

ML Lab Report Week 14: CNN Image Classification

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SECTION :5C

1)Introduction

The objective of this lab was to design, implement, and train a Convolutional Neural Network (CNN) capable of classifying images of hand gestures into three categories: rock, paper, and scissors. Using the Rock–Paper–Scissors dataset, the task involved data preprocessing, model construction in PyTorch, training, testing, and evaluating real predictions. The lab provided hands-on experience with convolutional architectures, activation functions, pooling mechanisms, and end-to-end deep learning workflows for image classification.

2. Model Architecture

The CNN model developed in this lab is composed of three sequential convolutional blocks, each designed to extract increasingly complex spatial features from the input images.

Convolutional Block 1:

- Conv2d layer: $3 \rightarrow 16$ channels
- Kernel size: 3×3 , padding 1
- Activation: ReLU
- Downsampling: MaxPool2d (2×2)

Convolutional Block 2:

- Conv2d layer: $16 \rightarrow 32$ channels
- Kernel size: 3×3 , padding 1
- Activation: ReLU
- Downsampling: MaxPool2d (2×2)

Convolutional Block 3:

- Conv2d layer: $32 \rightarrow 64$ channels
- Kernel size: 3×3 , padding 1
- Activation: ReLU
- Downsampling: MaxPool2d (2×2)

Each MaxPooling layer reduces the spatial dimensions by half, transforming the original 128×128 input into 16×16 feature maps after three pooling operations. These features are then flattened and passed into a fully connected classifier, which includes:

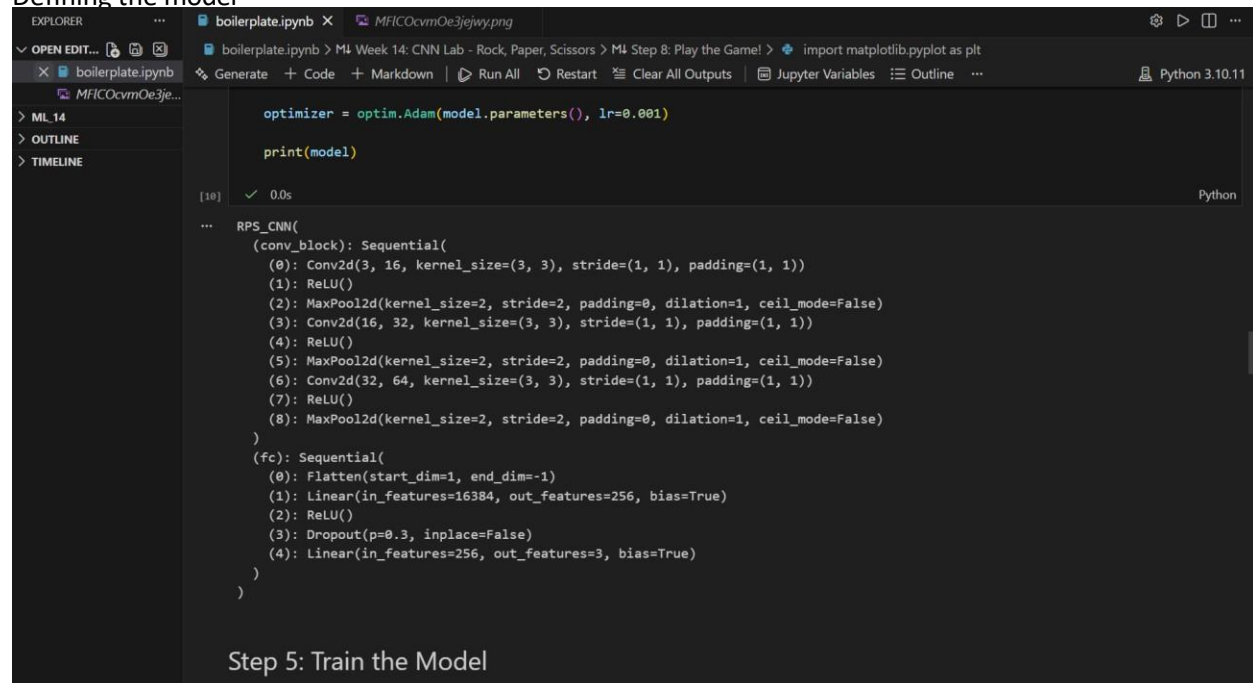
- A Linear layer mapping $64 \times 16 \times 16 \rightarrow 256$
- ReLU activation for non-linearity
- Dropout ($p = 0.3$) to reduce overfitting
- A final Linear layer mapping $256 \rightarrow 3$, producing logits for the three gesture classes. This architecture balances depth and computational efficiency, enabling effective feature extraction and robust classification performance for the Rock–Paper–Scissors dataset.

3. Training and Performance

The model was trained using the following hyperparameters:

- Optimizer: Adam
- Loss Function: CrossEntropyLoss
- Learning Rate: 0.001
- Epochs: 10
- Batch Size: 32

Defining the model



The screenshot shows a Jupyter Notebook with the following components:

- EXPLORER:** Lists files like `boilerplate.ipynb` and `MFICOcmOe3je...`.
- Code Editor:** Contains the following Python code:

```
optimizer = optim.Adam(model.parameters(), lr=0.001)

print(model)

[10] ✓ 0.0s Python

...
RPS_CNN(
  (conv_block): Sequential(
    (0): Conv2d(3, 16, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (1): ReLU()
    (2): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (3): Conv2d(16, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (4): ReLU()
    (5): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (6): Conv2d(32, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (7): ReLU()
    (8): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  )
  (fc): Sequential(
    (0): Flatten(start_dim=1, end_dim=-1)
    (1): Linear(in_features=16384, out_features=256, bias=True)
    (2): ReLU()
    (3): Dropout(p=0.3, inplace=False)
    (4): Linear(in_features=256, out_features=3, bias=True)
  )
)
```
- Output:** Shows the execution of the code, with a status bar indicating "Python 3.10.11".
- Footer:** A text label "Step 5: Train the Model" is visible at the bottom of the notebook interface.

Training the model:

```
boilerplate.ipynb > M4 Week 14: CNN Lab - Rock, Paper, Scissors > M4 Step 8: Play the Game! > import matplotlib.pyplot as plt
loss = criterion(outputs, labels)

# 4. Backward pass
loss.backward()

# 5. Update weights
optimizer.step()

total_loss += loss.item()

print(f"Epoch {epoch+1}/{EPOCHS}, Loss = {total_loss/len(train_loader):.4f}")

print("Training complete!")
```

[11] ✓ 4m 43.4s Python

... Epoch 1/10, Loss = 0.5903
Epoch 2/10, Loss = 0.1551
Epoch 3/10, Loss = 0.0703
Epoch 4/10, Loss = 0.0407
Epoch 5/10, Loss = 0.0178
Epoch 6/10, Loss = 0.0188
Epoch 7/10, Loss = 0.0138
Epoch 8/10, Loss = 0.0081
Epoch 9/10, Loss = 0.0075
Epoch 10/10, Loss = 0.0061
Training complete!

Evaluate the Model:

```
boilerplate.ipynb > M4 Week 14: CNN Lab - Rock, Paper, Scissors > M4 Step 8: Play the Game! > import matplotlib.pyplot as plt

Step 6: Evaluate the Model

Test the model's accuracy on the unseen test set.

model.eval() # Set the model to evaluation mode
correct = 0
total = 0

# TODO: Use torch.no_grad()
with torch.no_grad():
    for images, labels in test_loader:
        images, labels = images.to(device), labels.to(device)

        # 1. Get model outputs (logits)
        outputs = model(images)

        # 2. Get predicted class
        _, predicted = torch.max(outputs, 1)

        total += labels.size(0)
        correct += (predicted == labels).sum().item()

print(f"Test Accuracy: {100 * correct / total:.2f}%")
```

[12] ✓ 12.7s Python

... Test Accuracy: 97.26%

The dataset was split into 80% training and 20% testing. After training, the model achieved a final test accuracy of 97.26%, demonstrating strong generalization to unseen images.

Testing the model:

```
def predict_image(model, img_path):
    model.eval()

    img = Image.open(img_path).convert("RGB")
    img = transform(img).unsqueeze(0).to(device) # Apply transforms + batch dimension

    with torch.no_grad():
        # 1. Get raw model outputs (logits)
        output = model(img)

        # 2. Get predicted class index
        _, pred = torch.max(output, 1)

    return class_names[pred.item()]


# test the prediction function
test_img_path = "./dataset/paper/0Uomd0HvOB33m47I.png"
prediction = predict_image(model, test_img_path)
print(f"Model prediction for {test_img_path}: {prediction}")
```

[13] ✓ 0.0s

... Model prediction for [./dataset/paper/0Uomd0HvOB33m47I.png](#): paper

0Uomd0HvOB33m47I.png X

0Uomd0HvOB33m47I.png



Play the game:

```
# 3. Decide the winner
# -----

print("\nRESULT:", rps_winner(p1, p2))

[15] ✓ 0.0s

... Randomly selected images:
Image 1: ./dataset/scissors\uQLROCDZVtwVCXfm.png
Image 2: ./dataset/scissors\MF1COcvmOe3jejwy.png

Player 1 shows: scissors
Player 2 shows: scissors

RESULT: Draw

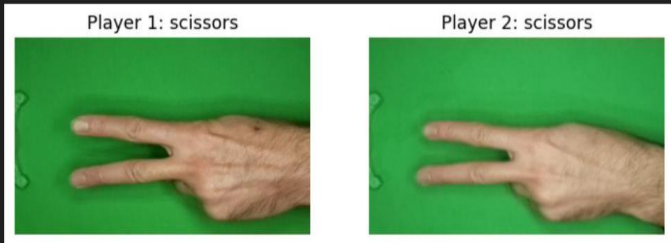
import matplotlib.pyplot as plt

# Display the two random images
plt.figure(figsize=(8, 4))

plt.axis('off')

plt.show()

[17] ✓ 0.1s
```



4. Conclusion and Analysis

The model performed extremely well, achieving 97.26% accuracy on the test set. The CNN successfully learned to distinguish among the three gesture classes, validating the effectiveness of the chosen architecture. Challenges included setting up the dataset paths correctly and ensuring consistent preprocessing. Future enhancements that could further improve performance include applying data augmentation techniques or expanding the network with additional layers or batch normalization to improve feature extraction and stability