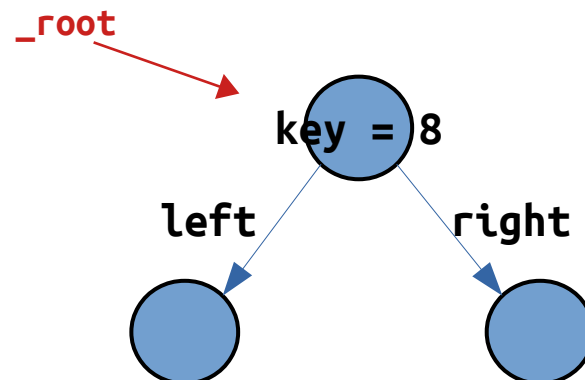


Binary Search Tree

```
6  class BSTree
7  {
8      private:
9
10         Node* _root;
11
12     public:
13
14         class Node
15         {
16             public:
17                 Node(){}
18                 Node(int key) : key(key), right(nullptr), left(nullptr){}
19                 int key;
20                 Node* right;
21                 Node* left;
22         };
23 }
```



Binary Search Tree – Insertion

```
177
178 int main()
179 {
180     BSTree myTree;
181
182     std::vector<int> data = {8, 3, 10, 1, 6, 14, 4, 7, 13};
183
184     for(int i = 0; i < data.size(); i++)
185         myTree.insert(data[i]);
```

Binary Search Tree – Insertion

```
void insert(int key)
{
    Node* it = _root;

    Node* newNode = new Node(key); // new node
    Node* parent = nullptr; // new node's parent

    while(it != nullptr)
    {
        parent = it; // keep trail of the parent
        it = newNode->key < it->key ? it->left : it->right;
    }

    if(!parent)
    {
        _root = newNode; // tree was empty
    }
    else if(newNode->key < parent->key)
    {
        parent->left = newNode;
    } else {
        parent->right = newNode;
    }
}
```

Binary Search Tree – Insertion

Insert elements: 8 3 10 1 6 14 4 7 13

8

```
void insert(int key)
{
    Node* it = _root;

    Node* newNode = new Node(key); // new node
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    }

    if(!parent)
    {
        _root = newNode; // tree was empty
    }
    else if(newNode->key < parent->key)
    {
        parent->left = newNode;
    } else {
        parent->right = newNode;
    }
}
```

Binary Search Tree – Insertion

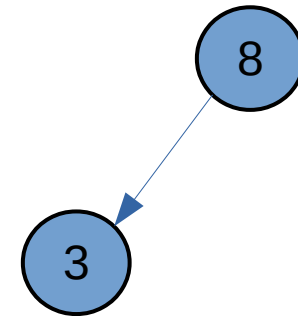
Insert elements: 8 3 10 1 6 14 4 7 13

```
void insert(int key)
{
    Node* it = _root;

    Node* newNode = new Node(key); // new node
    Node* parent = nullptr;        // new node's parent

    while(it != nullptr)
    {
        parent = it; // keep trail of the parent
        it = newNode->key < it->key ? it->left : it->right;
    }

    if(!parent)
    {
        _root = newNode; // tree was empty
    }
    else if(newNode->key < parent->key)
    {
        parent->left = newNode;
    }
    else {
        parent->right = newNode;
    }
}
```



Binary Search Tree – Insertion

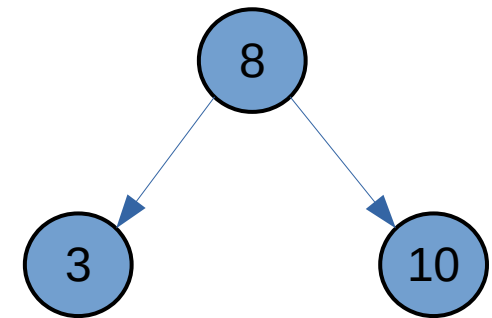
Insert elements: 8 3 10 1 6 14 4 7 13

```
void insert(int key)
{
    Node* it = _root;

    Node* newNode = new Node(key); // new node
    Node* parent = nullptr;        // new node's parent

    while(it != nullptr)
    {
        parent = it; // keep trail of the parent
        it = newNode->key < it->key ? it->left : it->right;
    }

    if(!parent)
    {
        _root = newNode; // tree was empty
    }
    else if(newNode->key < parent->key)
    {
        parent->left = newNode;
    } else {
        parent->right = newNode;
    }
}
```



Binary Search Tree – Insertion

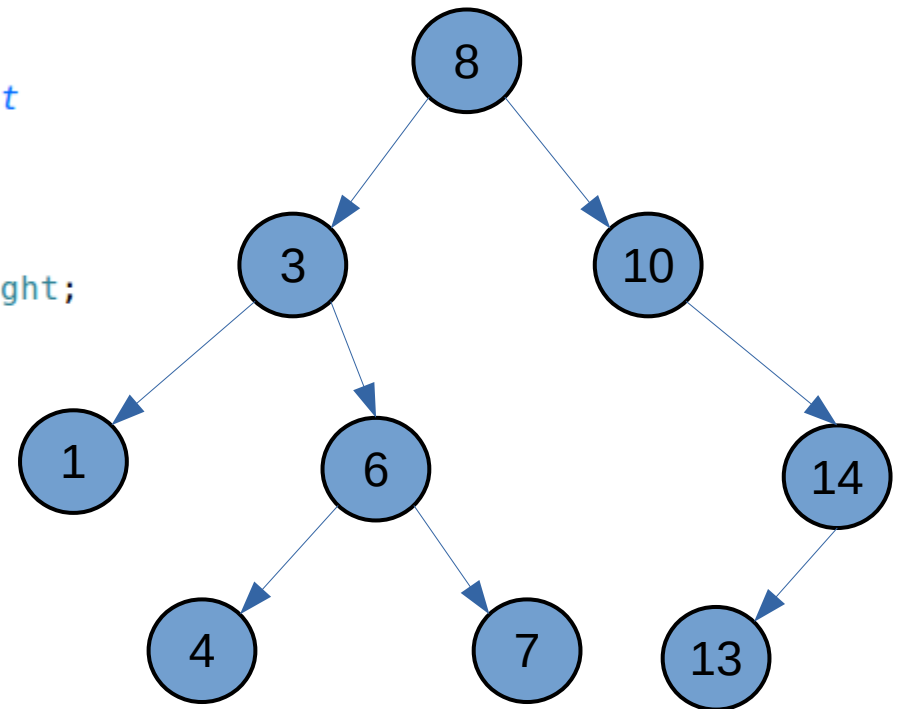
Insert elements: 8 3 10 1 6 14 4 7 13

```
void insert(int key)
{
    Node* it = _root;

    Node* newNode = new Node(key); // new node
    Node* parent = nullptr;        // new node's parent

    while(it != nullptr)
    {
        parent = it; // keep trail of the parent
        it = newNode->key < it->key ? it->left : it->right;
    }

    if(!parent)
    {
        _root = newNode; // tree was empty
    }
    else if(newNode->key < parent->key)
    {
        parent->left = newNode;
    }
    else {
        parent->right = newNode;
    }
}
```



Binary Search Tree – Search

```
// class method to search that returns the pointer to the node with  
key k  
Node* search(int k)  
{  
    Node* x = _root;  
  
    while(x is not a null pointer AND  
          the key of x is not equal to k)  
    {  
        if(k < key of x)  
            x = left child of x;  
        else  
            x = right child of x;  
    }  
  
    return x;  
}
```


Binary Search Tree – Search

```
int main()
{
    BSTree myTree;

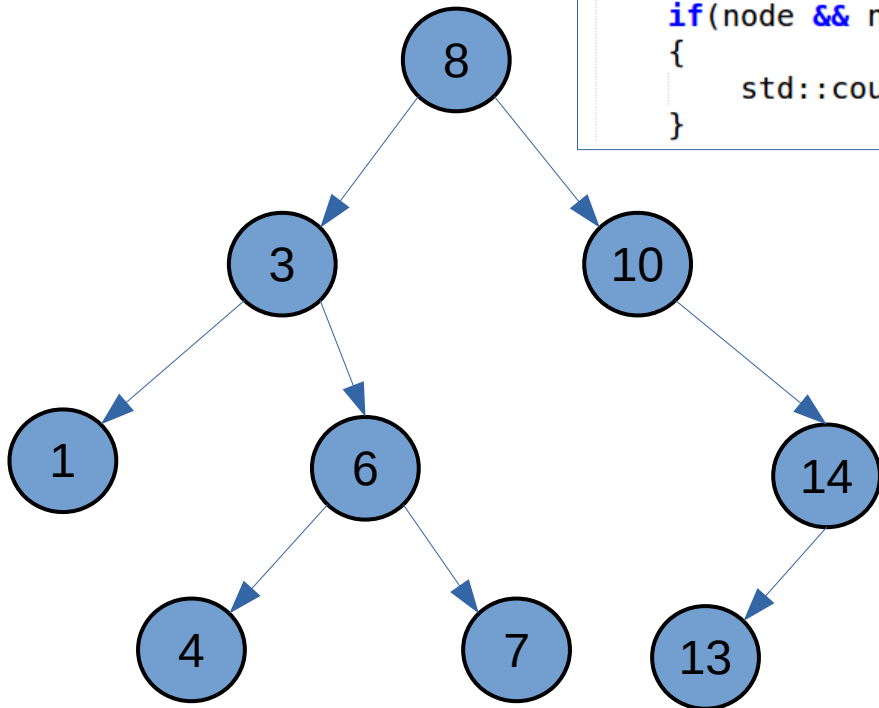
    std::vector<int> data = {8, 3, 10, 1, 6, 14, 4, 7, 13};

    for(int i = 0; i < data.size(); i++)
        myTree.insert(data[i]);

    if(! myTree.search(99) )
    {
        std::cout << "Not Found!" << std::endl;
    }

    BSTree::Node* node = myTree.search(10);

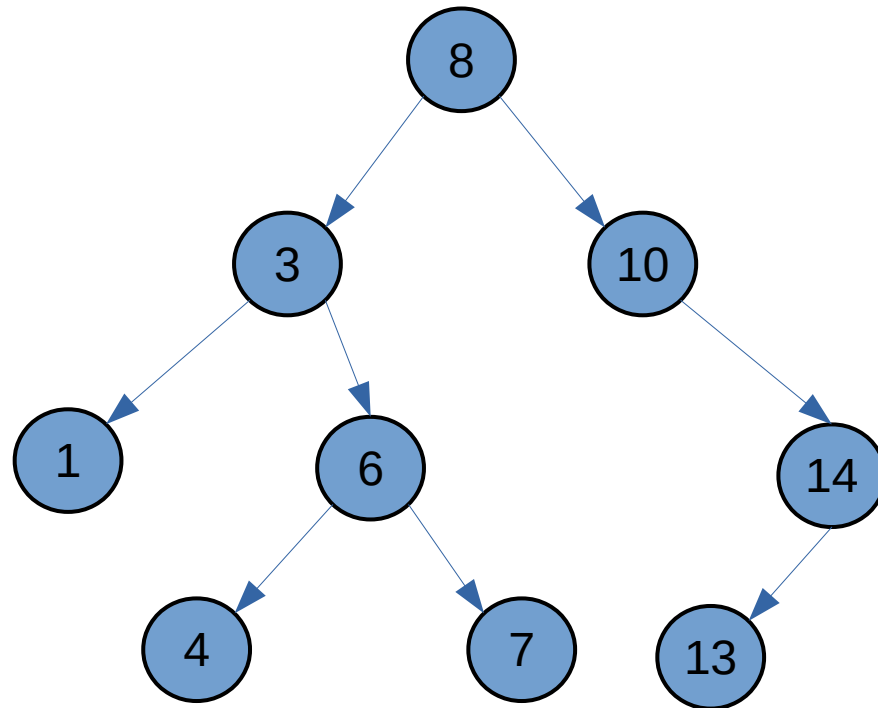
    if(node && node->right)
    {
        std::cout<< "The right son of 10 is: " << node->right->key << std::endl;
    }
}
```



```
Not Found!
The right son of 10 is: 14
```

Tree Traversals – Inorder

In a given node: Visit left subtree, then the **node**,
and finally the right subtree



Tree Traversals – Inorder

In a given node: Visit left subtree, then the node, and finally the right subtree

```
void inorder(BSTree::Node* currentNode)
{
    if(currentNode)
    {
        inorder(currentNode->left);
        std::cout << currentNode->key << ' ';
        inorder(currentNode->right);
    }
}
```

```
int main()
{
    BSTree myTree;

    std::vector<int> data = {8, 3, 10, 1, 6, 14, 4, 7, 13};

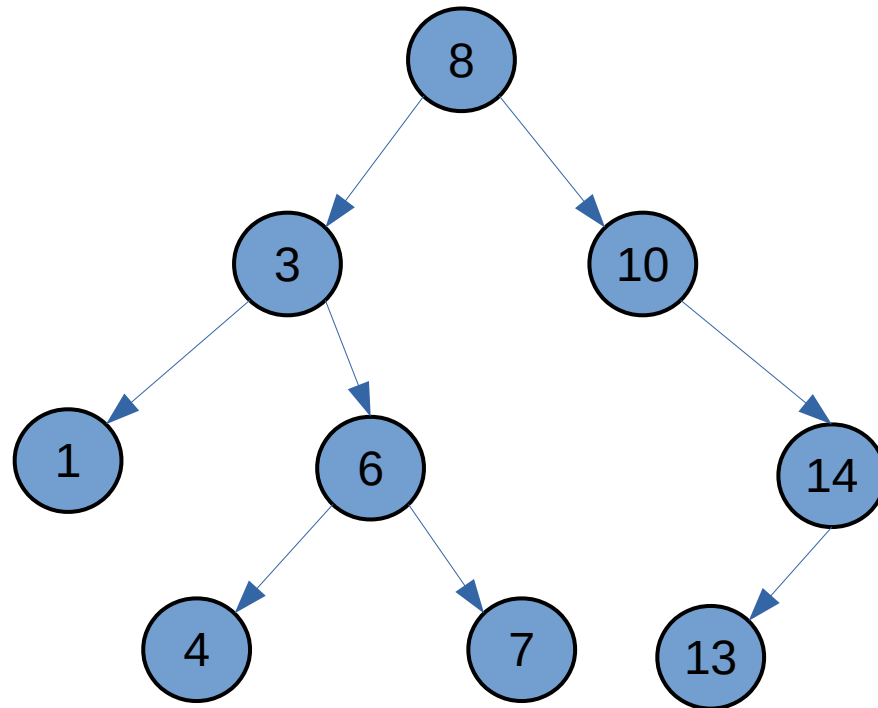
    for(int i = 0; i < data.size(); i++)
        myTree.insert(data[i]);

    BSTree::Node* root = myTree.getRoot();

    inorder(root);
    std::cout << std::endl;
```

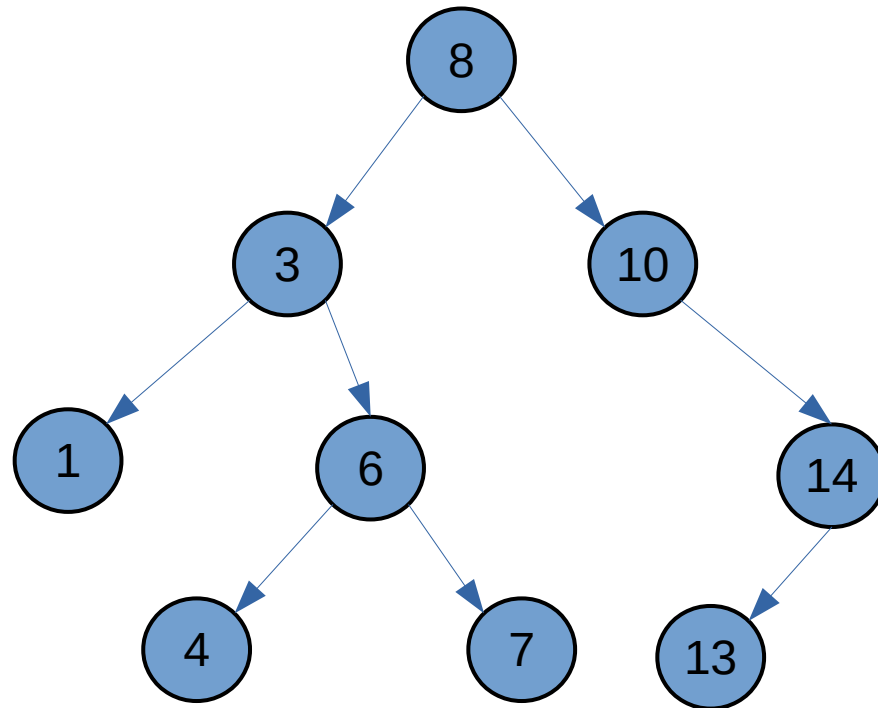
Tree Traversals – Preorder

In a given node: Visit first the **node**, then the left subtree, and finally the right subtree



Tree Traversals – **Postorder**

In a given node: Visit first the left subtree, then the right subtree, and finally the **node**



Tree Traversals – (Iterative) Level-order

Idea: visit level-by-level

This is also called **Breadth-First Search (BFS)**

Previous order traversals are instead **Depth-First Search (DFS)**

```
void levelorder(BSTree& myTree)
{
    BSTree::Node* root = myTree.getRoot();

    if(!root)
        return;

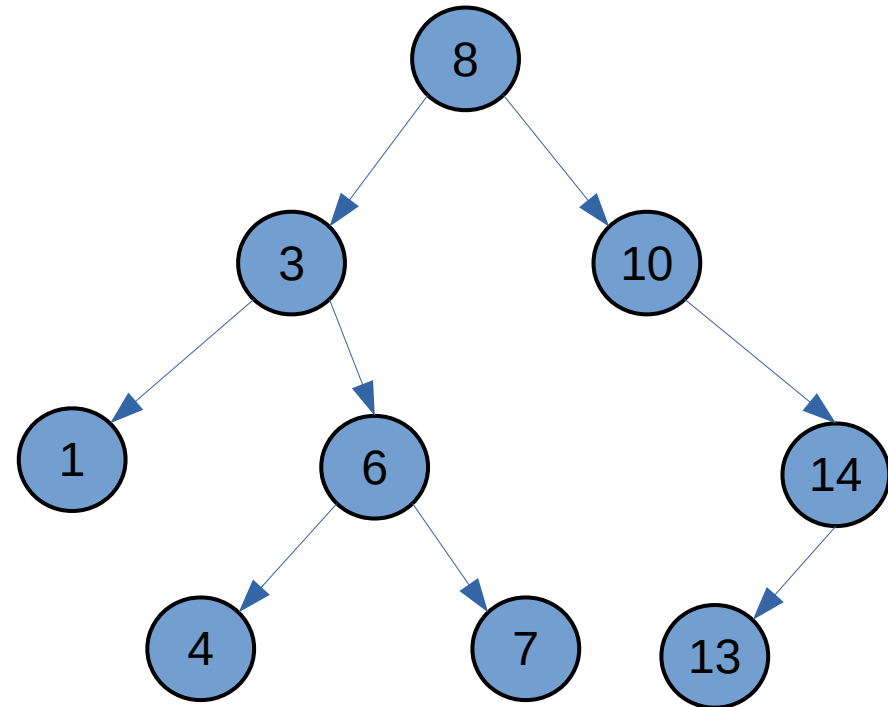
    std::queue<BSTree::Node*> queue;

    queue.push(root);

    while(!queue.empty())
    {
        BSTree::Node* node = queue.front();
        std::cout << node->key << " ";
        queue.pop();

        if (node->left)
            queue.push(node->left);

        if (node->right)
            queue.push(node->right);
    }
}
```



Tree Traversals – (Iterative) Level-order

Idea: visit level-by-level

This is also called **Breadth-First Search (BFS)**

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```
void levelorder(BSTree& myTree)
{
    BSTree::Node* root = myTree.getRoot();

    if(!root)
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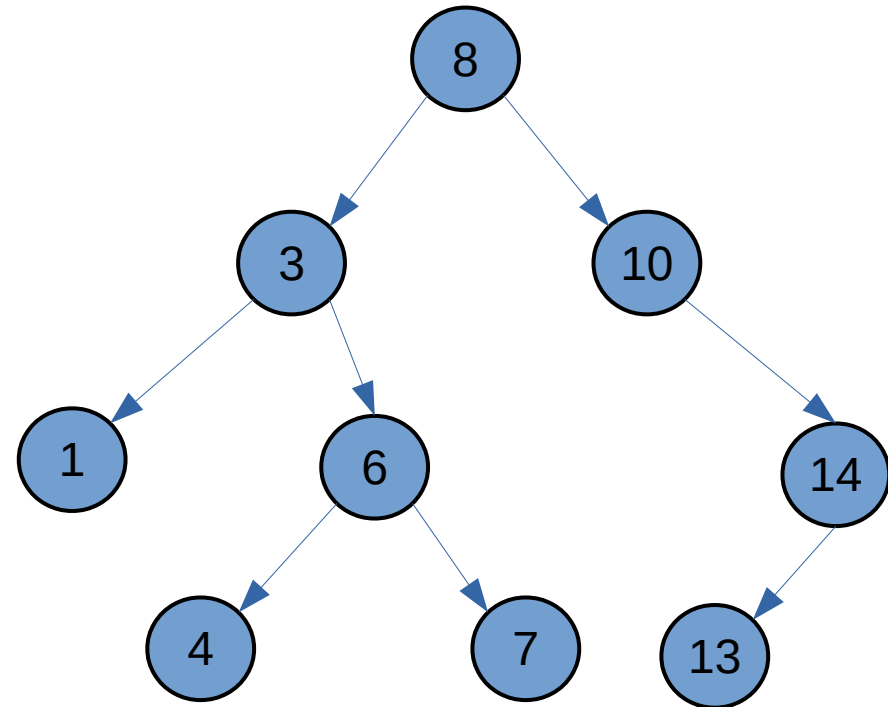
    std::queue<BSTree::Node*> queue;

    queue.push(root);

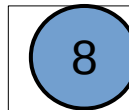
    while(!queue.empty())
    {
        BSTree::Node* node = queue.front();
        std::cout << node->key << " ";
        queue.pop();

        if (node->left)
            queue.push(node->left);

        if (node->right)
            queue.push(node->right);
    }
}
```



queue
front



Output:

8

Tree Traversals – (Iterative) Level-order

Idea: visit level-by-level

This is also called **Breadth-First Search (BFS)**

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```
void levelorder(BSTree& myTree)
{
    BSTree::Node* root = myTree.getRoot();

    if(!root)
        return;

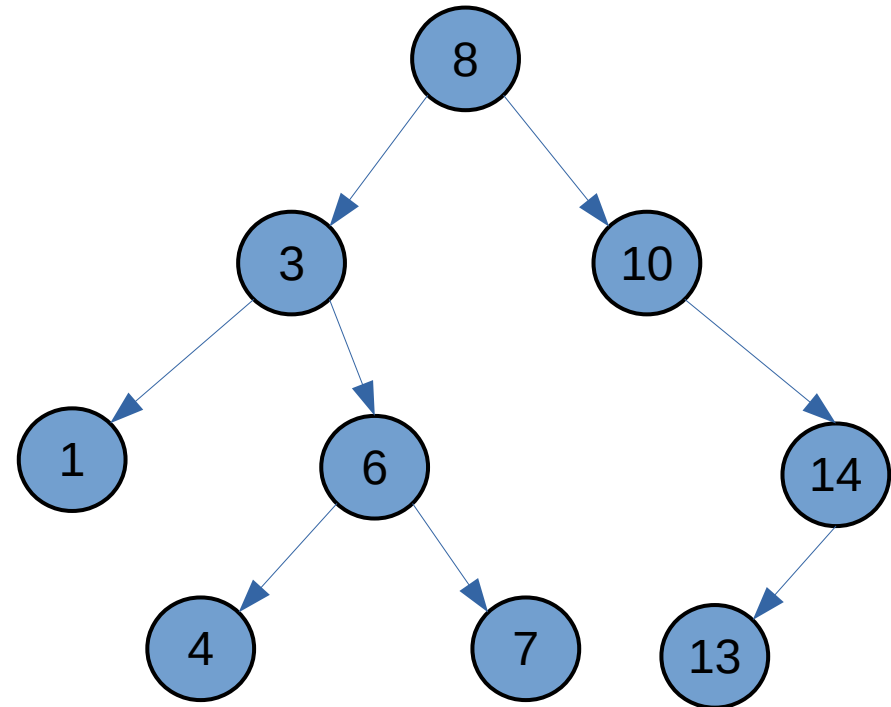
    std::queue<BSTree::Node*> queue;

    queue.push(root);

    while(!queue.empty())
    {
        BSTree::Node* node = queue.front();
        std::cout << node->key << " ";
        queue.pop();

        if (node->left)
            queue.push(node->left);

        if (node->right)
            queue.push(node->right);
    }
}
```



queue
front



Output:

8

Tree Traversals – (Iterative) Level-order

Idea: visit level-by-level

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```
void levelorder(BSTree& myTree)
{
    BSTree::Node* root = myTree.getRoot();

    if(!root)
        return;

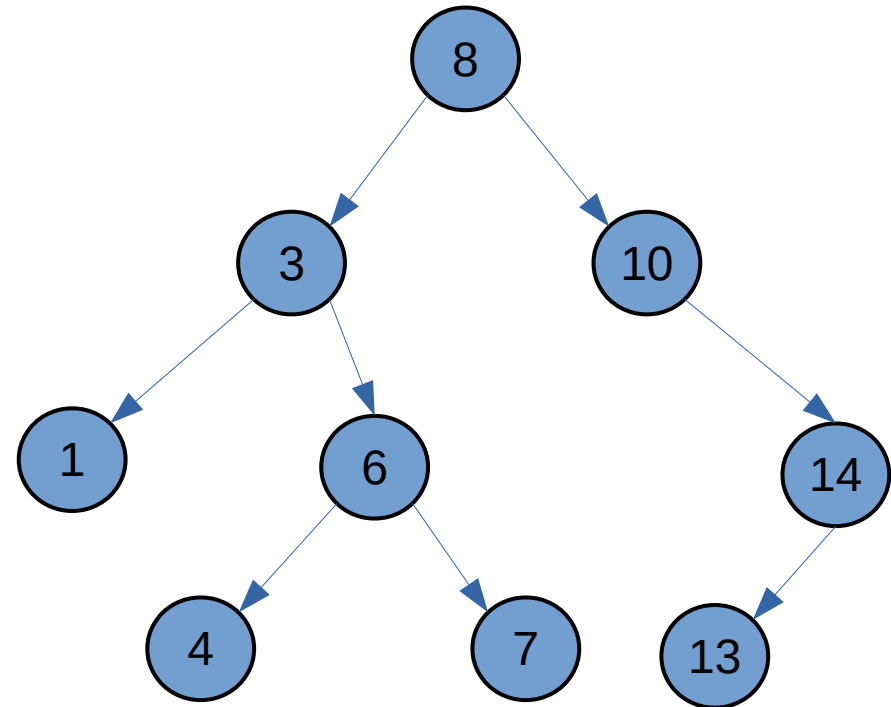
    std::queue<BSTree::Node*> queue;

    queue.push(root);

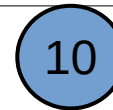
    while(!queue.empty())
    {
        BSTree::Node* node = queue.front();
        std::cout << node->key << " ";
        queue.pop();

        if (node->left)
            queue.push(node->left);

        if (node->right)
            queue.push(node->right);
    }
}
```



queue
front



Output:

8

3

Tree Traversals – (Iterative) Level-order

Idea: visit level-by-level

This is also called **Breadth-First Search (BFS)**

Previous order traversals are instead **Depth-First Search (DFS)**

```
void levelorder(BSTree& myTree)
{
    BSTree::Node* root = myTree.getRoot();

    if(!root)
        return;

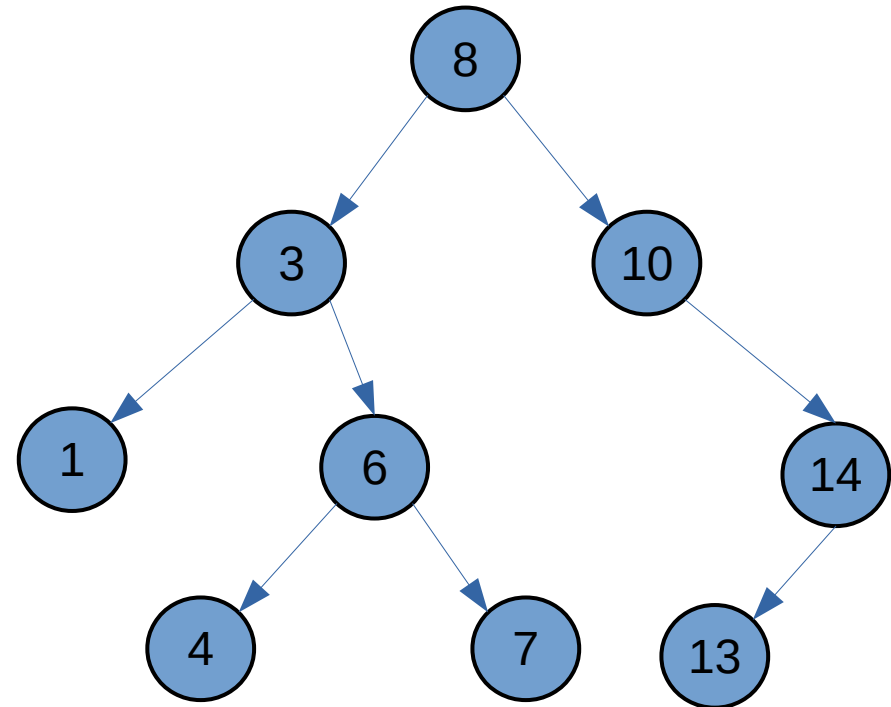
    std::queue<BSTree::Node*> queue;

    queue.push(root);

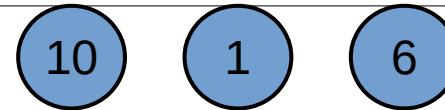
    while(!queue.empty())
    {
        BSTree::Node* node = queue.front();
        std::cout << node->key << " ";
        queue.pop();

        if (node->left)
            queue.push(node->left);

        if (node->right)
            queue.push(node->right);
    }
}
```



queue
front



Output:

8

3

Tree Traversals – (Iterative) Level-order

Idea: visit level-by-level

This is also called **Breadth-First Search (BFS)**

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```
void levelorder(BSTree& myTree)
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    BSTree::Node* root = myTree.getRoot();

    if(!root)
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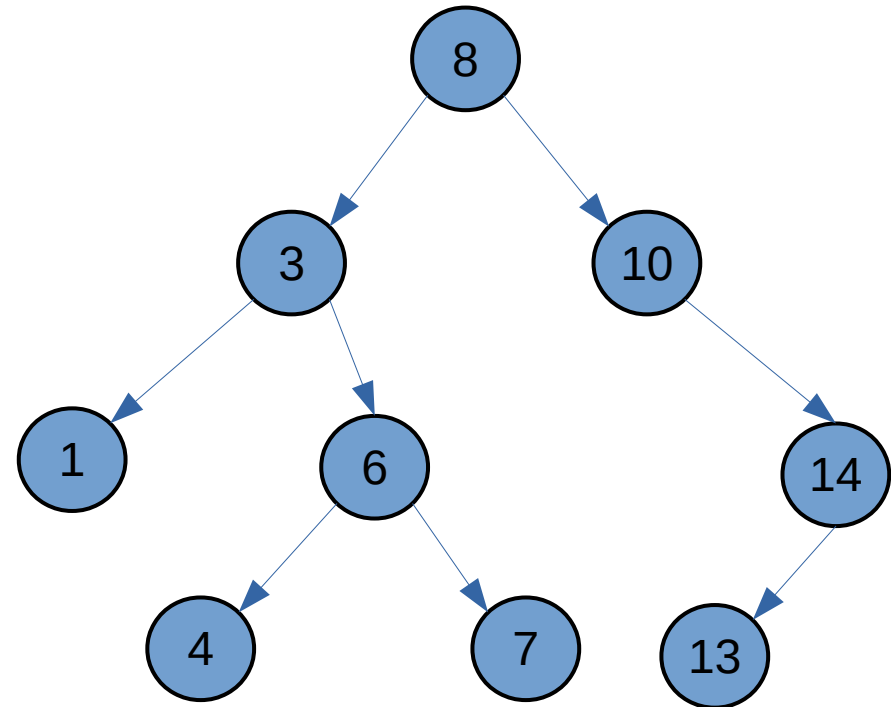
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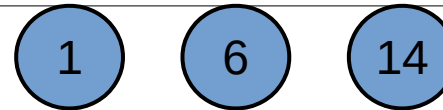
    while(!queue.empty())
    {
        BSTree::Node* node = queue.front();
        std::cout << node->key << " ";
        queue.pop();

        if (node->left)
            queue.push(node->left);

        if (node->right)
            queue.push(node->right);
    }
}
```



queue
front



Output:

8 3 10