



1. Description

1.1. Project

Project Name	scorbot_controller
Board Name	NUCLEO-F767ZI
Generated with:	STM32CubeMX 6.9.2
Date	01/18/2024

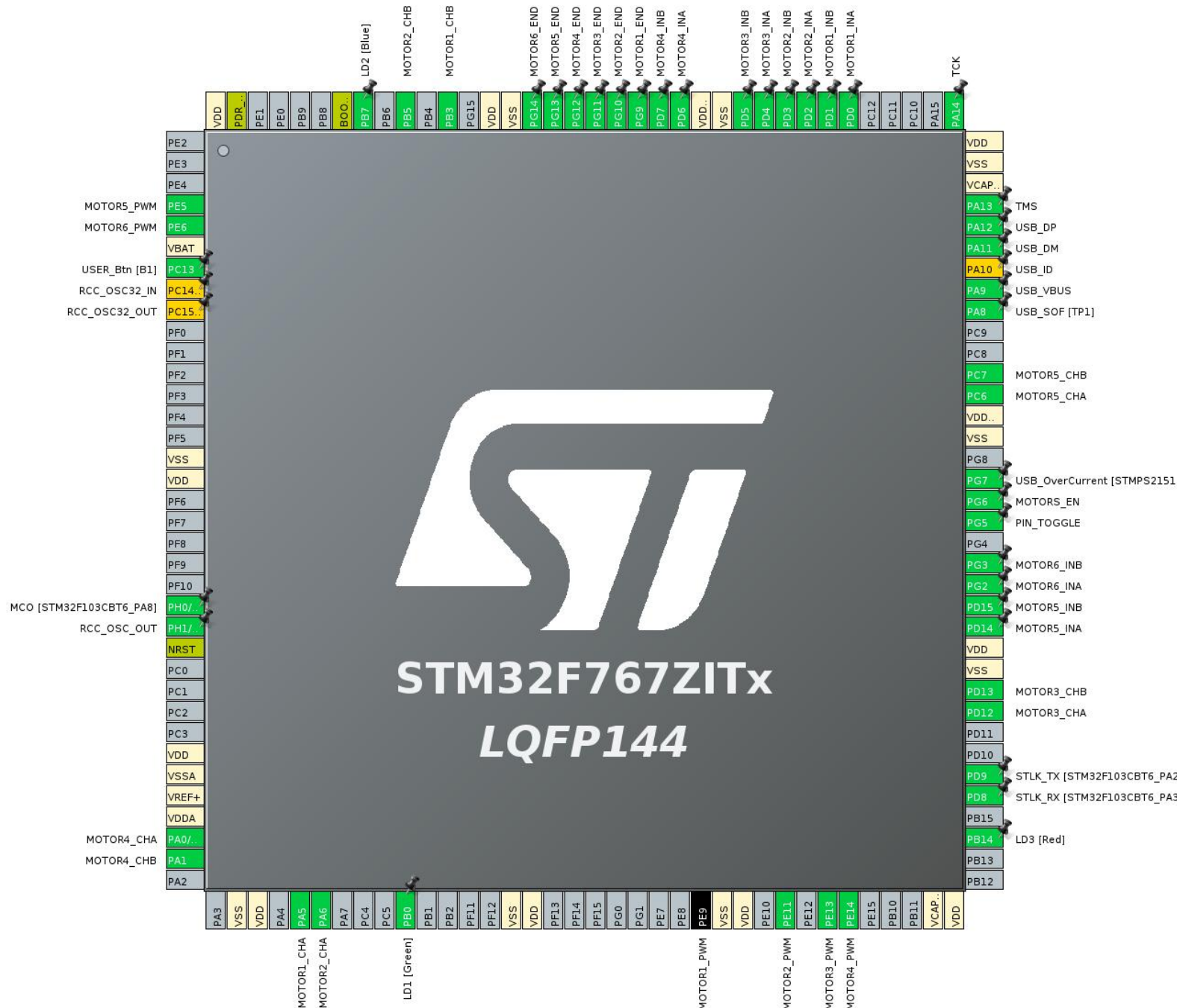
1.2. MCU

MCU Series	STM32F7
MCU Line	STM32F7x7
MCU name	STM32F767ZITx
MCU Package	LQFP144
MCU Pin number	144

1.3. Core(s) information

Core(s)	Arm Cortex-M7
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2. Pinout Configuration



3. Pins Configuration

Pin Number LQFP144	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
4	PE5	I/O	TIM9_CH1	MOTOR5_PWM
5	PE6	I/O	TIM9_CH2	MOTOR6_PWM
6	VBAT	Power		
7	PC13	I/O	GPIO_EXTI13	USER_Btn [B1]
8	PC14/OSC32_IN *	I/O	RCC_OSC32_IN	
9	PC15/OSC32_OUT *	I/O	RCC_OSC32_OUT	
16	VSS	Power		
17	VDD	Power		
23	PH0/OSC_IN	I/O	RCC_OSC_IN	MCO [STM32F103CBT6_PA8]
24	PH1/OSC_OUT	I/O	RCC_OSC_OUT	
25	NRST	Reset		
30	VDD	Power		
31	VSSA	Power		
32	VREF+	Power		
33	VDDA	Power		
34	PA0/WKUP	I/O	TIM5_CH1	MOTOR4_CHA
35	PA1	I/O	TIM5_CH2	MOTOR4_CHB
38	VSS	Power		
39	VDD	Power		
41	PA5	I/O	TIM2_CH1	MOTOR1_CHA
42	PA6	I/O	TIM3_CH1	MOTOR2_CHA
46	PB0 **	I/O	GPIO_Output	LD1 [Green]
51	VSS	Power		
52	VDD	Power		
60	PE9	I/O	TIM1_CH1	MOTOR1_PWM
61	VSS	Power		
62	VDD	Power		
64	PE11	I/O	TIM1_CH2	MOTOR2_PWM
66	PE13	I/O	TIM1_CH3	MOTOR3_PWM
67	PE14	I/O	TIM1_CH4	MOTOR4_PWM
71	VCAP_1	Power		
72	VDD	Power		
75	PB14 **	I/O	GPIO_Output	LD3 [Red]
77	PD8	I/O	USART3_TX	STLK_RX [STM32F103CBT6_PA3]

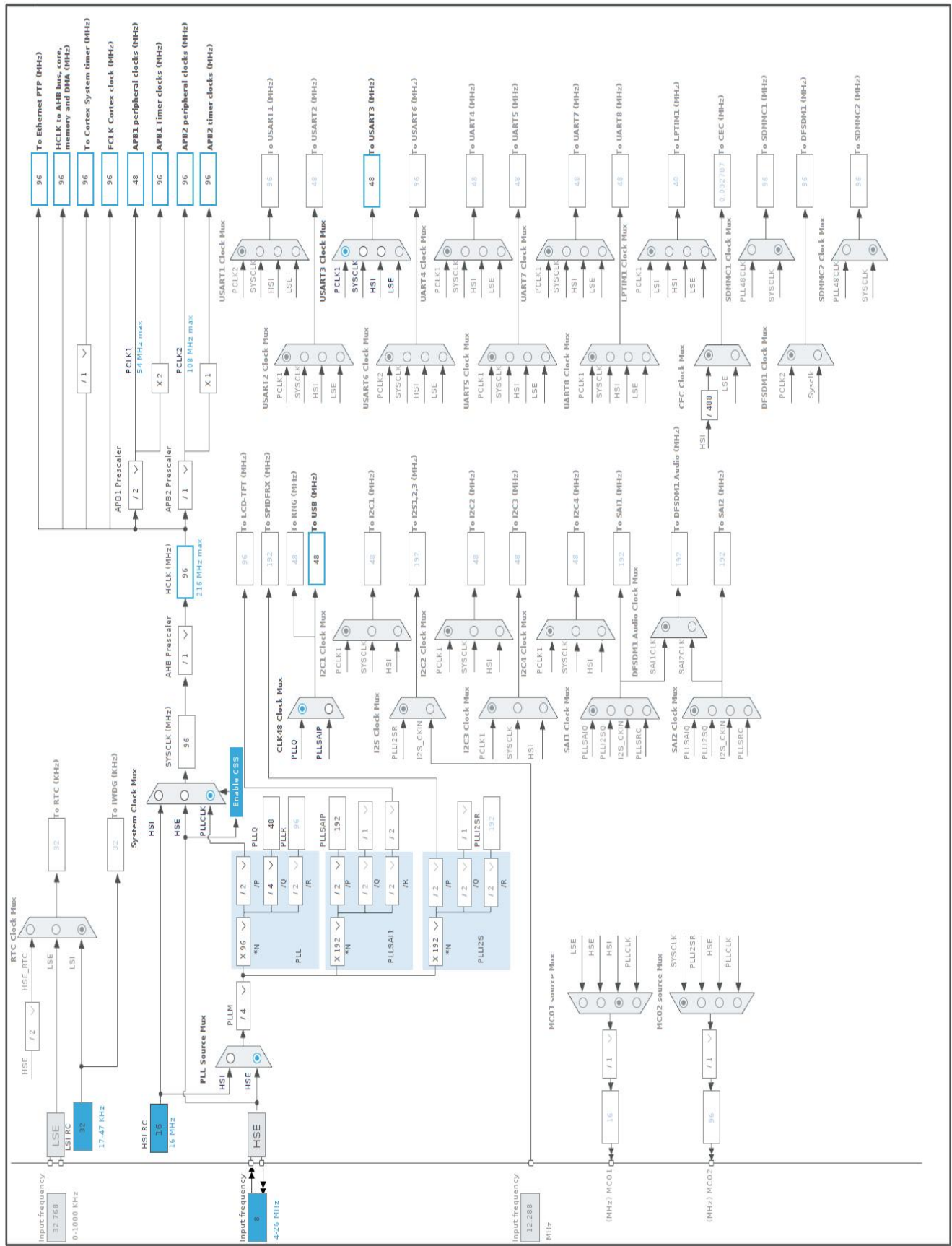
Pin Number LQFP144	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
78	PD9	I/O	USART3_RX	STLK_TX [STM32F103CBT6_PA2]
81	PD12	I/O	TIM4_CH1	MOTOR3_CHA
82	PD13	I/O	TIM4_CH2	MOTOR3_CHB
83	VSS	Power		
84	VDD	Power		
85	PD14 **	I/O	GPIO_Output	MOTOR5_INA
86	PD15 **	I/O	GPIO_Output	MOTOR5_INB
87	PG2 **	I/O	GPIO_Output	MOTOR6_INA
88	PG3 **	I/O	GPIO_Output	MOTOR6_INB
90	PG5 **	I/O	GPIO_Output	PIN_TOGGLE
91	PG6 **	I/O	GPIO_Output	MOTORS_EN
92	PG7 **	I/O	GPIO_Input	USB_OverCurrent [STMP52151STR_FAULT]
94	VSS	Power		
95	VDDUSB	Power		
96	PC6	I/O	TIM8_CH1	MOTOR5_CHA
97	PC7	I/O	TIM8_CH2	MOTOR5_CHB
100	PA8	I/O	USB_OTG_FS_SOF	USB_SOF [TP1]
101	PA9	I/O	USB_OTG_FS_VBUS	USB_VBUS
102	PA10 *	I/O	USB_OTG_FS_ID	USB_ID
103	PA11	I/O	USB_OTG_FS_DM	USB_DM
104	PA12	I/O	USB_OTG_FS_DP	USB_DP
105	PA13	I/O	SYS_JTMS-SWDIO	TMS
106	VCAP_2	Power		
107	VSS	Power		
108	VDD	Power		
109	PA14	I/O	SYS_JTCK-SWCLK	TCK
114	PD0 **	I/O	GPIO_Output	MOTOR1_INA
115	PD1 **	I/O	GPIO_Output	MOTOR1_INB
116	PD2 **	I/O	GPIO_Output	MOTOR2_INA
117	PD3 **	I/O	GPIO_Output	MOTOR2_INB
118	PD4 **	I/O	GPIO_Output	MOTOR3_INA
119	PD5 **	I/O	GPIO_Output	MOTOR3_INB
120	VSS	Power		
121	VDDSDMMC	Power		
122	PD6 **	I/O	GPIO_Output	MOTOR4_INA
123	PD7 **	I/O	GPIO_Output	MOTOR4_INB
124	PG9 **	I/O	GPIO_Output	MOTOR1_END
125	PG10 **	I/O	GPIO_Output	MOTOR2_END

Pin Number LQFP144	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
126	PG11 **	I/O	GPIO_Output	MOTOR3_END
127	PG12 **	I/O	GPIO_Output	MOTOR4_END
128	PG13 **	I/O	GPIO_Output	MOTOR5_END
129	PG14 **	I/O	GPIO_Output	MOTOR6_END
130	VSS	Power		
131	VDD	Power		
133	PB3	I/O	TIM2_CH2	MOTOR1_CHB
135	PB5	I/O	TIM3_CH2	MOTOR2_CHB
137	PB7 **	I/O	GPIO_Output	LD2 [Blue]
138	BOOT0	Boot		
143	PDR_ON	Reset		
144	VDD	Power		

** The pin is affected with an I/O function

* The pin is affected with a peripheral function but no peripheral mode is activated

4. Clock Tree Configuration



5. Software Project

5.1. Project Settings

Name	Value
Project Name	scorbot_controller
Project Folder	/home/persdg/Documents/universita/tesi/RACS/scorbot_controller
Toolchain / IDE	STM32CubeIDE
Firmware Package Name and Version	STM32Cube FW_F7 V1.17.1
Application Structure	Advanced
Generate Under Root	Yes
Do not generate the main()	No
Minimum Heap Size	0x200
Minimum Stack Size	0x400

5.2. Code Generation Settings

Name	Value
STM32Cube MCU packages and embedded software	Copy only the necessary library files
Generate peripheral initialization as a pair of '.c/.h' files	Yes
Backup previously generated files when re-generating	No
Keep User Code when re-generating	Yes
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power consumption)	No
Enable Full Assert	No

5.3. Advanced Settings - Generated Function Calls

Rank	Function Name	Peripheral Instance Name
1	SystemClock_Config	RCC
2	MX_GPIO_Init	GPIO
3	MX_DMA_Init	DMA
4	MX_USART3_UART_Init	USART3
5	MX_USB_OTG_FS_PCD_Init	USB_OTG_FS
6	MX_TIM1_Init	TIM1
7	MX_TIM2_Init	TIM2
8	MX_TIM3_Init	TIM3
9	MX_TIM4_Init	TIM4
10	MX_TIM5_Init	TIM5
11	MX_TIM8_Init	TIM8

Rank	Function Name	Peripheral Instance Name
12	MX_TIM9_Init	TIM9

1. Power Consumption Calculator report

1.1. Microcontroller Selection

Series	STM32F7
Line	STM32F7x7
MCU	STM32F767ZITx
Datasheet	DS11532_Rev4

1.2. Parameter Selection

Temperature	25
Vdd	3.3

1.3. Battery Selection

Battery	Alkaline(9V)
Capacity	625.0 mAh
Self Discharge	0.3 %/month
Nominal Voltage	9.0 V
Max Cont Current	200.0 mA
Max Pulse Current	0.0 mA
Cells in series	1
Cells in parallel	1

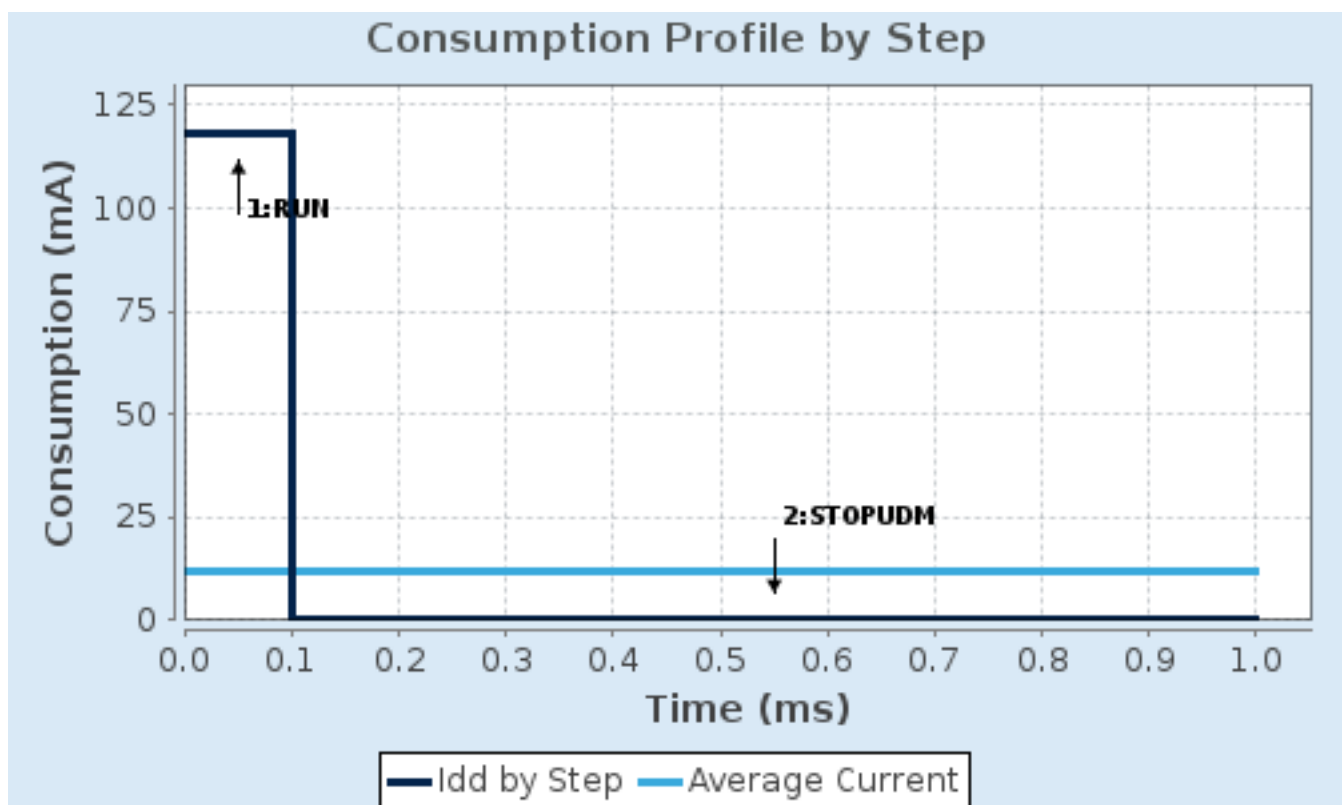
1.4. Sequence

Step	Step1	Step2
Mode	RUN	STOP UDM (Under Drive)
Vdd	3.3	3.3
Voltage Source	Battery	Battery
Range	Scale1-High	No Scale
Fetch Type	ICTM FLASH-SingleBank REGON	n/a
CPU Frequency	216 MHz	0 Hz
Clock Configuration	HSE PLL	Regulator LP Flash-PwrDwn
Clock Source Frequency	4 MHz	0 Hz
Peripherals		
Additional Cons.	0 mA	0 mA
Average Current	118 mA	130 μ A
Duration	0.1 ms	0.9 ms
DMIPS	462.0	0.0
Ta Max	89.42	104.98
Category	In DS Table	In DS Table

1.5. Results

Sequence Time	1 ms	Average Current	11.92 mA
Battery Life	2 days, 4 hours	Average DMIPS	462.24005 DMIPS

1.6. Chart



2. Peripherals and Middlewares Configuration

2.1. RCC

High Speed Clock (HSE): Crystal/Ceramic Resonator

2.1.1. Parameter Settings:

System Parameters:

VDD voltage (V)	3.3
Flash Latency(WS)	3 WS (4 CPU cycle)

RCC Parameters:

HSI Calibration Value	16
TIM Prescaler Selection	Disabled
HSE Startup Timeout Value (ms)	100
LSE Startup Timeout Value (ms)	5000

Power Parameters:

Power Over Drive	Enabled
Power Regulator Voltage Scale	Power Regulator Voltage Scale 3

2.2. SYS

Debug: Serial Wire

Timebase Source: TIM6

2.3. TIM1

Clock Source : Internal Clock

Channel1: PWM Generation CH1

Channel2: PWM Generation CH2

Channel3: PWM Generation CH3

Channel4: PWM Generation CH4

2.3.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	96-1 *
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	65535
Internal Clock Division (CKD)	No Division
Repetition Counter (RCR - 16 bits value)	0
auto-reload preload	Disable

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection TRGO	Reset (UG bit from TIMx_EGR)
Trigger Event Selection TRGO2	Reset (UG bit from TIMx_EGR)

Break And Dead Time management - BRK Configuration:

BRK State	Disable
BRK Polarity	High
BRK Filter (4 bits value)	0
BRK Sources Configuration	
- Digital Input	Disable
- DFSDM	Disable

Break And Dead Time management - BRK2 Configuration:

BRK2 State	Disable
BRK2 Polarity	High
BRK2 Filter (4 bits value)	0
BRK2 Sources Configuration	
- Digital Input	Disable
- DFSDM	Disable

Break And Dead Time management - Output Configuration:

Automatic Output State	Disable
Off State Selection for Run Mode (OSSR)	Disable
Off State Selection for Idle Mode (OSSI)	Disable
Lock Configuration	Off

PWM Generation Channel 1:

Mode	PWM mode 1
Pulse (16 bits value)	0
Output compare preload	Enable
Fast Mode	Disable
CH Polarity	High
CH Idle State	Reset

PWM Generation Channel 2:

Mode	PWM mode 1
Pulse (16 bits value)	0
Output compare preload	Enable
Fast Mode	Disable
CH Polarity	High
CH Idle State	Reset

PWM Generation Channel 3:

Mode	PWM mode 1
Pulse (16 bits value)	0
Output compare preload	Enable
Fast Mode	Disable

CH Polarity	High
CH Idle State	Reset

PWM Generation Channel 4:

Mode	PWM mode 1
Pulse (16 bits value)	0
Output compare preload	Enable
Fast Mode	Disable
CH Polarity	High
CH Idle State	Reset

2.4. TIM2

Combined Channels: Encoder Mode

2.4.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 32 bits value)	4294967295
Internal Clock Division (CKD)	No Division
auto-reload preload	Disable

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection TRGO	Reset (UG bit from TIMx_EGR)

Encoder:

Encoder Mode	Encoder Mode TI1
_____ Parameters for Channel 1 _____	

Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0

_____ Parameters for Channel 2 _____

Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0

2.5. TIM3

Combined Channels: Encoder Mode

2.5.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	65535
Internal Clock Division (CKD)	No Division
auto-reload preload	Disable

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection TRGO	Reset (UG bit from TIMx_EGR)

Encoder:

Encoder Mode	Encoder Mode TI1
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____ Parameters for Channel 1 ____

Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0

____ Parameters for Channel 2 ____

Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0

2.6. TIM4

Combined Channels: Encoder Mode

2.6.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	65535
Internal Clock Division (CKD)	No Division
auto-reload preload	Disable

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection TRGO	Reset (UG bit from TIMx_EGR)

Encoder:

Encoder Mode	Encoder Mode TI1
____ Parameters for Channel 1 ____	
Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0
____ Parameters for Channel 2 ____	
Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0

2.7. TIM5

Combined Channels: Encoder Mode

2.7.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 32 bits value)	4294967295
Internal Clock Division (CKD)	No Division
auto-reload preload	Disable

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection TRGO	Reset (UG bit from TIMx_EGR)

Encoder:

Encoder Mode	Encoder Mode TI1
____ Parameters for Channel 1 ____	
Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0
____ Parameters for Channel 2 ____	
Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0

2.8. TIM8

Combined Channels: Encoder Mode

2.8.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	65535
Internal Clock Division (CKD)	No Division
Repetition Counter (RCR - 16 bits value)	0
auto-reload preload	Disable

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection TRGO	Reset (UG bit from TIMx_EGR)
Trigger Event Selection TRGO2	Reset (UG bit from TIMx_EGR)

Encoder:

Encoder Mode	Encoder Mode T11
____ Parameters for Channel 1 ____	
Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0
____ Parameters for Channel 2 ____	
Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0

2.9. TIM9

Channel1: PWM Generation CH1

Channel2: PWM Generation CH2

2.9.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	65535
Internal Clock Division (CKD)	No Division
auto-reload preload	Disable

PWM Generation Channel 1:

Mode	PWM mode 1
Pulse (16 bits value)	0
Output compare preload	Enable
Fast Mode	Disable
CH Polarity	High

PWM Generation Channel 2:

Mode	PWM mode 1
Pulse (16 bits value)	0
Output compare preload	Enable
Fast Mode	Disable
CH Polarity	High

2.10. USART3

Mode: Asynchronous

2.10.1. Parameter Settings:

Basic Parameters:

Baud Rate	115200
Word Length	8 Bits (including Parity)
Parity	None
Stop Bits	1

Advanced Parameters:

Data Direction	Receive and Transmit
Over Sampling	16 Samples
Single Sample	Disable

Advanced Features:

Auto Baudrate	Disable
TX Pin Active Level Inversion	Disable
RX Pin Active Level Inversion	Disable
Data Inversion	Disable
TX and RX Pins Swapping	Disable
Overrun	Enable
DMA on RX Error	Enable
MSB First	Disable

2.11. USB_OTG_FS

Mode: Device_Only

mode: Activate_SOF

mode: Activate_VBUS

2.11.1. Parameter Settings:

Speed	Device Full Speed 12MBit/s
Low power	Disabled
Link Power Management	Disabled
VBUS sensing	Enabled
Signal start of frame	Enabled

2.12. FREERTOS

Interface: CMSIS_V2

2.12.1. Config parameters:

API:

FreeRTOS API	CMSIS v2
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Versions:

FreeRTOS version	10.2.1
CMSIS-RTOS version	2.00

MPU/FPU:

ENABLE_MPU	Disabled
ENABLE_FPU	Disabled

Kernel settings:

USE_PREEMPTION	Enabled
CPU_CLOCK_HZ	SystemCoreClock
TICK_RATE_HZ	1000
MAX_PRIORITIES	56
MINIMAL_STACK_SIZE	128
MAX_TASK_NAME_LEN	16
USE_16_BIT_TICKS	Disabled
IDLE_SHOULD_YIELD	Enabled
USE_MUTEXES	Enabled
USE_RECURSIVE_MUTEXES	Enabled
USE_COUNTING_SEMAPHORES	Enabled
QUEUE_REGISTRY_SIZE	8
USE_APPLICATION_TASK_TAG	Disabled
ENABLE_BACKWARD_COMPATIBILITY	Enabled
USE_PORT_OPTIMISED_TASK_SELECTION	Disabled

USE_TICKLESS_IDLE	Disabled
USE_TASK_NOTIFICATIONS	Enabled
RECORD_STACK_HIGH_ADDRESS	Disabled

Memory management settings:

Memory Allocation	Dynamic / Static
TOTAL_HEAP_SIZE	15360
Memory Management scheme	heap_4

Hook function related definitions:

USE_IDLE_HOOK	Disabled
USE_TICK_HOOK	Disabled
USE_MALLOC_FAILED_HOOK	Disabled
USE_DAEMON_TASK_STARTUP_HOOK	Disabled
CHECK_FOR_STACK_OVERFLOW	Disabled

Run time and task stats gathering related definitions:

GENERATE_RUN_TIME_STATS	Disabled
USE_TRACE_FACILITY	Enabled
USE_STATS_FORMATTING_FUNCTIONS	Disabled

Co-routine related definitions:

USE_CO_ROUTINES	Disabled
MAX_CO_ROUTINE_PRIORITIES	2

Software timer definitions:

USE_TIMERS	Enabled
TIMER_TASK_PRIORITY	2
TIMER_QUEUE_LENGTH	10
TIMER_TASK_STACK_DEPTH	256

Interrupt nesting behaviour configuration:

LIBRARY_LOWEST_INTERRUPT_PRIORITY	15
LIBRARY_MAX_SYSCALL_INTERRUPT_PRIORITY	5

Added with 10.2.1 support:

MESSAGE_BUFFER_LENGTH_TYPE	size_t
USE_POSIX_ERRNO	Disabled

2.12.2. Include parameters:

Include definitions:

vTaskPrioritySet	Enabled
uxTaskPriorityGet	Enabled
vTaskDelete	Enabled
vTaskCleanUpResources	Disabled
vTaskSuspend	Enabled
vTaskDelayUntil	Enabled

vTaskDelay	Enabled
xTaskGetSchedulerState	Enabled
xTaskResumeFromISR	Enabled
xQueueGetMutexHolder	Enabled
xSemaphoreGetMutexHolder	Disabled
pcTaskGetTaskName	Disabled
uxTaskGetStackHighWaterMark	Enabled
xTaskGetCurrentTaskHandle	Disabled
eTaskGetState	Enabled
xEventGroupSetBitFromISR	Disabled
xTimerPendFunctionCall	Enabled
xTaskAbortDelay	Disabled
xTaskGetHandle	Disabled
uxTaskGetStackHighWaterMark2	Disabled

2.12.3. Advanced settings:

Newlib settings (see parameter description first):

USE_NEWLIB_REENTRANT **Enabled ***

Project settings (see parameter description first):

Use FW pack heap file Enabled

*** User modified value**

3. System Configuration

3.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
RCC	PH0/OSC_IN	RCC_OSC_IN	n/a	n/a	n/a	MCO [STM32F103CBT6_PA8]
	PH1/OSC_OUT	RCC_OSC_OUT	n/a	n/a	n/a	
SYS	PA13	SYS_JTMS-SWDIO	n/a	n/a	n/a	TMS
	PA14	SYS_JTCK-SWCLK	n/a	n/a	n/a	TCK
TIM1	PE9	TIM1_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR1_PWM
	PE11	TIM1_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR2_PWM
	PE13	TIM1_CH3	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR3_PWM
	PE14	TIM1_CH4	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR4_PWM
TIM2	PA5	TIM2_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR1_CHA
	PB3	TIM2_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR1_CHB
TIM3	PA6	TIM3_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR2_CHA
	PB5	TIM3_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR2_CHB
TIM4	PD12	TIM4_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR3_CHA
	PD13	TIM4_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR3_CHB
TIM5	PA0/WKUP	TIM5_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR4_CHA
	PA1	TIM5_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR4_CHB
TIM8	PC6	TIM8_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR5_CHA
	PC7	TIM8_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR5_CHB
TIM9	PE5	TIM9_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR5_PWM
	PE6	TIM9_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR6_PWM
USART3	PD8	USART3_TX	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	STLK_RX [STM32F103CBT6_PA3]
	PD9	USART3_RX	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	STLK_TX [STM32F103CBT6_PA2]
USB_OTG_FS	PA8	USB_OTG_FS_SOF	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	USB_SOF [TP1]
	PA9	USB_OTG_FS_VBUS	Input mode	No pull-up and no pull-down	n/a	USB_VBUS
	PA11	USB_OTG_FS_DM	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	USB_DM
	PA12	USB_OTG_FS_DP	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	USB_DP

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
Single Mapped Signals	PC14/OSC32_IN	RCC_OSC32_IN	n/a	n/a	n/a	
	PC15/OSC32_OUT	RCC_OSC32_OUT	n/a	n/a	n/a	
	PA10	USB_OTG_FS_ID	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	USB_ID
GPIO	PC13	GPIO_EXTI13	External Interrupt Mode with Rising edge trigger detection	No pull-up and no pull-down	n/a	USER_Btn [B1]
	PB0	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LD1 [Green]
	PB14	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LD3 [Red]
	PD14	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR5_INA
	PD15	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR5_INB
	PG2	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR6_INA
	PG3	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR6_INB
	PG5	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	PIN_TOGGLE
	PG6	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTORS_EN
	PG7	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	USB_OverCurrent [STMPS2151STR_FAULT]
	PD0	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR1_INA
	PD1	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR1_INB
	PD2	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR2_INA
	PD3	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR2_INB
	PD4	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR3_INA
	PD5	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR3_INB
	PD6	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR4_INA
	PD7	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR4_INB
	PG9	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR1_END
	PG10	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR2_END
	PG11	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR3_END
	PG12	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR4_END
	PG13	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR5_END
	PG14	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR6_END
	PB7	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LD2 [Blue]

3.2. DMA configuration

DMA request	Stream	Direction	Priority
USART3_TX	DMA1_Stream3	Memory To Peripheral	Very High *
USART3_RX	DMA1_Stream1	Peripheral To Memory	Very High *

USART3_TX: DMA1_Stream3 DMA request Settings:

Mode: Normal
Use fifo: Disable
Peripheral Increment: Disable
Memory Increment: **Enable ***
Peripheral Data Width: Byte
Memory Data Width: Byte

USART3_RX: DMA1_Stream1 DMA request Settings:

Mode: **Circular ***
Use fifo: Disable
Peripheral Increment: Disable
Memory Increment: **Enable ***
Peripheral Data Width: Byte
Memory Data Width: Byte

3.3. NVIC configuration

3.3.1. NVIC

Interrupt Table	Enable	Preenmption Priority	SubPriority
Non maskable interrupt	true	0	0
Hard fault interrupt	true	0	0
Memory management fault	true	0	0
Pre-fetch fault, memory access fault	true	0	0
Undefined instruction or illegal state	true	0	0
System service call via SWI instruction	true	0	0
Debug monitor	true	0	0
Pendable request for system service	true	15	0
System tick timer	true	15	0
DMA1 stream1 global interrupt	true	5	0
DMA1 stream3 global interrupt	true	5	0
USART3 global interrupt	true	5	0
TIM6 global interrupt, DAC1 and DAC2 underrun error interrupts	true	15	0
PVD interrupt through EXTI line 16	unused		
Flash global interrupt	unused		
RCC global interrupt	unused		
TIM1 break interrupt and TIM9 global interrupt	unused		
TIM1 update interrupt and TIM10 global interrupt	unused		
TIM1 trigger and commutation interrupts and TIM11 global interrupt	unused		
TIM1 capture compare interrupt	unused		
TIM2 global interrupt	unused		
TIM3 global interrupt	unused		
TIM4 global interrupt	unused		
EXTI line[15:10] interrupts	unused		
TIM8 break interrupt and TIM12 global interrupt	unused		
TIM8 update interrupt and TIM13 global interrupt	unused		
TIM8 trigger and commutation interrupts and TIM14 global interrupt	unused		
TIM8 capture compare interrupt	unused		
TIM5 global interrupt	unused		
USB On The Go FS global interrupt	unused		
FPU global interrupt	unused		

3.3.2. NVIC Code generation

Enabled interrupt Table	Select for init sequence ordering	Generate IRQ handler	Call HAL handler
Non maskable interrupt	false	true	false
Hard fault interrupt	false	true	false
Memory management fault	false	true	false
Pre-fetch fault, memory access fault	false	true	false
Undefined instruction or illegal state	false	true	false
System service call via SWI instruction	false	false	false
Debug monitor	false	true	false
Pendable request for system service	false	false	false
System tick timer	false	false	true
DMA1 stream1 global interrupt	false	true	true
DMA1 stream3 global interrupt	false	true	true
USART3 global interrupt	false	true	true
TIM6 global interrupt, DAC1 and DAC2 underrun error interrupts	false	true	true

* User modified value

4. System Views

4.1. Category view

4.1.1. Current

Middleware						
FREERTOS						
System Core	Analog	Timers	Connectivity	Multimedia	Security	Computing
CORTEX_M7		TIM1	USART3			
DMA		TIM2	USB_FS			
GPIO		TIM3				
NVIC		TIM4				
RCC		TIM5				
SYS		TIM8				
		TIM9				

5. Docs & Resources

Type	Link
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