Research Centre Jülich



Writing Efficient Programs with C++

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General Overview

Abstractions in C++

The Abstraction Penalty

How to beat it

(Some) Existing Solutions



Part I: Abstractions and their Cost

Short recapitulation of some C++ abstractions. Special emphasize on runtime performance and optimizations + a look under the hood of existing C++ implementations

Part II: Template Metaprogramming

Introduction of a special programming technique that allows for fascinating optimizations. It is especially this technique that distinguishes C++ from other languages (e.g. Fortran, C).

Part III: Advanced Techniques

... be prepared:)



In this course we are talking about



Thus, C++ according to the

International Standard ISO/IEC 14882

and neither GNU C++, Microsoft Visual C++, Borland C++, or any other vendor specific C++ implementation!



I. Abstractions and their Cost

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Overview

- Classes
- Polymorphism
 - Inheritance
 - Overloading
 - Conversions
 - Templates
- Further Topics
- References



I.1. Classes Introduction

What is a class?

- user defined type
- provides methods for logical grouping of data and functionality
- provides methods for data-hiding and protection
- can be used to express hierarchical relationships between concepts (derived classes)

A class consists of

- data memebers are variables of arbitrary type (perhaps, classes)
- member functions are action/operations usually applied to data members (they define how a class behaves)
- **constructors** are called during creation of an object (initialize data members, request system resources)
- **destructor** is called during deletion of an object (free system resources)

An *instance* of a class is called **object**



I.1. Classes Definitions

Grady Booch: Object-Oriented Analysis and Design With Applications

An **object** has **state**, **behavior**, and **identity**; the structure and behavior of similar objects are defined in their common **class**; the terms instance and object are interchangeable.

James Rumbaugh: Object-Oriented Modeling and Design

An **object** is a **concept**, **abstraction**, or **thing**, with crisp boundaries and meaning for the problem at hand. Objects serve two purposes:

- they promote understanding of the real world and
- provide a practical basis for computer implementation.

Decomposition of a problem into objects depends on judgment and the nature of the problem. There is no one correct representation.



I.1. Classes Introduction - An Example

```
class doubleVec3 {
private:
   int Size;
   double* data;
protected:
   const double* getData() const {
     return data;
   }
public:
   int getSize() const {
     return size;
   }
};
```

- Class definitions are introduced by the keyword **class** and always end with a semicolon.
- Specifiers **public**, **private**, and **protected** are used to control access to members.
- const member functions do not change the object



I.1. Classes Lifecycle of an Object

The lifecycle of an object consists of five phases:

- Allocation of memory to hold data members create space for object
 - Construction (done by *constructors*): initialization of data members, potentially allocation of system resources (e.g. open a file)
 - Usage
 - **Destruction** (done by *destructor*): free potentially allocated system resources (e.g. close a file)
- **De-Allocation** of memory to store data members



I.1. Classes Lifecycle of an Object - Constructor Types

There are three kinds of constructors

- **Default constructor** may be called without supplying an argument. Thus, either doesn't take any, or all of them have a default value
- Regular constructor takes at least one argument
- Copy constructor used to create copy of object. (Do not confuse with assignment operator!)
- If there is no user-defined constructor, **default constructor** and **copy constructor** are automatically created by the compiler (*see next slide*)
- Constructors always have the name of the class
- Maybe placed in **public**, **private**, or **protected** section of class definition



I.1. Classes Lifecycle of an Object - Automatically generated Constructors

Automatically generated default constructor

• Empty member initializer list / empty function body, thus A::A() {}

Automatically generated copy constructor

- Has form A::A (const A&), if each direct or virtual base class B of A has a copy constructor whose first parameter is of type const B& or const volatile B&, and for all the nonstatic data members of A that are of a class type M (or array thereof), each such class type has a copy constructor whose first parameter is of type const M& or const volatile M&, otherwise it has form A::A(A&)
- Performs memberwise copy of its subobjects

Implicitly declared constructors are public inline members of their class



Note 0: Function Inlining

inline functions help reducing the function call overhead

- push parameters to function on stack
- call the function (push instruction pointer to stack jump to code of function)
- reserve stack space for local variables
- ... execute function ...
- clean stack space (local variables)
- return to caller
- clean stack (remove parameters)

The effect is to substitute each occurrence of the function call with the text of the body of the function.

```
inline int square(int i) {
   return i*i;
}
...
int i = square(3);
...
int j = square(10);
int j = 10*10;
```

Note 0: Function Inlining

Note! inline specifier is simply a hint, not a mandate to the C++ compiler!

- removes overhead
- provides better opportunities for further optimizations
- increases code size
- reduces efficiency if abused (e.g. code no longer fits cache)

More on inlining later ...

I.1. Classes Lifecycle of an Object - Automatically generated Constructors

• Take care when relying on automatically genereated constructors!

```
class Foo {
                        myInt and myIntPtr are not initialized to zero by
public:
                        automatically created default constructor!
  int myInt;
  int* myIntPtr;
};
                       Memory for global static variables is filled with
Foo a;
                       zeroes
void bar() {
  Foo b:
  if (b.myInt)
                        May fail or succeed - depending on the contents of the
                        stack
};
```

I.1. Classes Lifecycle of an Object - Automatically generated Constructors - Augmenting I

```
class Foo { public: Foo(); ... };
class Bar { public: Bar(); Bar(int); ... };
class Zap { public: Zap(); ... };
class MyClass {
  int anInt;
public:
                     Automatically synthesized constructor for MyClass invokes
  Foo f:
  Bar b;
                     default constructors for each member object. anInt remains
  Zap z;
                     uninitialized
};
              MyClass::MyClass(MyClass* this) {
                Foo::Foo(this->f);
                Bar::Bar(this->b);
                Zap::Zap(this->z);
```

I.1. Classes Lifecycle of an Object - Automatically generated Constructors - Augmenting II

What happens for the following case? Do **f** and **z** remain uninitialized?

```
class MyClass {
  int anInt;
public:
    MyClass() : b(1024) { anInt = 12; }
    Foo f;
    Bar b;
    Zap z;
};
No, our constructor gets augmented:
```

Notice, that the order of initializations corresponds to the order in which the members have been declared!

```
MyClass::MyClass(MyClass* this) {
   Foo::Foo(this->f);
   Bar::Bar(this->b,1024);
   Zap::Zap(this->z);
   anInt=12;
}
```

I.1. Classes Lifecycle of an Object - Destructors

- \bullet Destructors always have the name of the class prepended with \sim
- Must be placed in **public** section of class definition (or **protected** section of abstract base class)
- Guaranteed to be invoked when an object gets destroyed
- If not defined, compiler generates one of form A::~A() {}

I.1. Classes Lifecycle of an Object - Constructor / Destructor Example

```
class doubleVec3 {
private:
  double* data;
public:
  doubleVec3() { // default constructor
    data=new double[3];
  doubleVec3(const doubleVec3& rhs) { // copy constructor
    data = new double[3];
    data[0]=rhs.data[0]; data[1]=rhs.data[1]; data[2]=rhs.data[2];
  doubleVec3( int val ) { // regular constructor
    data = new double[3];
    data[0]=val; data[1]=val; data[2]=val;
  }
  ~doubleVec3() { // destructor
    delete [] data;
};
```

• A *named automatic object* is created each time its declaration is encountered in the execution of the program and destroyed each time the program exits the block in which it occurs

```
Allocation: reserve space on stack

(e.g. decrement stack pointer by d's size)

void foo() {
    doubleVec3 d;
    Destruction: call d. doubleVec3()

De-Allocation: free stack space
    (e.g. increment Stack pointer by d's size)
```

• Passing arguments by value involves calling the copy constructor

```
Construction: call f.doubleVec3(const doubleVec3&) with the argument passed to bar
```



Note 1: Copy Constructor

- ? Why must copy constructors take their arguments by reference?
- ! To avoid infinite recursion.

```
class A {
  int a;
public:
  A() {
    a=1;
  }
    calls rhs.A( ca )

A(A rhs) {
    a=rhs.a;
  }
};
calls cb.A( ca )
```

Note 2: Passing arguments to functions / class member functions

! Passing arguments by reference may save runtime!

• Passing arguments by reference avoids call to copy constructor

```
void bar(doubleVec3& f) {
}
```

• Pass arguments *by const reference* to avoid call to copy constructor and to avoid users from changing the associated object

• A *nonstatic member* is created and destroyed with its hosting object.

```
class C {
   doubleVec3 d;
   ...
};

Allocation: reserve stack space for c (includes c.d)

void foo() {
   C c;
}

Construction: call c.C() - d.doubleVec3() gets called

Destruction: call c.~C() - d.~doubleVec3() get called

De-Allocation: free stack space
```

• A free store object is created using operator new and destroyed using operator delete

```
Allocation & Construction: allocate free store for d - call d.doubleVec3 (12)

doubleVec3 *d = new doubleVec3 (12);

...

delete d; Destruction & De-Allocation: free heap space - call d.~doubleVec3 ()
```

• An *array element* is created and destroyed when the array of which it is an element is created and destroyed

```
Allocation & Construction: allocate free store for 100 elements of type doubleVec3 and call doubleVec3() for each of them.

doubleVec3 *dArray = new doubleVec3[ 100 ];

delete [] dArray;

Destruction & De-Allocation: free heap space - call ~doubleVec3() 100 times

remember to distinguish between operator delete and operator delete[]
```

• A *global*, *namespace*, or *class static object* is created at the start of the program and destroyed once at the termination of the program



• A *local static object* is created the first time its declaration is encountered and destroyed once at the termination of the program

```
void f(int i) {
    static doubleVec3 a; De-Allocation & Destruction of a and b at end of program.

if (i != 0) {
    static doubleVec3 b;
    ...
}
f(0); Construction of a doesn't happen before this call.

f(1); Construction of b doesn't happen before this call - a isn't constructed again!
```

• A *temporary object* that is the result of an expression gets destroyed at the end of the full expression (*More on temporaries later*).



I.1. Classes Lifecycle of an Object - Penalties

- Definition of an object does not only mean to reserve space but also to run some initialization code!
- Definition of an array or creating an array with operator **new** respectively, results in calling the initialization code for every item of this array.
- Leaving scope (e.g. function / for-loop) may mean to call de-initialization code for one or multiple object.
- Initialization overhead of super classes / class members maybe unknown
- Possibly doing initialization multiple times (redundant construction)

Note 3: Redundant Construction

A member initialization list may save runtime!

```
class A {
  int a[100];
public:
  A() { setA(255); }
  A(int b) { setA(b);}
  setA( int b) {
     for (int i=0; i<100; i++)
                                        Expensive!
       a[i] = b;
                                      Better variant: use mem-initializer list
                                      class B {
class B {
                                         Aa;
  Aa;
                                      public:
public:
                                         B( int j ) | : a(j) | {}
  B( int j ) { a.setA(j); }
                                       };
};
Very bad: a . setA is called twice (once through default constructor)!
```

Note 4: Member Initialization List (MIL) Pittfall

Why does this program print "No"?

```
class S {
public:
  int i;
  int j;
  S(int v) : j(v), i(j) { }
};
S s(10);
int main() {
  if (s.i == s.j)
    cout << "Yes";</pre>
  else
    cout << "No";
  return 0;
};
```

The order of initializations in the MIL does not matter. Members are always initialized in the order they are defined!

```
S::S(S* this,int v) {
  this->i = this->j;
  this->j = v;
}
```

Note 5: Lazy Construction

! Variables not necessarily need to be declared at the beginning of a function - postpone variable declaration as long as possible

```
class A {
  int a[100];
public:
  A() { setA(255); }
  A(int b) { setA(b);}
  setA( int b) {
    for (int i=0; i<100; i++)
      a[i] = b;
};
void f(bool b,const A& z) {
 A \times , y;
  if (b) {
   x = z;
    // do something with x
  };
  // do something with y
```

Point of construction may save runtime!

```
void f(bool b,constA& z) {
  if (b) {
    A x = z;
    // do something with 'x'
    // (possibly "return" !)
    // A::~A(x) destructor call
  };
  A y;
}
```

Note 6: *Explicit Initialization*

! If possible: prefer explicit initialization!

```
class A {
                                    void f(bool b,constA& z) {
  int a[100];
                                      A \times = z; // also possible A \times (z);
public:
  A()
     { setA(255); }
  A(int b) { setA(b);}
                                      just invokes the copy constructor
  setA( int b) {
    for (int i=0; i<100; i++)
      a[i] = b;
};
void f(bool b,const A& z) {
                                   Default constructor gets called here
  A x;
                                   operator= gets called!
```

Note 7: Anticipated Destruction

! Sometimes it may be reasonable to destroy objects earlier than the current scope ends -> open a new scope!

```
class A {
  int* a;
public:
  A() \{ a = new int[100]; \}
        setA(255); }
  ~A() { delete [] a;}
  setA( int b) {
    for (int i=0; i<100; i++)
      a[i] = b;
};
void f(bool b,const A& z) {
  A \times , y;
  //... do something with x
  // x no longer needed
  //... do something with y
} // x and y get destroyed here
```

```
Note: Explicitly calling the destructor (e.g. x.~A()) may cause trouble (resource gets freed twice!)
```

Point of destruction may help to save space!

```
void f(bool b,constA& p) {
    { A x = p;
        // do something with 'x'
    } // x gets destroyed here !
    A y;
} // y gets destroyed here
```

Note 8: Constructors and Caching

Be aware of the architecture of your system!

```
class A {
                            A standard-conforming constructor will lay out
  int a;
                            an object of type A in the declaration order!
  int ar[8192];
                            a is separated by 8192 bytes from c
  int c;
public:
  A() : a(1),c(2) {}
                            Will probably cause a cache miss!
class A {
  int a;
                            Reorder members to avoid possible cache miss
  int c;
  int ar[8192];
public:
  A() : a(1),c(2) {}
```

Order of data members may influence caching behavior!

Overview

- Classes
- Polymorphism
 - Inheritance
 - Overloading
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 - Templates
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I.2. Polymorphism Definition

What is a polymorphism?

• from Greek language: having multiple forms

Strachey (1967)

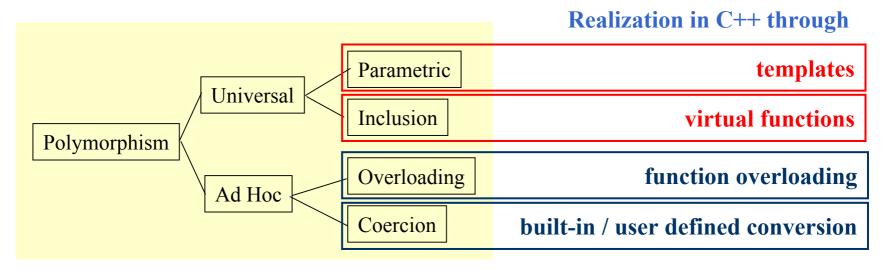
Parametric polymorphism is obtained when a function works uniformly on a range of types; these types normally exhibit some common structure. Ad-hoc polymorphism is obtained when a function works, or appears to work, on several different types (which may not exhibit a common structure) and may behave in unrelated ways for each type.

Cardelli and Wegner (1985)

Refined Strachey's definition by adding **inclusion polymorphism** to model subtypes and subclasses (inheritance). Strachey's parametric polymorphism is divided into **parametric** and **inclusion polymorphism**, which are closely related, but separated to draw a clear distinction between the two forms, which are then joined as specializations of the new **universal polymorphism**.



I.2. Polymorphism Polymorphism in C++



Polymorphism according to Cardelli & Wegner

In OO languages inclusion polymorphism is often called subtype polymorphism

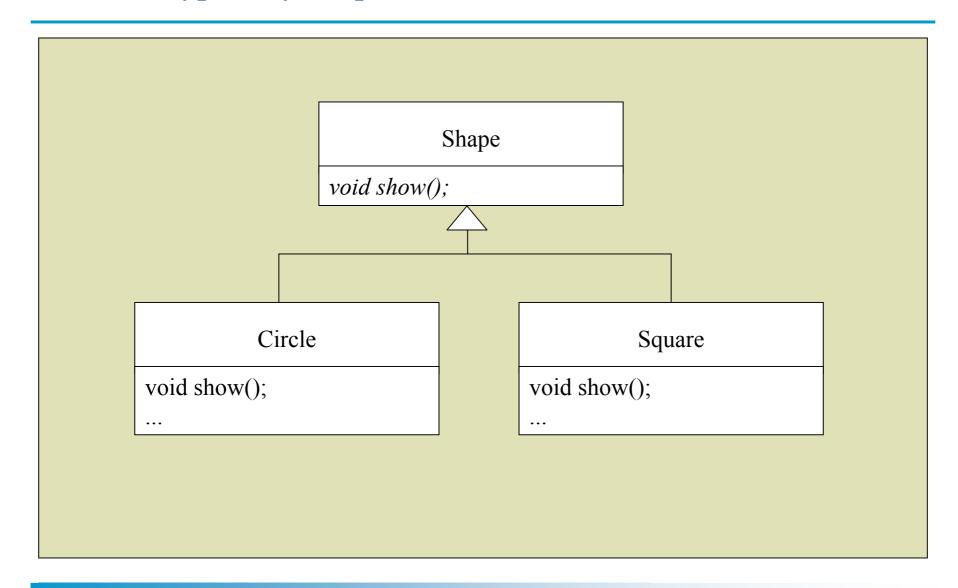


Overview

- Classes
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I.2.1. Subtype Polymorphism Virtual Functions



I.2.1. Subtype Polymorphism Virtual Functions

Example:

```
class Shape {
public:
  virtual void show() = 0;
};
class Circle : public Shape {
  double r m;
public:
  void show(); // virtual !
  Circle(double r) : r m(r) {}
};
class Square : public Shape {
  double r 1;
public:
  void show(); // virtual !
  Square(double 1) : r 1(1) {}
};
```

```
Shape* Sptr = new Square(3);
Circle c(4);

Shape& Sref = c;
Shape S;  // illegal !

Sptr->show(); // Square::show
Sref.show(); // Circle::show
S.show(); // illegal !!
```

If a virtual member function is **overridden** by a derived class and called through a *pointer* or *reference*, the type of the pointed to/referenced object determines which function gets called.

I.2.1. Subtype Polymorphism Virtual Functions 2

- If a virtual member function is **overridden** by a derived class and called through a *pointer* or *reference*, the type of the *pointed to/referenced* object determines which function gets called.
- Type of *pointed to/referenced* object maybe unresolvable during compile-time
- Therefore: dynamic binding (or late binding) is a runtime mechanism

Redefining a virtual member function in a derived class is called **overriding**

Remark: Some people distinguish **overriding** and **augmenting**, whereas overriding means to completely substitute the implementation of the base class and augmenting refers to extending the implementation of the base class (by e.g. making a call to it).



Note 9: Parameterized Inheritance

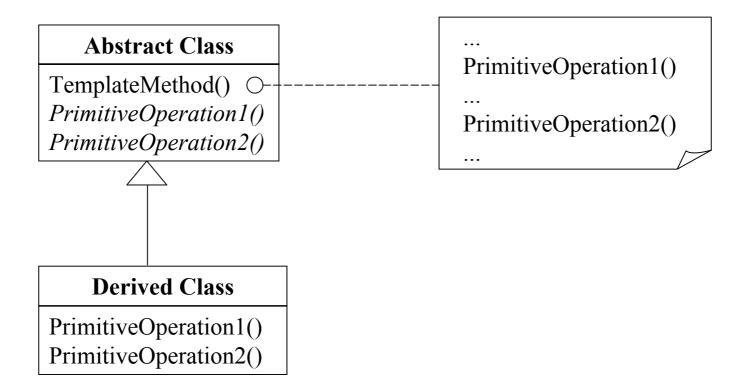
! C++ supports parameterized inheritance / subtype polymorphism

```
template <class SuperClass>
class DerivedClass : public SuperClass {
   ...
};
```

This technique often is used to implement static wrappers or template methods. It also maybe used as an alternative to multiple inheritance for implementing mixin-based designs.

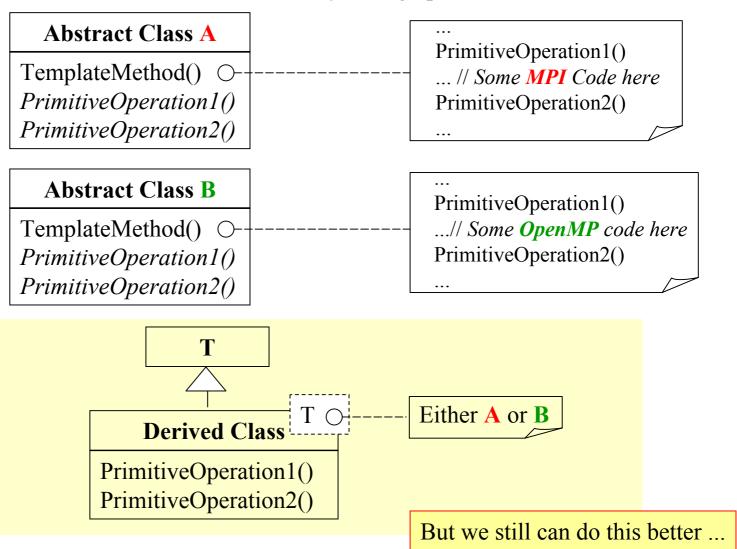
Note 9: Parameterized Inheritance

Example: Template Method



Note 9: Parameterized Inheritance

Example: Template Method - **Increased flexibility** through parametrized inheritance



Note 9: Parameterized Inheritance - Pitfall

! Take care when using similar names for methods / functions !

```
void afunc() {
  cout << "global afunc !" << endl;</pre>
class A {
protected:
  virtual void afunc() {
    cout << "A's afunc !" << endl;</pre>
};
template <class SuperClass>
struct DerivedClass : public SuperClass {
  void tfunc() {
                                      Always calls global afunc!
    afunc();
                                        (Relation to SuperClass is unclear!)
};
DerivedClass<A> a;
a.tfunc(); Prints "global afunc!"
```

Note 9: Parameterized Inheritance - Pitfall - Solution

! Take care when using similar names for methods / functions!

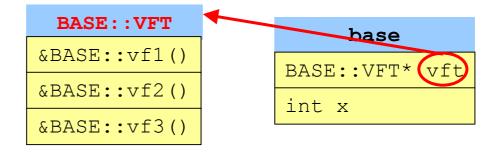
```
void afunc() {
  cout << "global afunc !" << endl;</pre>
class A {
protected:
  virtual void afunc() {
    cout << "A's afunc !" << endl;</pre>
};
template <class SuperClass>
struct DerivedClass : public SuperClass {
  typedef DerviedClass<SuperClass> self;
  void tfunc() {
    self::afunc();
                     Now relation is clear!
};
```

I.2.1. Subtype Polymorphism Method Dispatch - Basics

```
class BASE {
private:
   int x;
public:
   virtual void vf1();
   virtual void vf2();
   virtual void vf3();
};

BASE* base = new BASE;
```

Create Virtual Function Table (VFT) for every class with virtual members or inherited virtual members:



Object contains pointer to VFT

Call to base->vf1() is transformed into base->vft[0] (base)

Remember the implicit parameter (this)

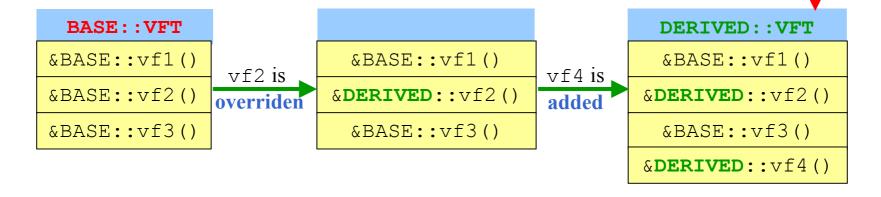


I.2.1. Subtype Polymorphism Method Dispatch - Single Inheritance

```
class DERIVED : public BASE {
  int y;
public:
  void vf2();
  virtual void vf4();
}; overrides BASE::vf2 adds vf4 and y

DERIVED* derived = new DERIVED;
```

Start with the VFT of the BASE class:





derived

DERIVED::VFT* (vft

int x

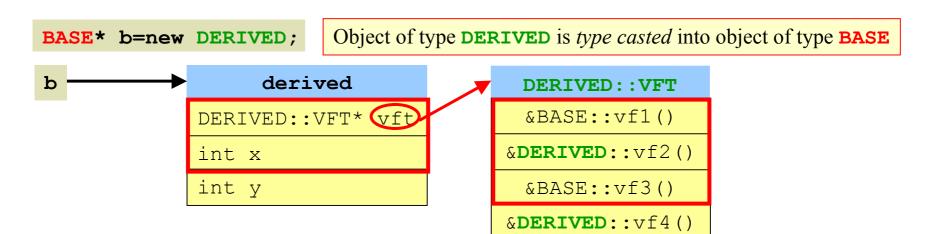
int y

I.2.1. Subtype Polymorphism Method Dispatch - C-style type casting

• Single inheritance utilizes C-style casting

C-style *type casting*

C-style type casting an object of type A into an object of type B means to handle the address space used by A as if it contains an object of type B.



The derived object's memory layout is compatible with objects of type BASE.

call to b->vf2() is transformed into b->vft[1](base)

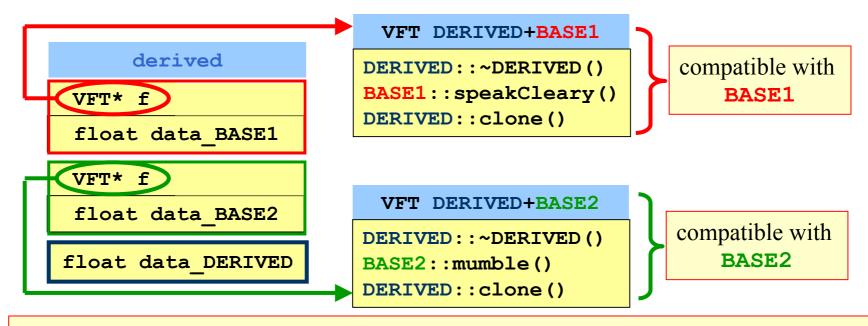
I.2.1. Subtype Polymorphism Method Dispatch - Multiple Inheritance

• C-style casting does not work under the presence of Multiple Inheritance (MI)

```
class BASE1 {
                                 class BASE2 {
public:
                                 public:
  BASE1();
                                   BASE2();
                                   virtual ~BASE2();
  virtual ~BASE1();
  virtual BASE1* clone() const;
                                  virtual BASE2* clone() const;
protected:
                                 protected:
                                   float data BASE2;
  float data BASE1;
};
                                 };
class DERIVED : public BASE1, public BASE2 {
public:
 DERIVED();
                                Note: DERIVED may either be casted to BASE1
 virtual ~DERIVED();
                                     or BASE2:
 virtual DERIVED* clone() const;
protected:
                                     BASE1* b1 = new DERIVED;
  float data DERIVED;
                                     BASE2* b2 = new DERIVED;
};
```

I.2.1. Subtype Polymorphism Method Dispatch - Multiple Inheritance II

- DERIVED needs access to BASE1's VFT and BASE2's VFT
- store pointer to *both* VFT's inside of object:



Observation:

- 1) A pointer to an instance of **DERIVED** is cast compatible with a pointer to an instance of **BASE1**.
- 2) If incremented by sizeof (BASE1), a pointer to an instance of DERIVED is cast compatible with a pointer to an instance of BASE2.



I.2.1. Subtype Polymorphism Method Dispatch - Multiple Inheritance III

Adjustment of the this pointer during runtime is necessary:

```
BASE2* pbase2 = new DERIVED;
```

*pbase2 needs to behave like an instance of BASE2 - increment pbase2 by sizeof (BASE1):

```
DERIVED tmp* = new DERIVED;
BASE2* pbase2 = tmp + sizeof(BASE1);
```

Nonpolymorphic access to members of BASE2 still works (e.g. pbase2->data_BASE2)

BASE1::speakClearly is inaccessible now - unacceptable during virtual function calls!

Thus: if *calling a virtual function* the implicitly **this** parameter has to be adjusted in order to point to the beginning of the object - store suitable offset o inside object.

```
becomes

BASE2* theClone = pbase2->clone();

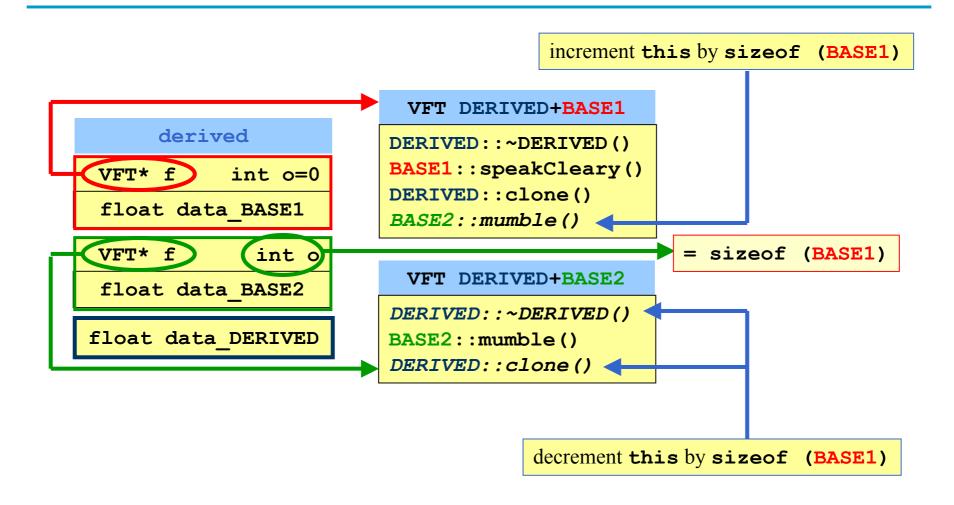
becomes

BASE2* theClone = pbase2->f->clone( pbase2 - pbase2->o );

call DERIVED::clone -> this has to be of type DERIVED!
```



I.2.1. Subtype Polymorphism Method Dispatch - Multiple Inheritance IV



This is how *cfront* implements virtual function calls.



Note 10: Thunks

- !
- The VFT technique *penalizes all virtual function* invocations regardless of whether the offset adjustment is necessary, both in the
 - cost of one extra access and addition of offset and in
 - the *increased size* of each virtual table slot.
- Many compilers (e.g. GCC) use **thunks** for virtual function calls.

A **thunk** is a small assembly stub that adjusts the **this** pointer with the appropriate offset and then jumps to the virtual function.

The thunk associated with the call to the **DERIVED** class destructor through a **BASE2** pointer look as follows:

```
Pbase2_dtor_thunk:
   this -= sizeof(BASE1);
   DERIVED::~DERIVED( this );
```

Address placed within the VFT either directly addresses the virtual function or points to the associated thunk.

I.2.1. Subtype Polymorphism Penalties

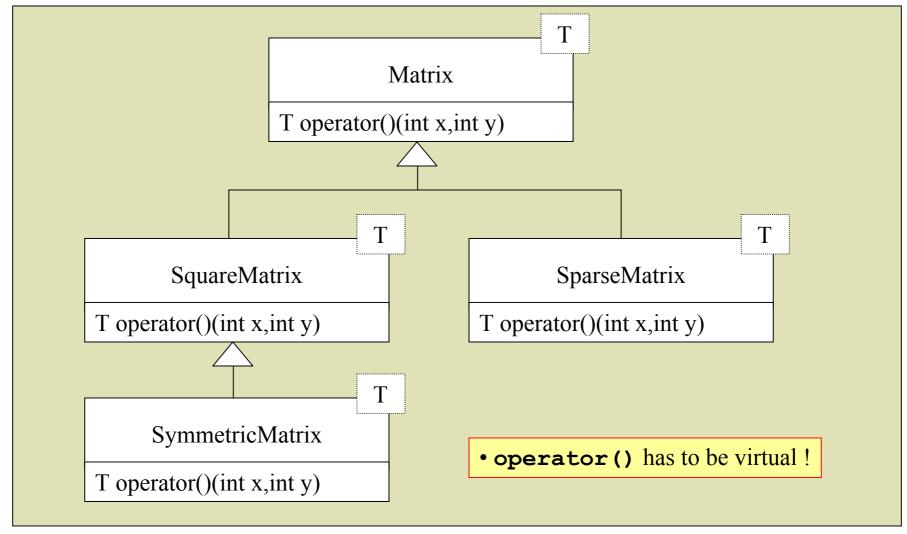
- standard implementation of virtual dispatch uses virtual function tables (VFT) which are basically tables of function pointers
- Initialization of pointer to **VFT** in constructor code
- in a typical implementation a virtual function call involves
 - 1. two indirections to get the function pointer out of the VFT (get the VFT address and then the function address from the VFT)
 - 2. an extra indirection to get the pointer casting offset from the VFT (the offset is needed for multiple inheritance to work correctly)
 - 3. Offset addition (object plus the pointer casting offset)
 - 4. Function call
- small memory overhead (one VFT per class / at least one pointer to VFT + pointer casting offset per object.
- virtual function calls may prevent the compiler from applying various optimizations (the target of the call is unknown during compile time)

Avoid virtual functions, if they are small and used frequently!



Note 11: Avoiding virtual Functions - Engines

- Consider matrices with different storage schemes (dense, sparse, symmetric, etc.)
- Usual OO approach: build hierarchy (e.g. **SquareMatrix is-a Matrix**):



Note 11: Avoiding virtual Functions - Engines II

```
template <typename T> class Symmetric {
 // Encapsulates storage info for symmetric matrices
};
template <typename T> class Square {
 // Encapsulates storage info for square matrices
};
template<class Engine T> // Wrapper
class Matrix {
private:
 Engine T engine;  // has an instance of an engine
                         // (imports Engine t's functionality)
};
// Example routine which takes any matrix structure
template<class <pre>Engine T>
double sum(Matrix<Engine T>& A);
// Example use ...
Matrix<Symmetric<double> > A;
sum(A);
```

Note 11: Avoiding virtual Functions - Engines III

• Delegate functionality to the engine

```
template <typename T> class Symmetric {
  typedef T Element T;
  inline Element t& operator()(int x,int y) { ... }
  bool isPositiveDefinite() { ... }
};
template<class Engine T>
class Matrix {
  typedef typename Engine T:: Element T Element T;
  inline Element T& operator()(int x,int y) {
    return engine(x,y);
  bool isPositiveDefinite() {
     return engine.isPosisitiveDefinite();
private:
  Engine T engine; // instance of engine
};
```

- Matrix *subtypes* types must have the same member functions
- Some members only make sense for a subset of all subtypes (e.g. isPositiveDefinite)

Note 11: Avoiding virtual Functions - Engines IV

- What about **Square**?
- Needs to have **isPositiveDefinite** as well:

```
template <typename T> class Square {
  typedef T Element_T;
  inline Element_t& operator() (int x,int y) { ... }
  bool isPositiveDefinite() {
    throw makeError("Method not defined for square matrices !");
  }
};
```

Matrix base class needs to have the union of all methods provided by the subtype

if you have to deal with a huge class hierarchy, adding a single method to a subtype means to change every subtype as well!

Note 12: Avoiding virtual Functions - Barton/Nackman Trick I

```
// Base class takes a template parameter. This parameter
// is the type of the class which derives from it.
template<class Leaftype T>
class Matrix {
public:
  Leaftype T& asLeaf() { return static cast<Leaftype T&>(*this);}
  // delegate to leaf
  double operator()(int i, int j) { return asLeaf()(i,j); }
};
class SymmetricMatrix : public Matrix<SymmetricMatrix> { ... };
class UpperTriMatrix : public Matrix<UpperTriMatrix> { ... };
// Example routine which takes any matrix structure
template<class Leaftype T>
double sum(Matrix<Leaftype T>& A);
// Example use ...
SymmetricMatrix A;
sum(A);
```

Note 12: Avoiding virtual Functions - Barton/Nackman Trick II

- More convenient inheritance-hierarchy approach
- Base class still delegates functionality to the leaf classes
- Members can selectively specified / specialised in the leaf class

```
template<class Leaftype T>
class Matrix {
public:
  Leaftype T& asLeaf() { return static cast<Leaftype T&>(*this);}
  // delegate to leaf
  double operator()(int i, int j) { return asLeaf()(i,j); }
 bool isPositiveDefinite() {
    throw makeError("Method not defined for square matrices !");
};
class SymmetricMatrix : public Matrix<SymmetricMatrix> {
 bool isPositiveDefinite() { ... }
};
```

Overview

- Classes
- Polymorphism
 - Inheritance
 - Overloading
 - Conversions
 - Templates
- Further Topics
- References



I.2.2. Overloading

Overloading

In C++ functions are identified by their **name** *and* their **argument types**. Having multiple functions of the same name but different argument types is called **overloading**.

```
void swap(int& a,int& b) {
  int t;
  t=a; a=b; b=t;
}

void swap(double& a,double& b) {
  double t;
  t=a; a=b; b=t
}
```

• Overloading on the return type is not supported, because a function may be called just for its side effects:

```
e.g. foo(); instead of ResultType t = foo();
```



I.2.2. Overloading

• Besides function overloading C++ supports **operator overloading**.

Binary Operator Overloading

A binary operator is an infix function that may be written between their arguments rather before them, as in the case for ordinary functions.

I.2.2. Overloading - A Sample Class

• Sample class to represent complex numbers:

```
class Complex {
private:
  double re;
  double im;
public:
  Complex (double r=0.0, double i=0.0) : re(r), im (i) {}
  Complex(const Complex& rhs) : re(rhs.re),im(rhs.im) {}
  const double& real() const { return re; }
  const double& imag() const { return im; }
  double& real() { return re; }
  double& imag() { return im; }
};
```

I.2.2. Overloading - Assignment Operators

• The assignment operator (**operator=**) can be overloaded. *It has to be implemented as a class member function*:

```
Complex& Complex::operator=(const Complex& rhs) {
  re = rhs.real() ; im = rhs.imag();
  return *this;
}
```

• To allow daisy chaining (e.g. a = b = c), assignment operators return references.

If not defined, the compiler *automatically creates* an **assignment operator** that performs a memberwise copy.

• Do not forget to distinguish between copy constructor and assignment operator

I.2.2. Overloading - Arithmetic Operator Overloading

- C++ allows arithmetic operators (+=, -=, *=, /=, %= and their binary cousins +, -, *, /, %) to be overloaded
- Overloaded operators are syntactic sugar allowing to write code like

```
Complex a,b,c,d;
a = b + c * d;
```

- Operator precedence cannot be changed, thus, b + c * d always is identical to b + (c * d)
- Inventing new operators is impossible (e.g. (c ** d))

I.2.2. Overloading - Arithmetic Assignment Operators

• Arithmetic assignment operators (+=, -=, *=, /=, %=) are overloaded through class member functions

```
const Complex& Complex::operator+=(const Complex& rhs) {
  re += rhs.real() ; im += rhs.imag();
  return *this;
}
```

• return const object to disallow expressions like (a += b) ++

```
Complex a,b; transformed by compiler into
a+=b;

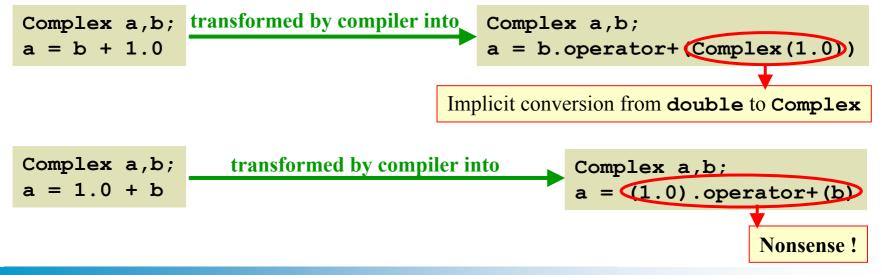
Complex a,b;
a.operator+=(b);
```

I.2.2. Overloading - Binary Arithmetic Operators & Member Functions

Binary operators shouldn't be class members - especially if the operation should be **commutative**.

```
Complex Complex::operator+(const Complex& a) const {
  return Complex(*this) += a ;
}
```

• Due to the presence of a constructor from **double**, a value of type **double** *implicitly* can be *converted* into a value of type **Complex**. Thus, this operator implicitly defines how to add a **double** to a **Complex** - but *not* how to add a **Complex** to a **double**:





I.2.2. Overloading - Binary Arithmetic Operators & Free Functions

• **Binary operators** should not be class members, but free functions:

```
Complex operator+(const Complex& a,const Complex& b) {
   Complex tmp;
   tmp.re = a.real() + b.real();
   tmp.im = a.imag() + b.imag();
   return tmp;
}
```

To gain access to a class' private data members, a binary operator can be made a **friend** function, or it can be based on the implementation of **operator+=**:

```
Complex operator+(const Complex& a,const Complex& b) {
  return Complex(a)+=b;
}
```

Binary operators have to return their result by value, because a new object is created!



I.2.2. Overloading - Penalties

At first glance the following code seems harmless:

```
Complex a,b,c;
a = b + c;
Complex a,b,c,d;
a.operator=(operator+(b,c));
```

Unfortunately we have to deal with *two* temporary objects:

- operator+ creates a temporary (local object)
- another temporary is created to return the result by value:

```
Complex tmp;
```

return tmp;

Constructor needs to be called *two* times - **very expensive** for e.g. matrices

• implicit conversion may introduce additional temporaries (see next section), e.g.

```
Complex a,b;
a = b + 1;
```

• Overload resolution consumes compile time



Note 13: Named Return Value (NRV) Optimization

• Some compilers perform the Named Return Value Optimization.

```
Complex operator+(const Complex& a,const Complex& b) {
   Complex tmp;
   tmp.re = a.real() + b.real();
   tmp.im = a.imag() + b.imag();
   return tmp;
}
Complex c = a + b;
```

• two temporaries get created: local temporary tmp and temporary to carry result

NRV

- eliminates local temporary, copy constructor call, and destructor call
- does not apply if multiple return statements return objects of different name
- probably problematic (copy constructor has side effects)

Note 13: Named Return Value (NRV) Optimization II

```
Complex operator+(const Complex& a,const Complex& b) {
   Complex tmp;
   tmp.re = a.real() + b.real();
   tmp.im = a.imag() + b.imag();
   return tmp;
}
```

♦ NRV (eliminates *local* temporary tmp)

Note 14: Optimizing away Temporary Return Values

```
Complex c = a + b;
    Complex c; // Raw memory - no constructor call here !
    Complex retval;
                              // Temporary to hold return value
    optimized
    Complex::Complex(c, retval ); // copy construct c from retval
    Complex::~Complex(retval) // destruct temporary
    Complex c;
                                  No temporary needed!
    operator+(c,a,b);
c = a + b;
    Complex retval;
                             // Temporary to hold return value
    operator+(retval,a,b);
                             // compute result
                             // expects retval to be raw memory
    Complex::~Complex(retval);  // destruct temporary
    Complex::~Complex(c);// must call destructor here
    operator+(c,a,b); // semantically Complex::Complex(c, a + b );
```

assignment vs. **destruction** + **copy construction** - cannot remove temporary

Note 15: Computational Constructors

What, if your compiler does not perform the NRV?

• **Solution 1**: do computation within constructor:

- How to perform subtraction now? This scheme leads to ambiguous constructor definitions!
- Introduce a Tag Class

Note 15: Computational Constructors

```
struct Add {};
struct Sub {};
class Complex {
  //...
public:
  Complex (double r=0.0, double i=0.0) : re(r), im (i) {}
  Complex(const Complex& rhs) : re(rhs.re),im(rhs.im) {}
  Complex(const Complex& a,const Complex& b,const Add&) :
      re(a.re + b.re),
      im(a.im + b.im) {}
  Complex(const Complex& a,const Complex& b,const Sub&) :
      re(a.re - b.re),
      im(a.im - b.im) {}
  // ...
};
```

```
Complex operator+(const Complex& a, const Complex& b) {
   return Complex(a,b,Add());
}
Complex operator-(const Complex& a, const Complex& b) {
   return Complex(a,b,Sub());
}
```

Note 16: Reuse Arithmetic Assignment Operqutors

! Consider reusing arithmetic assignment operators. Does this make sense ?

```
const Complex& Complex::operator+=(const Complex& rhs) {
   re += rhs.real() ; im += rhs.imag();
   return *this;
}

No temporary here!

Complex operator+(const Complex& a,const Complex& b) {
   return Complex(a)+=b;
}

Anonymous temporaries get optimized away by most compilers - but you need to provide a copy constructor!
```

But: we still need a temporary to carry the return value!

Note 17: *op++ vs. ++op*

! Prefer ++op / --op if possible !

Semantics of op++ / op--: Return the current value of op - then increment / decrement it

```
X X::operator++(int) {
    X current(*this);

//... Computation to increment *this (e.g. perform ++(*this))
    return current;
}
```

Semantics of ++op / --op: Return the incremented / decremented value of op

```
X X::operator++() {
   //... Computation to increment *this
   return *this;
}
No local temporary needed !!
```

Note 18: Arithmetic Assignment Operators to Replace Binary Op's

Observation:

Usually arithmetic assignment operators can be implemented without introducing a local temporary.

```
Complex a,b;
result = a + b; // local temporary gets created !

transformed by hand

Complex a,b;
result = a; // operator= - no local temporary
result += b; // operator+= - no local temporary
```

... unfortunately, we loose a lot of beauty here ...

Overview

- Classes
- Polymorphism
 - Inheritance
 - Overloading
 - Conversions
 - Templates
- Further Topics
- References



I.2.3. Conversions

- C++ supports user defined / automatic conversion
- Unary constructors can be used to perform **implicit conversion** from the type of ist first parameter to the type of its class

```
Complex a,b;
a = b + 1;

Is converted into Complex through unary constructor
```

- implicit conversion introduces temporary objects
- use keyword explicit to disallow implicit conversion, e.g.:

```
explicit Complex(double r=0.0, double i=0.0) : re(r), im(i) {}
```

- unary constructors cannot be used to
 - 1.) convert a user type into a fundamental type (e.g. int, double)
 - 2.) convert a new class to an existing one (need to change existing class)



I.2.3. Conversions - Conversion Functions

• conversion functions are special class member functions, e.g.:

```
Complex::operator
  return real();
}
return type specified by operator name only
```

• Caution: ambiguities are possible

```
Complex a = b + 5

operator+(Complex, Complex) or built-in operator+(double, double) ?
```

- an implicit conversion sequence is one of the following forms
 - **1.)** a standard conversion sequence
 - **2.)** a user-defined conversion sequence
 - 3.) an ellipsis conversion sequence



I.2.3. Conversions - Standard Conversions I

1. Lvalue-to-rvalue conversion

Exact Match

An Ivalue is an expression that may be used to the left of an assignment operator. An rvalue is an expression that may be used to the right of an assignment operator: it represents a value that does not have an address and that cannot be modified.

```
int& f() { ... }
int x = f();
```

2. Array to pointer conversion

Exact Match

An array of **T**'s can be converted into a pointer to **T**

```
int i[20];
int* j=i;
```

3. Function to pointer conversion

Exact Match

An Ivalue of function type **T** can be converted to an rvalue of type "pointer to **T**." The result is a pointer to the function.

```
int& (g^*)() = f;
```



I.2.3. Conversions - Standard Conversions II

4. Qualification conversion

Exact Match

A qualification conversion adds **const** or **volatile** qualifications to pointers.

```
int f(const int& a) { return a + 3; }
int i;
f(i);
```

5. Floating point promotion

Promotion

An rvalue of type **float** can be converted to an rvalue of type **double**.

```
float f;
double d;
d = f;
```

6. Floating point conversion

Conversion

An rvalue of floating point type can be converted to an rvalue of another floating point type.



I.2.3. Conversions - Standard Conversions III

7. Integral promotion

Promotion

- An rvalue of type char, signed char, unsigned char, short int, or unsigned short int can be converted to an rvalue of type int if int can represent all the values of the source type; otherwise, the source rvalue can be converted to an rvalue of type unsigned int.
- An rvalue of type wchar_t or an enumeration type can be converted to an rvalue of the first of the following types that can represent all the values of its underlying type: int, unsigned int, long, or unsigned long.
- An rvalue for an integral bit-field can be converted to an rvalue of type int if int can represent all the values of the bit-field; otherwise, it can be converted to unsigned int if unsigned int can represent all the values of the bit-field. If the bit-field is larger yet, no integral promotion applies to it. If the bit-field has an enumerated type, it is treated as any other value of that type for promotion purposes.

I.2.3. Conversions - Standard Conversions IV

8. Integral conversion

Conversion

An rvalue of an integer type can be converted to an rvalue of another integer type. An rvalue of an enumeration type can be converted to an rvalue of an integer type.

9. Floating-integral conversion

Conversion

- An rvalue of a floating point type can be converted to an rvalue of an integer type. The conversion truncates; that is, the fractional part is discarded.
- An rvalue of an integer type or of an enumeration type can be converted to an rvalue of a floating point type. The result is exact if possible.

10. Pointer conversion

Conversion

- An rvalue of type pointer to $cv \, \mathbf{T}$, where \mathbf{T} is an object type, can be converted to an rvalue of type pointer to $cv \, \mathbf{void}$.
- An rvalue of type pointer to cv D, where D is a class type, can be converted to an rvalue of type pointer to cv B, where B is a base class of D.

cv=[const,volatile] - (may be empty)



I.2.3. Conversions - Standard Conversions V

11. Pointer to member conversions

Conversion

An rvalue of type pointer to member of B of type cv T, where B is a class type, can be converted to an rvalue of type pointer to member of D of type cv T, where D is a derived class of B.

12. Boolean conversions

Conversion

An rvalue of arithmetic, enumeration, pointer, or pointer to member type can be converted to an rvalue of type bool. A zero value, null pointer value, or null member pointer value is converted to false; any other value is converted to true.



I.2.3. Conversions - Conversion Sequences

Standard Conversion Sequence

A **standard conversion sequence** is either the Identity conversion by itself (that is, no conversion) or consists of one to three conversions from the categories Lvalue Transformation, Qualification Adjustment, Promotion, and Conversion. At most one conversion from each category is allowed in a single standard conversion sequence.

User-defined Conversion Sequence

A **user-defined conversion sequence** consists of an initial standard conversion sequence followed by a user-defined conversion followed by a second standard conversion sequence.

Only *one* user-defined conversion per conversion sequence!

Ellipsis Conversion Sequence

An **ellipsis conversion sequence** occurs when an argument in a function call is matched with the ellipsis parameter specification of the function called.



Note 19: Overloading on Return Type

Suppose we want to overload functions based on the return type:

```
class A { ... };
class B { ... };

A foo(int x) { ... } // 1
B foo(int x) { ... } // 2

A a = foo(3); // calls 1
B b = foo(3); // calls 2
```

We can't do that in C++. But we can fake it!

Idea: provide a single function **foo** that returns a value that can be converted into a value of type **A** or a value of type **B** respectively - let **foo** return a **proxy object**!

Note 19: Overloading on Return Type

```
A fooA(int x) { ... }
B fooB(int x) { ... }
class C {
  int x m;
public:
  C(int x) : x m(x) \{ \}
  operator A() const { return fooA(x m); }
  operator B() const { return fooB(x m); }
};
C foo(int x) { return C(x); }
A = foo(3); // calls C::operator A() - calls fooA
B b = foo(3); // calls C::operator B() - calls fooB
```

Calling a function just for its side effects is not possible anymore!

Overview

- Classes
- Polymorphism
 - Inheritance
 - Overloading
 - Conversions
 - Templates
- Further Topics
- References



I.2.4. Templates

- Allows a part of a program to be used with different types
- Types as additional parameters to function / class / or member function declarations
- Substitution of type parameters during compile time (template instantiation)
- Ideal for container classes (e.g. Stack, List, Tree STL)
- C++ supports
 - function templates
 - class templates
 - member function templates



I.2.4. Templates - Function Templates

```
template <typename T>
void copyArray(const T& source, T& dest, int size) {
  for (int i=0 ; i<size ; i++)
    dest[i]=source[i];
}</pre>
```

- T is a type parameter
- no code is generated until template gets **instantiated**

Instantiation

Instantiation is the process of binding actual types and expressions to the associated type parameters of the template.

```
int aI[100], bI[100];
...
copyArray(aI,bI,100);
```

• Using the **copyArray** template the instantiation process binds **T** to **int*** and creates a program text instance of **copyArray** (by possibly overloading existing versions).



I.2.4. Templates - Multiple Type Parameters

```
template <typename T>
void copyArray(const T& source,T& dest,int size) {
  for (int i=0 ; i<size ; i++)
     dest[i]=source[i];
}
int aI[100], bI[100];
double aD[100],bD[100];
...
copyArray(aI,bI,100); // o.k. instantiation with T=int*
copyArray(aD,bD,100); // o.k. instantiation with T=double*
copyArray(aI,bD,100); //error: source and dest must be of same type</pre>
```

• Introduce second type parameter to make this work:

```
template <typename T1, typename T2>
void copyArray(const T1& source, T2& dest, int size) {
   for (int i=0 ; i < size ; i++)
        dest[i]=source[i];
}

Constraint: elementwise conversion from T2 to T1 must exist!
        But: there are more constraints here!</pre>
```

I.2.4. Templates - Explicit Qualification

```
template <typename T>
T average(const T& a,const T& b) {
   return (a + b) / 2;
}
int a,b;
double c,d;
...
average(a,b); // o.k. instantiation with T=int
average(c,d); // o.k. instantiation with T=double
average(a,c); // error: source and dest must be of equal Type T
```

- **problem:** type cannot be deduced from arguments (**int** or **double**?)
- use explicit qualification

• explicit qualification can be **mandatory**

```
template <typename R, typename A>
R convert_A2R(A a) { return R(a); }
```



I.2.4. Templates - Class Templates

• Classes may be templates:

• Like function templates, only instantiated if needed

```
dArray<int> aI(100),bI(100);
dArray<double> aD(100),bD(100)
```

• Does copyArray (aI,bI) work?

Yes: dArray<int> provides a subscript operator and copy from int to int is trivial!



I.2.4. Templates - Non-type Parameters I

- What if we don't want to use dynamic memory allocation because the size of the array is always known during compile time?
- Make **size** a template parameter:

```
template <typename T,int size>
class sArray {
private:
   T data[size];
public:
   T& operator[](int s) { return data[s]; }
   const T& operator[](int s) const { return data[s]; }
};
```

• Still works with copyArray but we can utilize that size is known at compile time:

```
template <typename T1, typename T2, int s>
void copyArray(sArray<T1, s>& source, sArray<T2, s>& dest, int S=s) {
  for (int i=0 ; i<S ; i++)
    dest[i]=source[i];
}</pre>
```



I.2.4. Templates - Non-type Parameters II

- A non-type *template-parameter* shall have one of the following (optionally *cv-qualified*) types:
 - integral or enumeration type,
 - pointer to object or pointer to function,
 - reference to object or reference to function,
 - pointer to member.
- non-type parameters **shall not** be declared to have
 - floating point type (e.g. **float**, **double**)
 - class type
 - void type

```
template <double& a> struct A {...};  // is o.k. !
template <float* b> struct B {...};  // o.k. as well !
Template <double d> struct C {...};  // error !
```



I.2.4. Templates - Template Template Parameters

• templates as template parameter

```
template <class T, template <class U> class C>
class Group {
   C<T> container;
};
```

- a template template argument shall be the name of a *class templates*!
- function templates are not allowed as template template arguments
- instantiation:

```
Group< double, std::list > a; // use class template std::list.
Group< int, std::vector > b; // use class template std::vector
```

I.2.4. Templates - Member Templates I

• a class member function can be a template

```
template <typename A>
class foo {
private:
   A value;
public:
   foo(const A& v) : value(v) {}
   template <typename T>
   void setValue(const T& v) { value = v; }
};
```

• definition of class member template outside class definition

```
template <typename A>
template <typename T>
void foo<A>::setValue(const T& v) { value = v; }
```

- a class template may contain member templates and/or other class templates
- class member templates may not be virtual
- local classes shall not contain member templates



I.2.4. Templates - Member Templates II

• a specialization of a member template does not override a virtual function from a base class:

• calling template conversion functions:

I.2.4. Templates - Default Template Arguments

• a default template argument may be specified for any type of template parameter

```
template <typename T,int size = 1000>
class sArray { ... };
```

- may only be specified in a class template declaration / definition
- if a template parameter has a default argument, all subsequent template parameters shall have a default argument as well.

```
template <typename T = double, int size> // error !
class sArray {... };
```

• The scope of a *template-parameter* extends from its point of declaration until the end of its template.

```
template<class T, T* p, class U = T> class X { ... };
```

• caution: the first non-nested > is taken as the end of template parameter list

```
template <int s = 2 > 42 > ... // error !
template <int s = (2 > 42) > ... // o.k.
```

I.2.4. Templates - Explicit Instantiation

- usually template instantiation is done implicitly by the compiler
- it also can be done explicitly by the programmer

- if a class gets explicitly instantiated, every member gets instantiated as well
- explicit instantiation can save compile time and link time



I.2.4. Templates - Specialization

• class templates, function templates and member templates may be explicitly specialized

```
template <typename T>
struct A {
  void bar(const T&);
  static void foo() { cout << "Hello !" << endl; }
};

template <>
struct A<char*> {
  static void foo() { cout << "World" << endl; }
};

A<int>::foo(); // prints "Hello !"
A<char*>::foo(); // prints "World"
```

• nothing gets implicitly instantiated during explicit specialization

```
A<char*>::bar("Hello"); // error ! Method bar not defined in // specialization of A
```

• implicitly generated and explicitly specialized classed do not need to be related!



I.2.4. Templates - Specialization II - Specialization of Class Members / Member Templates

• Specialization of members is allowed even if they have been defined in class definition

```
template <typename A>
class foo {
  template <typename T>
  T void id (const T& t) {
    return t;
  }
 void f(const A& a);
};
template <>
                                // specialization of member
void foo<int>::f(const int& a);
template <>
                                // specialization of member template
template <>
int void foo<int>::id<double>(const double& d) {
  return d*2;
};
```

I.2.4. Templates - Specialization III - Point of Declaration / Point of Instantiation

• placement of explicit specialization declaration is important!



I.2.4. Templates - Specialization IV - Function Templates - Inline / Static Vars

• an explicit specialization of a function template is inline only if it is explicitly declared to be

```
template <typename T> inline T twice(const T& t) {
  return 2 * t;
}

template <> int twice<int>(const int& t) { // not inline !
  return t << 1;
}</pre>
```

• each function template specialization has its own copy of any static variables

```
template <typename T> void test(T a) {
   static int j;
   cout << j << " ";
   j=a; cout << j << endl;
}

double d=3.33; int i=2;
test(d); // prints "0 3"
test(i); // prints "0 2"
test(d); // prints "3 3"</pre>
```

I.2.4. Templates - Class Template Partial Specialization

• Primary Template (unspecialized)

```
template <typename A, typename B, int i> class foo {};
```

• Partial Specialization - B=A* - B is a pointer to A

```
template <typename Q,int j> class foo<Q,Q*,j> {};
```

• Partial Specialization - A is a pointer

```
template <typename Q, typename R, int j> class foo<Q*,R,j> {};
```

• Partial Specialization - A is an int, B is a pointer

```
template <typename Q,int j> class foo<int,Q*,j> {};
```

• Full Specialization A=int B=int i=3

```
template <> class foo<int,int,3> {};
```

foo<int,int*,5> a; // selects third specialization



I.2.4. Templates - Partial Specialization - Member Templates

```
template <typename A> class foo {
  template <typename B> class bar {
    template <typename C> class zap { ... };
  };
};
```

• full specialization - all template parameter get bound

```
template <> template<>
class foo<int>::bar<int>::zap<int> {
};
```

• partial specialization - few template parameter get bound (outer to inner)

```
template <> template<typename B> template<typename C>
class foo<int>::bar<B>::zap<C> {
};
```

• specializing a class template / class member template without specializing enclosing templates is illegal

```
template <typename A> template<typename B> template<>
class foo<A>::bar<B>::zap<int> { // ILLFORMED !
};
```

Note 20: How to specialize inner-class template I

```
template <typename A> template<typename B> template<>
class foo<A>::bar<B>::zap<int> { ...}; // ILLFORMED
template <typename A, typename B, typename C>
struct zap { ... };
template <typename A, typename B>
struct zap<A,B,int> { ... }; // Allowed specialization !
template <typename A>
struct foo {
                                   Problem: zap is not in scope of foo and bar
   typedef int Value t;
   template<typename B>
   struct bar {
                                   But: zap can access all static information that is
     template<typename C>
                                   exported by foo and bar!
     struct zap {
       typedef zap<A,B,C> Ret;
     };
   };
};
foo<int>::bar<double>::zap<int>::Ret a; // Selects partial
                                          // specialization of zap
```

Note 20: How to specialize inner-class template II

```
template <typename A> foo; // Declare foo such that we can use it
                            // within zap
template <typename A, typename B, typename C>
struct zap {
  typedef typename foo<A>::Value t Value t;
};
template <typename A, typename B>
                                         Import type definition from foo
struct zap<A,B,int> {
  typedef typename foo<A>::Value t Value t;
};
template <typename A>
struct foo {
   typedef int Value t; // 'Export' a type definition
   template<typename B>
   struct bar {
     template<typename C>
     struct zap {
       typedef zap<A,B,C> Ret;
     };
   };
};
```

Overview

- Classes
- Polymorphism
 - Inheritance
 - Overloading
 - Conversions
 - Templates
- Further Topics
- References



```
void foo(double y[], const double* a, int n ) {
  for( int i=0; i<n; i++ )
    y[i] = 1.0 - *a;
}</pre>
```

Assuming the *a remains invariant during execution of the loop, we can perform the following optimization:

```
void foo(double y[], const double* a, int n ) {
  float temp = 1.0 - *a;
  for( int i=0; i<n; i++ )
    y[i] = temp;
}</pre>
```

Problem: If y and a overlap, this optimization changes the semantics!



```
void foo(double y[], const double* a, int n ) {
  for( int i=0; i<n; i++ )
    y[i] = 1.0 - *a;
}

double ar[100];
ar[50] = 1.0;
foo( ar, &ar[50], 100)</pre>
```

- first 50 iterations set ar [0] ...ar [49] to 0.0(1 ar [50])
- the 51st iteration changes ar [50] from 1.0 to 0.0.
- Since *a is aliased to ar[50] subsequent iterations set ar[51]...ar[99] to 1.0

The optimizer needs to be conservative!

Optimization is not performed!



• **Solution:** sign a contract with the compiler!

```
void foo(double* restrict y, const double* a, int n ) {
  for( int i=0; i<n; i++ )
    y[i] = 1.0 - *a;
}</pre>
```

- restrict is a type specifier like const, volatile
- it qualifies the pointer **y** not the target
- restrict double* is illegal!

For the lifetime of pointer \mathbf{y} , only \mathbf{y} or pointers copied directly or indirectly from \mathbf{y} will be used to reference the sub-object pointed to by \mathbf{y} .

• restrict must not be part of the interface

```
void foo(double* y, const double* a, int n ) {
  double* restrict local_y = y;
  for( int i=0; i<n; i++ )
    local_y[i] = 1.0 - *a;
}</pre>
```

- restrict is not part of the C++ standard (however, many compilers support it)
- you therefore may prefer using it in the body of a function only and keep the interface clean
- however, making it visible in the interface tells the client not to pass aliased pointers
- example: memcpy aliasing not allowed by standard!

Notice, that there may exists hidden invariants (e.g. hidden by an inline function or a template)

I.3.2. Advanced Inlining - Virtual functions

• Often asked: "Does inlining of virtual functions make sense?"

```
struct foo {
  inline virtual void test() { ... }
};
struct bar : public foo {
  inline virtual void test() {
    foo::test(); // inlining
};
inline void no inline(const foo* f) {
  f->test(); // no inlining
bar b;
b.test(); // inlining
no inline(&b);
```

Yes, because sometimes the target of the call is resolvable during compiletime!



I.3.2. Advanced Inlining - Cross-Call Optimization

• Inlining may enable additional optimizations

```
double foo = 90.0;
//.. code that doesn't change foo
float bar = sin(foo);

double foo = 90.0;
// ...
float bar = PI/2;
```

A clever compiler could optimize away the call to sin

```
void test(double& f) {
  if (f != 90.0)
    f=0;
}

Note: there are compilers that even regard
  this case.

double foo = 90.0;
test(foo);  // may change foo's value
float bar = sin(foo);  // -> no optimization here
```

I.3.2. Advanced Inlining - Cross-Call Optimization

```
inline void test(double& f) {
  if (f != 90.0)
    f=0;
}
double foo = 90.0;
test(foo);
float bar = sin( foo );
double foo = 90.0;
if (foo != 90.00)
  foo = 0;
float bar = sin( foo );
double foo = 90.0;
// ...
float bar = sin( foo );
double foo = 90.0;
float bar = PI/2;
```

Inlining enables optimization.

No inter-procedural analysis required!



I.3.2. Advanced Inlining - Why not inline everything?

Inlining may have negative side-effects

- Decreased Performance

- Suppose a program that (without inlining) never produces cache-faults
- Inlining may increase code-size; program doesn't fit into cache no more
- frequent cache-faults may impact runtime performance severely

Increased compile-time / time for development

- Inline functions must appear in header-files
- Changing the body of an inlined function necessitates recompilation not just relinking

Debugging becomes more complicated

- can't use single breakpoints to track entry/exit from functions
- difficult to track variable names across source boundaries

Profiling / Performance Analysis

– inlined methods do not appear in program profiles



I.3.2. Advanced Inlining - The Inlining Decision Matrix from Bulka/Mayhew

	Static Size		
Dynamic Frequency	Large (20+ loc)	Medium (5-20 loc)	Small (-5 loc)
Low (the bottom 80% of call frequency)	Do not inline	Do not inline	Consider inlining
Medium (the top 5-20% of call frequency)	Do not inline	Consider rewriting the code to expose its fast path and then inline	Always inline
High (the top 5% of call frequency)	Consider rewriting the code to expose its fast path and then inline	Selectively inline the high frequency static invocation points	Always inline



^{*} taken from Bulka, Mayhew: "Efficient C++" - see references at the end of this section

I.3.2. Advanced Inlining - Conditional Inlining

delay of inlining

```
// foo.h
#ifnded FOO H
#define FOO H
class foo {
  int bar(int a);
};
#ifdef INLINE
#include "foo.inl"
#endif
#endif
```

```
// foo.inl

#ifndef INLINE
#define inline
#endif

inline
foo::bar(int a) {
...
};
```

```
// foo.cc
#ifndef INLINE
#include "foo.inl"
#endif
....
```

If **INLINE** is *not* defined, the preprocessor removes the inline specifier (it then is defined to be empty)

I.3.3. Reference Counting - Problems with Pointer Data Members I

Consider the following class to represent strings:

```
class String { public:
  String(const char* s=0) : c string(0) { setString(s); }
  ~String()
                         { if (c string) delete [] c string; }
  int length() const { return strlen(c string);
  const char* c str() const { return c string;
private:
  char* c string;
  void setString(const char* s) { if (c string) {
                                    delete [] c string;
                                    c string = 0;
                                  else if (s) {
                                    c string=new char [strlen(s)+1];
                                    strcpy(c string,s);
};
```

Problem: Automatically generated copy constructor / assignment operator perform bitwise copy!

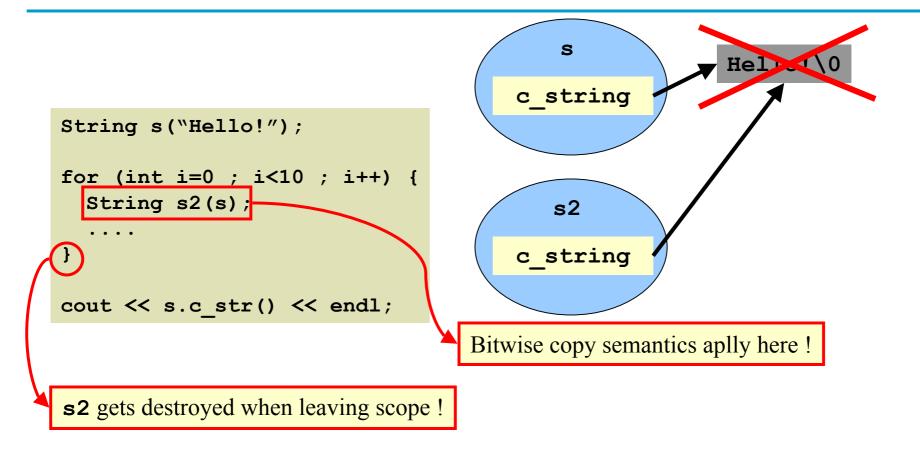


I.3.3. Reference Counting - Problems with Pointer Data Members II

```
S
                                                          Hello!\0
                                        c string
String s("Hello!");
for (int i=0 ; i<10 ; i++) {
  String s2(s);
                                           s2
                                        c string
cout << s.c_str() << endl;</pre>
                                    Bitwise copy semantics aplly here!
s2 gets destroyed when leaving scope!
```



I.3.3. Reference Counting - Problems with Pointer Data Members III



s.c_string is invalid now!



I.3.3. Reference Counting - Problems with Pointer Data Members IV

Simple solution: whenever a string gets copied (either by a copy constructor or by a call to an assignment operator), we perform a **deep copy**.

```
String& String::operator=(const String& rhs) {
   if (&rhs != this) {
      setString(rhs.c_string);
   }
   return *this;
}
```

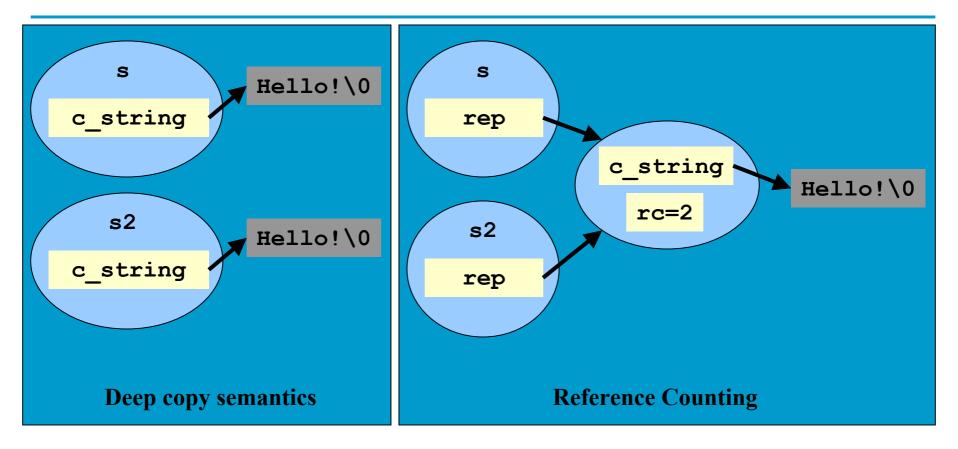
Why perform self-test?

- most important: for safety reasons!
- for speed (avoid unnecessary copy)

Reference counting helps to avoid duplicate objects.



I.3.3. Reference Counting - Reference Counting I - The Idea



- store string in separate object
- count how many references to this object exist
- destroy object if it isn't referenced any more



I.3.3. Reference Counting - Reference Counting II - The Handle/Body Class Idiom

Reference counting is a special case of handle/body class idiom

- Handle class: user visible class
- Body class: helper class for data representation
 - handle class is friend of body class (may access protected/private members)
 - all members of body class are private
 - contains typically only constructor / destructor and necessary data members

```
class StrRep {
  friend class String;
private:
  StrRep(const char* s=0) : c_string(0),rc(0) { setStr(s); }
  ~StrRep() { if (c_string) delete [] c_string; }
  void setStr(const char* s);
  char* c_string;
  int rc;
};
```

I.3.3. Reference Counting - Reference Counting III - The Handle Class I

The handle class string

- implements extra intelligence to do the reference counting
- forwards / uses the body class **StrRep**

Private data now pointer to body class **StrRep**:

```
class String {
private:
   StrRep* rep;
```

Default constructor allocates **StringRep** object and sets reference count to **1**

```
public:
   String(const char* s=0) {
    rep = new StrRep(s); rep->rc=1;
}
```

Copy constructor copies the **rep** object and increments reference counter

```
String(const String& rhs) {
  rep = rhs.rep; rep->rc++;
}
```



I.3.3. Reference Counting - Reference Counting III - The Handle Class II

Destructor deletes rep object if it is no longer referenced

```
~String() {
  if (--rep->rc <=0) delete rep;
}</pre>
```

Access functions "forward" operation to StrRep object

```
const char* c_str() const { return rep->c_string; }
int length() const { return strlen(rep->c_stirng; }
```

Other member function that need special attention

```
// Assignment operators
String& operator=(const String& rhs);
String& operator=(const char* rhs);

// Equality test operator
bool operator==(const Sring& rhs) const;
};
```

I.3.3. Reference Counting - Reference Counting III - The Handle Class III

The **String** assignment operator

- deletes old StrRep object if it is no longer referenced
- copies **StrRep** object and increments reference counter
- returns a reference to allow for daisy chaining

```
String& operator=(const String& rhs) {
  if (rep == rhs.rep)
    return *this;
  if (--rep->rc <=0) delete rep;
  rep = rhs.rep;
  rep->rc++;
  return *this;
}
```

Char* to String assignment

```
String& operator=(const char* rhs) {
  if (--rep->rc <=0) delete rep;
  rep = new StrRep(rhs); rep->rc=1;
  return *this;
}
```

I.3.3. Reference Counting - Reference Counting III - The Handle Class IV

The equality test operator

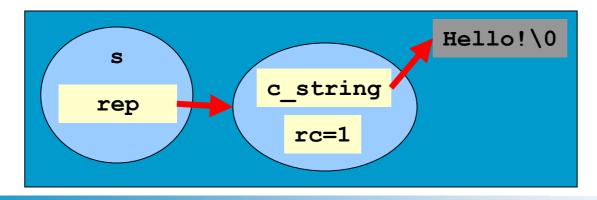
- for speed: compare pointer first
- forwards operation to StrRep object

```
bool operator=(const String& rhs) const {
  if (rep == rhs.rep)
    return true;
  return !strcmp(rhs.rep->str,rep->str);
}
```

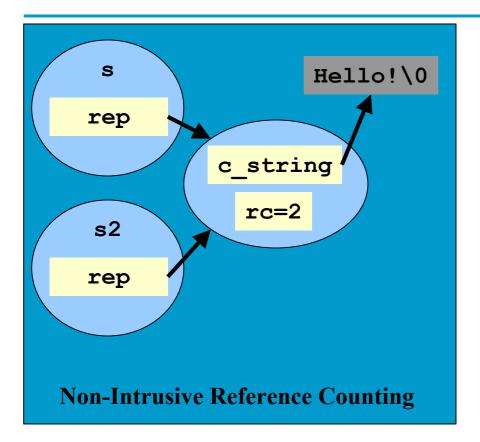
```
Looks good so far, but ...
```

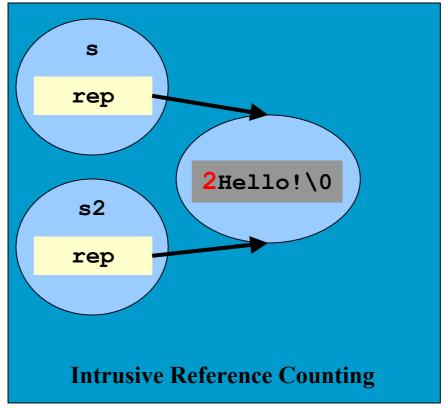
... there are two indirections :(

```
String s("Hello");
cout << s.c_str() << endl;</pre>
```



I.3.3. Reference Counting - Intrusive Reference Counting I





Store reference counter inside of object



I.3.3. Reference Counting - Intrusive Reference Counting II

Make member object aware of reference counting - leave String class untouched

```
struct StringStorage {
  friend class String;
private:
  struct Data {
    int refCount;
    char c string[1];
  };
 Data *data;
  void Assign(const char* s) {
    int slen= (strlen(s)+1) * sizeof(char);
    data = static cast<Data*>( operator new(sizeof(Data)+slen) );
    data->refCount = 1;
  void Release() {
    if (--data->refCount) operator delete(data);
  const char* c string() const { return data->c string; }
```



I.3.3. Reference Counting - Intrusive Reference Counting III

```
StringStorage(const char* s) { Assign(s); }
 ~StringStorage()
                   { Release(); }
 StringStorage& operator=(const StringStorage& rhs) {
   if (data == rhs.data) return *this;
   Release();
   data = rhs.data;
   ++ (data->refCount);
 StringStorage& operator=(const char* rhs) {
   if (rhs==data->c string) return *this;
   Release();
   Assign(rhs);
};
```

- String class now stores value of type StringStorage.
- Bitwise copy semantics do not apply for automatically generated copy constructor / assignment operator !
- Only a single indirection is needed (as for "usual" implementation)

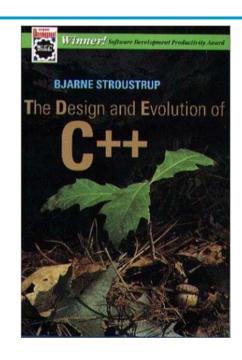


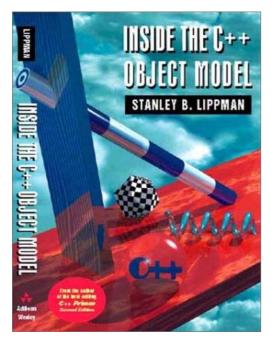
Overview

- Classes
- Polymorphism
 - Inheritance
 - Overloading
 - Conversions
 - Templates
- Further Topics
- References



B. Stroustrup: The Design and Evolution of C++, Addison-Wesley, 1994

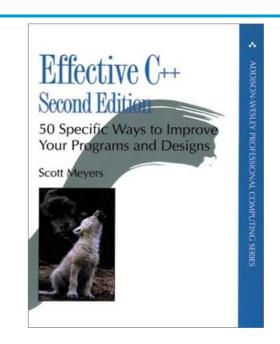


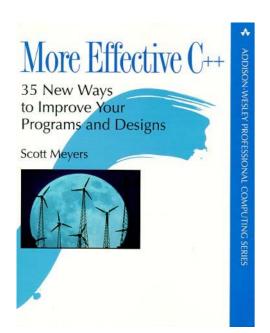


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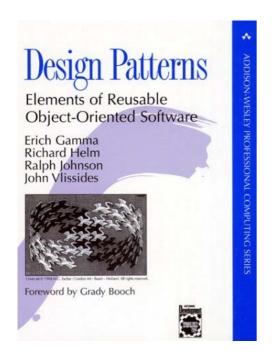
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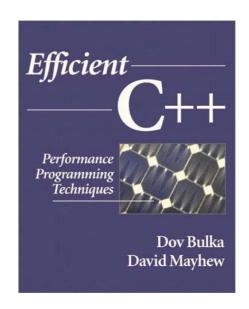




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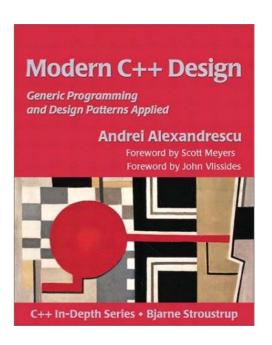




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II. Template Metaprogramming

This section of the course partially is result of joint work with

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Czarnecki/Eisenecker: Generative Programming Addison Wesley, 2000

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I always knew that C++ templates were the work of the Devil, and now I'm sure :-)
- Cliff Click

Overview

- What is template metaprogramming?
- Metainformation
- Computing values
- Computing types
- Functional Flavor of the Static Level
- Code generation
- Outlook and evaluation
- References



II.1. Metaprogramming / Template Metaprogramming

What is Metaprogramming?

- **Metaprogramming** is about writing programs that **represent** and **manipulate** other programs or themselves.
- **Metaprograms** are programs about other programs or themselves, e.g., compilers, interpreters, macros, etc.
- Metaprograms can be executed at compile time (static) or runtime (dynamic).

What is Template Metaprogramming (TMP)?

- Template metaprograms are executed by the compiler at compile time (static metaprogramming).
- They are Representing and manipulating programs (classic metaprogramming).
- They are used to compute static values.



Overview

- What is template metaprogramming?
- Metainformation
- Computing values
- Computing types
- Functional Flavor of the Static Level
- Code generation
- Outlook and evaluation
- References



II.2. Metainformation - Overview

Metainformation is information that is available during compile time

- types (including typedefs)
- constants stored in enums
- non-type template parameters

Metainformation on a type could be stored

- in a type itself (as a member)
- using a traits template
- using a traits class



II.2.1. Metainformation - In a type itself

```
struct Int {
  enum { is integral = 1, is exact = 1 };
 // ...
};
struct Double {
  enum { is integral = 0, is exact = 0 };
 // ...
};
template <class IntegralsOnly>
void foo(const IntegralsOnly& I) {
   assert(IntegralsOnly::is integral == true);
  // ...
```

II.2.1. Metainformation - In a type itself - Summary

- Information and metainformation located in one place
- Metainformation cannot be extended without invasively modifying the implementation of the type, i.e., no metainformation for basic types like double, int
- Metainformation for *various purposes* is mixed



II.2.2. Metainformation - Traits Templates

```
Excerpt from numeric limits
template<class T>
class numeric limits
{ public:
      static const bool is_specialized = false;
      static T min() throw();
      static T max() throw();
      static const int digits = 0;
      static const int digits10 = 0;
      static const bool is signed = false;
      static const bool is integer = false;
      static const bool is exact = false;
      static const int radix = 0:
      static T epsilon() throw();
      static T round error() throw();
      // ...
```



II.2.2. Metainformation - Traits Templates - Specialization

```
template<>
class numeric limits<float>
{ public:
      static const bool is specialized = true;
      inline static float min() throw() { return 1.17549435E-38F; }
      inline static float max() throw() { return 3.40282347E+38F; }
      static const int digits = 24;
      static const int digits10 = 6;
      static const bool is signed = true;
      static const bool is integer = false;
      static const bool is exact = false;
      static const int radix = 2:
      inline static float epsilon() throw(){
         return 1.19209290E-07F; }
      inline static float round error() throw() { return 0.5F; }
      // ...
                  Excerpt from the specialization for numeric limits<float>
```

II.2.2. Metainformation - Traits Templates - Usage

```
cout << numeric_limits<float>::is_integer << endl;
cout << numeric_limits<int>::is_integer << endl;

cout << numeric_limits<complex<float> >::is_specialized << endl;

// "false" implies that numeric_limits was not specialized
// for complex<float>
```



II.2.2. Metainformation - Traits Templates - Summary

- Extending metainformation without modifying the type (decoupling of metainformation and type declaration)
- Modularly dividing metainformation (numeric_limits,
 special_metainfo ...)
- Only one specialization of a traits template per type
- Information and metainformation located in different places



II.2.2. Metainformation - Traits Classes (Configuration Repository)

SampleConfig is not a template!



II.2.2. Metainformation - Traits Classes - Importing / Exporting Configurations

• Fixed size vector - configured by **config** - traits class.

```
template <class config>
class GenVector {
public:
  typedef config Config t; // export configuration
  typedef typename config::Element t Element t;
  typedef typename config::Size t
  GenVector() : size m(config::size) {
    for (Size t i=0; i < size(); ++i) el[i] = 0.0;
  const Size t& size() const {
    return size m;
  void element(const Size t& i,const Element t& e) { el[i] = e; }
  const Element t& element(const Size T& i) const { return el[i]; }
private:
  Element t el[config::size];
  const Size t size m;
};
```



II.2.2. Metainformation - Traits Classes - Usage

```
typedef SampleConfig::Vector Vector;
Vector v;
v.element(2,42.1);
cout << v.size();

typedef Vector::Size_t Size_t;
for (Size_t i=0; i<v.size() ; ++i)
    cout << '\t' << v.element(i);
cout << endl;</pre>
```

SampleConfig::Vector is the vector type that is provided by the *configuration* repository SampleConfig.



II.2.3. Metainformation - Structured Configuration Repository

A configuration repository can provide configurations for more than one type:

```
struct SampleConfig {
  struct ForVector {
    typedef int Element t;
    enum { size = 5 };
  };
  struct ForMatrix {
    typedef double Element t;
    enum { rows = 5, cols = 5 };
  };
  typedef GenVector<SampleConfig> Vector;
  typedef GenMatrix<SampleConfig> Matrix;
};
```



II.2.3. Metainformation - Structured Configuration Repository

```
template <class config>
class GenVector {
public:
  typedef config Config;
  typedef typename Config::ForVector MyConfig;
  typedef typename MyConfig::Element t Element t;
  // ...
};
template <class config>
class GenMatrix {
public:
  typedef config Config;
  typedef typename Config::ForMatrix MyConfig;
  typedef typename MyConfig::Element_t;
  // ...
};
```

II.2.3. Metainformation - Structured Configuration Repository - Usage

```
typedef SampleConfig::Vector Vector;
typedef SampleConfig::Matrix Matrix;
Vector v;
Matrix m;
// ...
```



II.2.4. Metainformation - Computing Configuration Repositories

```
struct Precise {
  typedef long double Element t;
};
struct Compact {
  typedef float Element t;
};
// Configuration Parameters
template <int Size = 10, class Precision = Compact>
struct ComputeConfig { // Configuration Repository
  struct Config {
    typedef typename Precision:: Element t Element t;
    enum { size = Size };
    typedef Vector<Config> Vector;
  };
};
```



II.2.4. Metainformation - Computing Configuration Repositories

Compute Configuration Repository

```
template <class config>
class GenVector {
public:
  typedef config Config; // export config
  typedef typename Config::Element t Element t;
      // ...
};
typedef ComputeConfig<5,Precise>::Config SampleConfig;
typedef SampleConfig: Vector Vector;
Vector v;
// ...
```

II.2.5. Metainformation - Traits Classes - Summary

- Parameterizing components with different traits classes in a flexible way
- Traits classes containing configuration information for a set of components (configuration repository)
- Structured configuration repositories
- Computing configuration repositories
- Information and metainformation located in different places
- Configuration repositories can get large



Overview

- What is template metaprogramming?
- Metainformation
- Computing values
- Computing types
- Functional Flavor of the Static Level
- Code generation
- Outlook and evaluation
- References



II.3. Computing Values - Overview

- Computing constants
- Simple template metafunctions (TMF)
- TMF calling other TMF
- TMF with several statements
- TMF as TMF parameters



II.3.1. Computing Values - Computing Constants - Advantages

```
const double PI = 22.0/7.0;
const double PI_SQUARED = PI*PI;
```

- More descriptive (higher intentionality)
- Implementation (the computation formula) easy to modify
- Depended on *meaningful names*



II.3.1. Computing Values - Computing Constants - Examples

```
const int C1 = 40320; not descriptive

thard to maintain

value fixed at compile-time
```

```
int factorial(int n) {
  return (n==0) ? 1 : n*factorial(n-1);
}
const int C3 = factorial(8);
```

```
very descriptive
easy to maintain
computed at runtime
```



II.3.2. Computing Values - Template Metafunction

```
fac 0 = 1
fac n = n * fac (n-1)
```

```
cout << Factorial<8>::RET << endl; // 3 cout << 40320 << endl;
```



II.3.2. Computing Values - Template Metafunctions - Example

```
template <3>
struct Factorial {
   enum { RET = 3 * Factorial<2>::RET };
                                              3 * 2 * 1 * 1
};
  template <2>
  struct Factorial {
     enum { RET = 2 * Factorial<1> :RET };
  };
    template <1>
    struct Factorial {
       enum { RET = 1 * Factorial<0>: RET };
    };
           template <>
           struct Factorial<0> {
              enum { RET = 1 };
           };
```

Class templates can be used as **compile-time functions**



II.3.2. Computing Values - TMF calling other TMF

- Take k from n elements
 - without putting elements back
 - without taking order into account

(Combinations without repetitions)

$$C(k,n) = \frac{n!}{k! \cdot (n-k)!}$$



II.3.2. Computing Values - TMF calling other TMF

```
Combinations k n = fac n / (fac (k) * fac (n-k))
```

```
cout << Combinations<2,4>::RET << endl;</pre>
```



II.3.2. Computing Values - TMF with several statements

• A TMF may contain multiple statements

```
template<int k, int n>
class Combinations {
  enum { num = Factorial<n>::RET, // statement 1
          denom = Factorial<k>::RET * // statement 2
          Factorial<n-k>::RET
      };
public:
  enum { RET = num / denom }; // statement 3
};
```



II.3.2. Computing Values - TMF as TMF Parameter (Template Template Para.)

• Consider accumulate function (like in the STL):

```
accumulate(n, f) := f(0) + f(1) + \dots + f(n)
```

```
// Passing a template as a template parameter
template<int n, template<int> class F>
struct Accumulate {
   enum { RET = Accumulate<n-1,F>::RET + F<n>::RET };
};

template<template<int> class F>
struct Accumulate<0,F> {
   enum { RET = F<0>::RET };
};
```



II.3.2. Computing Values - TMF as TMF argument

```
template<int n, template<int> class F>
                                    struct Accumulate {
template<int n>
                                     enum { RET = Accumulate<n-1,F>::RET + F<n>::RET };
                                    };
struct Square {
                                    template<template<int> class F>
  enum { RET = n*n };
                                    struct Accumulate<0,F> {
};
                                     enum { RET = F<0>::RET };
cout << Accumulate<3, Square>::RET << endl;</pre>
   Accumulate<2,F>::RET + Square<3>::RET
   Accumulate<1,F>::RET + Square<2>::RET + Square<3>::RET
   Accumulate<0,F>::RET + Square<1>::RET + Square<2>::RET + Square<3>::RET
   Square<0>::RET + Square<1>::RET + Square<2>::RET + Square<3>::RET
   0*0 + 1*1 + 2*2 + 3*3
                                                 cout << 14 << endl
```

II.3.2. Computing Values - TMF as TMF Parameter (Member Templates)

- **Problem:** only a few compiler support template template parameter
- Solution: Use member templates instead:

```
struct Square {
  template<int n>
  struct Apply {
    enum { RET = n*n };
 };
};
template<int n, class F>
struct Accumulate {
  enum { RET = Accumulate<n-1,F>::RET + F::template Apply<n>::RET };
};
template<class F>
struct Accumulate<0,F> {
  enum { RET = F::template Apply<0>::RET };
};
```



II.3.3. Computing Values - Summary

- Computation at compile time, thus
 - better performance
 - smaller object code
- Descriptive and easy to maintain representations of constants
- Full spectrum as for dynamic function calls
 - Functions calling other functions
 - Functions as function parameters
- Recursion as the only iteration mechanism
- 1 Unusual syntax
- 1 Longer compilation times



Overview

- What is template metaprogramming?
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II.4. Computing Types - Overview

- Simple selection (If)
- Multiple selection (switch / case)
- Decision tables



II.4.1. Computing Types - Simple Selection - Application Example

Consider a matrix library.

- **Solution:** TMF selecting the conceptually larger type
- The necessary metainformation is available (numeric_limits<>::max_exponent10, numeric limits<>::digits)
- **Required:** A *simple selection* of one from two types based on a Boolean expression



II.4.1. Computing Types - Simple Selection

```
template<br/>bool condition, class THEN, class ELSE>
                                // condition = true
struct IF {
  typedef THEN RET;
};
// partial specialization
template<class THEN, class ELSE>
struct IF<false, THEN, ELSE> { // condition = false
  typedef ELSE RET;
};
IF<(1+2>4), int, float>::RET i;
     3>4
               IF<false, int, float>::RET yields float
   false
```

II.4.1. Computing Types - Simple Selection

```
template<class A, class B>
struct Promote {
  enum {
    cond = (numeric limits<A>::max exponent10 <</pre>
            numeric limits<B>::max exponent10) ||
            ( numeric limits<A>::max exponent10 ==
             numeric limits<B>::max exponent10 &&
             numeric limits<A>::digits <</pre>
             numeric limits<B>::digits )
  };
  typedef typename IF<cond, B, A>::RET RET; // A<B ? A : B;
};
```



II.4.1. Computing Types - Simple Selection - Example

```
template <class T1, class T2>
Matrix<Promote<T1, T2>::RET> operator+(Matrix<T1>& m1, Matrix<T2>& m2) {
  Matrix<Promote<T1,T2>::RET> result;
  // ... Perform computation
  return result;
}
//...
typedef int Type1;
typedef double Type2;
Matrix<Type1> m;
Matrix<Type2> n;
Matrix<Promote<Type1, Type2>::RET> r = m + n; // Matrix<double>
// or you may wish save the result of Promote for future use ...
typedef Promote<Type1, Type2>::RET RET;
Matrix < RET > r = m + n; // Matrix < double >
```

II.4.1. Computing Types - Simple Selection - Alternative Implementation

- Some compilers do not allow for partial specialization (e.g. Microsoft's Visual C++)
- Idea: Regard if as a function that selects one value out of a tuple.

```
// class that offers a metafunction that returns the first
// element of a tuple
struct SelectThen {
  template<class ThenType, class ElseType>
  struct Result {
    typedef ThenType RET;
 };
};
// class that offers a metafunction that returns the second
// element of a tuple
struct SelectElse {
 template<class ThenType, class ElseType>
 struct Result {
   typedef ElseType RET;
 };
};
```



II.4.1. Computing Types - Simple Selection - Alternative Implementation

```
template <bool condition > // Choosing a selecting class
struct ChooseSelector
{ typedef SelectThen RET; };
template<>
struct ChooseSelector<false> // Full specialization !!
{ typedef SelectElse RET; };
template<bool condition, class ThenType, class ElseType>
struct IF {
 typedef typename ChooseSelector<condition>::RET Selector;
 typedef typename Selector::template Result<ThenType,ElseType>::RET
         RET;
};
```



II.4.1. Computing Types - Simple Selection - Summary

- **IF<>::RET** returns a type
- Used like a "normal" if
- **IF** and its evaluation are easy to save
 - typedef IF< 1!=2, A, B> Result;
 - typedef IF< 1!=2, A, B>::RET Result;
- Type-dependent *selection of code* or member access

```
- IF< 1!=2, A, B>::RET::some_static_function();
```

- int result = IF< 1!=2, A, B>::RET::some_int;



- Customization of a automatic teller machine (ATM)
- Messages in a local language depending on the country of installation
- One ATM contains only the code for the needed language
- Configuration at compile time



```
struct SpracheDeutsch {
  static const char* kreditUeberzogen() {
    return "Kreditrahmen ueberschritten";
  static const char* limitUeberschritten() {
    return "Hoechstbetrag ueberschritten";
  static const char* zuwenigGeld() {
    return "Unzureichender Geldvorrat";
  static const char* sonstigeStoerung() {
    return "Funktionsstoerung";
};
// SpracheEnglisch, SprachePolnisch
```



```
template <class Landessprache> // Parameterized Polymorphism !
class Bankautomat : protected Landessprache {
private:
  typedef Bankautomat<Landessprache> self;
public:
  // ...
  void auszahlen(const double& betrag) {
    if (kreditrahmenUeberzogen(betrag)) {
      cout << self::kreditUeberzogen() << endl;</pre>
      return;
     if (betrag > limit()) {
       cout << self::limitUeberschritten() << endl;</pre>
       return;
```



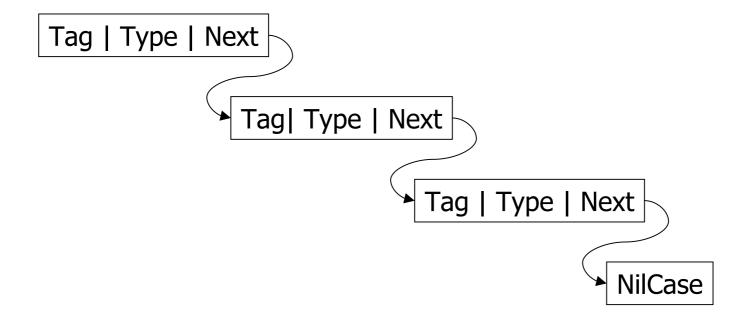
typedef Bankautomat<Sprache> RET;

};

```
enum Land { Deutschland, England, Oesterreich, Polen, USA };
// ...
LOKALISIERE BANKAUTOMAT < Deutschland >:: RET bankautomat;
teste(bankautomat);
template <Land land>
struct LOKALISIERE BANKAUTOMAT {
  typedef typename
          SWITCH<land,
                 CASE < Deutschland, SpracheDeutsch,
                 CASE<England, SpracheEnglisch,</pre>
                 CASE<Oesterreich, SpracheDeutsch,
                 CASE<Polen, SprachePolnisch,
                 CASE<USA, SpracheEnglisch
                > > > > > :: RET Sprache;
```



II.4.2. Computing Types - Multiple Selection - Implementation





II.4.2. Computing Types - Multiple Selection - Implementation

```
const int DEFAULT = \sim (\sim 0u >> 1); // plattform-independent: smallest
                                   // integer value
struct NilCase {};
template <int TAG, class TYPE, class NEXT = NilCase>
struct CASE {
  enum { tag = TAG };
  typedef TYPE Type;
  typedef NEXT Next;
};
```



II.4.2. Computing Types - Multiple Selection - Implementation

```
template<int tag, class Case> // Solution with partial specialization
struct SWITCH {
 typedef typename Case::Next NextCase;
 enum { caseTag = Case::tag,
           found = (caseTag == tag || caseTag == DEFAULT)
         };
 typedef typename
         IF<found,
             typename Case::Type, // return head of list
             typename SWITCH<tag, NextCase>::RET // search in tail
            >::RET RET;
};
template<int tag>
struct SWITCH<tag, NilCase> {
 typedef NilCase RET;
};
```



II.4.2. Computing Types - Multiple Selection - Summary

- Usage like a "normal" switch; different implementations possible
 - **DEFAULT<...>** instead of **CASE<DEFAULT**, ...>
 - **DEFAULT<...>** can stand at an arbitrary place
- Implementation with member templates possible
- Special checks
 - Detecting multiple **DEFAULT** branches
 - Detecting multiple tags



II.4.3. Computing Types - Dependency Tables

- Customizing output language based on country and state
- One ATM contains only the code for the needed language
- Configuration at compile time



II.4.3. Computing Types - Dependency Tables

Land	Bundesland	Sprache
Deutschland	*	BankautomatDeutsch
England	*	BankautomatEnglisch
Österreich	*	BankautomatDeutsch
Polen	*	BankautomatPolnisch
USA	*	BankautomatEnglisch
Kanada	Québec	BankautomatFranzösisch
Kanada	*	BankautomatEnglisch
Schweiz	Jura	BankautomatFranzösisch
Schweiz	Wallis	BankautomatFranzösisch
Schweiz	Genf	BankautomatFranzösisch
Schweiz	Freiburg	BankautomatFranzösisch
Schweiz	Waadt	BankautomatFranzösisch
Schweiz	Tessin	${ t BankautomatItalienisch}$
Schweiz	*	BankautomatDeutsch
*	*	BankautomatEnglisch



II.4.3. Computing Types - Dependency Tables - Example

• land and bundesland are input-types

```
typedef typename EVALTABLE
//*************************
                land , CELL< bundesland
      CELL<
, ROW< CELL<Deutschland , CELL<
                            anyValue
                                      , SpracheDeutsch
, ROW< CELL<
            England , CELL<
                            anyValue
                                      , SpracheEnglisch
                                                            > >
                                      , SpracheDeutsch
 ROW< CELL< Oesterreich, CELL<
                            anyValue
                                                            > >
                                      , SprachePolnisch
              Polen , CELL<
                            anyValue
                                                           > >
 ROW< CELL<
 ROW< CELL<
            USA
                    , CELL< anyValue
                                      , SpracheEnglisch
                                                            > >
 ROW< CELL< Kanada , CELL< Quebec
                                      , SpracheFranzoesisch
, ROW< CELL< Kanada , CELL<
                            anyValue
                                      , SpracheEnglisch
                                                            > >
 ROW< CELL< Schweiz , CELL< Jura
                                      , SpracheFranzoesisch
                                                           > >
            Schweiz , CELL< Wallis
                                      , SpracheFranzoesisch
, ROW< CELL<
                                                           > >
 ROW< CELL< Schweiz , CELL< Genf
ROW< CELL< Schweiz , CELL< Freiburg
                                      , SpracheFranzoesisch
 ROW< CELL<
                                                           > >
                                      , SpracheFranzoesisch
                                                           > >
            Schweiz , CELL< Waadt
, ROW< CELL<
                                      , SpracheFranzoesisch
                                                          > >
            Schweiz , CELL< Tessin
                                      , SpracheItalienisch
, ROW< CELL<
            Schweiz , CELL< Zuerich
                                      , SpracheDeutsch
 ROW< CELL<
                                      , SpracheEnglisch
ROW< CELL< anyValue
                     , CELL< anyValue
//************************
>>>>>>>>>>>;:RET Sprachanpassung;
```

Yes, that's C++ code!



II.4.3. Computing Types - Dependency Tables - Usage

```
enum Land { Deutschland, // etc. };
enum Bundesland {
   // Deutschland
  BadenWuerttemberg, // etc.
};
template <Land land, Bundesland bundesland>
struct LOKALISIERE BANKAUTOMAT {
   typedef typename EVAL TABLE<
     // ... See previous slide
   >::RET Sprachanpassung;
  typedef Bankautomat<Sprachanpassung> RET;
};
LOKALISIERE BANKAUTOMAT<Schweiz, Wallis>::RET bankautomat;
teste (bankautomat);
```

II.4.3. Computing Types - Dependency Tables - Summary

- Implementation somewhat more complex (see Knaupp, Eisenecker, Czarnecki: Mit Tabellen zur Entscheidung, in OBJEKTspektrum 5/99)
- Extended dependency tables
 - Evaluation in the top-down direction
 - joker (anyValue)
- Returning multiple values
 - Chaining results in lists
 - Configuration repositories



Overview

- What is template metaprogramming?
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II.5. Functional Flavor of the Static Level

- Static C++ code is functional, writing static C++ code is like programming in a functional language.
- Functional programming languages
 - have no variables
 - no assignment
 - no iterative constructs
 - are based on the concept of mathematical functions (lambda calculus)
 - use recursions instead of loops
- Class templates as functions
 - compile-time functions
 - take types/integers as arguments and return types or integers
 - template instantiation \boxtimes function application, however, when writing static code we usually separate return value from template itself (Factorial<5>::RET)
- Integers and types as data
 - Static code operates on integers and types as data
 - We will later see how to represent complex data (e.g. lists, trees)



II.5. Functional Flavor of the Static Level

- Symbolic names instead of variables
 - variables are typedef names and integral constants
 - they are initialized once their value cannot be changed
 - use symbolic names rather than true variables
- Constant initialization and typedef Statement instead of assignment
 - use enum declaration if you need an integer value at the static level
 - static constant members are considered as misfeature by Stroustrup
 - use typedef to introduce member types
- Template recursion instead of loops
 - as in functional programming there is no loop statement
 - it is possible to mimic FOR, DO, WHILE
 - take care of infinite recursion
 - recursion may be limited by number of "pending instantiations"



Overview

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II.6. Code Generation - Overview

- Code generating TMFs
- Simple Code Selection
- DO
- WHILE
- FOR



II.6.1. Code Generation - Practical Example

- Many language dependent attributes for ATM exits
- Each possible instance has to be tested!



II.6.1. Code Generation - Practical Example - Explicit Coding

```
{ LOKALISIERE_BANKAUTOMAT<Deutschland>::RET bankautomat;
  teste(bankautomat);
}
{ LOKALISIERE_BANKAUTOMAT<England>::RET bankautomat;
  teste(bankautomat);
}
// ...
predundant code
perror-prone
```

Thard to maintain

II.6.1. Code Generation - Practical Example

```
enum Land { Deutschland, England, Oesterreich, Polen, USA, STOP };
// LOKALISIERE BANKAUTOMAT reamins unchanged
template <Land land = Deutschland>
struct test all {
  static void execute() {
    LOKALISIERE BANKAUTOMAT<land>::RET bankautomat;
    teste(bankautomat);
    typedef test all<Land(land + 1) > naechsterTest;
    naechsterTest::execute();
};
// explicit spcialization to terminate recursion
template <> struct test all<STOP> {
  static void execute() {}
};
test all<>::execute();
```



II.6.2. Code Generation - Simple Code Selection

```
struct algoA {
   static void execute() {
     cout << "Hello A" << endl;
   }
};

struct algoB {
   static void execute() {
     cout << "Hello B" << endl;
   }
};

IF<(1<2), algoA, algoB>::RET::execute(); // cout<<"Hello A"<<endl;</pre>
```

- execute is a static inline function compiler can optimize away any overhead
- code selection criteria may depend on very complex (static) computations
- Note the difference to preprocessor approaches metaprograms allow for much more control (e.g. preprocessor directives may not contain C++ static data)



II.6.3. Code Generation - Recursive Code Expansion

- Template Metaprograms can be used to expand code recursively
- optimize code (e.g. loop unrolling), generate test code

```
inline int power(const int& m,int n) {
  int r=1;
  for ( ;n>0; --n) r*=m;
  return r;
}
int m,k;
cin >> m;
k = power(m,3);
```

- The **exponent** is known at compile-time!
- unroll loop to optimize code:

```
inline int power3(int& m) {
  in r=1; r*=m; r*=m;
  return r;
}
```

• Although done by compilers automatically, TMFs give you more control!



II.6.3. Code Generation - Recursive Code Expansion - Example

```
template <int n>
inline
int power(const int& m) {
  return power<n-1>(m) * m;
template<>
inline
int power<1>(const int& m) {
  return m;
template<>
inline
int power<0>(const int& m) {
  return 1;
```

```
cout<< power<3>(m) << endl;</pre>
cout<< power<2>(m) * m << endl;</pre>
cout<< power<1>(m) * m * m << endl;</pre>
cout<< 1 * m * m * m << endl;
```

different calling syntax!

unrolling not limited

• In case your compiler doesn't support explicit function template specialization: use class templates



II.6.3. Code Generation - Recursive Code Expansion - Optimize Vector Operations

```
inline
void add vec(int size, const double* a,const double *b,double *c) {
 while (size--) *c++ = *a++ + *b++;
}
double a[3] = \{ 1.1, 2.2, 3.3 \};
double b[3] = \{ -1.0, -2.0, -3-0 \};
double c[3];
add vec(3, a,b,c); // size of vector known during compile-time !
template <int size>
inline void add vec(const double* a,const double* b,double *c) {
  *c = *a + *b:
  add vec<size-1>(a+1,b+1,c+1); // recursive function call
}
template <>
```

inline void add vec<0>(const double* a,const double* b,double *c) {}

II.6.3. Code Generation - Recursive Code Expansion - Vector Example

```
add vec<3>(a,b,c);
     *c = *a + *b:
     add vec<2>(a+1,b+1,c+1);
  *c = *a + *b;
  *(c+1) = *(a+1) + *(b+1);
  add vec<1>(a+1+1,b+1+1,c+1+1);
*c = *a + *b:
*(c+1) = *(a+1) + *(b+1);
*(c+2) = *(a+2) + *(b+2);
add vec<0>(a+1+1+1,b+1+1+1,c+1+1+1);
     *c = *a + *b;
     *(c+1) = *(a+1) + *(b+1);
     *(c+2) = *(a+2) + *(b+2);
```

II.6.3. Code Generation - Recursive Code Expansion - Limiting Depth of Recursion 1

```
struct OPT ENVIRON { enum { unroll depth=2 }; }; // Traits class !
template<int n> inline int power(const int& m) {
  return IF< n <= OPT ENVIRON::unroll depth,
             unroll power<n>,
             normal power<n>
           >::RET::exec(m); // code selection !
// needs to be defined before power !
template <int n> struct unroll power {
  static inline int exec(const int& m) {
    return unroll power<n-1>::exec(m) * m;
};
template <> struct unroll power<1> {
  static inline int exec(const int& m) { return m; }
};
template <> struct unroll power<0> {
  static inline int exec(const int& m) { return 1; }
};
```



II.6.3. Code Generation - Recursive Code Expansion - Limiting Depth of Recursion 2

```
template <int n> struct normal_power {
   static inline int exec(const int& m) {
     int r=1;
     for (int i=0; i< N ; i+=OPT_ENVIRON::unroll_depth)
        r*=unroll_power<unroll_depth>::exec(m);
     for (int i=0 ; i < N % OPT_ENVIRON::unroll_depth ; i++)
        r*=m;
     return r;
   }
}</pre>
```

• calling syntax still different!



II.6.3. Code Generation - Recursive Code Expansion - Compile time / Runtime

• n/m known at compile time:

```
template <int m,int n> struct Power {
  enum { RET = Power<m,n-1>::RET * m };
};

template <int m> struct Power<m,0> {
  enum { RET = 1 };
};
```

- n known at compile time: use power<n>
- n and m are not known until runtime: use power function
- How to establish a uniform interface / a single **power** function
- → Move information into Type of m / n

```
template <int n> StaticInt {
  enum { RET = n };
  operator const int() const { return n; }
};
```

II.6.3. Code Generation - Recursive Code Expansion - Offline Partial Evaluation

```
// Power<int>(), power<int>(int), power(int,int), as before
template <int m, int n>
inline StaticInt<Power<m,n>::RET> power(const StaticInt<m>&,
                                const StaticInt<n>&) {
 return StaticInt<Power<m,n>::RET>;
}
template <int n>
inline int power(const int& m,const StaticInt<n>&) {
 return power<n>(m);
}
StaticInt<2> c2;
StaticInt<3> c3;
cout << power(2,3) << endl; // uses loop</pre>
cout << power(c2,3) << endl;  // uses loop</pre>
cout << power(c2,power(c2,c3)) << end1; // cout << 256 << end1;
```



II.6.4. Code Generation - Imperative Style - Do & WHILE

```
enum Land { Deutschland, England, Oesterreich, Polen, USA };
// No need for STOP! LOKALISIERE BANKAUTOMAT remains unchanged
template <Land land = Deutschland>
struct Statement {
  enum { land = land };
  static void exec() {
    LOKALISIERE BANKAUTOMAT<land>::RET bankautomat;
    teste (bankautomat);
  typedef Statement<Land(land + 1) > Next;
};
struct Condition {
 template <class STATEMENT>
  struct Code {
    enum { RET = Land(STATEMENT::land ) <= USA };</pre>
 };
};
DO<Statement<>, Condition>::exec();
WHILE<Condition,Statement<> >::exec();
```

II.6.4. Code Generation - Imperative Style - Implementation of DO

```
struct Stop {
 static inline void exec() {};
};
template <class Statement, class Condition>
struct DO {
 typedef typename Statement::Next NextStatement;
 static void exec() {
    Statement::exec();  // Statement.exec
   IF <Condition::template Code<NextStatement>::RET,
       DO<NextStatement, Condition>,
                                // if (Condition)
       Stop
      >::RET::exec();
                                //
                                      DO (NextStatement, Condition)
                                // else
};
                                //
                                       Stop.exec
```

II.6.4. Code Generation - Imperative Style - Application of DO

• Goal: produce the follwing code:

• Statement-class:

```
template <int i=1>
struct printPower2 {
  enum { m=i }; // export i
  StaticInt<i> I;
  static void exec() {
    cout<< "2^"<<i<<"="<<\
        power(2,I)<<endl;
  }
  typedef printPower<i+1> Next;
};
```

Condition-class

```
template <int n>
struct powerCond {
  template <typename Statement>
  struct Code {
    enum { RET = Statement::m < n }
  };
};</pre>
```

Solution: DO<printPower2<>,powerCond<4> >::exec()



II.6.4. Code Generation - Imperative Style - Implementation of WHILE

```
struct Stop {
  static void exec() {};
};
template <class Condition, class Statement>
struct WHILE {
  static void exec() {
    IF < Condition::template Code < Statement >:: RET,
       Statement,
       Stop
      >::RET::exec();
     typedef typename Statement::Next NextStatement;
         <Condition::template Code<Statement>::RET,
          WHILE<Condition, NextStatement >,
          Stop
         >::RET::exec();
};
```



II.6.4. Code Generation - Imperative Style - FOR

```
struct Statement {
  template <int land>
  struct Code {
    static void exec() {
      LOKALISIERE BANKAUTOMAT < (Land) land>::RET bankautomat;
      teste (bankautomat);
 };
};
FOR<Deutschland, LessEqual, USA, 1, Statement>::exec();
```



II.6.4. Code Generation - Implementation of Less and LessEqual

```
struct Less {
  template<int x, int y>
  struct Code {
    enum { RET = x < y };
 };
};
struct LessEqual {
  template<int x, int y>
  struct Code {
    enum { RET = x \le y };
 };
};
```



II.6.4. Code Generation - Imperative Style - Implementation of FOR

```
template <int from, class Compare, int to, int by, class Statement>
struct FOR {
  static void exec() {
     typedef typename Statement::Code<from> Code ;
     IF<Compare::template Code<from, to>::RET,
        Code ,
        Stop
       >::RET::exec();
     IF<Compare::template Code<from, to>::RET,
        FOR<from+by, Compare, to, by, Statement>,
        Stop
      >::RET::exec();
};
```



II.6.4. Code Generation - Nesting Loops

```
int m[3][4] = \{ \{1, 2, 3, 4\}, \{5, 6, 7, 8\}, \{9,10,11,12\} \};
struct OuterLoop {
  template <int i>
  struct Code {
    struct InnerLoop {
      template <int j>
      struct Code {
        static void exec() {
          cout << i << ',' << j << ": " << m[i][j];
           if (i == 3)
             cout << endl;</pre>
           else cout << '\t';
    };
    static void exec() {
      FOR<0,LessEqual,3,+1,InnereSchleife>::exec();
  };
FOR<0,LessEqual,2,+1,AeussereSchleife>::exec();
```

II.6.5. Code Generation - Summary

- Regarding memory usage and compile time, sophisticated code generating
 TMFs are most efficient
- **DO, WHILE** and **FOR** are very descriptive (higher intentionality)
- **DO**, **WHILE** and **FOR** are similar to their runtime counterparts and allow for an easy adaptation of existing algorithms
- **DO, WHILE** and **FOR** are recursively implemented. However, their use doesn't reveal this implementation detail



Note 21: Turing Completeness of TMFs

- A *Turing Complete* language is a language with at least a conditional and a while-loop construct such a language can be used to implement a Turing machine.
- Under Church's conjecture, any language in which a Turing machine can be simulated is powerful enough to perform any realizable algorithm

The static C++ level is Turing complete, there are no theoretical limits to what you can implement at that level

Overview

- What is template metaprogramming?
- Metainformation
- Computing values
- Computing types
- Functional Flavor of the Static Level
- Code generation
- Outlook and evaluation
- References



II.7.1. Outlook and Evaluation - Further Topics

Further Topics

- Expression-Templates
 - generation of parse tress for expressions like
 e = m1 + m2 +m3 // for Matrices
 - optimizing code through transformation of parse trees
 - implementation of domain-specific languages (e.g. FACT!)
- Implementation of functional language execution during compile-time (e.g. LISP kernel)
- Generation of meaningful error messages during compile time (concept checking)
- Partial Evaluation



II.7.1. Outlook and Evaluation - Further Topics

Further Topics

- Configuration generators
- Lazy and full evaluation of TMF expression templates
- Multiparadigm programming with C++
- Template Metaprogramming allows for fascinating applications like
 - generative programming in C++
 - scientific computing



II.7.2. Outlook and Evaluation - History

- Randomly discovered there was no intend by the language designers
- First template meta program was written by *Erwin Unruh*:

```
template <int i> struct D { D (void*); operator int(); };
template <int p,int i> struct is prime {
  enum { prim= (p%i) && is prime<(i>2 ? p :0),i-1>::prim }
};
template <int i> struct Prime print {
  Prime print<i-1> a;
  enum { prim = is prime<i,i-1>::prim }
 void f() { D<i> d = prim; }
};
struct is prime<0,0> { enum {prim=1}; };
struct is primt<0,1> { enum {prim=1}; };
struct Prime print<2> { enum {prim=1}; void f() { D<2> d = prim; } };
#ifndef LAST
#define LAST 10
#endif
main {
 Prime print<LAST> a;
```



II.7.3. Outlook and Evaluation - Problems

- Several problems exist
 - debugging
 - error messages
 - readability of code
 - compile time
 - compiler limitations



II.7.3. Outlook and Evaluation - Debugger

- There is no debugger for TMF's
- Workarounds for producing meaningful error messages do not ever work optimal
- **typename** expressions can become very long
- Compiler cuts long typenames
- Meta programs result in very long typenames



II.7.3. Outlook and Evaluation - Example for a very long typename

Typename for the matrix expression (A+B)*C

```
MultiplicationExpression<class LazyBinaryExpression<class AdditionExpression<class
MatrixTCCL::Matrix<class MatrixTCCL::BoundsChecker<class MatrixTCCL::ArrFormat<class
MatrixICCL::StatExt<struct MatrixDSL::int number<int,7>,struct
MatrixDSL::int number<int,7>>,class MatrixICCL::Rect<class MatrixICCL::StatExt<struct
MatrixDSL::int number<int,7>,struct MatrixDSL::int number<int,7>>>,class
MatrixICCL::Dyn2DCContainer<class MATRIX ASSEMBLE COMPONENTS<class
MATRIX DSL ASSIGN DEFAULTS<class MATRIX DSL PARSER<struct MatrixDSL::matrix<int,struct
MatrixDSL::structure<struct MatrixDSL::rect<struct MatrixDSL::stat val<struct
MatrixDSL::int number<int,7>>,struct MatrixDSL::stat val<struct
MatrixDSL::int number<int,7>>, struct MatrixDSL::unspecified DSL feature>, struct
MatrixDSL::dense<struct MatrixDSL::unspecified DSL feature>, struct MatrixDSL::dyn<struct
MatrixDSL::unspecified DSL feature>>, struct MatrixDSL::speed<struct
MatrixDSL::unspecified DSL feature>, struct MatrixDSL::unspecified DSL feature, struct
MatrixDSL::unspecified DSL feature, struct MatrixDSL::unspecified DSL feature, struct
MatrixDSL::unspecified DSL feature>>::DSLConfig>::DSLConfig>>>>, class
MatrixICCL::Matrix<class MatrixICCL::BoundsChecker<class MatrixICCL::ArrFormat<class
MatrixICCL::StatExt<struct MatrixDSL::int number<int,7>,struct
MatrixDSL::int number<int,7>>,class MatrixICCL::Rect<class MatrixICCL::StatExt<struct
MatrixDSL::int number<int,7>,struct MatrixDSL::int number<int,7>>>,class
MatrixICCL::Dyn2DCContainer<class MATRIX ASSEMBLE COMPONENTS<class
MATRIX DSL ASSIGN DEFAULTS<class MATRIX DSL PARSER<struct MatrixDSL::matrix<int,struct
MatrixDSL::structure<struct MatrixDSL::rect<struct MatrixDSL::stat val<struct
MatrixDSL::int number<int,7>>, struct MatrixDSL::stat val<struct
MatrixDSL::int number<int,7>>,struct MatrixDSL::unspecified DSL featu
                                                                             ıct
MatrixDSL::dense<struct MatrixDSL::unspecified DSL feature>,struct Ma
```



II.7.3. Outlook and Evaluation - Readability

- Reading and understanding TMFs needs some practice
- TMF like EVAL_TABLE increase readability but extend compile time
- A lot of "<" and ">" increase possibility for errors.



II.7.3. Outlook and Evaluation - Compile time

- C++ compilers are not optimized for template metaprogramming
- compile times increase significantly (sometimes dramatically)
- template meta programs get interpreted, not compiled
- compile time depends on complexity of meta program, programming style and the implementation of the compiler



II.7.3. Outlook and Evaluation - Compiler Limits

- limitations vary among different compilers
- Execution of template meta programs are a byproduct of type generation and type inference
- complex computations result in complex types
- The C++ standard requires only 17 nested template instantiations (Annex AA)



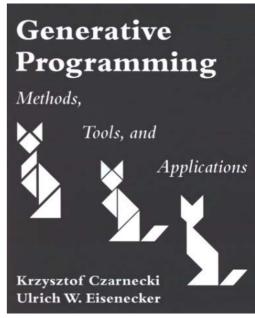
Overview

- What is template metaprogramming?
- Metainformation
- Computing values
- Computing types
- Functional Flavor of the Static Level
- Code generation
- Outlook and evaluation
- References



II.8. References

 Czarnecki, Eisenecker: Generative Programming: Methods, Techniques, and Applications, Addison-Wesley, 2000



- Eisenecker, Czarnecki: **Template-Metaprogrammierung eine Einführung**, OBJEKTspektrum 3/99
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III. Advanced Techniques



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Overview

- Template Metaprogramming & Data Structures
- Type Checking
- Guiding Code Production with Data Structures
- Expression Templates and PETE
- Advanced Metaprograms
- References



III.1.1. TMP & Data Structures - Overview

- Simple Variables
- Singly Linked Lists
- Trees



III.1.1. TMP & Data Structures - Simple Variables

• varaibles are **typedef** names and integral constants

```
struct StopTag {};

typedef PrintPower2<5> DefaultStatement;

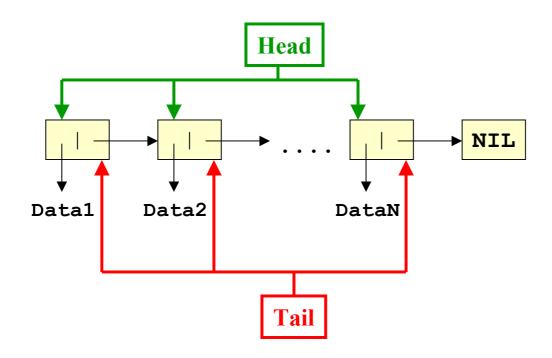
const int UNROLL_DEPTH = 2;
```

• single assignment rule:

Variables are initialized ones, their value cannot be changed

III.1.2. TMP & Data Structures - Singly Linked Lists

- Use **nested templates** to represent list.
- View list as chain of head-and-tail pairs:



- Head contains list-element, Tail contains rest of list.
- Tail of last element is **NIL** the empty list



III.1.2. TMP & Data Structures - Singly Linked Lists (SLL)

- Remember the *functional flavor*!
- With LISP, lists get created through the cons contructor:

```
(cons 0 (cons 0 (cons 7 (cons 42 nil))))
creates the list ( 0 0 7 42 )
```

• Make cons a template struct and nil a struct:

```
CONS<0, CONS<0, CONS<7, CONS<42, NIL>>>>
```

```
struct NIL { enum {head=(~(~0u) >> 1)} };

template <int headVal,typename TAIL>
struct CONS {
   enum { head=headVal };
   typedef TAIL Tail_t;
};
```

```
# length: [a] -> int
length [] = 0
length (h:t) = 1 + length t
                               Argument type becomes template parameter
template < typename LIST> struct Length;
template <>
struct Length<NIL> {
  enum { RET = 0 };
};
template <typename LIST>
struct Length {
  enum { RET = 1 + Length<typename LIST::Tail T>::RET }
};
```

```
# length: [a] -> int
length []
length (h:t) = 1/+ length t
                               Integral result-type becomes enum member
template <typename LIST> struct Length;
template <>
struct Length<NIL> {
 enum { RET = 0 };
};
template <typename LIST>
struct Length {
 enum { RET = 1 + Length<typename LIST::Tail T>::RET }
};
```



```
# length: [a] -> int
length []
                                 Every pattern becomes a template /
length (h:t) = 1 + length t
                                 template specialization
template <typename LIST> struct Length;
template <>
struct Length<NIL>
  enum { RET = 0 };
};
template <tvpename LIST>
struct Length { // struct Length<LIST>
  enum { RET = 1 + Length<typename LIST::Tail T>::RET }
};
```



```
# length: [a] -> int
length []
            = 0
                                   Statement becomes assignment to RET /
length (h:t) = 1 + length t
                                   typedef definition for RET
template <typename LIST> struct Length;
template <>
struct Length<NIL> {
 enum { RET = 0 };
};
template <typename LIST>
struct Length {
  enum { RET = 1 + Length<typename LIST::Tail T>::RET }
};
```

III.1.2. TMP & Data Structures - SLL - Checking for a List Member

III.1.2. TMP & Data Structures - SLL - Append

```
# append: [a] -> [a] -> [a]
append [] a = a
append (h:t) a = h:append t a
```

```
template <typename LIST1, typename LIST2> struct append;
template <typename LIST2>
struct append<NIL,LIST2> {
 typedef LIST2 RET;
};
template <typename LIST1, typename LIST2>
struct append {
  typedef CONS<LIST1::head,
               typename append<typename LIST1::Tail T, LIST2>::RET
              > RET;
};
```

III.1.2. TMP & Data Structures - SLL - Storing More Complex Meta-Data

• Producing lists of elements of arbitrary types:

```
struct NIL { };

template <typename HEAD, typename TAIL>
struct CONS {
   typedef HEAD Head_T;
   typedef TAIL Tail_T;
};
```

- length and append still work!
- Slightly different version of **member** needed now!



III.1.2. TMP & Data Structures - SLL - Member II

template <typename LIST, typename M>

struct Member {

};

```
# equal a -> b -> bool
                        template <typename T1, typename T2>
equal x y = False
                        struct EOUAL { enum { RET = false}; };
equal x x = true
                        template <typename T>
                        struct EQUAL <T,T> { enum { RET = true }; };
# member: [a] -> a -> bool
member [] a = False
member (h:t) a = h==a || member t a
template <typename LIST, typename M> struct Member;
template <typename M>
struct Member<NIL,M> {
  enum { RET = false };
};
```

enum { RET = EQUAL<typename LIST::Head T,M>::RET | |

Member<typename LIST::Tail T,M>::RET };

III.1.3. TMP & Data Structures - Trees

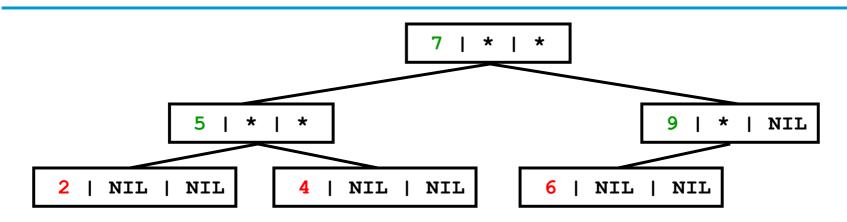
- *Idea*: flatten tree into a list
- First, define tree and nodes:

```
struct NIL {};

template <int value, typename LEFT, typename RIGHT>
struct BinaryNode {
  typedef LEFT Left_T;
  enum { Value=value };
  typedef RIGHT Right_T;
}
```



III.1.3. TMP & Data Structures - Trees - A Binary Tree



III.1.3. TMP & Data Structures - Trees - Depth of a Tree

```
template <int v1,int v2>
struct Max {
 enum { RET = (v1 > v2) ? v1 : v2 };
};
template <typename T> struct Depth;
template <> struct Depth<NIL> {
  enum { RET = 0 };
};
template <typename T> struct Depth {
   enum { RET = 1 + Max<Depth<typename T::Left T>::RET,
                        Depth<typename T::Right T>::RET
                       >::RET;
        };
};
```



III.1.3. TMP & Data Structures

- Nested templates can be used to represent data
- Lists, Trees, Nodes, Graphs, etc. possible
- TMFs act on data
- tight relation to functional programming
- type names may get even longer
- increased compile time



Overview

- Template Metaprogramming & Data Structures
- *Type Checking*
- Guiding Code Production with Data Structures
- Expression Templates and PETE
- Advanced Metaprograms
- References



III.2. Type Checking - Member

• **Problem:** It is not obvious that **member** is acting on a list!

```
template <typename LIST, typename M> struct Member;
template <typename M>
struct Member<NIL,M> {
 enum { RET = false };
};
template <typename LIST, typename M>
struct Member {
  enum { RET = EQUAL< typename LIST : Head T, M>::RET | |
               Member typename LIST::Tail T,M>::RET };
};
                          name of parameter as a hint
```

• Calling **Member** with other *types* results in complicated error messages



III.2. Type Checking - Error

```
//..
const bool inList = Member<double,double>::RET; // line 133
```

• g++ 2.95.2 generates the following error message:

```
List.cc: In instantiation of 'Member<double,double>'
list.cc:133: instantiated from here
list.cc:133: 'double' is not a class, struct, or union type
list.cc:133: template argument 1 is invalid
list.cc:133: 'double' is not a class, struct, or union type
list.cc:133: template argument 1 is invalid
list.cc:133: enumerator value of 'RET' not integer constant
```

- Oops: the real problem is that **double** is not a **CONS** type g++ doesn't tell ...
- Understanding error message depends on accessibility of **Member**
- But: no pointer to definition of **Member**



III.2. Type Checking - Generating Errors / Error Templates

• Declare a template structure whose name is the error message to generate

• In case of a type-error: create an instance of the error template

```
template <typename LIST, typename M>
struct Member2 {
   ERROR_EXPECTED_A_LIST_TYPE<LIST> error;
};
```

Instantiating this template will cause an error because ERROR_EXPECTED_A_LIST_TYPE

is undefined!

• template specializations for *type-safe* cases:

```
template <typename M>
struct Member2<NIL, M> { ... }:

template <typename M, typename HEAD, typename TAIL>
struct Member2<CONS<HEAD, TAIL>, M> { ... };
```



III.2. Type Checking - Generating Errors

This error message contains a lot more information:

- The real **error message** appears and contains a hint to the **wrong argument**
- Line **294** contains the **erroneous call** to the **Member 2** TMF
- The definition of Member starts at line 119
- Still not an optimal solution. Unfortunately, the best one I have at hand



III.2. Type Checking - Generating Error Messages: A more complicated example I

• Another possible solution:

```
template <typename M>
class Error__First_parameter_must_be_a_LIST {
   // IGNORE_THIS is private in Member2 !
   typedef typename M::IGNORE_THIS T;
   enum { RET = T::IGNORE_THIS_AS_WELL };
};
```

```
template <typename NON_LIST,typename M>
struct Member3 {
private:
   struct IGNORE_THIS { enum { IGNORE_THIS_AS_WELL }; };
public:
   enum { RET = Error__First_parameter_must_be_a_LIST<Member3>::RET };
};
```

III.2. Type Checking - Generating Error Messages: A more complicated example II

```
//..
const bool inList = Member3<double,double>::RET; // line 165
```

• g++ 2.95.2 generates the following error message:

- Message starts with "real" error
- pointer to implementation of **Member3**
- still difficult to read



Overview

- Template Metaprogramming & Data Structures
- Type Checking
- Guiding Code Production with Data Structures
- Expression Templates and PETE
- Advanced Metaprograms
- References



III.3. Guiding Code Production - SLL - Polymorphic Lists (Runtime)

• Developing lists that store values of arbitrary types:

```
struct NIL { };
                                 Manipulate runtime data - runtime behaviour
template <typename HEAD, typename TAIL>
struct CONS {
   typedef HEAD Head T;
                                 Static information
   typedef TAIL Tail T;
   CONS(const HEAD & h,const TAIL& t) : head(h),tail(t) {}
   CONS(const CONS& rhs) : head(rhs.head),tail(rhs.tail) {}
   CONS& operator=(const CONS& rhs);
   const Head T& getHead() const { return head; }
   const Tail T& getTail() const { return tail; }
private:
   HEAD head:
                   Store instances of parameters - runtime information!
   TAIL tail;
```

III.3. Guiding Code Production - SLL - Polymorphic Lists (Runtime)

• convenience function to build lists

```
template <typename HEAD, typename TAIL>
inline CONS<HEAD, TAIL> cons(const HEAD& h, const TAIL& t) {
  return CONS<HEAD, TAIL>(h,t);
}
```

Example:

III.3. Guiding Code Production - Generating a List

- use function to produce temporary
- overload function to support lists of different size

```
template <typename A1, typename A2, typename A3>
CONS<A1,CONS<A2,CONS<A3,NIL> >>
mkList(const A1& a1,const A2& a2,const A3& a3) {
  return cons(a1,cons(a2,cons(a3,NIL())));
}

template <typename A1, typename A2, typename A3, typename A4>
CONS<A1,CONS<A2,CONS<A3,CONS<A4,NIL> >>>
mkList(const A1& a1,const A2& a2,const A3& a3,const A4& a4) {
  return cons(a1,cons(a2,cons(a3,cons(a4,NIL()))));
}
```



```
# foreach: [a] -> (a->b) -> [b]
foreach [] f = []
foreach (h:t) f = (f h):foreach t f
```

- applying **f** to the empty list [] yields the empty list []
- If the list is separable into a head **h** and a tail **t** we return a list whose
 - first element results from applying **f** to **h**
 - the tail of the list results from applying foreach to it

• passing anything else but a list to Foreach should yield a type error

```
# foreach: [a] -> (a->b) -> [b]
foreach [] f = []
foreach (h:t) f = (f h):foreach t f
```

• Return the empty list **NIL**, if **foreach** is applied to **NIL**

```
static part - compute result-type

template <typename F>
struct Foreach<NIL,F> {

    typedef NIL RET;

    static inline
    RET apply(const NIL& n) {
        return n;
    }
};
Runtime part - compute value
```

```
# foreach: [a] -> (a->b) -> [b]
foreach [] f = []
                                         Static part - compute result-type
foreach (h:t) f = (f h):foreach t f
template <typename HEAD, typename TAIL, typename fTAG>
struct Foreach<CONS<HEAD,TAIL>, fTAG> {
  typedef CONS< typename ApplyFunctor<HEAD, fTAG>::RET,
                 typename Foreach<TAIL, fTAG>::RET
              > RET;
 static inline
 RET apply(const CONS<HEAD,TAIL>& 1,const fTAG& f) {
     return cons(
             ApplyFunctor<HEAD,fTAG>::apply(l.getHead(),f),
             Foreach<TAIL,F>::apply(1.getTail(),f)
            );
```

Runtime part - compute value



• Indirectly calling the functor has some advantages

```
template <typename T,typename fTAG>
struct ApplyFunctor {};
```

• Per default, we apply the identity function:

```
struct IDTag {};

template <typename T>
struct ApplyFunctor<T,IDTag> {
   typedef T RET;
   static inline
   RET apply(const T& t,const IDTag&) { return t; }
};
```

• As for **cons**, we introduce a convenience function:

• Example [Inserting the values of a list into a stream]:

```
struct PrintValues {
 PrintValues(ostream& o) : o( o) {}
 ostream& getStream() const { return o; }
 std::ostream& o;
};
template <typename T>
struct ApplyFunctor<T,PrintValues > {
 typedef T RET;
  static inline RET apply(const T& n,const PrintValues& p) {
    p.getStream() << "[" << n << "]";</pre>
    return n;
 };
};
std::complex<double> c(1.0,3.0);
double
                    d=2.0;
forEach( mkList(c,d,s), PrintValues(std::cout) );
```

Transformed during compile time

```
std::complex<double> c(1.0,3.0);
std::string s="Hello";
double d=2.0;
cout << "[" << s << "]";
cout << "[" << d << "]";
cout << "[" << c << "]";</pre>
```

- Why reverse order (List is (c d s))?
- C++ does eager evaluation (call by name)



- *Task:* find a value of type **T** in a polymorphic list
- This only makes sense, if the list contains any value of type **T**

```
template <typename LIST, typename A>
bool isMember( const LIST& 1, const A& m ) {
  const bool TYPE_IN_LIST = Member2<LIST, A>::RET;
  if (! TYPE_IN_LIST) {
    return false;
  }
  else {
    // ... search the item
  };
};
```

• Use code selection to move execution of **if** into compile time



```
template <typename LIST, typename A>
struct returnFALSE {
  static inline bool exec(const LIST&,const A&) {
    return false;
};
template <typename LIST, typename A>
struct searchItem {
  static inline bool exec(const LIST& 1,const A& m) {
  // .. search the item
 };
};
template <typename LIST, typename A>
bool isMember( const LIST& 1, const A& m ) {
  enum { TYPE IN LIST = Member2<LIST, A>::RET };
  return IF< TYPE IN LIST, searchItem<LIST, A>,
                            returnFALSE<LIST, A>
           >::RET::exec(1,m);
};
```



- Only need to compare items of same type!
- Build new list that only contains values of desired type

```
template <typename P, typename HEAD, typename TAIL>
struct Filter<P, CONS<HEAD,TAIL> > {
//...
  struct return H F { // include HEAD
    static inline
    RET apply(const CONS<HEAD, TAIL>& 1) {
      return cons(1.getHead(),
                  Filter<P,TAIL>::apply( l.getTail() )
                 );
  };
  struct return F { // remove HEAD
    static inline
    RET apply(const CONS<HEAD, TAIL>& 1) {
      return Filter<P,TAIL>::apply( l.getTail() );
  };
  //..
```



```
template <typename P, typename HEAD, typenam TAIL>
struct Filter<P, CONS<HEAD,TAIL> > {
//...
  static inline
 RET apply(const CONS<HEAD, TAIL>& 1) {
    return IF<P::template apply<HEAD>::RET,
              return H F,
              return F
             >::apply(1);
//..
};
// ... handle case for empty list ...
```

```
template <typename P,typename LIST>
typename Filter<P,LIST>::RET filter(const P& p, const LIST& 1) {
  return Filter<P,LIST>::apply(1);
};
```



• *Example:* filtering all complex numbers:

```
struct isComplex {
  template <typename T> struct apply {
    enum { RET = false };
  };
  template <typename T> struct apply<complex<T> > {
    enum { RET = true };
 };
};
complex<double> c(1,2),d(3,4);
double x,y,z;
forEach( filter(isComplex(),
                mkList(c, d, x, y, z)
               ),
          printTag()
```

```
Transformed during compile time
```

```
cout << "[" << d << "]";
cout << "[" << c << "]";
```

III.3. Guiding Code Production - Finding Element in List (Runtime)

- operator == maybe undefined, especially if M != Head_T
- -> return false whenever M != Head_T

};

};



constraint: operator == needs to be defined!

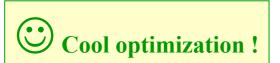
III.3. Guiding Code Production - Finding Element in List (Runtime)

```
template <typename HEAD, typename TAIL, typename M>
struct Member<CONS<HEAD,TAIL>, M> {
 //...
  struct returnFALSE {
    static inline bool exec(const CONS<HEAD, TAIL>& 1, const M& m) {
      return false;
  };
  struct returnCOMP {
    static inline bool exec(const CONS<HEAD, TAIL>& 1, const M& m) {
      return 1.getHead() == m;
  };
  static inline
 bool apply(const CONS<HEAD, TAIL>& 1, const M& m) {
    return IF< EQUAL<HEAD, M>::RET,
               returnCOMP, returnFALSE >::RET::exec(1,m) ||
           Member<TAIL,M>::apply(1.getTail(), m);
```



III.3. Guiding Code Production - Finding Element in List (Runtime)

```
complex<double> a(2,3);
string b="Hello";
double c=2.0;
double d=3.0;
complex<double> e(4,5);
member( filter(isComplex(),
                mkList(a,b,c,d)
               ),
         e
         ? cout << "Yes" : cout << "No";
          Transformed
                              a==e ? cout << "Yes" : cout << "No";</pre>
          during compile time
```







III.3. Guiding Code Production - Summary

- TMP provides good means to optimize programs
- TMP to do partial evaluation
- Expression templates use GCP
- Implementing sub language (FACT!)
- compile times increase
- meta programs + data structures result in very very long typenames



Overview

- Template Metaprogramming & Data Structures
- Type Checking
- Guiding Code Production with Data Structures
- Expression Templates and PETE
- Advanced Metaprograms
- References



III.4. Expression Templates - The Problem I

As shown on section **I**, operator overloading introduces a lot of temporaries and copy constructor calls:

```
complex<double> a,b,c,d,result;
result = a * b - (c + d);
```

How many temporaries are created here?

- a temporary to hold the value of a * b
- a temporary to hold the result of c + d
- a temporary to hold the result of subtraction
- may be very expensive!

```
// C - code:
complex<double> tmp1;
operator*(tmp1,a,b);

complex<double> tmp2;
operator+(tmp2,c,d);

complex<double> tmp3;
operator-(tmp3,tmp1,tmp2);

result.complex<double>::operator=(tmp3);

tmp3.complex<double>::~complex<double>;
tmp2.complex<double>::~complex<double>;
tmp1.complex<double>::~complex<double>;
```



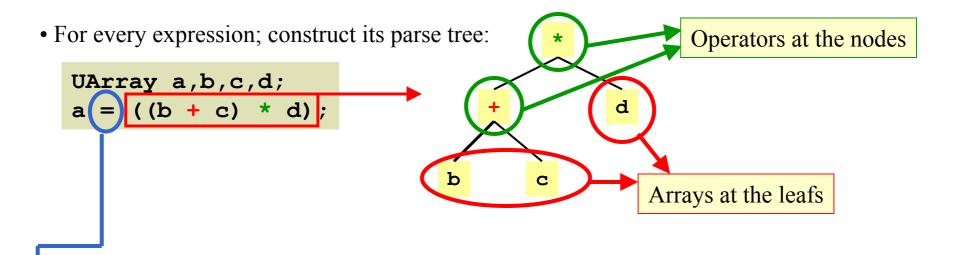
III.4. Expression Templates - The Problem II

```
template <int size>
struct UArray {
  // ... Constructors / destructor / other stuff
private:
  double data[size];
};
template <int size>
UArray<size> operator+(const UArray<size>& a,const UArray<size>& b) {
  array tmp;
  for (int i=0 ; i<size; i++) {
    tmp[i] = a[i] + b[i];
  return tmp;
//... almost the same for opertaor-, operator*, operator/, ...
                      Four loops (one for the assignment)!
UArray<10> a,b,c,d,e;
d = (a+b) / (c*d);
                       Desirable: single loop!
```

For brevity we omit the integer template parameter for the rest of this section



III.4. Expression Templates - The Fundamental Idea



• Traverse tree **size** times and perform actions according to tree nodes

```
template <typename ParseTree>
UArray& UArray::operator=(const ParseTree& t) {
  for (int i=0 ; i< size; i++)
    data[i] = TraverseTreeAndPerformOp( t, i );
}</pre>
```

Evaluation of expression is postponed until assignment occurs!



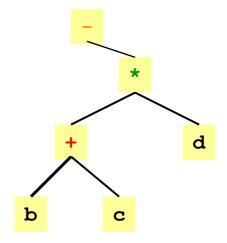
III.4. Expression Templates - The Expression Tree

• The datatypes for the parse tree (expression template tree)

```
Expression = Scalar a
| UnaryNode OpTag Expression |
| BinaryNode OpTag Expression Expression |
| TernaryNode OpTag Expression Expression Expression
```

• Example:

```
UArray b,c,d;
-((b + c) * d);
```



```
UnaryNode OpUnaryMinus (BinaryNode OpMultiply
(BinaryNode OpAdd UArray UArray)
UArray
)
```



III.4. Expression Templates - The Expression Tree

```
Expression = Scalar a
| UnaryNode OpTag Expression
| BinaryNode OpTag Expression Expression
| TernaryNode OpTag Expression Expression
```

```
template <typename T>
struct Scalar;

template <typename OpTag,typename CHILD>
struct UnaryNode;

template <typename OpTag,typename LEFT,typename RIGHT>
struct BinaryNode;

template <typename OpTag,typename LEFT,typename MIDDLE,typename RIGHT>
struct TernaryNode;
```

- Provide constructor, copy constructor
- Store tag and childs
- Provide constant access functions to childs and tag



III.4. Expression Templates - Node Types

• Example: Implementation of UnaryNode

```
template <typename OP, typename CHILD>
struct UnaryNode {
  UnaryNode(const OP& o,const CHILD& c) : op(o),child(c) {}
  UnaryNode(const UnaryNode& rhs) :
     op(rhs.op),child(rhs.child) {}
  const OP& operation() const { return op; }
  const CHILD& child() const { return child; }
private:
  OP
      op;
  CHILD child;
};
```



III.4. Expression Templates - Tags

```
struct OpUnaryMinus {
  template <typename T>
  inline T operator()(const T& t) const { return -t; }
};
struct OpMultiply {
  template <typename A1, typename A2>
  inline ??? operator()(const A1& a1,const A2& a2) const {
    return al * a2;
};
          Result-type? See section II.4.1
struct OpMultiply {
  template <typename A1, typename A2>
  inline typename BinaryReturn<A1,A2,OpMultiply>::Type t
     operator()(const A1& a1,const A2& a2) const {
    return a1 * a2;
};
```

• User may specialize **BinaryReturn** for his types (if necessary)



III.4. Expression Templates - Computing Return Types

• The default case for **BinaryReturn** can reuse the **Promote** metafunction that was introduced in **section II4.2**

```
template <typename A1, typename A2, typename OP>
struct BinaryReturn {
  typedef typename Promote<A1, A2>::RET Type_t;
};
```

• For user-defined classes (e.g. matrices) the user could specialize **BinaryReturn**:

```
template <typename A1, typename A2>
struct BinaryReturn<Matrix<A1>,Matrix<A2>, OpAdd > {
   typedef Matrix<typename Promote<A1,A2>::RET> Type_t;
};

template <typename A1, typename A2>
struct BinaryReturn<Matrix<A1>,Vector<A2>, OpMultiply > {
   typedef Vector<typename Promote<A1,A2>::RET> Type_t;
};
```

III.4. Expression Templates - Building the Parse Tree I

• **Problem:** we need overloaded versions of **operator+** for **15** other cases (see next slide)



III.4. Expression Templates - Building the Parse Tree II

```
UArray
UArray
UArray
```

```
+ UnaryNode<*,*>
+ BinaryNode<*,*,*>
+ TernaryNode<*,*,*,*>
```

```
UnaryNode<*,*>
                     + UArray
BinaryNode<*,*,*>
                     + UArray
TernaryNode<*,*,*,*>
                     + Uarray
                     + UnaryNode<*,*>
UnaryNode<*,*>
UnaryNode<*,*>
                     + BinaryNode<*,*,*>
UnaryNode<*,*>
                     + TernaryNode<*,*,*,*>
                     + BinaryNode<*,*,*>
BinaryNode<*,*,*>
BinaryNode<*,*,*>
                     + UnaryNode<*,*>
BinaryNode<*,*,*>
                     + TernaryNode<*,*,*,*>
TernaryNode<*,*,*,*> + TernaryNode<*,*,*,*>
TernaryNode<*,*,*,*> + BinaryNode<*,*,*>
TernaryNode<*,*,*,*> + UnaryNode<*,*>
```

These are all of type **Expression** but the compiler doesn't know - 3 additional cases are sufficient:

Use wrapper to indicate type!



III.4. Expression Templates - Building the Parse Tree III

```
template <typename E>
struct Expression {
  typedef E Expression_t;

  Expression(const E& _e) : e(_e) {}
  Expression(const Expression& rhs) : e(rhs.e) {}

  const Expression_t& expression() const { return e; }
  private:
    E e;
};
```

• Expression is used to wrap values of type UnaryNode, BinaryNode, TernaryNode

```
Expression< UnaryNode<OpUnaryMinus, UArray> >
Expression< BinaryNode<OpMultiply, UArray, UArray> >
```



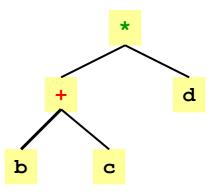
III.4. Expression Templates - Building the Parse Tree IV

```
Expression< BinaryNode<OpAdd,</pre>
                         UArray,
                         UArray> > operator+(const UArray& a,
                                               const UArray& b) {
  return Expression < BinaryNode < OpAdd, UArray, UArray > (
                      BinaryNode<OpAdd, UArray, UArray>(OpAdd(), a, b)
                      );
};
template <typename E, int size>
Expression < Binary Node < Op Add,
                       Ε,
                        UArray> > operator+(const Expression<E>& e,
                                              const UArray& b) {
  return Expression SinaryNode OpAdd, E, Uarray > (
                      BinaryNode<OpAdd, E, UArray>(OpAdd(), a,
                                                    e.expression())
                       );
};
```

• Notice how the incoming expression gets unwrapped and the result is wrapped ...



III.4. Expression Templates - Building the Parse Tree V



Resulting Expression Template Tree

Memory
(the Object)
OpMultiply
OpAdd
&b
&c
&c
&d

III.4. Expression Templates - Building the Parse Tree VI

- What shall we store at the Leafs? Copies, references, pointers?
- Allow the developer to specify this (if necessary)!

```
template <typename T>
struct CreateLeaf {
  typedef Scalar<T> Leaf_t;
  static inline Leaf_t make(const T& t) { return Scalar<T>(t); }
};
```



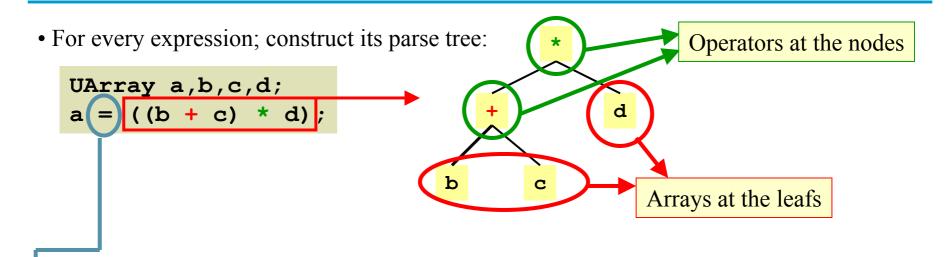
III.4. Expression Templates - Building the Parse Tree VII

- Storing copies of an array imposes lots of copy constructors being called
- PETE has special wrapper **Reference** to store references at the leaf:

```
template <>
struct CreateLeaf< UArray > {
  typedef Reference< UArray > Leaf_t;
  static inline Leaf_t make(const UArray& a) {
    return Leaf_t( a );
  }
};
```

- PETE offers tool-support for the generation of all the overloaded operators
- To build the expression tree, the user usually only has to specialize from CreateLeaf

III.4. Expression Templates - The Fundamental Idea - So far we have ...



• Traverse tree **size** times and perform actions according to tree nodes

```
template <typename ParseTree>
UArray& UArray::operator=(const ParseTree& t) {
  for (int i=0 ; i< size; i++)
    data[i] = TraverseTreeAndPerformOp( t, i );
}</pre>
```

III.4. Expression Templates - The Fundamental Idea - So far we have ...

• For every expression; construct its parse tree:

```
UArray a,b,c,d;
a = ((b + c) * d);

Resulting Expression Template Tree
Expression
Expression
Expression
Expression Template Tree

Expression
UArray

UArray

UArray

UArray

>
```

• Traverse tree size times and perform actions according to tree nodes

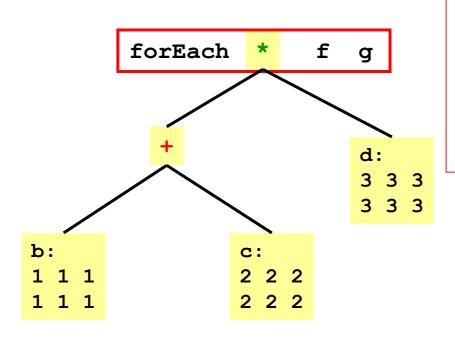
```
template <typename E>
UArray& UArray::operator=(const Expression<E>& t) {
  for (int i=0 ; i< size; i++)
    data[i] = TraverseTreeAndPerformOp( t, i );
}</pre>
```

TraverseTreeAndPerformOp is still missing



f: (applied to LEAFS) return value of array at index **i**

g: (applied to NODES) perform operation according to node



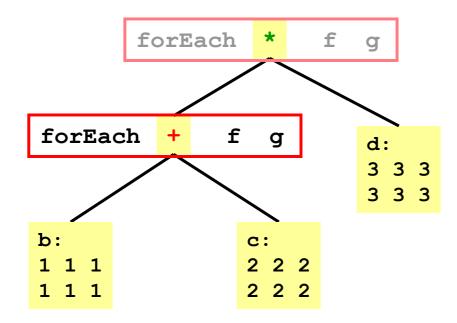
We are at a node: multiply left and right son

- -> evaluate left branch
- -> evaluate right branch
- -> perform multiplication



f: (applied at LEAFS) return value of array at index **i**

g: (applied at NODES) perform operation according to node

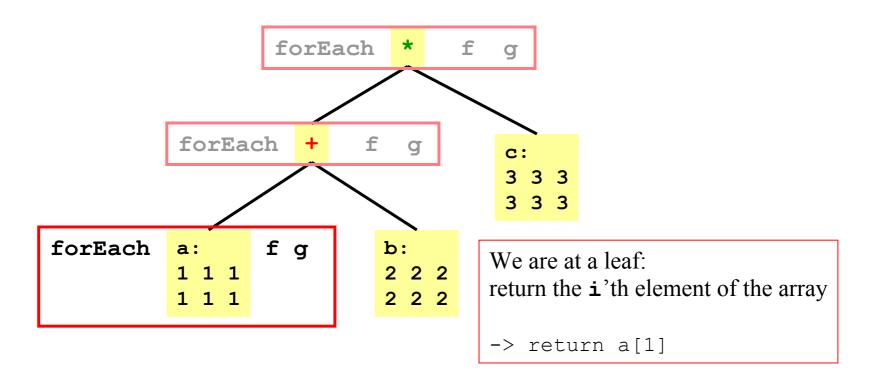


We are at a node: add left and right son

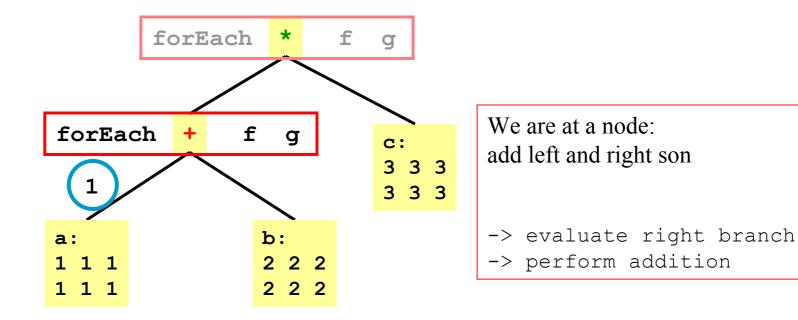
- -> evaluate left branch
- -> evaluate right branch
- -> perform addition



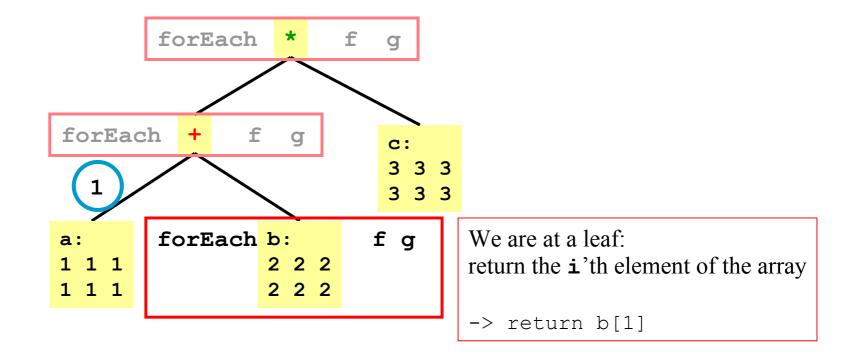
f: (applied to LEAFS) return value of array at index i



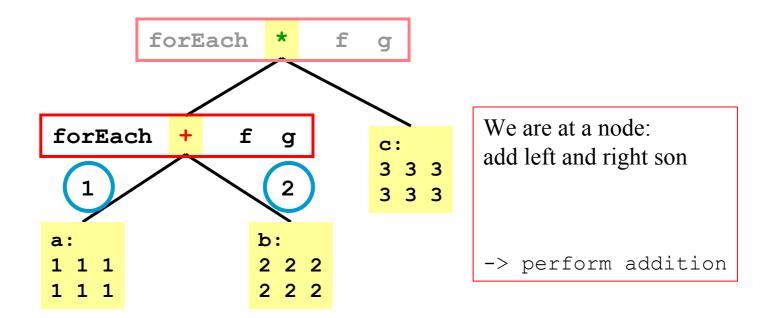
f: (applied to LEAFS) return value of array at index **i**



f: (applied to LEAFS) return value of array at index **i**

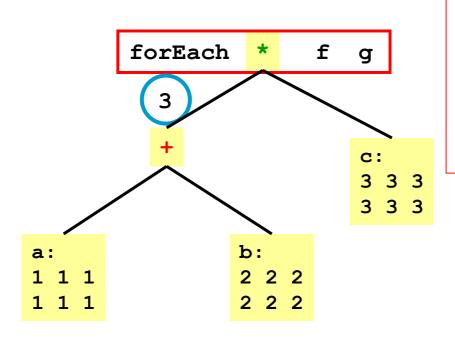


f: (applied to LEAFS) return value of array at index **i**



f: (applied to LEAFS) return value of array at index **i**

g: (applied to NODES) perform operation according to node

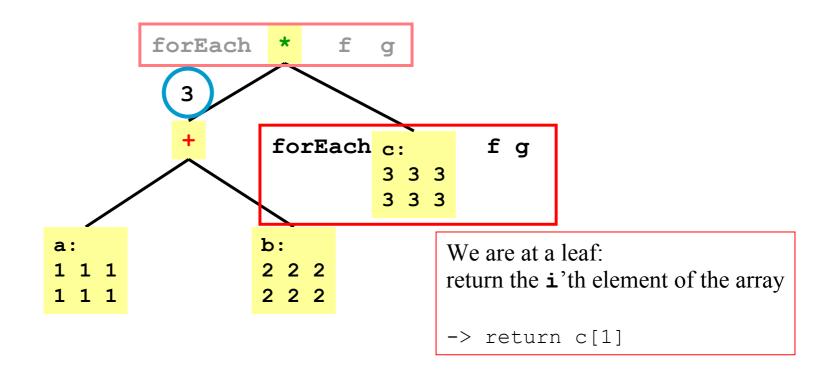


We are at a node: multiply left and right son

- -> evaluate right branch
- -> perform multiplication

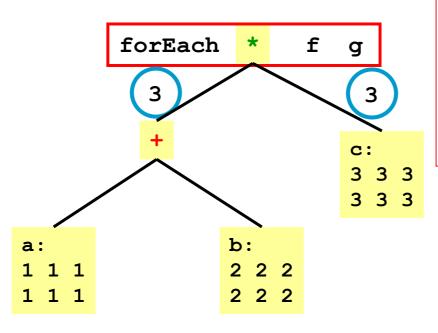


f: (applied to LEAFS) return value of array at index **i**



f: (applied to LEAFS) return value of array at index **i**

g: (applied to NODES) perform operation according to node

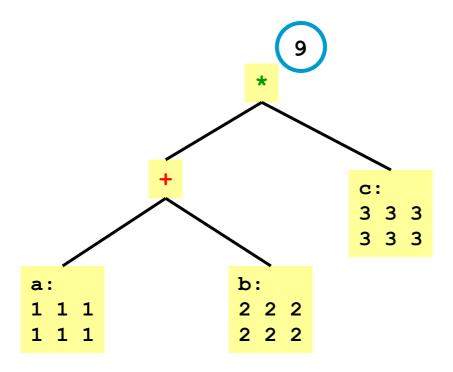


We are at a node: multiply left and right son

-> perform multiplication



f: (applied to LEAFS) return value of array at index i



- Use template metafunctions to traverse the expression tree and to produce code
- Guiding Code Production as we have done with lists (see III.3.)

General Version of ForEach:

```
template <typename Expression, typename fTag, typename gTag>
struct ForEach;
```



• When visiting a leaf we perform the action according to the tag **fTag**:

• For user-defined types, we need a specialization of **LeafFunctor**!

Example:

```
template <int size>
struct UArray {
};
struct EvalAt {
 EvalAt(int i) : n(i) {}
  const int& at() const { return n; }
 int n;
};
template <int size>
struct LeafFunctor<UArray<size>, EvalAt > {
  typedef double Type t;
  static inline
  Type t apply(const UArray<size>& u,const EvalAt& a) {
    return u[a.at()];
};
```



- Reaching a binary node, we have to
 - evaluate the left child
 - · evaluate the right child
 - perform the operation according to gTag

```
template <class Op, class L, class R, class fTag, class gTag>
struct ForEach<BinaryNode<Op,L,R>, fTag, gTag> {
 typedef typename ForEach<L,fTag,gTag>::Type t
                                                       NL t:
 typedef typename ForEach<R,fTag,gTag>::Type t
                                                      NR t;
 typedef typename Combine2<NL t,NR t, Op, gTag>::Type t Type t;
 static inline
 Type t apply (const BinaryNode<Op, L, R>& e,
               const fTag& f, const gTag& g) {
   return Combine2<NL t, NR t, Op, gTag>::apply(
               ForEach<L, fTag, gTag>::apply(e.left(),f,g),
                ForEach<R,fTag,gTag>::apply(e.right(),f,g),
               e.operation(),
               q );
```

• PETE provides the pre-defined **OpCombine** tag:

```
template <typename A, typename B, typename OP, typename gTag>
struct Combine2 {};

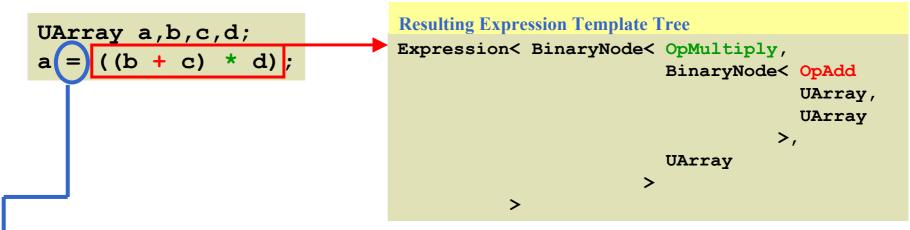
template <typename A, typename B, typename OP>
struct Combine2<A,B,OP, OpCombine> {

   typedef typename BinaryReturn<A,B,OP>::Type_t Type_t;

   static inline
   Type_t apply(A a,B b,OP op,OpCombine) {
      return op(a,b);
   }
};
```



III.4. Expression Templates - How it works



• Traverse tree **size** times and perform actions according to tree nodes

```
template <typename E>
UArray& UArray::operator=(const Expression<E>& t) {
  for (int i=0 ; i < size; i++)
      data[i] = forEach(t, EvalAt(i), OpCombine());
}

Transformed during compile time!

(b[i] + c[i]) * d[i]</pre>
```

III.4. Expression Templates - How it works

```
UArray a,b,c,d;
a = ((b + c) * d);

Transformed during compile time

for (int i=0 ; i<size; i++)
    a[i] = (b[i] + c[i]) * d[i];</pre>
```

Single loop!
No temporaries!

No overhead!... If using a highly optimizing C++ compiler ...



III.4. Expression Templates - Using PETE (Summary)

To make a user-defined type **T** aware of expression templates:

- The user has to provide a specialization for CreateLeaf<T>
- T should provide an assignment operator (operator=) from Expression
- The user eventually needs to provide a specialization of **LeafFunctor**

Who creates all the overloaded operators (e.g. **operator+**, **operator***) for the user defined type?

Use PETE's MakeOperators tool

http://www.acl.lanl.gov/pete



Overview

- Template Metaprogramming & Data Structures
- Type Checking
- Guiding Code Production with Data Structures
- Expression Templates and PETE
- Advanced Metaprograms
- References



III.5. Advanced Metaprograms - Checking for Convertibility

How to check whether a type **A** could be converted into a type **B**?

Idea: Use function overloading:

• Everything could be passed to a function that makes use of the ellipsis

```
void check(...);
```

• Overland check with a function that expects a value of type B

```
void check(B dummy);
```

Problem: How to determine which variant has been chosen?

Idea: sizeof is a very powerful tool; it can be applied to very complex expressions!

III.5. Advanced Metaprograms - Checking for Convertibility

```
// Metaprogram that check whether an instance of A could be
// converted into an instance of type B
template <typename A, typename B>
struct convertible {
 struct isConvertible { char a;
                                                   };
 struct isNOTConvertible { char a[sizeof(char)+2];};
 static isConvertible check(B);
 static isNOTConvertible check(...);
 static A MakeA();
 enum { Ret = ( sizeof(check MakeA()) == sizeof(isConvertible) ) };
};
```

Avoid call to eventually non existing default constructor!

Notice, that neither **MakeA**, nor **isConvertible** / **isNOTConvertible** must be defined!



III.5. Advanced Metaprograms - Checking for Inheritance

How to check whether a class **A** is a subclass of **B**?

Remember what we have said in section **I.2.3**:

10. Pointer conversion

Conversion

- An rvalue of type pointer to cv D, where D is a class type, can be converted to an rvalue of type pointer to cv B, where B is a base class of D.
- •An rvalue of type pointer to $cv \, \mathbf{T}$, where \mathbf{T} is an object type, can be converted to an rvalue of type pointer to $cv \, \mathbf{void}$.

Note: Using this definition SUB SUPERCLASS<A, A>::Ret evaluates to true



Overview

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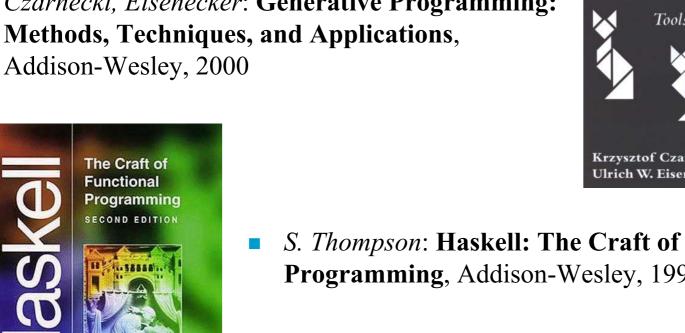


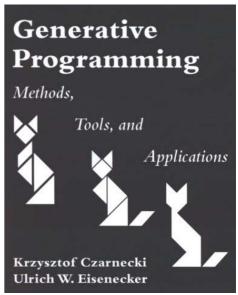
III.6. References

Simon Thompson

ADDISON-WESLEY

Czarnecki, Eisenecker: Generative Programming: Methods, Techniques, and Applications, Addison-Wesley, 2000





- S. Thompson: Haskell: The Craft of Functional **Programming**, Addison-Wesley, 1999
- For more info on Haskell go to http://www.haskell.org



III.6. References - Some Papers

- *T. Veldhuizen:* Expression Templates, C++ Report June 1995
- T. Veldhuizen, Using C++ template metaprograms, C++ Report May 1995
- J. Siek, A. Lumsdaine: Concept Checking: Binding Parametric Polymorphism in C++, Proceedings of TMPW 2000 http://oonumerics.org/tmpw00
- J. Striegnitz, S. Smith: An Expression Template aware Lambda Function, Proceedings of TMPW 2000 http://oonumerics.org/tmpw00



IV. Some Libraries

PETE

Easy addition of expression template functionality to user-defined classes

http://www.acl.lanl.gov/pete

POOMA

Efficient arrays for C++, array statements are executed data-parallel (MPI/threads - based on expression templates)

http://www.acl.lanl.gov/pooma

Blitz++

Efficient arrays for C++ - based on expression templates

http://oonumerics.org/blitz

FACT!

Functional programming with C++ (runtime - based on expression templates)

http://www.fz-juelich.de/zam/FACT

More at http://oonumerics.org



V. Conferences and Workshops

- European Conference on Object-Oriented Programming (ECOOP)
- Conference on Object-Oriented Programming, Systems, Languages, and Applications (OOPSLA)
- International Symposium on Computing in Object-Oriented Parallel Environments (ISCOPE)
- Workshop on Parallel/High Performance Object-Oriented Scientific Computing (POOSC)
- Workshop on C++ Template Programming (TMPW)
- Multi-Paradigm Programming with Object-Oriented Languages (MPOOL)