

# The *kernel-natural stress formulation* constitutive laws

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## Abstract

This work presents a kernel transformation for the natural stress formulation. The stabilization procedure follows the idea of applying a generic kernel function [A.M. Afonso, F.T. Pinho, M.A. Alves, J. Non-Newtonian Fluid Mech., 167-168 (2012) 30-37] on the tensor equation of the natural stress formulation []

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## 1. Introduction

## 2. Governing equations

The dimensionless governing equations in the present work are the mass, momentum and the constitutive equations given, respectively, by

$$\begin{aligned} \nabla \cdot \mathbf{v} &= 0, & \frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} &= -\nabla p + \frac{\beta}{Re} \nabla^2 \mathbf{v} + \frac{1}{Re} \nabla \cdot \mathbf{T}^p, \\ \mathbf{T}^p + Wi \left( + \frac{\kappa}{1 - \beta} \mathbf{g}(\mathbf{T}^p) \right) &= 2(1 - \beta) \mathbf{D}, \end{aligned} \tag{1} \quad \boxed{\text{GovEq}}$$

with

$$\mathbf{g}(\mathbf{T}^p) = \begin{cases} \mathbf{0}, & \text{Oldroyd-B,} \\ \text{tr}(\mathbf{T}^p) \mathbf{T}^p, & \text{PTT,} \\ (\mathbf{T}^p)^2, & \text{Giesekus,} \end{cases} \tag{2}$$

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where  $\mathbf{v}$  is the fluid velocity,  $p$  is the pressure,  $\mathbf{T}^p$  is the elastic extra-stress. The dimensionless parameters are the Reynolds number  $Re$ , the Weissenberg number  $Wi = \lambda_p \frac{U}{L}$  (the dimensionless relaxation time) and retardation parameter  $\beta \in [0, 1]$ . The upper-convected stress derivative is defined as

$$= \frac{\partial \mathbf{T}^p}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{T}^p - (\nabla \mathbf{v}) \mathbf{T}^p - \mathbf{T}^p (\nabla \mathbf{v})^T. \quad (3)$$

An alternative stress formulation introduces the conformation tensor  $\mathbf{A}$  through the transformation

$$\mathbf{T}^p = \frac{1 - \beta}{Wi} (\mathbf{A} - \mathbf{I}), \quad (4)$$

so that the constitutive equation (1) becomes

$$Wi \mathbf{A} + (\mathbf{A} - \mathbf{I}) + \kappa \mathbf{g} (\mathbf{A} - \mathbf{I}) = \mathbf{0}. \quad (5)$$

The conformation tensor is a variance-covariance, symmetric positive definite tensor (SPD), and it may be decomposed using the natural stress basis as

$$\mathbf{A} = \lambda \mathbf{v} \mathbf{v}^T + \mu (\mathbf{v} \mathbf{w}^T + \mathbf{w} \mathbf{v}^T) + \nu \mathbf{w} \mathbf{w}^T, \quad (6)$$

where

$$\mathbf{v} = (u, v)^T, \quad \mathbf{w} = \frac{1}{|\mathbf{v}|^2} (-v, u)^T. \quad (7)$$

This is referred to as the natural stress formulation (NSF) and its components satisfy the following system of equation

$$\begin{aligned} \frac{D\lambda}{Dt} &= -\frac{2}{|\mathbf{v}|^2} \left[ \frac{\partial u}{\partial t} \left( \lambda u + \mu \frac{v}{|\mathbf{v}|^2} \right) + \frac{\partial v}{\partial t} \left( \lambda v - \mu \frac{u}{|\mathbf{v}|^2} \right) \right] - 2\mu \nabla \cdot \mathbf{w} + \frac{1}{Wi} \left( \frac{1}{|\mathbf{v}|^2} - \lambda \right) + \frac{\kappa}{Wi} g_\lambda \\ \frac{D\mu}{Dt} &= \frac{\partial u}{\partial t} \left( \lambda v - \nu \frac{v}{|\mathbf{v}|^4} \right) + \frac{\partial v}{\partial t} \left( -\lambda u + \nu \frac{u}{|\mathbf{v}|^4} \right) - \nu \nabla \cdot \mathbf{w} - \frac{\mu}{Wi} + \frac{\kappa}{Wi} g_\mu \\ \frac{D\nu}{Dt} &= 2 \left[ \frac{\partial u}{\partial t} \left( \mu v + \nu \frac{u}{|\mathbf{v}|^2} \right) + \frac{\partial v}{\partial t} \left( \nu \frac{v}{|\mathbf{v}|^2} - u \mu \right) \right] + \frac{1}{Wi} (|\mathbf{v}|^2 - \nu) + \frac{\kappa}{Wi} g_\nu, \end{aligned} \quad (8) \quad \boxed{\text{NSFeq}}$$

with

$$\begin{aligned} g_\lambda &= \begin{cases} 0, & \text{Oldroyd-B,} \\ \left( \lambda |\mathbf{v}|^2 - 2 + \frac{\nu}{|\mathbf{v}|^2} \right) \left( \frac{1}{|\mathbf{v}|^2} - \lambda \right), & \text{PTT,} \\ - \left( \frac{1}{|\mathbf{v}|^2} - \lambda \right)^2 |\mathbf{v}|^2 - \frac{\mu^2}{|\mathbf{v}|^2}, & \text{Giesekus,} \end{cases} & g_\mu &= \begin{cases} 0, & \text{Oldroyd-B,} \\ - \left( \lambda |\mathbf{v}|^2 - 2 + \frac{\nu}{|\mathbf{v}|^2} \right) \mu, & \text{PTT/Giesekus,} \end{cases} \\ g_\nu &= \begin{cases} 0, & \text{Oldroyd-B,} \\ \left( \lambda |\mathbf{v}|^2 - 2 + \frac{\nu}{|\mathbf{v}|^2} \right) (|\mathbf{v}|^2 - \nu), & \text{PTT,} \\ - (\nu - |\mathbf{v}|^2)^2 \frac{1}{|\mathbf{v}|^2} - \mu^2 |\mathbf{v}|^2, & \text{Giesekus} \end{cases} \end{aligned} \quad (9)$$

and

$$\nabla \cdot \mathbf{w} = \frac{1}{|\mathbf{v}|^4} \left[ (v^2 - u^2) \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) + 4uv \frac{\partial u}{\partial x} \right]. \quad (10)$$

Numerically, it is more interesting to work with the following format of Eq. (8)

$$\begin{aligned}
\frac{\partial \hat{\lambda}}{\partial t} &= -|\mathbf{v}|^2 (\mathbf{v} \cdot \nabla) \left( \frac{\hat{\lambda}}{|\mathbf{v}|^2} \right) + 2 \frac{\hat{\mu}}{|\mathbf{v}|^2} \left( u \frac{\partial v}{\partial t} - v \frac{\partial u}{\partial t} \right) - 2 \hat{\mu} |\mathbf{v}|^2 \nabla \cdot \mathbf{w} + \frac{1}{W_i} (1 - \hat{\lambda}) + \frac{\kappa}{W_i} g_{\hat{\lambda}}, \\
\frac{\partial \hat{\mu}}{\partial t} &= -(\mathbf{v} \cdot \nabla) \hat{\mu} + \frac{\hat{\nu} - \hat{\lambda}}{|\mathbf{v}|^2} \left( u \frac{\partial v}{\partial t} - v \frac{\partial u}{\partial t} \right) - \nu |\mathbf{v}|^2 \nabla \cdot \mathbf{w} - \frac{\hat{\mu}}{W_i} + \frac{\kappa}{W_i} g_{\hat{\mu}}, \\
\frac{\partial \hat{\nu}}{\partial t} &= -\frac{1}{|\mathbf{v}|^2} (\mathbf{v} \cdot \nabla) (\hat{\nu} |\mathbf{v}|^2) - 2 \frac{\hat{\mu}}{|\mathbf{v}|^2} \left( u \frac{\partial v}{\partial t} - v \frac{\partial u}{\partial t} \right) + \frac{1}{W_i} (1 - \hat{\nu}) + \frac{\kappa}{W_i} g_{\hat{\nu}},
\end{aligned} \tag{11}$$

or, in terms of the total derivative, as

$$\begin{aligned}
\frac{D \hat{\lambda}}{Dt} &= \frac{\hat{\lambda}}{|\mathbf{v}|^2} (\mathbf{v} \cdot \nabla) |\mathbf{v}|^2 + 2 \frac{\hat{\mu}}{|\mathbf{v}|^2} \left( u \frac{\partial v}{\partial t} - v \frac{\partial u}{\partial t} \right) - 2 \hat{\mu} |\mathbf{v}|^2 \nabla \cdot \mathbf{w} + \frac{1}{W_i} (1 - \hat{\lambda}) + \frac{\kappa}{W_i} g_{\hat{\lambda}}, \\
\frac{D \hat{\mu}}{Dt} &= \frac{\hat{\nu} - \hat{\lambda}}{|\mathbf{v}|^2} \left( u \frac{\partial v}{\partial t} - v \frac{\partial u}{\partial t} \right) - \nu |\mathbf{v}|^2 \nabla \cdot \mathbf{w} - \frac{\hat{\mu}}{W_i} + \frac{\kappa}{W_i} g_{\hat{\mu}}, \\
\frac{D \hat{\nu}}{Dt} &= -\frac{\hat{\nu}}{|\mathbf{v}|^2} (\mathbf{v} \cdot \nabla) |\mathbf{v}|^2 - 2 \frac{\hat{\mu}}{|\mathbf{v}|^2} \left( u \frac{\partial v}{\partial t} - v \frac{\partial u}{\partial t} \right) + \frac{1}{W_i} (1 - \hat{\nu}) + \frac{\kappa}{W_i} g_{\hat{\nu}},
\end{aligned} \tag{12}$$

NSFeqHat

where

$$\hat{\lambda} = \lambda |\lambda|^2, \quad \hat{\mu} = \mu, \quad \hat{\nu} = \frac{\nu}{|\mathbf{v}|^2}, \tag{13}$$

$$\begin{aligned}
g_{\hat{\lambda}} &= \begin{cases} 0, & \text{Oldroyd-B,} \\ (\hat{\lambda} - 2 + \hat{\nu}) (1 - \hat{\lambda}), & \text{PTT,} \\ - (1 - \hat{\lambda})^2 - \hat{\mu}^2, & \text{Giesekus,} \end{cases} & g_{\hat{\mu}} &= \begin{cases} 0, & \text{Oldroyd-B,} \\ - (\hat{\lambda} - 2 + \hat{\nu}) \hat{\mu}, & \text{PTT/Giesekus,} \end{cases} \\
g_{\hat{\nu}} &= \begin{cases} 0, & \text{Oldroyd-B,} \\ (\hat{\lambda} - 2 + \hat{\nu}) (1 - \hat{\nu}), & \text{PTT,} \\ - (1 - \hat{\nu})^2 - \hat{\mu}^2, & \text{Giesekus} \end{cases}
\end{aligned} \tag{14}$$

### 3. The kernel-natural stress formulation

Defining the tensors

$$\mathbf{S} = \begin{pmatrix} \hat{\lambda} & \hat{\mu} \\ \hat{\mu} & \hat{\nu} \end{pmatrix}, \quad \mathbf{R} = \frac{1}{|\mathbf{v}|} \begin{pmatrix} u & -v \\ v & u \end{pmatrix}, \tag{15}$$

then we have the following relations between the conformation tensor  $\mathbf{A}$  and the natural tensor  $\mathbf{S}$ :

$$\mathbf{A} = \mathbf{R} \mathbf{S} \mathbf{R}^T \Rightarrow \mathbf{S} = \mathbf{R}^T \mathbf{A} \mathbf{R}. \tag{16}$$

RelationA

The equation for the conformation tensor is giving by

$$\frac{D \mathbf{A}}{Dt} = \nabla \mathbf{v} \mathbf{A} + \mathbf{A} \nabla \mathbf{v}^T + \frac{1}{W_i} (\mathbf{I} - \mathbf{A}) + \frac{\kappa}{W_i} \mathbf{g}(\mathbf{A}), \tag{17}$$

where

$$\mathbf{g}(\mathbf{A}) = \begin{cases} 0, & \text{Oldroyd-B,} \\ \text{tr}(\mathbf{A} - \mathbf{I}) (\mathbf{I} - \mathbf{A}), & \text{PTT,} \\ (\mathbf{A} - \mathbf{I}) (\mathbf{I} - \mathbf{A}), & \text{Giesekus.} \end{cases} \tag{18}$$

Then, the equation for  $\mathbf{S}$  can be constructed by applying the total derivative in the relation (16), i.e.,

$$\frac{D\mathbf{S}}{Dt} = \frac{D\mathbf{R}^T}{Dt}\mathbf{A}\mathbf{R} + \mathbf{R}^T\frac{D\mathbf{A}}{Dt}\mathbf{R} + \mathbf{R}^T\mathbf{A}\frac{D\mathbf{R}}{Dt}, \quad (19)$$

which results in

$$\frac{D\mathbf{S}}{Dt} = \frac{D\mathbf{R}^T}{Dt}\mathbf{R}\mathbf{S} + \mathbf{R}^T\left[\nabla_{\mathbf{v}}\mathbf{A} + \mathbf{A}\nabla_{\mathbf{v}}^T + \frac{1}{Wi}(\mathbf{I} - \mathbf{A}) + \frac{\kappa}{Wi}\mathbf{g}(\mathbf{A})\right]\mathbf{R} + \mathbf{S}\mathbf{R}^T\frac{D\mathbf{R}}{Dt}, \quad (20)$$

and finally

$$\frac{D\mathbf{S}}{Dt} = (\mathbf{S}\mathbf{H} - \mathbf{H}\mathbf{S}) + \left(\bar{\nabla}_{\mathbf{v}}\mathbf{S} + \mathbf{S}\bar{\nabla}_{\mathbf{v}}^T\right) + \frac{1}{Wi}(\mathbf{I} - \mathbf{S}) + \frac{\kappa}{Wi}\mathbf{g}(\mathbf{S}), \quad (21) \quad \boxed{\text{MainEq}}$$

where

$$\mathbf{H} = \mathbf{R}^T\frac{D\mathbf{R}}{Dt}, \quad \bar{\nabla}_{\mathbf{v}} = \mathbf{R}^T\nabla_{\mathbf{v}}\mathbf{R}, \quad (22)$$

$$\mathbf{g}(\mathbf{S}) \begin{cases} 0, & \text{Oldroyd-B} \\ \text{tr}(\mathbf{S} - \mathbf{I})(\mathbf{I} - \mathbf{S}), & \text{PTT}, \\ (\mathbf{S} - \mathbf{I})(\mathbf{I} - \mathbf{S}), & \text{Giesekus.} \end{cases} \quad (23)$$

Eq. (21) can be written in 2D as

$$\begin{aligned} \frac{DS_{11}}{Dt} &= -2S_{12}H_{12} + 2\left(S_{11}\frac{\partial u}{\partial x} + S_{12}\frac{\partial u}{\partial y}\right) + \frac{1}{Wi}(1 - S_{11}) + \frac{\kappa}{Wi}g(\mathbf{S})_{11}, \\ \frac{DS_{12}}{Dt} &= H_{12}(S_{11} - S_{22}) + S_{11}\frac{\partial v}{\partial x} + S_{22}\frac{\partial u}{\partial y} + \frac{1}{Wi}(-S_{12}) + \frac{\kappa}{Wi}g(\mathbf{S})_{12}, \\ \frac{DS_{22}}{Dt} &= 2S_{12}H_{12} + 2\left(S_{12}\frac{\partial v}{\partial x} + S_{22}\frac{\partial v}{\partial y}\right) + \frac{1}{Wi}(1 - S_{22}) + \frac{\kappa}{Wi}g(\mathbf{S})_{22} \end{aligned} \quad (24) \quad \boxed{2DEq}$$

with

$$\begin{cases} \mathbf{H} = \frac{D\mathbf{R}}{Dt}\mathbf{R}^T = \begin{pmatrix} 0 & \frac{1}{|\mathbf{v}|^2}(v\frac{Du}{Dt} - u\frac{Dv}{Dt}) \\ -\frac{1}{|\mathbf{v}|^2}(v\frac{Du}{Dt} - u\frac{Dv}{Dt}) & 0 \end{pmatrix}, \\ \bar{\nabla}_{\mathbf{v}} = \mathbf{R}^T\nabla_{\mathbf{v}}\mathbf{R} = \frac{1}{|\mathbf{v}|^2} \begin{pmatrix} u^2\frac{\partial u}{\partial x} + uv\left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y}\right) + v^2\frac{\partial v}{\partial y} & u^2\frac{\partial u}{\partial y} + uv\left(\frac{\partial v}{\partial y} - \frac{\partial u}{\partial x}\right) - v^2\frac{\partial v}{\partial x} \\ u^2\frac{\partial v}{\partial x} + uv\left(\frac{\partial v}{\partial y} - \frac{\partial u}{\partial x}\right) - v^2\frac{\partial u}{\partial y} & v^2\frac{\partial v}{\partial x} - uv\left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y}\right) + u^2\frac{\partial v}{\partial y} \end{pmatrix}. \end{cases} \quad (25)$$

$$\begin{aligned} g(\mathbf{S})_{11} &= \begin{cases} 0, & \text{Oldroyd-B}, \\ (S_{11} + S_{22} - 2)(1 - S_{11}), & \text{PTT}, \\ -(1 - 2S_{11} + S_{11}^2 + S_{12}^2), & \text{Giesekus}, \end{cases} & g(\mathbf{S})_{12} &= \begin{cases} 0, & \text{Oldroyd-B}, \\ -S_{12}(S_{11} + S_{22} - 2), & \text{PTT/Giesekus}, \end{cases} \\ g(\mathbf{S})_{22} &= \begin{cases} 0, & \text{Oldroyd-B}, \\ (S_{11} + S_{22} - 2)(1 - S_{22}), & \text{PTT}, \\ -(1 - 2S_{22} + S_{22}^2 + S_{12}^2), & \text{Giesekus}. \end{cases} \end{aligned} \quad (26)$$

Note that,  $\mathbf{H}$  can also be written as

$$\mathbf{H} = \begin{pmatrix} R_{11} \frac{DR_{11}}{Dt} + R_{21} \frac{DR_{21}}{Dt} & R_{11} \frac{DR_{12}}{Dt} + R_{21} \frac{DR_{22}}{Dt} \\ R_{12} \frac{DR_{11}}{Dt} + R_{22} \frac{DR_{21}}{Dt} & R_{12} \frac{DR_{12}}{Dt} + R_{22} \frac{DR_{22}}{Dt} \end{pmatrix} \quad (27)$$

where

$$\begin{cases} R_{11} \frac{DR_{11}}{Dt} = \frac{uv}{|\mathbf{v}|^4} \left( v \frac{Du}{Dt} - u \frac{Dv}{Dt} \right), \\ R_{21} \frac{DR_{21}}{Dt} = -\frac{uv}{|\mathbf{v}|^4} \left( v \frac{Du}{Dt} - u \frac{Dv}{Dt} \right), \\ R_{11} \frac{DR_{12}}{Dt} = \frac{u^2}{|\mathbf{v}|^4} \left( v \frac{Du}{Dt} - u \frac{Dv}{Dt} \right), \\ R_{21} \frac{DR_{22}}{Dt} = \frac{v^2}{|\mathbf{v}|^4} \left( v \frac{Du}{Dt} - u \frac{Dv}{Dt} \right), \end{cases} \quad (28)$$

Observe in Eq. (24) that

$$\begin{cases} -(\mathbf{v} \cdot \nabla) S_{11} + 2S_{11} \frac{\partial \bar{u}}{\partial x} = -|\mathbf{v}|^2 (\mathbf{v} \cdot \nabla) \left( \frac{\hat{\lambda}}{|\mathbf{v}|^2} \right) = -(\mathbf{v} \cdot \nabla) \hat{\lambda} + \frac{\hat{\lambda}}{|\mathbf{v}|^2} (\mathbf{v} \cdot \nabla) |\mathbf{v}|^2, \\ -2S_{12} H_{12} + 2S_{12} \frac{\partial \bar{u}}{\partial y} = \frac{2\hat{\mu}}{|\mathbf{v}|^2} \left( u \frac{\partial v}{\partial t} - v \frac{\partial u}{\partial t} \right) - 2\hat{\mu} |\mathbf{v}|^2 \nabla \cdot \mathbf{w}, \\ -(\mathbf{v} \cdot \nabla) S_{22} + 2S_{22} \frac{\partial \bar{v}}{\partial y} = -\frac{1}{|\mathbf{v}|^2} (\mathbf{v} \cdot \nabla) (\hat{\nu} |\mathbf{v}|^2) = -(\mathbf{v} \cdot \nabla) \hat{\nu} - \frac{\hat{\nu}}{|\mathbf{v}|^2} (\mathbf{v} \cdot \nabla) |\mathbf{v}|^2, \\ 2S_{12} H_{12} + 2S_{12} \frac{\partial \bar{v}}{\partial x} = -\frac{2\hat{\mu}}{|\mathbf{v}|} \left( u \frac{\partial v}{\partial t} - v \frac{\partial u}{\partial t} \right). \end{cases} \quad (29)$$

Following the work of Fattal and Kupferman [[<empty citation>](#)] (see also Afonso et al. [[<empty citation>](#)]), the matrix  $\mathbf{M}$  can be decomposed as

$$\bar{\nabla} \mathbf{v} = \mathbf{M} = \mathbf{\Omega} + \mathbf{B} + \mathbf{N} \mathbf{S}^{-1} \quad (30) \quad \boxed{\text{FattalDec}}$$

where  $\mathbf{\Omega}, \mathbf{N}$  are anti-symmetric, and  $\mathbf{B}$  is symmetric and commutes with  $\mathbf{S}$ .

Substituting Eq. (30) in (21) results

$$\frac{D\mathbf{S}}{Dt} = (\mathbf{S}\mathbf{H} - \mathbf{H}\mathbf{S}) + (\mathbf{\Omega}\mathbf{S} - \mathbf{S}\mathbf{\Omega}) + 2\mathbf{B}\mathbf{S} + \frac{1}{W_i} (\mathbf{I} - \mathbf{S}) + \frac{\kappa}{W_i} \mathbf{g}(\mathbf{S}). \quad (31)$$

The eigendecomposition of  $\mathbf{S}$  is

$$\mathbf{S} = \mathbf{O} \mathbf{\Lambda} \mathbf{O}^T \Rightarrow \mathbf{\Lambda} = \mathbf{O}^T \mathbf{S} \mathbf{O}, \quad (32) \quad \boxed{\text{EigenS}}$$

applying the material derivative results

$$\frac{D\mathbf{\Lambda}}{Dt} = \left( \frac{D\mathbf{O}^T}{Dt} \mathbf{O} \right) \mathbf{\Lambda} + \mathbf{\Lambda} \left( \mathbf{O}^T \frac{D\mathbf{O}}{Dt} \right) + \mathbf{O}^T \frac{D\mathbf{S}}{Dt} \mathbf{O} \quad (33) \quad \boxed{\text{Lambda1}}$$

Defining the matrix  $\mathbf{V}$  as

$$\mathbf{V} = \mathbf{O}^T \frac{D\mathbf{O}}{Dt}, \quad (34)$$

we note that  $\mathbf{V}^T = -\mathbf{V}$ , i.e.,  $\mathbf{V}$  is an anti symmetric matrix. In fact,

$$\mathbf{0} = \frac{D(\mathbf{O}\mathbf{O}^T)}{Dt} = \frac{D\mathbf{O}}{Dt}\mathbf{O}^T + \mathbf{O}\frac{D\mathbf{O}^T}{Dt} \Rightarrow \frac{D\mathbf{O}}{Dt}\mathbf{O}^T = -\mathbf{O}\frac{D\mathbf{O}^T}{Dt}, \quad (35)$$

which results in

$$\mathbf{V}^T = -\mathbf{V}. \quad (36)$$

Then, equation (33) becomes

$$\frac{D\mathbf{\Lambda}}{Dt} = (\mathbf{\Lambda}\mathbf{V} - \mathbf{V}\mathbf{\Lambda}) + \mathbf{O}^T \frac{D\mathbf{S}}{Dt} \mathbf{O}. \quad (37) \quad \boxed{\text{EqInter}}$$

Substituting equation (??) in to equation (37), results

$$\frac{D\mathbf{\Lambda}}{Dt} = (\mathbf{\Lambda}\mathbf{V} - \mathbf{V}\mathbf{\Lambda}) + (\mathbf{\Lambda}\tilde{\mathbf{H}} - \tilde{\mathbf{H}}\mathbf{\Lambda}) + (\tilde{\mathbf{\Omega}}\mathbf{\Lambda} - \mathbf{\Lambda}\tilde{\mathbf{\Omega}}) + 2\tilde{\mathbf{B}}\mathbf{\Lambda} + \frac{1}{W_i}(\mathbf{I} - \mathbf{\Lambda}) + \frac{\kappa}{W_i}\mathbf{g}(\mathbf{\Lambda}), \quad (38) \quad \boxed{\text{Inter}}$$

where

$$\mathbf{g}(\mathbf{\Lambda}) = \begin{cases} \mathbf{0}, & \text{Oldroyd-B,} \\ \text{tr}(\mathbf{\Lambda} - \mathbf{I})(\mathbf{I} - \mathbf{\Lambda}), & \text{PTT,} \\ (\mathbf{\Lambda} - \mathbf{I})(\mathbf{I} - \mathbf{\Lambda}), & \text{Giesekus,} \end{cases} \quad (39)$$

Considering in Eq. (38)  $\mathbf{W} = \mathbf{V} + \tilde{\mathbf{H}}$  results in

$$\frac{D\mathbf{\Lambda}}{Dt} = (\mathbf{\Lambda}\mathbf{W} - \mathbf{W}\mathbf{\Lambda}) + (\tilde{\mathbf{\Omega}}\mathbf{\Lambda} - \mathbf{\Lambda}\tilde{\mathbf{\Omega}}) + 2\tilde{\mathbf{B}}\mathbf{\Lambda} + \frac{1}{W_i}(\mathbf{I} - \mathbf{\Lambda}) + \frac{\kappa}{W_i}\mathbf{g}(\mathbf{\Lambda}), \quad (40)$$

which we get

$$\begin{cases} W_{12} = V_{12} + \tilde{H}_{12} = \tilde{\Omega}_{12} \Rightarrow V_{12} = \tilde{\Omega}_{12} - \tilde{H}_{12}, \\ \frac{D\Lambda_{ii}}{Dt} = 2\tilde{B}_{ii}\Lambda_{ii} + \frac{1}{W_i}(1 - \Lambda_{ii}) + \frac{\kappa}{W_i}g(\mathbf{\Lambda})_{ii}, \quad i = 1, 2. \end{cases} \quad (41)$$

Note that,

$$\frac{D\mathbb{K}(\mathbf{\Lambda})}{Dt} = \frac{D\mathbf{\Lambda}}{Dt} \frac{\partial \mathbb{K}(\mathbf{\Lambda})}{\partial \mathbf{\Lambda}} = \frac{D\mathbf{\Lambda}}{Dt} \mathbf{J} \quad (42)$$

where

$$\mathbf{J} = \frac{\partial \mathbb{K}(\mathbf{\Lambda})}{\partial \mathbf{\Lambda}} = \begin{pmatrix} \frac{\partial \mathbb{K}(\Lambda_{11})}{\partial \Lambda_{11}} & 0 \\ 0 & \frac{\partial \mathbb{K}(\Lambda_{22})}{\partial \Lambda_{22}} \end{pmatrix}. \quad (43)$$

Then,

$$\frac{D\mathbb{K}(\mathbf{\Lambda})}{Dt} = \left[ 2\tilde{\mathbf{B}}\mathbf{\Lambda} + \frac{1}{W_i}(\mathbf{I} - \mathbf{\Lambda}) + \frac{\kappa}{W_i}\mathbf{g}(\mathbf{\Lambda}) \right] \mathbf{J}. \quad (44)$$

Applying a kernel transformation in Eq. (32), i.e.,

$$\begin{aligned}\mathbb{K}(\mathbf{S}) &= \mathbf{O}\mathbb{K}(\mathbf{\Lambda})\mathbf{O}^T \Rightarrow \\ &\Rightarrow \frac{D\mathbb{K}(\mathbf{S})}{Dt} = \mathbf{V}\mathbb{K}(\mathbf{S}) - \mathbb{K}(\mathbf{S})\mathbf{V} + \mathbf{O}\frac{D\mathbb{K}(\mathbf{\Lambda})}{Dt}\mathbf{O}^T.\end{aligned}\quad (45)$$

Finally, the Kernel-NSF equation is given by

$$\frac{D\mathbb{K}(\mathbf{S})}{Dt} = \mathbf{V}\mathbb{K}(\mathbf{S}) - \mathbb{K}(\mathbf{S})\mathbf{V} + \left[ 2\mathbf{B}\mathbf{S} + \frac{1}{Wi}(\mathbf{I} - \mathbf{S}) + \frac{\kappa}{Wi}\mathbf{g}(\mathbf{S}) \right] \tilde{\mathbf{J}}, \quad (46) \quad \boxed{\text{KernelEq}}$$

where

$$\tilde{\mathbf{J}} = \mathbf{O}\mathbf{J}\mathbf{O}^T. \quad (47)$$

$$\begin{aligned}\left( \begin{array}{cc} \frac{D\mathbb{K}(\mathbf{S})_{11}}{Dt} & \frac{D\mathbb{K}(\mathbf{S})_{12}}{Dt} \\ \frac{D\mathbb{K}(\mathbf{S})_{12}}{Dt} & \frac{D\mathbb{K}(\mathbf{S})_{22}}{Dt} \end{array} \right) &= \left( \begin{array}{cc} 2V_{12}\mathbb{K}(\mathbf{S})_{12} & V_{12}(\mathbb{K}(\mathbf{S})_{22} - \mathbb{K}(\mathbf{S})_{11}) \\ V_{12}(\mathbb{K}(\mathbf{S})_{22} - \mathbb{K}(\mathbf{S})_{11}) & -2V_{12}\mathbb{K}(\mathbf{S})_{12} \end{array} \right) + \\ &\left( \begin{array}{cc} 2(B_{11}S_{11} + B_{12}S_{12}) + \frac{1}{Wi}(1 - S_{11}) + \frac{\kappa}{Wi}g(\mathbf{S})_{11} & 2(B_{11}S_{12} + B_{12}S_{22}) + \frac{1}{Wi}(-S_{12}) + \frac{\kappa}{Wi}g(\mathbf{S})_{12} \\ 2(B_{12}S_{11} + B_{22}S_{12}) + \frac{1}{Wi}(-S_{12}) + \frac{\kappa}{Wi}g(\mathbf{S})_{12} & 2(B_{12}S_{12} + B_{22}S_{22}) + \frac{1}{Wi}(1 - S_{22}) + \frac{\kappa}{Wi}g(\mathbf{S})_{22} \end{array} \right) \begin{pmatrix} \tilde{J}_{11} & \tilde{J}_{12} \\ \tilde{J}_{12} & \tilde{J}_{22} \end{pmatrix} \end{aligned} \quad (48)$$

where

$$\tilde{\mathbf{J}} = \begin{pmatrix} O_{11}^2 J_{11} + O_{12}^2 J_{12} & O_{11}O_{21}J_{11} + O_{12}O_{22}J_{22} \\ O_{11}O_{21}J_{11} + O_{12}O_{22}J_{22} & O_{22}^2 J_{22} + O_{21}^2 J_{11} \end{pmatrix} \quad (49)$$

#### 4. Numerical method

#### 5. Numerical results

The meshes used in the numerical simulations are described in Table 1.

Mesh	Space-step	Number of cells
$M_1$	$\delta x_{min} = \delta y_{min} = 0.008$	$400 \times 380$
$M_2$	$\delta x_{min} = \delta y_{min} = 0.004$	

**Meshes**

Table 1: Details of the meshes.

##### 5.1. Verification of the asymptotic results

##### 5.2. Numerical verification: Corner vortex, vortex intensity and Couette correction

In Table ?? we present the Corner vortex, vortex intensity and Couette correction for several kernel functions with  $Wi = 1$ .

##### 5.3. Study of the positivity of the conformation tensor

##### 5.4. Numerical analysis of the kernel functions

#### 6. Conclusions

Method	$X_R$	$\Psi_R$	$C$
$\mathbf{T}^p$	1.496845	1.165636	0.335247
$\sqrt{\mathbf{A}}$	—	—	—
$\ln \mathbf{A}$	—	—	—
$\mathbf{N}$	1.496845	1.391620	0.335991
$\sqrt{\mathbf{N}}$	—	—	—
$\ln \mathbf{N}$	—	—	—

XrWi01

Table 2: Vortex size  $X_R$ , vortex intensity  $\Psi_R$  and Couette correction  $C$  using  $Wi = 0.1$ .

Method	$X_R$	$\Psi_R$	$C$
$\mathbf{T}^p$	1.496845	1.151294	0.291796
$\sqrt{\mathbf{A}}$	—	—	—
$\ln \mathbf{A}$	—	—	—
$\mathbf{N}$	1.496845	1.372660	0.290968
$\sqrt{\mathbf{N}}$	—	—	—
$\ln \mathbf{N}$	—	—	—

XrWi02

Table 3: Vortex size  $X_R$ , vortex intensity  $\Psi_R$  and Couette correction  $C$  using  $Wi = 0.2$ .

Method	$X_R$	$\Psi_R$	$C$
$\mathbf{T}^p$	1.496845	1.136462	0.245351
$\sqrt{\mathbf{A}}$	—	—	—
$\ln \mathbf{A}$	—	—	—
$\mathbf{N}$	1.496845	1.351782	0.243935
$\sqrt{\mathbf{N}}$	—	—	—
$\ln \mathbf{N}$	—	—	—

XrWi03

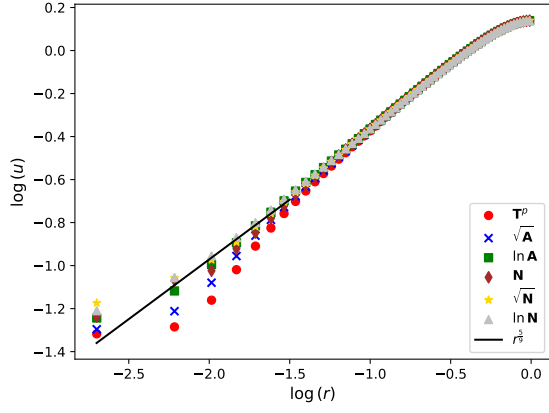
Table 4: Vortex size  $X_R$ , vortex intensity  $\Psi_R$  and Couette correction  $C$  using  $Wi = 0.3$ .

Method	$X_R$	$\Psi_R$	$C$
$\mathbf{T}^p$	1.496845	1.122511	0.197289
$\sqrt{\mathbf{A}}$	—	—	—
$\ln \mathbf{A}$	—	—	—
$\mathbf{N}$	1.496845	1.331674	0.195152
$\sqrt{\mathbf{N}}$	—	—	—
$\ln \mathbf{N}$	—	—	—

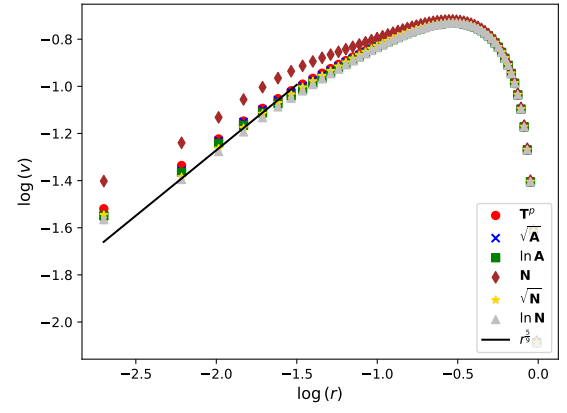
XrWi04

Table 5: Vortex size  $X_R$ , vortex intensity  $\Psi_R$  and Couette correction  $C$  using  $Wi = 0.4$ .

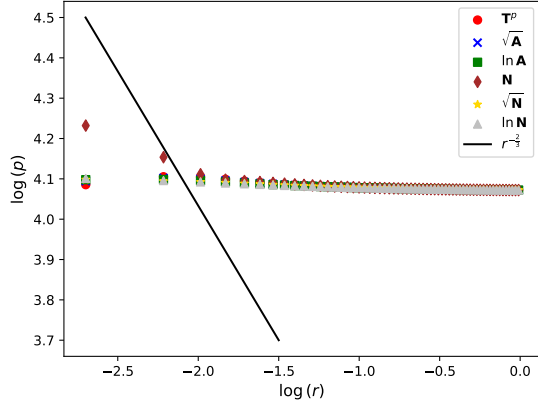




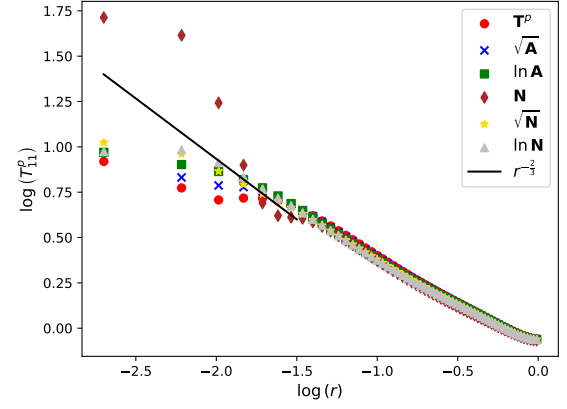
(a)



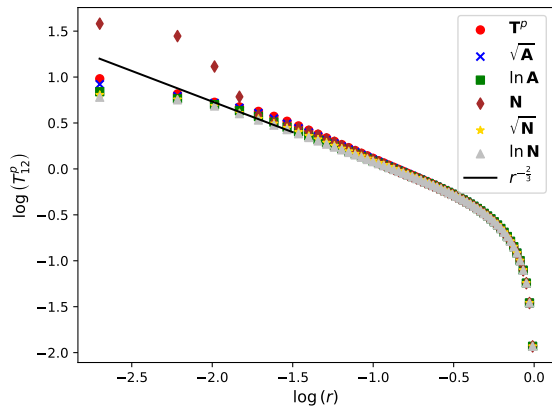
(b)



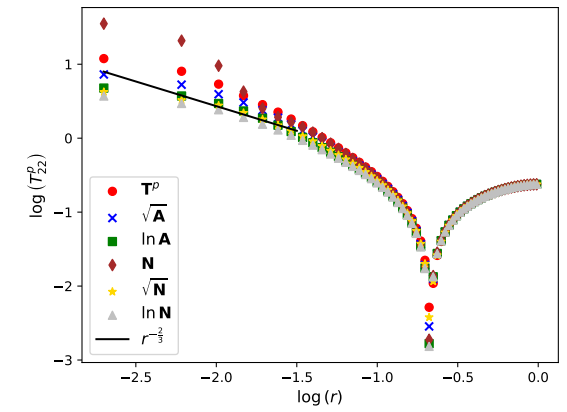
(c)



(d)



(e)



(f)

Figure 1: Numerical verification of the asymptotic behavior of the velocity components  $u$ ,  $v$ , pressure  $p$  and the components of the extra-stress tensor  $\mathbf{T}^p$  with  $Wi = 1$  for the 4:1 contraction flow.

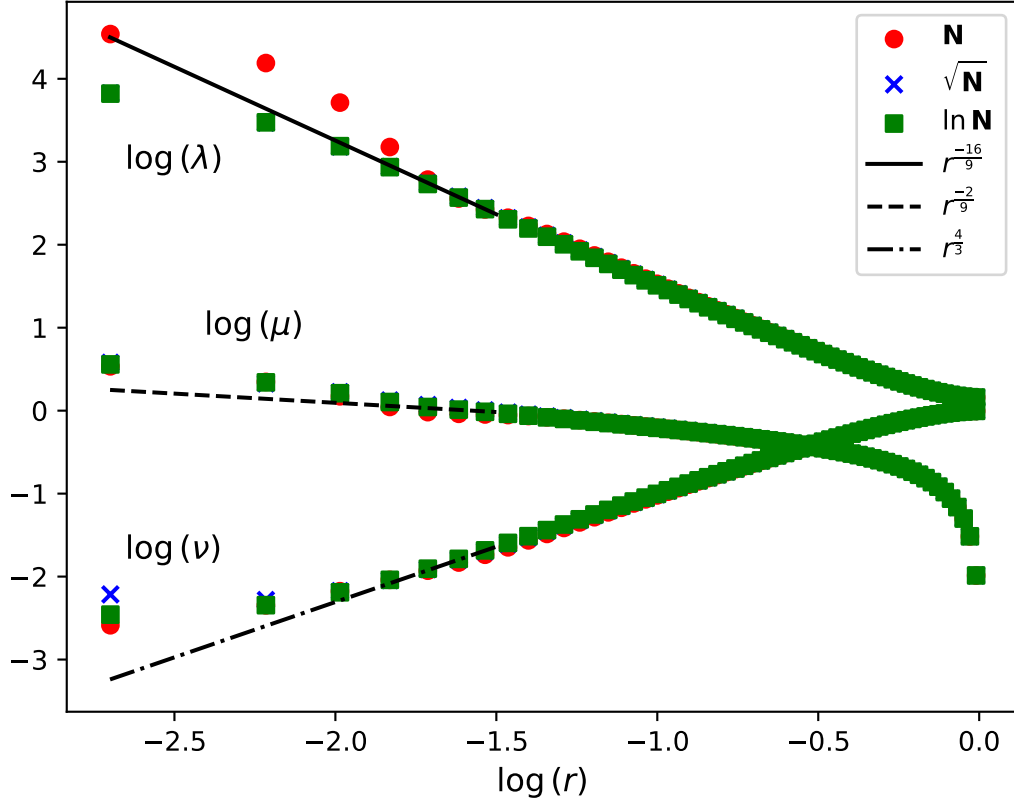


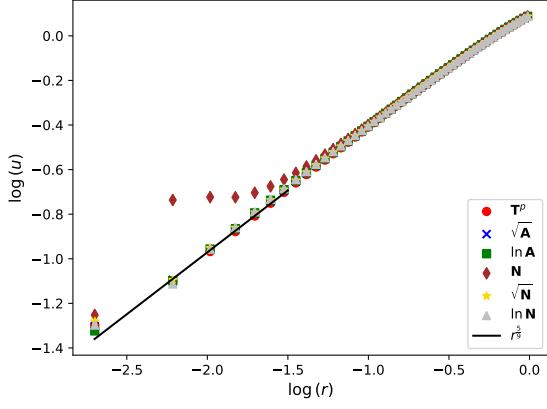
Figure 2: Numerical verification of the asymptotic behavior of the natural stress components  $\lambda$ ,  $\mu$  and  $\nu$  with  $Wi = 1$  for the 4:1 contraction flow.

NumVer

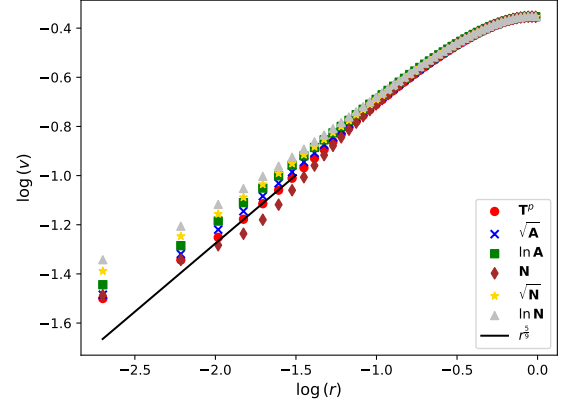
Method	$X_R$	$\Psi_R$	$C$
$\mathbf{T}^p$	1.451163	1.108696	0.147367
$\sqrt{\mathbf{A}}$	—	—	—
$\ln \mathbf{A}$	—	—	—
$\mathbf{N}$	—	—	—
$\sqrt{\mathbf{N}}$	1.496845	1.311177	0.145068
$\ln \mathbf{N}$	—	—	—

Table 6: Vortex size  $X_R$ , vortex intensity  $\Psi_R$  and Couette correction  $C$  using  $Wi = 0.5$ .

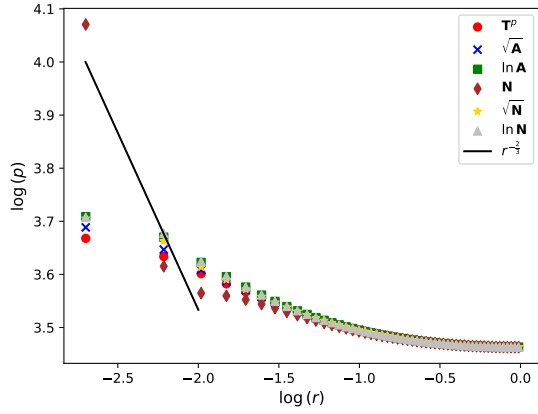
XrWi05



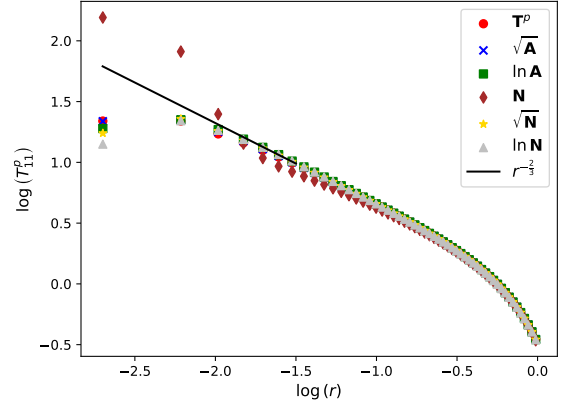
(a)



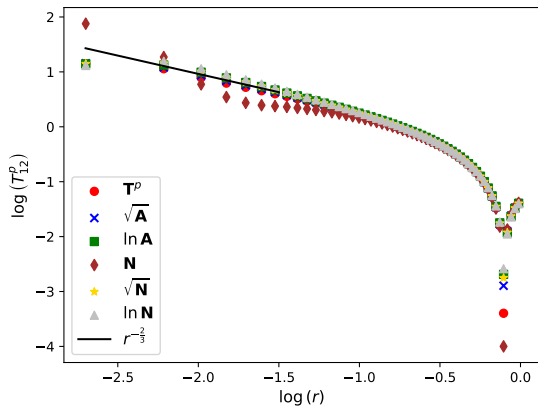
(b)



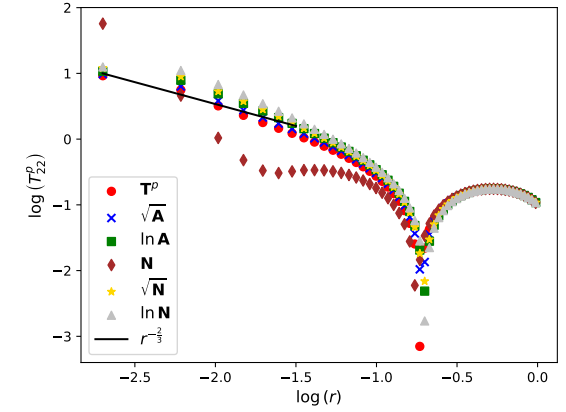
(c)



(d)



(e)



(f)

Figure 3: Numerical verification of the asymptotic behavior of the velocity components  $u$ ,  $v$ , pressure  $p$  and the components of the extra-stress tensor  $\mathbf{T}^p$  with  $Wi = 1$  for the L-shaped flow.

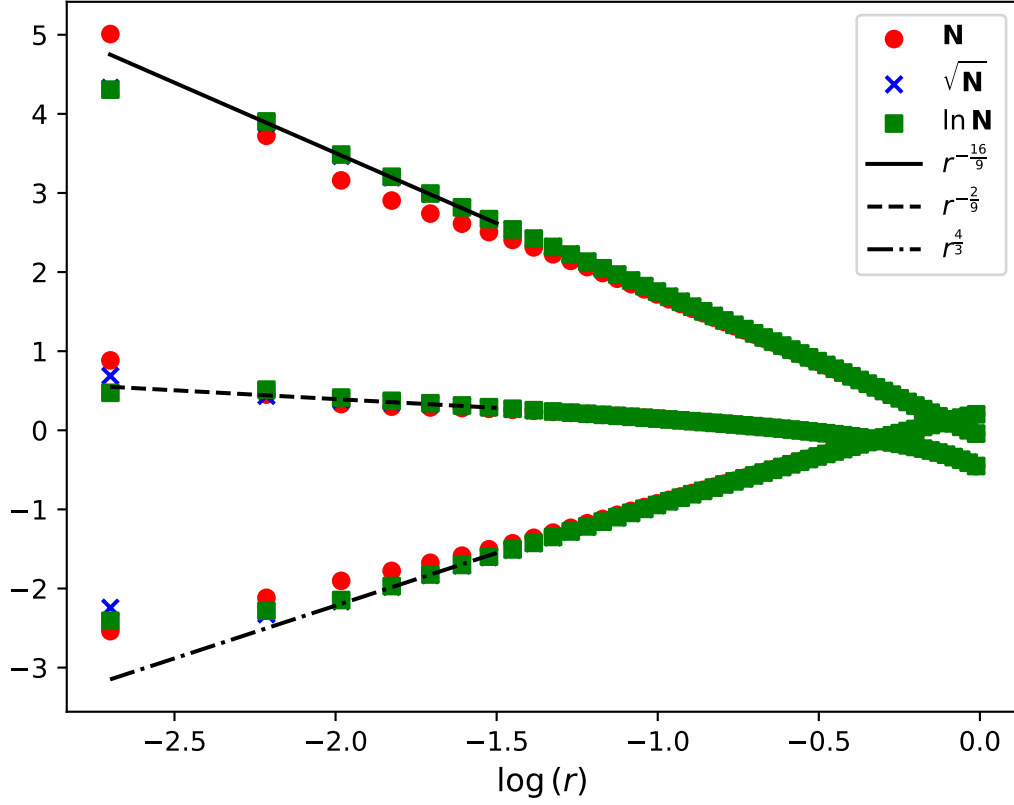


Figure 4: Numerical verification of the asymptotic behavior of the natural stress components  $\lambda$ ,  $\mu$  and  $\nu$  with  $Wi = 1$  for the L-shaped flow.

NumVer4

Method	$X_R$	$\Psi_R$	$C$
$\mathbf{T}^p$	1.451163	1.043963	-0.110588
$\sqrt{\mathbf{A}}$	1.451163	1.044549	-0.113106
$\ln \mathbf{A}$	1.451163	1.045088	-0.115949
$\mathbf{N}$	1.451163	1.223956	-0.116135
$\sqrt{\mathbf{N}}$	1.451163	1.043478	-0.115549
$\ln \mathbf{N}$	1.451163	1.046345	-0.116123

Table 7: Vortex size  $X_R$ , vortex intensity  $\Psi_R$  and Couette correction  $C$  using  $Wi = 1$ .

XrWi1

Formulation	Loses positivity	Simulation breakdown
$\mathbf{T}^p$	$Wi \geq 0.4$	$Wi \geq 5$
$\sqrt{\mathbf{A}}$	-	$Wi \geq 50$
$\ln \mathbf{A}$	-	$Wi \geq 100$
$\mathbf{N}$	$Wi \geq \frac{1}{2}$	-
$\sqrt{\mathbf{N}}$	-	-
$\ln \mathbf{N}$	-	-

WiCrit

Table 8: Critical Weissenberg number for different methods in the 4:1 contraction flow.

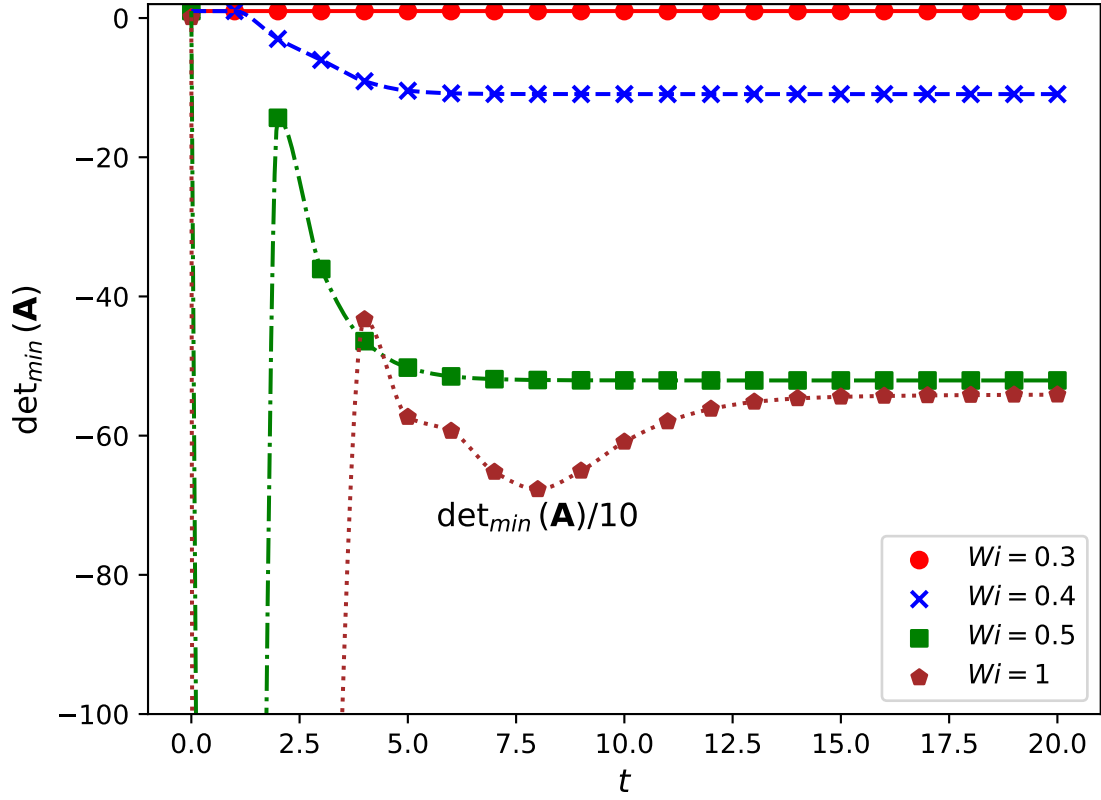
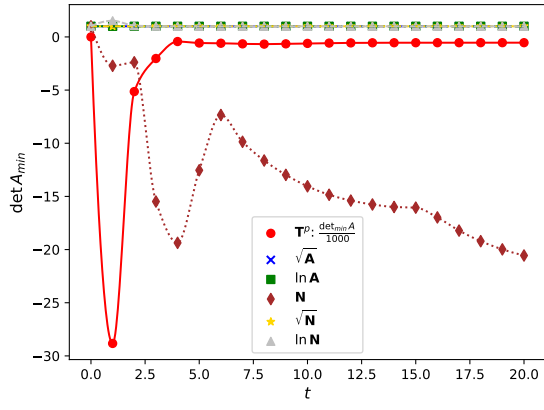
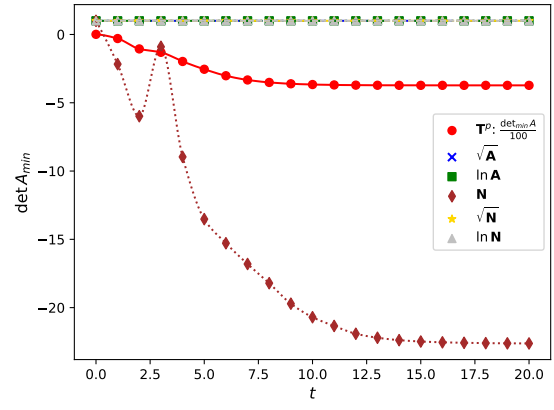


Figure 5: The minimum determinant of  $\mathbf{A}$ ,  $\det_{\min} \mathbf{A}$ , along the time  $t$  for the CSF in the 4:1 contraction flow.

detAmin



(a) 4:1 Contraction



(b) L-shaped

$\det \mathbf{A}$

Figure 6: The minimum determinant of  $\mathbf{A}$ ,  $\det \mathbf{A}_{min}$ , along the time  $t$  with  $Wi = 1$ .