## **Problem Formulation**

The metalevel search space: The MDP  $\langle S, A, T, R, s, t \rangle$ 

- A set of states  $s \in S$ .
- A set of actions  $a \in A$ .
- A transition function T(s, a, s').
- A reward function R(s).
- A start state s.
- A terminal state t.

The state: A state s is an object model consists of a grounded PDDL domain model  $\langle P, A \rangle$ .

- A set of propositions P.
- A set of actions  $a_{EFF}^{PRE} \in A$ .
- Each action  $a_e^p$  has a set PRE of preconditions and a set EFF of effects.

Working Domain:

Listing 1: LightSwitch Domain

## State Metaspace Analysis

Let p be the number of predicates, a be the number of actions.

Each action has a set PRE and EFF of propositions. For each proposition, there are three possible values that it can take on in a concrete instance of the model:

- The proposition can belong to clause as a positive literal.
- The proposition can belong to a clause as a negative literal.
- The proposition can not belong to the clause.

Thus, for each action, there are  $3^{2p}$  possibilities. For all a actions, there are  $\prod_{1}^{a} 3^{2p} = (3^{2p})^a = 3^{2ap}$  possibilities.

For the example domain, we have p=2 predicates and a=2 actions and  $3^{2ap}=3^{2*2*2}=3^8=6561$  possible domain models.

## **Action Metaspace Analysis**

Let p be the number of predicates, a be the number of actions. Given a metastate s in the metaspace S, each proposition can be changed to one of the other two possibile values. Thus, there are 4ap metaactions.