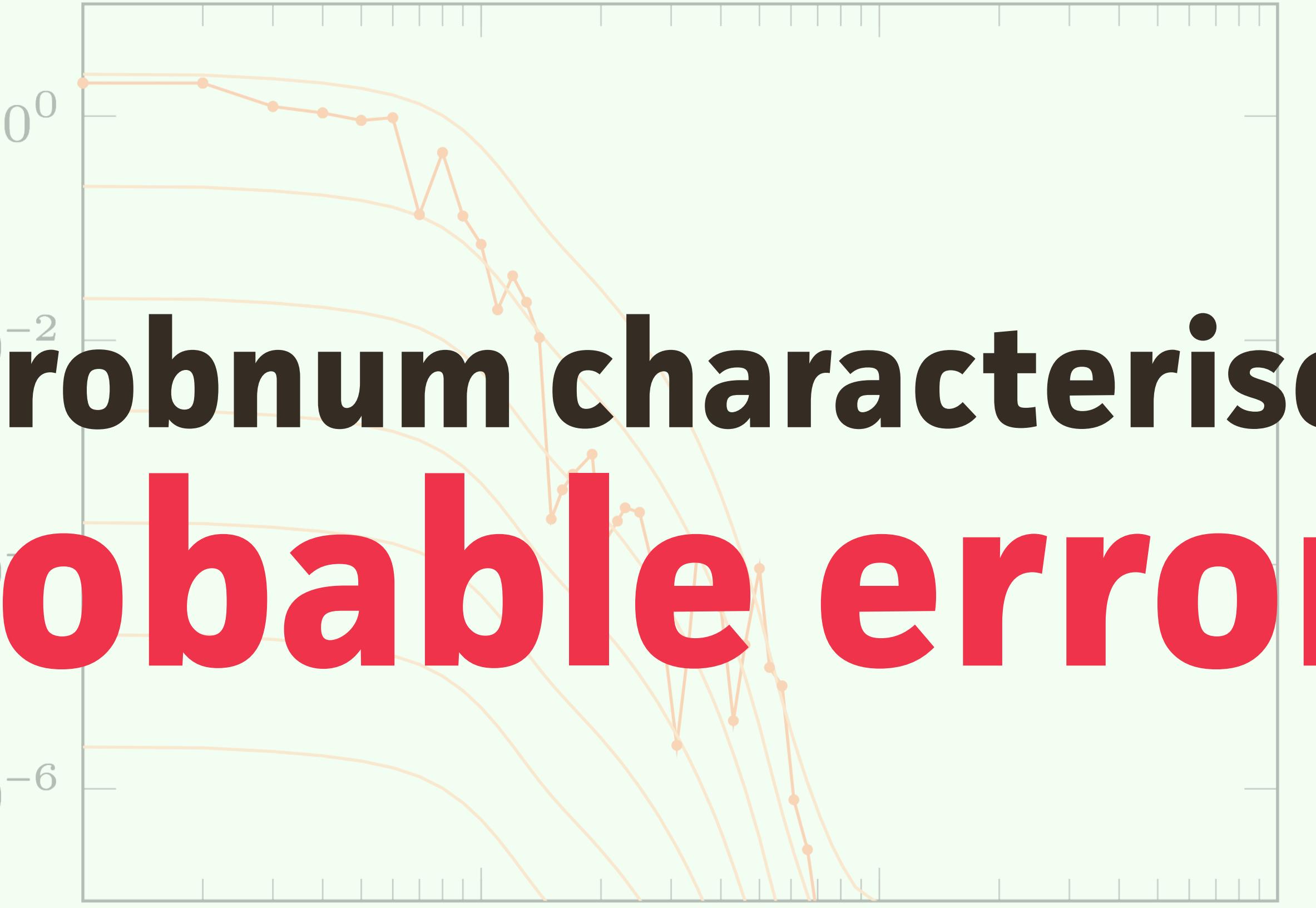
1. 6224441111111144444333333: seven d6 rolls with  $i$  repeats of the  $i$ th roll.
2. 1693993751058209749445923078: the 41st to 70th digits of  $\pi$ .
3. 7129042634726105902083360448: this sequence was generated by the von Neumann method with seed 908344.
4. 1000111110111111001010000: digits taken from a CD-ROM published by George Marsaglia.

A finite string of random numbers is **encoding some bias!**

# Recall:

1. numeric **error** is significant;
2. numeric methods are generic;
3. our numerics problems **tax**  
**our computation.**

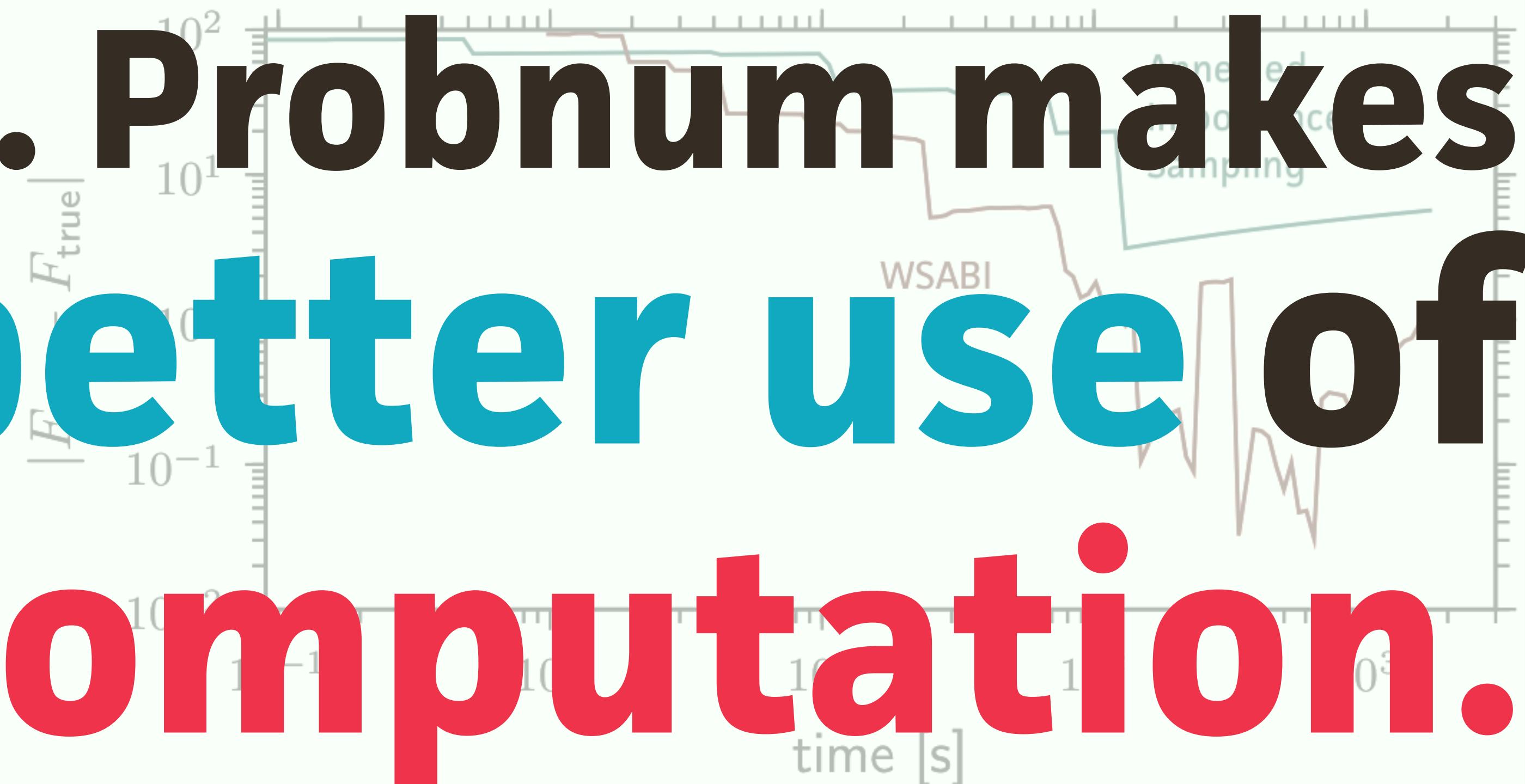
# 1. Probnum characterises probable error.



## 2. ProNum tailors

procedures  
to problems.

3. Probnum makes  
better use of  
computation.





# PROBABILISTIC-NUMERICS.ORG

Numerical algorithms, such as methods for the numerical solution of differential equations, as well as optimization algorithms. They estimate the value of a latent, intractable quantity, e.g. a differential equation, the location of an extremum, or the solution of an inverse problem.



probnum.org

Numerical algorithms, such as methods for the numerical solution of differential equations, as well as optimization algorithms. They estimate the value of a latent, intractable quantity of a differential equation, the location of an extremum, etc.

## LITERATURE

This page collects literature on all areas of probabilistic numerics. If you have any questions or comments, do not hesitate to contact us. The fastest way to get your file into the bibliography is to send us a pull-request.

### QUICK-JUMP LINKS:

- General and Foundational
- Quadrature
- Linear Algebra
- Optimization
- Ordinary Differential Equations
- Partial Differential Equations



Huge thanks to  
Philip  
Hennig.