

# PERI HASSANZADEH

+1(570) 764-7631 ◇ Pittsburgh, PA

[perihassanzadeh@gmail.com](mailto:perihassanzadeh@gmail.com) ◇ [linkedin.com/in/perihassanzadeh](https://www.linkedin.com/in/perihassanzadeh) ◇ <https://perihassanzadeh.github.io/>

## EDUCATION

|  |          |
|--|----------|
| <b>MS Electrical and Computer Engineering</b> , University of Pittsburgh | May 2025 |
| – Awarded Full Tuition Merit Scholarship                                 |          |
| <b>BS Computer Engineering</b> , University of Pittsburgh                | Dec 2022 |

## SKILLS

|                    |  |
|--------------------|--|
| <b>Programming</b> | C (MISRA)   Embedded C   C++   Python   Linux                                |
| <b>Tools</b>       | STM32 Toolchain   Debugging   Yocto   Altium Designer   MATLAB               |
| <b>PM</b>          | Git   JIRA   Confluence   Agile   Technical Communication   Stakeholder Mgt. |

## EXPERIENCE

|  |   |
|--|---|
| <b>Embedded Software Engineer - Navy Sustainment</b><br>Gecko Robotics | Jan 2025 - Present<br><i>Pittsburgh, PA</i> |
|--|---|

- Architected and implemented the transition from mechanical to **software-automated probe lifting mechanisms** for the ship deck inspection robot, reducing manual intervention by **80%** and enabling high-precision scanning.
- Developed and delivered **real-time** motor and actuator controller **firmware** in **C**, using **CAN** for command and **SPI** for driver communication, which improved first-pass fault detection rate by **45%**.
- Collaborated with the Hardware Platform team on system security to harden the **custom Linux OS** using **Yocto**, targeting IL5 compliance for high-assurance systems.
- Initiated and standardized the firmware and software release process across 6 embedded projects, ensuring stable releases and using **JIRA/Git** to manage version control and deployment for the ship deck inspection robotic system.

|  |  |
|--|--|
| <b>Graduate Student Researcher</b><br>NSF Center for Space, High Performance and Resilient Computing | Jan 2023 - May 2025<br><i>Pittsburgh, PA</i> |
|--|--|

- Led the Mission-Critical Sensor Processing Task, managing the **full project lifecycle** from proposal to delivery and **coordinating stakeholders** on critical design elements for multiple complex projects.
- Served as the **primary technical interface** for industry sponsors, **translating customer requirements** into actionable development objectives and **ensuring on-time delivery** of contractual commitments.
- Proactively managed project schedules and resource allocation, identifying and **resolving technical blockers** to maintain momentum and ensure **successful project outcomes** across parallel initiatives.

|   |   |
|---|---|
| <b>Graduate Engineering Intern</b><br>SpaceX - Starlink Product Engineering | May 2024 - Aug 2024<br><i>Hawthorne, CA</i> |
|---|---|

- Developed an automated **real-time** test environment for Wi-Fi interference analysis, enhancing **system reliability and performance** through telemetry visualization.
- Designed and deployed a network-accessible automated test execution interface, significantly improving technician **usability** and **reducing operational errors by 60%**.
- Owned the **complete project lifecycle** for Starlink User Terminal testing repository **integration**, from design and implementation to documentation, ensuring seamless team adoption.

## PROJECTS

**Formula Student** Led sensor prototype development and integration for aerodynamic subsystem; resulting in first-place innovation award at competition.

**Disarm-It!: Bop-It Spinoff** Designed and implemented embedded firmware for an interactive game using multiple digital sensors.

## CERTIFICATIONS

|  |          |
|--|----------|
| <b>Certified Associate in Project Management (CAPM)</b> , Project Management Institute (PMI) | Oct 2025 |
|--|----------|